

Redefining **high resolution and low noise** in Delta-Sigma ADC applications



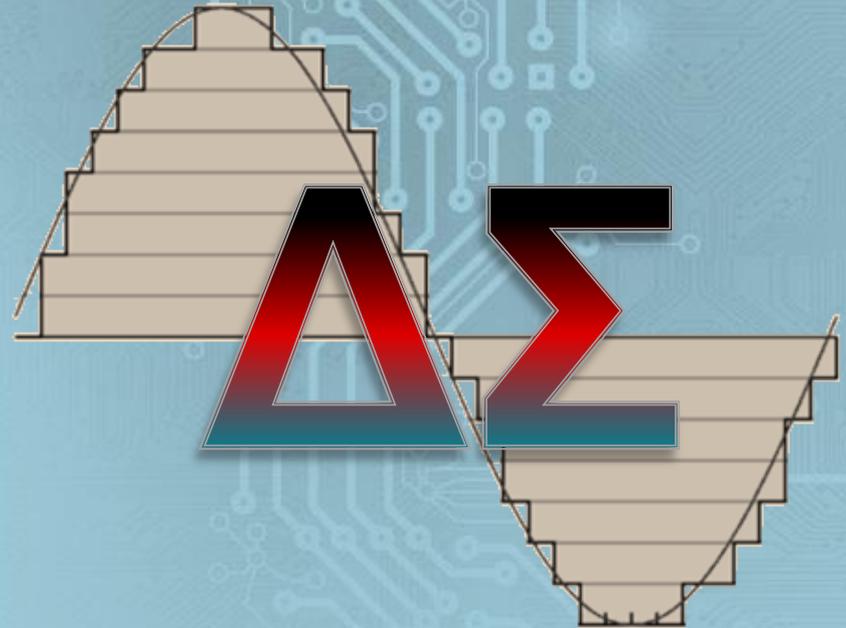
Agenda

Redefining high resolution and low noise in Delta-Sigma ADC applications

- **How do Precision Delta-Sigma ($\Delta\Sigma$) ADCs work?**
- **Introduction to the ADS1262 & ADS1263**
- **Common Application Circuits using the ADS126xEVM**
 - 3-/4-Wire RTDs
 - 3-/4-Wire RTD Pitfalls
 - Load Cells
 - Load Cell Pitfalls
- **How to use the ADS1262 and ADS1263 monitoring and diagnostic features**
- **Coming Soon... PLC reference design**
- **Additional Information**

Precision **Delta-Sigma** ADC Basics

Why is this a high resolution, low noise ADC architecture?



First, what do **Precision $\Delta\Sigma$ ADCs** do?

Temperature
Measurement



Pressure
Measurement



Vibration / Flow
Measurement



Power / Harmonics
Measurement



- High resolution + low noise
- Offer wide dynamic range
- Measure slow-moving signals
- Often application-specific

PLC / DCS
Systems



Seismic Data
Acquisition



Test &
Measurement

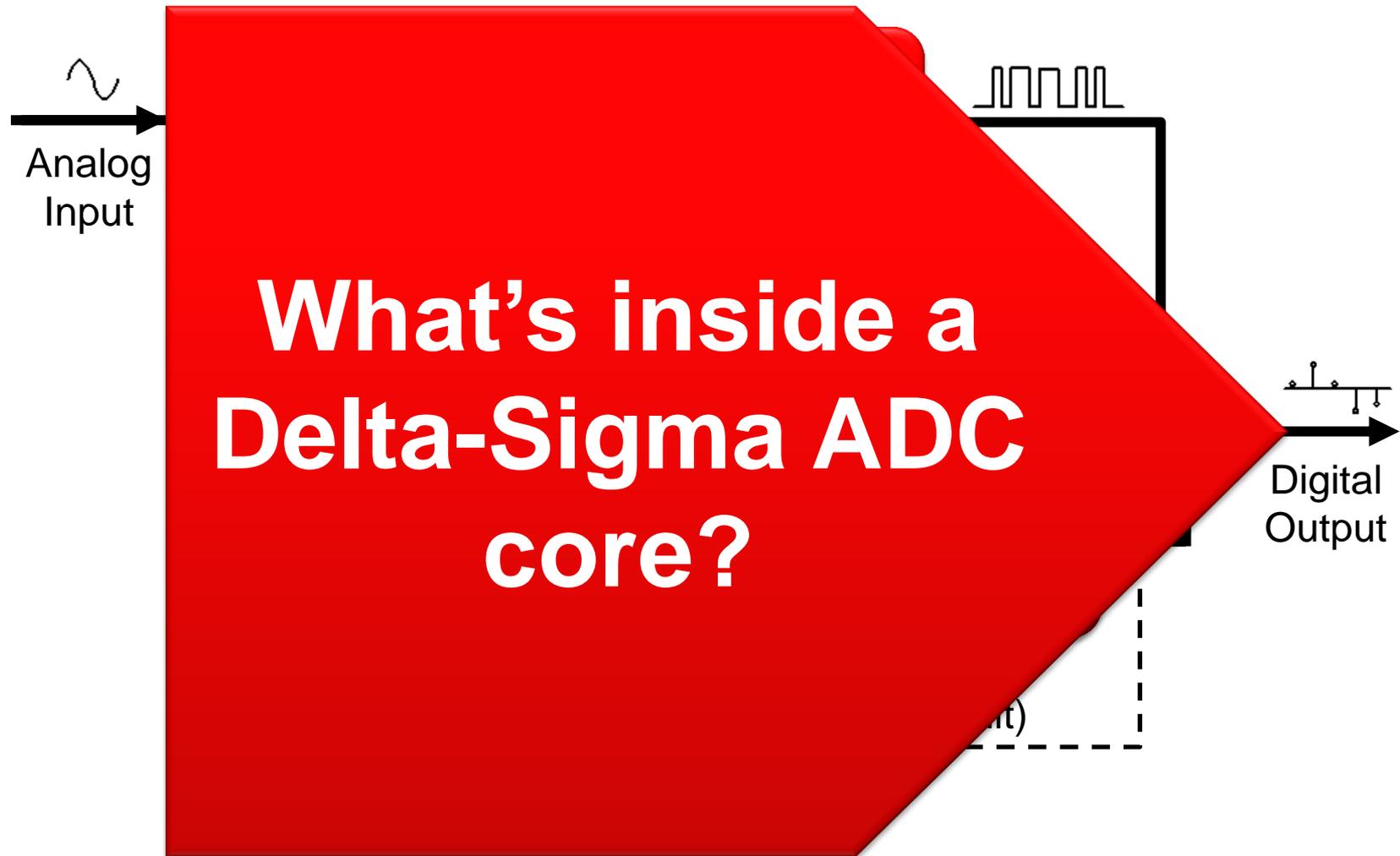


Medical



How Do Precision Delta-Sigma ADC's Work?

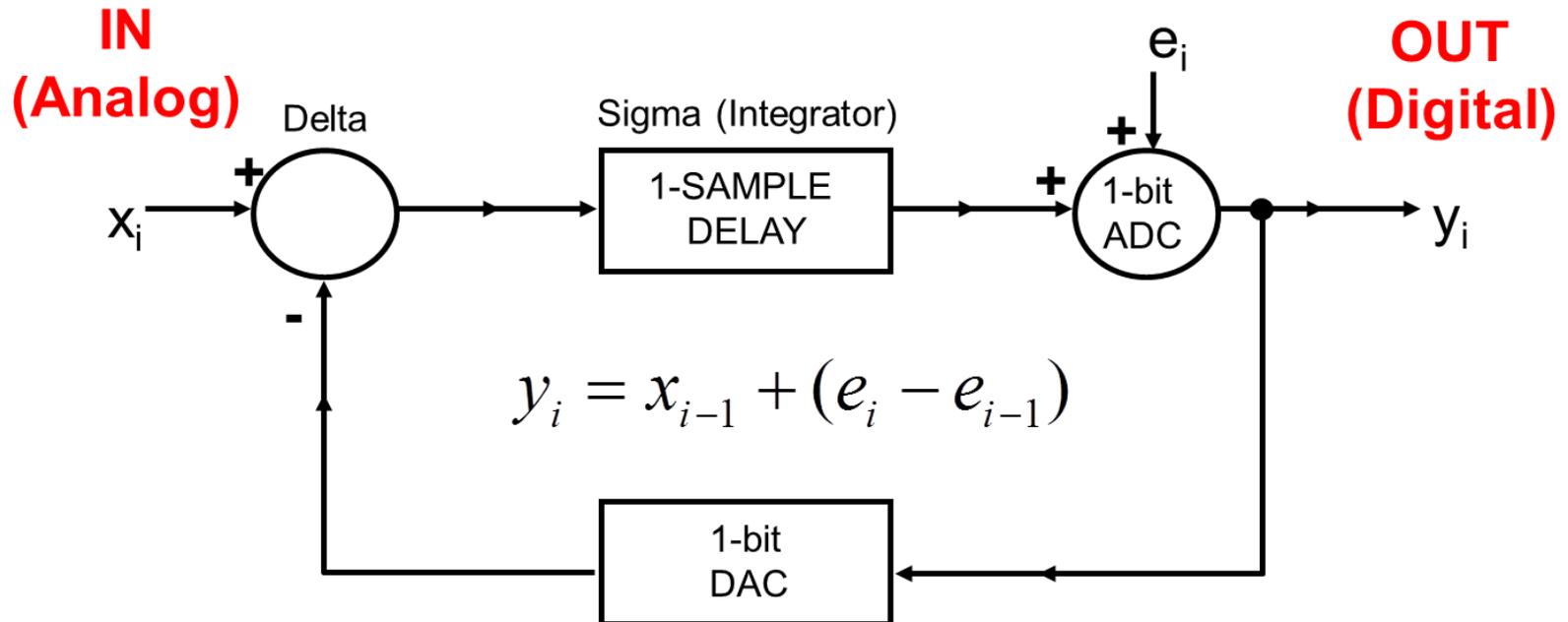
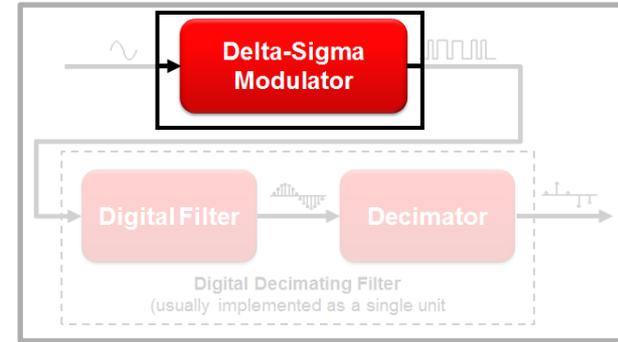
ADC Architecture Overview



How Do Precision Delta-Sigma ADC's Work?

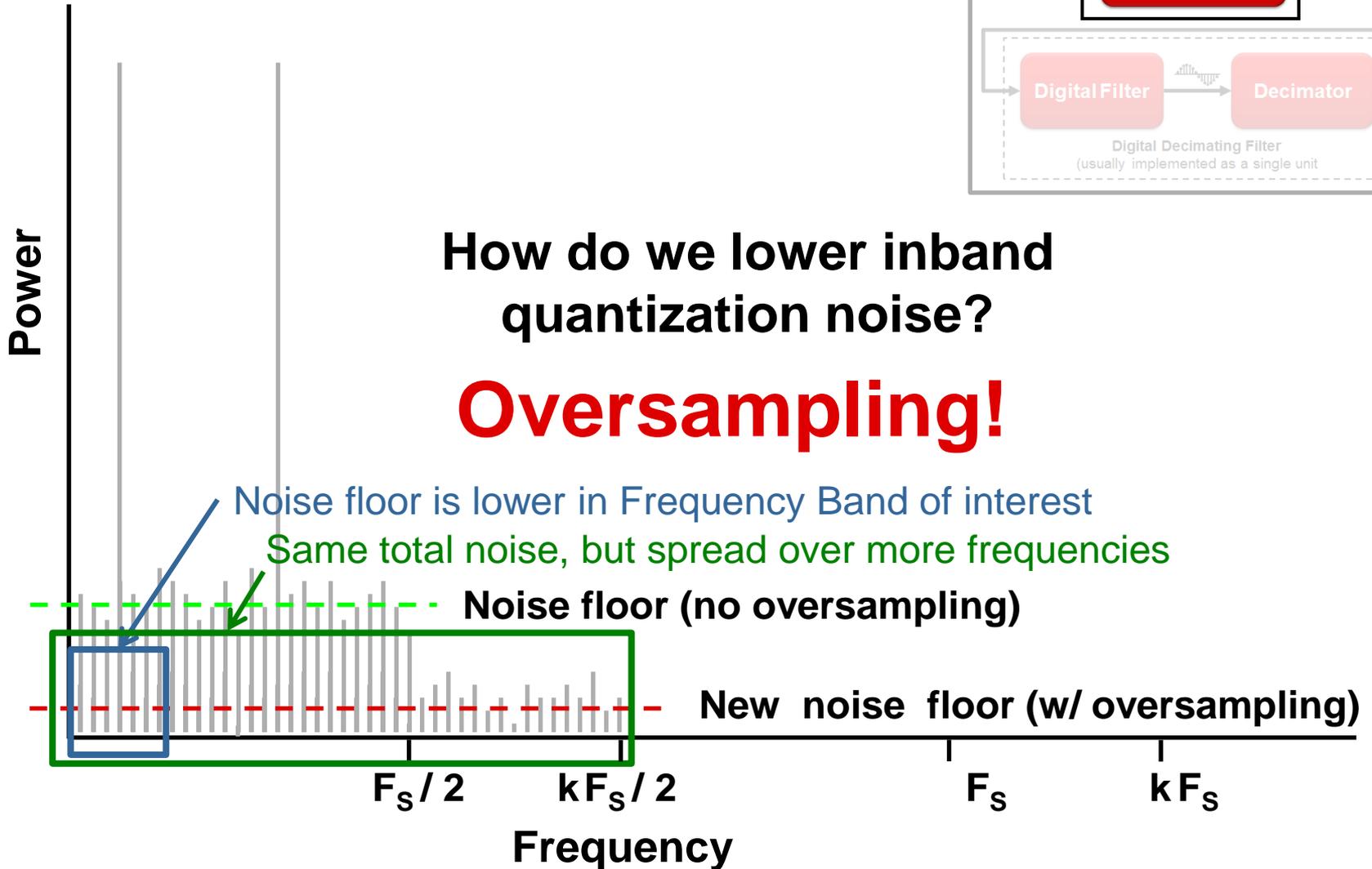
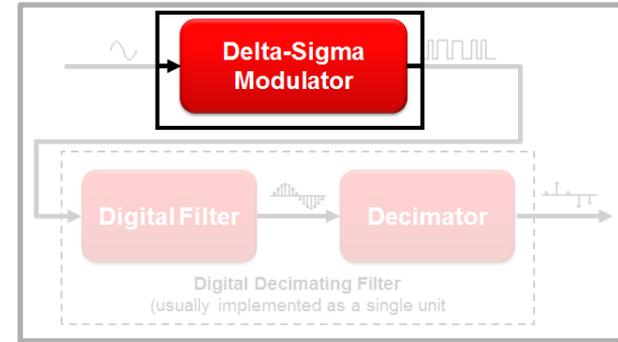
The Delta-Sigma Modulator – Time Domain

- Digital output is equal to the input plus the quantization noise
- Goal is to minimize error due to quantization noise



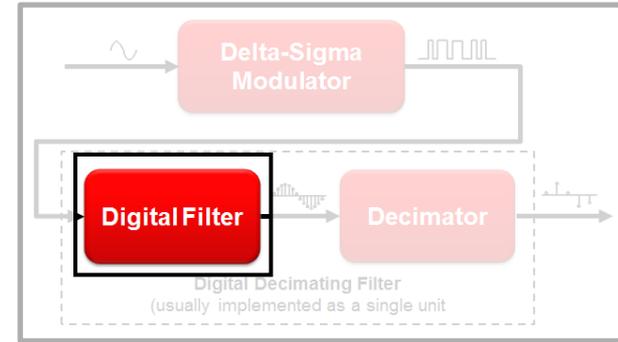
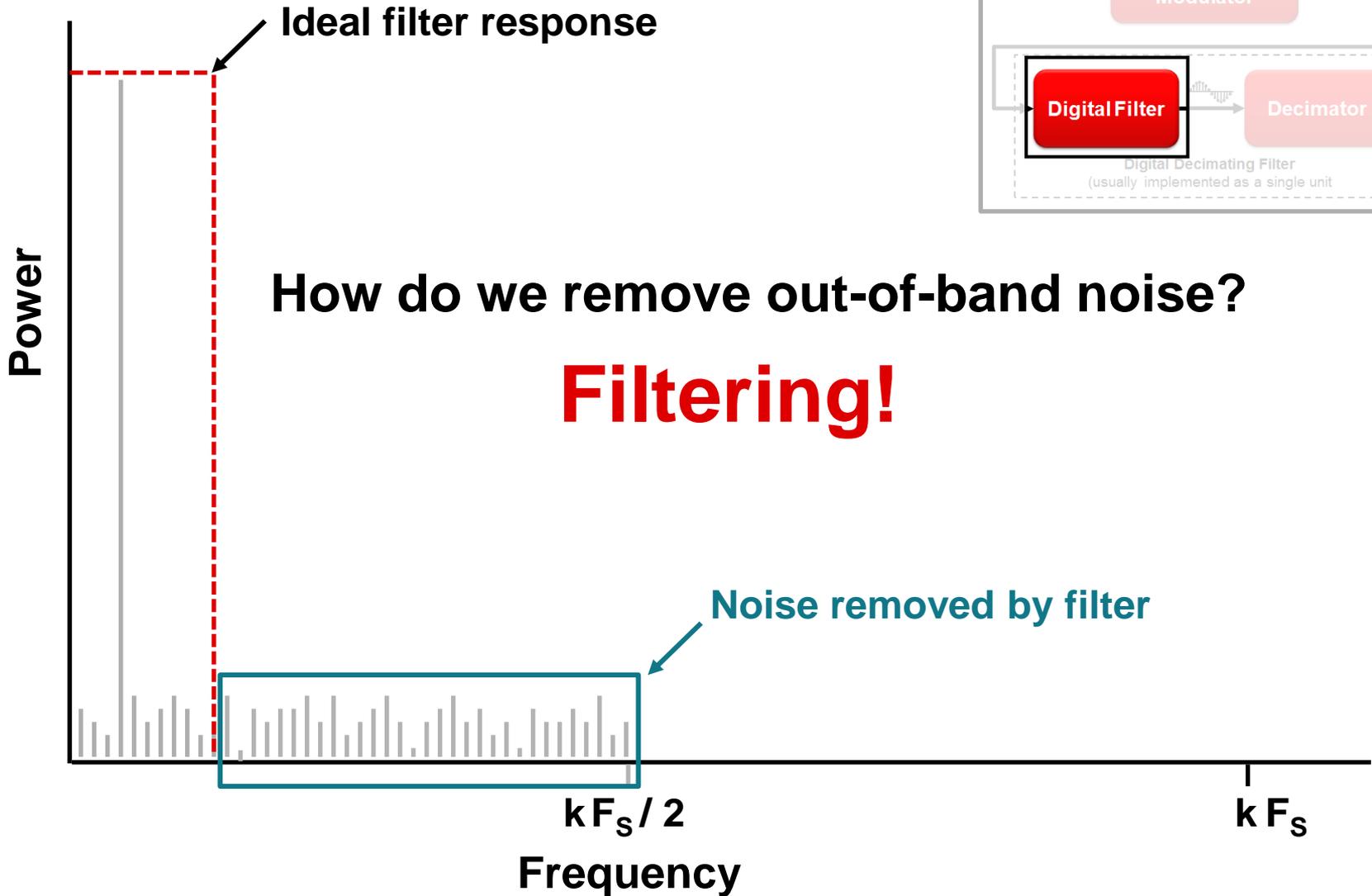
How Do Precision Delta-Sigma ADC's Work?

The Delta-Sigma Modulator – Frequency Domain



How Do Precision Delta-Sigma ADC's Work?

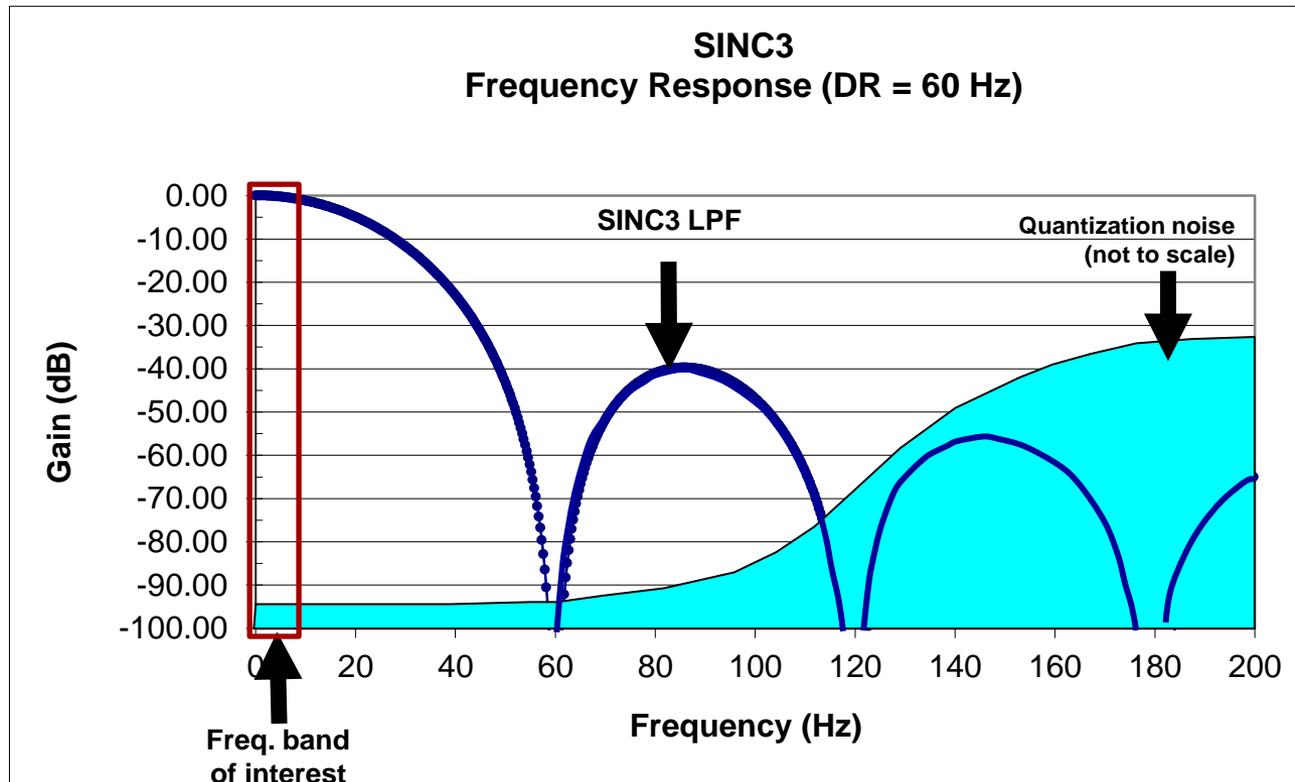
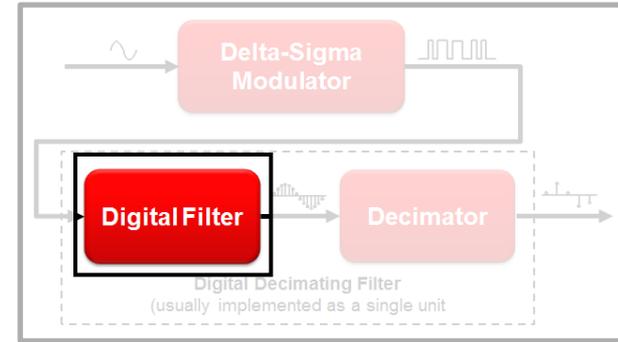
The Digital Filter – Ideal Response



How Do Precision Delta-Sigma ADC's Work?

The Digital Filter – Actual Response

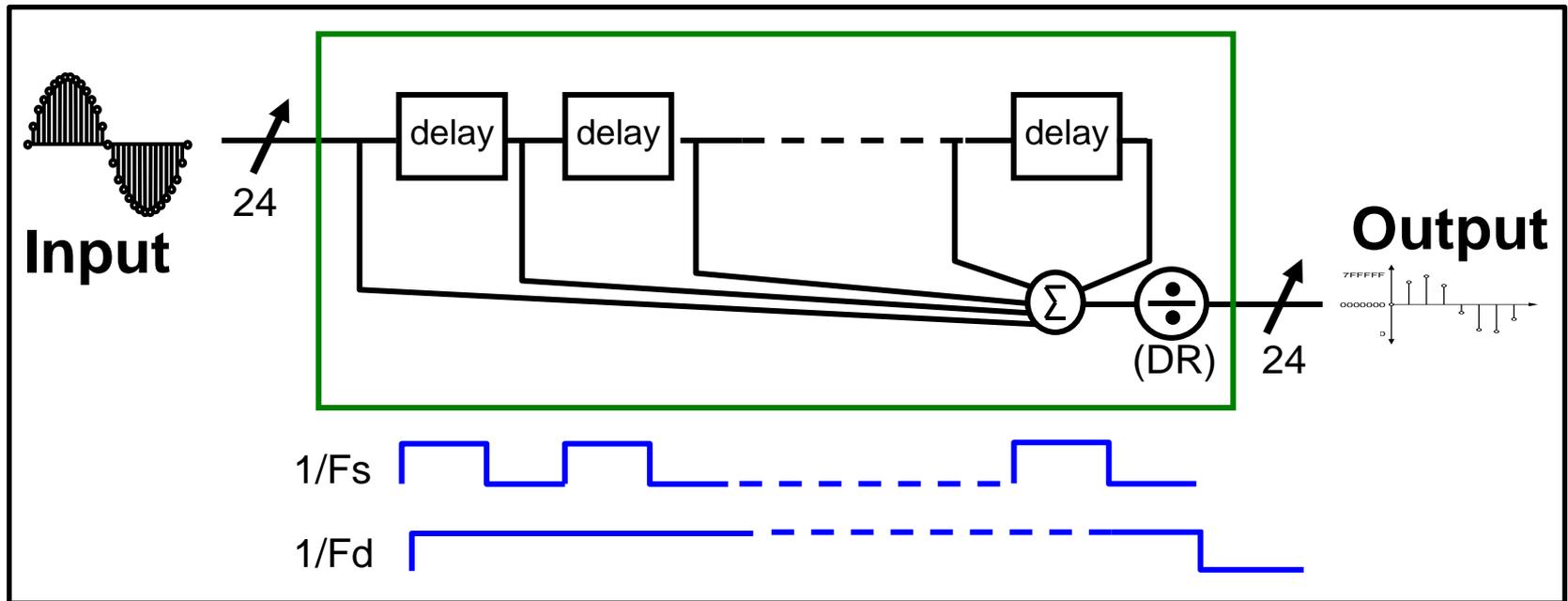
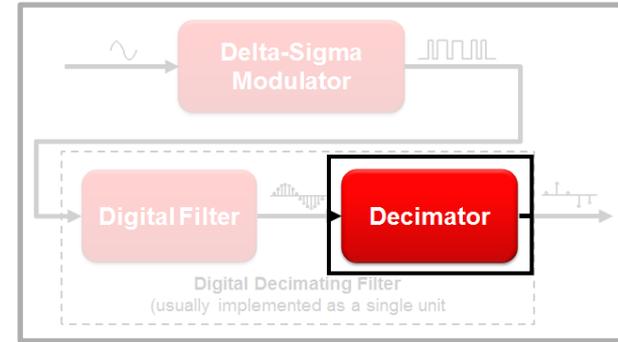
For a real-world SINC³ filter, the actual response and noise attenuation looks like this:



How Do Precision Delta-Sigma ADC's Work?

The Decimator

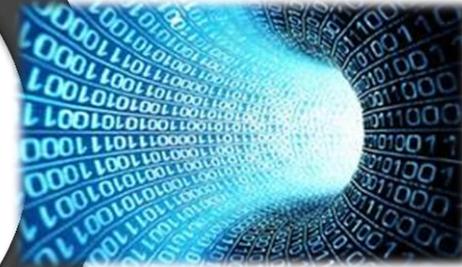
- Decimate the output by averaging several samples
- Often accomplish both filtering & decimation with SINC filter



How Do Precision Delta-Sigma ADC's Work?

Low Noise, High Resolution... & Beyond

Mostly
digital



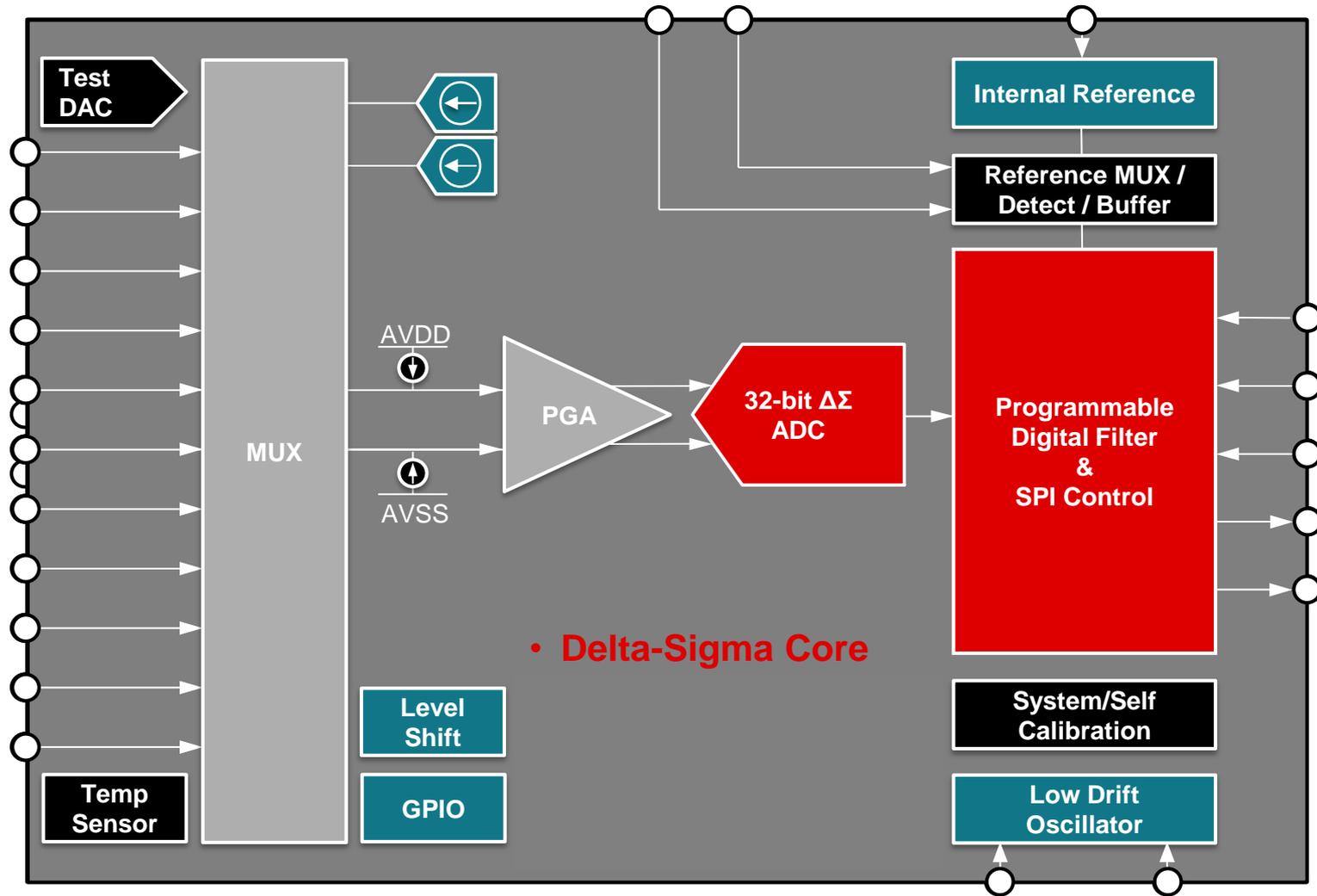
Are there other advantages
Let's look at an example
to this architecture?

More
room for
integration

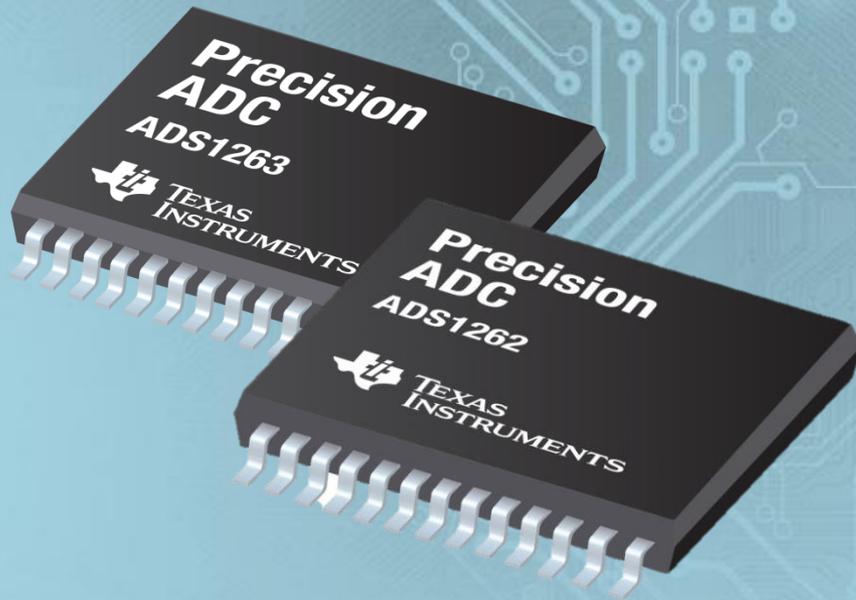


How Do Precision Delta-Sigma ADC's Work?

Lots of digital = lots of room for integration!



ADS1262 and ADS1263



ADS1262/3

Best-in-class Industrial $\Delta\Sigma$ ADC w/ Ultra Low Noise| 32-bit | 10/5 SE/Diff Channels

Features

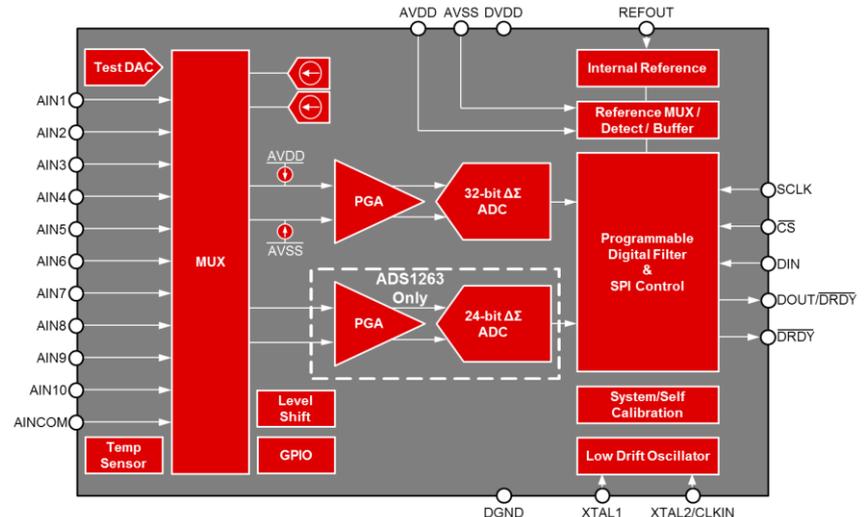
- **Highest Resolution ADC:**
 - 27 bit ENOB, 7nV Noise (@2.5SPS)
- **11 Flexible, Multiplexed Inputs:**
 - 10 Single-Ended OR 5 Differential
- **Highly Specified Performance:**
 - Offset Drift: 1nV/°C
 - Gain Drift: 0.5ppm/°C
 - INL: 3ppm
- **Highly Integrated Device:**
 - Low Drift Internal Reference: 2.5V
 - GPIOs (8)
 - Internal Clock: 7.3728MHz
 - High Impedance PGA: 1/2/4/8/16/32
 - SINC + 50/60Hz Digital Filter
- **Fault Detection/Input Diagnostics**

Applications

- Industrial PLC
- High-End Panel Meters and Process Controllers
- High Precision Weigh Scales
- Industrial Strain Gauge Analyzers
- Analytical Equipment
- RTD Measurement

Benefits

- Wide dynamic range 32-bit ADC enables direct digitization of low level sensors
- High-resolution, low-drift architecture provides the industry's best performing ADC
- A high level of integration eliminates the need for several typical discrete components, decreasing necessary PCB space and reducing costs
- Wide sample rate allows this device to be adaptable to a variety of applications
- On-chip sensor bias current sources make the ADS1262 RTD-ready
- Fault detection improves system reliability

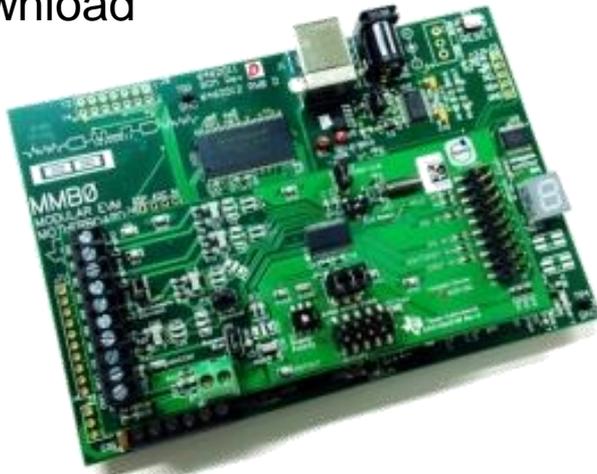


ADS1262/3 – Performance Development Kit

PDK

Performance development kits (PDKs)

- Daughter card, motherboard, USB cable and power supply.
- ADCPro™ evaluation software for Microsoft Windows with built-in analysis tools.
- Configurable inputs, references, supplies, and clock sources
- Getting started software available for download



ADS1263EVM- Connected to EVM

ADC1 Data Rate 391.8Hz ADC2 Data Rate 100.0Hz

1 Input MUX → Input MUX

7 Data \ MODE → Data \ MODE

2 Reference → Reference

8 Calibration → Calibration

3 Digital Filter → Digital Filter

9 Register Map → Register Map

4 IDAC / Sensor Bias → IDAC \ Sensor Bias

5 GPIO → GPIO

10 Extras / About → Extras / About

6 Test DAC → Test DAC

| MUX | ADC1 | | ADC2 | |
|--------|----------------------------------|----------------------------------|----------------------------------|----------------------------------|
| Signal | AINP1 | AINN1 | AINP2 | AINN2 |
| AIN1 | <input checked="" type="radio"/> | <input checked="" type="radio"/> | <input checked="" type="radio"/> | <input checked="" type="radio"/> |
| AIN2 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| AIN3 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| AIN4 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| AIN5 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| AIN6 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| AIN7 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| AIN8 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| AIN9 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| AINCOM | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| TEMP | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| AVDD | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| DVDD | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| TDAC | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |

PGA1 Gain 1 V/V Bypass Disabled Chop Enabled

PGA2 Gain 1 V/V

Other Input Functions REF BIAS GPIO TDAC

Collecting 100%

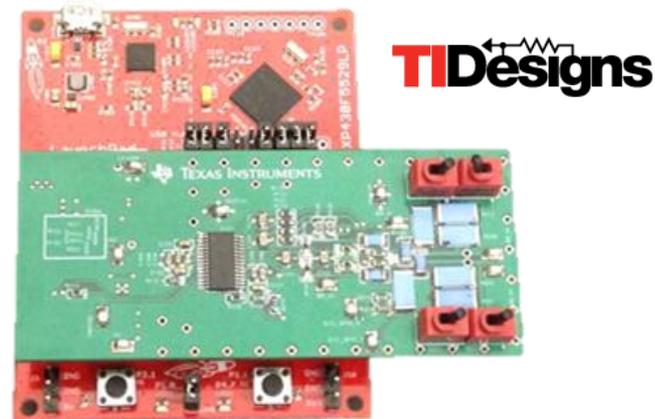
ADS1262/3 – More Tools for Faster Design

Precision Weigh Scale Reference Design | Excel Configuration Calculator

TI Designs reference design for high resolution, low drift, precision weigh scale measurements with AC bridge excitation

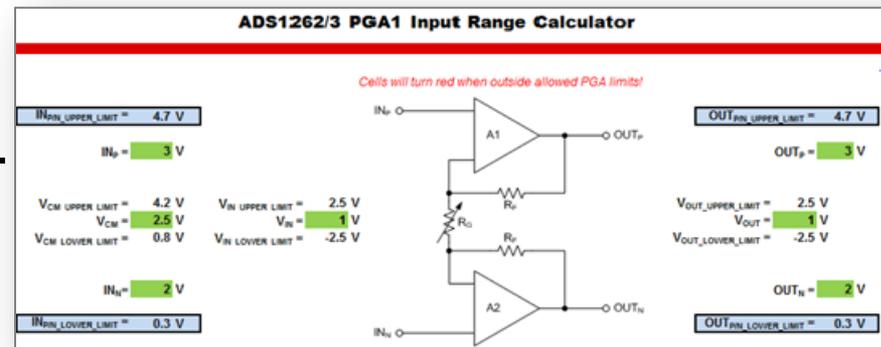
([TIPD188](#))

- Improve offset and offset drift performance for bridge measurements
- Accelerates time to market.
- Includes schematics, BOM and design files



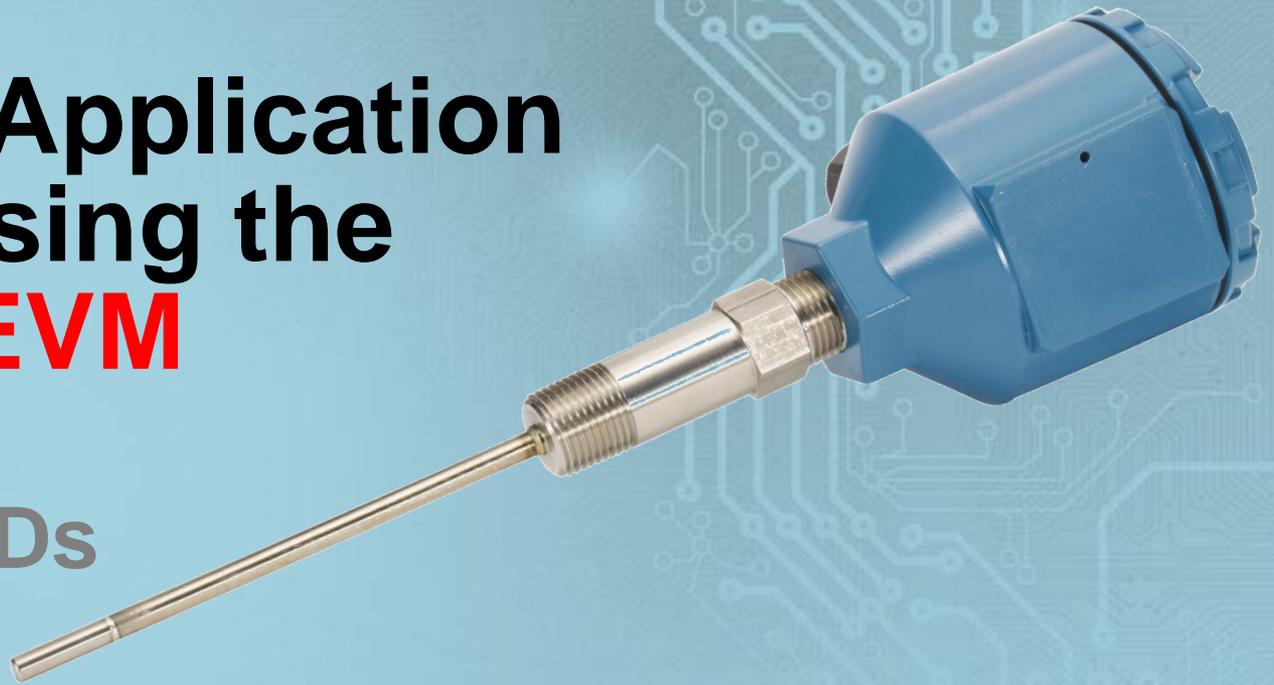
Excel-based calculator for device configuration

- Check PGA input range requirements.
- Calculate CRC/checksum values.
- Evaluate different SINC filter responses.
- View a register map.



Common Application Circuits using the **ADS126xEVM**

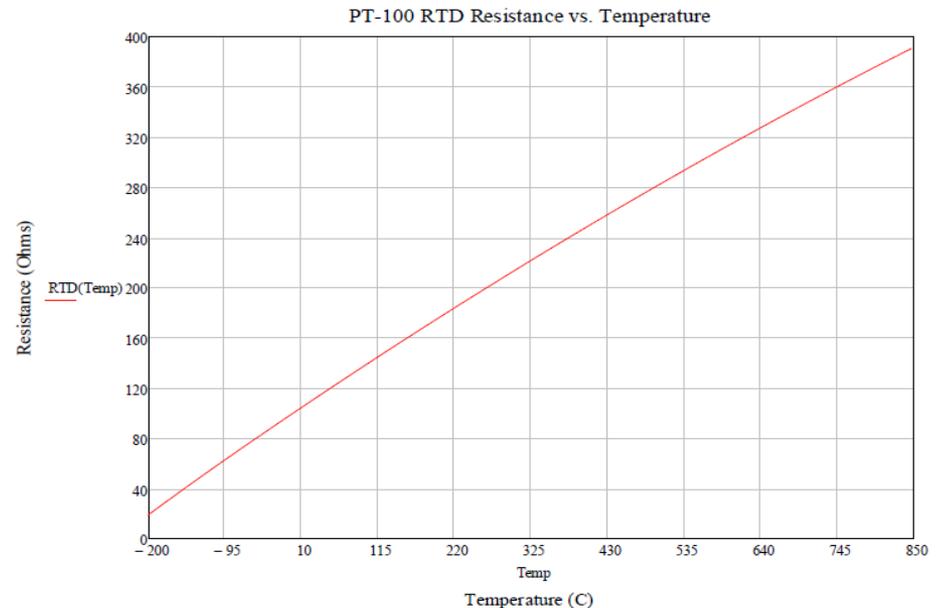
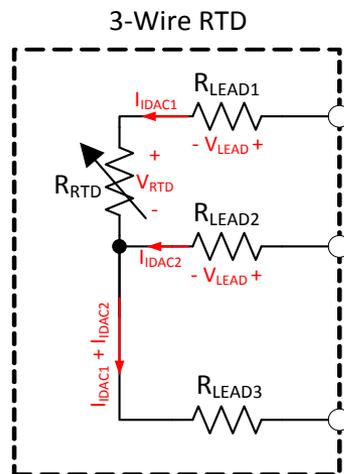
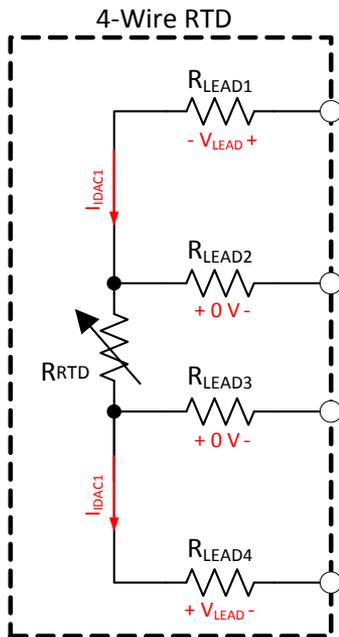
3-/4-Wire RTDs



Common Apps – 3-/4-Wire RTDs

Resistance Temperature Detector (RTD) Overview

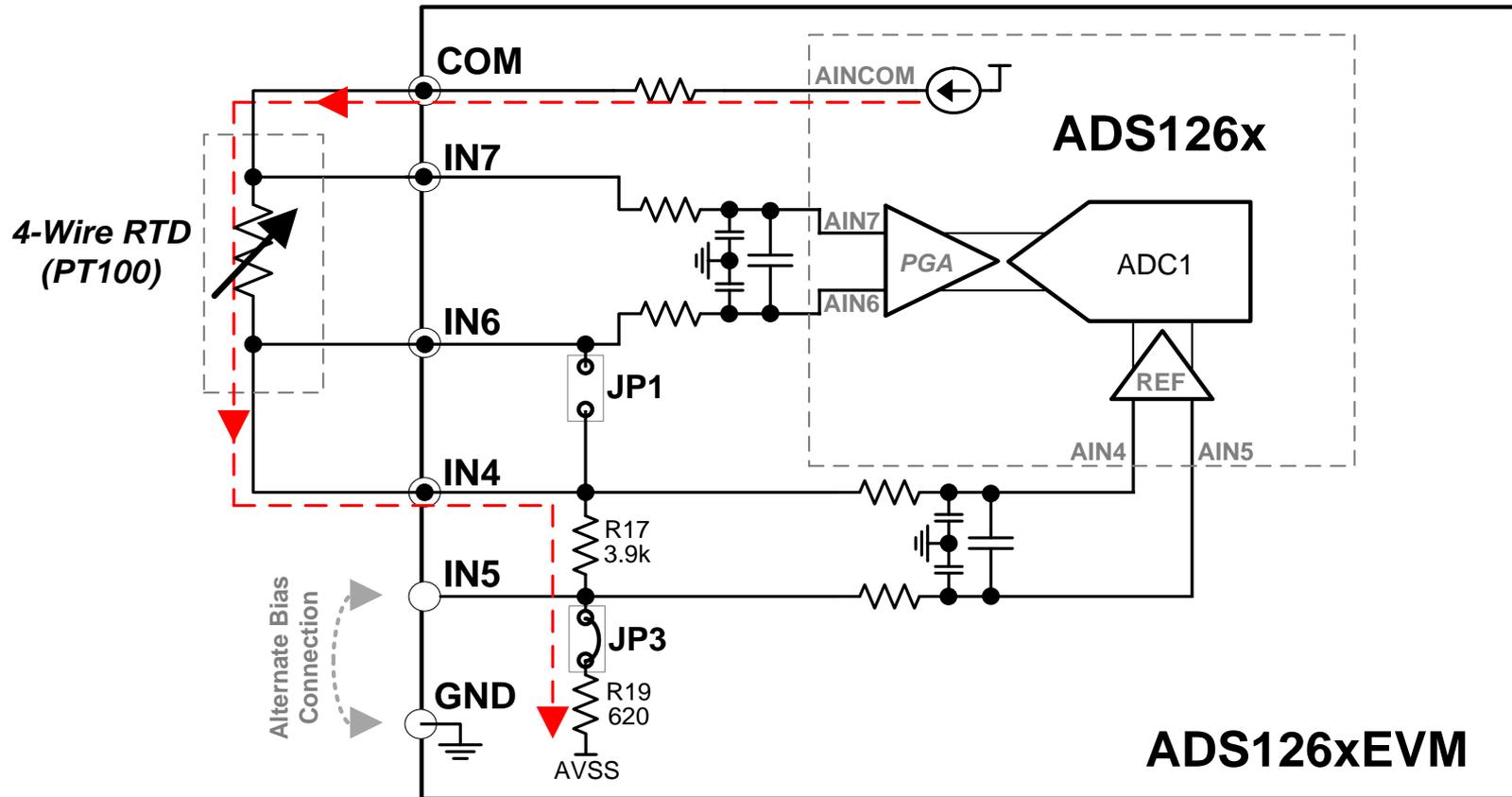
- Predictable resistance change
- Mostly made of platinum
- PT100 most common device used in industry
- High accuracy, stability and repeatability
- 2-, 3-, 4-wire types



Common Apps – 3-/4-Wire RTDs

4-Wire RTD Connections

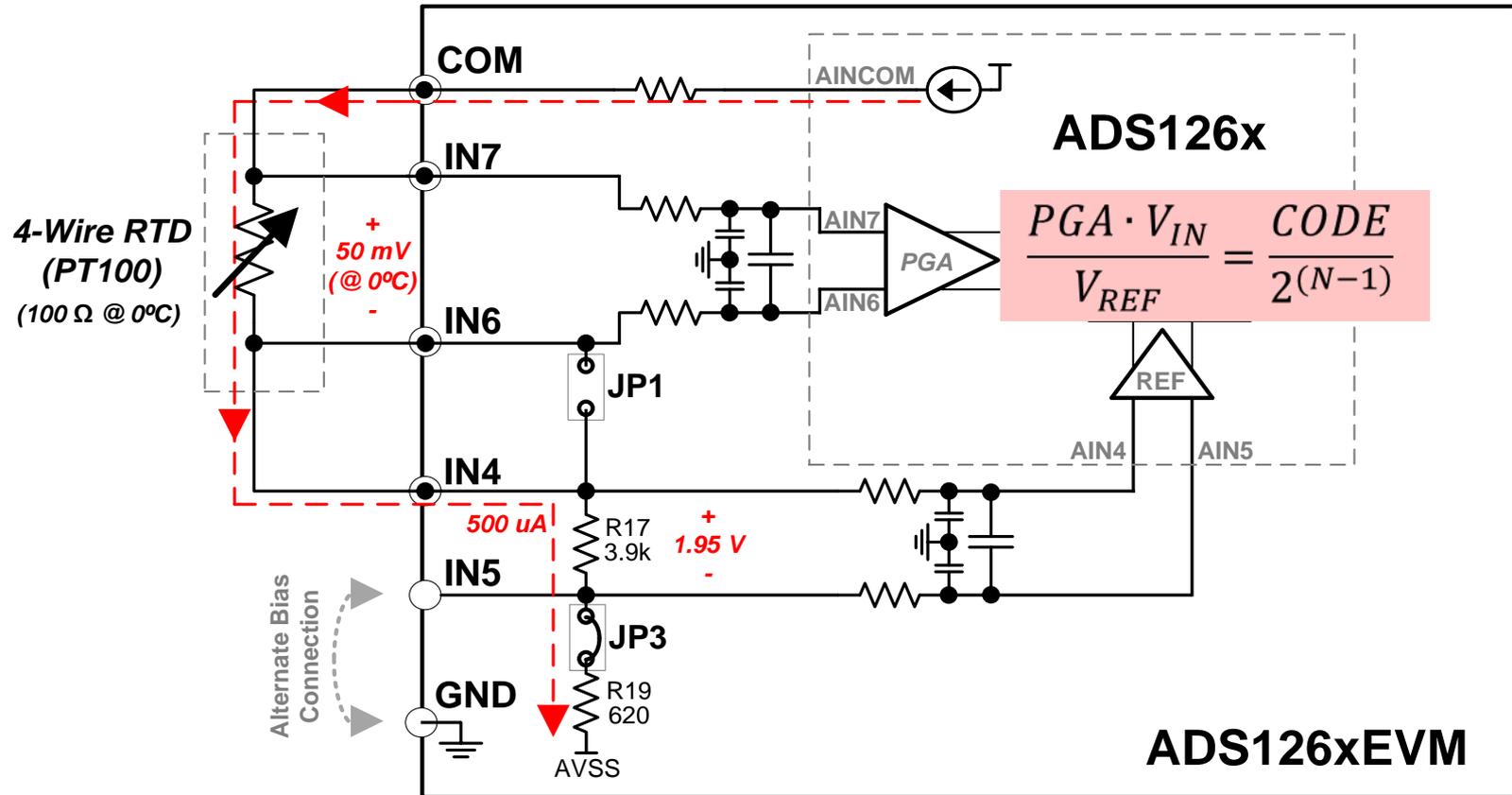
- IDAC is used to excite the RTD and generate the reference voltage (“*ratiometric*”)



Common Apps – 3-/4-Wire RTDs

4-Wire RTD Connections

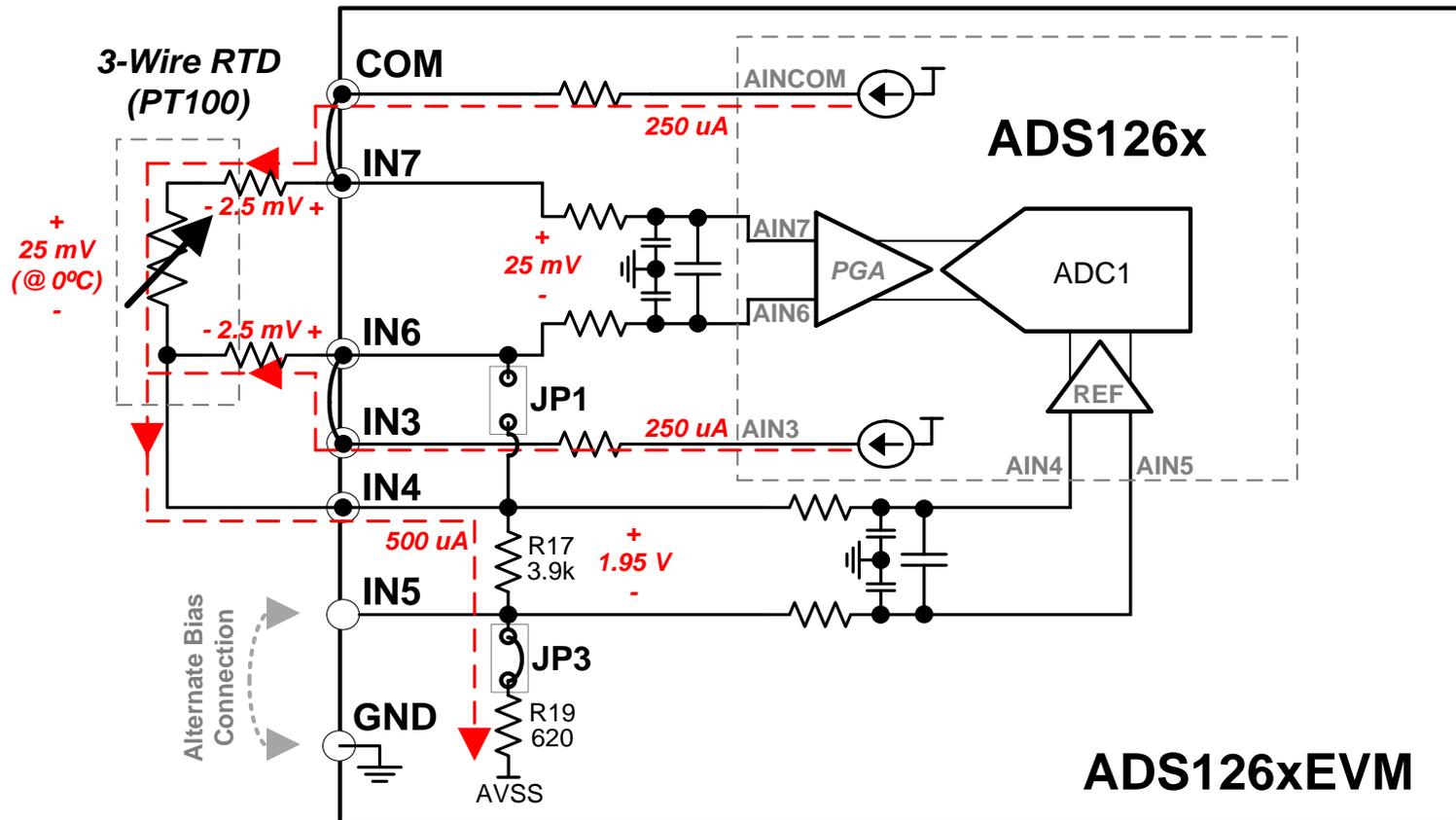
- Ratiometric configuration is unaffected by changes in IDAC current.



Common Apps – 3-/4-Wire RTDs

3-Wire RTD Connections

- A second (**matched**) IDAC current source is used to remove the effects of RTD lead resistance from the measurement.



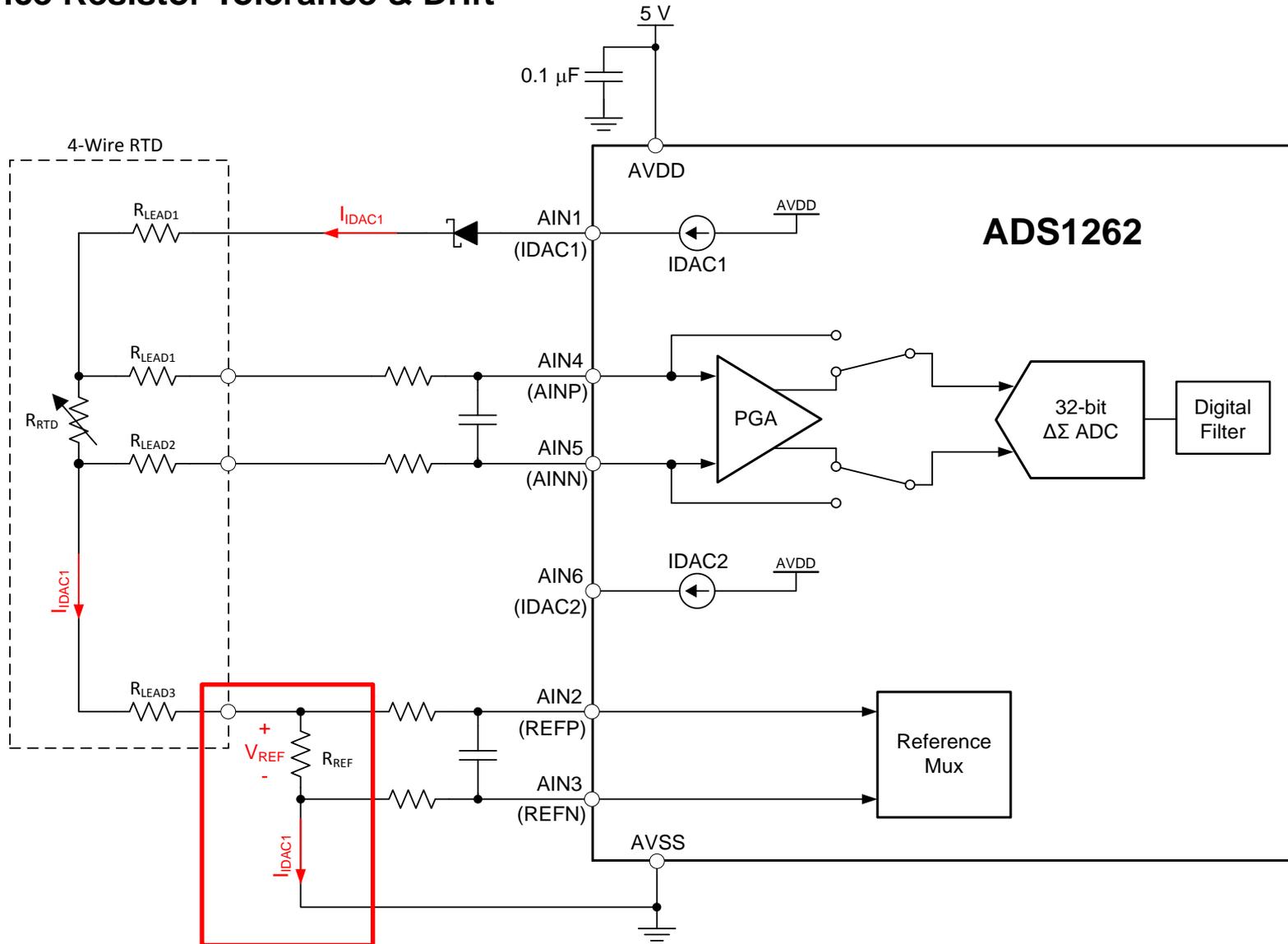
Common Application Circuits using the **ADS126xEVM**

3-/4-Wire RTD Pitfalls



Common Apps – 3-/4-Wire RTD Pitfalls

Reference Resistor Tolerance & Drift



Common Apps – 3-/4-Wire RTD Pitfalls

Reference Resistor Tolerance & Drift

- $\Delta R_{REF} \rightarrow$ Gain Error (GE)

1. Resistor Tolerance Gain Error (removed by calibration):

$$GE \text{ (ppm)} = 10,000 \cdot \text{Tolerance (\%)} \cdot \text{FSR Utilization (\%)}$$

2. Resistor Temperature Coefficient Gain Error (remains after cal):

$$GE \text{ (ppm)} = \text{Temp Co.} \left(\frac{\text{ppm}}{^{\circ}\text{C}} \right) \cdot \text{Temp Range (}^{\circ}\text{C)} \cdot \text{FSR Utilization (\%)}$$

– Example:

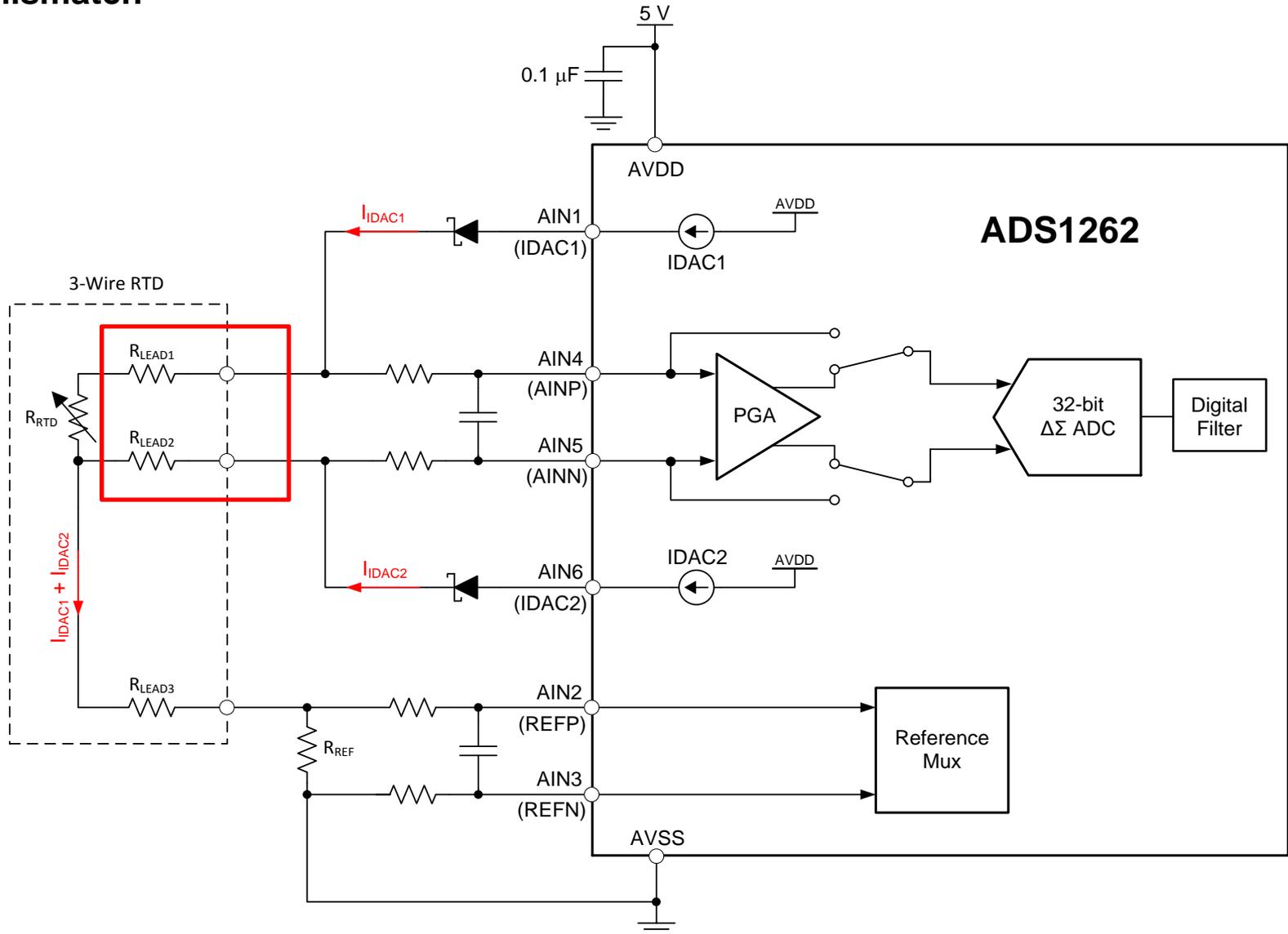
$$25 \frac{\text{ppm}}{^{\circ}\text{C}} \cdot 50 ^{\circ}\text{C} \cdot 90\% \text{ Utilization} = \mathbf{1125 \text{ ppm (9.8 bits accuracy)}}$$



Use a reference resistor with a temperature coefficient ≤ 1 ppm/ $^{\circ}\text{C}$

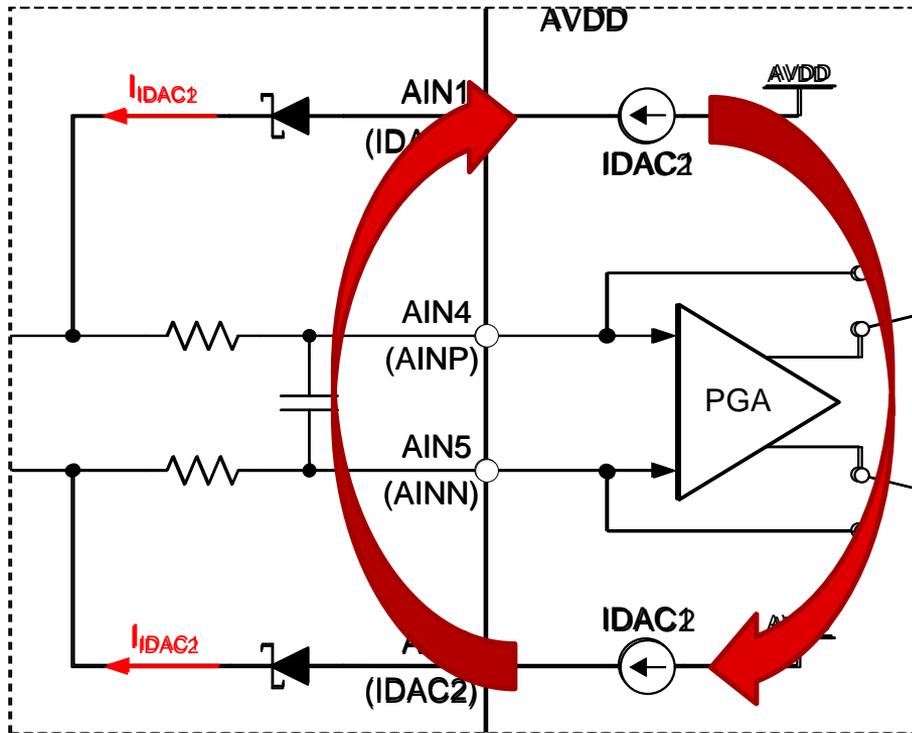
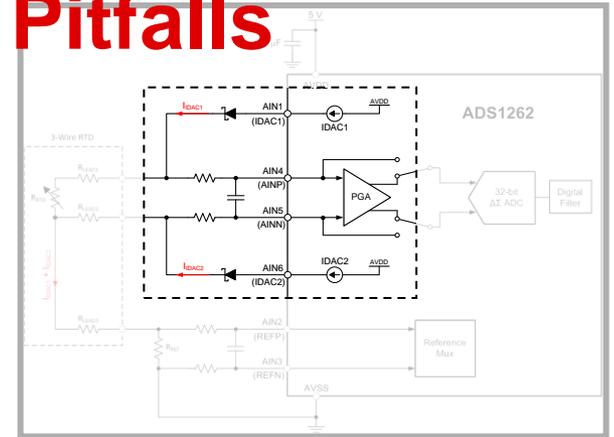
Common Apps – 3-/4-Wire RTD Pitfalls

IDAC Mismatch



Common Apps – 3-/4-Wire RTD Pitfalls

IDAC Chopping using the ADS1262/3



- 1) $V_{IN1} = V_{RTD} + \Delta V_{LEAD}$
 - 2) $V_{IN2} = V_{RTD} - \Delta V_{LEAD}$
- AVE: $\frac{1}{2} \cdot (V_{IN1} + V_{IN2}) = V_{RTD}$

Common Apps – 3-/4-Wire RTD Pitfalls

Error Improvements using IDAC Chopping

- (Neglecting R_{REF} & RTD errors)

| System Temperature Range | | | 50 | ($\Delta^{\circ}\text{C}$) | Before Calibration | | After Calibration | |
|----------------------------|------|----------------------------|----|------------------------------|--------------------|--|-------------------|-------|
| IDAC CHOPPING = OFF | | | | | | | | |
| IDAC Match Error | 0.1% | (%) | | 500 | (ppm) | | 0 | (ppm) |
| IDAC Match Drift | 5 | (ppm/ $^{\circ}\text{C}$) | | 125 | (ppm) | | 125 | (ppm) |
| ... | | | | ... | | | ... | |
| TOTAL ADC ERROR | | | | 556 | (ppm) | | 127 | (ppm) |
| IDAC CHOPPING = ON | | | | | | | | |
| IDAC Match Error | 0.0% | (%) | | 0 | (ppm) | | | (ppm) |
| IDAC Match Drift | 0 | (ppm/ $^{\circ}\text{C}$) | | 0 | (ppm) | | | (ppm) |
| ... | | | | ... | | | ... | |
| TOTAL ADC ERROR | | | | 210 | (ppm) | | 23 | (ppm) |

5x Accuracy Improvement!

Common Apps – 3-/4-Wire RTD Pitfalls

3-Wire RTD Error Analysis

- Neglects RTD errors
- Assume all errors are linear
- Errors added as the “root-sum-of-squares” (uncorrelated errors)
- **ADS1262 data sheet provides this characterization data!**

| System Temperature Range | | | 50 | ($\Delta^{\circ}\text{C}$) | ADS1262 Errors | | | | | |
|---|--------|--------------------------------------|----|------------------------------|--------------------|--------------|-------------------|--------------|--|--|
| | | | | | Before Calibration | | After Calibration | | | |
| FSR | 0.45 | (V) | | | 0.84 | (ppm) | 0.84 | (ppm) | | |
| Noise RTI (@ 20 SPS, FIR) | 266.01 | (nV _{r,p}) | | | 97.22 | (ppm) | 0.21 | (ppm) | | |
| Offset | 43.75 | (μV) | | | 1.53 | (ppm) | 1.53 | (ppm) | | |
| Offset Drift | 13.75 | (nV/ $^{\circ}\text{C}$) | | | 43 | (ppm) | 0.18 | (ppm) | | |
| Gain Error | 50 | (ppm) | | | 21.69 | (ppm) | 22 | (ppm) | | |
| Gain Error Drift | 0.5 | (ppm/ $^{\circ}\text{C}$) | | | 3 | (ppm) | 3 | (ppm) | | |
| INL | 3 | (ppm) | | | 0 | (ppm) | 0 | (ppm) | | |
| IDAC Absolute Error | 0.7% | (%) | | | 0 | (ppm) | 0 | (ppm) | | |
| IDAC Absolute Drift | 50 | (ppm/ $^{\circ}\text{C}$) | | | 0 | (ppm) | 0 | (ppm) | | |
| IDAC Match Error (Offset) (Gain Error) | 0.0% | (%) | | | 0 | (ppm) | 0 | (ppm) | | |
| IDAC Match Drift (Offset) (Gain Error) | 0 | (ppm/ $^{\circ}\text{C}$) | | | 0 | (ppm) | 0 | (ppm) | | |
| I _{REFP} Abs. Bias Current | 100 | (nA) | | | 174 | (ppm) | 0 | (ppm) | | |
| I _{REFP} Abs. Bias Current V Coeff | 50 | (nA/V) | | | 0 | (ppm) | 0 | (ppm) | | |
| I _{REFP} Abs. Bias Current Drift | 0.03 | (nA/ $^{\circ}\text{C}$) | | | 3 | (ppm) | 3 | (ppm) | | |
| I _{REF} Diff. Bias Current | 25 | (nA) | | | 45 | (ppm) | 0 | (ppm) | | |
| I _{REF} Diff. Bias Current V Coeff | 6 | (nA/V) | | | 0 | (ppm) | 0 | (ppm) | | |
| I _{REF} Diff. Bias Current Drift | 0.06 | (nA/ $^{\circ}\text{C}$) | | | 5 | (ppm) | 5 | (ppm) | | |
| I _{AINP/N} Abs. Bias Current | 2 | (nA) | | | 7 | (ppm) | 0 | (ppm) | | |
| I _{AINP/N} Abs. Bias Current V Coeff | 0.75 | (nA/V) | | | 0 | (ppm) | 0 | (ppm) | | |
| I _{AINP/N} Abs. Bias Current Drift | 0.01 | (nA/ $^{\circ}\text{C}$) | | | 0 | (ppm) | 0 | (ppm) | | |
| I _{AIN} Diff. Bias Current | 0.1 | (nA) | | | 0.11 | (ppm) | 0 | (ppm) | | |
| I _{AIN} Diff. Bias Current V Coeff | 0.20 | (nA/V) | | | 0.04 | (ppm) | 0.04 | (ppm) | | |
| I _{AIN} Diff. Bias Current Drift | 0.01 | (nA/ $^{\circ}\text{C}$) | | | 0.67 | (ppm) | 0.67 | (ppm) | | |
| TOTAL ADC ERROR | | | | | 210 | (ppm) | 23 | (ppm) | | |
| R_{REF} Errors | | | | | | | | | | |
| Tolerance | 0.05% | ($\pm\%$) | | | 434 | (ppm) | 0 | (ppm) | | |
| Temp Drift | 0.1 | ($\pm\text{ppm}/^{\circ}\text{C}$) | | | 4 | (ppm) | 4 | (ppm) | | |
| TOTAL R_{REF} ERROR | | | | | 434 | (ppm) | 4 | (ppm) | | |

| TOTAL ERROR | | | | | | |
|--|--|--------------|---|--|--------------|---|
| Total Uncorrelated System Error | | 482 | (ppm) | | 23 | (ppm) |
| | | 0.434 | ($\pm\Omega$) | | 0.021 | ($\pm\Omega$) |
| | | 1.127 | ($\pm^{\circ}\text{C}$) | | 0.054 | ($\pm^{\circ}\text{C}$) |

Common Apps – 3-/4-Wire RTD Pitfalls

Temperature Resolution

- Resolution = Measurement Repeatability or smallest discernable unit

| ADS1262 Configuration | | |
|-----------------------|--------|-------|
| PGA GAIN | 8 | (V/V) |
| Data Rate | 20 SPS | (SPS) |
| Filter | FIR | - |



| | | |
|---------------|--------|----------------------|
| ADC Noise RTI | 376.20 | (nV _{p-p}) |
|---------------|--------|----------------------|



| | | |
|------------------------|-------|----------------------|
| Noise-Free Bits | 18.9 | (nV _{p-p}) |
| Temperature Resolution | 0.002 | (°C _{p-p}) |

| RTD (PT100 type) | | |
|--|---------|------|
| T _H (°C) - T _L (°C): | 1050 | (°C) |
| VRTD (@ -200°C): | 9.260 | (mV) |
| VRTD (@ +850°C): | 195.241 | (mV) |



| | | |
|------|---------|------|
| ΔVin | 185.981 | (mV) |
|------|---------|------|



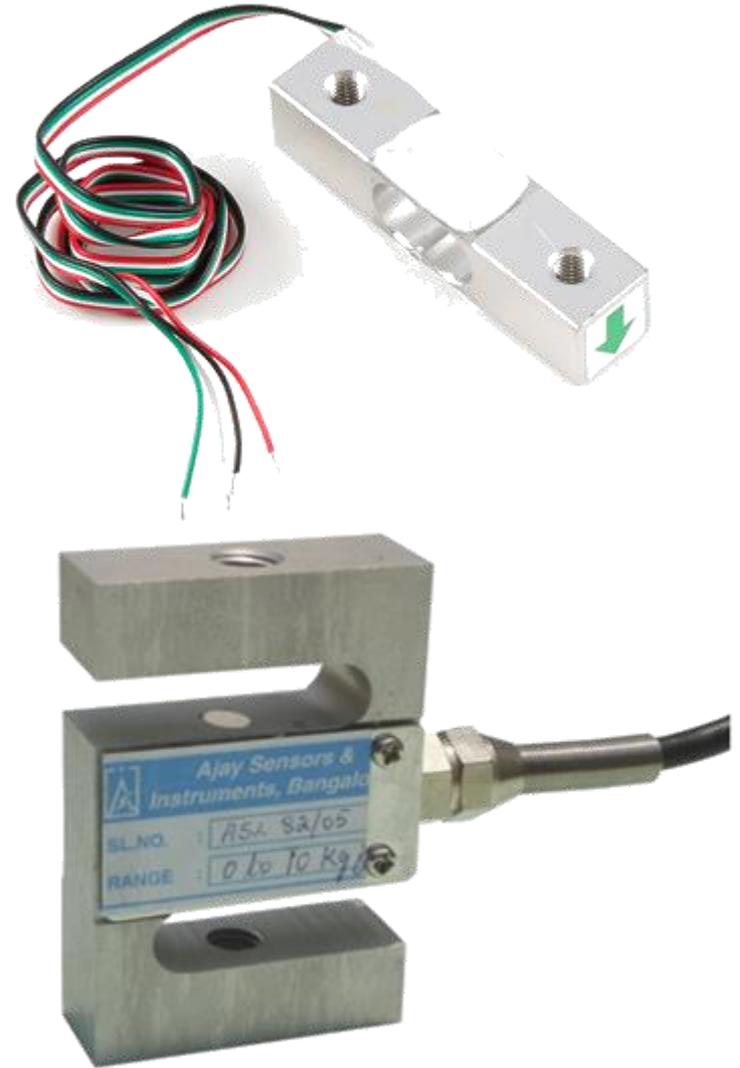
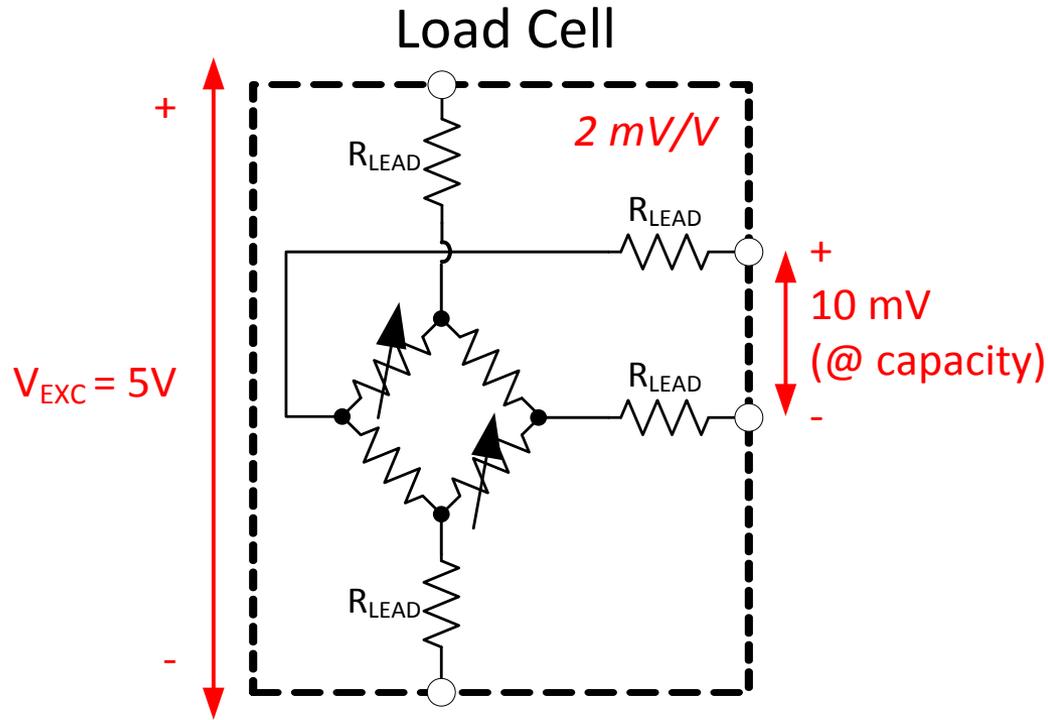
Common Application Circuits using the **ADS126xEVM**

Load Cells



Common Apps – Load Cells

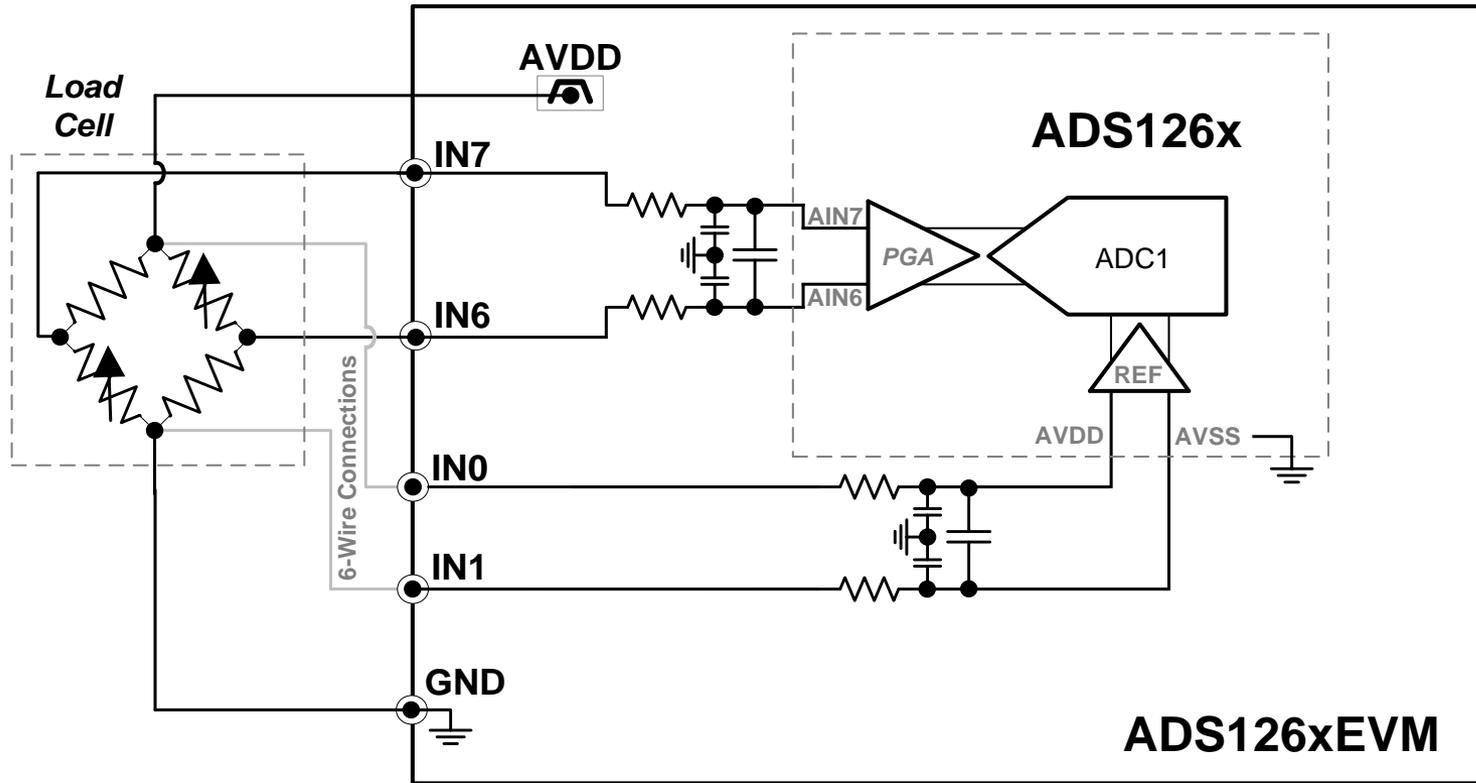
Introduction to Load Cells



Common Apps – Load Cells

Connecting a Load Cell to the ADS126xEVM

- 4-/6-Wire Load Cell Connections
- ADS126x can internally use the analog supply as the reference voltage



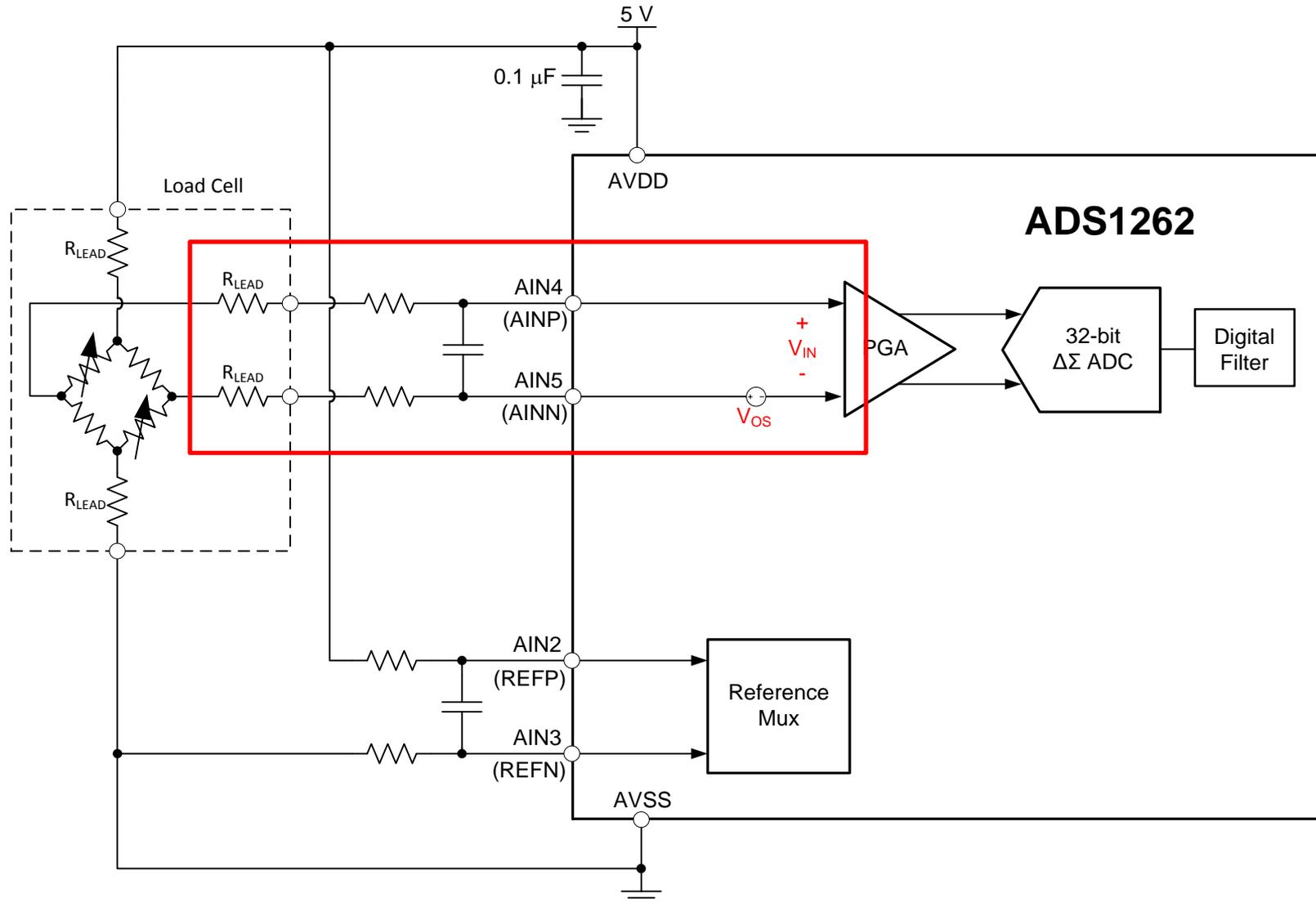
Common Application Circuits using the **ADS126xEVM**

Load Cell Pitfalls



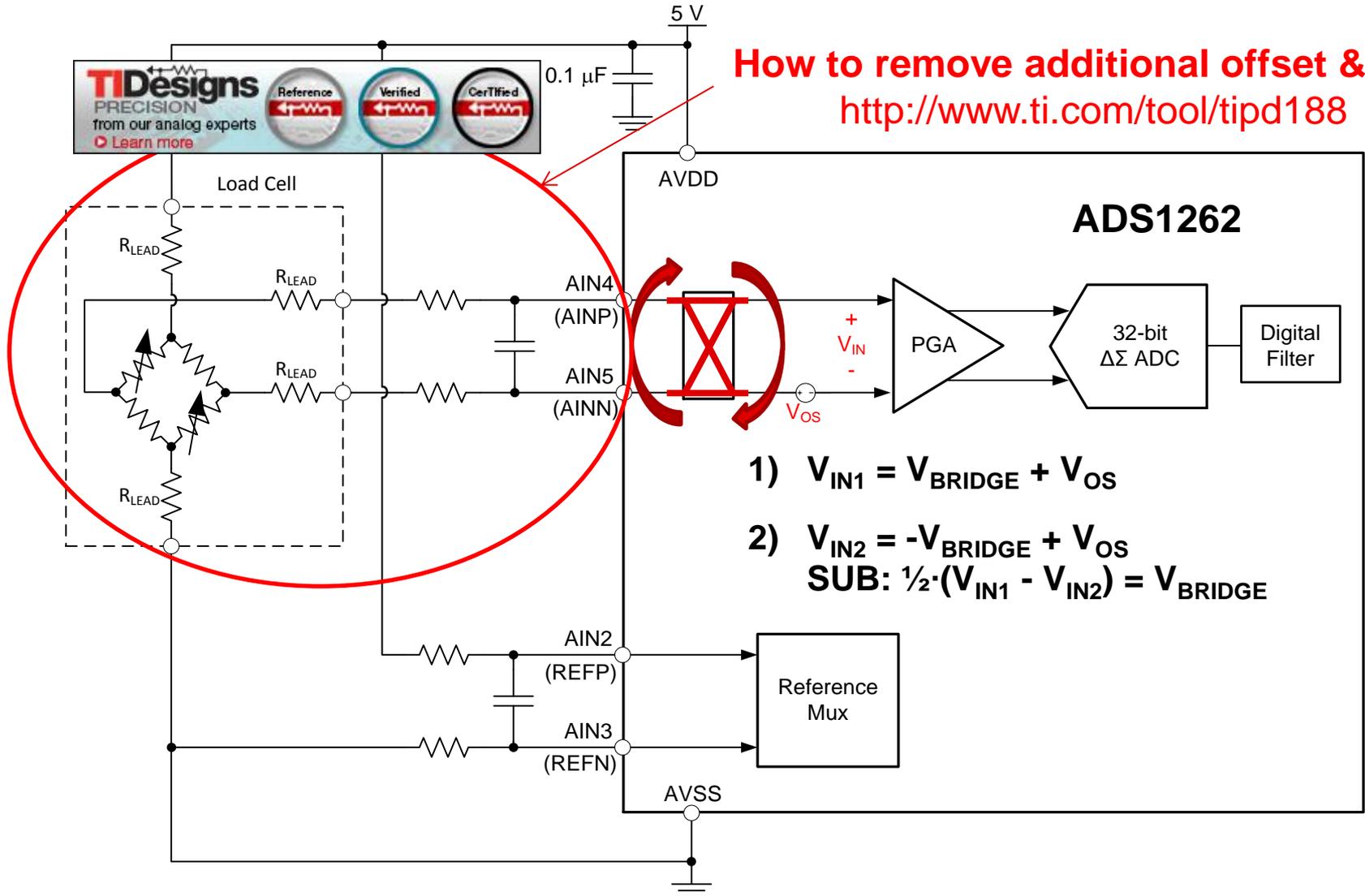
Common Apps – Load Cell Pitfalls

Offset Drift



Common Apps – Load Cell Pitfalls

Input Chopping to Remove Offset Drift using the ADS1262/3



Common Apps – Load Cell Pitfalls

Error Analysis

- Neglects load cell errors

| System Temperature Range | | 165 | ($\Delta^{\circ}\text{C}$) | ADS1262 Errors | | | |
|---|--------|----------------------------|------------------------------|--------------------|-------|-------------------|-------|
| | | | | Before Calibration | | After Calibration | |
| FSR | 0.3125 | (V) | | | | | |
| Noise RTI (@ 20 SPS, FIR) | 198.00 | (nV _{r-p}) | | 0.63 | (ppm) | 0.63 | (ppm) |
| Offset | 10.938 | (μV) | | 35 | (ppm) | 0.16 | (ppm) |
| Offset Drift | 10.9 | (nV/ $^{\circ}\text{C}$) | | 5.78 | (ppm) | 5.78 | (ppm) |
| Gain Error | 50 | (ppm) | | 3 | (ppm) | 0.01 | (ppm) |
| Gain Error Drift | 0.5 | (ppm/ $^{\circ}\text{C}$) | | 4.99 | (ppm) | 4.99 | (ppm) |
| INL | 3 | (ppm) | | 3 | (ppm) | 3 | (ppm) |
| I _{REFP} Abs. Bias Current | 100 | (nA) | | 0 | (ppm) | 0 | (ppm) |
| I _{REFP} Abs. Bias Current V Coeff | 50 | (nA/V) | | 0 | (ppm) | 0 | (ppm) |
| I _{REFP} Abs. Bias Current Drift | 0.03 | (nA/ $^{\circ}\text{C}$) | | 0 | (ppm) | 0 | (ppm) |
| I _{REF} Diff. Bias Current | 200 | (nA) | | 0.23 | (ppm) | 0 | (ppm) |
| I _{REF} Diff. Bias Current V Coeff | 6 | (nA/V) | | 0 | (ppm) | 0 | (ppm) |
| I _{REF} Diff. Bias Current Drift | 0.30 | (nA/ $^{\circ}\text{C}$) | | 0.06 | (ppm) | 0.06 | (ppm) |
| I _{AINP/N} Abs. Bias Current | 2 | (nA) | | 0.15 | (ppm) | 0 | (ppm) |
| I _{AINP/N} Abs. Bias Current V Coeff | 0.75 | (nA/V) | | 0 | (ppm) | 0 | (ppm) |
| I _{AINP/N} Abs. Bias Current Drift | 0.01 | (nA/ $^{\circ}\text{C}$) | | 0 | (ppm) | 0 | (ppm) |
| I _{AIN} Diff. Bias Current | 0.1 | (nA) | | 0.260 | (ppm) | 0 | (ppm) |
| I _{AIN} Diff. Bias Current V Coeff | 0.20 | (nA/V) | | 0.002 | (ppm) | 0.002 | (ppm) |
| I _{AIN} Diff. Bias Current Drift | 0.01 | (nA/ $^{\circ}\text{C}$) | | 5.16 | (ppm) | 5.16 | (ppm) |
| TOTAL ADC ERROR | | | | 36 | (ppm) | 10 | (ppm) |

| TOTAL ERROR | | | | | | | |
|---------------------------------|--|--|--|-------|----------------------|-------------------------|--|
| Total Uncorrelated System Error | | | | 36 | (ppm) | 10 (ppm) | |
| | | | | 11.39 | ($\pm\mu\text{V}$) | | |
| | | | | 0.365 | ($\pm\text{g}$) | | |
| | | | | 3.04 | ($\pm\mu\text{V}$) | 0.097 ($\pm\text{g}$) | |

Common Apps – Load Cell Pitfalls

Weight Resolution

- Resolution = Measurement Repeatability or smallest discernable unit

| ADS1262 Configuration | | |
|-----------------------|--------|-------|
| PGA GAIN | 32 | (V/V) |
| Data Rate | 20 SPS | (SPS) |
| Filter | FIR | - |



| | | |
|---------------|--------|----------------------|
| ADC Noise RTI | 198.00 | (nV _{p-p}) |
|---------------|--------|----------------------|



| | | |
|-------------------|-------|----------------------|
| Noise-Free Bits | 15.6 | (nV _{p-p}) |
| Weight Resolution | 0.198 | (g _{p-p}) |

| Load Cell | | |
|-------------------|----|--------|
| Max Load Capacity | 10 | (kg) |
| Sensitivity | 2 | (mV/V) |
| Excitation | 5 | (V) |



| | | |
|-----------------|----|------|
| ΔV_{in} | 10 | (mV) |
|-----------------|----|------|

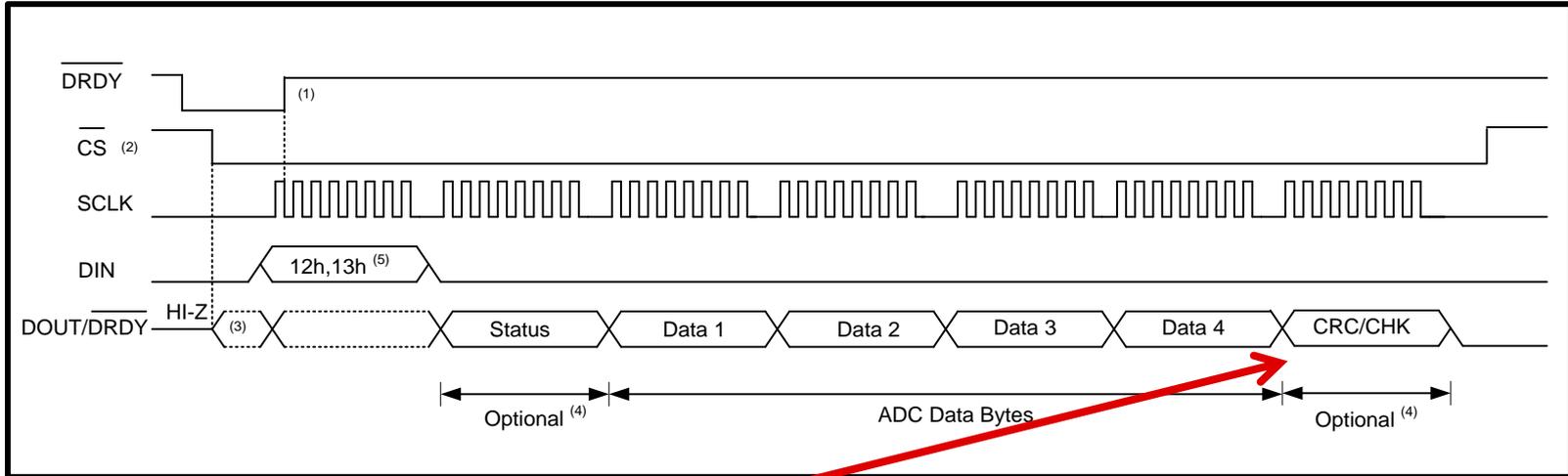


How to Use the **ADS126x Monitoring and Diagnostic Features**



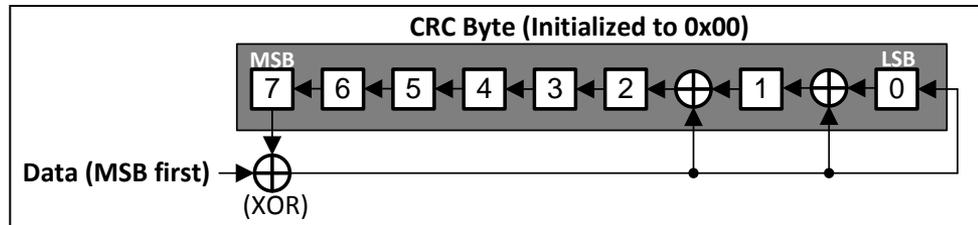
ADS126x Monitoring & Diagnostics

Communication Error Checking



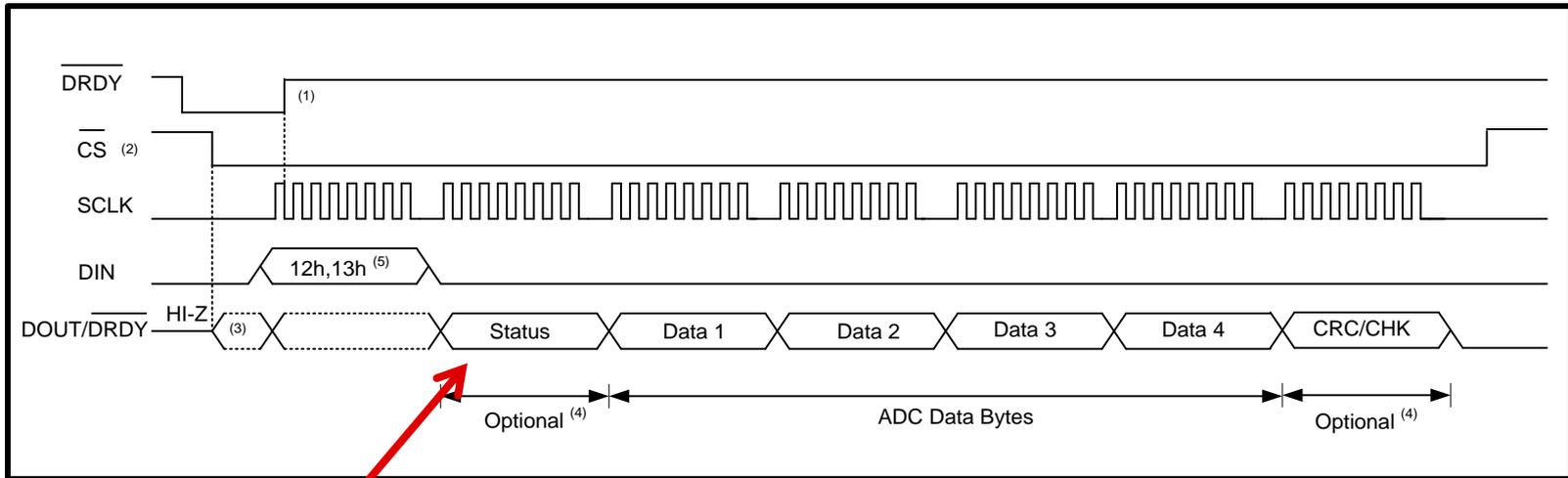
Checksum/CRC

| | |
|----------|----------------------|
| | Data byte 1 |
| + | Data byte 2 |
| + | Data byte 3 |
| + | Data byte 4 |
| + | 9Bh |
| <hr/> | |
| = | checksum byte |



ADS126x Monitoring & Diagnostics

Fault Monitoring



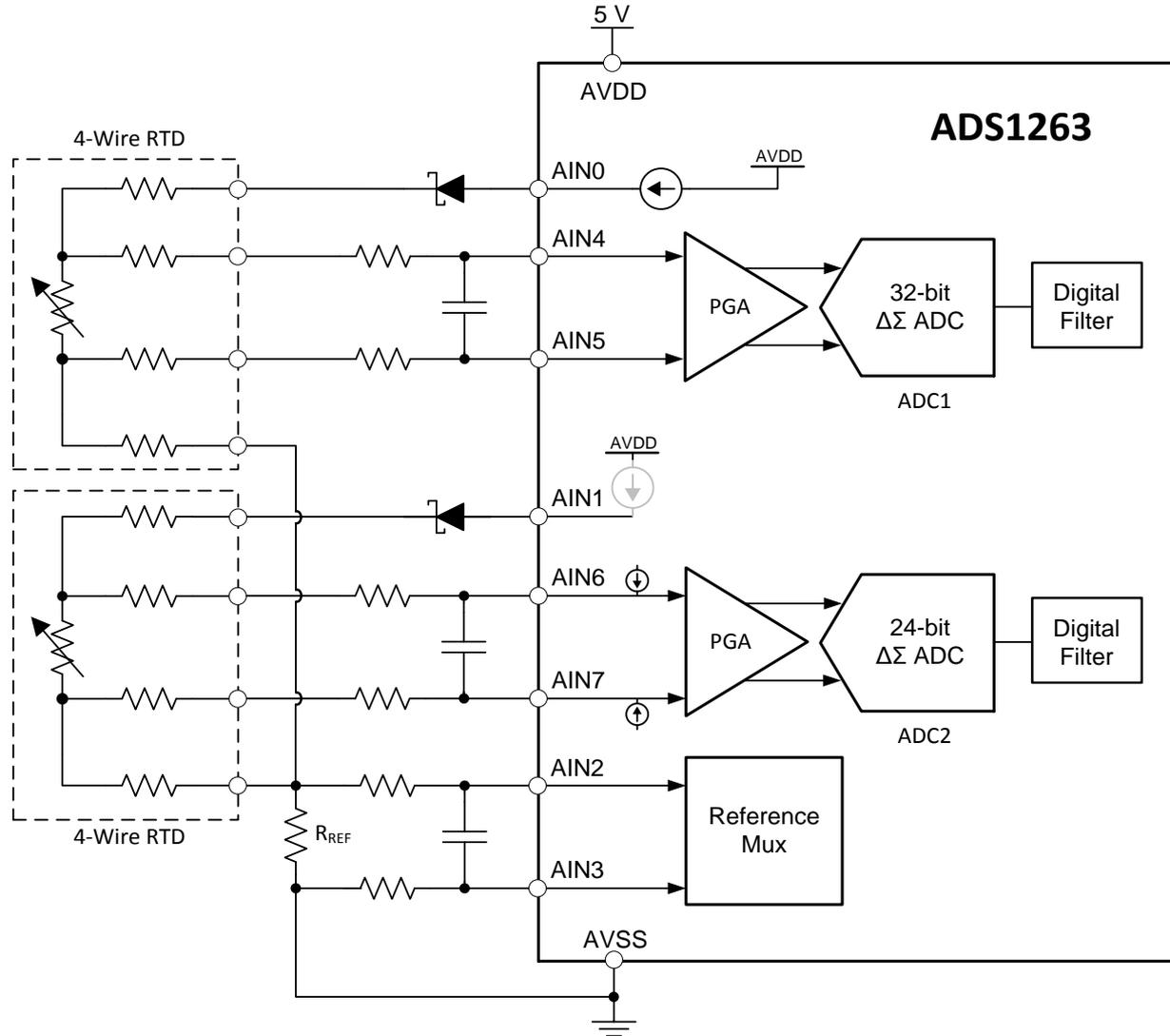
Status Byte

Figure 92. Status Byte (STATUS)

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|--------|---------|----------|----------|----------|-------|
| ADC2 | ADC1 | EXTCLK | REF_ALM | PGAL_ALM | PGAH_ALM | PGAD_ALM | RESET |

ADS126x Monitoring & Diagnostics

Burnout Detection with ADC2



Universal Input for Programmable Logic Controllers using the ADS1262

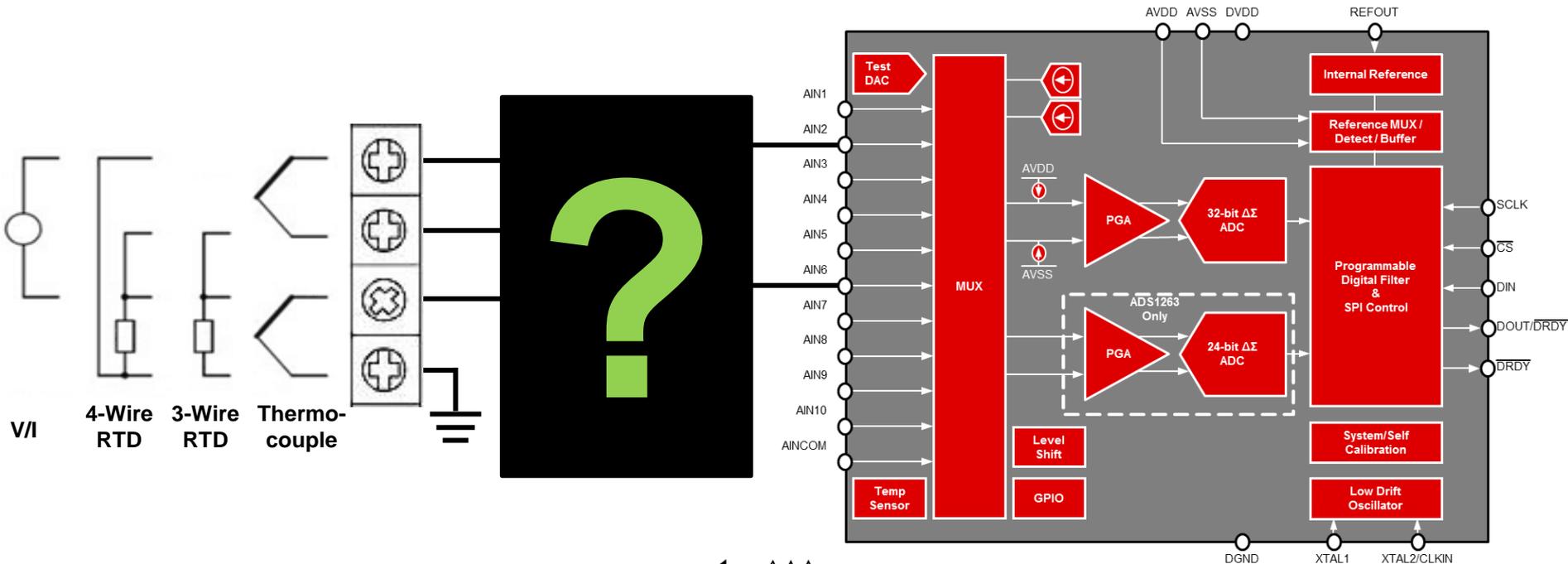


Upcoming Universal Input Module for PLC

Best-in-class Industrial $\Delta\Sigma$ ADC w/ Ultra Low Noise| 32-bit | 10/5 SE/Diff Channels

New Reference Design for Programmable Logic Controllers (PLC)

Coming soon...



TI Designs

Additional Information

Redefining high resolution and low noise in Delta-Sigma ADC applications

General Delta-Sigma ADC information:

- [Understanding the Delta-Sigma modulator](#)
- [Delta-Sigma basics: how the digital filter works](#)
- [How Delta-Sigma ADCs work \(Part 1\)](#)
- [How Delta-Sigma ADCs work \(Part 2\)](#)

ADS1262 & ADS1263 Information:

- [ADS1262 Product Folder](#)
- [ADS1262EVM](#)
- [ADS1262/3 precision weigh scale reference design](#)
- [ADS1262/3 configuration calculator](#)
- [Buy or sample the ADS1262/3](#)

Thanks!
Any Questions?