

DC Specifications:

input capacitance, leakage current, input impedance, reference voltage range, INL, and DNL

TIPL 4001

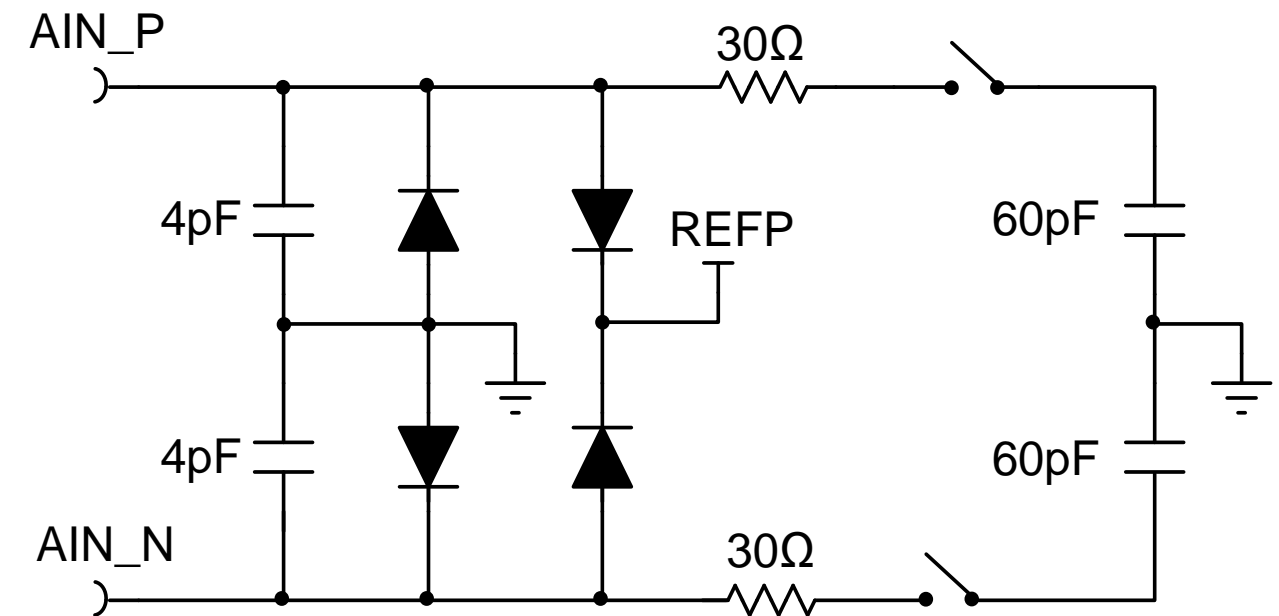
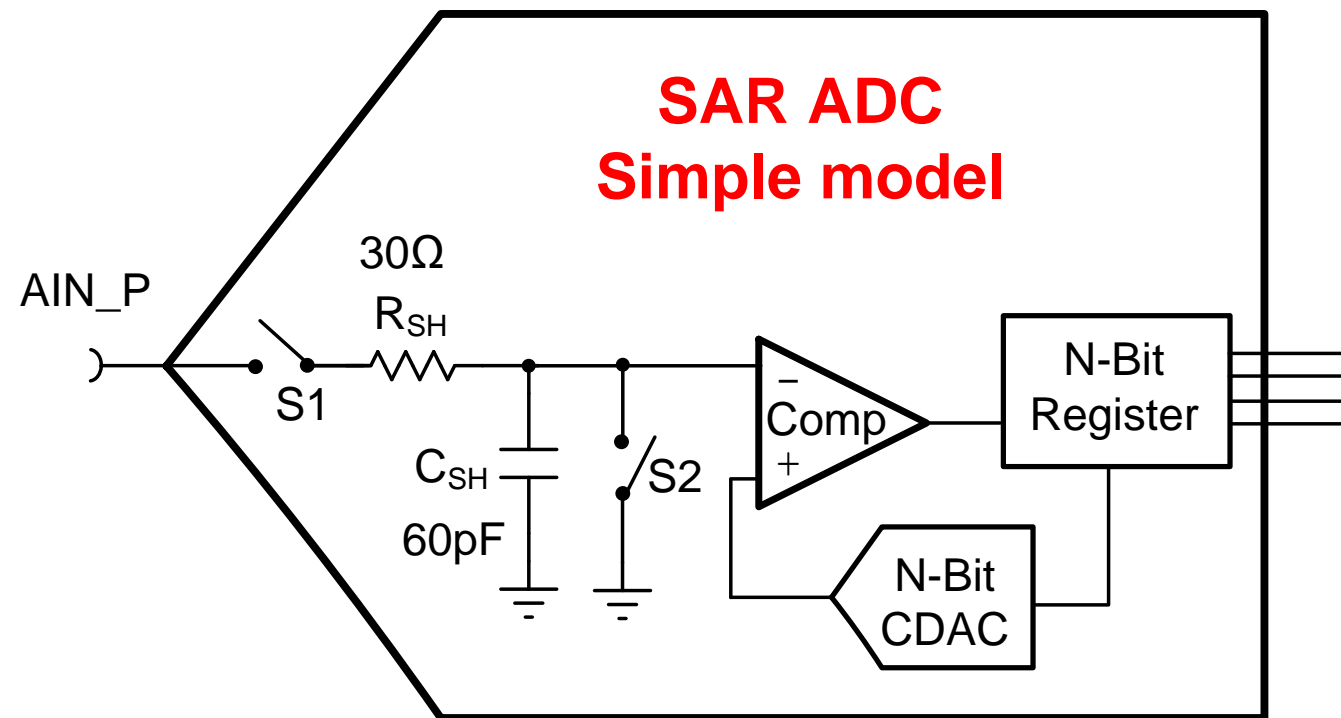
TI Precision Labs – ADCs

Created by Art Kay

Presented by Peggy Liska

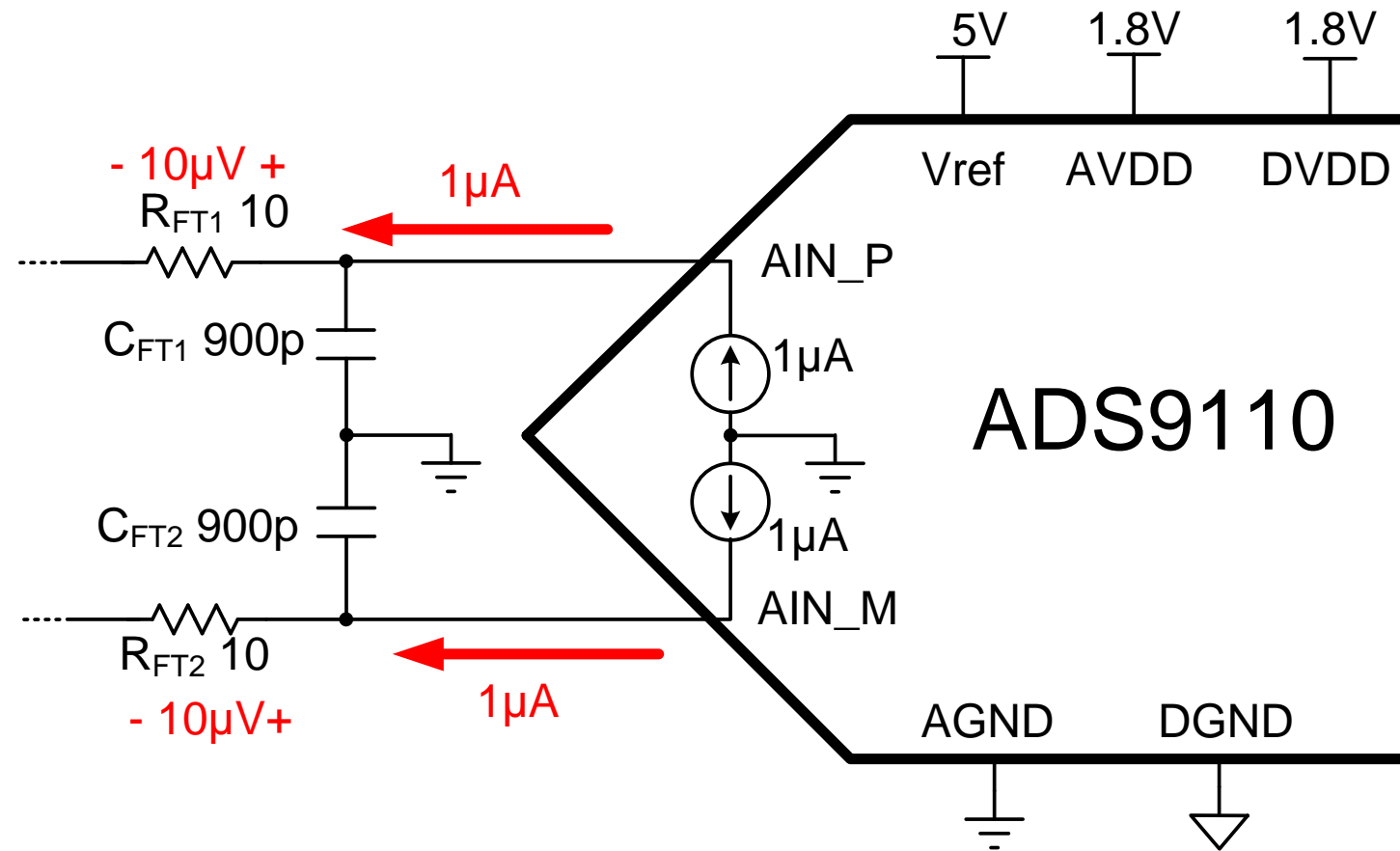
Analog Input: Input Capacitance

PARAMETER	TEST CONDITION	MIN	TYP	MAX	UNIT
ANALOG INPUT					
CIN Input capacitance	In sample mode		60		pF
	In hold mode		4		

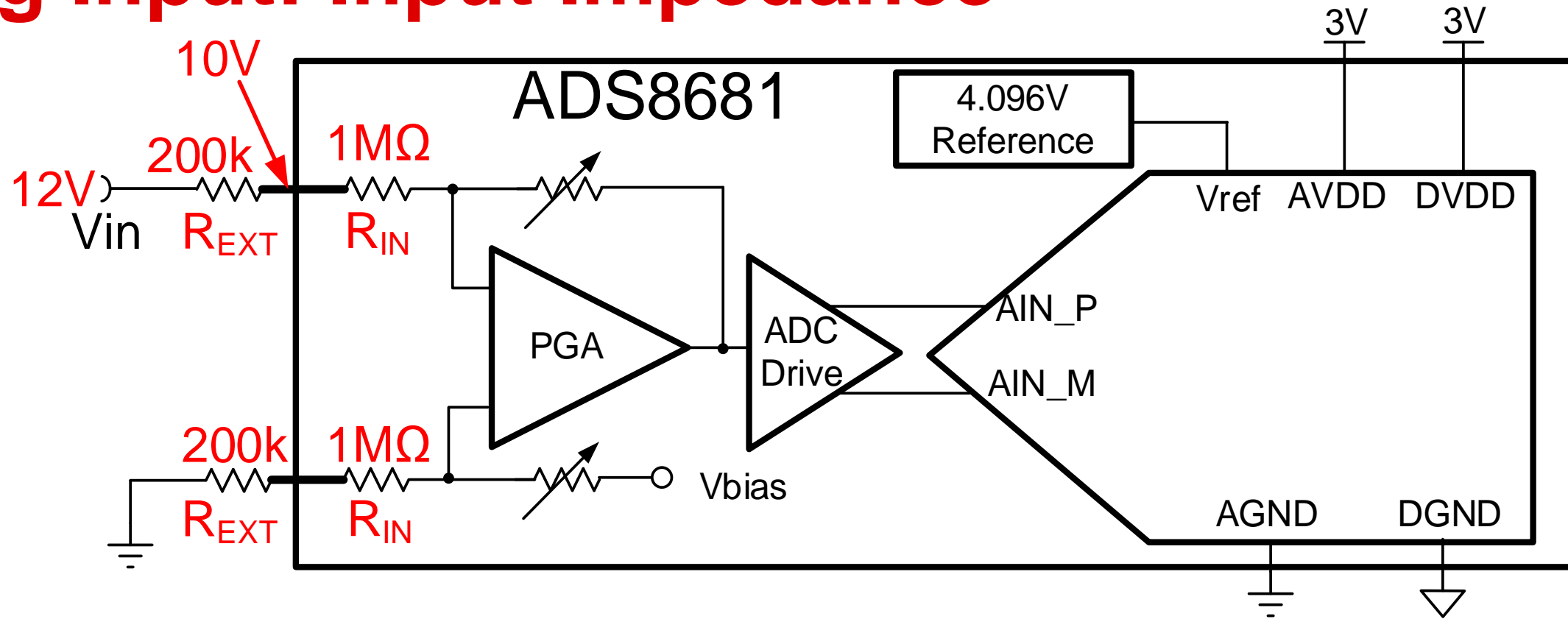


Analog Input: Input Leakage Current

PARAMETER	TEST CONDITION	MIN	TYP	MAX	UNIT
ANALOG INPUT					
I_{IL} Input leakage current			± 1		μA



Analog Input: Input Impedance



$$GE = \frac{1}{1 + \frac{R_{IN}}{R_{EXT}}}$$

System gain error

See document [SBAA239](#)

$$V_{IN_Range_Adj} = V_{IN_Range} \cdot \frac{R_{IN} + R_{EXT}}{R_{IN}}$$

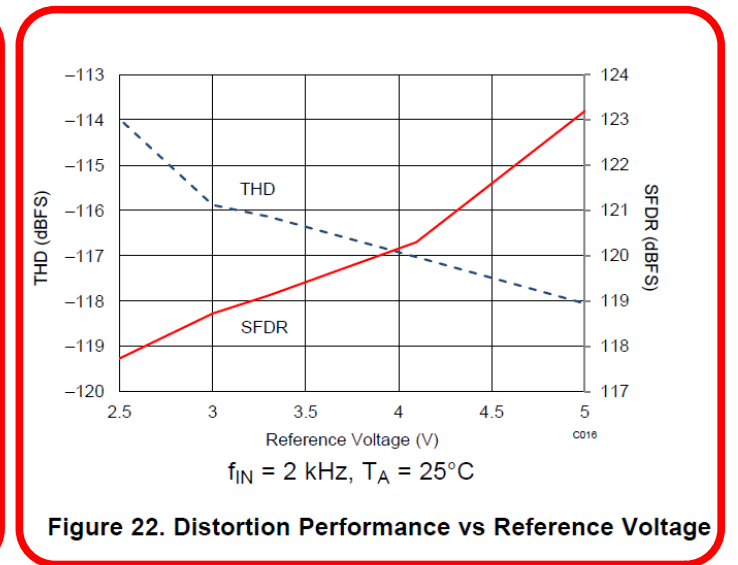
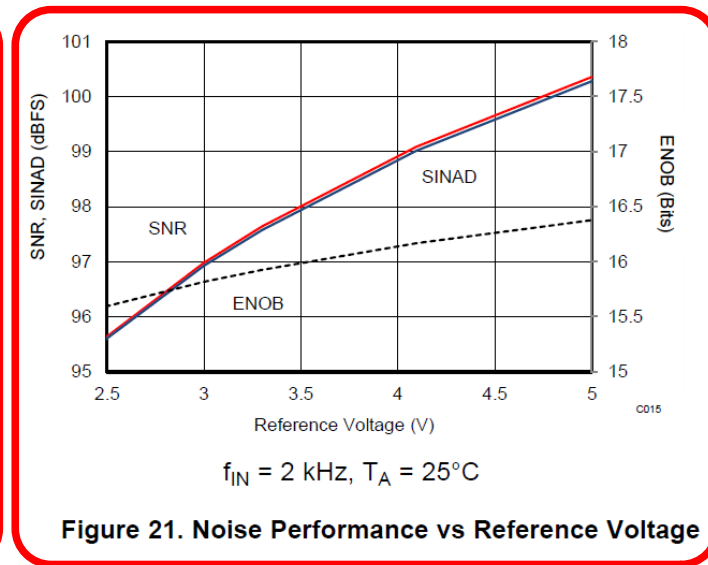
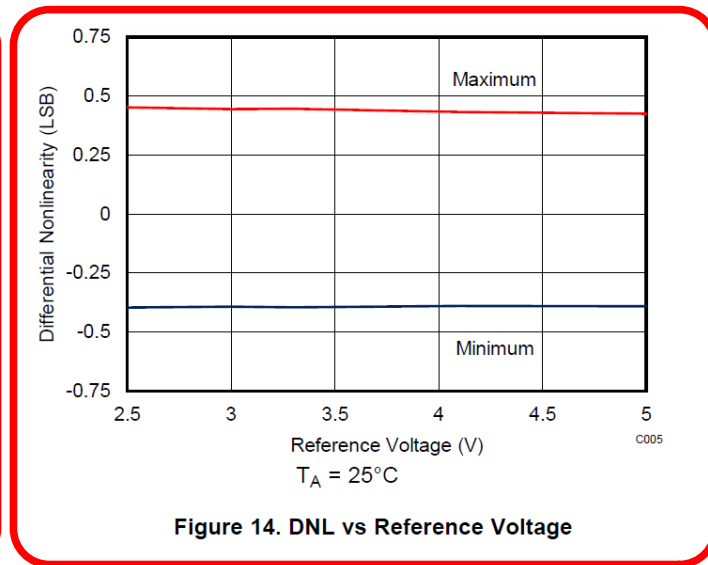
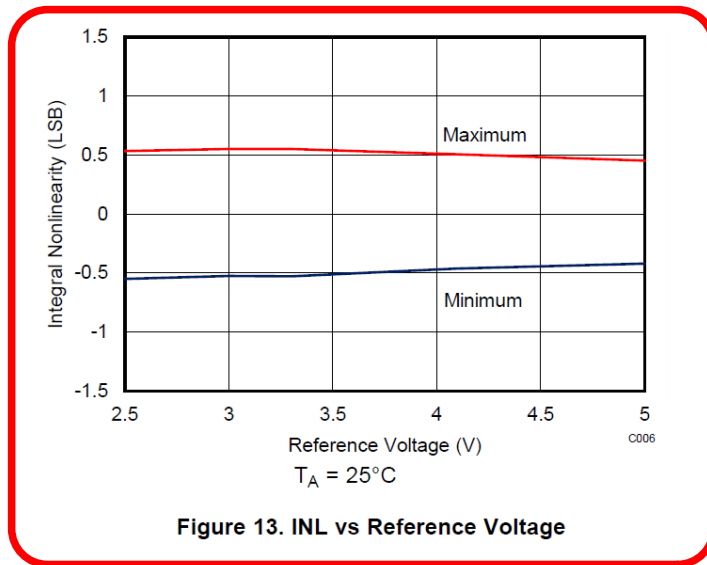
Extended input range

See document [SBAA244](#)

Reference Input: Reference Input Voltage Range

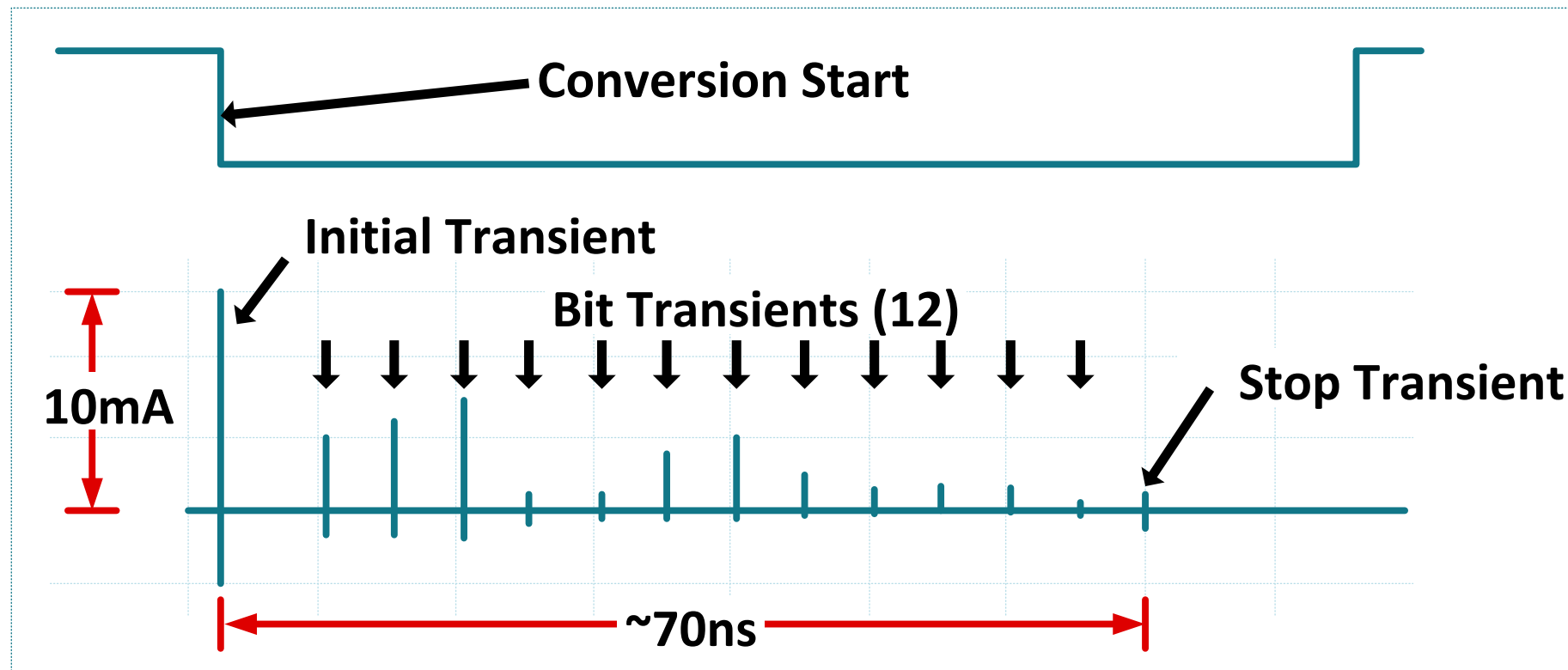
All specifications are for AVDD = 1.8V, DVDD = 1.8V, $V_{REF} = 5V$, and $f_{DATA} = 2Mps$, unless otherwise noted

PARAMETER	TEST CONDITION	MIN	TYP	MAX	UNIT
ANALOG INPUT					
V_{REF} Reference Input Voltage Range		2.5		5.0	V



Reference Input: Reference current

PARAMETER	TEST CONDITION	MIN	TYP	MAX	UNIT
EXTERNAL REFERENCE INPUT					
Reference input current	During conversion, 1MHz sample rate, midcode		300		μA
Input leakage Current			250		pA
C_{REF} Decoupling capacitor at the reference input		10	22		μF



System Performance: Ideal Transfer Function

$$\text{Number of Codes} = 2^N$$

$$V_{LSB} = \frac{FSR}{2^N}$$

Where

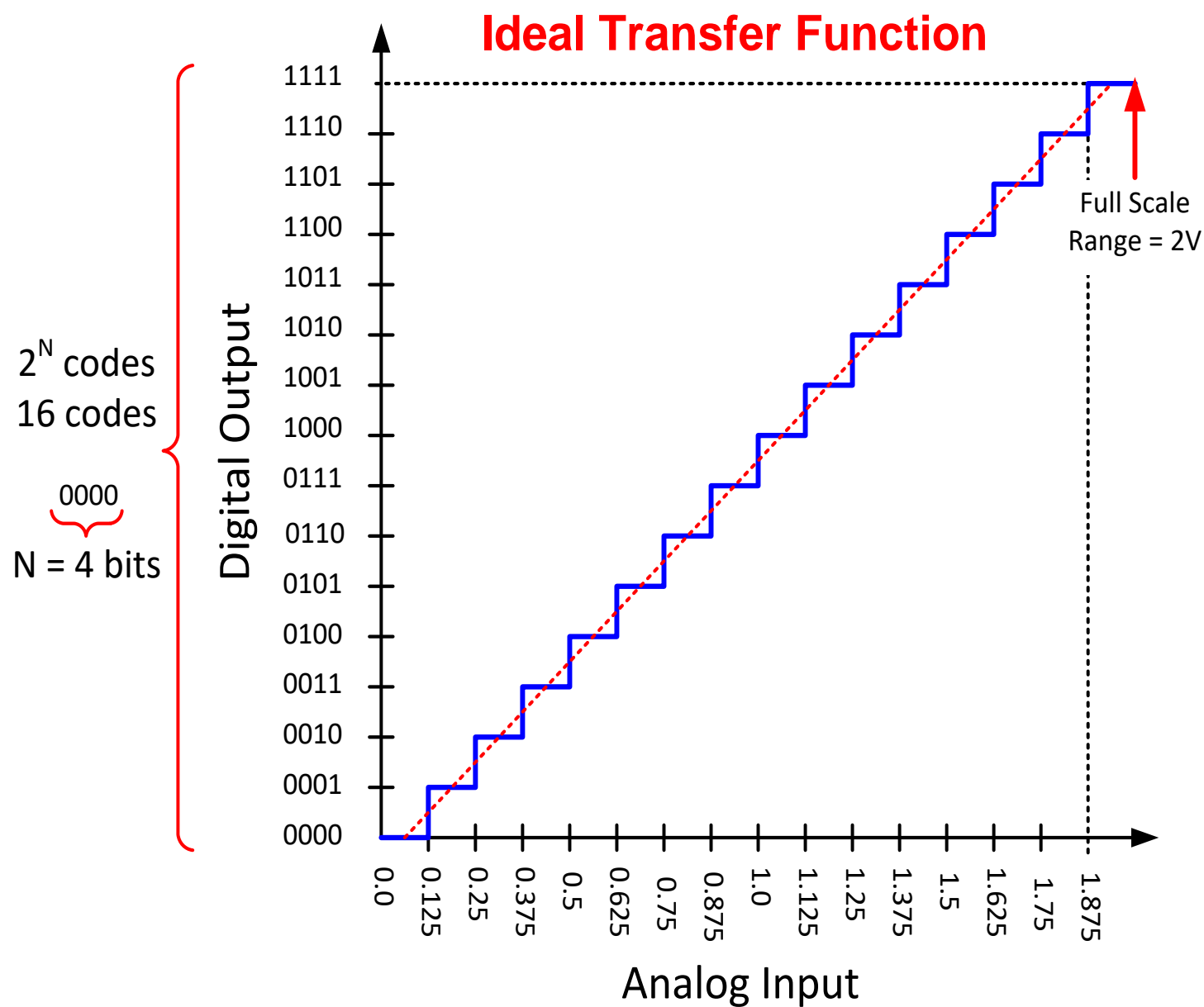
V_{LSB} = The minimum resolvable voltage width

FSR = Full Scale Range

N = Number of bits

$$V_{LSB} = \frac{FSR}{2^N} = \frac{2V}{2^4} = 0.125V$$

$$\text{Number of Codes} = 2^N = 2^4 = 16$$



System Performance: Differential Nonlinearity (DNL)

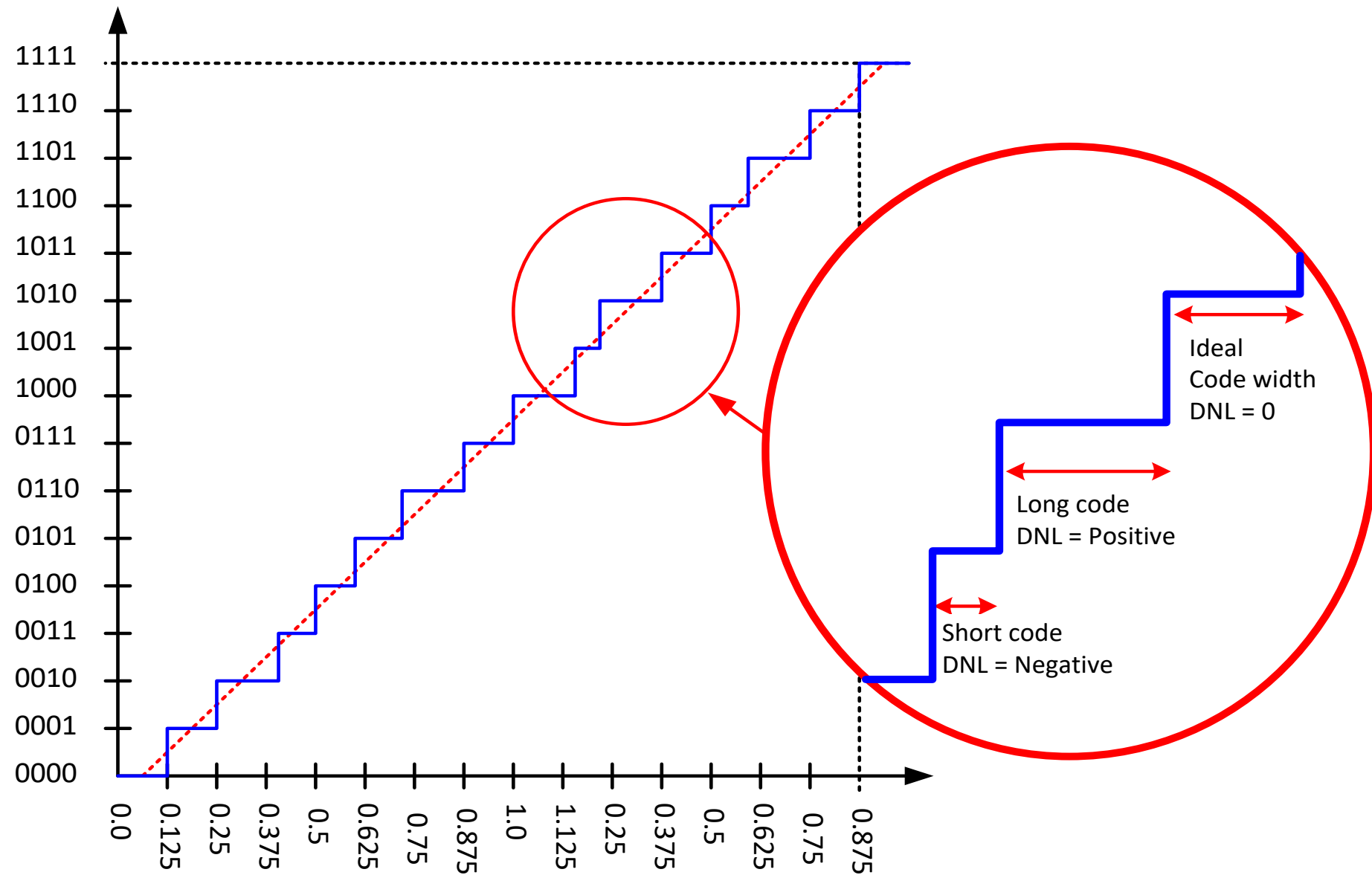
$$DNL[k] = \frac{W[k] - Q}{Q}$$

$$W[k] = T[k + 1] - T[k]$$

$W[k]$ the measured code width.

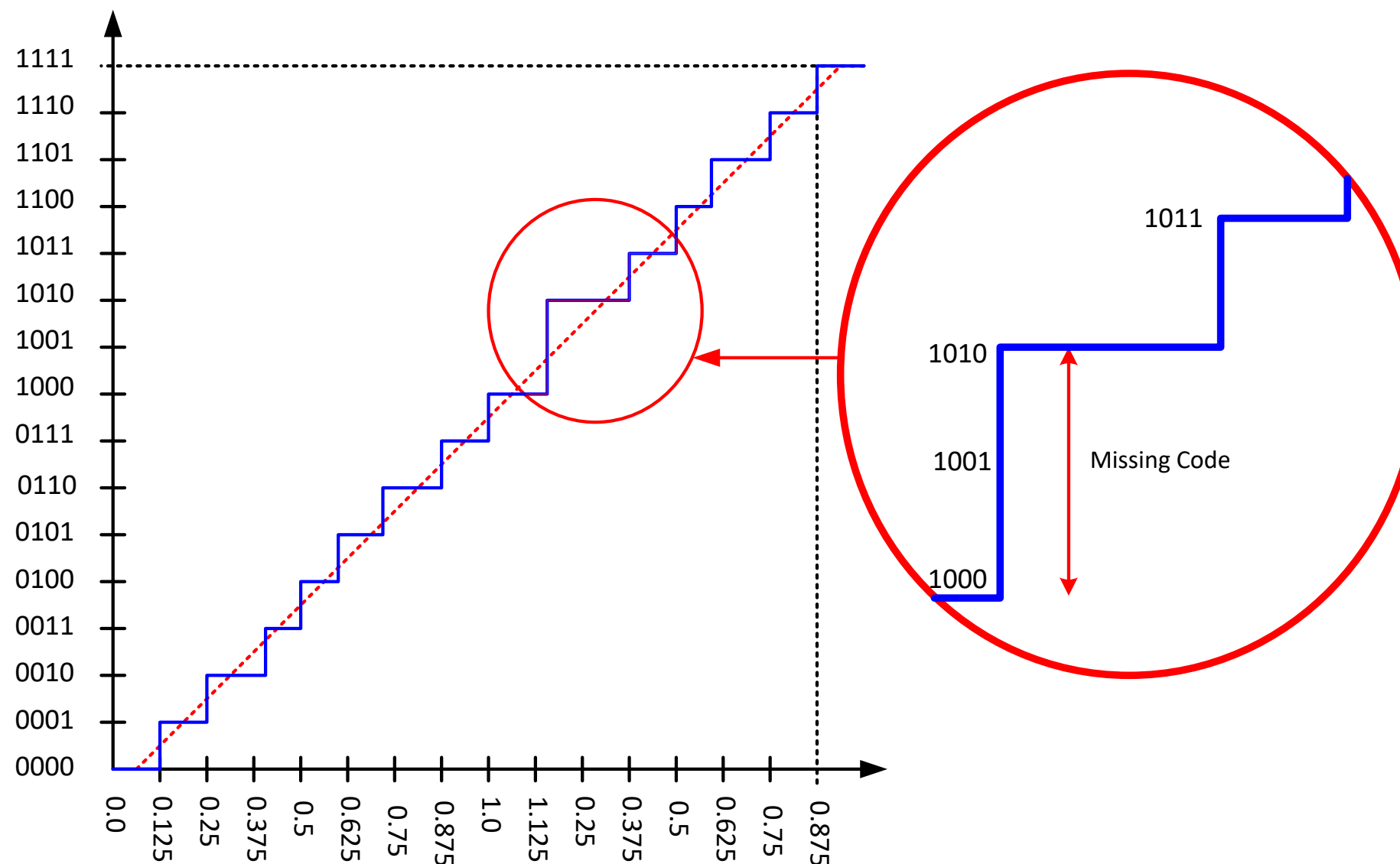
$T[k]$ The voltage level where a code transitions

Q Ideal code width



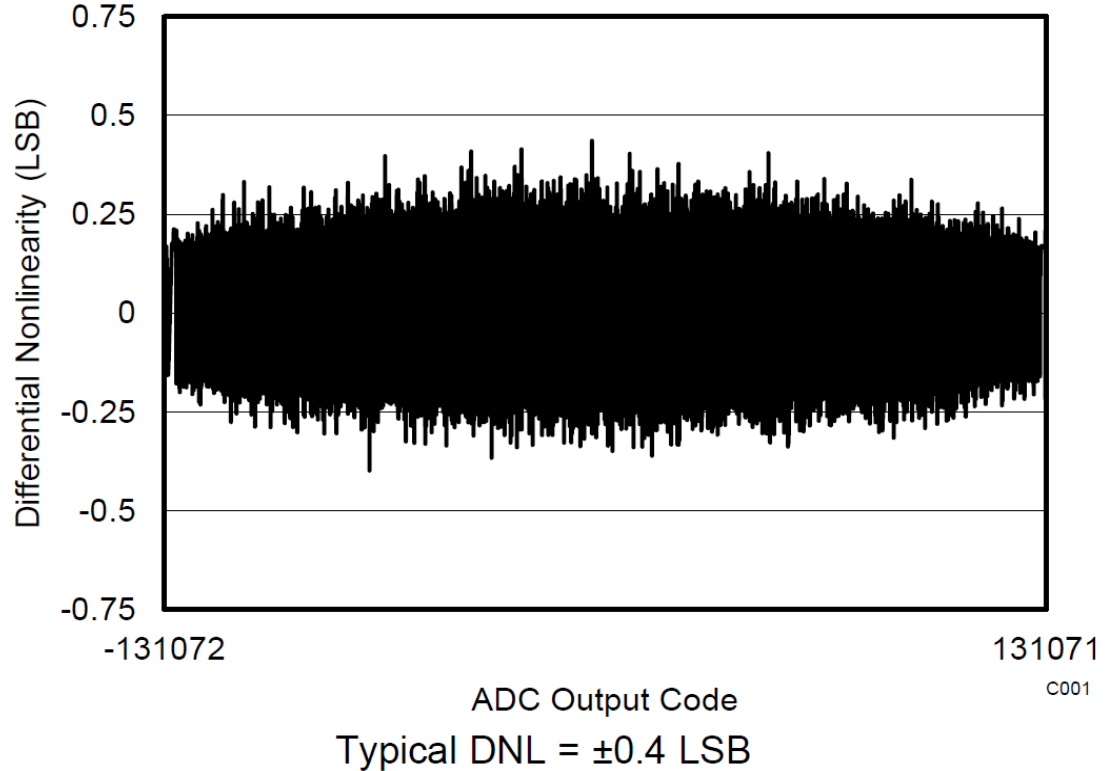
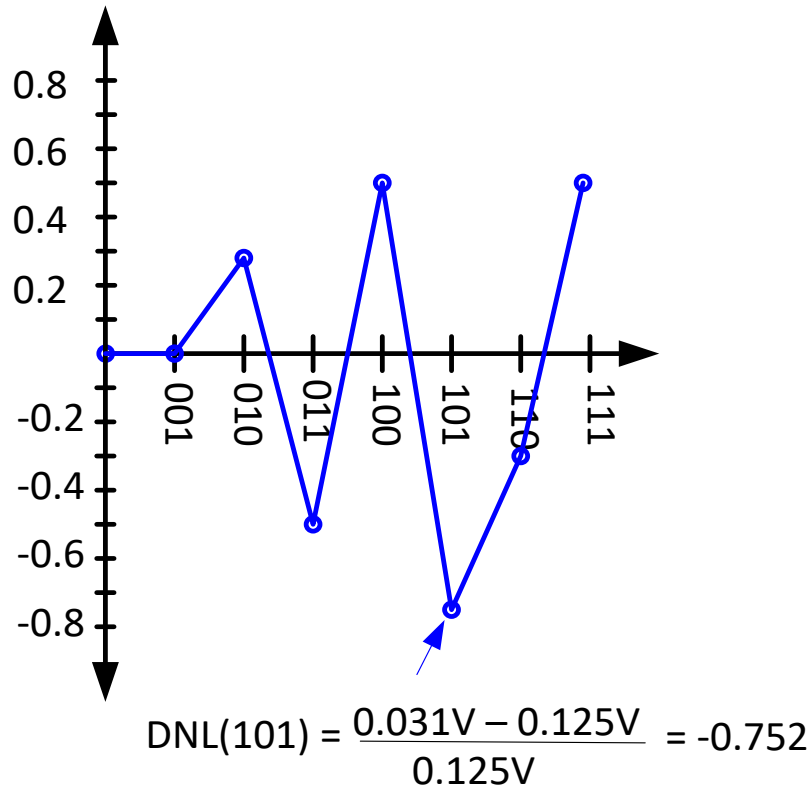
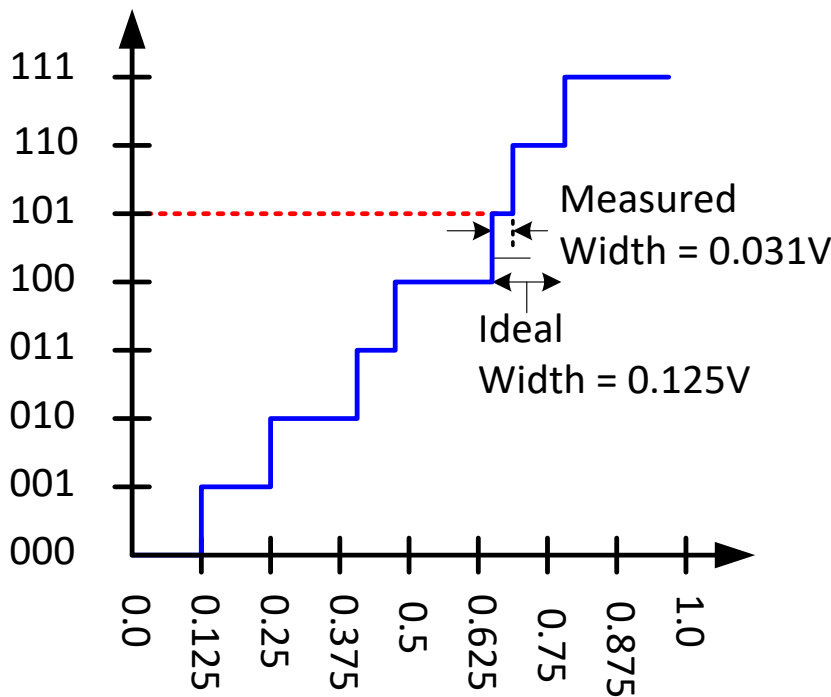
System Performance: No Missing Code (NMC)

PARAMETER	TEST CONDITION	MIN	TYP	MAX	UNIT
SYSTEM PERFORMANCE					
NMC Integral Nonlinearity	AVDD = 3V	12			Bits

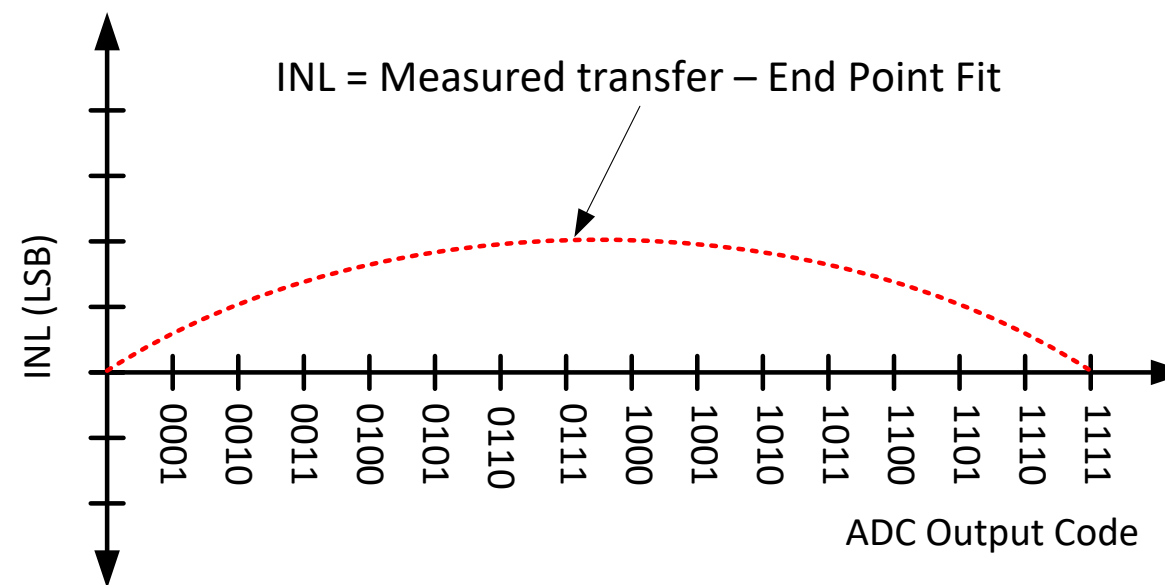
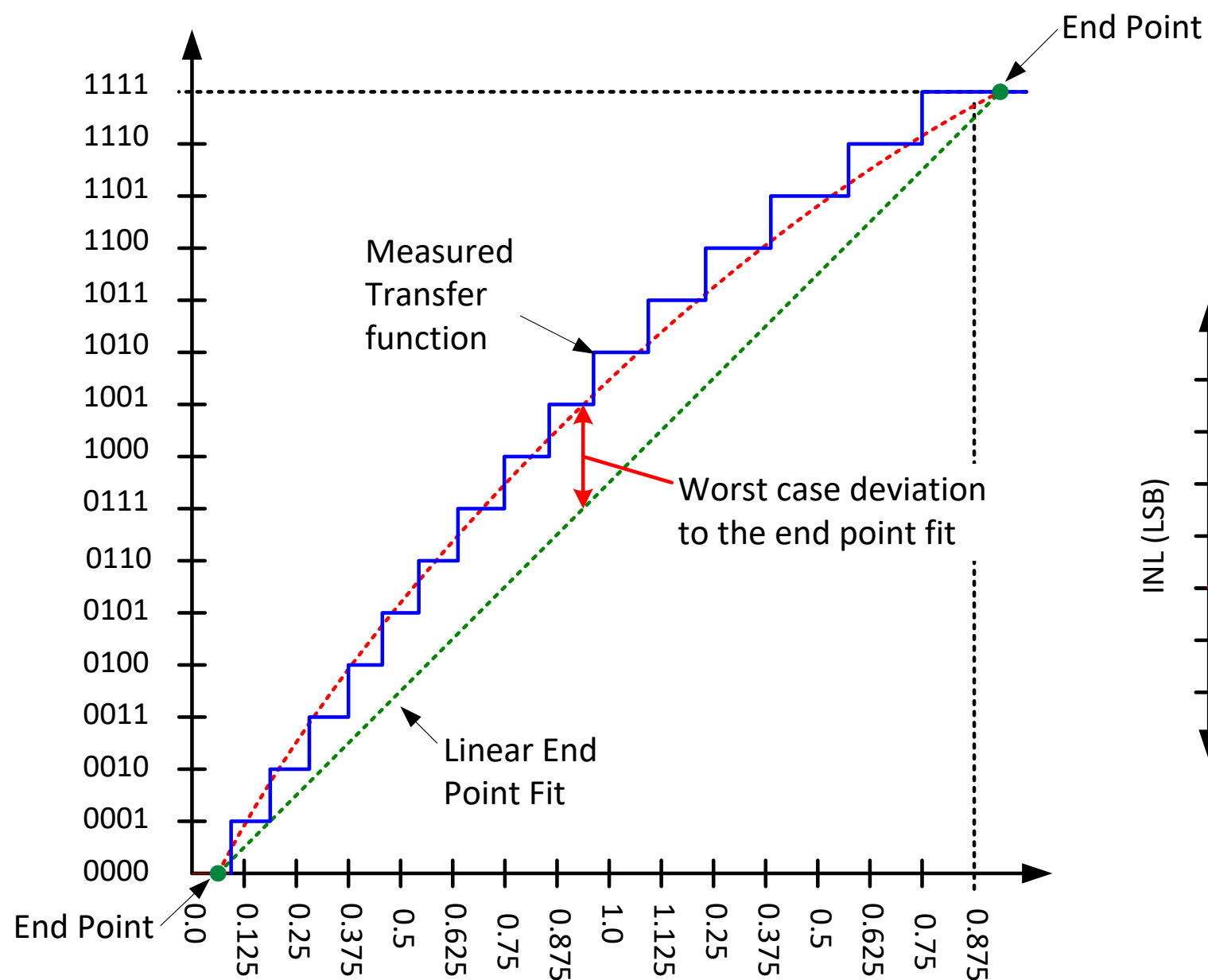


Differential Nonlinearity (DNL) vs. Code

PARAMETER ADS9110	TEST CONDITION	MIN	TYP	MAX	UNIT
SYSTEM PERFORMANCE					
DNL Differential Nonlinearity	AVDD = 1.8V	-0.75	±0.4	+0.75	LSB

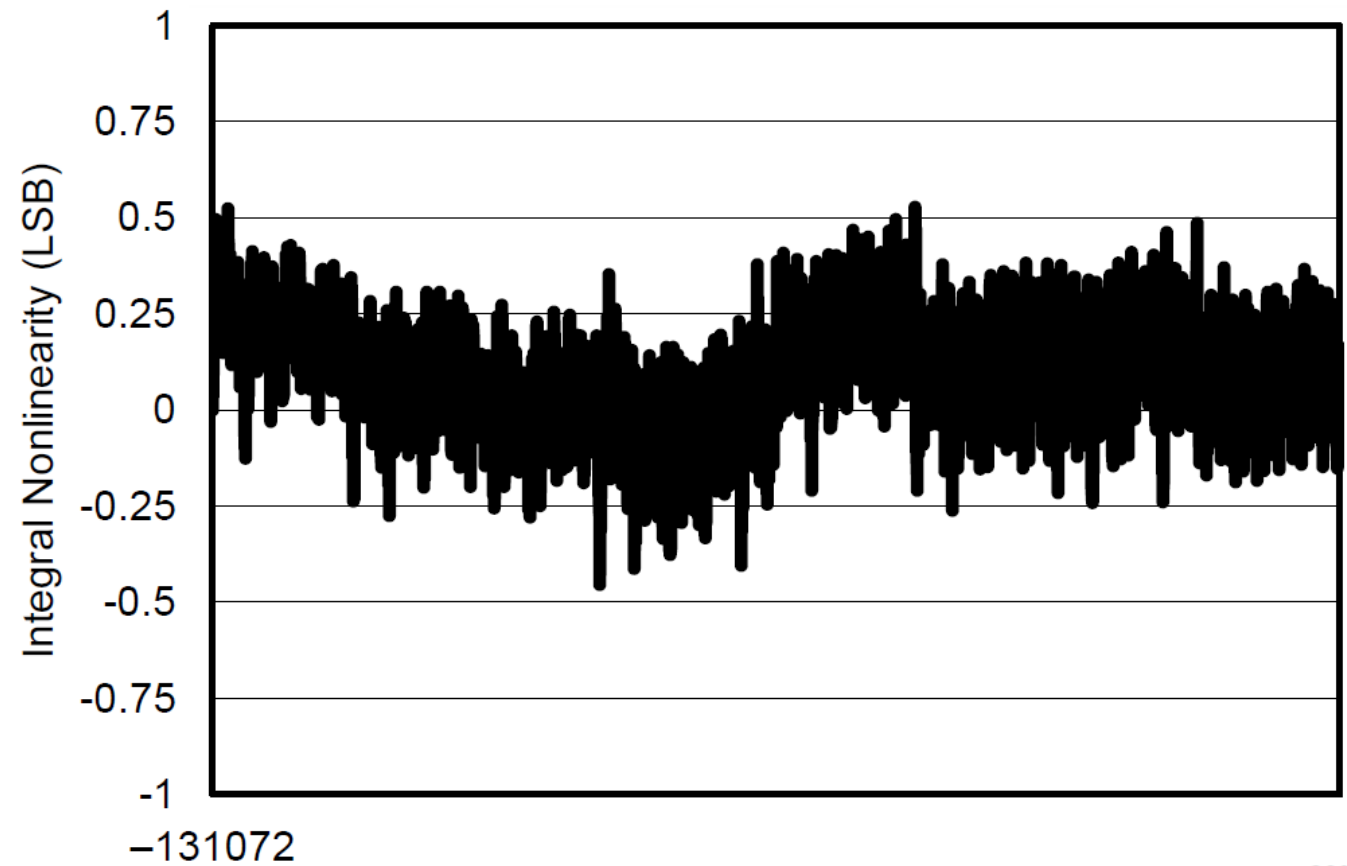


System Performance: Integral Nonlinearity (INL)



INL Data Sheet Specification

PARAMETER ADS9110	TEST CONDITION	MIN	TYP	MAX	UNIT
SYSTEM PERFORMANCE					
INL Integral Nonlinearity	AVDD = 3V	-1.5	±0.5	1.5	LSB



ADC Output Code
Typical INL of ±0.5 LSB

Thanks for your time!
Please try the quiz.

Quiz: DC Specifications

TIPL 4001

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Created by Art Kay

Quiz: DC Specifications

1. The input capacitance from a SAR ADC is from _____.
 - a. The parasitic capacitance of the ESD diodes
 - b. The sample and hold capacitance
 - c. Both a and b.

2. Input leakage current for a SAR ADC _____.
 - a. Is from the external RC filter circuit.
 - b. Will generate an error when flowing through any input resistance.
 - c. Is always negligible.

Quiz: DC Specifications

3. Reference input current _____.
 - a. Is a constant current typically in the milliamps.
 - b. Is a constant current typically in the microamps.
 - c. Has very fast transient spikes that may be milliamps.
 - d. Has very fast transient spikes that may be microamps.

4. How many codes does a four bit converter have?
 - a. 4
 - b. 8
 - c. 16
 - d. 32

Quiz: DC Specifications

5. Differential non-linearity is a measurement of _____.
- a. The code width as compared to the ideal code width.
 - b. The total number of codes in the transfer function.
 - c. The deviation of the measured code to an ideal end point fit line.
 - d. The worst case system error
6. Integral non-linearity is a measurement of _____.
- a. The code width as compared to the ideal code width.
 - b. The total number of codes in the transfer function.
 - c. The deviation of the measured code to an ideal end point fit line.
 - d. The worst case system error

Solutions

Solutions Quiz: DC Specifications

1. The input capacitance from a SAR ADC is from _____.
 - a. The parasitic capacitance of the ESD diodes
 - b. The sample and hold capacitance
 - c. Both a and b.**

2. Input leakage current for a SAR ADC _____.
 - a. Is from the external RC filter circuit.
 - b. Will generate an error when flowing through any input resistance.**
 - c. Is always negligible.

Solutions Quiz: DC Specifications

3. Reference input current _____.
- a. Is a constant current typically in the milliamps.
 - b. Is a constant current typically in the microamps.
 - c. Has very fast transient spikes that may be milliamps.**
 - d. Has very fast transient spikes that may be microamps.
4. How many codes does a four bit converter have?
- a. 4
 - b. 8
 - c. 16**
 - d. 32

Solutions Quiz: DC Specifications

5. Differential non-linearity is a measurement of _____.
- a. **The code width as compared to the ideal code width.**
 - b. The total number of codes in the transfer function.
 - c. The deviation of the measured code to an ideal end point fit line.
 - d. The worst case system error
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