

LMQ644xx-Q1 3V to 36V, Low I_{QD} , Dual 6/5/4A, Automotive Buck Converter Optimized for Power Density and Low EMI

1 Features

- AEC-Q100 qualified for automotive applications:
 - Device temperature grade 1: -40°C to $+125^{\circ}\text{C}$ ambient operating temperature
 - Operation up to 150°C junction temperature
- Functional Safety-Capable**
 - [Documentation available to aid functional safety system design](#)
- Designed for Low EMI
 - Symmetrical input voltage pins with $> 1\text{mm}$ clearance to ground
 - Four 22nF integrated VIN to GND bypass capacitors
 - Two bypass capacitors placed in series between each VIN and GND for high reliability
 - Pin selectable spread spectrum option
 - Pin selectable FPWM or auto mode operation
 - Enhanced HotRod™ QFN (25) package with wettable flanks
 - Switching frequency from 100kHz to 2.2MHz
 - Meets CISPR 25 class 5 EMI requirements
- Single and dual-output features
 - Wide input voltage range of 3V to 36V
 - 1% accurate fixed 3.3V, 5V or adjustable outputs from 0.8V to 20V
 - Hiccup-mode overcurrent protection and thermal shutdown protection with hysteresis
 - Precision ENABLE and PGOOD functions
 - 50ns $t_{ON(min)}$ for high V_{IN} / V_{OUT} ratio
 - 80ns $t_{OFF(min)}$ for low dropout
- Versatile dual-output operation
 - Shutdown mode current: 0.5 μA typical
 - No-load standby current: 9 μA typical
 - Built-in compensation and 3ms soft start
 - Independent precision ENABLE and PGOOD
- Adaptable single-output operation
 - $> 95\%$ efficient for an 8A load, single output, $V_{IN} = 12\text{V}$, $V_{OUT} = 5\text{V}$
 - External compensation and adjustable soft start
 - PGOOD, SYNCIN, and SYNCOUT functions

2 Applications

- Automotive infotainment and cluster: head unit, media hub, USB charge, display
- Automotive ADAS and body electronics
- General-purpose dual buck converters

3 Description

The LMQ644xx-Q1 is a 36V, synchronous, buck, DC/DC converter for high-current single or dual outputs. The device uses an interleaved, stackable, current-mode control architecture for easy loop compensation, fast transient response, excellent load and line regulation, and accurate current sharing with an output clock supporting up to 6 phases for currents up to 36A. A high-side switch minimum on-time of 50ns gives large step-down ratios, enabling the direct conversion from 12V, 24V, or automotive inputs to low-voltage rails for reduced system complexity and design cost.

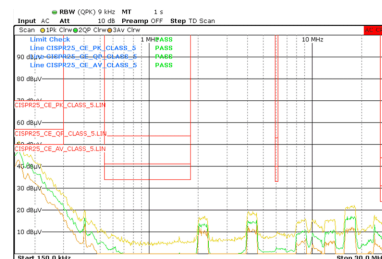
The LMQ644xx-Q1 incorporates spread spectrum in an optimized enhanced HotRod QFN package, with wettable flanks, and four 22nF high frequency integrated capacitors to minimize EMI. Dual Random Spread Spectrum (DRSS) frequency hopping is set to $\pm 10\%$ (typical), drastically reducing emissions through a combination of triangular and pseudo-random modulation. A bias pin allows the LMQ644xx-Q1 to save losses by powering the device from the output of the converter, achieving a 9 μA no-load quiescent current to extend the operating run-time in battery-powered systems. The LMQ644xx-Q1 can maintain high efficiency light-load operation even when stacking multiple devices for high efficiency over the full load range.

Device Information

PART NUMBER ⁽²⁾	PACKAGE ⁽¹⁾	BODY SIZE (NOM)
LMQ644A2-Q1	RXA (VQFN-FCRLF, 24)	4.0mm × 5.0mm
LMQ644A0-Q1		
LMQ64480-Q1		

(1) For more information, see [Section 11](#).

(2) See the [Device Comparison Table](#).



CISPR 25 Conducted, $V_{OUT} = 3.3\text{V}$, 2.1MHz, 12A



Table of Contents

1 Features	1	7.4 Device Functional Modes.....	29
2 Applications	1	8 Application and Implementation	35
3 Description	1	8.1 Application Information.....	35
4 Device Comparison Table	3	8.2 Typical Application.....	35
5 Pin Configuration and Functions	4	8.3 Power Supply Recommendations.....	52
5.1 Wettable Flanks.....	7	8.4 Layout.....	53
6 Specifications	8	9 Device and Documentation Support	55
6.1 Absolute Maximum Ratings.....	8	9.1 Device Support.....	55
6.2 ESD Ratings.....	8	9.2 Receiving Notification of Documentation Updates....	55
6.3 Recommended Operating Conditions.....	8	9.3 Support Resources.....	55
6.4 Thermal Information.....	8	9.4 Trademarks.....	55
6.5 Electrical Characteristics.....	9	9.5 Electrostatic Discharge Caution.....	55
6.6 Typical Characteristics.....	12	9.6 Glossary.....	55
7 Detailed Description	13	10 Revision History	55
7.1 Overview.....	13	11 Mechanical, Packaging, and Orderable Information	56
7.2 Functional Block Diagram.....	14		
7.3 Feature Description.....	15		

4 Device Comparison Table

DEVICE	ORDERABLE PART NUMBER	RATED OUTPUT CURRENT	PACKAGE	JUNCTION TEMPERATURE RANGE
LMQ644A2-Q1	LMQ644A2QRXARQ1	Dual 6 A/6 A, or stackable 12 A	RXA (WQFN, 24)	–40°C to 150°C
LMQ644A0-Q1	LMQ644A0QRXARQ1	Dual 5 A/5 A, or stackable 10 A	RXA (WQFN, 24)	–40°C to 150°C
LMQ64480-Q1	LMQ64480QRXARQ1	Dual 4 A/4 A, or stackable 8 A	RXA (WQFN, 24)	–40°C to 150°C

5 Pin Configuration and Functions

RXA package, 24-pin VQFN-FCRLF with Wettable Flanks

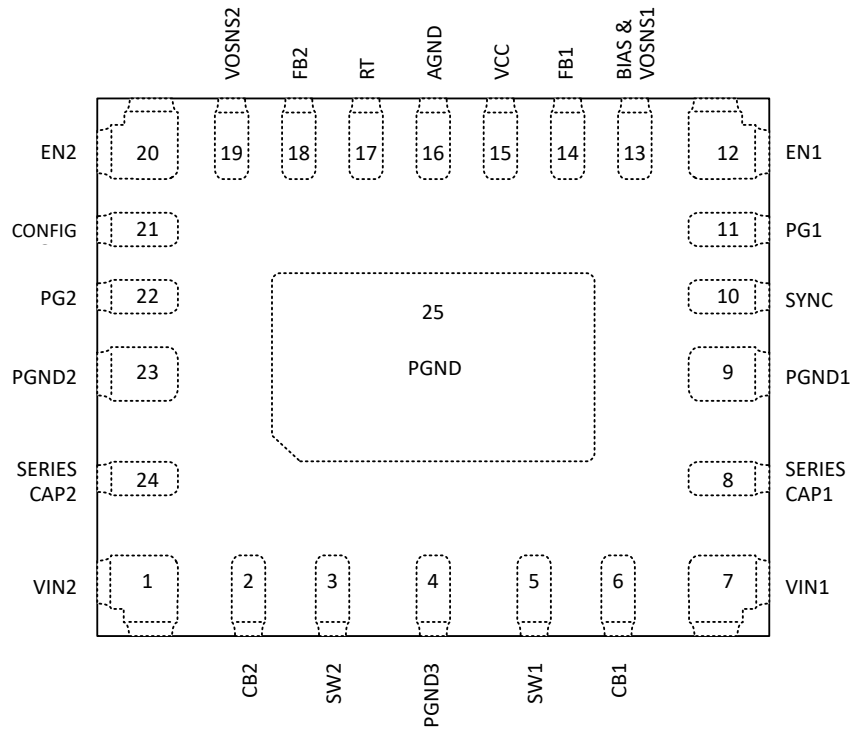


Figure 5-1. Dual Output (Top View)

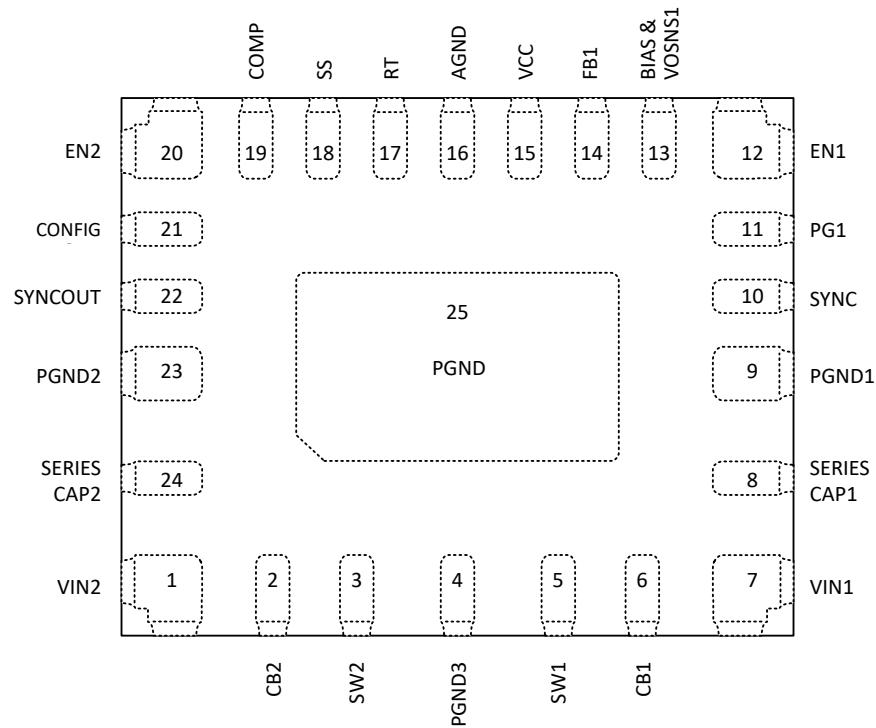


Figure 5-2. Single Output Primary (Top View)

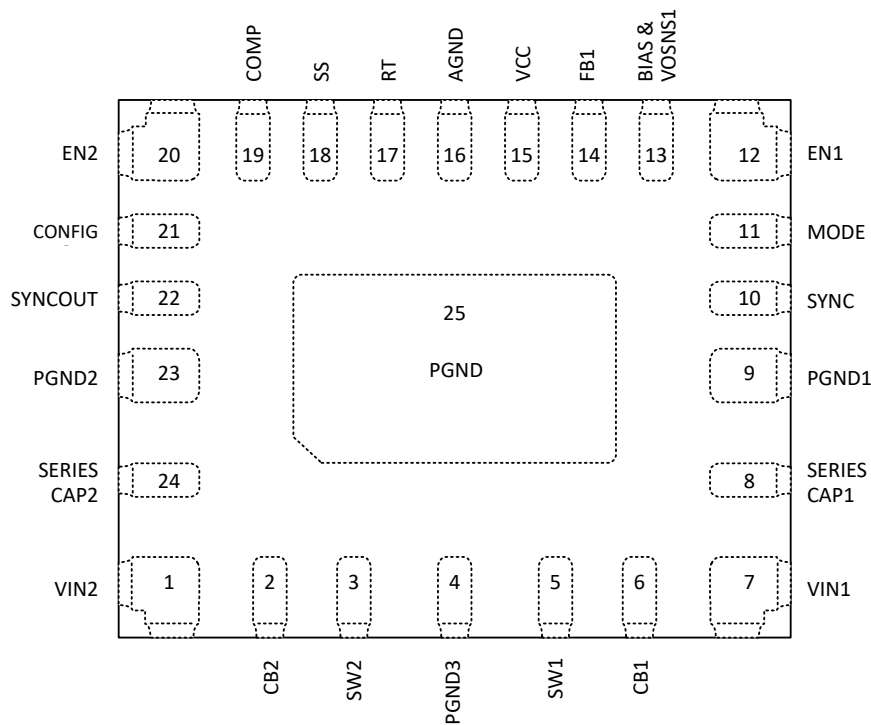


Figure 5-3. Single Output Secondary (Top View)

Table 5-1. Pin Functions

NO.	PIN		TYPE ⁽¹⁾	DESCRIPTION
	NAME			
	DUAL OUTPUT	SINGLE OUTPUT		
1	VIN2	VIN2	I	Input supply to the regulator. Connect a high quality bypass capacitors from this pin to PGND2. Low impedance connection must be provided to VIN1.
2	BOOT2	BOOT2	I/O	Channel 2 high-side driver upper supply rail. Connect a 100-nF capacitor between SW2 and BOOT2. An internal diode charges the capacitor while SW2 is low.
3	SW2	SW2	P	Channel 2 Switching node that is internally connected to the source of the high-side NMOS buck switch and the drain of the low-side NMOS synchronous rectifier. Connect to the switching node of the power inductor.
4	PGND3	PGND3	G	Power ground to internal low side MOSFET. Connect to system ground. Low impedance connection must be provided to PGND1, PGND2 and exposed pad.
5	SW1	SW1	P	Channel 1 Switching node that is internally connected to the source of the high-side NMOS buck switch and the drain of the low-side NMOS synchronous rectifier. Connect to the switching node of the power inductor.
6	BOOT1	BOOT1	I/O	Channel 1 High-side driver upper supply rail. Connect a 100-nF capacitor between SW1 and BOOT1. An internal diode charges the capacitor while SW1 is low.
7	VIN1	VIN1	I	Input supply to the regulator. Connect a high quality bypass capacitors from this pin to PGND1. Low impedance connection must be provided to VIN2.
8	SERIES CAP1	SERIES CAP1	NC	Pin is connected to mid-point of two series capacitors between pins VIN1 and PGND1. This pin can be left floating, or can be connected to the mid-point of additional bypass capacitors in series configuration if required for the end application.
9	PGND1	PGND1	G	Power ground to internal low side MOSFET. Connect to system ground. Low impedance connection must be provided to PGND2 and PGND3. Connect a high quality bypass capacitors from this pin to VIN1.
10	SYNC	SYNC	I	Multi-function pin. SYNC selects forced pulse width modulation (FPWM) or Diode Emulation mode. Connect SYNC to AGND to enable diode emulation mode. Connect SYNC to VCC to operate the LMQ644xx in FPWM mode with continuous conduction at light loads. SYNC can also be used as a synchronization input to synchronize the internal oscillator to an external clock. When used as a secondary device in single output configuration, the SYNC pin is connected to SYNC_OUT of the primary for clock timing.
11	PG1	MODE	O	Dual function pin. An open drain output that transitions low if VOSNS1 is outside a specified regulation window in dual output and single output primary configuration. In single output secondary mode configuration, this behaves as a mode pin to select between forced PWM (FPWM) mode and Diode Emulation Mode (DEM). Connect MODE of single output secondary to SYNC pin of single output primary to place them in the same mode of operation. For FPWM, connect MODE to VCC through a 10 kOhm resistor. For DEM connect to ground.
12	EN1	EN1	I	An active high input LMQ644xx ($V_{OH} > 1.375$ V) enables Output 1 in dual output operation. When in single output operation, an active high input enables all phases in the system. When disabled, the LMQ644xx is in shutdown mode. EN1 must never be floating.
13	BIAS & VOSNS1	BIAS & VOSNS1	I	Output voltage sense and input to internal voltage regulator. Connect to non-switching side of the inductor. Connect an optional high quality 0.1- μ F capacitor from this pin to AGND for best performance.
14	FB1	FB1	I	Feedback input to channel 1 of the LMQ644xx in dual output operation and feedback input to all channels in single output operation. Connect FB1 to VCC through a 10 kOhm resistor for a 5-V output or connect FB1 to AGND for a 3.3-V output. A resistive divider from the non-switching side of the inductor to FB1 sets the output voltage level between 0.8 V and 20 V. The regulation threshold at FB1 is 0.8 V. For lower output voltages use at least a 10 kOhm for the top of the resistor divider.
15	VCC	VCC	O	Internal regulator output. Used as supply to internal control circuits. Do not connect to any external loads. Connect a high quality 1- μ F capacitor from this pin to AGND.
16	AGND	AGND	G	Analog ground connection. Ground return for the internal voltage reference and analog circuits.
17	RT	RT	I	Frequency programming pin. A resistor from RT to AGND sets the oscillator frequency between 100 kHz and 2.2 MHz.

Table 5-1. Pin Functions (continued)

NO.	PIN		TYPE ⁽¹⁾	DESCRIPTION
	NAME			
	DUAL OUTPUT	SINGLE OUTPUT		
18	FB2	SS	I	Dual function pin. When in dual output operation, the pin functions as FB2, feedback input to channel 2 of the LMQ644xx. Connect FB2 to VCC through a 10 kOhm resistor for a 5-V output or connect FB2 to AGND for a 3.3-V output. A resistive divider from the non-switching side of the inductor to FB2 sets the output voltage level between 0.8 V and 20 V. For lower output voltages use at least a 10 kOhm for the top of the resistor divider. When in single output mode, the pin functions as SS. An external capacitor must be placed from SS to AGND for external soft-start of the output. Connect the SS pins of primary and secondaries for fault communication between devices.
19	VOSNS2	COMP	I	Dual function pin. In dual output operation, the pin functions as VOSNS2 for the fixed 3.3-V and 5-V and adjustable output conditions. In single output operation, the pin is the output of the internal error amplifier.
20	EN2	EN2	I	An active high input ($V_{OH} > 1.375$ V) enables Output 2 in dual output operation. When in single output mode, EN2 of all LMQ644xx must be connected together. An active high input enables all secondary phases in the system. When disabled, only one channel in the primary LMQ644xx is active while all remaining phases are in shutdown mode. EN2 must never be floating.
21	CONFIG	CONFIG	I	Single or Dual output selection. Connect specific resistor values to the pin (refer to Table 7-3) to select number of phases, primary and secondary and dither options.
22	PG2	SYNC_OUT	O	Dual function pin. In dual output operation, this pin behaves as PG2, an open drain output that transitions low if VOSNS2 is outside a specified regulation window. In single output mode, the pin functions as SYNC_OUT and provides clock information from primary to secondary.
23	PGND2	PGND2	G	Power ground to internal low side MOSFET. Connect to system ground. Low impedance connection must be provided to PGND1, PGND3 and PGND4. Connect a high quality bypass capacitors from this pin to VIN2.
24	SERIES CAP2	SERIES CAP2	NC	Pin is connected to mid-point of two series capacitors between pins VIN2 and PGND2. This pin can be left floating for better pin FMEA, or can be connected to the mid-point of a capacitive divider between VIN2 and PGND2 as per convenience.
25	PGND4	PGND4	G	Power ground and heat sink connection. Solder directly to system ground plane. Low impedance connection must be provided to PGND1, PGND2 and PGND3.

(1) I = input, O = output, P = power, G = ground

5.1 Wettable Flanks

100% automated visual inspection (AVI) post-assembly is typically required to meet requirements for high reliability and robustness. Optimized QFN packages do not have solderable or exposed pins and terminals that are easily viewed. It is therefore difficult to visually determine whether or not the package is successfully soldered onto the printed-circuit board (PCB). The wettable-flank process was developed to resolve the issue of side-lead wetting of leadless packaging. The LMQ644xx-Q1 is assembled using a 24-pin Enhanced HotRod QFN package with wettable flanks to provide a visual indicator of solderability, which reduces the inspection time and manufacturing costs.

6 Specifications

6.1 Absolute Maximum Ratings

Over operating junction temperature range (unless otherwise noted) ⁽¹⁾

		MIN	MAX	UNIT
Pin voltage	VIN1, VIN2 to PGND (transient)	-0.3	42	V
Pin voltage	SW1, SW2 to PGND (less than 10ns transient)	-6	42.3	V
Pin voltage	SW1, SW2 to PGND (transient)	-0.3	42.3	V
Pin voltage	BOOT1 - SW1, BOOT2 - SW2	-0.3	5.5	V
Pin voltage	EN1, EN2 to AGND	-0.3	42	V
Pin voltage	PG1, SYNC_OUT/PG2 to AGND	-0.3	20	V
Pin voltage	SYNC/MODE, FB1, FB2/SS, CONFIG to AGND	-0.3	5.5	V
Pin voltage	BIAS/VOSNS1, COMP/VOSNS2 to AGND	-0.3	22	V
Pin voltage	RT, VCC to AGND	-0.3	5.5	V
Pin voltage	PGND1/2/3 to AGND voltage differential	-1	2	V
Sink current	PG1, PG2		10	mA
T _J	Operating junction temperature	-40	150	°C
T _{stg}	Storage temperature	-55	150	°C

- (1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

6.2 ESD Ratings

			VALUE	UNIT	
V _(ESD)	Electrostatic discharge	Human body model (HBM), per AEC Q100-002 ⁽¹⁾ HBM ESD classification Level 2	±2000	V	
		Charged device model (CDM), per AEC Q100-011 CDM ESD classification Level C5	Corner pins (VIN1, VIN2, EN1, and EN2)		±750
			Other pins		±750

- (1) AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

6.3 Recommended Operating Conditions

Over operating junction temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V _{VOSNS1/2}	Output Voltage range	0.8		20	V
V _{IN1/2}	Input supply voltage range	VIN1, VIN2		36	V
F _{SW}	Frequency	Switching frequency range		2200	kHz
I _{OUT1/2}	Output current range	LMQ644A2		6	A
T _J	Operating junction temperature	-40		150	°C

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		DEVICE		UNIT
		RXA (JEDEC board 51-7)	RXA (LMQ644A2 EVM ⁽³⁾)	
		24 PINS	24 PINS	
R _{θJA}	Junction-to-ambient thermal resistance	34.2	17	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	6	⁽²⁾	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	9.6	⁽²⁾	°C/W
R _{θJB}	Junction-to-board thermal resistance	7.3	⁽²⁾	°C/W
ψ _{JT}	Junction-to-top characterization parameter	0.6	1	°C/W
ψ _{JB}	Junction-to-board characterization parameter	7.2	8.9	°C/W

- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

- (2) Not applicable to an EVM.
(3) Refer to the [EVM User's Guide](#) for board layout and additional information.

6.5 Electrical Characteristics

$T_J = -40^{\circ}\text{C}$ to $+150^{\circ}\text{C}$. Typical values are at $T_J = 25^{\circ}\text{C}$ and $V_{IN} = 13.5\text{ V}$ (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY						
$I_{Q(VIN-DT3p3)}$	VIN quiescent current, dual output mode, BIAS = 3.3V	Non-switching, $V_{EN} = 2\text{ V}$, $V_{BIAS} = V_{VOSNS1} = 3.3\text{V} + 10\%$, $V_{VOSNS2} = 5\text{ V} + 10\%$		7	30	μA
$I_{Q(VIN-ST5p0)}$	VIN quiescent current, single output mode	Non-switching, $V_{EN} = 2\text{ V}$, $V_{BIAS} = V_{VOSNS1} = 5\text{V} + 10\%$		29	45	μA
$I_{Q(VIN-ST3p3)}$	VIN quiescent current, single output mode	Non-switching, $V_{EN} = 2\text{ V}$, $V_{BIAS} = V_{VOSNS1} = 3.3\text{V} + 10\%$		18	35	μA
$I_{SD(VIN)}$	VIN shutdown supply current	$V_{EN} = 0\text{ V}$		0.5	8	μA
UVLO						
$V_{INUVLO(R)}$	VIN UVLO rising threshold	V_{IN} rising		3.5	3.80	V
$V_{INUVLO(F)}$	VIN UVLO falling threshold	V_{IN} falling		2.5	3	V
$V_{INUVLO(H)}$	VIN UVLO hysteresis		0.75	1	1.25	V
ENABLE						
$V_{EN(R)}$	EN1/2 voltage rising threshold	EN1/2 rising, enable switching	1.125	1.25	1.375	V
$V_{EN(F)}$	EN1/2 voltage falling threshold	EN1/2 falling, disable switching	0.8	0.9	1.0	V
$V_{EN(H)}$	EN1/2 voltage hysteresis		0.25	0.325	0.55	V
$V_{EN(W)}$	EN1/2 voltage wake-up threshold		0.4			V
I_{EN}	EN1/2 pin sourcing current post EN rising threshold	$V_{EN1/2} = V_{IN} = 13.5\text{ V}$		0.6	400	nA
INTERNAL LDO						
V_{VCC}	Internal LDO output voltage	$V_{BIAS} \geq 3.4\text{ V}$, $I_{VCC} \leq 100\text{ mA}$	2.7	3.1	3.7	V
I_{VCC}	Internal LDO short-circuit current limit	$V_{IN} = 13.5\text{ V}$	100	360	880	mA
$V_{VCC(UVLO-R)}$	VCC UVLO rising threshold for Startup		3.3	3.5	3.75	V
$V_{VCC(UVLO-F)}$	VCC UVLO falling threshold for Shutdown		2.3	2.5	3.0	V
REFERENCE VOLTAGE						
$V_{FB1/2}$	Dual Output FB voltages in adjustable output configuration		788	800	812	mV
V_{FB1_so}	Single Output mode FB voltage in adjustable output configuration		788	800	812	mV
$I_{FB1/2(LKG)}$	FB input leakage current in dual output configuration	$V_{FB1/2} = 0.8\text{ V}$		10	250	nA
$I_{FB1_so(LKG)}$	FB input leakage current in single output configuration	$V_{FB} = 0.8\text{ V}$		10	250	nA
$FB_{Sel-5v0}$	Voltage threshold for fixed 5.0V setting		VCC-0.5			V
$FB_{Sel-3v0}$	Resistor for fixed 3.3V setting				300	Ω
$FB_{Sel-ext}$	Minimum Thevenin Equivalent resistance of external FB divider option to select adjustable output voltage.		4			k Ω
ERROR AMPLIFIER						
g_{m-S1}	EA transconductance - single output mode	$V_{FB1} = V_{COMP}$	625	1000	1300	μS
$I_{COMP(src)}$	EA source current - single output mode	$V_{COMP} = 1\text{ V}$, $V_{FB1} = 0.4\text{ V}$	100	200	400	μA
$I_{COMP(sink)}$	EA sink current - single output mode	$V_{COMP} = 1\text{ V}$, $V_{FB1} = 0.8\text{ V}$	100	200	500	μA
SWITCHING FREQUENCY						
$f_{SW1(FPWM)}$	Switching frequency, FCCM operation	$R_{RT} = 7.15\text{ k}\Omega$ to AGND	1.9	2.1	2.3	MHz
$f_{SW2(FPWM)}$	Switching frequency, FCCM operation	$R_{RT} = 39.2\text{ k}\Omega$ to AGND	360	410	450	kHz
$f_{ADJ(FCCM)}$	Adjustable switching frequency range	R_{RT} resistor from 6.81 k Ω to 158 k Ω to AGND	0.1		2.2	MHz
$f_{SS(int)}$	Spread Spectrum switching frequency range	$R_{RT} = 7.15\text{ k}\Omega$, $R_{CONFIG} = 73.2\text{ k}\Omega$		+10%		
SYNCHRONIZATION						

LMQ64480-Q1, LMQ644A0-Q1, LMQ644A2-Q1

SNVSC42A – SEPTEMBER 2023 – REVISED JULY 2024

 $T_J = -40^{\circ}\text{C}$ to $+150^{\circ}\text{C}$. Typical values are at $T_J = 25^{\circ}\text{C}$ and $V_{IN} = 13.5\text{ V}$ (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{IH(sync)}$	SYNCIN High-Level Threshold			1.35	1.6	V
$V_{IL(sync)}$	SYNCIN Low-Level Threshold		0.65	0.95		V
$V_{OH(sync)}$	Sync output high voltage min	10 mA load	1.6	2.6		V
$V_{OL(sync)}$	Sync output low voltage max	10 mA load		0.35	0.68	V
$f_{SYNC-2p1}$	Frequency sync range around 2.1MHz	$R_{RT} = 7.15\text{ k}\Omega$ to AGND	1.7	2.1	2.4	MHz
$f_{SYNC-0p4}$	Frequency sync range around 400kHz	$R_{RT} = 39.2\text{ k}\Omega$ to AGND	320	400	480	kHz
$t_{SYNC(min)}$	Pulse width of external synchronization signal above $V_{IH(sync)}$		100			ns
$t_{SYNC(max)}$	Pulse width of low external synchronization signal below $V_{IL(sync)}$		100			ns
$t_{SYNC-SW(delay)}$	Delay from SYNC rising edge to SW rising edge - single output mode - secondary				115	ns
STARTUP						
$t_{SS(R)}$	Internal fixed soft-start time - dual output mode	From $V_{VOSNS1/2} = 0\%$ (first SW pulse) to $V_{VOSNS1/2} = 90\%$	2.7	4.5	7	ms
$t_{SS_Lockout(R)}$	Time from first SW1/2 pulse to enable FPWM mode if output not in regulation - dual output mode		7	13	32	ms
$I_{SS(R)}$	Soft-start charge current - single output mode	$V_{SS} = 0\text{ V}$	15	20	25	μA
$R_{SS(F)}$	Soft-start discharge resistance - single output mode			10	27	Ω
t_{EN}	EN1 (Single output mode) or EN1/EN2 (whichever first in dual output mode) HIGH to start of switching delay			600	900	μs
POWER STAGE						
$R_{DS(on)(HS)}$	High-side MOSFET on-resistance	$V_{BOOT-SW} = 3.3\text{ V}$, $I_{OUT} = 1\text{ A}$		37	75	m Ω
$R_{DS(on)(LS)}$	Low-side MOSFET on-resistance	$V_{VCC} = 3.3\text{ V}$, $I_{OUT} = 1\text{ A}$		23.9	50	m Ω
$t_{ON(min)}$	Minimum ON pulse width	$V_{IN} = 20\text{ V}$, $I_{OUT} = 2\text{ A}$		50	65	ns
$t_{ON(max)}$	Maximum ON pulse width (dual output, single output primary)	$R_{RT} = 7.15\text{ k}\Omega$	5	8	12	μs
$t_{ON(max)}$	Maximum ON pulse width (single output secondary)	$R_{RT} = 7.15\text{ k}\Omega$		16	25	μs
$t_{OFF(min)}$	Minimum OFF pulse width	$V_{IN} = 4\text{ V}$		80	110	ns
BOOT CIRCUIT						
OVERCURRENT PROTECTION						
$I_{HS(OC1)}$	High-side peak current limit LMQ64480-Q1	Peak current limit on HS FET when Duty Cycle approaches 0%	6.2	7.5	9.2	A
$I_{LS(OC1)}$	Low-side valley current limit LMQ64480-Q1	Valley current limit on LS FET	4.6	5.2	6.3	A
$I_{LS1(NOC)}$	Low-side negative current limit LMQ64480-Q1	Sinking current limit on LS FET		4		A
$I_{LPEAK1(min-0)}$	Min peak inductor current at minimum duty cycle LMQ64480-Q1	$V_{VCC} = 3.3\text{ V}$, $t_{pulse} \leq 100\text{ ns}$		1.1		A
$I_{LPEAK1(min-100)}$	Min peak inductor current at maximum duty cycle LMQ64480-Q1	$V_{VCC} = 3.3\text{ V}$, $t_{pulse} \geq 1\text{ }\mu\text{s}$		0.3		A
$I_{HS(OC2)}$	High-side peak current limit LMQ644A0-Q1	Peak current limit on HS FET when Duty Cycle approaches 0%	7.8	9.3	10.5	A
$I_{LPEAK2(min-0)}$	Min peak inductor current at minimum duty cycle LMQ644A0-Q1	$V_{VCC} = 3.3\text{ V}$, $t_{pulse} \leq 100\text{ ns}$		1.25		A
$I_{LPEAK2(min-100)}$	Min peak inductor current at maximum duty cycle LMQ644A0-Q1	$V_{VCC} = 3.3\text{ V}$, $t_{pulse} \geq 1\text{ }\mu\text{s}$		0.3		A
$I_{HS(OC3)}$	High-side peak current limit LMQ644A2-Q1	Peak current limit on HS FET when Duty Cycle approaches 0%	9	11	13.9	A
$I_{LS(OC3)}$	Low-side valley current limit LMQ644A2-Q1	Valley current limit on LS FET	6.2	7.7	9	A
$I_{LS3(NOC)}$	Low-side negative current limit LMQ644A2-Q1	Sinking current limit on LS FET		5		A

$T_J = -40^{\circ}\text{C}$ to $+150^{\circ}\text{C}$. Typical values are at $T_J = 25^{\circ}\text{C}$ and $V_{IN} = 13.5\text{ V}$ (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{L_PEAK3(\text{min-0})}$	Min peak inductor current at minimum duty cycle LMQ644A2-Q1	$V_{VCC} = 3.3\text{ V}$, $t_{\text{pulse}} \leq 100\text{ ns}$	1	1.5	2.0	A
$I_{L_PEAK3(\text{min-100})}$	Min peak inductor current at maximum duty cycle LMQ644A2-Q1	$V_{VCC} = 3.3\text{ V}$, $t_{\text{pulse}} \geq 1\text{ }\mu\text{s}$	0.3	0.7	1.8	A
$V_{\text{Hiccup-FB}}$	Hiccup threshold on FB pin - dual output mode, adjustable output option	LS FET On-time > 165 ns	.25	0.3	0.35	V
$t_{\text{Hiccup-1}}$	Wait time before entering Hiccup - single and dual output mode		126	128	130	Curent Limit cycles
$t_{\text{Hiccup-2}}$	Hiccup time before re-start		50	88		ms
POWER GOOD						
$V_{\text{PGTH-1}}$	Power Good threshold (PG1/2)	PGOOD low, $V_{\text{VOSNS1/2}}$ rising	93%	95%	97%	
$V_{\text{PGTH-2}}$	Power Good threshold (PG1/2)	PGOOD high, $V_{\text{VOSNS1/2}}$ falling	92%	94%	96%	
$V_{\text{PGTH-3}}$	Power Good threshold (PG1/2)	PGOOD high, $V_{\text{VOSNS1/2}}$ rising	105%	107%	110%	
$V_{\text{PGTH-4}}$	Power Good threshold (PG1/2)	PGOOD low, $V_{\text{VOSNS1/2}}$ falling	104%	106%	109%	
$t_{\text{PGOOD(R)}}$	PG1/2 delay from $V_{\text{VOSNS1/2}}$ valid to PGOOD high during startup	$V_{\text{VOSNS1/2}} = 3.3\text{ V}$	1.5	2.3	3	ms
$t_{\text{PGOOD(F)}}$	PG1/2 delay from $V_{\text{VOSNS1/2}}$ invalid to PGOOD low	$V_{\text{VOSNS1/2}} = 3.3\text{ V}$	25	45	70	μs
$I_{\text{PG(LKG)}}$	PG1/2 pin Leakage current when open drain output is high	$V_{\text{PG}} = 3.3\text{ V}$			0.075	μA
$V_{\text{PG-D(LOW)}}$	PG pin output low-level voltage for both channels	$I_{\text{PG}} = 1\text{ mA}$, $V_{\text{EN}} = 0\text{ V}$.			400	mV
$R_{\text{PG-1}}$	Pull Down MOSFET Resistance	$I_{\text{PG}} = 1\text{ mA}$, $V_{\text{EN}} = 3.3\text{ V}$.		30	90	Ω
$V_{\text{IN(PG_VALID)}}$	Min VIN for valid PG output	Pull up resistance on PG - $R_{\text{PG}} = 10\text{ k}\Omega$, Voltage Pull up on PG - $V_{\text{PULLUP_PG}}=3\text{ V}$, $V_{\text{PG-D (LOW)}}=0.4\text{ V}$	0.45		1.2	V
THERMAL SHUTDOWN						
$T_{\text{J(SD)}}$	Thermal shutdown threshold	Temperature rising		168		$^{\circ}\text{C}$
$T_{\text{J(HYS)}}$	Thermal shutdown hysteresis			10		$^{\circ}\text{C}$

6.6 Typical Characteristics

Unless otherwise specified, $V_{IN} = 13.5\text{ V}$.

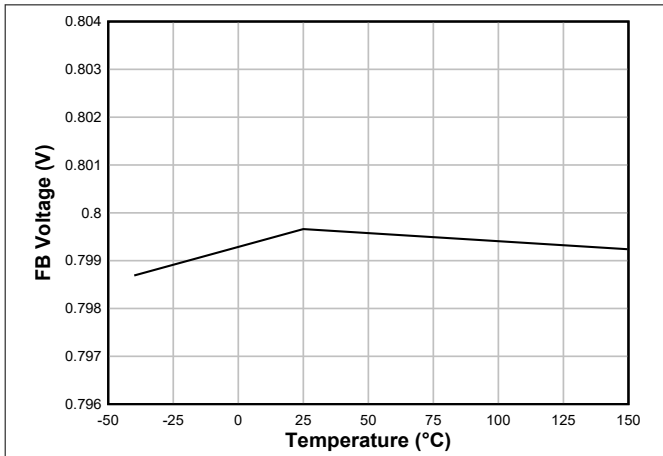


Figure 6-1. Feedback Voltage

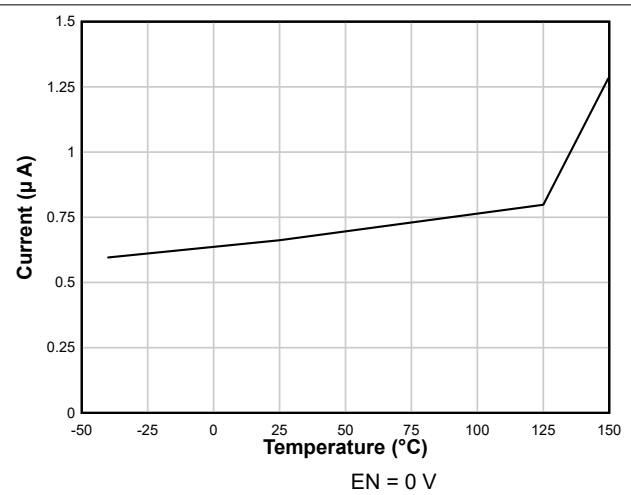


Figure 6-2. Shutdown Supply Current

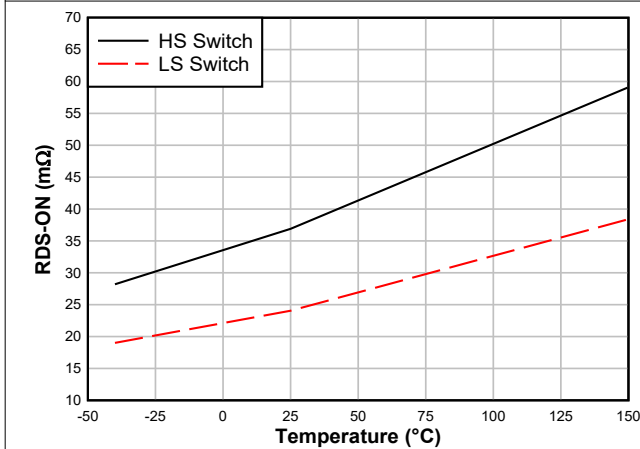


Figure 6-3. High-side and Low-side Switches
 R_{DS_ON}

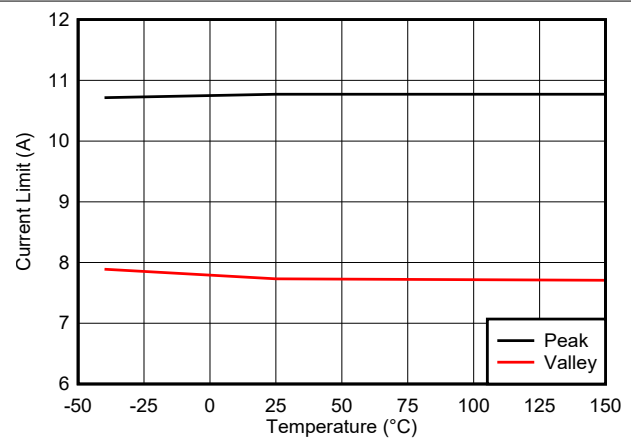


Figure 6-4. High-side and Low-side Current Limits
LMQ644A2

7 Detailed Description

7.1 Overview

The LMQ644xx is a wide-input, synchronous, buck DC/DC converter for high-current single or dual outputs. The device uses an interleaved, stackable, current-mode control architecture for easy loop compensation, fast transient response, excellent load and line regulation, and accurate current sharing stackable up to six phases for higher output currents up to 36 A.

A high-side switch minimum on-time of 55 ns allows large step-down ratios, enabling the direct conversion from 12-V, 24-V, or automotive inputs to low-voltage rails for reduced system complexity and design cost. The LMQ644xx supports input voltage dips as low as 3 V, at nearly 100% duty cycle. If the minimum on-time or minimum off-time does not support the desired conversion ratio, the frequency is reduced. This action automatically allows regulation to be maintained during load dump and with very low dropout during cranking.

Power the bias of LMQ644xx from the output of the converter for lower input quiescent current and power loss. Achieving 9- μ A no-load quiescent current in dual output configuration to extend operating run-time in battery-powered systems.

The LMQ644xx has been designed for low EMI. The device includes the following:

- Reduction of noise at the fundamental switching frequency through interleaving
 - To reduce input capacitor ripple current and EMI filter size, the device can be configured to operate in a stack of either two, four or six phases with corresponding phase shift interleave operation based on the number of phases. For example, in a 4 phase setup, a 90° out-of-phase clock output setup works well for cascaded, multi-channel, or multi-phase power stages. Phase relationship is maintained in light load operation for low output voltage ripple.
- Pin-enabled dual random spread spectrum (DRSS)
 - Dual Random Spread Spectrum (DRSS) frequency hopping is set to $\pm 10\%$ (typical), drastically reducing peak emissions through a combination of triangular and pseudorandom modulation.
- Symmetrical V_{IN} pinout for low input inductance
- Operation over a frequency range above and below AM radio band
 - Resistor-adjustable switching frequency adjustable from 100 kHz to 2.2 MHz can be synchronized to an external clock source to eliminate beat frequencies in noise-sensitive applications.
- Internal input capacitors for EMI reduction
 - Each phase has two 22-nF input bypass capacitors configured in series for improved system reliability.

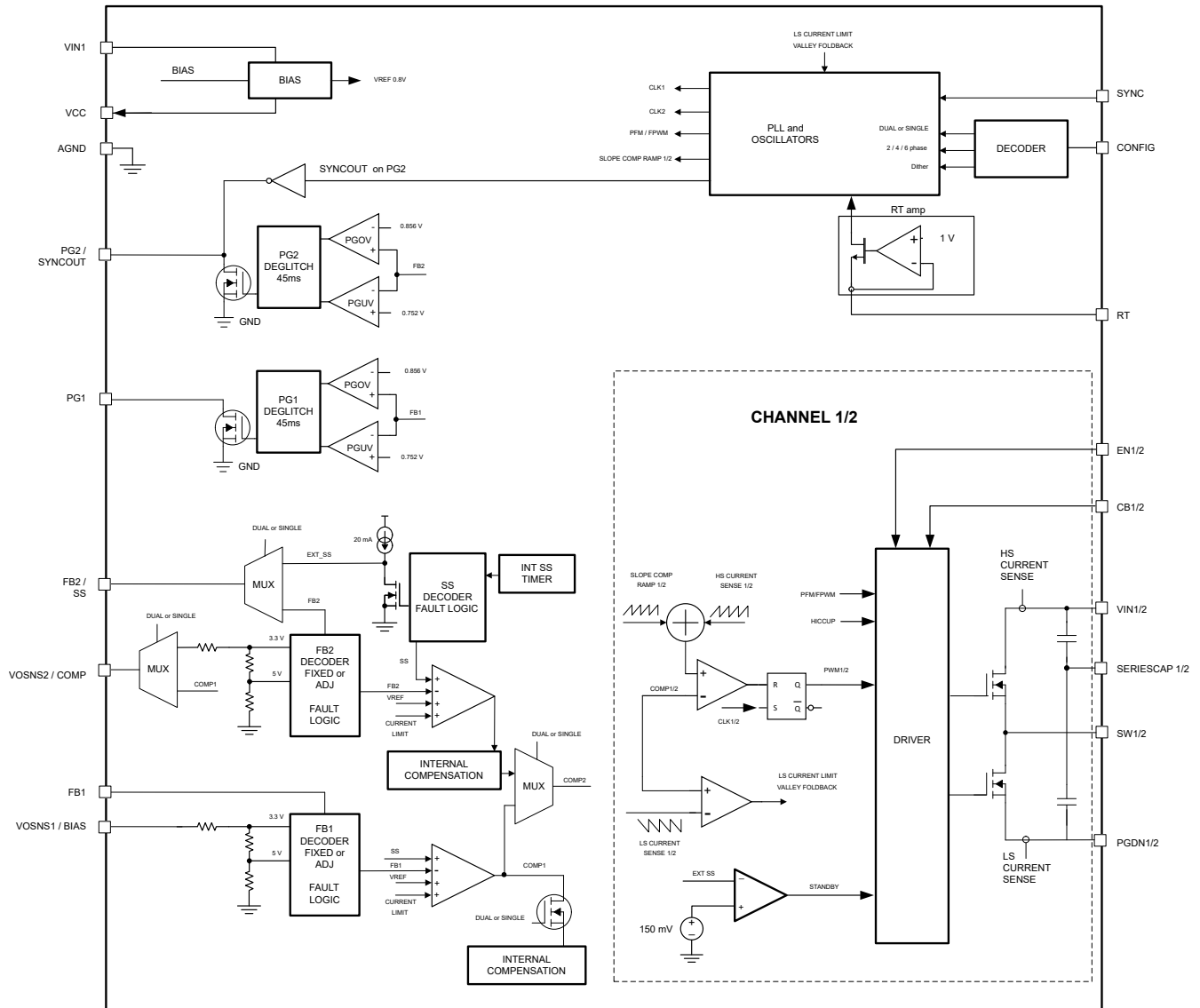
Together, these features can eliminate shielding and other expensive EMI mitigation measures.

The device also includes the following features:

- Internal fixed soft start or adjustable soft start using an external capacitor with monotonic start-up into prebiased loads
- Open-drain Power-Good flags with built-in delayed release for fault reporting and output monitoring
- Independent enable inputs
- Integrated VCC bias supply regulator
- Hiccup-mode overload protection
- Thermal shutdown protection with automatic recovery

The LMQ644xx comes in a 5-mm \times 4-mm Enhanced HotRod QFN 24-pin package with enlarged corner terminals for improved BLR and wettable flanks, allowing for optical inspection and allowing use in reliability-conscious environments

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 Input Voltage Range (V_{IN})

The LMQ644xx can start up from 3.5 V to 36 V, after start-up the input voltage range can extend down to 3 V. The device is intended for step-down conversions from 12-V automotive and 24-V industrial supply rails. The application circuit shows all the necessary components to implement an LMQ644xx based wide- V_{IN} dual-output step-down regulator using a single supply. The LMQ644xx uses an internal LDO subregulator to provide a VCC bias rail for the gate drive and control circuits.

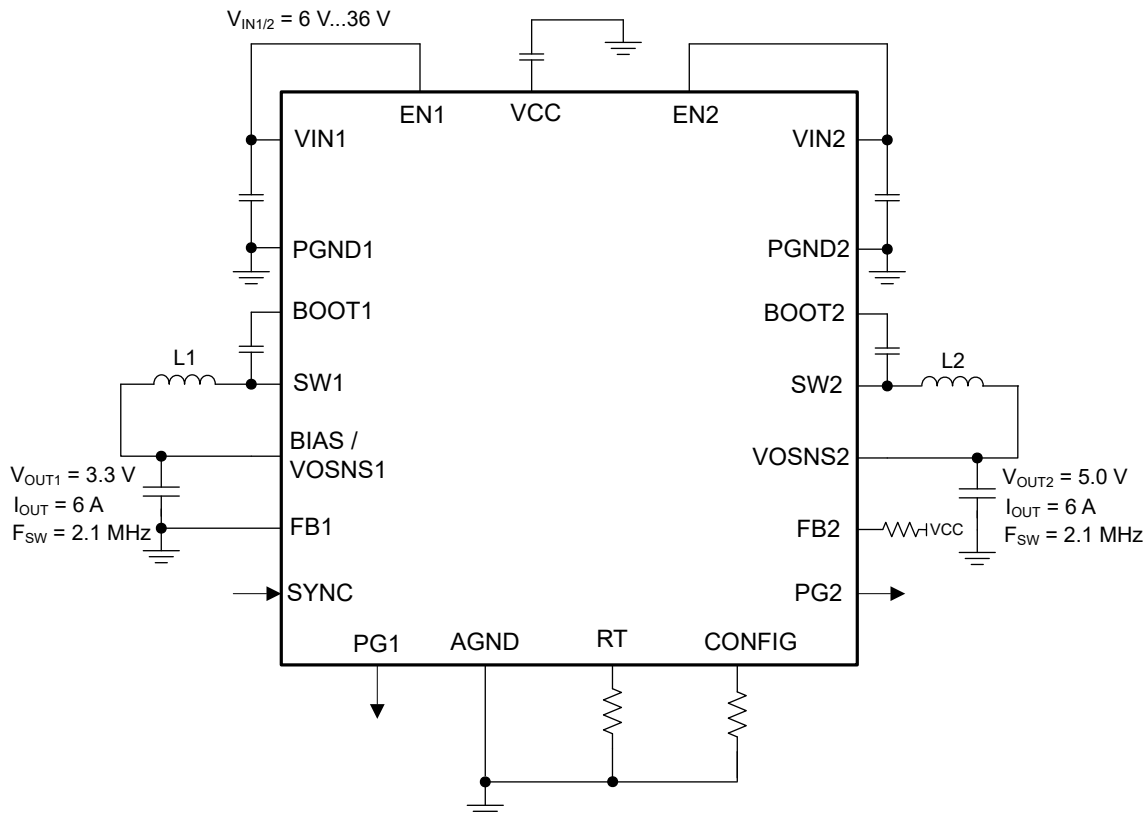


Figure 7-1. Dual-Output Regulator Schematic Diagram With Input Voltage Operating Range of 6 V to 36 V

In high input voltage applications, take extra care to make sure the VIN and SW pins do not exceed their absolute maximum voltage rating of 42 V during line or load transient events. Voltage excursions that exceed the maximum ratings can damage the IC. Proceed carefully during PCB board layout and use high-quality input bypass capacitors to minimize voltage overshoot and ringing.

7.3.2 Enable EN Pin and Use as V_{IN} UVLO

Apply a voltage less than 0.25 V to the EN1 pin to put the LMQ644xx into shutdown mode. In shutdown mode, the quiescent current drops to 0.5 μ A (typical). Above this voltage but below the lower EN threshold, VCC is active but switching on SW1 and SW2 remains inactive. After EN1 is above V_{EN} , the SW1 becomes active. EN2 controls switching on the second output SW2. In dual output configuration EN2 can be used to independently turn off the second output voltage, but does not control entering shutdown mode. In single-output multi-phase configuration EN1 on primaries and secondaries must be tied together. In single output configuration EN1 must not be used to disable the secondary devices for phase shedding. EN2 of the primary and secondaries must be tied together and can be used to shutdown the secondary phases. The very high efficiency of the device in PFM operation eliminates the need to phase shed in most designs as phase of the secondaries is controlled even under PFM operation.

The EN terminals cannot be left floating. The simplest way to enable the operation is to connect the EN pins to VIN. This action allows the self-start-up of the device when VIN drives the internal VCC above its UVLO level. However, many applications benefit from employing an enable divider string, which establishes a precision input undervoltage lockout (UVLO). The precision UVLO can be used for the following:

- Sequencing
- Preventing the device from retriggering when used with long input cables
- Reducing the occurrence of deep discharge of a battery power source

Note that EN thresholds are accurate. The rising enable threshold has 10% tolerance. Hysteresis is enough to prevent retriggering upon shutdown of the load (approximately 38%). The external logic output of another IC can also be used to drive the EN terminals, allowing system power sequencing.

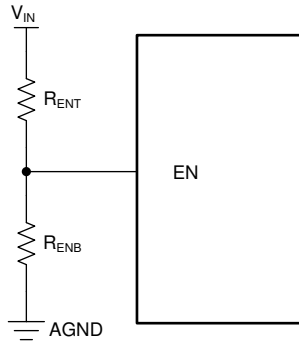


Figure 7-2. VIN UVLO Using the EN Pin

Resistor values can be calculated using [the equation below](#):

$$R_{ENB} = R_{ENT} \times \left(\frac{V_{EN(R)}}{V_{IN(on)} - V_{EN(R)}} \right) \quad (1)$$

$$V_{OFF} = V_{IN(on)} \times (1 - V_{EN(H)}) \quad (2)$$

where

- $V_{ON} = V_{IN}$ turn-on voltage
- $V_{OFF} = V_{IN}$ turn-off voltage

7.3.3 Output Voltage Selection and Soft Start

A voltage divider between the output voltage and the FB1 pin is used to create an adjustable output voltage from 0.8 to 20 V for the first buck converter. The thevenin impedance of the divider must be larger than 4 kohms, to correctly enter adjustable output voltage configuration. For lower output voltages a minimum of 10 kohms is recommended for R_{FBT} to meet this requirement. For a fixed 5-V output connect FB1 to VCC through a 10 kohm resistor. For a fixed 3.3 V connect FB1 to AGND. For fixed output voltage configurations the first channel output voltage is sensed on pin 13 BIAS/VOSNS1.

For dual-output voltage configuration, $R_{CONFIG} = 0$ (spread spectrum disabled) or 121 k Ω (spread spectrum enabled).

FB2 is configured in the same manner as FB1. A voltage divider between output voltage and the FB2 pin is used to create an adjustable output voltage from 0.8 to 20 V for the second buck converter. The thevenin impedance of the divider must be larger than 4 kohms, to correctly enter adjustable output voltage configuration. For lower output voltages a value of 10 kohms is recommended for R_{FBT} to meet this requirement. For a fixed 5-V output, connect FB2 to VCC through a 10 kohm resistor. For a fixed 3.3 V connect FB2 to AGND. For fixed output voltage configurations, the second channel output voltage is sensed on pin 19. that is, VOSNS2.

Current sharing between multiple buck channels can increase the current. For one device, single-output multi-phase operation can double the single buck current and provide up to 12 A. Using three devices allows six

times the current up to 36 A. When the device is configured to single-output multi-phase operation ($9.53\text{ k}\Omega < R_{\text{CONFIG}} < 93.1\text{ k}\Omega$), FB2 is re-configured to provide an adjustable soft start (SS). An external capacitor can be placed from this pin to ground to extend the internal soft-start time. The time can be calculated using the soft-start current of $20\text{ }\mu\text{A}$ (typical) charging the external capacitor to the reference voltage of 0.8 V (typical). As an example, a 220-nF capacitor provides a soft start of 8 ms after the initialization of the device. The pin must also be tied to FB2/SS of all other LMQ stacked devices for fault communication between primary and secondary devices. Faults, such as thermal shutdown, are communicated by pulling the pin low and stops switching for all devices.

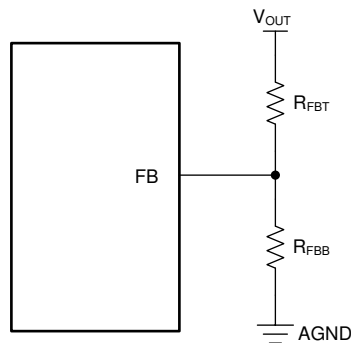


Figure 7-3. Setting Output Voltage of Adjustable Versions

The LMQ644xx uses a 0.8-V reference. The following equation can be used to determine R_{FBB} for a desired output voltage and a given R_{FBT} . Usually, R_{FBT} is limited to a maximum value of $100\text{ k}\Omega$ to prevent drifting due to PCB leakage under harsh conditions. To improve light load efficiency, a larger resistance of up to $1\text{ M}\Omega$ can be used in cleaner environments, or the fixed output voltage options can be used under harsher conditions.

$$R_{\text{FBB}}[\text{k}\Omega] = \frac{0.8 \times R_{\text{FBT}}[\text{k}\Omega]}{(V_{\text{OUT}} - 0.8)} \quad (3)$$

In addition, a feedforward capacitor C_{FF} can be used to optimize the transient response. Typical values are provided in the applications section and were selected based upon the top feedback resistor to place a zero slightly above the cross-over frequency.

7.3.4 SYNC Allows Clock Synchronization and Mode Selection

The SYNC pin can be used to select forced pulse width modulation (FPWM) or pulse frequency modulation (PFM). In FPWM the switching frequency remains constant at lighter output currents. In PFM the low-side FET is turned off when the inductor current goes negative and the frequency is reduced to improve efficiency under light-load conditions. Connect SYNC to AGND to enable PFM. Connect SYNC to VCC to operate the LMQ644xx in FPWM mode with continuous conduction at light loads.

The SYNC pin can also be used to synchronize the internal oscillator to an external clock. When synchronized to an external clock the LMQ644xx operates in FPWM. The internal oscillator can be synchronized to a positive edge into the SYNC pin. The coupled edge voltage at the SYNC pin must exceed the SYNC amplitude threshold of V_{SYNCDH} to trip the internal synchronization pulse detector. The minimum SYNC rising pulse and falling pulse durations must be longer than $t_{\text{PULSE_H}}$ and $t_{\text{PULSE_L}}$ respectively. The LMQ644xx switching action can be synchronized to an external clock from 200 kHz to 2.2 MHz . When synchronizing to an external clock, the R_{T} pin must be used to set the internal frequency to a value close to that of the external clock. This action prevents large frequency changes in the event of loss of synchronization. It is also used to set the slope compensation for secondary devices.

In single-output two-phase operation, the PG2/SYNC-OUT terminal of the primary can be left floating as clock information is shared internally.

In single-output four-phase operation, the PG2/SYNC-OUT terminal of the primary must be connected to the SYNC pin of the secondary to clock all four phases 90 degrees out of phase.

In single-output six-phase operation, the PG2/SYNC-OUT terminal of the primary must be connected to the SYNC pin of the secondary device. The PG2/SYNC-OUT terminal of the secondary must be connected to the SYNC pin of the tertiary device. In this way, the devices operate all six phases 60 degrees out of phase.

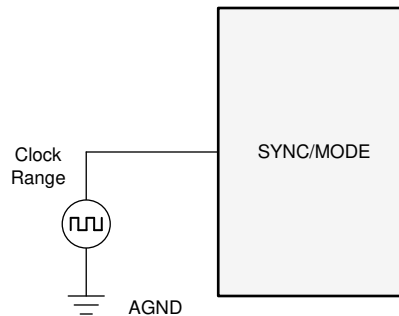
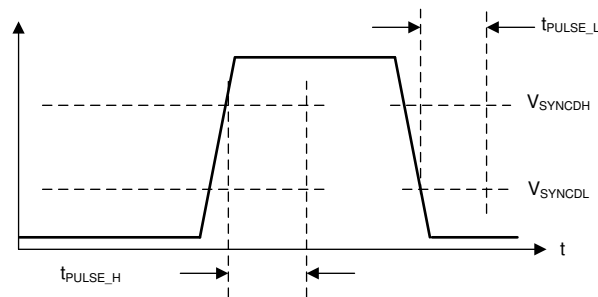


Figure 7-4. Typical Implementation Allowing Synchronization Using the SYNC/MODE Pin



This image shows the conditions needed for detection of a synchronization signal.

Figure 7-5. Typical SYNC/MODE Waveform

7.3.5 Clock Locking

After a valid synchronization signal is detected on the primary or dual output converter, a clock locking procedure is initiated. After approximately 32 pulses, the clock frequency abruptly changes to the frequency of the synchronization signal. While the frequency adjusts suddenly, phase is maintained so the clock cycle lying between operation at the default and synchronization frequencies is of intermediate length. There are no very long or very short pulses. After frequency is adjusted, phase is adjusted over a few tens of cycles so that rising synchronization edges correspond to rising the SW node pulses.

7.3.6 Adjustable Switching Frequency

The frequency is set using a resistor on the RT pin. A resistor to AGND is used to set the adjustable operating frequency. See below for resistor values. Note that if a resistor value falls outside of the recommended range, it can cause the device to stop switching. Do not apply a pulsed signal to this pin to force synchronization. If synchronization is needed, see the SYNC pin.

$$R_T[\text{k}\Omega] = \left(\frac{16.4}{f_{SW}[\text{MHz}]} - 0.633 \right) \quad (4)$$

For example, for $f_{SW} = 400 \text{ kHz}$, $R_T = (16.4 / 0.4) - 0.633 = 40.37$, so a 40.2-k Ω resistor is selected as the closest choice.

Table 7-1. Typical R_T values

R_T (k Ω)	Frequency (kHz)
6.81	2206
7.15	2106
15.4	1005
31.6	497.4
39.2	402
158	101

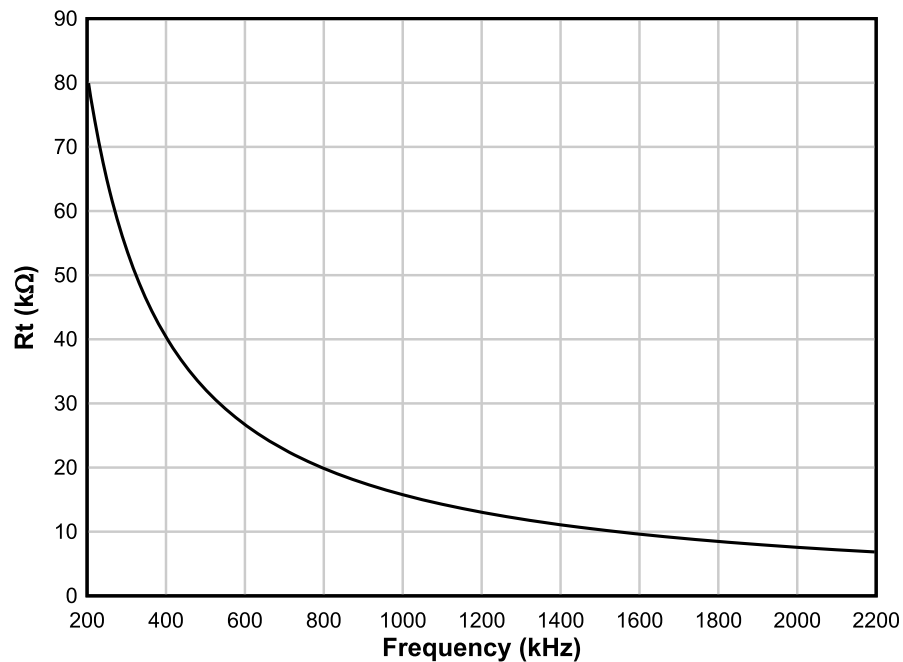


Figure 7-6. Setting Clock Frequency

7.3.7 Power-Good Output Voltage Monitoring

While the PG1/PG2 of the LMQ644xx resembles a standard power-good function, the functionality is designed to replace a discrete reset IC, reducing BOM cost. There are three major differences between the PG function and the normal power-good function seen in most regulators:

- A delay has been added for release of reset. See [Table 7-2](#).
- PG output signals a fault (pulls its output to ground) while the part is disabled.
- PG continues to operate with input voltage as low as 1.2 V. Below this input voltage, PG output can be high impedance.

For dual output configuration ($R_{CONFIG} = 0$ or 121 k Ω), The PG1 is an open-drain and must be tied through a resistor to an external voltage, and pulls low if the monitors on FB1 or VOSNS1 trip. The PG2 flag is configured in the same manner as PG1 and monitors the second output at either FB2 or VOSNS2.

For single-output multi-phase operation ($9.53 \text{ k}\Omega < R_{CONFIG} < 93.1 \text{ k}\Omega$), PG2 is re-configured as SYNC-OUT to provide a phase shifted clock to the secondary devices. In this configuration, the PG2/SYNC-OUT terminal of the primary device can be left floating for dual phase operation or tied to the SYNC pin of the secondary device for more than four-phases. For six-phase operation the PG2/SYNC-OUT pin of the secondary device is connected to the SYNC pin of the tertiary device.

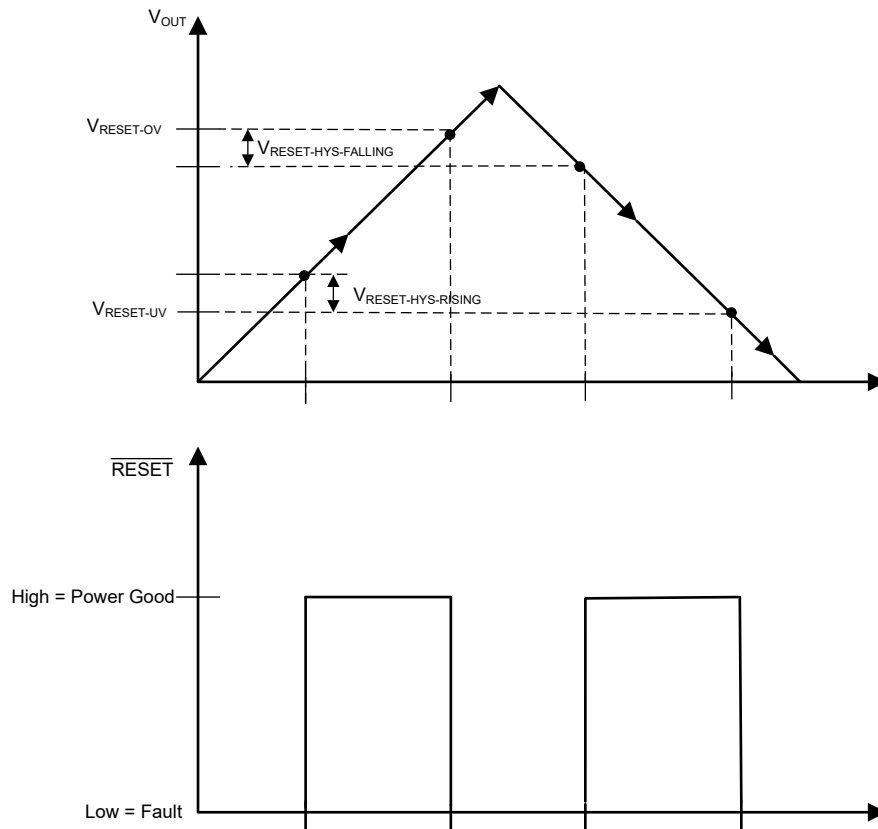


Figure 7-7. PG Static Voltage Thresholds

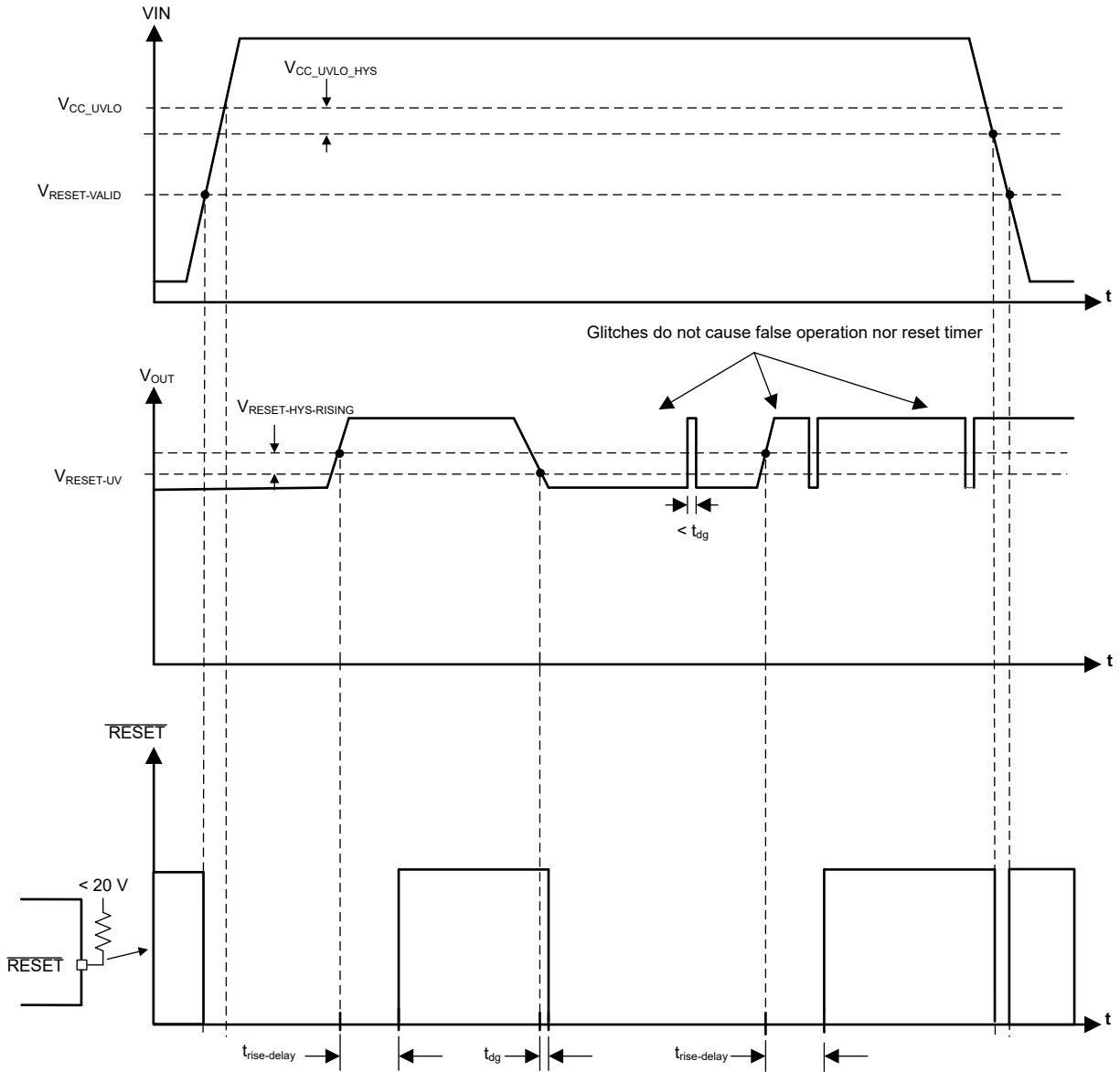


Figure 7-8. PG Timing Diagram (Excludes OV Events)

Table 7-2. Conditions that Cause PG to Signal a Fault (Pull Low)

FAULT CONDITION INITIATED	FAULT CONDITION ENDS (AFTER WHICH t_{RESET_ACT} MUST PASS BEFORE RESET OUTPUT IS RELEASED)
FB below V_{RESET_UV} for longer than t_{RESET_FILTER}	FB above $V_{RESET_UV} + V_{RESET_HYST}$ for longer than t_{RESET_FILTER}
FB above V_{RESET_OV} for longer than t_{RESET_FILTER}	FB below $V_{RESET_OV} - V_{RESET_HYST}$ for longer than t_{RESET_FILTER}
Junction temperature exceeds T_{SD_R}	Junction temperature falls below T_{SD_F} ⁽¹⁾
EN low	t_{EN} passes after EN becomes high ⁽¹⁾
VIN falls low enough so that VCC falls below $V_{CC_UVLO} - V_{CC_UVLO_HYST}$. This value is called $V_{IN_OPERATE}$.	Voltage on VIN is high enough so that VCC pin exceed V_{CC_UVLO} ⁽¹⁾

(1) As an additional operational check, PG remains low during soft start. It is defined as until the lesser of either full output voltage reached or t_{SS2} has passed since initiation. This is true even if all other conditions in this table are met and t_{RESET_ACT} has passed. Lockout during soft start does not require t_{RESET_ACT} to pass before PG is released.

The threshold voltage for the PG function is specified to take advantage of the availability of the internal feedback threshold to the PG circuit. This allows a maximum threshold of 96.5% of selected output voltage to be specified at the same time as 96% of actual operating point. The net result is a more accurate reset function while expanding the system allowance for transient response. See the output voltage error stack-up comparison in Figure 7-9.

In addition to signaling a fault upon overvoltage detection (FB above V_{RESET_OV}), the switch node is shut down and a small, approximately 1-mA pulldown is applied to the SW node.

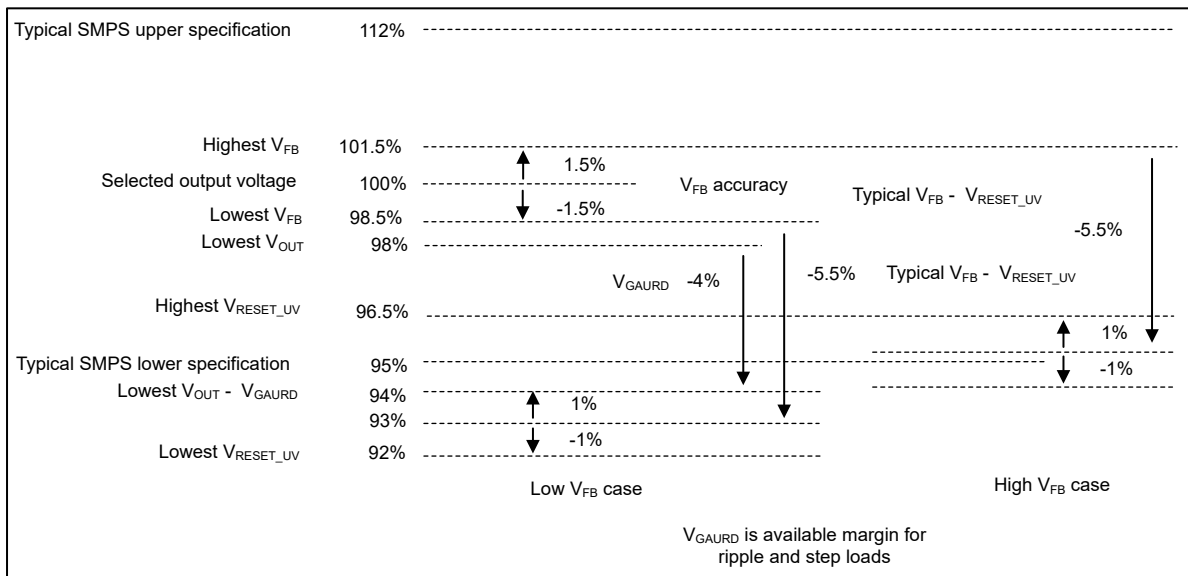


Figure 7-9. Reset Threshold Voltage Stack-Up

7.3.8 Internal LDO, VCC UVLO, and BIAS Input

The LMQ644xx uses VCC as its internal power supply. VCC is, in turn, powered from VIN or VOSNS1/BIAS. After the device is active power comes from VIN, if BIAS is less than approximately 3.1 V. Power comes from BIAS, if BIAS is more than 3.1 V. VCC is typically 3 V to 3.3 V under most conditions, but can be lower if VIN is very low. To prevent unsafe operation, VCC has a UVLO that prevents switching if the internal voltage is too low. See V_{CC_UVLO} and $V_{CC_UVLO_HYST}$. During start-up, VCC momentarily exceeds its normal operating voltage until V_{CC_UVLO} is exceeded, then drops to its normal operating voltage. These UVLO values, when combined with the dropout of the LDO when powering the LMQ644xx, are used to derive minimum input operating voltage.

7.3.9 Bootstrap Voltage and $V_{CBOOT-UVLO}$ (CB1 and CB2 Pin)

The driver of the power switch (HS switch) requires bias higher than VIN when the HS switch is ON. The capacitors connected between CB1 and SW1 and CB2 and SW2 work as charge pumps to boost voltage on the

CB terminals to (SW + VCC). The boot diode is integrated on the LMQ644xx die to minimize the physical design size. TI recommends a 100-nF capacitor rated for 10 V with X7R or better dielectric for the CBOOT capacitors. The boot (CB1 and CB2) rails have UVLO to protect the chip from operation with too little bias. This UVLO has a threshold of V_{BOOT_UVLO} and is typically 2.1 V. If the CBOOT capacitor voltage drops below V_{BOOT_UVLO} , then the device initiates a charging sequence using the low-side FET before attempting to turn on the high-side device.

7.3.10 CONFIG Device Configuration Pin

Several features are included to simplify compliance with CISPR 25 and automotive EMI requirements. To reduce input capacitor ripple current and EMI filter size, the device can be configured to operate in a stack of either two, four, or six phases with corresponding phase shift interleave operation based on the number of phases. For example, in a 4-phase setup, a 90° out-of-phase clock output setup works well for cascaded, multi-channel, or multi-phase power stages. Resistor-adjustable switching frequency as high as 2.2 MHz can be synchronized to an external clock source to eliminate beat frequencies in noise-sensitive applications. Optional spread spectrum modulation further improves the EMI signature.

The CONFIG terminal is used to set up the device for either dual output or single output multi-phase operation. The spread spectrum can also be turned on and off with different resistor values.

Table 7-3. R_{CONFIG} Resistor Selection

R _{CONFIG} (kΩ)	Mode	Spread Spectrum
0	Dual output	No
9.53	2 phase primary	No
19.1	4 phase primary	No
29.4	6 phase primary	No
41.2	Secondary	N/A
56.2	2 phase primary	Yes
73.2	4 phase primary	Yes
93.1	6 phase primary	Yes
121	Dual output	Yes

When configured in single output multi-phase operation, the VOSNS2 pin becomes the output of the error amplifier (COMP) and a resistor and capacitor are needed at this pin to compensate the control loop. $R_C = 11$ kOhms, $C_C = 2.2$ nF can be used in initial evaluation for many designs. Increasing the resistance results in higher loop gain and tends to require proportionately larger output capacitors. Decreasing the capacitance increases the loop response of the device, resulting in faster transients but can lower phase margin at the cross-over frequency and can require adjustments to the output capacitance. The table below has several settings for different output configurations.

Table 7-4. Typical Bill of Materials

MODE	V _{OUT1}	V _{OUT2}	FREQUENCY	C _{OUT} EACH PHASE	C _{IN} + C _{HF} EACH PHASE	L1, L2	R _C	C _C
DUAL	3.3 V	5 V	400 kHz	47 + 22 μF	2 × 10 μF + 1 × 100 nF	3.3 μH	INTERNAL	INTERNAL
DUAL	3.3 V	5 V	2200 kHz	47 + 22 μF	1 × 10 μF + 1 × 100 nF	0.68 μH	INTERNAL	INTERNAL
SINGLE	3.3 V	3.3 V	400 kHz	47 + 22 μF	2 × 10 μF + 1 × 100 nF	3.3 μH	11 kΩ	2.2 nF
SINGLE	5 V	5 V	2200 kHz	47 + 22 μF	1 × 10 μF + 1 × 100 nF	1 μH	11 kΩ	2.2 nF

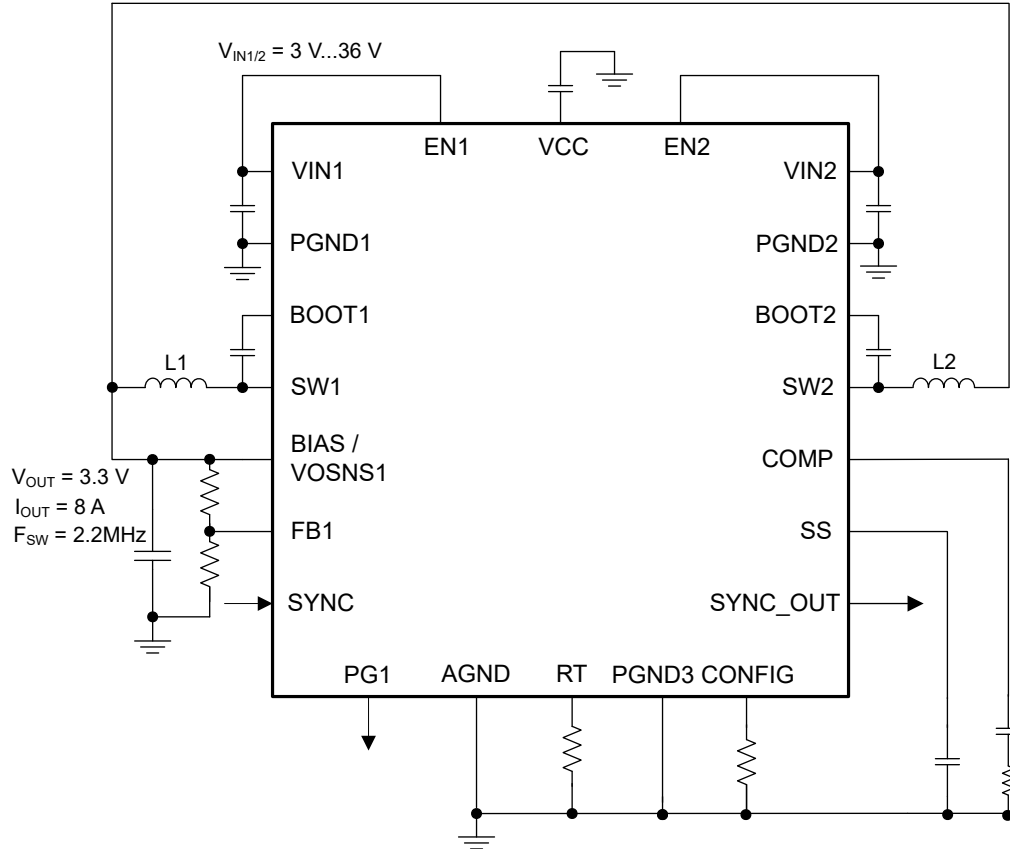


Figure 7-10. High-Efficiency, Single Output 2-Phase Step-Down Converter

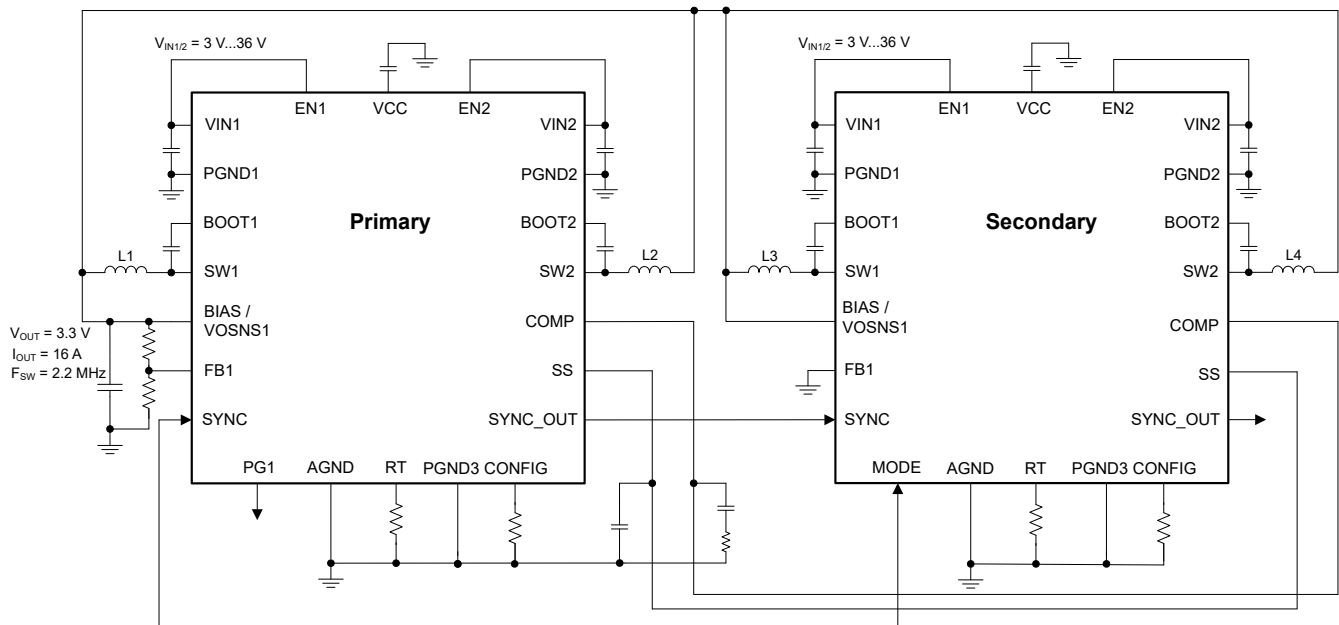
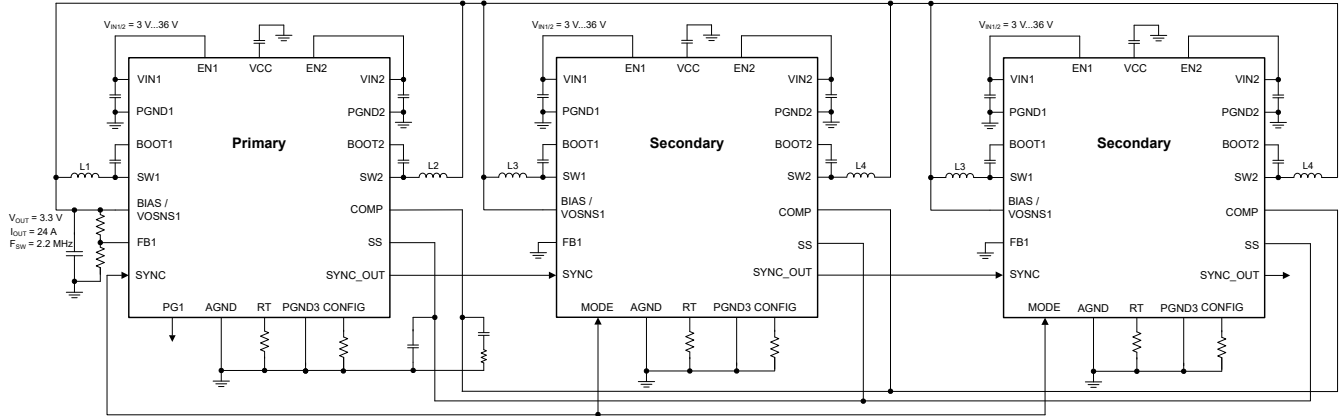


Figure 7-11. High-Efficiency, Single Output 4-Phase Step-Down Converter



High-Efficiency, Single Output 6-Phase Step-Down Converter

7.3.11 Spread Spectrum

Spread spectrum is configurable using the CONFIG pin. Spread spectrum eliminates peak emissions at specific frequencies by spreading these peaks across a wider range of frequencies than a part with fixed-frequency operation. The LMQ644xx implements a modulation pattern designed to reduce low frequency-conducted emissions from the first few harmonics of the switching frequency. The pattern can also help reduce the higher harmonics that are more difficult to filter, which can fall in the FM band. These harmonics often couple to the environment through electric fields around the switch node and inductor. The LMQ644xx uses a $\pm 10\%$ (typical) spread of frequencies which can spread energy smoothly across the FM and TV bands. The device implements Dual Random Spread Spectrum (DRSS). DRSS is a combination of a triangular frequency spreading pattern and pseudorandom frequency hopping. The combination allows the spread spectrum to be very effective at spreading the energy at the following:

- Fundamental switching harmonic with slow triangular pattern
- High frequency harmonics with additional pseudorandom jumps at the switching frequency

The advantage of DRSS is the equivalent harmonic attenuation in the upper frequencies with a smaller fundamental frequency deviation. This reduces the amount of input current and output voltage ripple that is introduced at the modulating frequency.

The spread spectrum is only available while the clocks of the The LMQ644xx are free running at the natural frequency. Any of the following conditions overrides the clock and can interfere with spread spectrum:

- The clock is slowed due to operation at low input voltage. This is operation in dropout.
- The clock is slowed under light load in auto mode. Note that if the device is operating in FPWM mode, spread spectrum is active, even if there is no load.
- The clock is slowed due to high input-to-output voltage ratio. This mode of operation is expected if on-time reaches minimum on-time. See the [Electrical Characteristics](#).
- The clock is synchronized with an external clock.

7.3.12 Soft Start and Recovery From Dropout

When designing with the The LMQ644xx, slowed rise in output voltage due to recovery from dropout and soft start must be considered separate phenomena. Soft start is triggered by any of the following conditions:

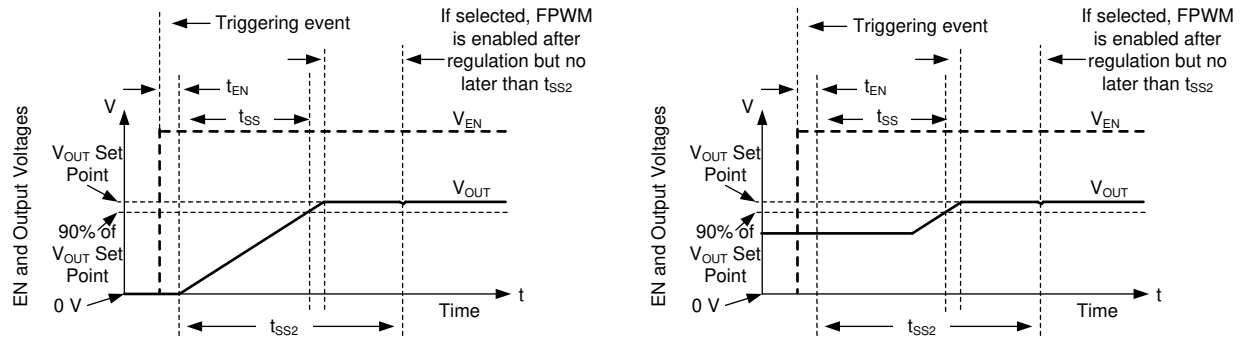
- EN is used to turn on the device.
- Recovery from a hiccup waiting period; see [Section 7.3.14](#).
- Recovery from shutdown due to overtemperature protection
- Power is applied to the VIN of the IC or the VCC UVLO is released.

After soft start is triggered, the IC takes the following actions:

- The reference used by the IC to regulate output voltage is slowly ramped from zero. The net result is that output voltage, if previously 0 V, takes t_{SS} to reach 90% of its desired value.

- Operating mode is set to auto, activating diode emulation. This allows start-up without pulling output low if there is a voltage already present on the output.
- Hiccup is disabled for the duration of soft start; see [Section 7.3.14](#).

All of these actions together provide start-up with limited inrush currents. They also allow the use of output capacitors and loading conditions that cause current to border on current limit during start-up without triggering hiccup. In addition, if output voltage is already present, output is not pulled down. See [Figure 7-12](#).



The left curves show soft start from 0 V. The right curves show soft starting behavior from a pre-biased or non-zero voltage. In either case, the output voltage reaches within 10% of the desired setpoint t_{SS} time after soft start is initiated. During soft start, FPWM and hiccup are disabled. Both hiccup and FPWM are enabled after output reaches regulation or t_{SS2} , whichever happens first.

Figure 7-12. Soft-Start Operation

Any time output voltage is more than a few percent low for any reason, output voltage ramps up slowly. This condition, called recovery from dropout, differs from soft start in three important ways:

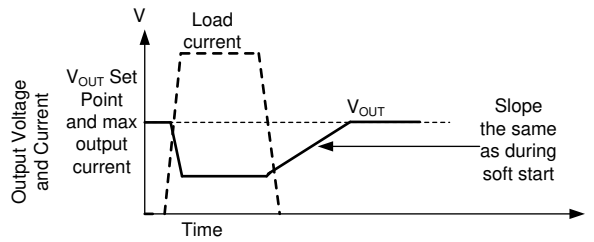
- Hiccup is allowed only if output voltage is less than 0.4 times its set point. Note that during dropout regulation itself, hiccup is inhibited. See [Section 7.3.14](#).
- FPWM mode is allowed during recovery from dropout. If output voltage were to suddenly be pulled up by an external supply, the The LMQ644xx can pull down on the output. Note that all the protections that are present during normal operation are in place, protecting the device if output is shorted to a high voltage or ground.
- The reference voltage is set to approximately 1% above that needed to achieve the current output voltage. It is not started from zero.

Despite the name, recovery from dropout is active whenever output voltage is more than a few percent lower than the setpoint for long enough that:

- Duty factor is controlled by maximum on-time or
- When the part is operating in current limit.

This primarily occurs under the following conditions:

- Dropout: When there is insufficient input voltage for the desired output voltage to be generated. See [Section 7.4.3.5](#).
- Overcurrent that is not severe enough to trigger hiccup or if the duration is too short to trigger hiccup. See [Section 7.3.14](#).



Whether output voltage falls due to high load or low input voltage, after the condition that causes output to fall below its setpoint is removed, output climbs at the same speed as during start-up. Even though hiccup does not trigger due to dropout, it can, in principal, be triggered during recovery if output voltage is below 0.4 times output the setpoint for more than 128 clock cycles during recovery.

Figure 7-13. Recovery From Dropout

7.3.13 Overcurrent and Short-Circuit Protection

The LMQ644xx is protected from overcurrent conditions by cycle-by-cycle current limiting on both the high-side and the low-side MOSFETs.

High-side MOSFET overcurrent protection is implemented by the nature of the peak current mode control. The HS switch current is sensed when the HS is turned on after a short blanking time. The HS switch current is compared to the output of the voltage regulation loop minus slope compensation, every switching cycle. Because the voltage loop has a maximum value and slope compensation increases with duty cycle, the HS current limit decreases with increased duty cycle such that the HS current limit is reduced by 35% for high output to input voltage duty ratios. See Figure 7-14.

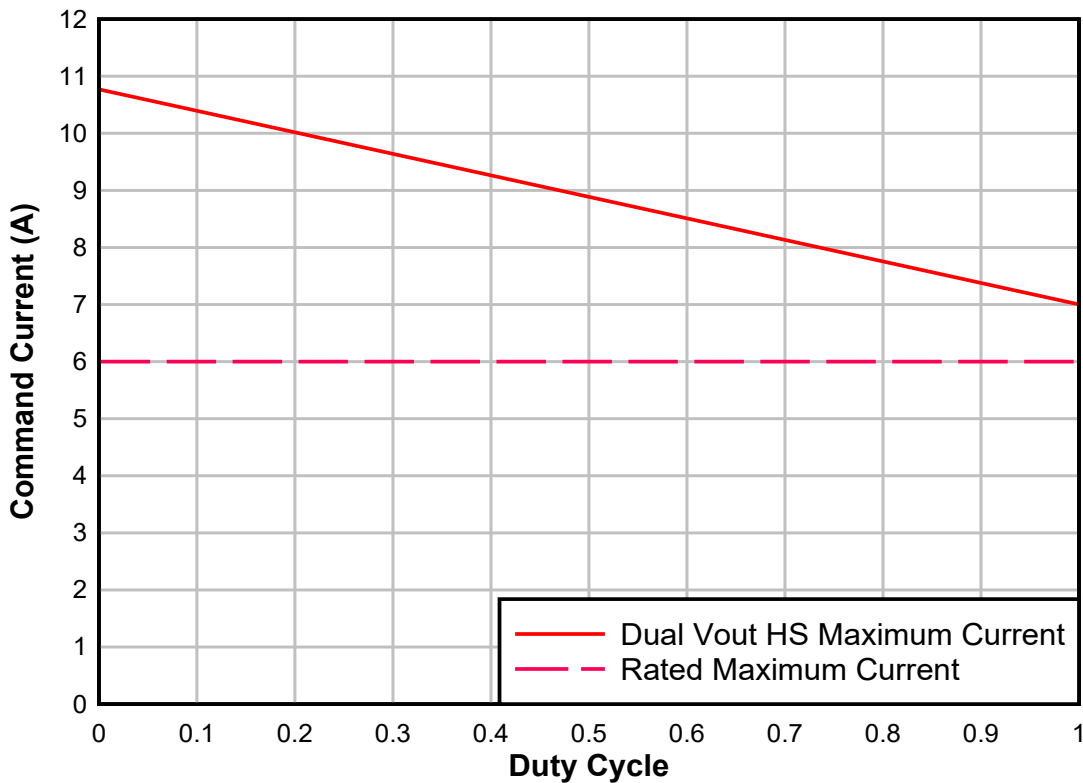


Figure 7-14. Maximum Current Allowed Through the HS FET - Function of Duty Cycle for LMQ644xx

When the LS switch is turned on, the current going through the LS switch is also sensed and monitored. Like the high-side device, the low-side device turn-off is commanded by the voltage control loop. For a low-side device,

turn-off is prevented if current exceeds this value, even if the oscillator normally starts a new switching cycle. See [Section 7.4.3.4](#). Also like the high-side device, there is a limit on how high the turn-off current is allowed to be. This is called the low-side current limit; see the [Electrical Characteristics](#) for values. If the LS current limit is exceeded, the LS MOSFET stays on and the HS switch is not turned on. The LS switch is turned off after the LS current falls below its limit. The HS switch is turned on again as long as at least one clock period has passed since the last time the HS device has turned on.

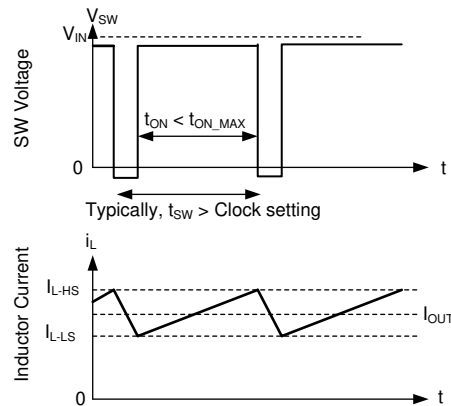


Figure 7-15. Current Limit Waveforms

The net effect of the operation of high-side and low-side current limit is that the IC operates in hysteretic control. Because the current waveform assumes values between I_{L-HS} and I_{L-LS} , output current is close to the average of these two values unless duty cycle is very high. After operating in current limit, hysteretic control is used and current does not increase as output voltage approaches zero.

If duty cycle is very high, current ripple must be very low to prevent instability; see [Section 8.2.2.3](#). Because current ripple is low, the part is able to deliver full current unless dropout across device is less than 0.5V. The current delivered is very close to I_{L-LS} .

If overloaded, after the overload is removed, the device recovers as though in soft start; see [Section 7.3.12](#). Note that hiccup can be triggered if output voltage drops below approximately 0.4 times the intended output voltage.

7.3.14 Hiccup

The LMQ644xx employs hiccup overcurrent protection to prevent overheating in the presence of a short circuit condition.

In dual output mode the part enters Hiccup when all of the following conditions are met for 128 consecutive switching cycles:

- A time greater than t_{SS2} has passed since soft start has started; see [Section 7.3.12](#).
- Output voltage is below approximately 0.4 times output setpoint.
- The part is not operating in dropout defined as having minimum off-time controlled by duty factor.

In single output mode the part enters Hiccup when all of the following conditions are met for 128 consecutive switching cycles:

- COMP pin is at max of 1.1V
- The part is not operating in dropout defined as having minimum off-time controlled by duty factor.

In hiccup mode, the device shuts itself down and attempts to soft start after t_{WV} . Hiccup mode helps reduce the device power dissipation under severe overcurrent conditions and short circuits.

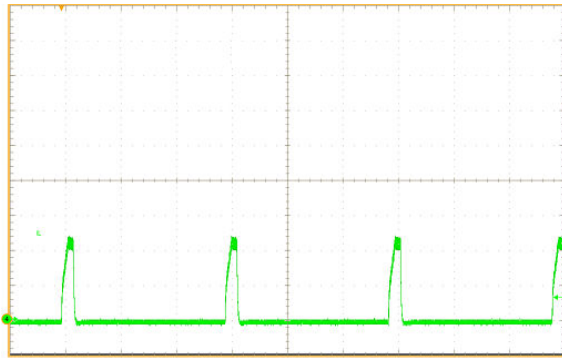


Figure 7-16. Inductor Current Bursts During Hiccup

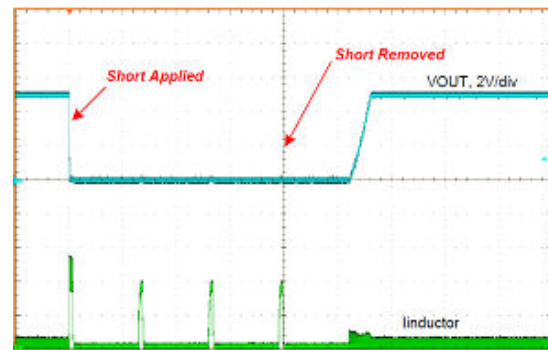


Figure 7-17. Short-Circuit Transient and Recovery

7.3.15 Thermal Shutdown

Thermal shutdown is a safety mechanism for the device that limits total power dissipation by turning off the internal switches when the a temperature sensor on the IC exceeds 168°C (typical). After thermal shutdown occurs, hysteresis prevents the device from switching until the temperature sensor temperature drops to approximately 159°C (typical). When the sensor temperature falls below 159°C (typical), the LMQ644xx attempts to soft start. While the sensor is close to the power FETs, it must not be used to determine maximum junction temperature of the device under load as there can be temperature gradients across the device. Instead thermal couples and other methods must be used to characterize thermal design in application.

While the LMQ644xx is shut down due to high junction temperature, power continues to be provided to VCC. To prevent overheating from a short circuit applied to VCC, the LDO providing power to VCC has reduced current limit while the part is disabled due to high junction temperature. The LDO only provides a few milliamperes during thermal shutdown.

7.4 Device Functional Modes

7.4.1 Shutdown Mode

The EN pin provides electrical on and off control of the device. When the EN pin voltage is below 0.4 V, both the regulator and the internal LDO have no output voltage and the part is in shutdown mode. In shutdown mode, the quiescent current drops to typically 0.66 μ A.

7.4.2 Standby Mode

The internal LDO has a lower EN threshold than the output of the regulator. The internal LDO regulates the VCC voltage at 3.3 V, typically when:

- The EN pin voltage is above 1.1 V (maximum) and
- The EN pin voltage is below the precision enable threshold for the output voltage.

The precision enable circuitry is ON after VCC is above its UVLO. The internal power MOSFETs of the SW node remain off unless the voltage on the EN terminal goes above its precision enable threshold. The LMQ644xx also employs UVLO protection. If the VCC voltage is below its UVLO level, the output of the regulator is turned off.

7.4.3 Active Mode

The device is in active mode when the following occurs:

- The EN pin is above V_{EN} .
- V_{IN} is above V_{EN} .
- V_{IN} is high enough to satisfy the V_{IN} minimum operating input voltage.
- No other fault conditions are present.

See [Section 7.3](#) for protection features. The simplest way to enable the operation is to connect EN to VIN, allowing self-start-up when the applied input voltage exceeds the minimum $V_{IN_OPERATE}$.

In active mode, depending on the load current, input voltage, and output voltage, the LMQ644xx is in one of six sub-modes:

- Continuous conduction mode (CCM) with fixed switching frequency and peak current mode operation
- Discontinuous conduction mode (DCM) while in auto mode when the load current is lower than half of the inductor current ripple. If current continues to reduce, the device enters Pulse Frequency Modulation (PFM) which reduces the switch frequency to maintain regulation while reducing switching losses to achieve higher efficiency at light load.
- Minimum on-time operation while the on-time of the device needed for full-frequency operation at the requested low-duty cycle is not supported by T_{ON_MIN}
- Forced pulse width modulation (FPWM) similar to CCM with fixed-switching frequency, but extends the fixed frequency range of operation from full to no load
- Dropout mode when switching frequency is reduced to minimize dropout
- Recovery from dropout similar to other modes of operation except the output voltage setpoint is gradually moved up until the programmed setpoint is reached.

7.4.3.1 Peak Current Mode Operation

The following operating description of the LMQ644xx refers to [Functional Block Diagram](#) and the waveforms in [Figure 7-18](#). Both supply a regulated output voltage by turning on the internal high-side (HS) and low-side (LS) NMOS switches with varying duty cycle (D). During the HS switch on-time, the SW terminal voltage, V_{SW} , swings up to approximately V_{IN} , and the inductor current, i_L , increases with a linear slope. The HS switch is turned off by the control logic. During the HS switch off-time, t_{OFF} , the LS switch is turned on. Inductor current discharges through the LS switch, forcing V_{SW} to swing below ground by the voltage drop across the LS switch. The regulator loop adjusts the duty cycle to maintain a constant output voltage. D is defined by the on-time of the HS switch over the switching period: $D = T_{ON} / (T_{ON} + T_{OFF})$.

In an ideal buck converter where losses are ignored, D is proportional to the output voltage and inversely proportional to the input voltage: $D = V_{OUT} / V_{IN}$.

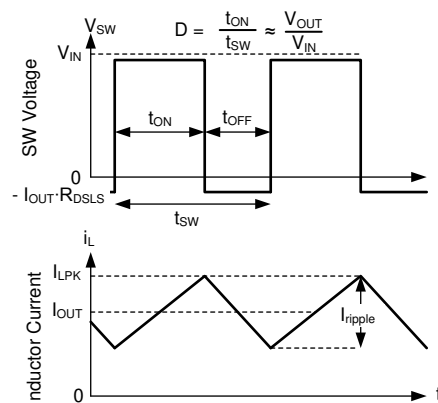


Figure 7-18. SW Voltage and Inductor Current Waveforms in Continuous Conduction Mode (CCM)

To get accurate DC load regulation, a voltage feedback loop is used. Peak and valley inductor currents are sensed for peak current mode control and current protection. The regulator operates with continuous conduction mode with constant switching frequency when load level is above one half of the minimum peak inductor current. The internally-compensated regulation network achieves fast and stable operation with small external components and low-ESR capacitors.

7.4.3.2 Auto Mode Operation

The LMQ644xx can have two behaviors while lightly loaded. One behavior, called auto mode operation, allows a seamless transition between normal current mode operation while heavily loaded and in highly-efficient light-load operation. The other behavior, called FPWM mode, maintains full frequency even when unloaded. Which mode the LMQ644xx operates in depends on the SYNC/MODE pin. When SYNC/MODE is high, the part is in FPWM. When SYNC/MODE is low, the part is in PFM.

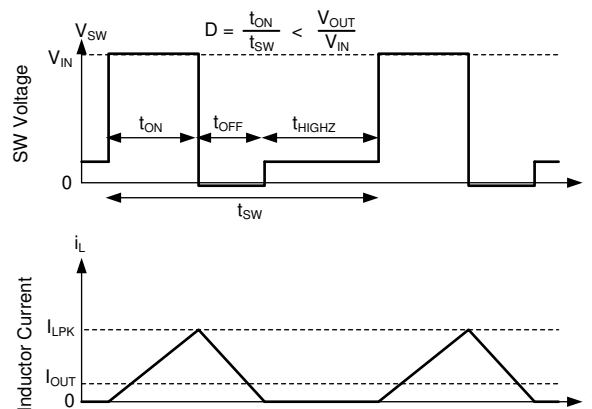
In auto mode, light-load operation is employed in the LMQ644xx at load lower than approximately 1/10th of the rated maximum output current. Light-load operation employs two techniques to improve efficiency:

- Diode emulation, which allows DCM operation
- Frequency reduction

Note that while these two features operate together to create excellent light load behavior, they operate independently of each other.

7.4.3.2.1 Diode Emulation

Diode emulation prevents reverse current through the inductor, which requires a lower frequency needed to regulate given a fixed peak inductor current. Diode emulation also limits ripple current as frequency is reduced. Frequency is reduced when peak inductor current goes below $I_{PEAK-MIN}$. With a fixed peak current, as output current is reduced to zero, frequency must be reduced to near zero to maintain regulation.



In auto mode, the low-side device is turned off after inductor current is near zero. As a result, after output current is less than half of inductor ripple in CCM, the part operates in DCM. This is equivalent to saying that diode emulation is active.

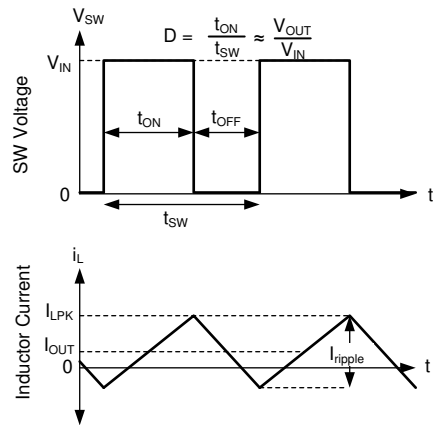
Figure 7-19. PFM Operation

The LMQ644xx has a minimum peak inductor current setting in auto mode. That being said, when current is reduced to a low value with fixed input voltage, on-time is constant. Regulation is then achieved by adjusting frequency. This mode of operation is called PFM mode regulation.

7.4.3.3 FPWM Mode Operation

Like auto mode operation, FPWM mode operation during light-load operation is selected using the SYNC/MODE pin.

In FPWM Mode, frequency is maintained while lightly loaded. To maintain frequency, a limited reverse current is allowed to flow through the inductor. Reverse current is limited by reverse current limit circuitry. See the [Electrical Characteristics](#) for reverse current limit values.



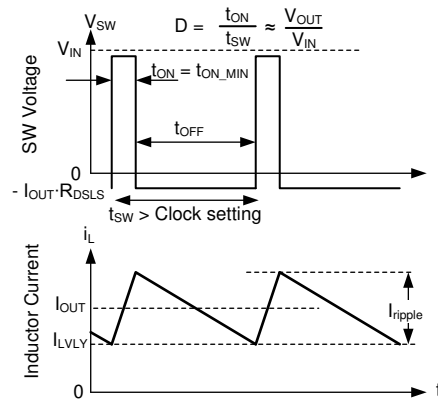
FPWM mode Continuous Conduction (CCM) is possible even if I_{OUT} is less than half of ripple.

Figure 7-20. FPWM Mode Operation

In FPWM mode, frequency reduction is still available if output voltage is high enough to command minimum on-time, even while lightly loaded. This allows good behavior during faults which involves the output being pulled up.

7.4.3.4 Minimum On-time (High Input Voltage) Operation

The LMQ644xx continues to regulate output voltage. This is true even if the input-to-output voltage ratio requires an on-time less than the minimum on-time of the chip with a given clock setting. This is accomplished using valley current control. At all times, the compensation circuit dictates both a maximum peak inductor current and a maximum valley inductor current. If, for any reason, valley current is exceeded, the clock cycle is extended until valley current falls below that determined by the compensation circuit. If it is not operating in current limit, the maximum valley current is set above the peak inductor current. This prevents valley control from being used unless there is a failure to regulate using peak current only. If the input-voltage to output-voltage ratio is too high, even though current exceeds the peak value dictated by compensation, the high-side device cannot be turned off quickly enough to regulate output voltage. See t_{ON_MIN} in the [Electrical Characteristics](#). As a result, the compensation circuit reduces both peak and valley current. After a low enough current is selected by the compensation circuit, valley current matches that being commanded by the compensation circuit. Under these conditions, the low-side device is kept on and the next clock cycle is prevented from starting until inductor current drops below the desired valley current. Because on-time is fixed at its minimum value, this type of operation resembles that of a device using a COT control scheme. See [Figure 7-21](#).

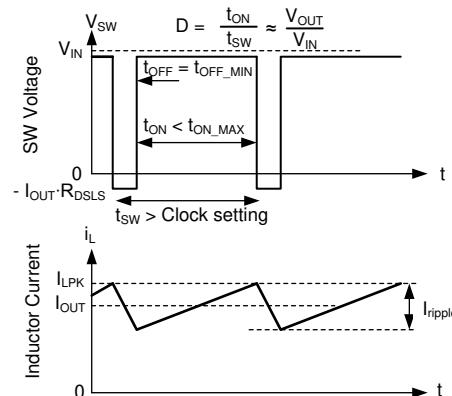


In valley control mode, the minimum inductor current is regulated, not peak inductor current.

Figure 7-21. Valley Current Mode Operation

7.4.3.5 Dropout

Dropout operation is defined as any input-to-output voltage ratio that requires frequency to drop to achieve the needed duty factor. At a given clock frequency, duty factor is limited by minimum off-time. After this limit is reached, if clock frequency is maintained, output voltage falls. Instead of allowing the output voltage to drop, the LMQ644xx extends on-time past the end of the clock cycle until the required peak inductor current is achieved. The clock can start a new cycle after peak inductor current is achieved or after a pre-determined maximum on-time, t_{ON_MAX} , of approximately 9 μ s passes. As a result, after the needed duty factor cannot be achieved at the selected clock frequency due to the existence of a minimum off-time, frequency drops to maintain regulation. If input voltage is low enough that the output voltage cannot be regulated even with an on-time of t_{ON_MAX} , output voltage drops to slightly below input voltage.



This image shows the switching waveforms while in dropout. Inductor current takes longer than a normal clock to reach the desired peak value. As a result, frequency drops. This frequency drop is limited by t_{ON_MAX} .

Figure 7-22. Dropout Waveforms

7.4.3.6 Recovery from Dropout

In some applications, input voltage can drop below the desired output voltage then recover to a higher value suddenly. With most regulators, the sudden increase in input voltage results in output voltage rising at a rate limited only by current limit until regulation is achieved. As input voltage reaches the desired output voltage, there is overshoot due to wind up in the control loop. This overshoot can be large in applications that have small

output capacitors and light loads. Also, large inrush currents can cause large fluctuations on the input line after the regulator starts regulating the output voltage. This typically requires less current than during this initial inrush.

The LMQ644xx greatly reduces inrush current and overshoot. This is done by engaging the soft-start circuit whenever the input voltage suddenly rises, after dipping low enough to cause the output voltage to droop. To prevent this feature from accidentally engaging, output voltage must fall more than 1% to engage this feature. Also, this feature engages only if operating in dropout or current limit, preventing interference with normal transient response but allowing several percent overshoot while engaging. If output voltage is very close to its desired level, overshoot is reduced by inductor current not having time to rise to a high level before regulation starts.

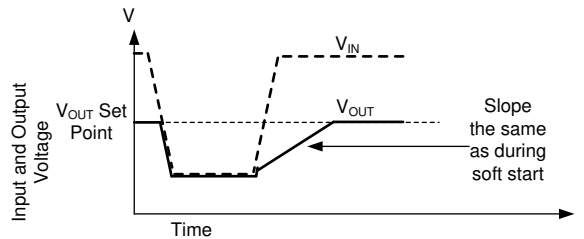


Figure 7-23. When Output Voltage Falls, It Recovers Slowly Preventing Overshoot and Large Inrush Currents

7.4.3.7 Other Fault Modes

Fault modes and their description can be found in [Section 7.3](#) of this data sheet.

8 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

8.1 Application Information

The LMQ644xx step-down DC-to-DC converter is typically used to convert a higher DC voltage to a lower DC voltage with a maximum output current up to 12 A per device. Maximum load current is dependent on the thermal environment of the design. The thermal performance curves for the EVM can be used as a starting point for determining load capability at different ambient temperatures.

The following design procedure can be used to select components for the LMQ644xx.

8.2 Typical Application

Figure 8-1 and Figure 8-2 show typical application circuits for the LMQ644xx. The following design procedure can be used to select components for the LMQ644xx. This device is designed to function over a wide range of external components and system parameters. However, the internal compensation is optimized for a certain range of external inductance and output capacitance. As a quick start guide, Table 8-2 provides typical component values for some of the most common configurations. The values given in the table are typical. Other values can be used to enhance certain performance criterion as required by the application. Note that for this eQFN package, the input capacitors are split and placed on either side of the package. See Section 8.2.2.5 for more details.

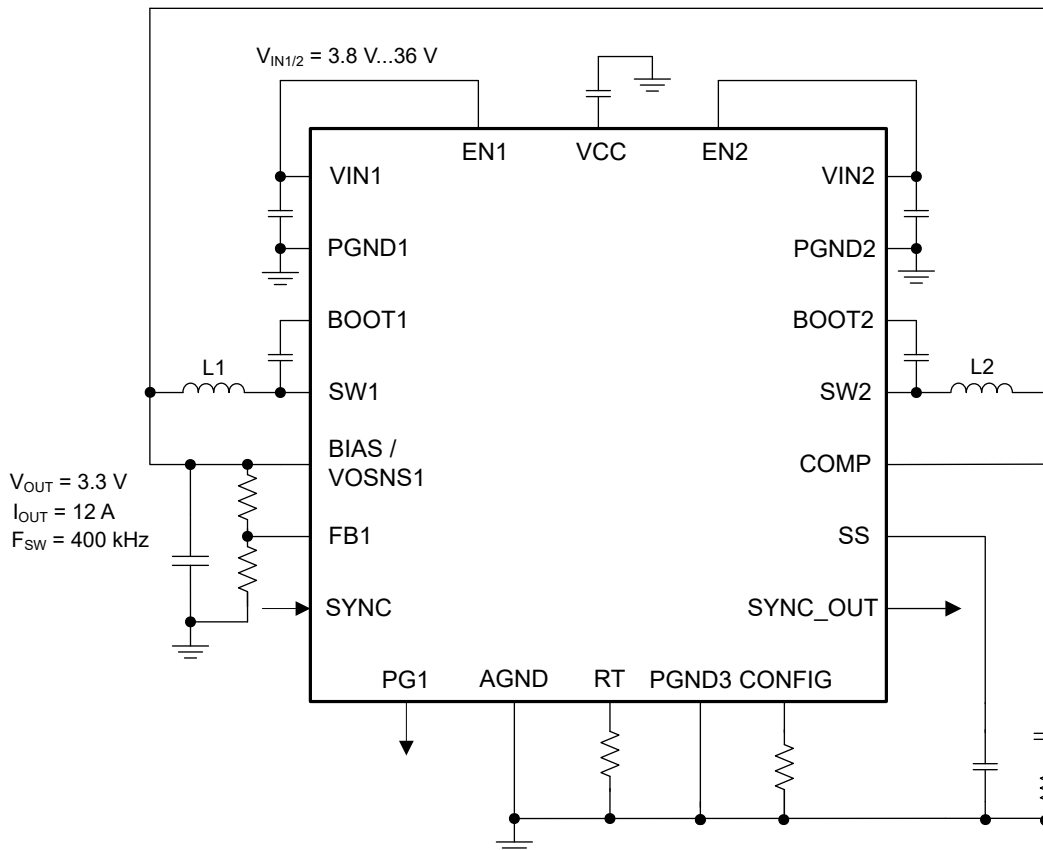


Figure 8-1. Example Application Circuit - 400-kHz Single Adjustable Output

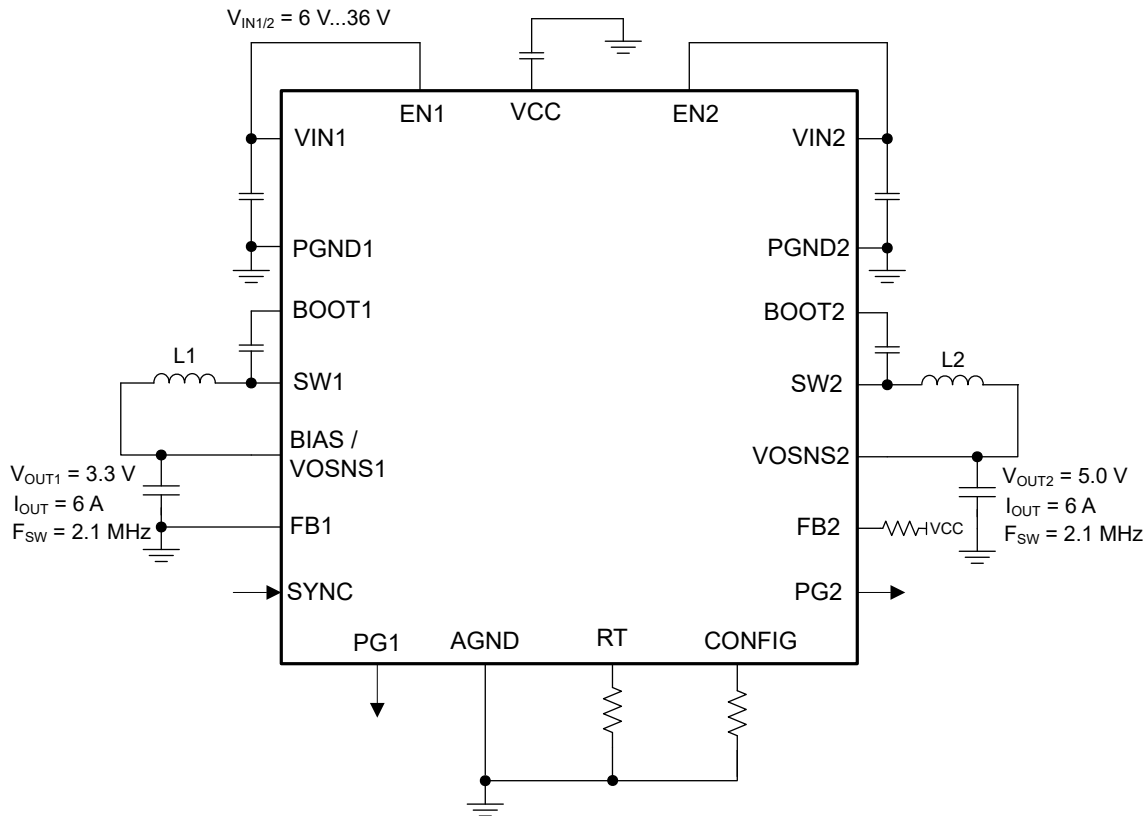


Figure 8-2. Example Application Circuit - 2.1-MHz Dual Fixed Output

8.2.1 Design Requirements

Table 8-1 provides the parameters for our detailed design procedure example for Figure 8-2:

Table 8-1. Detailed Design Parameters

DESIGN PARAMETER	EXAMPLE VALUE
Input voltage	13.5 V (6 V to 36 V)
Output voltage	3.3 and 5 V fixed

8.2.2 Detailed Design Procedure

The following design procedure refers to Figure 8-2, and Table 8-1.

8.2.2.1 Choosing the Switching Frequency

The choice of switching frequency is a compromise between conversion efficiency and overall design size. Lower switching frequency implies reduced switching losses, usually resulting in less power dissipated in the IC. Lower power dissipated in the IC results in higher system efficiency and a lower IC temperature. However, higher switching frequency allows the use of smaller inductors and output capacitors, hence, a more compact design. Many applications require that the AM band be avoided. These applications tend to operate at around 400 kHz (below the AM band), or 2.1 MHz (above the AM band). For 400 kHz, a 39.2k 1% resistor can be used. For this 2100 kHz example, a 7.15k 1% resistor is selected.

8.2.2.2 Setting the Output Voltage

The output regulation target can be programmed to a fixed 3.3 V by connecting FB to AGND, or a fixed 5.0-V output by connecting FB to VCC through a 10-kΩ resistor. Also, the output voltage of the LMQ644xx is externally adjustable using a resistor divider network. The divider network is comprised of the top and bottom feedback resistors, R_{FBT} and R_{FBB} , and closes the loop between the output voltage and the converter. The converter regulates the output voltage by holding the voltage at the internal error amplifier input equal to the internal

reference voltage, $V_{FB} = 0.8 \text{ V}$. The total resistance of the divider is a compromise between excessive noise pickup and excessive loading of the output. Lower resistance values reduce noise sensitivity but also reduce the light-load efficiency. The recommended value for R_{FBT} is around 100 k Ω with a maximum value of 1 M Ω .

8.2.2.3 Inductor Selection

The main parameters for selecting the inductor are the inductance and saturation current. The inductance is based on the desired peak-to-peak ripple current. The inductance is normally chosen to be in the range of 20% to 50% of the maximum output current. Experience shows that a good value for inductor ripple current is 30% of the maximum load current for systems with a fixed input voltage. This example uses $V_{IN} = 13.5 \text{ V}$, which is closer to the nominal voltage of a 12-V car battery. When selecting the ripple current for applications with much smaller maximum load than the maximum available from the device, the maximum device current must be used for this calculation. Equation 5 can be used to determine the value of the inductance. The constant K is the percentage of peak-to-peak inductor current ripple to rated output current. For this 6-A, 2100-kHz, 3.3-V example, $K = 0.25$ is chosen and the closest standard value of 1 μH was selected.

$$L = \left(\frac{V_{OUT}}{V_{IN}} \right) \times \left(\frac{V_{IN} - V_{OUT}}{f_{SW} \times K \times I_{OUT_MAX}} \right) \quad (5)$$

Ideally, the saturation current rating of the inductor must be at least as large as the high-side switch current limit, I_{HS} . This rating makes sure that the inductor does not saturate, even during a soft-short condition on the output. A hard short causes the LMQ644xx to enter hiccup mode (see Section 7.3.14). A soft short can hold the output current near the current limit without triggering hiccup. When the inductor core material saturates, the inductance can fall to a very low value, causing the inductor current to rise very rapidly. Although the valley current limit, I_{LS} , is designed to reduce the risk of current runaway, a saturated inductor can cause the current to rise to high values very rapidly. This event can lead to component damage, so the inductor not saturating is crucial. Inductors with a ferrite core material have very hard saturation characteristics, but usually have lower core losses than powdered iron cores. Powdered iron cores exhibit a soft saturation, allowing some relaxation in the saturation current rating of the inductor. However, they have more core losses at frequencies typically above 1 MHz. To avoid subharmonic oscillation, the inductance value must not be less than that given in Equation 6. The maximum inductance is limited by the minimum current ripple required for the current mode control to perform correctly. As a rule-of-thumb, the minimum inductor ripple current must be no less than about 10% of the device maximum rated current under nominal conditions.

$$L > \left(\frac{V_{OUT}}{f_{SW} \times I_{RATED}} \right) \quad (6)$$

8.2.2.4 Output Capacitor Selection

The output capacitor value and ESR determine the output voltage ripple and load transient performance. The output capacitor is usually limited by the load transient requirements rather than the output voltage ripple. Table 8-2 can be used to find capacitor values for C_{OUT} and C_{FF} for a few common applications. Note that 4.99-k Ω R_{FF} can be used in series with C_{FF} to limit high frequency noise into the FB pin. In this example, 3.3 V_{OUT} and 2.1 MHz, good transient performance is desired. From the table select 3 \times 22- μF ceramic as the output capacitor and 10 pF as C_{FF} . For other voltage a frequency combinations C_{out} can be estimated using the desired crossover frequency (f_x) and output voltage. Crossover is usually limited by the sampling pole created from the switching frequency. Thus, the crossover is usually a percentage such as 1/10th the switching frequency.

Table 8-2. Selected Output Capacitor and C_{FF} Values

FREQUENCY	I_{OUT}	TRANSIENT PERFORMANCE	3.3-V OUTPUT		5-V OUTPUT	
			C_{OUT} (per phase)	C_{FF}	C_{OUT}	C_{FF}
400 kHz	6 A	Minimum	3 \times 47- μF ceramic		2 \times 47- μF ceramic	
400 kHz	6 A	Better Transient	4 \times 47- μF ceramic	10 pF	3 \times 47- μF ceramic	10 pF
2.1 MHz	6 A	Minimum	3 \times 22- μF ceramic		2 \times 22- μF ceramic	
2.1 MHz	6 A	Better Transient	4 \times 22- μF ceramic	10 pF	3 \times 22- μF ceramic	10 pF

8.2.2.5 Input Capacitor Selection

The ceramic input capacitors provide a low impedance source to the regulator in addition to supplying the ripple current and isolating switching noise from other circuits. A minimum of 10- μ F ceramic capacitance is required at each input/ground pin pair of the LMQ644xx. Use 2 x 10- μ F ceramic capacitance or more for better EMI performance. This must be rated for at least the maximum input voltage that the application requires. It is preferable to have twice the maximum input voltage to reduce DC bias derating. This capacitance can be increased to help reduce input voltage ripple and maintain the input voltage during load transients. In addition, a small case size (0603 or 0402) ceramic capacitor can be used at each input/ground pin pair, VIN1/PGND1 and VIN2/PGND2. The capacitor must also have an X7R or better dielectric. Choose the highest capacitor value with these parameters. This provides a high frequency bypass to reduce switch-node ring and electromagnetic interference emissions. The LMQ644xx-Q1 also has two sets of internal capacitors to further improve bypassing. Each capacitor set is configured in series, so that in the unlikely scenario of a capacitor failure as a short, the second series capacitor can withstand the full input voltage and maintain operation. The eQFN (RXA) package provides two input voltage pins and two power ground pins on opposite sides of the package. This allows the input capacitors to be split and placed optimally with respect to the internal power MOSFETs, thus improving the effectiveness of the input bypassing. This example places two 10- μ F, 50-V, 1206, X7R ceramic capacitors and two 0.1- μ F, 50-V, 0402, X7R ceramic capacitors at each VIN/PGND pin pair.

Often, using an electrolytic capacitor on the input in parallel with the ceramics is desirable. This action is especially true if long leads/traces are used to connect the input supply to the regulator. The moderate ESR of this capacitor can help dampen ringing on the input supply caused by the inductance of the long power leads. The use of this additional capacitor also helps with momentary voltage dips caused by input supplies with unusually high impedance.

Most of the input switching current passes through the ceramic input capacitors. The approximate worst case RMS value of this current can be calculated with [Equation 7](#). This value must be checked against the manufacturers' maximum ratings.

$$I_{\text{RMS}} \cong I_{\text{OUT}} \times \sqrt{\left(\frac{V_{\text{OUT}}}{V_{\text{IN}}}\right)} \quad (7)$$

8.2.2.6 BOOT Capacitor

The LMQ644xx requires a bootstrap capacitor connected between the CBOOT pin and the SW pin. This capacitor stores energy which is used to supply the gate drivers for the power MOSFETs. TI recommends a high-quality, 100-nF ceramic capacitor with a rating of at least 10 V.

8.2.2.7 VCC

The VCC pin is the output of the internal LDO used as a supply to the internal control circuits of the regulator. This output requires a 1- μ F, 10-V, X7R or similar, 0603 or similar ceramic capacitor connected from VCC to AGND for proper operation. Generally avoid loading this output with any external circuitry. However, this output can be used to supply the pullup for the PG pin (see [Section 7.3.7](#)) as well as configuring the FB pin for fixed output voltages. A pullup resistor with value of 100 k Ω is a good choice in this case. The nominal output voltage on VCC is 3.3 V.

8.2.2.8 C_{FF} and R_{FF} Selection

A feedforward capacitor, C_{FF}, on the order of tens of picofarads and no bigger than 15 nF, can be used to improve phase margin and transient response of circuits which have output capacitors with low ESR and tight voltage margin requirements. Because this C_{FF} capacitor can conduct noise from the output of the circuit directly to the FB node of the IC, a 4.99-k Ω resistor, R_{FF}, can be placed in series with C_{FF} to lower high frequency susceptibility when it is used. If the ESR zero of the output capacitor is below 200 kHz, no C_{FF} must be used. In general the C_{FF} capacitor can be sized to add phase boost slightly above the desired crossover frequency.

$$C_{\text{FF}} = \left(\frac{1}{2 \times \pi \times R_{\text{FBT}} \times f_X \times 1.5} \right) \quad (8)$$

If output voltage is less than 2.5 V, C_{FF} has little effect, so it can be omitted. If output voltage is greater than 14 V, C_{FF} must be used cautiously because it can easily introduce too much gain at higher frequencies.

If 1 M Ω is selected for R_{FBT} , then a feedforward capacitor C_{FF} is usually required to offset parasitic capacitance in PCB construction.

8.2.2.9 SYNCHRONIZATION AND MODE

The SYNC pin allows you to synchronize the converter to an external clock voltage (SYNC). The pin also allows the selection between two modes. The following are the selectable modes:

- Forced pulse width modulation (FPWM) operation, which operates at a fixed frequency at all loads in typical operation
- Auto mode which automatically switches to pulse-frequency modulation (PFM) at light loads to improve light-load efficiency

Connect the SYNC pin to VCC through a 10 k Ω resistor for FPWM. Connect to ground for PFM. You can also apply a clock signal to synchronize the switching frequency to an external clock. See [Section 7.3.4](#) for more information.

8.2.2.10 External UVLO

In some cases, the user can need an input undervoltage lockout (UVLO) level different than that provided internal to the device. This can be accomplished by using the circuit shown in [Figure 7-2](#). The input voltage at which the device turns on is designated V_{ON} while the turn-off voltage is V_{OFF} . First, a value for R_{ENB} is chosen in the range of 10 k Ω to 100 k Ω , then [Equation 1](#) is used to calculate R_{ENT} and V_{OFF} .

8.2.2.11 Typical Thermal Performance

As with any power conversion device, the LMQ644xx dissipates internal power while operating. The effect of this power dissipation is to raise the internal temperature of the converter above ambient temperature. The internal die temperature (T_J) is a function of the following:

- Ambient temperature
- Power loss
- Effective thermal resistance, $R_{\theta JA}$ of the device
- PCB layout

The maximum internal die temperature for the LMQ644xx must be limited to 150°C. This establishes a limit on the maximum device power dissipation and, therefore, the load current. [Equation 9](#) shows the relationships between the important parameters. Larger ambient temperatures (T_A) and larger values of $R_{\theta JA}$ reduce the maximum available output current. For low ambient temperature designs the converter efficiency can be estimated by using the curves provided in the [Application Curves](#) section. If the desired operating conditions cannot be found in one of the curves, then the junction temperature can be roughly estimated using the EVM thermal performance as a starting point. Alternatively, the EVM can be adjusted to match the desired application requirements and the efficiency can be measured directly. The correct value of $R_{\theta JA}$ is more difficult to estimate. As stated in the [Semiconductor and IC Package Thermal Metrics application report](#), the JEDEC value of $R_{\theta JA}$ given in the electrical characteristics table is not always valid for design purposes and must not be used to estimate the thermal performance of the device in a real application. The values reported in the electrical characteristics table were measured under a specific set of conditions that are rarely obtained in an actual application.

$$I_{OUT_MAX} = \left(\frac{T_J - T_A}{R_{\theta JA}} \times \frac{\eta}{(1 - \eta)} \times \frac{1}{V_{OUT}} \right) \quad (9)$$

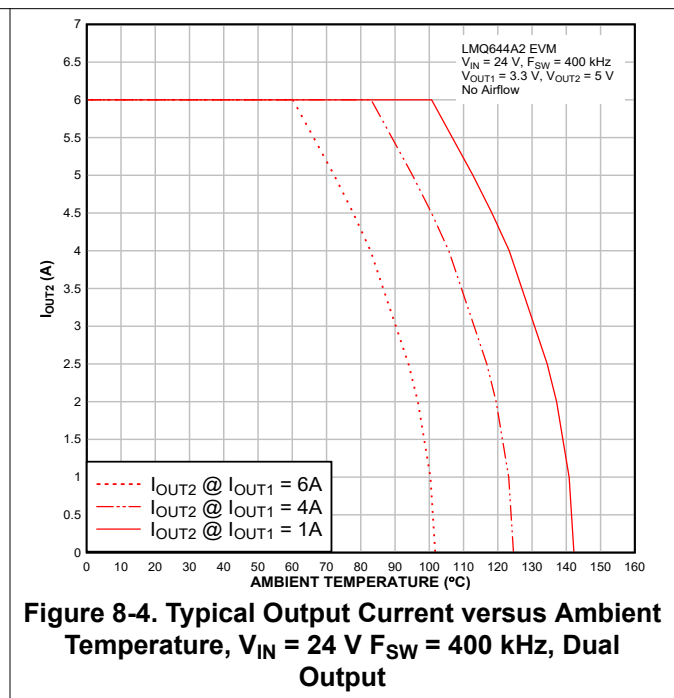
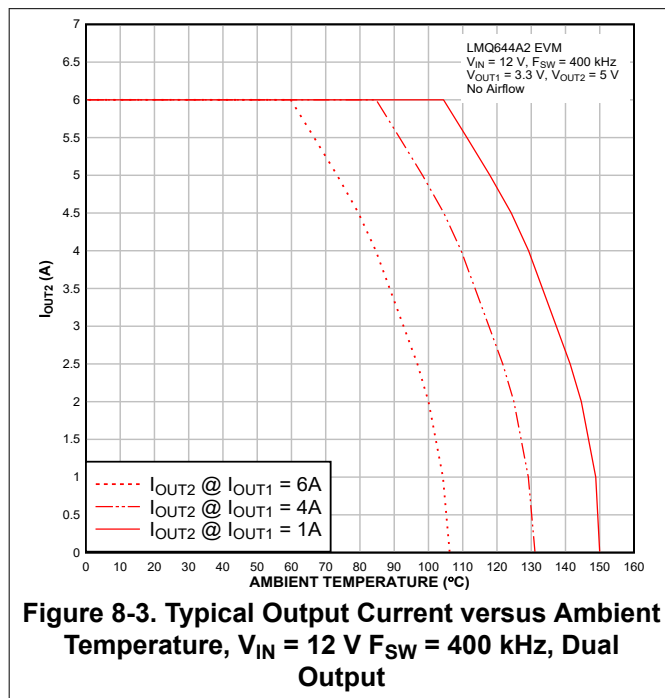
where

- η = efficiency
- T_A = ambient temperature
- T_J = junction temperature
- $R_{\theta JA}$ = the effective thermal resistance of the IC junction to the air, mainly through the PCB

The effective $R_{\theta JA}$ is a critical parameter and depends on many factors (just to mention a few of the most critical parameters):

- Power dissipation
- Air temperature
- Airflow
- PCB area
- Copper heat-sink area
- Number of thermal vias under or near the package
- Adjacent component placement

A typical curve of maximum output current versus ambient temperature is shown in [Figure 8-3](#) and [Figure 8-4](#) for a good thermal layout. This data is for the LMQ644A2 evaluation board. It must be remembered that the data given in these graphs are for illustration purposes only, and the actual performance in any given application depends on all of the previously mentioned factors.



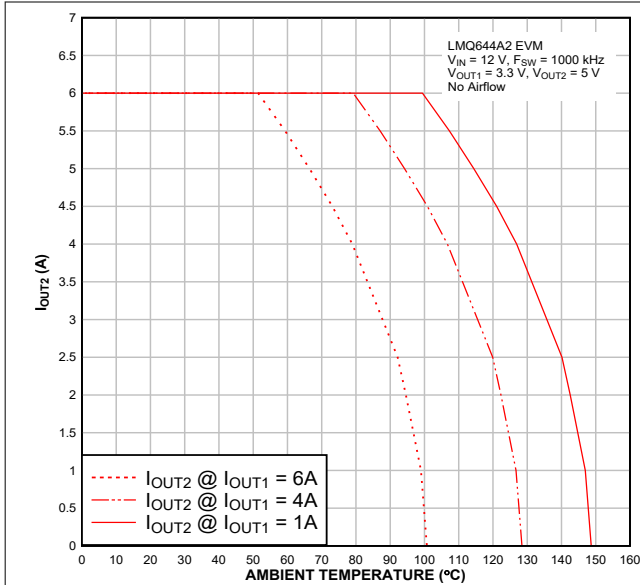


Figure 8-5. Typical Output Current versus Ambient Temperature, $V_{IN} = 12\text{ V}$ $F_{SW} = 1\text{ MHz}$, Dual Output

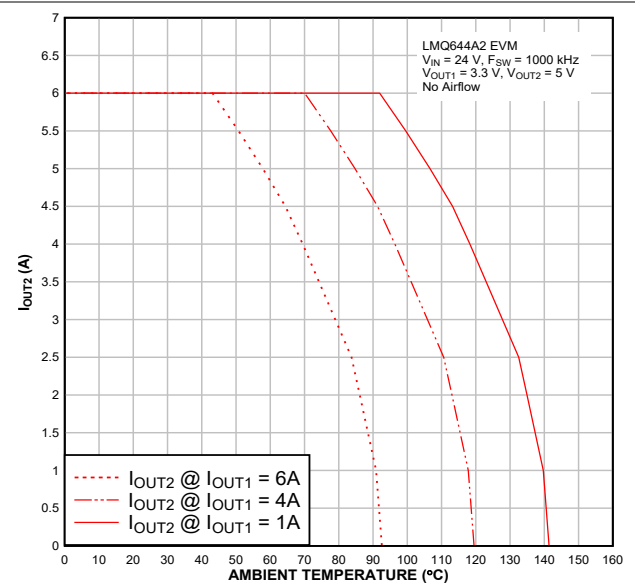


Figure 8-6. Typical Output Current versus Ambient Temperature, $V_{IN} = 24\text{ V}$ $F_{SW} = 1\text{ MHz}$, Dual Output

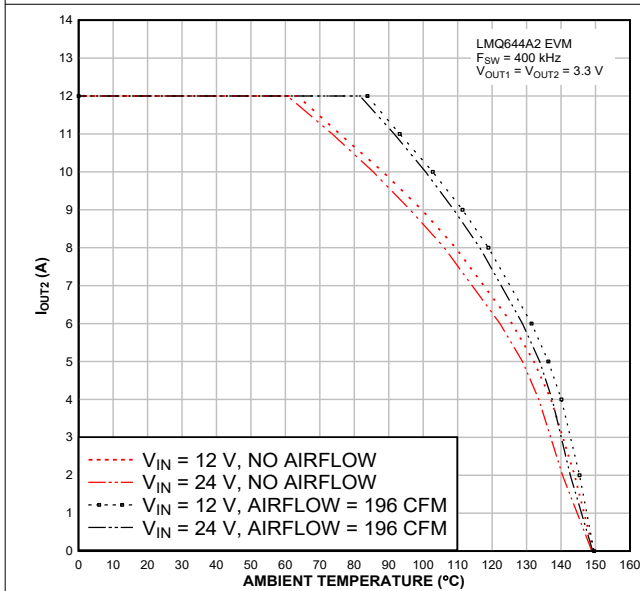


Figure 8-7. Typical Output Current versus Ambient Temperature, $F_{SW} = 400\text{ kHz}$, Single Output

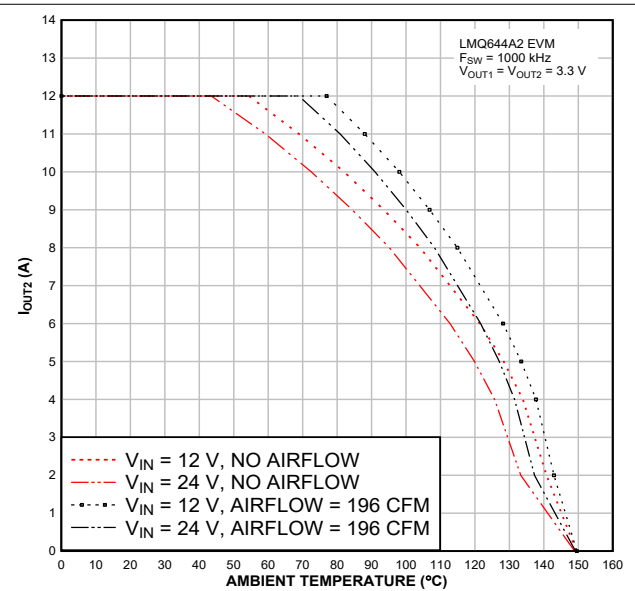


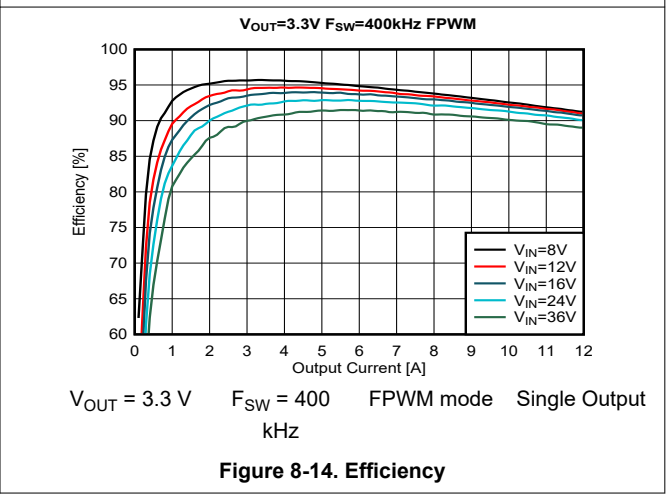
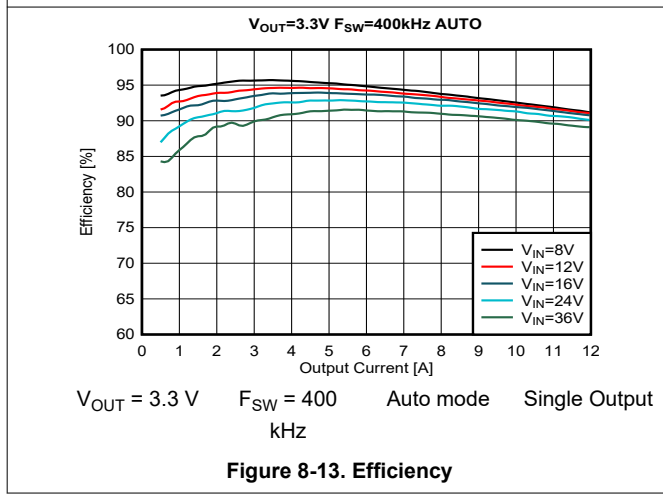
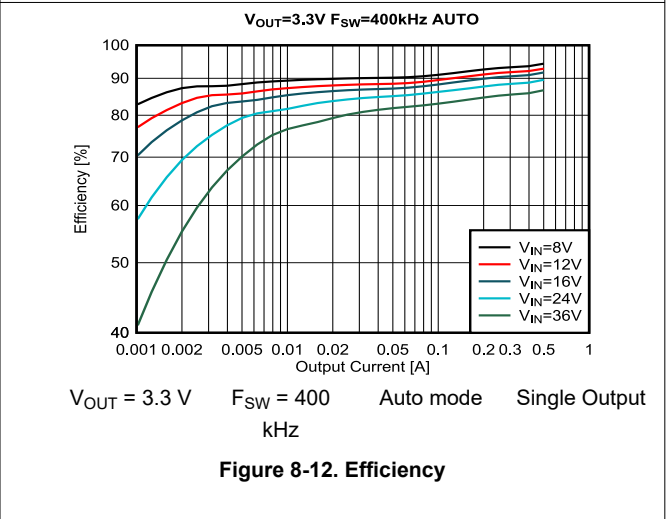
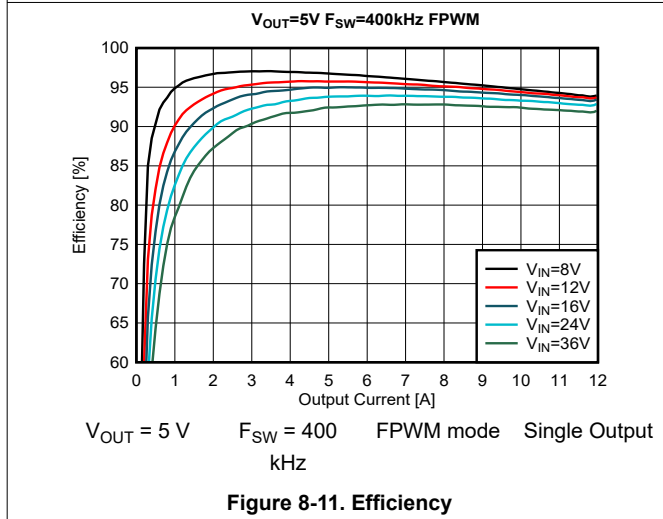
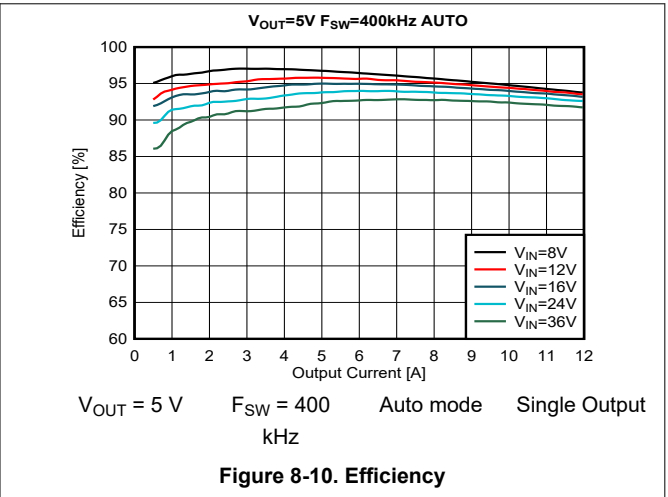
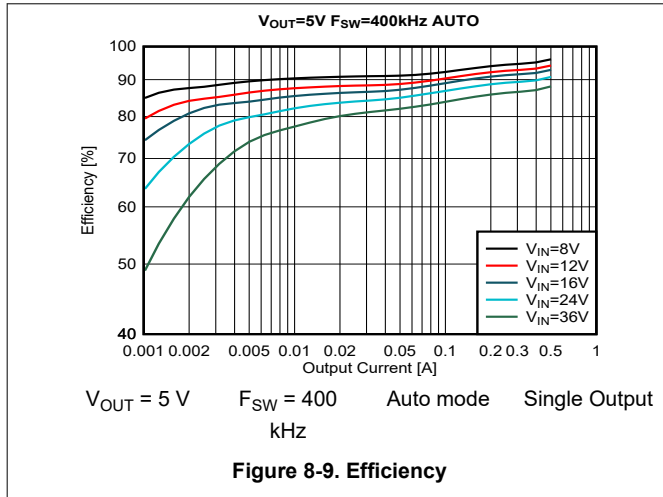
Figure 8-8. Typical Output Current versus Ambient Temperature, $F_{SW} = 1\text{ MHz}$, Single Output

Use the following resources as a guide to optimal thermal PCB design and estimating $R_{\theta JA}$ for a given application environment:

- [Thermal Design by Insight not Hindsight application note](#)
- [A Guide to Board Layout for Best Thermal Resistance for Exposed Pad Packages application note](#)
- [Semiconductor and IC Package Thermal Metrics application note](#)
- [Quick Reference Guide To TI Buck Switching DC/DC application note](#)

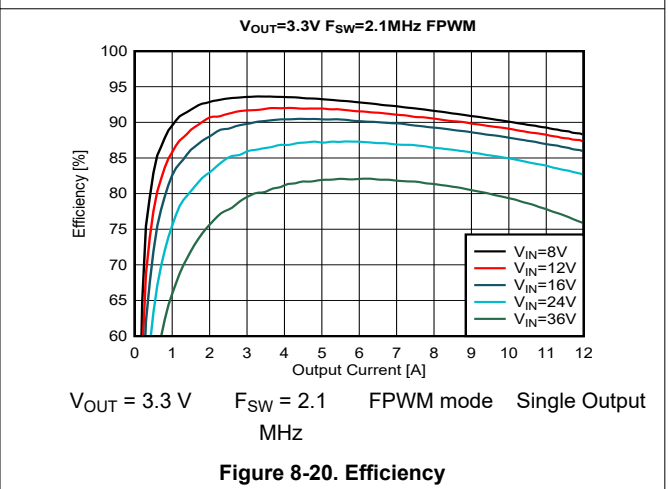
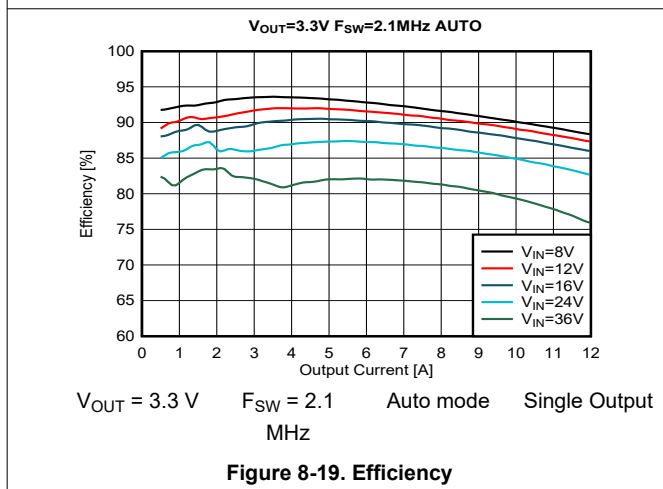
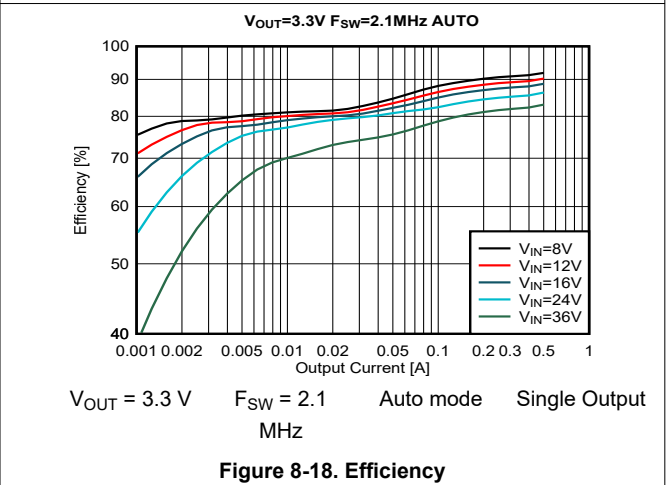
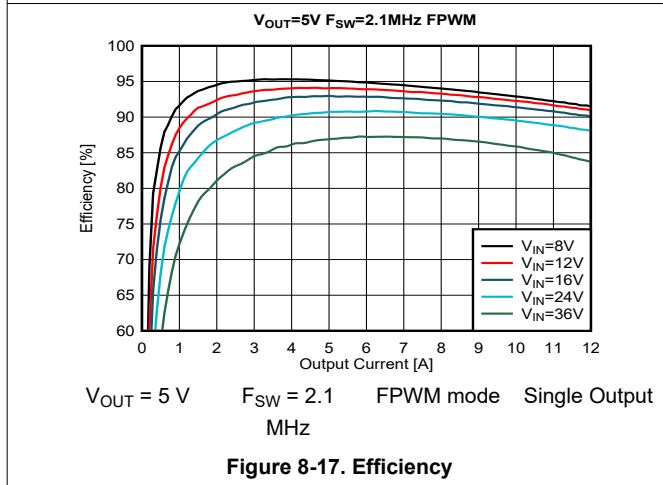
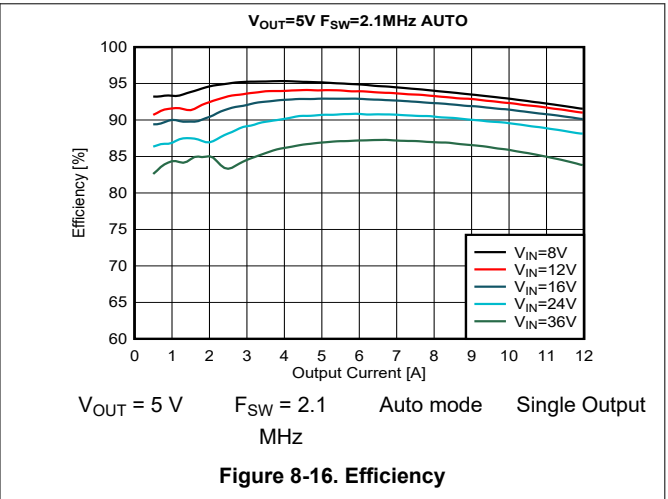
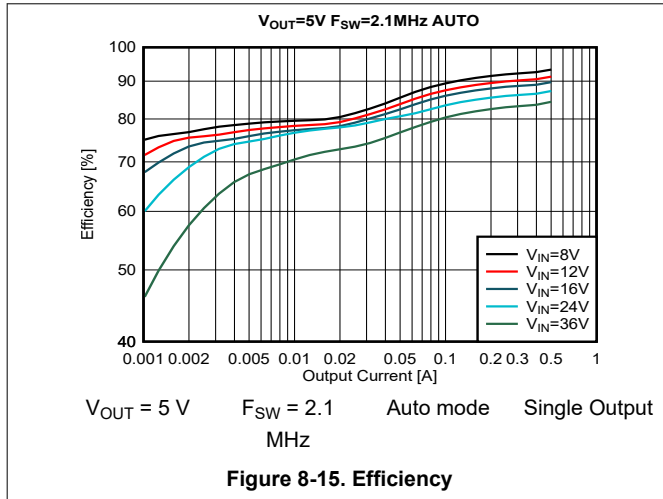
8.2.3 Application Curves

Unless otherwise specified, the following conditions apply: Device: LMQ644A2, $V_{IN} = 13.5\text{ V}$, $T_A = 25^\circ\text{C}$. The circuit is shown in Figure 8-1, and Figure 8-2 with the appropriate BOM from Table 8-3.



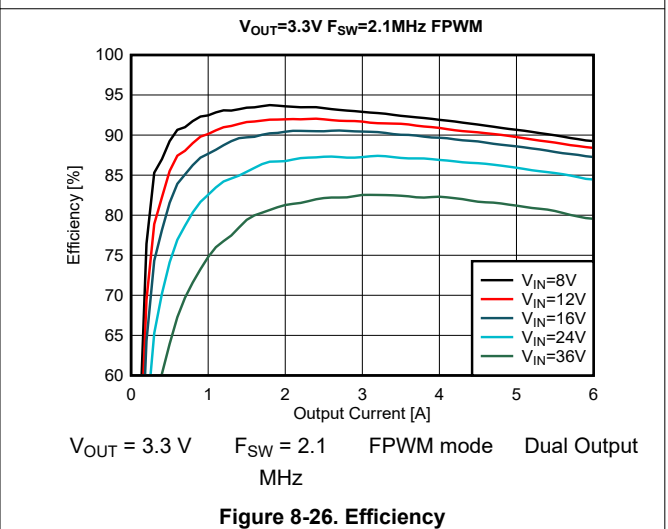
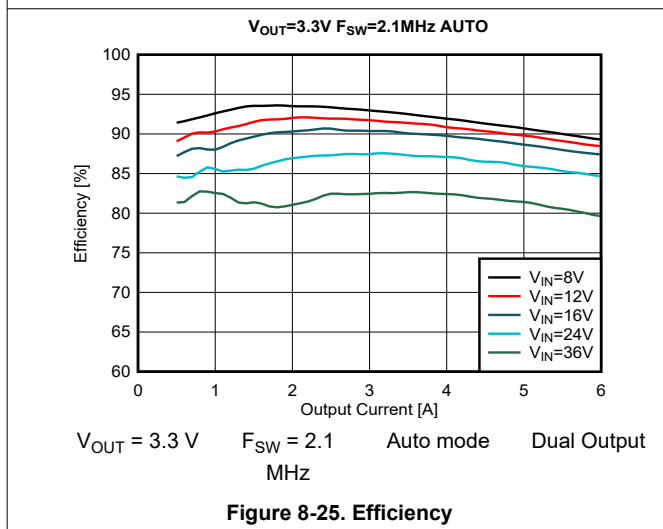
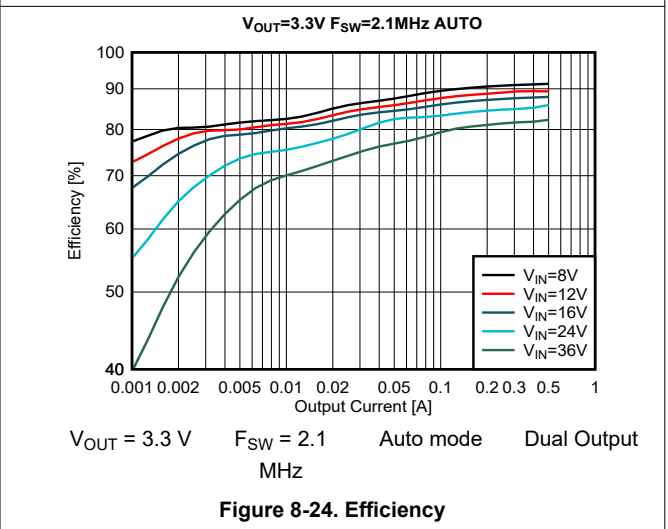
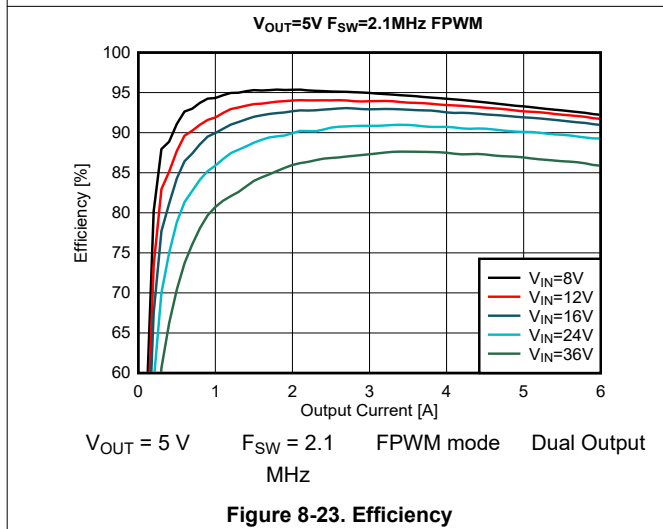
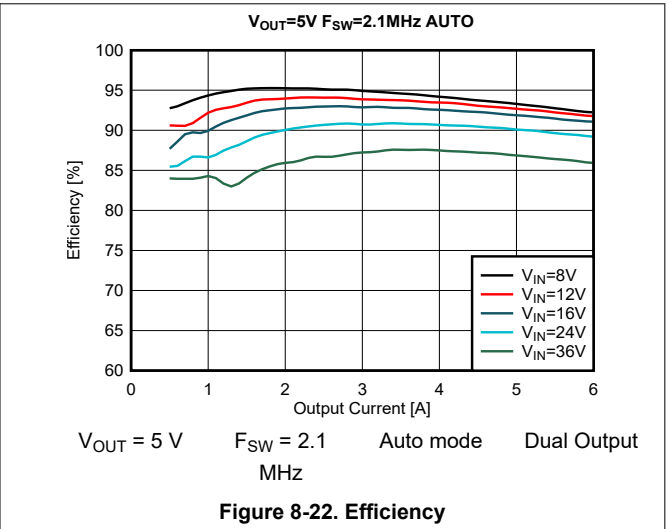
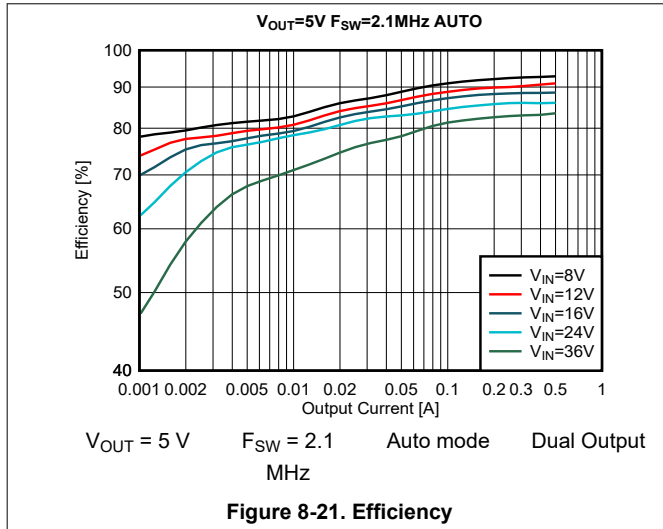
8.2.3 Application Curves (continued)

Unless otherwise specified, the following conditions apply: Device: LMQ644A2, $V_{IN} = 13.5\text{ V}$, $T_A = 25^\circ\text{C}$. The circuit is shown in Figure 8-1, and Figure 8-2 with the appropriate BOM from Table 8-3.



8.2.3 Application Curves (continued)

Unless otherwise specified, the following conditions apply: Device: LMQ644A2, $V_{IN} = 13.5\text{ V}$, $T_A = 25^\circ\text{C}$. The circuit is shown in Figure 8-1, and Figure 8-2 with the appropriate BOM from Table 8-3.



8.2.3 Application Curves (continued)

Unless otherwise specified, the following conditions apply: Device: LMQ644A2, $V_{IN} = 13.5\text{ V}$, $T_A = 25^\circ\text{C}$. The circuit is shown in Figure 8-1, and Figure 8-2 with the appropriate BOM from Table 8-3.

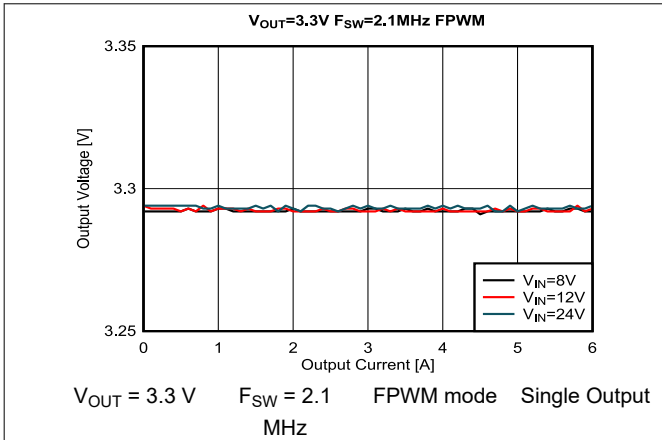


Figure 8-27. Load and Line Regulation

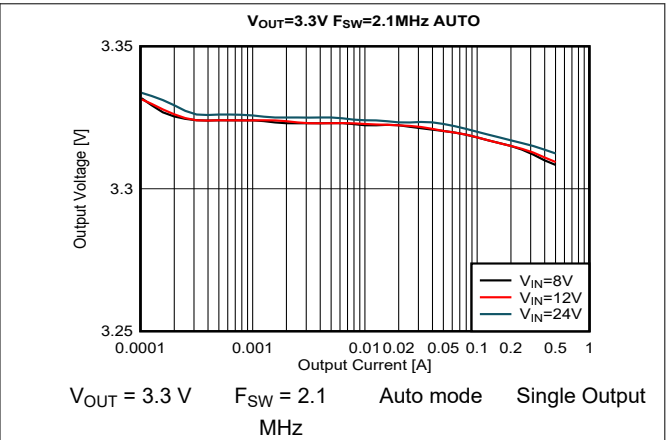


Figure 8-28. Load and Line Regulation

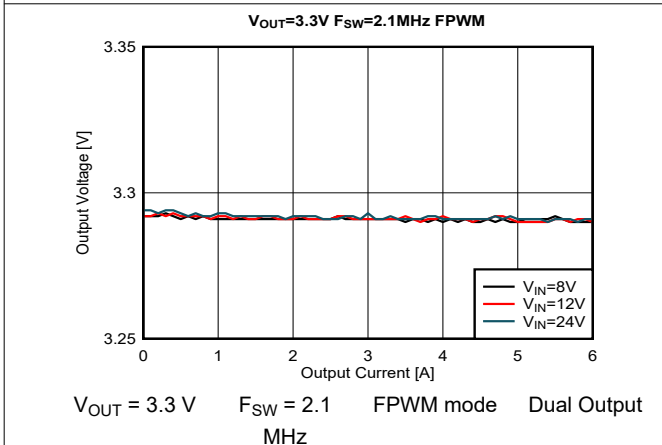


Figure 8-29. Load and Line Regulation

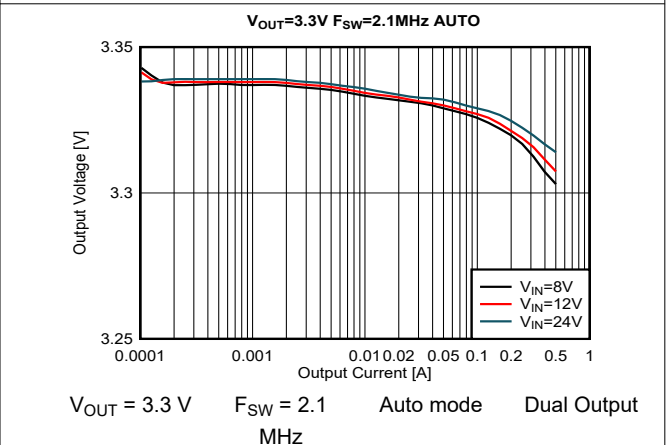


Figure 8-30. Load and Line Regulation

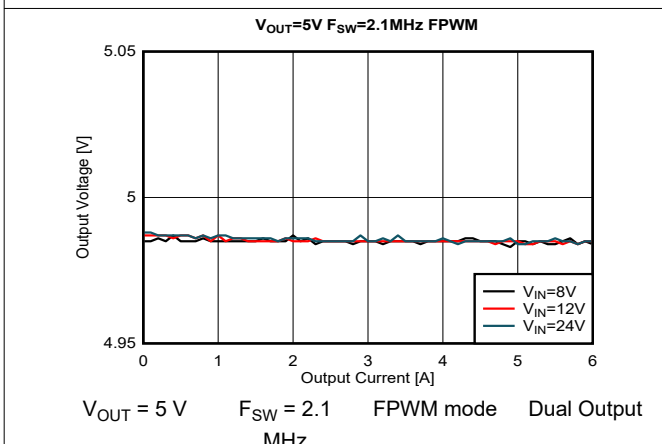


Figure 8-31. Load and Line Regulation

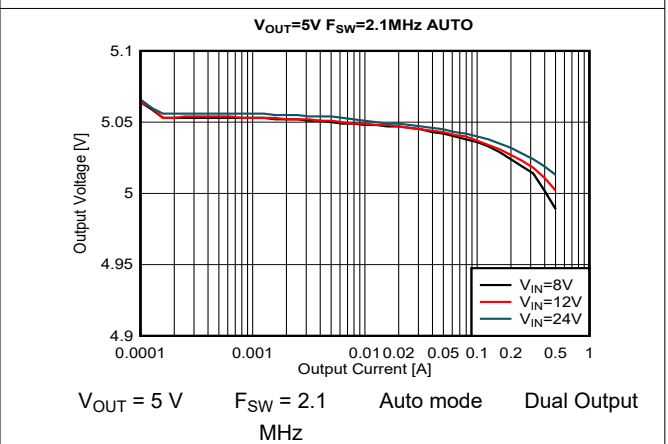
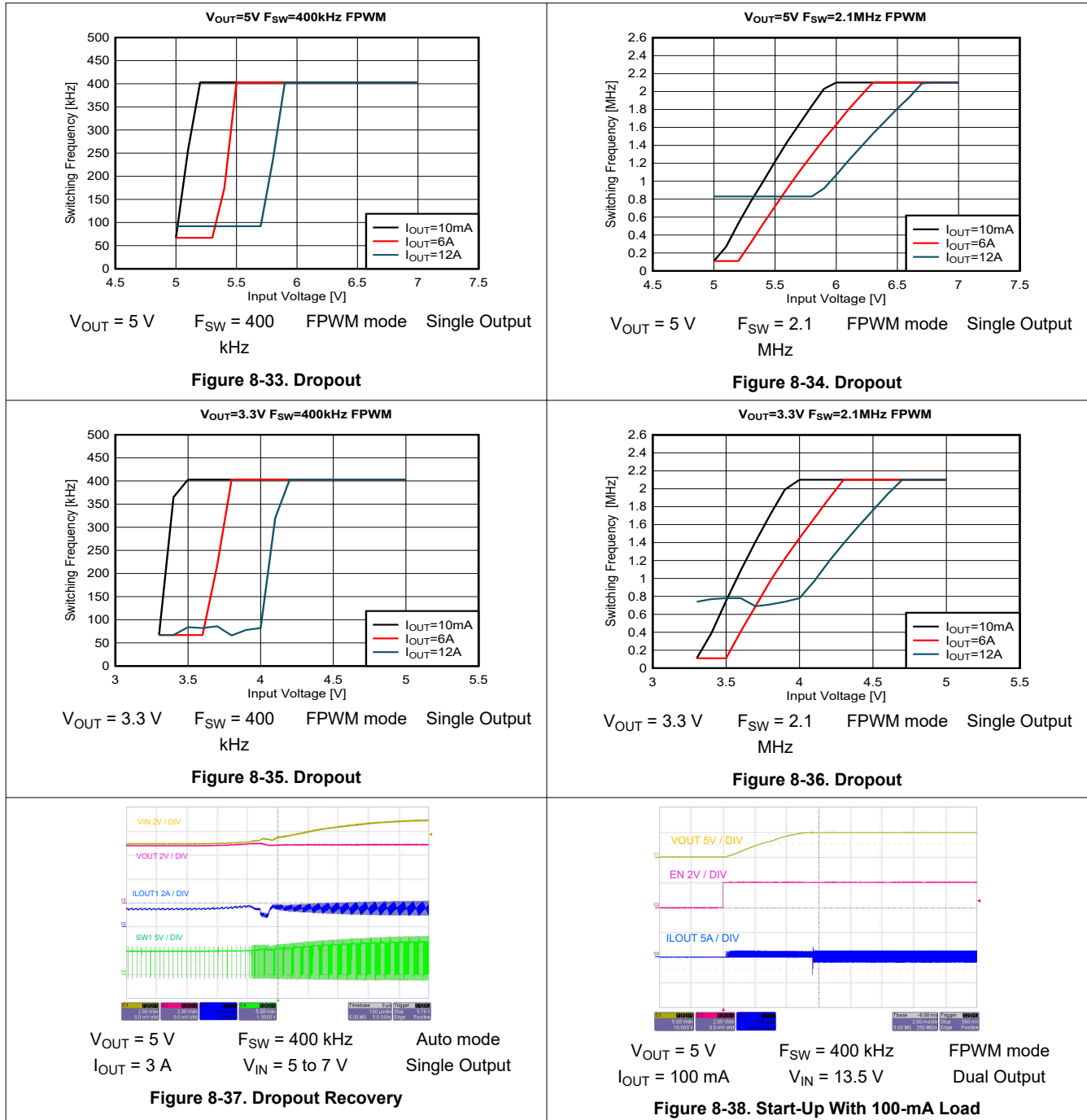


Figure 8-32. Load and Line Regulation

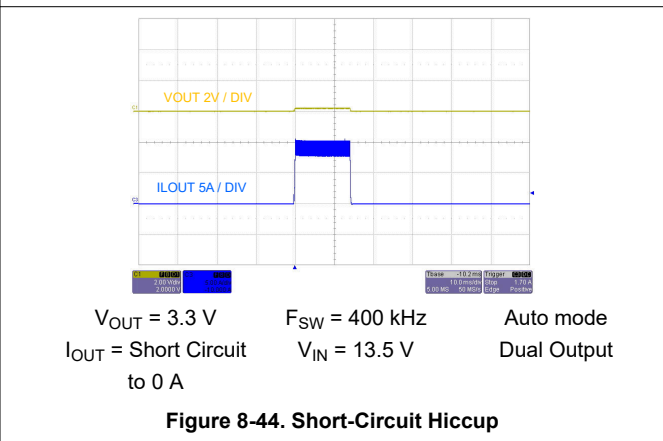
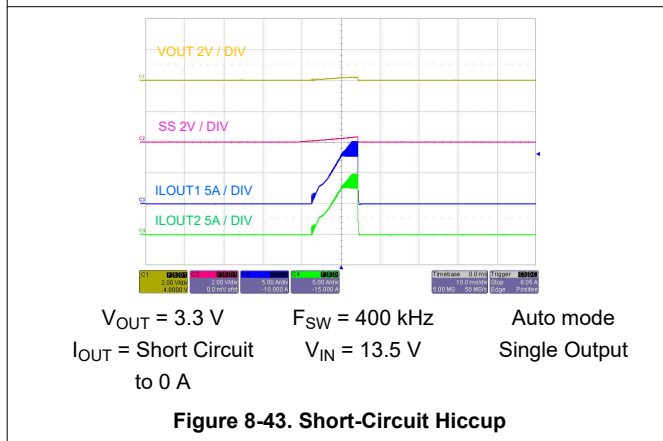
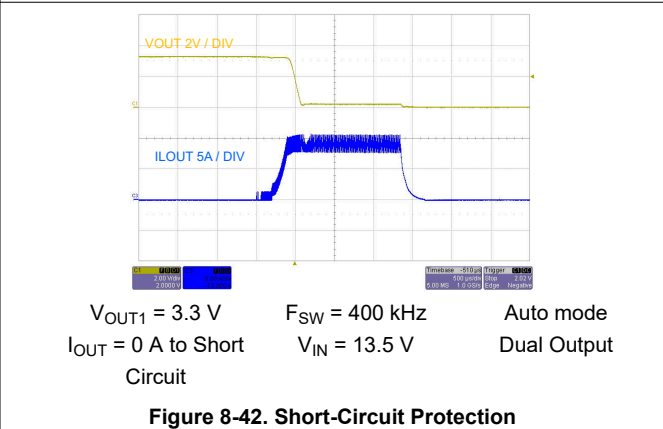
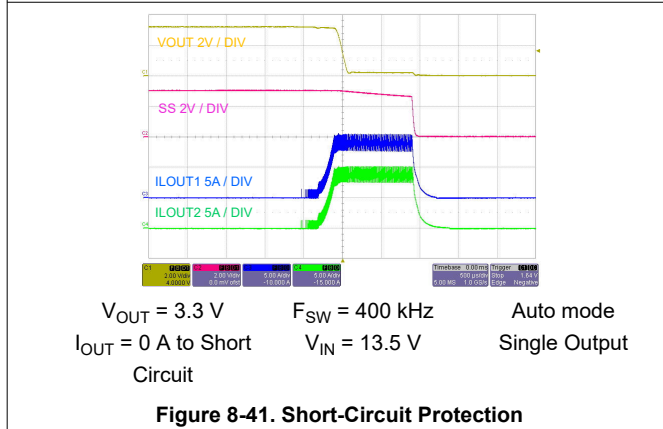
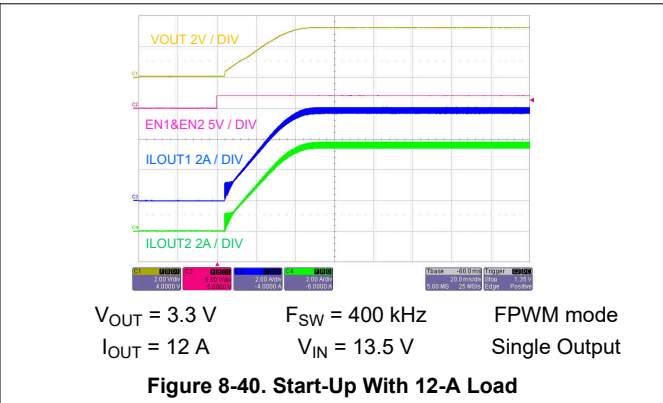
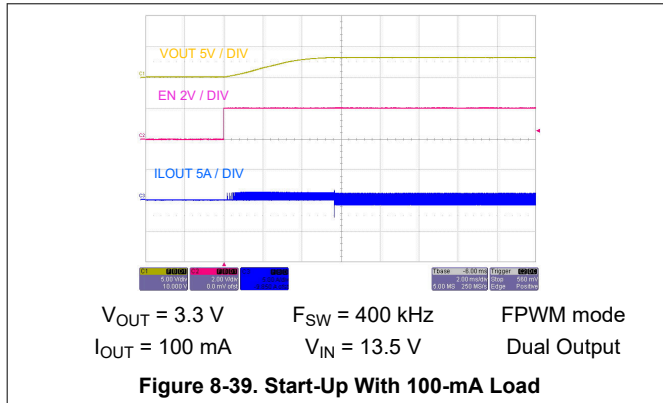
8.2.3 Application Curves (continued)

Unless otherwise specified, the following conditions apply: Device: LMQ644A2, $V_{IN} = 13.5\text{ V}$, $T_A = 25^\circ\text{C}$. The circuit is shown in Figure 8-1, and Figure 8-2 with the appropriate BOM from Table 8-3.



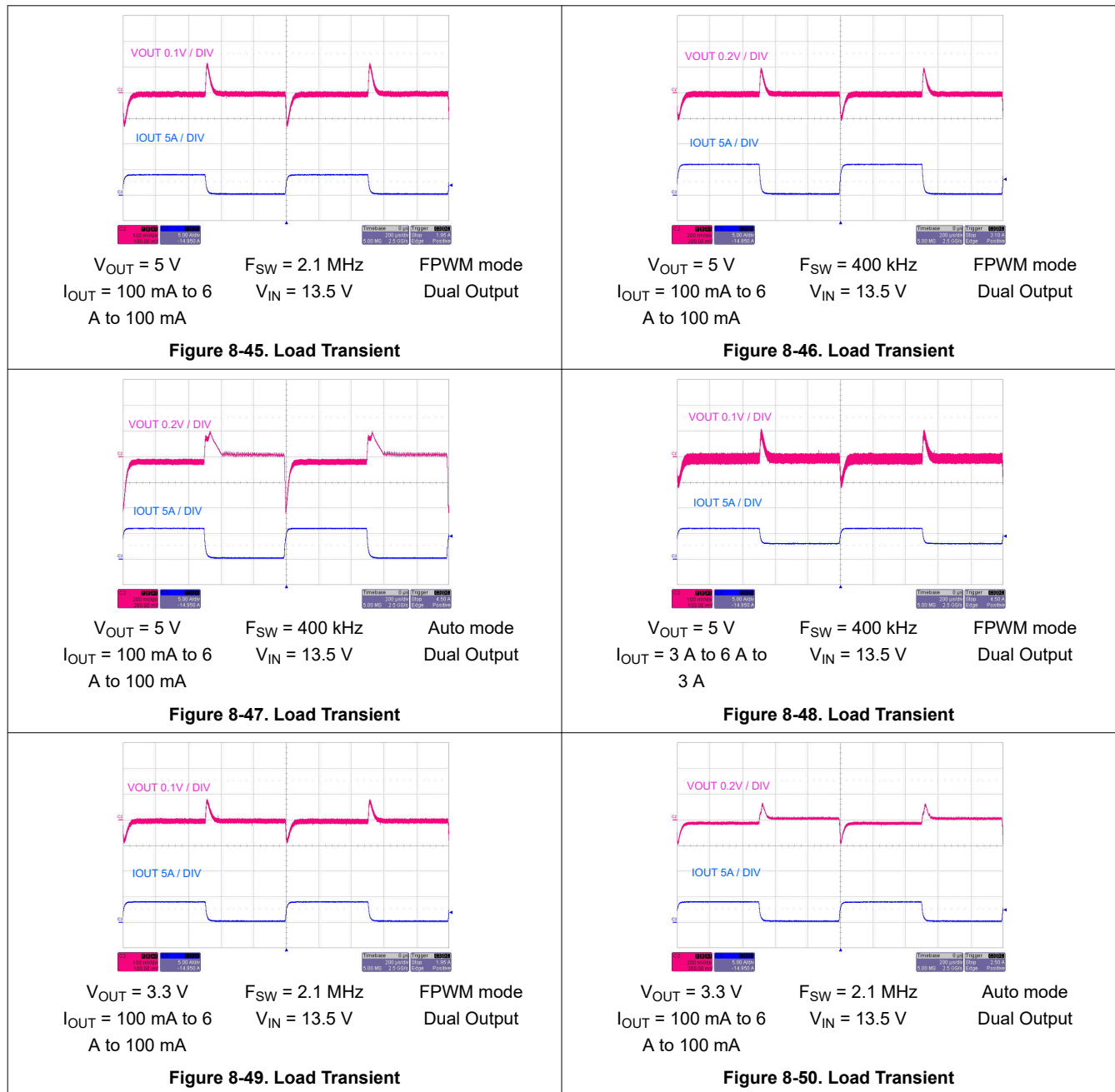
8.2.3 Application Curves (continued)

Unless otherwise specified, the following conditions apply: Device: LMQ644A2, $V_{IN} = 13.5\text{ V}$, $T_A = 25^\circ\text{C}$. The circuit is shown in Figure 8-1, and Figure 8-2 with the appropriate BOM from Table 8-3.



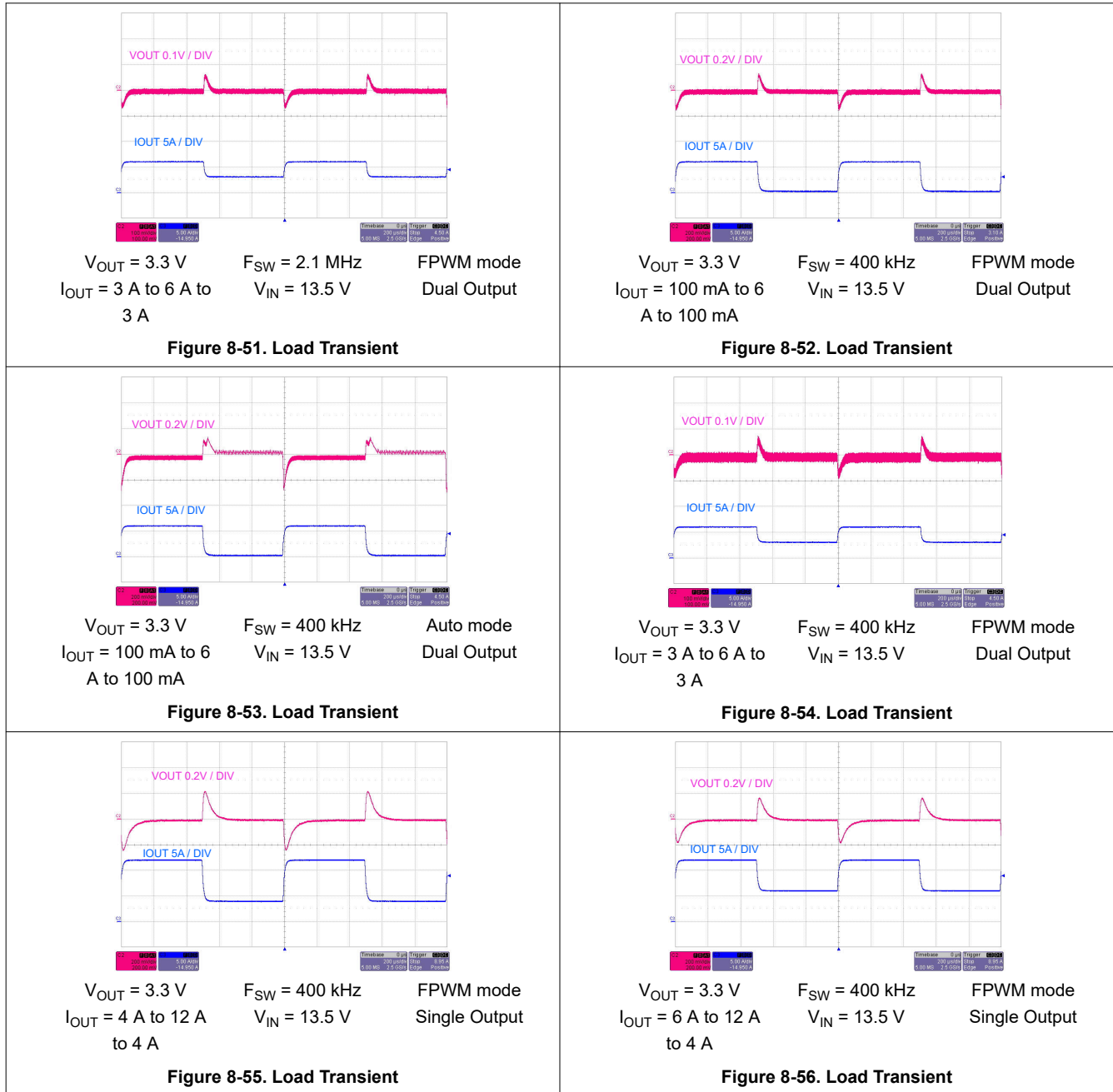
8.2.3 Application Curves (continued)

Unless otherwise specified, the following conditions apply: Device: LMQ644A2, $V_{IN} = 13.5\text{ V}$, $T_A = 25^\circ\text{C}$. The circuit is shown in Figure 8-1, and Figure 8-2 with the appropriate BOM from Table 8-3.



8.2.3 Application Curves (continued)

Unless otherwise specified, the following conditions apply: Device: LMQ644A2, $V_{IN} = 13.5\text{ V}$, $T_A = 25^\circ\text{C}$. The circuit is shown in Figure 8-1, and Figure 8-2 with the appropriate BOM from Table 8-3.



8.2.3 Application Curves (continued)

Unless otherwise specified, the following conditions apply: Device: LMQ644A2, $V_{IN} = 13.5\text{ V}$, $T_A = 25^\circ\text{C}$. The circuit is shown in Figure 8-1, and Figure 8-2 with the appropriate BOM from Table 8-3.

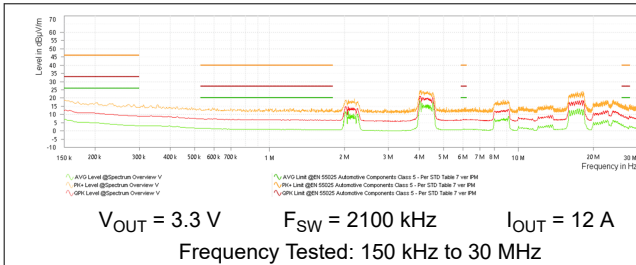


Figure 8-57. Single Output Monopole Radiated Emissions versus CISPR25 Class 5 Limits (Orange: Peak Signal, Red: Average Signal, Green: Quasi-Peak Signal)

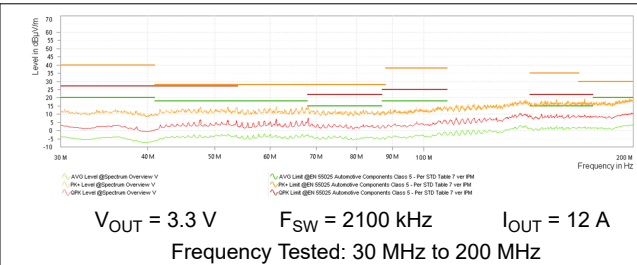


Figure 8-58. Single Output Bicon Radiated Emissions versus CISPR25 Class 5 Limits (Orange: Peak Signal, Red: Average Signal, Green: Quasi-Peak Signal)

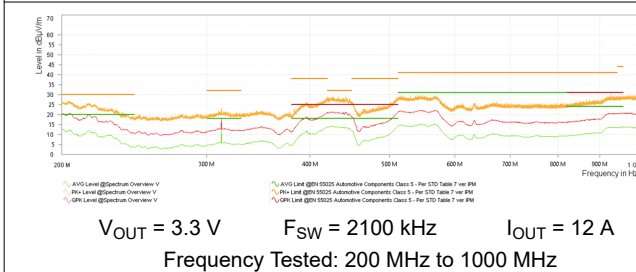


Figure 8-59. Single Output Log Radiated Emissions versus CISPR25 Class 5 Limits (Orange: Peak Signal, Red: Average Signal, Green: Quasi-Peak Signal)

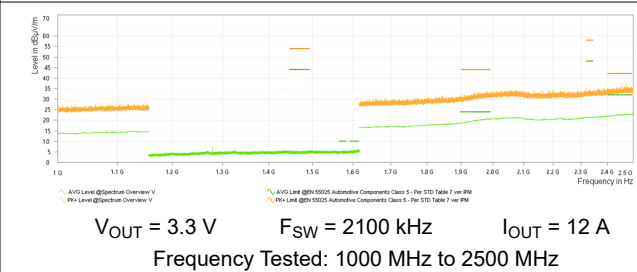


Figure 8-60. Single Output Horn Radiated Emissions versus CISPR25 Class 5 Limits (Orange: Peak Signal, Red: Average Signal, Green: Quasi-Peak Signal)

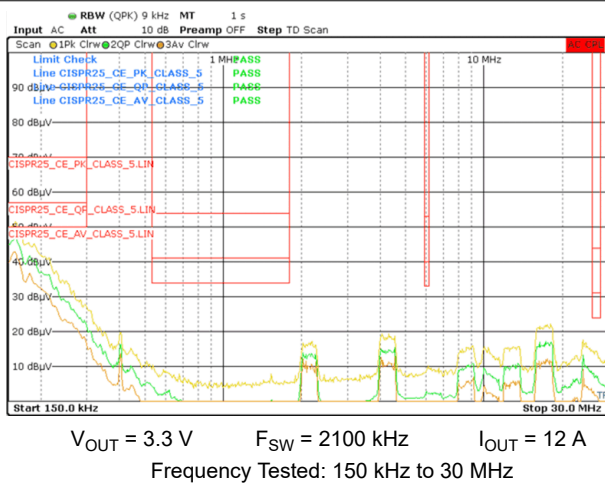


Figure 8-61. Single Output Conducted Emissions versus CISPR25 Class 5 Limits (Orange: Peak Signal, Red: Average Signal, Green: Quasi-Peak Signal)

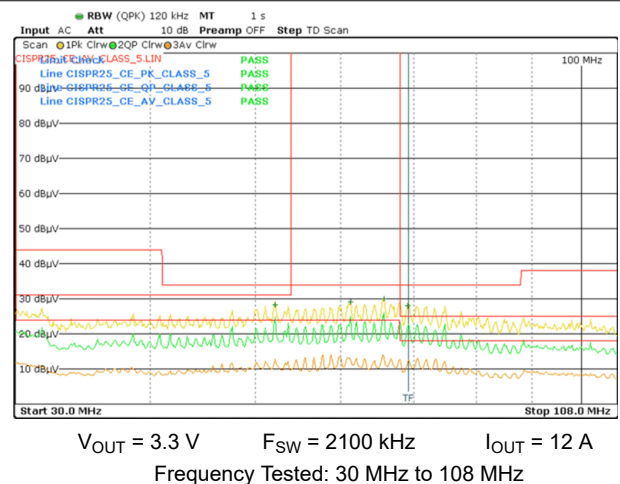


Figure 8-62. Single Output Conducted Emissions versus CISPR25 Class 5 Limits (Orange: Peak Signal, Red: Average Signal, Green: Quasi-Peak Signal)

8.2.3 Application Curves (continued)

Unless otherwise specified, the following conditions apply: Device: LMQ644A2, $V_{IN} = 13.5\text{ V}$, $T_A = 25^\circ\text{C}$. The circuit is shown in Figure 8-1, and Figure 8-2 with the appropriate BOM from Table 8-3.

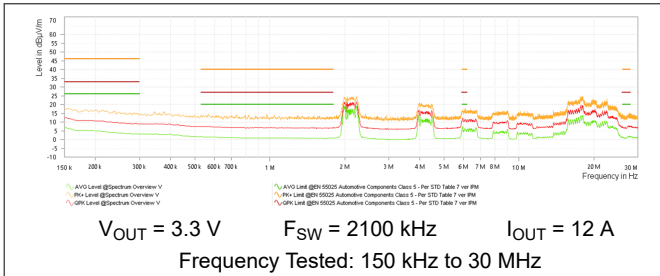


Figure 8-63. Dual Output Monopole Radiated Emissions versus CISPR25 Class 5 Limits (Orange: Peak Signal, Red: Average Signal, Green: Quasi-Peak Signal)

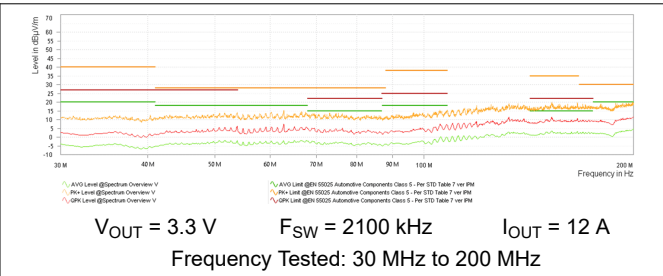


Figure 8-64. Dual Output Bicon Radiated Emissions versus CISPR25 Class 5 Limits (Orange: Peak Signal, Red: Average Signal, Green: Quasi-Peak Signal)

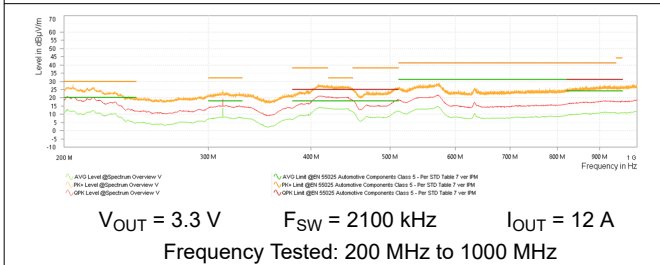


Figure 8-65. Dual Output Log Radiated Emissions versus CISPR25 Class 5 Limits (Orange: Peak Signal, Red: Average Signal, Green: Quasi-Peak Signal)

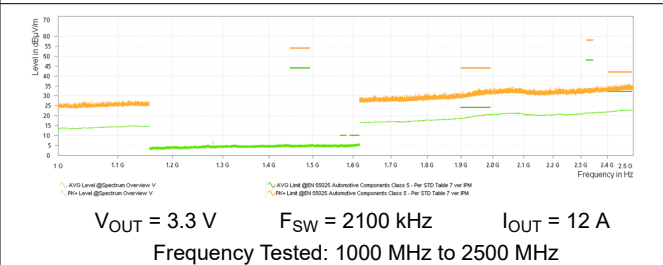


Figure 8-66. Dual Output Horn Radiated Emissions versus CISPR25 Class 5 Limits (Orange: Peak Signal, Red: Average Signal, Green: Quasi-Peak Signal)

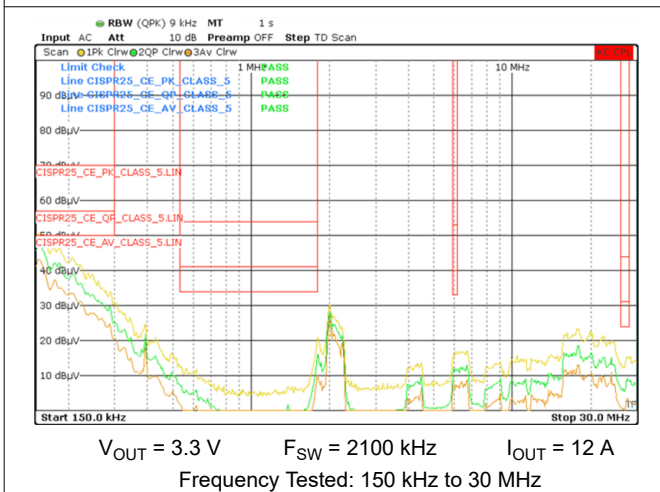


Figure 8-67. Dual Output Conducted Emissions versus CISPR25 Class 5 Limits (Orange: Peak Signal, Red: Average Signal, Green: Quasi-Peak Signal)

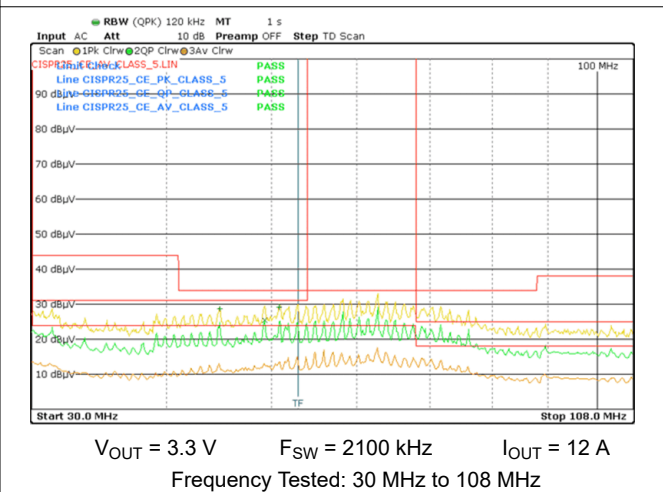


Figure 8-68. Dual Output Conducted Emissions versus CISPR25 Class 5 Limits (Orange: Peak Signal, Red: Average Signal, Green: Quasi-Peak Signal)

8.2.3 Application Curves (continued)

Unless otherwise specified, the following conditions apply: Device: LMQ644A2, $V_{IN} = 13.5\text{ V}$, $T_A = 25^\circ\text{C}$. The circuit is shown in Figure 8-1, and Figure 8-2 with the appropriate BOM from Table 8-3.

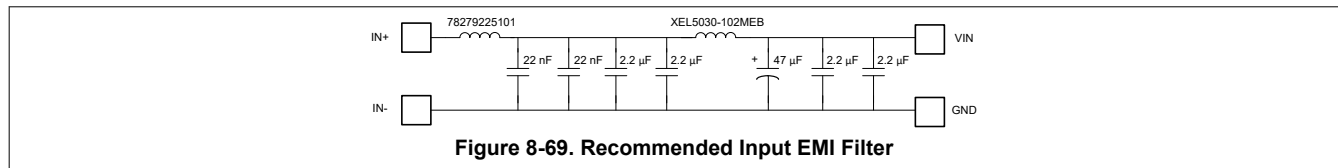


Table 8-3. BOM for Typical Application Curves

V_{OUT}	FREQUENCY	R_{FBB}	C_{OUT} EACH PHASE	$C_{IN} + C_{HF}$ EACH PHASE	L	C_{FF} FOR ADJUSTABLE OUTPUT
3.3 V	400 kHz	32.4 k Ω	47 + 22 μF	2 \times 10 μF + 1 \times 100 nF	2.8 μH	10 pF
3.3 V	2200 kHz	32.4 k Ω	47 + 22 μF	2 \times 10 μF + 1 \times 100 nF	1 μH	10 pF
5 V	400 kHz	19.1 k Ω	47 + 22 μF	2 \times 10 μF + 1 \times 100 nF	2.8 μH	10 pF
5 V	2200 kHz	19.1 k Ω	47 + 22 μF	2 \times 10 μF + 1 \times 100 nF	1 μH	10 pF

8.3 Power Supply Recommendations

The characteristics of the input supply must be capable of delivering the required input current to the loaded regulator. The average input current can be estimated with Equation 10.

$$I_{IN} \cong \frac{I_{OUT}}{\eta} \times \left(\frac{V_{OUT}}{V_{IN}} \right) \quad (10)$$

where

- η is the efficiency

If the regulator is connected to the input supply through long wires or PCB traces, special care is required to achieve good performance. The parasitic inductance and resistance of the input cables can have an adverse effect on the operation of the regulator. The parasitic inductance, in combination with the low-ESR ceramic input capacitors, can form an underdamped resonant circuit. This can result in overvoltage transients at the input to the regulator or tripping UVLO. Consider that the supply voltage can dip when a load transient is applied to the output depending on the parasitic resistance and inductance of the harness and characteristics of the supply. If the application is operating close to the minimum input voltage, this dip can cause the regulator to momentarily shut down and reset. The best way to solve these kinds of issues is to reduce the distance from the input supply to the regulator. Additionally, use an aluminum input capacitor in parallel with the ceramics. The moderate ESR of this type of capacitor helps damp the input resonant circuit and reduce any overshoots or undershoots. A value in the range of 20 μF to 100 μF is usually sufficient to provide input damping and help hold the input voltage steady during large load transients.

In some cases, a transient voltage suppressor (TVS) is used on the input of regulators. One class of this device has a snap-back characteristic (thyristor type). TI does not recommend to use a device with this type of characteristic. When the TVS fires, the clamping voltage falls to a very low value. If this voltage is less than the output voltage of the regulator, the output capacitors discharge through the device back to the input. This uncontrolled current flow can damage the device.

The input voltage must not be allowed to fall below the output voltage. In this scenario, such as a shorted input test, the output capacitors discharge through the internal parasitic diode found between the VIN and SW pins of the device. During this condition, the current can become uncontrolled, possibly causing damage to the device. If this scenario is considered likely, then use a Schottky diode between the input supply and the output.

8.4 Layout

8.4.1 Layout Guidelines

The PCB layout of any DC/DC converter is critical to the optimal performance of the design. Bad PCB layout can disrupt the operation of an otherwise good schematic design. Even if the converter regulates correctly, bad PCB layout can mean the difference between a robust design and one that cannot be mass produced. Furthermore, the EMI performance of the regulator is dependent on the PCB layout to a great extent. In a buck converter, the most EMI-critical PCB feature is the loop formed by the input capacitor or capacitors and power ground. This loop is shown in [Figure 8-70](#). This loop carries large transient currents that can cause large transient voltages when reacting with the trace inductance. Excessive transient voltages can disrupt the proper operation of the converter. Because of this, the traces in this loop must be wide and short while keeping the loop area as small as possible to reduce the parasitic inductance. [Figure 8-71](#) shows a recommended layout for the critical components of the LMQ644xx circuit.

- *Place the input capacitor or capacitors as close as possible to the input pin pairs:* VIN1 to PGND1 and VIN2 to PGND2. Place the small capacitors closest. Each pair of pins are adjacent, simplifying the input capacitor placement. With the QFN package, there are two VIN/PGND pairs on either side of the package. This provides a symmetrical layout and helps minimize switching noise and EMI generation. Use a wide VIN plane on a mid-layer to connect both of the VIN pairs together to the input supply. Route symmetrically from the supply to each VIN pin to best use the benefits of the symmetric pinout.
- *Place the bypass capacitor for VCC close to the VCC pin and AGND pin:* This capacitor must be routed with short, wide traces to the VCC and AGND pins.
- *Place the CBOOT capacitors as close as possible to the device with short, wide traces to the CBOOT and SW pins:* Make sure to route the SW connection with a short wide trace to handle the current, but not longer than necessary to avoid generating common mode noise.
- *Place the feedback divider as close as possible to the FB pin of the device:* Place R_{FBB} , R_{FBT} , C_{FF} if used, and R_{FF} if used, physically close to the device. The connections to FB and AGND through R_{FBB} must be short and close to those pins on the device. The connection to V_{OUT} can be somewhat longer. However, this latter trace must not be routed near any noise source (such as the SW node) that can capacitively couple into the feedback path of the regulator.
- *Make layer 2 of the PCB a ground plane:* This plane acts as a noise shield and as a heat dissipation path. Using layer 2 reduces the enclosed area in the input circulating current in the input loop, reducing inductance.
- *Provide wide paths for V_{IN} , V_{OUT} , and GND:* These paths must be as wide and direct as possible to reduce any voltage drops on the input or output paths of the converter to maximize efficiency.
- *Provide enough PCB area for proper heat sinking:* Enough copper area must be used to make sure a low $R_{\theta JA}$, considering maximum load current and ambient temperature. Make the top and bottom PCB layers with two-ounce copper and no less than one ounce. If the PCB design uses multiple copper layers (recommended), thermal vias can also be connected to the inner layer heat-spreading ground planes. Note that the package of this device dissipates heat through all pins. Wide traces can be used for all pins except where noise considerations dictate minimization of area.
- *Keep the switch area small:* Keep the copper area connecting the SW pin to the inductor as short and wide as possible. At the same time, the total area of this node must be minimized to help reduce radiated EMI.

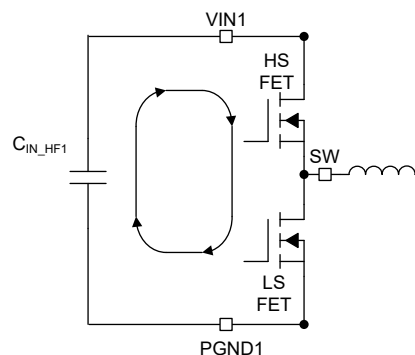


Figure 8-70. Input Current Loop

8.4.1.1 Ground and Thermal Considerations

As mentioned above, TI recommends using one of the middle layers as a solid ground plane. A ground plane provides shielding for sensitive circuits and traces. It also provides a quiet reference potential for the control circuitry. The AGND and PGND pins must be connected to the ground planes using vias next to the bypass capacitors. PGND pins connect directly to the grounds of the input and output capacitors. The PGND net contains noise at the switching frequency and can bounce due to load variations. The PGND trace, as well as the VIN and SW traces, must be constrained to one side of the ground plane. The other side of the ground plane contains much less noise and can be used for sensitive traces.

TI recommends providing adequate device heat sinking by using vias near PGND and VIN pins to connect to the system ground plane or V_{IN} strap, both of which dissipate heat. Use as much copper as possible for the system ground plane on the top and bottom layers and avoid plane cuts and bottlenecks for the heat flow for the best heat dissipation. Use a four-layer board with the copper thickness for the four layers, starting from the top as: 2 oz / 1 oz / 1 oz / 2 oz. A four-layer board with enough copper thickness and proper layout provides low current conduction impedance, proper shielding, and low thermal resistance.

8.4.2 Layout Example

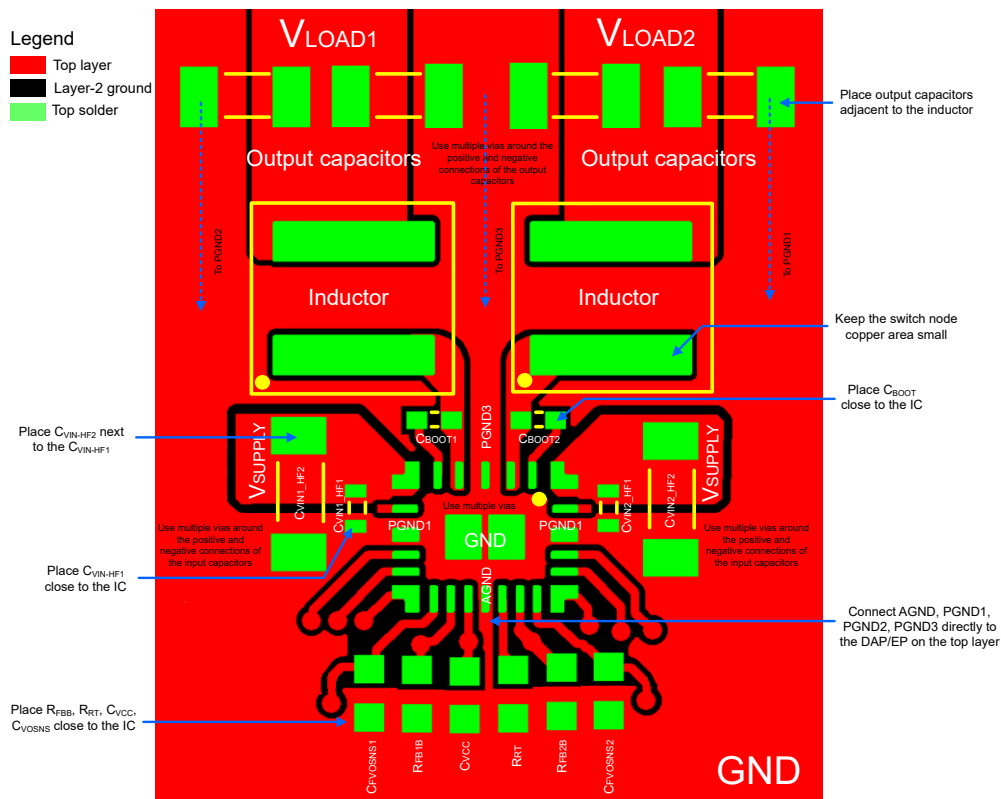


Figure 8-71. Layout Example

9 Device and Documentation Support

9.1 Device Support

9.1.1 Third-Party Products Disclaimer

TI'S PUBLICATION OF INFORMATION REGARDING THIRD-PARTY PRODUCTS OR SERVICES DOES NOT CONSTITUTE AN ENDORSEMENT REGARDING THE SUITABILITY OF SUCH PRODUCTS OR SERVICES OR A WARRANTY, REPRESENTATION OR ENDORSEMENT OF SUCH PRODUCTS OR SERVICES, EITHER ALONE OR IN COMBINATION WITH ANY TI PRODUCT OR SERVICE.

9.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com](https://www.ti.com). Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

9.3 Support Resources

[TI E2E™ support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

9.4 Trademarks

HotRod™ and TI E2E™ are trademarks of Texas Instruments.
All trademarks are the property of their respective owners.

9.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

9.6 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

10 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision * (September 2023) to Revision A (July 2024)	Page
• Added newly released device information for LMQ644A0 and LMQ64408.....	3
• Added missing footnote.....	8

11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
LMQ64480QRXARQ1	ACTIVE	VQFN-FCRLF	RXA	24	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 150	LMQ644 80B	Samples
LMQ644A0QRXARQ1	ACTIVE	VQFN-FCRLF	RXA	24	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 150	LMQ644 A0B	Samples
LMQ644A2QRXARQ1	ACTIVE	VQFN-FCRLF	RXA	24	3000	RoHS (In Work) & Green (In Work)	NIPDAU	Level-2-260C-1 YEAR	-40 to 150	LMQ644 A2B	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSELETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer:The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and

continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to [TI's Terms of Sale](#) or other applicable terms available either on [ti.com](https://www.ti.com) or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2024, Texas Instruments Incorporated