

直流特性の仕様について:

入力容量、漏れ電流、入力インピーダンス
リファレンス電圧範囲
INL（積分非直線性）DNL（微分非直線性）

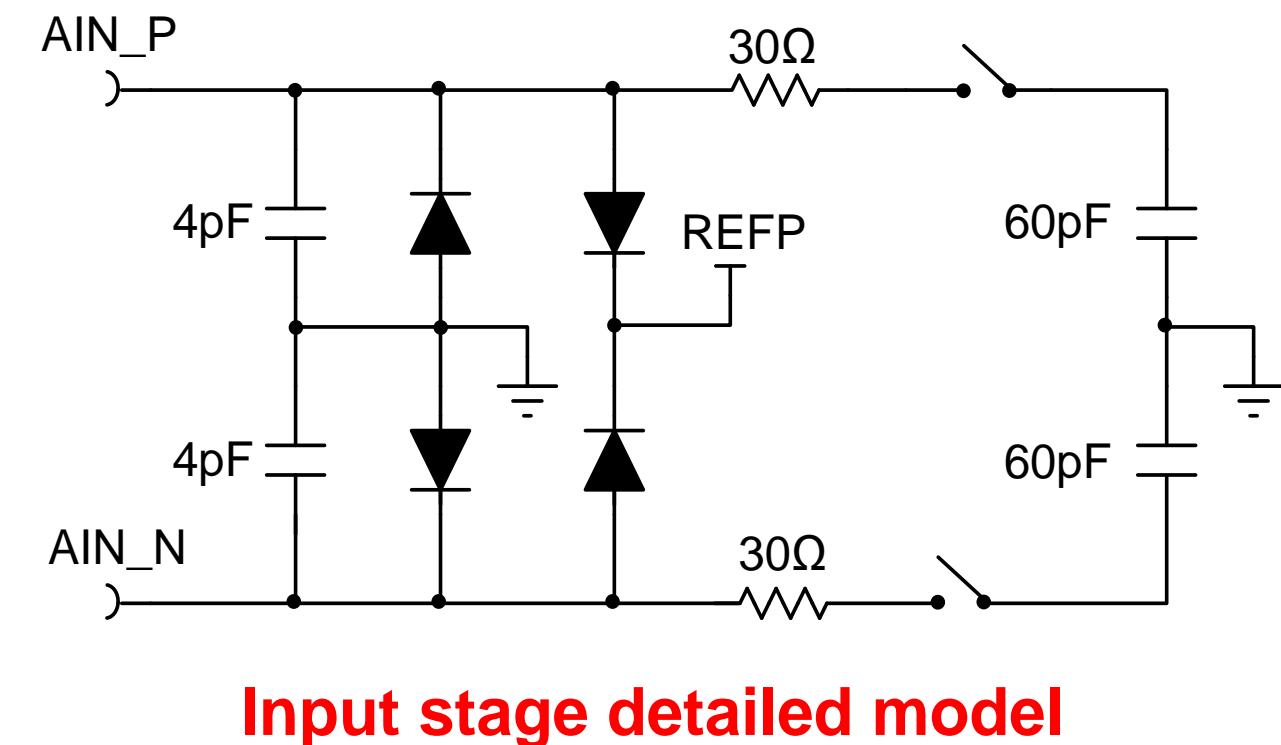
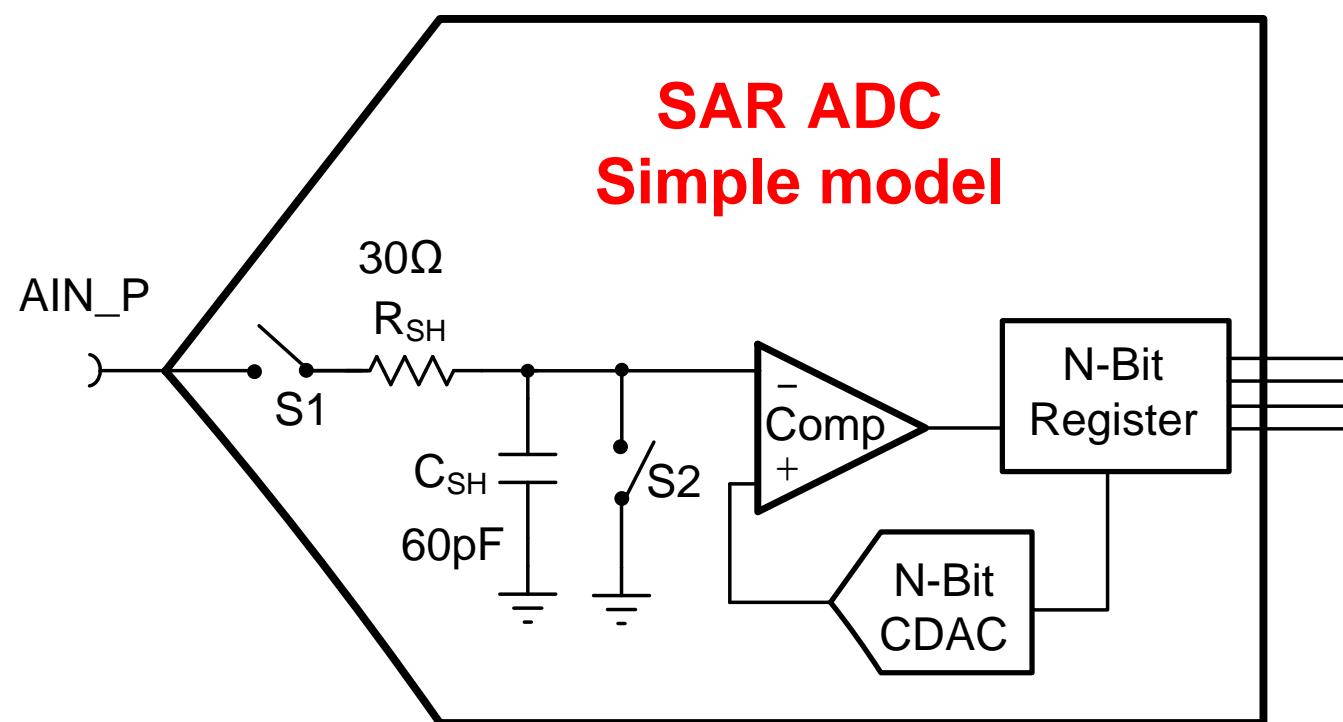
TIPL 4001
TI プレシジョン・ラボ – ADCs

Created by Art Kay

日本語版講師：宮崎 仁

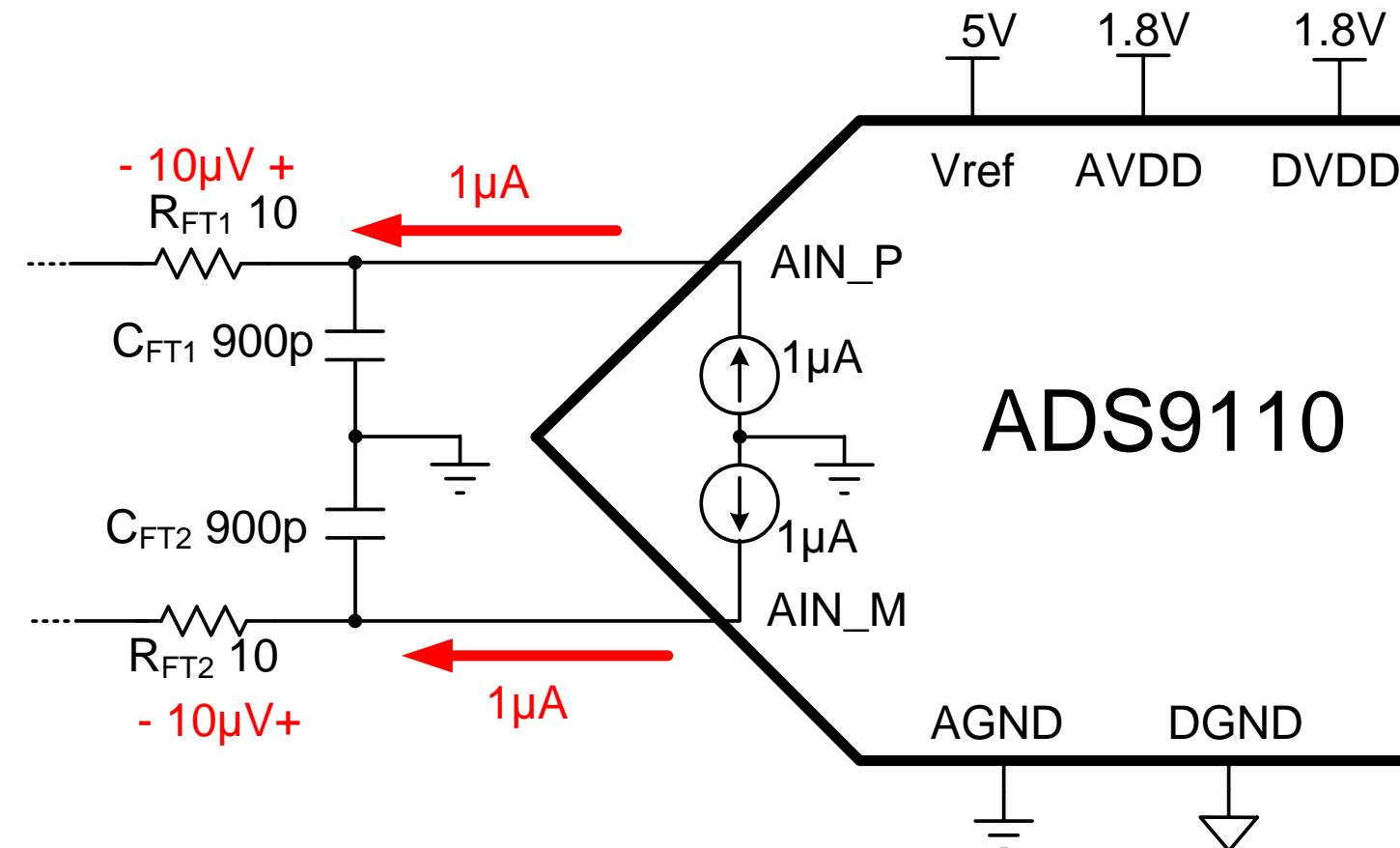
アナログ入力の入力容量

PARAMETER	TEST CONDITION	MIN	TYP	MAX	UNIT
ANALOG INPUT					
CIN Input capacitance	In sample mode	60			pF
	In hold mode	4			

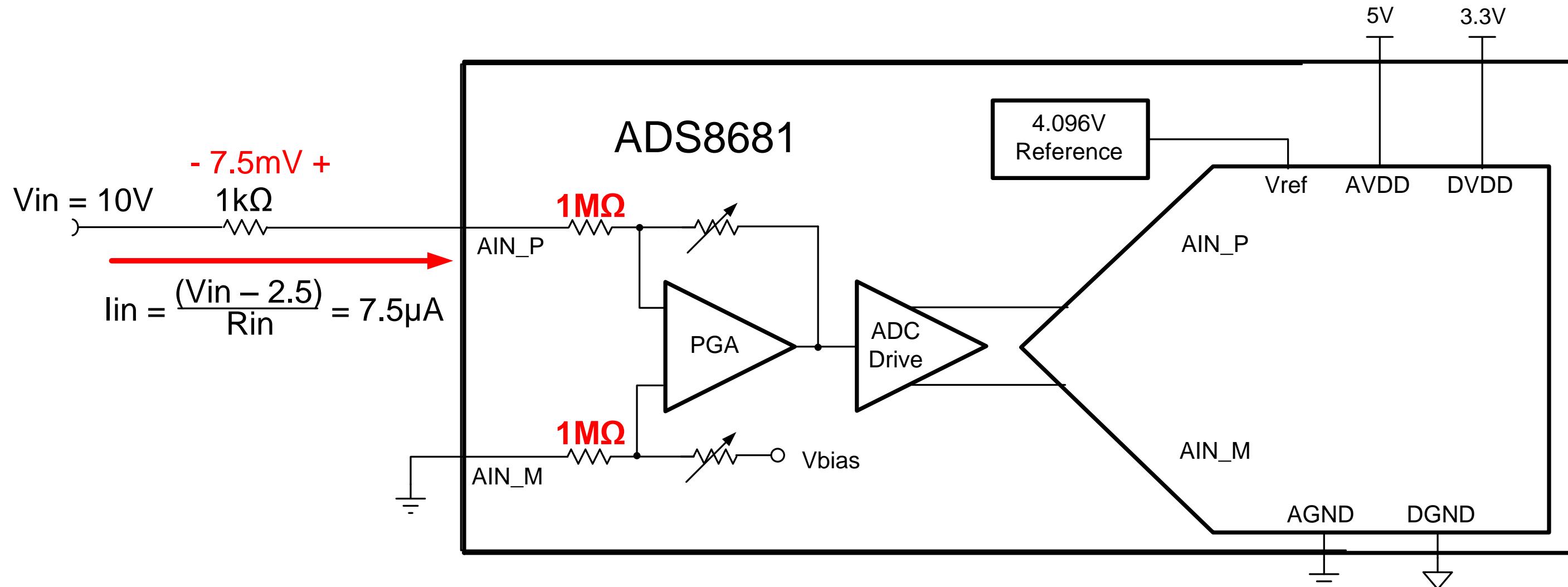


アナログ入力の入力漏れ電流

PARAMETER	TEST CONDITION	MIN	TYP	MAX	UNIT
ANALOG INPUT					
I_{IL} Input leakage current			± 1		μA



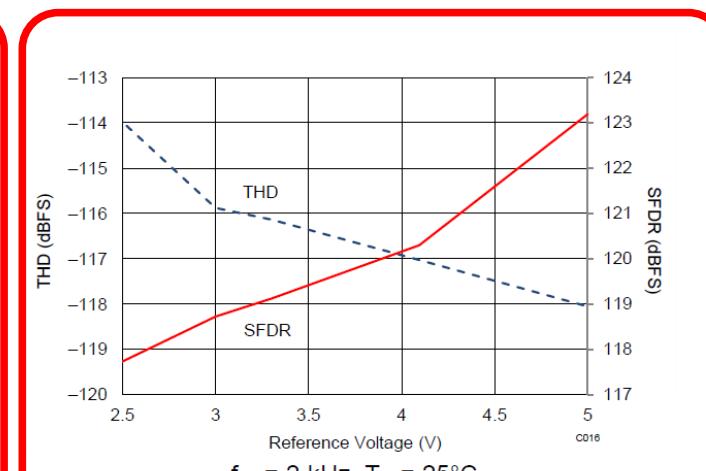
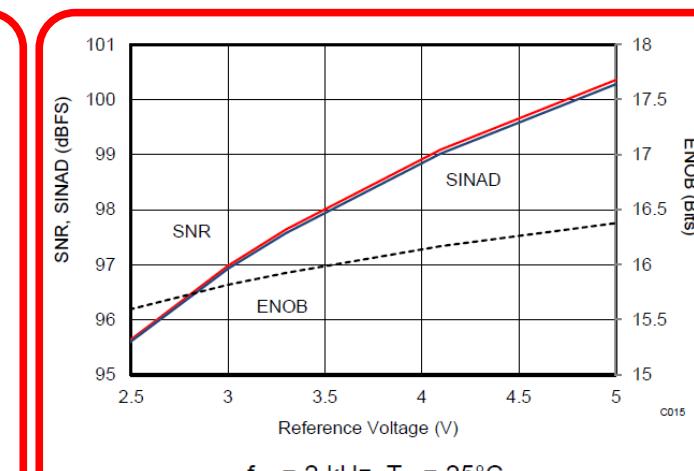
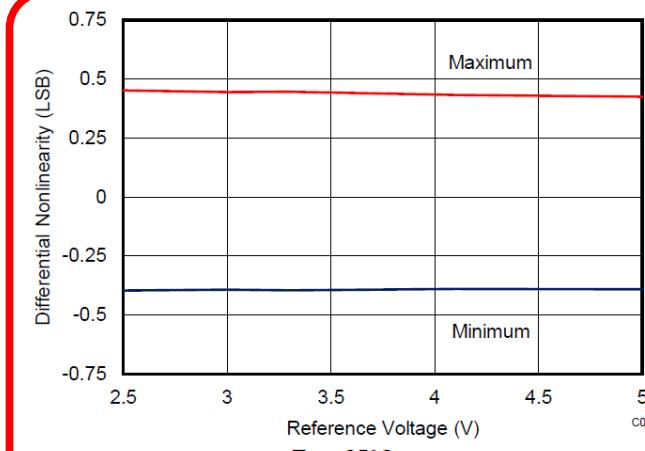
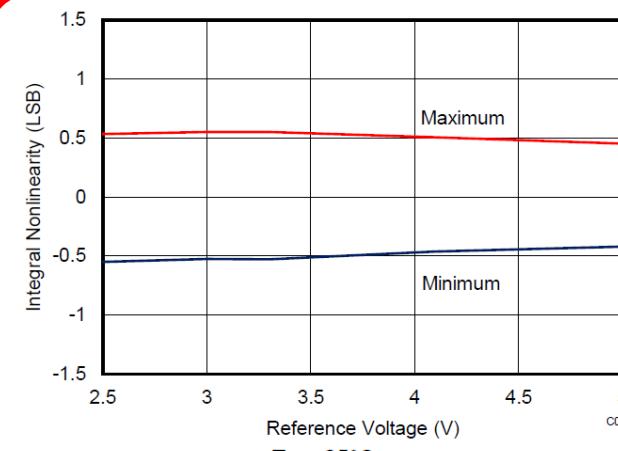
アナログ入力の入力インピーダンス



リファレンス入力の入力電圧範囲

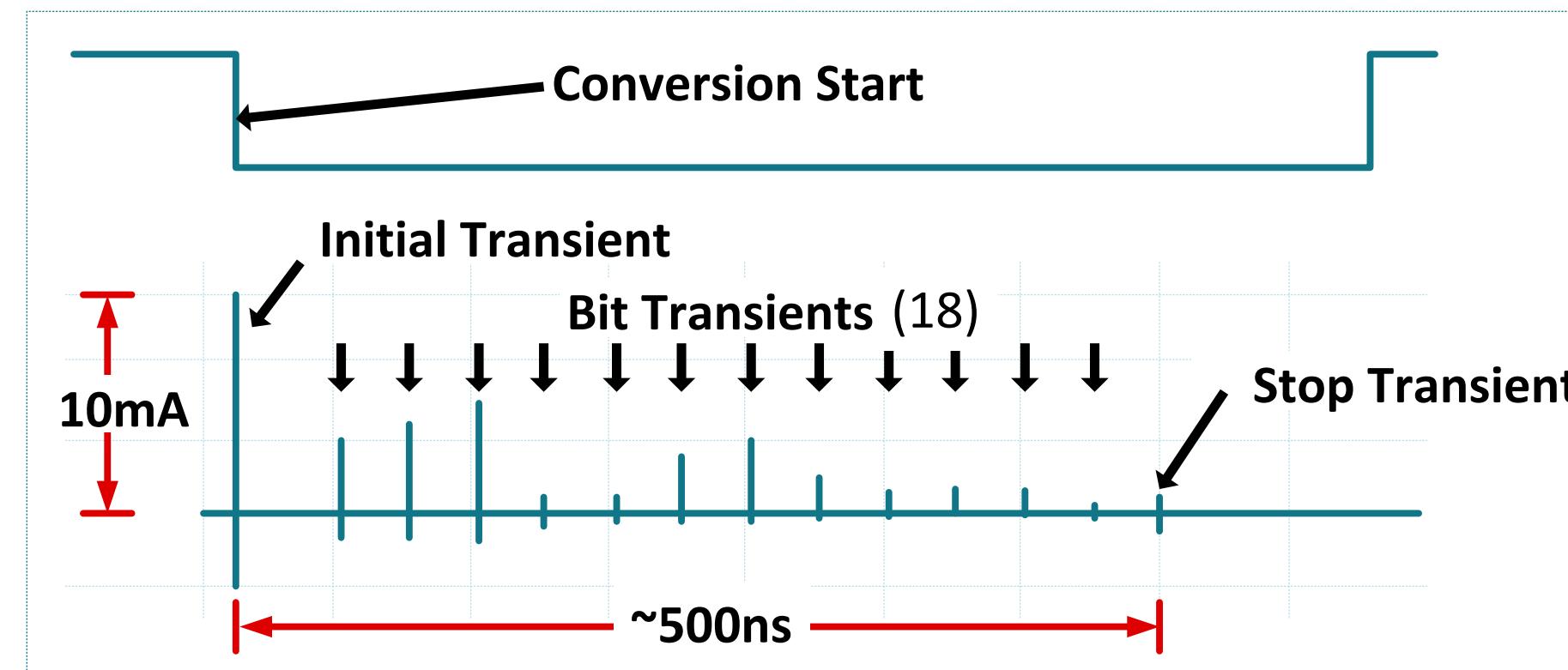
All specifications are for AVDD = 1.8V, DVDD = 1.8V, V_{REF} = 5V, and f_{DATA} = 2Msps, unless otherwise noted

PARAMETER	TEST CONDITION	MIN	TYP	MAX	UNIT
ANALOG INPUT					
V _{REF} Reference Input Voltage Range		2.5		5.0	V



リファレンス入力の入力電流

PARAMETER	TEST CONDITION	MIN	TYP	MAX	UNIT
EXTERNAL REFERENCE INPUT					
Reference input current	During conversion, 1MHz sample rate, midcode		300		µA
Input leakage Current			250		pA
C_{REF} Decoupling capacitor at the reference input		10	22		µF



システム性能: 理想的な伝達関数

$$\text{Number of Codes} = 2^N$$

$$V_{LSB} = \frac{FSR}{2^N}$$

Where

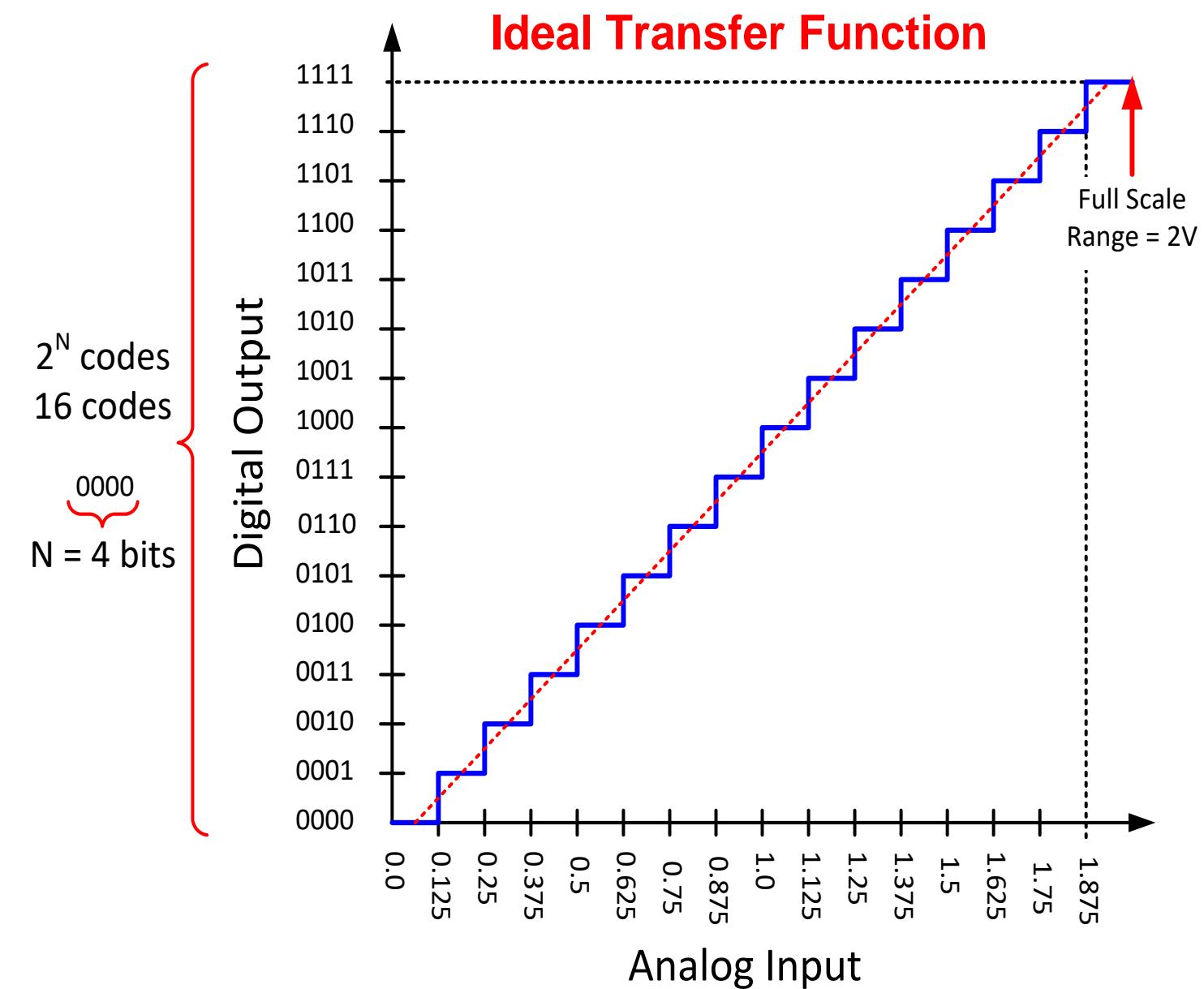
V_{LSB} = The minimum resolvable voltage width

FSR = Full Scale Range

N = Number of bits

$$V_{LSB} = \frac{FSR}{2^N} = \frac{2V}{2^4} = 0.125V$$

$$\text{Number of Codes} = 2^N = 2^4 = 16$$



システム性能: 微分非直線性 (DNL)

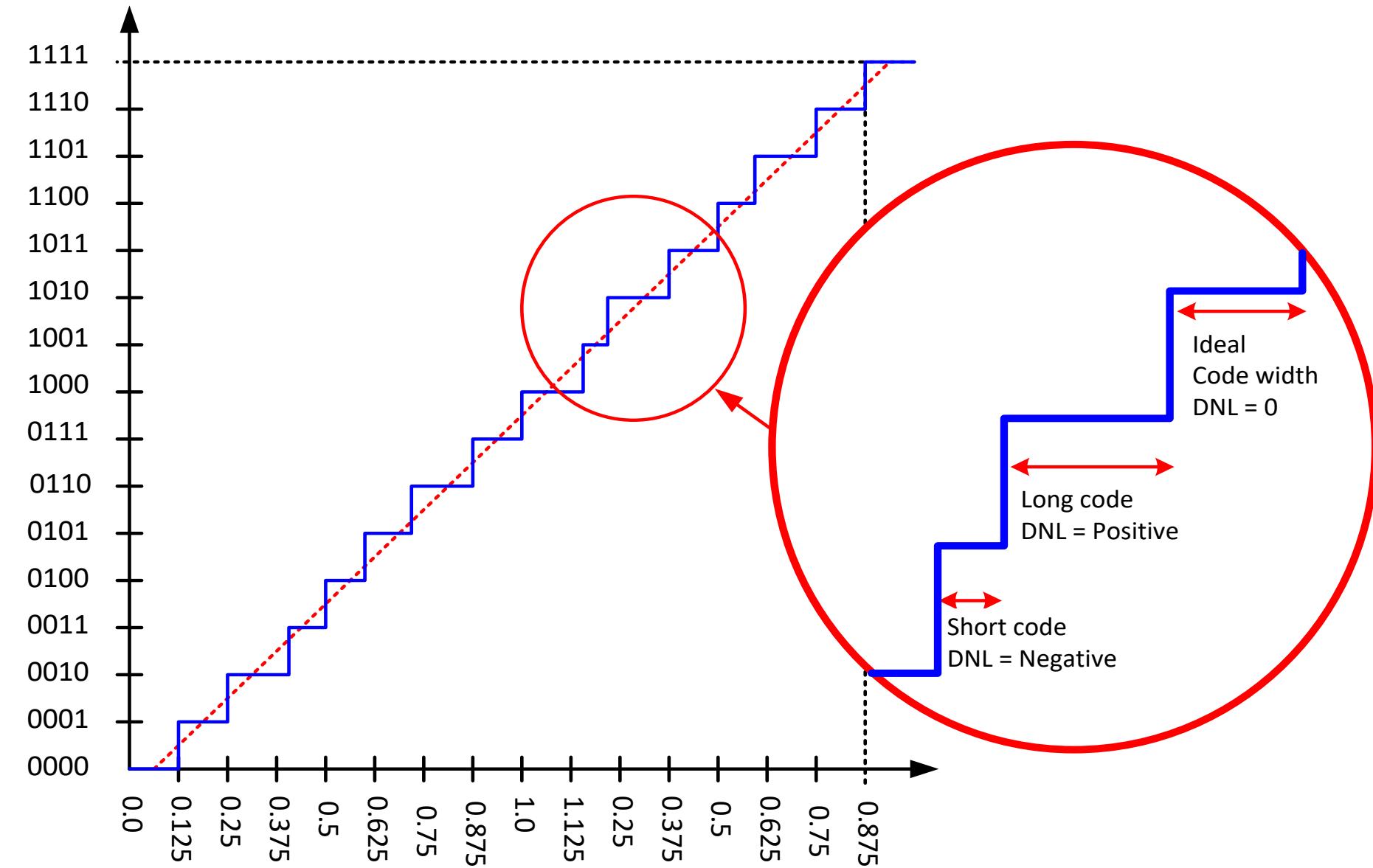
$$DNL[k] = \frac{W[k] - Q}{Q}$$

$$W[k] = T[k + 1] - T[k]$$

$W[k]$ the measured code width.

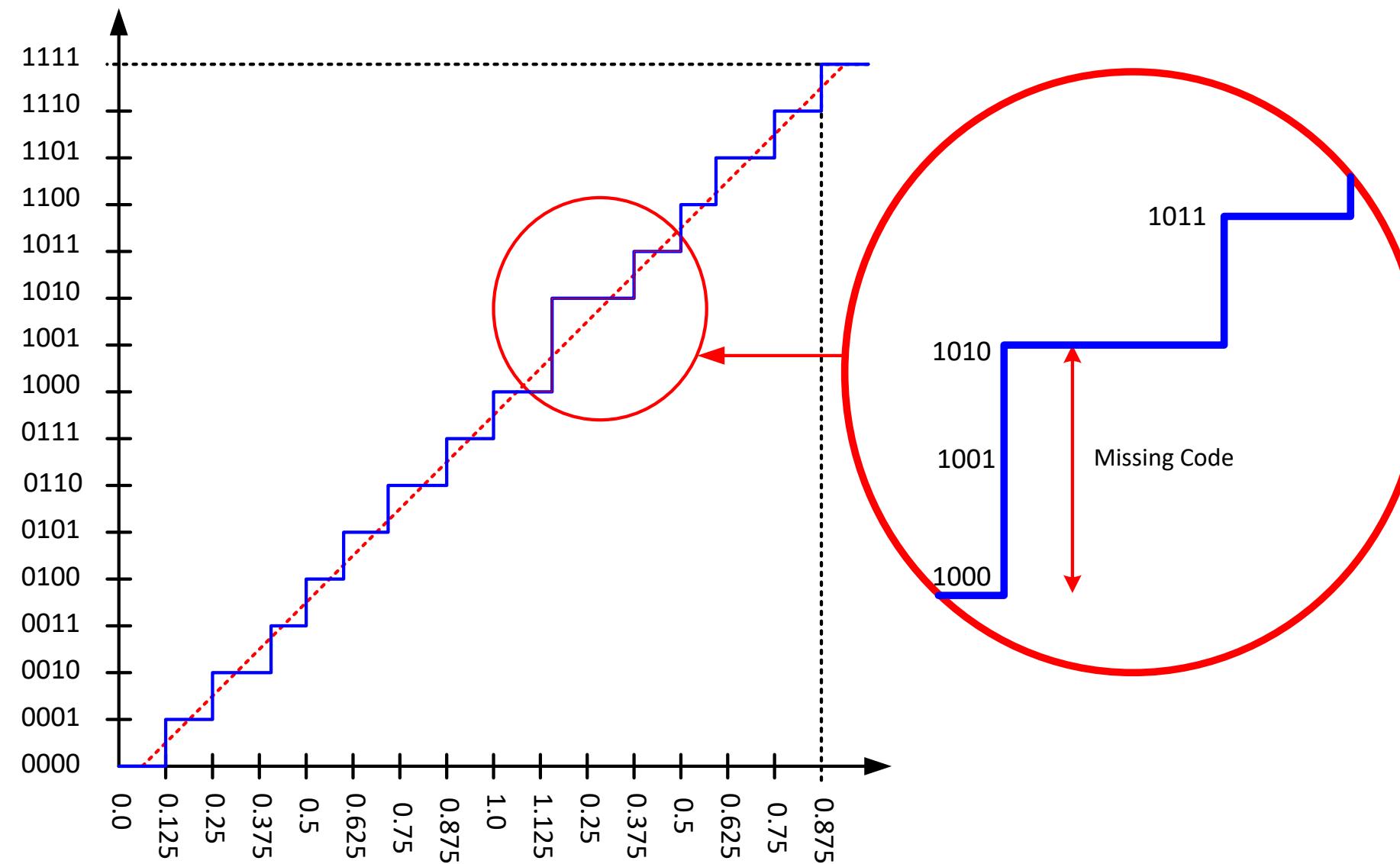
$T[k]$ The voltage level where a code transitions

Q Ideal code width



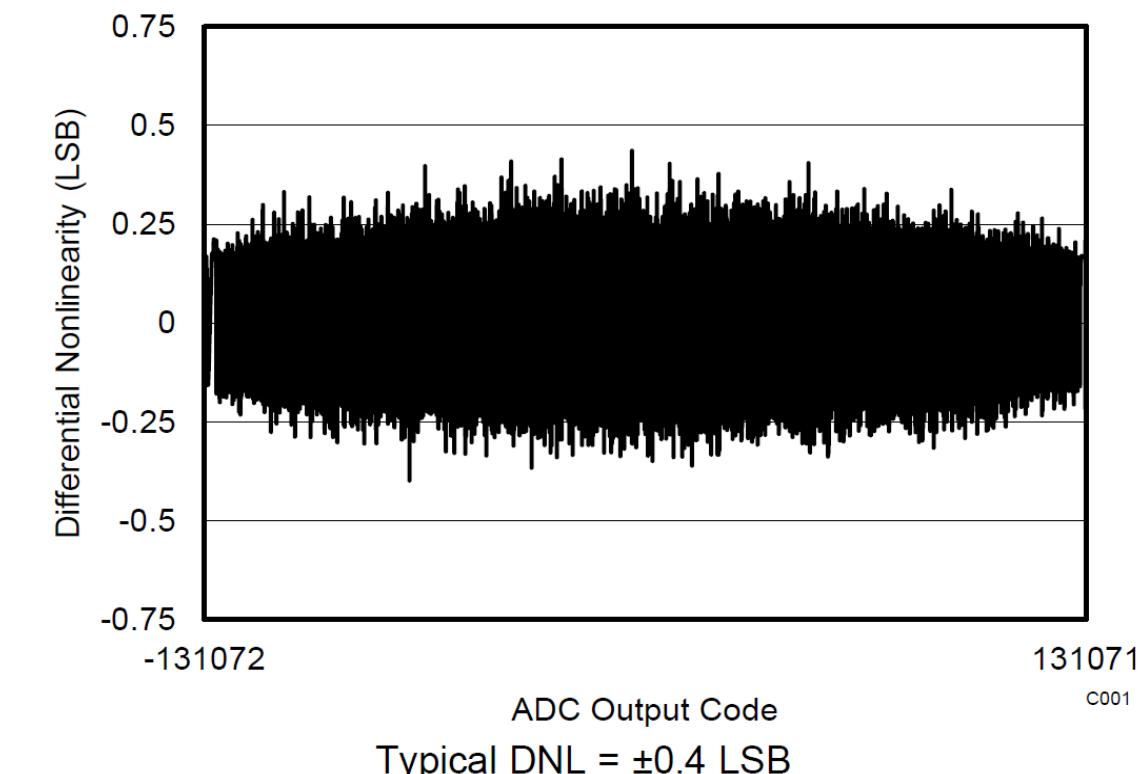
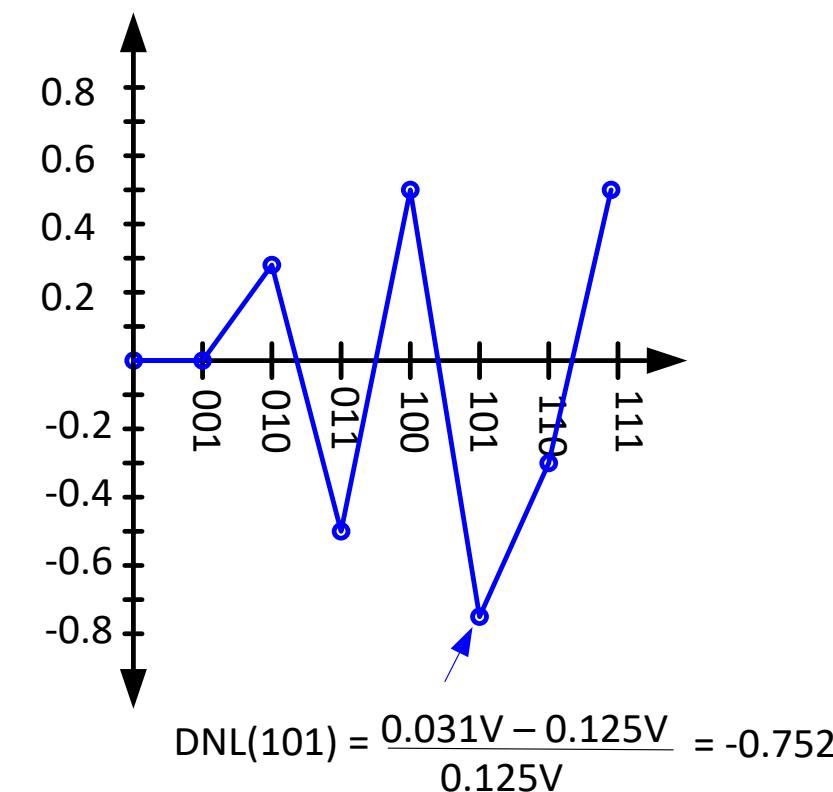
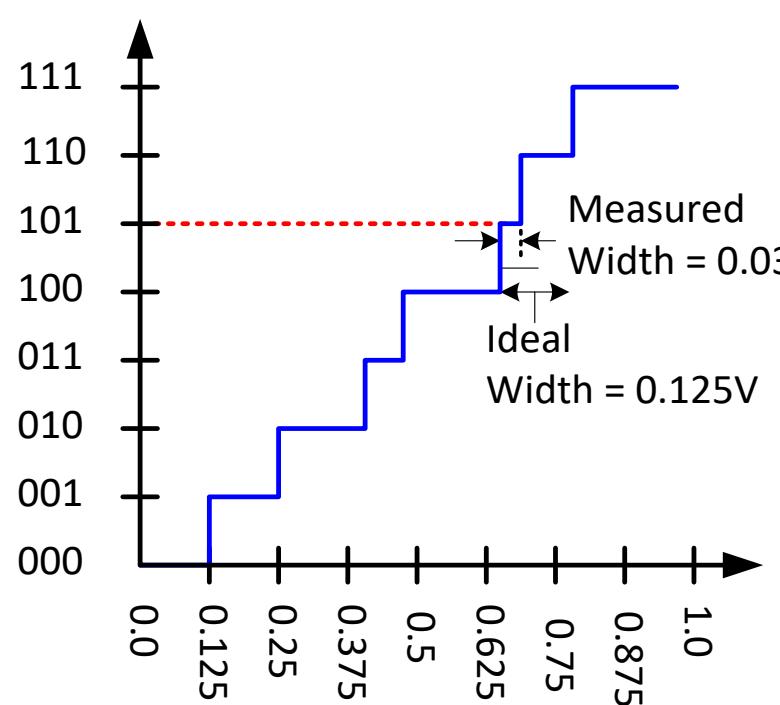
システム性能: ノー・ミッシング・コード (NMC)

PARAMETER	TEST CONDITION	MIN	TYP	MAX	UNIT
SYSTEM PERFORMANCE					
NMC Integral Nonlinearity	AVDD = 3V	12			Bits

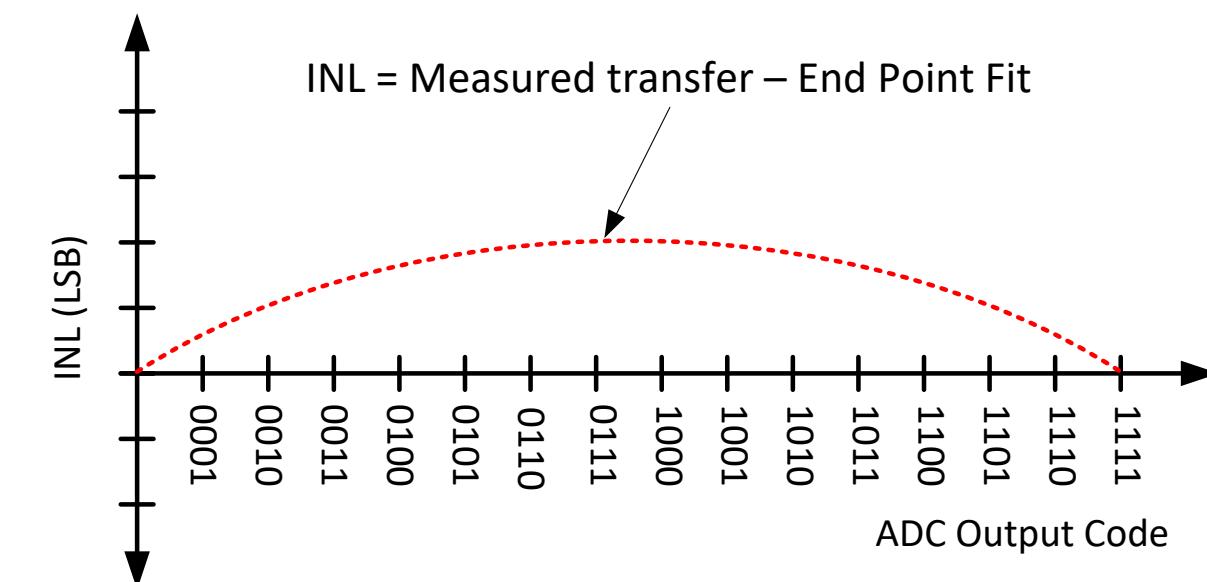
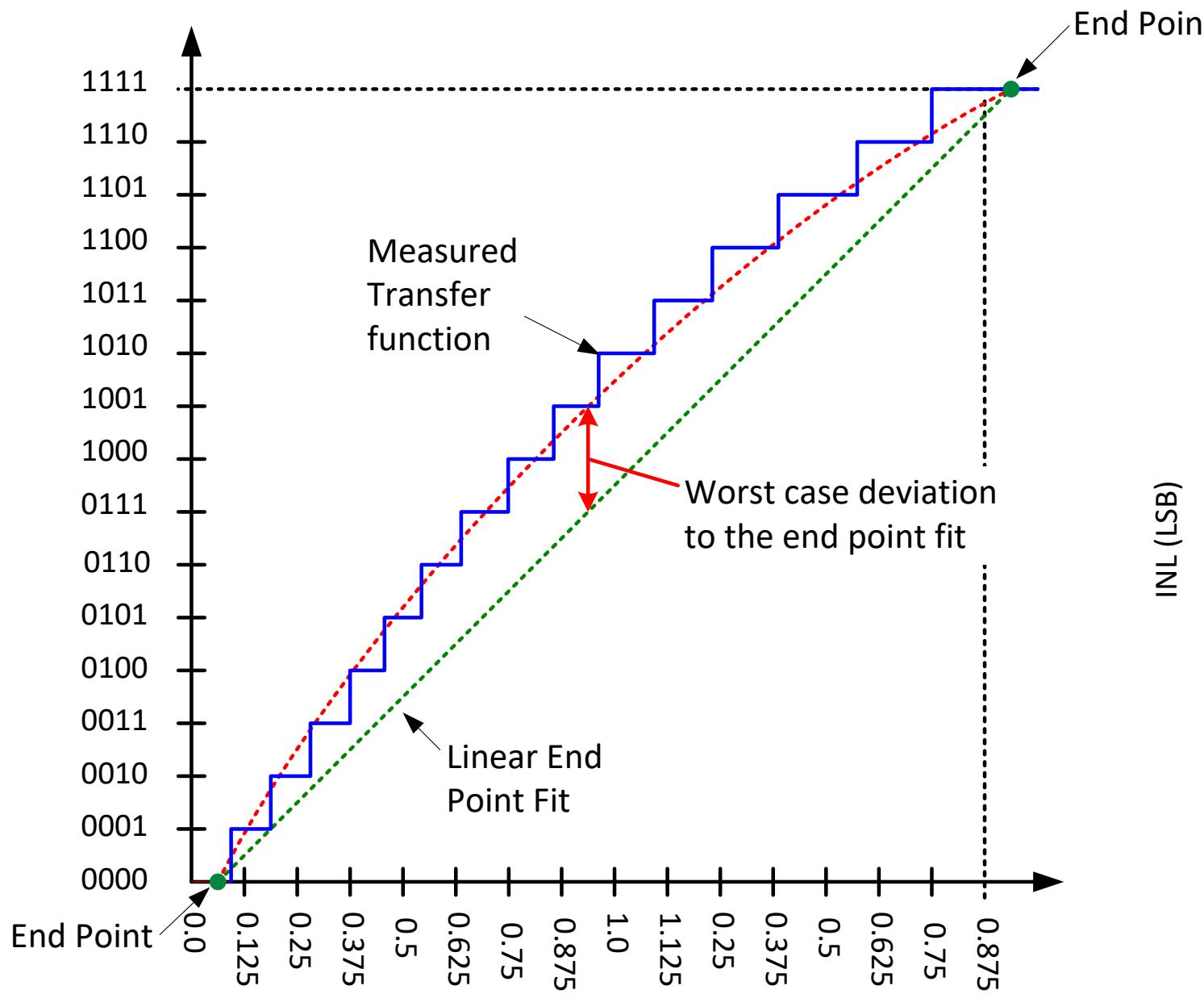


コードによる微分非直線性 (DNL) の変動

PARAMETER ADS9110	TEST CONDITION	MIN	TYP	MAX	UNIT
SYSTEM PERFORMANCE					
DNL Differential Nonlinearity	AVDD = 1.8V	-0.75	± 0.4	+0.75	LSB



システム性能: 積分非直線性 (INL)



データシートでのINL の規定

PARAMETER ADS9110	TEST CONDITION	MIN	TYP	MAX	UNIT
SYSTEM PERFORMANCE					
INL Integral Nonlinearity	AVDD = 3V	-1.5	± 0.5	1.5	LSB

