

MIXED SIGNAL MICROCONTROLLER

FEATURES

- Low Supply-Voltage Range: 1.8 V to 3.6 V
- Ultra-Low Power Consumption
 - Active Mode: 220 µA at 1 MHz, 2.2 V
 - Standby Mode: 0.5 μA
 - Off Mode (RAM Retention): 0.1 μA
- Five Power-Saving Modes
- Ultra-Fast Wake-Up From Standby Mode in Less Than 1 µs
- 16-Bit RISC Architecture, 62.5-ns Instruction Cycle Time
- Basic Clock Module Configurations
 - Internal Frequencies up to 16 MHz With One Calibrated Frequency
 - Internal Very Low Power Low-Frequency (LF) Oscillator
 - 32-kHz Crystal
 - External Digital Clock Source

- 16-Bit Timer_A With Two Capture/Compare Registers
- Universal Serial Interface (USI) Supporting SPI and I2C (See Table 1)
- Brownout Detector
- 10-Bit 200-ksps A/D Converter With Internal Reference, Sample-and-Hold, and Autoscan (See Table 1)
- Serial Onboard Programming, No External Programming Voltage Needed, Programmable Code Protection by Security Fuse
- On-Chip Emulation Logic With Spy-Bi-Wire Interface
- For Family Members Details, See Table 1
- Available in 14-Pin Plastic Small-Outline Thin Package (TSSOP) (PW), 14-Pin Plastic Dual Inline Package (PDIP) (N), and 16-Pin QFN Package (RSA)
- For Complete Module Descriptions, See the MSP430x2xx Family User's Guide (SLAU144)

DESCRIPTION

The Texas Instruments MSP430 family of ultra-low-power microcontrollers consists of several devices featuring different sets of peripherals targeted for various applications. The architecture, combined with five low-power modes, is optimized to achieve extended battery life in portable measurement applications. The device features a powerful 16-bit RISC CPU, 16-bit registers, and constant generators that contribute to maximum code efficiency. The digitally controlled oscillator (DCO) allows wake-up from low-power modes to active mode in less than 1 µs.

The MSP430G2x21/G2x31 series is an ultra-low-power mixed signal microcontroller with a built-in 16-bit timer and ten I/O pins. The MSP430G2x31 family members have a 10-bit A/D converter and built-in communication capability using synchronous protocols (SPI or I2C). For configuration details, see Table 1.

Typical applications include low-cost sensor systems that capture analog signals, convert them to digital values, and then process the data for display or for transmission to a host system.





Table 1. Available Options⁽¹⁾

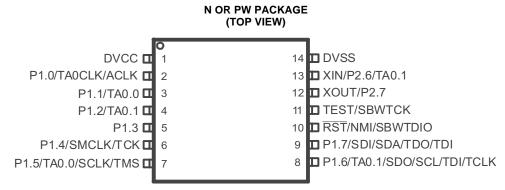
Device	BSL	EEM	Flash (KB)	RAM (B)	Timer_A	USI	ADC10 Channel	Clock	1/0	Package Type ⁽²⁾
MSP430G2231IRSA16 MSP430G2231IPW14 MSP430G2231IN14	-	1	2	128	1x TA2	1	8	LF, DCO, VLO	10	16-QFN 14-TSSOP 14-PDIP
MSP430G2221IRSA16 MSP430G2221IPW14 MSP430G2221IN14	-	1	2	128	1x TA2	1	-	LF, DCO, VLO	10	16-QFN 14-TSSOP 14-PDIP
MSP430G2131IRSA16 MSP430G2131IPW14 MSP430G2131IN14	-	1	1	128	1x TA2	1	8	LF, DCO, VLO	10	16-QFN 14-TSSOP 14-PDIP
MSP430G2121IRSA16 MSP430G2121IPW14 MSP430G2121IN14	-	1	1	128	1x TA2	1	-	LF, DCO, VLO	10	16-QFN 14-TSSOP 14-PDIP

⁽¹⁾ For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI web site at www.ti.com.

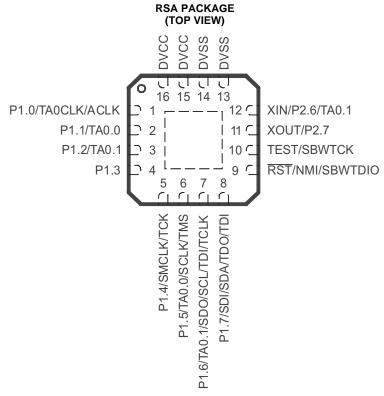
⁽²⁾ Package drawings, thermal data, and symbolization are available at www.ti.com/packaging.



Device Pinout, MSP430G2x21



NOTE: See port schematics in Application Information for detailed I/O information.



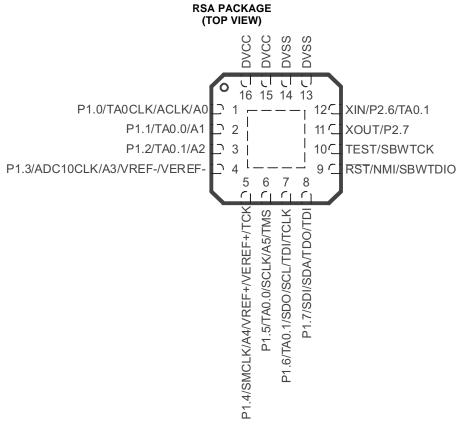
NOTE: See port schematics in Application Information for detailed I/O information.



Device Pinout, MSP430G2x31

N OR PW PACKAGE (TOP VIEW) DVCC 🗖 14 🗖 DVSS P1.0/TA0CLK/ACLK/A0 2 13 XIN/P2.6/TA0.1 12 **X**OUT/P2.7 P1.1/TA0.0/A1 3 11 TEST/SBWTCK P1.2/TA0.1/A2 10 RST/NMI/SBWTDIO P1.3/ADC10CLK/A3/VREF-/VEREF-5 P1.4/SMCLK/A4/VREF+/VEREF+/TCK □ P1.7/A7/SDI/SDA/TDO/TDI 6 P1.6/TA0.1/A6/SDO/SCL/TDI/TCLK P1.5/TA0.0/A5/SCLK/TMS

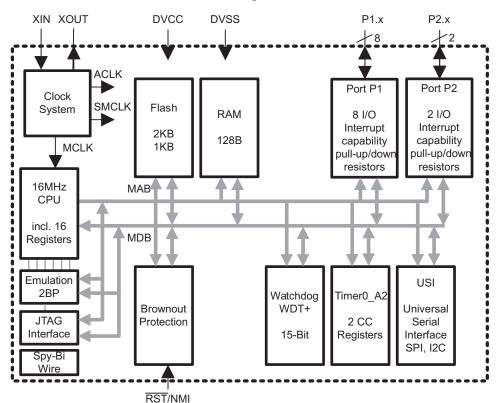
NOTE: See port schematics in Application Information for detailed I/O information.



NOTE: See port schematics in Application Information for detailed I/O information.



Functional Block Diagram, MSP430G2x21



Functional Block Diagram, MSP430G2x31

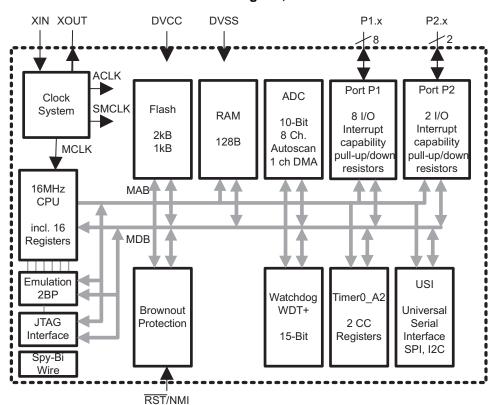




Table 2. Terminal Functions

TERM	INAL			
	N	0.	I/O	DESCRIPTION
NAME	N, PW	RSA	y	
P1.0/ TA0CLK/ ACLK/ A0	2	1	I/O	General-purpose digital I/O pin Timer0_A, clock signal TACLK input ACLK signal output ADC10 analog input A0 ⁽¹⁾
P1.1/ TA0.0/ A1	3	2	I/O	General-purpose digital I/O pin Timer0_A, capture: CCI0A input, compare: Out0 output ADC10 analog input A1 ⁽¹⁾
P1.2/ TA0.1/ A2	4	3	I/O	General-purpose digital I/O pin Timer0_A, capture: CCl1A input, compare: Out1 output ADC10 analog input A2 ⁽¹⁾
P1.3/ ADC10CLK/ A3/ VREF-/VEREF	5	4	I/O	General-purpose digital I/O pin ADC10, conversion clock output ⁽¹⁾ ADC10 analog input A3 ⁽¹⁾ ADC10 negative reference voltage ⁽¹⁾
P1.4/ SMCLK/ A4/ VREF+/VEREF+/ TCK	6	5	I/O	General-purpose digital I/O pin SMCLK signal output ADC10 analog input A4 ⁽¹⁾ ADC10 positive reference voltage ⁽¹⁾ JTAG test clock, input terminal for device programming and test
P1.5/ TA0.0/ A5/ SCLK/ TMS	7	6	I/O	General-purpose digital I/O pin Timer0_A, compare: Out0 output ADC10 analog input A5 ⁽¹⁾ USI: clock input in I2C mode; clock input/output in SPI mode JTAG test mode select, input terminal for device programming and test
P1.6/ TA0.1/ A6/ SDO/ SCL/ TDI/TCLK	8	7	I/O	General-purpose digital I/O pin Timer0_A, capture: CCI1A input, compare: Out1 output ADC10 analog input A6 ⁽¹⁾ USI: Data output in SPI mode USI: I2C clock in I2C mode JTAG test data input or test clock input during programming and test
P1.7/ A7/ SDI/ SDA/ TDO/TDI ⁽²⁾	9	8	I/O	General-purpose digital I/O pin ADC10 analog input A7 ⁽¹⁾ USI: Data input in SPI mode USI: I2C data in I2C mode JTAG test data output terminal or test data input during programming and test
XIN/ P2.6/ TA0.1	13	12	I/O	Input terminal of crystal oscillator General-purpose digital I/O pin Timer0_A, compare: Out1 output
XOUT/ P2.7	12	11	I/O	Output terminal of crystal oscillator ⁽³⁾ General-purpose digital I/O pin
RST/ NMI/ SBWTDIO	10	9	I	Reset Nonmaskable interrupt input Spy-Bi-Wire test data input/output during programming and test
TEST/ SBWTCK	11	10	I	Selects test mode for JTAG pins on Port 1. The device protection fuse is connected to TEST. Spy-Bi-Wire test clock input during programming and test
DVCC	1	15, 16	NA	Supply voltage
DVSS	14	13, 14	NA	Ground reference
QFN Pad	-	Pad	NA	QFN package pad connection to V _{SS} recommended.

⁽¹⁾ MSP430G2x31 only
(2) TDO or TDI is selected via JTAG instruction.
(3) If XOUT/P2.7 is used as an input, excess current will flow until P2SEL.7 is cleared. This is due to the oscillator output driver connection to this pad after reset.



SHORT-FORM DESCRIPTION

CPU

The MSP430 CPU has a 16-bit RISC architecture that is highly transparent to the application. All operations, other than program-flow instructions, are performed as register operations in conjunction with seven addressing modes for source operand and four addressing modes for destination operand.

The CPU is integrated with 16 registers that provide reduced instruction execution time. The register-to-register operation execution time is one cycle of the CPU clock.

Four of the registers, R0 to R3, are dedicated as program counter, stack pointer, status register, and constant generator, respectively. The remaining registers are general-purpose registers.

Peripherals are connected to the CPU using data, address, and control buses, and can be handled with all instructions.

The instruction set consists of the original 51 instructions with three formats and seven address modes and additional instructions for the expanded address range. Each instruction can operate on word and byte data.

Instruction Set

The instruction set consists of 51 instructions with three formats and seven address modes. Each instruction can operate on word and byte data. Table 3 shows examples of the three types of instruction formats; Table 4 shows the address modes.

Program Counter	PC/R0
Stack Pointer	SP/R1
Status Register	SR/CG1/R2
Constant Generator	CG2/R3
General-Purpose Register	R4
General-Purpose Register	R5
General-Purpose Register	R6
General-Purpose Register	R7
General-Purpose Register	R8
General-Purpose Register	R9
General-Purpose Register	R10
General-Purpose Register	R11
General-Purpose Register	R12
General-Purpose Register	R13
General-Purpose Register	R14
General-Purpose Register	R15

Table 3. Instruction Word Formats

INSTRUCTION FORMAT	SYNTAX	OPERATION
Dual operands, source-destination	ADD R4,R5	R4 + R5> R5
Single operands, destination only	CALL R8	PC>(TOS), R8> PC
Relative jump, un/conditional	JNE	Jump-on-equal bit = 0

Table 4. Address Mode Descriptions⁽¹⁾

ADDRESS MODE	S	D	SYNTAX	EXAMPLE	OPERATION
Register	✓	✓	MOV Rs,Rd	MOV R10,R11	R10> R11
Indexed	✓	✓	MOV X(Rn),Y(Rm)	MOV 2(R5),6(R6)	M(2+R5)> M(6+R6)
Symbolic (PC relative)	✓	✓	MOV EDE,TONI		M(EDE)> M(TONI)
Absolute	1	✓	MOV &MEM,&TCDAT		M(MEM)> M(TCDAT)
Indirect	✓		MOV @Rn,Y(Rm)	MOV @R10,Tab(R6)	M(R10)> M(Tab+R6)
Indirect autoincrement	✓		MOV @Rn+,Rm	MOV @R10+,R11	M(R10)> R11 R10 + 2> R10
Immediate	✓		MOV #X,TONI	MOV #45,TONI	#45> M(TONI)

(1) S = source, D = destination



Operating Modes

The MSP430 has one active mode and five software selectable low-power modes of operation. An interrupt event can wake up the device from any of the low-power modes, service the request, and restore back to the low-power mode on return from the interrupt program.

The following six operating modes can be configured by software:

- Active mode (AM)
 - All clocks are active
- Low-power mode 0 (LPM0)
 - CPU is disabled
 - ACLK and SMCLK remain active, MCLK is disabled
- Low-power mode 1 (LPM1)
 - CPU is disabled
 - ACLK and SMCLK remain active, MCLK is disabled
 - DCO's dc generator is disabled if DCO not used in active mode
- Low-power mode 2 (LPM2)
 - CPU is disabled
 - MCLK and SMCLK are disabled
 - DCO's dc generator remains enabled
 - ACLK remains active
- Low-power mode 3 (LPM3)
 - CPU is disabled
 - MCLK and SMCLK are disabled
 - DCO's dc generator is disabled
 - ACLK remains active
- Low-power mode 4 (LPM4)
 - CPU is disabled
 - ACLK is disabled
 - MCLK and SMCLK are disabled
 - DCO's dc generator is disabled
 - Crystal oscillator is stopped



Interrupt Vector Addresses

The interrupt vectors and the power-up starting address are located in the address range 0FFFFh to 0FFC0h. The vector contains the 16-bit address of the appropriate interrupt handler instruction sequence.

If the reset vector (located at address 0FFFEh) contains 0FFFFh (for example, flash is not programmed) the CPU goes into LPM4 immediately after power-up.

Table 5. Interrupt Sources, Flags, and Vectors

INTERRUPT SOURCE	INTERRUPT FLAG	SYSTEM INTERRUPT	WORD ADDRESS	PRIORITY
Power-Up External Reset Watchdog Timer+ Flash key violation PC out-of-range ⁽¹⁾	PORIFG RSTIFG WDTIFG KEYV ⁽²⁾	Reset	0FFFEh	31, highest
NMI Oscillator fault Flash memory access violation	NMIIFG OFIFG ACCVIFG ⁽²⁾⁽³⁾	(non)-maskable (non)-maskable (non)-maskable	0FFFCh	30
			0FFFAh	29
			0FFF8h	28
			0FFF6h	27
Watchdog Timer+	WDTIFG	maskable	0FFF4h	26
Timer_A2	TACCR0 CCIFG ⁽⁴⁾	maskable	0FFF2h	25
Timer_A2	TACCR1 CCIFG, TAIFG (2)(4)	maskable	0FFF0h	24
			0FFEEh	23
			0FFECh	22
ADC10 ⁽⁵⁾	ADC10IFG ⁽⁴⁾⁽⁵⁾	maskable	0FFEAh	21
USI	USIIFG, USISTTIFG ⁽²⁾⁽⁴⁾	maskable	0FFE8h	20
I/O Port P2 (two flags)	P2IFG.6 to P2IFG.7 ⁽²⁾⁽⁴⁾	maskable	0FFE6h	19
I/O Port P1 (eight flags)	P1IFG.0 to P1IFG.7 ⁽²⁾⁽⁴⁾	maskable	0FFE4h	18
			0FFE2h	17
			0FFE0h	16
See ⁽⁶⁾			0FFDEh to 0FFC0h	15 to 0, lowest

⁽¹⁾ A reset is generated if the CPU tries to fetch instructions from within the module register memory address range (0h to 01FFh) or from within unused address ranges.

⁽²⁾ Multiple source flags

^{(3) (}non)-maskable: the individual interrupt-enable bit can disable an interrupt event, but the general interrupt enable cannot.

⁽⁴⁾ Interrupt flags are located in the module.

⁽⁵⁾ MSP430G2x31 only

⁽⁶⁾ The interrupt vectors at addresses 0FFDEh to 0FFC0h are not used in this device and can be used for regular program code if necessary.



Special Function Registers (SFRs)

Most interrupt and module enable bits are collected into the lowest address space. Special function register bits not allocated to a functional purpose are not physically present in the device. Simple software access is provided with this arrangement.

Legend Bit can be read and written. rw:

> rw-0,1: Bit can be read and written. It is reset or set by PUC. rw-(0,1): Bit can be read and written. It is reset or set by POR.

SFR bit is not present in device.

Table 6. Interrupt Enable Register 1 and 2

Address	7	6	5	4	3	2	1	0	
00h			ACCVIE	NMIIE			OFIE	WDTIE	
			rw-0	rw-0			rw-0	rw-0	
WDTIE	Watchdog Timer interrupt enable. Inactive if watchdog mode is selected. Active if Watchdog Timer is configured in interval timer mode.								
OFIE	Oscillator	fault interrupt e	nable						
NMIIE	(Non)mas	skable interrupt	enable						
ACCVIE	Flash acc	cess violation int	terrupt enable						
Address	7	6	5	4	3	2	1	0	
01h									

Table 7. Interrupt Flag Register 1 and 2

Address	7	6	5	4	3	2	1	0
02h				NMIIFG	RSTIFG	PORIFG	OFIFG	WDTIFG
				rw-0	rw-(0)	rw-(1)	rw-1	rw-(0)

WDTIFG Set on watchdog timer overflow (in watchdog mode) or security key violation.

Reset on V_{CC} power-on or a reset condition at the RST/NMI pin in reset mode.

OFIFG Flag set on oscillator fault.

Power-On Reset interrupt flag. Set on V_{CC} power-up. **PORIFG**

External reset interrupt flag. Set on a reset condition at RST/NMI pin in reset mode. Reset on V_{CC} power-up. **RSTIFG**

NMIIFG Set via RST/NMI pin

Address	7	6	5	4	3	2	1	0
03h								



Memory Organization

Table 8. Memory Organization

		MSP430G2021 MSP430G2031	MSP430G2121 MSP430G2131	MSP430G2221 MSP430G2231
Memory	Size	512B	1kB	2kB
Main: interrupt vector	Flash	0xFFFF to 0xFFC0	0xFFFF to 0xFFC0	0xFFFF to 0xFFC0
Main: code memory	Flash	0xFFFF to 0xFE00	0xFFFF to 0xFC00	0xFFFF to 0xF800
Information memory	Size	256 Byte	256 Byte	256 Byte
	Flash	010FFh to 01000h	010FFh to 01000h	010FFh to 01000h
RAM	Size	128B 027Fh to 0200h	128B 027Fh to 0200h	128B 027Fh to 0200h
Peripherals	16-bit	01FFh to 0100h	01FFh to 0100h	01FFh to 0100h
	8-bit	0FFh to 010h	0FFh to 010h	0FFh to 010h
	8-bit SFR	0Fh to 00h	0Fh to 00h	0Fh to 00h

Flash Memory

The flash memory can be programmed via the Spy-Bi-Wire/JTAG port or in-system by the CPU. The CPU can perform single-byte and single-word writes to the flash memory. Features of the flash memory include:

- Flash memory has n segments of main memory and four segments of information memory (A to D) of 64 bytes each. Each segment in main memory is 512 bytes in size.
- Segments 0 to n may be erased in one step, or each segment may be individually erased.
- Segments A to D can be erased individually or as a group with segments 0 to n. Segments A to D are also called *information memory*.
- Segment A contains calibration data. After reset segment A is protected against programming and erasing. It
 can be unlocked but care should be taken not to erase this segment if the device-specific calibration data is
 required.



Peripherals

Peripherals are connected to the CPU through data, address, and control buses and can be handled using all instructions. For complete module descriptions, see the MSP430x2xx Family User's Guide (SLAU144).

Oscillator and System Clock

The clock system is supported by the basic clock module that includes support for a 32768-Hz watch crystal oscillator, an internal very-low-power low-frequency oscillator and an internal digitally controlled oscillator (DCO). The basic clock module is designed to meet the requirements of both low system cost and low power consumption. The internal DCO provides a fast turn-on clock source and stabilizes in less than 1µs. The basic clock module provides the following clock signals:

- Auxiliary clock (ACLK), sourced either from a 32768-Hz watch crystal or the internal LF oscillator.
- · Main clock (MCLK), the system clock used by the CPU.
- Sub-Main clock (SMCLK), the sub-system clock used by the peripheral modules.

Table 9. DCO Calibration Data (Provided From Factory In Flash Information Memory Segment A)

DCO FREQUENCY	CALIBRATION REGISTER CALBC1_1MHZ CALDCO_1MHZ	SIZE	ADDRESS	
1 MHz	CALBC1_1MHZ	byte	010FFh	
I IVITZ	CALDCO_1MHZ	byte	010FEh	

Brownout

The brownout circuit is implemented to provide the proper internal reset signal to the device during power on and power off.

Digital I/O

There is one 8-bit I/O port implemented—port P1—and two bits of I/O port P2:

- All individual I/O bits are independently programmable.
- Any combination of input, output, and interrupt condition is possible.
- Edge-selectable interrupt input capability for all the eight bits of port P1 and the two bits of port P2.
- Read/write access to port-control registers is supported by all instructions.
- Each I/O has an individually programmable pull-up/pull-down resistor.

WDT+ Watchdog Timer

The primary function of the watchdog timer (WDT+) module is to perform a controlled system restart after a software problem occurs. If the selected time interval expires, a system reset is generated. If the watchdog function is not needed in an application, the module can be disabled or configured as an interval timer and can generate interrupts at selected time intervals.



Timer A2

Timer_A2 is a 16-bit timer/counter with two capture/compare registers. Timer_A2 can support multiple capture/compares, PWM outputs, and interval timing. Timer_A2 also has extensive interrupt capabilities. Interrupts may be generated from the counter on overflow conditions and from each of the capture/compare registers.

Table 10. Timer_A2 Signal Connections – Device With ADC10

INPUT PIN	NUMBER	DEVICE INPUT	MODULE	MODULE	MODULE	OUTPUT PI	N NUMBER
PW, N	RSA	SIGNAL	INPUT NAME	BLOCK	OUTPUT SIGNAL	PW, N	RSA
2 - P1.0	1 - P1.0	TACLK	TACLK				
		ACLK	ACLK	Timer	NA		
		SMCLK	SMCLK				
2 - P1.0	1 - P1.0	TACLK	INCLK				
3 - P1.1	2 - P1.1	TA0	CCI0A			3 - P1.1	2 - P1.1
		ACLK (internal)	CCI0B	CCDO	TA0	7 - P1.5	6 - P1.5
		VSS	GND	CCR0	TA0		
		VCC	VCC				
4 - P1.2	3 - P1.2	TA1	CCI1A			4 - P1.2	3 - P1.2
8 - P1.6	7 - P1.6	TA1	CCI1B	CCD4	TA1	8 - P1.6	7 - P1.6
		VSS	GND	CCR1		13 - P2.6	12 - P2.6
		VCC	VCC				

USI

The universal serial interface (USI) module is used for serial data communication and provides the basic hardware for synchronous communication protocols like SPI and I2C.

ADC10 (MSP430G2x31 only)

The ADC10 module supports fast, 10-bit analog-to-digital conversions. The module implements a 10-bit SAR core, sample select control, reference generator and data transfer controller, or DTC, for automatic conversion result handling, allowing ADC samples to be converted and stored without any CPU intervention.



Peripheral File Map

Table 11. Peripherals With Word Access

MODULE	REGISTER DESCRIPTION	REGISTER NAME	OFFSET
ADC10 (MSP430G2x31 only)	ADC data transfer start address	ADC10SA	1BCh
	ADC control 0	ADC10CTL0	01B0h
	ADC control 1	ADC10CTL0	01B2h
	ADC memory	ADC10MEM	01B4h
Timer_A	Capture/compare register	TACCR1	0174h
	Capture/compare register	TACCR0	0172h
	Timer_A register	TAR	0170h
	Capture/compare control	TACCTL1	0164h
	Capture/compare control	TACCTL0	0162h
	Timer_A control	TACTL	0160h
	Timer_A interrupt vector	TAIV	012Eh
Flash Memory	Flash control 3	FCTL3	012Ch
	Flash control 2	FCTL2	012Ah
	Flash control 1	FCTL1	0128h
Watchdog Timer+	Watchdog/timer control	WDTCTL	0120h

Table 12. Peripherals With Byte Access

MODULE	REGISTER DESCRIPTION	REGISTER NAME	OFFSET
ADC10 (MSP430G2x31 only)	ADC analog enable	ADC10AE0	04Ah
	ADC data transfer control 1	ADC10DTC1	049h
	ADC data transfer control 0	ADC10DTC0	048h
USI	USI control 0	USICTL0	078h
	USI control 1	USICTL1	079h
	USI clock control	USICKCTL	07Ah
	USI bit counter	USICNT	07Bh
	USI shift register	USISR	07Ch
Basic Clock System+	Basic clock system control 3	BCSCTL3	053h
	Basic clock system control 2	BCSCTL2	058h
	Basic clock system control 1	BCSCTL1	057h
	DCO clock frequency control	DCOCTL	056h
Port P2	Port P2 resistor enable	P2REN	02Fh
	Port P2 selection	P2SEL	02Eh
	Port P2 interrupt enable	P2IE	02Dh
	Port P2 interrupt edge select	P2IES	02Ch
	Port P2 interrupt flag	P2IFG	02Bh
	Port P2 direction	P2DIR	02Ah
	Port P2 output	P2OUT	029h
	Port P2 input	P2IN	028h



Table 12. Peripherals With Byte Access (continued)

MODULE	REGISTER DESCRIPTION	REGISTER NAME	OFFSET
Port P1	Port P1 resistor enable	P1REN	027h
	Port P1 selection	P1SEL	026h
	Port P1 interrupt enable	P1IE	025h
	Port P1 interrupt edge select	P1IES	024h
	Port P1 interrupt flag	P1IFG	023h
	Port P1 direction	P1DIR	022h
	Port P1 output	P1OUT	021h
	Port P1 input	P1IN	020h
Special Function	SFR interrupt flag 2	IFG2	003h
	SFR interrupt flag 1	IFG1	002h
	SFR interrupt enable 2	IE2	001h
	SFR interrupt enable 1	IE1	000h



Absolute Maximum Ratings(1)

Voltage applied at V _{CC} to V _{SS}		–0.3 V to 4.1 V
Voltage applied to any pin ⁽²⁾		-0.3 V to V _{CC} + 0.3 V
Diode current at any device pin		±2 mA
Ct t T (3)	Unprogrammed device	-55°C to 150°C
Storage temperature range, T _{stg} ⁽³⁾	Programmed device	-55°C to 150°C

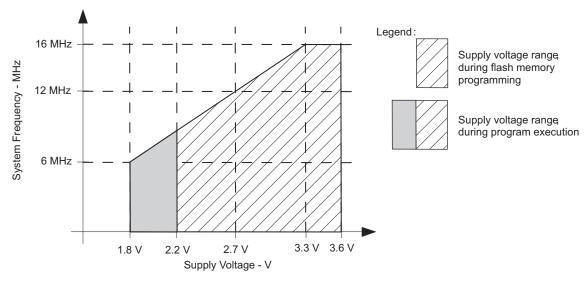
- (1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltages referenced to V_{SS}. The JTAG fuse-blow voltage, V_{FB}, is allowed to exceed the absolute maximum rating. The voltage is applied to the TEST pin when blowing the JTAG fuse.
- (3) Higher temperature may be applied during board soldering according to the current JEDEC J-STD-020 specification with peak reflow temperatures not higher than classified on the device label on the shipping boxes or reels.

Recommended Operating Conditions

Typical values are specified at $V_{CC} = 3.3 \text{ V}$ and $T_A = 25^{\circ}\text{C}$ (unless otherwise noted)

			MIN	NOM	MAX	UNIT
V	Cupply veltage	During program execution	1.8		3.6	V
V _{CC}	Supply voltage	During flash programming	2.2		3.6	V
V _{SS}	Supply voltage			0		V
T _A	Operating free-air temperature	I version	-40		85	°C
		$V_{CC} = 1.8 \text{ V},$ Duty cycle = 50% ± 10%	dc		6	
f _{SYSTEM}	Processor frequency (maximum MCLK frequency) ⁽¹⁾⁽²⁾	$V_{CC} = 2.7 \text{ V},$ Duty cycle = 50% ± 10%	dc		12	MHz
		$V_{CC} = 3.3 \text{ V},$ Duty cycle = 50% ± 10%	dc		16	

- (1) The MSP430 CPU is clocked directly with MCLK. Both the high and low phase of MCLK must not exceed the pulse width of the specified maximum frequency.
- (2) Modules might have a different maximum input clock specification. See the specification of the respective module in this data sheet.



Note: Minimum processor frequency is defined by system clock. Flash program or erase operations require a minimum V_{CC} of 2.2 V.

Figure 1. Safe Operating Area



Electrical Characteristics

Active Mode Supply Current Into V_{CC} Excluding External Current

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (1)(2)

PA	RAMETER	TEST CONDITIONS	T _A	V _{cc}	MIN	TYP	MAX	UNIT
		$f_{DCO} = f_{MCLK} = f_{SMCLK} = 1 \text{ MHz},$		2.2 V		220		
	Active mode (AM) current (1 MHz)	f _{ACLK} = 32768 Hz, Program executes in flash, BCSCTL1 = CALBC1_1MHZ, DCOCTL = CALDCO_1MHZ, CPUOFF = 0, SCG0 = 0, SCG1 = 0, OSCOFF = 0		3 V		300	370	μА

- All inputs are tied to 0 V or to V_{CC} . Outputs do not source or sink any current. The currents are characterized with a Micro Crystal CC4V-T1A SMD crystal with a load capacitance of 9 pF. The internal and external load capacitance is chosen to closely match the required 9 pF.

Typical Characteristics – Active Mode Supply Current (Into V_{CC})

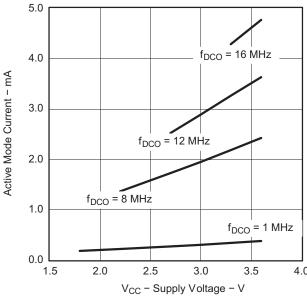


Figure 2. Active Mode Current vs V_{CC} , $T_A = 25$ °C

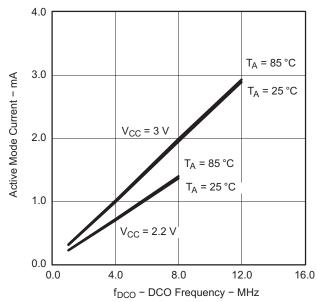


Figure 3. Active Mode Current vs DCO Frequency



Low-Power Mode Supply Currents (Into V_{CC}) Excluding External Current

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (1) (2)

P	ARAMETER	TEST CONDITIONS	T _A	V _{CC}	MIN	TYP	MAX	UNIT
I _{LPM0,1MHz}	Low-power mode 0 (LPM0) current ⁽³⁾	$\begin{split} &f_{\text{MCLK}} = 0 \text{ MHz,} \\ &f_{\text{SMCLK}} = f_{\text{DCO}} = 1 \text{ MHz,} \\ &f_{\text{ACLK}} = 32768 \text{ Hz,} \\ &\text{BCSCTL1} = \text{CALBC1_1MHZ,} \\ &\text{DCOCTL} = \text{CALDCO_1MHZ,} \\ &\text{CPUOFF} = 1, \text{SCG0} = 0, \text{SCG1} = 0, \\ &\text{OSCOFF} = 0 \end{split}$	25°C	2.2 V		65		μΑ
I _{LPM2}	Low-power mode 2 (LPM2) current ⁽⁴⁾	$\begin{split} &f_{\text{MCLK}} = f_{\text{SMCLK}} = 0 \text{ MHz}, \\ &f_{\text{DCO}} = 1 \text{ MHz}, \\ &f_{\text{ACLK}} = 32768 \text{ Hz}, \\ &\text{BCSCTL1} = \text{CALBC1_1MHZ}, \\ &\text{DCOCTL} = \text{CALDCO_1MHZ}, \\ &\text{CPUOFF} = 1, \text{SCG0} = 0, \text{SCG1} = 1, \\ &\text{OSCOFF} = 0 \end{split}$	25°C	2.2 V		22		μΑ
I _{LPM3,LFXT1}	Low-power mode 3 (LPM3) current ⁽⁴⁾	$ \begin{aligned} f_{DCO} &= f_{MCLK} = f_{SMCLK} = 0 \text{ MHz}, \\ f_{ACLK} &= 32768 \text{ Hz}, \\ CPUOFF &= 1, SCG0 = 1, SCG1 = 1, \\ OSCOFF &= 0 \end{aligned} $	25°C	2.2 V		0.7	1.5	μΑ
I _{LPM3,VLO}	Low-power mode 3 current, (LPM3) ⁽⁴⁾	$ \begin{aligned} f_{DCO} &= f_{MCLK} = f_{SMCLK} = 0 \text{ MHz}, \\ f_{ACLK} &\text{from internal LF oscillator (VLO),} \\ CPUOFF &= 1, SCG0 = 1, SCG1 = 1, \\ OSCOFF &= 0 \end{aligned} $	25°C	2.2 V		0.5	0.7	μΑ
		$f_{DCO} = f_{MCLK} = f_{SMCLK} = 0 \text{ MHz},$	25°C	2.2 V		0.1	0.5	μΑ
I _{LPM4}	Low-power mode 4 (LPM4) current ⁽⁵⁾	f _{ACLK} = 0 Hz, CPUOFF = 1, SCG0 = 1, SCG1 = 1, OSCOFF = 1	85°C	2.2 V		0.8	1.5	μΑ

- (1) All inputs are tied to 0 V or to V_{CC}. Outputs do not source or sink any current.
- (2) The currents are characterized with a Micro Crystal CC4V-T1A SMD crystal with a load capacitance of 9 pF.
- (3) Current for brownout and WDT clocked by SMCLK included.
- (4) Current for brownout and WDT clocked by ACLK included.
- (5) Current for brownout included.

Typical Characteristics Low-Power Mode Supply Currents

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

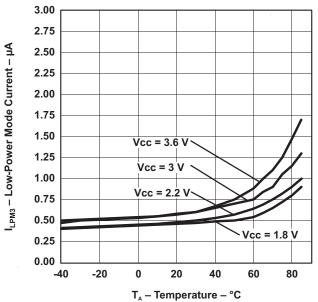


Figure 4. LPM3 Current vs Temperature

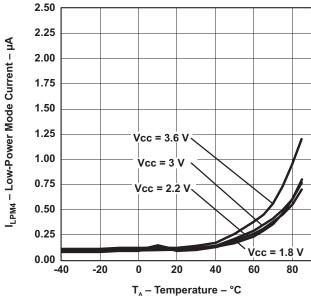


Figure 5. LPM4 Current vs Temperature



Schmitt-Trigger Inputs – Ports Px

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN	TYP	MAX	UNIT
\/	Desitive going input threshold valtage			0.45 V _{CC}		0.75 V _{CC}	V
V_{IT+}	Positive-going input threshold voltage		3 V	1.35		2.25	V
.,	No matical parisms in part throughout a salt and			0.25 V _{CC}		0.55 V _{CC}	
V_{IT-}	Negative-going input threshold voltage		3 V	0.75		1.65	V
V_{hys}	Input voltage hysteresis (V _{IT+} – V _{IT-})		3 V	0.3		1	V
R _{Pull}	Pullup/pulldown resistor	For pullup: V _{IN} = V _{SS} For pulldown: V _{IN} = V _{CC}	3 V	20	35	50	kΩ
Cı	Input capacitance	$V_{IN} = V_{SS}$ or V_{CC}			5		pF

Leakage Current - Ports Px

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN MAX	UNIT
I _{lkg(Px.y)}	High-impedance leakage current	(1) (2)	3 V	±50	nΑ

- The leakage current is measured with V_{SS} or V_{CC} applied to the corresponding pin(s), unless otherwise noted. The leakage of the digital port pins is measured individually. The port pin is selected for input and the pullup/pulldown resistor is disabled.

Outputs - Ports Px

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
V_{OH}	High-level output voltage	$I_{(OHmax)} = -6 \text{ mA}^{(1)}$	3 V	\	/ _{CC} – 0.3		V
V_{OL}	Low-level output voltage	$I_{(OLmax)} = 6 \text{ mA}^{(1)}$	3 V	'	√ _{SS} + 0.3		V

⁽¹⁾ The maximum total current, I_(OHmax), and I_(OLmax), for all outputs combined should not exceed ±48 mA to hold the maximum voltage drop

Output Frequency – Ports Px

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

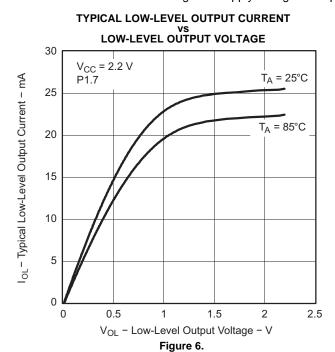
	PARAMETER	TEST CONDITIONS	v_{cc}	MIN	TYP	MAX	UNIT
f _{Px.y}	Port output frequency (with load)	Px.y, $C_L = 20 \text{ pF}$, $R_L = 1 \text{ k}\Omega^{(1)}$ (2)	3 V		12		MHz
f _{Port_CLK}	Clock output frequency	$Px.y, C_L = 20 pF^{(2)}$	3 V		16		MHz

- A resistive divider with 2 \times 0.5 k Ω between V_{CC} and V_{SS} is used as load. The output is connected to the center tap of the divider. The output voltage reaches at least 10% and 90% V_{CC} at the specified toggle frequency.



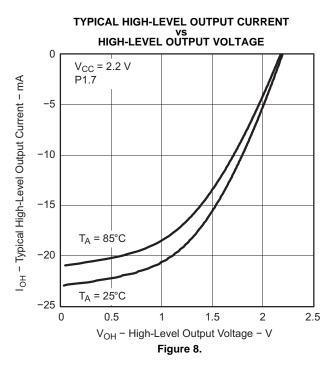
Typical Characteristics – Outputs

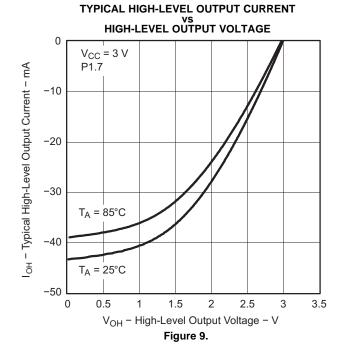
over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)



TYPICAL LOW-LEVEL OUTPUT CURRENT LOW-LEVEL OUTPUT VOLTAGE 50 V_{CC} = 3 V P1.7 $T_A = 25^{\circ}C$ IoL - Typical Low-Level Output Current - mA 40 $T_A = 85^{\circ}C$ 30 20 10 0 0.5 3.5 0 1.5 V_{OL} - Low-Level Output Voltage - V

Figure 7.







POR, BOR (1)(2)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN TYP	MAX	UNIT
V _{CC(start)}	See Figure 10	dV _{CC} /dt ≤ 3 V/s		$0.7 \times V_{(B_IT-)}$		V
$V_{(B_IT-)}$	See Figure 10 through Figure 12	dV _{CC} /dt ≤ 3 V/s		1.35		V
V _{hys(B_IT-)}	See Figure 10	dV _{CC} /dt ≤ 3 V/s		140		mV
t _{d(BOR)}	See Figure 10				2000	μs
t _(reset)	Pulse duration needed at RST/NMI pin to accepted reset internally		2.2 V, 3 V	2		μs

- The current consumption of the brownout module is already included in the I_{CC} current consumption data. The voltage level V_(B | T-) +
- $V_{hys(B_{\perp}IT_{-})}$ is \leq 1.8 V. During power up, the CPU begins code execution following a period of $t_{d(BOR)}$ after $V_{CC} = V_{(B_{\perp}IT_{-})} + V_{hys(B_{\perp}IT_{-})}$. The default DCO settings must not be changed until $V_{CC} \geq V_{CC(min)}$, where $V_{CC(min)}$ is the minimum supply voltage for the desired operating frequency.

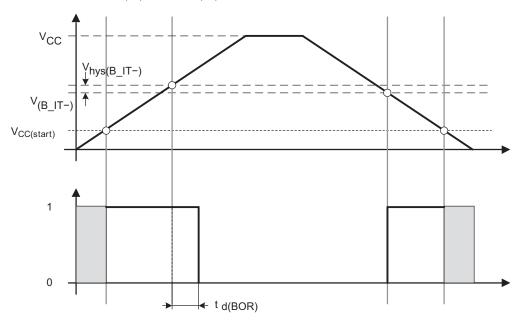


Figure 10. POR and BOR vs Supply Voltage



Typical Characteristics - POR and BOR

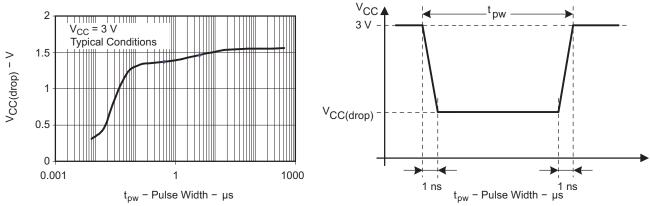


Figure 11. V_{CC(drop)} Level With a Square Voltage Drop to Generate a POR or BOR Signal

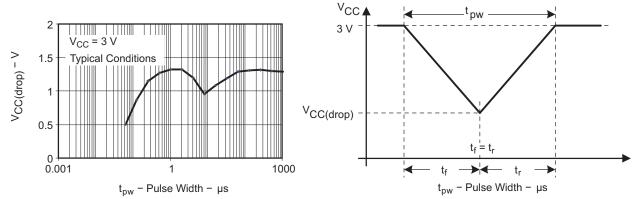


Figure 12. $V_{CC(drop)}$ Level With a Triangle Voltage Drop to Generate a POR or BOR Signal



Main DCO Characteristics

- All ranges selected by RSELx overlap with RSELx + 1: RSELx = 0 overlaps RSELx = 1, ... RSELx = 14 overlaps RSELx = 15.
- DCO control bits DCOx have a step size as defined by parameter S_{DCO}.
- Modulation control bits MODx select how often f_{DCO(RSEL,DCO+1)} is used within the period of 32 DCOCLK cycles. The frequency f_{DCO(RSEL,DCO)} is used for the remaining cycles. The frequency is an average equal to:

$$f_{average} = \frac{32 \times f_{DCO(RSEL,DCO)} \times f_{DCO(RSEL,DCO+1)}}{MOD \times f_{DCO(RSEL,DCO)} + (32 - MOD) \times f_{DCO(RSEL,DCO+1)}}$$

DCO Frequency

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
		RSELx < 14		1.8		3.6	V
V_{CC}	Supply voltage	RSELx = 14		2.2		3.6	V
		RSELx = 15		3		3.6	V
f _{DCO(0,0)}	DCO frequency (0, 0)	RSELx = 0, $DCOx = 0$, $MODx = 0$	3 V	0.06		0.14	MHz
f _{DCO(0,3)}	DCO frequency (0, 3)	RSELx = 0, $DCOx = 3$, $MODx = 0$	3 V		0.12		MHz
f _{DCO(1,3)}	DCO frequency (1, 3)	RSELx = 1, $DCOx = 3$, $MODx = 0$	3 V		0.15		MHz
f _{DCO(2,3)}	DCO frequency (2, 3)	RSELx = 2, $DCOx = 3$, $MODx = 0$	3 V		0.21		MHz
f _{DCO(3,3)}	DCO frequency (3, 3)	RSELx = 3, $DCOx = 3$, $MODx = 0$	3 V		0.30		MHz
f _{DCO(4,3)}	DCO frequency (4, 3)	RSELx = 4, $DCOx = 3$, $MODx = 0$	3 V		0.41		MHz
f _{DCO(5,3)}	DCO frequency (5, 3)	RSELx = 5, $DCOx = 3$, $MODx = 0$	3 V		0.58		MHz
f _{DCO(6,3)}	DCO frequency (6, 3)	RSELx = 6, $DCOx = 3$, $MODx = 0$	3 V		0.80		MHz
f _{DCO(7,3)}	DCO frequency (7, 3)	RSELx = 7, $DCOx = 3$, $MODx = 0$	3 V	0.8		1.5	MHz
f _{DCO(8,3)}	DCO frequency (8, 3)	RSELx = 8, $DCOx = 3$, $MODx = 0$	3 V		1.6		MHz
f _{DCO(9,3)}	DCO frequency (9, 3)	RSELx = 9, $DCOx = 3$, $MODx = 0$	3 V		2.3		MHz
f _{DCO(10,3)}	DCO frequency (10, 3)	RSELx = 10, DCOx = 3, MODx = 0	3 V		3.4		MHz
f _{DCO(11,3)}	DCO frequency (11, 3)	RSELx = 11, DCOx = 3, MODx = 0	3 V		4.25		MHz
f _{DCO(12,3)}	DCO frequency (12, 3)	RSELx = 12, $DCOx = 3$, $MODx = 0$	3 V	4.3		7.3	MHz
f _{DCO(13,3)}	DCO frequency (13, 3)	RSELx = 13, $DCOx = 3$, $MODx = 0$	3 V		7.8		MHz
f _{DCO(14,3)}	DCO frequency (14, 3)	RSELx = 14, $DCOx = 3$, $MODx = 0$	3 V	8.6		13.9	MHz
f _{DCO(15,3)}	DCO frequency (15, 3)	RSELx = 15, DCOx = 3, MODx = 0	3 V		15.25		MHz
f _{DCO(15,7)}	DCO frequency (15, 7)	RSELx = 15, DCOx = 7, MODx = 0	3 V		21		MHz
S _{RSEL}	Frequency step between range RSEL and RSEL+1	$S_{RSEL} = f_{DCO(RSEL+1,DCO)}/f_{DCO(RSEL,DCO)}$	3 V		1.35		ratio
S _{DCO}	Frequency step between tap DCO and DCO+1	$S_{DCO} = f_{DCO(RSEL,DCO+1)}/f_{DCO(RSEL,DCO)}$	3 V		1.08		ratio
	Duty cycle	Measured at SMCLK output	3 V		50		%



Calibrated DCO Frequencies – Tolerance

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER	TEST CONDITIONS	T _A	V _{cc}	MIN	TYP	MAX	UNIT
1-MHz tolerance over temperature ⁽¹⁾	BCSCTL1= CALBC1_1MHz, DCOCTL = CALDCO_1MHz, calibrated at 30°C and 3 V	0°C to 85°C	3 V	-3	±0.5	+3	%
1-MHz tolerance over V _{CC}	BCSCTL1= CALBC1_1MHz, DCOCTL = CALDCO_1MHz, calibrated at 30°C and 3 V	30°C	1.8 V to 3.6 V	-3	±2	+3	%
1-MHz tolerance overall	BCSCTL1= CALBC1_1MHz, DCOCTL = CALDCO_1MHz, calibrated at 30°C and 3 V	-40°C to 85°C	1.8 V to 3.6 V	-6	±3	+6	%

⁽¹⁾ This is the frequency change from the measured frequency at 30°C over temperature.

Wake-Up From Lower-Power Modes (LPM3/4) - Electrical Characteristics

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
t _{DCO,LPM3/4}	DCO clock wake-up time from LPM3/4 ⁽¹⁾	BCSCTL1= CALBC1_1MHz, DCOCTL = CALDCO_1MHz	3 V		1.5		μs
t _{CPU,LPM3/4}	CPU wake-up time from LPM3/4 ⁽²⁾			1	1/f _{MCLK} +		

⁽¹⁾ The DCO clock wake-up time is measured from the edge of an external wake-up signal (for example, port interrupt) to the first clock edge observable externally on a clock pin (MCLK or SMCLK).

Typical Characteristics - DCO Clock Wake-Up Time From LPM3/4

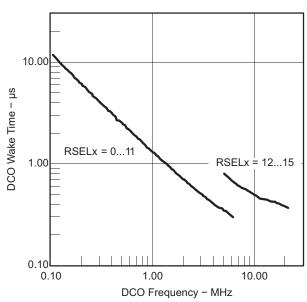


Figure 13. DCO Wake-Up Time From LPM3 vs DCO Frequency

⁽²⁾ Parameter applicable only if DCOCLK is used for MCLK.



Crystal Oscillator, XT1, Low-Frequency Mode⁽¹⁾

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
f _{LFXT1,LF}	LFXT1 oscillator crystal frequency, LF mode 0, 1	XTS = 0, LFXT1Sx = 0 or 1	1.8 V to 3.6 V		32768		Hz
f _{LFXT1,LF,logic}	LFXT1 oscillator logic level square wave input frequency, LF mode	XTS = 0, XCAPx = 0, LFXT1Sx = 3	1.8 V to 3.6 V	10000	32768	50000	Hz
04	Oscillation allowance for	$XTS = 0$, $LFXT1Sx = 0$, $f_{LFXT1,LF} = 32768$ Hz, $C_{L,eff} = 6$ pF			500		kΩ
OA _{LF}	LF crystals	$XTS = 0$, $LFXT1Sx = 0$, $f_{LFXT1,LF} = 32768$ Hz, $C_{L,eff} = 12$ pF			200		K12
		XTS = 0, $XCAPx = 0$			1		
0	Integrated effective load	XTS = 0, XCAPx = 1			5.5		"F
$C_{L,eff}$	capacitance, LF mode (2)	XTS = 0, $XCAPx = 2$			8.5		pF
		XTS = 0, $XCAPx = 3$			11		
	Duty cycle, LF mode	XTS = 0, Measured at P2.0/ACLK, $f_{LFXT1,LF}$ = 32768 Hz	2.2 V	30	50	70	%
f _{Fault,LF}	Oscillator fault frequency, LF mode ⁽³⁾	XTS = 0, XCAPx = 0, LFXT1Sx = 3 ⁽⁴⁾	2.2 V	10		10000	Hz

- (1) To improve EMI on the XT1 oscillator, the following guidelines should be observed.
 - (a) Keep the trace between the device and the crystal as short as possible.
 - (b) Design a good ground plane around the oscillator pins.
 - (c) Prevent crosstalk from other clock or data lines into oscillator pins XIN and XOUT.
 - (d) Avoid running PCB traces underneath or adjacent to the XIN and XOUT pins.
 - (e) Use assembly materials and praxis to avoid any parasitic load on the oscillator XIN and XOUT pins.
 - (f) If conformal coating is used, ensure that it does not induce capacitive/resistive leakage between the oscillator pins.
 - (g) Do not route the XOUT line to the JTAG header to support the serial programming adapter as shown in other documentation. This signal is no longer required for the serial programming adapter.
- (2) Includes parasitic bond and package capacitance (approximately 2 pF per pin).
 - Since the PCB adds additional capacitance, it is recommended to verify the correct load by measuring the ACLK frequency. For a correct setup, the effective load capacitance should always match the specification of the used crystal.
- (3) Frequencies below the MIN specification set the fault flag. Frequencies above the MAX specification do not set the fault flag. Frequencies in between might set the flag.
- (4) Measured with logic-level input frequency but also applies to operation with crystals.

Internal Very-Low-Power Low-Frequency Oscillator (VLO)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	T _A	V _{cc}	MIN	TYP	MAX	UNIT
f_{VLO}	VLO frequency	-40°C to 85°C	3 V	4	12	20	kHz
df_{VLO}/d_{T}	VLO frequency temperature drift	-40°C to 85°C	3 V		0.5		%/°C
df_{VLO}/dV_{CC}	VLO frequency supply voltage drift	25°C	1.8 V to 3.6 V		4		%/V

Timer A

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN TYP MAX	UNIT
f_{TA}	Timer_A input clock frequency	Internal: SMCLK, ACLK External: TACLK, INCLK Duty cycle = 50% ± 10%		f _{SYSTEM}	MHz
t _{TA,cap}	Timer_A capture timing	TA0, TA1	3 V	20	ns

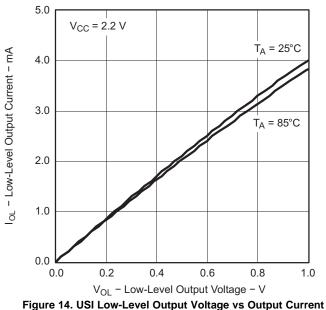


USI, Universal Serial Interface

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN	TYP	MAX	UNIT
f _{USI}	USI clock frequency	External: SCLK, Duty cycle = 50% ±10%, SPI slave mode		fsystem		MHz	
V _{OL,I2C}	Low-level output voltage on SDA and SCL	USI module in I2C mode, I _(OLmax) = 1.5 mA	3 V	V_{SS}		V _{SS} + 0.4	V

Typical Characteristics - USI Low-Level Output Voltage on SDA and SCL



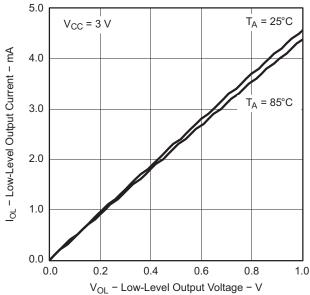


Figure 15. USI Low-Level Output Voltage vs Output Current



10-Bit ADC, Power Supply and Input Range Conditions (MSP430G2x31 Only)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)(1)

	PARAMETER	TEST CONDITIONS	T _A	V _{CC}	MIN	TYP I	ΛΑX	UNIT
V _{CC}	Analog supply voltage	V _{SS} = 0 V			2.2		3.6	V
V _{Ax}	Analog input voltage ⁽²⁾	All Ax terminals, Analog inputs selected in ADC10AE register		3 V	0		V _{CC}	V
I _{ADC10}	ADC10 supply current ⁽³⁾	f _{ADC10CLK} = 5.0 MHz, ADC10ON = 1, REFON = 0, ADC10SHT0 = 1, ADC10SHT1 = 0, ADC10DIV = 0	25°C	3 V		0.6		mA
	Reference supply current,	f _{ADC10CLK} = 5.0 MHz, ADC10ON = 0, REF2_5V = 0, REFON = 1, REFOUT = 0	2500	2.1/		0.25		A
I _{REF+}	Reference supply current, reference buffer disabled (4)	f _{ADC10CLK} = 5.0 MHz, ADC10ON = 0, REF2_5V = 1, REFON = 1, REFOUT = 0	25°C	3 V		0.25		mA
I _{REFB,0}	Reference buffer supply current with ADC10SR = $0^{(4)}$	f _{ADC10CLK} = 5.0 MHz, ADC10ON = 0, REFON = 1, REF2_5V = 0, REFOUT = 1, ADC10SR = 0	25°C	3 V		1.1		mA
I _{REFB,1}	Reference buffer supply current with ADC10SR = 1 (4)	f _{ADC10CLK} = 5.0 MHz, ADC10ON = 0, REFON = 1, REF2_5V = 0, REFOUT = 1, ADC10SR = 1	25°C	3 V		0.5		mA
Cı	Input capacitance	Only one terminal Ax can be selected at one time	25°C	3 V			27	pF
R_{l}	Input MUX ON resistance	$0 \text{ V} \leq \text{V}_{Ax} \leq \text{V}_{CC}$	25°C	3 V		1000		Ω

The leakage current is defined in the leakage current table with Px.y/Ax parameter.

The analog input voltage range must be within the selected reference voltage range V_{R+} to V_{R-} for valid conversion results.

The internal reference supply current is not included in current consumption parameter I_{ADC10} . The internal reference current is supplied via terminal V_{CC} . Consumption is independent of the ADC10ON control bit, unless a conversion is active. The REFON bit enables the built-in reference to settle before starting an A/D conversion.



10-Bit ADC, Built-In Voltage Reference (MSP430G2x31 Only)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN	TYP	MAX	UNIT
V	Positive built-in reference	I _{VREF+} ≤ 1 mA, REF2_5V = 0		2.2			V
$V_{CC,REF+}$	analog supply voltage range	I _{VREF+} ≤ 1 mA, REF2_5V = 1		2.9			V
V	Positive built-in reference	$I_{VREF+} \le I_{VREF+} max$, REF2_5V = 0	3 V	1.41	1.5	1.59	V
V_{REF+}	voltage	$I_{VREF+} \le I_{VREF+}$ max, REF2_5V = 1	3 V	2.35	2.5	2.65	V
I _{LD,VREF+}	Maximum VREF+ load current		3 V			±1	mA
	VDEE Lload regulation	I_{VREF+} = 500 μA ± 100 μA, Analog input voltage V_{Ax} ≉ 0.75 V, REF2_5V = 0	3 V			±2	LSB
	VREF+ load regulation	I_{VREF+} = 500 μA ± 100 μA, Analog input voltage V_{Ax} ≉ 1.25 V, REF2_5V = 1	3 V			±2	LOB
	V _{REF+} load regulation response time	I_{VREF+} = 100 μA \rightarrow 900 μA, V_{Ax} # 0.5 × VREF+, Error of conversion result ≤ 1 LSB, ADC10SR = 0	3 V			400	ns
C _{VREF+}	Maximum capacitance at pin VREF+	I _{VREF+} ≤ ±1 mA, REFON = 1, REFOUT = 1	3 V			100	pF
TC _{REF+}	Temperature coefficient	I_{VREF+} = const with 0 mA $\leq I_{VREF+} \leq$ 1 mA	3 V			±100	ppm/ °C
t _{REFON}	Settling time of internal reference voltage to 99.9% VREF	$I_{VREF+} = 0.5$ mA, REF2_5V = 0, REFON = 0 \rightarrow 1	3.6 V			30	μs
t _{REFBURST}	Settling time of reference buffer to 99.9% VREF	I _{VREF+} = 0.5 mA, REF2_5V = 1, REFON = 1, REFBURST = 1, ADC10SR = 0	3 V			2	μs



10-Bit ADC, External Reference⁽¹⁾ (MSP430G2x31 Only)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN	TYP MAX	UNIT
VEREF+	Positive external reference input	VEREF+ > VEREF-, SREF1 = 1, SREF0 = 0		1.4	V _{CC}	V
VEREF+	voltage range (2)	VEREF- \leq VEREF+ \leq V _{CC} - 0.15 V, SREF1 = 1, SREF0 = 1 (3)		1.4	3	V
VEREF-	Negative external reference input voltage range ⁽⁴⁾	VEREF+ > VEREF-		0	1.2	V
ΔVEREF	Differential external reference input voltage range, ΔVEREF = VEREF+ – VEREF-	VEREF+ > VEREF- (5)		1.4	V_{CC}	V
	Static input current into VEREF+	$0 \text{ V} \leq \text{VEREF+} \leq \text{V}_{\text{CC}},$ SREF1 = 1, SREF0 = 0	3 V		±1	
IVEREF+	Static input current into VEREF+	$0 \text{ V} \le \text{VEREF+} \le \text{V}_{\text{CC}} - 0.15 \text{ V} \le 3 \text{ V},$ SREF1 = 1, SREF0 = $1^{(3)}$	3 V		0	μΑ
I _{VEREF}	Static input current into VEREF-	0 V ≤ VEREF- ≤ V _{CC}	3 V		±1	μΑ

- (1) The external reference is used during conversion to charge and discharge the capacitance array. The input capacitance, C_I, is also the dynamic load for an external reference during conversion. The dynamic impedance of the reference supply should follow the recommendations on analog-source impedance to allow the charge to settle for 10-bit accuracy.
- (2) The accuracy limits the minimum positive external reference voltage. Lower reference voltage levels may be applied with reduced accuracy requirements.
- (3) Under this condition the external reference is internally buffered. The reference buffer is active and requires the reference buffer supply current I_{REFB}. The current consumption can be limited to the sample and conversion period with REBURST = 1.
- (4) The accuracy limits the maximum negative external reference voltage. Higher reference voltage levels may be applied with reduced accuracy requirements.
- (5) The accuracy limits the minimum external differential reference voltage. Lower differential reference voltage levels may be applied with reduced accuracy requirements.

10-Bit ADC, Timing Parameters (MSP430G2x31 Only)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITION	ONS	V _{CC}	MIN	TYP	MAX	UNIT
	ADC10 input clock	For specified performance of	ADC10SR = 0	3 V	0.45		6.3	MHz
†ADC10CLK	frequency	ADC10 linearity parameters	ADC10SR = 1	3 V	0.45		1.5	IVI□Z
f _{ADC10OSC}	ADC10 built-in oscillator frequency	ADC10DIVx = 0, ADC10SSELx $f_{ADC10CLK} = f_{ADC10OSC}$	= 0,	3 V	3.7		6.3	MHz
		ADC10 built-in oscillator, ADC10 f _{ADC10CLK} = f _{ADC10OSC}	OSSELx = 0,	3 V	2.06		3.51	
t _{CONVERT}	Conversion time	$f_{ADC10CLK}$ from ACLK, MCLK, or ADC10SSELx $\neq 0$	SMCLK,			13 × C10DIV : ADC10CLK		μs
t _{ADC10ON}	Turn-on settling time of the ADC	(1)					100	ns

The condition is that the error in a conversion started after t_{ADC100N} is less than ±0.5 LSB. The reference and input signal are already settled.

10-Bit ADC, Linearity Parameters (MSP430G2x31 Only)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
Eı	Integral linearity error		3 V			±1	LSB
E _D	Differential linearity error		3 V			±1	LSB
Eo	Offset error	Source impedance $R_S < 100 \Omega$	3 V			±1	LSB
E_G	Gain error		3 V		±1.1	±2	LSB
E _T	Total unadjusted error		3 V		±2	±5	LSB



10-Bit ADC, Temperature Sensor and Built-In V_{MID} (MSP430G2x31 Only)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN .	TYP	MAX	UNIT
I _{SENSOR}	Temperature sensor supply current ⁽¹⁾	REFON = 0, INCHx = 0Ah, $T_A = 25$ °C	3 V		60		μA
TC _{SENSOR}		ADC10ON = 1, INCHx = 0Ah (2)	3 V	;	3.55		mV/°C
t _{Sensor(sample)}	Sample time required if channel 10 is selected (3)	ADC10ON = 1, INCHx = 0Ah, Error of conversion result ≤ 1 LSB	3 V	30			μs
I _{VMID}	Current into divider at channel 11	ADC10ON = 1, INCHx = 0Bh	3 V			(4)	μΑ
V _{MID}	V _{CC} divider at channel 11	ADC10ON = 1, INCHx = 0Bh, $V_{MID} \neq 0.5 \times V_{CC}$	3 V		1.5		V
t _{VMID(sample)}	Sample time required if channel 11 is selected ⁽⁵⁾	ADC10ON = 1, INCHx = 0Bh, Error of conversion result ≤ 1 LSB	3 V	1220			ns

⁽¹⁾ The sensor current I_{SENSOR} is consumed if (ADC10ON = 1 and REFON = 1) or (ADC10ON = 1 and INCH = 0Ah and sample signal is high). When REFON = 1, I_{SENSOR} is included in I_{REF+}. When REFON = 0, I_{SENSOR} applies during conversion of the temperature sensor input (INCH = 0Ah).

(2) The following formula can be used to calculate the temperature sensor output voltage:

 $V_{Sensor,typ} = TC_{Sensor} (273 + T [^{\circ}C]) + V_{Offset,sensor} [mV] \text{ or}$

(4) No additional current is needed. The V_{MID} is used during sampling.

Flash Memory

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
V _{CC(PGM/ERASE)}	Program and erase supply voltage			2.2		3.6	V
f_{FTG}	Flash timing generator frequency			257		476	kHz
I _{PGM}	Supply current from V _{CC} during program		2.2 V, 3.6 V		1	5	mA
I _{ERASE}	Supply current from V _{CC} during erase		2.2 V, 3.6 V		1	7	mA
t _{CPT}	Cumulative program time ⁽¹⁾		2.2 V, 3.6 V			10	ms
t _{CMErase}	Cumulative mass erase time		2.2 V, 3.6 V	20			ms
	Program/erase endurance			10 ⁴	10 ⁵		cycles
t _{Retention}	Data retention duration	T _J = 25°C		100			years
t _{Word}	Word or byte program time	(2)			30		t _{FTG}
t _{Block, 0}	Block program time for first byte or word	(2)			25		t _{FTG}
t _{Block, 1-63}	Block program time for each additional byte or word	(2)			18		t _{FTG}
t _{Block, End}	Block program end-sequence wait time	(2)			6		t _{FTG}
t _{Mass Erase}	Mass erase time	(2)			10593		t _{FTG}
t _{Seg Erase}	Segment erase time	(2)			4819		t _{FTG}

⁽¹⁾ The cumulative program time must not be exceeded when writing to a 64-byte flash block. This parameter applies to all programming methods: individual word/byte write and block write modes.

(2) These values are hardwired into the Flash Controller's state machine (t_{FTG} = 1/f_{FTG}).

 $V_{Sensor,typ} = TC_{Sensor} T [^{\circ}C] + V_{Sensor} (T_A = 0^{\circ}C) [^{m}V]$ The typical equivalent impedance of the sensor is 51 k Ω . The sample time required includes the sensor-on time $t_{SENSOR(on)}$.

⁽⁵⁾ The on-time t_{VMID(on)} is included in the sampling time t_{VMID(sample)}; no additional on time is needed.



RAM

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN MAX	UNIT
V _(RAMh)	RAM retention supply voltage (1)	CPU halted	1.6	V

⁽¹⁾ This parameter defines the minimum supply voltage V_{CC} when the data in RAM remains unchanged. No program execution should happen during this supply voltage condition.

JTAG and Spy-Bi-Wire Interface

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN	TYP	MAX	UNIT
f_{SBW}	Spy-Bi-Wire input frequency		2.2 V, 3 V	0		20	MHz
t _{SBW,Low}	Spy-Bi-Wire low clock pulse length		2.2 V, 3 V	0.025		15	μs
t _{SBW,En}	Spy-Bi-Wire enable time (TEST high to acceptance of first clock edge ⁽¹⁾)		2.2 V, 3 V			1	μs
t _{SBW,Ret}	Spy-Bi-Wire return to normal operation time		2.2 V, 3 V	15		100	μs
f _{TCK}	TCK input frequency ⁽²⁾		2.2 V	0		5	MHz
	TCK input frequency		3 V	0		10	MHz
R _{Internal}	Internal pulldown resistance on TEST		2.2 V, 3 V	25	60	90	kΩ

⁽¹⁾ Tools accessing the Spy-Bi-Wire interface need to wait for the maximum t_{SBW,En} time after pulling the TEST/SBWCLK pin high before applying the first SBWCLK clock edge.

JTAG Fuse⁽¹⁾

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT
V _{CC(FB)}	Supply voltage during fuse-blow condition	T _A = 25°C	2.5		V
V _{FB}	Voltage level on TEST for fuse blow		6	7	V
I _{FB}	Supply current into TEST during fuse blow			100	mA
t _{FB}	Time to blow fuse			1	ms

(1) Once the fuse is blown, no further access to the JTAG/Test, Spy-Bi-Wire, and emulation feature is possible, and JTAG is switched to bypass mode.

⁽²⁾ f_{TCK} may be restricted to meet the timing requirements of the module selected.



APPLICATION INFORMATION

Port P1 Pin Schematic: P1.0 to P1.3, Input/Output With Schmitt Trigger - MSP430G2x21

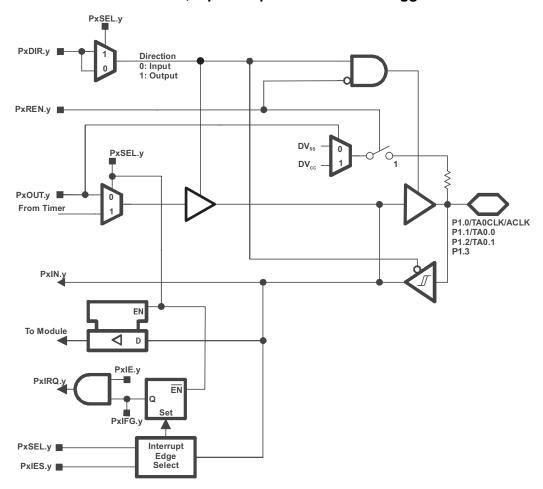


Table 13. Port P1 (P1.0 to P1.3) Pin Functions - MSP430G2x21

DINI NAME (D4)		FUNCTION	CONTROL BITS/SIGNALS			
PIN NAME (P1.x)	X	FUNCTION	P1DIR.x	P1SEL.x		
P1.0/		P1.0 (I/O)	I: 0; O: 1	0		
TA0CLK/	0	TA0CLK	0	1		
ACLK		ACLK	1	1		
P1.1/		P1.1 (I/O)	I: 0; O: 1	0		
TA0.0	1	TA0.CCI0A	0	1		
		TA0.0	1	1		
P1.2/		P1.2 (I/O)	I: 0; O: 1	0		
TA0.1	2	TA0.CCI1A	0	1		
		TA0.1	1	1		
P1.3	3	P1.3 (I/O)	I: 0; O: 1	0		



Port P1 Pin Schematic: P1.4, Input/Output With Schmitt Trigger - MSP430G2x21

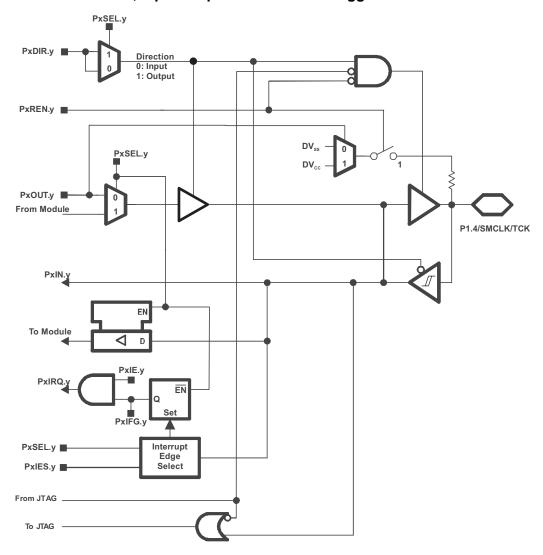


Table 14. Port P1 (P1.4) Pin Functions - MSP430G2x21

DIN NAME (D4 v)	х	FUNCTION	CONTROL BITS / SIGNALS ⁽¹⁾				
PIN NAME (P1.x)		FUNCTION	P1DIR.x	P1SEL.x	JTAG Mode		
P1.4/		P1.x (I/O)	I: 0; O: 1	0	0		
SMCLK/	4	SMCLK	1	1	0		
TCK		TCK	X	X	1		



Port P1 Pin Schematic: P1.5, Input/Output With Schmitt Trigger - MSP430G2x21

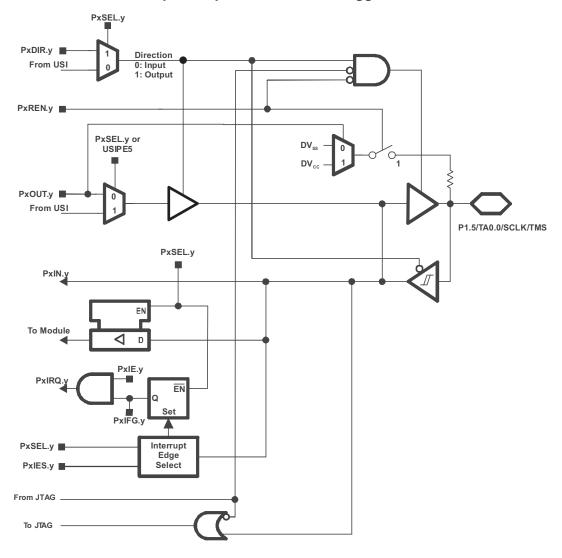


Table 15. Port P1 (P1.5) Pin Functions - MSP430G2x21

DIN NAME (D4)		FUNCTION	CONTROL BITS / SIGNALS ⁽¹⁾					
PIN NAME (P1.x)	х		P1DIR.x	P1SEL.x	USIP.x	JTAG Mode		
P1.5/		P1.x (I/O)	I: 0; O: 1	0	0	0		
TA0.0/	_	TA0.0	1	1	0	0		
SCLK/	5	SCLK	Х	Х	1	0		
TMS		TMS	X	X	0	1		



Port P1 Pin Schematic: P1.6, Input/Output With Schmitt Trigger - MSP430G2x21

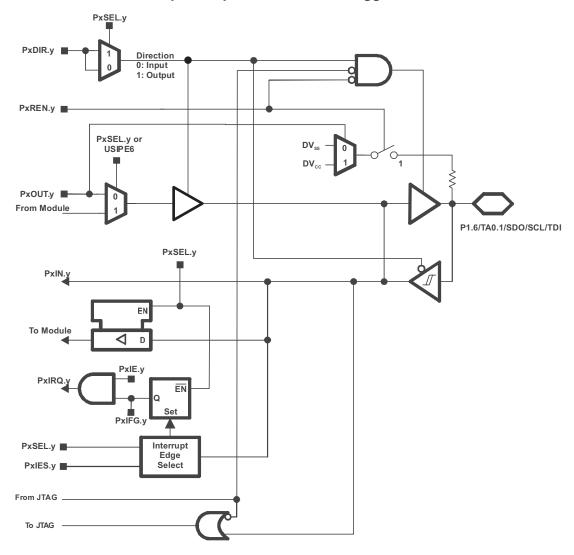


Table 16. Port P1 (P1.6) Pin Functions - MSP430G2x21

DIN NAME (D4 v)		FUNCTION	CONTROL BITS / SIGNALS ⁽¹⁾					
PIN NAME (P1.x)	X	FUNCTION	P1DIR.x	P1SEL.x	USIP.x	JTAG Mode		
P1.6/		P1.x (I/O)	I: 0; O: 1	0	0	0		
TA0.1/		TA0.1	1	1	0	0		
	6	TA0.CCI1B	0	1	0	0		
SDO/SCL/		SDO/SCL	X	X	1	0		
TDI/TCLK		TDI/TCLK	Х	X	0	1		



Port P1 Pin Schematic: P1.7, Input/Output With Schmitt Trigger - MSP430G2x21

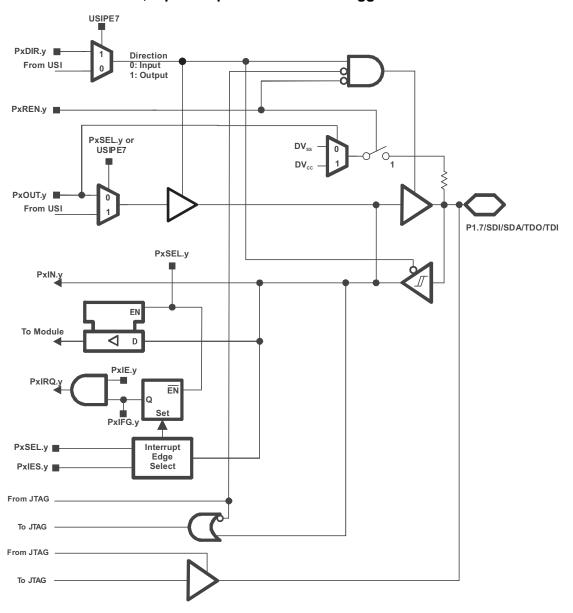


Table 17. Port P1 (P1.7) Pin Functions - MSP430G2x21

PIN NAME (P(1.x)		FUNCTION	CONTROL BITS / SIGNALS ⁽¹⁾					
		FONCTION	P1DIR.x	P1SEL.x	USIP.x	JTAG Mode		
P1.7/		P1.x (I/O)	I: 0; O: 1	0	0	0		
SDI/SDA/	7	SDI/SDA	X	X	1	0		
TDO/TDI		TDO/TDI	X	X	0	1		



Port P1 Pin Schematic: P1.0 to P1.2, Input/Output With Schmitt Trigger - MSP430G2x31

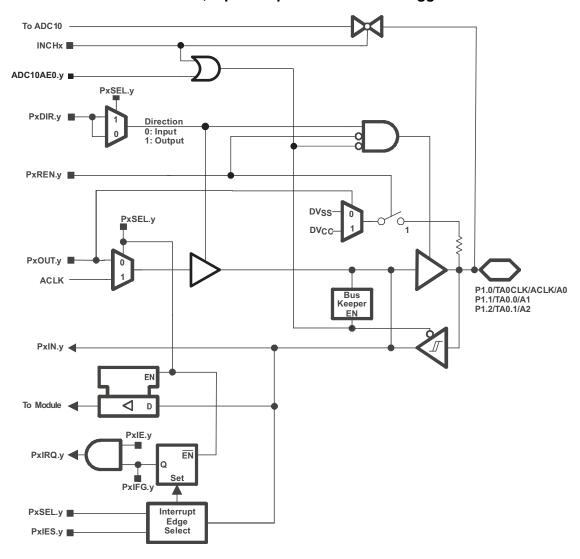


Table 18. Port P1 (P1.0 to P1.2) Pin Functions - MSP430G2x31

			CONTR	OL BITS / SIG	NALS ⁽¹⁾
PIN NAME (P1.x)	x	FUNCTION	P1DIR.x	P1SEL.x	ADC10AE.x (INCH.y = 1)
P1.0/		P1.x (I/O)	I: 0; O: 1	0	0
TA0CLK/	0	TA0.TACLK	0	1	0
ACLK/	U	ACLK	1	1	0
A0		A0	X	Х	1 (y = 0)
P1.1/		P1.x (I/O)	l: 0; O: 1	0	0
TA0.0/		TA0.0	1	1	0
	1	TA0.CCI0A	0	1	0
A1		A1	X	Х	1 (y = 1)
P1.2/		P1.x (I/O)	l: 0; O: 1	0	0
TA0.1/		TA0.1	1	1	0
	2	TA0.CCI1A	0	1	0
A2/		A2	Х	Х	1 (y = 2)

(1) X = don't care



Port P1 Pin Schematic: P1.3, Input/Output With Schmitt Trigger - MSP430G2x31

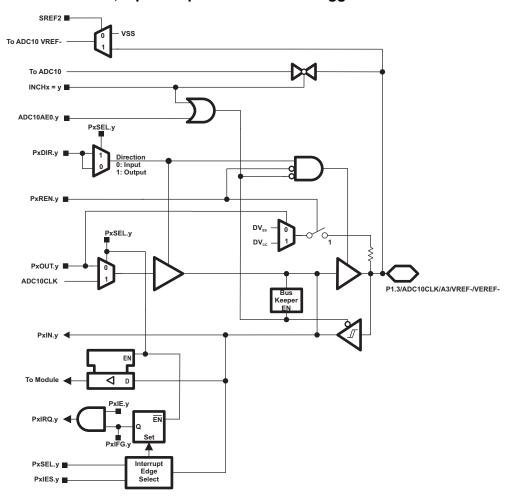


Table 19. Port P1 (P1.3) Pin Functions - MSP430G2x31

			CONTROL BITS / SIGNALS ⁽¹⁾				
PIN NAME (P1.x)	X	FUNCTION	P1DIR.x	P1SEL.x	ADC10AE.x (INCH.x = 1)		
P1.3/		P1.x (I/O)	I: 0; O: 1	0	0		
ADC10CLK/		ADC10CLK	1	1	0		
A3/	3	A3	Х	Χ	1 (y = 3)		
VREF-/		VREF-	Х	Χ	1		
VEREF-		VEREF-	Χ	Χ	1		

(1) X = don't care



Port P1 Pin Schematic: P1.4, Input/Output With Schmitt Trigger - MSP430G2x31

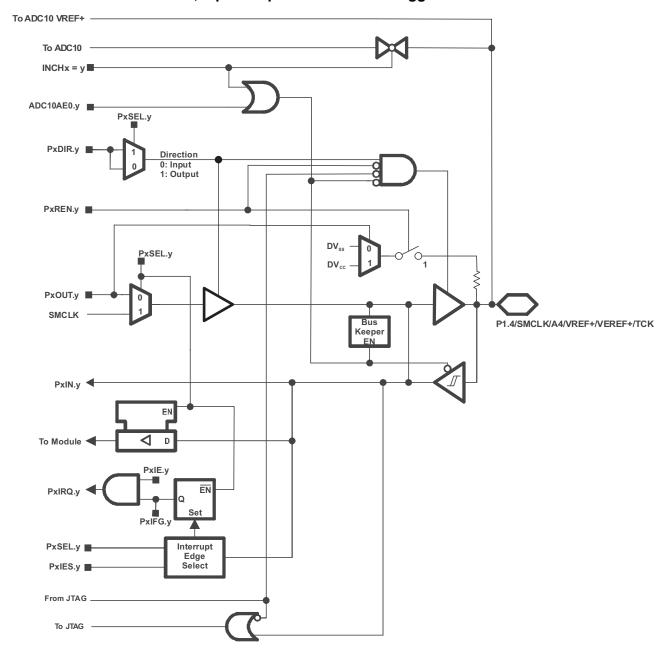




Table 20. Port P1 (P1.4) Pin Functions - MSP430G2x31

			CONTROL BITS / SIGNALS ⁽¹⁾					
PIN NAME (P1.x)	x	FUNCTION	P1DIR.x	P1SEL.x	ADC10AE.x (INCH.x = 1)	JTAG Mode		
P1.4/		P1.x (I/O)	I: 0; O: 1	0	0	0		
SMCLK/		SMCLK	1	1	0	0		
A4/	4	A4	Х	Х	1 (y = 4)	0		
VREF+/	4	VREF+	Х	Х	1	0		
VEREF+/		VEREF+	X	Х	1	0		
TCK		TCK	Х	Х	0	1		

(1) X = don't care

Port P1 Pin Schematic: P1.5, Input/Output With Schmitt Trigger - MSP430G2x31

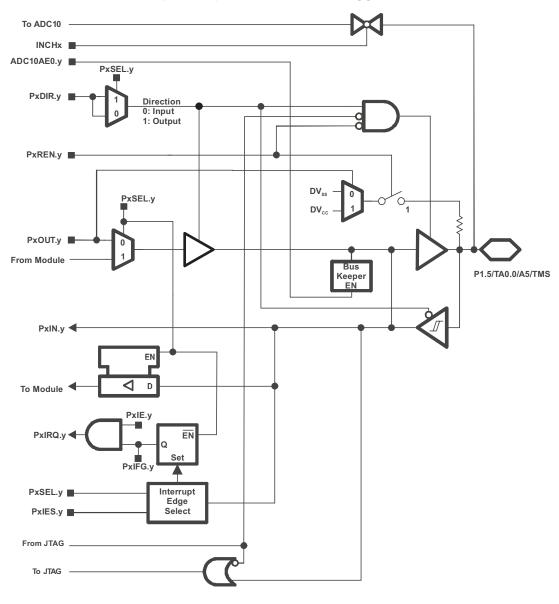


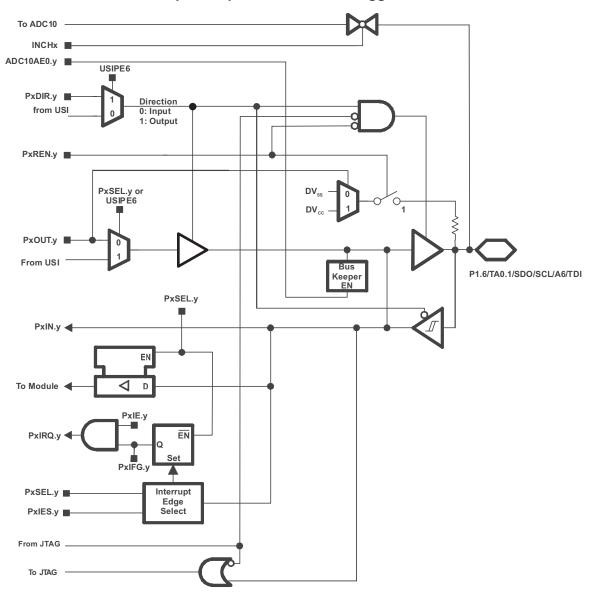


Table 21. Port P1 (P1.5) Pin Functions - MSP430G2x31

			CONTROL BITS / SIGNALS ⁽¹⁾							
PIN NAME (P1.x)	x	FUNCTION	P1DIR.x	P1SEL.x	USIP.x	ADC10AE.x (INCH.x = 1)	JTAG Mode			
P1.5/		P1.x (I/O)	I: 0; O: 1	0	0	0	0			
TA0.0/		TA0.0	1	1	0	0	0			
A5/	5	A5	Х	Х	Х	1 (y = 5)	0			
SCLK/		SCLK	Х	Х	1	0	0			
TMS		TMS	Х	Х	0	0	1			

(1) X = don't care

Port P1 Pin Schematic: P1.6, Input/Output With Schmitt Trigger - MSP430G2x31



USI in I2C mode: Output driver drives low level only. Driver is disabled in JTAG mode.



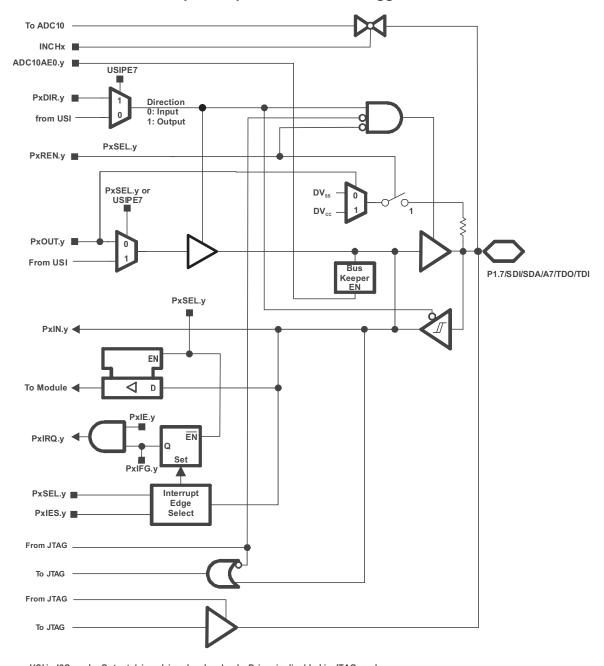
Table 22. Port P1 (P1.6) Pin Functions - MSP430G2x31

			CONTROL BITS / SIGNALS ⁽¹⁾							
PIN NAME (P1.x)	x	FUNCTION	P1DIR.x	P1SEL.x	USIP.x	ADC10AE.x (INCH.x = 1)	JTAG Mode			
P1.6/		P1.x (I/O)	I: 0; O: 1	0	0	0	0			
TA0.1/		TA0.1	1	1	0	0	0			
	6	TA0.CCR1B	0	1	0	0	0			
A6/	О	A6	Х	Х	0	1 (y = 6)	0			
SDO/		SDO	Х	Х	1	0	0			
TDI/TCLK		TDI/TCLK	Х	Χ	0	0	1			

⁽¹⁾ X = don't care



Port P1 Pin Schematic: P1.7, Input/Output With Schmitt Trigger - MSP430G2x31



USI in I2C mode: Output driver drives low level only. Driver is disabled in JTAG mode.

Table 23. Port P1 (P1.7) Pin Functions - MSP430G2x31

			CONTROL BITS / SIGNALS ⁽¹⁾						
PIN NAME (P1.x)	x	FUNCTION	P1DIR.x	P1SEL.x	USIP.x	ADC10AE.x (INCH.x = 1)	JTAG Mode		
P1.7/		P1.x (I/O)	I: 0; O: 1	0	0	0	0		
A7/	7	A7	Х	Χ	0	1 (y = 7)	0		
SDI/SDO	/	SDI/SDO	Х	Χ	1	0	0		
TDO/TDI		TDO/TDI	Х	Х	0	0	1		

(1) X = don't care



Port P2 Pin Schematic: P2.6, Input/Output With Schmitt Trigger – MSP430G2x21 and MSP430G2x31

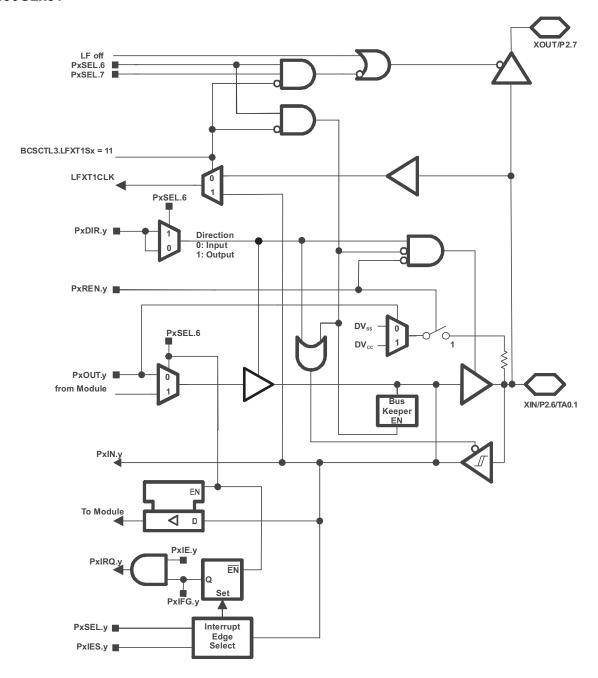


Table 24. Port P2 (P2.6) Pin Functions - MSP430G2x21 and MSP430G2x31

DIN NAME (D2 v)	,	FUNCTION	CONTROL BITS / SIGNALS ⁽¹⁾				
PIN NAME (P2.x)	X	FUNCTION	P2DIR.x	P2SEL.6	P2SEL.7		
XIN		XIN	0	1	1		
P2.6	6	P2.x (I/O)	l: 0; O: 1	0	Χ		
TA0.1		TA0.1 ⁽²⁾	1	1	Х		

(1) X = don't care

(2) BCSCTL3.LFXT1Sx = 11 is required.



Port P2 Pin Schematic: P2.7, Input/Output With Schmitt Trigger – MSP430G2x21 and MSP430G2x31

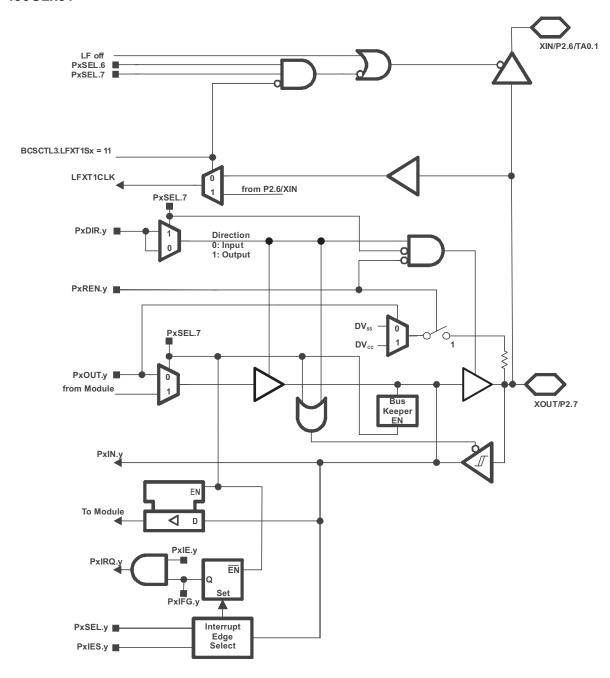


Table 25. Port P2 (P2.7) Pin Functions - MSP430G2x21 and MSP430G2x31

DIN NAME (D2 v)		FUNCTION	CONTROL BITS / SIGNALS ⁽¹⁾			
PIN NAME (P2.x)	X	FUNCTION	P2DIR.x	P2SEL.6	P2SEL.7	
XOUT	7	XOUT	1	1	1	
P2.7	′	P2.x (I/O)	I: 0; O: 1	Х	0	

(1) X = don't care



REVISION HISTORY

REVISION	DESCRIPTION
SLAS694	Limited Product Preview release
SLAS694A	Updated Product Preview release. Changes throughout for sampling.
SLAS694B	Updated Product Preview release
SLAS694C	Production Data release
SLAS694D	Updated Table 12, Table 15, Table 16, Table 17, Table 19, Table 20, Table 21, Table 24, Table 25. Updated MSP430G2x31 port schematics: P1.0 to P1.3, P1.5, P1.6, P1.7.
SLAS694E	Updated Table 20, Table 21, Table 24. Updated MSP430G2x31 port schematics: P1.3, P1.4.
SLAS694F	Corrected TA0.1 signal description in Table 2. Added ADC10SA register to Table 11. Added ADC10DTC1 and ADC10DTC0 registers to Table 12. Corrected control bits in Table 13. Corrected control bits in Table 25.
SLAS694G	Changed T _{stg} , Programmed device, to -40°C to 150°C in Absolute Maximum Ratings.
SLAS694H	Changed T _{stg} , Programmed device, to -55°C to 150°C in Absolute Maximum Ratings. Changed f _{SYSTEM} MAX at V _{CC} = 1.8 V from 4.15 to 6 MHz in Recommended Operating Conditions.
SLAS694I	Corrected all port schematics (added buffer after PxOUT.y mux) in APPLICATION INFORMATION
SLAS694J	Recommended Operating Conditions, Added test conditions for typical values. POR, BOR, Added note (2).





4-Feb-2021

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
MSP430G2121IN14	ACTIVE	PDIP	N	14	25	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MSP430G2121	Samples
MSP430G2121IPW14	ACTIVE	TSSOP	PW	14	90	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	G2121	Samples
MSP430G2121IPW14R	ACTIVE	TSSOP	PW	14	2000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	G2121	Samples
MSP430G2121IRSA16R	ACTIVE	QFN	RSA	16	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	M430G 2121	Samples
MSP430G2121IRSA16T	ACTIVE	QFN	RSA	16	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	M430G 2121	Samples
MSP430G2131IN14	ACTIVE	PDIP	N	14	25	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MSP430G2131	Samples
MSP430G2131IPW14	ACTIVE	TSSOP	PW	14	90	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	G2131	Samples
MSP430G2131IPW14R	ACTIVE	TSSOP	PW	14	2000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	G2131	Samples
MSP430G2131IRSA16R	ACTIVE	QFN	RSA	16	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	M430G 2131	Samples
MSP430G2131IRSA16T	ACTIVE	QFN	RSA	16	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	M430G 2131	Samples
MSP430G2221IN14	ACTIVE	PDIP	N	14	25	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MSP430G2221	Samples
MSP430G2221IPW14	ACTIVE	TSSOP	PW	14	90	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	G2221	Samples
MSP430G2221IPW14R	ACTIVE	TSSOP	PW	14	2000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	G2221	Samples
MSP430G2221IRSA16R	ACTIVE	QFN	RSA	16	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	M430G 2221	Samples
MSP430G2221IRSA16T	ACTIVE	QFN	RSA	16	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	M430G 2221	Samples
MSP430G2231IN14	ACTIVE	PDIP	N	14	25	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	MSP430G2231	Samples
MSP430G2231IPW14	ACTIVE	TSSOP	PW	14	90	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	G2231	Samples
MSP430G2231IPW14R	ACTIVE	TSSOP	PW	14	2000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 85	G2231	Samples
MSP430G2231IRSA16R	ACTIVE	QFN	RSA	16	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	M430G	Samples



PACKAGE OPTION ADDENDUM

4-Feb-2021

Orderable Device	Status	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
							(6)				
										2231	
MSP430G2231IRSA16T	ACTIVE	QFN	RSA	16	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	M430G 2231	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

OTHER QUALIFIED VERSIONS OF MSP430G2231:



PACKAGE OPTION ADDENDUM

4-Feb-2021

Automotive: MSP430G2231-Q1

● Enhanced Product: MSP430G2231-EP

NOTE: Qualified Version Definitions:

- Automotive Q100 devices qualified for high-reliability automotive applications targeting zero defects
- Enhanced Product Supports Defense, Aerospace and Medical Applications



www.ti.com 30-May-2024

TAPE AND REEL INFORMATION



TAPE DIMENSIONS + K0 - P1 - B0 W Cavity - A0 -

A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
MSP430G2121IPW14R	TSSOP	PW	14	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1
MSP430G2121IRSA16R	QFN	RSA	16	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430G2121IRSA16T	QFN	RSA	16	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430G2131IPW14R	TSSOP	PW	14	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1
MSP430G2131IRSA16R	QFN	RSA	16	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430G2131IRSA16T	QFN	RSA	16	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430G2221IPW14R	TSSOP	PW	14	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1
MSP430G2221IRSA16R	QFN	RSA	16	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430G2221IRSA16T	QFN	RSA	16	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430G2231IPW14R	TSSOP	PW	14	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1
MSP430G2231IRSA16R	QFN	RSA	16	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
MSP430G2231IRSA16T	QFN	RSA	16	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2



www.ti.com 30-May-2024



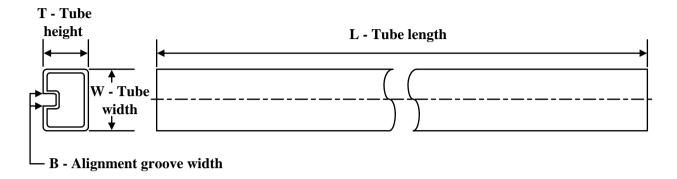
*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)	
MSP430G2121IPW14R	TSSOP	PW	14	2000	356.0	356.0	35.0	
MSP430G2121IRSA16R	QFN	RSA	16	3000	367.0	367.0	35.0	
MSP430G2121IRSA16T	QFN	RSA	16	250	210.0	185.0	35.0	
MSP430G2131IPW14R	TSSOP	PW	14	2000	356.0	356.0	35.0	
MSP430G2131IRSA16R	QFN	RSA	16	3000	346.0	346.0	33.0	
MSP430G2131IRSA16T	QFN	RSA	16	250	210.0	185.0	35.0	
MSP430G2221IPW14R	TSSOP	PW	14	2000	356.0	356.0	35.0	
MSP430G2221IRSA16R	QFN	RSA	16	3000	346.0	346.0	33.0	
MSP430G2221IRSA16T	QFN	RSA	16	250	210.0	185.0	35.0	
MSP430G2231IPW14R	TSSOP	PW	14	2000	356.0	356.0	35.0	
MSP430G2231IRSA16R	QFN	RSA	16	3000	346.0	346.0	33.0	
MSP430G2231IRSA16T	QFN	RSA	16	250	210.0	185.0	35.0	



www.ti.com 30-May-2024

TUBE



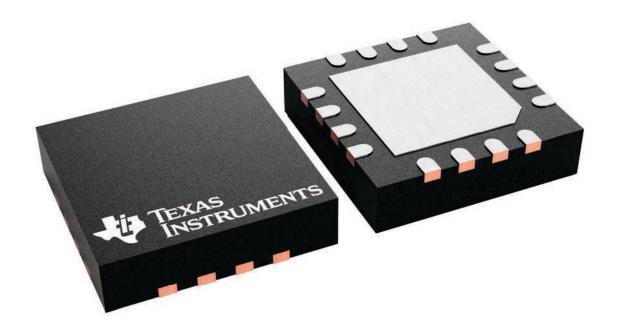
*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
MSP430G2121IN14	N	PDIP	14	25	506	13.97	11230	4.32
MSP430G2121IPW14	PW	TSSOP	14	90	530	10.2	3600	3.5
MSP430G2121IPW14	PW	TSSOP	14	90	530	10.2	3600	3.5
MSP430G2131IN14	N	PDIP	14	25	506	13.97	11230	4.32
MSP430G2131IPW14	PW	TSSOP	14	90	530	10.2	3600	3.5
MSP430G2131IPW14	PW	TSSOP	14	90	530	10.2	3600	3.5
MSP430G2221IN14	N	PDIP	14	25	506	13.97	11230	4.32
MSP430G2221IPW14	PW	TSSOP	14	90	530	10.2	3600	3.5
MSP430G2221IPW14	PW	TSSOP	14	90	530	10.2	3600	3.5
MSP430G2231IN14	N	PDIP	14	25	506	13.97	11230	4.32
MSP430G2231IPW14	PW	TSSOP	14	90	530	10.2	3600	3.5
MSP430G2231IPW14	PW	TSSOP	14	90	530	10.2	3600	3.5

4 x 4, 0.65 mm pitch

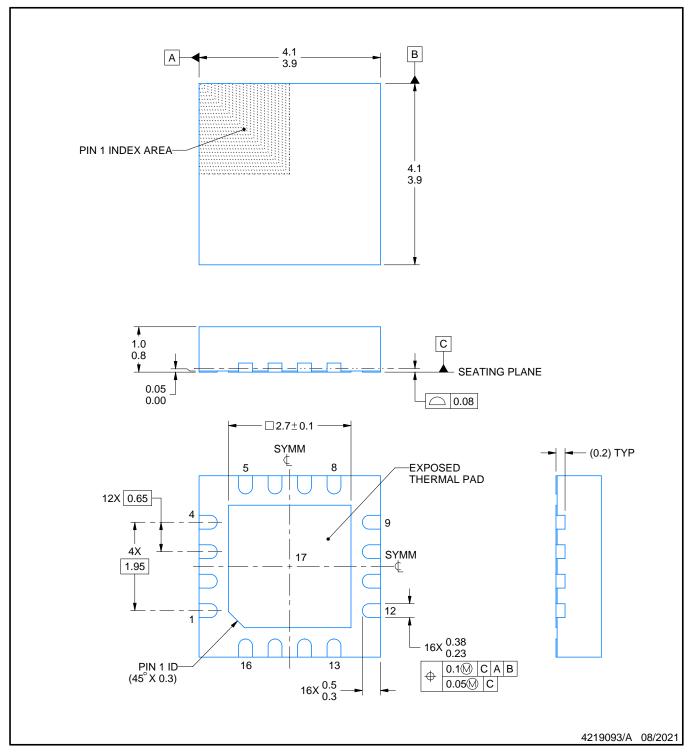
PLASTIC QUAD FLATPACK - NO LEAD

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.





PLASTIC QUAD FLATPACK - NO LEAD



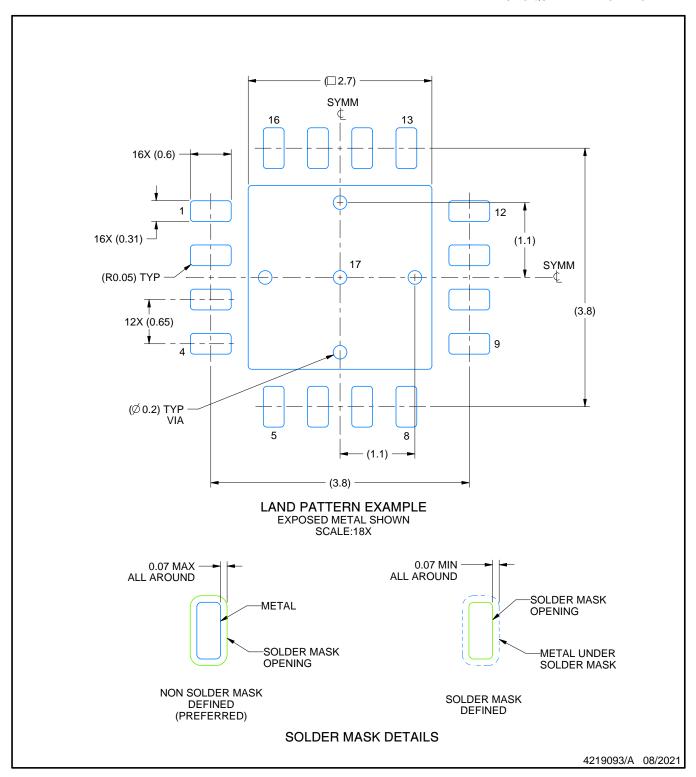
NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

 4. Reference JEDEC registration MO-220.



PLASTIC QUAD FLATPACK - NO LEAD

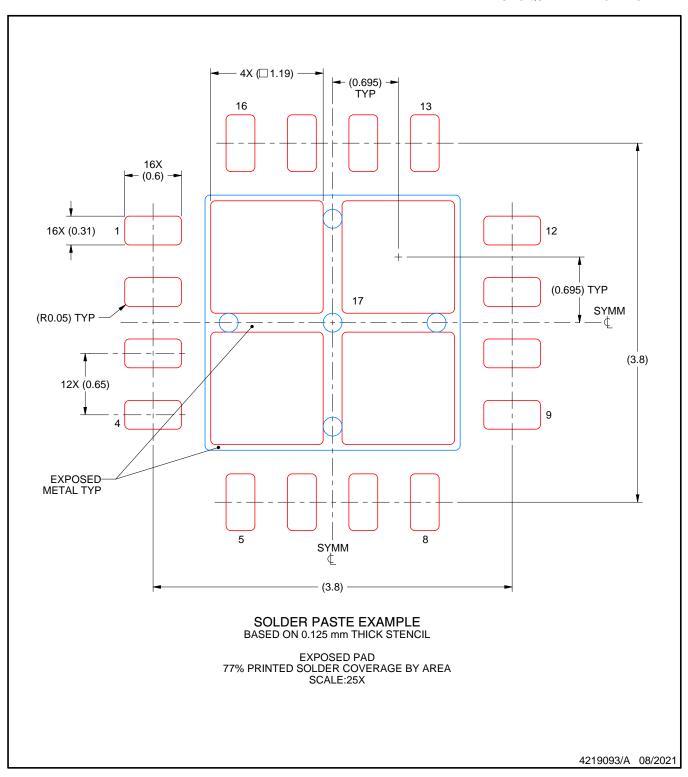


NOTES: (continued)

- 5. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- 6. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

7. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



PW (R-PDSO-G14)

PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M—1994.
- B. This drawing is subject to change without notice.
 - Sody length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0,15 each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0,25 each side.
- E. Falls within JEDEC MO-153



N (R-PDIP-T**)

PLASTIC DUAL-IN-LINE PACKAGE

16 PINS SHOWN



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- Falls within JEDEC MS-001, except 18 and 20 pin minimum body length (Dim A).
- The 20 pin end lead shoulder width is a vendor option, either half or full width.



IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2024, Texas Instruments Incorporated