







INA296A. INA296B SBOSA04C - MARCH 2022 - REVISED OCTOBER 2023

INA296x -5 V to 110 V, Bidirectional, 1.1 MHz, 8 V/μs, Ultra-Precise Current Sense **Amplifier**

1 Features

Wide common-mode voltage:

Operational voltage: −5 V to +110 V

Survival voltage: −20 V to +120 V

Bidirectional operation

High small signal bandwidth: 1.1 MHz (at all gains)

Slew rate: 8 V/µs

Step response settling time to 1%: 1 µs

Excellent CMRR: 166 dB

Accuracy:

Gain error (maximum)

Version A: ±0.01%, ±1 ppm/°C drift

Version B: ±0.1%, ±5 ppm/°C drift

Offset voltage (maximum)

Version A: ±10 μV, ±0.1 μV/°C drift

Version B: $\pm 150 \mu V$, $\pm 0.5 \mu V$ /°C drift

Available gains:

– INA296A1, INA296B1 : 10 V/V

– INA296A2, INA296B2 : 20 V/V

– INA296A3, INA296B3 : 50 V/V

– INA296A4, INA296B4: 100 V/V

– INA296A5, INA296B5 : 200 V/V

Package options: SOT23-8, VSSOP-8, SOIC-8, VSSOP-10

2 Applications

- 48-V DC/DC Converter
- 48-V battery management systems (BMS)
- Test & Measurement
- Macro remote radio unit (RRU)
- 48-V rack server
- 48-V merchant network & server power supply (PSU)

3 Description

The INA296x is an ultra-precise, bidirectional current sense amplifier than can measure voltage drops across shunt resistors over a wide common-mode range from -5 V to 110 V, independent of the supply voltage. The high-precision current measurement is achieved through a combination of low offset voltage (±10 μV, maximum), small gain error (±0.01%, maximum) and a high DC CMRR (typical 166 dB). The INA296x is not only designed for high voltage, bidirectional DC current measurements, but also for high-speed applications (such as transient detection and fast overcurrent protection) with a high signal bandwidth of 1.1 MHz and fast settling time.

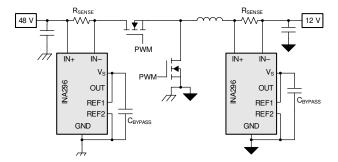
The INA296x operates from a single 2.7 V to 20 V supply, drawing 2.5 mA of supply current. The INA296x is available in five gain options: 10 V/V, 20 V/V, 50 V/V, 100 V/V, and 200 V/V. Multiple gain options allow for optimization between available shunt resistor values and wide output dynamic range requirements.

The INA296x is specified over operating temperature range of -40° C to $+125^{\circ}$ C.

Package Information

| | • | |
|-------------|------------------------|-----------------------------|
| PART NUMBER | PACKAGE ⁽¹⁾ | PACKAGE SIZE ⁽²⁾ |
| | DDF (SOT-23, 8) | 2.90 mm × 2.80 mm |
| INA296A | DGK (VSSOP, 8) | 3.00 mm × 4.90 mm |
| INA296B | D (SOIC, 8) | 4.90 mm × 6.00 mm |
| | DGS (VSSOP, 10) | 3.00 mm × 4.90 mm |

- For all available packages, see the package option addendum at the end of the data sheet.
- The package size (length × width) is a nominal value and (2) includes pins, where applicable.
- (3) Package is preview only



Typical Application - DC/DC Converter



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4 Revision History

| Changes from Revision B (July 2023) to Revision C (October 2023) | Page |
|--|--------------|
| Removed preview note from D package from package information table and throughout th | e data sheet |
| Changes from Revision A (August 2022) to Revision B (July 2023) | Page |
| Added the D and DGS packages to the data sheet | |
| Changed package information from body size to package size | |
| Removed preview note from DGK package from package information table | |
| Added the D and DGS packages pin configuration | |
| Added DGS package in recommended layout examples | |
| | |

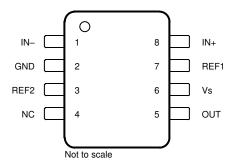


5 Device Comparison

Table 5-1. Device Comparison

| DEVICE NAME | GAIN |
|--------------------|---------|
| INA296A1, INA296B1 | 10 V/V |
| INA296A2, INA296B2 | 20 V/V |
| INA296A3, INA296B3 | 50 V/V |
| INA296A4, INA296B4 | 100 V/V |
| INA296A5, INA296B5 | 200 V/V |

6 Pin Configuration and Functions



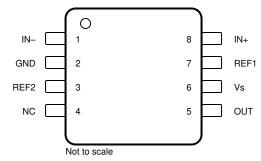


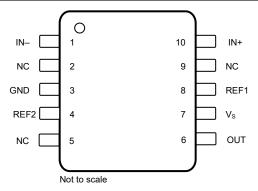
Figure 6-1. INA296x: DDF Package 8-Pin SOT-23
Top View

Figure 6-2. INA296x: D and DGK Package 8-Pin SOIC and 8-Pin VSSOP Top View

Table 6-1. Pin Functions: D, DDF and DGK Packages

| PIN | | TYPE | DESCRIPTION |
|------|-----|--------|---|
| NAME | NO. | 1175 | DESCRIPTION |
| GND | 2 | Ground | Ground |
| IN+ | 8 | Input | Current-sense amplifier positive input. For high-side applications, connect to bus-voltage side of sense resistor. For low-side applications, connect to load side of sense resistor. |
| IN- | 1 | Input | Current-sense amplifier negative input. For high-side applications, connect to load side of sense resistor. For low-side applications, connect to ground side of sense resistor. |
| NC | 4 | Ground | Reserved. Connect to ground. |
| OUT | 5 | Output | Output voltage |
| REF1 | 7 | Input | Reference 1 voltage. Connect to voltage potential from 0 V to V _S ; see <i>Adjusting the Output With the Reference Pins</i> for connection options. |
| REF2 | 3 | Input | Reference 2 voltage. Connect to voltage potential from 0 V to V _S ; see <i>Adjusting the Output With the Reference Pins</i> for connection options. |
| Vs | 6 | Power | Power supply, 2.7 V to 20 V |





Note: The DGS (VSSOP) package is preview only.

Figure 6-3. INA296x: DGS Package 10-Pin VSSOP Top View

Table 6-2. Pin Functions: DGS Package

| | Table 0-2. I III I unctions. DOS I acrage | | | | | |
|------|---|--------|---|--|--|--|
| PIN | | TYPE | DESCRIPTION | | | |
| NAME | NO. | 1112 | DESCRIPTION | | | |
| GND | 3 | Ground | Ground | | | |
| IN+ | 10 | Input | Current-sense amplifier positive input. For high-side applications, connect to bus-voltage side of sense resistor. For low-side applications, connect to load side of sense resistor. | | | |
| IN- | 1 | Input | ent-sense amplifier negative input. For high-side applications, connect to load side of se resistor. For low-side applications, connect to ground side of sense resistor. | | | |
| NC | 5 | Ground | Reserved. Connect to ground. | | | |
| NC | 2 | _ | Leave unconnected | | | |
| NC | 9 | _ | Leave unconnected | | | |
| OUT | 6 | Output | Output voltage | | | |
| REF1 | 8 | Input | Reference 1 voltage. Connect to voltage potential from 0 V to V _S ; see <i>Adjusting the Output With the Reference Pins</i> for connection options. | | | |
| REF2 | 4 | Input | Reference 2 voltage. Connect to voltage potential from 0 V to V_S ; see <i>Adjusting the Output With the Reference Pins</i> for connection options. | | | |
| Vs | 7 | Power | Power supply, 2.7 V to 20 V | | | |

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7 Specifications

7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)(1)

| | | MIN | MAX | UNIT |
|---|--|-----------|----------------------|------|
| Supply voltage (V _S) | | | 22 | V |
| Analog inputs, | Differential (V _{IN+}) - (V _{IN-}) | -30 | 30 | V |
| V _{IN+} , V _{IN-} (2) | Common-mode | -20 | 120 | V |
| REF1, REF2, NC inputs | | GND - 0.3 | V _S + 0.3 | V |
| Output | | GND - 0.3 | Vs + 0.3 | V |
| T _A | Operating temperature | -55 | 150 | °C |
| T _J | Junction temperature | | 150 | °C |
| T _{stg} | Storage temperature | -65 | 150 | °C |

⁽¹⁾ Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

7.2 ESD Ratings

| | | | VALUE | UNIT |
|--------------------|-------------------------|---|-------|------|
| V | Electrostatic discharge | Human body model (HBM), per ANSI/ESDA/ JEDEC JS-001, all pins ⁽¹⁾ | ±2000 | V |
| V _(ESD) | Electrostatic discrarge | Charged device model (CDM), per ANSI/ESDA/ JEDEC JS-002, all pins ⁽²⁾ | ±1000 | V |

⁽¹⁾ JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

| | | MIN | NOM | MAX | UNIT |
|-----------------|-------------------------|-----|-----|-----|------|
| V _{CM} | Common-mode input range | -5 | 48 | 110 | V |
| Vs | Operating supply range | 2.7 | 5 | 20 | V |
| T _A | Ambient temperature | -40 | | 125 | °C |

7.4 Thermal Information

| | | INA296x | | | | |
|-----------------------|--|-------------|-------------|----------|----------------|------|
| THERMAL METRIC(1) | | DDF (SOT23) | DGK (VSSOP) | D (SOIC) | DGS (VSSOP)(2) | UNIT |
| | | 8 PINS | 8 PINS | 8 PINS | 10 PINS | |
| R _{0JA} | Junction-to-ambient thermal resistance | 129.7 | 167.2 | 122.9 | TBD | °C/W |
| R _{0JC(top)} | Junction-to-case (top) thermal resistance | 58 | 58.9 | 54.7 | TBD | °C/W |
| $R_{\theta JB}$ | Junction-to-board thermal resistance | 52.6 | 88.9 | 68.8 | TBD | °C/W |
| Ψ_{JT} | Junction-to-top characterization parameter | 2.3 | 8.1 | 12.2 | TBD | °C/W |
| Ψ_{JB} | Junction-to-board characterization parameter | 52.3 | 87.4 | 67.5 | TBD | °C/W |

⁽¹⁾ For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

⁽²⁾ V_{IN+} and V_{IN-} are the voltages at the IN+ and IN- pins, respectively.

⁽²⁾ JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



(2) This package is preview only.

7.5 Electrical Characteristics

 $\underline{\text{at T}_{\text{A}} = 25 \text{ °C, V}_{\text{S}} = 5 \text{ V, V}_{\text{SENSE}} = V_{\text{IN+}} - V_{\text{IN-}}, V_{\text{CM}} = V_{\text{IN-}} = 48 \text{ V, and V}_{\text{REF1}} = V_{\text{REF2}} = V_{\text{S}} \text{ / 2 (unless otherwise noted)} }$

| at 1 _A 2 | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT | |
|----------------------|--|---|-----|-------|-------|-------|--|
| INPUT | | | | | | | |
| V _{CM} | Common-mode input range ⁽¹⁾ | V_{IN+} , $V_{IN-} = -5$ V to 110 V, $V_{SENSE} = 0$ mV $T_A = -40$ °C to 125°C | -5 | | 110 | V | |
| | | V_{IN+} , $V_{IN-} = -5$ V to 110 V, $V_{SENSE} = 0$ mV $T_A = -40$ °C to 125°C, INA296A | 150 | 166 | | | |
| CMRR | Common-mode rejection ratio, input- referred | V_{IN+} , $V_{IN-} = -5$ V to 110 V, $V_{SENSE} = 0$ mV $T_A = -40$ °C to 125°C, INA296B | 120 | 130 | | dB | |
| | | f = 50 kHz | | 105 | | | |
| | | V _{SENSE} = 0 mV, INA296A1 | | ±5 | ±20 | | |
| V _{os} | | V _{SENSE} = 0 mV, INA296A2 | | ±3 | ±15 | | |
| | Offset voltage, input-referred | V _{SENSE} = 0 mV, INA296A3, INA296A4 | | ±3 | ±10 | μV | |
| | | V _{SENSE} = 0 mV, INA296A5 | | ±2 | ±8 | | |
| | | V _{SENSE} = 0 mV, INA296B | | ±25 | ±150 | | |
| | | T _A = -40°C to 125°C, INA296A1 | | ±50 | ±250 | | |
| | | T _A = -40°C to 125°C, INA296A2 | | ±30 | ±150 | nV/°C | |
| dV _{os} /dT | Offset voltage drift, input-referred | T _A = -40°C to 125°C, INA296A3, INA296A4, INA296A5 | | ±20 | ±100 | | |
| | | T _A = -40°C to 125°C, INA296B | | ±100 | ±500 | | |
| | | $V_S = 2.7 \text{ V to } 20 \text{ V, } V_{SENSE} = 0 \text{ mV,}$ $V_{REF1} = V_{REF2} = 1 \text{ V,}$ $T_A = -40 ^{\circ}\text{C to } 125 ^{\circ}\text{C, INA296A1}$ | | ±0.2 | ±1 | | |
| | | $V_S = 2.7 \text{ V to } 20 \text{ V, } V_{SENSE} = 0 \text{ mV,}$ $V_{REF1} = V_{REF2} = 1 \text{ V,}$ $V_A = -40 ^{\circ}\text{C to } 125 ^{\circ}\text{C, INA296A2}$ | | ±0.1 | ±0.75 | μV/V | |
| PSRR | Power-supply rejection ratio, input- referred | $V_S = 2.7 \text{ V to } 20 \text{ V, } V_{SENSE} = 0 \text{ mV,}$ $V_{REF1} = V_{REF2} = 1 \text{ V,}$ $T_A = -40^{\circ}\text{C} \text{ to } 125^{\circ}\text{C, INA296A3,}$ INA296A4, INA296A5 | | ±0.06 | ±0.5 | | |
| | | $V_S = 2.7 \text{ V to } 20 \text{ V, } V_{SENSE} = 0 \text{ mV,}$ $V_{REF1} = V_{REF2} = 1 \text{ V,}$ $T_A = -40 ^{\circ}\text{C to } 125 ^{\circ}\text{C, INA296B}$ | | ±1 | ±10 | | |
| I _B | Input bias current | I _{B+} , I _{B-} , V _{SENSE} =0 mV | 25 | 35 | 45 | uA | |
| | Reference input range | | 0 | | Vs | V | |
| OUTPUT | | | | | | | |
| | | A1, B1 Devices | | 10 | | V/V | |
| | | A2, B2 Devices | | 20 | | V/V | |
| G | Gain | A3, B3 Devices | 50 | | | V/V | |
| | | A4, B4 Devices | | 100 | V/V | | |
| | | A5, B5 Devices | | 200 | | V/V | |

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| | PARAMETER | TEST CONDITIONS | MIN TYP | MAX | UNIT | |
|------------------|---|---|-----------------------|----------------------|--------|--|
| | | (GND + 50 mV) < V _{OUT} < (V _S - 200 mV), INA296A1, INA296A2, INA296A3 | ±0.002 | ±0.01 | | |
| | Gain Error | (GND + 50 mV) < V _{OUT} < (V _S - 200 mV), INA296A4, INA296A5 | ±0.003 | ±0.015 | % | |
| G | | (GND + 50 mV) < V _{OUT} < (V _S - 200 mV), INA296B | ±0.02 | ±0.1 | | |
| G _{ERR} | | T _A = -40°C to +125°C, INA296A1, INA296A2, INA296A3 | ±0.05 | ±1 | | |
| | Gain Error Drift | T _A = -40°C to +125°C, INA296A4, INA296A5 | ±0.1 | ±2 | ppm/°C | |
| | | T _A = -40°C to +125°C, INA296B | ±0.2 | ±5 | | |
| | Non-Linearity Error | | ±0.001 | | % | |
| | Maximum Capacitive Load | No sustained oscillations, No isolation resistor | 1 | | nF | |
| VOLTAG | SE OUTPUT | | | | | |
| | Swing to V _S Power Supply Rail | R_L = 10 kΩ to GND, T_A = -40°C to +125°C | V _S - 0.07 | V _S - 0.2 | V | |
| | Swing to Ground | $R_L = 10 \text{ k}\Omega \text{ to GND, } V_{SENSE} = 0$ mV, $V_{REF1} = V_{REF2} = 0 \text{ V,}$ $T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$ | 8 | 20 | mV | |
| REFERE | NCE INPUT | | | | | |
| | | V _{REF1} = V _{REF2} = 0.5 V to 4.5 V, T _A = -40°C to +125°C, INA296A1, | ±1 | ±2.5 | | |
| RVRR | Reference voltage rejection ratio, input- referred | V _{REF1} = V _{REF2} = 0.5 V to 4.5 V, T _A = -40°C to +125°C, INA296A2, INA296A3, INA296A4, INA296A5 | ±0.5 | ±1.5 | μV/V | |
| | | V _{REF1} = V _{REF2} = 0.5 V to 4.5 V, T _A = -40°C to +125°C, INA296B | ±10 | ±20 | | |
| | | $\begin{aligned} &V_{OUT} = (V_{REF1} + V_{REF2}) \ / \ 2 \ at \ V_{SENSE} = 0 \\ &mV, \\ &V_{REF1} = V_S, \ V_{REF2} = GND \\ &V_{REF1} = GND, \ V_{REF2} = V_S \\ &T_A = -40^{\circ}C \ to + 125^{\circ}C, \ INA296A1, \\ &INA296A2, \end{aligned}$ | ±0.002 | ±0.005 | | |
| | Reference divider accuracy | $\begin{aligned} &V_{OUT} = (V_{REF1} + V_{REF2}) \ / \ 2 \ at \ V_{SENSE} = 0 \\ &mV, \\ &V_{REF1} = V_S, \ V_{REF2} = GND \\ &V_{REF1} = GND, \ V_{REF2} = V_S \\ &T_A = -40^{\circ}C \ to \ +125^{\circ}C, \ INA296A3, \\ &INA296A4, \ INA296A5 \end{aligned}$ | ±0.002 | ±0.01 | % | |
| | | $V_{OUT} = (V_{REF1} + V_{REF2}) / 2$ at $V_{SENSE} = 0$ mV, $V_{REF1} = V_S$, $V_{REF2} = GND$ $V_{REF1} = GND$, $V_{REF2} = V_S$ $T_A = -40^{\circ}C$ to +125 $^{\circ}C$, INA296B | ±0.02 | ±0.15 | | |
| FREQUI | ENCY RESPONSE | | | | | |
| BW | Bandwidth | All Gains, -3dB Bandwidth | 1.1 | | MHz | |
| | | $V_{\text{IN+}}$, $V_{\text{IN-}}$ = 48 V, V_{OUT} = 0.5 V to 4.5 V, Output settles to 0.5% | 1.5 | | μs | |
| | Settling time | $V_{\text{IN+}}$, $V_{\text{IN-}}$ = 48 V, V_{OUT} = 0.5 V to 4.5 V, Output settles to 1% | 1 | | μs | |
| | | $V_{\text{IN+}}$, $V_{\text{IN-}}$ = 48 V, V_{OUT} = 0.5 V to 4.5 V, Output settles to 5% | 0.5 | | μs | |
| SR | Slew Rate | Rising | 8 | | V/µs | |

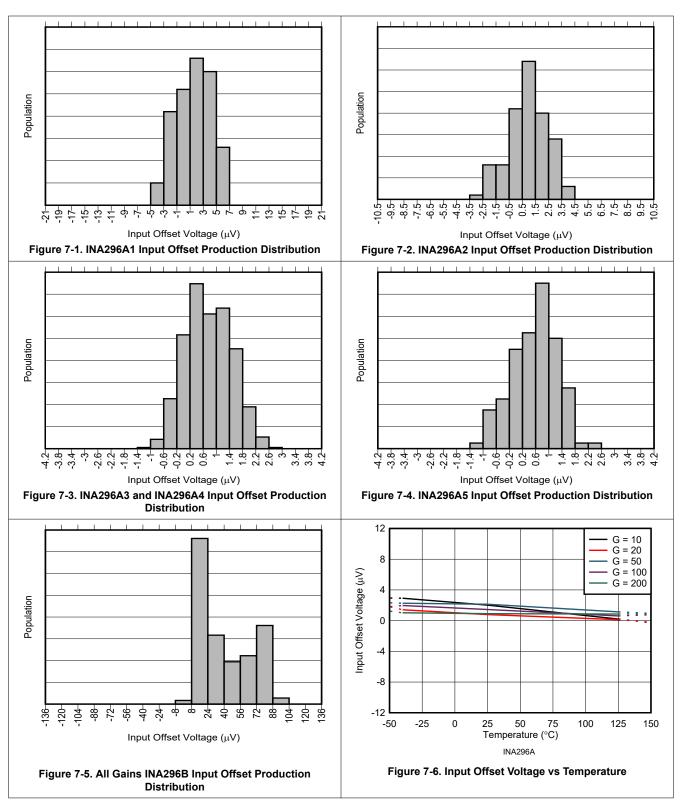


| | PARAMETER | TEST CONDITIONS | MIN TYP | MAX | UNIT |
|----------------|-----------------------|--|---------|-----|--------|
| NOISE | E (Input referred) | | | | |
| | | A1, B1 Devices | 62 | | |
| | | A2, B2 Devices | 49 | | |
| | Voltage noise density | A3, B3 Devices | 39 | | nV/√Hz |
| | | A4, B4 Devices | 36 | | |
| | | A5, B5 Devices | 28 | | |
| POWE | ER SUPPLY | | | · | |
| Vs | Supply Voltage | | 2.7 | 20 | V |
| | | V _{SENSE} = 0 mV | 2.5 | 3 | mA |
| IQ | Quiescent current | $V_{SENSE} = 0 \text{ mV},$ $T_A = -40^{\circ}\text{C to+}125^{\circ}\text{C}$ | | 3.2 | mA |
| TEMP | ERATURE | | · | | |
| T _A | Specified Range | | -40 | 125 | °C |

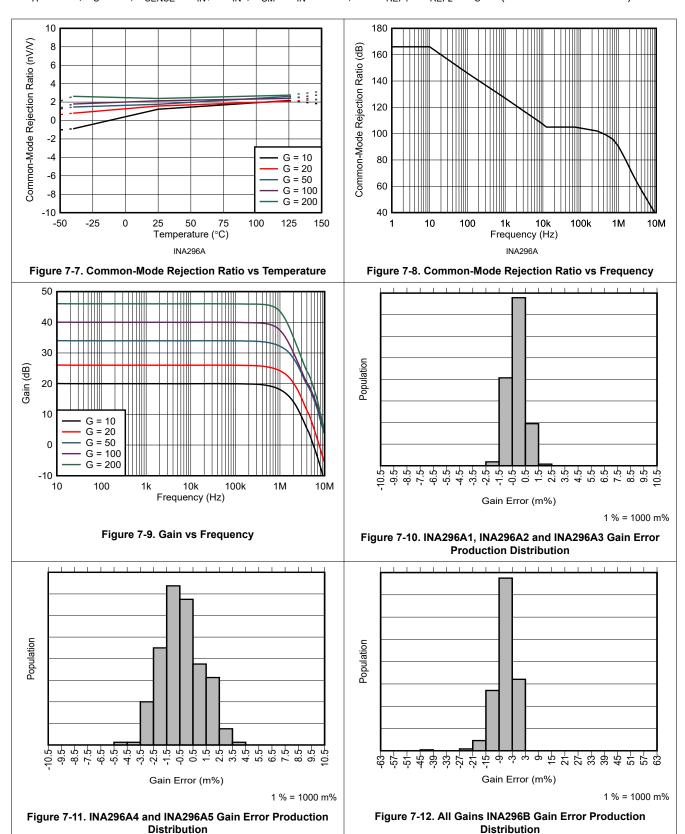
Common-mode voltage at both $V_{\text{IN-}}$ and $V_{\text{IN-}}$ must not exceed the specified common-mode input range.



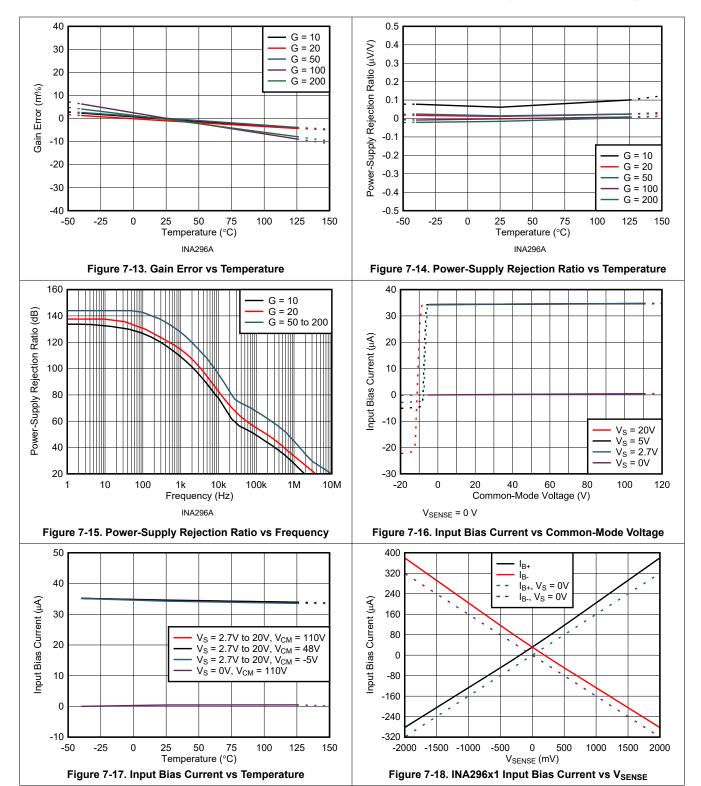
7.6 Typical Characteristics



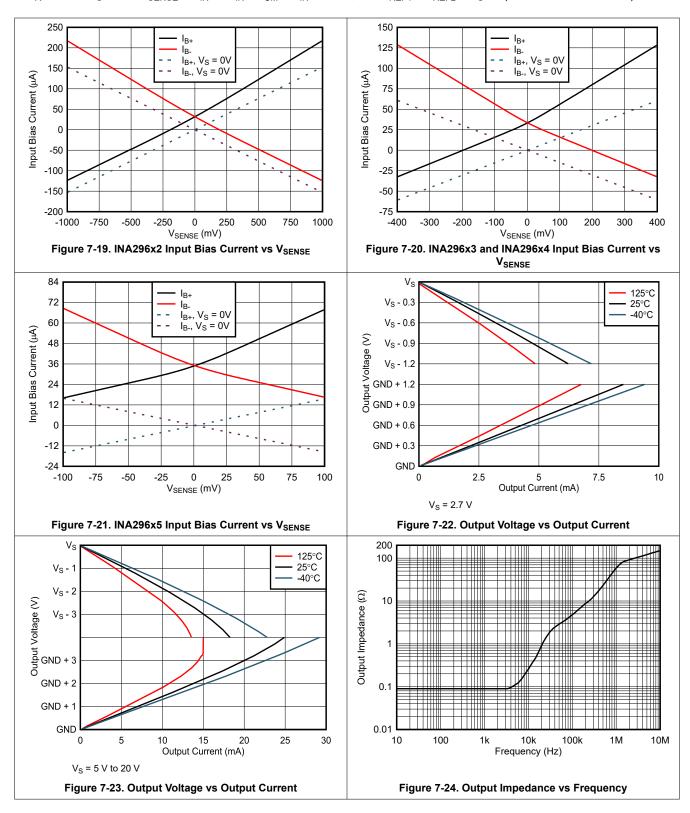




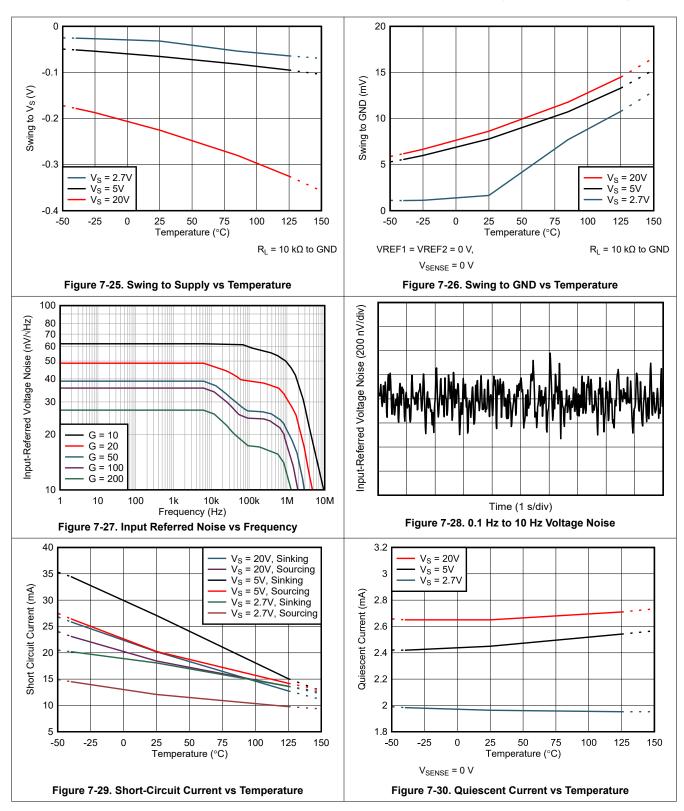




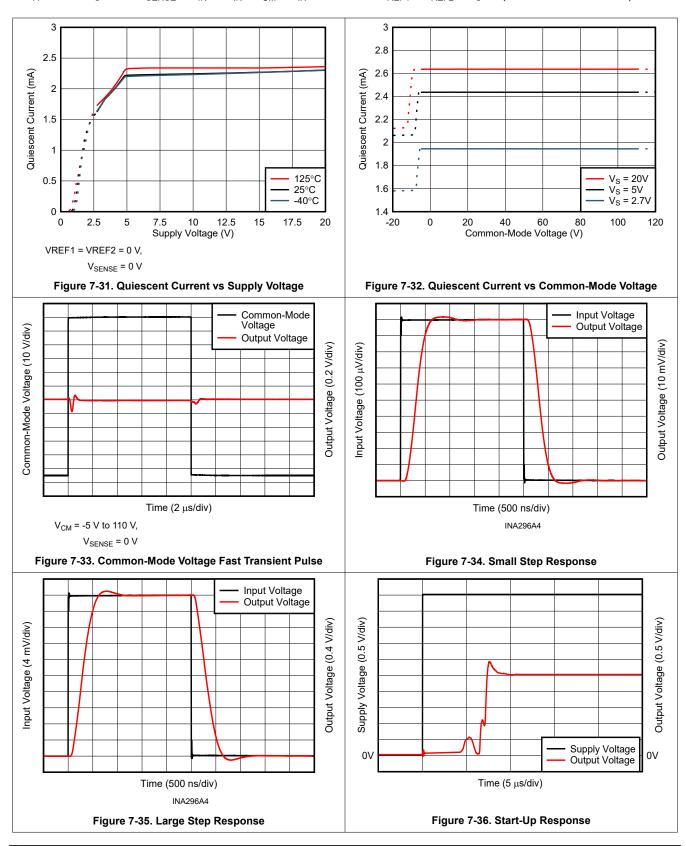




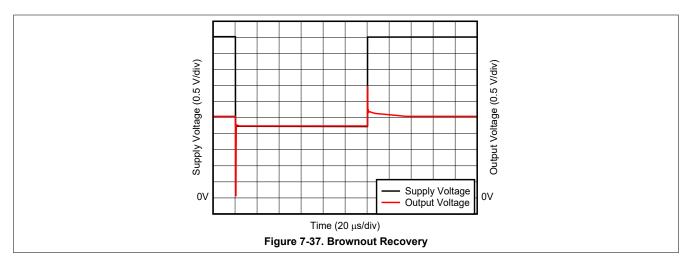










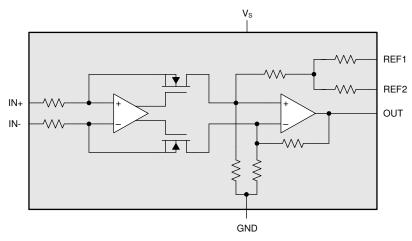


8 Detailed Description

8.1 Overview

The INA296x is a high-side, inline, or low-side bidirectional, high-speed current-sense amplifier that offers a wide common-mode range, precision zero-drift topology, excellent common-mode rejection ratio (CMRR) and fast slew rate. Different gain versions are available to optimize the output dynamic range based on the application. The INA296x is designed using an architecture that enables low bias currents of 35 µA with a specified common-mode voltage range from –5 V to 110 V with signal bandwidths up to 1.1 MHz.

8.2 Functional Block Diagram



8.3 Feature Description

8.3.1 Amplifier Input Common-Mode Signal

The INA296x supports large input common-mode voltages from -5 V to +110 V. The internal topology of the INA296x allows the common-mode range to exceed the power-supply voltage (V_S). This allows for the INA296x to be used for low-side, inline, and high-side current-sensing applications that extend beyond the supply range of 2.7 V to 20 V.

8.3.1.1 Input-Signal Bandwidth

The INA296x is available with several gain options including 10 V/V, 20 V/V, 50 V/V, 100 V/V, and 200 V/V. The unique multistage design enables the amplifier to achieve high bandwidth of 1.1 MHz at all gains. This high bandwidth provides the throughput and fast response that is required for the rapid detection and processing of over-current events.

8.3.1.2 Low Input Bias Current

The INA296x inputs draw $35 \mu A$ (typical) bias current per input pin at common-mode voltages as high as 110 V, which enables precision current sensing on applications that require lower current leakage. Unlike many high voltage current sense amplifiers whose input bias currents are proportional to the common-mode voltage, the input bias current of the INA296x remains constant over the entire common-mode voltage range.

8.3.1.3 Low V_{SENSE} Operation

The INA296x features high performance operation across the entire valid V_{SENSE} range. The zero-drift input architecture of the INA296x provides the low offset voltage and low offset drift needed to measure low V_{SENSE} levels accurately across the wide operating temperature of -40° C to $+125^{\circ}$ C. Low V_{SENSE} operation is particularly beneficial when using low ohmic shunts for low current measurements, as power losses across the shunt are significantly reduced.

8.3.1.4 Wide Fixed Gain Output

The INA296x maximum gain error is ±0.01% at room temperature, with a maximum drift of ±1 ppm/°C over the full temperature range of –40°C to +125°C. The INA296x is available in multiple gain options of 10 V/V, 20 V/V, 50 V/V, 100 V/V, and 200 V/V, which the system designer should select based on their desired signal-to-noise ratio and other system requirements, such as the dynamic current range and full-scale output voltage target.

8.3.1.5 Wide Supply Range

The INA296x operates with a wide supply range from 2.7 V to 20 V. While the input common-mode voltage range of the INA296x is independent of the supply voltage, the output voltage is bound by the supply voltage applied to the device. The output voltage can range from as low as 20 mV to as high as 200 mV below the supply voltage.

8.4 Device Functional Modes

8.4.1 Adjusting the Output With the Reference Pins

Figure 8-1 shows a test circuit for reference-divider accuracy. The INA296x output is configurable to allow for unidirectional or bidirectional operation.

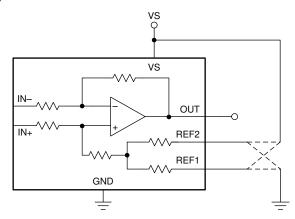


Figure 8-1. Test Circuit For Reference Divider Accuracy

The output voltage is set by applying a voltage or voltages to the reference voltage inputs, REF1 and REF2. The reference inputs are connected to an internal gain network. There is no operational difference between the two reference pins. The resistor network connected to the two reference pins are designed with ultra-precision and matching. Output is set accurately at the mid-point voltage between the voltages applied to reference voltage inputs, when current-sense input voltage is 0 V as shown in Equation 1. In most bidirectional applications, one reference input is connected to the positive supply and the other reference input is connected to the negative supply (GND pin) to set the output voltage to mid-supply.

$$V_{OUT} = G \times (V_{IN} + V_{IN}) + \frac{V_{REF1} + V_{REF2}}{2}$$
 (1)

8.4.2 Reference Pin Connections for Unidirectional Current Measurements

Unidirectional operation allows current measurements through a resistive shunt in one direction. For unidirectional operation, connect the device reference pins together and then to the negative rail (see the *Ground Referenced Output* section) or the positive rail (see the *VS Referenced Output* section). The required differential input polarity depends on the reference input setting. The amplifier output moves away from the referenced rail proportional to the current passing through the external shunt resistor. If the amplifier reference pins are connected to the positive rail, then the input polarity must be negative to move the amplifier output down (towards ground). If the amplifier reference pins are connected to ground, then the input polarity must be positive to move the amplifier output up (towards supply).

The following sections describe how to configure the output for unidirectional operation cases.

8.4.2.1 Ground Referenced Output

When using the INA296x in a unidirectional mode with a ground referenced output, both reference inputs are connected to ground. This configuration takes the output to ground when there is a 0 V differential at the input (see Figure 8-2).

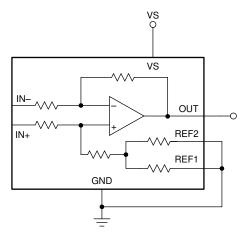


Figure 8-2. Ground Referenced Output

8.4.2.2 VS Referenced Output

Unidirectional mode with a VS referenced output is configured by connecting both reference pins to the positive supply. Use this configuration for circuits that require power up and stabilization of the amplifier output signal and other control circuitry before power is applied to the load (see Figure 8-3).

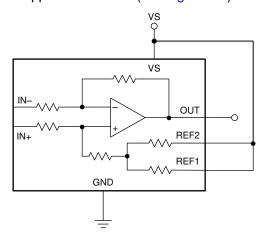


Figure 8-3. VS Referenced Output

8.4.3 Reference Pin Connections for Bidirectional Current Measurements

The INA296x measures the differential voltage developed by current flowing through a resistor, commonly referred to as a current-sensing resistor or a current-shunt resistor. The INA296x can operate in either a unidirectional or bidirectional mode based on the voltage potential placed on the reference pins.

The linear range of the output stage is limited to how close the output voltage can approach ground as well the supply voltage as described in the *Specifications*. The selection of the current-sensing resistor along with the current range to be measured, selection of the gain option, as well as the voltage applied to the reference pins should be chosen to keep the INA296x within the linear region of operation.

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8.4.3.1 Output Set to External Reference Voltage

Connecting both pins together and then to a reference voltage results in an output voltage equal to the reference voltage for the condition of shorted input pins or a 0 V differential input. Figure 8-4 shows this configuration. The output voltage decreases below the reference voltage when the IN+ pin is negative relative to the IN- pin and increases when the IN+ pin is positive relative to the IN- pin. This technique is the most accurate way to bias the output to a precise voltage.

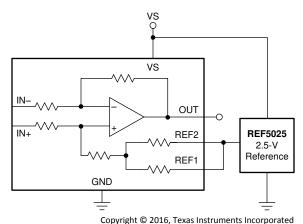


Figure 8-4. External Reference Output

8.4.3.2 Output Set to Mid-Supply Voltage

By connecting one reference pin to VS and the other to the GND pin, Figure 8-5 shows that the output is set at half of the supply voltage when there is no differential input. This method creates a ratiometric offset to the supply voltage, where the output voltage remains at VS / 2 for 0 V applied to the inputs.

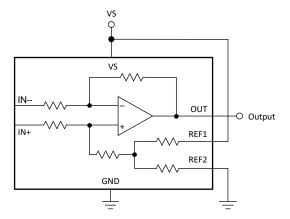


Figure 8-5. Mid-Supply Voltage Output

8.4.3.3 Output Set to Mid-External Reference

In this case, Figure 8-6 shows how an external reference can divided by two by connecting one REF pin to ground and the other REF pin to the reference.



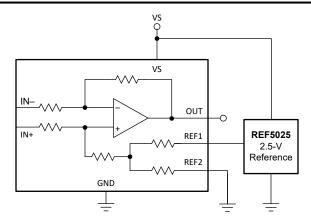


Figure 8-6. Mid-External Reference Output

8.4.3.4 Output Set Using Resistor Divider

The INA296x reference pins allow for the mid-point of the output voltage to be adjusted for system circuitry connections to analog to digital converters (ADCs) or other amplifiers. The reference pins are designed to be connected directly to supply, ground, or a low-impedance reference voltage. The reference pins can be connected together and biased using a resistor divider to achieve a custom output voltage. If the amplifier is used in this configuration, as shown in Figure 8-7, use the output as a differential signal with respect to the resistor divider voltage. Use of the amplifier output as a single-ended signal in this configuration is not recommended because the internal impedance shifts can adversely affect device performance specifications. If single-ended measurement is required, TI recommends to use an external op amp to buffer the resistor divider voltage (see Figure 8-8).

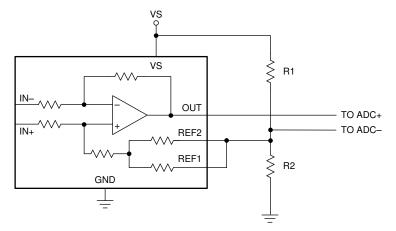


Figure 8-7. Setting the Reference Using a Resistor Divider



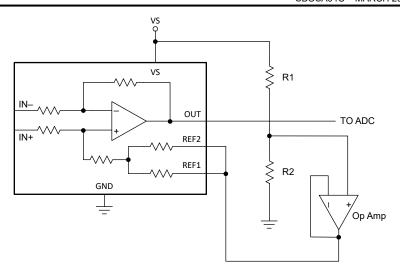


Figure 8-8. Setting the Reference Using a Resistor Divider and an Op Amp buffer



8.4.4 High Signal Throughput

With a bandwidth of 1.1 MHz at a gain of 20 V/V and a slew rate of 8 V/ μ s, the INA296x is specifically designed for detecting and protecting applications from fast inrush currents. As shown in Table 8-1, the INA296x responds in less than 1 μ s for a system measuring a 75 A threshold on a 2 m Ω shunt.

Table 8-1. Response Time

| | PARAMETER | EQUATION | INA296x AT V _S = 5 V |
|------------------------|-------------------------------------|--|---------------------------------|
| G | Gain | | 20 V/V |
| I _{MAX} | Maximum current | | 100 A |
| I _{Threshold} | Threshold current | | 75 A |
| R _{SENSE} | Current sense resistor value | | 2 mΩ |
| V _{OUT_MAX} | Output voltage at maximum current | $V_{OUT_MAX} = I_{MAX} \times R_{SENSE} \times G$ | 4 V |
| V _{OUT_THR} | Output voltage at threshold current | V _{OUT_THR} = I _{THR} × R _{SENSE} × G | 3 V |
| SR | Slew rate | | 8 V/µs |
| T _{response} | Output response time | T _{response} = V _{OUT_THR} / SR | < 1 µs |

9 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

9.1 Application Information

The INA296x amplifies the voltage developed across a current-sensing resistor as current flows through the resistor to the load. The wide input common-mode voltage range and high common-mode rejection of the INA296x make it usable over a wide range of voltage rails while still maintaining an accurate current measurement.

9.1.1 R_{SENSE} and Device Gain Selection

The accuracy of any current-sense amplifier is maximized by choosing the largest current-sense resistor value possible. A larger value sense resistor maximizes the differential input signal for a given amount of current flow and reduces the error contribution of the offset voltage. However, there are practical limits as to how large the current-sense resistor value can be in a given application because of the physical dimensions of the package, package construction, and maximum power dissipation. Equation 2 gives the maximum value for the current-sense resistor for a given power dissipation budget:

$$R_{SENSE} < \frac{PD_{MAX}}{I_{MAX}^2} \tag{2}$$

where:

- PD_{MAX} is the maximum allowable power dissipation in R_{SENSE}.
- I_{MAX} is the maximum current that will flow through R_{SENSE}.

An additional limitation on the size of the current-sense resistor and device gain is due to the power-supply voltage, V_S , and device swing-to-rail limitations. To make sure that the current-sense signal is properly passed to the output, both positive and negative output swing limitations must be examined. Equation 3 provides the maximum values of R_{SENSE} and GAIN to keep the device from exceeding the positive swing limitation.

$$I_{MAX} \times R_{SENSE} \times GAIN < V_{SP}$$
 (3)

where:

- I_{MAX} is the maximum current that will flow through R_{SENSE}.
- GAIN is the gain of the current-sense amplifier.
- V_{SP} is the positive output swing of the device as specified in the Specifications.

To avoid positive output swing limitations when selecting the value of R_{SENSE}, there is always a trade-off between the value of the sense resistor and the gain of the device under consideration. If the sense resistor selected for the maximum power dissipation is too large, then it is possible to select a lower gain device to avoid positive swing limitations.

The negative swing limitation places a limit on how small the sense resistor value can be for a given application. Equation 4 provides the limit on the minimum value of the sense resistor.

$$I_{MIN} \times R_{SENSE} \times GAIN > V_{SN}$$
 (4)

where:

- I_{MIN} is the minimum current that will flow through R_{SENSE}.
- GAIN is the gain of the current-sense amplifier.
- V_{SN} is the negative output swing of the device as specified in the Specifications.

Table 9-1 shows an example of the different results obtained from using five different gain versions of the INA296x. From the table data, the highest gain device allows a smaller current-shunt resistor and decreased power dissipation in the element.

| Table 9-1. Rs | ENSE Selection | and Power | Dissipation ⁽¹⁾ | |
|---------------|-----------------------|-----------|----------------------------|--|
|---------------|-----------------------|-----------|----------------------------|--|

| | | | RESULTS AT V _S = 5 V | | | | | | | |
|--------------------|--|--|---------------------------------|-------------------|-------------------|-------------------|-------------------|--|--|--|
| | PARAMETER | EQUATION | A1, B1 DEVICES | A2, B2 DEVICES | A3, B3 DEVICES | A4, B4 DEVICES | A5, B5 DEVICES | | | |
| G | Gain | | 10 V/V | 20 V/V | 50 V/V | 100 V/V | 200 V/V | | | |
| V _{SENSE} | Ideal differential input voltage | V _{SENSE} = V _{OUT} / G | 500 mV | 250 mV | 100 mV | 50 mV | 25 mV | | | |
| R _{SENSE} | Current sense resistor value | R _{SENSE} = V _{SENSE} / I _{MAX} | 50 mΩ | 25 mΩ | 10 mΩ | 5 mΩ | 2.5 mΩ | | | |
| P _{SENSE} | Current-sense resistor power dissipation | R _{SENSE} × I _{MAX} 2 | 5 W | 2.5 W | 1 W | 0.5 W | 0.25 W | | | |

(1) Design example with 10 A full-scale current with maximum output voltage set to 5 V.

9.2 Typical Application

The INA296x is a bidirectional, current-sense amplifier capable of measuring currents through a resistive shunt with common-mode voltages from –5 V to +110 V.

9.2.1 Current Sensing in a Solenoid Application

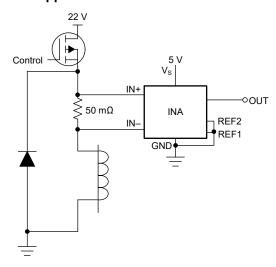


Figure 9-1. Solenoid Drive Application Circuit

9.2.1.1 Design Requirements

In this example application, the common-mode voltage ranges from 0 V to 22 V. The maximum sense current is 1.25 A, and a 5-V supply is available for the INA296x. Following the design guidelines from R_{SENSE} and Device Gain Selection, a R_{SENSE} of 50 m Ω and a gain of 20 V/V are selected to provide good output dynamic range. Table 9-2 lists the design setup for this application.

Table 9-2. Design Parameters

| DESIGN PARAMETERS | EXAMPLE VALUE | | | | |
|-----------------------------|---------------|--|--|--|--|
| Power supply voltage | 5 V | | | | |
| Common mode voltage range | 0 V to 22 V | | | | |
| Maximum sense current | 1.25 A | | | | |
| R _{SENSE} resistor | 50 mΩ | | | | |

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Table 9-2. Design Parameters (continued)

| DESIGN PARAMETERS | EXAMPLE VALUE |
|-------------------|---------------|
| Gain option | 20 V/V |

9.2.1.2 Detailed Design Procedure

The INA296x is designed to measure current in a typical solenoid application. The INA296x measures current across the $50\text{-m}\Omega$ shunt that is placed at the output in series with solenoid. The INA296x measures the differential voltage across the shunt resistor, and the signal is internally amplified with a gain of 20 V/V. The output of the INA296x is connected to the analog-to-digital converter (ADC) of an MCU to digitize the current measurements.

Solenoid loads are highly inductive and are often prone to failure. Solenoids are often used for position control, precise fluid control, and fluid regulation. Measuring real-time current on the solenoid continuously can indicate premature failure of the solenoid, which can lead to a faulty control loop in the system. Measuring high-side current also indicates if there are any ground faults on the solenoid or the FETs that can be damaged in an application. The INA296x, with high bandwidth and slew rate, can be used to detect fast overcurrent conditions to prevent the solenoid damage from short-to-ground faults.

9.2.1.3 Application Curve

Figure 9-2 shows the output response of a solenoid.

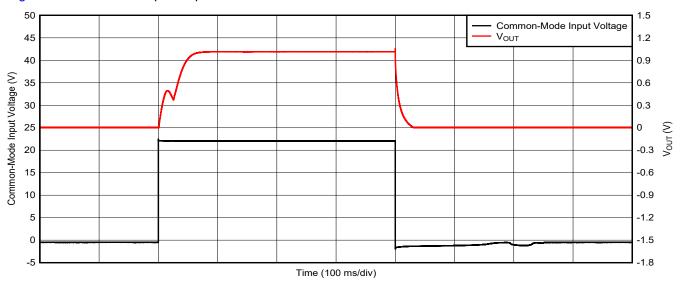


Figure 9-2. Solenoid Control Current Response



9.3 Power Supply Recommendations

The INA296x makes accurate measurements beyond the connected power-supply voltage (V_S) because the inputs (IN+ and IN-) can operate anywhere between -5 V and +110 V independent of V_S . For example, with the V_S power supply equal to 5 V, the common-mode voltage of the measured shunt can be as high as +110 V.

9.3.1 Power Supply Decoupling

Place the power-supply bypass capacitor as close to the supply and ground pins as possible. TI recommends a bypass capacitor value of 0.1 μ F. Additional decoupling capacitance can be added to compensate for noisy or high-impedance power supplies.

9.4 Layout

9.4.1 Layout Guidelines

Attention to good layout practices is always recommended.

- Connect the input pins to the sensing resistor using a Kelvin or 4-wire connection. This connection technique
 makes sure that only the current-sensing resistor impedance is detected between the input pins. Poor routing
 of the current-sensing resistor commonly results in additional resistance present between the input pins.
 Given the very low ohmic value of the current sense resistor, any additional high-current carrying impedance
 can cause significant measurement errors.
- Place the power-supply bypass capacitor as close to the device power supply and ground pins as possible.
 The recommended value of this bypass capacitor is 0.1 µF. Additional decoupling capacitance can be added to compensate for noisy or high-impedance power supplies.

9.4.2 Layout Examples

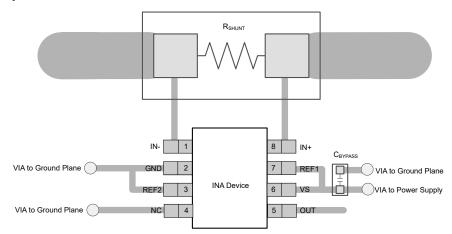


Figure 9-3. INA296x SOT-23 (DDF), SOIC (D) and VSSOP (DGK) Package Recommended Layout

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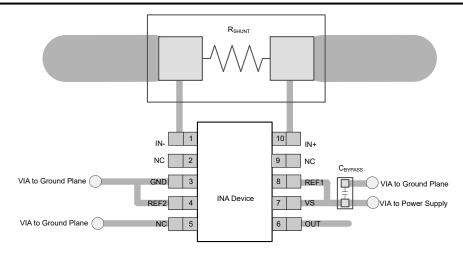


Figure 9-4. INA296x 10-Pin VSSOP (DGS) Package Recommended Layout



10 Device and Documentation Support

10.1 Receiving Notification of Documentation Updates

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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

10.5 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.

11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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PACKAGING INFORMATION

| Orderable Device | Status (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan | Lead finish/ Ball material | MSL Peak Temp | Op Temp (°C) | Device Marking (4/5) | Samples |
|------------------|------------|--------------|--------------------|------|----------------|--------------|-------------------------------|---------------------|--------------|-------------------------|---------|
| INA296A1IDDFR | ACTIVE | SOT-23-THIN | DDF | 8 | 3000 | RoHS & Green | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 2SA3 | Samples |
| INA296A1IDGKR | ACTIVE | VSSOP | DGK | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | 2TUB | Samples |
| INA296A1IDR | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | I296A1 | Samples |
| INA296A2IDDFR | ACTIVE | SOT-23-THIN | DDF | 8 | 3000 | RoHS & Green | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 2SB3 | Samples |
| INA296A2IDGKR | ACTIVE | VSSOP | DGK | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | 2TVB | Samples |
| INA296A2IDR | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | I296A2 | Samples |
| INA296A3IDDFR | ACTIVE | SOT-23-THIN | DDF | 8 | 3000 | RoHS & Green | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 2SC3 | Samples |
| INA296A3IDGKR | ACTIVE | VSSOP | DGK | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | 2TWB | Samples |
| INA296A3IDR | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | I296A3 | Samples |
| INA296A4IDDFR | ACTIVE | SOT-23-THIN | DDF | 8 | 3000 | RoHS & Green | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 2SD3 | Samples |
| INA296A4IDGKR | ACTIVE | VSSOP | DGK | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | 2TXB | Samples |
| INA296A4IDR | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | I296A4 | Samples |
| INA296A5IDDFR | ACTIVE | SOT-23-THIN | DDF | 8 | 3000 | RoHS & Green | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 2SE3 | Samples |
| INA296A5IDGKR | ACTIVE | VSSOP | DGK | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | 2TZB | Samples |
| INA296A5IDR | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | I296A5 | Samples |
| INA296B1IDDFR | ACTIVE | SOT-23-THIN | DDF | 8 | 3000 | RoHS & Green | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 2SF3 | Samples |
| INA296B1IDGKR | ACTIVE | VSSOP | DGK | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | 2U1B | Samples |
| INA296B1IDR | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | I296B1 | Samples |
| INA296B2IDDFR | ACTIVE | SOT-23-THIN | DDF | 8 | 3000 | RoHS & Green | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 2SG3 | Samples |
| INA296B2IDGKR | ACTIVE | VSSOP | DGK | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | 2U2B | Samples |



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| Orderable Device | Status (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan | Lead finish/ Ball material | MSL Peak Temp | Op Temp (°C) | Device Marking (4/5) | Samples |
|------------------|------------|--------------|--------------------|------|----------------|--------------|-------------------------------|---------------------|--------------|----------------------|---------|
| INA296B2IDR | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | I296B2 | Samples |
| INA296B3IDDFR | ACTIVE | SOT-23-THIN | DDF | 8 | 3000 | RoHS & Green | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 2SH3 | Samples |
| INA296B3IDGKR | ACTIVE | VSSOP | DGK | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | 2U3B | Samples |
| INA296B3IDR | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | I296B3 | Samples |
| INA296B4IDDFR | ACTIVE | SOT-23-THIN | DDF | 8 | 3000 | RoHS & Green | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 2SI3 | Samples |
| INA296B4IDGKR | ACTIVE | VSSOP | DGK | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | 2U4B | Samples |
| INA296B4IDR | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | I296B4 | Samples |
| INA296B5IDDFR | ACTIVE | SOT-23-THIN | DDF | 8 | 3000 | RoHS & Green | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 2SJ3 | Samples |
| INA296B5IDGKR | ACTIVE | VSSOP | DGK | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | 2U5B | Samples |
| INA296B5IDR | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | NIPDAU | Level-2-260C-1 YEAR | -40 to 125 | I296B5 | Samples |

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

⁽³⁾ MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

⁽⁴⁾ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

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(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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OTHER QUALIFIED VERSIONS OF INA296A, INA296B:

Automotive: INA296A-Q1, INA296B-Q1

NOTE: Qualified Version Definitions:

Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects



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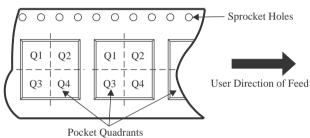
TAPE AND REEL INFORMATION





| A0 | Dimension designed to accommodate the component width |
|----|---|
| В0 | Dimension designed to accommodate the component length |
| K0 | Dimension designed to accommodate the component thickness |
| W | Overall width of the carrier tape |
| P1 | Pitch between successive cavity centers |

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|---------------|-----------------|--------------------|------|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| INA296A1IDDFR | SOT-23- THIN | DDF | 8 | 3000 | 180.0 | 8.4 | 3.15 | 3.1 | 1.55 | 4.0 | 8.0 | Q3 |
| INA296A1IDDFR | SOT-23- THIN | DDF | 8 | 3000 | 180.0 | 8.4 | 3.2 | 3.2 | 1.4 | 4.0 | 8.0 | Q3 |
| INA296A1IDGKR | VSSOP | DGK | 8 | 2500 | 330.0 | 12.4 | 5.3 | 3.4 | 1.4 | 8.0 | 12.0 | Q1 |
| INA296A1IDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |
| INA296A2IDDFR | SOT-23- THIN | DDF | 8 | 3000 | 180.0 | 8.4 | 3.15 | 3.1 | 1.55 | 4.0 | 8.0 | Q3 |
| INA296A2IDGKR | VSSOP | DGK | 8 | 2500 | 330.0 | 12.4 | 5.3 | 3.4 | 1.4 | 8.0 | 12.0 | Q1 |
| INA296A2IDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |
| INA296A3IDGKR | VSSOP | DGK | 8 | 2500 | 330.0 | 12.4 | 5.3 | 3.4 | 1.4 | 8.0 | 12.0 | Q1 |
| INA296A3IDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |
| INA296A4IDDFR | SOT-23- THIN | DDF | 8 | 3000 | 180.0 | 8.4 | 3.15 | 3.1 | 1.55 | 4.0 | 8.0 | Q3 |
| INA296A4IDGKR | VSSOP | DGK | 8 | 2500 | 330.0 | 12.4 | 5.3 | 3.4 | 1.4 | 8.0 | 12.0 | Q1 |
| INA296A4IDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |



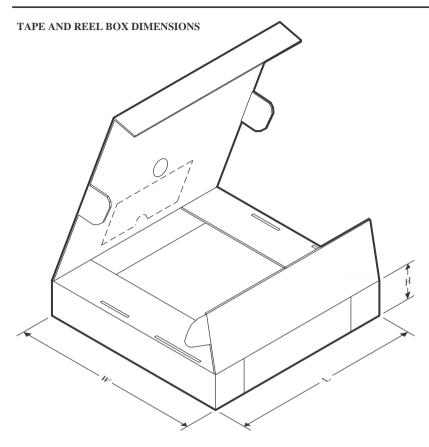
PACKAGE MATERIALS INFORMATION

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| Device | Package Type | Package Drawing | Pins | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|---------------|-----------------|--------------------|------|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| INA296A5IDDFR | SOT-23- THIN | DDF | 8 | 3000 | 180.0 | 8.4 | 3.2 | 3.2 | 1.4 | 4.0 | 8.0 | Q3 |
| INA296A5IDDFR | SOT-23- THIN | DDF | 8 | 3000 | 180.0 | 8.4 | 3.15 | 3.1 | 1.55 | 4.0 | 8.0 | Q3 |
| INA296A5IDGKR | VSSOP | DGK | 8 | 2500 | 330.0 | 12.4 | 5.3 | 3.4 | 1.4 | 8.0 | 12.0 | Q1 |
| INA296A5IDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |
| INA296B1IDDFR | SOT-23- THIN | DDF | 8 | 3000 | 180.0 | 8.4 | 3.15 | 3.1 | 1.55 | 4.0 | 8.0 | Q3 |
| INA296B1IDDFR | SOT-23- THIN | DDF | 8 | 3000 | 180.0 | 8.4 | 3.2 | 3.2 | 1.4 | 4.0 | 8.0 | Q3 |
| INA296B1IDGKR | VSSOP | DGK | 8 | 2500 | 330.0 | 12.4 | 5.3 | 3.4 | 1.4 | 8.0 | 12.0 | Q1 |
| INA296B1IDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |
| INA296B2IDDFR | SOT-23- THIN | DDF | 8 | 3000 | 180.0 | 8.4 | 3.15 | 3.1 | 1.55 | 4.0 | 8.0 | Q3 |
| INA296B2IDGKR | VSSOP | DGK | 8 | 2500 | 330.0 | 12.4 | 5.3 | 3.4 | 1.4 | 8.0 | 12.0 | Q1 |
| INA296B2IDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |
| INA296B3IDDFR | SOT-23- THIN | DDF | 8 | 3000 | 180.0 | 8.4 | 3.15 | 3.1 | 1.55 | 4.0 | 8.0 | Q3 |
| INA296B3IDGKR | VSSOP | DGK | 8 | 2500 | 330.0 | 12.4 | 5.3 | 3.4 | 1.4 | 8.0 | 12.0 | Q1 |
| INA296B3IDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |
| INA296B4IDDFR | SOT-23- THIN | DDF | 8 | 3000 | 180.0 | 8.4 | 3.15 | 3.1 | 1.55 | 4.0 | 8.0 | Q3 |
| INA296B4IDGKR | VSSOP | DGK | 8 | 2500 | 330.0 | 12.4 | 5.3 | 3.4 | 1.4 | 8.0 | 12.0 | Q1 |
| INA296B4IDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |
| INA296B5IDDFR | SOT-23- THIN | DDF | 8 | 3000 | 180.0 | 8.4 | 3.15 | 3.1 | 1.55 | 4.0 | 8.0 | Q3 |
| INA296B5IDDFR | SOT-23- THIN | DDF | 8 | 3000 | 180.0 | 8.4 | 3.2 | 3.2 | 1.4 | 4.0 | 8.0 | Q3 |
| INA296B5IDGKR | VSSOP | DGK | 8 | 2500 | 330.0 | 12.4 | 5.3 | 3.4 | 1.4 | 8.0 | 12.0 | Q1 |
| INA296B5IDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |



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*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|---------------|--------------|-----------------|------|------|-------------|------------|-------------|
| INA296A1IDDFR | SOT-23-THIN | DDF | 8 | 3000 | 210.0 | 185.0 | 35.0 |
| INA296A1IDDFR | SOT-23-THIN | DDF | 8 | 3000 | 210.0 | 185.0 | 35.0 |
| INA296A1IDGKR | VSSOP | DGK | 8 | 2500 | 356.0 | 356.0 | 35.0 |
| INA296A1IDR | SOIC | D | 8 | 2500 | 353.0 | 353.0 | 32.0 |
| INA296A2IDDFR | SOT-23-THIN | DDF | 8 | 3000 | 210.0 | 185.0 | 35.0 |
| INA296A2IDGKR | VSSOP | DGK | 8 | 2500 | 356.0 | 356.0 | 35.0 |
| INA296A2IDR | SOIC | D | 8 | 2500 | 340.5 | 336.1 | 25.0 |
| INA296A3IDGKR | VSSOP | DGK | 8 | 2500 | 356.0 | 356.0 | 35.0 |
| INA296A3IDR | SOIC | D | 8 | 2500 | 353.0 | 353.0 | 32.0 |
| INA296A4IDDFR | SOT-23-THIN | DDF | 8 | 3000 | 210.0 | 185.0 | 35.0 |
| INA296A4IDGKR | VSSOP | DGK | 8 | 2500 | 356.0 | 356.0 | 35.0 |
| INA296A4IDR | SOIC | D | 8 | 2500 | 353.0 | 353.0 | 32.0 |
| INA296A5IDDFR | SOT-23-THIN | DDF | 8 | 3000 | 210.0 | 185.0 | 35.0 |
| INA296A5IDDFR | SOT-23-THIN | DDF | 8 | 3000 | 210.0 | 185.0 | 35.0 |
| INA296A5IDGKR | VSSOP | DGK | 8 | 2500 | 356.0 | 356.0 | 35.0 |
| INA296A5IDR | SOIC | D | 8 | 2500 | 340.5 | 336.1 | 25.0 |
| INA296B1IDDFR | SOT-23-THIN | DDF | 8 | 3000 | 210.0 | 185.0 | 35.0 |
| INA296B1IDDFR | SOT-23-THIN | DDF | 8 | 3000 | 210.0 | 185.0 | 35.0 |



PACKAGE MATERIALS INFORMATION

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| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|---------------|--------------|-----------------|------|------|-------------|------------|-------------|
| INA296B1IDGKR | VSSOP | DGK | 8 | 2500 | 356.0 | 356.0 | 35.0 |
| INA296B1IDR | SOIC | D | 8 | 2500 | 353.0 | 353.0 | 32.0 |
| INA296B2IDDFR | SOT-23-THIN | DDF | 8 | 3000 | 210.0 | 185.0 | 35.0 |
| INA296B2IDGKR | VSSOP | DGK | 8 | 2500 | 356.0 | 356.0 | 35.0 |
| INA296B2IDR | SOIC | D | 8 | 2500 | 353.0 | 353.0 | 32.0 |
| INA296B3IDDFR | SOT-23-THIN | DDF | 8 | 3000 | 210.0 | 185.0 | 35.0 |
| INA296B3IDGKR | VSSOP | DGK | 8 | 2500 | 356.0 | 356.0 | 35.0 |
| INA296B3IDR | SOIC | D | 8 | 2500 | 353.0 | 353.0 | 32.0 |
| INA296B4IDDFR | SOT-23-THIN | DDF | 8 | 3000 | 210.0 | 185.0 | 35.0 |
| INA296B4IDGKR | VSSOP | DGK | 8 | 2500 | 356.0 | 356.0 | 35.0 |
| INA296B4IDR | SOIC | D | 8 | 2500 | 353.0 | 353.0 | 32.0 |
| INA296B5IDDFR | SOT-23-THIN | DDF | 8 | 3000 | 210.0 | 185.0 | 35.0 |
| INA296B5IDDFR | SOT-23-THIN | DDF | 8 | 3000 | 210.0 | 185.0 | 35.0 |
| INA296B5IDGKR | VSSOP | DGK | 8 | 2500 | 356.0 | 356.0 | 35.0 |
| INA296B5IDR | SOIC | D | 8 | 2500 | 353.0 | 353.0 | 32.0 |



SMALL OUTLINE PACKAGE



NOTES:

PowerPAD is a trademark of Texas Instruments.

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

 2. This drawing is subject to change without notice.

 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-187.



SMALL OUTLINE PACKAGE



NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- 8. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.
- 9. Size of metal pad may vary due to creepage requirement.



SMALL OUTLINE PACKAGE



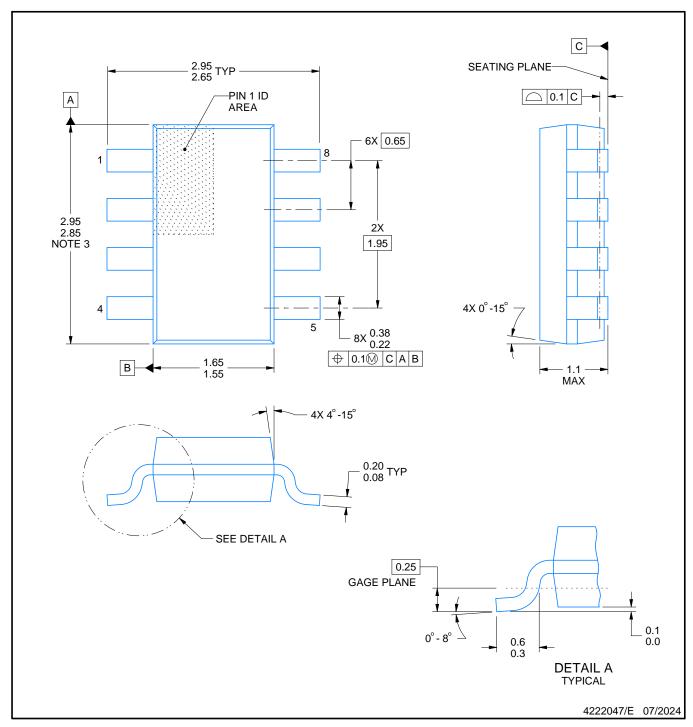
NOTES: (continued)

- 11. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 12. Board assembly site may have different recommendations for stencil design.





PLASTIC SMALL OUTLINE



NOTES:

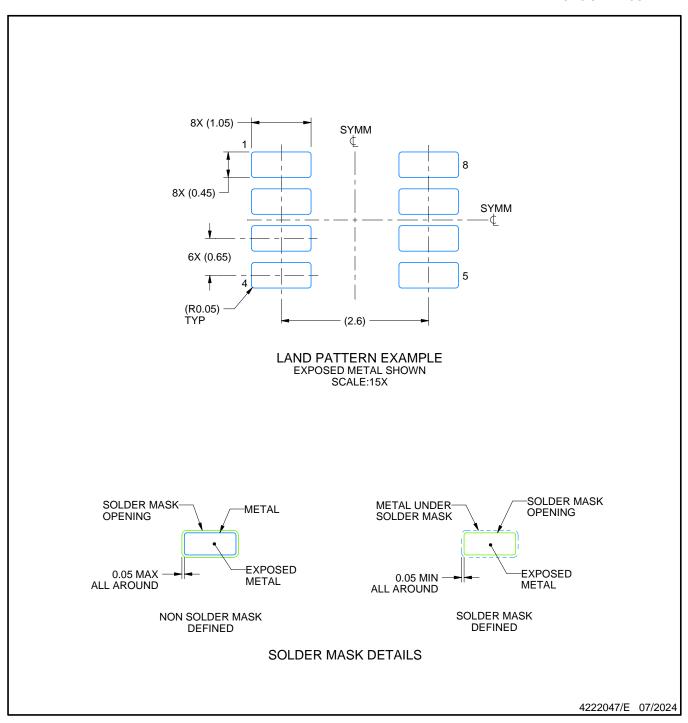
- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

 2. This drawing is subject to change without notice.

 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.



PLASTIC SMALL OUTLINE

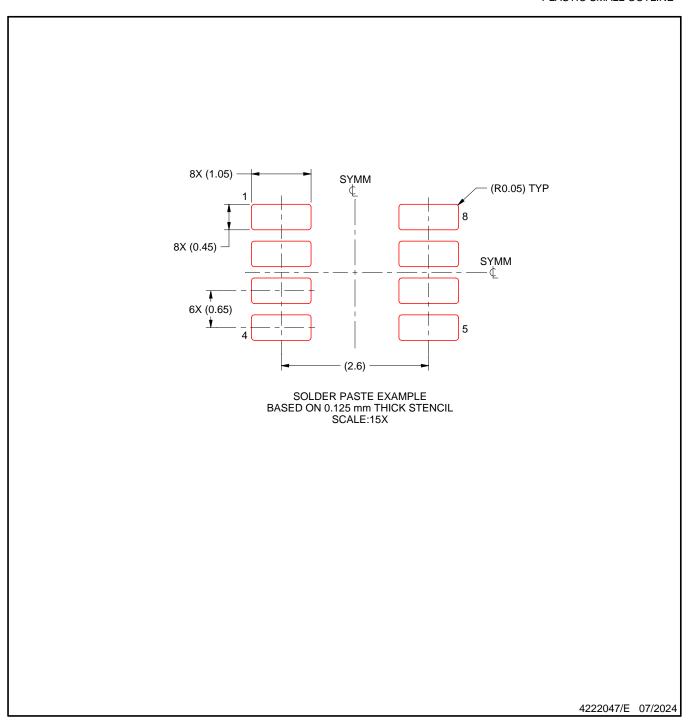


NOTES: (continued)

- 4. Publication IPC-7351 may have alternate designs.
- 5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



PLASTIC SMALL OUTLINE



NOTES: (continued)

- 6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 7. Board assembly site may have different recommendations for stencil design.





SMALL OUTLINE INTEGRATED CIRCUIT



NOTES:

- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



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