

Introduction to RTD measurement circuits

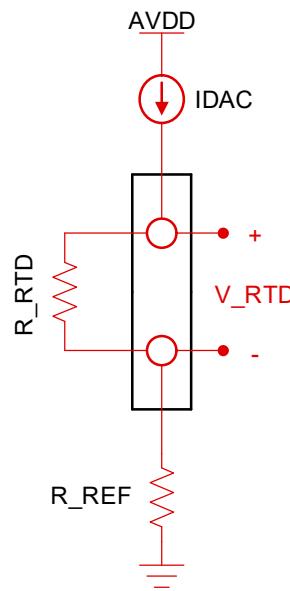
TI Precision Labs – ADCs

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Presented by Josh Brown

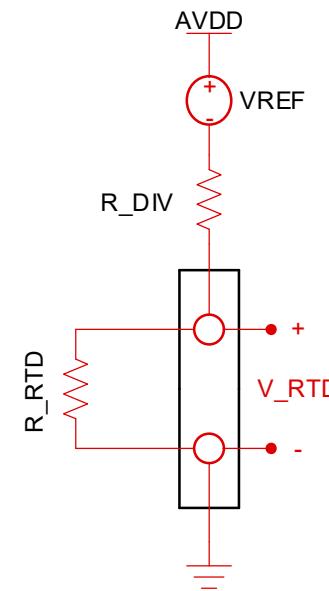
RTD biasing schemes

Constant current



$$V_{RTD} = IDAC * R_{RTD} \rightarrow \text{linear equation}$$

Constant voltage

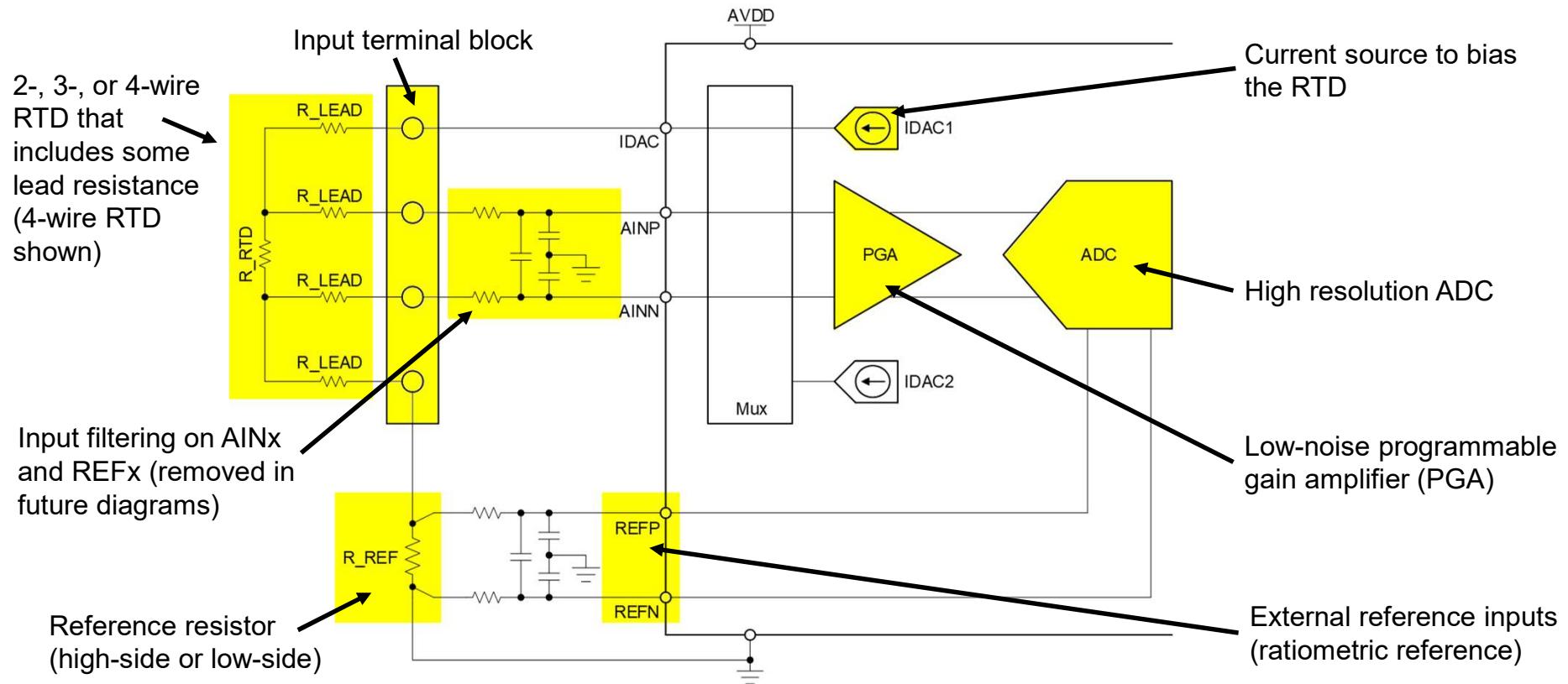


$$V_{RTD} = VREF \frac{R_{RTD}}{R_{RTD} + R_{DIV}} \rightarrow$$

Nonlinear equation due
to the R_{RTD} term in
the denominator

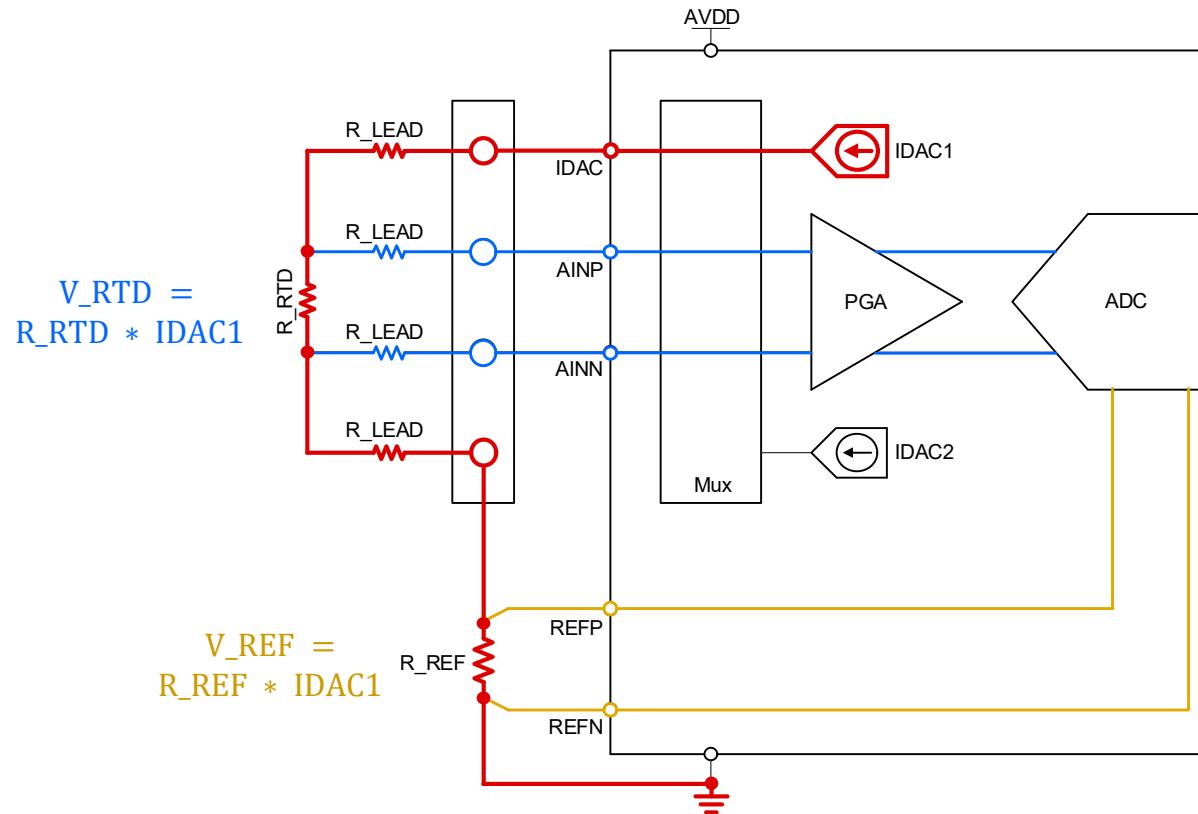
RTD measurement circuit basics

Basic 4-wire RTD measurement system using a low-side R_REF



IDAC biasing & ratiometric measurements

Basic 4-wire RTD measurement system using a low-side R_REF



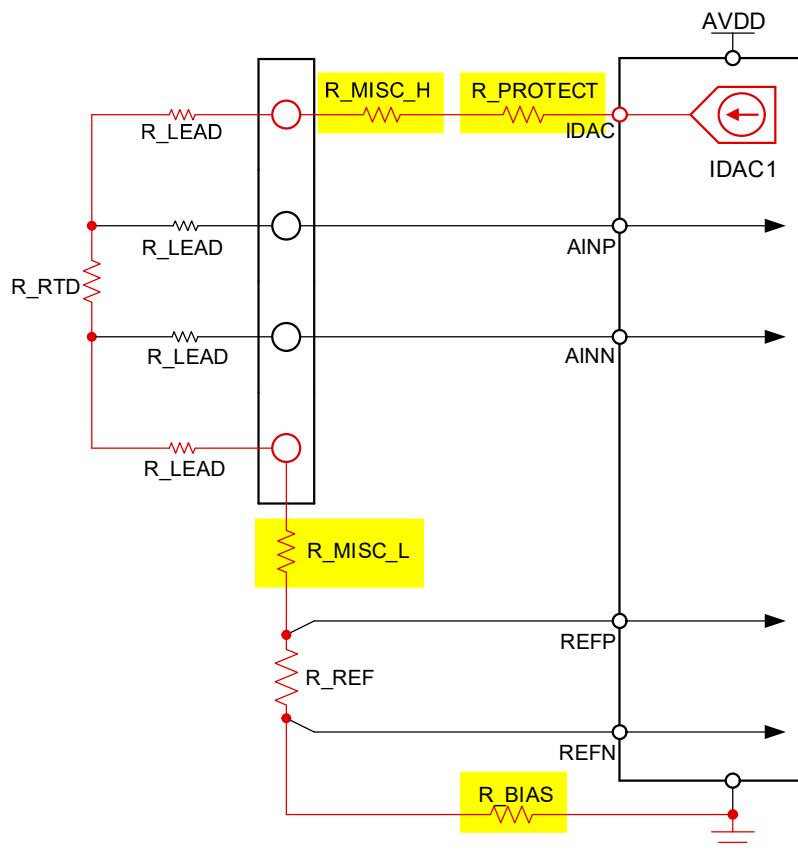
$$\text{ADC Code} \propto \frac{V_{RTD}}{V_{REF}}$$

$$\frac{V_{RTD}}{V_{REF}} = \frac{R_{RTD} * IDAC1}{R_{REF} * IDAC1}$$

$$= \frac{R_{RTD}}{R_{REF}}$$

Output code is independent of
IDAC1 value = ratiometric

Total circuit resistance (R_TOTAL)



Additional sources of circuit resistance

Resistance	Description
R_PROTECT	Limits current into IDAC pin in case of an overvoltage event due to miswiring
R_MISC_H	Any additional miscellaneous resistance in the circuit <i>before</i> the RTD e.g. multiplexer R_{ON}
R_MISC_L	Any additional miscellaneous resistance in the circuit <i>after</i> the RTD e.g. multiplexer R_{ON}
R_BIAS	Bias resistor helps shift the input signal into the common-mode range of the integrated PGA



$$R_{TOTAL} = R_{PROTECT} + R_{MISC_H} + 2 * R_{LEAD} + R_{RTD} + R_{MISC_L} + R_{REF} + R_{BIAS}$$

Why is R_TOTAL important?

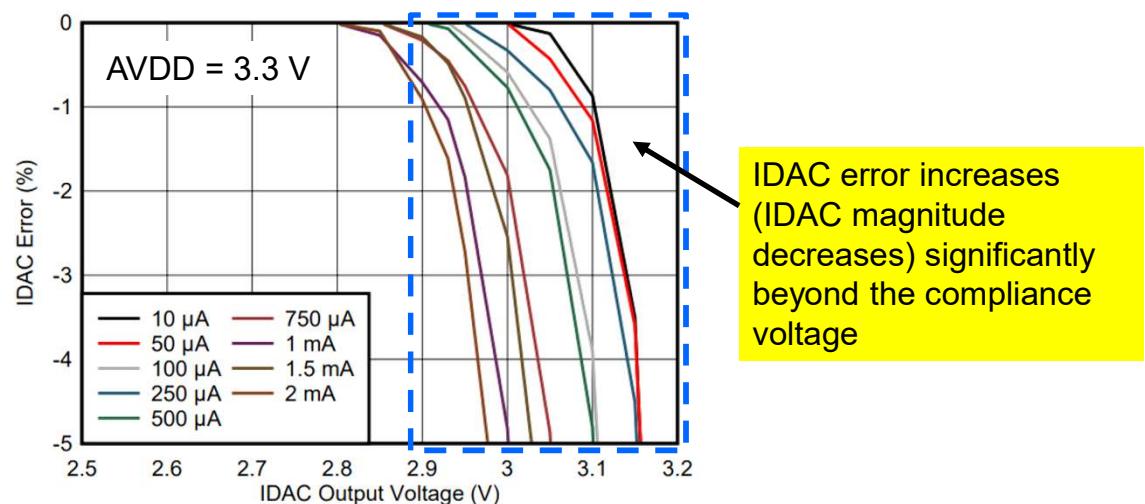
IDAC compliance voltage

Compliance voltage:

- Headroom required between IDAC output and AVDD to maintain constant current
- Voltage at IDAC output pin = $R_{TOTAL} * IDAC$
- Typically specified to 0.1% deviation
- May depend on the selected IDAC current

ADS124S08 IDAC Accuracy vs Compliance Voltage

Parameter	Condition	MIN	TYP	MAX	Unit
Current settings		10, 50, 100, 250, 500, 750, 1000, 1500, 2000			µA
Compliance voltage	10 µA to 750 µA, 0.1% deviation	AVSS		AVDD – 0.4	V
	1 mA to 2 mA, 0.1% deviation	AVSS		AVDD – 0.6	



Code to RTD resistance to temperature

$$\text{ADC code} = 2^N * \text{Gain} \frac{V_{\text{RTD}}}{A * V_{\text{REF}}}$$

$$\frac{V_{\text{RTD}}}{V_{\text{REF}}} = \frac{\text{IDAC} * R_{\text{RTD}}}{\text{IDAC} * R_{\text{REF}}}$$

$$\text{ADC code} = 2^N * \text{Gain} \frac{R_{\text{RTD}}}{A * R_{\text{REF}}}$$

$$R_{\text{RTD}} = \frac{\text{ADC code} * A * R_{\text{REF}}}{2^N * \text{Gain}}$$

- N = ADC resolution
- A = constant → for example:
 - A = 4 if FSR = $\pm 2 * V_{\text{REF}} / \text{gain}$
 - A = 2 if FSR = $\pm V_{\text{REF}} / \text{gain}$

Callendar-Van Dusen equation

For T < 0°C:

$$R_{\text{RTD}} = R_0 * (1 + (A * T) + (B * T^2) + [(C * T^3) * (T - 100)])$$

For T > 0°C:

$$R_{\text{RTD}} = R_0 * [1 + (A * T) + (B * T^2)]$$

R_{RTD} look-up table (LUT)

°C	Temperature in °C									
	0	1	2	3	4	5	6	7	8	9
-50	80.31									
-40	84.27	83.87	83.48	83.08	82.69	82.29	81.89	81.50	81.10	80.70
-30	88.22	87.83	87.43	87.04	86.64	86.25	85.85	85.46	85.06	84.67
-20	92.16	91.77	91.37	90.98	90.59	90.19	89.80	89.40	89.01	88.62
-10	96.09	95.69	95.30	94.91	94.52	94.12	93.73	93.34	92.95	92.55
0	100.00	99.61	99.22	98.83	98.44	98.04	97.65	97.26	96.87	96.48
0	100.00	100.39	100.78	101.17	101.56	101.95	102.34	102.73	103.12	103.51
10	103.90	104.29	104.68	105.07	105.46	105.85	106.24	106.63	107.02	107.40
20	107.79	108.18	108.57	108.96	109.35	109.73	110.12	110.51	110.90	111.29
30	111.67	112.06	112.45	112.83	113.22	113.61	114.00	114.38	114.77	115.15
40	115.54	115.93	116.31	116.70	117.08	117.47	117.86	118.24	118.63	119.01
50	119.40	119.78	120.17	120.55	120.94	121.32	121.71	122.09	122.47	122.86
60	123.24	123.63	124.01	124.39	124.78	125.16	125.54	125.93	126.31	126.69
70	127.08	127.46	127.84	128.22	128.61	128.99	129.37	129.75	130.13	130.52
80	130.90	131.28	131.66	132.04	132.42	132.80	133.18	133.57	133.95	134.33
90	134.71	135.09	135.47	135.85	136.23	136.61	136.99	137.37	137.75	138.13
100	138.51	138.88	139.26	139.64	140.02	140.40	140.78	141.16	141.54	141.91

LUT linear interpolation

R_{RTD} look-up table (LUT)

°C	Temperature in °C									
	0	1	2	3	4	5	6	7	8	9
Resistance in Ω										
-50	80.31									
-40	84.27	83.87	83.48	83.08	82.69	82.29	81.89	81.50	81.10	80.70
-30	88.22	87.83	87.43	87.04	86.64	86.25	85.85	85.46	85.06	84.67
-20	92.16	91.77	91.37	90.98	90.59	90.19	89.80	89.40	89.01	88.62
-10	96.09	95.69	95.30	94.91	94.52	94.12	93.73	93.34	92.95	92.55
0	100.00	99.61	99.22	98.83	98.44	98.04	97.65	97.26	96.87	96.48
10	103.90	104.29	104.68	105.07	105.46	105.85	106.24	106.63	107.02	107.40
20	107.79	108.18	108.57	108.96	109.35	109.73	110.12	110.51	110.90	111.29
30	111.67	112.06	112.45	112.83	113.22	113.61	114.00	114.38	114.77	115.15
40	115.54	115.93	116.31	116.70	117.08	117.47	117.86	118.24	118.63	119.01
50	119.40	119.78	120.17	120.55	120.94	121.32	121.71	122.09	122.47	122.86
60	123.24	123.63	124.01	124.39	124.78	125.16	125.54	125.93	126.31	126.69
70	127.08	127.46	127.84	128.22	128.61	128.99	129.37	129.75	130.13	130.52
80	130.90	131.28	131.66	132.04	132.42	132.80	133.18	133.57	133.95	134.33
90	134.71	135.09	135.47	135.85	136.23	136.61	136.99	137.37	137.75	138.13
100	138.51	138.88	139.26	139.64	140.02	140.40	140.78	141.16	141.54	141.91

- Computationally simple
- Assumes linear response between two points

$$R_1 = 131.28 \Omega$$

$$(T_1 = 81^\circ\text{C})$$

$$R_{\text{MEAS}} = 131.5 \Omega$$

$$(T_{\text{MEAS}} = ?)$$

$$R_2 = 131.66 \Omega$$

$$(T_2 = 82^\circ\text{C})$$

Equation of a line**: $T_x = M * R_x + B$

Calculate the slope:

$$M = \frac{T_2 - T_1}{R_2 - R_1}$$

$$= \frac{82 - 81}{131.66 - 131.28} = 2.632 \frac{^\circ\text{C}}{\Omega}$$

Calculate y-intercept:

$$B = T_x - M * R_x$$

$$= 81^\circ\text{C} - 2.632 \frac{^\circ\text{C}}{\Omega} * 131.28 \Omega = -264.474^\circ\text{C}$$

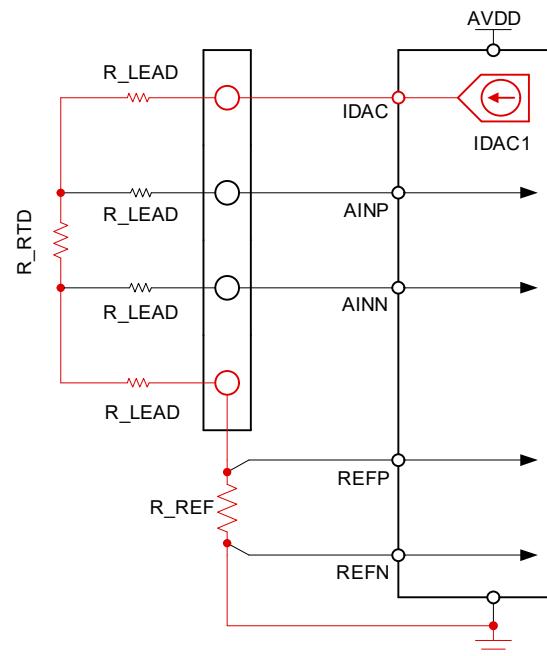
Calculate T_{MEAS} :

$$T_{\text{MEAS}} = 2.632 \frac{^\circ\text{C}}{\Omega} * R_{\text{MEAS}} - 264.474^\circ\text{C}$$

$$= 81.585^\circ\text{C}$$

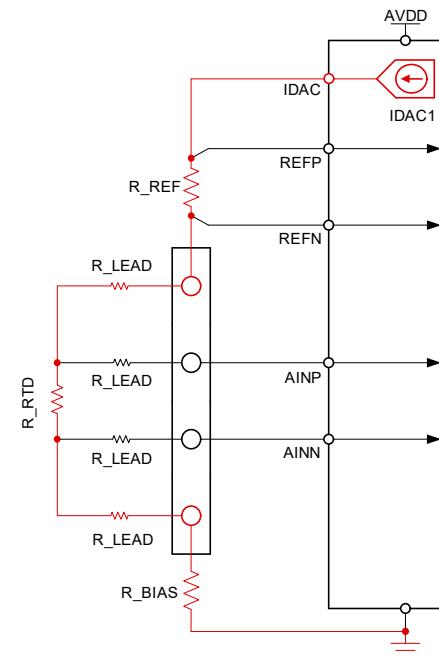
Low-side versus high-side reference resistor

Low-side R_REF (4-wire RTD)



- ✓ No bias resistor required
- ✗ No inherent IDAC protection

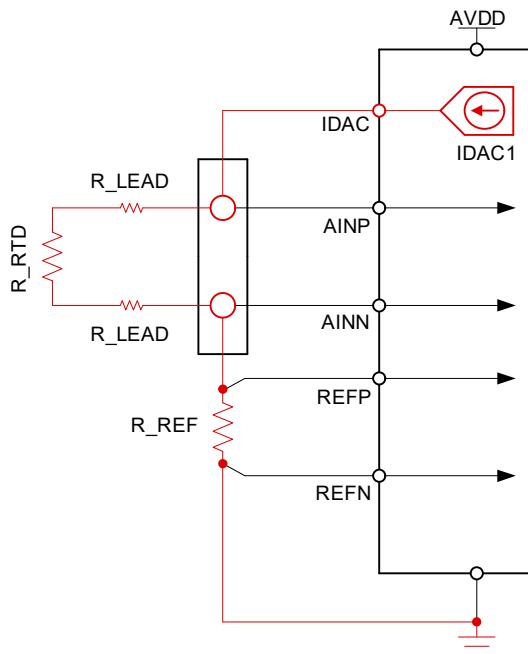
High-side R_REF (4-wire RTD)



- ✓ R_REF limits current into IDAC pin
- ✗ Can require extra bias resistor

2-, 3-, and 4-wire RTD wiring configurations**

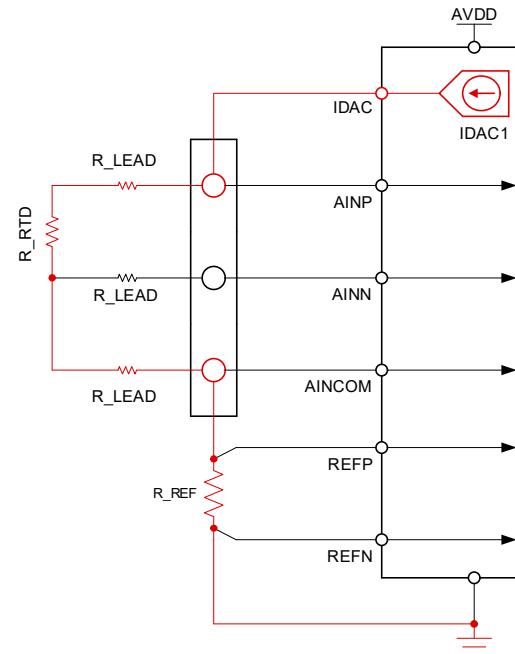
2-wire RTD



✓ Lowest cost

✗ No lead resistance cancellation

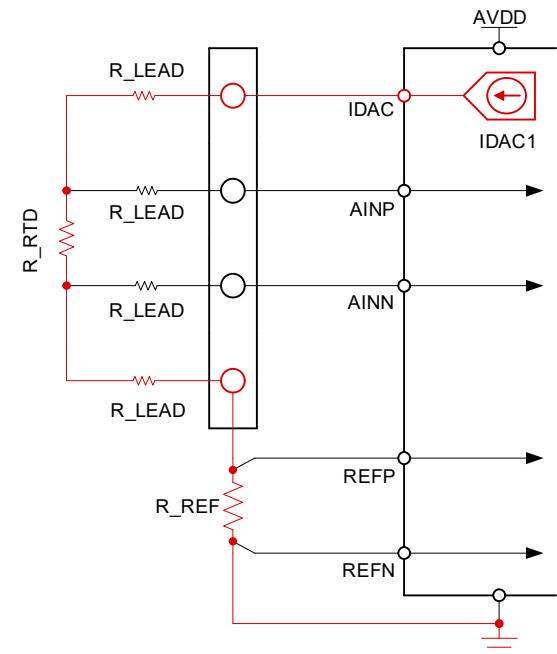
3-wire RTD



✓ Balances accuracy & cost

✗ IDAC mismatch error

4-wire RTD



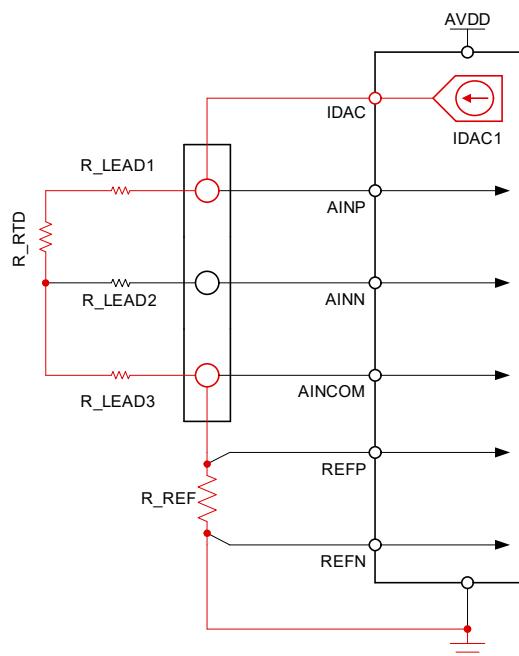
✓ Highest accuracy

✗ Most expensive

**Low-side R_REF shown; high-side R_REF is possible

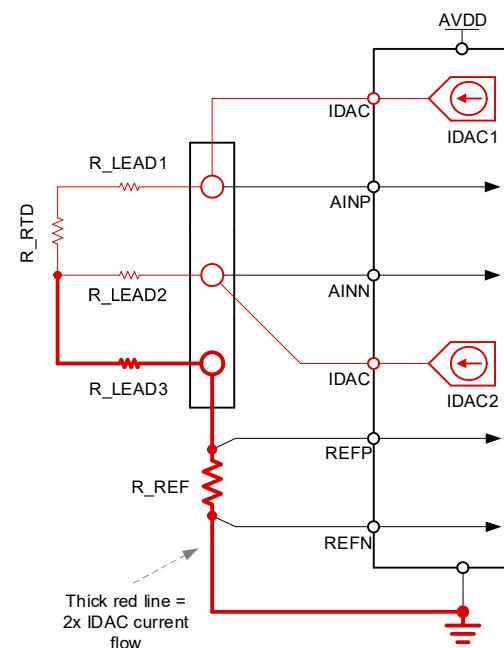
1x IDAC versus 2x IDACs for 3-wire RTDs

3-wire RTD using 1x IDAC**



- ✓ No IDAC mismatch errors
- ✗ Requires 2x measurements

3-wire RTD using 2x IDACs**



- ✓ Automatic lead resistance cancellation
- ✗ IDAC mismatch causes additional error

Additional information

RTD Design Guide = more detailed analysis of all RTD circuit configurations:

- 2-wire RTD w/ low-side R_REF
- 2-wire RTD w/ high-side R_REF
- 3-wire RTD w/ low-side R_REF and 1x IDAC
- 3-wire RTD w/ high-side R_REF and 1x IDAC
- 3-wire RTD w/ low-side R_REF and 2x IDACs
- 3-wire RTD w/ high-side R_REF and 2x IDACs
- 4-wire RTD w/ low-side R_REF
- 4-wire RTD w/ high-side R_R
- Multi-RTD systems



Application Report
SBAA275—June 2018

TEXAS INSTRUMENTS

A Basic Guide to RTD Measurements

Joseph Wu

ABSTRACT

RTDs, or resistance temperature detectors, are sensors used to measure temperature. These sensors are among the most accurate temperature sensors available, covering large temperature ranges. However, getting accurate measurements with precision analog-to-digital converters (ADCs) requires attention to detail in design of measurement circuit and calculation of the measurement. This application note starts with an overview of the RTD, discussing their specification, construction, and details in their use in temperature measurement. Different circuit topologies with precision ADCs are presented for different RTD configurations. Each circuit is shown with a basic design guide, showing calculations necessary to determine the ADC settings, limit measurement errors, and verify that the design fits in the operating range of the ADC.

Contents

1	RTD Overview.....	2
2	RTD Measurement Circuits.....	9
3	Summary	41

List of Figures

1	PT100 RTD Resistance From -200°C to 850°C	2
2	PT100 RTD Non-Linearity From -200°C to 850°C.....	3
3	Two-Wire, Three-Wire, and Four-Wire RTDs	4
4	Example of a Ratiometric RTD Measurement	4
5	Example of Lead Wire Resistance Cancellation.....	5
6	Swapping IDAC1 and IDAC2 to Chop the Measurement	6
7	Two-Wire RTD, Low-Side Reference Measurement Circuit	10
8	Two-Wire RTD, High-Side Reference Measurement Circuit	12
9	Three-Wire RTD, Low-Side Reference Measurement Circuit	14
10	Three-Wire RTD, Low-Side Reference Measurement Circuit With One IDAC Current Source	17
11	Three-Wire RTD, High-Side Reference Measurement Circuit	20
12	Four-Wire RTD, Low-Side Reference Measurement Circuit	23
13	Two Series Two-Wire RTD, Low-Side Reference Measurement Circuit.....	25
14	Two Series Four-Wire RTD, Low-Side Reference Measurement Circuit	27
15	Multiple Two-Wire RTDs Measurement Circuit.....	29
16	Multiple Three-Wire RTDs Measurement Circuit	31
17	Multiple Parallelized Four-Wire RTD Measurement Circuit	33
18	Universal RTD Measurement Interface With Low-Side Reference Circuit.....	35
19	Universal RTD Measurement Interface With High-Side Reference Circuit.....	38

For more detailed information, review TI's app note on RTD measurement circuits (SBAA275)

**Thanks for your time!
Please try the quiz.**

Quiz: Introduction to RTD measurement circuits

1. What does the IDAC compliance voltage specification indicate?
 - a) It provides the voltage range at the IDAC output pin over which the IDAC can maintain constant current, within some defined deviation
 - b) It shows that the IDAC is compliant with IEC test standards for electrical overstress
 - c) It indicates the range of current that the IDAC is capable of outputting
 - d) It is an indicator of how much temperature drift to expect in the IDAC
2. (T/F) The reference resistor (R_{REF}) does not need to have good accuracy as the ratiometric properties of the reference eliminates initial tolerance errors
 - a) True
 - b) False

Quiz: Introduction to RTD measurement circuits

3. One advantage of a high side reference resistor is that it can offer some protection against electrical overstress. What is a disadvantage to this method?
 - a) Input filter capacitors may be required for this method
 - b) An extra bias resistor can be required to keep the input in the proper common mode range
 - c) The common mode rejection of the ADC is impacted by this resistor
 - d) The voltage coefficient of this resistor can cause nonlinearity
4. (True/False) When using a ratiometric reference, errors in the biasing current cancel out because the RTD output and reference scale proportionately.
 - a) True
 - b) False

Thanks for your time!



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