

CC1314R10 SimpleLink™ 高性能 Sub-1GHz ワイヤレス・マイコン

1 特長

ワイヤレス・マイクロコントローラ

- 強力な 48MHz Arm® Cortex®-M33 プロセッサと TrustZone® の組み合わせ
- FPU と DSP の拡張機能
- 1024kB フラッシュ・プログラム・メモリ
- 8kB のキャッシュ SRAM
- 高信頼性動作に適した 256kB の超低リーク SRAM (パリティ付き)
 - パリティが無効になっている場合は 32kB の SRAM を追加可能
- ダイナミック・マルチプロトコル・マネージャ (DMM) ドライバ
- OTA (Over-The-Air) アップグレードに対応

超低消費電力センサ・コントローラ

- 4kB の SRAM を備えた自律型 MCU
- センサ・データのサンプリング、保存、処理
- 高速ウェークアップによる低消費電力動作
- ソフトウェア定義ペリフェラル、静電容量式タッチ、流量計、LCD

低い消費電力

- MCU の消費電流:
 - 3.4mA (アクティブ・モード、CoreMark®)
 - 71µA/MHz (CoreMark 実行中)
 - 0.98µA (スタンバイ・モード、RTC、256kB RAM)
 - 0.17µA (シャットダウン・モード、ウェークアップ・オン・ピン)
- 超低消費電力センサ・コントローラの消費電流:
 - 30µA (2MHz モード)
 - 809µA (24MHz モード)
- 無線の消費電流:
 - 25.8mA (TX、+14dBm、868MHz)

無線プロトコルのサポート

- Wi-SUN®
- MIOTY®
- Amazon Sidewalk
- ワイヤレス M-Bus
- SimpleLink™ TI 15.4 スタック (Sub-1GHz)
- 独自システム

高性能の無線

- コヒーレント・モデム、802.15.4 O-QPSK
- 121dBm (2.5kbps、長距離モード)
- 110dBm (50kbps、802.15.4、868MHz)

法規制の順守

- 以下の規格への準拠を目的としたシステムに最適:
 - ETSI EN 300 220 Receiver Cat.1.5 および 2、EN 303 131、EN 303 204
 - FCC CFR47 Part 15
 - ARIB STD-T108 および STD-T67

MCU のペリフェラル

- ほとんどのデジタル・ペリフェラルを任意の GPIO に配線可能
- 4 つの 32 ビットまたは 8 つの 16 ビット汎用タイマ
- 12 ビット SAR ADC、200ksps、8 チャンネル
- 8 ビット DAC
- 2 つのコンパレータ
- プログラマブル電流ソース
- 4 つの UART、4 つの SPI、2 つの I²C、I²S
- リアルタイム・クロック (RTC)
- 温度およびバッテリー・モニタを内蔵

セキュリティを実現する機能

- セキュア・ブートのサポート
- セキュア・キー・ストレージとデバイス ID をサポート
- 信頼できる実行環境に対応する Arm TrustZone
- AES 128 および 256 ビット暗号化アクセラレータ
- 公開鍵アクセラレータ
- SHA2 アクセラレータ (SHA-512 までのフル・スイート)
- TRNG (True Random Number Generator)
- セキュア・デバッグ・ロック
- ソフトウェア・アンチロールバック保護

開発ツールとソフトウェア

- LP-EM-CC1314R10
- LP-XDS110、LP-XDS110ET または TMDSEMU110-U (TMDSEMU110-ETH アドオン使用) デバッグ・プローブ
- SimpleLink™ LOWPOWER F2 ソフトウェア開発キット (SDK)
- SmartRF™ Studio による簡素な無線構成
- Sensor Controller Studio により低消費電力のセンシング・アプリケーションを構築
- SysConfig システム・コンフィギュレーション・ツール

動作範囲

- オンチップの降圧型 DC/DC コンバータ
- 1.8V~3.8V の単一電源電圧
- 40°C~+105°C

パッケージ

- 7mm × 7mm RGZ VQFN48 (GPIO 30 本)



- 8mm × 8mm RSK VQFN64 (GPIO 46 本)¹
- RoHS 準拠のパッケージ

2 アプリケーション

- 315、433、470～510、868、902～928MHz の ISM および SRD システム²(最小 4kHz の受信帯域幅)
- ビルディング・オートメーション
 - ビルディングのセキュリティ・システム – モーション検出器、電子スマート・ロック、ドアおよび窓センサ、ガレージ・ドア・システム、ゲートウェイ
 - HVAC - サーモスタット、ワイヤレス環境センサ、HVAC システム・コントローラ、ゲートウェイ
 - 防火システム - 煙および熱感知器、火災警報制御パネル (FACP)
 - ビデオ監視 - IP ネットワーク・カメラ
 - エレベータとエスカレータ - エレベータとエスカレータのエレベータ・メイン制御パネル
- グリッド・インフラストラクチャ

- スマート・メータ - 水道メータ、ガス・メータ、電気メータ、ヒート・コスト・アラーム
- グリッド通信 - 無線通信 - 長距離センサ・アプリケーション
- その他の代替エネルギー - 環境発電、ソーラーインバータ
- 産業用輸送 - アセット・トラッキング
- ファクトリ・オートメーションおよび制御
- 医療用
- 電子 POS (EPOS) - 電子棚札 (ESL)
- パーソナル・エレクトロニクス
 - ネットワーク接続の周辺機器 - 民生用ワイヤレス・モジュール
 - ホーム・シアターおよびエンターテインメント - スマート・スピーカ、セット・トップ・ボックス
 - ゲーム
 - ウェアラブル (非医療用)

3 概要

SimpleLink™ CC1314R10 デバイスは低消費電力の Sub-1GHz ワイヤレス・マイクロコントローラ (MCU) で、強化されたセキュリティ、オンチップのワイヤレス更新機能、高度なアプリケーションや大規模なワイヤレス・プロトコルのサポートを必要とするアプリケーションを対象としています。IEEE 802.15.4、IPv6 対応スマート・オブジェクト (6LoWPAN)、ワイヤレス M-Bus、Wi-SUN、Amazon Sidewalk、MIOTY、および TI 15.4-Stack (Sub-1GHz) などの各種独自システムをサポートしています。本デバイスは、ビルディングのセキュリティ・システム、HVAC、スマート・メータ、医療、有線ネットワーク、ゲートウェイとグリッド通信、ホーム・シアター / エンターテインメント、ネットワーク接続周辺機器市場を対象とした低消費電力の無線通信と高度なセンシングに最適化されています。このデバイスの主な特長を以下に示します

- Arm TrustZone ベースのセキュア・キー・ストレージ、デバイス ID、トラステッド機能をサポート。
- 産業用の要求を満たす業界標準の周波数帯域 (315MHz、433MHz、868MHz、915MHz など) に対応するフレキシブルな Sub-1GHz 無線。
- Wi-SUN、Amazon Sidewalk、SimpleLink 15.4-Stack (Sub-1GHz) などの SimpleLink LOWPOWER F2 ソフトウェア開発キット (SDK) で幅広いプロトコル・スタックを柔軟にサポート。
- Sub-1GHz (消費電流 25.8mA) で +14dBm の最大送信出力。
- 0.98μA の小さいスタンバイ電流 (全 RAM 保持) によるバッテリー寿命が長いワイヤレス・アプリケーション。
- 産業用温度に対応し、105°C で 13μA の最小スタンバイ電流 (全 RAM 保持)。
- 高速ウェークアップ機能を備えたプログラマブルな自律型超低消費電力センサ・コントローラ CPU による高度なセンシング。たとえば、このセンサ・コントローラは、1.2μA のシステム電流で 1Hz の ADC サンプリングが可能です。
- 潜在的な放射線イベントによるデータ破損を防止する常時オン SRAM パリティを備え、低い SER (ソフト・エラー・レート) FIT (Failure-in-time、故障率) により、産業用市場向けに中断のない長い動作寿命を実現。
- 柔軟性の高い低消費電力 RF トランシーバ機能を備えた専用のソフトウェア制御無線コントローラ (Arm Cortex-M0) により、複数の物理層および RF 規格をサポート。
- SimpleLink 長距離モードに対応する優れた無線感度 (-121dBm) と堅牢 (選択度、ブロッキング) 性能。

CC1314R10 デバイスは、SimpleLink™ MCU プラットフォームの一部です。本プラットフォームは、単一のコア SDK (ソフトウェア開発キット) と豊富なツール・セットを備えた使いやすい共通の開発環境を共有する Wi-Fi®、Bluetooth Low Energy、Thread、Zigbee、Sub-1GHz MCU、およびホスト MCU で構成されています。SimpleLink プラットフォームの統合を 1 回行うだけで、どのようなデバイスの組み合わせでも、ポートフォリオから自分の設計に追加でき、設計の要件が変化した場合でも、コードを 100% 再利用することができます。詳細については、「SimpleLink MCU プラットフォーム」を参照してください。

¹ RSK パッケージ (8.00mm × 8.00mm) に関する情報はプレビューについてのものであり、変更される可能性があります。

² サポートしているプロトコル規格、変調フォーマット、データ・レートの詳細については、RF コアを参照してください。

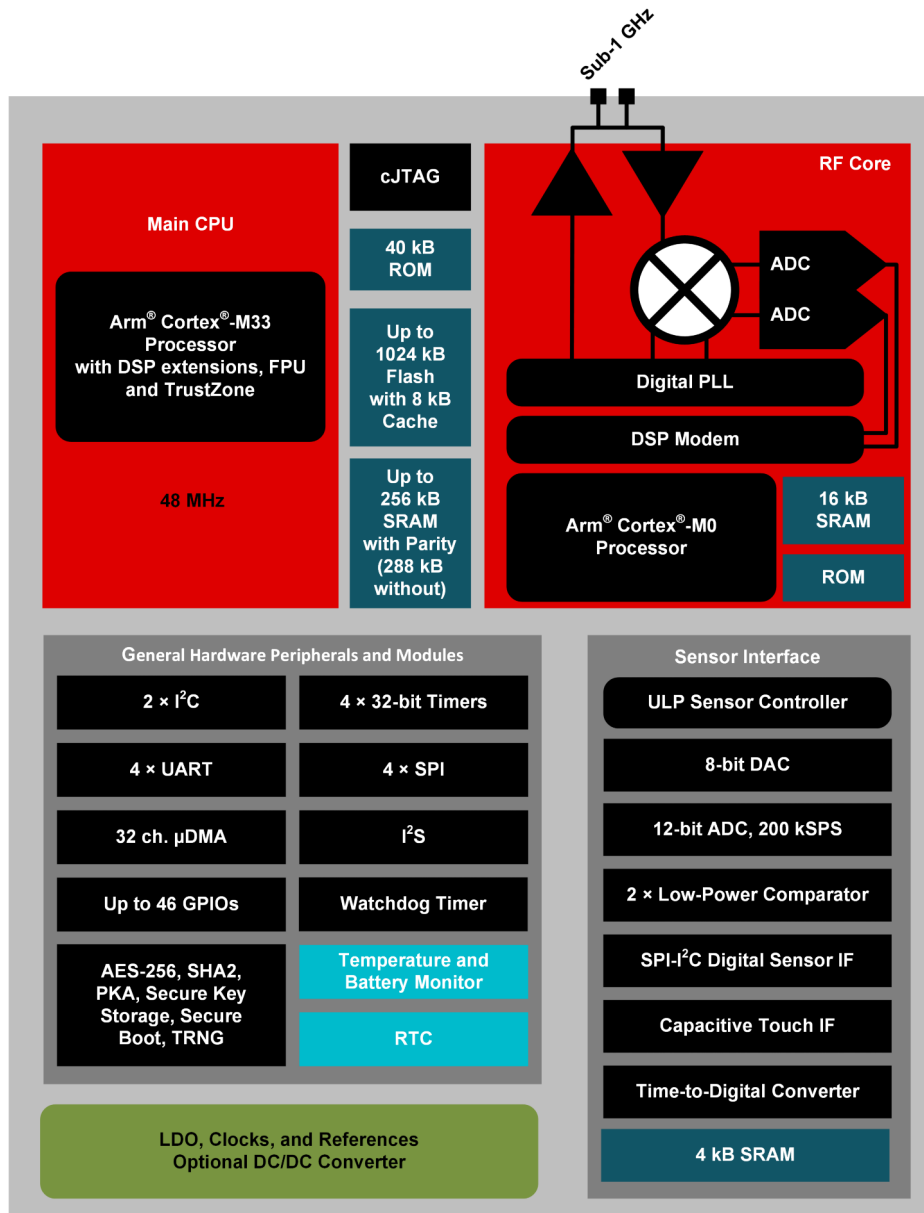
ソフトウェアの互換性に加えて、Sub-1GHz ワイヤレス MCU は 7 × 7mm の QFN パッケージに封止済みで、32kB のフラッシュから 1MB のフラッシュまでの間でピン互換性があるので、設計のスケラビリティを最大限に高めることができます。テキサス・インスツルメンツの Sub-1GHz ソリューションの詳細については、www.ti.com/sub1ghz を参照してください。

製品情報

| 部品番号 ⁽¹⁾ | パッケージ | 本体サイズ (公称) |
|---------------------|-----------|-----------------|
| CC1314R106T0RGZ | VQFN (48) | 7.00mm × 7.00mm |
| CC1314R106T0RSK | VQFN (64) | 8.00mm × 8.00mm |

- (1) 提供中の全デバイスに関する最新の製品、パッケージ、および注文情報については、[セクション 12](#) のパッケージ・オプションに関する付録、または [テキサス・インスツルメンツの Web サイト](#) を参照してください。

4 Functional Block Diagram



4-1. CC1314R10 Block Diagram

ADVANCE INFORMATION

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5 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Changes from December 8, 2022 to June 14, 2023 (from Revision * (December 2022) to Revision A (June 2023))

| | Page |
|---|------|
| • Added devices to the Device Comparison table..... | 6 |
| • Deleted device revision limitation for LQI in 表 9-1 | 52 |
| • Updated links in the Reference Designs..... | 61 |

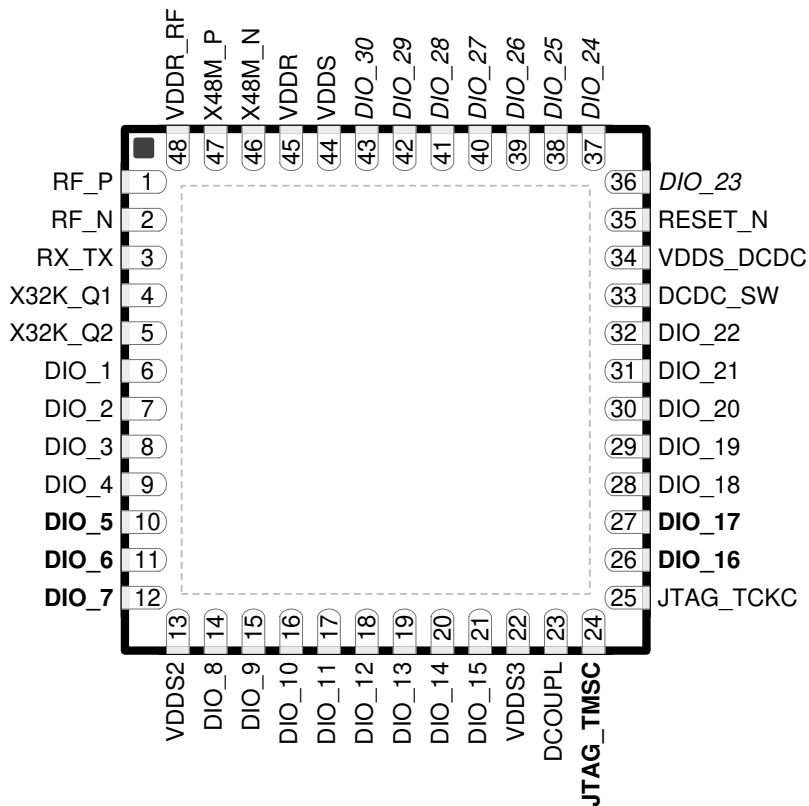
6 Device Comparison

| Device | RADIO SUPPORT | | | | | | | | | | | FLASH (kB) | RAM + Cache (kB) | GPIO | PACKAGE SIZE | | | | | |
|-------------|-----------------|--------------|----------------|-------|---------|----------|---------------|--------|--------|---------------|------------|------------|------------------|-------|--------------------|--------------------|--------------------|--------------------|--------------------|--------------------|
| | Sub-1 GHz Prop. | 2.4GHz Prop. | Wireless M-Bus | mioty | Wi-SUN® | Sidewalk | Bluetooth® LE | ZigBee | Thread | Multiprotocol | +20 dBm PA | | | | 4 x 4 mm VQFN (24) | 4 x 4 mm VQFN (32) | 5 x 5 mm VQFN (32) | 5 x 5 mm VQFN (40) | 7 x 7 mm VQFN (48) | 8 x 8 mm VQFN (64) |
| CC1310 | √ | | √ | √ | | | | | | | | 32-128 | 16-20 + 8 | 10-30 | | √ | √ | | √ | |
| CC1311R3 | √ | | √ | √ | | | | | | | | 352 | 32 + 8 | 22-30 | | | | √ | √ | |
| CC1311P3 | √ | | √ | √ | | | | | | | √ | 352 | 32 + 8 | 26 | | | | | √ | |
| CC1312R | √ | | √ | √ | √ | | | | | | | 352 | 80 + 8 | 30 | | | | | √ | |
| CC1312R7 | √ | | √ | √ | √ | √ | | | √ | | | 704 | 144 + 8 | 30 | | | | | √ | |
| CC1314R10 | √ | | √ | √ | √ | √ | | | √ | | | 1024 | 256 + 8 | 30-46 | | | | | √ | √ |
| CC1352R | √ | √ | √ | √ | √ | | √ | √ | √ | √ | | 352 | 80 + 8 | 28 | | | | | √ | |
| CC1354R10 | √ | √ | √ | √ | √ | | √ | √ | √ | √ | | 1024 | 256 + 8 | 28-42 | | | | | √ | √ |
| CC1352P | √ | √ | √ | √ | √ | | √ | √ | √ | √ | √ | 352 | 80 + 8 | 26 | | | | | √ | |
| CC1352P7 | √ | √ | √ | √ | √ | √ | √ | √ | √ | √ | √ | 704 | 144 + 8 | 26 | | | | | √ | |
| CC1354P10 | √ | √ | √ | √ | √ | √ | √ | √ | √ | √ | √ | 1024 | 256 + 8 | 26-42 | | | | | √ | √ |
| CC2340R2 | | √ | | | | | √ | √ | | | | 256 | 28 | 12 | √ | | | | | |
| CC2340R5 | | √ | | | | | √ | √ | √ | | | 512 | 36 | 12-26 | √ | | | √ | | |
| CC2340R5-Q1 | | | | | | | √ | | | | | 512 | 36 | 19 | | | √ | | | |
| CC2640R2F | | | | | | | √ | | | | | 128 | 20 + 8 | 10-31 | | √ | √ | | √ | |
| CC2642R | | | | | | | √ | | | | | 352 | 80 + 8 | 31 | | | | | √ | |
| CC2642R-Q1 | | | | | | | √ | | | | | 352 | 80 + 8 | 31 | | | | | √ | |
| CC2651R3 | | √ | | | | | √ | √ | | | | 352 | 32 + 8 | 23-31 | | | | √ | √ | |
| CC2651P3 | | √ | | | | | √ | √ | | √ | | 352 | 32 + 8 | 22-26 | | | | √ | √ | |
| CC2652R | | √ | | | | | √ | √ | √ | √ | | 352 | 80 + 8 | 31 | | | | | √ | |
| CC2652RB | | √ | | | | | √ | √ | √ | √ | | 352 | 80 + 8 | 31 | | | | | √ | |
| CC2652R7 | | √ | | | | | √ | √ | √ | √ | | 704 | 144 + 8 | 31 | | | | | √ | |
| CC2652P | | √ | | | | | √ | √ | √ | √ | √ | 352 | 80 + 8 | 26 | | | | | √ | |
| CC2652P7 | | √ | | | | | √ | √ | √ | √ | √ | 704 | 144 + 8 | 26 | | | | | √ | |
| CC2674R10 | | √ | | | | | √ | √ | √ | √ | | 1024 | 256 + 8 | 31-45 | | | | | √ | √ |
| CC2674P10 | | √ | | | | | √ | √ | √ | √ | √ | 1024 | 256 + 8 | 26-45 | | | | | √ | √ |

ADVANCE INFORMATION

7 Terminal Configuration and Functions

7.1 Pin Diagram – RGZ Package (Top View)



7-1. RGZ (7 mm × 7 mm) Pinout, 0.5 mm Pitch (Top View)

The following I/O pins marked in 7-1 in **bold** have high-drive capabilities:

- Pin 10, **DIO_5**
- Pin 11, **DIO_6**
- Pin 12, **DIO_7**
- Pin 24, **JTAG_TMSC**
- Pin 26, **DIO_16**
- Pin 27, **DIO_17**

The following I/O pins marked in 7-1 in *italics* have analog capabilities:

- Pin 36, *DIO_23*
- Pin 37, *DIO_24*
- Pin 38, *DIO_25*
- Pin 39, *DIO_26*
- Pin 40, *DIO_27*
- Pin 41, *DIO_28*
- Pin 42, *DIO_29*
- Pin 43, *DIO_30*

7.2 Signal Descriptions – RGZ Package

表 7-1. Signal Descriptions – RGZ Package

| PIN | | I/O | TYPE | DESCRIPTION |
|------------|-----|-----|-------------------|---|
| NAME | NO. | | | |
| DCDC_SW | 33 | — | Power | Output from internal DC/DC converter ⁽¹⁾ |
| DCOUPPL | 23 | — | Power | For decoupling of internal 1.27 V regulated digital-supply ⁽²⁾ |
| DIO_1 | 6 | I/O | Digital | GPIO |
| DIO_2 | 7 | I/O | Digital | GPIO |
| DIO_3 | 8 | I/O | Digital | GPIO |
| DIO_4 | 9 | I/O | Digital | GPIO |
| DIO_5 | 10 | I/O | Digital | GPIO, high-drive capability |
| DIO_6 | 11 | I/O | Digital | GPIO, high-drive capability |
| DIO_7 | 12 | I/O | Digital | GPIO, high-drive capability |
| DIO_8 | 14 | I/O | Digital | GPIO |
| DIO_9 | 15 | I/O | Digital | GPIO |
| DIO_10 | 16 | I/O | Digital | GPIO |
| DIO_11 | 17 | I/O | Digital | GPIO |
| DIO_12 | 18 | I/O | Digital | GPIO |
| DIO_13 | 19 | I/O | Digital | GPIO |
| DIO_14 | 20 | I/O | Digital | GPIO |
| DIO_15 | 21 | I/O | Digital | GPIO |
| DIO_16 | 26 | I/O | Digital | GPIO, JTAG_TDO, high-drive capability |
| DIO_17 | 27 | I/O | Digital | GPIO, JTAG_TDI, high-drive capability |
| DIO_18 | 28 | I/O | Digital | GPIO |
| DIO_19 | 29 | I/O | Digital | GPIO |
| DIO_20 | 30 | I/O | Digital | GPIO |
| DIO_21 | 31 | I/O | Digital | GPIO |
| DIO_22 | 32 | I/O | Digital | GPIO |
| DIO_23 | 36 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_24 | 37 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_25 | 38 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_26 | 39 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_27 | 40 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_28 | 41 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_29 | 42 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_30 | 43 | I/O | Digital or Analog | GPIO, analog capability |
| EGP | — | — | GND | Ground – exposed ground pad ⁽³⁾ |
| JTAG_TMISC | 24 | I/O | Digital | JTAG TMISC, high-drive capability |
| JTAG_TCKC | 25 | I | Digital | JTAG TCKC |
| RESET_N | 35 | I | Digital | Reset, active low. No internal pullup resistor |
| RF_P | 1 | — | RF | Positive RF input signal to LNA during RX Positive RF output signal from PA during TX |
| RF_N | 2 | — | RF | Negative RF input signal to LNA during RX Negative RF output signal from PA during TX |
| RX_TX | 3 | — | RF | Optional bias pin for the RF LNA |
| VDDR | 45 | — | Power | Internal supply, must be powered from the internal DC/DC converter or the internal LDO ^{(2) (4) (6)} |

表 7-1. Signal Descriptions – RGZ Package (continued)

| PIN | | I/O | TYPE | DESCRIPTION |
|-----------|-----|-----|--------|---|
| NAME | NO. | | | |
| VDDR_RF | 48 | — | Power | Internal supply, must be powered from the internal DC/DC converter or the internal LDO ^{(2) (5) (6)} |
| VDDS | 44 | — | Power | 1.8 V to 3.8 V main chip supply ⁽¹⁾ |
| VDDS2 | 13 | — | Power | 1.8 V to 3.8 V DIO supply ⁽¹⁾ |
| VDDS3 | 22 | — | Power | 1.8 V to 3.8 V DIO supply ⁽¹⁾ |
| VDDS_DCDC | 34 | — | Power | 1.8 V to 3.8 V DC/DC converter supply |
| X48M_N | 46 | — | Analog | 48 MHz crystal oscillator pin N |
| X48M_P | 47 | — | Analog | 48 MHz crystal oscillator pin P |
| X32K_Q1 | 4 | — | Analog | 32 kHz crystal oscillator pin 1 |
| X32K_Q2 | 5 | — | Analog | 32 kHz crystal oscillator pin 2 |

- (1) For more details, see technical reference manual listed in [セクション 11.2](#).
- (2) Do not supply external circuitry from this pin.
- (3) EGP is the only ground connection for the device. Good electrical connection to device ground on printed circuit board (PCB) is imperative for proper device operation.
- (4) If internal DC/DC converter is not used, this pin is supplied internally from the main LDO.
- (5) If internal DC/DC converter is not used, this pin must be connected to VDDR for supply from the main LDO.
- (6) Output from internal DC/DC and LDO is trimmed to 1.68 V.

7.3 Connections for Unused Pins and Modules – RGZ Package

表 7-2. Connections for Unused Pins – RGZ Package

| FUNCTION | SIGNAL NAME | PIN NUMBER | ACCEPTABLE PRACTICE ⁽¹⁾ | PREFERRED PRACTICE ⁽¹⁾ |
|--------------------------------|-------------|------------|------------------------------------|-----------------------------------|
| GPIO | DIO_n | 6–12 | NC or GND | NC |
| | | 14–21 | | |
| | | 26–32 | | |
| | | 36–43 | | |
| 32.768 kHz crystal | X32K_Q1 | 4 | NC or GND | NC |
| | X32K_Q2 | 5 | | |
| DC/DC converter ⁽²⁾ | DCDC_SW | 33 | NC | NC |
| | VDDS_DCDC | 34 | VDDS | VDDS |

- (1) NC = No connect
- (2) When the DC/DC converter is not used, the inductor between DCDC_SW and VDDR can be removed. VDDR and VDDR_RF must still be connected and the 22 µF DCDC capacitor must be kept on the VDDR net.

7.4 Pin Diagram – RSK Package (Top View)

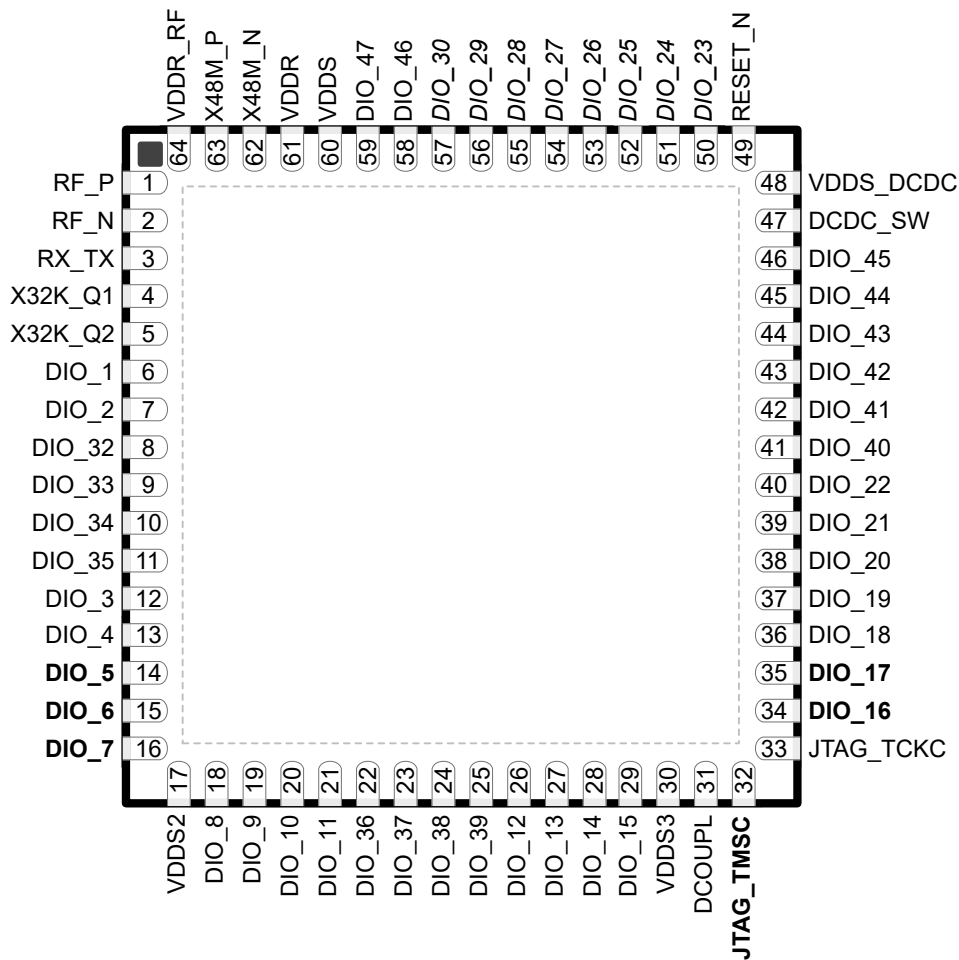


FIG 7-2. RSK (8 mm × 8 mm) Pinout, 0.4 mm Pitch (Top View)

The following I/O pins marked in FIG 7-2 in **bold** have high-drive capabilities:

- Pin 14, DIO_5
- Pin 15, DIO_6
- Pin 16, DIO_7
- Pin 32, JTAG_TMSC
- Pin 34, DIO_16
- Pin 35, DIO_17

The following I/O pins marked in FIG 7-2 in *italics* have analog capabilities:

- Pin 50, DIO_23
- Pin 51, DIO_24
- Pin 52, DIO_25
- Pin 53, DIO_26
- Pin 54, DIO_27
- Pin 55, DIO_28
- Pin 56, DIO_29
- Pin 57, DIO_30

7.5 Signal Descriptions – RSK Package

表 7-3. Signal Descriptions – RSK Package

| PIN | | I/O | TYPE | DESCRIPTION |
|---------|-----|-----|-------------------|---|
| NAME | NO. | | | |
| DCDC_SW | 47 | — | Power | Output from internal DC/DC converter ⁽¹⁾ |
| DCOUPPL | 31 | — | Power | For decoupling of internal 1.27 V regulated digital-supply ⁽²⁾ |
| DIO_1 | 6 | I/O | Digital | GPIO |
| DIO_2 | 7 | I/O | Digital | GPIO |
| DIO_3 | 12 | I/O | Digital | GPIO |
| DIO_4 | 13 | I/O | Digital | GPIO |
| DIO_5 | 14 | I/O | Digital | GPIO, high-drive capability |
| DIO_6 | 15 | I/O | Digital | GPIO, high-drive capability |
| DIO_7 | 16 | I/O | Digital | GPIO, high-drive capability |
| DIO_8 | 18 | I/O | Digital | GPIO |
| DIO_9 | 19 | I/O | Digital | GPIO |
| DIO_10 | 20 | I/O | Digital | GPIO |
| DIO_11 | 21 | I/O | Digital | GPIO |
| DIO_12 | 26 | I/O | Digital | GPIO |
| DIO_13 | 27 | I/O | Digital | GPIO |
| DIO_14 | 28 | I/O | Digital | GPIO |
| DIO_15 | 29 | I/O | Digital | GPIO |
| DIO_16 | 34 | I/O | Digital | GPIO, JTAG_TDO, high-drive capability |
| DIO_17 | 35 | I/O | Digital | GPIO, JTAG_TDI, high-drive capability |
| DIO_18 | 36 | I/O | Digital | GPIO |
| DIO_19 | 37 | I/O | Digital | GPIO |
| DIO_20 | 38 | I/O | Digital | GPIO |
| DIO_21 | 39 | I/O | Digital | GPIO |
| DIO_22 | 40 | I/O | Digital | GPIO |
| DIO_23 | 50 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_24 | 51 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_25 | 52 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_26 | 53 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_27 | 54 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_28 | 55 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_29 | 56 | I/O | Digital or Analog | GPIO, analog capability |
| DIO_30 | 57 | I/O | Digital | GPIO, analog capability |
| DIO_32 | 8 | I/O | Digital | GPIO |
| DIO_33 | 9 | I/O | Digital | GPIO |
| DIO_34 | 10 | I/O | Digital | GPIO |
| DIO_35 | 11 | I/O | Digital | GPIO |
| DIO_36 | 22 | I/O | Digital | GPIO |
| DIO_37 | 23 | I/O | Digital | GPIO |
| DIO_38 | 24 | I/O | Digital | GPIO |
| DIO_39 | 25 | I/O | Digital | GPIO |
| DIO_40 | 41 | I/O | Digital | GPIO |
| DIO_41 | 42 | I/O | Digital | GPIO |

表 7-3. Signal Descriptions – RSK Package (continued)

| PIN | | I/O | TYPE | DESCRIPTION |
|---------------|-----|-----|---------|---|
| NAME | NO. | | | |
| DIO_42 | 43 | I/O | Digital | GPIO |
| DIO_43 | 44 | I/O | Digital | GPIO |
| DIO_44 | 45 | I/O | Digital | GPIO |
| DIO_45 | 46 | I/O | Digital | GPIO |
| DIO_46 | 58 | I/O | Digital | GPIO |
| DIO_47 | 59 | I/O | Digital | GPIO |
| EGP | — | — | GND | Ground – exposed ground pad ⁽³⁾ |
| JTAG_TMSC | 32 | I/O | Digital | JTAG TMSC, high-drive capability |
| JTAG_TCKC | 33 | I | Digital | JTAG TCKC |
| RESET_N | 49 | I | Digital | Reset, active low. No internal pullup resistor |
| RF_P_SUB_1GHZ | 1 | — | RF | Positive RF input signal to LNA during RX Positive RF output signal from PA during TX |
| RF_N_SUB_1GHZ | 2 | — | RF | Negative RF input signal to LNA during RX Negative RF output signal from PA during TX |
| RX_TX | 3 | — | RF | Optional bias pin for the RF LNA |
| VDDR | 61 | — | Power | Internal supply, must be powered from the internal DC/DC converter or the internal LDO ^{(2) (4) (6)} |
| VDDR_RF | 64 | — | Power | Internal supply, must be powered from the internal DC/DC converter or the internal LDO ^{(2) (5) (6)} |
| VDDS | 60 | — | Power | 1.8 V to 3.8 V main chip supply ⁽¹⁾ |
| VDDS2 | 17 | — | Power | 1.8 V to 3.8 V DIO supply ⁽¹⁾ |
| VDDS3 | 30 | — | Power | 1.8 V to 3.8 V DIO supply ⁽¹⁾ |
| VDDS_DCDC | 48 | — | Power | 1.8 V to 3.8 V DC/DC converter supply |
| X48M_N | 62 | — | Analog | 48 MHz crystal oscillator pin N |
| X48M_P | 63 | — | Analog | 48 MHz crystal oscillator pin P |
| X32K_Q1 | 4 | — | Analog | 32 kHz crystal oscillator pin 1 |
| X32K_Q2 | 5 | — | Analog | 32 kHz crystal oscillator pin 2 |

(1) For more details, see technical reference manual listed in [セクション 11.2](#).

(2) Do not supply external circuitry from this pin.

(3) EGP is the only ground connection for the device. Good electrical connection to device ground on printed circuit board (PCB) is imperative for proper device operation.

(4) If internal DC/DC converter is not used, this pin is supplied internally from the main LDO.

(5) If internal DC/DC converter is not used, this pin must be connected to VDDR for supply from the main LDO.

(6) Output from internal DC/DC and LDO is trimmed to 1.68 V.

7.6 Connection of Unused Pins and Module – RSK Package

表 7-4. Connections for Unused Pins – RSK Package

| FUNCTION | SIGNAL NAME | PIN NUMBER | ACCEPTABLE PRACTICE ⁽¹⁾ | PREFERRED PRACTICE ⁽¹⁾ |
|--------------------------------|-------------|-----------------------------|------------------------------------|-----------------------------------|
| GPIO | DIO_n | 6–16, 18–29 34–46, 50–59 | NC or GND | NC |
| 32.768 kHz crystal | X32K_Q1 | 4 | NC or GND | NC |
| | X32K_Q2 | 5 | | |
| DC/DC converter ⁽²⁾ | DCDC_SW | 47 | NC | NC |
| | VDDS_DCDC | 48 | VDDS | VDDS |

(1) NC = No connect

- (2) When the DC/DC converter is not used, the inductor between DCDC_SW and VDDR can be removed. VDDR and VDDR_RF must still be connected and the 22 μ F DCDC capacitor must be kept on the VDDR net.

8 Specifications

8.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted)^{(1) (2)}

| | | MIN | MAX | UNIT |
|---|---|--|-----------------------------------|------|
| V _{DD} S ⁽³⁾ | Supply voltage | -0.3 | 4.1 | V |
| | Voltage on any digital pin ^{(4) (5)} | -0.3 | V _{DD} S + 0.3, max 4.1 | V |
| Voltage on crystal oscillator pins, X32K_Q1, X32K_Q2, X48M_N and X48M_P | | -0.3 | V _{DD} R + 0.3, max 2.25 | V |
| V _{in} | Voltage on ADC input | Voltage scaling enabled | V _{DD} S | V |
| | | Voltage scaling disabled, internal reference | 1.49 | |
| | | Voltage scaling disabled, V _{DD} S as reference | V _{DD} S / 2.9 | |
| Input level, RF pins | | | 10 | dBm |
| T _{stg} | Storage temperature | -40 | 150 | °C |

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltage values are with respect to ground, unless otherwise noted.
- (3) V_{DD}S_DCDC, V_{DD}S2 and V_{DD}S3 must be at the same potential as V_{DD}S.
- (4) Including analog capable DIOs.
- (5) Injection current is not supported on any GPIO pin

8.2 ESD Ratings

| | | | VALUE | UNIT | |
|------------------|-------------------------|---|----------|-------|---|
| V _{ESD} | Electrostatic discharge | Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾ | All pins | ±2000 | V |
| | | Charged device model (CDM), per ANSI/ESDA/JEDEC JS-002 ⁽²⁾ | All pins | ±500 | V |

- (1) JEDEC document JEP155 states that 500 V HBM allows safe manufacturing with a standard ESD control process
- (2) JEDEC document JEP157 states that 250 V CDM allows safe manufacturing with a standard ESD control process

8.3 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted)

| | | MIN | MAX | UNIT |
|--|---|-----|-----|-------|
| Operating ambient temperature ^{(1) (3)} | | -40 | 105 | °C |
| Operating supply voltage (V _{DD} S) | | 1.8 | 3.8 | V |
| Operating supply voltage (V _{DD} S), boost mode | V _{DD} R = 1.95 V +14 dBm RF output power | 2.1 | 3.8 | V |
| Rising supply voltage slew rate | | 0 | 100 | mV/μs |
| Falling supply voltage slew rate ⁽²⁾ | | 0 | 20 | mV/μs |

- (1) Operation at or near maximum operating temperature for extended durations will result in lifetime reduction.
- (2) For small coin-cell batteries, with high worst-case end-of-life equivalent source resistance, a 22 μF V_{DD}S input capacitor must be used to ensure compliance with this slew rate.
- (3) For thermal resistance characteristics refer to [Thermal Resistance Characteristics](#). For application considerations, refer to [SPRA953](#)

8.4 Power Supply and Modules

Over operating free-air temperature range (unless otherwise noted)

| PARAMETER | | MIN | TYP | MAX | UNIT |
|--|-------------------|------------|-----|-----|------|
| V _{DD} S Power-on-Reset (POR) threshold | | 1.1 - 1.55 | | | V |
| V _{DD} S Brown-out Detector (BOD) ⁽¹⁾ | Rising threshold | 1.77 | | | V |
| V _{DD} S Brown-out Detector (BOD), before initial boot ⁽²⁾ | Rising threshold | 1.70 | | | V |
| V _{DD} S Brown-out Detector (BOD) ⁽¹⁾ | Falling threshold | 1.75 | | | V |

- (1) For boost mode (V_{DD}R = 1.95 V), TI drivers software initialization will trim V_{DD}S BOD limits to maximum (approximately 2.0 V)

- (2) Brown-out Detector is trimmed at initial boot, value is kept until device is reset by a POR reset or the RESET_N pin

8.5 Power Consumption - Power Modes

When measured on the LP-EM-CC1314R10 reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.6\text{ V}$ with DC/DC enabled unless otherwise noted.

| PARAMETER | | TEST CONDITIONS | TYP | UNIT |
|---|---------------------------------------|---|-------|---------------|
| Core Current Consumption | | | | |
| I_{core} | Reset and Shutdown | Reset. RESET_N pin asserted or VDD5 below power-on-reset threshold | 150 | nA |
| | | Shutdown. No clocks running, no retention | 171 | |
| | Standby without cache retention | RTC running, CPU, 256 kB RAM and (partial) register retention. RCOSC_LF | 0.98 | μA |
| | | RTC running, CPU, 128 kB RAM and (partial) register retention. RCOSC_LF | 0.88 | |
| | | RTC running, CPU, 256 kB RAM and (partial) register retention. XOSC_LF | 1.08 | |
| | | RTC running, CPU, 128 kB RAM and (partial) register retention. XOSC_LF | 0.99 | |
| | Standby with cache retention | RTC running, CPU, 256 kB RAM and (partial) register retention. RCOSC_LF | 2.24 | μA |
| | | RTC running, CPU, 128 kB RAM and (partial) register retention. RCOSC_LF | 2.16 | |
| | | RTC running, CPU, 256 kB RAM and (partial) register retention. XOSC_LF | 2.34 | |
| | | RTC running, CPU, 128 kB RAM and (partial) register retention. XOSC_LF | 2.25 | |
| | Idle | Supply Systems and RAM powered. RCOSC_HF | 635 | μA |
| | Active | MCU running CoreMark at 48 MHz with parity enabled. RCOSC_HF | 3.5 | mA |
| | | MCU running CoreMark at 48 MHz with parity disabled. RCOSC_HF | 3.4 | |
| | Peripheral Current Consumption | | | |
| I_{peri} | Peripheral power domain | Delta current with domain enabled | 62.4 | μA |
| | Serial power domain | Delta current with domain enabled | 5.83 | |
| | RF Core | Delta current with power domain enabled, clock enabled, RF core idle | 102.0 | |
| | μDMA | Delta current with clock enabled, module is idle | 58.0 | |
| | Timers | Delta current with clock enabled, module is idle ⁽³⁾ | 97.2 | |
| | I2C | Delta current with clock enabled, module is idle | 9.8 | |
| | I2S | Delta current with clock enabled, module is idle | 22.2 | |
| | SPI | Delta current with clock enabled, module is idle ⁽²⁾ | 55.8 | |
| | UART | Delta current with clock enabled, module is idle ⁽¹⁾ | 114.2 | |
| | CRYPTO (AES) | Delta current with clock enabled, module is idle | 15.5 | |
| | PKA | Delta current with clock enabled, module is idle | 66.6 | |
| | TRNG | Delta current with clock enabled, module is idle | 21.0 | |
| Sensor Controller Engine Consumption | | | | |
| I_{SCE} | Active mode | 24 MHz, infinite loop, $V_{DD5} = 3.0\text{ V}$ | 820 | μA |
| | Low-power mode | 2 MHz, infinite loop, $V_{DD5} = 3.0\text{ V}$ | 32 | |

- (1) Only one UART running
 (2) Only one SPI running
 (3) Only one GPTimer running

8.6 Power Consumption - Radio Modes

When measured on the LP-EM-CC1314R10 reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{\text{DDS}} = 3.6\text{ V}$ with DC/DC enabled unless otherwise noted.

Using boost mode (increasing VDDR up to 1.95 V), will increase system current by 15% (does not apply to TX +14 dBm setting where this current is already included).

Relevant I_{core} and I_{peri} currents are included in below numbers.

| PARAMETER | | TEST CONDITIONS | TYP | UNIT |
|-----------|--------------------------------------|---|------|------|
| | Radio receive current, 868 MHz | | 5.8 | mA |
| | Radio transmit current | 0 dBm output power setting 868 MHz | 7.5 | mA |
| | | +10 dBm output power setting 868 MHz | 16.1 | mA |
| | Radio transmit current Boost mode | +14 dBm output power setting 868 MHz | 25.8 | mA |

8.7 Nonvolatile (Flash) Memory Characteristics

Over operating free-air temperature range and $V_{\text{DDS}} = 3.0\text{ V}$ (unless otherwise noted)

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---|---|------|------|------|------------------|
| Flash sector size | | | 2 | | kB |
| Supported flash erase cycles before failure, full bank ^{(1) (5)} | | 30 | | | k Cycles |
| Supported flash erase cycles before failure, single sector ⁽²⁾ | | 60 | | | k Cycles |
| Maximum number of write operations per row before sector erase ⁽³⁾ | | | | 83 | Write Operations |
| Flash retention | 105 °C | 11.4 | | | Years |
| Flash sector erase current | Average delta current | | 0.3 | | mA |
| Flash sector erase time ⁽⁴⁾ | Zero cycles | | 2.1 | | ms |
| | 30k cycles | | | 4000 | ms |
| Flash write current | Average delta current, 16 bytes at a time | | 3.0 | | mA |
| Flash write time ⁽⁴⁾ | 16 bytes at a time | | 21.4 | | µs |

- (1) A full bank erase is counted as a single erase cycle on each sector
- (2) Up to 4 customer-designated sectors can be individually erased an additional 30k times beyond the baseline bank limitation of 30k cycles
- (3) Each wordline is 2048 bits (or 256 bytes) wide. This limitation corresponds to sequential memory writes of 4 (3.1) bytes minimum per write over a whole wordline. If additional writes to the same wordline are required, a sector erase is required once the maximum number of write operations per row is reached.
- (4) This number is dependent on Flash aging and increases over time and erase cycles
- (5) Aborting flash during erase or program modes is not a safe operation.

8.8 Thermal Resistance Characteristics

| THERMAL METRIC ⁽¹⁾ | | PACKAGE | | UNIT |
|-------------------------------|--|------------|-----------|---------------------|
| | | RGZ (VQFN) | RSK(VQFN) | |
| | | 48 PINS | 64 PINS | |
| $R_{\theta\text{JA}}$ | Junction-to-ambient thermal resistance | 23.4 | TBD | °C/W ⁽²⁾ |
| $R_{\theta\text{JC(top)}}$ | Junction-to-case (top) thermal resistance | 13.3 | TBD | °C/W ⁽²⁾ |
| $R_{\theta\text{JB}}$ | Junction-to-board thermal resistance | 8.0 | TBD | °C/W ⁽²⁾ |
| Ψ_{JT} | Junction-to-top characterization parameter | 0.1 | TBD | °C/W ⁽²⁾ |
| Ψ_{JB} | Junction-to-board characterization parameter | 7.9 | TBD | °C/W ⁽²⁾ |
| $R_{\theta\text{JC(bot)}}$ | Junction-to-case (bottom) thermal resistance | 1.7 | TBD | °C/W ⁽²⁾ |

- (1) For more information about traditional and new thermal metrics, see [Semiconductor and IC Package Thermal Metrics](#).
- (2) °C/W = degrees Celsius per watt.

8.9 RF Frequency Bands

Over operating free-air temperature range (unless otherwise noted).

| PARAMETER | MIN | TYP | MAX | UNIT |
|-----------------|------|-----|------|------|
| Frequency bands | 1076 | | 1315 | MHz |
| | 861 | | 1054 | |
| | 431 | | 527 | |
| | 359 | | 439 | |
| | 287 | | 351 | |

ADVANCE INFORMATION

8.10 861 MHz to 1054 MHz - Receive (RX)

When Measured on the LP-EM-CC1314R10 reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD3} = 3.0\text{ V}$ with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---|--|-----|---------|------|------|
| General Parameters | | | | | |
| Digital channel filter programmable receive bandwidth | | 4 | | 4000 | kHz |
| Data rate step size | | | 1.5 | | bps |
| Spurious emissions 25 MHz to 1 GHz | 868 MHz | | < -57 | | dBm |
| Spurious emissions 1 GHz to 13 GHz | Conducted emissions measured according to ETSI EN 300 220 | | < -47 | | dBm |
| Wi-SUN, 50 kbps, ± 12.5 kHz deviation, 2-GFSK, 78 kHz RX BW, #1a | | | | | |
| Sensitivity | MRFSK, 866.6 MHz, 10% PER, 250 byte payload | | -106 | | dBm |
| Saturation limit | 10% PER, 250 byte payload, 866.6 MHz | | 10 | | dBm |
| Selectivity, +100 kHz | 10% PER, 250 byte payload, 866.6 MHz. Wanted signal 3 dB above sensitivity level. | | 33 | | dB |
| Selectivity, -100 kHz | | | 31 | | dB |
| Selectivity, +200 kHz | | | 38 | | dB |
| Selectivity, -200 kHz | | | 37 | | dB |
| RSSI dynamic range | Starting from the sensitivity limit | | 93 | | dB |
| RSSI accuracy | Starting from the sensitivity limit across the given dynamic range | | ± 3 | | dB |
| Wi-SUN, 50 kbps, ± 25 kHz deviation, 2-GFSK, 100 kHz RX BW, #1b | | | | | |
| Sensitivity | MRFSK, 918.2 MHz, 10% PER, 250 byte payload | | -106 | | dBm |
| Saturation limit | 10% PER, 250 byte payload, 918.2 MHz | | 10 | | dBm |
| Selectivity, +200 kHz | 10% PER, 250 byte payload, 918.2 MHz. Wanted signal 3 dB above sensitivity level. | | 37 | | dB |
| Selectivity, -200 kHz | | | 35 | | dB |
| Selectivity, +400 kHz | | | 42 | | dB |
| Selectivity, -400 kHz | | | 41 | | dB |
| RSSI dynamic range | Starting from the sensitivity limit | | 95 | | dB |
| RSSI accuracy | Starting from the sensitivity limit across the given dynamic range | | ± 3 | | dB |
| Wi-SUN, 100 kbps, ± 25 kHz deviation, 2-GFSK, 135 kHz RX BW, #2a | | | | | |
| Sensitivity | MRFSK, 866.6 MHz, 10% PER, 250 byte payload | | -103 | | dBm |
| Saturation limit | 10% PER, 250 byte payload, 866.6 MHz | | 10 | | dBm |
| Selectivity, +200 kHz | 10% PER, 250 byte payload, 866.6 MHz. Wanted signal 3 dB above sensitivity level. | | 40 | | dB |
| Selectivity, -200 kHz | | | 38 | | dB |
| Selectivity, +400 kHz | | | 46 | | dB |
| Selectivity, -400 kHz | | | 44 | | dB |
| RSSI dynamic range | Starting from the sensitivity limit | | 95 | | dB |
| RSSI accuracy | Starting from the sensitivity limit across the given dynamic range | | ± 3 | | dB |
| Wi-SUN, 100 kbps, ± 50 kHz deviation, 2-GFSK, 208 kHz RX BW, #2b | | | | | |
| Sensitivity | MRFSK, 920.9 MHz, 10% PER, 250 byte payload | | -102 | | dBm |
| Saturation limit | 10% PER, 250 byte payload, 920.9 MHz | | 10 | | dBm |
| Selectivity, +400 kHz | 10% PER, 250 byte payload, 920.9 MHz. Wanted signal 3 dB above sensitivity level, modulated blocker. | | 42 | | dB |
| Selectivity, -400 kHz | | | 39 | | dB |
| Selectivity, +800 kHz | | | 52 | | dB |
| Selectivity, -800 kHz | | | 46 | | dB |
| RSSI dynamic range | Starting from the sensitivity limit | | 91 | | dB |
| RSSI accuracy | Starting from the sensitivity limit across the given dynamic range | | ± 3 | | dB |
| Wi-SUN, 150 kbps, ± 37.5 kHz deviation, 2-GFSK, 273 kHz RX BW, #3 | | | | | |
| Sensitivity | MRFSK, 918.4 MHz, 10% PER, 250 byte payload | | -99 | | dBm |
| Saturation limit | 10% PER, 250 byte payload, 918.4 MHz | | 10 | | dBm |

8.10 861 MHz to 1054 MHz - Receive (RX) (continued)

When Measured on the LP-EM-CC1314R10 reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$ with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---|--|-----|------|-----|------|
| Selectivity, +400 kHz | 10% PER, 250 byte payload, 918.4 MHz. Wanted signal 3 dB above sensitivity level. | | 41 | | dB |
| Selectivity, -400 kHz | | | 39 | | dB |
| Selectivity, +800 kHz | | | 50 | | dB |
| Selectivity, -800 kHz | | | 46 | | dB |
| RSSI dynamic range | Starting from the sensitivity limit | | 86 | | dB |
| RSSI accuracy | Starting from the sensitivity limit across the given dynamic range | | ±3 | | dB |
| Wi-SUN, 200 kbps, ±50 kHz deviation, 2-GFSK, 335 kHz RX BW, #4a | | | | | |
| Sensitivity | MRFSK, 918.4 MHz, 10% PER, 250 byte payload | | -99 | | dBm |
| Saturation limit | 10% PER, 250 byte payload, 918.4 MHz | | 10 | | dBm |
| Selectivity, +400 kHz | 10% PER, 250 byte payload, 918.4 MHz. Wanted signal 3 dB above sensitivity level. | | 42 | | dB |
| Selectivity, -400 kHz | | | 40 | | dB |
| Selectivity, +800 kHz | | | 51 | | dB |
| Selectivity, -800 kHz | | | 47 | | dB |
| RSSI dynamic range | Starting from the sensitivity limit | | 91 | | dB |
| RSSI accuracy | Starting from the sensitivity limit across the given dynamic range | | ±3 | | dB |
| Wi-SUN, 200 kbps, ±100 kHz deviation, 2-GFSK, 416 kHz RX BW, #4b | | | | | |
| Sensitivity | MRFSK, 920.8 MHz, 10% PER, 250 byte payload | | -98 | | dBm |
| Saturation limit | 10% PER, 250 byte payload, 920.8 MHz | | 10 | | dBm |
| Selectivity, +600 kHz | 10% PER, 250 byte payload, 920.8 MHz. Wanted signal 3 dB above sensitivity level, modulated blocker. | | 46 | | dB |
| Selectivity, -600 kHz | | | 43 | | dB |
| Selectivity, +1200 kHz | | | 54 | | dB |
| Selectivity, -1200 kHz | | | 51 | | dB |
| RSSI dynamic range | Starting from the sensitivity limit | | 86 | | dB |
| RSSI accuracy | Starting from the sensitivity limit across the given dynamic range | | ±3 | | dB |
| Wi-SUN, 300 kbps, ±75 kHz deviation, 2-GFSK, 496 kHz RX BW, #5 | | | | | |
| Sensitivity | MRFSK, 917.6 MHz, 10% PER, 250 byte payload | | -97 | | dBm |
| Saturation limit | 10% PER, 250 byte payload, 917.6 MHz | | 10 | | dBm |
| Selectivity, +600 kHz | 10% PER, 250 byte payload, 917.6 MHz. Wanted signal 3 dB above sensitivity level. | | 42 | | dB |
| Selectivity, -600 kHz | | | 37 | | dB |
| Selectivity, +1200 kHz | | | 51 | | dB |
| Selectivity, -1200 kHz | | | 40 | | dB |
| RSSI dynamic range | Starting from the sensitivity limit | | 86 | | dB |
| RSSI accuracy | Starting from the sensitivity limit across the given dynamic range | | ±3 | | dB |
| 802.15.4-2020, 10 kbps, 2-FSK, 26 kHz RX BW, Mode #1a | | | | | |
| Sensitivity | FSK, 915.0 MHz, 20 byte PSDU < 10% PER | | -113 | | dBm |
| Sensitivity | FSK, 868.3 MHz, 20 byte PSDU < 10% PER | | -113 | | dBm |
| Saturation limit | PSDU length 20 octets; PER < 10%, 868.3 MHz | | 10 | | dBm |

8.10 861 MHz to 1054 MHz - Receive (RX) (continued)

When Measured on the LP-EM-CC1314R10 reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$ with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--|--|-----|-------|-----|------|
| Selectivity, +50 kHz | PSDU length 20 octets; PER < 10%, 868.3 MHz | | 36 | | dB |
| Selectivity, -50 kHz | | | 36 | | dB |
| Selectivity, +100 kHz | | | 40 | | dB |
| Selectivity, -100 kHz | | | 39 | | dB |
| Selectivity, +200 kHz | | | 44 | | dB |
| Selectivity, -200 kHz | | | 37 | | dB |
| Blocking, +1 MHz | | | 60 | | dB |
| Blocking, -1 MHz | | | 59 | | dB |
| Blocking, +2 MHz | | | 64 | | dB |
| Blocking, -2 MHz | | | 64 | | dB |
| Blocking, +5 MHz | | | 75 | | dB |
| Blocking, -5 MHz | | | 74 | | dB |
| Blocking, +10 MHz | | | 79 | | dB |
| Blocking, -10 MHz | | | 79 | | dB |
| Selectivity, +50 kHz | PSDU length 20 octets; PER < 10%, 868.3 MHz. Wanted signal 3 dB above sensitivity level. | | 35 | | dB |
| Selectivity, -50 kHz | | | 35 | | dB |
| Selectivity, +100 kHz | | | 39 | | dB |
| Selectivity, -100 kHz | | | 38 | | dB |
| Selectivity, +200 kHz | | | 44 | | dB |
| Selectivity, -200 kHz | | | 44 | | dB |
| Blocking, +1 MHz | | | 58 | | dB |
| Blocking, -1 MHz | | | 58 | | dB |
| Blocking, +2 MHz | | | 62 | | dB |
| Blocking, -2 MHz | | | 63 | | dB |
| Blocking, +5 MHz | | | 74 | | dB |
| Blocking, -5 MHz | | | 74 | | dB |
| Blocking, +10 MHz | | | 73 | | dB |
| Blocking, -10 MHz | | | 78 | | dB |
| Blocking + 5% Fc. (45.75 MHz) | 10% PER, 20 byte payload, 866.6 MHz 802.15.4g mandatory mode, wanted signal -94 dBm. 3 dB above usable sensitivity limit according to ETSI EN 300 220 V3.1.1 (usable sensitivity -97 dBm). Limit is Cat 1.5 requirement. | | -15 | | dBm |
| Blocking - 5% Fc. (-45.75 MHz) | | | -15 | | dBm |
| Image rejection (image compensation enabled) | 10% PER, 20 byte payload, measured at 10 dB above sensitivity level. Negative offset | | 39 | | dB |
| Image rejection (image compensation enabled) | PSDU length 20 octets; PER < 10%, 868.3 MHz | | 39 | | dB |
| Image rejection (image compensation enabled) | -40 to 125°C, 10% PER, 250 byte payload, 866.6 MHz | | 39 | | dB |
| RSSI dynamic range | Starting from the sensitivity limit | | 100 | | dB |
| RSSI accuracy | Starting from the sensitivity limit across the given dynamic range | | ±3 | | dB |
| Frequency error tolerance (ppm) | 10% PER, 20 byte payload, measured at 10 dB above sensitivity level. Negative offset | | -12 | | ppm |
| Frequency error tolerance (ppm) | 10% PER, 20 byte payload, measured at 10 dB above sensitivity level. Positive offset | | 12 | | ppm |
| Symbol rate error tolerance (ppm) | 10% PER, 20 byte payload, measured at 10 dB above sensitivity level. Negative offset | | -1000 | | ppm |
| Symbol rate error tolerance (ppm) | 1% BER, measured at 10 dB above sensitivity level. Positive offset | | 1000 | | ppm |
| 802.15.4-2020, 20 kbps, 2-FSK, 52 kHz RX BW, Mode #1b | | | | | |

8.10 861 MHz to 1054 MHz - Receive (RX) (continued)

When Measured on the LP-EM-CC1314R10 reference design with $T_c = 25^\circ\text{C}$, $V_{\text{DDS}} = 3.0\text{ V}$ with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT | |
|--|---|--|---------|-----|------|-----|
| Sensitivity | FSK, 20 kbps, ± 10 kHz deviation, 2-GFSK, 915.0 MHz, 52 kHz RX BW, 20 byte PSDU < 10% PER | | -110 | | dBm | |
| Sensitivity | FSK, 20 kbps, ± 10 kHz deviation, 2-GFSK, 868.3 MHz, 52 kHz RX BW, 20 byte PSDU < 10% PER | | -110 | | dBm | |
| Saturation limit | 20 byte PSDU < 10% PER, 868.3 MHz | | 10 | | dBm | |
| Selectivity, +100 kHz | 20 byte PSDU < 10% PER, 868.3 MHz | | 38 | | dB | |
| Selectivity, -100 kHz | | | 36 | | dB | |
| Selectivity, +200 kHz | | | 44 | | dB | |
| Selectivity, -200 kHz | | | 42 | | dB | |
| Selectivity, +400 kHz | | | 49 | | dB | |
| Selectivity, -400 kHz | | | 44 | | dB | |
| Blocking, +1 MHz | | | 58 | | dB | |
| Blocking, -1 MHz | | | 54 | | dB | |
| Blocking, -2 MHz | | | 61 | | dB | |
| Blocking, +2 MHz | | | 61 | | dB | |
| Blocking, -5 MHz | | | 70 | | dB | |
| Blocking, +5 MHz | | | 70 | | dB | |
| Blocking, -10 MHz | | | 75 | | dB | |
| Blocking, +10 MHz | | | 76 | | dB | |
| Selectivity, +100 kHz | | 20 byte PSDU < 10% PER, 868.3 MHz. Wanted signal 3 dB above sensitivity level. | | 36 | | dB |
| Selectivity, -100 kHz | | | | 34 | | dB |
| Selectivity, +200 kHz | | | | 42 | | dB |
| Selectivity, -200 kHz | | | | 41 | | dB |
| Selectivity, +400 kHz | | | | 47 | | dB |
| Selectivity, -400 kHz | | | 46 | | dB | |
| Blocking, +1 MHz | | | 56 | | dB | |
| Blocking, -1 MHz | | | 55 | | dB | |
| Blocking, +2 MHz | | | 61 | | dB | |
| Blocking, -2 MHz | | | 61 | | dB | |
| Blocking, +5 MHz | | | 71 | | dB | |
| Blocking, -5 MHz | | | 70 | | dB | |
| Blocking, +10 MHz | | | 75 | | dB | |
| Blocking, -10 MHz | | | 75 | | dB | |
| Blocking + 5% Fc. (45.75 MHz) | 20 byte PSDU < 10% PER, 866.6 MHz, wanted signal -94 dBm. 3 dB above usable sensitivity limit according to ETSI EN 300 220 V3.1.1 (usable sensitivity -97 dBm). Limit is Cat 1.5 requirement. | | | -13 | | dBm |
| Blocking - 5% Fc. (-45.75 MHz) | | | | -13 | | dBm |
| Image rejection (image compensation enabled) | 20 byte PSDU < 10% PER, 866.6 MHz. Wanted signal 3 dB above sensitivity limit. | | | 39 | | dB |
| Image rejection (image compensation enabled) | 20 byte PSDU < 10% PER, 866.6 MHz ⁽¹⁾ | | | 39 | | dB |
| Image rejection (image compensation enabled) | -40 to 125°C, 10% PER, 250 byte payload, 866.6 MHz | | | 39 | | dB |
| RSSI dynamic range | Starting from the sensitivity limit | | 100 | | dB | |
| RSSI accuracy | Starting from the sensitivity limit across the given dynamic range | | ± 3 | | dB | |
| Frequency error tolerance (ppm) | 20 byte PSDU < 10% PER, measured at 10 dB above sensitivity level. Negative offset | | -24 | | ppm | |
| Frequency error tolerance (ppm) | 20 byte PSDU < 10% PER, measured at 10 dB above sensitivity level. Positive offset | | 24 | | ppm | |

8.10 861 MHz to 1054 MHz - Receive (RX) (continued)

When Measured on the LP-EM-CC1314R10 reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$ with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--|--|-----|--------|-----|------|
| Symbol rate error tolerance (ppm) | 20 byte PSDU < 10% PER, measured at 10 dB above sensitivity level. Negative offset | | -1000 | | ppm |
| Symbol rate error tolerance (ppm) | 20 byte PSDU < 10% PER, measured at 10 dB above sensitivity level. Negative offset | | 1000 | | ppm |
| 802.15.4, 200 kbps, ±50 kHz deviation, 2-GFSK, 311 kHz RX BW | | | | | |
| Sensitivity | BER = 10^{-2} , 868 MHz | | -103 | | dBm |
| Sensitivity | BER = 10^{-2} , 915 MHz | | -103 | | dBm |
| Selectivity, +400 kHz | BER = 10^{-2} , 915 MHz. Wanted signal 3 dB above sensitivity limit. | | 45 | | dB |
| Selectivity, -400 kHz | BER = 10^{-2} , 915 MHz. Wanted signal 3 dB above sensitivity limit. | | 45 | | dB |
| Selectivity, +800 kHz | BER = 10^{-2} , 915 MHz. Wanted signal 3 dB above sensitivity limit. | | 52 | | dB |
| Selectivity, -800 kHz | BER = 10^{-2} , 915 MHz. Wanted signal 3 dB above sensitivity limit. | | 47 | | dB |
| Blocking, +2 MHz | BER = 10^{-2} , 915 MHz. Wanted signal 3 dB above sensitivity limit. | | 59 | | dB |
| Blocking, -2 MHz | BER = 10^{-2} , 915 MHz. Wanted signal 3 dB above sensitivity limit. | | 56 | | dB |
| Blocking, +10 MHz | BER = 10^{-2} , 915 MHz. Wanted signal 3 dB above sensitivity limit. | | 71 | | dB |
| Blocking, -10 MHz | BER = 10^{-2} , 915 MHz. Wanted signal 3 dB above sensitivity limit. | | 70 | | dB |
| 802.15.4, 500 kbps, ±190 kHz deviation, 2-GFSK, 622 kHz RX BW | | | | | |
| Sensitivity 500 kbps | 915 MHz, 1% PER, 127 byte payload | | -95 | | dBm |
| Selectivity, ±1 MHz | 915 MHz, 1% PER, 127 byte payload. Wanted signal at -88 dBm | | 34 | | dB |
| Selectivity, ±2 MHz | 915 MHz, 1% PER, 127 byte payload. Wanted signal at -88 dBm | | 46 | | dB |
| Co-channel rejection | 915 MHz, 1% PER, 127 byte payload. Wanted signal at -71 dBm | | -8 | | dB |
| SimpleLink™ Long Range 2.5/5 kbps (20 ksps), ±5 kHz Deviation, 2-GFSK, 34 kHz RX Bandwidth, FEC = 1:2, DSSS = 1:4/1:2 | | | | | |
| Sensitivity | 2.5 kbps, BER = 10^{-2} , 868 MHz | | -121 | | dBm |
| Sensitivity | 2.5 kbps, BER = 10^{-2} , 915 MHz | | -121 | | dBm |
| Sensitivity | 5 kbps, BER = 10^{-2} , 868 MHz | | -119 | | dBm |
| Sensitivity | 5 kbps, BER = 10^{-2} , 915 MHz | | -119 | | dBm |
| Saturation limit | 2.5 kbps, BER = 10^{-2} , 868 MHz | | 10 | | dBm |
| Selectivity, +100 kHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 49 | | dB |
| Selectivity, -100 kHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 49 | | dB |
| Selectivity, +200 kHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 52 | | dB |
| Selectivity, -200 kHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 48 | | dB |
| Selectivity, +300 kHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 54 | | dB |
| Selectivity, -300 kHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 48 | | dB |
| Blocking, +1 MHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 65 | | dB |
| Blocking, -1 MHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 60 | | dB |
| Blocking, +2 MHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 70 | | dB |
| Blocking, -2 MHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 68 | | dB |
| Blocking, +5 MHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 78 | | dB |
| Blocking, -5 MHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 77 | | dB |
| Blocking, +10 MHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 87 | | dB |
| Blocking, -10 MHz | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 92 | | dB |
| Image rejection (image compensation enabled) | 2.5 kbps, BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 47 | | dB |
| RSSI accuracy | Starting from the sensitivity limit across the given dynamic range | | ±3 | | dB |
| Frequency error tolerance (ppm) | 2.5 kbps, 20 kbaud, DSSS=4, ½ K=7 FEC. measured at -110 dBm. | | -24/26 | | ppm |
| Symbolrate error tolerance (ppm) | 2.5 kbps, 20 kbaud, DSSS=4, ½ K=7 FEC. measured at -110 dBm. Referred to 20 kbaud chip rate. | | -90/70 | | ppm |

8.10 861 MHz to 1054 MHz - Receive (RX) (continued)

When Measured on the LP-EM-CC1314R10 reference design with $T_c = 25^\circ\text{C}$, $V_{\text{DD5}} = 3.0\text{ V}$ with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT | |
|---|--|--|------|-----|------|----|
| Narrowband, 9.6 kbps ± 2.4 kHz deviation, 2-GFSK, 868 MHz, 17.1 kHz RX BW | | | | | | |
| Sensitivity | 1% BER | | -117 | | dBm | |
| Adjacent Channel Rejection | 1% BER. Wanted signal 3 dB above usable sensitivity limit (usable sensitivity -104.6 dBm). Interferer ± 20 kHz | | 42 | | dB | |
| Alternate Channel Rejection | 1% BER. Wanted signal 3 dB above usable sensitivity limit (usable sensitivity -104.6 dBm). Interferer ± 40 kHz | | 42 | | dB | |
| Blocking, ± 1 MHz | 1% BER. Wanted signal 3 dB above usable sensitivity limit (usable sensitivity -104.6 dBm). | | 66 | | dB | |
| Blocking, ± 2 MHz | 1% BER. Wanted signal 3 dB above usable sensitivity limit (usable sensitivity -104.6 dBm). | | 71 | | dB | |
| Blocking, ± 10 MHz | 1% BER. Wanted signal 3 dB above usable sensitivity limit (usable sensitivity -104.6 dBm). | | 85 | | dB | |
| 802.15.4, 50 kbps, ± 25 kHz Deviation, 2-GFSK, 100 kHz RX BW (Legacy) | | | | | | |
| Sensitivity | BER = 10^{-2} , 868 MHz | | -110 | | dBm | |
| Sensitivity | BER = 10^{-2} , 915 MHz | | -110 | | dBm | |
| Saturation limit | BER = 10^{-2} , 868 MHz | | 10 | | dBm | |
| Selectivity, +200 kHz | BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 44 | | dB | |
| Selectivity, -200 kHz | | | 44 | | dB | |
| Selectivity, +400 kHz | | | 54 | | dB | |
| Selectivity, -400 kHz | | | 44 | | dB | |
| Blocking, +1 MHz | | | 57 | | dB | |
| Blocking, -1 MHz | | | 57 | | dB | |
| Blocking, +2 MHz | | | 61 | | dB | |
| Blocking, -2 MHz | | | 61 | | dB | |
| Blocking, +5 MHz | | | 67 | | dB | |
| Blocking, -5 MHz | | | 67 | | dB | |
| Blocking, +10 MHz | | | 76 | | dB | |
| Blocking, -10 MHz | | | 76 | | dB | |
| Selectivity, +200 kHz | | BER = 10^{-2} , 868 MHz. Wanted signal 3 dB above sensitivity limit. | | 45 | | dB |
| Selectivity, -200 kHz | | | | 45 | | dB |
| Selectivity, +400 kHz | | | | 51 | | dB |
| Selectivity, -400 kHz | | | | 45 | | dB |
| Blocking, +1 MHz | | | | 61 | | dB |
| Blocking, -1 MHz | | | | 61 | | dB |
| Blocking, +2 MHz | | | 63 | | dB | |
| Blocking, -2 MHz | | | 63 | | dB | |
| Blocking, +5 MHz | | | 67 | | dB | |
| Blocking, -5 MHz | | | 67 | | dB | |
| Blocking, +10 MHz | | | 73 | | dB | |
| Blocking, -10 MHz | | | 73 | | dB | |
| Blocking + 5% Fc. (43.42 MHz) | BER = 10^{-2} , 868 MHz | | -15 | | dBm | |
| Blocking - 5% Fc. (-43.42 MHz) | 802.15.4g mandatory mode, wanted signal -94 dBm. 3 dB above usable sensitivity limit according to ETSI EN 300 220 V3.1.1 (usable sensitivity -97 dBm). Limit is Cat 1.5 requirement. | | -15 | | dBm | |
| Image rejection (image compensation enabled) | BER = 10^{-2} , 868 MHz. Wanted signal 3 dB above sensitivity limit. | | 39 | | dB | |
| Image rejection (image compensation enabled) | BER = 10^{-2} , 868 MHz ⁽¹⁾ | | 39 | | dB | |
| Image rejection (image compensation enabled) | -40 to 125°C. BER = 10^{-2} , 868 MHz | | 41 | | dB | |

8.10 861 MHz to 1054 MHz - Receive (RX) (continued)

When Measured on the LP-EM-CC1314R10 reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$ with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT | |
|--|---|--|-------|-----|------|-----|
| RSSI dynamic range | Starting from the sensitivity limit | | 95 | | dB | |
| RSSI accuracy | Starting from the sensitivity limit across the given dynamic range | | ±3 | | dB | |
| Frequency error tolerance (ppm) | 1% BER, measured at -100 dBm (10 dB above sensitivity level). Negative offset | | -30 | | ppm | |
| Frequency error tolerance (ppm) | 1% BER, measured at -100 dBm (10 dB above sensitivity level). Positive offset | | 25 | | ppm | |
| Symbol rate error tolerance (ppm) | 1% BER, measured at -100 dBm (10 dB above sensitivity level). Negative offset | | -2000 | | ppm | |
| Symbol rate error tolerance (ppm) | 1% BER, measured at -100 dBm (10 dB above sensitivity level) Positive offset | | 2000 | | ppm | |
| 802.15.4, 100 kbps, ±25 kHz deviation, 2-GFSK, 137 kHz RX BW | | | | | | |
| Sensitivity 100 kbps | 868 MHz, 1% PER, 127 byte payload | | -103 | | dBm | |
| Selectivity, ±200 kHz | 868 MHz, 1% PER, 127 byte payload. Wanted signal at -96 dBm | | 38 | | dB | |
| Selectivity, ±400 kHz | | | 44 | | dB | |
| Co-channel rejection | 868 MHz, 1% PER, 127 byte payload. Wanted signal at -79 dBm | | -9 | | dB | |
| Generic OOK (16.384 kbps, OOK w / Manchester encoding, 100 kHz RX BW) | | | | | | |
| Sensitivity | OOK, 915.0 MHz, 1% BER | | -114 | | dBm | |
| Sensitivity | OOK, 868.8 MHz, 1% BER | | -113 | | dBm | |
| Saturation limit | 868.3 MHz | | 0 | | dBm | |
| Selectivity, +200 kHz | 868.3 MHz ⁽¹⁾ | | 52 | | dB | |
| Selectivity, -200 kHz | | | 48 | | dB | |
| Selectivity, +400 kHz | | | 68 | | dB | |
| Selectivity, -400 kHz | | | 64 | | dB | |
| Blocking, +1 MHz | | | 64 | | dB | |
| Blocking, -1 MHz | | | 59 | | dB | |
| Blocking, +2 MHz | | | 64 | | dB | |
| Blocking, -2 MHz | | | 59 | | dB | |
| Blocking, +5 MHz | | | 72 | | dB | |
| Blocking, -5 MHz | | | 73 | | dB | |
| Blocking, +10 MHz | | | 64 | | dB | |
| Blocking, -10 MHz | | | 58 | | dB | |
| Selectivity, +200 kHz | | 868.3 MHz. Wanted signal 3 dB above sensitivity level. | | 52 | | dB |
| Selectivity, -200 kHz | | | | 47 | | dB |
| Selectivity, +400 kHz | | | | 42 | | dB |
| Selectivity, -400 kHz | | | | 42 | | dB |
| Blocking, +1 MHz | | | 68 | | dB | |
| Blocking, -1 MHz | | | 64 | | dB | |
| Blocking, +2 MHz | | | 68 | | dB | |
| Blocking, -2 MHz | | | 64 | | dB | |
| Blocking, +5 MHz | | | 74 | | dB | |
| Blocking, -5 MHz | | | 73 | | dB | |
| Blocking, +10 MHz | | | 68 | | dB | |
| Blocking, -10 MHz | | | 64 | | dB | |
| RSSI dynamic range | Starting from the sensitivity limit | | | 95 | | dB |
| RSSI accuracy | Starting from the sensitivity limit across the given dynamic range | | | ±3 | | dB |
| Frequency error tolerance (ppm) | Measured at 10 dB above sensitivity level. Negative offset | | | -40 | | ppm |
| Frequency error tolerance (ppm) | Measured at 10 dB above sensitivity level. Positive offset | | | 40 | | ppm |

8.10 861 MHz to 1054 MHz - Receive (RX) (continued)

When Measured on the LP-EM-CC1314R10 reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$ with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-----------------------------------|---|-----|-------|-----|------|
| Symbol rate error tolerance (ppm) | Measured at 10 dB above sensitivity level. Negative offset | | -2000 | | ppm |
| Symbol rate error tolerance (ppm) | Measured at 10 dB above sensitivity level Positive offset | | 2000 | | ppm |

(1) Wanted signal 3 dB above usable sensitivity limit according to ETSI EN 300 220 v. 3.1.1.

8.11 861 MHz to 1054 MHz - Transmit (TX)

When measured on the LP-EM-CC1314R10 reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{\text{DDS}} = 3.0\text{ V}$ with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted. ⁽¹⁾

| PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--|---|--|-----|-------|-----|------|
| General parameters | | | | | | |
| Max output power, boost mode | | VDDR = 1.95 V Minimum supply voltage (VDDS) for boost mode is 2.1 V 868 MHz and 915 MHz | | 14 | | dBm |
| Max output power | | 868 MHz and 915 MHz | | 12 | | dBm |
| Output power programmable range | | 868 MHz and 915 MHz, 1dB step size. | | 34 | | dB |
| Output power variation over temperature | | +10 dBm setting Over recommended temperature operating range | | ±2 | | dB |
| Output power variation over temperature Boost mode | | +14 dBm setting Over recommended temperature operating range | | ±1.5 | | dB |
| Spurious emissions and harmonics | | | | | | |
| Spurious emissions (excluding harmonics) ⁽³⁾ | 30 MHz to 1 GHz | +14 dBm setting ETSI restricted bands | | < -54 | | dBm |
| | | +14 dBm setting ETSI outside restricted bands | | < -36 | | dBm |
| | 1 GHz to 12.75 GHz (outside ETSI restricted bands) | +14 dBm setting measured in 1 MHz bandwidth (ETSI) | | < -30 | | dBm |
| Spurious emissions out-of-band, 915 MHz ⁽³⁾ | 30 MHz to 88 MHz (within FCC restricted bands) | +14 dBm setting | | < -56 | | dBm |
| | 88 MHz to 216 MHz (within FCC restricted bands) | +14 dBm setting | | < -52 | | dBm |
| | 216 MHz to 960 MHz (within FCC restricted bands) | +14 dBm setting | | < -50 | | dBm |
| | 960 MHz to 2390 MHz and above 2483.5 MHz (within FCC restricted band) | +14 dBm setting | | < -42 | | dBm |
| | 1 GHz to 12.75 GHz (outside FCC restricted bands) | +14 dBm setting | | < -40 | | dBm |
| Spurious emissions out-of-band, 920.6/928 MHz ⁽³⁾ | Below 710 MHz (ARIB T-108) | +14 dBm setting | | < -36 | | dBm |
| | 710 MHz to 900 MHz (ARIB T-108) | +14 dBm setting | | < -55 | | dBm |
| | 900 MHz to 915 MHz (ARIB T-108) | +14 dBm setting | | < -55 | | dBm |
| | 930 MHz to 1000 MHz (ARIB T-108) | +14 dBm setting | | < -55 | | dBm |
| | 1000 MHz to 1215 MHz (ARIB T-108) | +14 dBm setting | | < -45 | | dBm |
| | Above 1215 MHz (ARIB T-108) | +14 dBm setting | | < -30 | | dBm |
| Harmonics | Second harmonic | +14 dBm setting, 868 MHz | | < -30 | | dBm |
| | | +14 dBm setting, 915 MHz | | < -30 | | |
| | Third harmonic | +14 dBm setting, 868 MHz | | < -30 | | dBm |
| | | +14 dBm setting, 915 MHz | | < -42 | | |
| | Fourth harmonic | +14 dBm setting, 868 MHz | | < -30 | | dBm |
| | | +14 dBm setting, 915 MHz | | < -30 | | |
| | Fifth harmonic | +14 dBm setting, 868 MHz | | < -30 | | dBm |
| | | +14 dBm setting, 915 MHz | | < -42 | | |

(1) Some combinations of frequency, data rate and modulation format requires use of external crystal load capacitors for regulatory compliance. More details can be found in the device errata.

(2) Suitable for systems targeting compliance with EN 300 220, EN 303 131, EN 303 204, FCC CFR47 Part 15, ARIB STD-T108.

8.12 861 MHz to 1054 MHz - PLL Phase Noise Wideband Mode

 When measured on the LP-EM-CC1314R10 reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--|-------------------|-----|------|-----|--------|
| Phase noise in the 868- and 915-MHz bands 20 kHz PLL loop bandwidth | ±10 kHz offset | | -74 | | dBc/Hz |
| | ±100 kHz offset | | -97 | | dBc/Hz |
| | ±200 kHz offset | | -107 | | dBc/Hz |
| | ±400 kHz offset | | -113 | | dBc/Hz |
| | ±1000 kHz offset | | -120 | | dBc/Hz |
| | ±2000 kHz offset | | -127 | | dBc/Hz |
| | ±10000 kHz offset | | -141 | | dBc/Hz |

8.13 861 MHz to 1054 MHz - PLL Phase Noise Narrowband Mode

 When measured on the LP-EM-CC1314R10 reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---|-------------------|-----|------|-----|--------|
| Phase noise in the 868- and 915-MHz bands 150 kHz PLL loop bandwidth | ±10 kHz offset | | -96 | | dBc/Hz |
| | ±100 kHz offset | | -95 | | dBc/Hz |
| | ±200 kHz offset | | -94 | | dBc/Hz |
| | ±400 kHz offset | | -104 | | dBc/Hz |
| | ±1000 kHz offset | | -121 | | dBc/Hz |
| | ±2000 kHz offset | | -130 | | dBc/Hz |
| | ±10000 kHz offset | | -140 | | dBc/Hz |

8.14 Timing and Switching Characteristics

8.14.1 Reset Timing

| PARAMETER | MIN | TYP | MAX | UNIT |
|----------------------|-----|-----|-----|------|
| RESET_N low duration | 1 | | | μs |

8.14.2 Wakeup Timing

 Measured over operating free-air temperature with $V_{DD5} = 3.0\text{ V}$ (unless otherwise noted). The times listed here do not include software overhead.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--|-----------------|-----|------------|-----|------|
| MCU, Reset to Active ⁽¹⁾ | | | 850 - 4000 | | μs |
| MCU, Shutdown to Active ⁽¹⁾ | | | 850 - 4000 | | μs |
| MCU, Standby to Active | | | 160 | | μs |
| MCU, Active to Standby | | | 39 | | μs |
| MCU, Idle to Active | | | 15 | | μs |

(1) The wakeup time is dependent on remaining charge on VDDR capacitor when starting the device, and thus how long the device has been in Reset or Shutdown before starting up again. The wake up time increases with a higher capacitor value.

8.14.3 Clock Specifications

8.14.3.1 48 MHz Clock Input (TCXO)

Measured on a Texas Instruments reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$, unless otherwise noted.⁽¹⁾

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--|---|---|-----|-----|------|------|
| | Clock frequency | | | 48 | | MHz |
| | TCXO clipped sine output, peak-to-peak | TCXO clipped sine output connected to pin X48M_P through series capacitor | 0.8 | | 1.7 | V |
| | TCXO with CMOS output, High input voltage | TCXO with CMOS output | 1.3 | | VDDR | V |
| | TCXO with CMOS output, Low input voltage | directly coupled to pin X48M_P | 0 | | 0.3 | V |

(1) Probing or otherwise stopping the TCXO while the DC/DC converter is enabled may cause permanent damage to the device.

8.14.3.2 48 MHz Crystal Oscillator (XOSC_HF)

Measured on a Texas Instruments reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$, unless otherwise noted.⁽¹⁾

| | PARAMETER | MIN | TYP | MAX | UNIT |
|-------|---|-----|-------------------------------|-----|---------------|
| | Crystal frequency | | 48 | | MHz |
| ESR | Equivalent series resistance $6\text{ pF} < C_L \leq 9\text{ pF}$ | | 20 | 60 | Ω |
| ESR | Equivalent series resistance $5\text{ pF} < C_L \leq 6\text{ pF}$ | | | 80 | Ω |
| L_M | Motional inductance, relates to the load capacitance that is used for the crystal (C_L in Farads) ⁽⁵⁾ | | $< 3 \times 10^{-25} / C_L^2$ | | H |
| C_L | Crystal load capacitance ⁽⁴⁾ | 5 | 7 ⁽³⁾ | 9 | pF |
| | Start-up time ⁽²⁾ | | 200 | | μs |

- (1) Probing or otherwise stopping the crystal while the DC/DC converter is enabled may cause permanent damage to the device.
- (2) Start-up time using the TI-provided power driver. Start-up time may increase if driver is not used.
- (3) On-chip default connected capacitance including reference design parasitic capacitance. Connected internal capacitance is changed through software in the Customer Configuration section (CCFG).
- (4) Adjustable load capacitance is integrated into the device. External load capacitors are required for systems targeting compliance with certain regulations. See the device errata for further details.
- (5) The crystal manufacturer's specification must satisfy this requirement for proper operation.

8.14.3.3 48 MHz RC Oscillator (RCOSC_HF)

Measured on a Texas Instruments reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$, unless otherwise noted.

| | MIN | TYP | MAX | UNIT |
|--|-----|------------|-----|---------------|
| Frequency | | 48 | | MHz |
| Uncalibrated frequency accuracy | | ± 1 | | % |
| Calibrated frequency accuracy ⁽¹⁾ | | ± 0.25 | | % |
| Start-up time | | 5 | | μs |

(1) Accuracy relative to the calibration source (XOSC_HF)

8.14.3.4 2 MHz RC Oscillator (RCOSC_MF)

Measured on a Texas Instruments reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$, unless otherwise noted.

| | MIN | TYP | MAX | UNIT |
|----------------------|-----|-----|-----|---------------|
| Calibrated frequency | | 2 | | MHz |
| Start-up time | | 5 | | μs |

8.14.3.5 32.768 kHz Crystal Oscillator (XOSC_LF)

Measured on a Texas Instruments reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$, unless otherwise noted.

| | MIN | TYP | MAX | UNIT |
|-------------------|-----|--------|-----|------|
| Crystal frequency | | 32.768 | | kHz |

8.14.3.5 32.768 kHz Crystal Oscillator (XOSC_LF) (continued)

Measured on a Texas Instruments reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$, unless otherwise noted.

| | | MIN | TYP | MAX | UNIT |
|-------|------------------------------|-----|------------------|-----|------------|
| ESR | Equivalent series resistance | | 30 | 100 | k Ω |
| C_L | Crystal load capacitance | 6 | 7 ⁽¹⁾ | 12 | pF |

- (1) Default load capacitance using TI reference designs including parasitic capacitance. Crystals with different load capacitance may be used.

8.14.3.6 32 kHz RC Oscillator (RCOSC_LF)

Measured on a Texas Instruments reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$, unless otherwise noted.

| | | MIN | TYP | MAX | UNIT |
|--|-------------------------|-----|---------------------|-----|-----------------------|
| | Calibrated frequency | | 32.8 ⁽¹⁾ | | kHz |
| | Temperature coefficient | | 50 | | ppm/ $^\circ\text{C}$ |

- (1) When using RCOSC_LF as source for the low frequency system clock (SCLK_LF), the accuracy of the SCLK_LF-derived Real Time Clock (RTC) can be improved by measuring RCOSC_LF relative to XOSC_HF and compensating for the RTC tick speed. This functionality is available through the TI-provided Power driver.

8.14.4 Serial Peripheral Interface (SPI) Characteristics

8.14.4.1 SPI Characteristics

over operating free-air temperature range (unless otherwise noted)

| PARAMETERS | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|----------------------------|---------------------|--------------------------------------|-----|-----|-----|------|
| f_{SCLK} $1/t_{sclk}$ | SPI clock frequency | Master Mode $1.8 < V_{DD5} < 3.8$ | | | 12 | MHz |
| | | Slave Mode $2.7 < V_{DD5} < 3.8$ | | | 8 | |
| | | Slave Mode $V_{DD5} < 2.7$ | | | 7 | |
| DC_{SCK} | SCK Duty Cycle | | 45 | 50 | 55 | % |

8.14.4.2 SPI Master Mode

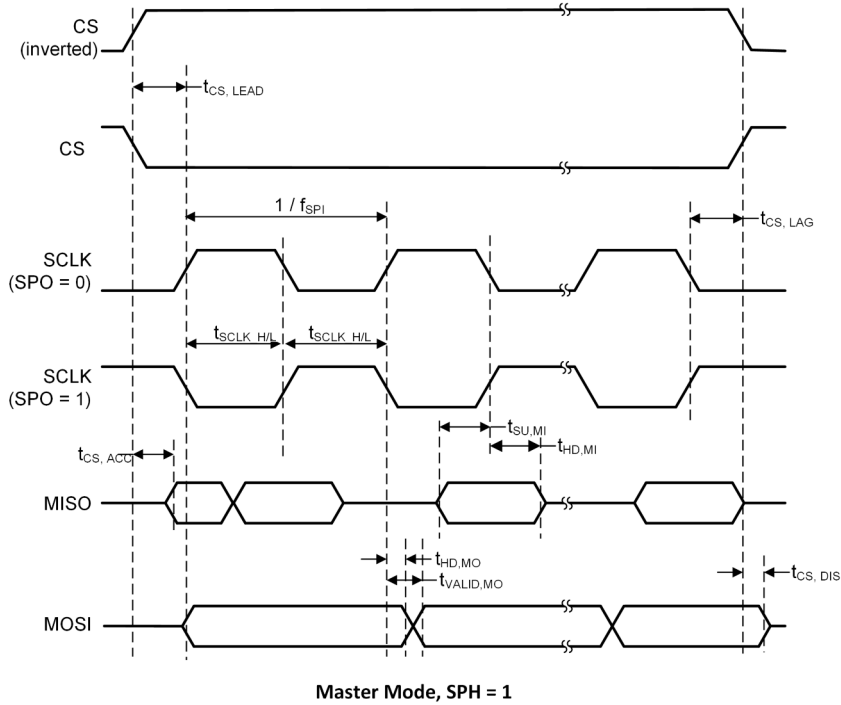
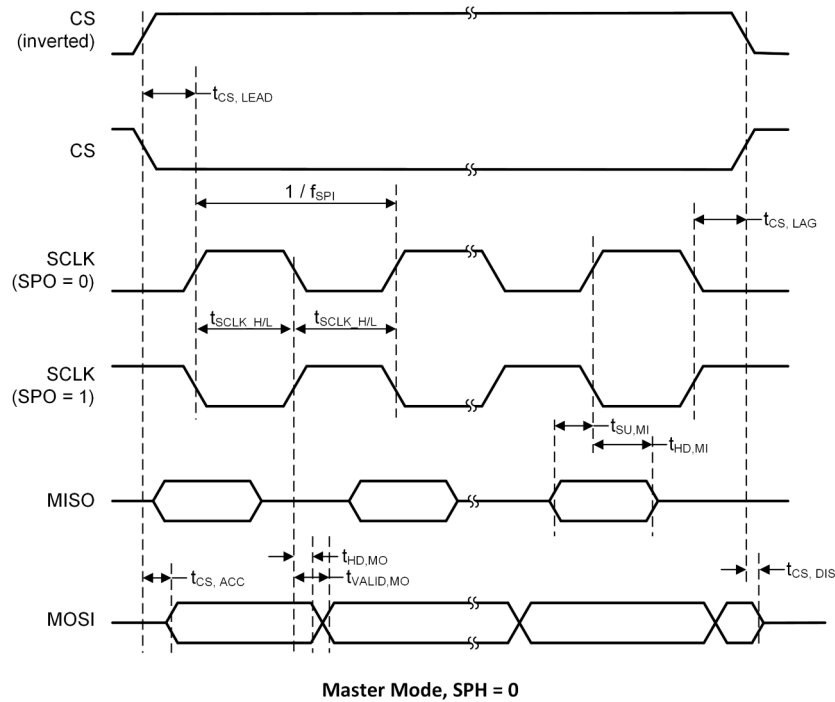
over operating free-air temperature range (unless otherwise noted)

| PARAMETERS | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-----------------|---|--|-------------------|---------------|-------------------|------|
| $t_{SCLK_H/L}$ | SCLK High or Low time | | $(t_{SPI}/2) - 1$ | $t_{SPI} / 2$ | $(t_{SPI}/2) + 1$ | ns |
| t_{CS_LEAD} | CS lead-time, CS active to clock | | 1 | | | SCLK |
| t_{CS_LAG} | CS lag time, Last clock to CS inactive | | 1 | | | SCLK |
| t_{CS_ACC} | CS access time, CS active to MOSI data out | | | | 1 | SCLK |
| t_{CS_DIS} | CS disable time, CS inactive to MOSI high impedance | | | | 1 | SCLK |
| t_{SU_MI} | MISO input data setup time ⁽¹⁾ | $V_{DD5} = 3.3\text{ V}$ | 12.5 | | | ns |
| t_{SU_MI} | MISO input data setup time | $V_{DD5} = 1.8\text{ V}$ | 23.5 | | | ns |
| t_{HD_MI} | MISO input data hold time | | 0 | | | ns |
| t_{VALID_MO} | MOSI output data valid time ⁽²⁾ | SCLK edge to MOSI valid, $CL = 20\text{ pF}$ (4) | | | 13 | ns |
| t_{HD_MO} | MOSI output data hold time ⁽³⁾ | $CL = 20\text{ pF}$ | 0 | | | ns |

- (1) The MISO input data setup time can be fully compensated when delayed sampling feature is enabled.
 (2) Specifies the time to drive the next valid data to the output after the output changing SCLK clock edge
 (3)

Specifies how long data on the output is valid after the output changing SCLK clock edge

8.14.4.3 SPI Master Mode Timing Diagrams



8-1. SPI Master Mode Timing

8.14.4.4 SPI Slave Mode

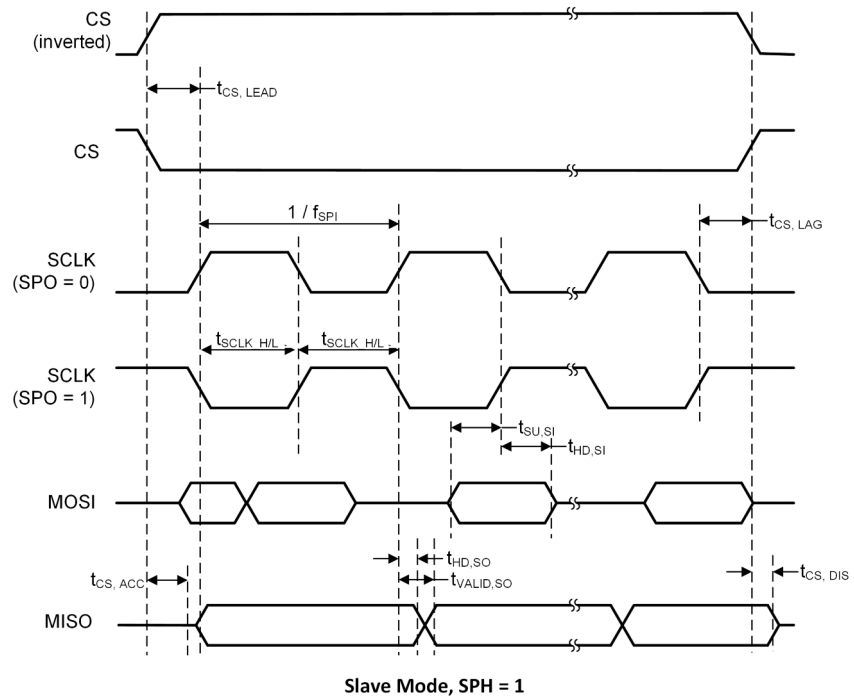
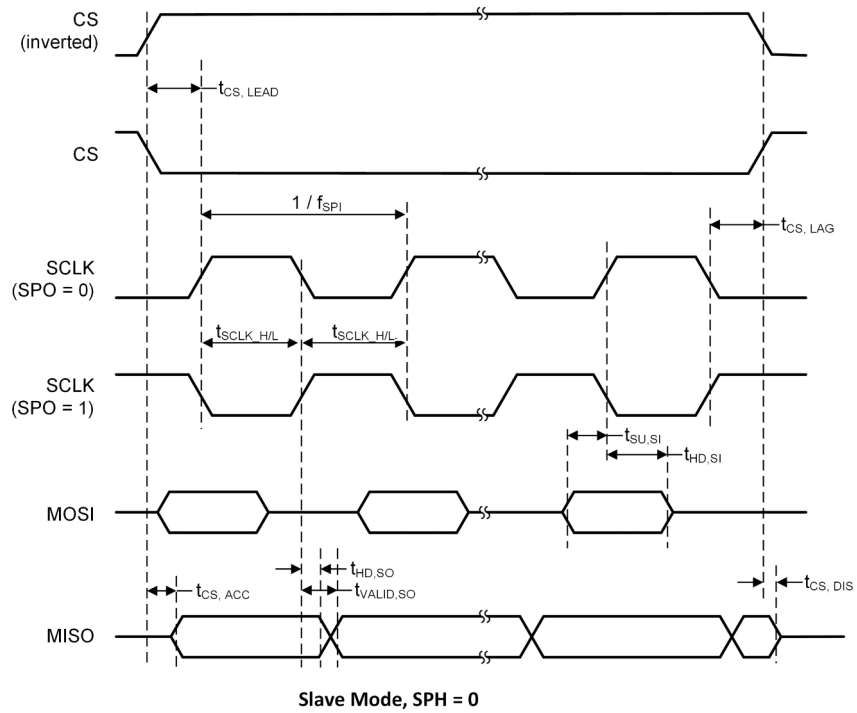
over operating free-air temperature range (unless otherwise noted)

| PARAMETERS | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|----------------|---|--|-----|-----|-----|------|
| $t_{CS.LEAD}$ | CS lead-time, CS active to clock | | 1 | | | SCLK |
| $t_{CS.LAG}$ | CS lag time, Last clock to CS inactive | | 1 | | | SCLK |
| $t_{CS.ACC}$ | CS access time, CS active to MISO data out | VDDS = 3.3V | | | 56 | ns |
| $t_{CS.ACC}$ | CS access time, CS active to MISO data out | VDDS = 1.8V | | | 70 | ns |
| $t_{CS.DIS}$ | CS disable time, CS inactive to MISO high impedance | VDDS = 3.3V | | | 56 | ns |
| $t_{CS.DIS}$ | CS disable time, CS inactive to MISO high impedance | VDDS = 1.8V | | | 70 | ns |
| $t_{SU.SI}$ | MOSI input data setup time | | 30 | | | ns |
| $t_{HD.SI}$ | MOSI input data hold time | | 0 | | | ns |
| $t_{VALID.SO}$ | MISO output data valid time ⁽¹⁾ | SCLK edge to MISO valid, $C_L = 20$ pF, 3.3V (4) | | | 50 | ns |
| $t_{VALID.SO}$ | MISO output data valid time ⁽¹⁾ | SCLK edge to MISO valid, $C_L = 20$ pF, 1.8V (4) | | | 65 | ns |
| $t_{HD.SO}$ | MISO output data hold time ⁽²⁾ | $C_L = 20$ pF | 0 | | | ns |

(1) Specifies the time to drive the next valid data to the output after the output changing SCLK clock edge

(2) Specifies how long data on the output is valid after the output changing SCLK clock edge

8.14.4.5 SPI Slave Mode Timing Diagrams



8-2. SPI Slave Mode Timing

ADVANCE INFORMATION

8.14.5 UART

8.14.5.1 UART Characteristics

over operating free-air temperature range (unless otherwise noted)

| PARAMETER | MIN | TYP | MAX | UNIT |
|-----------|-----|-----|-----|-------|
| UART rate | | | 3 | MBaud |

8.15 Peripheral Characteristics

8.15.1 ADC

8.15.1.1 Analog-to-Digital Converter (ADC) Characteristics

$T_c = 25\text{ }^\circ\text{C}$, $V_{\text{DDS}} = 3.0\text{ V}$ and voltage scaling enabled, unless otherwise noted.⁽¹⁾

Performance numbers require use of offset and gain adjustments in software by TI-provided ADC drivers.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---------------------|--|---|-------|-----------------------------------|--------------|
| Input voltage range | | 0 | | V _{DDS} | V |
| Resolution | | | 12 | | Bits |
| Sample Rate | | | | 200 | ksps |
| Offset | Internal 4.3 V equivalent reference ⁽²⁾ | | -0.24 | | LSB |
| Gain error | Internal 4.3 V equivalent reference ⁽²⁾ | | 7.14 | | LSB |
| DNL ⁽⁴⁾ | Differential nonlinearity | | >-1 | | LSB |
| INL | Integral nonlinearity | | ±4 | | LSB |
| ENOB | Effective number of bits | Internal 4.3 V equivalent reference ⁽²⁾ , 200 kSamples/s, 9.6 kHz input tone | | 9.8 | Bits |
| | | Internal 4.3 V equivalent reference ⁽²⁾ , 200 kSamples/s, 9.6 kHz input tone, DC/DC enabled | | 9.8 | |
| | | V _{DDS} as reference, 200 kSamples/s, 9.6 kHz input tone | | 10.1 | |
| | | Internal reference, voltage scaling disabled, 32 samples average, 200 kSamples/s, 300 Hz input tone | | 11.1 | |
| | | Internal reference, voltage scaling disabled, 14-bit mode, 200 kSamples/s, 300 Hz input tone ⁽⁵⁾ | | 11.3 | |
| | | Internal reference, voltage scaling disabled, 15-bit mode, 200 kSamples/s, 300 Hz input tone ⁽⁵⁾ | | 11.6 | |
| THD | Total harmonic distortion | Internal 4.3 V equivalent reference ⁽²⁾ , 200 kSamples/s, 9.6 kHz input tone | | -65 | dB |
| | | V _{DDS} as reference, 200 kSamples/s, 9.6 kHz input tone | | -70 | |
| | | Internal reference, voltage scaling disabled, 32 samples average, 200 kSamples/s, 300 Hz input tone | | -72 | |
| SINAD, SNDR | Signal-to-noise and distortion ratio | Internal 4.3 V equivalent reference ⁽²⁾ , 200 kSamples/s, 9.6 kHz input tone | | 60 | dB |
| | | V _{DDS} as reference, 200 kSamples/s, 9.6 kHz input tone | | 63 | |
| | | Internal reference, voltage scaling disabled, 32 samples average, 200 kSamples/s, 300 Hz input tone | | 68 | |
| SFDR | Spurious-free dynamic range | Internal 4.3 V equivalent reference ⁽²⁾ , 200 kSamples/s, 9.6 kHz input tone | | 70 | dB |
| | | V _{DDS} as reference, 200 kSamples/s, 9.6 kHz input tone | | 73 | |
| | | Internal reference, voltage scaling disabled, 32 samples average, 200 kSamples/s, 300 Hz input tone | | 75 | |
| | Conversion time | Serial conversion, time-to-output, 24 MHz clock | | 50 | Clock Cycles |
| | Current consumption | Internal 4.3 V equivalent reference ⁽²⁾ | | 0.42 | mA |
| | Current consumption | V _{DDS} as reference | | 0.6 | mA |
| | Reference voltage | Equivalent fixed internal reference (input voltage scaling enabled). For best accuracy, the ADC conversion should be initiated through the TI-RTOS API in order to include the gain/offset compensation factors stored in FCFG1 | | 4.3 ⁽²⁾ ⁽³⁾ | V |

8.15.1.1 Analog-to-Digital Converter (ADC) Characteristics (continued)

$T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$ and voltage scaling enabled, unless otherwise noted.⁽¹⁾

Performance numbers require use of offset and gain adjustments in software by TI-provided ADC drivers.

| PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-----------|-------------------|---|-----|----------------------------|-----|------|
| | Reference voltage | Fixed internal reference (input voltage scaling disabled). For best accuracy, the ADC conversion should be initiated through the TI-RTOS API in order to include the gain/offset compensation factors stored in FCFG1. This value is derived from the scaled value (4.3 V) as follows: $V_{ref} = 4.3\text{ V} \times 1408 / 4095$ | | 1.48 | | V |
| | Reference voltage | VDDS as reference, input voltage scaling enabled | | VDDS | | V |
| | Reference voltage | VDDS as reference, input voltage scaling disabled | | VDDS / 2.82 ⁽³⁾ | | V |
| | Input impedance | 200 kSamples/s, voltage scaling enabled. Capacitive input, Input impedance depends on sampling frequency and sampling time | | >1 | | MΩ |

- (1) Using IEEE Std 1241-2010 for terminology and test methods
- (2) Input signal scaled down internally before conversion, as if voltage range was 0 to 4.3 V
- (3) Applied voltage must be within [Absolute Maximum Ratings](#) at all times
- (4) No missing codes
- (5) $ADC_output = \Sigma(4^n \text{ samples}) \gg n$, $n = \text{desired extra bits}$

8.15.2 DAC

8.15.2.1 Digital-to-Analog Converter (DAC) Characteristics

$T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$, unless otherwise noted.

| PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--|---|---|-----|-------|------|--------------------|
| General Parameters | | | | | | |
| | Resolution | | | 8 | | Bits |
| V_{DD5} | Supply voltage | Any load, any V_{REF} , pre-charge OFF, DAC charge-pump ON | 1.8 | | 3.8 | V |
| | | External Load ⁽⁴⁾ , any V_{REF} , pre-charge OFF, DAC charge-pump OFF | 2.0 | | 3.8 | |
| | | Any load, $V_{REF} = \text{DCOUP}$, pre-charge ON | 2.6 | | 3.8 | |
| F_{DAC} | Clock frequency | Buffer ON (recommended for external load) | 16 | | 250 | kHz |
| | | Buffer OFF (internal load) | 16 | | 1000 | |
| | Voltage output settling time | $V_{REF} = V_{DD5}$, buffer OFF, internal load | | 13 | | 1 / F_{DAC} |
| | | $V_{REF} = V_{DD5}$, buffer ON, external capacitive load = 20 pF ⁽³⁾ | | 13.8 | | |
| | External capacitive load | | | 20 | 200 | pF |
| | External resistive load | | 10 | | | MΩ |
| | Short circuit current | | | | 400 | μA |
| Z_{MAX} | Max output impedance $V_{ref} = V_{DD5}$, buffer ON, CLK 250 kHz | $V_{DD5} = 3.8\text{ V}$, DAC charge-pump OFF | | 50.8 | | kΩ |
| | | $V_{DD5} = 3.0\text{ V}$, DAC charge-pump ON | | 51.7 | | |
| | | $V_{DD5} = 3.0\text{ V}$, DAC charge-pump OFF | | 53.2 | | |
| | | $V_{DD5} = 2.0\text{ V}$, DAC charge-pump ON | | 48.7 | | |
| | | $V_{DD5} = 2.0\text{ V}$, DAC charge-pump OFF | | 70.2 | | |
| | | $V_{DD5} = 1.8\text{ V}$, DAC charge-pump ON | | 46.3 | | |
| | | $V_{DD5} = 1.8\text{ V}$, DAC charge-pump OFF | | 88.9 | | |
| Internal Load - Continuous Time Comparator / Low Power Clocked Comparator | | | | | | |
| DNL | Differential nonlinearity | $V_{REF} = V_{DD5}$, load = Continuous Time Comparator or Low Power Clocked Comparator $F_{DAC} = 250\text{ kHz}$ | | ±1 | | LSB ⁽¹⁾ |
| | Differential nonlinearity | $V_{REF} = V_{DD5}$, load = Continuous Time Comparator or Low Power Clocked Comparator $F_{DAC} = 16\text{ kHz}$ | | ±1.2 | | |
| | Offset error ⁽²⁾ Load = Continuous Time Comparator | $V_{REF} = V_{DD5} = 3.8\text{ V}$ | | ±0.64 | | LSB ⁽¹⁾ |
| | | $V_{REF} = V_{DD5} = 3.0\text{ V}$ | | ±0.81 | | |
| | | $V_{REF} = V_{DD5} = 1.8\text{ V}$ | | ±1.27 | | |
| | | $V_{REF} = \text{DCOUP}$, pre-charge ON | | ±3.43 | | |
| | | $V_{REF} = \text{DCOUP}$, pre-charge OFF | | ±2.88 | | |
| | | $V_{REF} = \text{ADCRE}$ | | ±2.37 | | |
| | Offset error ⁽²⁾ Load = Low Power Clocked Comparator | $V_{REF} = V_{DD5} = 3.8\text{ V}$ | | ±0.78 | | LSB ⁽¹⁾ |
| | | $V_{REF} = V_{DD5} = 3.0\text{ V}$ | | ±0.77 | | |
| | | $V_{REF} = V_{DD5} = 1.8\text{ V}$ | | ±3.46 | | |
| | | $V_{REF} = \text{DCOUP}$, pre-charge ON | | ±3.44 | | |
| | | $V_{REF} = \text{DCOUP}$, pre-charge OFF | | ±4.70 | | |
| | | $V_{REF} = \text{ADCRE}$ | | ±4.11 | | |
| | Max code output voltage variation ⁽²⁾ Load = Continuous Time Comparator | $V_{REF} = V_{DD5} = 3.8\text{ V}$ | | ±1.53 | | LSB ⁽¹⁾ |
| | | $V_{REF} = V_{DD5} = 3.0\text{ V}$ | | ±1.71 | | |
| | | $V_{REF} = V_{DD5} = 1.8\text{ V}$ | | ±2.10 | | |
| | | $V_{REF} = \text{DCOUP}$, pre-charge ON | | ±6.00 | | |
| | | $V_{REF} = \text{DCOUP}$, pre-charge OFF | | ±3.85 | | |
| | | $V_{REF} = \text{ADCRE}$ | | ±5.84 | | |

8.15.2.1 Digital-to-Analog Converter (DAC) Characteristics (continued)

T_c = 25 °C, V_{DDS} = 3.0 V, unless otherwise noted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---|---|--|-------|-------|--------------------|
| Max code output voltage variation ⁽²⁾ Load = Low Power Clocked Comparator | V _{REF} = V _{DDS} = 3.8 V | | ±2.92 | | LSB ⁽¹⁾ |
| | V _{REF} = V _{DDS} = 3.0 V | | ±3.06 | | |
| | V _{REF} = V _{DDS} = 1.8 V | | ±3.91 | | |
| | V _{REF} = DCOUPL, pre-charge ON | | ±7.84 | | |
| | V _{REF} = DCOUPL, pre-charge OFF | | ±4.06 | | |
| | V _{REF} = ADCREF | | ±6.94 | | |
| Output voltage range ⁽²⁾ Load = Continuous Time Comparator | V _{REF} = V _{DDS} = 3.8 V, code 1 | | 0.03 | | V |
| | V _{REF} = V _{DDS} = 3.8 V, code 255 | | 3.62 | | |
| | V _{REF} = V _{DDS} = 3.0 V, code 1 | | 0.02 | | |
| | V _{REF} = V _{DDS} = 3.0 V, code 255 | | 2.86 | | |
| | V _{REF} = V _{DDS} = 1.8 V, code 1 | | 0.01 | | |
| | V _{REF} = V _{DDS} = 1.8 V, code 255 | | 1.71 | | |
| | V _{REF} = DCOUPL, pre-charge OFF, code 1 | | 0.01 | | |
| | V _{REF} = DCOUPL, pre-charge OFF, code 255 | | 1.21 | | |
| | V _{REF} = DCOUPL, pre-charge ON, code 1 | | 1.27 | | |
| | V _{REF} = DCOUPL, pre-charge ON, code 255 | | 2.46 | | |
| | V _{REF} = ADCREF, code 1 | | 0.01 | | |
| | V _{REF} = ADCREF, code 255 | | 1.41 | | |
| Output voltage range ⁽²⁾ Load = Low Power Clocked Comparator | V _{REF} = V _{DDS} = 3.8 V, code 1 | | 0.03 | | V |
| | V _{REF} = V _{DDS} = 3.8 V, code 255 | | 3.61 | | |
| | V _{REF} = V _{DDS} = 3.0 V, code 1 | | 0.02 | | |
| | V _{REF} = V _{DDS} = 3.0 V, code 255 | | 2.85 | | |
| | V _{REF} = V _{DDS} = 1.8 V, code 1 | | 0.01 | | |
| | V _{REF} = V _{DDS} = 1.8 V, code 255 | | 1.71 | | |
| | V _{REF} = DCOUPL, pre-charge OFF, code 1 | | 0.01 | | |
| | V _{REF} = DCOUPL, pre-charge OFF, code 255 | | 1.21 | | |
| | V _{REF} = DCOUPL, pre-charge ON, code 1 | | 1.27 | | |
| | V _{REF} = DCOUPL, pre-charge ON, code 255 | | 2.46 | | |
| | V _{REF} = ADCREF, code 1 | | 0.01 | | |
| | V _{REF} = ADCREF, code 255 | | 1.41 | | |
| External Load (Keysight 34401A Multimeter) | | | | | |
| INL | Integral nonlinearity | V _{REF} = V _{DDS} , F _{DAC} = 250 kHz | | ±1 | LSB ⁽¹⁾ |
| | | V _{REF} = DCOUPL, F _{DAC} = 250 kHz | | ±1 | |
| | | V _{REF} = ADCREF, F _{DAC} = 250 kHz | | ±1 | |
| DNL | Differential nonlinearity | V _{REF} = V _{DDS} , F _{DAC} = 250 kHz | | ±1 | LSB ⁽¹⁾ |
| Offset error | | V _{REF} = V _{DDS} = 3.8 V | | ±0.20 | LSB ⁽¹⁾ |
| | | V _{REF} = V _{DDS} = 3.0 V | | ±0.25 | |
| | | V _{REF} = V _{DDS} = 1.8 V | | ±0.45 | |
| | | V _{REF} = DCOUPL, pre-charge ON | | ±1.55 | |
| | | V _{REF} = DCOUPL, pre-charge OFF | | ±1.30 | |
| | | V _{REF} = ADCREF | | ±1.10 | |
| Max code output voltage variation | | V _{REF} = V _{DDS} = 3.8 V | | ±0.60 | LSB ⁽¹⁾ |
| | | V _{REF} = V _{DDS} = 3.0 V | | ±0.55 | |
| | | V _{REF} = V _{DDS} = 1.8 V | | ±0.60 | |
| | | V _{REF} = DCOUPL, pre-charge ON | | ±3.45 | |
| | | V _{REF} = DCOUPL, pre-charge OFF | | ±2.10 | |
| | | V _{REF} = ADCREF | | ±1.90 | |

8.15.2.1 Digital-to-Analog Converter (DAC) Characteristics (continued)

$T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$, unless otherwise noted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--|---|-----|------|-----|------|
| Output voltage range Load = Low Power Clocked Comparator | $V_{REF} = V_{DD5} = 3.8\text{ V}$, code 1 | | 0.03 | | V |
| | $V_{REF} = V_{DD5} = 3.8\text{ V}$, code 255 | | 3.61 | | |
| | $V_{REF} = V_{DD5} = 3.0\text{ V}$, code 1 | | 0.02 | | |
| | $V_{REF} = V_{DD5} = 3.0\text{ V}$, code 255 | | 2.85 | | |
| | $V_{REF} = V_{DD5} = 1.8\text{ V}$, code 1 | | 0.02 | | |
| | $V_{REF} = V_{DD5} = 1.8\text{ V}$, code 255 | | 1.71 | | |
| | $V_{REF} = \text{DCOUPPL}$, pre-charge OFF, code 1 | | 0.02 | | |
| | $V_{REF} = \text{DCOUPPL}$, pre-charge OFF, code 255 | | 1.20 | | |
| | $V_{REF} = \text{DCOUPPL}$, pre-charge ON, code 1 | | 1.27 | | |
| | $V_{REF} = \text{DCOUPPL}$, pre-charge ON, code 255 | | 2.46 | | |
| | $V_{REF} = \text{ADCREFL}$, code 1 | | 0.02 | | |
| | $V_{REF} = \text{ADCREFL}$, code 255 | | 1.42 | | |

- (1) 1 LSB ($V_{REF} = 3.8\text{ V}/3.0\text{ V}/1.8\text{ V}/\text{DCOUPPL}/\text{ADCREFL}$) = 14.10 mV/11.13 mV/6.68 mV/4.67 mV/5.48 mV
- (2) Includes comparator offset
- (3) A load > 20 pF will increase the settling time
- (4) Keysight 34401A Multimeter

8.15.3 Temperature and Battery Monitor

8.15.3.1 Temperature Sensor

Measured on a Texas Instruments reference design with $T_c = 25\text{ }^\circ\text{C}$, $V_{\text{DDS}} = 3.0\text{ V}$, unless otherwise noted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---|--|-----|-----------|-----|--------------------|
| Resolution | | | 2 | | $^\circ\text{C}$ |
| Accuracy | -40 $^\circ\text{C}$ to 0 $^\circ\text{C}$ | | ± 4.0 | | $^\circ\text{C}$ |
| Accuracy | 0 $^\circ\text{C}$ to 105 $^\circ\text{C}$ | | ± 2.5 | | $^\circ\text{C}$ |
| Supply voltage coefficient ⁽¹⁾ | | | 3.6 | | $^\circ\text{C/V}$ |

(1) The temperature sensor is automatically compensated for V_{DDS} variation when using the TI-provided driver.

8.15.3.2 Battery Monitor

Measured on a Texas Instruments reference design with $T_c = 25\text{ }^\circ\text{C}$, unless otherwise noted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-----------------------------|---------------------------------|-----|------|-----|------|
| Resolution | | | 25 | | mV |
| Range | | 1.8 | | 3.8 | V |
| Integral nonlinearity (max) | | | 23 | | mV |
| Accuracy | $V_{\text{DDS}} = 3.0\text{ V}$ | | 22.5 | | mV |
| Offset error | | | -32 | | mV |
| Gain error | | | -1 | | % |

8.15.4 Comparators

8.15.4.1 Low-Power Clocked Comparator

$T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$, unless otherwise noted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---|--|-----|---------------|-----------|-------------|
| Input voltage range | | 0 | | V_{DD5} | V |
| Clock frequency | | | SCLK_LF | | |
| Internal reference voltage ⁽¹⁾ | Using internal DAC with V_{DD5} as reference voltage, DAC code = 0 - 255 | | 0.024 - 2.865 | | V |
| Offset | Measured at $V_{DD5} / 2$, includes error from internal DAC | | ± 5 | | mV |
| Decision time | Step from -50 mV to 50 mV | | 1 | | Clock Cycle |

- (1) The comparator can use an internal 8 bits DAC as its reference. The DAC output voltage range depends on the reference voltage selected. See [DAC Characteristics](#)

8.15.4.2 Continuous Time Comparator

$T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$, unless otherwise noted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|------------------------------------|---|-----|---------|-----------|---------------|
| Input voltage range ⁽¹⁾ | | 0 | | V_{DD5} | V |
| Offset | Measured at $V_{DD5} / 2$ | | ± 5 | | mV |
| Decision time | Step from -10 mV to 10 mV | | 0.78 | | μs |
| Current consumption | Internal reference | | 8.6 | | μA |

- (1) The input voltages can be generated externally and connected throughout I/Os or an internal reference voltage can be generated using the DAC

8.15.5 Current Source

8.15.5.1 Programmable Current Source

$T_c = 25\text{ }^\circ\text{C}$, $V_{DD5} = 3.0\text{ V}$, unless otherwise noted.

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--|-----------------|-----|-----------|-----|---------------|
| Current source programmable output range (logarithmic range) | | | 0.25 - 20 | | μA |
| Resolution | | | 0.25 | | μA |

8.15.6 GPIO

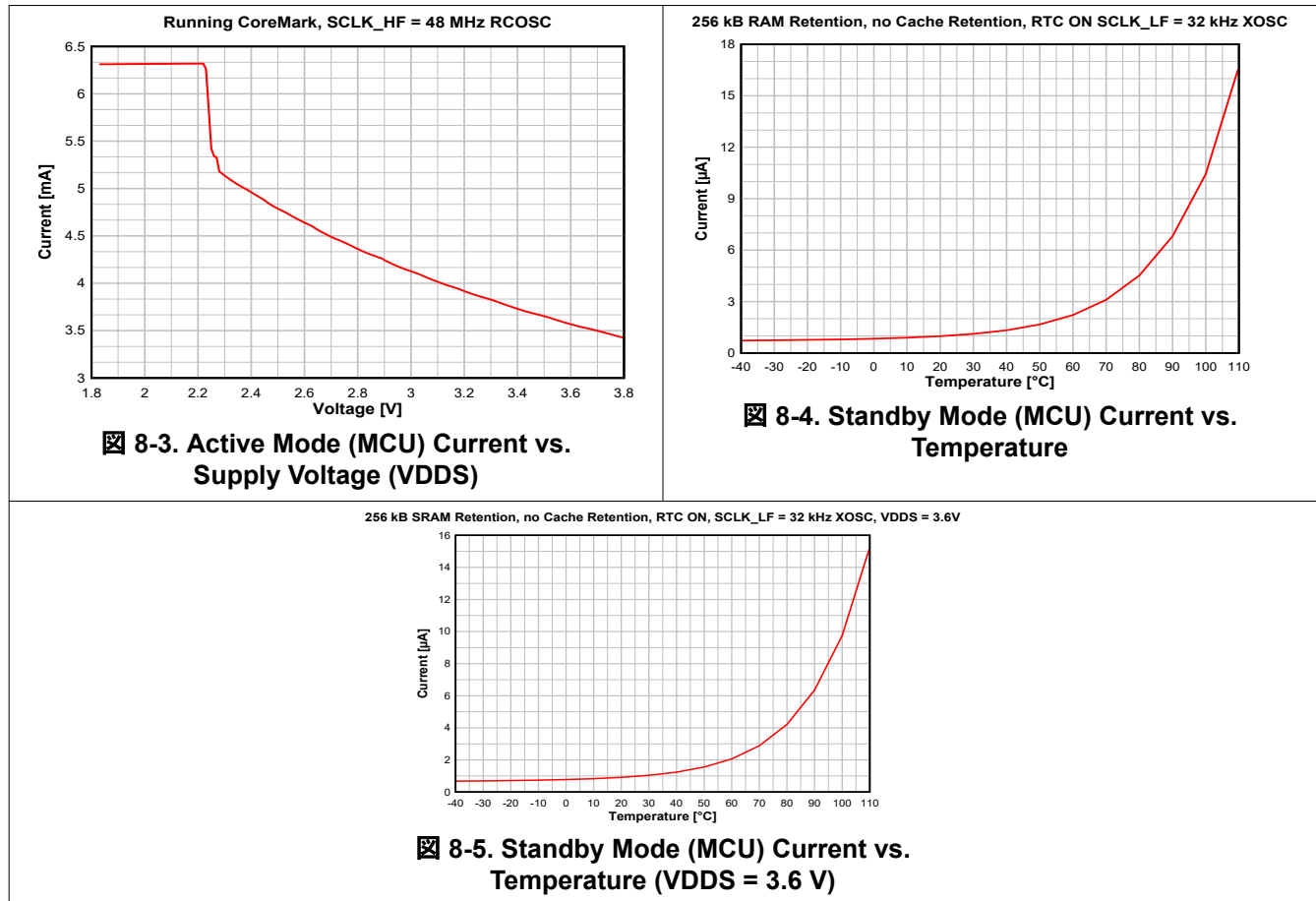
8.15.6.1 GPIO DC Characteristics

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---|---|----------------------|----------------------|-----|------|
| T_A = 25 °C, V_{DDs} = 1.8 V | | | | | |
| GPIO VOH at 8 mA load | IOCURR = 2, high-drive GPIOs only | | 1.56 | | V |
| GPIO VOL at 8 mA load | IOCURR = 2, high-drive GPIOs only | | 0.24 | | V |
| GPIO VOH at 4 mA load | IOCURR = 1 | | 1.59 | | V |
| GPIO VOL at 4 mA load | IOCURR = 1 | | 0.21 | | V |
| GPIO pullup current | Input mode, pullup enabled, Vpad = 0 V | | 73 | | μA |
| GPIO pulldown current | Input mode, pulldown enabled, Vpad = VDDs | | 19 | | μA |
| GPIO low-to-high input transition, with hysteresis | IH = 1, transition voltage for input read as 0 → 1 | | 1.08 | | V |
| GPIO high-to-low input transition, with hysteresis | IH = 1, transition voltage for input read as 1 → 0 | | 0.73 | | V |
| GPIO input hysteresis | IH = 1, difference between 0 → 1 and 1 → 0 points | | 0.35 | | V |
| T_A = 25 °C, V_{DDs} = 3.0 V | | | | | |
| GPIO VOH at 8 mA load | IOCURR = 2, high-drive GPIOs only | | 2.59 | | V |
| GPIO VOL at 8 mA load | IOCURR = 2, high-drive GPIOs only | | 0.42 | | V |
| GPIO VOH at 4 mA load | IOCURR = 1 | | 2.63 | | V |
| GPIO VOL at 4 mA load | IOCURR = 1 | | 0.40 | | V |
| T_A = 25 °C, V_{DDs} = 3.8 V | | | | | |
| GPIO pullup current | Input mode, pullup enabled, Vpad = 0 V | | 282 | | μA |
| GPIO pulldown current | Input mode, pulldown enabled, Vpad = VDDs | | 110 | | μA |
| GPIO low-to-high input transition, with hysteresis | IH = 1, transition voltage for input read as 0 → 1 | | 1.97 | | V |
| GPIO high-to-low input transition, with hysteresis | IH = 1, transition voltage for input read as 1 → 0 | | 1.55 | | V |
| GPIO input hysteresis | IH = 1, difference between 0 → 1 and 1 → 0 points | | 0.42 | | V |
| T_A = 25 °C | | | | | |
| VIH | Lowest GPIO input voltage reliably interpreted as a <i>High</i> | 0.8*V _{DDs} | | | V |
| VIL | Highest GPIO input voltage reliably interpreted as a <i>Low</i> | | 0.2*V _{DDs} | | V |

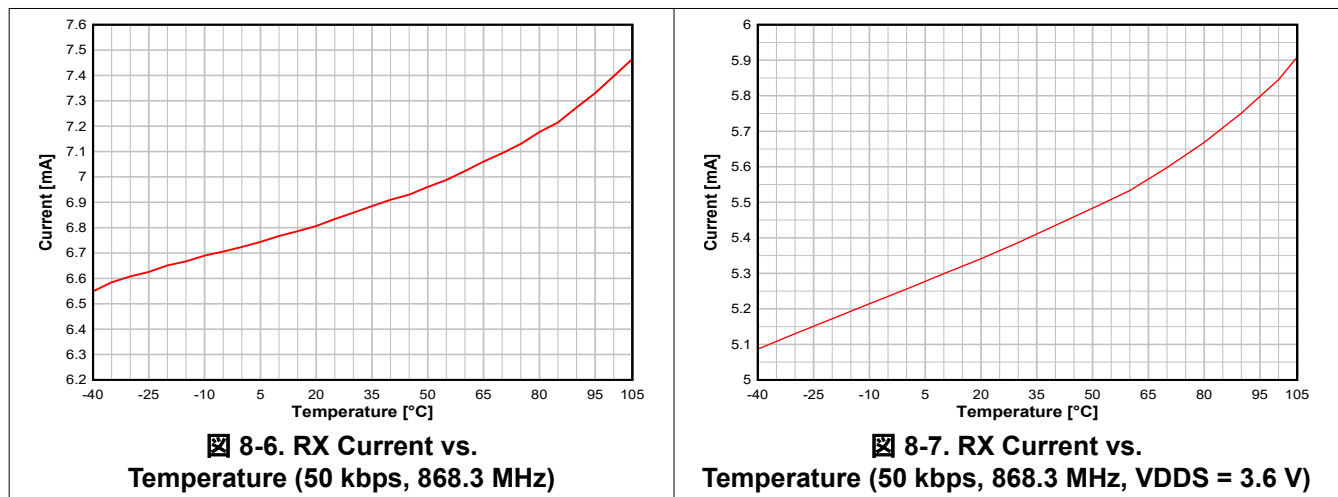
8.16 Typical Characteristics

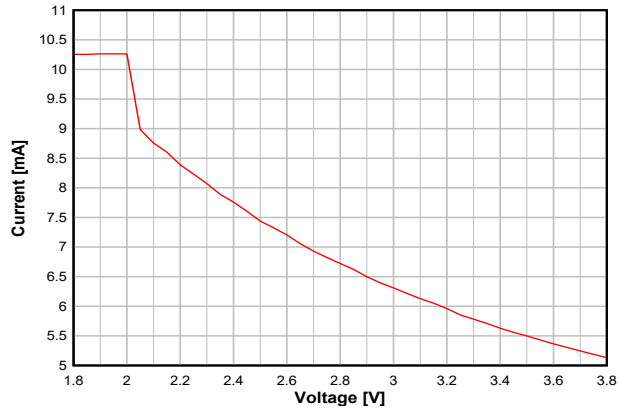
All measurements in this section are done with $T_c = 25\text{ }^\circ\text{C}$ and $V_{DD5} = 3.0\text{ V}$, unless otherwise noted. See *Recommended Operating Conditions*, [セクション 8.3](#), for device limits. Values exceeding these limits are for reference only.

8.16.1 MCU Current



8.16.2 RX Current

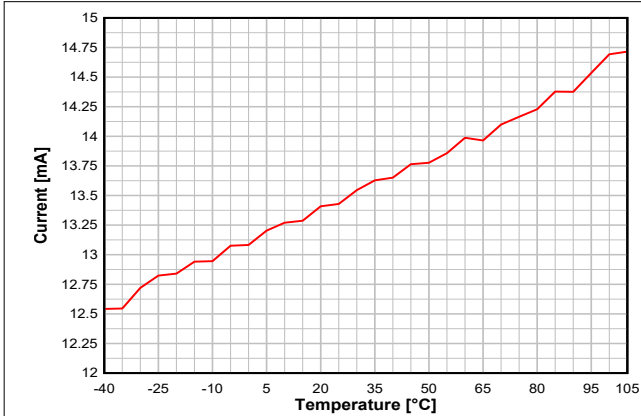




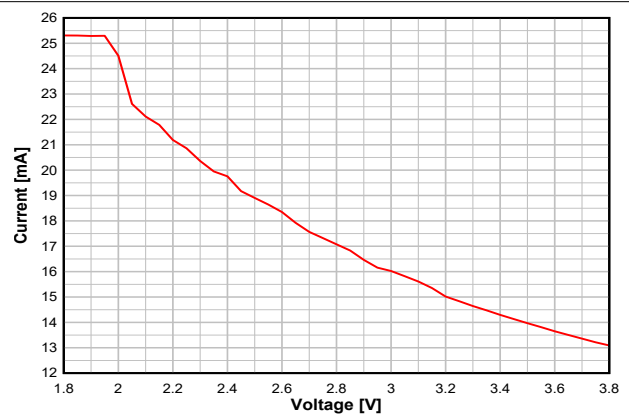
8-8. RX Current vs. Supply Voltage (VDDS) (50 kbps, 868.3 MHz)

8.16.3 TX Current

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☒ 8-9. TX Current vs. Temperature (50 kbps, 868.3 MHz, VDD5 = 3.6 V)



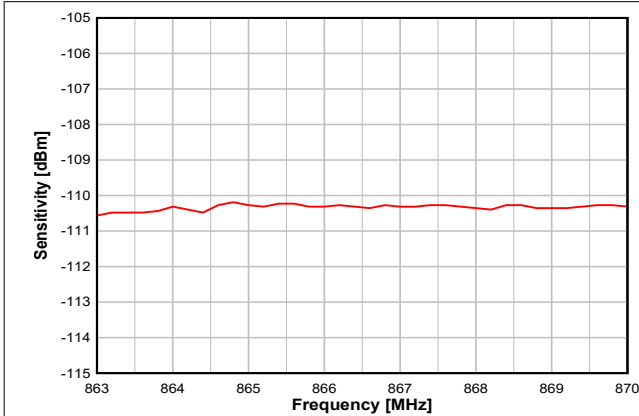
☒ 8-10. TX Current vs. Supply Voltage (VDD5) (50 kbps, 868.3 MHz)

表 8-1 shows typical TX current and output power for different output power settings.

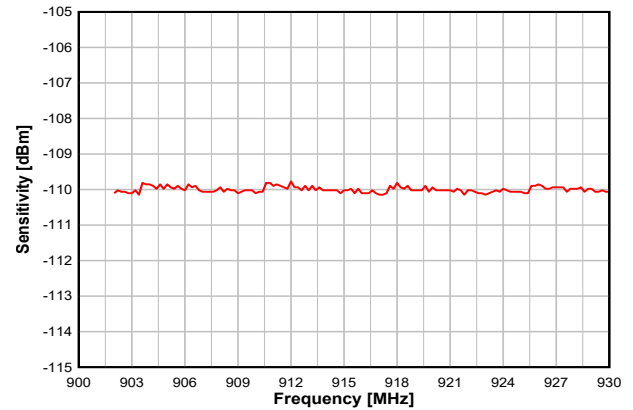
表 8-1. Typical TX Current and Output Power

| CC1314R10 at 868 MHz, VDDS = 3.6 V (Measured on CC1312-R7EM-XD7793) | | | |
|---|-----------------------------------|----------------------------|----------------------------------|
| txPower | TX Power Setting (SmartRF Studio) | Typical Output Power [dBm] | Typical Current Consumption [mA] |
| 0x013F | 14 | 14.6 | 25 |
| 0xB224 | 12.5 | 13.0 | 18.3 |
| 0x895E | 12 | 12.6 | 17.4 |
| 0x669A | 11 | 11.6 | 15.8 |
| 0x3E92 | 10 | 10.7 | 14.2 |
| 0x3EDC | 9 | 9.7 | 13.3 |
| 0x2CD8 | 8 | 9.1 | 12.4 |
| 0x26D4 | 7 | 8.2 | 11.5 |
| 0x20D1 | 6 | 7.2 | 10.6 |
| 0x1CCE | 5 | 5.9 | 9.8 |
| 0x16CD | 4 | 5.4 | 9.4 |
| 0x14CB | 3 | 4.1 | 8.8 |
| 0x12CA | 2 | 3.3 | 8.4 |
| 0x12C9 | 1 | 2.5 | 8.0 |
| 0x10C8 | 0 | 1.5 | 7.7 |
| 0x0AC4 | -5 | -4.6 | 6.1 |
| 0x0AC2 | -10 | -10.3 | 5.4 |
| 0x06C1 | -15 | -14.8 | 5.0 |
| 0x04C0 | -20 | -19.8 | 4.7 |

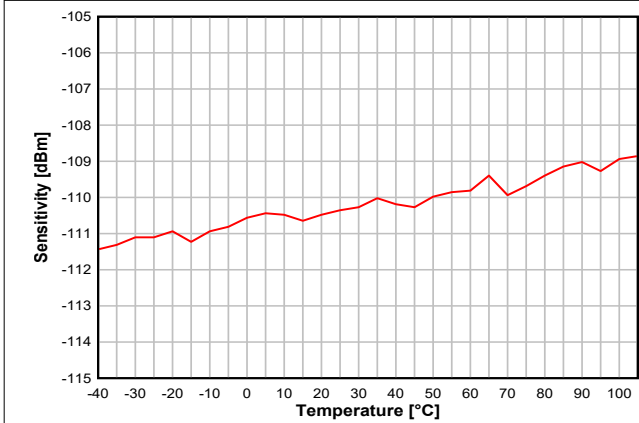
8.16.4 RX Performance



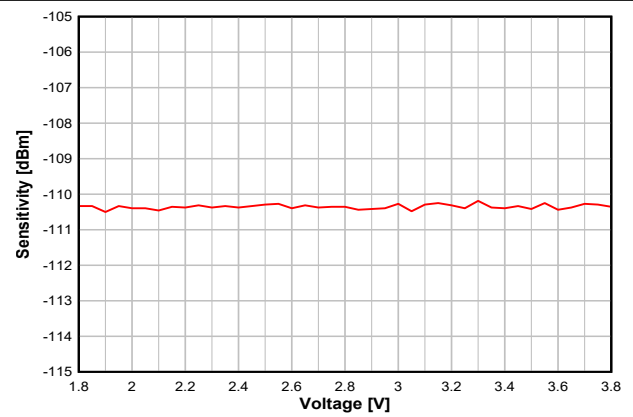
8-11. Sensitivity vs. Frequency (50 kbps, 868 MHz)



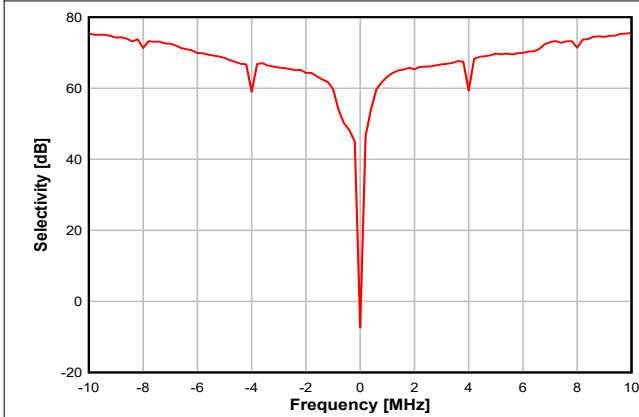
8-12. Sensitivity vs. Frequency (50 kbps, 915 MHz)



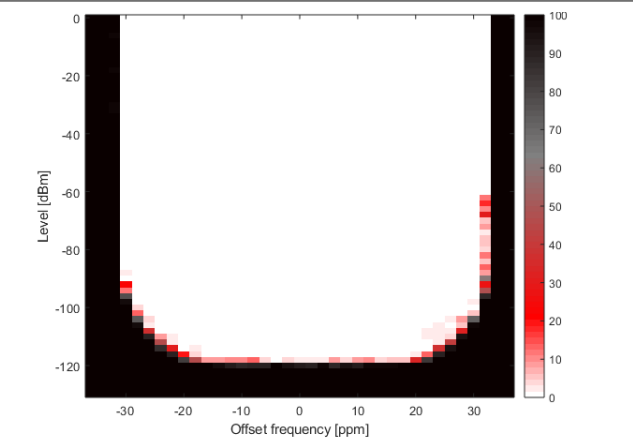
8-13. Sensitivity vs. Temperature (50 kbps, 868.3 MHz)



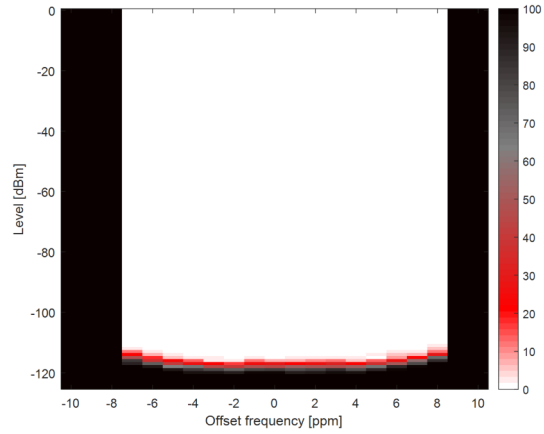
8-14. Sensitivity vs. Supply Voltage (VDD5) (50 kbps, 868.3 MHz)



8-15. Selectivity vs. Frequency Offset (50 kbps, 868.3 MHz)



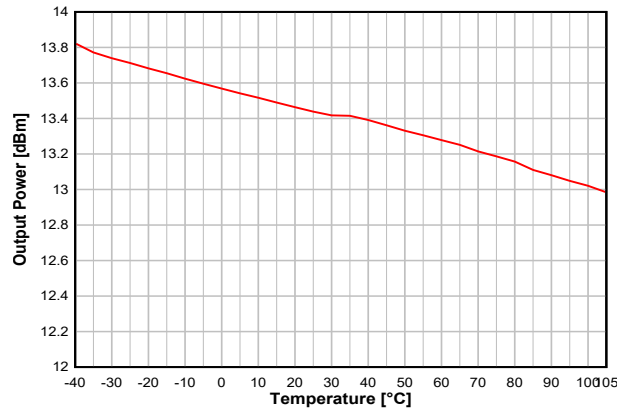
8-16. PER vs. Level vs. Frequency (SimpleLink™ Long Range 5 kbps, 868 MHz)



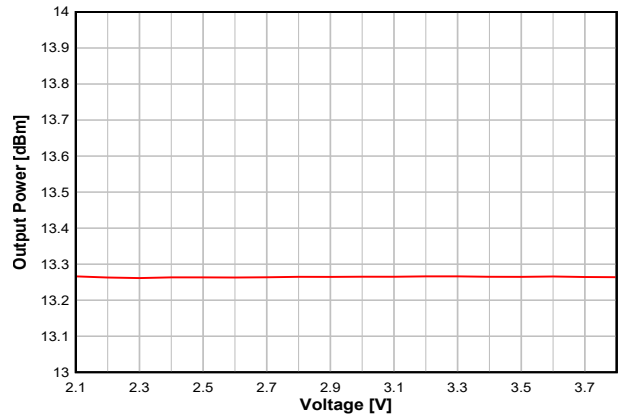
8-17. PER vs. Level vs. Frequency (Narrowband, 9.6 kbps, ±2.4 kHz deviation, 2-GFSK, 868 MHz, 17.1 kHz RX bandwidth)

8.16.5 TX Performance

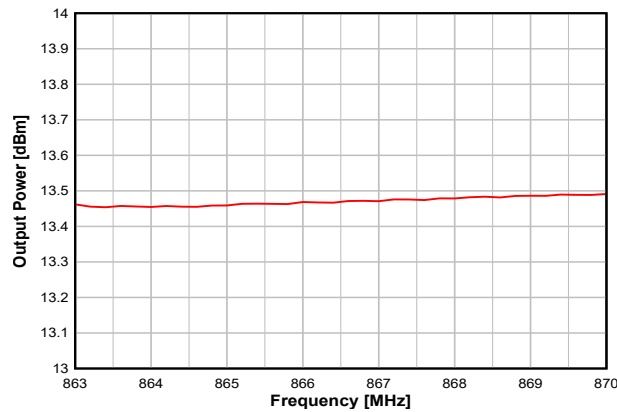
ADVANCE INFORMATION



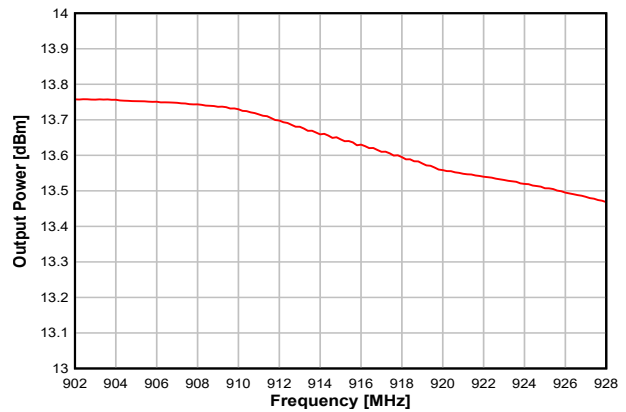
8-18. Output Power vs. Temperature (50 kbps, 868.3 MHz)



8-19. Output Power vs. Supply Voltage (VDDS) (50 kbps, 868.3 MHz)

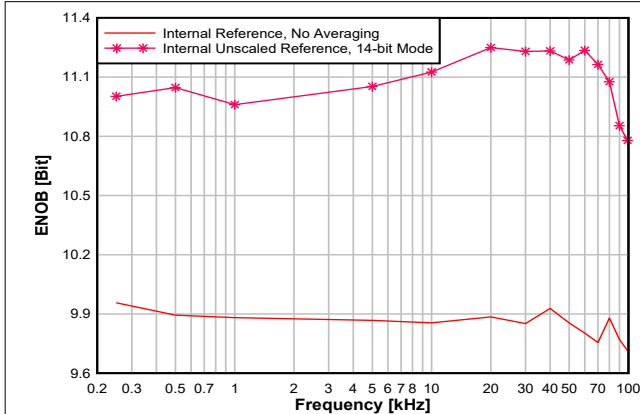


8-20. Output Power vs. Frequency (50 kbps, 868 MHz)

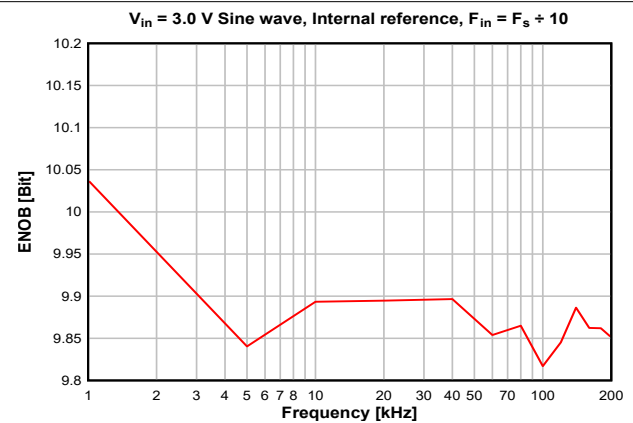


8-21. Output Power vs. Frequency (50 kbps, 915 MHz)

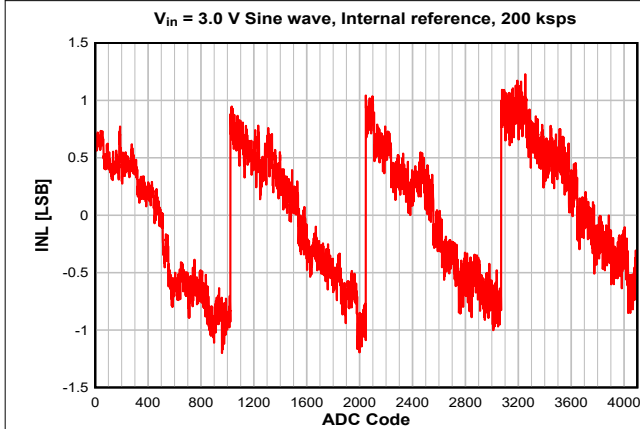
8.16.6 ADC Performance



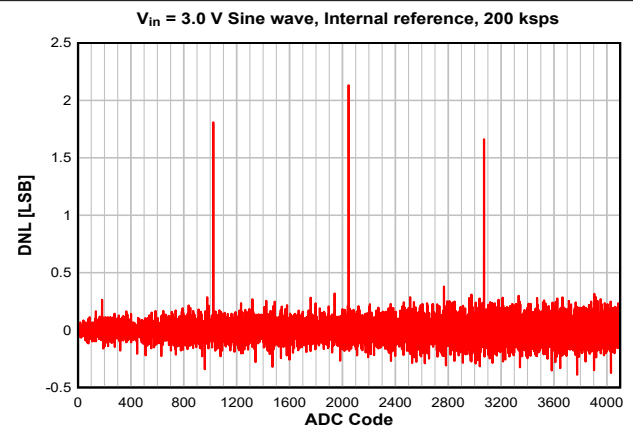
8-22. ENOB vs. Input Frequency



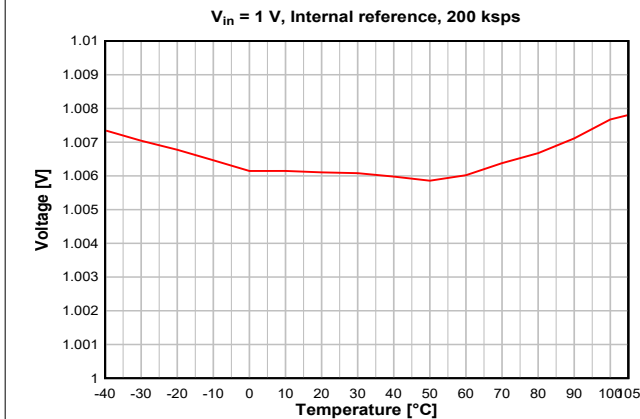
8-23. ENOB vs. Sampling Frequency



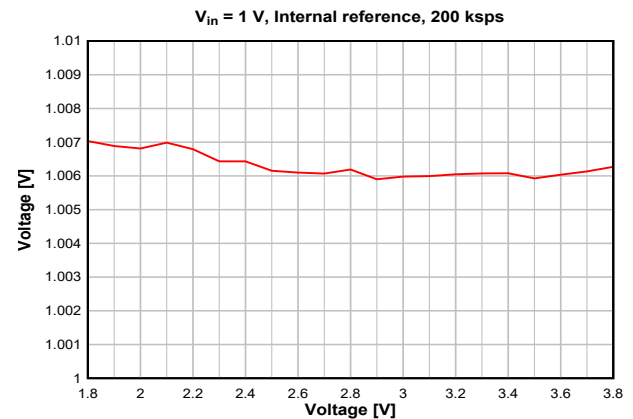
8-24. INL vs. ADC Code



8-25. DNL vs. ADC Code



8-26. ADC Accuracy vs. Temperature



8-27. ADC Accuracy vs. Supply Voltage (VDD5)

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9 Detailed Description

9.1 Overview

セクション 4 shows the core modules of the CC1314R10 device.

Throughout this section, see the Technical Reference Manual listed in [Section 11.2](#) for more details.

9.2 System CPU

The CC1314R10 SimpleLink™ Wireless MCU contains an Arm® Cortex®-M33 system CPU with TrustZone®, which runs the application and the higher layers of radio protocol stacks.

The system CPU is the foundation of a high-performance, low-cost platform that meets the system requirements of minimal memory implementation, and low-power consumption, while delivering outstanding computational performance and exceptional system response to interrupts.

Its features include the following:

- ARMv8-M architecture with TrustZone® security extension optimized for small-footprint embedded applications
- Arm Thumb®-2 mixed 16- and 32-bit instruction set delivers the high performance expected of a 32-bit Arm core in a compact memory size
- 8 regions of non-secure memory protected regions
- 8 regions of secure memory protected regions
- 4 regions of Security Attribute Unit (SAU)
- Single-cycle multiply instruction and hardware divide
- Digital-signal-processing (DSP) extension
- IEEE 754-compliant single-precision Floating Point Unit (FPU)
- Fast code execution permits increased sleep mode time
- Deterministic, high-performance interrupt handling for time-critical applications
- Full debug with data matching for watchpoint generation
 - Data Watchpoint and Trace Unit (DWT)
 - JTAG Debug Access Port (DAP)
 - Flash Patch and Breakpoint Unit (FPB)
- Trace support reduces the number of pins required for debugging and tracing
 - Instrumentation Trace Macrocell Unit (ITM)
 - Trace Port Interface Unit (TPIU) with asynchronous serial wire output (SWO)
- Optimized for single-cycle flash memory access
- Tightly connected to 8 kB 4-way random replacement cache for minimal active power consumption and wait states
- Ultra-low-power consumption with integrated sleep modes
- 48 MHz operation

9.3 Radio (RF Core)

The RF Core is a highly flexible and future proof radio module which contains an Arm Cortex-M0 processor that interfaces the analog RF and base-band circuitry, handles data to and from the system CPU side, and assembles the information bits in a given packet structure. The RF core offers a high level, command-based API to the main CPU that configurations and data are passed through. The Arm Cortex-M0 processor is not programmable by customers and is interfaced through the TI-provided RF driver that is included with the SimpleLink Software Development Kit (SDK).

The RF core can autonomously handle the time-critical aspects of the radio protocols, thus offloading the main CPU, which reduces power and leaves more resources for the user application. Several signals are also available to control external circuitry such as RF switches or range extenders autonomously.

The various physical layer radio formats are partly built as a software defined radio where the radio behavior is either defined by radio ROM contents or by non-ROM radio formats delivered in form of firmware patches with the SimpleLink SDKs. This allows the radio platform to be updated for support of future versions of standards even with over-the-air (OTA) updates while still using the same silicon.

注

Not all combinations of features, frequencies, data rates, and modulation formats described in this chapter are supported. Over time, TI can enable new physical radio formats (PHYs) for the device and provides performance numbers for selected PHYs in the data sheet. Supported radio formats for a specific device, including optimized settings to use with the TI RF driver, are included in the [SmartRF Studio](#) tool with performance numbers of selected formats found in [セクション 8](#).

9.3.1 Proprietary Radio Formats

The CC1314R10 radio can support a wide range of physical radio formats through a set of hardware peripherals combined with firmware available in the device ROM, covering various customer needs for optimizing towards parameters such as speed or sensitivity. This allows great flexibility in tuning the radio both to work with legacy protocols as well as customizing the behavior for specific application needs.

表 9-1 gives a simplified overview of features of the various radio formats available in ROM. Other radio formats may be available in the form of radio firmware patches or programs through the Software Development Kit (SDK) and may combine features in a different manner, as well as add other features.

表 9-1. Feature Support

| Feature | Main 2-(G)FSK Mode | High Data Rates | Low Data Rates | SimpleLink™ Long Range |
|---|--------------------|----------------------|------------------------------------|------------------------|
| Programmable preamble, sync word and CRC | Yes | Yes | Yes | No |
| Programmable receive bandwidth | Yes | Yes | Yes (down to 4 kHz) | Yes |
| Data / Symbol rate ⁽³⁾ | 20 to 1000 kbps | ≤ 2 Msps | ≤ 100 ksps | ≤ 20 ksps |
| Modulation format | 2-(G)FSK | 2-(G)FSK 4-(G)FSK | 2-(G)FSK 4-(G)FSK SUN-O-QPSK | 2-(G)FSK |
| Dual Sync Word | Yes | Yes | No | No |
| Carrier Sense ⁽¹⁾ ⁽²⁾ | Yes | No | No | No |
| Preamble Detection ⁽²⁾ | Yes | Yes | Yes | No |
| Data Whitening | Yes | Yes | Yes | Yes |
| Digital RSSI | Yes | Yes | Yes | Yes |
| CRC filtering | Yes | Yes | Yes | Yes |
| Direct-sequence spread spectrum (DSSS) | No | No | No | 1:2 1:4 1:8 |
| Forward error correction (FEC) | No | No | No | Yes |
| Link Quality Indicator (LQI) | Yes | Yes | Yes | Yes |

- (1) Carrier Sense can be used to implement HW-controlled listen-before-talk (LBT) and Clear Channel Assessment (CCA) for compliance with such requirements in regulatory standards. This is available through the CMD_PROP_CS radio API.
- (2) Carrier Sense and Preamble Detection can be used to implement sniff modes where the radio is duty cycled to save power.
- (3) Data rates are only indicative. Data rates outside this range may also be supported. For some specific combinations of settings, a smaller range might be supported.

9.4 Memory

The up to 1024 kB nonvolatile (Flash) memory provides storage for code and data. The flash memory is in-system programmable and erasable. The last flash memory sector must contain a Customer Configuration section (CCFG) that is used by boot ROM and TI provided drivers to configure the device. This configuration is done through the `ccfg.c` source file that is included in all TI provided examples.

The ultra-low leakage system static RAM (SRAM) is split into up to eight 32 kB blocks and can be used for both storage of data and execution of code. Retention of SRAM contents in Standby power mode is enabled by default and included in Standby mode power consumption numbers. Parity checking for detection of bit errors in memory is built-in, which reduces chip-level soft errors and thereby increases reliability. Parity can be disabled for an additional 32 kB which can be allocated for general purpose SRAM. System SRAM is always initialized to zeroes upon code execution from boot.

To improve code execution speed and lower power when executing code from nonvolatile memory, a 4-way nonassociative 8 kB cache is enabled by default to cache and prefetch instructions read by the system CPU. The cache can be used as a general-purpose RAM by enabling this feature in the Customer Configuration Area (CCFG).

There is a 4 kB ultra-low leakage SRAM available for use with the Sensor Controller Engine which is typically used for storing Sensor Controller programs, data and configuration parameters. This RAM is also accessible by the system CPU. The Sensor Controller RAM is not cleared to zeroes between system resets.

The ROM includes a TI-RTOS kernel and low-level drivers, as well as significant parts of selected radio stacks, which frees up flash memory for the application. The ROM also contains a serial (SPI and UART) bootloader that can be used for initial programming of the device.

9.5 Sensor Controller

The Sensor Controller contains circuitry that can be selectively enabled in both Standby and Active power modes. The peripherals in this domain can be controlled by the Sensor Controller Engine, which is a proprietary power-optimized CPU. This CPU can read and monitor sensors or perform other tasks autonomously; thereby significantly reducing power consumption and offloading the system CPU.

The Sensor Controller Engine is user programmable with a simple programming language that has syntax similar to C. This programmability allows for sensor polling and other tasks to be specified as sequential algorithms rather than static configuration of complex peripheral modules, timers, DMA, register programmable state machines, or event routing.

The main advantages are:

- Flexibility - data can be read and processed in unlimited manners while still [ensuring ultra-low power](#)
- 2 MHz low-power mode enables lowest possible handling of digital sensors
- Dynamic reuse of hardware resources
- 40-bit accumulator supporting multiplication, addition and shift
- Observability and debugging options

[Sensor Controller Studio](#) is used to write, test, and debug code for the Sensor Controller. The tool produces C driver source code, which the System CPU application uses to control and exchange data with the Sensor Controller. Typical use cases may be (but are not limited to) the following:

- Read analog sensors using integrated ADC or comparators
- Interface digital sensors using GPIOs, SPI, UART, or I²C (UART and I²C are bit-banged)
- Capacitive sensing
- Waveform generation
- Very low-power pulse counting (flow metering)
- Key scan

The peripherals in the Sensor Controller include the following:

- The low-power clocked comparator can be used to wake the system CPU from any state in which the comparator is active. A configurable internal reference DAC can be used in conjunction with the comparator. The output of the comparator can also be used to trigger an interrupt or the ADC.
- Capacitive sensing functionality is implemented through the use of a constant current source, a time-to-digital converter, and a comparator. The continuous time comparator in this block can also be used as a higher-accuracy alternative to the low-power clocked comparator. The Sensor Controller takes care of baseline tracking, hysteresis, filtering, and other related functions when these modules are used for capacitive sensing.
- The ADC is a 12-bit 200 ksps ADC with eight inputs and a built-in voltage reference. The ADC can be triggered by many different sources including timers, I/O pins, software, and comparators.
- The analog modules can connect to up to eight different GPIOs
- Dedicated SPI master with up to 6 MHz clock speed

The peripherals in the Sensor Controller can also be controlled from the main application processor.

9.6 Cryptography

The CC1314R10 device comes with a wide set of modern cryptography-related hardware accelerators, drastically reducing code footprint and execution time for cryptographic operations. It also has the benefit of being lower power and improves availability and responsiveness of the system because the cryptography operations runs in a background hardware thread.

Together with a large selection of open-source cryptography libraries provided with the Software Development Kit (SDK), this allows for secure and future proof IoT applications to be easily built on top of the platform. The hardware accelerator modules are:

- **True Random Number Generator (TRNG)** module provides a true, nondeterministic noise source for the purpose of generating keys, initialization vectors (IVs), and other random number requirements. The TRNG is built on 24 ring oscillators that create unpredictable output to feed a complex nonlinear-combinatorial circuit
- **Secure Hash Algorithm 2 (SHA-2)** with support for SHA224, SHA256, SHA384, and SHA512
- **Advanced Encryption Standard (AES)** with 128, 192 and 256 bit key lengths
- **Public Key Accelerator** - Hardware accelerator supporting mathematical operations needed for elliptic curves up to 512 bits

Through use of these modules and the TI provided cryptography drivers, the following capabilities are available for an application or stack:

- **Key Agreement Schemes**
 - Elliptic Curve Diffie–Hellman with static or ephemeral keys (ECDH and ECDHE)
 - Elliptic curve Password Authenticated Key Exchange by Juggling (ECJ-PAKE)
- **Signature Processing**
 - Elliptic curve Diffie–Hellman Digital Signature Algorithm (ECDSA)
 - Edwards-curve Digital Signature Algorithm (EdDSA)
- **Curve Support**
 - Short Weierstrass form, such as:
 - NIST-P224 (secp224r1), NIST-P256 (secp256r1), NIST-P384 (secp384r1), NIST-P521 (secp521r1)
 - Brainpool-256R1, Brainpool-384R1, Brainpool-512R1
 - Montgomery form, such as:
 - Curve25519
 - Twisted Edwards form, such as:
 - Ed25519
- **Message Authentication Codes**
 - AEC CBC-MAC
 - AES CMAC
 - HMAC with SHA224, SHA256, SHA384 and SHA512
- **Block cipher mode of operation**
 - AES CCM and AES CCM-Star
 - AES GCM
 - AES ECB
 - AES CBC
 - AES CTR
- **Hash Algorithm**
 - SHA224
 - SHA256
 - SHA384
 - SHA512
- **True random number generation**

Other capabilities, such as RSA encryption and signatures (using keys as large as 2048 bits) as well as other ECC curves such as Curve1174, can be implemented using the provided public key accelerator but are not part of the TI SimpleLink SDK for the CC1314R10 device.

9.7 Timers

A large selection of timers are available as part of the CC1314R10 device. These timers are:

- **Real-Time Clock (RTC)**

A 70-bit 3-channel timer running on the 32 kHz low frequency system clock (SCLK_LF)

This timer is available in all power modes except Shutdown. The timer can be calibrated to compensate for frequency drift when using the LF RCOSC as the low frequency system clock. If an external LF clock with frequency different from 32.768 kHz is used, the RTC tick speed can be adjusted to compensate for this.

When using TI-RTOS, the RTC is used as the base timer in the operating system and should thus only be accessed through the kernel APIs such as the Clock module. The real time clock can also be read by the Sensor Controller Engine to timestamp sensor data and also has dedicated capture channels. By default, the RTC halts when a debugger halts the device.

- **General Purpose Timers (GPTIMER)**

The four flexible GPTIMERS can be used as either 4× 32 bit timers or 8× 16 bit timers, all running on up to 48 MHz. Each of the 16- or 32-bit timers support a wide range of features such as one-shot or periodic counting, pulse width modulation (PWM), time counting between edges and edge counting. The inputs and outputs of the timer are connected to the device event fabric, which allows the timers to interact with signals such as GPIO inputs, other timers, DMA and ADC. The GPTIMERS are available in Active and Idle power modes.

- **Sensor Controller Timers**

The Sensor Controller contains 3 timers:

AUX Timer 0 and 1 are 16-bit timers with a 2^N prescaler. Timers can either increment on a clock or on each edge of a selected tick source. Both one-shot and periodical timer modes are available.

AUX Timer 2 is a 16-bit timer that can operate at 24 MHz, 2 MHz or 32 kHz independent of the Sensor Controller functionality. There are 4 capture or compare channels, which can be operated in one-shot or periodical modes. The timer can be used to generate events for the Sensor Controller Engine or the ADC, as well as for PWM output or waveform generation.

- **Radio Timer**

A multichannel 32-bit timer running at 4 MHz is available as part of the device radio. The radio timer is typically used as the timing base in wireless network communication using the 32-bit timing word as the network time. The radio timer is synchronized with the RTC by using a dedicated radio API when the device radio is turned on or off. This ensures that for a network stack, the radio timer seems to always be running when the radio is enabled. The radio timer is in most cases used indirectly through the trigger time fields in the radio APIs and should only be used when running the accurate 48 MHz high frequency crystal is the source of SCLK_HF.

- **Watchdog timer**

The watchdog timer is used to regain control if the system operates incorrectly due to software errors. It is typically used to generate an interrupt and reset the device for the case where periodic monitoring of the system components and tasks fails to verify proper functionality. The watchdog timer runs on a 1.5 MHz clock rate and cannot be stopped once enabled. The watchdog timer continues to run in Standby power mode but pauses when a debugger halts the device.

- **Always On Watchdog Timer (AON_WDT)**

The Always On Watchdog Timer is used during standby to regain control when the system has failed due to a software error or failure of an external device to respond in the expected way. It generates a reset when its configured time-out counter reaches zero and cannot be stopped once started, unless by asserting a device reset. The Always-on watchdog timer runs in Standby power mode and may pause when a debugger halts the device.

9.8 Serial Peripherals and I/O

The SPI interface provides a standardized synchronous serial interface to communicate with devices compatible with SPI (3 and 4 wire), MICROWIRE and TI Synchronous Serial Format. The SPIs support master/slave operation up to 12 MHz, programmable clock bit rate with prescaler, as well as configurable phase and polarity.

The UART interface implements universal asynchronous receiver and transmitter functions. The UART supports flexible baud-rate generation up to a maximum of 3 Mbps with FIFO, multiple data sizes, stop and parity bits as well as hardware handshake.

The I²S interface provides a standardized interface to exchange digital audio with devices compatible with this standard, including ADCs, DACs and CODECs. The I²S can also receive pulse-density modulation (PDM) data from devices such as digital microphones and perform conversion to PCM data.

The I²C interface enables low speed serial communications with devices compatible with the I²C standard. The I²C interface can handle both standard (100 kHz) and fast (400 kHz) speeds, as well as four modes of operation: master transmit/receive and slave transmit/receive.

The I/O controller (IOC) controls the digital I/O pins and contains multiplexer circuitry to allow a set of peripherals to be assigned to I/O pins in a flexible manner. All digital I/Os are interrupt and wake-up capable, have a programmable pullup and pulldown function, and can generate an interrupt on a negative or positive edge (configurable). When configured as an output, pins can function as either push-pull or open-drain. Five GPIOs have high-drive capabilities, which are marked in **bold** in [セクション 7](#). All digital peripherals can be connected to any digital pin on the device.

9.9 Battery and Temperature Monitor

A combined temperature and battery voltage monitor is available in the CC1314R10 device. The battery and temperature monitor allows an application to continuously monitor on-chip temperature and supply voltage and respond to changes in environmental conditions as needed. The module contains window comparators to interrupt the system CPU when temperature or supply voltage go outside defined windows. These events can also be used to wake up the device from Standby mode through the Always-On (AON) event fabric.

9.10 μ DMA

The device includes a direct memory access (μ DMA) controller. The μ DMA controller provides a way to offload data-transfer tasks from the system CPU, thus allowing for more efficient use of the processor and the available bus bandwidth. The μ DMA controller can perform a transfer between memory and peripherals. The μ DMA controller has dedicated channels for each supported on-chip module and can be programmed to automatically perform transfers between peripherals and memory when the peripheral is ready to transfer more data.

Some features of the μ DMA controller include the following (this is not an exhaustive list):

- Highly flexible and configurable channel operation of up to 32 channels
- Transfer modes: memory-to-memory, memory-to-peripheral, peripheral-to-memory, and peripheral-to-peripheral
- Data sizes of 8, 16, and 32 bits
- Ping-pong mode for continuous streaming of data

9.11 Debug

The debug subsystem implements two IEEE standards for debug and test purposes:

IEEE 1149.7 Class 4: Reduced-pin and Enhanced-functionality Test Access Port and Boundary-scan Architecture. This is known by the acronym cJTAG (compact JTAG) and this device uses only two pins to communicate to the target: TMS (JTAG_TMSC) and TCK (JTAG_TCKC). This is the default mode of operation.

IEEE standard 1149.1: Test Access Port and Boundary Scan Architecture Test Access Port (TAP). This standard is known by the acronym JTAG and this device uses four pins to communicate to the target: TMS (JTAG_TMSC), TCK (JTAG_TCKC), TDI (JTAG_TDI) and TDO (JTAG_TDO).

The debug subsystem also implements a user-configurable firewall to control unauthorized access to debug/test ports.

ADVANCE INFORMATION

9.12 Power Management

To minimize power consumption, the CC1314R10 supports a number of power modes and power management features (see 表 9-2).

表 9-2. Power Modes

| MODE | SOFTWARE CONFIGURABLE POWER MODES | | | | RESET PIN HELD |
|------------------------------------|-----------------------------------|---------------------|---------------------|-----------|----------------|
| | ACTIVE | IDLE | STANDBY | SHUTDOWN | |
| CPU | Active | Off | Off | Off | Off |
| Flash | On | Available | Off | Off | Off |
| SRAM | On | On | Retention | Off | Off |
| Supply System | On | On | Duty Cycled | Off | Off |
| Register and CPU retention | Full | Full | Partial | No | No |
| SRAM retention | Full | Full | Full | No | No |
| 48 MHz high-speed clock (SCLK_HF) | XOSC_HF or RCOSC_HF | XOSC_HF or RCOSC_HF | Off | Off | Off |
| 2 MHz medium-speed clock (SCLK_MF) | RCOSC_MF | RCOSC_MF | Available | Off | Off |
| 32 kHz low-speed clock (SCLK_LF) | XOSC_LF or RCOSC_LF | XOSC_LF or RCOSC_LF | XOSC_LF or RCOSC_LF | Off | Off |
| Peripherals | Available | Available | Off | Off | Off |
| Sensor Controller | Available | Available | Available | Off | Off |
| Wake-up on RTC | Available | Available | Available | Off | Off |
| Wake-up on pin edge | Available | Available | Available | Available | Off |
| Wake-up on reset pin | On | On | On | On | On |
| Brownout detector (BOD) | On | On | Duty Cycled | Off | Off |
| Power-on reset (POR) | On | On | On | Off | Off |
| Watchdog timer (WDT) | Available | Available | Paused | Off | Off |
| Always-on Watchdog timer (AON_WDT) | Available | Available | Available | Off | Off |

In **Active** mode, the application system CPU is actively executing code. Active mode provides normal operation of the processor and all of the peripherals that are currently enabled. The system clock can be any available clock source (see 表 9-2).

In **Idle** mode, all active peripherals can be clocked, but the Application CPU core and memory are not clocked and no code is executed. Any interrupt event brings the processor back into active mode.

In **Standby** mode, only the always-on (AON) domain is active. An external wake-up event, RTC event, or Sensor Controller event is required to bring the device back to active mode. MCU peripherals with retention do not need to be reconfigured when waking up again, and the CPU continues execution from where it went into standby mode. All GPIOs are latched in standby mode.

In **Shutdown** mode, the device is entirely turned off (including the AON domain and Sensor Controller), and the I/Os are latched with the value they had before entering shutdown mode. A change of state on any I/O pin defined as a *wake from shutdown pin* wakes up the device and functions as a reset trigger. The CPU can differentiate between reset in this way and reset-by-reset pin or power-on reset by reading the reset status register. The only state retained in this mode is the latched I/O state and the flash memory contents.

The Sensor Controller is an autonomous processor that can control the peripherals in the Sensor Controller independently of the system CPU. This means that the system CPU does not have to wake up, for example to perform an ADC sampling or poll a digital sensor over SPI, thus saving both current and wake-up time that would otherwise be wasted. The [Sensor Controller Studio](#) tool enables the user to program the Sensor Controller, control its peripherals, and wake up the system CPU as needed. All Sensor Controller peripherals can also be controlled by the system CPU.

注

The power, RF and clock management for the CC1314R10 device require specific configuration and handling by software for optimized performance. This configuration and handling is implemented in the TI-provided drivers that are part of the CC1314R10 software development kit (SDK). Therefore, TI highly recommends using this software framework for all application development on the device. The complete [SDK](#) with TI-RTOS (optional), device drivers, and examples are offered free of charge in source code.

9.13 Clock Systems

The CC1314R10 device has several internal system clocks.

The 48 MHz SCLK_HF is used as the main system (MCU and peripherals) clock. This can be driven by the internal 48 MHz RC Oscillator (RCOSC_HF) or an external 48 MHz crystal (XOSC_HF). Radio operation requires an external 48 MHz crystal.

SCLK_MF is an internal 2 MHz clock that is used by the Sensor Controller in low-power mode and also for internal power management circuitry. The SCLK_MF clock is always driven by the internal 2 MHz RC Oscillator (RCOSC_MF).

SCLK_LF is the 32.768 kHz internal low-frequency system clock. It can be used by the Sensor Controller for ultra-low-power operation and is also used for the RTC and to synchronize the radio timer before or after Standby power mode. SCLK_LF can be driven by the internal 32.8 kHz RC Oscillator (RCOSC_LF), a 32.768 kHz watch-type crystal, or a clock input on any digital IO.

When using a crystal or the internal RC oscillator, the device can output the 32 kHz SCLK_LF signal to other devices, thereby reducing the overall system cost.

9.14 Network Processor

Depending on the product configuration, the CC1314R10 device can function as a wireless network processor (WNP - a device running the wireless protocol stack with the application running on a separate host MCU), or as a system-on-chip (SoC) with the application and protocol stack running on the system CPU inside the device.

In the first case, the external host MCU communicates with the device using SPI or UART. In the second case, the application must be written according to the application framework supplied with the wireless protocol stack.

10 Application, Implementation, and Layout

注

Information in the following Applications section is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

For general design guidelines and hardware configuration guidelines, refer to [CC13xx/CC26xx Hardware Configuration and PCB Design Considerations Application Report](#).

10.1 Reference Designs

The following reference designs should be followed closely when implementing designs using the CC1314R10 device.

Special attention must be paid to RF component placement, decoupling capacitors and DCDC regulator components, as well as ground connections for all of these.

[CC1312-R7EM-XD7793 Design Files](#)

The CC1312-R7EM-XD7793 reference design provides schematic, layout and production files for the characterization board used for deriving the performance number found in this document.

[LP-EM-CC1314R10 Design Files](#)

The CC1314R10 LaunchPad Design Files contain detailed schematics and layouts to build application specific boards using the CC1314R10 device.

[Sub-1 GHz and 2.4 GHz Antenna Kit for LaunchPad™ Development Kit and SensorTag](#)

The antenna kit allows real-life testing to identify the optimal antenna for your application. The antenna kit includes 16 antennas for frequencies from 169 MHz to 2.4 GHz, including:

- PCB antennas
- Helical antennas
- Chip antennas
- Dual-band antennas for 868 MHz and 915 MHz combined with 2.4 GHz

The antenna kit includes a JSC cable to connect to the Wireless MCU LaunchPad Development Kits and SensorTags.

10.2 Junction Temperature Calculation

This section shows the different techniques for calculating the junction temperature under various operating conditions. For more details, see [Semiconductor and IC Package Thermal Metrics](#).

There are three recommended ways to derive the junction temperature from other measured temperatures:

1. From package temperature:

$$T_J = \psi_{JT} \times P + T_{\text{case}} \quad (1)$$

2. From board temperature:

$$T_J = \psi_{JB} \times P + T_{\text{board}} \quad (2)$$

3. From ambient temperature:

$$T_J = R_{\theta JA} \times P + T_A \quad (3)$$

P is the power dissipated from the device and can be calculated by multiplying current consumption with supply voltage. Thermal resistance coefficients are found in [セクション 8.8](#).

For various application use cases current consumption for other modules may have to be added to calculate the appropriate power dissipation. For example, the MCU may be running simultaneously as the radio, peripheral modules may be enabled, etc. Typically, the easiest way to find the peak current consumption, and thus the peak power dissipation in the device, is to measure as described in [Measuring CC13xx and CC26xx current consumption](#).

11 Device and Documentation Support

TI offers an extensive line of development tools. Tools and software to evaluate the performance of the device, generate code, and develop solutions are listed as follows.

11.1 Tools and Software

The CC1314R10 device is supported by a variety of software and hardware development tools.

Development Kit

[CC1314R10 LaunchPad™ Development Kit](#)

The CC1314R10 LaunchPad™ Development Kit enables development of high-performance Sub-1 GHz wireless applications that benefit from low-power operation. The kit features the CC1314R10 Sub-1 GHz SimpleLink Wireless MCU. The kit works with the LaunchPad ecosystem, easily enabling additional functionality like sensors, display, and more.

[LP-XDS110 LaunchPad™ Debug Probe](#)

The LP-XDS110 LaunchPad™ Debug Probe enables development of high-performance wireless applications in the entire family of LP-EM LaunchPad™ development boards. Featuring a seamless connection with the new 20-pin LP-EM Debug connector, it supports not only multiple standards such as JTAG/cJTAG/SWD but also a UART backchannel for maximum debugging flexibility. It also features an Arm® 10-pin Debug connector to perform debugging in any custom board.

[LP-XDS110ET LaunchPad™ Debug Probe](#)

The LP-XDS110ET LaunchPad™ Debug Probe enables development of high-performance wireless applications in the entire family of LP-EM LaunchPad™ development boards. Featuring a seamless connection with the new 20-pin LP-EM Debug connector, it supports not only multiple standards such as JTAG/cJTAG/SWD but also a UART backchannel for maximum debugging flexibility. In addition, it also features an Arm® 10-pin Debug connector to perform debugging in any custom board. This Debug Probe also features the XDS110 EnergyTrace™ technology, which is a new method for measuring the current consumption that captures the complete operational profile of the wireless MCU.

[TMDSEMU110-U Debug Probe](#)

The TMDSEMU110-U Debug Probe enables development of high-performance wireless applications in the entire family of SimpleLink LaunchPad™ development boards. Featuring a convenient enclosure, which grants the proper mechanical robustness for field and production environments, it supports not only multiple standards such as JTAG/cJTAG/SWD but also a UART backchannel and four GPIOs for maximum debugging flexibility. In addition, the expansion connector allows using the [TMDSEMU110-ETH](#) add-on (sold separately), which adds the full featured XDS110 EnergyTrace™ technology with variable supply voltage from 1.8V to 3.6V and up to 800 mA of supply current. The XDS110 EnergyTrace™ technology is a new method for measuring the current consumption that captures the complete operational profile of the wireless MCU.

Software

[SimpleLink™ LOWPOWER F2 SDK](#)

The SimpleLink LOWPOWER F2 Software Development Kit (SDK) provides a complete package for the development of wireless applications on the CC13XX / CC26XX family of devices. The SDK includes a comprehensive software package for the CC1314R10 device, including the following protocol stacks:

- Bluetooth Low Energy 4 and 5.3
- Thread (based on OpenThread)
- TI Z-Stack (Zigbee 3.0)

- TI 15.4-Stack - an IEEE 802.15.4-based star networking solution for Sub-1 GHz and 2.4 GHz
- EasyLink - a large set of building blocks for building proprietary RF software stacks
- Multiprotocol support - concurrent operation between stacks using the Dynamic Multiprotocol Manager (DMM)
- TI Wi-SUN FAN Stack
- Matter

The SimpleLink LOWPOWER F2 SDK is part of TI's SimpleLink MCU platform, offering a single development environment that delivers flexible hardware, software and tool options for customers developing wired and wireless applications. For more information about the SimpleLink MCU Platform, visit ti.com/simplelink.

Development Tools

Code Composer Studio™ Integrated Development Environment (IDE)

Code Composer Studio is an integrated development environment (IDE) that supports TI's Microcontroller and Embedded Processors portfolio. Code Composer Studio comprises a suite of tools used to develop and debug embedded applications. It includes an optimizing C/C++ compiler, source code editor, project build environment, debugger, profiler, and many other features. The intuitive IDE provides a single user interface taking you through each step of the application development flow. Familiar tools and interfaces allow users to get started faster than ever before. Code Composer Studio combines the advantages of the Eclipse® software framework with advanced embedded debug capabilities from TI resulting in a compelling feature-rich development environment for embedded developers.

CCS has support for all SimpleLink Wireless MCUs and includes support for EnergyTrace™ software (application energy usage profiling). A real-time object viewer plugin is available for TI-RTOS, part of the SimpleLink SDK.

Code Composer Studio is provided free of charge when used in conjunction with the XDS debuggers included on a LaunchPad Development Kit.

Code Composer Studio™ Cloud IDE

Code Composer Studio (CCS) Cloud is a web-based IDE that allows you to create, edit and build CCS and Energia™ projects. After you have successfully built your project, you can download and run on your connected LaunchPad. Basic debugging, including features like setting breakpoints and viewing variable values is now supported with CCS Cloud.

IAR Embedded Workbench® for Arm®

IAR Embedded Workbench® is a set of development tools for building and debugging embedded system applications using assembler, C and C++. It provides a completely integrated development environment that includes a project manager, editor, and build tools. IAR has support for all SimpleLink Wireless MCUs. It offers broad debugger support, including XDS110, IAR I-jet™ and Segger J-Link™. A real-time object viewer plugin is available for TI-RTOS, part of the SimpleLink SDK. IAR is also supported out-of-the-box on most software examples provided as part of the SimpleLink SDK.

A 30-day evaluation or a 32 kB size-limited version is available through iar.com.

SmartRF™ Studio

SmartRF™ Studio is a Windows® application that can be used to evaluate and configure SimpleLink Wireless MCUs from Texas Instruments. The application will help designers of RF systems to easily evaluate the radio at an early stage in the design process. It is especially useful for generation of configuration register values and for practical testing and debugging of the RF system. SmartRF Studio can be used either as a standalone application or together with applicable evaluation boards or debug probes for the RF device. Features of the SmartRF Studio include:

- Link tests - send and receive packets between nodes

- Antenna and radiation tests - set the radio in continuous wave TX and RX states
- Export radio configuration code for use with the TI SimpleLink SDK RF driver
- Custom GPIO configuration for signaling and control of external switches

Sensor Controller Studio

Sensor Controller Studio is used to write, test and debug code for the Sensor Controller peripheral. The tool generates a Sensor Controller Interface driver, which is a set of C source files that are compiled into the System CPU application. These source files also contain the Sensor Controller binary image and allow the System CPU application to control and exchange data with the Sensor Controller. Features of the Sensor Controller Studio include:

- Ready-to-use examples for several common use cases
- Full toolchain with built-in compiler and assembler for programming in a C-like programming language
- Provides rapid development by using the integrated sensor controller task testing and debugging functionality, including visualization of sensor data and verification of algorithms

UniFlash

UniFlash is a standalone tool used to program on-chip flash memory on TI MCUs. UniFlash has a GUI, command line, and scripting interface. UniFlash is available free of charge.

11.1.1 SimpleLink™ Microcontroller Platform

The SimpleLink microcontroller platform sets a new standard for developers with the broadest portfolio of wired and wireless Arm® MCUs (System-on-Chip) in a single software development environment. Delivering flexible hardware, software and tool options for your IoT applications. Invest once in the SimpleLink software development kit and use throughout your entire portfolio. Learn more on ti.com/simplelink.

11.2 Documentation Support

To receive notification of documentation updates on data sheets, errata, application notes and similar, navigate to the device product folder on ti.com/product/CC1314R10. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

The current documentation that describes the MCU, related peripherals, and other technical collateral is listed as follows.

TI Resource Explorer

[TI Resource Explorer](#) Software examples, libraries, executables, and documentation are available for your device and development board.

Errata

[CC1314R10 Silicon Errata](#)

The silicon errata describes the known exceptions to the functional specifications for each silicon revision of the device and description on how to recognize a device revision.

Application Reports

All application reports for the CC1314R10 device are found on the device product folder at: ti.com/product/CC1314R10/technicaldocuments.

Technical Reference Manual (TRM)

[CC13x4, CC26x4 SimpleLink™ Wireless MCU Technical Reference Manual](#)

The TRM provides a detailed description of all modules and peripherals available in the device family.

11.3 サポート・リソース

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11.5 静電気放電に関する注意事項



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11.6 用語集

[テキサス・インスツルメンツ用語集](#)

この用語集には、用語や略語の一覧および定義が記載されています。

12 Mechanical, Packaging, and Orderable Information

12.1 Packaging Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

注

The RSK (S-PQVFN-N64) package drawings in this datasheet are preliminary and will change for the production release of this IC. The change will be related to the exposed thermal pad size of the IC. The current sample has a 3.7 mm x 3.7 mm thermal ground pad. Production devices will have a 4.7 mm x 4.7mm thermal ground pad. It is recommended to design the thermal ground pad to be 4.7 mm x 4.7 mm, with a stencil opening of 3.7 mm x 3.7mm for pre-production devices. For production devices, only the stencil will need to change to 4.7 mm x 4.7 mm. No change to the PCB will be required.

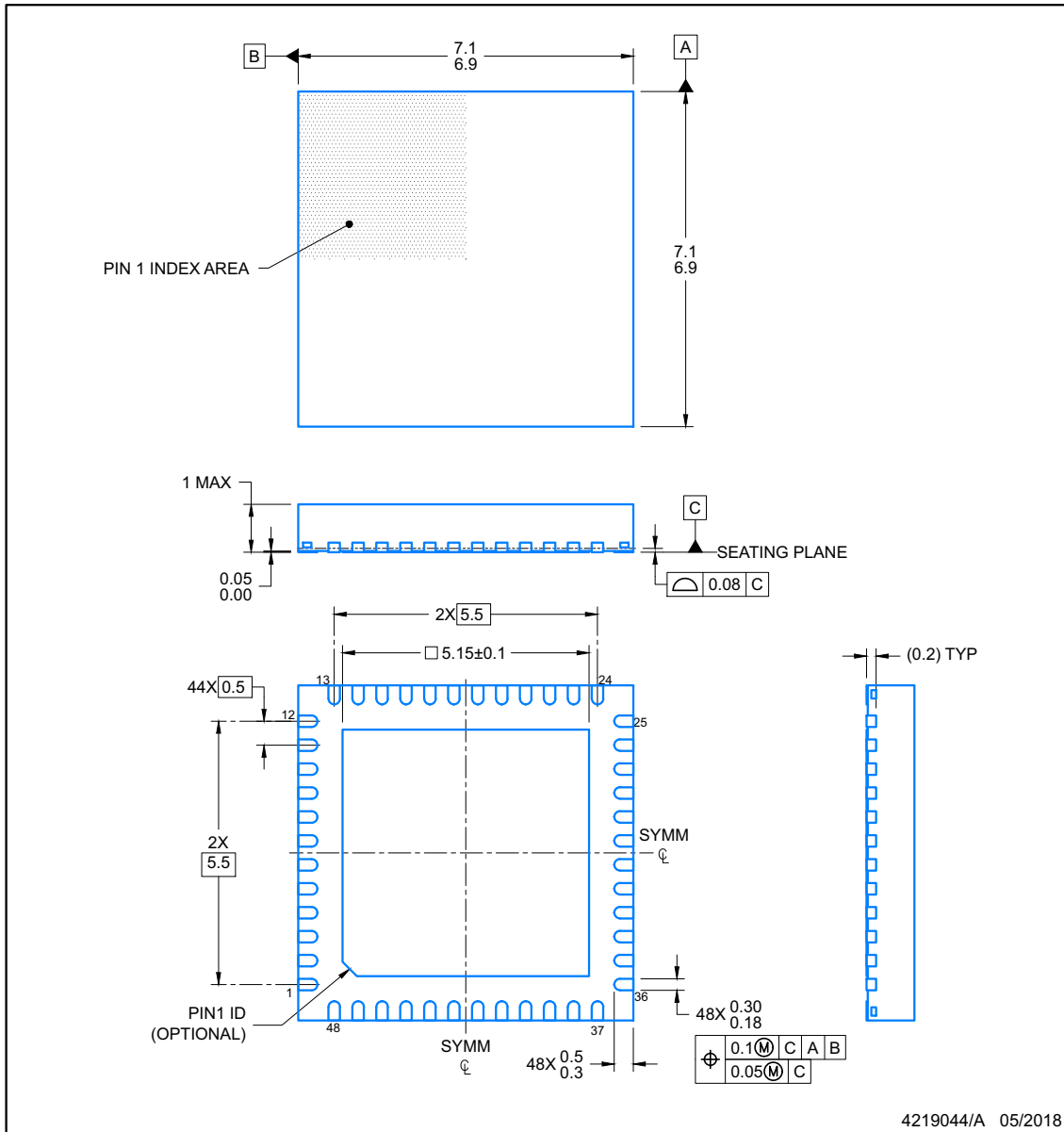
PACKAGE OUTLINE

VQFN - 1 mm max height

RGZ0048A

PLASTIC QUADFLAT PACK- NO LEAD

ADVANCE INFORMATION



NOTES:

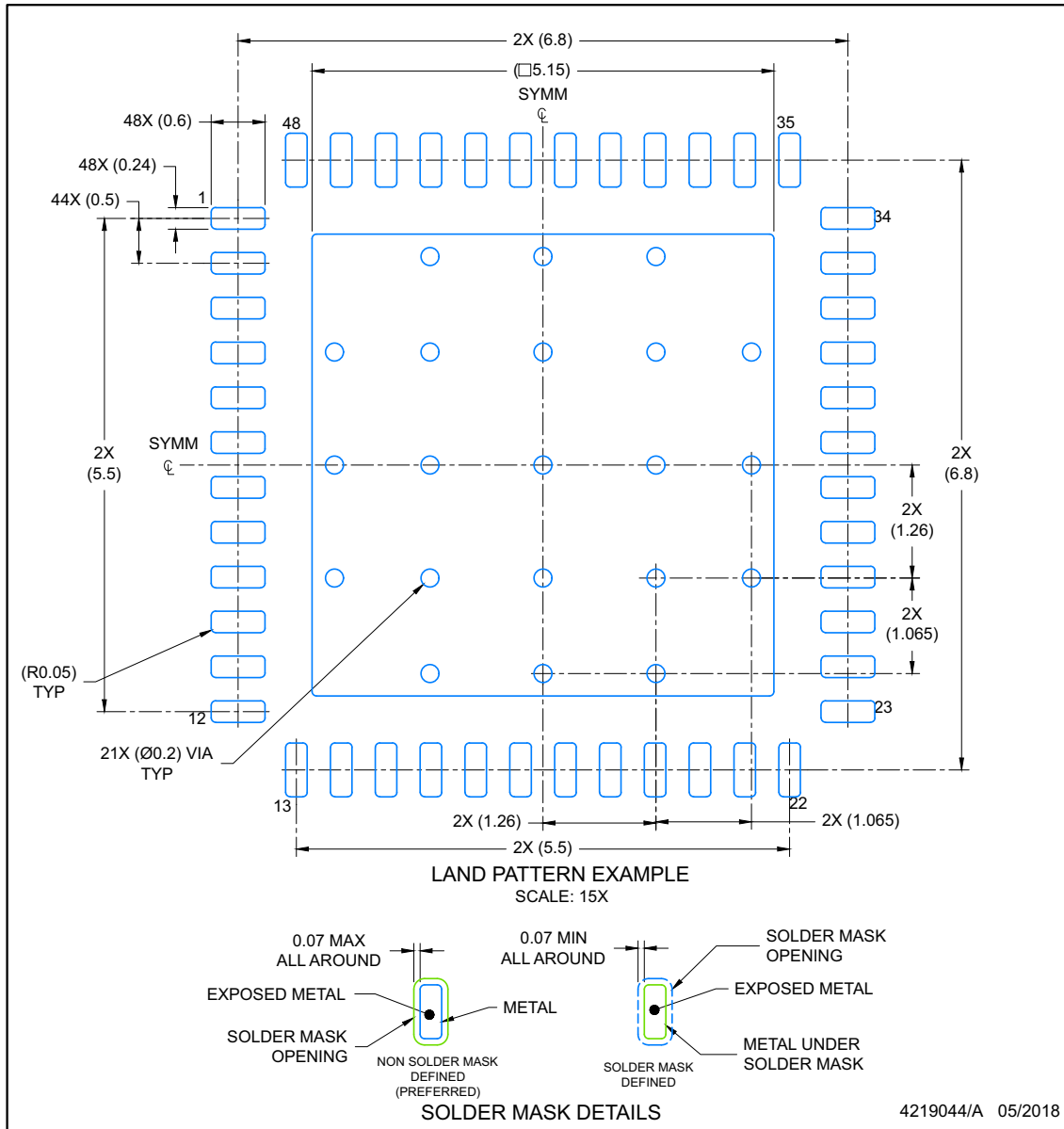
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.

EXAMPLE BOARD LAYOUT

RGZ0048A

VQFN - 1 mm max height

PLASTIC QUADFLAT PACK- NO LEAD



ADVANCE INFORMATION

NOTES: (continued)

- This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/sl原因271).
- Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

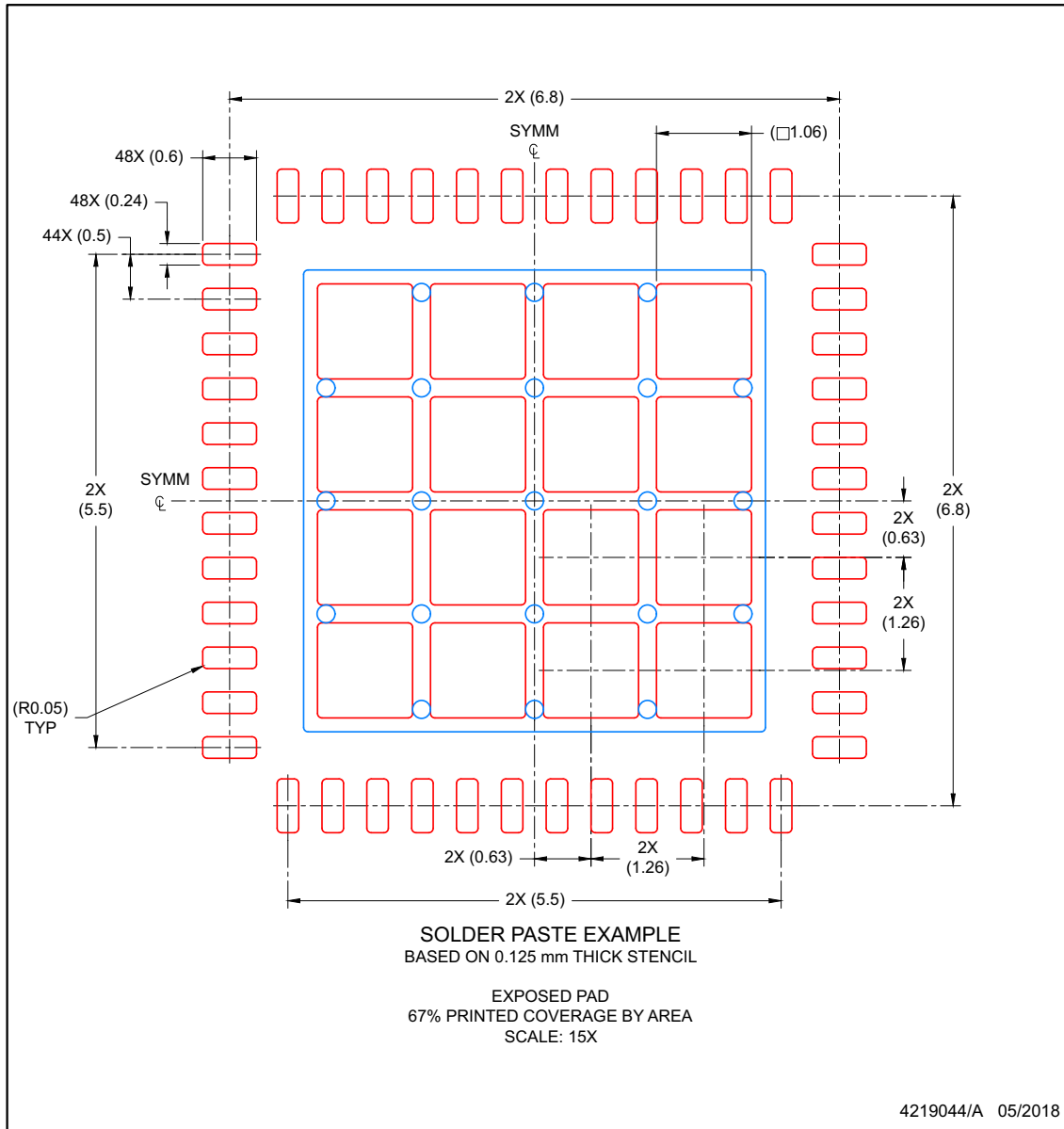
EXAMPLE STENCIL DESIGN

VQFN - 1 mm max height

RGZ0048A

PLASTIC QUADFLAT PACK- NO LEAD

ADVANCE INFORMATION



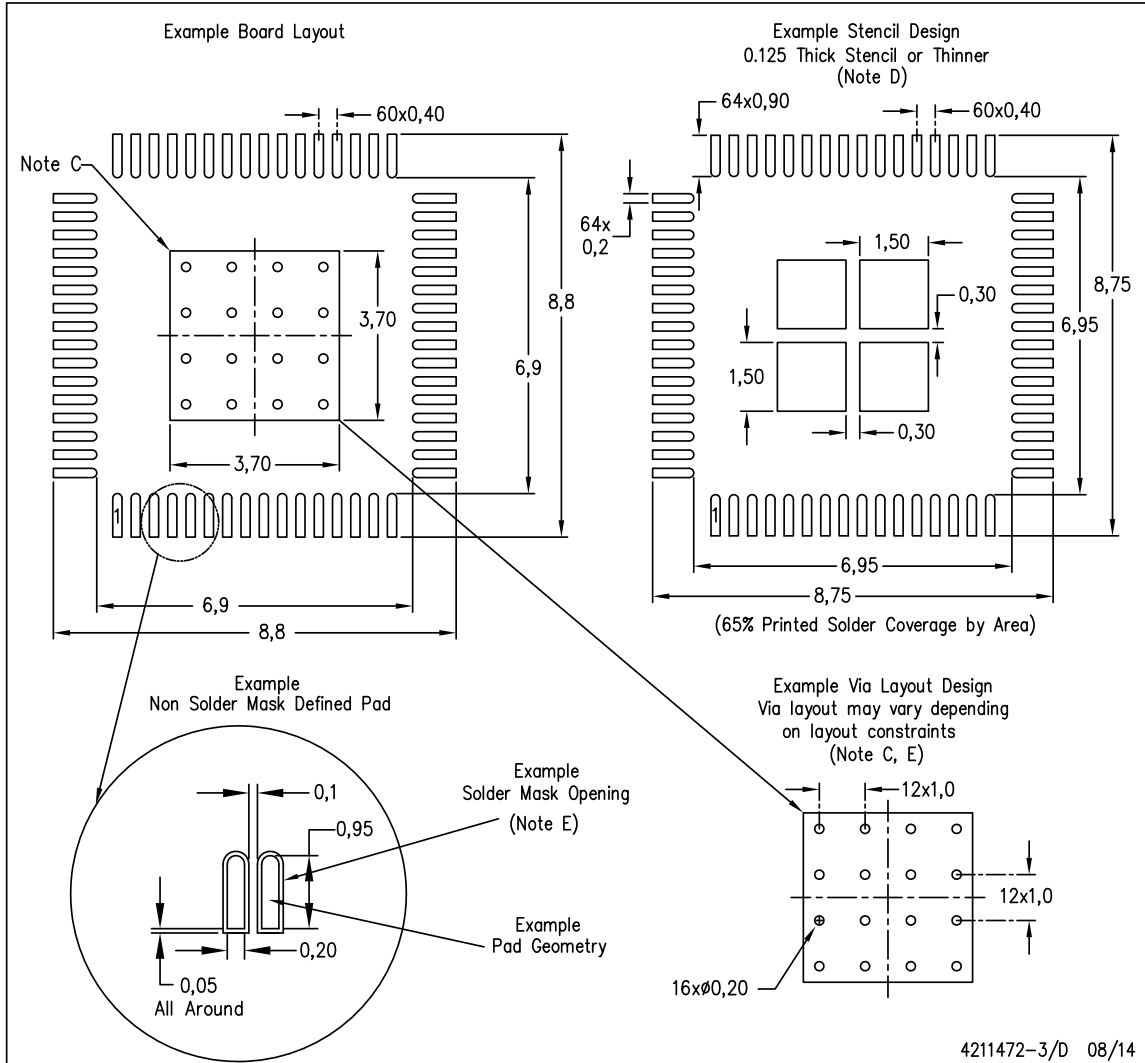
NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

LAND PATTERN DATA

RSK (S-PVQFN-N64)

PLASTIC QUAD FLATPACK NO-LEAD



- NOTES:
- All linear dimensions are in millimeters.
 - This drawing is subject to change without notice.
 - This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack Packages, Texas Instruments Literature No. SCBA017, SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <<http://www.ti.com>>.
 - Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
 - Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for any larger diameter vias placed in the thermal pad.

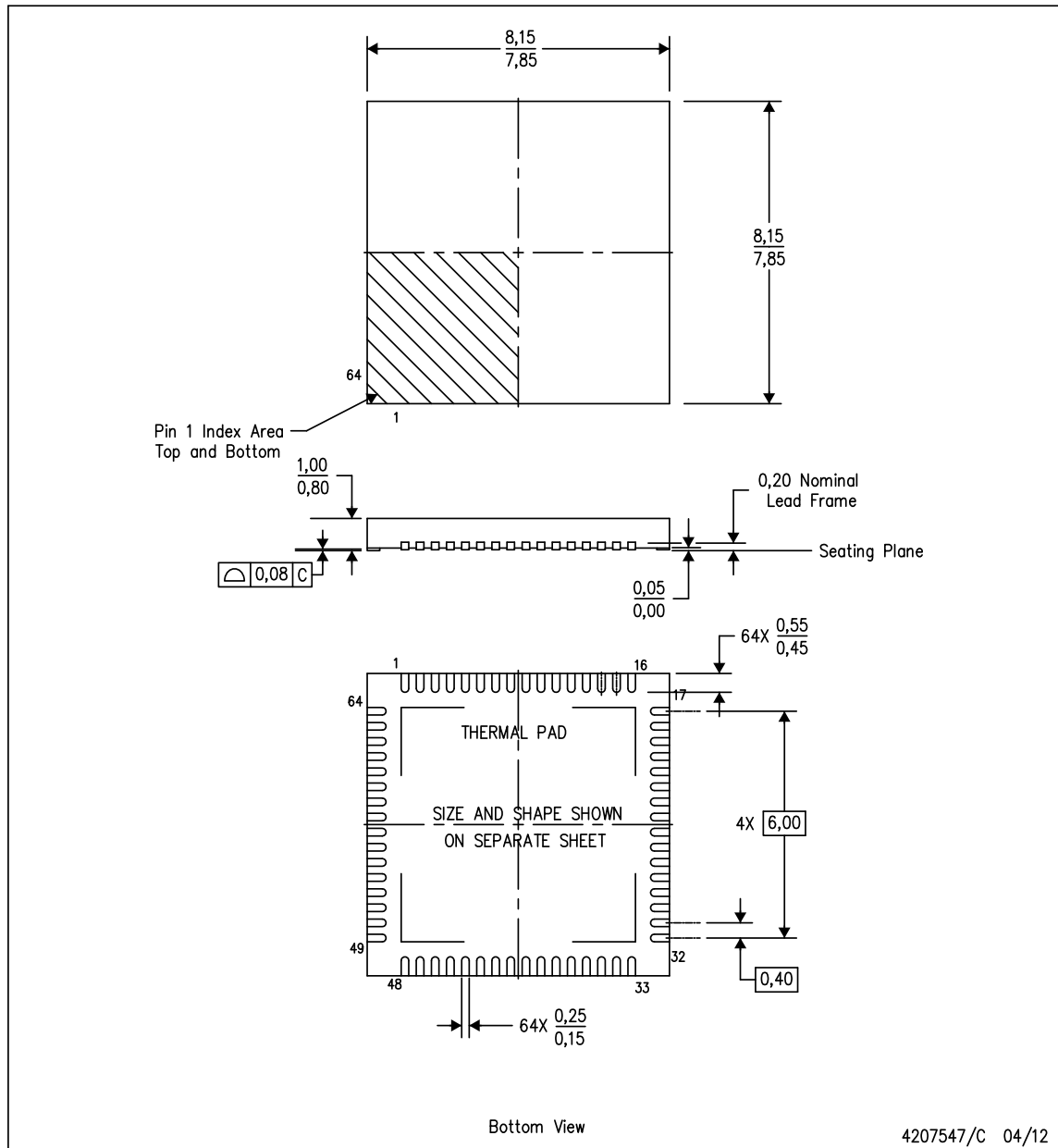
ADVANCE INFORMATION

MECHANICAL DATA

RSK (S-PVQFN-N64)

PLASTIC QUAD FLATPACK NO-LEAD

ADVANCE INFORMATION



- NOTES:
- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5-1994.
 - B. This drawing is subject to change without notice.
 - C. QFN (Quad Flatpack No-Lead) Package configuration.
 - D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
 - E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.

THERMAL PAD MECHANICAL DATA

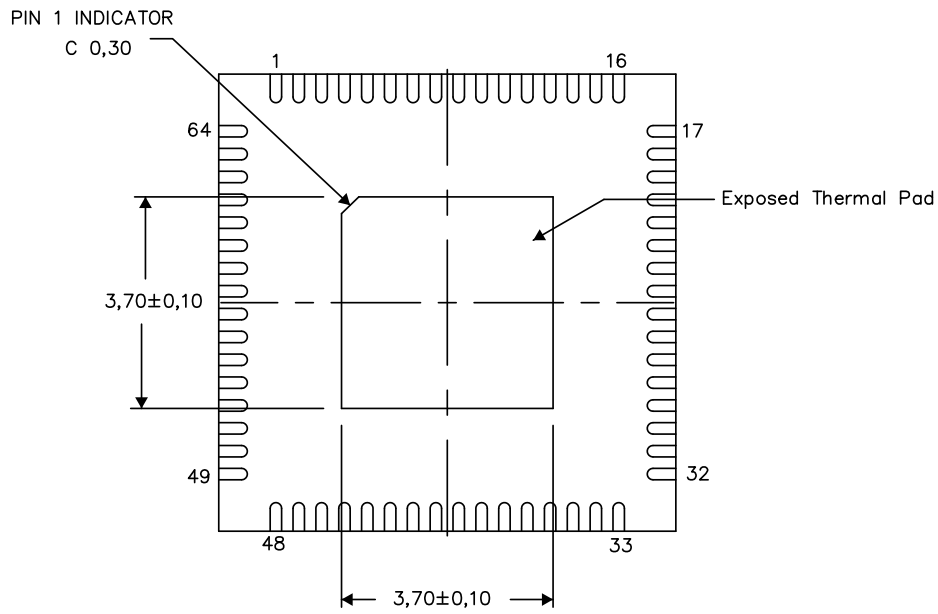
RSK (S–PVQFN–N64) PLASTIC QUAD FLATPACK NO–LEAD

THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No–Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



Bottom View

Exposed Thermal Pad Dimensions

4208001–3/H 08/14

NOTE: A. All linear dimensions are in millimeters

ADVANCE INFORMATION

PACKAGING INFORMATION

| Orderable Device | Status (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan (2) | Lead finish/ Ball material (6) | MSL Peak Temp (3) | Op Temp (°C) | Device Marking (4/5) | Samples |
|------------------|---------------|--------------|-----------------|------|-------------|-----------------|--------------------------------------|----------------------|--------------|-------------------------|-------------------------|
| CC1314R106T0RGZR | ACTIVE | VQFN | RGZ | 48 | 2500 | RoHS & Green | NIPDAU | Level-3-260C-168 HR | -40 to 105 | CC1314 R106 | Samples |
| CC1314R106T0RSKR | ACTIVE | VQFN | RSK | 64 | 2000 | RoHS & Green | NIPDAU | Level-3-260C-168 HR | -40 to 105 | CC1314 R106 | Samples |
| XCC1314R106T0RGZ | ACTIVE | VQFN | RGZ | 48 | 260 | TBD | Call TI | Call TI | -40 to 105 | | Samples |
| XCC1314R106T0RSK | ACTIVE | VQFN | RSK | 64 | 4000 | TBD | Call TI | Call TI | -40 to 105 | | Samples |

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSELETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

GENERIC PACKAGE VIEW

RGZ 48

VQFN - 1 mm max height

7 x 7, 0.5 mm pitch

PLASTIC QUADFLAT PACK- NO LEAD



Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

4224671/A



4219044/D 02/2022

NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.



NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

EXAMPLE STENCIL DESIGN

RGZ0048A

VQFN - 1 mm max height

PLASTIC QUADFLAT PACK- NO LEAD

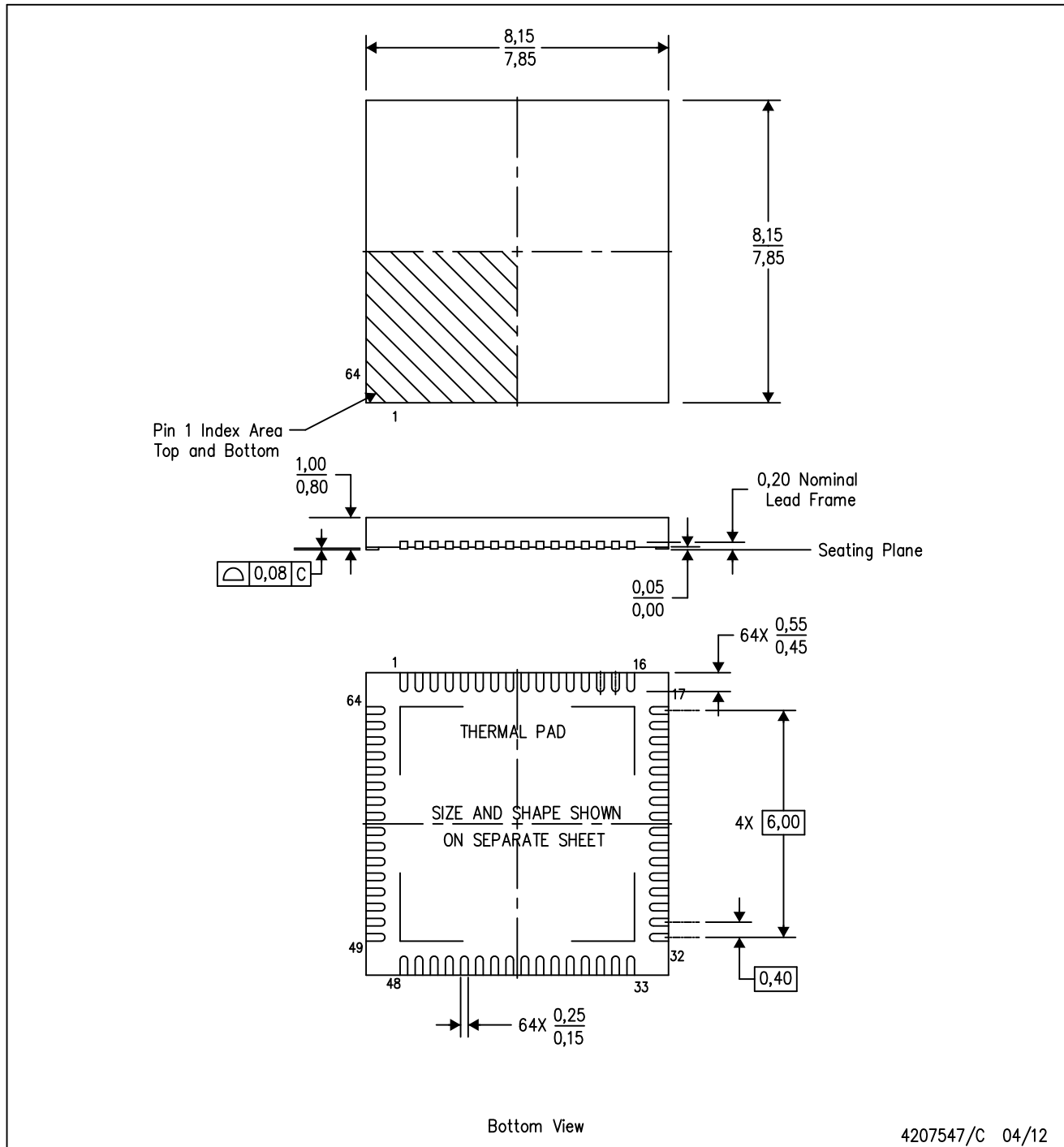


NOTES: (continued)

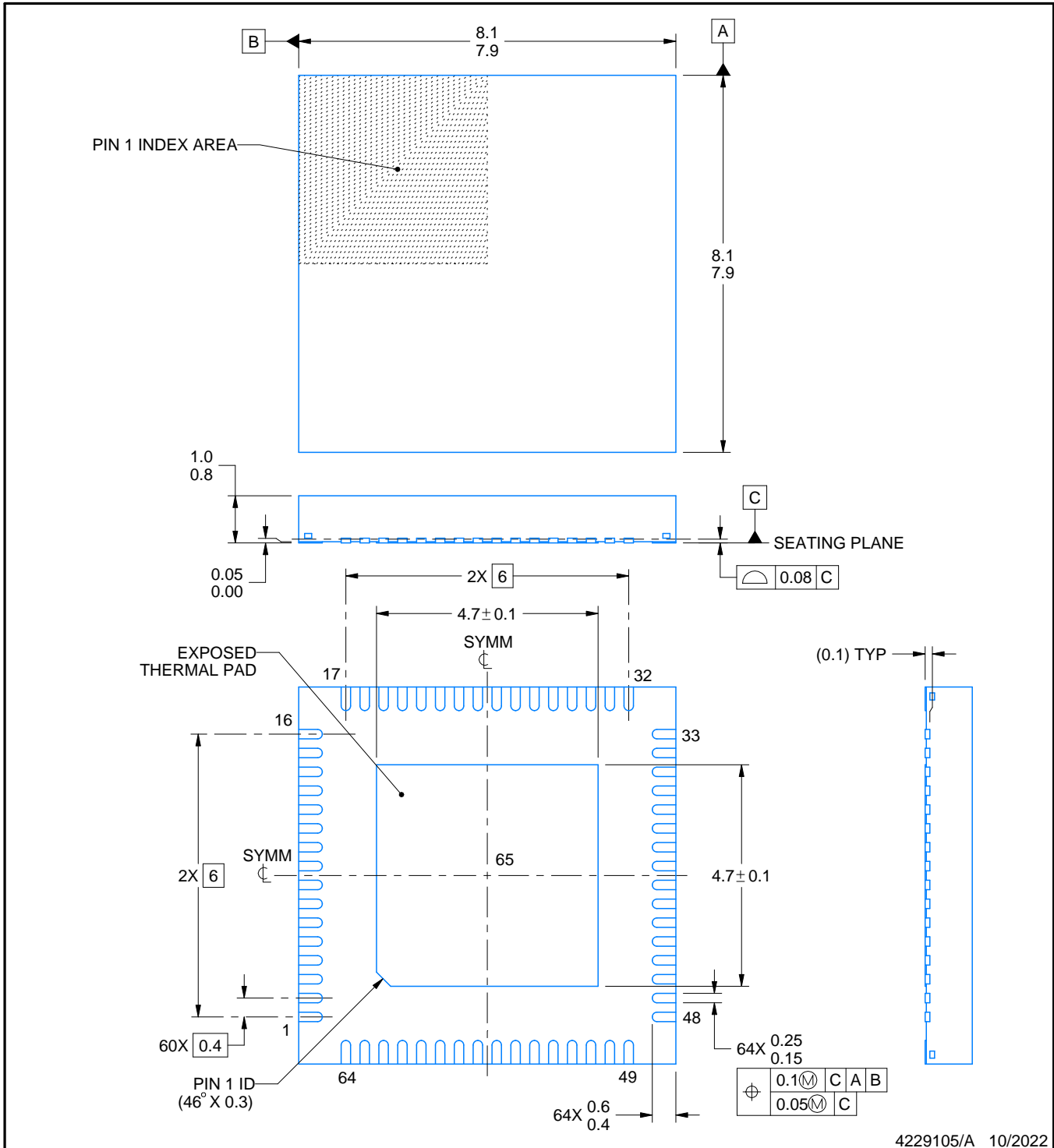
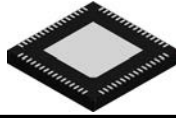
6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

RSK (S-PVQFN-N64)

PLASTIC QUAD FLATPACK NO-LEAD



- NOTES:
- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5-1994.
 - B. This drawing is subject to change without notice.
 - C. QFN (Quad Flatpack No-Lead) Package configuration.
 - D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
 - E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.



4229105/A 10/2022

NOTES:

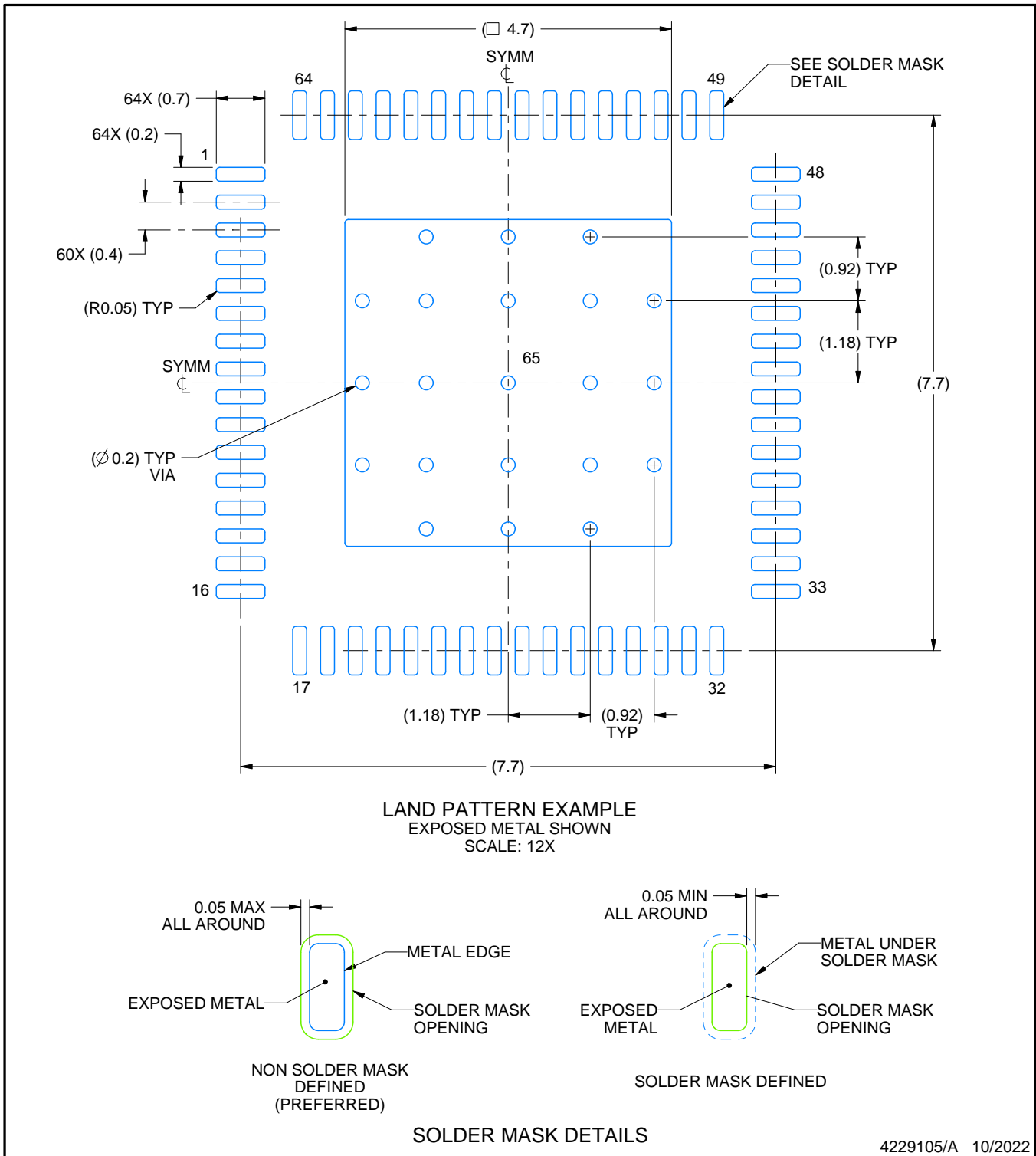
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

EXAMPLE BOARD LAYOUT

RSK0064D

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

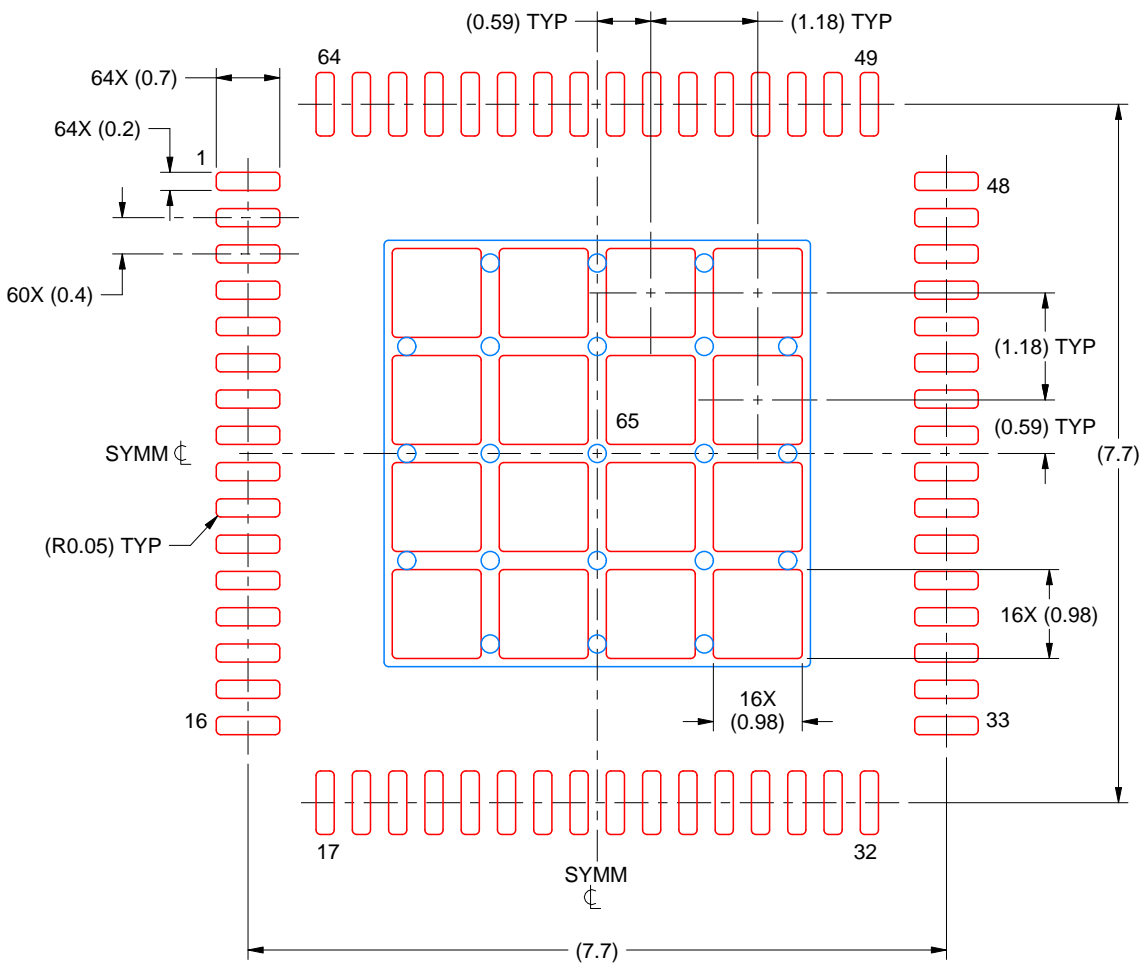
- This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/sluea271).
- Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

EXAMPLE STENCIL DESIGN

RSK0064D

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



SOLDER PASTE EXAMPLE
 BASED ON 0.100 MM THICK STENCIL
 SCALE: 12X

EXPOSED PAD 65
 70% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE

4229105/A 10/2022

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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