

# Topic 6

## Using PMBus for Improved System-Level Power Management

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# Agenda

- ◆ **PMBus overview**
- ◆ Some tasks and PMBus solutions
- ◆ Brief design example

# Evolution

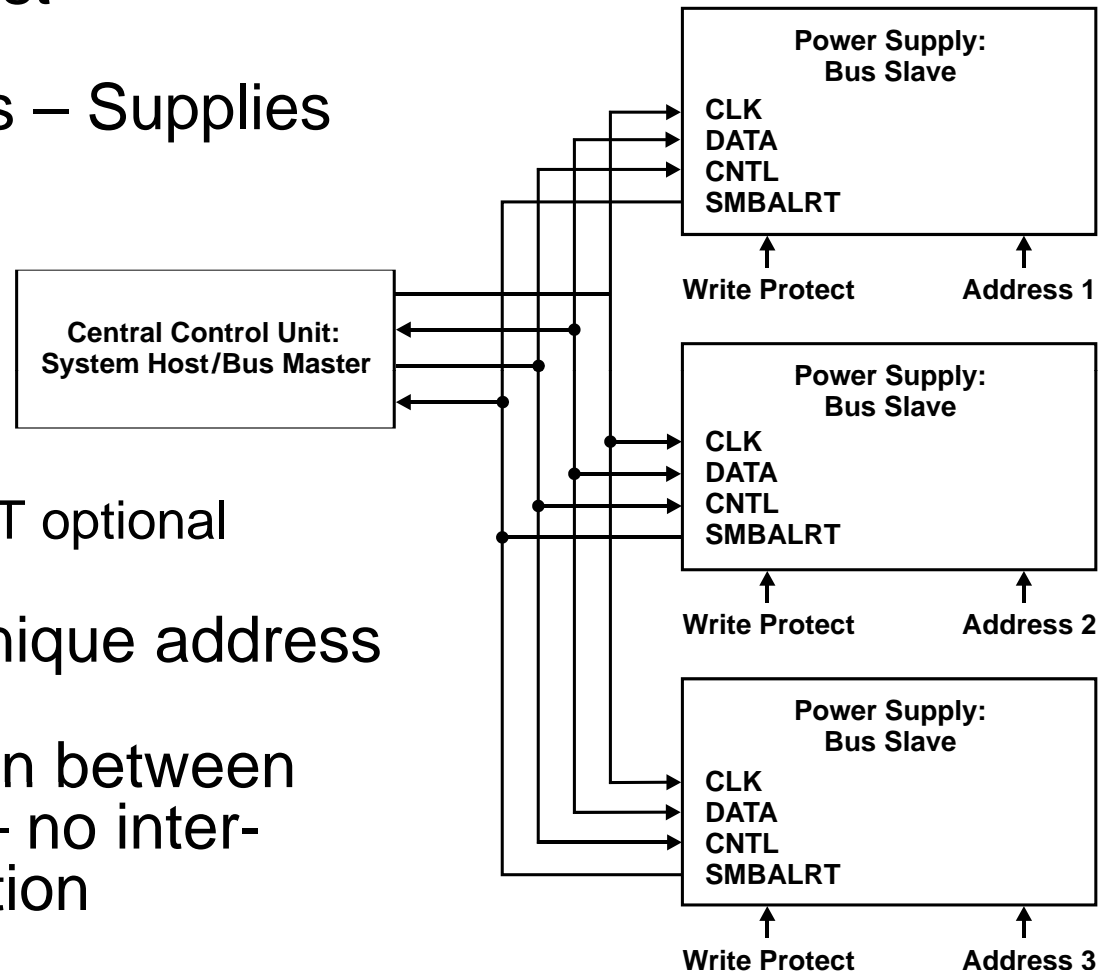
- ◆ Newer systems require more advanced capabilities
- ◆ Supplies evolving in:
  - Size and integration
  - Functionality
  - Flexibility
  - Monitoring and control
- ◆ PMBus is an answer

# What is PMBus?

- ◆ Open standard
  - Serial interface to controller
    - ◆ Electrical specification protocol and command language
  - Anyone can use – royalty free
  - Controlled by Special Interest Group (SIG):
    - ◆ [www.pmbus.org](http://www.pmbus.org)
- ◆ Communication only
  - No form factor
  - No I/O specification
  - No specific functionality requirement
  - No pinout
- ◆ Implementation of the physical supply is completely open

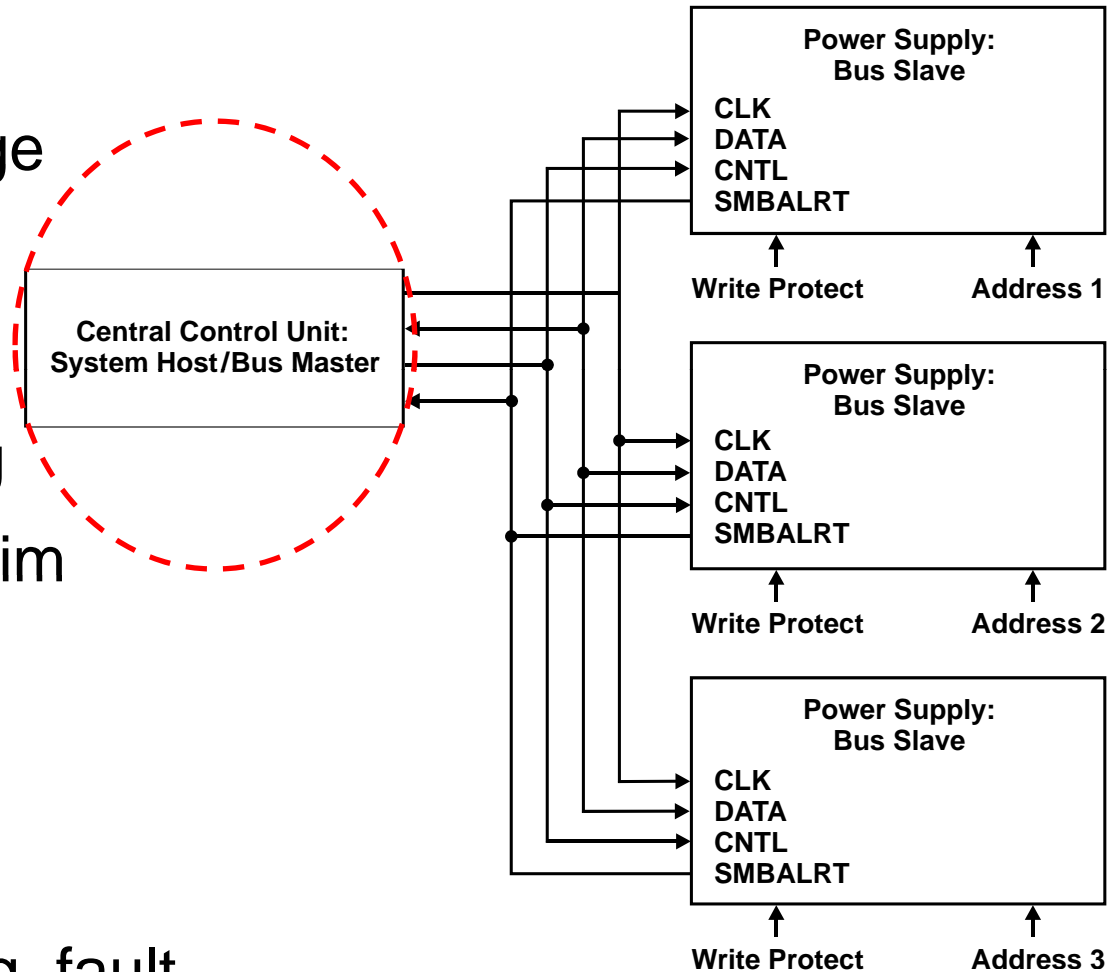
# Typical PMBus System

- ◆ Single master – Host
- ◆ One or more slaves – Supplies
- ◆ Bus:
  - CLOCK and DATA required
  - CNTL and SMBALRT optional
- ◆ Each device has unique address
- ◆ Only communication between host and supplies – no inter-supply communication



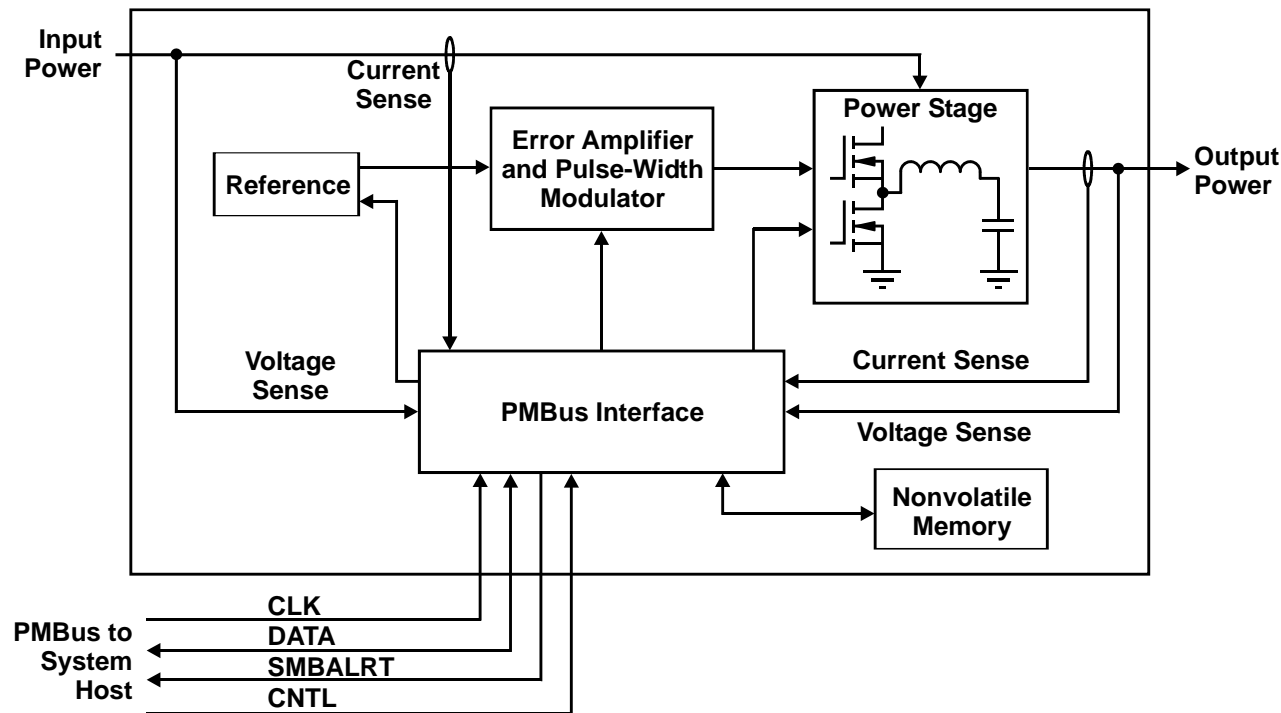
# What is the Host?

- ◆ PC
  - Development stage
- ◆ Automatic Test Equipment
  - Production testing
  - Final parameter trim
- ◆ Microcontroller/  
Microprocessor
  - In the field
  - Power sequencing, fault management, etc.

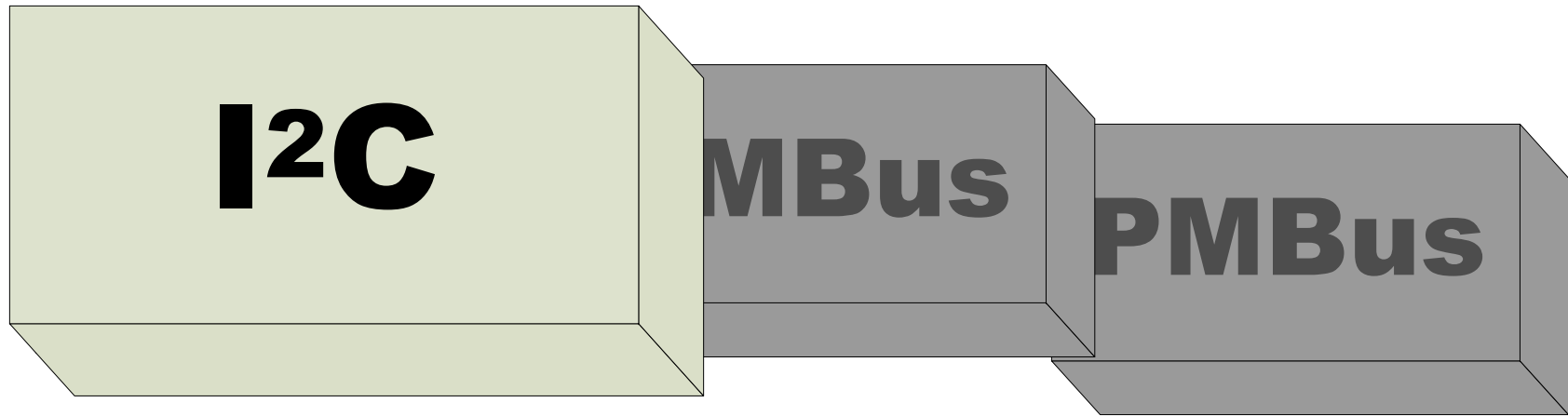


# PMBus-Converter Architecture

- ◆ Similar to standard controller
- ◆ PMBus interface add-on is typical
  - Hooks into controller for PMBus functions
- ◆ NVRAM
  - Store operating parameters, user data, etc.



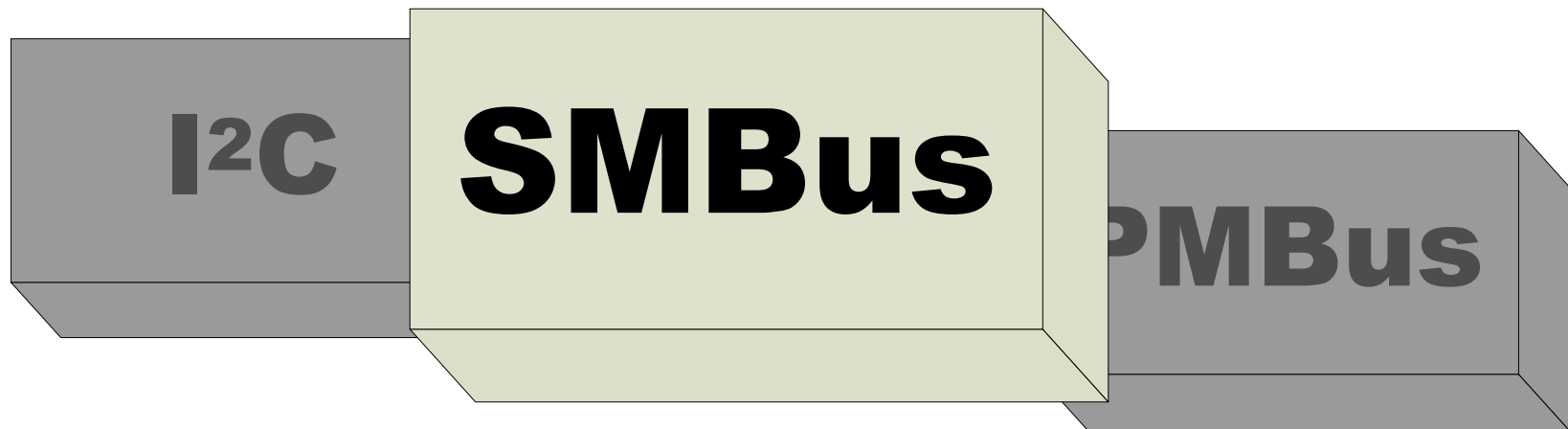
# Ancestry of PMBus



- ◆ Inter-Integrated Circuit – Philips development
- ◆ Simple serial 2-wire bus
- ◆ Vulnerable
  - Excessive clock stretching causing bus lockup
  - No standard error check

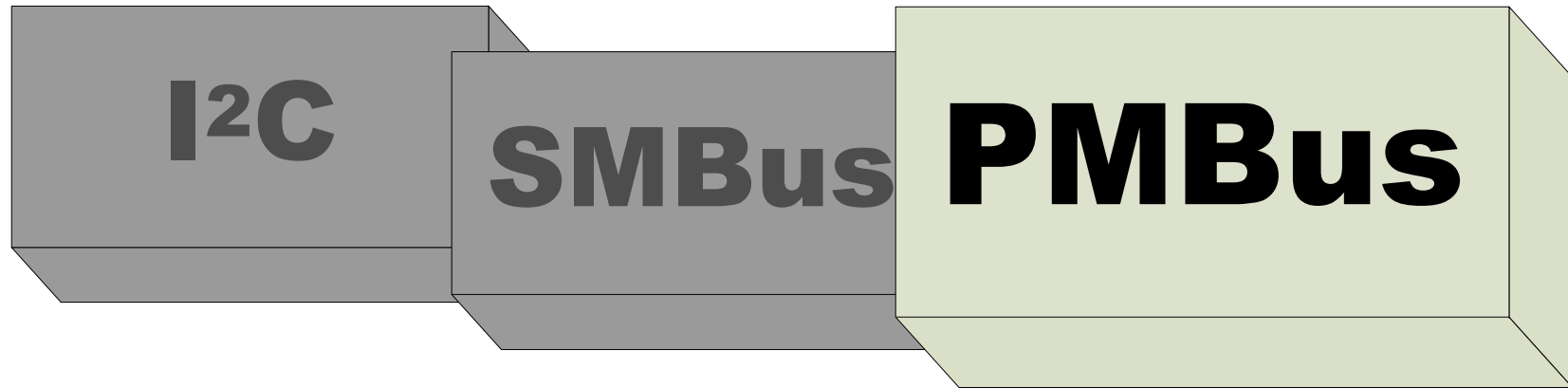


# Ancestry of PMBus



- ◆ System Management Bus – [www.smbus.org](http://www.smbus.org)
- ◆ Fixes bus lockup from clock stretching issues
  - Bus times out and resets
- ◆ Standard error checking defined
- ◆ Host-notify protocol defined
  - Slave device can alert master when needed

# Ancestry of PMBus



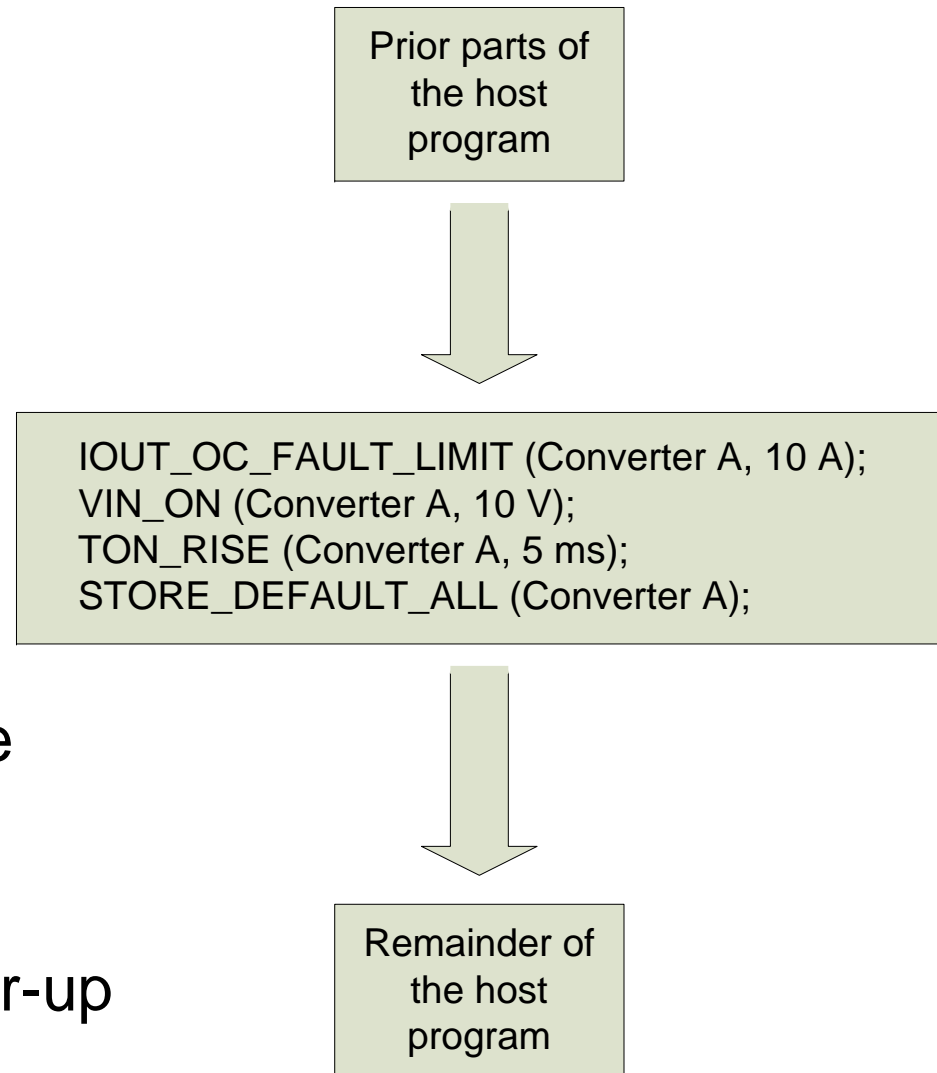
- ◆ Power Management Bus – [www.pmbus.org](http://www.pmbus.org)
- ◆ Outgrowth of SMBus
- ◆ Notable differences
  - Host-notify protocol is optional
  - Group-command protocol
    - ◆ Multiple devices can execute commands at the same time

# PMBus Compliance

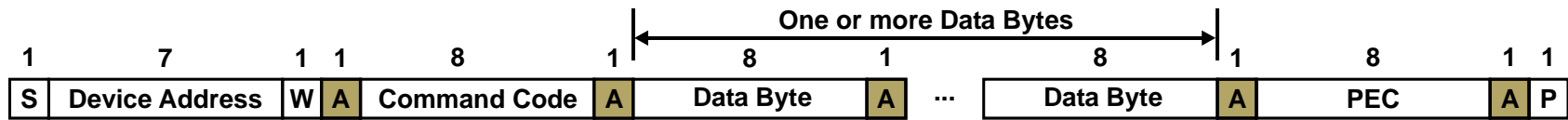
- ◆ PMBus specification is in two parts
- ◆ Compliant converters must:
  - Meet all Part I specifications
    - ◆ Hardware interface (electrical, timing)
  - Implement at least one command
    - ◆ Other than manufacturer specific
  - Supported commands must comply with Part II of the specification
    - ◆ Command language
  - Non-supported command
    - ◆ Respond according to Part II
- ◆ Also:
  - Must be able start without PMBus communication

# Usage Mechanics

- ◆ Not hard!
- ◆ Simple sequential commands
- ◆ Example sets converter's:
  - Overcurrent limit
  - Input turn-on voltage
  - Soft-start time
  - Parameters to power-up defaults



# PMBus Command



- ◆ PMBus command is fairly simple
- ◆ START and STOP conditions have DATA-change state while CLK is high.
  - Normal transfer: DATA is stable while CLK is high

# Types of Commands Available

## ◆ On, off, and margin testing

- ◆ Output voltage related
- ◆ Addressing, memory communication, and capability
- ◆ Fault handling
- ◆ Sequencing
- ◆ Status
- ◆ Telemetry
- ◆ Other

## ◆ Deal with turning converter on and off, output margining

## ◆ Commands in group:

- OPERATION
- ON\_OFF\_CONFIG
- VOUT\_MARGIN\_HIGH
- VOUT\_MARGIN\_LOW

# Types of Commands Available

- ◆ On, off, and margin testing
- ◆ **Output voltage related**
- ◆ Addressing, memory communication, and capability
- ◆ Fault handling
- ◆ Sequencing
- ◆ Status
- ◆ Telemetry
- ◆ Other
- ◆ Commands affect the output voltage of the converter
- ◆ Commands in group:
  - VOUT\_COMMAND
  - VOUT\_TRIM
  - VOUT\_CAL\_OFFSET
  - VOUT\_SCALE\_LOOP

# Types of Commands Available

- ◆ On, off, and margin testing
- ◆ Output voltage related
- ◆ **Addressing, memory communication, and capability**
- ◆ Fault handling
- ◆ Sequencing
- ◆ Status
- ◆ Telemetry
- ◆ Other
- ◆ Deal with device addressing, memory, communication, and capability of the converter
- ◆ Commands in group:
  - STORE\_DEFAULT\_ALL
  - STORE\_DEFAULT\_CODE
  - PHASE, PAGE
  - WRITE\_PROTECT



# Types of Commands Available

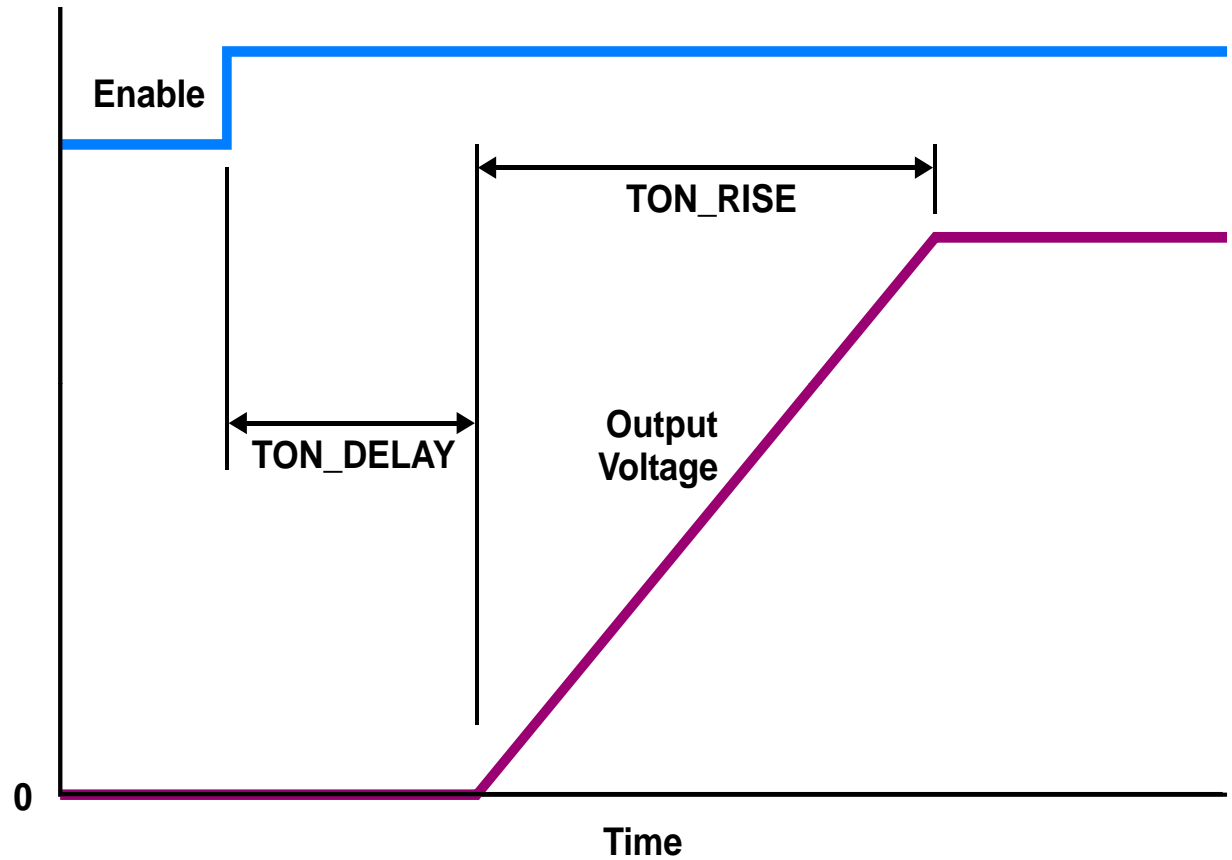
- ◆ On, off, and margin testing
- ◆ Output voltage related
- ◆ Addressing, memory communication, and capability
- ◆ **Fault handling**
- ◆ Sequencing
- ◆ Status
- ◆ Telemetry
- ◆ Other
- ◆ Determine how converter responds to faults
- ◆ Defines what fault and warning levels are
- ◆ Commands in group:
  - IOUT\_OC\_WARN\_LIMIT
  - IOUT\_OC\_FAULT\_LIMIT
  - IOUT\_OC\_FAULT\_RESPONSE
  - Many others

# Types of Commands Available

- ◆ On, off, and margin testing
  - ◆ Output voltage related
  - ◆ Addressing, memory communication, and capability
  - ◆ Fault handling
  - ◆ **Sequencing**
  - ◆ Status
  - ◆ Telemetry
  - ◆ Other
- ◆ Deals with timing of startup and shutdown
  - ◆ Commands in group:
    - TON\_DELAY
    - TON\_RISE
    - TOFF\_DELAY
    - TOFF\_FALL

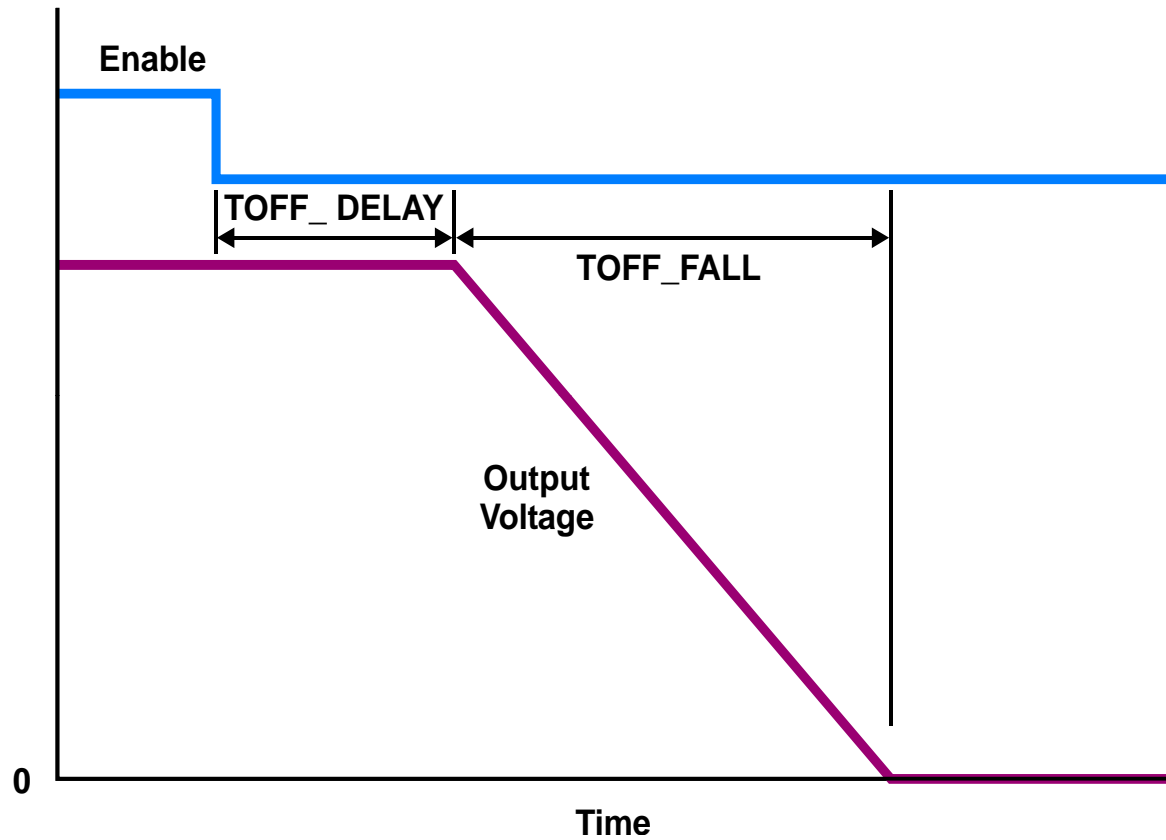
# Power-On Sequencing

- ◆ Enable
- CNTL
- VIN\_ON
- OPERATION



# Power-Off Sequencing

- ◆ Enable
- CNTL
- VIN\_OFF
- OPERATION

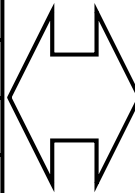


# Types of Commands Available

- ◆ On, off, and margin testing
- ◆ Output voltage related
- ◆ Addressing, memory communication, and capability
- ◆ Fault handling
- ◆ Sequencing
- ◆ **Status**
- ◆ Telemetry
- ◆ Other
- ◆ Information about status of converter
- ◆ Commands in group:
  - STATUS\_BYTE
  - STATUS\_WORD
  - STATUS\_IOUT
  - STATUS\_CML

# STATUS\_BYTE and STATUS\_WORD

STATUS_WORD	
High Byte	
7-	VOUT
6-	IOUT/POUT
5-	INPUT
4-	MFR
3-	POWER_GOOD
2-	FANS
1-	OTHER
0-	UNKNOWN
Low Byte	
7-	BUSY
6-	OFF
5-	VOUT_OV
4-	IOUT_OC
3-	VIN_UV
2-	TEMPERATURE
1-	CML
0-	None of the above



- ◆ STATUS\_BYTE part of STATUS\_WORD
- ◆ Most flags have more detailed status commands

STATUS_BYTE	
7-	BUSY
6-	OFF
5-	VOUT_OV
4-	IOUT_OC
3-	VIN_UV
2-	TEMPERATURE
1-	CML
0-	None of the above

# Types of Commands Available

- ◆ On, off, and margin testing
- ◆ Output voltage related
- ◆ Addressing, memory communication, and capability
- ◆ Fault handling
- ◆ Sequencing
- ◆ Status
- ◆ **Telemetry**
- ◆ Other
- ◆ Report back converter operating conditions
- ◆ Commands in group:
  - READ\_VIN
  - READ\_VOUT
  - READ\_IIN
  - READ\_IOUT
  - READ\_DUTY\_CYCLE
  - READ\_FREQUENCY
  - Several others

# Types of Commands Available

- ◆ On, off, and margin testing
  - ◆ Output voltage related
  - ◆ Addressing, memory communication, and capability
  - ◆ Fault handling
  - ◆ Sequencing
  - ◆ Status
  - ◆ Telemetry
  - ◆ **Other**
- ◆ Commands that don't really fit elsewhere:
    - FREQUENCY\_SWITCH
    - VIN\_ON
    - VIN\_OFF
    - IOUT\_CAL\_GAIN
    - IOUT\_CAL\_OFFSET
  - ◆ Other classes not mentioned:
    - Manufacturer data
    - User data



# Agenda

- ◆ PMBus overview
- ◆ **Some tasks and PMBus solutions**
- ◆ Brief design example

# PMBus in the System

- ◆ Converter may not support all PMBus commands
- ◆ Consider tasks needed
  - Match capability to task requirements
- ◆ For example
  - Sequencing
  - Margining
  - Monitoring, etc.

# Sequencing

- ◆ Several ways to accomplish with PMBus facilities:

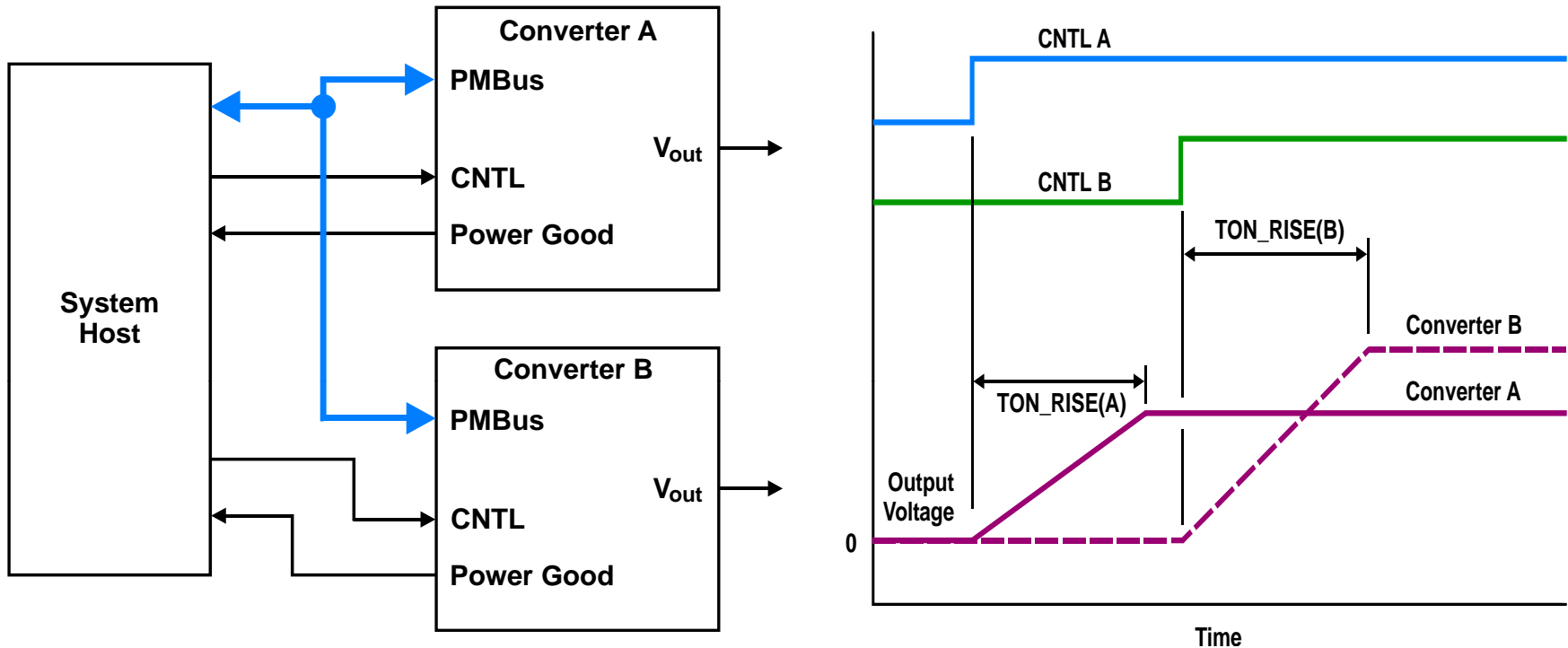
- Remote enable

- ◆ CNTRL pin
- ◆ OPERATION command

- Time delay

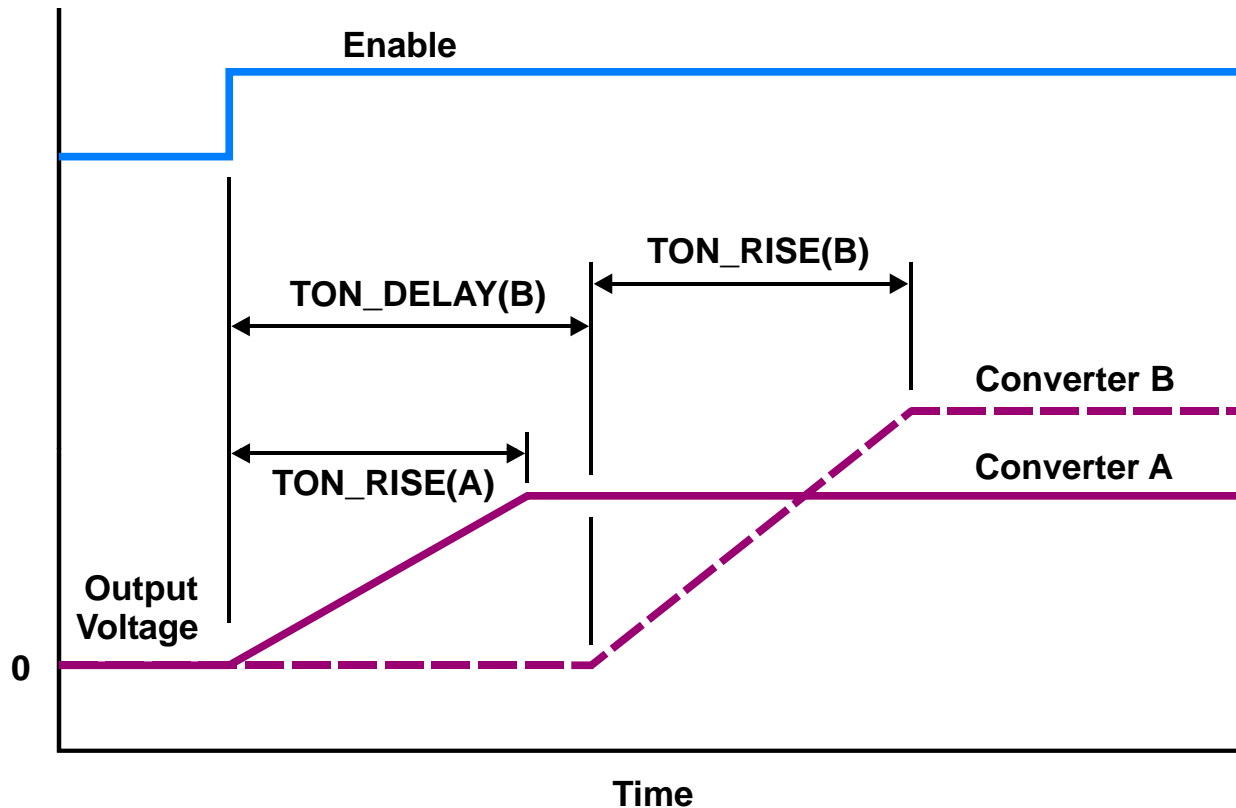
- Open-loop tracking

# Remote Enable



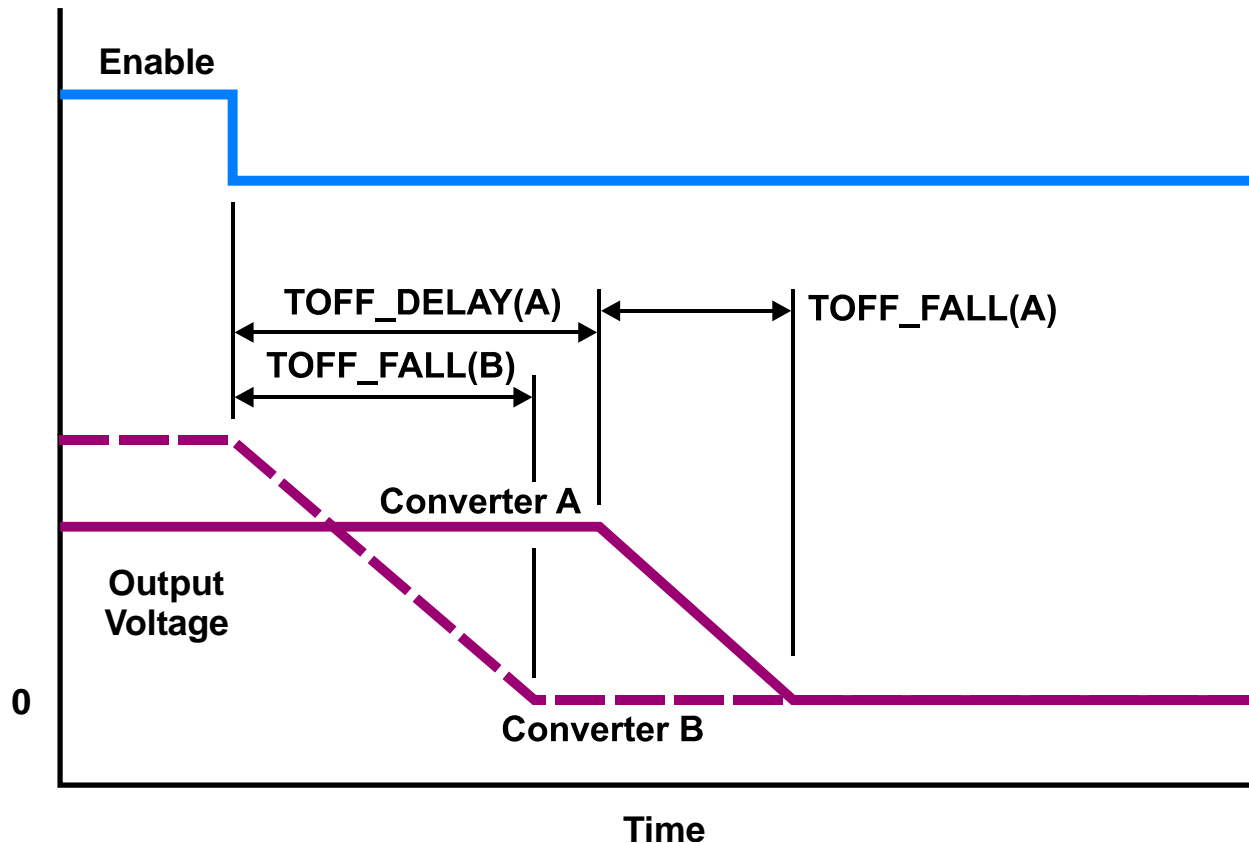
- ◆ Simple – not really PMBus solution
- ◆ CNTL is like ENABLE pin
- ◆ Controlled individually – conventional
- ◆ Similar operation possible using OPERATION commands over PMBus

# Time-Delay Sequencing



- ◆ Converters programmed with startup delay ( $TON\_RISE$ )
- ◆ Enabled simultaneously
- ◆ Eases burden on system host

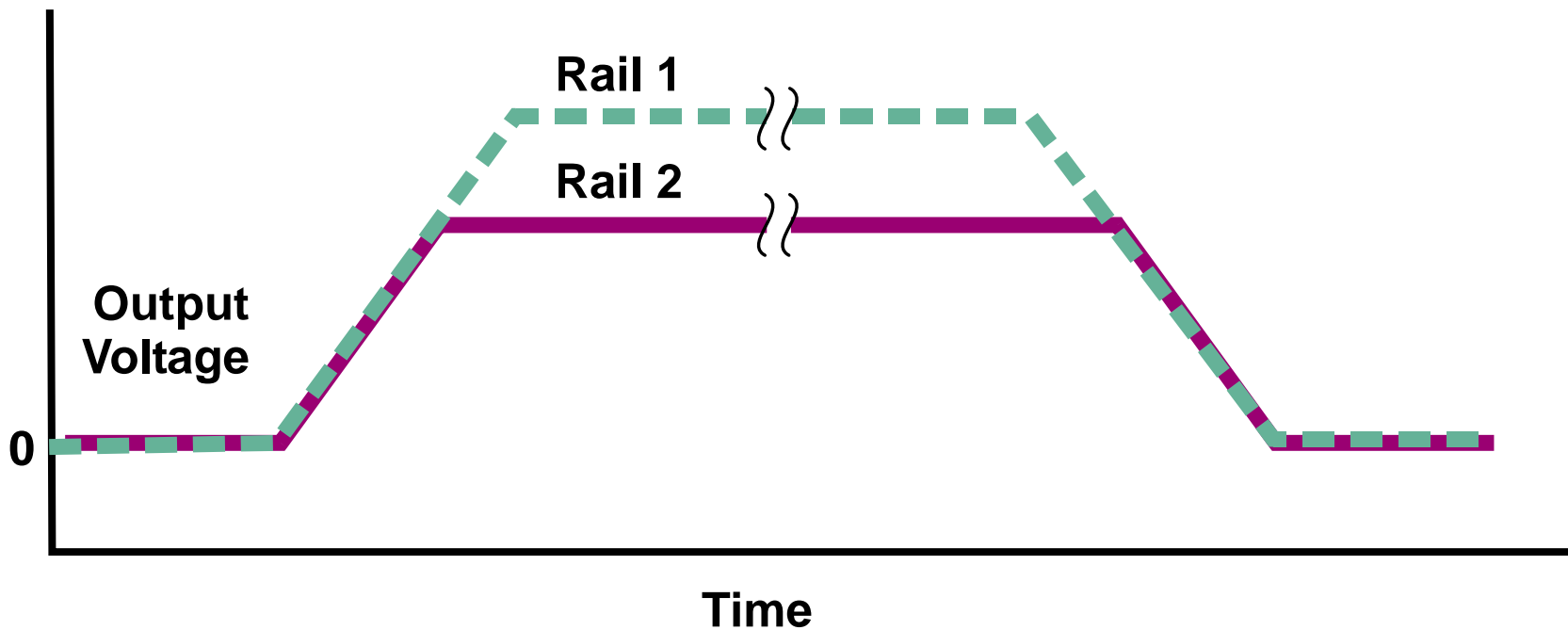
# Time-Delay Off



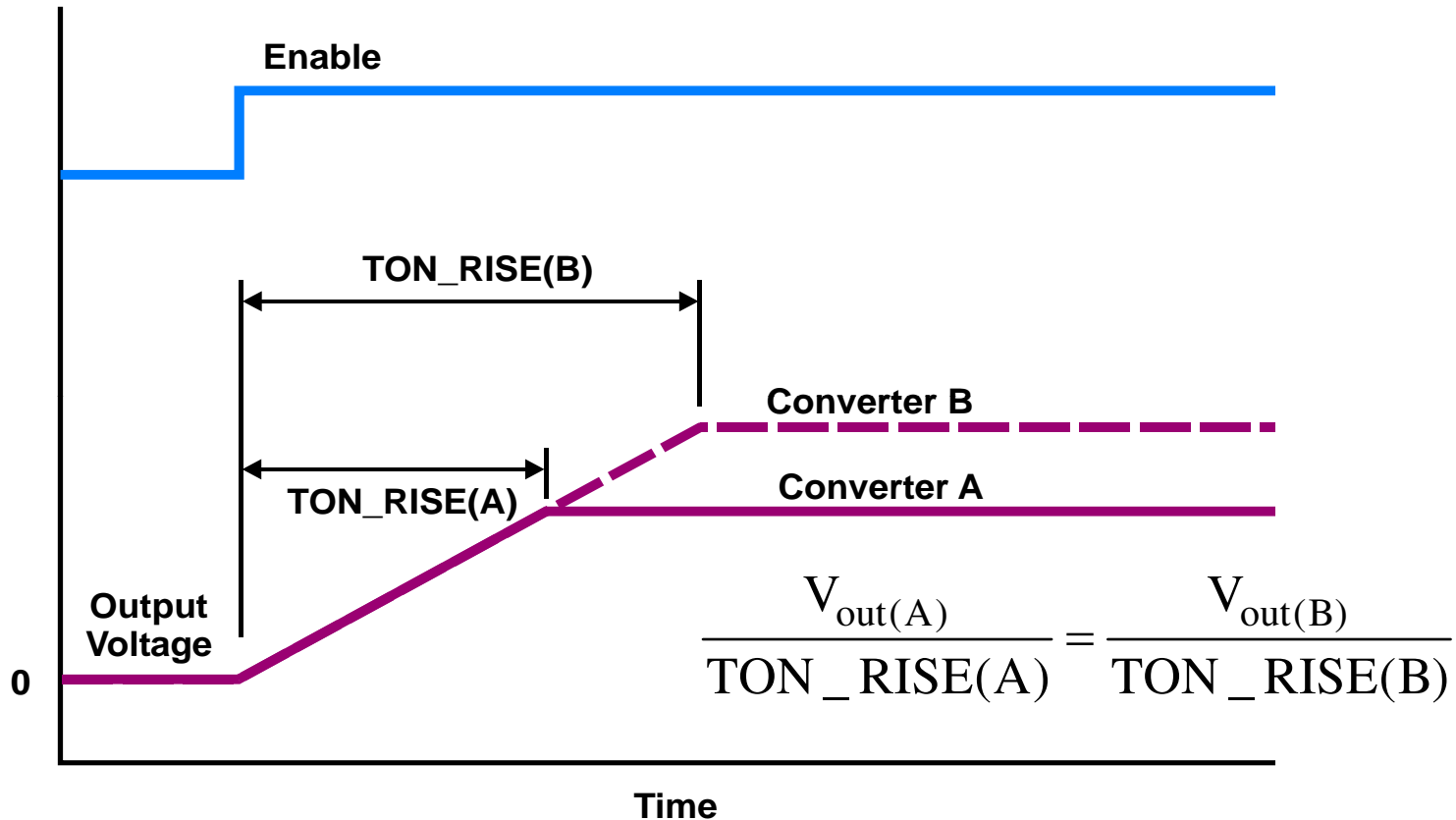
- ◆ Similar to previous – using  $TOFF\_DELAY$
- ◆ Watch fall times if  $TOFF\_FALL$  not supported
- ◆ Both converters disabled simultaneously

# Tracking

- ◆ Startup methodology keeping multiple-voltage rails close
  - Startup
  - Possibly shutdown
  - Startup and shutdown only here - Not for DDR



# PMBus-Tracking Startup



- ◆ Set slopes of rise times equal
- ◆ Requires very fine control of TON\_RISE

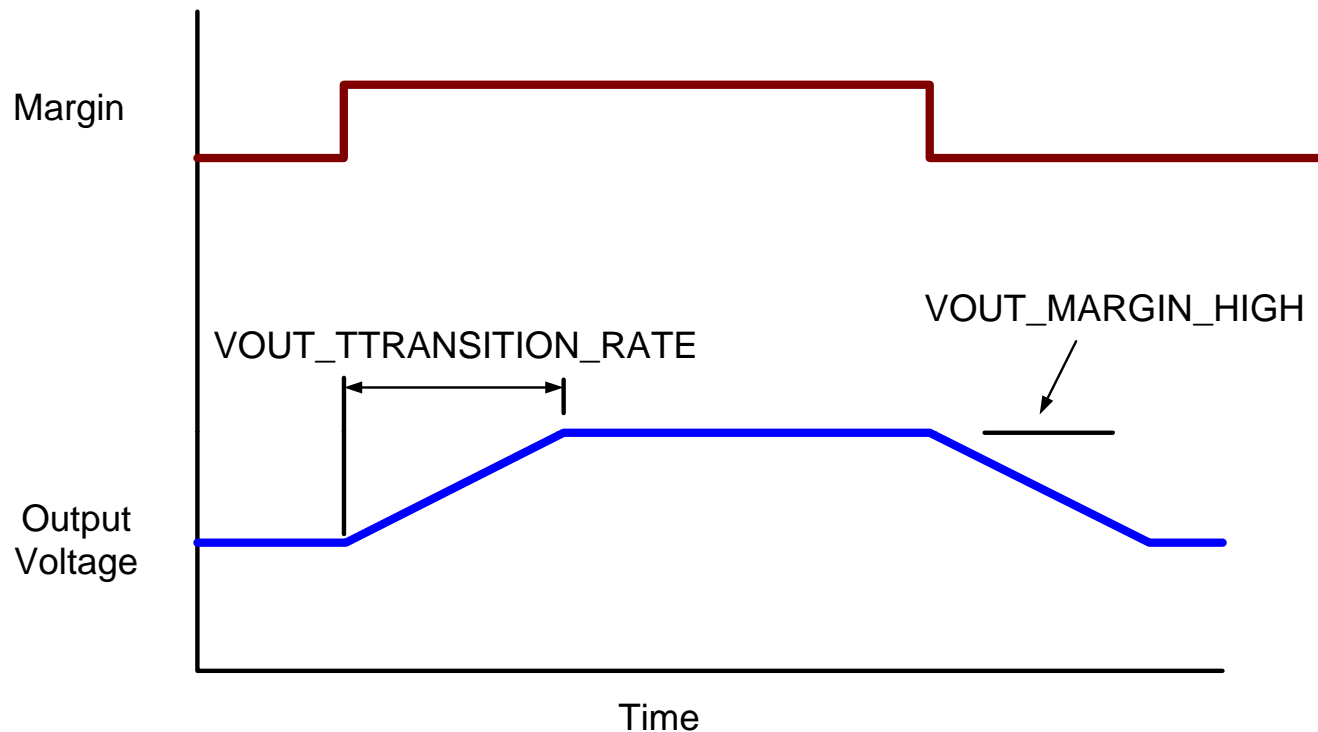




# Margining

- ◆ Vary output voltages to test system
  - Requires either
    - ◆ Converter support
    - ◆ External device(s) to implement
- ◆ PMBus support
  - Variable margin voltages
  - Variable transition rate
  - Programmable fault response during margin
- ◆ Set margin voltages and use OPERATION command to execute

# Margin Illustrated



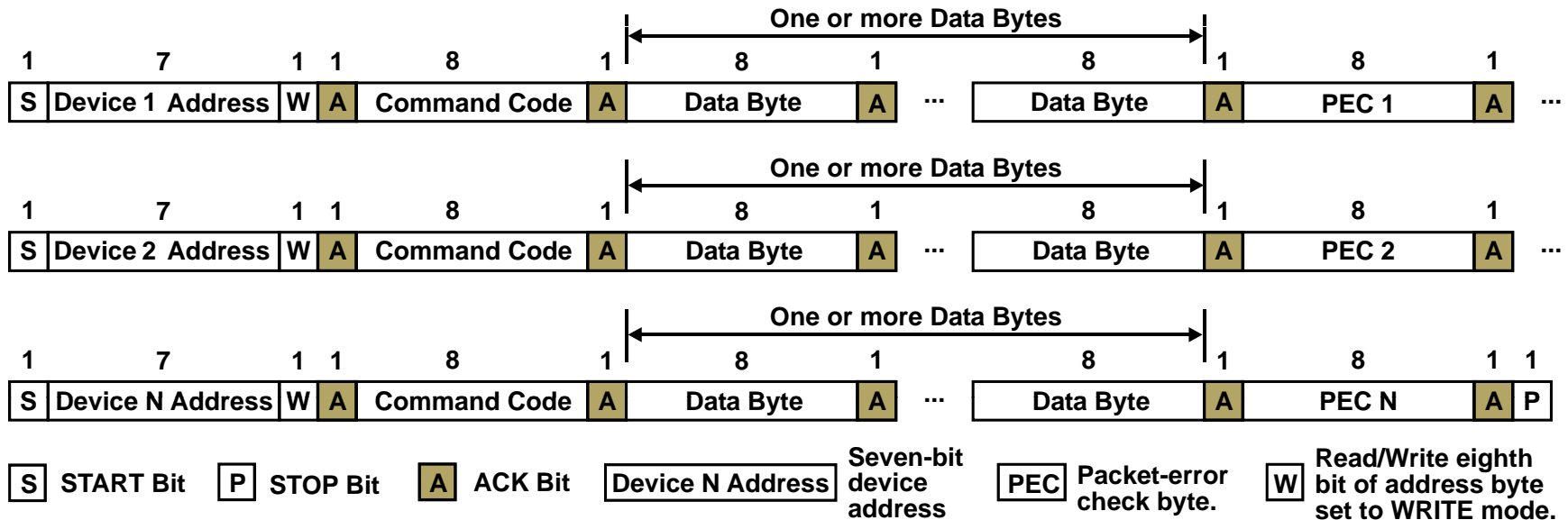
- ◆ Margin initiated using OPERATION command
- ◆ Transition rate and margin voltage are variable
- ◆ Much more flexible than hardware solution

# Timing Issue

- ◆ How to synchronize PMBus commands
  - Startup/tracking require known timing relationships
  - Serial bus not inherently good
  - PMBus solution:

## Group Command Protocol

# PMBus Group Command



- ◆ Like single command except:
  - No STOP after first command
  - START repeats and next command is issued
  - STOP issued after final command
  - Commands simultaneously executed after the STOP

# PMBus Group Command

Group command caveats:

1. No more than one command in a group can be addressed to a single slave device
2. No command in the group can require the slave to respond over the PMBus

## Other Uses of PMBus

- ◆ Change system power parameters
  - Factory or field
  - No hardware modification
- ◆ Accidental overvoltage protection
  - Inadvertent/erroneous command
- ◆ System monitoring
- ◆ Compensation and capacitive loading
- ◆ Fault and incident tracking

# Agenda

- ◆ PMBus overview
- ◆ Some tasks and PMBus solutions
- ◆ **Brief design example**



# Design Example

- ◆ Important: Not all converters support all functions
- ◆ Determine necessary functions
- ◆ Select converter or controller accordingly

# Target Specifications

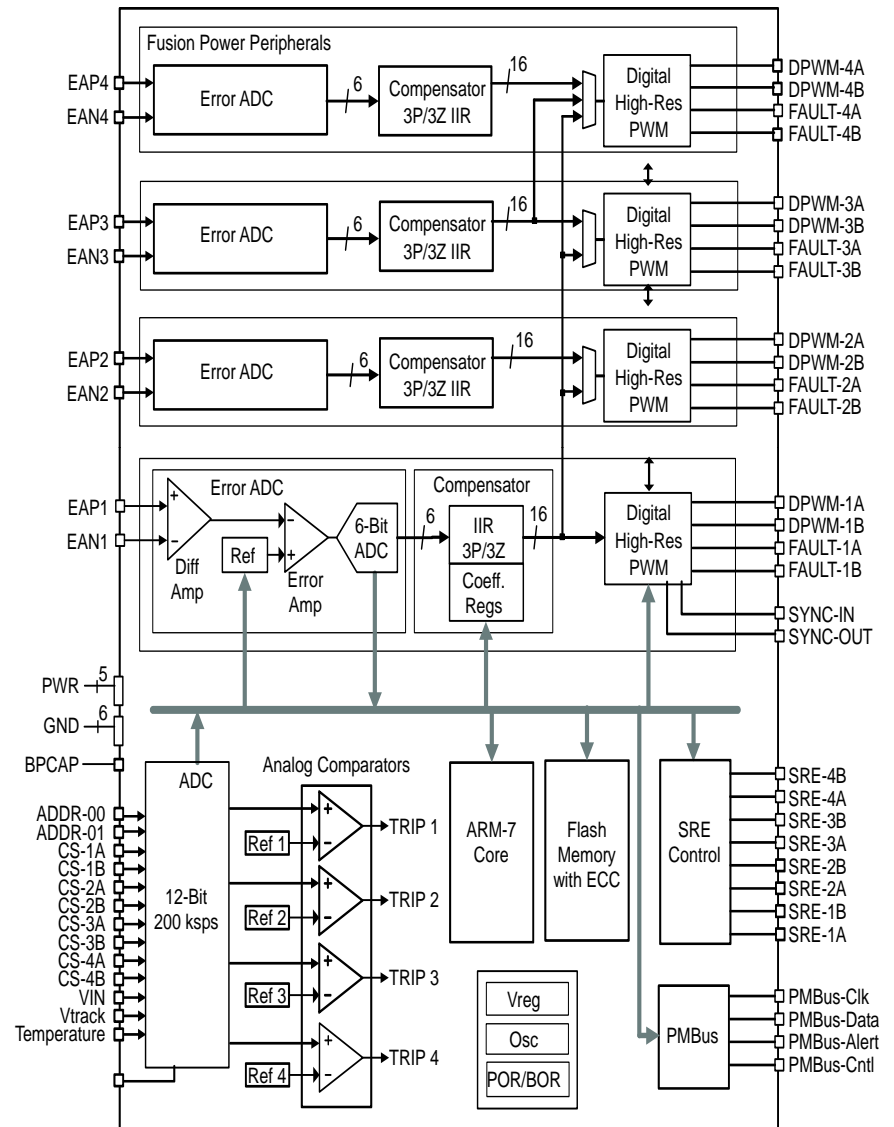
- ◆ Power supply for two processors in communications rack
  - Core and I/O for each
- ◆ Input voltage: 12 V
- ◆ Core output voltage: 1.2 V at 10 A per processor
  - Must be able to change from 1.1 V to 1.2 V
- ◆ I/O output voltage: 3.3 V at 3 A per processor
- ◆ Sequencing required: Core up first, then I/O's
- ◆ Margin testing support for field and factory
- ◆ Output voltage and current monitoring
- ◆ Minimal cost

# PMBus Features Required

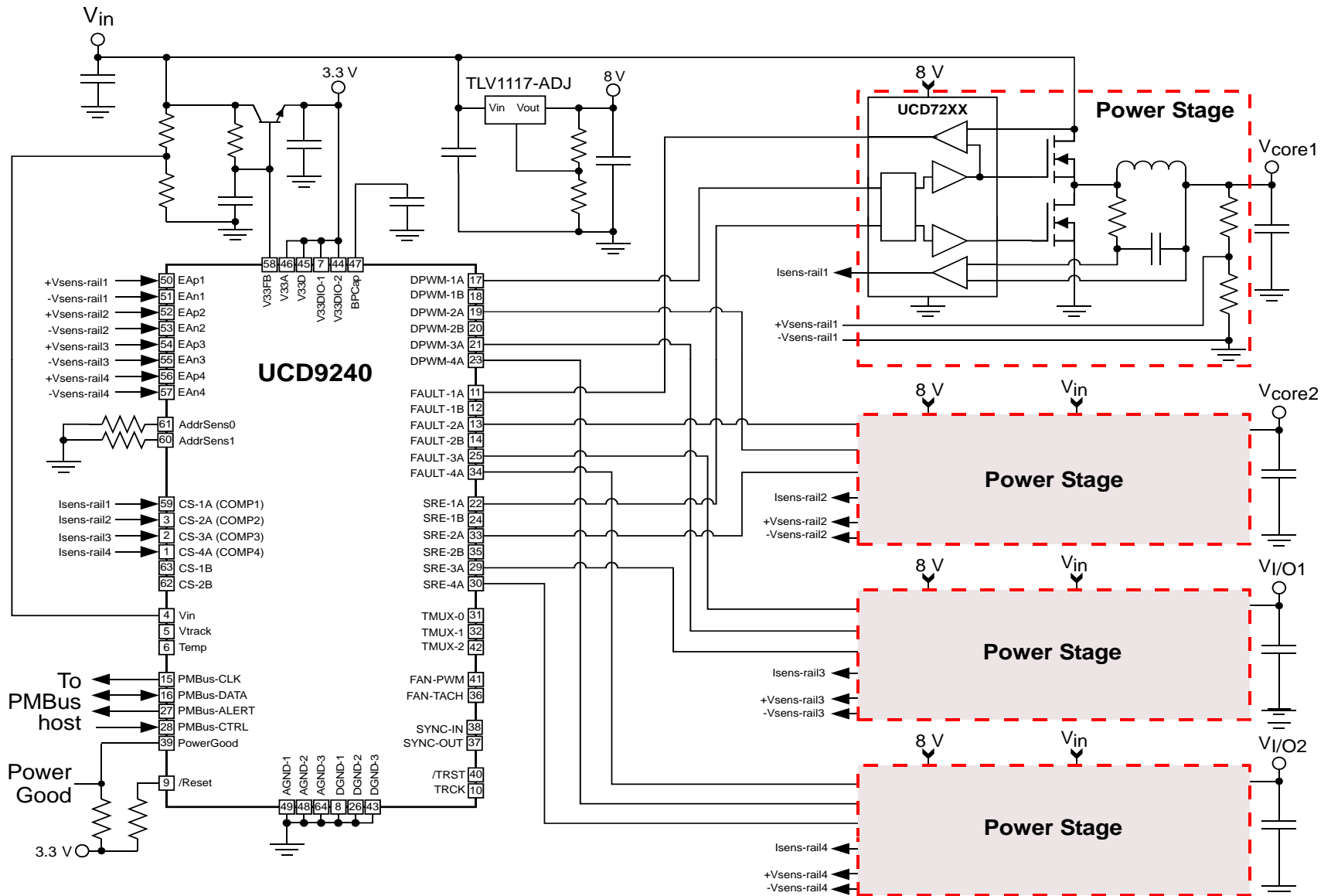
- ◆ Nonvolatile memory
  - Store default operating parameters
- ◆ Power-on sequencing
  - TON\_DELAY
- ◆ VOUT\_TRIM command
  - To adjust nominal output voltage on cores
- ◆ Margin commands
  - VOUT\_MARGIN\_HIGH, VOUT\_MARGIN\_LOW, OPERATION
  - VOUT\_TRANSITION\_RATE nice to have
- ◆ READ\_VOUT, READ\_IOUT
  - Monitor output power
  - READ\_POUT would work too

# Proposed Solution

- ◆ UCD9240
- ◆ Digital PMBus controller
- ◆ Features
  - Up to 4 independent rail control
  - $\pm 1$ -mV feedback resolution
  - Hardware accelerated digital compensator
  - 12-bit monitoring of supply parameters
  - Programmable softstart and stop
  - Nonvolatile memory with ECC
  - Supports voltage tracking
  - Programmable margining and sequencing
  - PC-based design tools



# Proposed Solution



# Conclusions

- ◆ PMBus as a standard supports a wide range of functionality
- ◆ Many system-level tasks can be accomplished by the facilities provided by PMBus
- ◆ Converters won't generally fully support PMBus command set
  - Match system requirements to converter capability