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# **LMK04100 Family Clock Jitter Cleaner with Cascaded PLLs**

**Check for Samples: [LMK04100,](http://www.ti.com/product/lmk04100#samples) [LMK04101](http://www.ti.com/product/lmk04101#samples), [LMK04102](http://www.ti.com/product/lmk04102#samples), [LMK04110](http://www.ti.com/product/lmk04110#samples), [LMK04111](http://www.ti.com/product/lmk04111#samples), [LMK04131,](http://www.ti.com/product/lmk04131#samples) [LMK04133](http://www.ti.com/product/lmk04133#samples)**

# **<sup>1</sup>FEATURES**

- - -
		- **– Loss of Signal Detection**
		- **APPLICATIONS – Automatic and Manual Selection of**
	- - **• Cellular Repeaters – Phase Detector Rate up to 100 MHz**
		-
		-
- - **– LVPECL/2VPECL, LVDS, and LVCMOS Formats • Optical Transport Networks**
	- **– Support Clock Rates up to 1080 MHz • Broadcast Video, HDTV**
	- **– Five Dedicated Channel Divider Blocks • Serial ATA**
	-
	- **– Common Output Frequencies Supported: DESCRIPTION MHz, 155.52 MHz, 156.25 MHz, 159.375** VCXO modules. **MHz, 187.5 MHz, 200 MHz, 212.5 MHz,**
- **• MICROWIRE (SPI) Programming Interface**
- **<sup>23</sup>• Cascaded PLLatinum™ PLL Architecture • Industrial Temperature Range: -40 to 85 °C**
- **– PLL1 • 3.15 V to 3.45 V Operation**
	- **– Redundant Reference Inputs • Package: 48 Pin WQFN (7.0 x 7.0 x 0.8 mm)**

- **Reference Clock Input • Multi-Carrier/Multi-Mode/Multi-Band 2G/3G/4G Basestations – PLL2**
	-
	- **– Input Frequency-Doubler • High Speed A/D clocking**
	- **• SONET/SDH OC-48/OC-192/OC-768 Line Cards – Integrated VCO**
- **• GbE/10GbE, 1/2/4/8/10G Fibre Channel Line • Outputs Cards**
	-
	-
	-

30.72 MHz, 01.44 MHz, 02.3 MHz, 74.23<br>
MHz, 75 MHz, 77.76 MHz, 100 MHz,<br>
106.25 MHz, 125 MHz, 122.88 MHz, 150<br>
distribution without the need for high-performance **106.25 MHz, 125 MHz, 122.88 MHz, 150** distribution without the need for high-performance

245.76 MHz, 250 MHz, 311.04 MHz, 312.5<br>MHz, 368.64 MHz, 491.52 MHz, 622.08 clock and a VCXO, the device generates 5 low jitter<br>MHz, 625 MHz, 983.04 MHz



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### **Table 2. Device Output Format Information**



[Table](#page-2-0) 3 shows a limited list of example frequencies. Multiple output frequencies can be programmed on a single device provided that the VCO frequency and VCO divider values are the same.



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<span id="page-2-0"></span>

**Table 3. Example Configurations for Common Frequencies**

(1) Use VCO Frequency to select proper device option

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**TEXAS INSTRUMENTS** 

# **Functional Block Diagram**





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#### **Connection Diagram**



#### **Figure 1. 48-Pin WQFN Package Top Down View**

#### **PIN DESCRIPTIONS**



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#### **PIN DESCRIPTIONS (continued)**



(1) The reference clock inputs may be either AC or DC coupled.

(2) The reference clock inputs may be either AC or DC coupled.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

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# **Absolute Maximum Ratings(1)(2)(3)(4)**



(1) "Absolute Maximum Ratings" indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but do not guarantee specific performance limits. For guaranteed specifications and test conditions, see the Electrical Characteristics. The guaranteed specifications apply only to the test conditions listed.

(2) This device is a high performance RF integrated circuit with an ESD rating up to 8 KV Human Body Model, up to 300 V Machine Model and up to 1,250 V Charged Device Model and is ESD sensitive. Handling and assembly of this device should only be done at ESD-free workstations.

(3) Stresses in excess of the absolute maximum ratings can cause permanent or latent damage to the device. These are absolute stress ratings only. Functional operation of the device is only implied at these or any other conditions in excess of those given in the operation sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect device reliability.

(4) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/Distributors for availability and specifications.

(5) Never to exceed 3.6 V.

### **Package Thermal Resistance**



(1) Specification assumes 16 thermal vias connect the die attach pad to the embedded copper plane on the 4-layer JEDEC board. These vias play a key role in improving the thermal performance of the WQFN. It is recommended that the maximum number of vias be used in the board layout.

#### <span id="page-6-0"></span>**Recommended Operating Conditions**



### **Electrical Characteristics**

(3.15 V  $\leq$  V<sub>CC</sub>  $\leq$  3.45 V, -40 °C  $\leq$  T<sub>A</sub>  $\leq$  85 °C. Typical values represent most likely parametric norms at V<sub>CC</sub> = 3.3 V, T<sub>A</sub> = 25 °C, at the [Recommended](#page-6-0) Operating Conditions at the time of product characterization and are not guaranteed.)



(1) Load conditions for output clocks: LVPECL: 50 Ω to V<sub>CC</sub>-2 V. 2VPECL: 50 Ω to V<sub>CC</sub>-2.36 V. LVDS: 100 Ω differential. LVCMOS: 10 pF.

(2) Additional test conditions for  $I_{CC}$  limits: CLKoutX\_DIV = 510, PLL1 and PLL2 locked. (See [Table](#page-38-0) 34 for more information)

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# **Electrical Characteristics (continued)**

(3.15 V ≤ V<sub>CC</sub> ≤ 3.45 V, -40 °C ≤ T<sub>A</sub> ≤ 85 °C. Typical values represent most likely parametric norms at V<sub>CC</sub> = 3.3 V, T<sub>A</sub> = 25 °C, at the [Recommended](#page-6-0) Operating Conditions at the time of product characterization and are not guaranteed.)



(3) CLKin0 and CLKin1 maximum of 400 MHz is guaranteed by characterization, production tested at 200 MHz.<br>(4) In order to meet the jitter performance listed in the subsequent sections of this data sheet. the minimum recc

In order to meet the jitter performance listed in the subsequent sections of this data sheet, the minimum recommended slew rate for all input clocks is 0.5 V/ns. This is especially true for single-ended clocks. Phase noise performance will begin to degrade as the clock input slew rate is reduced. However, the device will function at slew rates down to the minimum listed. When compared to single-ended clocks, differential clocks (LVDS, LVPECL) will be less susceptible to degradation in phase noise performance at lower slew rates due to their common mode noise rejection. However, it is also recommended to use the highest possible slew rate for differential clocks to achieve optimal phase noise performance at the device outputs.

(5) See Differential Voltage [Measurement](#page-14-0) Terminology for definition of  $V_{1D}$  and  $V_{0D}$  voltages.

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#### **Electrical Characteristics (continued)**

(3.15 V ≤ V<sub>CC</sub> ≤ 3.45 V, -40 °C ≤ T<sub>A</sub> ≤ 85 °C. Typical values represent most likely parametric norms at V<sub>CC</sub> = 3.3 V, T<sub>A</sub> = 25 °C, at the [Recommended](#page-6-0) Operating Conditions at the time of product characterization and are not guaranteed.)



(6) This parameter is programmable

(7) Foscin maximum frequency guaranteed by characterization. Production tested at 200 MHz.<br>(8) The EN\_PLL2\_REF2X bit (Register 13) enables/disables a frequency doubler mode for the (8) The EN\_PLL2\_REF2X bit (Register 13) enables/disables a frequency doubler mode for the PLL2 OSCin path.

(9) See Differential Voltage [Measurement](#page-14-0) Terminology for definition of  $V_{\text{ID}}$  and  $V_{\text{OD}}$  voltages.

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# **Electrical Characteristics (continued)**

(3.15 V ≤ V<sub>CC</sub> ≤ 3.45 V, -40 °C ≤ T<sub>A</sub> ≤ 85 °C. Typical values represent most likely parametric norms at V<sub>CC</sub> = 3.3 V, T<sub>A</sub> = 25 °C, at the [Recommended](#page-6-0) Operating Conditions at the time of product characterization and are not guaranteed.)



(10) See Application Section discussion of Crystal Power Dissipation.



#### **Electrical Characteristics (continued)**

(3.15 V  $\leq$  V<sub>CC</sub>  $\leq$  3.45 V, -40 °C  $\leq$  T<sub>A</sub>  $\leq$  85 °C. Typical values represent most likely parametric norms at V<sub>CC</sub> = 3.3 V, T<sub>A</sub> = 25 °C, at the [Recommended](#page-6-0) Operating Conditions at the time of product characterization and are not guaranteed.)



(11) Maximum Allowable Temperature Drift for Continuous Lock is how far the temperature can drift in either direction from the value it was at the time that the R0 register was last programmed, and still have the part stay in lock. The action of programming the R0 register, even to the same value, activates a frequency calibration routine. This implies the part will work over the entire frequency range, but if the temperature drifts more than the maximum allowable drift for continuous lock, then it will be necessary to reload the R0 register to ensure it stays in lock. Regardless of what temperature the part was initially programmed at, the temperature can never drift outside the frequency range of -40 °C to 85 °C without violating specifications.

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# **Electrical Characteristics (continued)**

(3.15 V ≤ V<sub>CC</sub> ≤ 3.45 V, -40 °C ≤ T<sub>A</sub> ≤ 85 °C. Typical values represent most likely parametric norms at V<sub>CC</sub> = 3.3 V, T<sub>A</sub> = 25 °C, at the [Recommended](#page-6-0) Operating Conditions at the time of product characterization and are not guaranteed.)



(12) Equal loading and identical channel configuration on each channel is required for specification to be valid.

(13) See Differential Voltage [Measurement](#page-14-0) Terminology for definition of  $V_{ID}$  and  $V_{OD}$  voltages.

(14) LVPECL/2VPECL is programmable for all NSIDs.

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#### **Electrical Characteristics (continued)**

(3.15 V ≤ V<sub>CC</sub> ≤ 3.45 V, -40 °C ≤ T<sub>A</sub> ≤ 85 °C. Typical values represent most likely parametric norms at V<sub>CC</sub> = 3.3 V, T<sub>A</sub> = 25 °C, at the [Recommended](#page-6-0) Operating Conditions at the time of product characterization and are not guaranteed.)



(15) Equal loading and identical channel configuration on each channel is required for specification to be valid.

(16) See Differential Voltage [Measurement](#page-14-0) Terminology for definition of  $V_{1D}$  and  $V_{OD}$  voltages.

(17) Guaranteed by characterization.

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## **Serial Data Timing Diagram**



Register programming information on the DATAuWire pin is clocked into a shift register on each rising edge of the CLKuWire signal. On the rising edge of the LEuWire signal, the register is sent from the shift register to the register addressed. A slew rate of at least 30 V/µs is recommended for these signals. After programming is complete the CLKuWire, DATAuWire, and LEuWire signals should be returned to a low state. If the CLKuWire or DATAuWire lines are toggled while the VCO is in lock, as is sometimes the case when these lines are shared with other parts, the phase noise may be degraded during this programming.





I1 = Charge Pump Sink Current at  $V_{C\text{Pout}} = V_{CC} - \Delta V$ 

 $I2 =$  Charge Pump Sink Current at  $V_{CPout} = V_{CC}/2$ 

I3 = Charge Pump Sink Current at  $V_{CPout} = ΔV$ 

I4 = Charge Pump Source Current at  $V_{CPout} = V_{CC} - \Delta V$ 

 $I5$  = Charge Pump Source Current at  $V_{C\text{Pout}} = V_{C\text{C}}/2$ 

I6 = Charge Pump Source Current at  $V_{C\text{Pout}} = ΔV$ 

 $\Delta V$  = Voltage offset from the positive and negative supply rails. Defined to be 0.5 V for this device.

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### **CHARGE PUMP OUTPUT CURRENT MAGNITUDE VARIATION VS. CHARGE PUMP OUTPUT VOLTAGE**

$$
I_{\text{CPout}} \text{ Vs } V_{\text{CPout}} = \frac{|11| - |13|}{|11| + |13|} \times 100\%
$$

$$
= \frac{|14| - |16|}{|14| + |16|} \times 100\%
$$

### **CHARGE PUMP SINK CURRENT VS. CHARGE PUMP OUTPUT SOURCE CURRENT MISMATCH**

$$
I_{CPort}
$$
 Sink Vs  $I_{CPort}$  Source = 
$$
\frac{||2|-||5|}{||2|+||5|} \times 100\%
$$

### **CHARGE PUMP OUTPUT CURRENT MAGNITUDE VARIATION VS. TEMPERATURE**

$$
I_{CPout} \text{ Vs } T_A = \frac{|I_2| \left| \frac{1}{T_A} - |I_2| \right|_{T_A = 25^\circ \text{C}}} |I_2| \left| \frac{1}{T_A = 25^\circ \text{C}} \right| \times 100\%
$$

$$
= \frac{|I_5| \left| \frac{1}{T_A} - |I_5| \right|_{T_A = 25^\circ \text{C}}} |I_5| \left| \frac{1}{T_A = 25^\circ \text{C}} \right| \times 100\%
$$

#### <span id="page-14-0"></span>**Differential Voltage Measurement Terminology**

The differential voltage of a differential signal can be described by two different definitions causing confusion when reading datasheets or communicating with other engineers. This section will address the measurement and description of a differential signal so that the reader will be able to understand and discern between the two different definitions when used.

The first definition used to describe a differential signal is the absolute value of the voltage potential between the inverting and non-inverting signal. The symbol for this first measurement is typically  $V_{ID}$  or  $V_{OD}$  depending on if an input or output voltage is being described.

The second definition used to describe a differential signal is to measure the potential of the non-inverting signal with respect to the inverting signal. The symbol for this second measurement is  $V_{SS}$  and is a calculated parameter. Nowhere in the IC does this signal exist with respect to ground, it only exists in reference to its differential pair. V<sub>SS</sub> can be measured directly by oscilloscopes with floating references, otherwise this value can be calculated as twice the value of  $V_{OD}$  as described in the first description.

Figure 11 illustrates the two different definitions side-by-side for inputs and Figure 12 illustrates the two different definitions side-by-side for outputs. The V<sub>ID</sub> and V<sub>OD</sub> definitions show V<sub>A</sub> and V<sub>B</sub> DC levels that the non-inverting and inverting signals toggle between with respect to ground.  $V_{SS}$  input and output definitions show that if the inverting signal is considered the voltage potential reference, the non-inverting signal voltage potential is now increasing and decreasing above and below the non-inverting reference. Thus the peak-to-peak voltage of the differential signal can be measured.

 $V_{\text{ID}}$  and  $V_{\text{OD}}$  are often defined as volts (V) and  $V_{\text{SS}}$  is often defined as volts peak-to-peak (V<sub>PP</sub>).







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Refer to application note AN-912 Common Data Transmission Parameters and their Definitions [\(SNLA036](http://www.ti.com/lit/pdf/SNLA036)) for more information.

#### **Figure 4. Two Different Definitions for Differential Output Signals**



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### **Typical Performance Characteristics**

# <span id="page-16-0"></span>**CLOCK OUTPUT AC CHARACTERISTICS**



**Figure 9.**

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# **FEATURES**

## **SYSTEM ARCHITECTURE**

The cascaded PLL architecture of the LMK041xx was chosen to provide the lowest jitter performance over the widest range of output frequencies and phase noise offset frequencies. The first stage PLL (PLL1) is used in conjunction with an external reference clock and an external VCXO to provide a frequency accurate, low phase noise reference clock for the second stage frequency multiplication PLL (PLL2). PLL1 typically uses a narrow loop bandwidth (10 Hz to 200 Hz) to retain the frequency accuracy of the reference clock input signal while at the same time suppressing the higher offset frequency phase noise that the reference clock may have accumulated along its path or from other circuits. The "cleaned" reference clock frequency accuracy is combined with the low phase noise of an external VCXO to provide the reference input to PLL2. The low phase noise reference provided to PLL2 allows it to use wider loop bandwidths (50 kHz to 200 kHz). The chosen loop bandwidth for PLL2 should take best advantage of the superior high offset frequency phase noise profile of the internal VCO and the good low offset frequency phase noise of the reference VCXO for PLL2. Low jitter is achieved by allowing the external VCXO's phase noise to dominate the final output phase noise at low offset frequencies and the internal VCO's phase noise to dominate the final output phase noise at high offset frequencies. This results in best overall phase noise and jitter performance.

## **REDUNDANT REFERENCE INPUTS (CLKin0/CLKin0\*, CLKin1/CLKin1\*)**

The LMK041xx has two LVDS/LVPECL/LVCMOS compatible reference clock inputs for PLL1, CLKin0 and CLKin1. The selection of the preferred input may be fixed to either CLKin0 or CLKin1, or may be configured to employ one of two automatic switching modes when redundant clock signals are present. The PLL1 reference clock input buffers may also be individually configured as either a CMOS buffered input or a bipolar buffered input.

# **PLL1 CLKinX (X=0,1) LOSS OF SIGNAL (LOS)**

When either of the two auto-switching modes is selected for the reference clock input mode, the signal status of the selected reference clock input is indicated by the state of the CLKinX\_LOS (loss-of-signal) output. These outputs may be configured as either CMOS (active HIGH on loss-of-signal), NMOS open-drain or PMOS opendrain. If PLL1 was originally locked and then both reference clocks go away, then the frequency accuracy of the LMK04100 device will be set by the absolute tuning range of the VCXO used on PLL1. The absolute tuning range of the VCXO can be determined by multiplying its' tuning constant by the charge pump voltage.

### **INTEGRATED LOOP FILTER POLES**

The LMK041xx features programmable 3rd and 4th order loop filter poles for PLL2. When enabled, internal resistors and capacitor values may be selected from a fixed range of values to achieve either 3rd or 4th order loop filter response. These programmable components compliment external components mounted near the chip.

### **CLOCK DISTRIBUTION**

The LMK041xx features a clock distribution block with a minimum of five outputs that are a mixture of LVPECL, 2VPECL, LVDS, and LVCMOS. The exact combination is determined by the part number. The 2VPECL is a Texas Instruments proprietary configuration that produces a 2 Vpp differential swing for compatibility with many data converters. More than five outputs may be available for device versions that offer dual LVCMOS outputs.

# **CLKout DIVIDE (CLKoutX\_DIV, X = 0 to 4)**

Each individual clock distribution channel includes a channel divider. The range of divide values is 2 to 510, in steps of 2. "Bypass" mode operates as a divide-by-1.

### **GLOBAL CLOCK OUTPUT SYNCHRONIZATION (SYNC\*)**

The SYNC\* input is used to synchronize the active clock outputs. When SYNC\* is held in a logic low state, the outputs are also held in a logic low state. When SYNC\* goes high, the clock outputs are activated and will transition to a high state simultaneously with one another.

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SYNC\* must be held low for greater than one clock cycle of the Clock Distribution Path. After this low event has been registered, the outputs will not reflect the low state for four more cycles. Similarly after SYNC\* becomes high, the outputs will simultaneously transition high after four Clock Distribution Path cycles have passed. See [Figure](#page-18-0) 10 for further detail.



**Figure 10. Clock Output synchronization using the SYNC\* pin**

# <span id="page-18-0"></span>**GLOBAL OUTPUT ENABLE AND LOCK DETECT**

Each Clock Output Channel may be either enabled or put into a high impedance state via the Clock Output Enable control bit (one for each channel). Each output enable control bit is gated with the Global Output Enable input pin (GOE). The GOE pin provides an internal pull-up so that if it is un-terminated externally, then the clock output states are determined by the Clock Channel Output Enable Register bits. All clock outputs can be disabled simultaneously if the GOE pin is pulled low by an external signal.

#### **Table 4. Clock Output Control**



The Lock Detect (LD) signal can be connected to the GOE pin in which case all outputs are disabled automatically if the synthesizer is not locked. See EN CLKoutX: Clock Channel Output Enable and also SYSTEM LEVEL [DIAGRAM](#page-36-0) for actual implementation details.

The Lock Detect (LD) pin can be programmed to output a 'High' when both PLL1 and PLL2 are locked, or only when PLL1 is locked or only when PLL2 is locked.

### **Functional Description**

#### **ARCHITECTURAL OVERVIEW**

The LMK041xx chip consists of two high performance synthesizer blocks (Phase Locked Loop, internal VCO/VCO Divider, and loop filter), source selection, distribution system, and independent clock output channels.

The Phase Frequency Detector in PLL1 compares the divided (R Divider 1) system clock signal from the selected CLKinX and CLKinX\* input with the divided (N Divider 1) output of the external VCXO attached to the PLL2 OSCin port. The external loop filter for PLL1 should be narrow to provide an clean reference clock from the external VCXO to the OSCin/OSCin\* pins for PLL2.

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The Phase Frequency Detector in PLL2 then compares the divided (R Divider 2) reference signal from the PLL2 OSCin port with the divided (N Divider 2 and VCO Divider) output of the internal VCO. The bandwidth of the external loop filter for PLL2 should be designed to be wide enough to take advantage of the low in-band phase noise of PLL2 and the low high offset phase noise of the internal VCO. The VCO output is passed through a common VCO divider block and placed on a distribution path for the clock distribution section. It is also routed to the PLL2\_N counter. Each clock output channel allows the user to select a path with a programmable divider block, a phase synchronization circuit, and LVDS/LVPECL/2VPECL/LVCMOS compatible output buffers.

### **PHASE DETECTOR 1 (PD1)**

Phase Detector 1 in PLL1 (PD1) can operate up to 40 MHz. Since a narrow loop bandwidth should be used for PLL1, the need to operate at high phase detector rate to lower the in-band phase noise becomes unnecessary.

#### **PHASE DETECTOR 2 (PD2)**

Phase Detector 2 in PLL2 (PD2) supports a maximum comparison rate of 100 MHz, though the actual maximum frequency at the input port (PLL2 OSCin/OSCin\*) is 250 MHz. Operating at highest possible phase detector rate will ensure low in-band phase noise for PLL2 which in turn produces lower total jitter, as the in-band phase noise from the reference input and PLL are proportional to  $N^2$ .

#### **PLL2 FREQUENCY DOUBLER**

The PLL2 reference input at the OSCin port may be optionally routed through a frequency doubler function rather than through the PLL2\_R counter. The maximum phase comparison frequency of the PLL2 phase detector is 100 MHz, so the input to the frequency doubler is limited to a maximum of 50 MHz. The frequency doubler feature allows the phase comparison frequency to be increased when a relative low frequency oscillator is driving the OSCin port. By doubling the PLL2 phase comparison frequency, the in-band PLL2 noise is reduced by about 3 dB.

### **INPUTS / OUTPUTS**

#### **PLL1 Reference Inputs (CLKin0 / CLKin0\*, CLKin1 / CLKin1\*)**

The reference clock inputs for PLL1 may be selected from either CLKin0 and CLKin1. The user has the capability to manually select one of the two inputs or to configure an automatic switching mode operation. A detailed description of this function is described in the uWire programming section of this data sheet.

#### **PLL2 OSCin / OSCin\* Port**

The feedback from the external oscillator being locked with PLL1 is injected to the PLL2 OSCin/OSCin<sup>\*</sup> pins. This input may be driven with either an AC coupled single-ended or AC coupled differential signal. If operated in single ended mode, the unused input should be tied to GND with a 0.1 µF capacitor. Internal to the chip, this signal is routed to the PLL1\_N Counter and to the reference input for PLL2. The internal circuitry of the OSCin port also supports the optional implementation of a crystal based oscillator circuit. A crystal, varactor diode and a small number of other external components may be used to implement the oscillator. The internal oscillator circuit is enabled by setting the EN\_PLL2\_XTAL bit.

#### **CPout1 / CPout2**

The CPout1 pin provides the charge pump current output to drive the loop filter for PLL1. This loop filter should be configured so that the total loop bandwidth for PLL1 is less than 200 Hz. When combined with an external oscillator that has low phase noise at offsets close to the carrier, PLL1 generates a reference for PLL2 that is frequency locked to the PLL1 reference clock but has the phase noise performance of the oscillator. The CPout2 pin provides the charge pump current output to drive the loop filter for PLL2. This loop filter should be configured so that the total loop bandwidth for PLL2 is in the range of 50 kHz to 200 kHz. See the section on uWire device control for a description of the charge pump current gain control.

#### **Fout**

The buffered output of the internal VCO is available at the Fout pin. This is a single-ended output (sinusoid). Each time the PLL2\_N counter value is updated via the uWire interface, an internal algorithm is triggered that optimizes the VCO performance.

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#### **Digital Lock Detect 1 Bypass**

The VCO coarse tuning algorithm requires a stable OSCin clock (reference clock to PLL2) to frequency calibrate the internal VCO correctly. In order to ensure a stable OSCin clock, the first PLL must achieve lock status. A digital lock detect is used in PLL1 to monitor its lock status. After lock is achieved by PLL1, the coarse tuning circuitry is enabled and frequency calibration for the internal VCO begins.

The (DLD\_BYP) pin is provided to allow an external bypass cap to be connected to the digital lock detect 1. This capacitor will eliminate potential glitches at initial startup of PLL1 due to unknown phase relationships between the Ncntr1 and Rcntr1.

#### **Bias**

Proper bypassing of this pin by a 1  $\mu$ F capacitor connected to  $V_{CC}$  is important for low noise performance.

#### <span id="page-20-1"></span>**General Programming Information**

LMK041xx devices are programmed using several 32-bit registers. Each register consists of a 4-bit address field and 28-bit data field. The address field is formed by bits 0 through 3 (LSBs) and the data field is formed by bits 4 through 31 (MSBs). The contents of each register are clocked in MSB first (bit 31), and the LSB (bit 0) last. During programming, the LE signal should be held LOW. The serial data is clocked in on the rising edge of the CLK signal. After the LSB (bit 0) is clocked in the LE signal should be toggled LOW-to-HIGH-to-LOW to latch the contents into the register selected in the address field. Registers R0-R4, R7, and R8-R15 must be programmed in order to achieve proper device operation. [Figure](#page-20-0) 11 illustrates the serial data timing sequence.



**Figure 11. uWire Timing Diagram**

<span id="page-20-0"></span>To achieve proper frequency calibration, the OSCin port must be driven with a valid signal before programming Register 15. Changes to PLL2\_R Counter or the OSCin port signal require Register 15 to be reloaded in order to activate the frequency calibration process.

### **RECOMMENDED PROGRAMMING SEQUENCE**

The recommended programming sequence involves programming R7 with the reset bit set to 1 (Reg. 7, bit 4) to ensure the device is in a default state. If R7 is programmed again, the reset bit should be set to 0. Registers are programmed in order with R15 being the last register programmed. An example programming sequence is shown below:

- Program R7 with the RESET bit = 1 ( $b4 = 1$ ). This ensures that the device is configured with default settings. When  $RESET = 1$ , all other R7 bits are ignored.
	- If R7 is programmed again during the initial configuration of the device, the RESET bit should be cleared  $(b4 = 0)$
- Program R0 through R4 as necessary to configure the clock outputs as desired. These registers configure clock channel functions such as the channel multiplexer output selection, divide value, and enable/disable bit.
- Program R5 and R6 with the default values shown in the register map on the following pages.
- Program R7 with  $RESET = 0$ .
- Program R8 through R10 with the default values shown in the register map on the following pages.
- Program R11 to configure the reference clock inputs (CLKin0 and CLKin1).
	- type, LOS timeout, LOS type, and mode (manual or auto-switching)
- Program R12 to configure PLL1.



- Charge pump gain, polarity, R counter and N counter
- Program R13 through R15 to configure PLL2 parameters, crystal mode options, and certain globally asserted functions.

The following table provides the register map for device programming:



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## **Table 5. Register Map**



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**Table 5. Register Map (continued)**

Register	31	30	29	28	27	26	25	${\bf 24}$	23	22	21	${\bf 20}$	19	18	17	16	15	14	13	12	11	10	9	8	$\overline{7}$	6	5	4	$\mathbf{3}$	$\mathbf{2}$	$\mathbf{1}$	$\mathbf 0$
R7	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf{0}$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	0	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	0	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	0	$\mathbf 0$	<b>RESET</b>	$\overline{0}$	$\mathbf{1}$	$\mathbf{1}$	$\mathbf{1}$
R <sub>8</sub>	$\mathsf{O}$	$\mathsf 0$	$\mathbf 0$	$\mathbf 0$	$\mathsf 0$	$\mathbf 0$	$\mathbf 0$	$\mathsf 0$	$\pmb{0}$	$\mathsf{O}\xspace$	$\mathsf{O}\xspace$	$\mathbf 0$	$\mathbf 0$	$\mathsf 0$	$\mathsf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathsf{O}\xspace$	$\mathsf{O}\xspace$	$\mathsf 0$	$\mathbf 0$	$\mathbf 0$	$\mathsf{O}\xspace$	$\mathsf{O}\xspace$	$\mathbf 0$	$\mathbf 0$	$\mathsf{O}\xspace$	$\mathbf{1}$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$
R <sub>9</sub>	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf{1}$	$\mathbf 0$	$\mathbf{1}$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf{1}$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\overline{1}$	$\mathbf 0$	$\mathbf{1}$	$\mathbf 0$	$\mathbf{1}$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf{1}$	$\mathbf 0$	$\mathsf{O}\xspace$	$\overline{1}$
R <sub>10</sub>	$\mathbf 0$	$\mathbf 0$	Start RC_DLD1	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\overline{1}$	$\mathbf 0$	$\overline{1}$	$\mathbf 0$	$\overline{1}$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf{1}$	$\mathbf 0$	$\mathbf{1}$	$\mathsf{O}\xspace$
R <sub>11</sub>	$\mathbf 0$	$\mathbf 0$	0	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathsf 0$	$\mathbf 0$	$\overline{1}$	$\mathbf{1}$	$\mathbf 0$	$\mathbf 0$	$\overline{1}$	$\mathbf 0$	$\overline{1}$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	CLKin1_BUFTYPE	CLKin0_BUFTYPE		LOS_TIMEOUT [1:0]		LOS_TYPE [1:0]		CLKin_SEL [1:0]	$\mathbf{1}$	$\boldsymbol{0}$	$\mathbf{1}$	$\mathbf{1}$
R <sub>12</sub>	PLL1_CP_POL	PLL1_CP_ GAIN [2:0] PLL1_R Counter [11:0]													PLL1_N Counter [11:0]											$\mathbf{1}$	$\mathbf{1}$	$\mathsf{O}$	$\mathbf 0$			
R <sub>13</sub>	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$\mathbf{1}$	$\mathbf 0$	$\overline{1}$	$\mathbf 0$	$\mathbf 0$	$\mathbf 0$	$EN$ PLL2 XTAL	$EN_F$ Fout	$\mathbf 0$	EN_CLKout_Global, default=1	POWER DOWN, default = 0	EN_PLL2_REF2X	PLL2 CP TRI-STATE	PLL1 CP TRI-STATE	PLL2_R4_LF [2:0]   PLL2_R3_LF [2:0]							PLL2_C3_C4_LF [3:0]				$\overline{1}$	$\mathbf 0$	$\overline{1}$
R <sub>14</sub>	$\mathbf 0$	$\mathsf 0$	$\mathbf 0$					OSCin_FREQ [7:0]			PLL_MUX [4:0]							PLL2_R Counter [11:0] $\mathbf{1}$											$\mathbf{1}$	$\overline{1}$	$\mathbf 0$	
<b>R15</b>	$\pmb{0}$	$\mathsf 0$	$\mathbf 0$	$\mathbf{1}$		PLL2_CP_GAIN [1:0] VCO_DIV [3:0]						PLL2_N Counter [17:0]														$\mathbf{1}$	$\mathbf{1}$	$\mathbf{1}$	$\overline{1}$			

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## **DEFAULT DEVICE REGISTER SETTINGS AFTER POWER ON/RESET**

[Table](#page-24-0) 6 illustrates the default register settings programmed in silicon for the LMK041xx after power on or asserting the reset bit.

<span id="page-24-0"></span>

#### **Table 6. Default Device Register Settings after Power On/Reset**

(1) These registers are reserved. The Power On/Reset values for these registers are shown in the register map and should not be changed during programming.

(2) If the CLKin\_SEL value is set to either [0,0] or [0,1], the LOS\_TYPE field should be set to [0,0].

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#### **REGISTER R0 TO R4**

Registers R0 through R4 control the five clock outputs. Register R0 controls CLKout0, Register R1 controls CLKout1, and so on. Aside from this, the functions of the bits in these registers are identical. The X in CLKoutX\_MUX, CLKoutX\_DIV, and CLKoutX\_EN denote the actual clock output which may be from 0 to 4.

#### **CLKoutX\_DIV: Clock Channel Divide Registers**

Each of the five clock output channels (0 though 4) has a dedicated 8-bit divider followed by a fixed divide by 2 that is used to generate even integer related versions of the distribution path clock frequency (VCO Divider output). If the VCO Divider value is even then the Channel Divider may be bypassed (See CLK Output Mux), giving an effective divisor of 1 while preserving a 50% duty cycle output waveform.





## <span id="page-25-0"></span>**EN\_CLKoutX: Clock Channel Output Enable**

Each Clock Output Channel may be either enabled or disabled via the Clock Output Enable control bits. Each output enable control bit is gated with the Global Output Enable input pin (GOE) and Global Output Enable bit (EN\_CLKout\_Global). The GOE pin provides an internal pull-up so that if it is unterminated externally, the clock output states are determined by the Clock Output Enable Register bits. All clock outputs can be set to the low state simultaneously if the GOE pin is pulled low by an external signal. If EN\_CLKout\_Global is programmed to 0 all outputs are turned off. If both GOE and EN\_CLKout\_Global are low the clock outputs are turned off.



#### **Table 8. EN\_CLKoutX: Clock Channel Output Enable Control Bits**

Note the default state of CLKout2 is ON after power on or RESET assertion. The nominal frequency is 62 MHz (LMK041x1) or 81 MHz (LMK041x3). This is based on a channel divide value of 12 and default VCO\_DIV value of 2. If an active CLKout2 at power on is inappropriate for the user's application, the following method can be employed to shut off CLKout2 during system initialization:

When the device is powered on, holding the GOE pin LOW will disable all clock outputs. The device can be programmed while the GOE is held LOW. The state of CLKout2 can be altered during device programming according to the user's specific application needs. After device configuration is complete, the GOE pin should be set HIGH to enable the active clock channels.



#### **CLKoutX/CLKoutX\* LVCMOS Mode Control**

For clock outputs that are configured as LVCMOS, the LVCMOS CLKoutX/CLKoutX<sup>\*</sup> outputs can be independently configured by uWire CLKoutXA STATE and CLKoutXB STATE bits. The following choices are available for LVCMOS outputs:



#### **Table 9. CLKoutXA\_STATE, CLKoutXB\_STATE Control Bits for LVCMOS Modes**

### **CLKoutX/CLKoutX\* LVPECL Mode Control**

Clock outputs designated as LVPECL can be configured in one of two possible output levels. The default mode is the common LVPECL swing of 800 mVp-p single-ended (1.6 Vp-p differential). A second mode, 2VPECL, can be enabled in which the swing is increased to 1000 mVp-p single-ended (2 Vp-p differential).

#### **Table 10. LVPECL Output Format Control**



#### **CLKoutX\_MUX: Clock Output Mux**

The output of each CLKoutX channel pair is controlled by its' channel multiplexer (mux). The mux can select between several signals: bypassed, divided only.

#### **Table 11. CLKoutX\_MUX: Clock Channel Multiplexer Control Bits**



#### **REGISTERS 5, 6**

These registers are reserved. These register values should not be modified from the values shown in the register map.

#### **REGISTER 7**

#### **RESET bit**

This bit is only in register R7. The use of this bit is optional and it should be set to '0' if not used. Setting this bit to a '1' forces all registers to their power on reset condition and therefore automatically clears this bit.

#### **REGISTERS 8, 9**

These registers are reserved. These register values should not be modified from the values shown in the register map.

#### **REGISTER 10**

#### **RC\_DLD1\_Start: PLL1 Digital Lock Detect Run Control bit**

This bit is used to control the state machine for the PLL2 VCO tuning algorithm. The following table describes the function of this bit.

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#### **Table 12. RC\_DLD1\_Start bit states**



If the user is unsure of the state of the reference clock input at startup of the LMK041xx device, setting RC DLD1 Start = 0 will allow PLL2 to tune and lock the internal VCO to the oscillator attached to the OSCin port. This ensures that the active clock outputs will start up at frequencies close to their desired values. The error in clock output frequency will depend on the open loop accuracy of the oscillator driving the OSCin port. The frequency of an active clock output is normally given by:

$$
F_{CLK} = \frac{N}{R} \cdot \frac{F_{OSCin}}{(VCO_DIV \cdot CLK_DIV)}
$$

If the open loop frequency accuracy of the external oscillator (either a VCXO or crystal based oscillator) is "X" ppm, then the error in the output clock frequency ( $F_{\text{CLK}}$  error) will be:

$$
F_{CLK} \text{ error} = \frac{N}{R} \cdot \frac{X \cdot F_{OSCin}}{(VCO_DIV \cdot CLK_DIV)}
$$

Setting this bit to 0 does not prevent PLL1 from locking the external oscillator to the reference clock input after the latter input becomes valid.

#### **REGISTER 11**

#### **CLKinX\_BUFTYPE: PLL1 CLKinX/CLKinX\* Buffer Mode Control**

The user may choose between one of two input buffer modes for the PLL1 reference clock inputs: either bipolar junction differential or MOS. Both CLKinX and CLKinX\* input pins must be AC coupled when driven differentially. In single ended mode, the CLKinX\* pin must be coupled to ground through a capacitor. The active CLKinX buffer mode is selected by the CLKinX TYPE bits programmed via the uWire interface.



#### **Table 13. PLL1 CLKinX\_BUFTYPE Mode Control Bits**

#### **CLKin\_SEL: PLL1 Reference Clock Selection and Revertive Mode Control Bits**

This register allows the user to set the reference clock input that is used to lock PLL1, or to select an autoswitching mode. The automatic switching modes are revertive or non-revertive. In either revertive or nonrevertive mode, CLKin0 is the initial default reference source for the auto-switching mode. When revertive mode is active, the switching control logic will always select CLKin0 as the reference if it is active, otherwise it selects CLKin1. When non-revertive mode is active, the switching logic will only switch the reference input if the currently selected input fails.

[Table](#page-28-0) 14 illustrates the control modes. Modes [1,0] and [1,1] are the auto-switching modes. The behavior of both modes is tied to the state of the LOS signals for the respective reference clock inputs.





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If the reference clock inputs are active prior to configuration of the device, then the normal programming sequence described under General [Programming](#page-20-1) Information can be used without modification. If it cannot be guaranteed that the reference clocks are active prior to device programming, then the device programming sequence should be modified in order to ensure that CLKin0 is selected as the default. Under this scenario, the device should be programmed as described in "General Programming Information", with CLKin\_SEL bits programmed to [0,0] in register R11. The other R11 fields for clock type and LOS timeout should be programmed with the appropriate values for the given application. After the reference clock inputs have started, register R11 should be programmed a second time with the CLKin SEL field modified to the set the desired mode. The clock type field and LOS field values should remain the same.

<span id="page-28-0"></span>

#### **Table 14. CLKin\_SEL: Reference Clock Selection Bits**

#### **CLKinX\_LOS**

The CLKin0\_LOS and CLKin1\_LOS pins indicate the state of the respective PLL1 CLKinX reference input when the CLKin\_SEL bits are set set to either [1,0] or [1,1]. The detection logic that determines the state of the reference inputs is sensitive to the frequency of the reference inputs and must be configured to operate with the appropriate frequency range of the reference inputs, as described in the next section.

#### **PLL1 Reference Clock LOS Timeout Control**

This register is used to tune the LOS timeout based upon the frequency of the reference clock input(s). The register value controls the timeout setting for both CLKin0 and CLKin1. The value programmed in the LOS\_TIMEOUT register represents the minimum input frequency for which loss of signal can be detected. For example, if the reference input frequency is 12.288 MHz, then either register values (0,0) or (0,1) will result in valid loss of signal detection. If the reference input frequency is 1 MHz, then only the register value (0,0) will result in valid detection of signal loss.



#### **Table 15. Reference Clock LOS Timeout Control Bits**

#### **LOS Output Type Control**

The output format of the LOS pins may be selected as active CMOS, open drain NMOS and open drain PMOS, as shown in the following table.



#### **Table 16. Loss of Signal (LOS) Output Pin Format Type**

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The LOS output signal is valid only when CLKin\_SEL bits are set to either [1,0] or [1,1]. If the CLKin\_SEL field is programmed to either of the fixed inputs, [0,0] or [0,1], the LOS\_TYPE bits should be set to [0,0].

#### **REGISTER 12**

#### **PLL1\_N: PLL1\_N Counter**

The size of the PLL1 N counter is 12 bits. This counter will support a maximum divide ratio of 4095 and minimum divide ratio of 1. The 12 bit resolution is sufficient to support minimum phase detector frequency resolution of approximately 50 kHz when the VCXO frequency is 200 MHz.

For a 200 MHz external VCXO, the minimum phase detector rate will be PDmin = 200 MHz/4095 = 48.84 kHz



#### **Table 17. PLL1\_N Counter Values**

#### **PLL1\_R: PLL1\_R Counter**

The size of the PLL1\_R counter is 12 bits. This counter will support a maximum divide ratio of 4095 and minimum divide ratio of 1.



#### **Table 18. PLL1\_R Counter Values**

#### **PLL1 Charge Pump Current Gain (PLL1\_CP\_GAIN) and Polarity Control (PLL1\_CP\_POL)**

The Loop Band Width (LBW) on PLL1 should be narrow to suppress the noise from the system or input clocks at CLKinX/CLKinX\* port. This configuration allows the noise of the external VCXO to dominate at low offset frequencies. Given that the noise of the external VCXO is far superior than the noise of PLL1, this setting produces a very clean reference clock to PLL2 at the OSCin port.

In order to achieve a LBW as low as 10 Hz at the supported VCXO frequency (1 MHz to 200 MHz), a range of charge pump currents in PLL1 is provided. The table below shows the available current gains. A small charge pump current is required to obtain a narrow LBW at high phase detector rate (small N value).

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#### **Table 19. PLL1 Charge Pump Current Selections (PLL1\_CP\_GAIN)**



The PLL1\_CP\_POL bit sets the PLL1 charge pump for operation with a positive or negative slope VCO/VCXO. A positive slope VCO/VCXO increases frequency with increased tuning voltage. A negative slope VCO/VCXO increases frequency with decreased tuning voltage.

#### **Table 20. PLL1 Charge Pump Polarity Control Bits (PLL1\_CP\_POL)**



#### **REGISTER 13**

#### **EN\_PLL2\_XTAL: Crystal Oscillator Option Enable**

If an external crystal is being used to implement a discrete VCXO, the internal feedback amplifier must be enabled in order to complete the oscillator circuit.





#### **EN\_Fout: Fout Power Down Bit**

The  $EN_F$ out bit allows the Fout port to be enabled or disabled. By default  $EN_F$ out = 0.

#### **CLK Global Enable: Clock Global enable bit**

In addition to the external GOE pin, an internal Register 13 bit (b18) can be used to globally enable/disable the clock outputs via the uWire programming interface. The default value is 1. When CLK Global Enable = 1, the active output clocks are enabled. The active output clocks are disabled if this bit is 0.

#### **POWERDOWN Bit -- Device Power Down**

This bit can power down the entire device. Enabling this bit powers down the entire device and all functional blocks, regardless of the state of any of the other bits or pins.



#### **Table 22. Power Down Bit Values**

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#### **EN\_PLL2 REF2X: PLL2 Frequency Doubler control bit**

When  $F_{\text{OSCin}}$  is below 50 MHz, the PLL2 frequency doubler can be enabled by setting EN\_PLL2\_REF2X = 1. The default value is 0. When EN\_PLL2\_REF2X = 1, the signal at the OSCin port bypasses the PLL2\_R counter and is passed through a frequency doubler circuit. The output of this circuit is then input to the PLL2 phase comparator block. This feature allows the phase comparison frequency to be increased for lower frequency OSCin sources (< 50 MHz), and can be used with either VXCOs or crystals. For instance, when using a pullable crystal of 12.288 MHz to drive the OSCin port, the PLL2 phase comparison frequency is 24.576 MHz when EN\_PLL2\_REF2X = 1. A higher PLL phase comparison frequency reduces PLL2 in-band phase noise and RMS jitter. The PLL in-band phase noise can be reduced by approximately 2 to 3 dB. The on-chip loop filter typically is enabled to reduce PLL2 reference spurs when EN\_PLL2\_REF2X is enabled. Suggested values in this case are:  $R3 = 600$  Ω, C3 = 50 pF, R4 = 10 kΩ, C4 = 60 pF.

#### **PLL2 Internal Loop Filter Component Values**

Internal loop filter components are available for PLL2, enabling the user to implement either 3rd or 4th order loop filters without requiring external components. The user may select from a fixed set of values for both the resistors and capacitors. Internal loop filter resistance values for R3 and R4 can be set individually according to Table 20 and Table 21.



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### **Table 23. PLL2 Internal Loop Filter Resistor Values, PLL2\_R3\_LF**



### **Table 24. PLL2 Internal Loop Filter Resistor Values, PLL2\_R4\_LF**



Internal loop filter capacitors for C3 and C4 can be set individually according to the following table.

### **Table 25. PLL2 Internal Loop Filter Capacitor Values**





#### **PLL1 CP TRI-STATE and PLL2 CP TRI-STATE**

The charge pump output of either CPout1 or CPout2 may be placed in a TRI-STATE mode by setting the appropriate PLLx CP TRI-STATE bit.

#### **Table 26. PLL1 Charge Pump TRI-STATE bit values**



#### **Table 27. PLL2 Charge Pump TRI-STATE bit values**



#### **REGISTER 14**

#### **OSCin\_FREQ: PLL2 Oscillator Input Frequency Register**

The frequency of the PLL2 reference input to the PLL2 Phase Detector (OSCin/OSCin\* port) must be programmed in order to support proper operation of the internal VCO tuning algorithm. This is an 8-bit register that sets the frequency to the nearest 1-MHz increment.



#### **Table 28. OSCin\_FREQ Register Values**

#### **PLL2\_R: PLL2\_R Counter**

The PLL2 R Counter is 12 bits wide. It divides the PLL2 OSCin/OSCin\* clock and is connected to the PLL2 Phase Detector.





#### **PLL\_MUX: LD Pin Selectable Output**

The signal appearing on the LD pin is programmable via the uWire interface and provides access to several internal signals which may be valuable for either status monitoring during normal operation or for debugging during the hardware development phase. This pin may be forced to either a HIGH or LOW state, and may also be configured as specified in Table 27.





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## **Table 30. PLL\_MUX: LD Pin Selectable Outputs**



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### **REGISTER 15**

#### **PLL2\_N: PLL2\_N Counter**

The PLL2\_N Counter is 18 bits wide. It divides the output of the VCO Divider and is connected to the PLL2 Phase Detector. Each time the PLL2\_N Counter value is updated via the uWire interface, an internal algorithm is triggered that optimizes the VCO performance.



#### **Table 31. PLL2\_N: PLL2\_N Counter Values**

### **PLL2\_CP\_GAIN: PLL2 Charge Pump Current and Output Control**

The PLL2 charge pump output current level is controlled with the PLL2\_CP\_GAIN register. The following table presents the charge pump current control values.

#### **Table 32. PLL2\_CP\_GAIN: PLL2 Charge Pump Current Selections**



### **VCO\_DIV: PLL2 VCO Divide Register**

A divider is provided on the output of the PLL2 VCO to enable a wide range of output clock frequencies. The output of this divider is placed on the input path for the clock distribution section, which feeds each of the individual clock channels. The divider provides integer divide ratios from 2 to 8.



#### **Table 33. VCO\_DIV: PLL2 VCO Divider Values**

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## **APPLICATION INFORMATION**

# <span id="page-36-0"></span>**SYSTEM LEVEL DIAGRAM**

The following diagram illustrates the typical interconnection of the LMK041xx in a clocking application.



**Figure 12. Typical Application**

<span id="page-36-1"></span>[Figure](#page-36-1) 12 shows an LMK04100 family device with external circuitry. The primary reference clock input is at CLKin0/0\*. A secondary reference clock is driving CLKin1/1\*. Both clocks are depicted as AC coupled differential drivers. The VCXO attached to the OSCin/OSCin\* port is configured as an AC coupled single-ended driver. Any of the input ports (CLKin0/0\*, CLKin1/1\*, or OSCin/OSCin\*) may be configured as either differential or singleended. These options are discussed later in the data sheet.

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The diagram shows an optional connection between the LD pin and GOE. With this arrangement, the LD pin can be programmed to output a lock detect signal that is active HIGH (see Table 27 for optional LD pin outputs). If lock is lost, the LD pin will transition to a LOW, pulling GOE low and causing all clock outputs to be disabled. This scheme should be used only if disabling the clock outputs is desirable when lock is lost.

The loop filter for PLL2 consists of three external components that implement two lower order poles, plus optional internal integrated components if 3rd or 4th order poles are needed. The loop filter components for PLL1 must be external components.

The VCO output buffer signal that appears at the Fout pin when enabled (EN\_Fout = 1) should be AC coupled using a 100 pF capacitor. This output is a single-ended signal by default. If a differential signal is required, a 50 Ω balun may be connected to this pin to convert it to differential.

The clock outputs are all AC coupled with 0.1 µF capacitors. CLKout1 and CLKout3 are depicted as LVPECL, with 120  $Ω$  emitter resistors as source termination. However, the output format of the clock channels will vary by device part number, so the designer should use the appropriate source termination for each channel. Later sections of this data sheet illustrate alternative methods for AC coupling, DC coupling and terminating the clock outputs.

### **LDO BYPASS AND BIAS PIN**

The LDObyp1 and LDObyp2 pins should be connected to GND through external capacitors, as shown in the diagram. Furthermore, the Bias pin should be connected to  $V_{CC}$  through a 1 µF capacitor in series.

#### **LOOP FILTER**

Each PLL of the LMK04100 family requires a dedicated loop filter. The loop filter for PLL1 must be connected to the CPout1 pin. [Figure](#page-38-1) 13 shows a simple 2-pole loop filter. The output of the filter drives an external VCXO module or discrete implementation of a VCXO using a crystal resonator. Higher order loop filters may be implemented using additional external R and C components. It is recommended the loop filter for PLL1 result in a total closed loop bandwidth in the range of 10 Hz to 200 Hz. The design of the loop filter is application specific and highly dependent on parameters such as the phase noise of the reference clock, VCXO phase noise, and phase detector frequency for PLL1. TI's Clock Conditioner Owner's Manual covers this topic in detail and TI's Clock Design Tool can be used to simulate loop filter designs for both PLLs. These resources may be found: [http://www.ti.com/lsds/ti/analog/clocksandtimers/clocks\\_and\\_timers.page](http://www.ti.com/lsds/ti/analog/clocksandtimers/clocks_and_timers.page).

As shown in the diagram, the charge pump for PLL2 is directly connected to the optional internal loop filter components, which are normally used only if either a third or fourth pole is needed. The first and second poles are implemented with external components. The loop must be designed to be stable over the entire applicationspecific tuning range of the VCO. The designer should note the range of  $K<sub>VCO</sub>$  listed in the table of Electrical Characteristics and how this value can change over the expected range of VCO tuning frequencies. Because loop bandwidth is directly proportional to  $K_{VCO}$ , the designer should model and simulate the loop at the expected extremes of the desired tuning range, using the appropriate values for  $K<sub>VCO</sub>$ .

When designing with the integrated loop filter of the LMK04100 family, considerations for minimum resistor thermal noise often lead one to the decision to design for the minimum value for integrated resistors, R3 and R4. Both the integrated loop filter resistors and capacitors (C3 and C4) also restrict the maximum loop bandwidth. However, these integrated components do have the advantage that they are closer to the VCO and can therefore filter out some noise and spurs better than external components. For this reason, a common strategy is to minimize the internal loop filter resistors and then design for the largest internal capacitor values that permit a wide enough loop bandwidth. In situations where spurs requirements are very stringent and there is margin on phase noise, it might make sense to design for a loop filter with integrated resistor values larger than their minimum value.

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**Figure 13. Loop Filter**

<span id="page-38-1"></span><span id="page-38-0"></span>

#### **Table 34. Typical Current Consumption for Selected Functional Blocks**

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output

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Divider bypassed (CLKout\_MUX =  $0, 2$ )  $0$  0 0  $\vert$  -

Divider enabled, divide > 2 (CLKout\_MUX = 1, 3) 8.5 28 28

High Channel Internal The high channel internal buffer is enabled when one <sup>10</sup> <sup>33</sup> -

Divide circuitry per  $Divider enabled, divide = 2 (CLKout_MUX = 1, 3)$  5.3 17

of CLKout1 through CLKout4 is enabled

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(1) Dynamic power dissipation of LVCMOS buffer varies with output frequency and can be found in the LVCMOS dynamic  $I_{CC}$  vs frequency plot, as shown in CLOCK OUTPUT AC [CHARACTERISTICS.](#page-16-0) Total power dissipation of the LVCMOS buffer is the sum of static and dynamic power dissipation. CLKoutXa and CLKoutXb are each considered an LVCMOS buffer.

(2) Assuming ThetaJ =  $27.4$  °C/W, the total power dissipated on chip must be less than  $40/27.4 = 1450$  mW to quarantee a junction temperature is less than 125 °C.

(3) Worst case power dissipation can be estimated by multiplying typical power dissipation with a factor of 1.2.

# **CURRENT CONSUMPTION / POWER DISSIPATION CALCULATIONS**

Due to the myriad of possible configurations the following table serves to provide enough information to allow the user to calculate estimated current consumption of the device. Unless otherwise noted  $V_{CC} = 3.3 V$ ,  $T_A = 25 °C$ .

From [Table](#page-38-0) 34 the current consumption can be calculated in any configuration. For example, the current for the entire device with 1 LVDS (CLKout0) & 1 LVPECL (CLKout1) output in bypassed mode can be calculated by adding up the following blocks: core current, clock buffer, one LVDS output buffer current, and one LVPECL output buffer current. There will also be one LVPECL output drawing emitter current, but some of the power from the current draw is dissipated in the external 120  $\Omega$  resistors which doesn't add to the power dissipation budget for the device. If divides are switched in, then the additional current for these stages needs to be added as well.

For power dissipated by the device, the total current entering the device is multiplied by the voltage at the device minus the power dissipated in any emitter resistors connected to any of the LVPECL outputs. If no emitter resistors are connected to the LVPECL outputs, this power will be 0 watts. For example, in the case of 1 LVDS (CLKout0) & 1 LVPECL (CLKout1) operating at 3.3 V, we calculate 3.3 V  $\times$  (115 + 10 + 10 + 19.3 + 40) mA = 3.3  $V \times 194.3$  mA = 641.2 mW. Because the LVPECL output (CLKout1) has the emitter resistors hooked up and the power dissipated by these resistors is 50 mW, the total device power dissipation is 641.2 mW - 50 mW = 591.2 mW.

When the LVPECL output is active, ~1.7 V is the average voltage on each output as calculated from the LVPECL V<sub>OH</sub> & V<sub>OL</sub> typical specification. Therefore the power dissipated in each emitter resistor is approximately (1.7 V)<sup>2</sup> / 120  $\Omega$  = 25 mW. When the LVPECL output is disabled, the emitter resistor voltage is ~1.07 V. Therefore the power dissipated in each emitter resistor is approximately (1.07 V)<sup>2</sup> / 120 Ω = 9.5 mW.

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#### **POWER SUPPLY CONDITIONING**

The recommended technique for power supply management is to connect the power pins for the clock outputs (pins 13, 37, 40, 43, and 46) to a dedicated power plane and connect all other power pins on the device (pins 3, 8, 18, 19, 22, 24, 30, 31, and 33) to a second power plane. Note: the LMK04100 family has internal voltage regulators for the PLL and VCO blocks to provide noise immunity.

#### **THERMAL MANAGEMENT**

Power consumption of the LMK04100 family of devices can be high enough to require attention to thermal management. For reliability and performance reasons the die temperature should be limited to a maximum of 125 °C. That is, as an estimate,  $T_A$  (ambient temperature) plus device power consumption times  $\theta_{JA}$  should not exceed 125 °C.

The package of the device has an exposed pad that provides the primary heat removal path as well as excellent electrical grounding to a printed circuit board. To maximize the removal of heat from the package a thermal land pattern including multiple vias to a ground plane must be incorporated on the PCB within the footprint of the package. The exposed pad must be soldered down to ensure adequate heat conduction out of the package. A recommended land and via pattern is shown in [Figure](#page-40-0) 14. More information on soldering WQFN packages can be obtained: [http://www.ti.com/packaging.](http://www.ti.com/packaging)



**Figure 14. Recommended Land and Via Pattern**

<span id="page-40-0"></span>To minimize junction temperature it is recommended that a simple heat sink be built into the PCB (if the ground plane layer is not exposed). This is done by including a copper area of about 2 square inches on the opposite side of the PCB from the device. This copper area may be plated or solder coated to prevent corrosion but should not have conformal coating (if possible), which could provide thermal insulation. The vias shown in [Figure](#page-40-0) 14 should connect these top and bottom copper layers and to the ground layer. These vias act as "heat pipes" to carry the thermal energy away from the device side of the board to where it can be more effectively dissipated.

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**Figure 15. Reference Design Circuit for Crystal Oscillator Option**

# <span id="page-41-0"></span>**OPTIONAL CRYSTAL OSCILLATOR IMPLEMENTATION (OSCin/OSCin\*)**

The LMK04100 family features supporting circuitry for a discretely implemented oscillator driving the OSCin port pins. [Figure](#page-41-0) 15 illustrates a reference design circuit for a crystal oscillator:

This circuit topology represents a parallel resonant mode oscillator design. When selecting a crystal for parallel resonance, the total load capacitance,  $C_L$ , must be specified. The load capacitance is the sum of the tuning capacitance ( $C_{\text{TUNE}}$ ), the capacitance seen looking into the OSCin port ( $C_{\text{IN}}$ ), and stray capacitance due to PCB parasitics  $(C_{\text{STRAY}})$ , and is given by:

$$
C_{L} = C_{\text{TUNE}} + C_{\text{IN}} + \frac{C_{\text{STRAY}}}{2} \tag{1}
$$

 $C_{\text{TIME}}$  is provided by the varactor diode shown in [Figure](#page-41-0) 15, Skyworks model SMV1249-074. A dual diode package with common cathode provides the variable capacitance for tuning. The single diode capacitance ranges from approximately 31 pF at 0.3 V to 3.4 pF at 3 V. The capacitance range of the dual package (anode to anode) is approximately 15.5 pF at 3 V to 1.7 pF at 0.3 V. The desired value of  $V_{\text{TUNE}}$  applied to the diode should be  $V_{\text{CC}}/2$ , or 1.65 V for  $V_{\text{CC}} = 3.3$  V. The typical performance curve from the data sheet for the SMV1249-074 indicates that the capacitance at this voltage is approximately 6 pF (12 pF/2).

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The nominal input capacitance  $(C_{N})$  of the LMK04100 family OSCin pins is 6 pF. The stray capacitance  $(C_{STRAY})$ of the PCB should be minimized by arranging the oscillator circuit layout to achieve trace lengths as short as possible and as narrow as possible trace width (50  $Ω$  characteristic impedance is not required). As an example, assume that  $C_{STRAY}$  is 4 pF. The total load capacitance is nominally:

$$
C_{L} = 6 + 6 + \frac{4}{2} = 14 \text{ pF}
$$

Consequently the load capacitance specification for the crystal in this case should be nominally 14 pF.

The 2.2 nF capacitors shown in the circuit are coupling capacitors that block the DC tuning voltage applied by the 4.7 k and 10 k resistors. The value of these coupling capacitors should be large, relative to the value of  $C_{\text{TUNE}}$  $(C_{C1} = C_{C2} \gg C_{TUNE})$ , so that  $C_{TUNE}$  becomes the dominant capacitance.

For a specific value of  $C_L$ , the corresponding resonant frequency (F<sub>L</sub>) of the parallel resonant mode circuit is:

$$
F_L = F_S \cdot \left\{ \frac{C_1}{2(C_0 + C_{L1})} + 1 \right\} = F_S \cdot \left\{ 2 \left( \frac{C_0}{C_1} + \frac{C_L}{C_1} \right) + 1 \right\}
$$

 $F_S$  = Series resonant frequency

 $C_1$  = Motional capacitance of the crystal

 $C_L$  = Load capacitance

 $C_0$  = Shunt capacitance of the crystal, specified on the crystal datasheet

The normalized tuning range of the circuit is closely approximated by:

$$
\frac{\Delta F}{F} = \frac{F_{CL1} - F_{CL2}}{F_{FCL1}} = \frac{C_1}{2} \cdot \left\{ \frac{1}{(C_0 + C_{L1})} - \frac{1}{(C_0 + C_{L2})} \right\} = \frac{1}{2} \cdot \left\{ \frac{1}{C_0} \frac{C_{L1}}{C_1} + \frac{C_{L2}}{C_1} \right\} - \frac{1}{C_0 \left( \frac{C_0}{C_1} + \frac{C_{L2}}{C_1} \right)} \right\}
$$
(4)

 $C_{L1}$ ,  $C_{L2}$  = The endpoints of the circuit's load capacitance range, assuming a variable capacitance element is one component of the load.  $F_{CL1}$ ,  $F_{CL2}$  = parallel resonant frequencies at the extremes of the circuit's load capacitance range.

A common range for the pullability ratio,  $C_0/C_1$ , is 250 to 280. The ratio of the load capacitance to the shunt capacitance is  $\sim$  (n  $*$  1000), n < 10. Hence, picking a crystal with a smaller pullability ratio supports a wider tuning range because this allows the scale factors related to the load capacitance to dominate.

Example crystal specifications are presented in [Table](#page-42-0) 35.



<span id="page-42-0"></span>

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(3)

(2)

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See [Figure](#page-43-0) 16 for a representative tuning curve.



**Figure 16. Example Tuning Curve, 12.288 MHz Crystal**

The tuning curve achieved in the user's application may differ from the curve shown above due to differences in PCB layout and component selection.

This data is measured on the bench with the crystal integrated with the LMK04100 family. Using a voltmeter to monitor the  $V_{\text{TUNE}}$  node for the crystal, the PLL1 reference clock input frequency is swept in frequency and the resulting tuning voltage generated by PLL1 is measured at each frequency. At each value of the reference clock frequency, the lock state of PLL1 should be monitored to ensure that the tuning voltage applied to the crystal is valid.

The curve shows over the tuning voltage range of 0.17 VDC to 3.0 VDC, the frequency range is  $\pm$  163 ppm; or equivalently, a tuning range of  $\pm$  2000 Hz. The measured tuning voltage at the nominal crystal frequency (12.288) MHz) is 1.4 V. Using the diode data sheet tuning characteristics, this voltage results in a tuning capacitance of approximately 6.5 pF.

<span id="page-43-0"></span>Figure 16. Example Tuning Curve,<br>
v<sub>TUNE</sub> (VDC)<br>
re achieved in the user's application may differ fri<br>
component selection.<br>
assured on the bench with the crystal integrated<br>
w<sub>NE</sub> node for the crystal, the PLL1 reference The tuning curve data can be used to calculate the gain of the oscillator  $(K<sub>VCO</sub>)$ . The data used in the calculations is taken from the most linear portion of the curve, a region centered on the crossover point at the nominal frequency (12.288 MHz). For a well designed circuit, this is the most likely operating range. In this case, the tuning range used for the calculations is  $\pm$  1000 Hz ( $\pm$  0.001 MHz), or  $\pm$  81.4 ppm. The simplest method is to calculate the ratio:

$$
K_{VCO} = \frac{\Delta F}{\Delta V} = \left(\frac{\Delta F_2 - \Delta F_1}{V_{TUNE2} - V_{TUNE1}}\right), \frac{MHz}{V}
$$
  
\n
$$
\Delta F2 \text{ and } \Delta F1 \text{ are in units of MHz. Using data from the curve this becomes:\n0.001 - (-0.001)
$$

ΔF2 and ΔF1 are in units of MHz. Using data from the curve this becomes:

$$
\frac{0.001 - (-0.001)}{2.03 - 0.814} = 0.00164 \frac{\text{MHz}}{\text{V}}
$$
  
A second method uses the tuning data in units of ppm:  

$$
\frac{F_{\text{NOM}} \cdot (\Delta p p m_2 - \Delta p p m_1)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (\Delta p p m_2 - \Delta p p m_1)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (\Delta p p m_2 - \Delta p p m_1)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (\Delta p p m_2 - \Delta p p m_1)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (\Delta p p m_2 - \Delta p p m_1)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (\Delta p p m_2 - \Delta p p m_1)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (\Delta p p m_2 - \Delta p p m_1)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (\Delta p p m_2 - \Delta p p m_1)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (\Delta p p m_2 - \Delta p p m_1)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (\Delta p p m_2 - \Delta p p m_1)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (\Delta p p m_2 - \Delta p p m_1)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (F_{\text{NOM}} \cdot \Delta p p m_2)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (F_{\text{NOM}} \cdot \Delta p p m_2)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (F_{\text{NOM}} \cdot \Delta p p m_2)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (F_{\text{NOM}} \cdot \Delta p p m_2)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (F_{\text{NOM}} \cdot \Delta p p m_2)}{N_{\text{VCO}}} = \frac{F_{\text{NOM}} \cdot (F_{\text{NOM}} \cdot \Delta p p m_2)}{N_{\text{VCO}}} = \frac{F_{\text{
$$

A second method uses the tuning data in units of ppm:

$$
K_{VCO} = \frac{F_{NOM} \cdot (\Delta p p m_2 - \Delta p p m_1)}{\Delta V \cdot 10^6}
$$
 (7)

$$
\frac{12.288 \cdot (81.4 - (-81.4))}{(2.03 - 0.814) \cdot 10^6} = 0.00164, \frac{\text{MHz}}{\text{V}}
$$

(8)

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**NSTRUMENTS** 



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In order to ensure startup of the oscillator circuit, the equivalent series resistance (ESR) of the selected crystal should conform to the specifications listed in the table of Electrical Characteristics. It is also important to select a crystal with adequate power dissipation capability, or drive level. If the drive level supplied by the oscillator exceeds the maximum specified by the crystal manufacturer, the crystal will undergo excessive aging and possibly become damaged. Drive level is directly proportional to resonant frequency, capacitive load seen by the crystal, voltage and equivalent series resistance (ESR).

For more complete coverage of crystal oscillator design, see Application Note AN-1939: [SNAA065.](http://www.ti.com/lit/pdf/snaa065)

## **ADDITIONAL OUTPUTS WITH AN LMK04100 FAMILY DEVICE**

The number of outputs on a LMK04100 family device can be expanded in many ways. The first method is to use the differential outputs as two single-ended outputs. For CMOS outputs, both the positive and negative outputs can be programmed to be in phase, or 180 degrees out of phase. LVDS/LVPECL positive and negative outputs are always 180 degrees out of phase. LVDS single-ended is not recommended.

In addition to this technique, the number of outputs can be expanded with a LMK01000 family device. To do this, one of the clock outputs of a LMK04100 can drive the LMK01000 device.

For more information on phase synchronization with multiple devices, please refer to application note AN-1864: [SNAA060.](http://www.ti.com/lit/pdf/snaa060)



# **PACKAGING INFORMATION**







**(1)** The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures. "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

**(3)** MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

**(4)** There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

**(5)** Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

**(6)** Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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**TEXAS** 

### **TAPE AND REEL INFORMATION**

**ISTRUMENTS** 





#### **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**





# **PACKAGE MATERIALS INFORMATION**



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# **PACKAGE MATERIALS INFORMATION**

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# **PACKAGE OUTLINE**

# **RHS0048A WQFN - 0.8 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



# **EXAMPLE BOARD LAYOUT**

# **RHS0048A WQFN - 0.8 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD



4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



# **EXAMPLE STENCIL DESIGN**

# **RHS0048A WQFN - 0.8 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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