

TI mmWave Sensors IWR14xx/16xx Device Overview

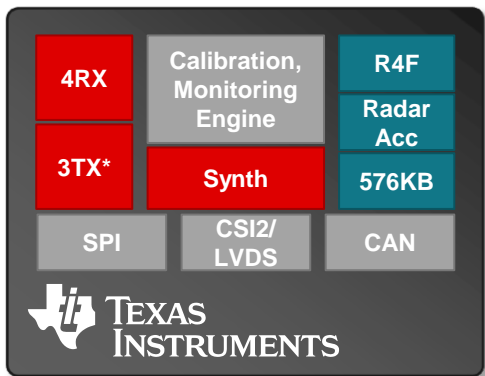
Agenda

- Device Overview
 - TI mmWave sensor portfolio
 - IWR1xx Signal processing chain
 - Example System topologies
- Functional Blocks
 - Device Block Diagram
 - RF and Analog Subsystem
 - Radar Subsystem (aka BSS or **BIST** Subsystem)
 - Master Subsystem (MSS)
 - DSP Subsystem (DSS: IWR16xx only)
 - Radar Hardware accelerator
- Boot modes
- Software Platform

Device Overview

mmWave Sensors – 76-81 GHz Portfolio

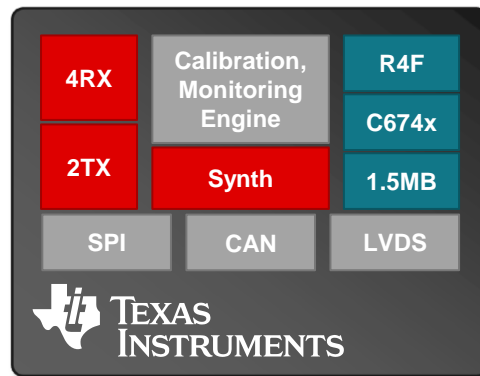
IWR1443



mmWave Sensor + HW Accelerator

- Use Case
 - Satellite Sensor with MCU
 - 4X IWR14 + Central Processor
 - 2X IWR14 + Central Processor
 - Entry-level Single-chip Sensor
 - Power-optimized applications
 - HW acceleration for limited processing

IWR1642



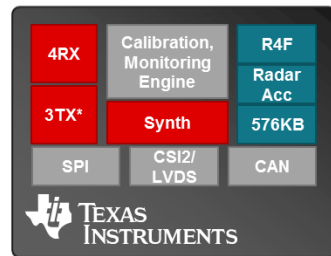
mmWave Sensor + DSP

- Use Cases
 - Full functionality single-chip radar
 - Increased on-board memory for higher range and resolution measurement
 - On-chip DSP for advanced algorithms

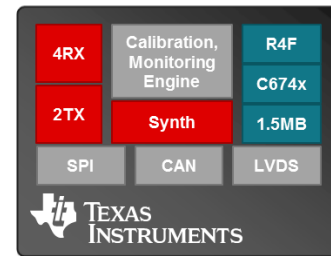
Key Features

- FMCW Radar transceiver with 76-81 GHz operating frequency with 4 GHz chirp bandwidth
- MIMO: Up to three transmitter and four receiver chains
- Programmable, flexible chirp profiles for both long and short range sensing in the same radar frame
- 200MHz ARM Cortex R4F MCU for user application processing
- Radar Hardware accelerator for FFT and CFAR processing (14xx only)
- C674x DSP for FMCW signal processing and advanced tracking, clustering and object classification (I16xx only)
- Continuous monitoring and calibration of Analog/RF through a second dedicated Cortex R4F MCU
- CAN support for ECU Interface
- QSPI Serial Flash support for autonomous boot
- MIBSPI, SPI, I2C, and UART Serial Interfaces Support
- CSI2 (IWR14xx only) and LVDS interfaces for high speed raw data transfer

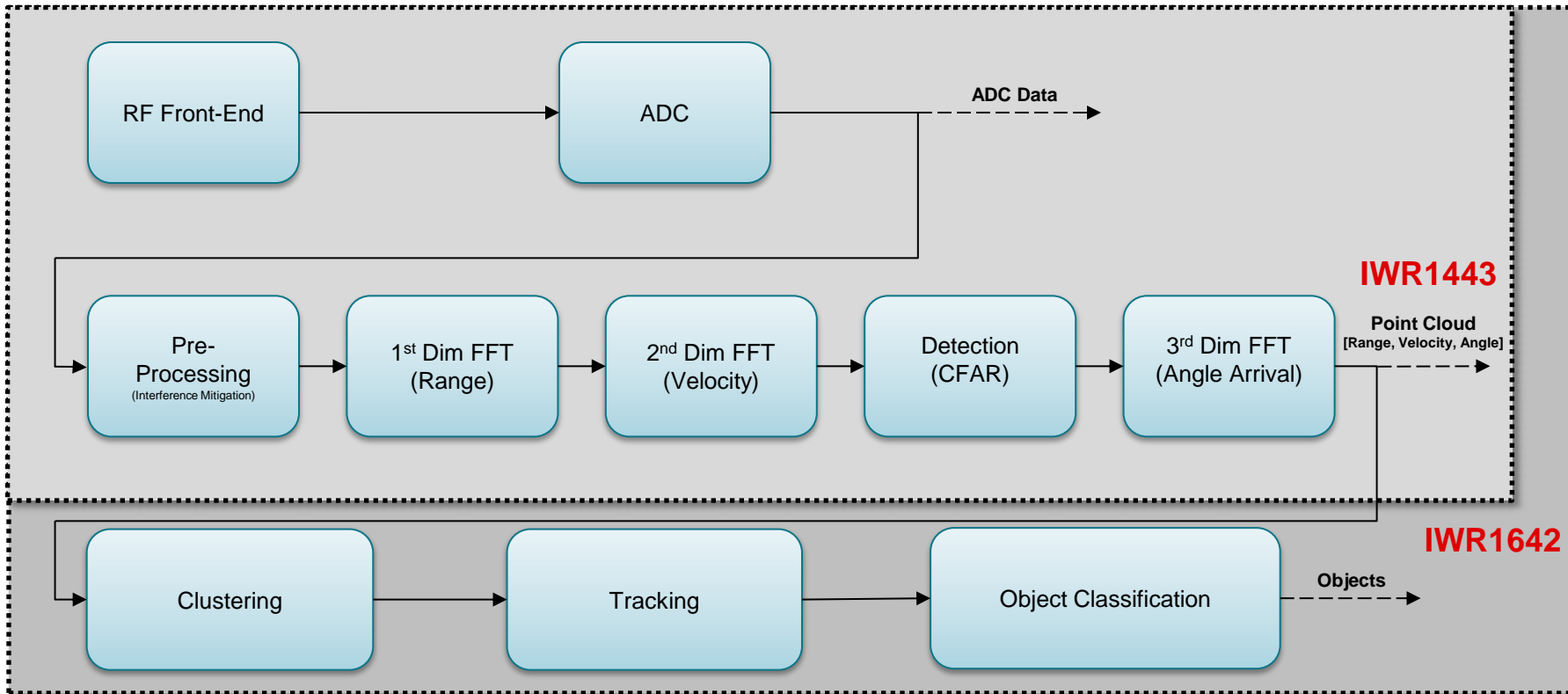
IWR1443



IWR1642

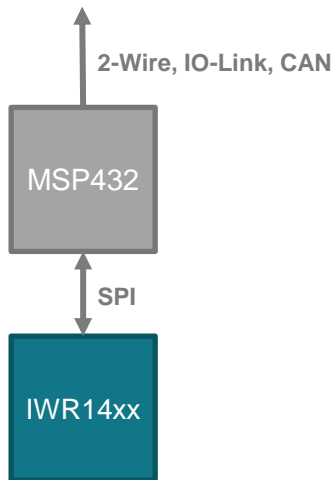


IWR1xxx mmWave Signal Processing

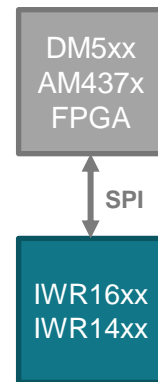


Example System Topologies

Fluid Level Sensing

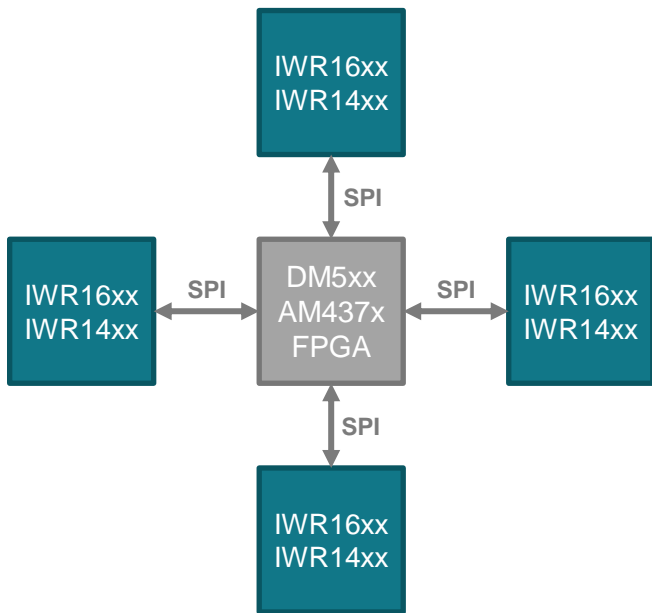


Transport and Mobile Robots: Front-View and Landing

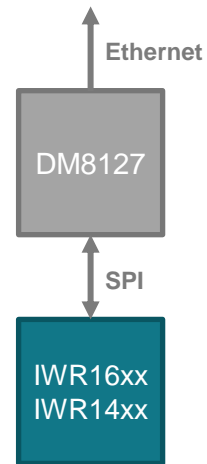


Example System Topologies

Transport and Mobile Robots: Surround Sensing

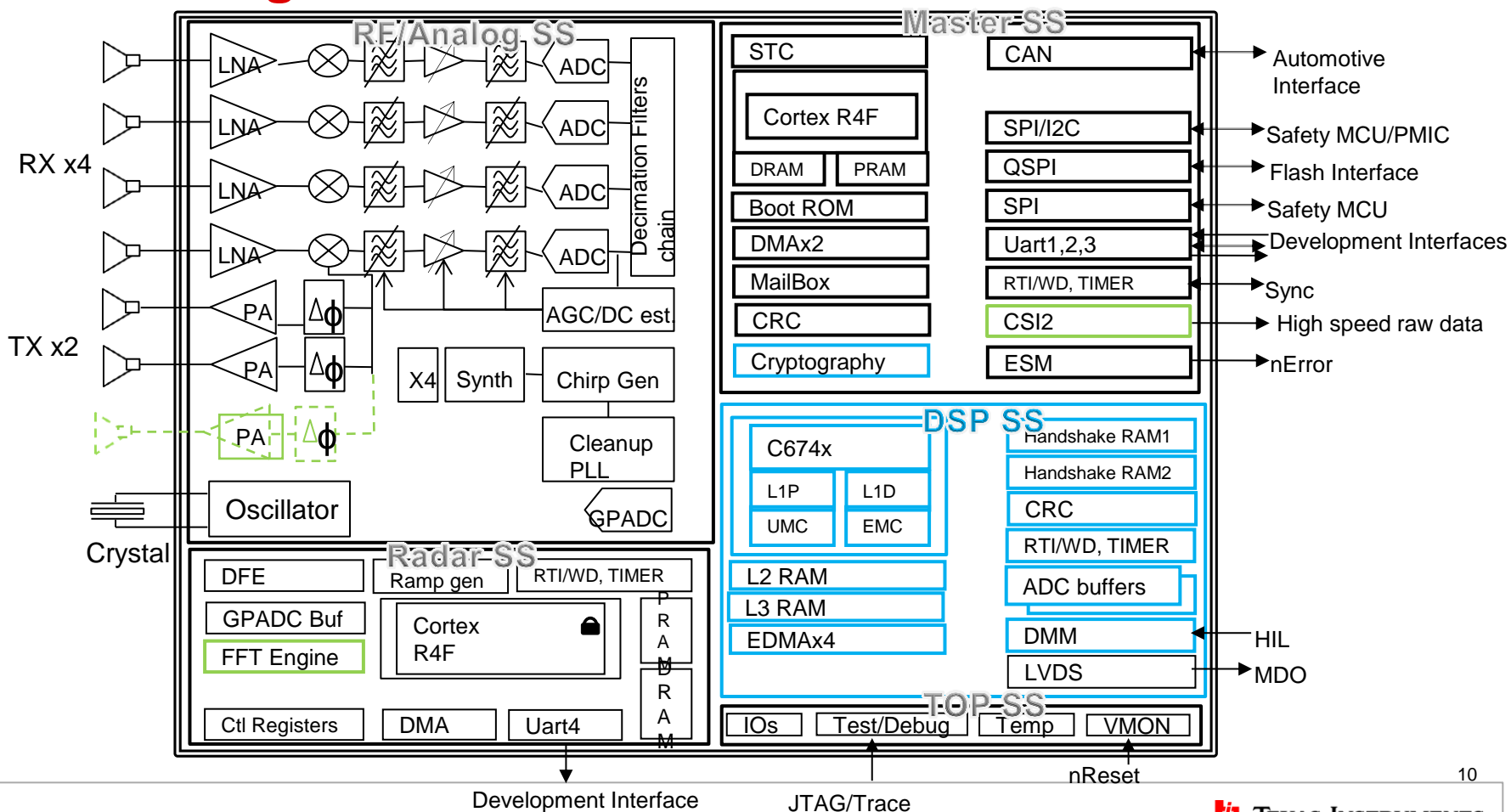


Traffic Monitoring

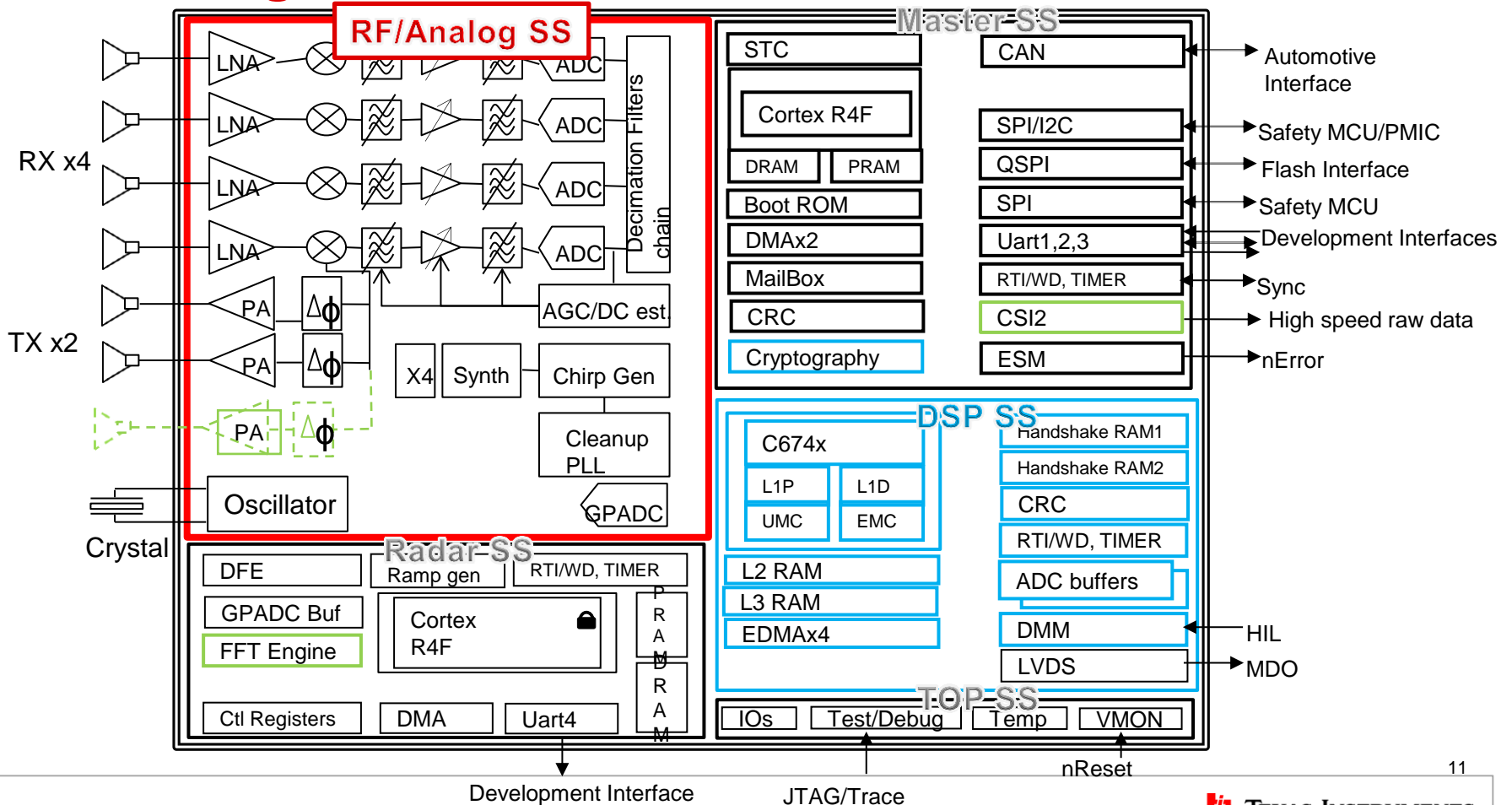


Functional Blocks

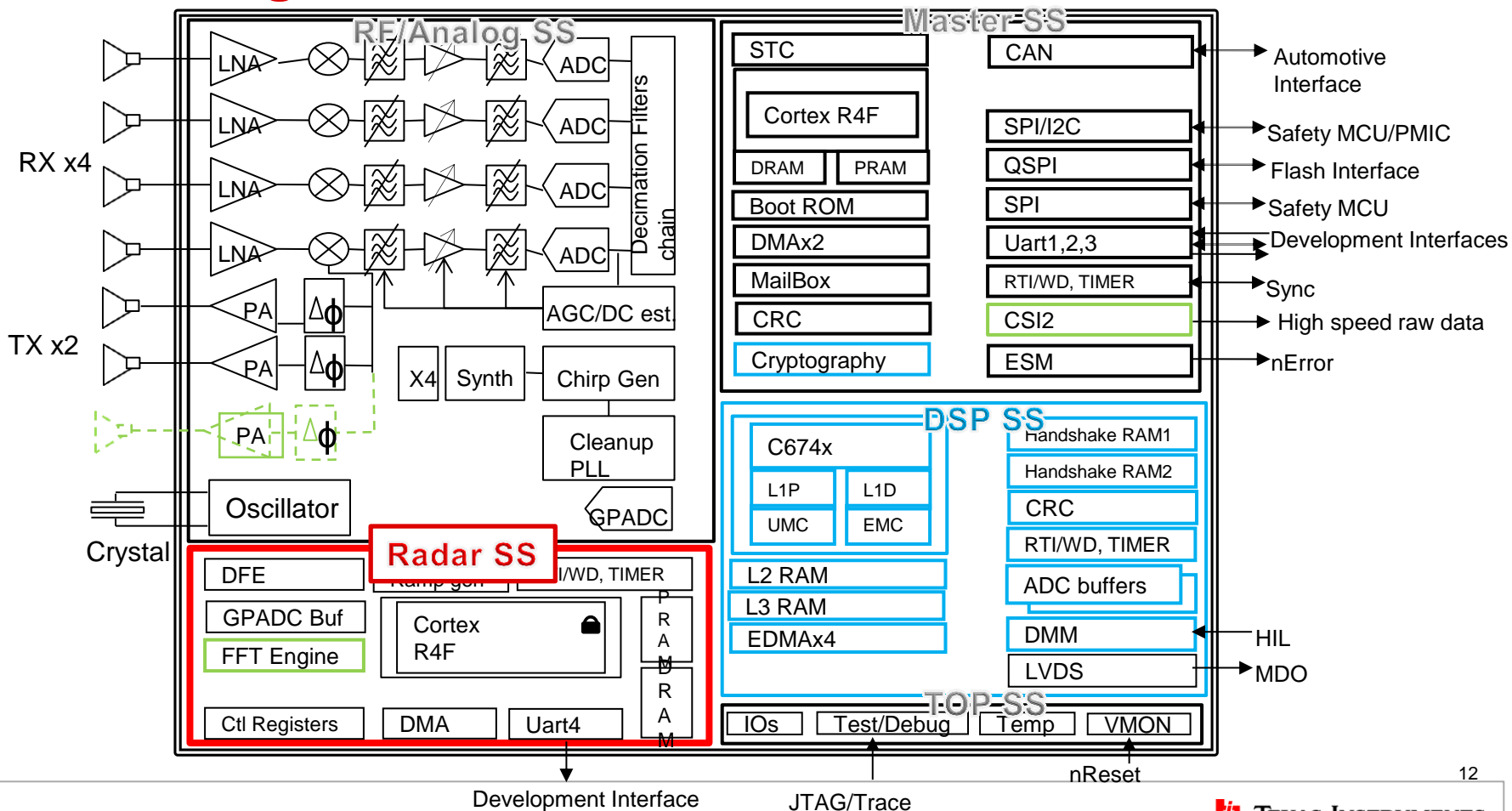
Block Diagram : IWR14xx/IWR16xx



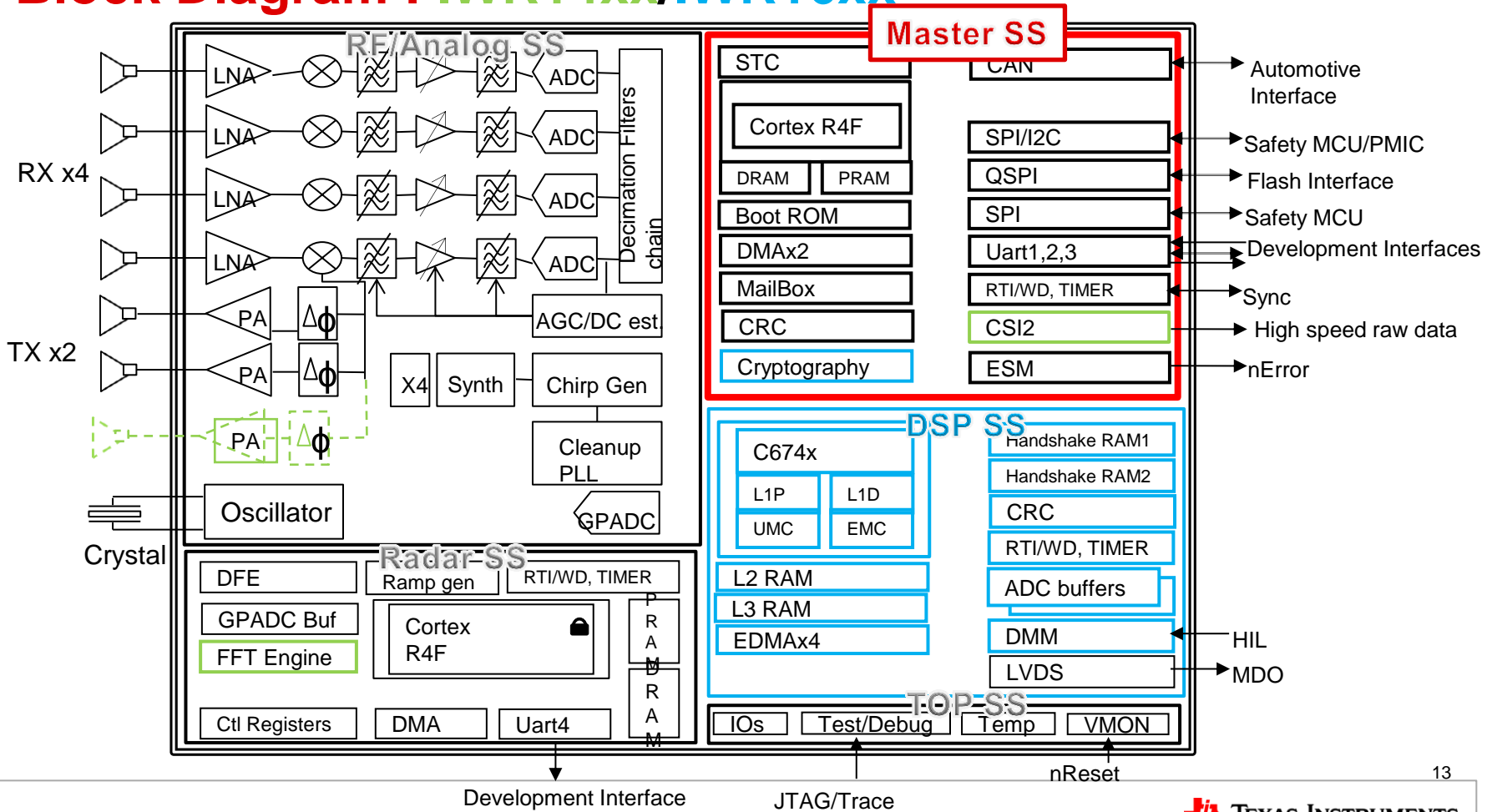
Block Diagram : IWR14xx/IWR16xx



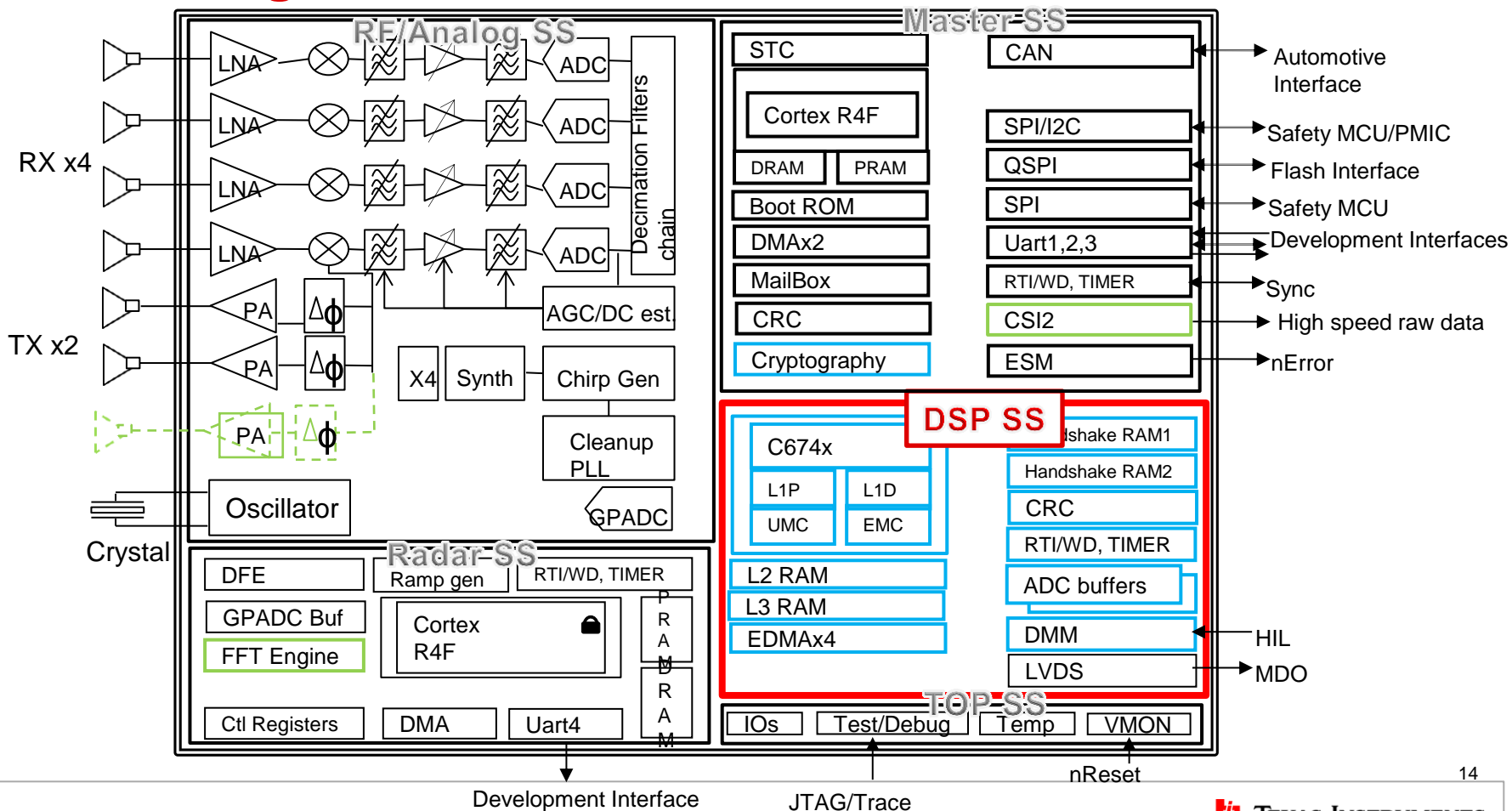
Block Diagram : IWR14xx/IWR16xx



Block Diagram : IWR14xx/IWR16xx

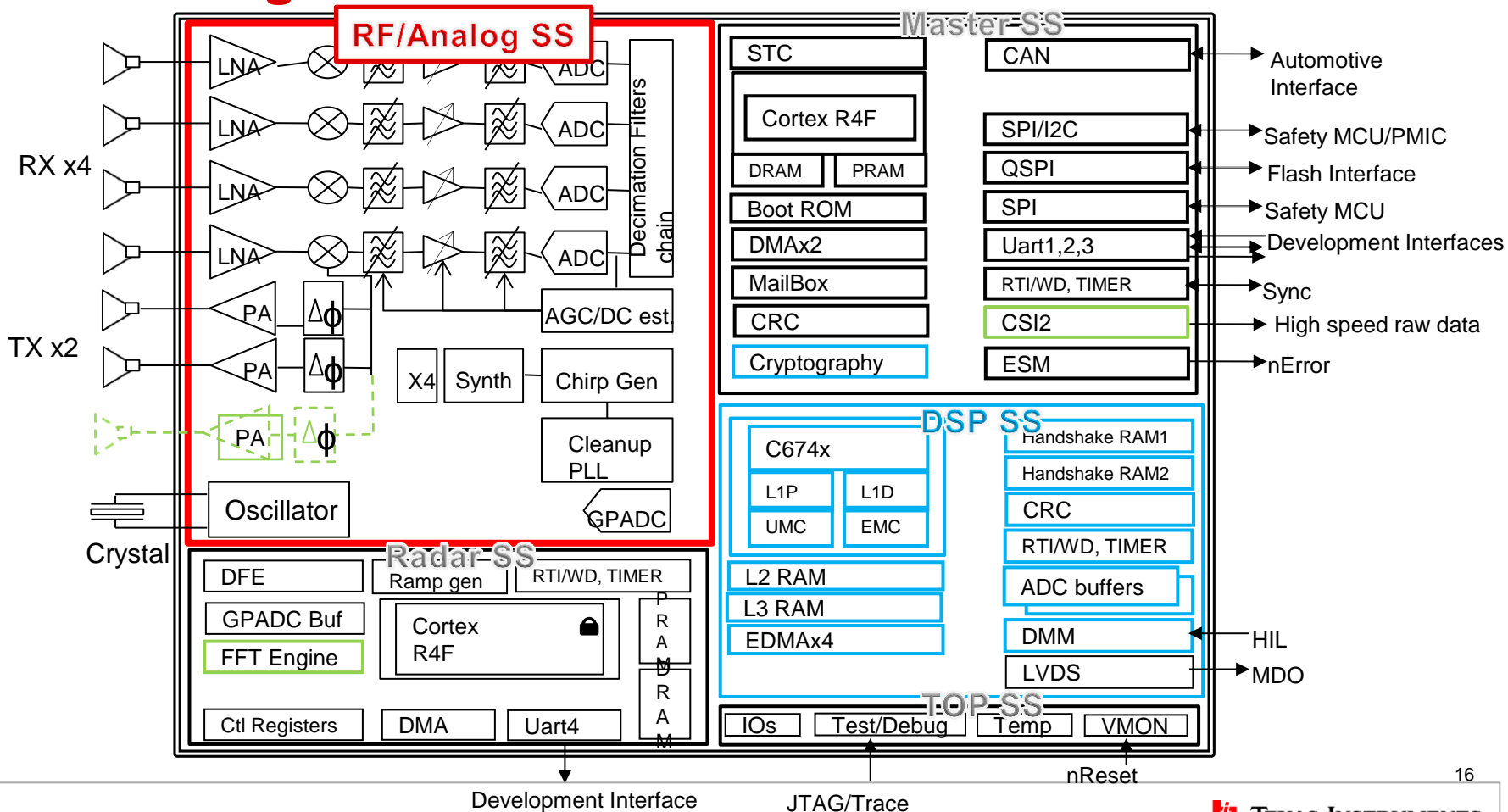


Block Diagram : IWR14xx/IWR16xx



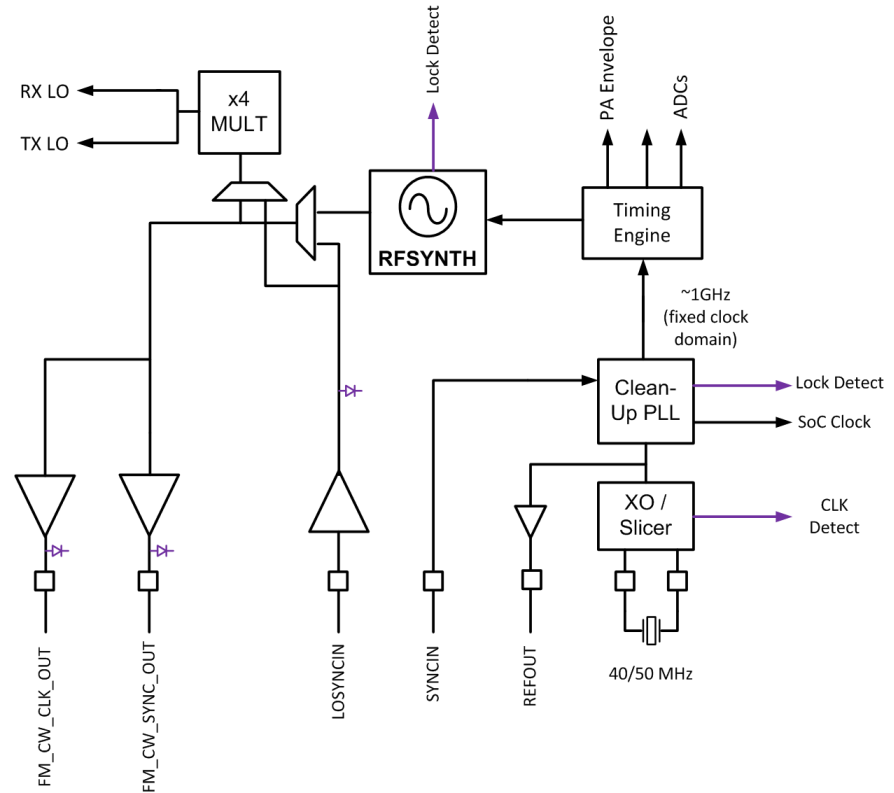
RF and Analog Subsystem

Block Diagram : IWR14xx/IWR16xx



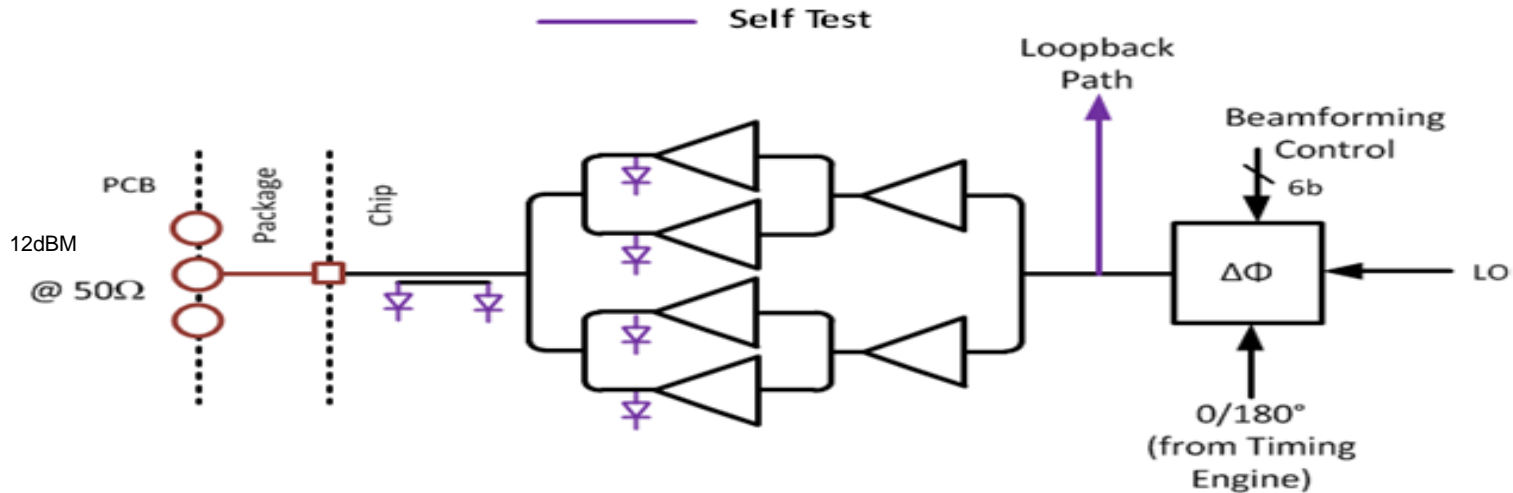
RF and Analog: Clock Subsystem

- Supports 40MHz crystal.
- Clean-up PLL provides high-frequency reference for modulated synthesizer and clocks to digital, ADCs.
- FMCW waveforms synthesized in a 19-20.25GHz closed loop frequency synthesizer.



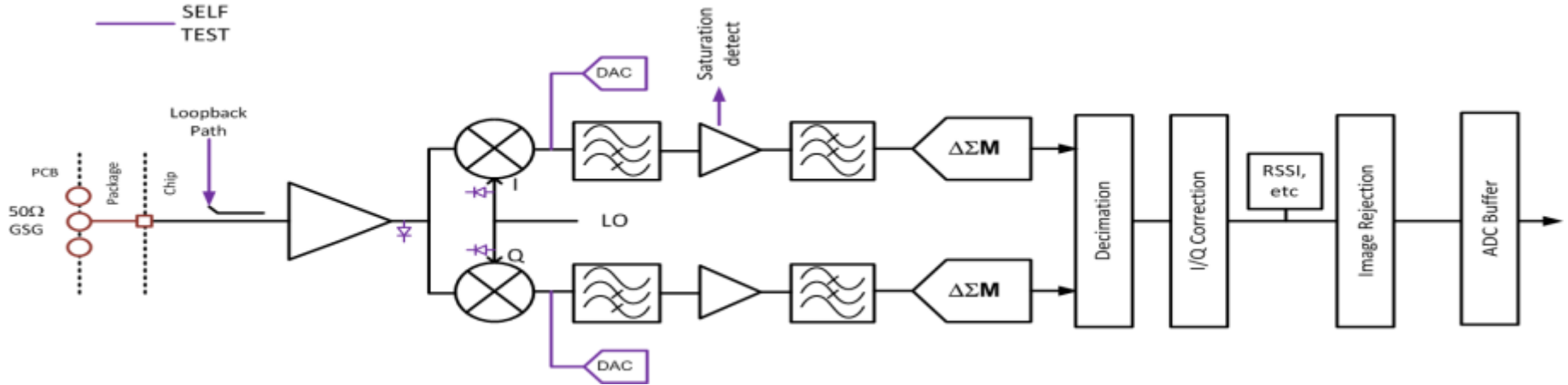
RF and Analog: Transmit Subsystem

- Single-ended antenna interface matched to a 50 ohm GCPW on the PCB at the edge of the package.
- Power/impedance monitors at the edge of the die.
- Binary (0/180) phase modulation for MIMO radar and interference mitigation.



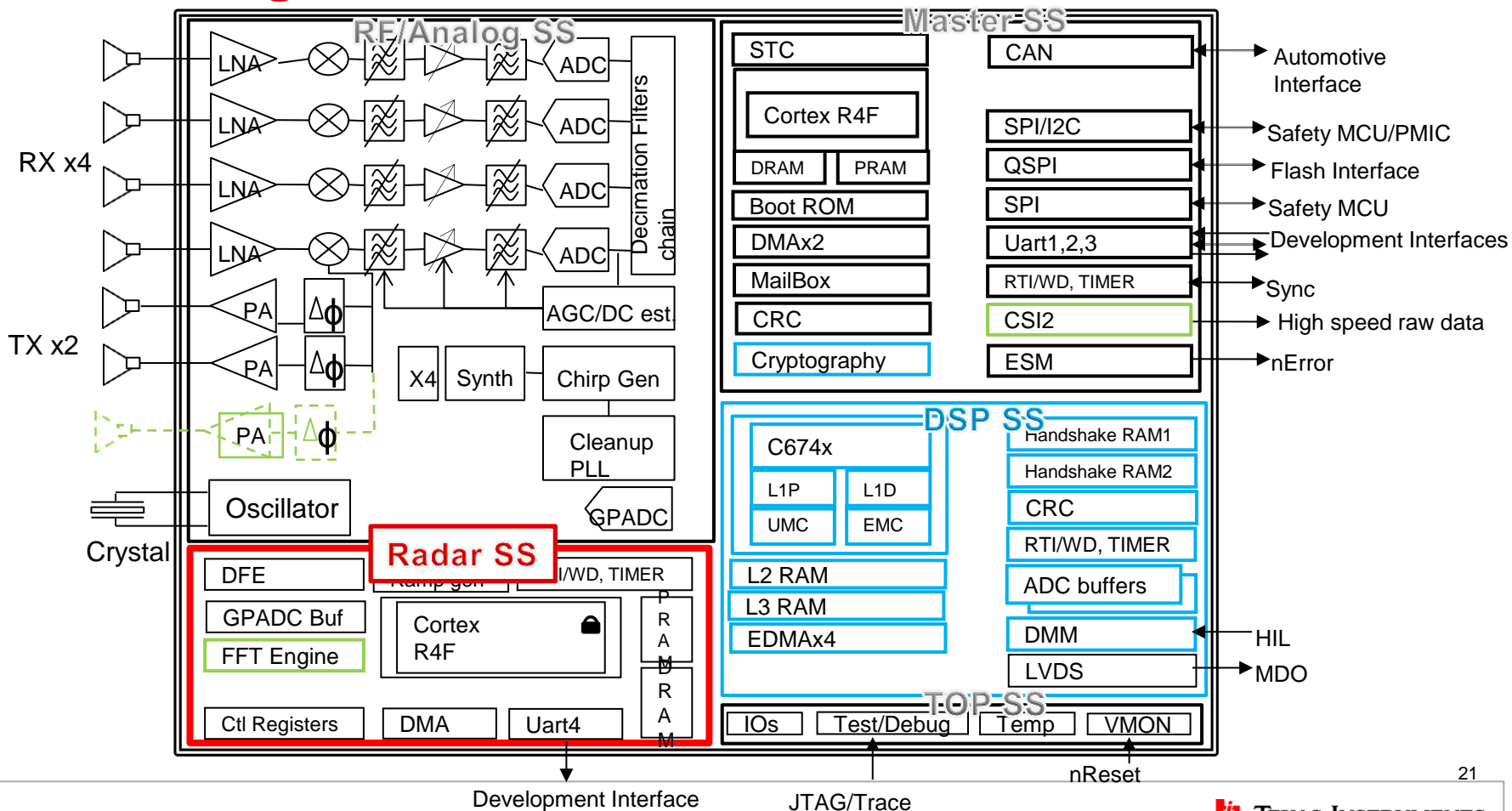
RF and Analog: Receive Subsystem

- Complex (I/Q) baseband.
- Programmable high pass filters to compensate for channel loss.
- CTSDM ADC supports IF bandwidths up to 15MHz.



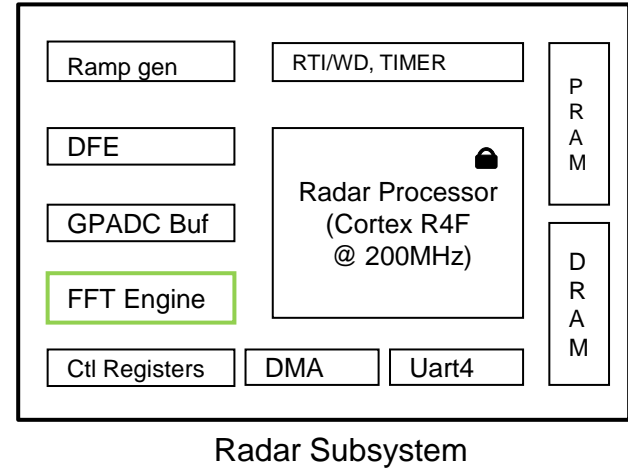
Radarsubsystem (aka BSS)

Block Diagram : IWR14xx/IWR16xx



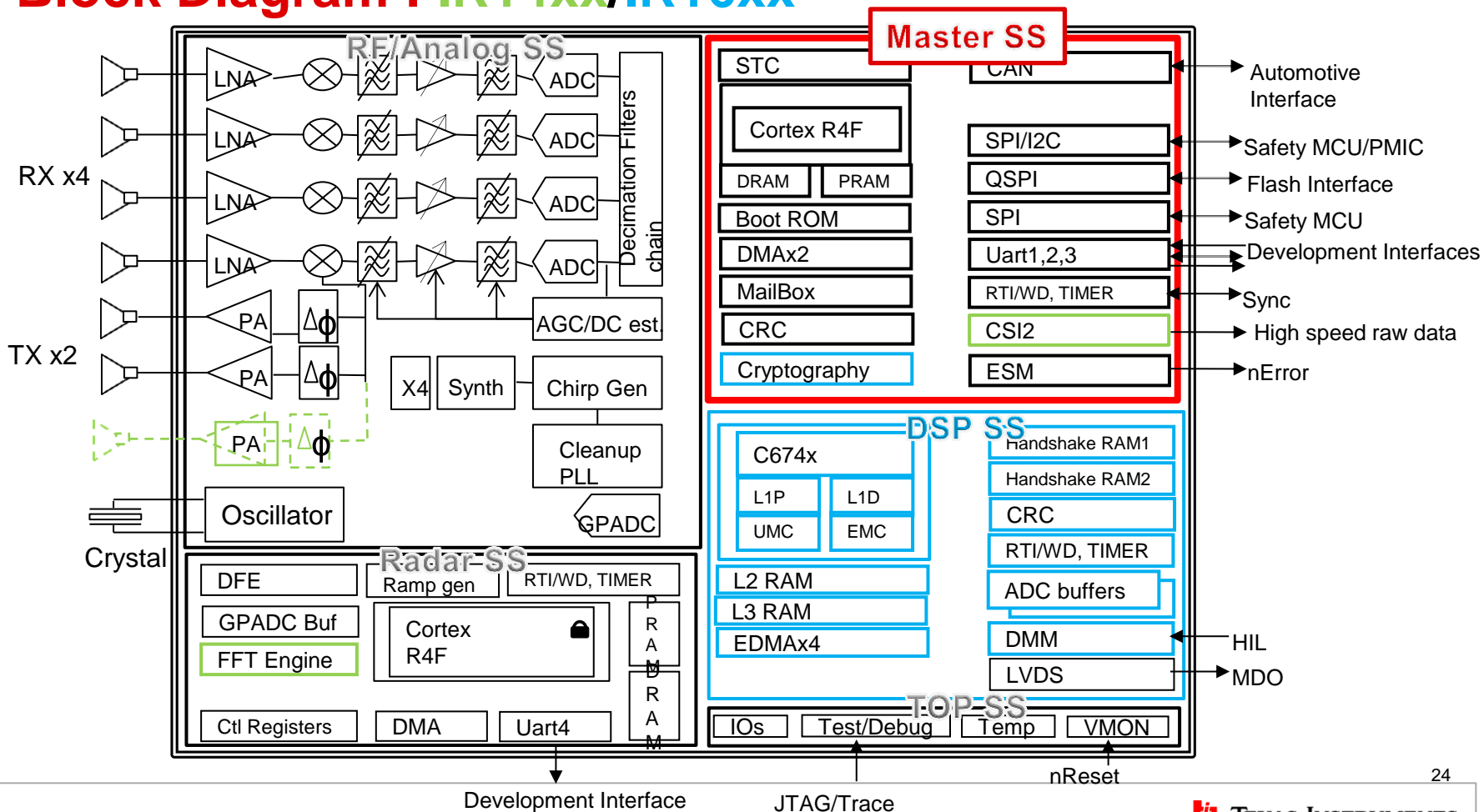
Radar Subsystem (BSS)

- Also known as the BSS, includes the DFE (digital front-end) and Ramp Generator
- Also includes a dedicated Cortex R4F MCU for configuration, monitoring, and calibration of the low-level RF/Analog components
- Access to the Radar subsystem provided through hardware mailboxes and a well defined API



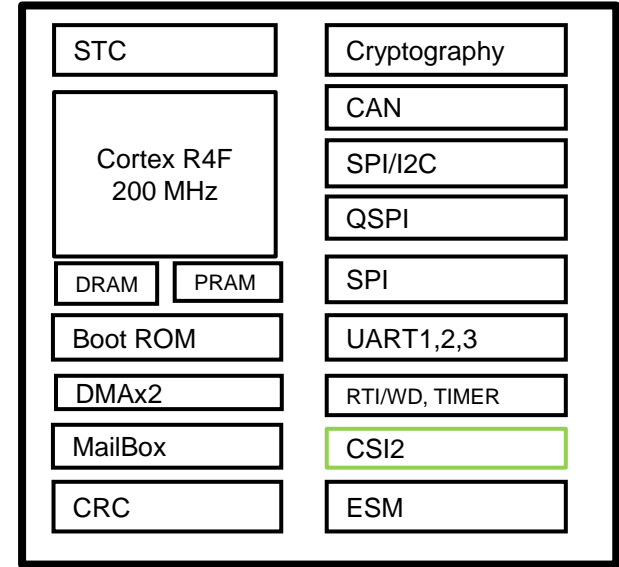
Master Subsystem (MSS)

Block Diagram : IR14xx/IR16xx



Master (Control) Subsystem

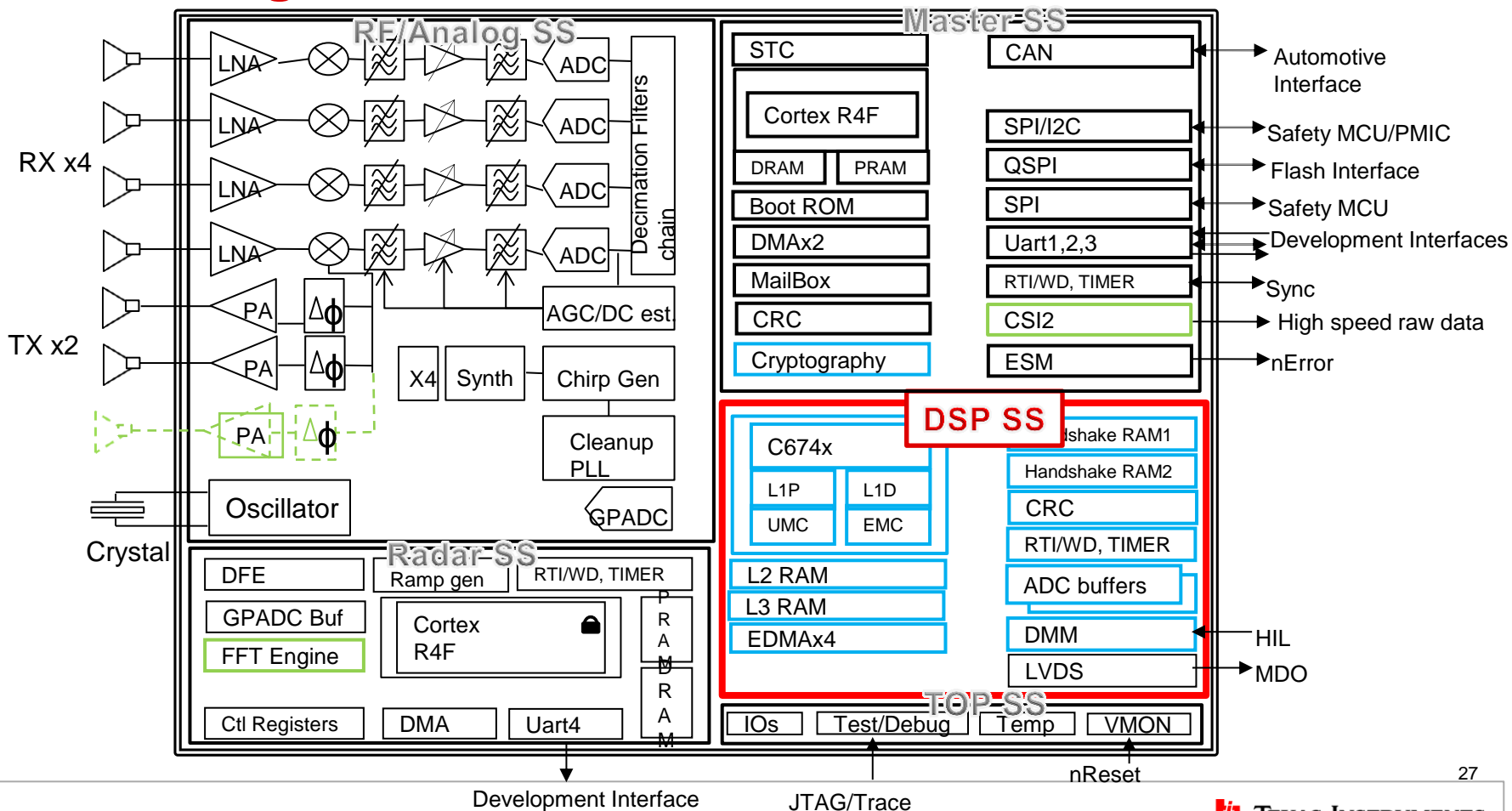
- The MSS includes an ARM Cortex R4F processor clocked at 200 MHz for running application code.
- User application running on MSS controls overall operation of the device, including Radar subsystem (BSS) control via well-defined API messages and perform radar signal processing.
- This subsystem also includes the various external interfaces available on the 14 or 16xx devices.



Master Subsystem

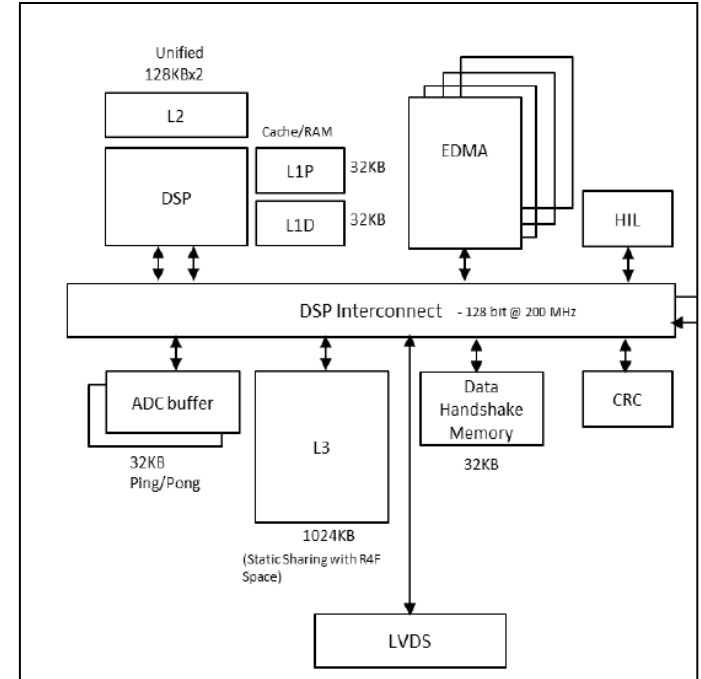
DSP Subsystem (DSS)

Block Diagram : IWR14xx/IWR16xx



DSP Subsystem (DSS): IWR16xx only

- C674x DSP clocked at 600 MHz for advanced Radar signal processing
- High bandwidth interconnect for high performance (128-bit, 200MHz)
- 256 KB L2 and 1 MB of L3 memory
- Four DMAs for data transfer, LVDS interface for Measurement data output, ADC buffers, CRC engine and data handshake memory

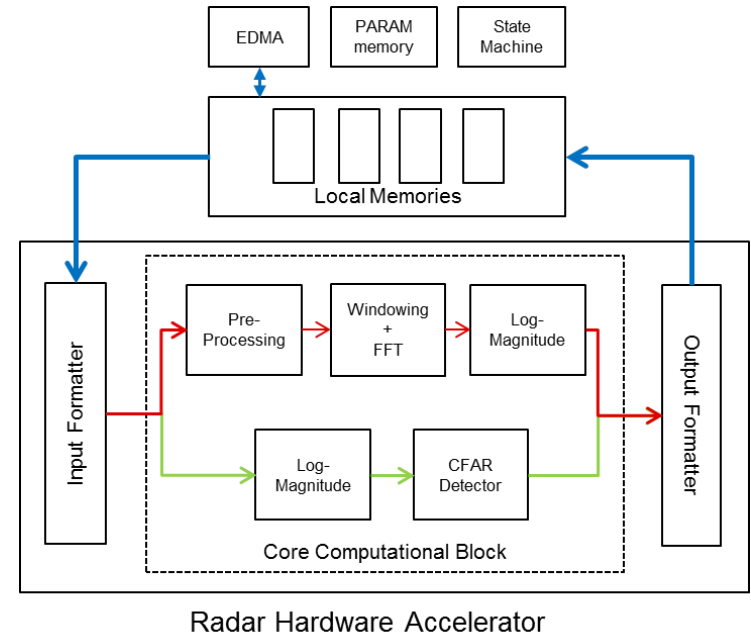


DSP Subsystem (DSS)

Radar Hardware Accelerator

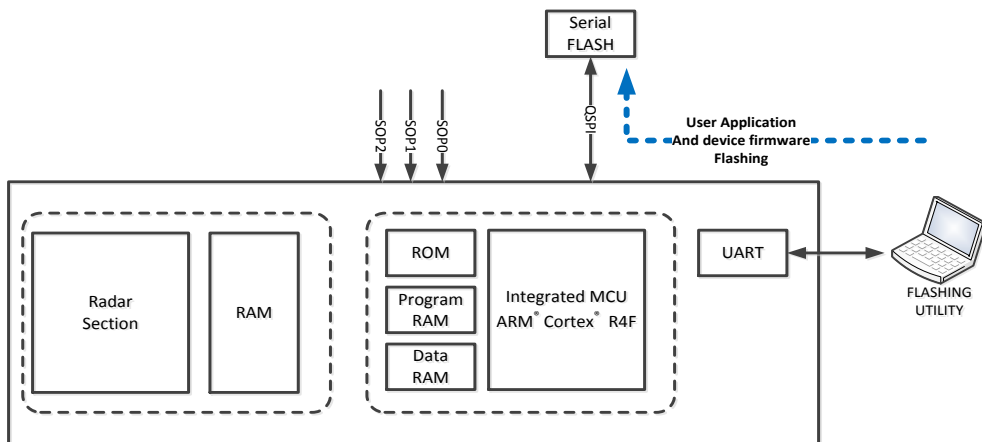
Radar Hardware Accelerator

- Accelerates FFT and CFAR detection operations
- Simple pre-FFT processing and Magnitude and Log-Magnitude computation capability
- Flexible data flow and data sample arrangement to support efficient multi-dimensional FFT operations and transpose accesses
- Chaining and Looping mechanism to sequence accelerator operations with minimal intervention from the main processor
- CFAR-CA detector support (linear and logarithmic)



Boot Modes

Boot Modes

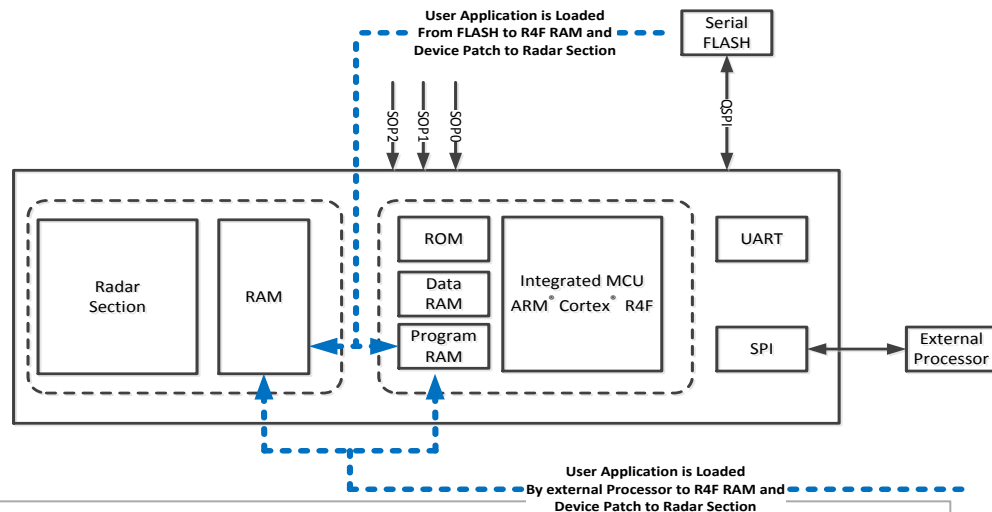


Functional Mode:

- Bootloader looks for a valid image in the serial flash memory, interfaced over the QSPI port.
- Bootloader transfers the same to Master System's memory sub-system

Flashing Mode:

- Bootloader enables the UART driver
- Expects a data stream comprising of User Application (Binary Image)
- Loads data to appropriate sections of the serial FLASH



Software Platform

mmWave Software

Simplified evaluation and development

mmWave SDK

Includes:

- TI RTOS
- Drivers
 - SPI
 - CAN
 - LVDS / CSI-2
 - EDMA
 - UART
 - I2C
 - GPIO
 - Timers
 - FFT HW
- Signal Processing Library
 - On DSP
 - On HW Accelerator
- mmWaveAPI
- mmWaveLink
- mmWaveLib

mmWave Examples

- TI Designs:
 - Power-Optimized Field Transmitter
 - Traffic monitoring
- Examples:
 - mmWaveDemo (OOB)
- Labs:
 - Water Vs Ground Lab
 - Vital Sign Lab

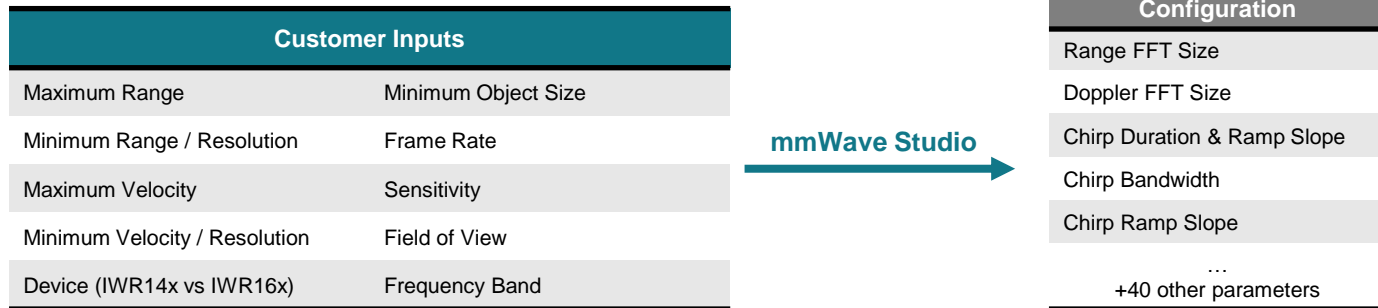
mmWave Studio

Includes:

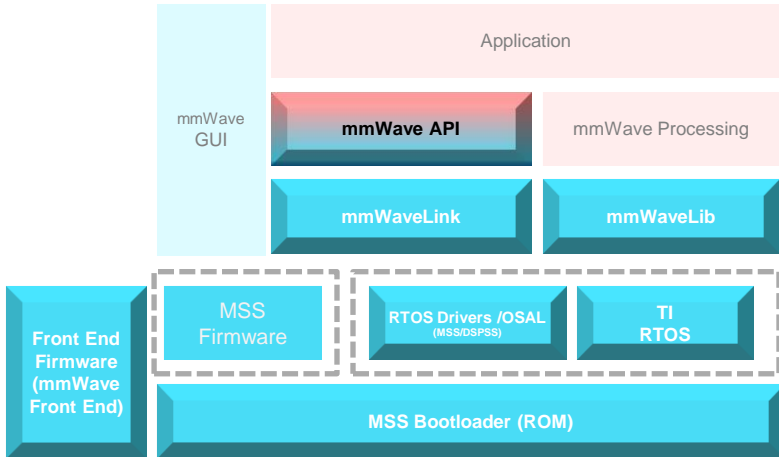
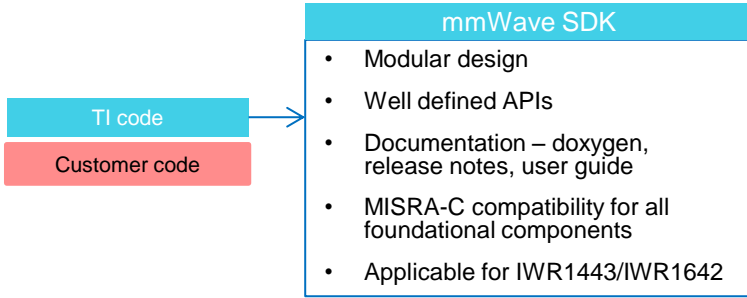
- System Estimator – define chirp configuration through abstracted parameters like max range, minimum range, etc
- Capture – capture raw ADC data from capture HW onto the PC

Simplified mmWave sensor configuration

- Generate mmWave sensor chirp configurations through system-level parameters to control [Range, Velocity, Angle] output
- mmWave OOB GUI for visualization of the output



mmWave SDK – The TI components



RTOS Drivers

- Encapsulate the functionality of the hardware IPs in the SOC
- Provide a well defined API to the higher layers.
- OS-agnostic via the OSAL layer

OSAL

- An abstraction layer for some of the common OS services. (Semaphore, Interrupts, Clock)
- Sample TI RTOS based port in mmWaveSDK
- Customers can port the OSAL for their custom OS, as per their requirements

BSS Firmware

- ROM Firmware for mmWave Front End
- Provides well defined APIs to configure, start and monitor mmWave Front End
- Communicates with MSS via Mailbox and proprietary protocol

mmWaveLink

- Low level control for mmWave Front End
- Communicates over Mailbox to BSS (front end)
- Implements the communication protocol between the BIST subsystem and Master subsystem

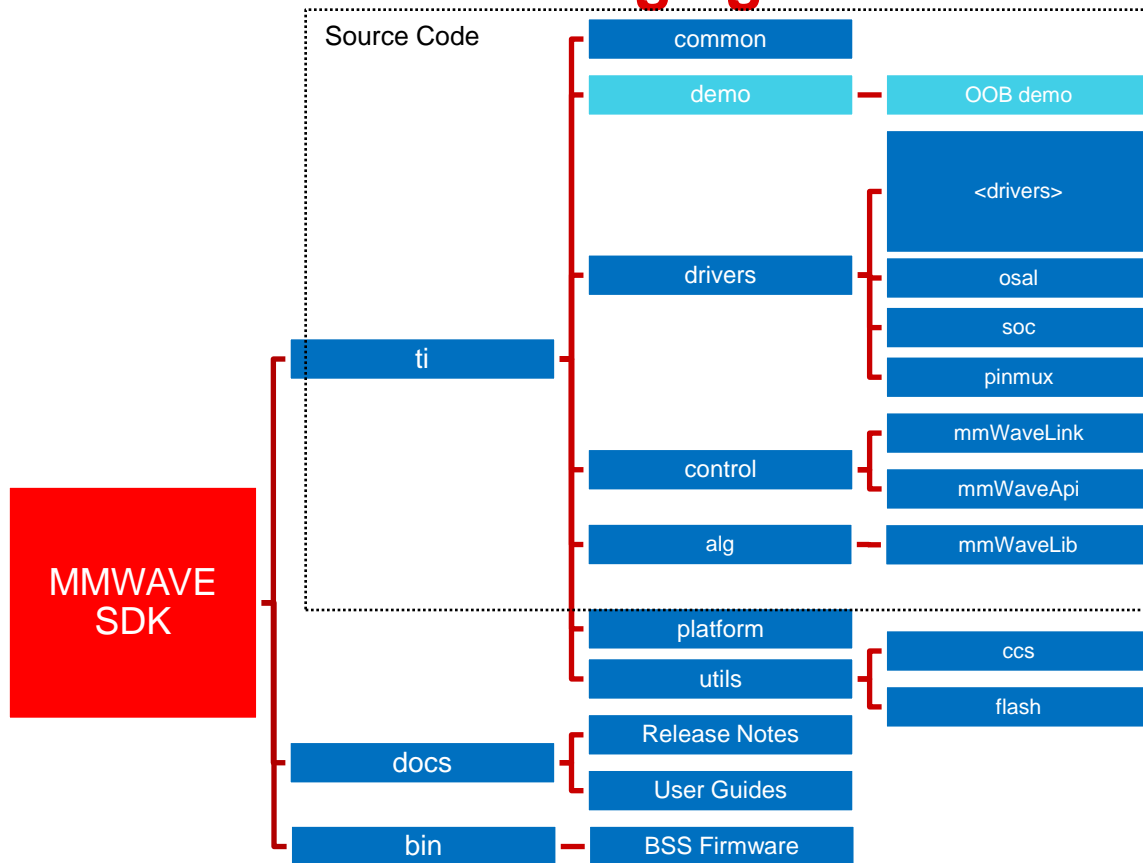
mmWave API

- Simple APIs for application to perform the task of radar sensing
- High level control for mmWave Front End and DSS
- Runs on top of mmWaveLink/IPC and Drivers.

mmWaveLib

- Provides functions for elements or sub functions of typical radar processing chain
- Optimized for C674x
- Accelerate customer code development and reduce SW effort to achieve a working radar processing chain

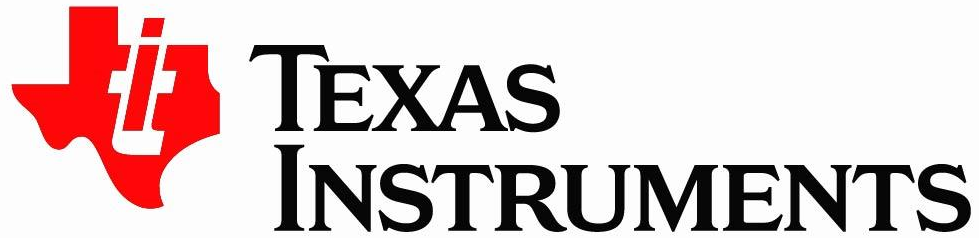
mmWave SDK - Packaging



- Uses TI compiler tools (Cortex-R4F, C674X) provided as part of CCS
- Demo built over TI RTOS
- Simple makefile based build system

Learn more about Industrial mmWave Sensors

- Learn more about IWR1x devices, please visit the product pages
 - IWR1443: <http://www.ti.com/product/IWR1443>
 - IWR1642: <http://www.ti.com/product/IWR1642>
- Get started evaluating the platform with IWR1x EVMs, purchase EVM at
 - IWR1443 EVM: <http://www.ti.com/tool/IWR1443BOOST>
 - IWR1642 EVM: <http://www.ti.com/tool/IWR1642BOOST>
- Download mmWave SDK @ <http://www.ti.com/tool/MMWAVE-SDK>
- Ask question on TI's E2E forum @ <http://e2e.ti.com>



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