

Sensors for Building Automation

Daniel Mar

Kumar Parthasarathy

March, 2017

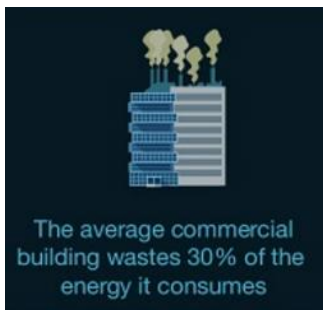
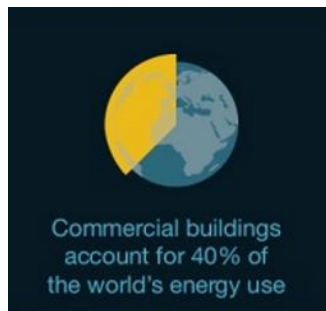
Engineering a Smarter Buildings

Industry Trends:

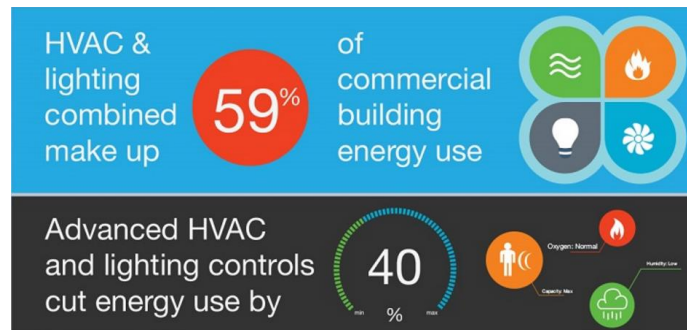
- Energy Efficiency
- Increasing Comfort
- Increasing Safety & Security
- Data
 - Connected & Cloud Driven
 - Higher accuracy
 - More frequency
 - Greater Localization



Energy Efficient Buildings

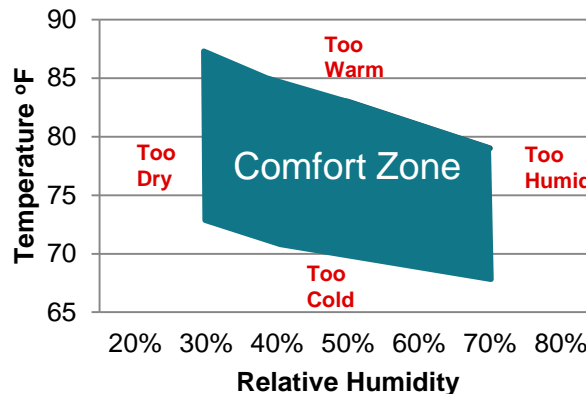


- Energy Savings thru Greater Intelligence:
 - People Counting
 - Distributed Sensor Networks
 - Big Data Analysis



Optimizing the thermostat

- Fast & Accurate Temperature Measurement
 - Reduce overshooting target temperature
 - Consumer Benefit: Greater Comfort, Energy savings
- Optimizing for comfort not just temperature (Psychrometric Factors)
 - Temperature
 - Humidity
 - Airflow
 - IR Radiation



Achieving Accuracy In a thermostat

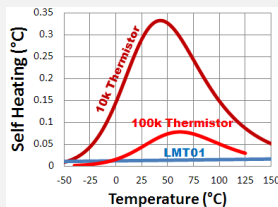
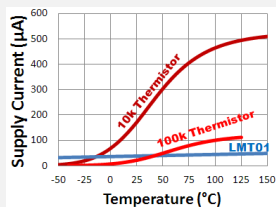
Reduce Self Heating

Accuracy problem: For low noise and minimized effects of parasitic resistances, a low value thermistor (10k Ω or less) should be chosen

Accuracy trade-off: Low value thermistor introduces more error from self-heating

Power trade-off: Low value thermistor draws more current and increases average power dissipation

Solution: Use IC-based sensor for minimal self-heating, low average power consumption across temp range, and consistently high accuracy



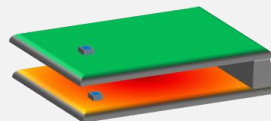
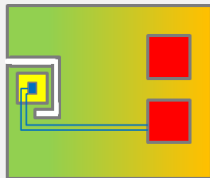
Thermal Design Considerations

Isolate: Thermally decouple sensor from high power circuitry on the PCB while increasing thermal transfer with the air.

Differential Measurements: Calculate the ambient temp by thermally modeling the temperature delta between two sensors.

Reduce Thermal Mass: Smaller sensors & less PCB around the sensor for faster thermal response

Passive Air Flow: Design housing to leverage self heating to draw fresh air past sensor



Recommended Devices

TMP112:

- $\pm 0.5^{\circ}\text{C}$ accurate
- 10 μA (max), 1.4V Capable
- Compact SOT-563 package (1.6 x 1.6 x 0.55mm)
- I2C Interface

TMP108:

- $\pm 0.5^{\circ}\text{C}$ accurate
- 6 μA (max) 1.4V Capable
- Ultrasmall WCSP package (1.2 x 0.8 x 0.625mm)
- I2C Interface

LMT70:

- $\pm 0.13^{\circ}\text{C}$ accurate
- 12 μA (max) 2.0V Capable
- Ultrasmall WCSP package (0.88 x 0.88 x 0.6mm)
- Analog Out

LMT01:

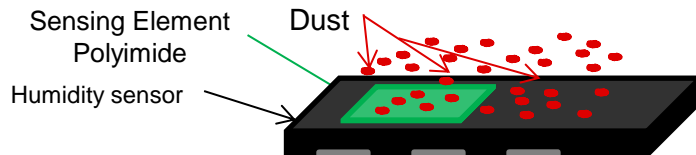
- $\pm 0.5^{\circ}\text{C}$ accurate
- Pulse Counter Interface
- 2 Pin package

LMT84:

- Fast TO-92S package
- Analog Out

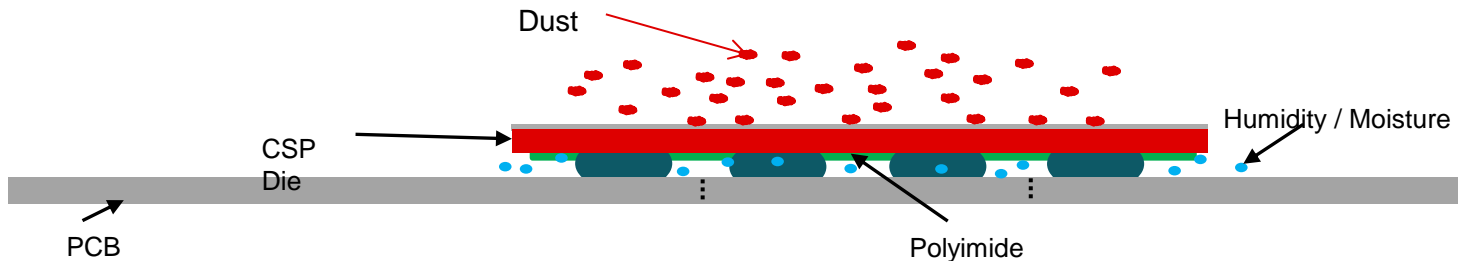
Protecting the humidity sensor

Classical solution in DFN package



- Dust falls on top of the sensing element reducing the performances until the complete blockage of the sensor
- Some competitors suggest to cover the sensor with a filter/grid (very expensive more than the device itself)

HDC1010 intrinsic dust resistant structure



- HDC1010 has the sensing element on the bottom part of the sensor.
- Sensing element is intrinsically protect from the dust that falls on the top part

HDC1010

Humidity & Temperature Sensor

Features

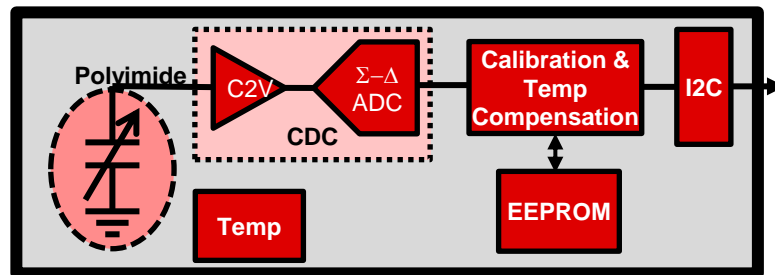
- Relative Humidity Range 0% to 100%
- Humidity Accuracy $\pm 2\%$
- Typical Drift $< 0.5\%/yr$
- Supply Current (Measuring) 180uA
- Avg Supply Current (@1sps) 1.3uA
- Temperature Accuracy $\pm 0.2^{\circ}C$
- Temperature Range (Operating) $-20^{\circ}C$ to $+85^{\circ}C$
- Operating Voltage 2.7V to 5.5V
- Package
 - 8 pin WLCSP HDC1000 (1.59mm x 2.04mm)

Applications

- HVAC
- White goods (dryer, fridge, microwave, dishwasher)
- Printers
- Handheld Meters
- Camera Defog
- Smart Thermostats and Room Monitors
- Medical Devices

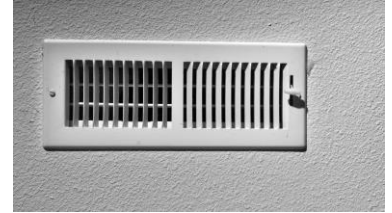
Benefits

- Completely integrated humidity and temperature IC provides guaranteed performance
- Fully calibrated sensor enables quick time-to-market
- Very low power consumption
- Small package size supports compact designs



Localized sensors & control

Low power wireless sensors to provide localized environmental monitoring to control thermostat and/or zone controlled ventilation.



Humidity & Temperature Sensing Node for Sub-1 GHz Star Networks Enabling 10+ Year Coin Cell Battery Life

TI Designs Number: TIDA-00484



Solution Features

- Configurable System Wakeup Interval
- Extremely low off-state current (270 nA for 59.97 seconds)
- Ultra low on-state current due to low active processor and radio transmit currents (3.376 mA for 30 ms)
- Extended transmit range due to Sub-1 GHz radio
- $\pm 3\%$ Relative Humidity Accuracy
- $\pm 0.2^\circ\text{C}$ Temperature Accuracy

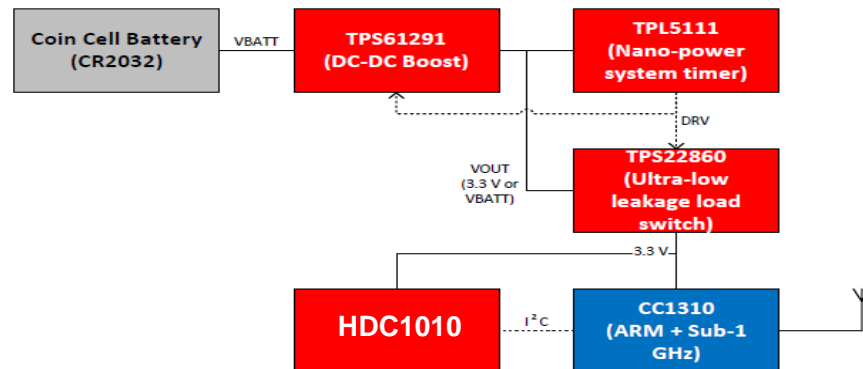
Tools & Resources



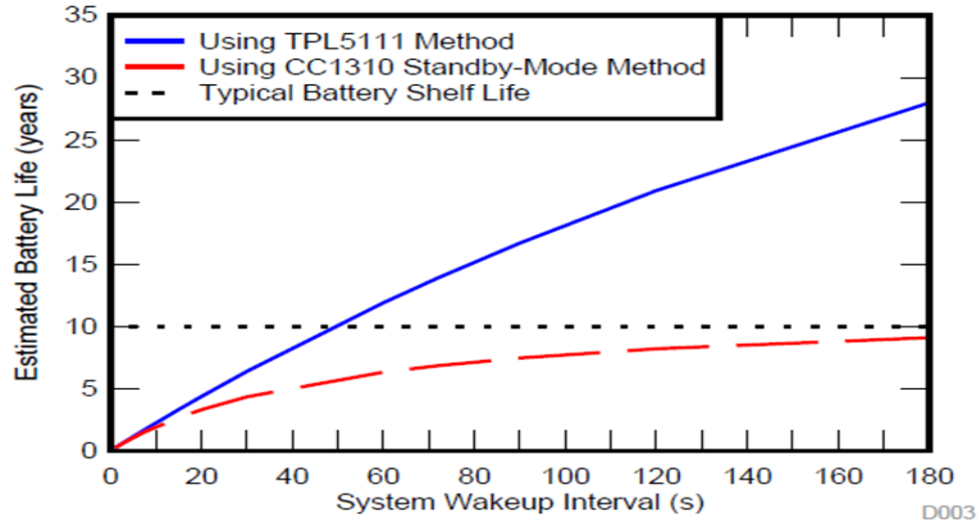
- [TIDA-00484 Tools Folder](#)
- [User Guide](#)
- **Design Files:** Schematics, BOM, Gerbers, Software, and more
- **Device Datasheets:**
 - [HDC1000](#)
 - [TPL5111](#)
 - [TPS22860](#)
 - [TPS61291](#)
 - [CC1310](#)

Solution Benefits

- Use of Nano-Power System Timer to Duty-Cycle the System Results in 10+ year battery life from CR2032 coin cell
- Small, integrated solution size due to the integrated sensor and radio SoC



TPL5110 test results: comparison of the topologies



Estimated Battery Life Comparison: TPL5111 Nano-Power System Timer Versus CC1310 Standby Mode

Humidity & Temperature Sensing Node for Star Networks Enabling 10+ year Coin Cell Battery Life



TI Designs Number: TIDA-00374

Solution Features

- HDC1010 humidity and temp digital sensing
- Detect relative humidity from 0 – 100%
±3% accuracy
- Detect temp. at $\pm 0.2^{\circ}\text{C}$ (nominal) over 5°C to 60°C
- Configurable sleep time
- Power management partitioning for extremely low power consumption

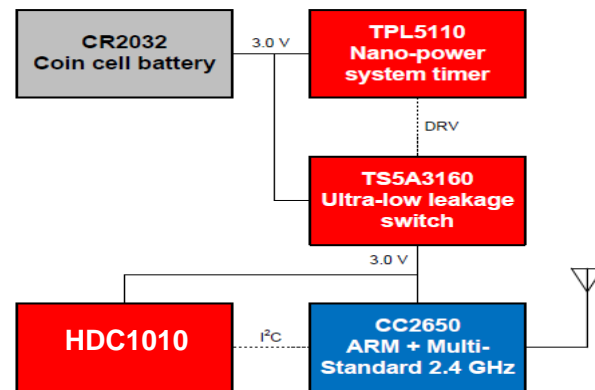
Tools & Resources

- [TIDA-00374 Tools folder](#)
- [User Guide](#)
- **Design Files:** Schematics, BOM, Gerbers, Software, and more
- **Device Datasheets:**
 - [HDC1010](#)
 - [TPL5110](#)
 - [TS5A3160](#)
 - [CC2650](#)



Solution Benefits

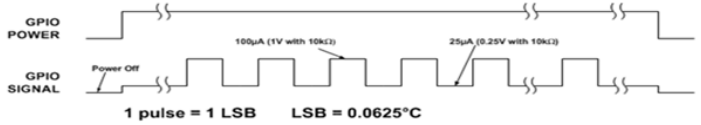
- Small, integrated solution size due to the integrated sensor and radio + mcu SoC
- Long Battery Lifetime: Designing for 10+ years off a single CR2032 coin cell battery



Digital Replacements for HVAC Temperature Probes

LMT01: Pulse Count Temp Sensor

- Simple 2 Pin Interface
- Mechanically compatible with existing hardware
- 0.5oC Accuracy



$$Temp = \left(\frac{NP}{4096} \times 256^{\circ}C \right) - 50^{\circ}C$$



TMP107: Daisy Chan Temp Sensor

- String multiple temp sensors in a single cable up to 300m
 - Reducing wiring & assembly costs
- ½ Duplex UART Interface
- 0.4oC Accuracy



Fire Safety

Smoke Detectors

- A device that detects an abnormal concentration of smoke, typically an early indication of a fire.
- Two basic types: Ionization and photoelectric
- Industry Standards
 - UL-217 North American
 - EN-54-7 European
- Commonly detect CO also
- Temperature sensor used for circuit compensation

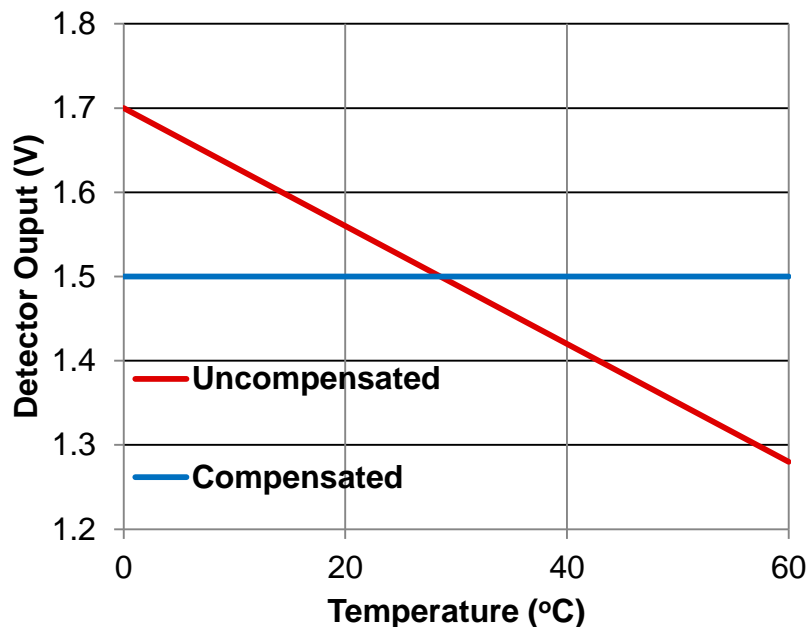


Heat Detectors

- Detects abnormally high temperatures or fast temperature increases
- Fixed-temperature or Rate-of-Rise
- Industry Standards
 - UL-521, UL-539 North American
 - EN-54-5 European
- Common Trip Points
 - 135°F for Fixed Temp
 - +15°F/minute RoR
- Temperature sensor used to monitoring the environment



Temperature Compensation for Photoelectric Smoke Detection



Graph shows hypothetical representation of smoke detector output vs temperature.

- Temperature has a significant impact on photoelectric smoke detector output level. **Failure to compensate for temperature can cause false alarms.**
- Temperature-dependent characteristics of IR LED
 - a) Spectral distribution
 - b) Light emission intensity
 - c) Forward voltage
- **Temperature sensors can be used to mitigate these errors**

UL-521 Specification for Heat Detectors (1999 Ed)

System-Level Spec

UL-521 Oven Test for 15-ft Spacing

- Ordinary Class temperature range: 29.4C-78.9C
- Response time $t \leq 2$ min
- Approximate oven rate-of-rise $\alpha \approx 33.3$ C/min



Applying Thermal Model (EN-54-5)

$$\Delta T = \alpha(t - \tau_u(1 - e^{-\frac{t}{\tau_u}}))$$

- ΔT ~ temperature rise [C], $\Delta T = 40$ C for A1
- α ~ rate of rise [C/min]
- t ~ response time [sec]
- τ_u ~ thermal time constant [sec] @ airflow of u [m/s]



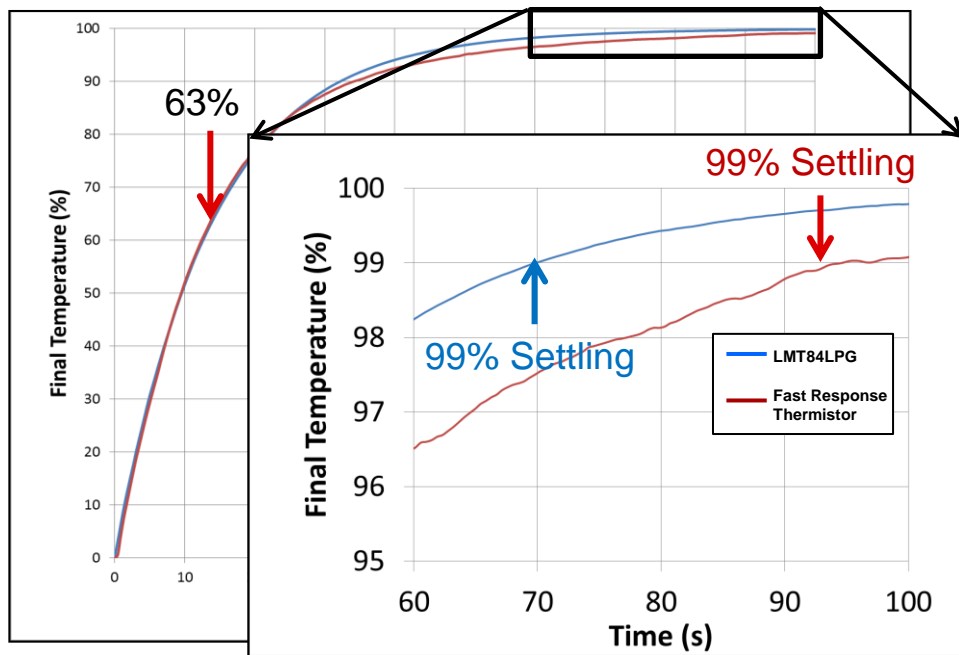
Component-Level Spec

The system-level specifications define the component-level requirements. In this case, a time constant of

$$\tau_u \leq 30 \text{ sec}$$

is needed to meet the system-level specifications of UL-521 Oven Test

LMT8xLPG vs Fast Thermal Response Thermistor



Test Conditions:

- $T_i=25^{\circ}\text{C}$, $T_f=70^{\circ}\text{C}$, Airflow=1.2m/s
- Directional dependency ~ 2 sec

Time Constant	Fast Response Thermistor	LMT84LPG
63% (t)	13 sec	13.5 sec
99% (5t)	94 sec	70 sec

LMT8xLPG supports UL-521 ($\tau \leq 30$ sec)

- Comparable thermal response
- Faster settling time

Additional Benefits of LMT8xLPG

- Guaranteed accuracy across wide temp range
 - No calibration required
 - Linear output
- Low power: 9uA (max)
- Fast Startup: 1.9ms ($C_L = 0$ pF to 1100 pF)
- Family of gain & supply options

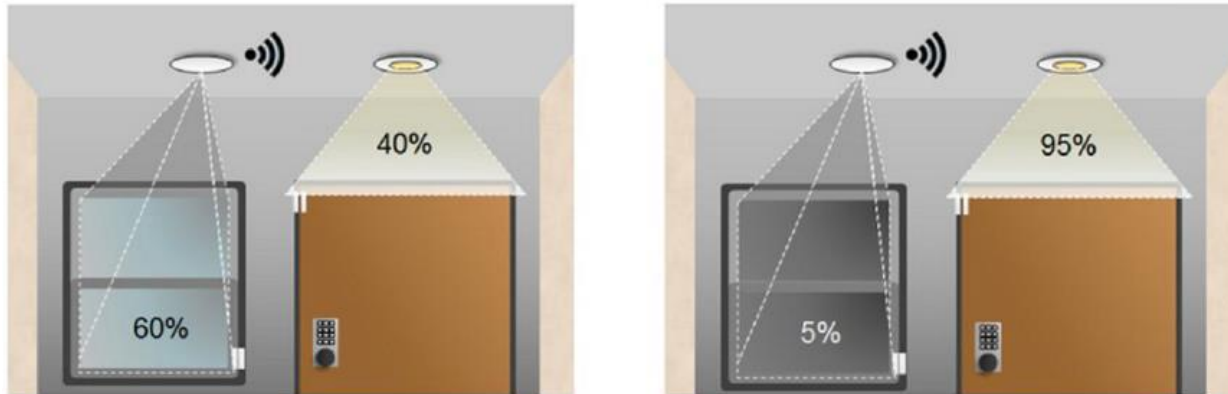
TI Part	Accuracy $^{\circ}\text{C}$ (max)	Gain mV/ $^{\circ}\text{C}$	Supply
LMT84	± 2.7	-5.5	1.5 V to 5.5 V
LMT85	± 2.7	-8.2	1.8 V to 5.5 V
LMT86	± 2.7	-10.9	2.2 V to 5.5 V
LMT87	± 2.7	-13.6	2.7 V to 5.5 V

Optical Solutions in BA - Daylight Harvesting & Occupancy Detection

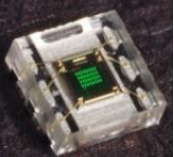
Kumar Parthasarathy
Systems & Marketing Manager
Texas Instruments

Daylight Harvesting

- Smart control of the building lighting by monitoring ambient light and adjusting artificial lighting accordingly
- Each energy code has specific rules on daylight zones
- Trade-off exists between battery life and frequency of data collection for sensor nodes
- Secondary Benefit: Compensation for aging effects of the bulbs “Luminary Maintenance”



OPT3001- Ambient Light Sensor



Features

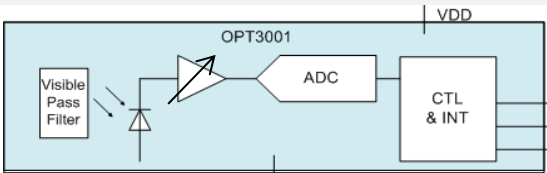
- Good Human Eye spectral matching
 - <1% IR Response
- Optical Power Sensitivity
 - 0.01 – 83,000Lux
 - Automatic range setting
- Tight Absolute Accuracy: 10%
- Wide 1.6V - 3.6V Power Supply Range
- Low 1.8uA (typ) Operating Current.
- Flexible Interrupt System
- Small 2.0 x 2.0mm Package

Benefits

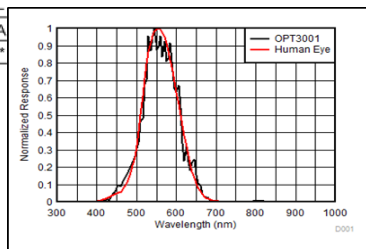
- Best Representation of Human Experience
 - Low measurement variation between light sources Florescent, Sunlight, Halogen, etc.
 - Especially good under dark glass
- Tight accuracy can eliminate need for calibration
- Interrupt system allows system to go to sleep until a relevant optical event
- Simpler Software, no req. for proper range selection
- Low operating current allows long operating life on small batteries

Applications

- Lighting, Building/Home Automation
- Any Lit Screen Exposed to Varied Lighting
- Any Lighting Control Changing with Ambient
- HMI: Displays Intensity Control
- Automotive and Consumer



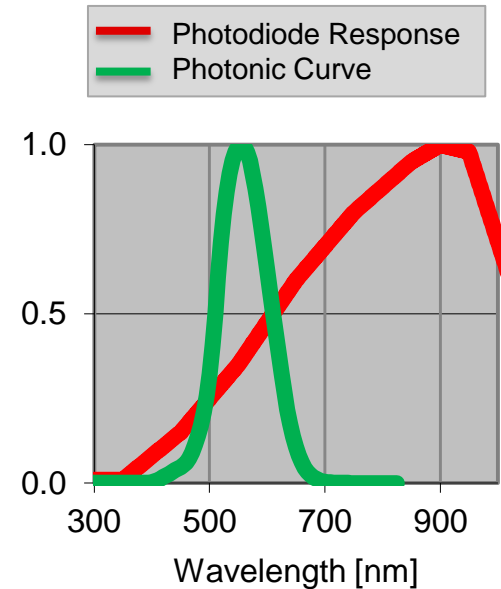
HMI POS/ vending machines	Lighting, Building/Home Automation Home Automation Traffic Lights	Consumer
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Human Eye vs OPT3001

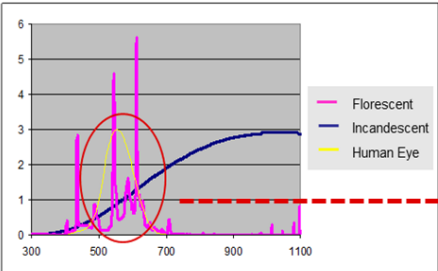
Why Not a Photodiode?

- Spectral sensitivity does not match human eye
- Strong IR sensitivity can result in larger errors on IR intensive light sources (sun, incandescent, halogen)
- Trans-impedance amplifier can be challenging to design
- Difficult to measure low light levels due to leakage currents (dark currents)

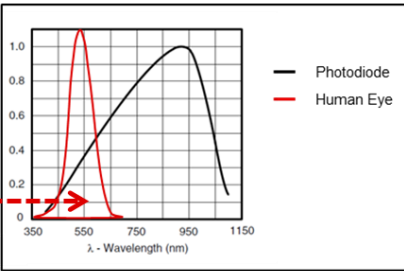


OPT3001 Benefits

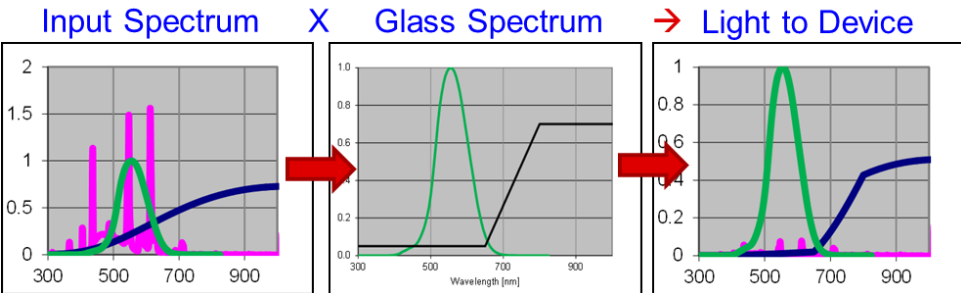
- Human Eye Response
- Improved user experience
- Accurate measurement of ambient light



Light Spectrum of Real World



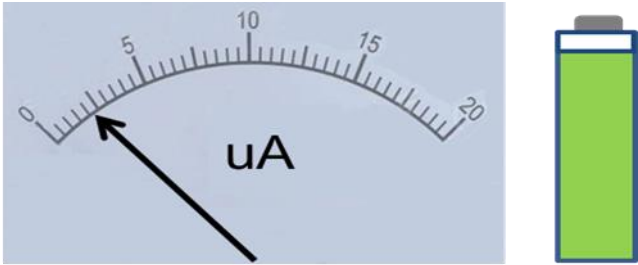
Human Eye vs Photodiode



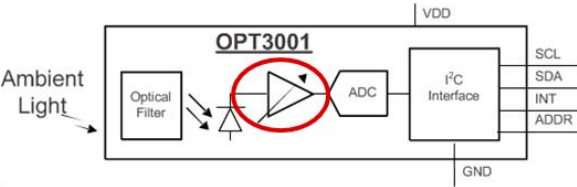
- Dark Glass transmits IR
- Sources like Incandescent has high IR
- OPT3001's excellent IR rejection helps prevent erroneous reading of light level

OPT3001 Benefits

- Ultra-low power → extends battery life and enables frequent light measurement



OPT3001 is ~2uA Operational current



- Auto-gain setting feature helps adjust internal setting automatically based on input light level
- No additional adjustment required
- Always in optimal range with good resolution and tight accuracy

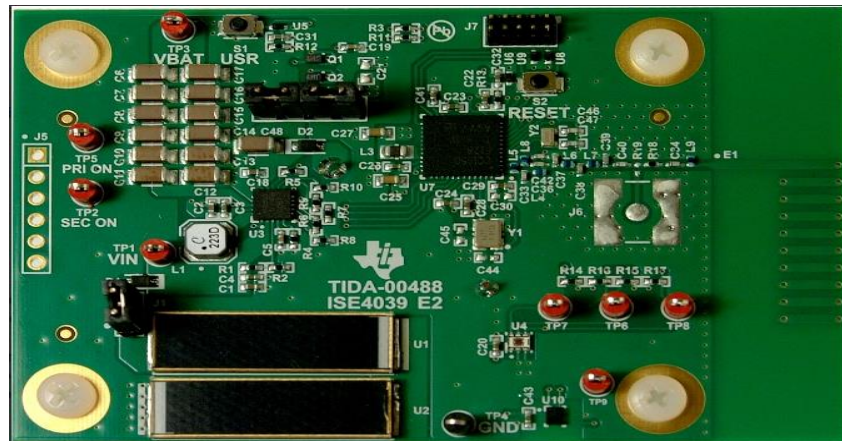
TIDA 00488: Energy Harvesting Ambient Light and Environment Sensor Node for Sub-1GHz Networks Reference Design

Description:

Uses ultra-low power and a renewable method of wireless environmental sensing using daylight energy harvesting. Senses natural ambient light coming into the building to precisely control the building's lighting systems.

Features:

- Long backup battery life (up to 10 years) in interrupt mode
- Senses natural ambient light coming into a building to precisely control the building's lighting systems
- Monitors temperature and relative humidity in addition to ambient light



Applications:

- Energy Harvesting
- Environmental sensor

Resources:

- <http://www.ti.com/tool/TIDA-00488>

3D Time of Flight Solutions (ToF) for Occupancy Detection

Occupancy Detection – Use Cases

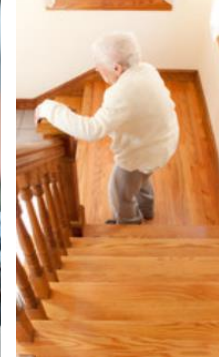
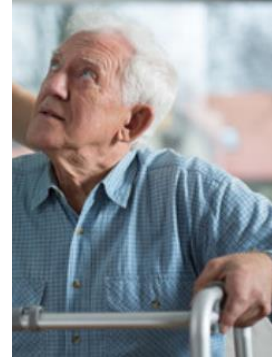
Surveillance



Note:

\$45B lost due to theft and fraud in US stores ⁽¹⁾

Home Monitoring for Elderly & Patients



Note:

1.8M elderly Americans treated for fall injury in 2004 ⁽²⁾

Demand Controlled Ventilation



Note:

In 2013, US building energy cost topped \$321Billion

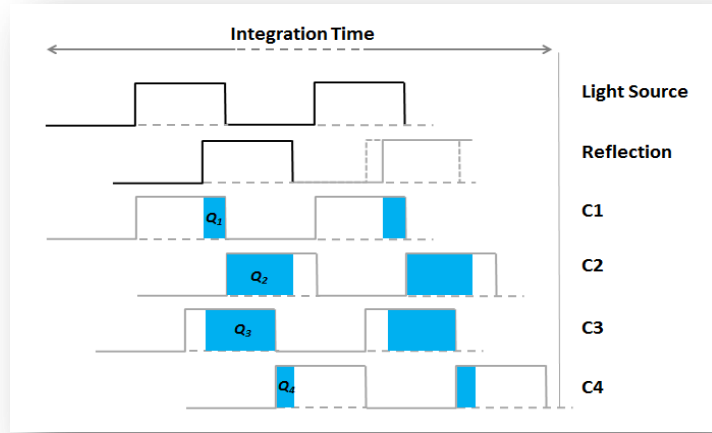
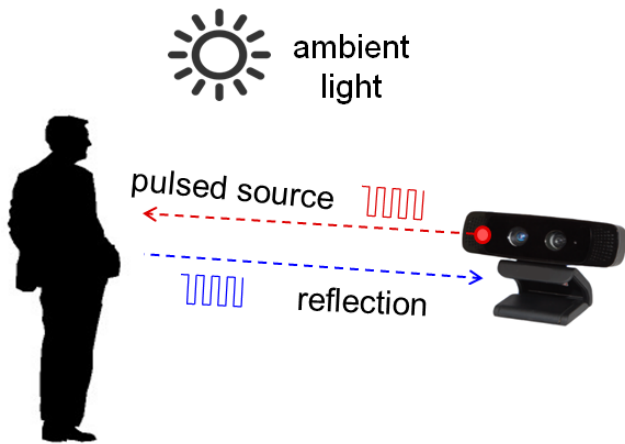
Queue/Checkout Line Monitoring



Note:

Excessively long line may lead to a loss of business

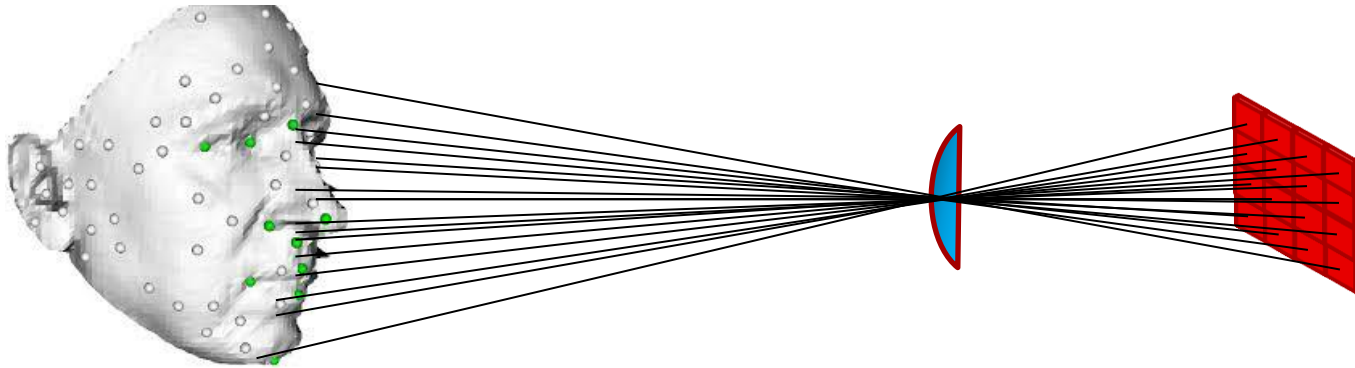
Theory of operation



$$\phi = \arctan\left(\frac{Q_3 - Q_4}{Q_1 - Q_2}\right) \quad d = \frac{c}{2f} \cdot \frac{\phi}{2\pi}$$

Distance measured by emitting a modulated light and measuring phase delay of returned light

How 3D Time of Flight Sensor Works



Single pixel measures distance to a single point

An array of pixels are used to map a region

ToF Camera Output

The screenshot displays the Voxel Viewer software interface, showing the output of a Time-of-Flight (ToF) camera. The main window displays a 3D point cloud of a person sitting at a desk. On the left, there are two smaller windows: 'Phase' showing a color-coded depth map and 'Amplitude' showing a grayscale image of the person. Below these is a 'Data Flow Diagram' showing the processing pipeline from raw frames to a point cloud. On the right, there are 'Frequently Used Parameters' for various settings like range, power, and integration time. The bottom status bar shows device connection and statistics.

Phase

Threshold: [Slider]

Amplitude

Threshold: [Slider]

Point Cloud

Depth Threshold: [Slider]

Frequently Used Parameters

Unambiguous Range (unambiguous_range)

double_min = True
max_freq1 = 40.000%
max_freq2 = 5.000%
sub_range_min_max = 2 (2)
max_freq2 = 50.000%
nb = 2
nb = 3
create_3D_obj_enable = False
display_3D_obj = 2

Illumination Power (Run_power_percentage)

[Slider] 100 %
Run_power = 8000mW

Integration Duty Cycle (intp_time)

[Slider] 20 %
Integration time = 5.12 ms

Video Mode

[Slider] 10.00 fps

Region of Interest

[Box] 0 x 0 300

Data Flow Diagram

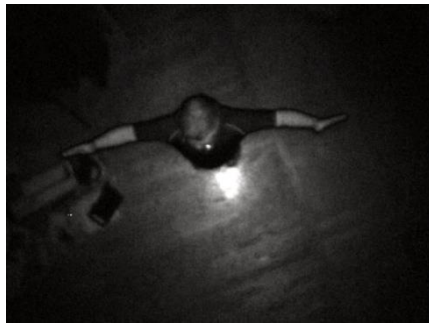
```
graph LR; A[Raw Frame (processor)] --> B[Raw Frame (processor)]; B --> C[Raw Frame (processor)]; C --> D[Voxel: MedianFilter (processor)]; D --> E[Voxel: TemporalMedianFilter (processor)]; E --> F[Depth Frame]; F --> G[Depth Frame]; G --> H[Point Cloud Frame]; H --> I[Point Cloud Frame];
```

Watch List Data Flow Diagram Log

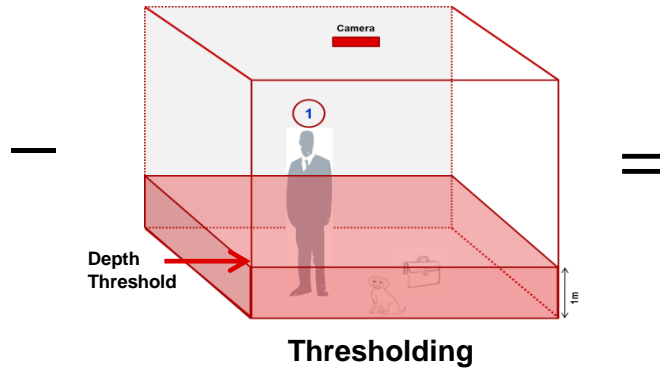
Device connected [x] Temporal Statistics

8 (289, 0) -> Amp: 1.00; Phase: 120; Sub: 1.00; Z: 1.00; TEXAS INSTRUMENTS

Figure-Ground Separation (Top View)

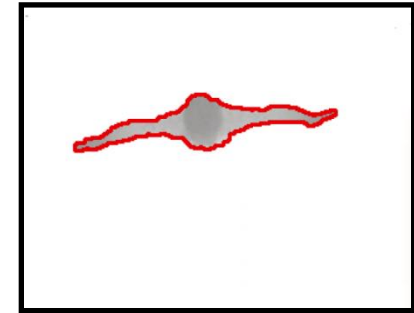


Sampled Image



Thresholding

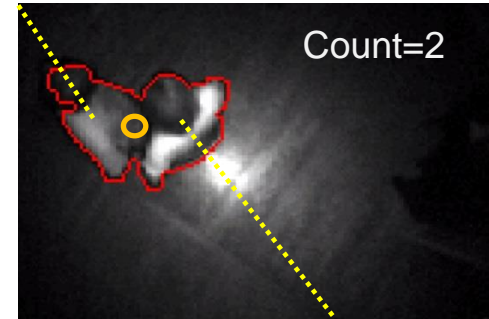
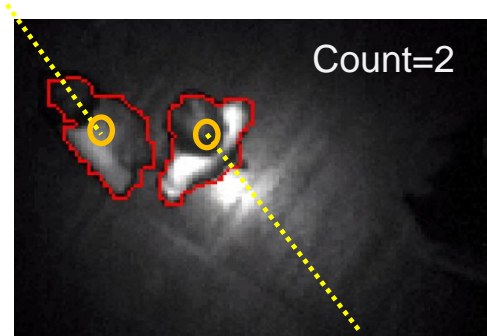
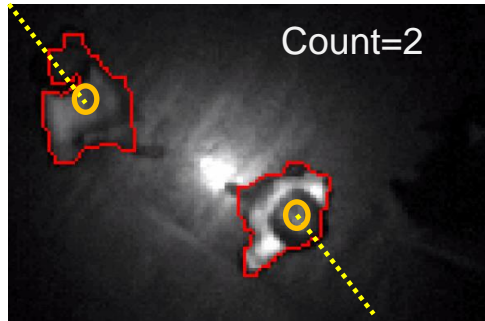
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Foreground

- Find the “bodies” in the image using depth as threshold
- One can generally assume the pixel closest to the camera is the head
- If necessary, crop out any surrounding pixels violating this assumption

Keypoints Tracking

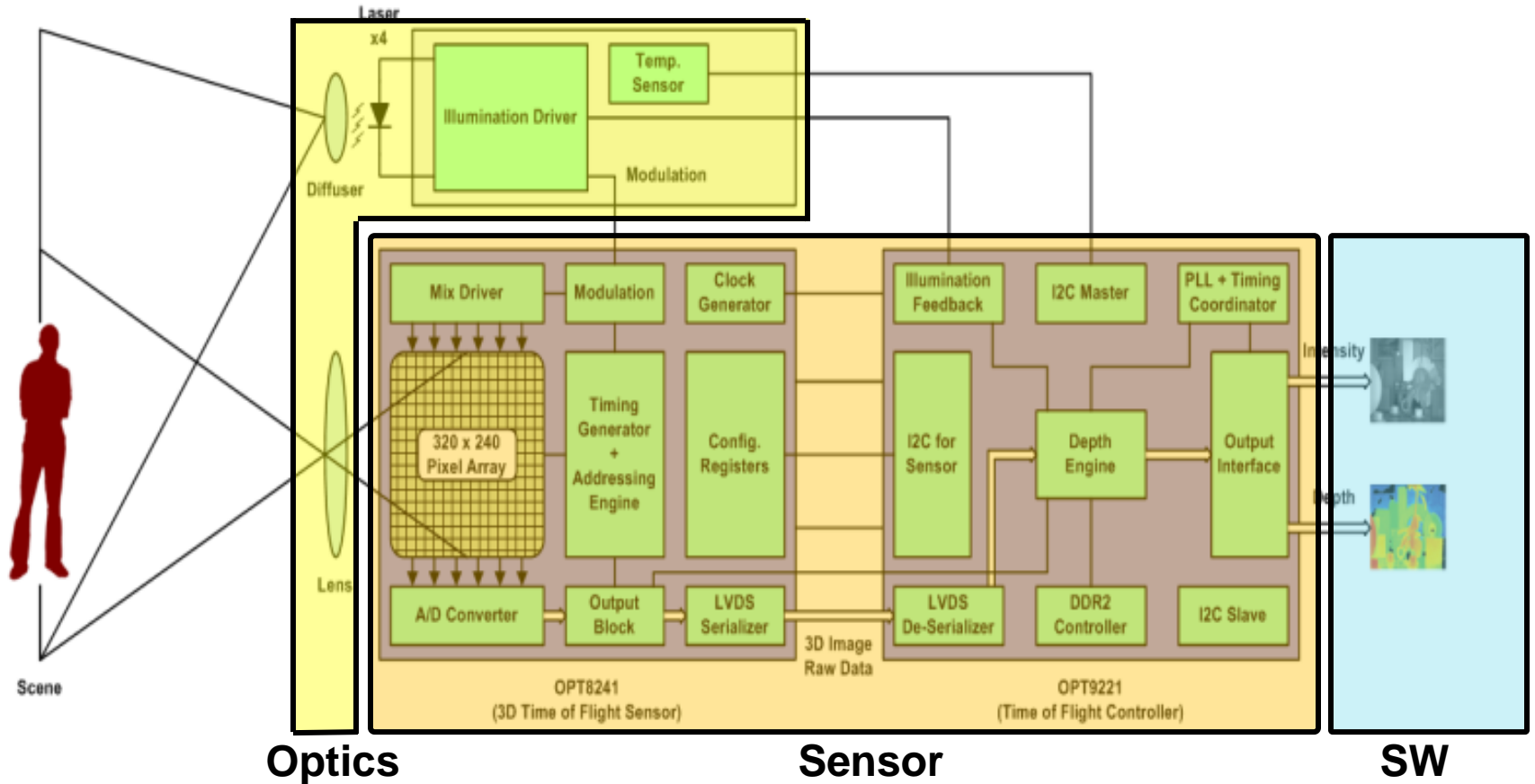


- Trajectory is a history of keypoint position
- For each frame, each keypoint is matched to the nearest trajectory
- Number of active trajectories indicates number of persons
- Mismatching #keypoints and #trajectories reconciled based on known constraints



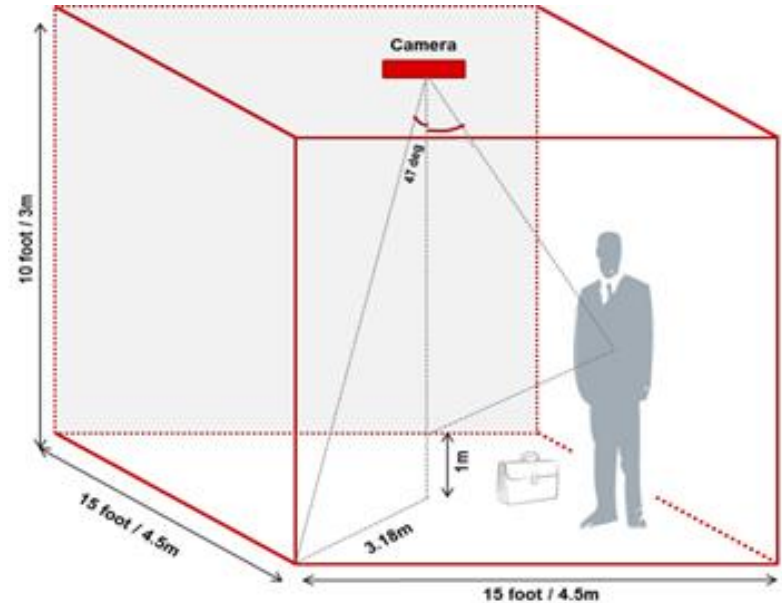
Video showing side view person

Typical System Diagram

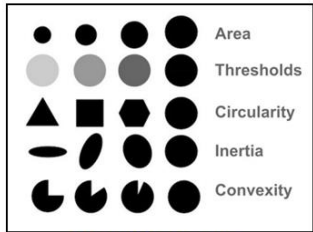
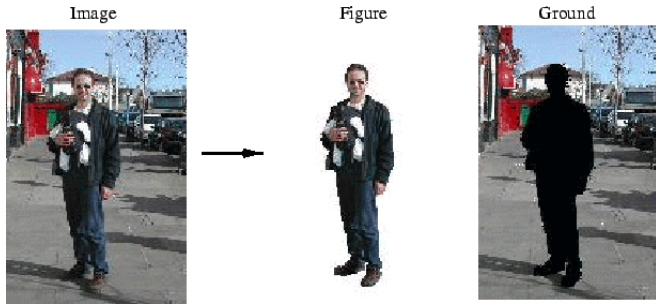


Choosing the Right Resolution

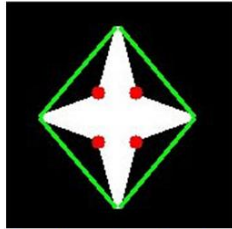
- The smallest object that can be seen from the camera theoretically is dictated by:
 - Field of View (FOV)
 - Pixel Resolution
- Presence of noise requires smallest object to be greater than a pixel



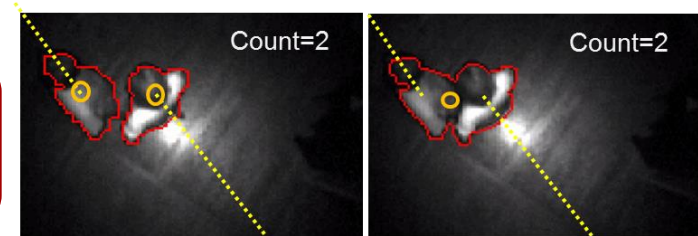
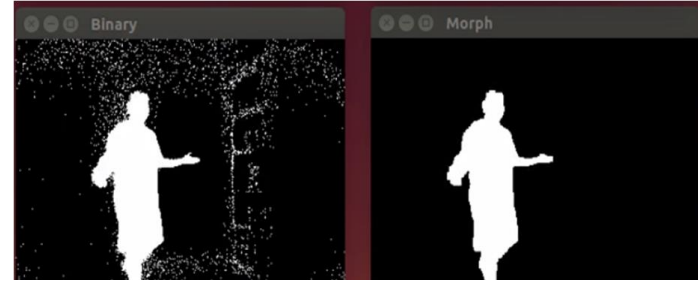
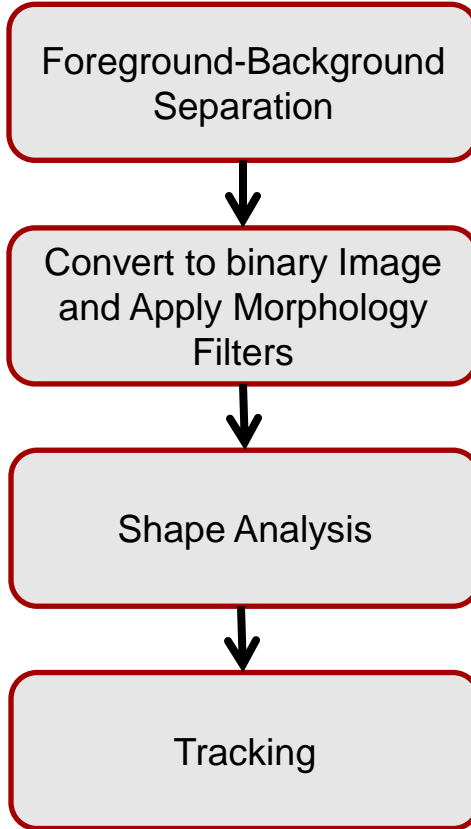
Algorithms



Blob Analysis



Contour Analysis



TI Design (TIDA-00750): People Counter for HVAC

Description:

This is a 3D Time of Flight based occupancy detection reference design that is used for people counting.

Features:

- Configurable response time, occupancy data available in real-time or periodically
- Wide field of View: $H74.4^\circ \times V59.3^\circ$
- Being independent of ambient light, 3D ToF camera can even see in the dark
 - Auto-illumination
 - Four NIR lasers provide large illumination area
 - Short diffused laser pulses inherently eye-safe
- Runs on an embedded platform

<http://www.ti.com/tool/TIDA-00750>

The screenshot shows the TI Design page for TIDA-00750. At the top, it says "TI Designs" and "People Counting for Demand Controlled Ventilation Using 3D Time-of-Flight (ToF) Reference Design". Below this is the Texas Instruments logo. The page is divided into several sections: "TI Designs" (describing the subsystem solution), "Design Resources" (listing folders for TIDA-00750, OPT8241, AM337x, and MYIR AM437x), "Design Features" (listing accuracy, response time, field of view, and independence from ambient light), "Design Resources" (listing folders for design, product, and tool), "Featured Applications" (listing HVAC, elevators, machine vision, etc.), and "ASK Our E2E Experts" (with a community link). At the bottom, there is a block diagram of the system and a photo of the people counter in operation, showing red outlines of people.

TI Designs
People Counting for Demand Controlled Ventilation Using 3D ToF reference design is a subsystem solution that uses TI's 3D ToF image sensor combined with tracking and detection algorithms to count the number of occupants present in a given area with high resolution and accuracy. The sensor technology is developed in standard CMOS, allowing systems to achieve very high integration at a low cost. Because ToF image sensors process visual data in three dimensions, the sensor can detect the exact shape of a human body as well as track movement and locate people with unprecedented precision, including subtle movement changes. For this reason, ToF cameras are potentially capable of performing real-time people counting and people tracking functions much more effectively than traditional surveillance cameras and video analytics.

Design Resources
[TIDA-00750](#) Design Folder
[OPT8241](#) Product Folder
[OPT8241](#) Product Folder
[AM337x](#) Product Folder
[OPT8241-CDK-EVM](#) Tool Folder
[MYIR AM437x](#) Tool Folder
[EVMs](#) Tool Folder

Design Features

- Accuracy: > 90%
- Configurable Response Time, Occupancy Data Available in Real-Time or Periodically
- Wide Field of View: $H74.4^\circ \times V59.3^\circ$
- Being Independent of Ambient Light, 3D ToF Camera Can See in the Dark
 - Auto-Illumination
 - Four NIR Lasers Provide Large Illumination Area
 - Short Diffused Laser Pulses Inherently Eye-Safe
- Unlike CO2 Sensors, Performance Not Affected by Localized Elevated CO2 Concentration, EMI, or Presence of any Other Pollutants
- Runs on an Embedded Platform
- No Moving Part or Periodic Calibration

Featured Applications

- HVAC: Demand Controlled Ventilation
- Smart Elevator
- Machine Vision
- Object Detection
- Gesture Detection
- Robotics
- Building Safety and Security

ASK Our E2E Experts
[ASK Our E2E Experts](#)

TI E2E Community

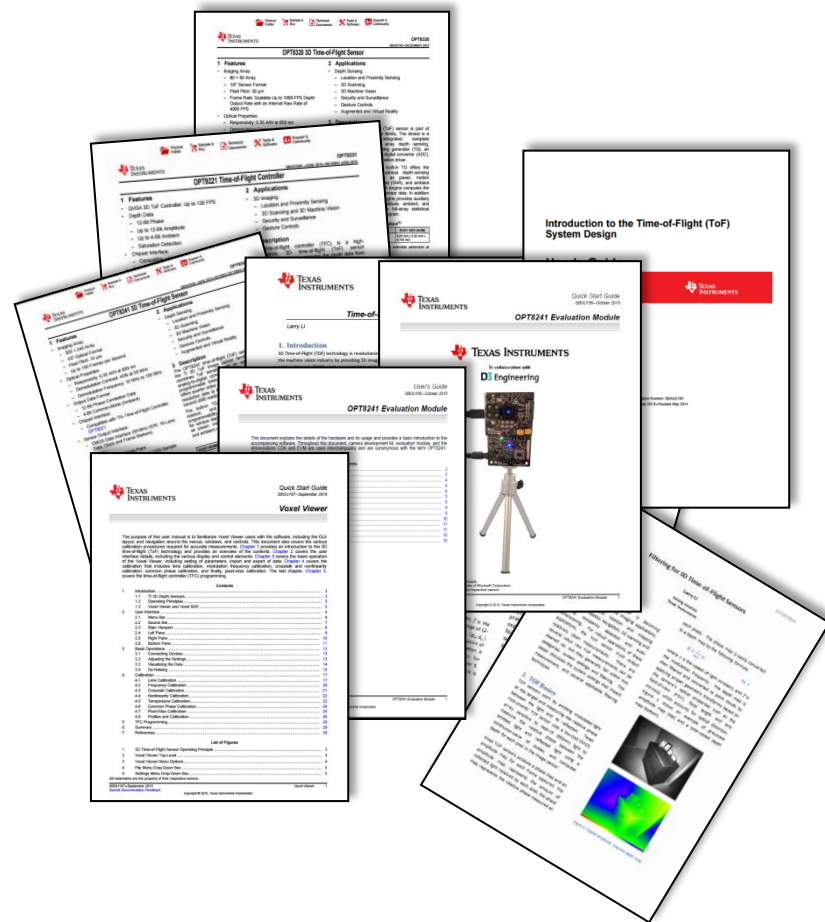
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TIDUBLSA—April 2016—Revised May 2016
Submit Documentation Feedback

People Counting for Demand Controlled Ventilation Using 3D Time-of-Flight (ToF) Reference Design
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Technical Documents

- Data Sheets
 - OPT8241
 - OPT9221
- White Papers
 - Time-of-Flight Camera—an Introduction
 - Time-of-Flight Camera Calibration
 - Filtering for 3D Time-of-Flight Sensors
- System Design Guide
- CDK Quick Start Guide
- CDK User Guide
- VoxelViewer User Guide
- “Getting Started with 3D Time-of-Flight Sensor” Video Series



<http://www.ti.com/3dtof>

Figure-Ground Separation (Side View)



Sampled Image

—



Background

=



Foreground

- Finding “people” in a side view requires sampling of *background*
- Subtracting background from sampled image will result in just the foreground, which contains object of interest
- Background can be updated by pixel-wise median filter

Questions?

Thank you for attending

www.ti.com/sensors