THVD24xxV-EP 拡張 3V～5.5V RS-485 トランシーバ、1.8V VIO 機能搭載

1 特長

- TIA/EIA-485A および TIA/EIA-422B 規格の要件に適合またはそれを上回る性能
- エンハンスド製品
  - 軍事用温度範囲 (-55℃～125℃)
  - 1 箇所のウェハー製造拠点と 1 箇所のアセンブリ / テスト拠点
  - 金ボンド ワイヤ、NiPdAu リード仕上げ
  - ウェハー ロットをトレース可能
  - 長期にわたる製品ライフ サイクル
- 電源電圧:3V～5.5V
- 5V 電源で 2.1V を超える差動出力により PROFIBUS に準拠
- データおよびイネーブル信号用の 1.65V～5.5V 電源
- SLR ピンで選択可能なデータ レート:
  - THVD2410V-EP:250kbps、1Mbps
  - THVD2450V-EP、THVD2452V-EP:20Mbps、50Mbps
- バス I/O 保護
  - DC ±70V バス フォルト
  - ±16kV HBM ESD
  - THVD2410V-EP、THVD2450V-EP
    - ±15kV IEC 61000-4-2 接触および気中放電
  - THVD2452V-EP
    - ±8kV IEC 61000-4-2 接触および気中放電
  - ±4kV IEC 61000-4-4 高速過渡バースト
- 2 つの速度グレードに対応する半二重および全二重デバイス
- 対称同相電圧範囲:±12 V
- レシーバのヒステリシスを大きくすることでノイズ耐性を確保
- 低消費電力
  - 小さいシャットダウン時消費電流:1µA 未満
  - 動作時電流:5.3mA 未満
- グリッチなしの電源オン / オフによるホット プラグイン機能
- 開放、短絡、アイドル バスのフェイルセーフ
- サーマル シャットダウン
- 1/8 単位負荷 (最大 256 のバス ノード)
- 基板面積を削減できる小型 3mm x 3mm VSON パッケージ (半二重)、またはドロップイン互換の 14-D パッケージ (全二重)

2 アプリケーション

- 航空
- スマート弾薬
- センサ、画像処理、レーダー
- 高耐久性通信

3 概要

THVD24xxV-EP は、データおよびイネーブル ロジック信号用の 1.65V～5.5V のロジック電源と 3V～5.5V のバス側電源を使用する、±70V 障害保護機能付き半二重および全二重 RS-422/RS-485 トランシーバです。これらのデバイスはスルーレート選択機能を備えています。このスルーレート選択機能を使うと、SLR ピンの設定に基づいて 2 つの最大速度でこれらのデバイスを使うことができます。

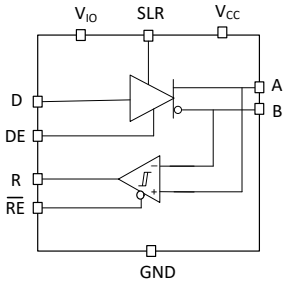
IEC ESD 保護機能を内蔵しているため、システムレベルの外部保護部品は不要です。±12V 入力同相範囲により、長いケーブルを使用する場合やグランド ループ電圧が大きい場合でもデータ通信の信頼性を高めることができます。250mV のレシーバ ヒステリシスを強化することで、高いノイズ除去性能を実現します。また、レシーバのフェイルセーフ機能により、入力が開放または短絡した場合、出力が確実に論理 High に固定されます。

THVD24xxV-EP の半二重デバイスは、スペースに制約がある用途向けに、小型の VSON パッケージで供給されます。これらのデバイスは、標準の 14-SOIC パッケージで供給されています。

パッケージ情報

部品番号	パッケージ(1)	パッケージ サイズ(2)
THVD2410V-EP THVD2450V-EP	VSON (10)	3mm × 3mm
THVD2452V-EP	SOIC (14)	8.65mm × 6mm

(1) 詳細については、セクション 11 を参照してください。
(2) パッケージ サイズ (長さ × 幅) は公称値であり、該当する場合はピンも含まれます。



THVD2410V-EP および THVD2450V-EP の概略回路図

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4 Pin Configuration and Functions

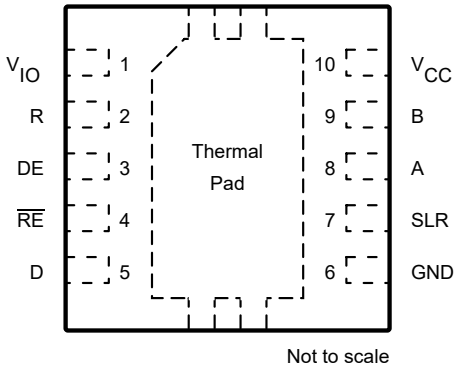


図 4-1. THVD2410V-EP, THVD2450V-EP 10-Pin DRC Package (VSON) (Top View)

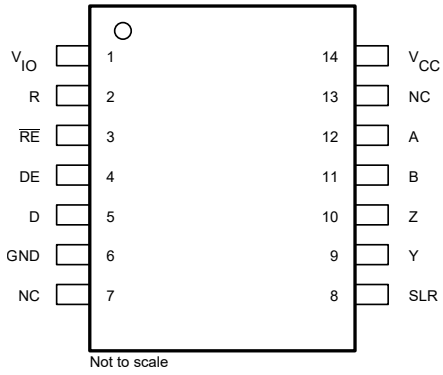


図 4-2. THVD2452V-EP 14-Pin D Package (SOIC) (Top View)

表 4-1. Pin Functions

NAME	PIN NO.		TYPE	DESCRIPTION
	DRC	D		
V_{IO}	1	1	Logic Supply	1.65V to 5.5V supply for logic I/O signals R, $\overline{RE}$, D, DE, and SLR)
R	2	2	Digital Output	Receive data output
DE	3	4	Digital Input	Driver enable input; integrated pull-down
$\overline{RE}$	4	3	Digital Input	Receiver enable input; integrated pull-up
D	5	5	Digital Input	Transmission data input; integrated pull-up
GND	6	6	Reference Potential	Local device ground
SLR	7	8	Digital Input	Slew rate select ; integrated pull-down. For THVD2410V-EP: Low = 1Mbps, High = 250kbps. Defaults to 1Mbps if SLR is left floating. For THVD2450V-EP and THVD2452V-EP: Low = 50Mbps, High = 20Mbps. Defaults to 50Mbps if left floating.
A	8	11	Bus Input	Bus I/O (half-duplex), bus input (full-duplex)
B	9	12	Bus Input	Bus I/O (half-duplex), bus input (full-duplex)
V_{CC}	10	14	Bus Supply	3V to 5.5V supply for the transceiver
Y	-	9	Bus Output	Bus output, Y
Z	-	10	Bus Output	Bus output, Z
NC	-	7, 13		No connect pin. Internally not connected

5 Specifications

5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) (1) (2)

		MIN	MAX	UNIT
Logic supply voltage	V_{IO}	–0.5	V_{CC} + 0.2	V
Bus supply voltage	V_{CC}	–0.5	6.5	V
Bus voltage	Range at any bus pin as differential or common-mode with respect to GND	–70	70	V
Input voltage	Range at any logic pin (D, DE, SLR or $\overline{RE}$)	–0.3	V_{IO} + 0.2	V
Receiver output current	I_O	–24	24	mA
Storage temperature	T_{stg}	–65	170	°C

(1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.
(2) All voltage values, except differential I/O bus voltages, are with respect to ground terminal.

5.2 ESD Ratings

				VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001(1)	Bus terminals and GND	±16,000	V
			All pins except bus terminals and GND	±4,000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101(2)		±1,500	V

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

5.3 ESD Ratings [IEC]

				VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge, Half duplex devices THVD2410V/2450V-EP (1)	Contact discharge, per IEC 61000-4-2	Bus terminals and GND	±15,000	V
		Air-gap discharge, per IEC 61000-4-2	Bus terminals and GND	±15,000	
$V_{(ESD)}$	Electrostatic discharge, Full duplex devices THVD2452V-EP (1)	Contact discharge, per IEC 61000-4-2	Bus terminals and GND	±8,000	V
		Air-gap discharge, per IEC 61000-4-2	Bus terminals and GND	±8,000	
$V_{(EFT)}$	Electrical fast transient	Per IEC 61000-4-4	Bus terminals	±4,000	V

(1) For optimized IEC ESD performance, it is recommended to have series resistor (≥ 50 Ω) on all logic inputs to minimize transient currents going into or out of the logic pins.

5.4 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

			MIN	NOM	MAX	UNIT
V_{CC}	Supply voltage		3		5.5	V
V_{IO}	I/O supply voltage		1.65		V_{CC}	V
V_I	Input voltage at any bus terminal (separately or common mode)(1)		–12		12	V
V_{IH}	High-level input voltage (driver, driver enable, receiver enable and slew rate select inputs)		0.7*V_{IO}		V_{IO}	V
V_{IL}	Low-level input voltage (driver, driver enable, receiver enable and slew rate select inputs)		0		0.3*V_{IO}	V
V_{ID}	Differential input voltage bus pins		–25		25	V
I_O	Output current, driver		–60		60	mA
I_{OR}	Output current, receiver	V_{IO} = 1.8 V or 2.5 V	–4		4	mA
I_{OR}	Output current, receiver	V_{IO} = 3.3 V or 5 V	–8		8	mA
R_L	Differential load resistance		54	60		Ω
$1/t_{UI}$	Signaling rate	THVD2410V, THVD2412V with SLR = V_{IO}			250	kbps
		THVD2410V, THVD2412V with SLR = GND or floating			1	Mbps
		THVD2450V, THVD2452V with SLR = V_{IO}			20	Mbps
		THVD2450V, THVD2452V with SLR = GND or floating			50	Mbps
T_A	Operating ambient temperature		-55		125	°C
T_J	Junction temperature		-55		150	°C

(1) The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet.

5.5 Thermal Information

THERMAL METRIC(1)		THVD2410V-EP THVD2450V-EP	THVD2452V-EP	UNIT
		DRC (VSON)	D (SOIC)	
		10 PINS	14 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	46.7	87.5	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	47.7	41.8	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	19.1	43.7	°C/W
ψ_{JT}	Junction-to-top characterization parameter	0.7	8.1	°C/W
ψ_{JB}	Junction-to-board characterization parameter	19.1	43.3	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	4.6	N/A	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

5.6 Power Dissipation

PARAMETER		TEST CONDITIONS			VALUE	UNIT
P_D	Driver and receiver enabled, loopback for full duplex devices (A connected to Y, B connected to Z) V_{CC} = 5.5 V, T_A = 125 °C, square wave at 50% duty cycle	Unterminated R_L = 300 Ω, C_L = 50 pF (driver)	THVD2410V-EP	250 kbps	160	mW
				1Mbps	250	
			THVD2450V-EP THVD2452V-EP	20Mbps	310	
				50 Mbps	630	
		RS-422 load R_L = 100 Ω, C_L = 50 pF (driver)	THVD2410V-EP	250 kbps	170	mW
				1Mbps	250	
			THVD2450V-EP THVD2452V-EP	20Mbps	290	
				50 Mbps	570	
		RS-485 load R_L = 54 Ω, C_L = 50 pF (driver)	THVD2410V-EP	250 kbps	220	mW
				1Mbps	280	
			THVD2450V-EP THVD2452V-EP	20Mbps	325	
				50 Mbps	560	

5.7 Electrical Characteristics

over operating free-air temperature range (unless otherwise noted). All typical values are at 25°C and supply voltage of V_{CC} = 5 V, V_{IO} = 3.3 V , unless otherwise noted. (1)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
Driver							
$\|V_{OD}\|$	Driver differential output voltage magnitude	R_L = 60 Ω, –25 V ≤ V_{test} ≤ 25 V (See 図 6-1)		1.5	3.3		V
		R_L = 60 Ω, –25 V ≤ V_{test} ≤ 25 V, 4.5 V ≤ V_{CC} ≤ 5.5 V (See 図 6-1)		2.1	3.3		V
		R_L = 100 Ω (See 図 6-2)		2	4		V
		R_L = 54 Ω (See 図 6-2)		1.5	3.5		V
$\Delta\|V_{OD}\|$	Change in differential output voltage	R_L = 54 Ω or 100 Ω (See 図 6-2)		–50		50	mV
V_{OC}	Common-mode output voltage	R_L = 54 Ω or 100 Ω (See 図 6-2)		1	V_{CC}/2	3	V
$\Delta V_{OC(SS)}$	Change in steady-state common-mode output voltage	R_L = 54 Ω or 100 Ω (See 図 6-2)		–50		50	mV
I_{OS}	Short-circuit output current	DE = V_{IO}, -70 V ≤ (V_A or V_B) ≤ 70 V, or A shorted to B (A,B are driver terminals for half duplex, Y/Z are for full duplex)		–250		250	mA
Receiver							
I_I	Bus input current	DE = 0 V, V_{CC} and V_{IO} = 0 V or 5.5 V	V_I = 12 V		90	125	µA
			V_I = 25 V		200	250	µA
			V_I = –7 V	–100	–80		µA
			V_I = –25 V	–350	–220		µA
V_{TH+}	Positive-going input threshold voltage (2)	Over common-mode range of ± 12 V		40	125	200	mV
V_{TH-}	Negative-going input threshold voltage (2)			–200	–125	-40	mV
V_{HYS}	Input hysteresis				250		mV
V_{TH_FSH}	Input fail-safe threshold			–40		40	mV
$C_{A,B}$	Input differential capacitance	Measured between A and B, f = 1 MHz			50		pF
V_{OH}	Output high voltage	I_{OH} = –8 mA, V_{IO} = 3 to 3.6 V or 4.5 V to 5.5 V		V_{IO} – 0.4	V_{IO} – 0.2		V
V_{OL}	Output low voltage	I_{OL} = 8 mA, V_{IO} = 3 to 3.6 V or 4.5 V to 5.5 V			0.2	0.4	V
V_{OH}	Output high voltage	I_{OH} = –4 mA, V_{IO} = 1.65 to 1.95 V or 2.25 V to 2.75 V		V_{IO} – 0.4	V_{IO} – 0.2		V
V_{OL}	Output low voltage	I_{OL} = 4 mA, V_{IO} = 1.65 to 1.95 V or 2.25 V to 2.75 V			0.2	0.4	V
I_{OZ}	Output high-impedance current, R pin	V_O = 0 V or V_{IO}, $\overline{RE}$ = V_{IO}		–1		1	µA
Logic							
I_{IN}	Input current (DE , SLR)	1.65 V ≤ V_{IO} ≤ 5.5 V, 0 V ≤ V_{IN} ≤ V_{IO}				5	µA
I_{IN}	Input current (D, $\overline{RE}$)	1.65 V ≤ V_{IO} ≤ 5.5 V, 0 V ≤ V_{IN} ≤ V_{IO}		–5			µA
Thermal Protection							
T_{SHDN}	Thermal shutdown threshold	Temperature rising		150	180		°C
T_{HYS}	Thermal shutdown hysteresis				10		°C
Supply							
UV_{VCC} (rising)	Rising under-voltage threshold on V_{CC}				2.3	2.6	V
UV_{VCC} (falling)	Falling under-voltage threshold on V_{CC}			1.95	2.2		V
$UV_{VCC(hys)}$	Hysteresis on under-voltage of V_{CC}				150		mV
UV_{VIO} (rising)	Rising under-voltage threshold on V_{IO}				1.4	1.6	V
UV_{VIO} (falling)	Falling under-voltage threshold on V_{IO}			1.2	1.3		V

5.7 Electrical Characteristics (続き)

over operating free-air temperature range (unless otherwise noted). All typical values are at 25°C and supply voltage of V_{CC} = 5 V, V_{IO} = 3.3 V , unless otherwise noted. (1)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
$UV_{VIO(hys)}$	Hysteresis on under-voltage of V_{IO}				30		mV
I_{CC}	Supply current (quiescent), V_{CC} = 4.5 V to 5.5 V	Driver and receiver enabled	$\overline{RE}$ = 0 V, DE = V_{IO}, No load		3.5	5.3	mA
		Driver enabled, receiver disabled	$\overline{RE}$ = V_{IO}, DE = V_{IO}, No load		2.5	4.2	mA
		Driver disabled, receiver enabled	$\overline{RE}$ = 0 V, DE = 0 V, No load		1.8	2.4	mA
		Driver and receiver disabled	$\overline{RE}$ = V_{IO}, DE = 0 V, D = open, No load		0.1	1.2	µA
I_{CC}	Supply current (quiescent), V_{CC} = 3 V to 3.6 V	Driver and receiver enabled	$\overline{RE}$ = 0 V, DE = V_{IO}, No load		3	4.1	mA
		Driver enabled, receiver disabled	$\overline{RE}$ = V_{IO}, DE = V_{IO}, No load		2	3	mA
		Driver disabled, receiver enabled	$\overline{RE}$ = 0 V, DE = 0 V, No load		1.6	2.2	mA
		Driver and receiver disabled	$\overline{RE}$ = V_{IO}, DE = 0 V, D = open, No load		0.1	1	µA
I_{IO}	Logic supply current (quiescent), V_{IO} = 3 to 3.6 V	Driver disabled, Receiver enabled, SLR = GND	DE = 0 V, $\overline{RE}$ = 0 V, No load		4.5	8.4	µA
		Driver disabled, Receiver enabled, SLR = V_{IO}	DE = 0 V, $\overline{RE}$ = 0 V, No load		3.3	8.4	µA
		Driver disabled, Receiver disabled, SLR = GND	DE = 0 V, $\overline{RE}$ = V_{IO}, No load		0.1	1	µA
		Driver disabled, Receiver disabled, SLR = V_{IO}	DE = 0 V, $\overline{RE}$ = V_{IO}, No load		1.8	4	µA

(1) A, B are driver output and receiver input terminals for Half duplex devices; A/B are Receiver input, Y/Z are driver output terminals for Full duplex devices

(2) Under any specific conditions, V_{TH+} is assured to be at least V_{HYS} higher than V_{TH-}.

5.8 Switching Characteristics - 250 kbps

250-kbps (THVD2410V-EP with SLR = V_{IO}) over recommended operating conditions. All typical values are at 25°C and supply voltage of V_{CC} = 5 V , V_{IO} = 3.3 V, unless otherwise noted. (1)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
Driver							
t_r, t_f	Differential output rise/fall time	V_{CC} = 3 to 3.6 V, Typical at 3.3V	R_L = 54 Ω, C_L = 50 pF See 図 6-3	450	560	1200	ns
		V_{CC} = 4.5 to 5.5 V, Typical at 5 V		500	625	1200	ns
t_{PHL}, t_{PLH}	Propagation delay	V_{CC} = 3 to 3.6 V, Typical at 3.3V			500	720	ns
		V_{CC} = 4.5 to 5.5 V, Typical at 5 V			540	770	ns
$t_{SK(P)}$	Pulse skew, $\lvert t_{PHL} - t_{PLH} \rvert$	V_{CC} = 3 to 3.6 V, Typical at 3.3V			10	70	ns
		V_{CC} = 4.5 to 5.5 V, Typical at 5 V			10	70	ns
t_{PHZ}, t_{PLZ}	Disable time	$\overline{RE}$ = X	See 図 6-4 and 図 6-5		40	75	ns
t_{PZH}, t_{PZL}	Enable time	$\overline{RE}$ = 0 V			70	280	ns
		$\overline{RE}$ = V_{IO}			2.5	4.5	µs
t_{SHDN}	Time to shutdown	$\overline{RE}$ = V_{IO}		50		500	ns
Receiver							
t_r, t_f	Output rise/fall time	C_L = 15 pF	See 図 6-6		7	20	ns
t_{PHL}, t_{PLH}	Propagation delay				800	1270	ns
$t_{SK(P)}$	Pulse skew, $\lvert t_{PHL} - t_{PLH} \rvert$				5	45	ns
t_{PHZ}, t_{PLZ}	Disable time	DE = X			30	40	ns
$t_{PZH(1)}$	Enable time	V_{IO} = 3 V to 3.6 V; DE = V_{IO}	See 図 6-7		90	120	ns
		V_{IO} = 1.65 V to 1.95 V, DE = V_{IO}			100	130	ns
$t_{PZL(1)}$		V_{IO} = 3 V to 3.6 V; DE = V_{IO}			900	1320	ns
		V_{IO} = 1.65 V to 1.95 V; DE = V_{IO}			900	1320	ns
$t_{PZH(2)}$, $t_{PZL(2)}$	Enable time	DE = 0 V	See 図 6-8		3.3	5.4	µs
$t_{D(OFS)}$	Delay to enter fail-safe operation	C_L = 15 pF	See 図 6-9	7	11	18	µs
$t_{D(FSO)}$	Delay to exit fail-safe operation			540	800	1260	ns
t_{SHDN}	Time to shutdown	DE = 0 V	See 図 6-8	50		500	ns

(1) A, B are driver output and receiver input terminals for Half duplex devices; A/B are Receiver input, Y/Z are driver output terminals for Full duplex device

5.9 Switching Characteristics - 1 Mbps

1Mbps (THVD2410V-EP with SLR = 0 or floating) over recommended operating conditions. All typical values are at 25°C and supply voltage of V_{CC} = 5 V , V_{IO} = 3.3 V, unless otherwise noted. (1)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
Driver							
t_r, t_f	Differential output rise/fall time	V_{CC} = 3 to 3.6 V, Typical at 3.3 V	R_L = 54 Ω, C_L = 50 pF See 図 6-3	125	150	300	ns
		V_{CC} = 4.5 to 5.5 V, Typical at 5 V		130	160	300	ns
t_{PHL}, t_{PLH}	Propagation delay	V_{CC} = 3 to 3.6 V, Typical at 3.3 V			160	240	ns
		V_{CC} = 4.5 to 5.5 V, Typical at 5 V			185	280	ns
$t_{SK(P)}$	Pulse skew, $\lvert t_{PHL} - t_{PLH} \rvert$	V_{CC} = 3 to 3.6 V, Typical at 3.3 V			2	20	ns
		V_{CC} = 4.5 to 5.5 V, Typical at 5 V			2	15	ns
t_{PHZ}, t_{PLZ}	Disable time	$\overline{RE}$ = X	See 図 6-4 and 図 6-5		40	95	ns
t_{PZH}, t_{PZL}	Enable time	$\overline{RE}$ = 0 V			90	275	ns
		$\overline{RE}$ = V_{IO}			3	4.6	µs
t_{SHDN}	Time to shutdown	$\overline{RE}$ = V_{IO}		50		500	ns
Receiver							
t_r, t_f	Output rise/fall time	C_L = 15 pF	See 図 6-6		7	15	ns
t_{PHL}, t_{PLH}	Propagation delay				50	85	ns
$t_{SK(P)}$	Pulse skew, $\lvert t_{PHL} - t_{PLH} \rvert$				4	12.5	ns
t_{PHZ}, t_{PLZ}	Disable time	DE = X			30	40	ns
$t_{PZH(1)}$, $t_{PZL(1)}$	Enable time	V_{IO} = 3 V to 3.6 V; DE = V_{IO}	See 図 6-7		90	120	ns
		V_{IO} = 1.65 V to 1.95 V; DE = V_{IO}			90	130	ns
$t_{PZH(2)}$, $t_{PZL(2)}$	Enable time	DE = 0 V	See 図 6-8		3	4.5	µs
$t_{D(OFS)}$	Delay to enter fail-safe operation	C_L = 15 pF	See 図 6-9	7	10	18	µs
$t_{D(FSO)}$	Delay to exit fail-safe operation			27	40	60	ns
t_{SHDN}	Time to shutdown	DE = 0 V	See 図 6-8	50		500	ns

(1) A, B are driver output and receiver input terminals for Half duplex devices; A/B are Receiver input, Y/Z are driver output terminals for Full duplex device

5.10 Switching Characteristics - 20 Mbps

20-Mbps (THVD2450V-EP, THVD2452V-EP with SLR = V_{IO}) over recommended operating conditions. All typical values are at 25°C and supply voltage of V_{CC} = 5 V, V_{IO} = 3.3 V, unless otherwise noted. (1)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
Driver							
t_r, t_f	Differential output rise/fall time	V_{CC} = 3 to 3.6 V, Typical at 3.3 V	R_L = 54 Ω, C_L = 50 pF See 図 6-3	4	8	15	ns
		V_{CC} = 4.5 to 5.5 V, Typical at 5 V		4	7	15	ns
t_{PHL}, t_{PLH}	Propagation delay	V_{CC} = 3 to 3.6 V, Typical at 3.3 V		6	12	30	ns
		V_{CC} = 4.5 to 5.5 V, Typical at 5 V		4	9	26	ns
$t_{SK(P)}$	Pulse skew, $\lvert t_{PHL} - t_{PLH} \rvert$	V_{CC} = 3 to 3.6 V, Typical at 3.3 V			1	3	ns
		V_{CC} = 4.5 to 5.5 V, Typical at 5 V			1	3	ns
t_{PHZ}, t_{PLZ}	Disable time	$\overline{RE}$ = X	See 図 6-4 and 図 6-5		17	35	ns
t_{PZH}, t_{PZL}	Enable time	$\overline{RE}$ = 0 V			14	39	ns
		$\overline{RE}$ = V_{IO}			3	4.5	µs
t_{SHDN}	Time to shutdown	$\overline{RE}$ = V_{IO}		50		500	ns
Receiver							
t_r, t_f	Output rise/fall time	C_L = 15 pF	See 図 6-6		1.5	6	ns
t_{PHL}, t_{PLH}	Propagation delay	V_{IO} = 3 V to 3.6 V		25	33	58	ns
		V_{IO} = 1.65 V to 1.95 V		25	35	60	ns
$t_{SK(P)}$	Pulse skew, $\lvert t_{PHL} - t_{PLH} \rvert$	C_L = 15 pF			0.5	5	ns
t_{PHZ}, t_{PLZ}	Disable time	DE = X			12	25	ns
$t_{PZH(1)}$, $t_{PZL(1)}$	Enable time	DE = V_{IO}	See 図 6-7		50	82	ns
$t_{PZH(2)}$, $t_{PZL(2)}$	Enable time	DE = 0 V	See 図 6-8		2.8	5	µs
$t_{D(OFS)}$	Delay to enter fail-safe operation	C_L = 15 pF	See 図 6-9	7	10	18	µs
$t_{D(FSO)}$	Delay to exit fail-safe operation			19	32	50	ns
t_{SHDN}	Time to shutdown	DE = 0 V	See 図 6-8	50		500	ns

(1) A, B are driver output and receiver input terminals for Half duplex devices; A/B are Receiver input, Y/Z are driver output terminals for Full duplex device

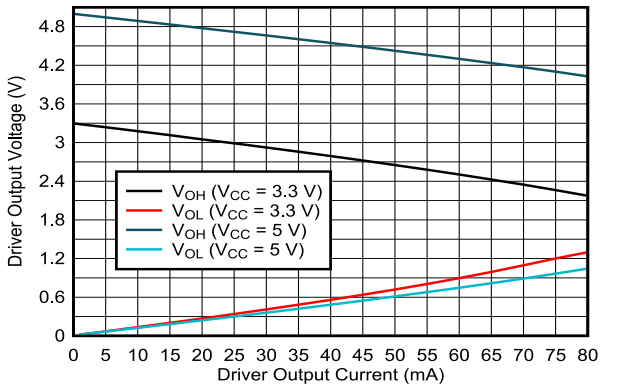
5.11 Switching Characteristics - 50 Mbps

50-Mbps (THVD2450V-EP, THVD2452V-EP with SLR = 0 or floating) over recommended operating conditions. All typical values are at 25°C and supply voltage of V_{CC} = 5 V, V_{IO} = 3.3 V, unless otherwise noted. (1)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
Driver							
t_r, t_f	Differential output rise/fall time	V_{IO} = 3 V to 3.6 V, V_{CC} = 3 to 3.6 V, Typical at 3.3 V	R_L = 54 Ω, C_L = 50 pF See 図 6-3	1	5	7	ns
		V_{CC} = 4.5 to 5.5 V, Typical at 5 V		1	5	6	ns
t_{PHL}, t_{PLH}	Propagation delay	V_{IO} = 3 V to 3.6 V, V_{CC} = 3 to 3.6 V, Typical at 3.3 V		5	11	19	ns
		V_{IO} = 1.65 V to 1.95 V, V_{CC} = 3 to 3.6 V, Typical at 3.3 V		7	12	22	ns
		V_{IO} = 3 V to 3.6 V, V_{CC} = 4.5 to 5.5 V, Typical at 5 V		4	8	15	ns
		V_{IO} = 1.65 V to 1.95 V, V_{CC} = 4.5 to 5.5 V, Typical at 5 V		6	10	19	ns
$t_{SK(P)}$	Pulse skew, $\lvert t_{PHL} - t_{PLH} \rvert$	V_{CC} = 3 to 3.6 V, Typical at 3.3 V			1	3	ns
		V_{CC} = 4.5 to 5.5 V, Typical at 5 V			1	3	ns
t_{PHZ}, t_{PLZ}	Disable time	$\overline{RE}$ = X	See 図 6-4 and 図 6-5		14	30	ns
t_{PZH}, t_{PZL}	Enable time	$\overline{RE}$ = 0 V ; V_{IO} = 1.65 V to 1.95 V, 2.25 V to 2.75 V			20	35	ns
		$\overline{RE}$ = 0 V ; V_{IO} = 3 V to V_{CC} V			15	32	ns
		$\overline{RE}$ = V_{IO}			2.5	4.5	µs
t_{SHDN}	Time to shutdown	$\overline{RE}$ = V_{IO}		50		500	ns
Receiver							
t_r, t_f	Output rise/fall time	C_L = 15 pF	See 図 6-6		1.5	6	ns
t_{PHL}, t_{PLH}	Propagation delay	C_L = 15 pF, V_{IO} = 3 V to 3.6 V	See 図 6-6	25	33	58	ns
t_{PHL}, t_{PLH}	Propagation delay	C_L = 15 pF, V_{IO} = 1.65 V to 1.95 V	See 図 6-6	25	35	60	ns
$t_{SK(P)}$	Pulse skew, $\lvert t_{PHL} - t_{PLH} \rvert$	C_L = 15 pF	See 図 6-6		0.5	5	ns
t_{PHZ}, t_{PLZ}	Disable time	DE = X			12	25	ns
$t_{PZH(1)}$, $t_{PZL(1)}$	Enable time	DE = V_{IO}	V_{IO} = 1.65 V to 1.95 V, See 図 6-7		50	82	ns
			V_{IO} = 3 V to 3.6 V, See 図 6-7		50	75	ns
$t_{PZH(2)}$, $t_{PZL(2)}$	Enable time	DE = 0 V	See 図 6-8		2.8	5	µs
$t_{D(OFS)}$	Delay to enter fail-safe operation	C_L = 15 pF	See 図 6-9	7	10	18	µs
$t_{D(FSO)}$	Delay to exit fail-safe operation			19	32	50	ns
t_{SHDN}	Time to shutdown	DE = 0 V	See 図 6-8	50		500	ns

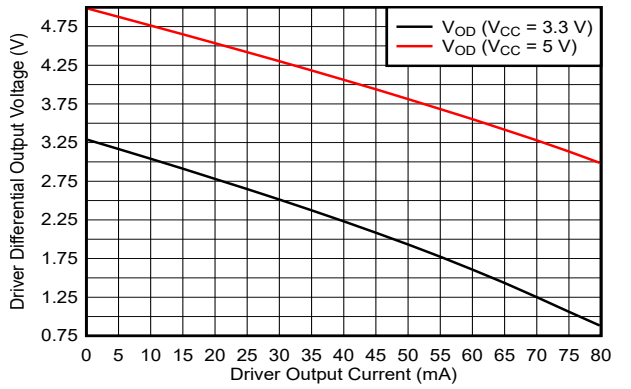
(1) A, B are driver output and receiver input terminals for Half duplex devices; A/B are Receiver input, Y/Z are driver output terminals for Full duplex device

5.12 Typical Characteristics



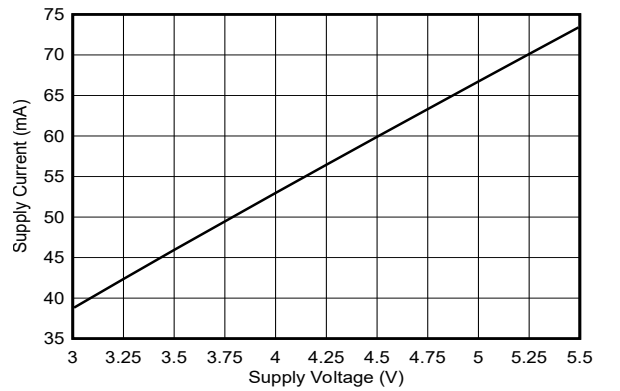
DE = V_{CC} D = 0V T_A = 25 °C

図 5-1. Driver Output Voltage vs Driver Output Current



DE = V_{CC} D = 0V T_A = 25 °C

図 5-2. Driver Differential Output voltage vs Driver Output Current



T_A = 25 °C DE = D = V_{CC} R_L = 54Ω

図 5-3. Driver Output Current vs Supply Voltage

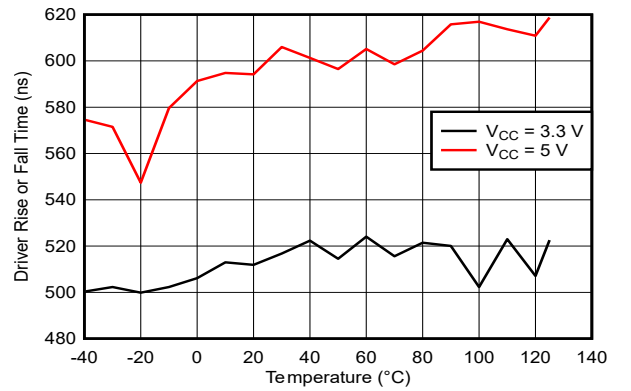


図 5-4. THVD2410V-EP Driver Rise or Fall Time vs Temperature

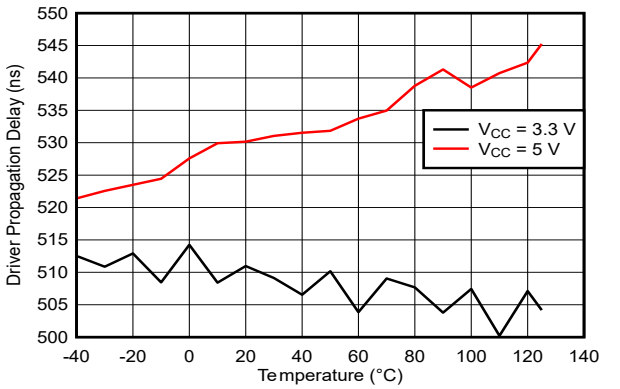
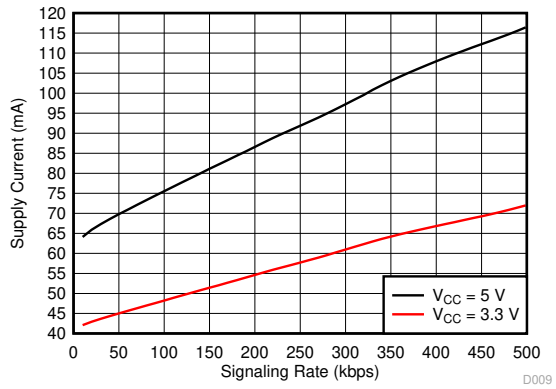


図 5-5. THVD2410V-EP Driver Propagation Delay vs Temperature



T_A = 25 °C R_L = 54Ω

図 5-6. THVD2410V-EP Supply Current vs Signal Rate

5.12 Typical Characteristics (continued)

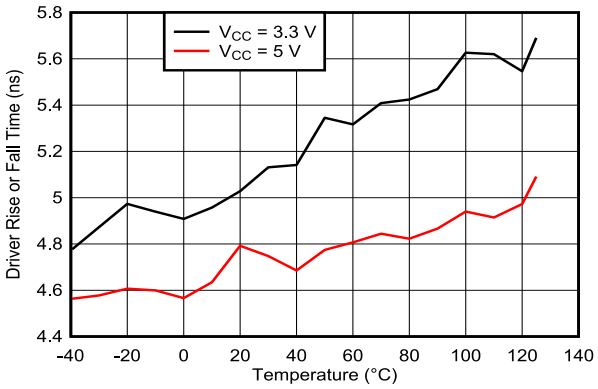


図 5-7. THVD2450V-EP: 50Mbps Driver Rise or Fall Time vs Temperature

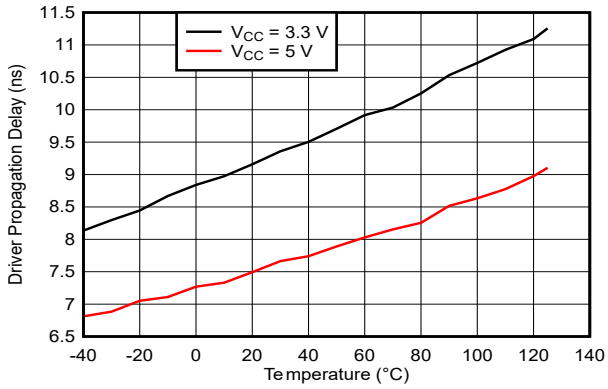


図 5-8. THVD2450V-EP: 50Mbps Driver Propagation Delay vs Temperature

6 Parameter Measurement Information

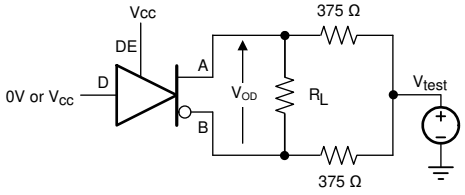


図 6-1. Measurement of Driver Differential Output Voltage With Common-Mode Load

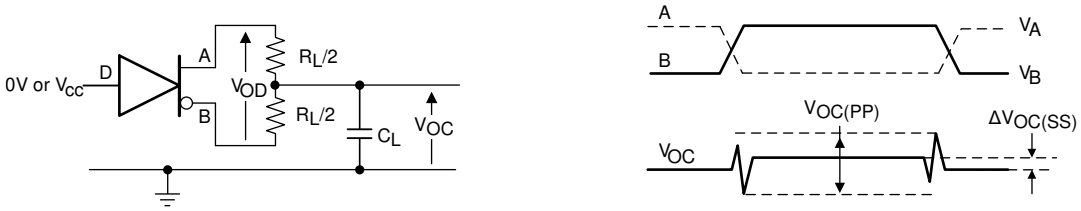


図 6-2. Measurement of Driver Differential and Common-Mode Output With RS-485 Load

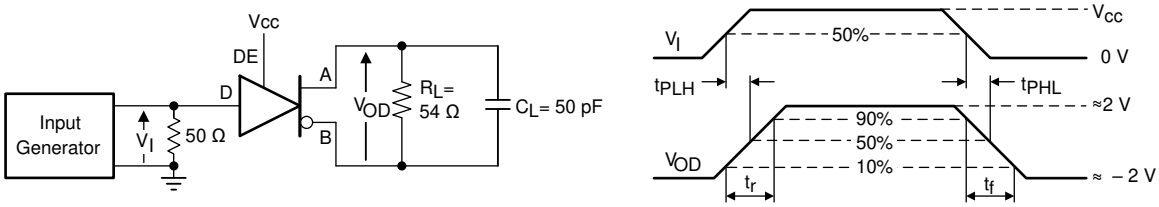


図 6-3. Measurement of Driver Differential Output Rise and Fall Times and Propagation Delays

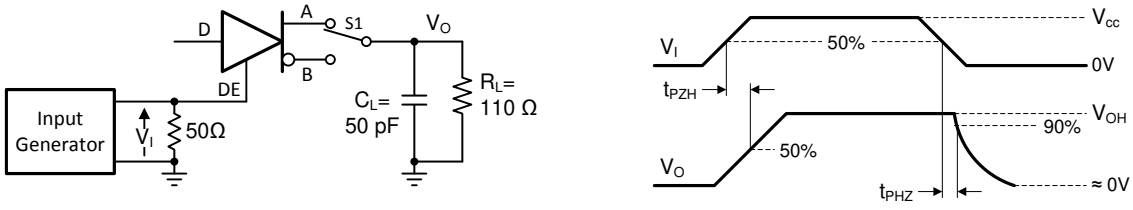


図 6-4. Measurement of Driver Enable and Disable Times With Active High Output and Pull-Down Load

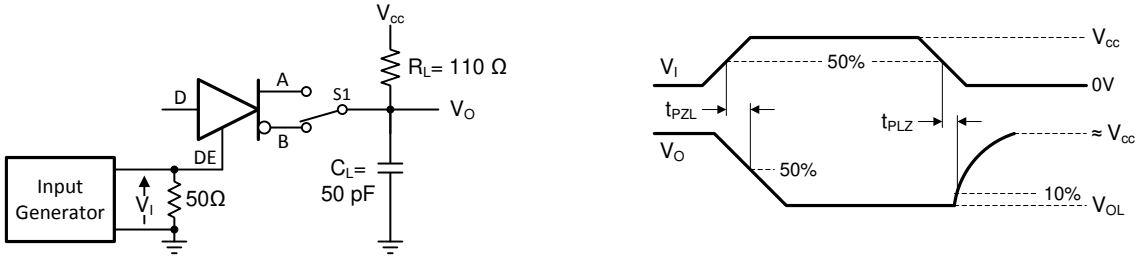


図 6-5. Measurement of Driver Enable and Disable Times With Active Low Output and Pull-up Load

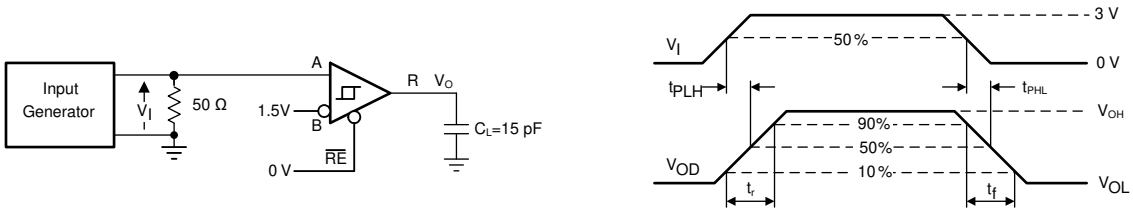


図 6-6. Measurement of Receiver Output Rise and Fall Times and Propagation Delays

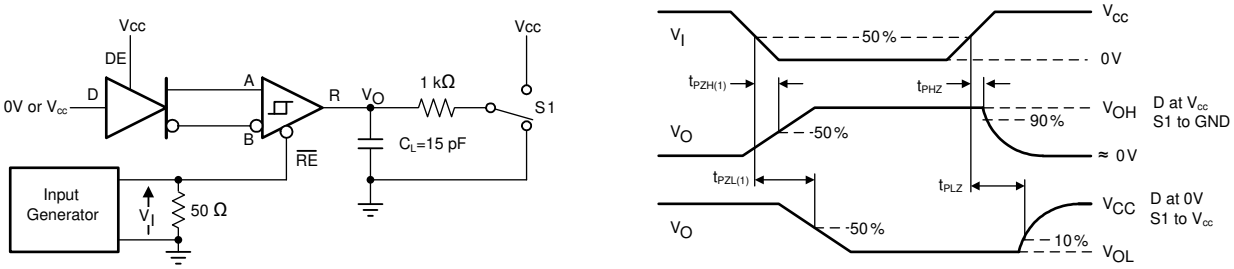


図 6-7. Measurement of Receiver Enable/Disable Times With Driver Enabled

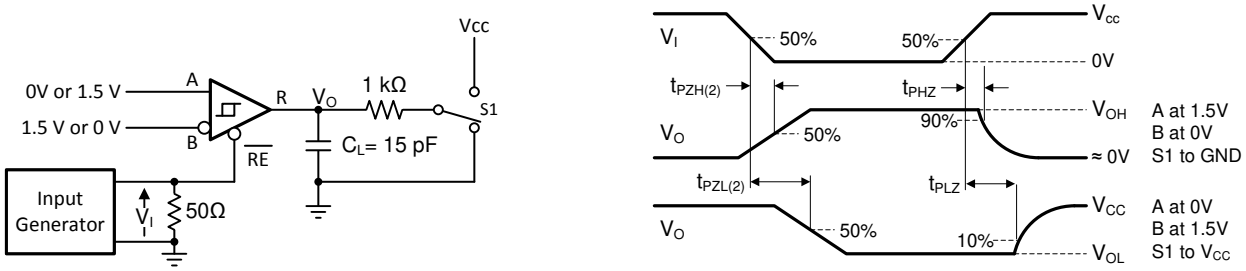


図 6-8. Measurement of Receiver Enable Times With Driver Disabled

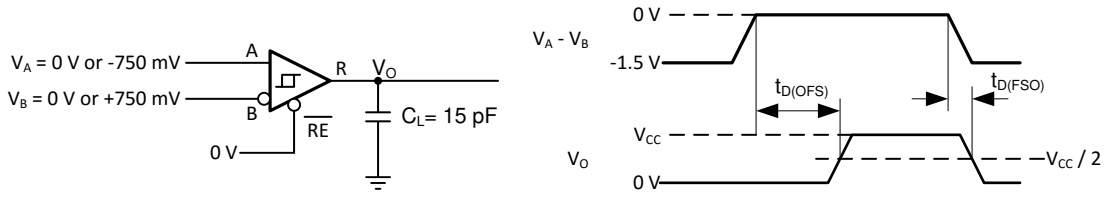


図 6-9. Measurement of Fail-Safe Delay

7 Detailed Description

7.1 Overview

THVD2410V-EP and THVD2450V-EP are fault-protected, half duplex RS-485 transceivers available in two speed grades suitable for data transmission up to 1Mbps and 50Mbps respectively. THVD2452V-EP is a full-duplex transceiver that can be configured for two speeds using the SLR pin: 20Mbps and 50Mbps. The devices have active-high driver enables and active-low receiver enables. A shutdown current of less than 1µA can be achieved by disabling both driver and receiver.

7.2 Functional Block Diagrams

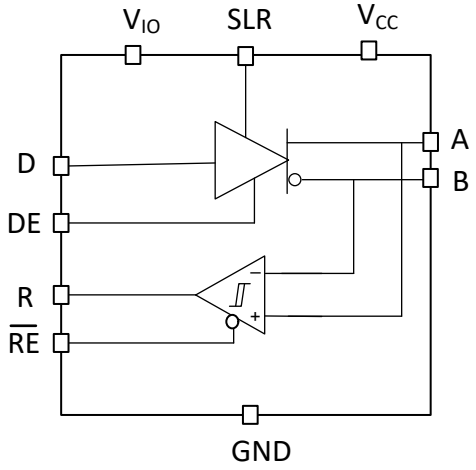


図 7-1. THVD2410V-EP and THVD2450V-EP Block Diagram

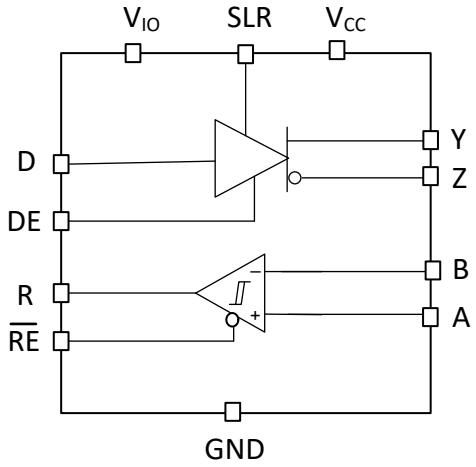


図 7-2. THVD2452V-EP Block Diagram

7.3 Feature Description

7.3.1 ±70-V Fault Protection

THVD24xxV-EP transceivers have extended bus fault protection compared to standard RS-485 devices. Transceivers that operate in rugged industrial environments are often exposed to voltage transients greater than the -7V to +12V defined by the TIA/EIA-485A standard. To protect against such conditions, the generic RS-485 devices with lower absolute maximum ratings requires expensive external protection components. To simplify system design and reduce overall system cost, THVD24xxV-EP devices are protected up to ±70V without the need for any external components.

7.3.2 Integrated IEC ESD and EFT Protection

Internal ESD protection circuits protect the transceivers against electrostatic discharges (ESD) according to IEC 61000-4-2 of up to ±12kV and against electrical fast transients (EFT) according to IEC 61000-4-4 of up to ±4kV. THVD24xxV-EP ESD structures help to limit voltage excursions and recover from them quickly that they allow EFT Criterion A at the system level (no data loss when transient noise is present).

7.3.3 Driver Overvoltage and Overcurrent Protection

The THVD24xxV-EP drivers are protected against any DC supply shorts in the range of -70V to +70V. The devices internally limit the short circuit current to ±250mA to comply with the TIA/EIA-485A standard. In addition, a fold-back current limiting circuit further reduces the driver short circuit current to less than ±5mA if the output fault voltage exceeds |±25V|.

All devices feature thermal shutdown protection that disables the driver and the receiver if the junction temperature exceeds the T_{SHDN} threshold due to excessive power dissipation.

7.3.4 Enhanced Receiver Noise Immunity

The differential receivers of THVD24xxV-EP feature fully symmetric thresholds to maintain duty cycle of the signal even with small input amplitudes. In addition, 250mV (typical) hysteresis provides noise immunity.

7.3.5 Receiver Fail-Safe Operation

The receivers are fail-safe to invalid bus states caused by the following:

- Open bus conditions, such as a disconnected connector
- Shorted bus conditions, such as cable damage shorting the twisted-pair together
- Idle bus conditions that occur when no driver on the bus is actively driving

In any of these cases, the receiver outputs a fail-safe logic high state if the input amplitude stays for longer than $t_{D(OFS)}$ at less than $|V_{TH\_FSH}|$.

7.3.6 Low-Power Shutdown Mode

Driving DE low and $\overline{RE}$ high for longer than 500ns puts the devices into the shutdown mode. If either DE goes high or $\overline{RE}$ goes low, the counters reset. The devices does not enter the shutdown mode if the enable pins are in disable state for less than 50ns. This feature prevents the devices from accidentally going into shutdown mode due to skew between DE and $\overline{RE}$.

7.4 Device Functional Modes

When the driver enable pin, DE, is logic high, the differential outputs A and B follow the logic states at data input D. A logic high at D causes A to turn high and B to turn low. In this case the differential output voltage defined as $V_{OD} = V_A – V_B$ is positive. When D is low, the output states reverse: B turns high, A becomes low, and V_{OD} is negative.

When DE is low, both outputs turn high-impedance. In this condition the logic state at D is irrelevant. The DE pin has an internal pull-down resistor to ground, thus when left open the driver is disabled (high-impedance) by default. The D pin has an internal pull-up resistor to V_{CC}, thus, when left open while the driver is enabled, output A turns high and B turns low.

表 7-1. Driver Function Table

INPUT	ENABLE	OUTPUTS		FUNCTION
D	DE	A/Y	B/Z	
H	H	H	L	Actively drive bus high
L	H	L	H	Actively drive bus low
X	L	Z	Z	Driver disabled
X	OPEN	Z	Z	Driver disabled by default
OPEN	H	H	L	Actively drive bus high by default

When the receiver enable pin, $\overline{RE}$, is logic low, the receiver is enabled. When the differential input voltage defined as $V_{ID} = V_A – V_B$ is higher than the positive input threshold, V_{TH+}, the receiver output, R, turns high. When V_{ID} is lower than the negative input threshold, V_{TH-}, the receiver output, R, turns low. If V_{ID} is between V_{TH+} and V_{TH-} the output is indeterminate.

When $\overline{RE}$ is logic high or left open, the receiver output is high-impedance and the magnitude and polarity of V_{ID} are irrelevant. Internal biasing of the receiver inputs causes the output to go failsafe-high when the transceiver is disconnected from the bus (open-circuit), the bus lines are shorted to one another (short-circuit), or the bus is not actively driven (idle bus).

表 7-2. Receiver Function Table

DIFFERENTIAL INPUT	ENABLE	OUTPUT	FUNCTION
$V_{ID} = V_A – V_B$	$\overline{RE}$	R	
$V_{TH+} < V_{ID}$	L	H	Receive valid bus high
$V_{TH-} < V_{ID} < V_{TH+}$	L	?	Indeterminate bus state
$V_{ID} < V_{TH-}$	L	L	Receive valid bus low
X	H	Z	Receiver disabled
X	OPEN	Z	Receiver disabled by default
Open-circuit bus	L	H	Fail-safe high output
Short-circuit bus	L	H	Fail-safe high output
Idle (terminated) bus	L	H	Fail-safe high output

表 7-3 shows SLR (slew rate select) pin functionality. SLR has integrated pull-down, so the device remains in higher speed mode until SLR is pulled high which limits the slew rate and puts the device in slower speed mode.

表 7-3. SLR pin control

Device	Functionality w.r.t SLR pin
THVD2410V-EP	SLR = Low or floating: Both transmitter (TX) and receiver (RX) maximum speed is 1Mbps SLR = High: Both TX and RX maximum speed is limited to 250kbps
THVD2450V-EP, THVD2452V-EP	SLR = Low or floating: Both transmitter (TX) and receiver (RX) maximum speed is 50Mbps SLR = High: Both TX and RX maximum speed is limited to 20Mbps

表 7-4 shows the device behavior in undervoltage scenarios:

表 7-4. Supply Function Table

Supply Function Table	V_{IO}	Driver Output	Receiver Output
> $UV_{VCC(rising)}$	> $UV_{VIO(rising)}$	Determined by DE and D inputs	Determined by $\overline{RE}$ and A-B
< $UV_{VCC(falling)}$	> $UV_{VIO(rising)}$	High impedance	High impedance
> $UV_{VCC(rising)}$	< $UV_{VIO(falling)}$	High impedance	High impedance
< $UV_{VCC(falling)}$	< $UV_{VIO(falling)}$	High impedance	High impedance

8 Application and Implementation

注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

THVD2410 and THVD2450 are fault-protected, half-duplex RS-485 transceivers commonly used for asynchronous data transmissions. For these devices, the driver and receiver enable pins allow for the configuration of different operating modes.

8.2 Typical Application

An RS-485 bus consists of multiple transceivers connecting in parallel to a bus cable. To eliminate line reflections, each cable end is terminated with a termination resistor, R_T, whose value matches the characteristic impedance, Z_0, of the cable. This method, known as parallel termination, generally allows for higher data rates over longer cable length.

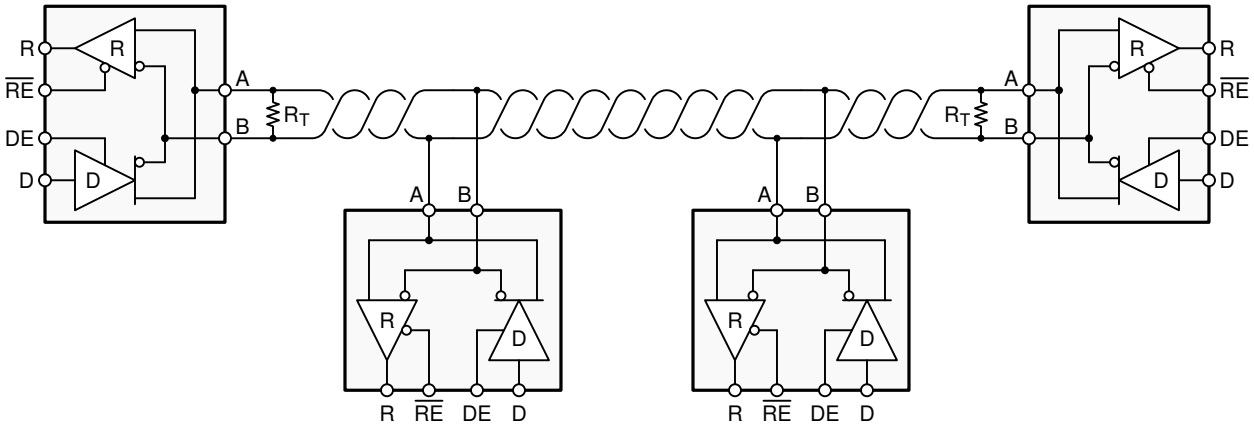


図 8-1. Typical RS-485 Network With Half-Duplex Transceivers

8.2.1 Design Requirements

RS-485 is a robust electrical standard suitable for long-distance networking that may be used in a wide range of applications with varying requirements, such as distance, data rate, and number of nodes.

8.2.1.1 Data Rate and Bus Length

There is an inverse relationship between data rate and cable length, which means the higher the data rate, the short the cable length; and conversely, the lower the data rate, the longer the cable length. While most RS-485 systems use data rates between 10kbps and 100kbps, some applications require data rates up to 250kbps at distances of 4000 feet and longer. Longer distances are possible by allowing for small signal jitter of up to 5 or 10%.

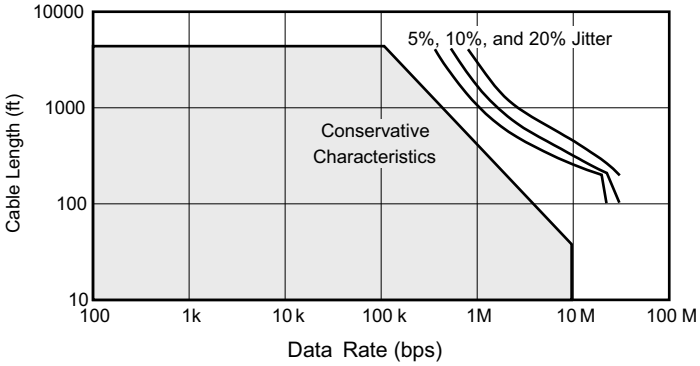


図 8-2. Cable Length vs Data Rate Characteristic

Even higher data rates are achievable (that is, 50Mbps for the THVD2450) in cases where the interconnect is short enough (or has suitably low attenuation at signal frequencies) to not degrade the data.

8.2.1.2 Stub Length

When connecting a node to the bus, the distance between the transceiver inputs and the cable trunk, known as the stub, should be as short as possible. Stubs present a non-terminated piece of bus line which can introduce reflections of varying phase as the length of the stub increases. As a general guideline, the electrical length, or round-trip delay, of a stub should be less than one-tenth of the rise time of the driver, thus giving a maximum physical stub length as shown in 式 1.

$$L_{(STUB)} \leq 0.1 \times t_r \times v \times c \quad (1)$$

where

- t_r is the 10/90 rise time of the driver
- c is the speed of light (3×10^8 m/s)
- v is the signal velocity of the cable or trace as a factor of c

8.2.1.3 Bus Loading

The RS-485 standard specifies that a compliant driver must be able to drive 32 unit loads (UL), where 1 unit load represents a load impedance of approximately 12kΩ. Because the THVD24xxV-EP devices consist of 1/8 UL transceivers, connecting up to 256 receivers to the bus is possible.

8.2.1.4 Transient Protection

The bus pins of the THVD24xxV-EP transceivers include on-chip ESD protection against ±30kV HBM and ±12kV IEC 61000-4-2 contact discharge. The International Electrotechnical Commission (IEC) ESD test is far more severe than the HBM ESD test. The 50% higher charge capacitance, $C_{(S)}$, and 78% lower discharge resistance, $R_{(D)}$, of the IEC model produce significantly higher discharge currents than the HBM model. As stated in the IEC 61000-4-2 standard, contact discharge is the preferred transient protection test method.

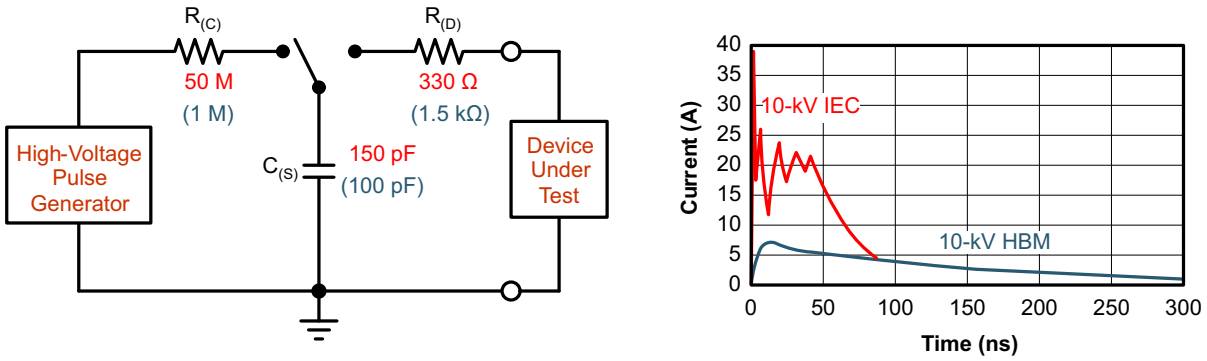


図 8-3. HBM and IEC ESD Models and Currents in Comparison (HBM Values in Parenthesis)

The on-chip implementation of IEC ESD protection significantly increases the robustness of equipment. Common discharge events occur because of human contact with connectors and cables. Designers may choose to implement protection against longer duration transients, typically referred to as surge transients.

EFTs are generally caused by relay-contact bounce or the interruption of inductive loads. Surge transients often result from lightning strikes (direct strike or an indirect strike which induce voltages and currents), or the switching of power systems, including load changes and short circuit switching. These transients are often encountered in industrial environments, such as factory automation and power-grid systems.

図 8-4 compares the pulse-power of the EFT and surge transients with the power caused by an IEC ESD transient. The left side diagram shows the relative pulse-power for a 0.5kV surge transient and 4kV EFT transient, both of which dwarf the 10kV ESD transient visible in the lower-left corner. 500V surge transients are representative of events that may occur in factory environments in industrial and process automation.

The right side diagram shows the pulse power of a 6kV surge transient, relative to the same 0.5kV surge transient. 6kV surge transients are most likely to occur in power generation and power-grid systems.

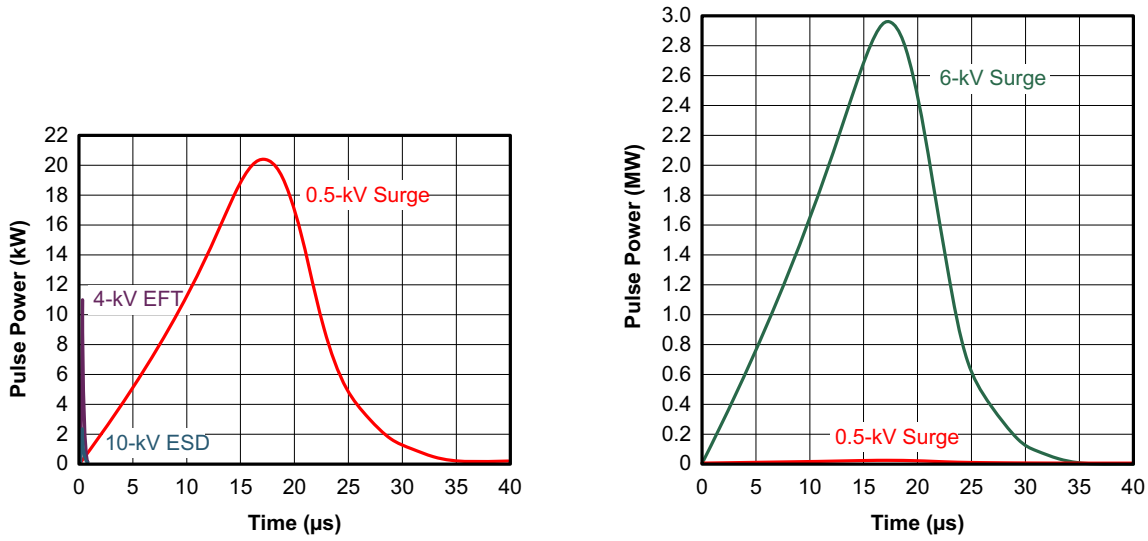


図 8-4. Power Comparison of ESD, EFT, and Surge Transients

For surge transients, high-energy content is characterized by long pulse duration and slow decaying pulse power. The electrical energy of a transient that is dumped into the internal protection cells of a transceiver is converted into thermal energy, which heats and destroys the protection cells, thus destroying the transceiver. 図 8-5 shows the large differences in transient energies for single ESD, EFT, surge transients, and an EFT pulse train that is commonly applied during compliance testing.

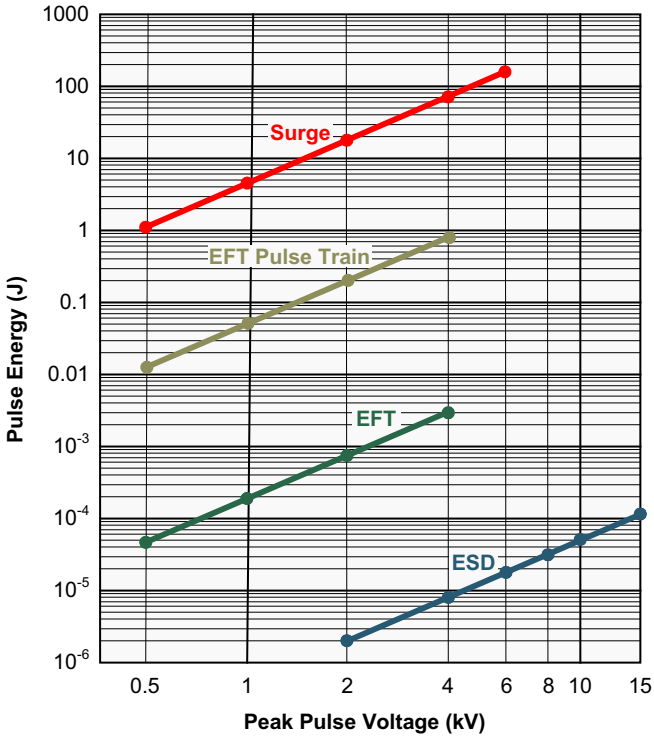


図 8-5. Comparison of Transient Energies

8.2.2 Detailed Design Procedure

図 8-6 suggests a protection circuit against 1kV surge (IEC 61000-4-5) transients. 表 8-1 shows the associated bill of materials. SMAJ30CA TVS diodes are rated to operate up to 30V. This makes sure the protection diodes do not conduct if a direct RS-485 bus shorts to 24V DC industrial power rail.

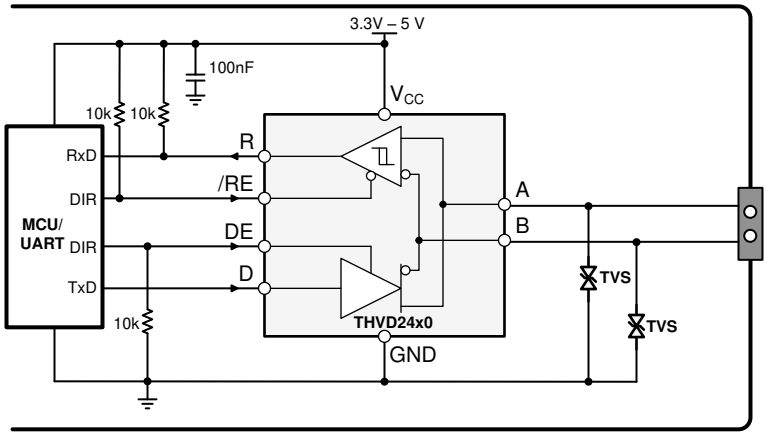


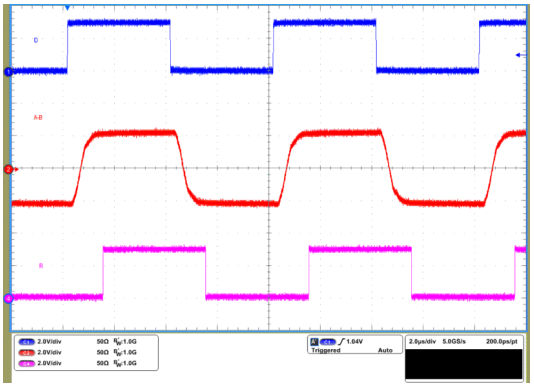
図 8-6. Transient Protection Against Surge Transients for Half-Duplex Devices

表 8-1. Components List

DEVICE	FUNCTION	ORDER NUMBER	MANUFACTURER(1)
XCVR	RS-485 transceiver	THVD2410V-EP Or THVD2450V-EP	TI
TVS	Bidirectional 400-W transient suppressor	SMAJ30CA	Littelfuse

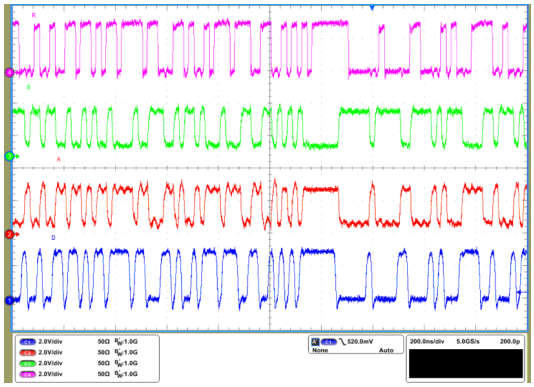
(1) See Third-Party Products Disclaimer

8.2.3 Application Curves



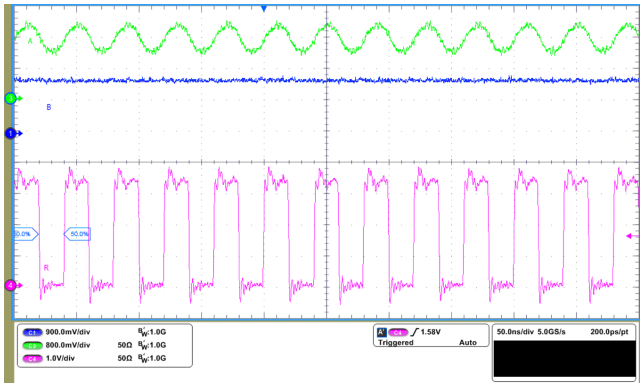
THVD2410V-EP V_{CC} = 3.3V R_L = 50Ω
Random (PRBS7) data at 250kbps

図 8-7. THVD2410V-EP Waveforms at V_{CC} = 3.3V



THVD2450V-EP V_{CC} = 3.3V R_L = 50Ω
Random (PRBS7) data at 50Mbps

図 8-8. THVD2450V-EP Waveforms at V_{CC} = 3.3V



THVD2450V-EP Pin A is supplied with ±200mV with 1.5V DC bias Pin B = 1.5V

図 8-9. THVD2450V-EP Receiver Waveforms with ±200mV V_{ID}

8.3 Power Supply Recommendations

For reliable operation at all data rates and supply voltages, each supply should be decoupled with a 100nF ceramic capacitor located as close to the supply pins as possible. This helps to reduce supply voltage ripple present on the outputs of switched-mode power supplies and also helps to compensate for the resistance and inductance of the PCB power planes.

8.4 Layout

8.4.1 Layout Guidelines

Robust and reliable bus node design often requires the use of external transient protection devices to protect against surge transients that may occur in industrial environments. Since these transients have a wide frequency bandwidth (from approximately 3MHz to 300MHz), high-frequency layout techniques should be applied during PCB design.

1. Place the protection circuitry close to the bus connector to prevent noise transients from propagating across the board.
2. Use V_{CC} and ground planes to provide low inductance. Note that high-frequency currents tend to follow the path of least impedance and not the path of least resistance.
3. Design the protection components into the direction of the signal path. Do not force the transient currents to divert from the signal path to reach the protection device.
4. Apply 100nF to 220nF decoupling capacitors as close as possible to the V_{CC} and V_{IO} pins of transceiver, UART and/or controller ICs on the board.
5. Use at least two vias for the ground connections of the decoupling capacitors at the power pins and the protection devices to minimize the effective via inductance.
6. Use 1kΩ to 10kΩ pull-up and pull-down resistors for enable lines to limit noise currents in these lines during transient events.
7. Insert pulse-proof resistors into the A and B bus lines if the TVS clamping voltage is higher than the specified maximum voltage of the transceiver bus pins. These resistors limit the residual clamping current into the transceiver and prevent it from latching up.

8.4.2 Layout Example

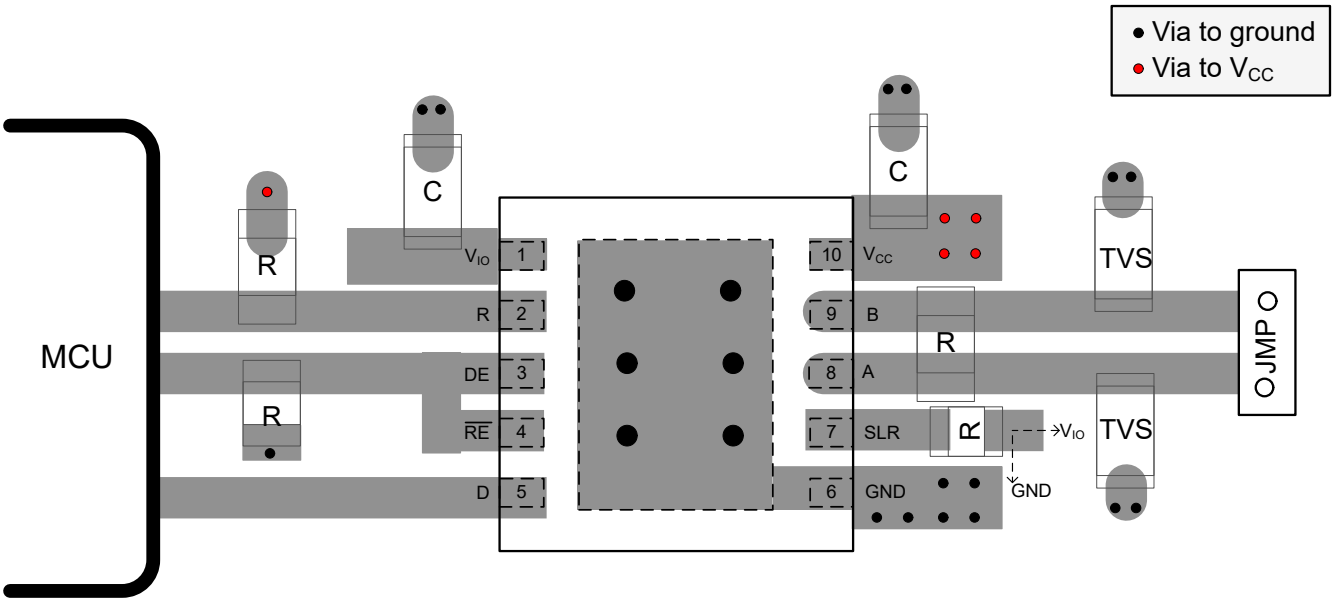


図 8-10. THVD2410V-EP, THVD2450V-EP (Half-Duplex) Layout Example

9 Device and Documentation Support

9.1 Device Support

9.1.1 サード・パーティ製品に関する免責事項

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9.6 用語集

テキサス・インスツルメンツ用語集　　この用語集には、用語や略語の一覧および定義が記載されています。

10 Revision History

Changes from Revision * (May 2024) to Revision A (August 2024)	Page
• 「特長」のバス I/O 保護の一覧を変更	1
• 動作中の電流を次のように変更：「特長」の < 5.6mA から < 5.3mA に	1
• Added table note 1 to THVD2452V-EP in the *IEC ESD Ratings* table	4

11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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郵送先住所:Texas Instruments, Post Office Box 655303, Dallas, Texas 75265

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
THVD2410VDRCREP	ACTIVE	VSON	DRC	10	5000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-55 to 125	V2410	Samples
THVD2450VDRCREP	ACTIVE	VSON	DRC	10	5000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-55 to 125	V2450	Samples
THVD2452VDREP	ACTIVE	SOIC	D	14	2500	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-55 to 125	T2452V	Samples
V62/22613-01XE	ACTIVE	VSON	DRC	10	5000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR		V2410	Samples
V62/22613-02XE	ACTIVE	VSON	DRC	10	5000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR		V2450	Samples
V62/22613-03XE	ACTIVE	SOIC	D	14	2500	RoHS & Green	NIPDAU	Level-1-260C-UNLIM		T2452V	Samples

(1) The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".
RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.
Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

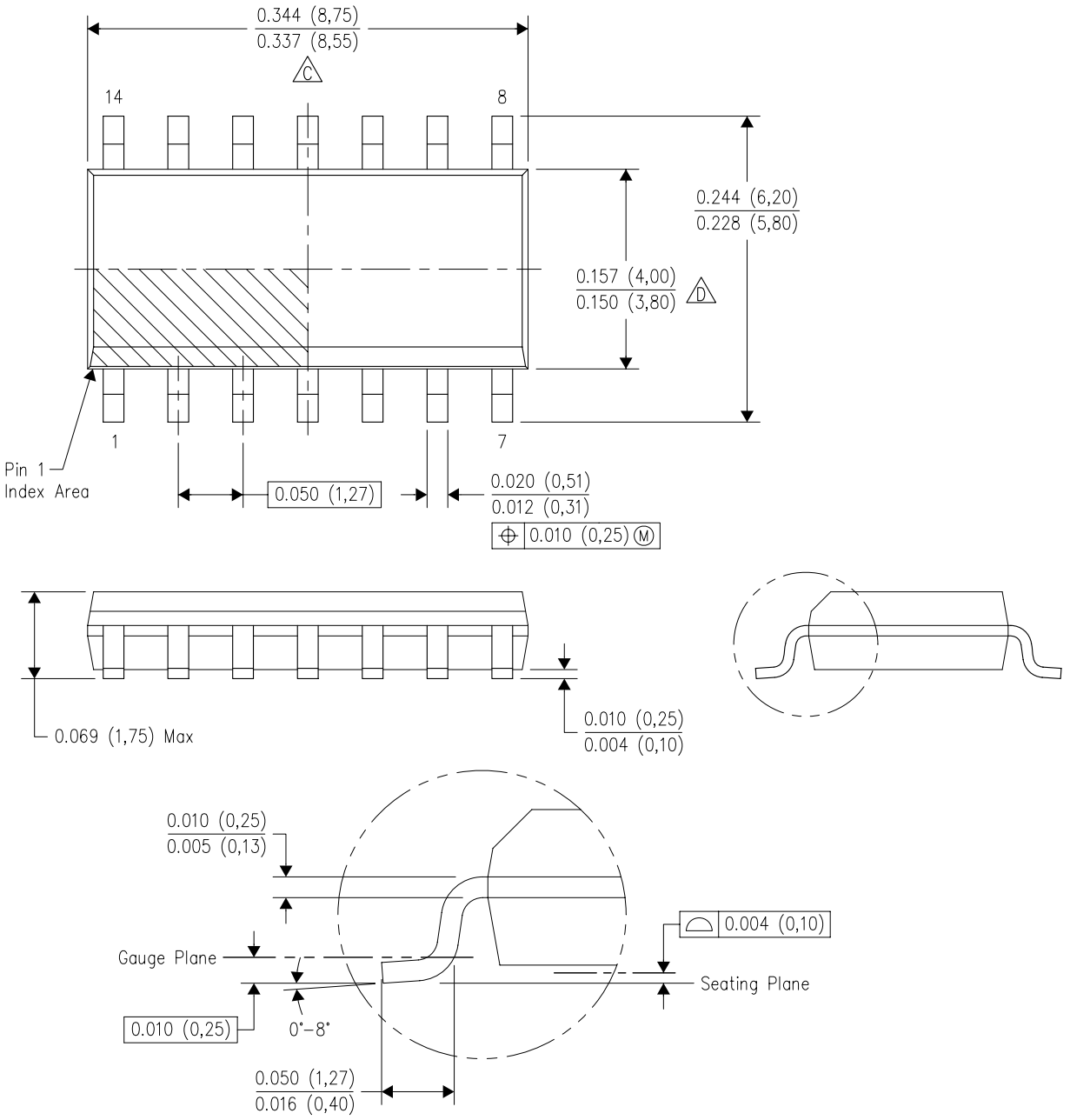
OTHER QUALIFIED VERSIONS OF THVD2410V-EP, THVD2450V-EP, THVD2452V-EP :

- Catalog : THVD2410V, THVD2450V, THVD2452V

NOTE: Qualified Version Definitions:

- Catalog - TI's standard catalog product

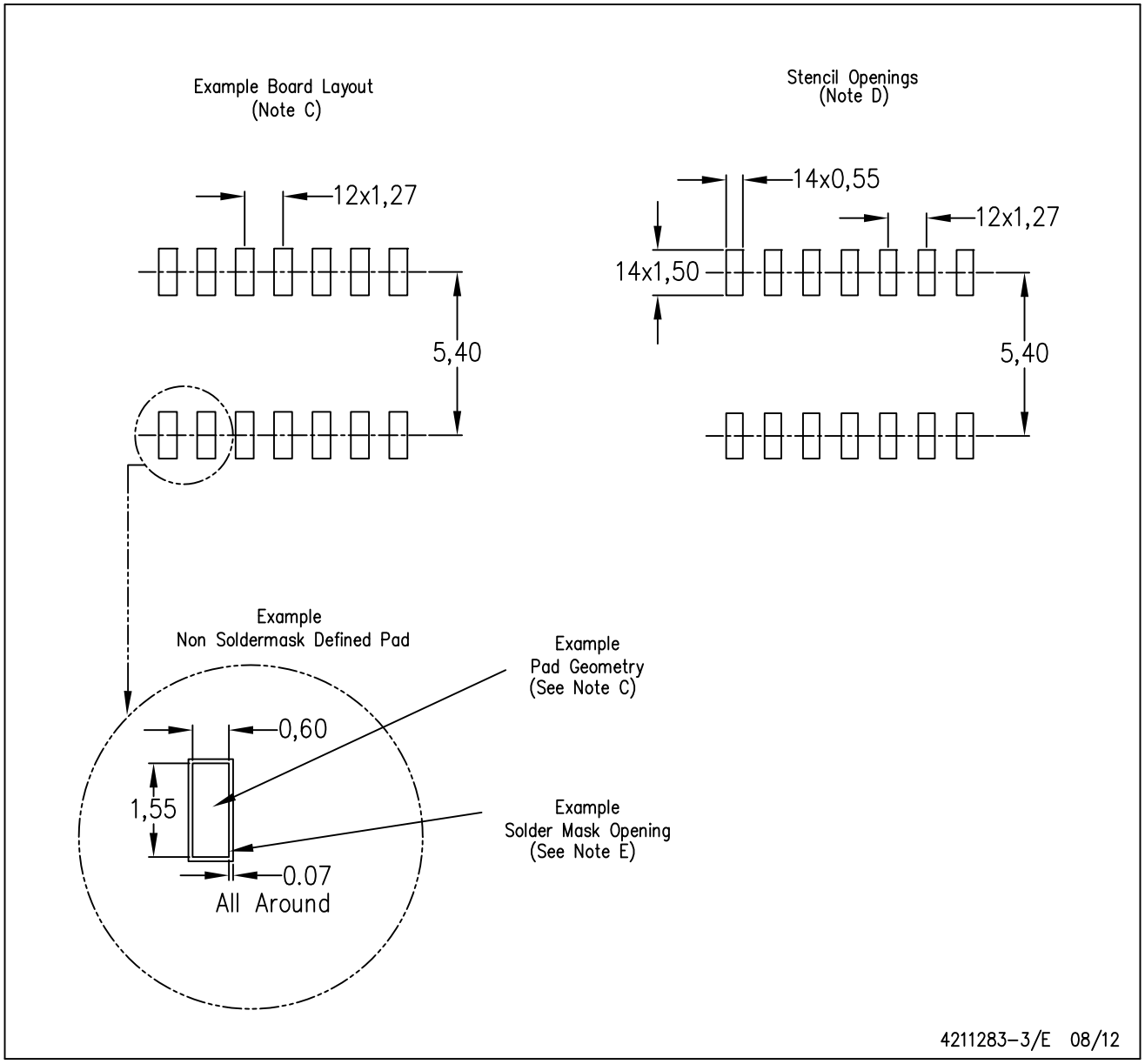
D (R–PDSO–G14) PLASTIC SMALL OUTLINE



4040047–5/M 06/11

NOTES:
A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
D. Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
E. Reference JEDEC MS–012 variation AB.

D (R–PDSO–G14) PLASTIC SMALL OUTLINE



NOTES:
A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Publication IPC–7351 is recommended for alternate designs.
D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC–7525 for other stencil recommendations.
E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

GENERIC PACKAGE VIEW

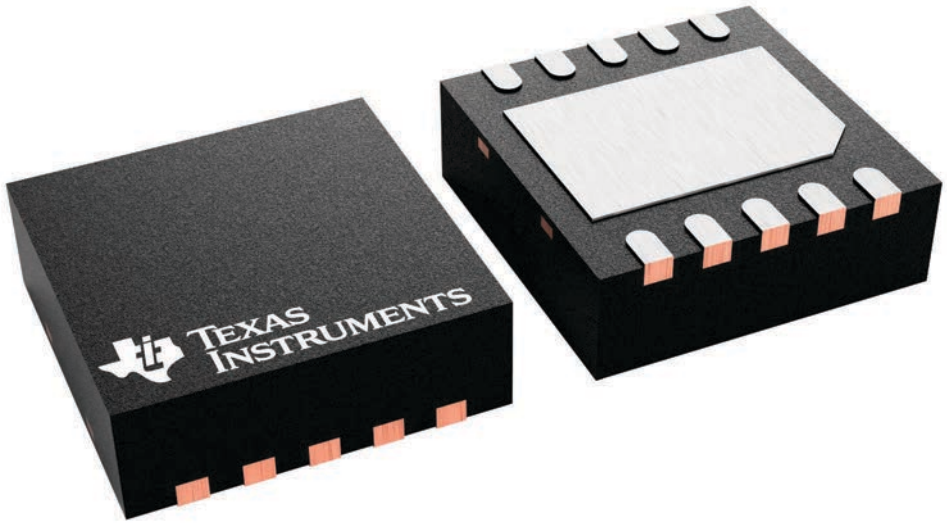
DRC 10

VSON - 1 mm max height

3 x 3, 0.5 mm pitch

PLASTIC SMALL OUTLINE - NO LEAD

This image is a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.



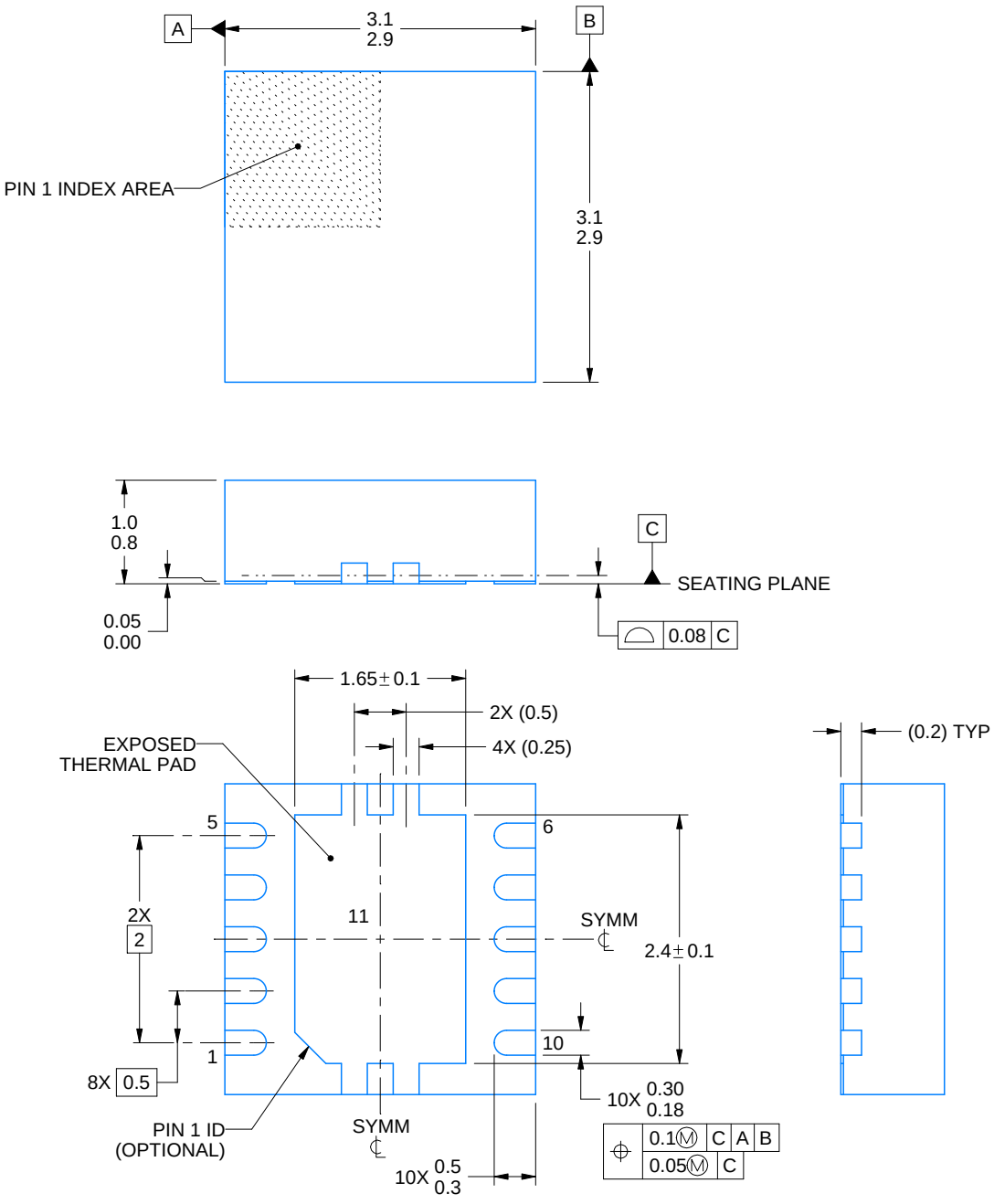
4226193/A

DRC0010J

PACKAGE OUTLINE

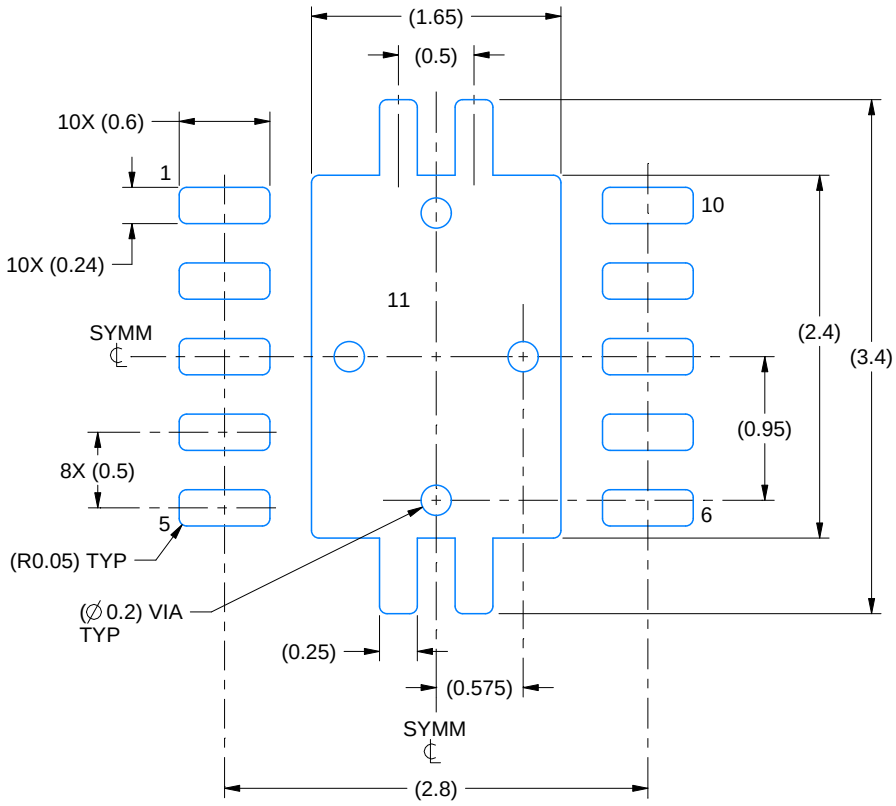
VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD

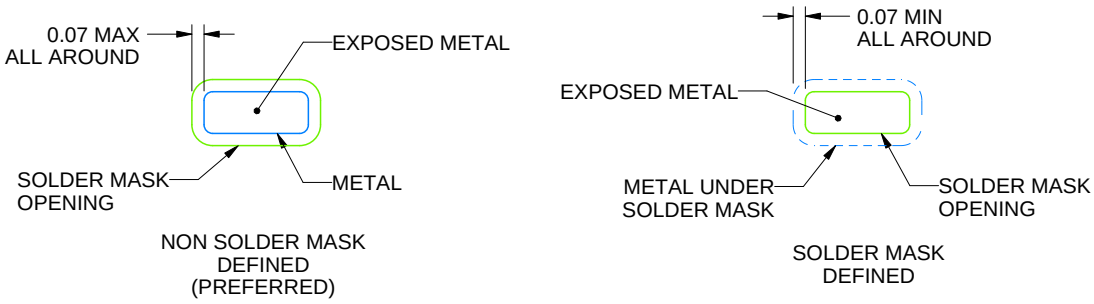


NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:20X



SOLDER MASK DETAILS

4218878/B 07/2018

NOTES: (continued)

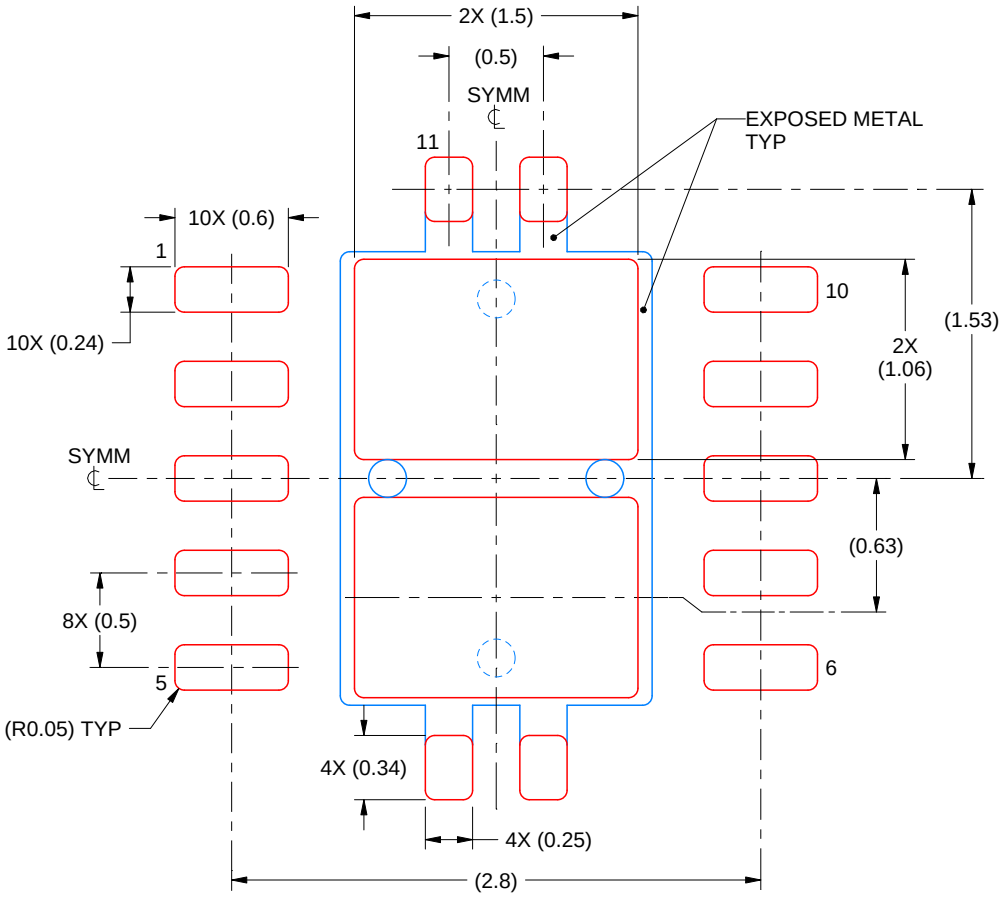
4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

EXAMPLE STENCIL DESIGN

DRC0010J

VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD 11:
80% PRINTED SOLDER COVERAGE BY AREA
SCALE:25X

4218878/B 07/2018

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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