

Technical documentation

₩ **TEXAS INSTRUMENTS**

[BQ24160](https://www.ti.com/product/ja-jp/bq24160?qgpn=bq24160), [BQ24160A](https://www.ti.com/product/ja-jp/bq24160a?qgpn=bq24160a), [BQ24161,](https://www.ti.com/product/ja-jp/bq24161?qgpn=bq24161) [BQ24161B,](https://www.ti.com/product/ja-jp/bq24161b?qgpn=bq24161b) [BQ24163](https://www.ti.com/product/ja-jp/bq24163?qgpn=bq24163), [BQ24168](https://www.ti.com/product/ja-jp/bq24168?qgpn=bq24168) [JAJSOY8H](https://www.tij.co.jp/jp/lit/pdf/JAJSOY8) – NOVEMBER 2011 – REVISED JULY 2022

BQ2416xx パワー・パス管理および **I2C** インターフェイス搭載、**2.5A**、デュア ル入力、シングル・セルのスイッチ・モード・リチウムイオン・バッテリ・ チャージャ

1 特長

- 独立のパワー・パス制御機能を搭載した、高効率のス イッチ・モード・チャージャ
	- 深放電されたバッテリまたはバッテリなしで、システ ムをただちに起動
- MaxLife™ テクノロジーと互換性があり、BQ27530 と 組み合わせれば、より高速な充電が可能
- 最大 2.5A の充電に対応するデュアル入力、FET 内 蔵のチャージャ
	- 入力定格 20V で過電圧保護 (OVP) を搭載
		- 最大 1.5A の USB 入力について 6.5V
		- 最大 2.5A の IN 入力 (BQ24160、 BQ24160A、BQ24161、BQ24163) について 10.5V
		- 最大 2.5A の IN 入力 (BQ24168) で 6.5V
- 安全で高精度のバッテリ管理機能
	- 1% のバッテリ・レギュレーション精度
	- 10% の充電電流精度
- I²C インターフェイスを使用して充電パラメータをプログ ラム
- 電圧ベースの NTC 監視入力
	- JEITA 互換 (BQ24160、BQ24160A、 BQ24161B、BQ24163、BQ24168)
- 2.8mm × 2.8mm の小型 49 ボール WCSP または 4mm × 4mm の VQFN-24 パッケージで供給

2 アプリケーション

- ハンドヘルド製品
- ポータブル・メディア・プレーヤ
- 携帯機器
- ネットブックおよびポータブル・インターネット・デバイス

3 概要

BQ24160 、 BQ24160A 、 BQ24161 、 BQ24161B 、 BQ24163、BQ24168 は、スペースに制約があり、大容量 バッテリを使用するポータブル・アプリケーションを対象と した、高集積のシングル・セル・リチウムイオン・バッテリ・チ ャージャおよびシステム・パワー・パス管理デバイスです。 シングル・セル・チャージャにはデュアル入力があり、USB ポート、またはより大電力の入力電源 (AC アダプタまたは ワイヤレス充電入力) で動作でき、多様なソリューションを 実現できます。2 つの入力は互いに完全に絶縁されてお り、I²C インターフェイスを使用して簡単に選択できます。

電力パス管理機能により、BQ2416xx は高効率の DC-DC コンバータからシステムに電力を供給するとともに、バ ッテリを同時に独立して充電できます。パワー・パス管理ア ーキテクチャにより、バッテリ・パックに欠陥がある、または 存在しない場合でもシステムを動作させ、バッテリが完全 に放電した、または存在しない状態でもシステムを即座に オンできます。

制具棒級

(1) 利用可能なすべてのパッケージについては、このデータシートの 末尾にある注文情報を参照してください。

アプリケーション回路図

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4 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Changes from Revision F (July 2014) to Revision G (November 2015) Page

Changes from Revision E (November 2013) to Revision F (January 2014) Page

Changes from Revision D (November 2012) to Revision E (November 2013) Page

- 特長を追加: MaxLife テクノロジーと互換性があり、BQ27530と組み合わせれば、より高速な充電が可能.................[1](#page-0-0)
- データシート全体にわたって次のように変更:データシート全体にわたって QFN-24 パッケージを VQFN-24 パッケー ジに変更..[1](#page-0-0)

Changes from Revision C (October 2012) to Revision D (November 2012) Page

• Changed the Ordering Information table to include the WSCP package for BQ24161BRGR and BQ24161BYFF... [4](#page-3-0)

5 Device Comparison Table

(1) Each of the above are available in as YFF and RGE packages with the following options:

R - tabed and reeled in quantities of 3,000 devices per reel.

T - taped and reeled in quantities of 250 devices per reel.

(2) This product is RoHS compatible, including a lead concentration that does not exceed 0.1% of total product weight, and is suitable for use in specified lead-free soldering processes. In addition, this product uses package materials that do not contain halogens, including bromine (Br) or antimony (Sb) above 0.1% of total product weight.

6 Pin Configuration and Functions

図 **6-2. YFF Package WCSP 49 Pins Top View**

表 **6-1. Pin Functions**

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表 **6-1. Pin Functions (continued)**

7 Specifications

7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) (1)

(1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability. All voltage values are with respect to the network ground terminal unless otherwise noted.

7.2 Handling Ratings

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

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7.4 Thermal Information

(1) For more information about traditional and new thermal metrics, see *[The IC Package Thermal Metrics Application Report](https://www.ti.com/jp/lit/pdf/SPRA953)*.

7.5 Electrical Characteristics

Circuit of \boxtimes [9-1](#page-33-0), V_{SUPPLY} = V_{USB} or V_{IN} (whichever is supplying the IC), V_{UVLO} < V_{SUPPLY} < V_{OVP} and V_{SUPPLY} > V_{BAT}+V_{SLP}, T $_{\textrm{J}}$ = -40°C – 125°C and T $_{\textrm{J}}$ = 25°C for typical values (unless otherwise noted)

7.5 Electrical Characteristics (continued)

Circuit of \boxtimes [9-1](#page-33-0), V_{SUPPLY} = V_{USB} or V_{IN} (whichever is supplying the IC), V_{UVLO} < V_{SUPPLY} < V_{OVP} and V_{SUPPLY} > V_{BAT} + V_{SLP} , T $_{\textrm{J}}$ = -40°C – 125°C and T $_{\textrm{J}}$ = 25°C for typical values (unless otherwise noted)

7.5 Electrical Characteristics (continued)

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7.6 Typical Characteristics

7.6 Typical Characteristics (continued)

8 Detailed Description

8.1 Overview

The BQ24160/BQ24160A/BQ24161/BQ24161B/BQ24163/BQ24168 devices are highly integrated single-cell Li-Ion battery chargers and system power path management devices targeted for space-limited, portable applications with high-capacity batteries. The dual-input, single-cell charger operates from either a USB port or alternate power source (that is, wall adapter or wireless power input) for a versatile solution.

The power path management feature allows the BQ2416xx to power the system from a high-efficiency DC-DC converter while simultaneously and independently charging the battery. The charger monitors the battery current at all times and reduces the charge current when the system load requires current above the input current limit. This allows proper charge termination and enables the system to run with a defective or absent battery pack. Additionally, this enables instant system turnon even with a totally discharged battery or no battery. The powerpath management architecture also permits the battery to supplement the system current requirements when the adapter cannot deliver the peak system currents. This enables the use of a smaller adapter. The 2.5-A current capability allows for GSM phone calls as soon as the adapter is plugged in regardless of the battery voltage. The charge parameters are programmable using the 1^2C interface.

8.2 Functional Block Diagram

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8.3 Feature Description

8.3.1 Charge Mode Operation

8.3.1.1 Charge Profile

The internal battery MOSFET is used to charge the battery. When the battery is above the MINSYS voltage, the internal FET is on to maximize efficiency and the PWM converter regulates the charge current into the battery. When battery is less than MINSYS, the SYS is regulated to $V_{\text{SYS(REG)}}$ and battery is charged using the battery FET to regulate the charge current. There are 5 loops that influence the charge current:

- Constant current loop (CC)
- Constant voltage loop (CV)
- Thermal-regulation loop
- Minimum system-voltage loop (MINSYS)
- Input-voltage dynamic power-management loop $(V_{IN}-DPM)$

During the charging process, all five loops are enabled and the one that is dominant takes control. The BQ2416xx supports a precision Li-ion or Li-polymer charging system for single-cell applications. The Dynamic Power Path Management (DPPM) feature regulates the system voltage to a minimum of V_{MINSYS}, so that startup is enabled even for a missing or deeply discharged battery. \boxtimes 8-1 shows a typical charge profile including the minimum system output voltage feature.

図 **8-1. Typical BQ2416xx Charging Profile**

8.3.1.2 PWM Controller in Charge Mode

The BQ2416xx provides an integrated, fixed-frequency 1.5-MHz voltage-mode controller to power the system and supply the charge current. The voltage loop is internally compensated and provides enough phase margin for stable operation, allowing the use of small ceramic capacitors with low ESR. When starting up, the BQ2416xx uses a "soft-start" function to help limit inrush current. When coming out of High Impedance mode, the BQ2416xx starts up with the input current limit set to 40% of the value programmed in the I²C register. After 80 ms, the input current limit threshold steps up in 256-µs steps. The steps are 40% to 50%, then 50% to 60%, then 60% to 70%, then 70% to 80%, and finally 80% to 100%. After the final step, soft start is complete and will not be restarted until the BQ2416xx enters High Impedance mode.

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The input scheme for the BQ2416xx prevents battery discharge when the supply voltages are lower than VBAT and also isolates the two inputs from each other. The high-side N-MOSFET (Q1/Q2) switches to control the power delivered to the output. The DRV LDO provides a supply for the gate drive for the low side MOSFET, while a bootstrap circuit (BST) with an external bootstrap capacitor is used to boost up the gate drive voltage for Q1 and Q2.

Both inputs are protected by a cycle-by-cycle current limit that is sensed through the high-side MOSFETs for Q1 and Q2. The threshold for the current limit is set to a nominal 5-A peak current. The inputs also utilize an input current limit that limits the current from the power source.

8.3.2 Battery Charging Process

Assuming a vaild input source is attached to IN or USB, as soon as a deeply discharged or shorted battery is attached to the BAT pin, (V_{BAT} < V_{BATSHRT}), the BQ2416xx applies $I_{BATSHRT}$ to close the pack protector switch and bring the battery voltage up to acceptable charging levels. During this time, the battery FET is linearly regulated and the system output is regulated to $V_{\text{SYS(REG)}}$. Once the battery rises above V_{BATSHRT} , the charge current is regulated to the value set in the I²C register. The battery FET is linearly regulated to maintain the system voltage at $V_{\rm SYS(REG)}$. Under normal conditions, the time spent in this region is a very short percentage of the total charging time, so the linear regulation of the charge current does not affect the overall charging efficiency for very long. If the die temperature does rise, the thermal regulation circuit reduces the charge current to maintain a die temperature less than 120°C. If the current limit for the SYS output is reached (limited by the input current limit, or V_{IN_DPM}), the SYS output drops to the V_{MINSYS} output voltage. When this happens, the charge current is reduced to provide the system with all the current that is needed while maintaining the minimum system voltage. If the charge current is reduced to 0mA, pulling further current from SYS causes the output to fall to the battery voltage and enter supplement mode. (See the *[Dynamic Power Path Management](#page-16-0)* section for more details.)

Once the battery is charged enough so that the system voltage begins to rise above $V_{\text{SYS(REG)}}$, the battery FET is turned on fully and the battery is charged with the full programmed charge current set by the I²C interface, I_{CHARGE}. The slew rate for the fast-charge current is controlled to minimize current and voltage overshoot during transients. The charge current is regulated to I_{CHARGF} until the battery is charged to the regulation voltage. As the battery voltage rises above VRCH, the battery regulation loop is activated. This may result in a small step down in the charge current as the loops transition between the charge current and charge voltage loops. As the battery voltage charges up to the regulation voltage, V_{BATREG} , the charge current is tapered down as shown in \boxtimes [8-1](#page-14-0) while the SYS output remains connected to the battery. The voltage between the BAT and PGND pins is regulated to V_{BATRFG} . The BQ2416xx is a fixed single-cell voltage version, with adjustable regulation voltage (3.5 V to 4.44 V), programmed using the ${}^{12}C$ interface.

The BQ2416xx monitors the charging current during the voltage-regulation phase. If the battery voltage is above the recharge threshold and the charge current has naturally tapered down to and remains below termination threshold, I_{TERM} , (without disturbance from events like supplement mode) for 32 ms, the charger terminates charge, turns off the battery charging FET and enters battery detection. Termination is disabled when the charge current is reduced by a loop other than the voltage regulation loop or the input current limit is set to 100 mA. For example, when the BQ2416xx is in half charge due to TS function, reverse boost protection is active, LOW_CHG bit is set, or the thermal regulation, V_{INDPM} or input current loops are active, termination will not occur. This prevents false termination events. During termination, the system output is regulated to the $V_{\text{SYS(REG)}}$ and supports the full current available from the input and the battery supplement mode is available. (See the *[Dynamic Power Path Management](#page-16-0)* section for more details.) The termination current level is programmable. When setting the termination threshold less than 150mA, the reverse boost protection may trip falsely with load transients and very fully charged batteries. This will prevent termination while in the reverse boost protection and may extend charge time. To disable the charge current termination, the host sets the charge termination bit (TE) of charge control register to 0, refer to 1^2C section for details.

A new charge cycle is initiated if \overline{CD} is low when either

- 1. V_{SIJPPLY} rises above UVLO while a battery with V_{BAT} < V_{BATREG} V_{RCH} is attached or
- 2. a battery with $V_{BAT} < V_{BATEG}$ V_{RCH} is attached while V_{SUPPLY} is above UVLO.

With V_{SUPPLY} above UVLO and V(BAT) < V_{BOVP} , a recharge cycle is initiated when one of the following conditions is detected:

- 1. The battery voltage falls below the $V_{BAT(REG)}$ -V_{RCH} threshold.
- 2. CE bit toggle or RESET bit toggle
- 3. Supplement mode event occurs
- 4. CD pin or HI-Z bit toggle

 $V_{BAT(RFG)}$ should never be programmed less than V_{BAT} . If the battery is ever 5% above the regulation threshold, the battery OVP circuit shuts the PWM converter off immediately and the battery FET is turned on to discharge the battery to safe operating levels. If the battery OVP condition exists for the 1ms deglitch, a battery OVP fault is reported in the I²C status registers. The battery OVP fault is cleared when the battery voltage discharges below V_{RCH} or if the IC enters hi-impedance mode (HZ_MODE=1 or CD=1). Always write BQ2416xx to high impedance mode before changing V_{BATRFG} to clear BOVP condition to ensure proper operation.

If the battery voltage is ever greater than VBATREG (for example, when an almost fully charged battery enters the JEITA WARM state due to the TS pin) but less than $V_{\rm BOVP}$, the reverse boost protection circuitry may activate as explained later in this data sheet. If the battery is ever above $V_{\rm BOVP}$, the buck converter turns off and the internal battery FET is turned on. This prevents further overcharging of the battery and allows the battery to discharge to safe operating levels. The battery OVP event does not clear until the battery voltage falls below V_{RCH}.

8.3.3 Battery Detection

When termination conditions are met, a battery detection cycle is started. During battery detection, IDETECT is pulled from V_{BAT} for t_{DETECT} to verify there is a battery. If the battery voltage remains above V_{DETECT} for the full duration of t_{DETECT}, a battery is determined to present and the IC enters "Charge Done". If V_{BAT} falls below V_{DETECT}, a "Battery Not Present" fault is signaled and battery detection continues. The next cycle of battery detection, the BQ2416xx turns on $I_{BATSHORT}$ for t_{DETECT} . If V_{BAT} rises to V_{DETECT} , the current source is turned offand after t_{DETECT}, the battery detection continues through another current sink cycle. Battery detection continues until charge is disabled or a battery is detected. Once a battery is detected, the fault status clears and a new charge cycle begins. Battery detection is not run when termination is disabled.

8.3.4 Dynamic Power Path Management (DPPM)

The BQ2416xx features a SYS output that powers the external system load connected to the battery. This output is active whenever a source is connected to IN, USB or BAT. The following sections discuss the behavior of SYS with a source connected to the supply or a battery source only.

8.3.5 Input Source Connected

When a valid input source is connected to IN or USB and the BQ2416xx is NOT in High Impedance mode, the buck converter enters soft-start and turns on to power the load on SYS. The STAT/INT pin outputs a 128-µs interrupt pulse to alert the host that an input has been connected. The FAULT bits indicate a normal condition, and the Supply Status register indicates that a new supply is connected. The CE bit (bit 1) in the control register (0x02) indicates whether a charge cycle is initiated. By default, the BQ2416xx (\overline{CE} = 0) enables a charge cycle when a valid input source is connected. When the \overline{CE} bit is '1' and a valid input source is connected, the battery FET is turned off and the SYS output is regulated to the $V_{\text{SYS(REG)}}$ programmed by the V_{BATREG} threshold in the I²C register. A charge cycle is initiated when the $\overline{\text{CE}}$ bit is written to a 0 value (cleared).

When the CE bit is a 0 and a valid source is connected to IN or USB, the buck converter starts up using softstart. A charge cycle is initiated 64 ms after the buck converter iniates startup. When V_{BAT} is high enough that V_{SYS} > V_{SYS(REG)}, the battery FET is turned on and the SYS output is connected to BAT. If the SYS voltage falls to $V_{\text{SYS/REGi}}$, it is regulated to that point to maintain the system output even with a deeply discharged or absent battery. In this mode, the SYS output voltage is regulated by the buck converter and the battery FET linearly regulates the charge current into the battery. The current from the supply is shared between charging the battery and powering the system load at SYS. The dynamic power-path management (DPPM) circuitry of the BQ2416xx monitors the current limits continuously, and if the SYS voltage falls to the V_{MINSYS} voltage, it adjusts charge current to maintain the minimum system voltage and supply the load on SYS. If the charge current is reduced to

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zero and the load increases further, the BQ2416xx enters battery-supplement mode. During supplement mode, the battery FET is turned on and the battery supplements the system load.

When an input is connected with no battery attached and termination enabled, the startup process proceeds as normal until the termination deglitch times out. After this, the BQ2416xx enters battery detection and waits for a battery to be connected. Once a battery is connected and passes battery detection, a new charge cycle begins. Once the battery is applied, the HZMODE bit or \overline{CD} pin must be toggled before writing the BATREG to a higher voltage and beginning a new charge cycle. Failure to do this can result in SYS unexpectedly regulating to 15% above V_{BATRFG} .

図 **8-2. Example DPPM Response (VSupply = 5 V, VBAT = 3.1 V, 1.5 A Input Current Limit)**

8.3.6 Battery Only Connected

When a battery with voltage greater than $V_{BATUVLO}$ is connected with no input source, the battery FET is turned on similar to supplement mode. In this mode, the current is not regulated; however, there is a short circuit current limit. If the short circuit limit is reached, the battery FET is turned off for the deglitch time (t_{DGL(SC1})). After the recovery time ($t_{REC(SC1)}$), the battery FET is turned on to test and see if the short has been removed. If it has not, the FET turns off and the process repeats until the short is removed. This process is to protect the internal FET from over current. If an external FET is used for discharge, the external FET's body diode prevents the load on SYS from being disconnected from the battery. If the battery voltage is less than $V_{BATUVLO}$, the internal battery FET (Q4) remains off and BAT is high-impedance. This prevents further discharging of deeply-discharged batteries.

8.3.7 Battery Discharge FET (BGATE)

The BQ2416xx contains a MOSFET driver to drive the gate of an external discharge FET between the battery and the system output. This external FET provides a low impedance path when supplying the system from the battery. Connect BGATE to the gate of the external discharge MOSFET. BGATE is on under the following conditions:

1. No input supply connected.

- 2. HZ_MODE bit = 1
- 3. \overline{CD} pin = 1

8.3.8 DEFAULT Mode

DEFAULT mode is used when I²C communication is not available. DEFAULT mode is entered in the following situations:

- 1. When the charger is enabled and $V_{BAT} < V_{BATGD}$ before I²C communication is established
- 2. When the watchdog timer expires without a reset from the $1²C$ interface and the safety timer has not expired.
- 3. When the device comes out of any fault condition (sleep mode, OVP, faulty adapter mode, etc.) before I²C communication is established

In DEFAULT mode, the $I²C$ registers are reset to the default values. The 27-minute safety timer (no timer for BQ24168) is reset and starts when DEFAULT mode is entered. The default value for VBATREG is 3.6 V, and the default value for I_{CHARGF} is 1 A. The input current limit for the IN input is set to 1.5 A. The input current limit for the USB input is determined by the D+/D– detection (BQ24160/3) or PSEL (BQ24161/1B/8). PSEL and D+/D– detection have no effect on the IN input. Default mode is exited by programming the 1^2C interface. Once 1^2C communication is established, PSEL has no effect on the USB input. Note that if termination is enabled and charging has terminated, a new charge cycle is NOT initiated when entering DEFAULT mode.

8.3.9 Safety Timer and Watchdog Timer (BQ24160/BQ24161/BQ24161B/BQ24163 only)

At the beginning of charging process, the BQ24160/1/1B/3 starts the safety timer. This timer is active during the entire charging process. If charging has not terminated before the safety timer expires, charging is disabled, the charge parameters are reset to the default values and the \overline{CE} bit is written to a "1". The length of the safety timer is selectable using the I^2C interface. A single 128-us pulse is sent on the STAT and INT outputs and the STATx bits of the status registers are updated in the $12C$. In DEFAULT mode, the safety timer can be reset and a new charge cycle initiated by input supply power on reset, removing/inserting battery or toggling the CD pin. In HOST mode, the CE bit is set to a '1' when the safety timer expires. The CE bit must be cleared to a '0' in order to resume charging and clear the safety timer fault. The safety timer duration is selectable using the TMR_X bits in the Safety Timer Register/ NTC Monitor register. Changing the safety timer duration resets the safety timer. This function prevents continuous charging of a defective battery. During the fast charge (CC) phase, several events increase the timer duration by 2× if the EN_2X_TMR bit is set in the register.

- 1. The system load current reduces the available charging current.
- 2. The input current needed for the fast charge current is limited by the input current loop.
- 3. The input current is reduced because the VINDPM loop is preventing the supply from crashing.
- 4. The device has entered thermal regulation because the IC junction temperature has exceeded TJ(REG).
- 5. The LOW_CHG bit is set.
- 6. The battery voltage is less than VBATSHORT.
- 7. The battery has entered the JEITA WARM or COLD state via the TS pin

During these events, the timer is slowed by half to extend the timer and prevent any false timer faults. Starting a new charge cycle by VSUPPLY POR or removing/replacing the battery or resuming a charge by toggling the CE or HZ_MODE bits, resets the safety timer. Additionally, thermal shutdown events cause the safety timer to reset.

In addition to the safety timer, the BQ24160/1/1B/3 contain a watchdog timer that monitors the host through the I²C interface. Once a read/write is performed on the I²C interface, a 30-second timer (t_{WATCHDOG}) is started. The 30-second timer is reset by the host using the I²C interface. This is done by writing a "1" to the reset bit (TMR_RST) in the control register. The TMR_RST bit is automatically set to "0" when the 30-second timer is reset. This process continues until the battery is fully charged or the safety timer expires. If the 30-second timer expires, the IC enters DEFAULT mode where the default register values are loaded, the safety timer restarts at 27 minutes and charging continues. The ¹²C may be accessed again to reinitialize the desired values and restart the watchdog timer. The watchdog timer flow chart is shown in \boxtimes [8-3.](#page-19-0)

図 **8-3. The Watchdog Timer Flow Chart for BQ2416xx**

8.3.10 D+, D– Based Adapter Detection for the USB Input (D+, D–, BQ24160/0A/3)

The BQ24160/0A/3 contain a D+, D– based adapter detection circuit that is used to program the input current limit for the USB input during DEFAULT mode. D+, D– detection is only performed in DEFAULT mode unless forced by the D+, D– EN bit in host mode. Writing to register 2 during detection stops the detection routine.

By default the USB input current limit is set to 100 mA. When a voltage higher than UVLO is applied to the USB input, the BQ24160/0A/3 performs a charger source identification to determine if it is connected to an SDP (USB port) or CDP/DCP (dedicated charger). The first step is D+, D- line connection detection as described in BC1.2. Primary detection begins 10 ms after the connection detection complete. The primary detection complies with the method described in BC1.2. During primary detection, the D+, D- lines are tested to determine if the port is an SDP or CDP/DCP. If a CDP/DCP is detected the input current limit is increased to 1.5 A, if an SDP is detected the current limit remains at 100 mA, until changed via the I2C interface. These two steps require at least 90 ms to complete but if they have not completed within 500 ms, the D+, D- detection routine selects 100 mA for the unknown input source. Secondary detection as described in BC1.2 is not performed.

Automatic detection is performed only if V_{D+} and V_{D-} are less than 0.6 V to avoid interfering with the USB transceiver which may also perform D+, D– detection when the system is running normally. However, D+, D– can be initiated at any time by the host by setting the D+, D– EN bit in the Control/Battery Voltage Register to 1.

After detection is complete the D+, D- EN bit is automatically reset to 0 and the detection circuitry is disconnected from the D+, D– pins to avoid interference with USB data transfer.

When a command is written to change the input current limit in the I²C, this overrides the current limit selected by D+/D– detection. D+, D– detection has no effect on the IN input.

8.3.11 USB Input Current Limit Selector Input (PSEL, BQ24161/161B/168 only)

The BQ24161, BQ24161B, and BQ24168 contain a PSEL input that is used to program the input current limit for USB during DEFAULT mode. Drive PSEL high to indicate that a USB source is connected to the USB input and program the 100 mA (BQ24161/8) or 500 mA (BQ24161B) current limit for USB. Drive PSEL low to indicate that an AC adapter is connected to the USB input. When PSEL is low, the IC starts up with a 1.5-A current limit for USB. PSEL has no effect on the IN input. Once an ${}^{12}C$ write is done, the PSEL has no effect on the input current limit until the watchdog timer expires.

8.3.12 Hardware Chip Disable Input (CD)

The BQ2416xx contains a $\overline{\text{CD}}$ input that is used to disable the IC and place the BQ2416xx into high-impedance mode. Drive \overline{CD} low to enable charge and enter normal operation. Drive \overline{CD} high to disable charge and place the BQ2416xx into high-impedance mode. Driving CD high during DEFAULT mode resets the safety timer. Driving CD high during HOST mode resets the safety timer and places the BQ2416xx into high impedance mode. The \overline{CD} pin has precedence over the I^2C control.

8.3.13 LDO Output (DRV)

The BQ2416xx contains a linear regulator (DRV) that is used to supply the internal MOSFET drivers and other circuitry. Additionally, DRV supplies up to 10-mA external loads to power the STAT LED or the USB transceiver circuitry. The maximum value of the DRV output is 5.45 V; ideal for protecting voltage sensitive USB circuits from high voltage fluctuations in the supply. The LDO is on whenever a supply is connected to the IN or USB inputs of the BQ2416xx. The DRV is disabled under the following conditions:

- 1. V_{SUPPLY} < UVLO
- 2. V_{SUPPIY} < V_{SIP}
- 3. Thermal Shutdown

8.3.14 External NTC Monitoring (TS)

The I²C interface allows the user to easily implement the JEITA standard for systems where the battery pack thermistor is monitored by the host. Additionally, the BQ2416xx provides a flexible, voltage based TS input for monitoring the battery pack NTC thermistor. The voltage at TS is monitored to determine that the battery is at a safe temperature during charging. The BQ24160, BQ24160A, BQ24161B, BQ24163, and BQ24168 enable the user to easily implement the JEITA standard for charging temperature while the BQ24161 only monitors the hot and cold cutoff temperatures and leaves the JEITA control to the host. The JEITA specification is shown in.

図 **8-4. Charge Current During TS Conditions**

To satisfy the JEITA requirements, four temperature thresholds are monitored; the cold battery threshold ($T_{\rm NTC}$ < 0°C), the cool battery threshold (0°C < T_{NTC} < 10°C), the warm battery threshold (45°C < T_{NTC} ≤ 60°C) and the hot battery threshold (T_{NTC} > 60°C). These temperatures correspond to the V_{COLD} , V_{COOL} , V_{WARM} , and V_{HOT} thresholds. Charging is suspended and timers are suspended when V_{TS} < V_{HOT} or V_{TS} > V_{COLD} . When V_{WARM} > V_{TS} > V_{HOT} , the battery regulation voltage is reduced by 140 mV from the programmed regulation threshold. When V_{COLD} > V_{TS} > V_{COOL} , the charging current is reduced to half of the programmed charge current.

The TS function is voltage based for maximum flexibility. Connect a resistor divider from DRV to GND with TS connected to the center tap to set the threshold. The connections are shown in \boxtimes [8-11](#page-27-0). The resistor values are calculated using the following equations:

$$
V_{DRV} \times \text{RCOLD} \times \text{RHOT} \times \left[\frac{1}{V_{\text{COLD}}} - \frac{1}{V_{\text{HOT}}} \right]
$$

\nRLO =
$$
\frac{V_{DRV}}{V_{\text{HOT}}} - 1 \left[-\text{RCOLD} \times \left[\frac{V_{DRV}}{V_{\text{COLD}}} - 1 \right] \right]
$$

\nRHI =
$$
\frac{V_{DRV}}{V_{\text{COLD}}} - 1
$$

\nRLO $\frac{V_{\text{DRV}}}{RLO}$ (2)

Where:

 $V_{\text{COL}D} = 0.60 \times V_{\text{DRV}}$

V_{HOT} = 0.30 \times V_{DRV}

Where R_{HOT} is the NTC resistance at the hot temperature and R_{COLD} is the NTC resistance at cold temperature.

For the BQ24160, BQ24161B, BQ24163, and BQ24168, the WARM and COOL thresholds are not independently programmable. The COOL and WARM NTC resistances for a selected resistor divider are calculated using the following equations:

図 **8-5. TS Circuit**

8.3.15 Thermal Regulation and Protection

During the charging process, to prevent chip overheating, the BQ2416xx monitors the junction temperature, T_J, of the die and begins to taper down the charge current once ${\sf T}_{\sf J}$ reaches the thermal regulation threshold, ${\sf T}_{\sf REG}$. The charge current is reduced to zero when the junction temperature increases about 10°C above T_{REG} . Once the charge current is reduced, the system current is reduced while the battery supplements the load to supply the system. This may cause a thermal shutdown of the BQ2416xx if the die temperature rises too high. At any state, if T_J exceeds T_{SHTDWN}, the BQ2416xx suspends charging and disables the buck converter. During thermal shutdown mode, the buck converter is turned off, all timers are suspended, and a single 128-μs pulse is sent on the STAT and INT outputs and the STATx and FAULT \bar{x} bits of the status registers are updated in the I²C. A new charging cycle begins when T_J falls below T_{SHTDWN} by approximately 10°C.

8.3.16 Input Voltage Protection in Charge Mode

8.3.16.1 Sleep Mode

The BQ2416xx enters the low-power sleep mode if the voltage on V_{SUPPLY} falls below the sleep-mode entry threshold, $V_{BAT}+V_{SLP}$, and V_{SUPPLY} is higher than the undervoltage lockout threshold, V_{UVLO} . This feature prevents draining the battery during the absence of V_{SUPPLY} . When V_{SUPPLY} < V_{BAT} + V_{SLP} , the BQ2416xx turns off the PWM converter, turns the battery FET on and drives BGATE to GND, sends a single 128-μs pulse on the STAT and INT outputs and updates the STATx and FAULT x bits in the status registers. Once V_{SUPPLY} > V_{BAT} + V_{SLP} , the STATx and FAULT x bits are cleared and the device initiates a new charge cycle.

8.3.16.2 Input Voltage Based DPM

During normal charging process, if the input power source is not able to support the programmed or default charging current, the supply voltage decreases. Once the supply drops to V_{IN_DPM} (default 4.2 V for both inputs), the input current limit is reduced to prevent further supply droop. When the IC enters this mode, the charge current is lower than the set value and the DPM_STATUS bit is set (Bit 5 in Register 05H). This feature provides

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IC compatibility with adapters with different current capabilities without a hardware change. \boxtimes 8-6 shows the V_{IN} –DPM behavior to a current-limited source. In this figure the input source has a 750-mA current limit and the charging is set to 750 mA. The SYS load is then increased to 1.2 A.

図 **8-6. BQ24160 VIN-DPM**

8.3.16.3 Bad Source Detection

When a source is connected to IN or USB, the BQ2416xx runs a Bad Source Detection procedure to determine if the source is strong enough to provide some current to charge the battery. A current sink is turned on (30 mA for USB input, 75 mA for the IN input) for 32 ms. If the source is valid after the 32 ms (V_{BADSOURCE} < V_{SUPPLY} < V_{OVP}), the buck converter starts up and normal operation continues. If the supply voltage falls below V_{BAD} SOURCE during the detection, the current sink shuts off for two seconds and then retries, a single 128-µs pulse is sent on the STAT and INT outputs and the STATx and FAULT_x bits of the status registers and the battery/supply status registers are updated. The detection circuits retry continuously until either a new source is connected to the other input or a valid source is detected after the detection time. If during normal operation the source falls to $V_{BAD-SouRCE}$, the BQ2416xx turns off the PWM converter, turns the battery FET on, sends a single 128-us pulse is sent on the STAT and INT outputs and the STAT x and FAULT x bits of the status registers, and the battery/supply status registers are updated. Once a good source is detected, the STATx and FAULT x bits are cleared and the device returns to normal operation.

If two supplies are connected, the supply with precedence is checked first. If the supply detection fails once, the device switches to the other supply for two seconds and then retries. This allows the priority supply to settle if the connection was jittery or the supply ramp was too slow to pass detection. If the priority supply fails the detection a second time, it is locked out and lower priority supply is used. Once the bad supply is locked out, it remains locked out until the supply voltage falls below UVLO. This prevents continuously switching between a weak supply and a good supply.

8.3.16.4 Input Overvoltage Protection

The built-in input overvoltage protection to protect the device and other downstream components against damage from overvoltage on the input supply (voltage from V_{IJSR} or V_{IN} to PGND). During normal operation, if V_{SUPPLY} > V_{OVP} , the BQ2416xx turns off the PWM converter, turns the battery FET and BGATE on, sends a single 128-us pulse is sent on the STAT and INT outputs and the STATx and FAULT x bits of the status registers and the battery/supply status registers are updated. Once the OVP fault is removed, the STATx and FAULT_x bits are cleared and the device returns to normal operation.

To allow operation with some unregulated adapters, the OVP circuit is not active during Bad Source Detection. This provides some time for the current sink to pull the unregulated adapter down into an acceptable range. If the adapter voltage is high at the end of the detection, the startup of the PWM converter does not occur. The OVP circuit is active during normal operation, so if the system standby current plus the charge current is not enough to pull down the source, operation is suspended.

8.3.16.5 Reverse Boost (Boost Back) Prevention Circuit

A buck converter has two operating modes, continuous conduction mode (CCM) and discontinuous conduction mode (DCM). In DCM, the inductor current ramps down to zero during the switching cycle while in CCM the inductor maintains a DC level of current. Transitioning from DCM to CCM during load transients, slows down the converter's transient response for those load steps, which can result in the SYS rail drooping. To achieve the fastest possible transient reponse for this charger, this charger's synchronous buck converter is forced to run in CCM even at light loads when the buck converter would typically revert to DCM. The challenge that presents itself when forcing CCM with a charger is that the output of the buck converter now has a power source. Thus, if the battery voltage, V(BAT), is ever greater than V_{BATRFG} , the inductor current goes fully negative and pushes current back to the input supply. This effect causes the input source voltage to rise if the input source cannot sink current. The input over-voltage protection circuit protects the IC from damage however some input sources may be damaged if the voltage rises. To prevent this, this charger has implemented a reverse boost prevention circuit. When reverse current is sensed that is not a result of the supplement comparator tripping, this circuit disables the internal battery FET and changes the feedback point to V_{SYSREG} for 1 ms. After the 1-ms timeout, the BATFET is turned on again and the battery is tested to see if it is higher than V_{BATREG} (negative current). The reverse current protection is only active when $V_{BOVP} > V_{BAT} > V_{BATEG} - V_{RCH}$. Having $V_{BOVP} > V_{BAT} > V_{BATEG}$ V_{RCH} results in an approximately 100-mV, 1000-Hz ripple on SYS as seen in \boxtimes [8-7](#page-25-0). The most common trigger for reverse boost prevention is a load transient on SYS that requires the charger to enter battery supplement mode. When the IC enters reverse boost prevention, the IC stops charging or exits charge done which may result in the battery never reaching full charge. With termination enabled and ITERM > 150 mA or with a high line impedance to the battery, the likelihood of activating the reverse boost prevention circuit is small and even when activated, the charger typically exits reverse boost prevention as the battery relaxes. With termination enabled and ITERM < 150 mA or with a low impedance battery, the likelihood of activating the reverse boost prevention circuit by a load transient or even the inductor ripple current is higher. In either case, the IC resumes charging until VBAT drops below VBATREG - VRCH, resulting in the battery always charging to at least 0.97 of full charge. If full charge is required with ITERM < 150 mA then the recommended solution to ensure full charge is as follows

1. SET the charger's enable no battery operation bit (EN_NOBATOP) = 1 to disable the reverse boost prevention circuits. Brief, low-amplitude voltage pulses on IN may be observed as the IC enters boost back to resolve instances where VBAT is greater than the VBATREG, for example when exiting supplement mode. The ¹²C communication software must ensure that VBATREG is never written below VBAT. The IC automatically rewrites the VBATREG register to the default value of 3.6 V when existing HOST mode. For JEITA enabled ICs, the IC automatically lowers the voltage reference to 0.98 of the VBATREG value. The software must account for these instances as well.

2. Disable the charger's termination function and TS functions and use a gas gauge to control termination and TS through its independent voltage and current measurements.

図 **8-7. V(SYS) When Reverse Boost Prevention Circuit is Active**

8.3.17 Charge Status Outputs (STAT, INT)

The STAT output is used to indicate operation conditions for BQ2416xx. STAT is pulled low during charging when EN_STAT bit in the control register (0x02h) is set to "1". When charge is complete or disabled, STAT is high impedance. When a fault occurs, a 128-us pulse (interrupt) is sent out to notify the host. The status of STAT during different operation conditions is summarized in $\frac{1}{36}$ 8-1. STAT drives an LED for visual indication or can be connected to the logic rail for host communication. The EN_STAT bit in the control register (00H) is used to enable/disable the charge status for STAT. The interrupt pulses are unaffected by EN_STAT and will always be shown. The INT output is identical to STAT and is used to interface with a low voltage host processor.

8.3.18 Good Battery Monitor

The BQ2416xx contains a good battery monitor circuit that places the BQ2416xx into high-z mode if the battery voltage is above the BATGD threshold while in DEFAULT mode. This function is used to enable compliance to the battery charging standard that prevents charging from an un-enumerated USB host while the battery is above the good battery threshold. If the BQ2416xx is in HOST mode, it is assumed that USB host has been enumerated and the good battery circuit has no effect on charging.

8.4 Device Functional Modes

The state machine of the BQ2416x automatically changes primary states (Off, sleep, HiZ, charge disabled, charging, charge done, battery OVP, fault) based on data in the I²C registers, IN and USB pin voltages, BAT pin voltage and current flow, TS pin voltage, \overline{CD} pin voltage and status of the safety timer. The BAT and TS pin voltages as well as current flow into the IN and USB pins, out of SYS pin and into/out of the BAT pin determine the charging sub-states, including conditioning, constant current (CC), CC with reduced charge current, constant voltage (CV) with reduced charge current.

8.5 Programming

8.5.1 Serial Interface Description

The BQ2416xx uses an 1^2 C-compatible interface to program charge parameters. 1^2 C is a 2-wire serial interface developed by Philips Semiconductor (see I²C-Bus Specification, Version 2.1, January 2000). The bus consists of a data line (SDA) and a clock line (SCL) with pullup structures. When the bus is idle, both SDA and SCL lines are pulled high. All ${}^{12}C$ -compatible devices connect to the ${}^{12}C$ bus through open drain I/O pins, SDA and SCL. A host device, usually a microcontroller or a digital signal processor, controls the bus. The host is responsible for generating the SCL signal and device addresses. The host also generates specific conditions that indicate the START and STOP of data transfer. A target device receives and/or transmits data on the bus under control of the host device.

The BQ2416xx device works as a target and supports the following data transfer modes, as defined in the I²C Bus Specification: standard mode (100 kbps) and fast mode (400 kbps). The interface adds flexibility to the battery charging solution, enabling most functions to be programmed to new values depending on the instantaneous application requirements. Register contents remain intact as long as battery voltage remains above 2.5 V (typical). The I²C circuitry is powered from VBUS when a supply is connected. If the VBUS supply is not connected, the I²C circuitry is powered from the battery through BAT. The battery voltage must stay above 2.5 V with no input connected in order to maintain proper operation.

The data transfer protocol for standard and fast modes is exactly the same; therefore, they are referred to as the F/S-mode in this document. The BQ2416xx devices only support 7-bit addressing. The device 7-bit address is defined as '1101011' (6Bh).

8.5.1.1 F/S Mode Protocol

The host initiates data transfer by generating a start condition. The start condition is when a high-to-low transition occurs on the SDA line while SCL is high, as shown in \boxtimes 8-8. All I²C-compatible devices should recognize a start condition.

図 **8-8. START and STOP Condition**

The host then generates the SCL pulses, and transmits the 8-bit address and the read/write direction bit R/W on the SDA line. During all transmissions, the host ensures that data is valid. A valid data condition requires the SDA line to be stable during the entire high period of the clock pulse (see \boxtimes 8-9). All devices recognize the address sent by the host and compare it to their internal fixed addresses. Only the target device with a matching address generates an acknowledge (see \boxtimes [8-10\)](#page-27-0) by pulling the SDA line low during the entire high period of the ninth SCL cycle. Upon detecting this acknowledge, the host knows that communication link with a target has been established.

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The host generates further SCL cycles to either transmit data to the target (R/W bit 1) or receive data from the target (R/W bit 0). In either case, the receiver needs to acknowledge the data sent by the transmitter. So an acknowledge signal can either be generated by the host or by the target, depending on which one is the receiver. The 9-bit valid data sequences consisting of 8-bit data and 1-bit acknowledge can continue as long as necessary. To signal the end of the data transfer, the host generates a stop condition by pulling the SDA line from low to high while the SCL line is high (see \boxtimes 8-11). This releases the bus and stops the communication link with the addressed target. All I²C compatible devices must recognize the stop condition. Upon the receipt of a stop condition, all devices know that the bus is released, and wait for a start condition followed by a matching address. If a transaction is terminated prematurely, the host needs sending a STOP condition to prevent the target I²C logic from remaining in an incorrect state. Attempting to read data from register addresses not listed in this section result in FFh being read out.

図 **8-11. Bus Protocol**

8.6 Register Maps

8.6.1 Status/Control Register (READ/WRITE)

Memory location: 00, Reset state: 0xxx 0xxx

SUPPLY_SEL Bit (Supply Precedence Selector)

The SUPPLY SEL bit selects which supply has precedence when both supplies are present. In cases where both supplies are connected, they must remain isolated from each other which means only one is allowed to charge the battery. Write a 1 to SUPPLY_SEL to select the USB input to have precedence. Write a 0 to select the IN input.Note the following behavior when switching the SUPPLY_SEL bit with both supplies attached:

- The BQ2416xx returns to high impedance mode
- The input supply is switched
- The BQ2416xx begins a full startup cycle starting with bad adapter detection then proceeding to soft-start

Similarly, if charging from the non-preferred supply when the preferred supply is attached, the BQ2416xx follows the same procedure.

STAT_x and FAULT_x Bits

The STAT x show the current status of the device and are updated dynamically as the IC changes state. The FAULT x bits show faults that have occurred and are only cleared by reading the bits, assuming the fault no longer exists. If multiple faults occur, the first one is the one that is shown.

8.6.2 Battery/ Supply Status Register (READ/WRITE)

Memory location: 01, Reset state: xxxx 0xxx

[BQ24160,](https://www.ti.com/product/ja-jp/bq24160?qgpn=bq24160) [BQ24160A,](https://www.ti.com/product/ja-jp/bq24160a?qgpn=bq24160a) [BQ24161](https://www.ti.com/product/ja-jp/bq24161?qgpn=bq24161), [BQ24161B](https://www.ti.com/product/ja-jp/bq24161b?qgpn=bq24161b), [BQ24163,](https://www.ti.com/product/ja-jp/bq24163?qgpn=bq24163) [BQ24168](https://www.ti.com/product/ja-jp/bq24168?qgpn=bq24168) [JAJSOY8H](https://www.tij.co.jp/jp/lit/pdf/JAJSOY8) – NOVEMBER 2011 – REVISED JULY 2022 **www.tij.co.jp**

OTG_LOCK Bit (USB Lockout)

The OTG_LOCK bit is used to prevent any charging from USB input regardless of the SUPPLY_SEL bit and IN supply status. For systems using OTG supplies, it is not desirable to charge from an OTG source. Doing so would mean draining the battery by allowing it to effectively charge itself. Write a "1" to OTG_LOCK to lock out the USB input. Write a "0" to OTG_LOCK to return to normal operation. During OTG lock, the USB input is ignored and DRV does not come up. The watchdog timer must be reset while in USB_LOCK to maintain the USB lockout state. This prevents the USB input from being permanently locked out for cases where the host loses I²C communication with OTG_LOCK set (for example, discharged battery from OTG operation). See the *Safety Timer and Watchdog Timer* section for more details.

EN_NOBATOP (No Battery Operation)

The EN_NOBATOP bit enables no battery operation. When using the BQ2416x without a battery attached, it is recommended to first disable charging, then disable charge termination and finally set this bit to 1. Setting this bit to 1 also disables the reverse boost prevention circuit and the BATOVP circuit. With a battery attached, setting this bit to 1 may be helpful to ensure full battery charging as explained in the reverse battery prevention circuit section. In the event of battery overvoltage (for example, recovery from large SYS load transient requiring supplement), the BATOVP protection circuit turns off the buck converter to allow the battery to discharge through SYS.

8.6.3 Control Register (READ/WRITE)

Memory location: 02, Reset state: 1000 1100

(1) When in DEFAULT mode, the D+/D– (BQ24160) or PSEL (BQ24161/8) inputs determine the input current limit for the USB input.

RESET Bit

The RESET bit in the control register (0x02h) is used to reset all the charge parameters. Write 1 to RESET bit to reset all the registers to default values and place the BQ2416xx into DEFAULT mode and turn off the watchdog timer. The RESET bit is automatically cleared to zero once the BQ2416xx enters DEFAULT mode.

CE Bit (Charge Enable)

The CE bit in the control register (0x02h) is used to disable or enable the charge process. A low logic level (0) on this bit enables the charge and a high logic level (1) disables the charge. When charge is disabled, the SYS output regulates to VSYS(REG) and battery is disconnected from the SYS. Supplement mode is still available if the system load demands cannot be met by the supply.

HZ_MODE Bit (High Impedance Mode Enable)

The HZ_MODE bit in the control register (0x02h) is used to disable or enable the high impedance mode. A low logic level (0) on this bit enables the IC and a high logic level (1) puts the IC in a low quiescent current state called high impedance mode. When in high impedance mode, the converter is off and the battery FET and BGATE are on. The load on SYS is supplied by the battery.

8.6.4 Control/Battery Voltage Register (READ/WRITE)

Memory location: 03, Reset state: 0001 0100

- Charge voltage range is 3.5 V 4.44 V with the offset of 3.5 V and step of 20 mV (default 3.6 V).
- Before writing to increase VBATREG register following a BATOVP event (for example, IN or USB voltage is applied, IC remains in DEFAULT mode and then VBAT > 3.6 V is attached), toggle the HiZ bit or CD pin to clear the BATOVP fault.

8.6.5 Vender/Part/Revision Register (READ only)

Memory location: 04, Reset state: 0100 0000

8.6.6 Battery Termination/Fast Charge Current Register (READ/WRITE)

Memory location: 05, Reset state: 0011 0010

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- Charge current sense offset is 550 mA and default charge current is 1000 mA.
- Termination threshold offset is 50 mA and default termination current is 150 mA

8.6.7 VIN-DPM Voltage/ DPPM Status Register

Memory location: 06, Reset state: xx00 0000

• V_{IN-DPM} voltage offset is 4.20 V and default V_{IN-DPM} threshold is 4.20 V.

8.6.8 Safety Timer/ NTC Monitor Register (READ/WRITE)

Memory location: 07, Reset state: 1001 1xxx

2xTMR_EN Bit (2x Timer Enable)

The 2xTMR_EN bit is used to slow down the timer when charge current is reduced by the system load. When 2xTMR_EN is a 1, the safety timer is slowed to half speed effectively doubling the timer time. The conditions that activate the 2x timer are: Input Current Limit, V_{INDPM}, Thermal Regulation, LOW_CHG, BATSHRT and TS Cool. When 2xTMR_EN is a 0, the timer operates at normal speed in all conditions.

LOW_CHG Bit (Low Charge Mode Enable)

The LOW_CHG bit is used to reduce the charge current from the programmed value. This feature is used by systems where battery NTC is monitored by the host and requires a reduced charge current setting or by systems that need a "preconditioning" current for low battery voltages. Write a 1 to this bit to charge at half of the programmed charge current (BQ24160/1/3/8). Write a 0 to this bit to charge at the programmed charge current.

9 Application and Implementation

9.1 Application Information

A typical application circuit using the BQ24160 with a smartphone's GSM power amplifier (PA) powered directly from the battery is shown in \boxtimes 9-1. A typical application circuit using the BQ24161 with a smartphone's GSM PA powered from the SYS rail, to allow for calls even with a deeply discharged battery, is shown in \boxtimes [9-2.](#page-34-0) Each circuit shows the minimum capacitance requirements for each pin and typical recommended inductance value of 1.5 µH. The TS resistor divider for configuring the TS function for the battery's specific thermistor can be computed from equations \pm 1 and \pm 2. The resistor on STAT is sized per the LED current requirements. All other configuration settings for VINDPM, input current limit, charge current and charge voltage are made in EEPROM registers using I²C commands. Options for sizing the inductor outside the 1.5 µH recommended value and additional SYS pin capacitance are explained in the next section.

9.2 Typical Application

図 **9-1. BQ24160, Shown with no External Discharge FET, PA Connected to Battery**

図 **9-2. BQ24161, Shown with External Discharge FET, PA Connected to System for GSM Call Support with a Deeply Discharged or No Battery**

9.2.1 Design Requirements

9.2.2 Detailed Design Procedure

9.2.2.1 Output Inductor and Capacitor Selection Guidelines

When selecting an inductor, several attributes must be examined to find the right part for the application. First, the inductance value should be selected. The BQ2416xx is designed to work with 1.5-µH to 2.2-µH inductors. The chosen value will have an effect on efficiency and package size. Due to the smaller current ripple, some efficiency gain is reached using the 2.2-µH inductor, however, due to the physical size of the inductor, this may not be a viable option. The 1.5-µH inductor provides a good tradeoff between size and efficiency.

Once the inductance has been selected, the peak current must be calculated in order to choose the current rating of the inductor. Use ± 5 to calculate the peak current.

$$
I_{PEAK} = I_{LOAD(MAX)} \times \left(1 + \frac{\%RIPPPLE}{2}\right)
$$

(5)

[BQ24160,](https://www.ti.com/product/ja-jp/bq24160?qgpn=bq24160) [BQ24160A,](https://www.ti.com/product/ja-jp/bq24160a?qgpn=bq24160a) [BQ24161](https://www.ti.com/product/ja-jp/bq24161?qgpn=bq24161), [BQ24161B](https://www.ti.com/product/ja-jp/bq24161b?qgpn=bq24161b), [BQ24163,](https://www.ti.com/product/ja-jp/bq24163?qgpn=bq24163) [BQ24168](https://www.ti.com/product/ja-jp/bq24168?qgpn=bq24168) [JAJSOY8H](https://www.tij.co.jp/jp/lit/pdf/JAJSOY8) – NOVEMBER 2011 – REVISED JULY 2022 **www.tij.co.jp**

The inductor selected must have a saturation current rating greater than or equal to the calculated I_{PEAK}. Due to the high currents possible with the BQ2416xx, a thermal analysis must also be done for the inductor. Many inductors have a 40°C temperature-rise rating. The DC component of the current can cause a 40°C temperature rise above the ambient temperature in the inductor. For this analysis, the typical load current may be used adjusted for the duty cycle of the load transients. For example, if the application requires a 1.5-A DC load with peaks at 2.5 A 20% of the time, a Δ40°C temperature rise current must be greater than 1.7 A:

$$
I_{\text{TEMPRISE}} = I_{\text{LOAD}} + D \times (I_{\text{PEAK}} - I_{\text{LOAD}}) = 1.5A + 0.2 \times (2.5A - 1.5A) = 1.7A
$$
 (6)

The BQ2416xx provides internal loop compensation. Using this scheme, the BQ2416xx is stable with 10 µF to 200 µF of local capacitance on the SYS output. The capacitance on the SYS rail can be higher if distributed amongst the rail. To reduce the output voltage ripple, a ceramic capacitor with the capacitance between 10 µF and 47 µF is recommended for local bypass to SYS. A 47-µF bypass capacitor is recommended for optimal transient response.

9.2.3 Application Curves

10 Power Supply Recommendations

10.1 Requirements for SYS Output

In order to provide an output voltage on SYS, the BQ2416xx requires either a power supply between 4.2 V and 6.0 V for USB input on all versions, 4.2 V and 6.0 V for IN input on BQ24168 and 4.2 V and 10.0 V on the remaining versions with at least 100-mA current rating connected to IN or USB or a single-cell LiIon battery with voltage > $V_{BATUVLO}$ connected to BAT. The source current rating needs to be at least 2.5 A in order for the charger's buck converter to provide maximum output power to SYS.

10.2 Requirements for Charging

In order for charging to occur, the source voltage as measured at the IC's USB or IN pins (factoring in cable/ trace losses from the source) must be greater than the VINDPM threshold (but less than the maximum values above) and the source's current rating must be higher than the buck converter needs to provide the load on SYS. For charging at a desired charge current of I_{CHRG}, V_{USBorIN}x I_{USBorIN} x η > V_{SYS} x (I_{SYS}+ I_{CHRG}) where η is the efficiency estimate from 図 [7-1](#page-10-0) or 図 [7-2](#page-10-0) and V_{SYS} = V_{BAT} when V_{BAT} charges above V_{MINSYS}. The charger limits I_{USBorIN} to that input's current limit setting. With I_{SYS} = 0 A, the charger consumes maximum power at the end of CC mode, when the voltage at the BAT pin is near VBATREG but I_{CHRG} has not started to taper off toward ITERM.

11 Layout

11.1 Layout Guidelines

It is important to pay special attention to the PCB layout. \boxtimes [11-1](#page-39-0) provides a sample layout for the high current paths of the BQ2416xx. A list of layout guidelines follows.

- To obtain optimal performance, the power input capacitors, connected from the PMID input to PGND, must be placed as close as possible to the BQ2416xx
- Minimize the amount of inductance between BAT and the postive connection of the battery terminal. If a large parasitic board inductance on BAT is expected, increase the bypass capacitance on BAT.
- Place 4.7-µF input capacitor as close to PMID_ pin and PGND pin as possible to make high frequency current loop area as small as possible. Place 1-µF input capacitor GNDs as close to the respective PMID cap GND and PGND pins as possible to minimize the ground difference between the input and PMID_.
- The traces from the input connector to the inputs of the BQ2416xx should be as wide as possible to minimize the impedance in the line. Although the VINDPM feature will allow operation from input sources having high resistances(impedances), the BQ2416xx input pins (IN and USB) have been optimized to connect to input sources with no more than 350 mΩ of input resistance, including cables and PCB traces
- The local bypass capacitor from SYS to GND should be connected between the SYS pin and PGND of the IC. The intent is to minimize the current path loop area from the SW pin through the LC filter and back to the PGND pin.
- Place all decoupling capacitors close to their respective IC pins and as close as to PGND (do not place components such that routing interrupts power stage currents). All small control signals should be routed away from the high-current paths.
- The PCB should have a ground plane (return) connected directly to the return of all components through vias (two vias per capacitor for power-stage capacitors, one via per capacitor for small-signal components). It is also recommended to put vias inside the PGND pads for the IC, if possible. A star ground design approach is typically used to keep circuit block currents isolated (high-power/low-power small-signal) which reduces noise-coupling and ground-bounce issues. A single ground plane for this design gives good results. With this small layout and a single ground plane, there is no ground-bounce issue, and having the components segregated minimizes coupling between signals.
- The high-current charge paths into IN, USB, BAT, SYS and from the SW pins must be sized appropriately for the maximum charge current in order to avoid voltage drops in these traces. The PGND pins should be connected to the ground plane to return current through the internal low-side FET.
- For high-current applications, the balls for the power paths should be connected to as much copper in the board as possible. This allows better thermal performance because the board conducts heat away from the IC.

11.2 Layout Example

VQFN

12 Device and Documentation Support

12.1 Device Support

12.1.1 Third-Party Products Disclaimer

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12.5 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

12.6 Glossary

[TI Glossary](https://www.ti.com/lit/pdf/SLYZ022) This glossary lists and explains terms, acronyms, and definitions.

Mechanical, Packaging, and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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PACKAGE OPTION ADDENDUM

www.ti.com 27-Sep-2023

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TEXAS

TAPE AND REEL INFORMATION

ISTRUMENTS

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

PACKAGE MATERIALS INFORMATION

www.ti.com 6-Jun-2024

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PACKAGE MATERIALS INFORMATION

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YFF (R-XBGA-N49)

DIE-SIZE BALL GRID ARRAY

Β. This drawing is subject to change without notice.

C. NanoFree™ package configuration.

NanoFree is a trademark of Texas Instruments

GENERIC PACKAGE VIEW

RGE 24 VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD

Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.

4204104/H

PACKAGE OUTLINE

VQFN - 1 mm max height RGE0024H

PLASTIC QUAD FLATPACK- NO LEAD

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the
- The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

EXAMPLE BOARD LAYOUT

RGE0024H VQFN - 1 mm max height

PLASTIC QUAD FLATPACK- NO LEAD

NOTES: (continued)

- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- 5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

RGE0024H VQFN - 1 mm max height

PLASTIC QUAD FLATPACK- NO LEAD

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations..

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