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4 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

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5 Pin Configuration and Functions

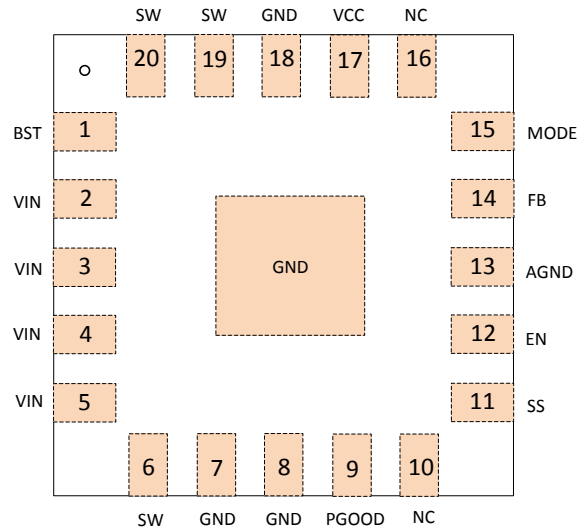


图 5-1. RJE Package 20-Pin VQFN (Top View)

表 5-1. Pin Functions

| PIN | | I/O | DESCRIPTION |
|-------|------------|-----|---|
| NAME | NO. | | |
| BST | 1 | I | Supply input for the gate drive voltage of the high-side MOSFET. Connect the bootstrap capacitor between BST and SW, 0.1 μ F is recommended. |
| VIN | 2,3,4,5 | P | Input voltage supply pin for the control circuitry. Connect the input decoupling capacitors between VIN and GND. |
| SW | 6,19,20 | O | Switch node terminal. Connect the output inductor to this pin. |
| GND | 7,8,18,Pad | G | Power GND terminal for the controller circuit and the internal circuitry. |
| PGOOD | 9 | O | Open drain power good indicator. It is asserted low if output voltage is out of PGOOD threshold, over voltage or if the device is under thermal shutdown, EN shutdown or during soft start. |
| SS | 11 | I | Soft-start time selection pin. Connecting an external capacitor sets the soft-start time and if no external capacitor is connected, the soft-start time is about 1.3 ms. |
| NC | 10,16 | | Not connect. Can be connected to GND plane for better thermal achieved. |
| EN | 12 | I | Enable pin of buck converter. EN pin is a digital input pin, decides turn on or off buck converter. Internal pull down current to disable converter if leave this pin open. |
| AGND | 13 | G | Ground of internal analog circuitry. Connect AGND to GND plane with a short trace. |
| FB | 14 | I | Converter feedback input. Connect to the center tap of the resistor divider between output voltage and AGND. |
| MODE | 15 | I | Light load operation mode selection pin. Connect this pin to a resistor divider from VCC and AGND, the different MODE options are shown in 表 7-1 |
| VCC | 17 | O | 5.0-V internal VCC LDO output. This pin supplies voltage to the internal circuitry and gate driver. Bypass this pin with a 1- μ F capacitor. |

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) ⁽¹⁾

| | | MIN | MAX | UNIT |
|------------------|--------------------------------|------|-----|------|
| Input voltage | VIN | -0.3 | 26 | V |
| | VBST | -0.3 | 31 | V |
| | VBST-SW | -0.3 | 6 | V |
| | EN, MODE, FB, SS | -0.3 | 6 | V |
| | PGND, AGND | -0.3 | 0.3 | V |
| Output voltage | SW | -2 | 26 | V |
| | SW (10-ns transient) | -3 | 28 | V |
| | PGOOD | -0.3 | 6 | V |
| T _J | Operating junction temperature | -40 | 150 | °C |
| T _{stg} | Storage temperature | -55 | 150 | °C |

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

| | | VALUE | UNIT | |
|--------------------|-------------------------|---|-------|---|
| V _(ESD) | Electrostatic discharge | Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾ | ±2000 | V |
| | | Charged-device model (CDM), per JEDEC specification JESD22- V C101 ⁽²⁾ | ±500 | V |

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

| | | MIN | MAX | UNIT |
|------------------|--------------------------------|------|-----|------|
| Input voltage | VIN ⁽¹⁾ | 4.5 | 24 | V |
| | VBST | -0.3 | 29 | V |
| | VBST-SW | -0.3 | 5.5 | V |
| | EN, MODE, FB, SS | -0.3 | 5.5 | V |
| | PGND, AGND | -0.3 | 0.3 | V |
| Output voltage | SW | -2 | 24 | V |
| | SW (10-ns transient) | -3 | 26 | V |
| | PGOOD | -0.3 | 5.5 | V |
| I _{OUT} | Output current | | 8 | A |
| T _J | Operating junction temperature | -40 | 125 | °C |

- (1) Max DC input (include tolerance) should be not over 24 V.

6.4 Thermal Information

| THERMAL METRIC ⁽¹⁾ | | TPS51396A | UNIT |
|-------------------------------|--|------------|------|
| | | RJE (VQFN) | |
| | | 20 PINS | |
| R _{θJA} | Junction-to-ambient thermal resistance | 44.9 | °C/W |
| R _{θJC(top)} | Junction-to-case (top) thermal resistance | 32.3 | °C/W |
| R _{θJB} | Junction-to-board thermal resistance | 13.3 | °C/W |
| ψ _{JT} | Junction-to-top characterization parameter | 1.3 | °C/W |
| ψ _{JB} | Junction-to-board characterization parameter | 13.5 | °C/W |
| R _{θJC(bot)} | Junction-to-case (bottom) thermal resistance | 16.1 | °C/W |

(1) For more information about traditional and new thermal metrics, see the [IC Package Thermal Metrics](#) application report.

6.5 Electrical Characteristics

T_J = -40°C to 125°C, V_{VIN} = 12 V, unless otherwise noted

| PARAMETER | | TEST CONDITION | MIN | TYP | MAX | UNIT |
|---|--------------------------------|--|------|------|------|------|
| SUPPLY CURRENT | | | | | | |
| V _{IN} | Input voltage range | V _{IN} | 4.5 | | 24 | V |
| I _{VIN} | V _{IN} supply current | No load, V _{EN} = 3.3 V, Switching | | 90 | | µA |
| I _{VINSDN} | Shutdown supply current | No load, V _{EN} = 0 V | | 2 | | µA |
| VCC OUTPUT | | | | | | |
| V _{CC} | VCC output voltage | V _{VIN} > 5.0 V | 4.85 | 5 | 5.15 | V |
| | | V _{VIN} = 4.5 V | | 4.5 | | V |
| I _{CC} | VCC current limit | | 20 | | | mA |
| FEEDBACK VOLTAGE | | | | | | |
| V _{FB} | FB voltage | T _J = 25°C | 594 | 600 | 606 | mV |
| | | T _J = -40°C to 125°C | 592 | 600 | 611 | mV |
| DUTY CYCLE and FREQUENCY CONTROL | | | | | | |
| F _{SW} | Switching frequency | T _J = 25°C, F _{SW} = 600 kHz, V _o = 1 V | | 600 | | kHz |
| T _{ON(MIN)} | SW minimum on time | T _J = 25°C | | 60 | | ns |
| T _{OFF(MIN)} | SW minimum off time | T _J = 25°C, V _{FB} = 0.5 V | | | 190 | ns |
| MOSFET and DRIVERS | | | | | | |
| R _{DS(ON)H} | High side switch resistance | T _J = 25°C | | 19.5 | | mΩ |
| R _{DS(ON)L} | Low side switch resistance | T _J = 25°C | | 9.5 | | mΩ |
| OOA FUNCTION | | | | | | |
| T _{OOA} | OOA mode operation period | | | 28 | | µs |
| OUTPUT DISCHARGE and SOFT START | | | | | | |
| R _{DIS} | Discharge resistance | T _J = 25°C, V _{EN} = 0 V | | 420 | | Ω |
| T _{SS} | Soft start time | Internal soft-start time, SS floating | | 1.3 | | ms |
| I _{SS} | Soft start charge current | | | 5 | | µA |
| POWER GOOD | | | | | | |
| T _{PGDLY} | PG start-up delay | PG from low to high | | 1 | | ms |
| V _{PGTH} | PG threshold | VFB falling (fault) | | 85 | | % |
| | | VFB rising (good) | | 90 | | % |
| | | VFB rising (fault) | | 115 | | % |
| | | VFB falling (good) | | 110 | | % |
| V _{PG_L} | PG sink current capability | I _{OL} = 4 mA | | | 0.4 | V |
| I _{PGLK} | PG leak current | V _{PGOOD} = 5.5 V | | | 1 | µA |

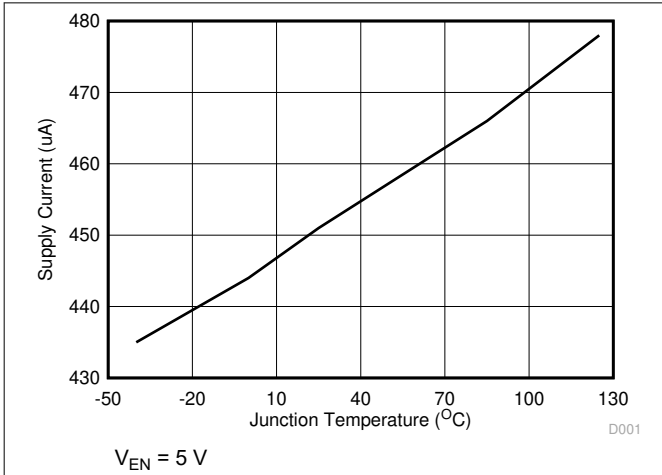
$T_J = -40^{\circ}\text{C}$ to 125°C , $V_{VIN} = 12\text{ V}$, unless otherwise noted

| PARAMETER | | TEST CONDITION | MIN | TYP | MAX | UNIT |
|---|-----------------------------------|----------------------------|-----|------|-----|--------------------|
| CURRENT LIMIT | | | | | | |
| I_{OCL} | Over current threshold | Valley current set point | 8.1 | 9.8 | 12 | A |
| I_{NOCL} | Negative over current threshold | | | 3.9 | | A |
| LOGIC THRESHOLD | | | | | | |
| V_{ENH} | EN high-level input voltage | | | 1.2 | 1.4 | V |
| V_{ENL} | EN low-level input voltage | | 0.8 | 1.05 | | V |
| I_{EN} | Enable internal pull down current | $V_{EN} = 0.8\text{ V}$ | | 2 | | μA |
| OUTPUT UNDERVOLTAGE AND OVERVOLTAGE PROTECTION | | | | | | |
| V_{OVP} | OVP trip threshold | | | 125 | | % |
| t_{OVPDLY} | OVP prop deglitch | $T_J = 25^{\circ}\text{C}$ | | 20 | | us |
| V_{UVP} | UVP trip threshold | | | 60 | | % |
| t_{UVPDLY} | UVP prop deglitch | | | 256 | | us |
| UVLO | | | | | | |
| $V_{UVLOVIN}$ | VIN UVLO threshold | Wake up | | 4.2 | 4.4 | V |
| | | Shutdown | 3.6 | 3.8 | | V |
| | | Hysteresis | | 0.4 | | V |
| OVER TEMPERATURE PROTECTION | | | | | | |
| T_{OTP} | OTP trip threshold ⁽¹⁾ | Shutdown temperature | | 150 | | $^{\circ}\text{C}$ |
| T_{OTPHSY} | OTP hysteresis ⁽¹⁾ | Hysteresis | | 20 | | $^{\circ}\text{C}$ |

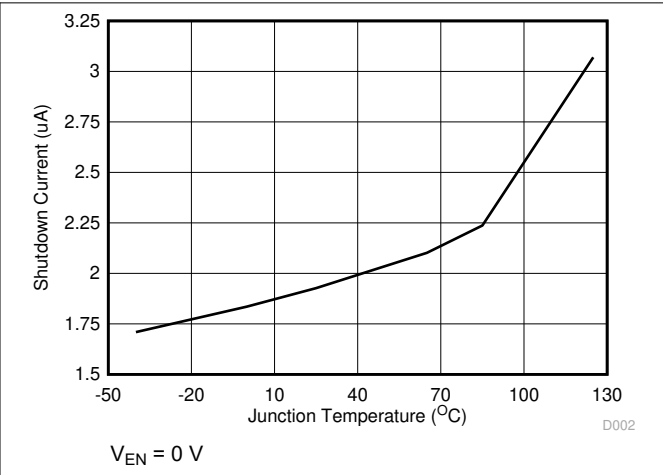
(1) Not production tested

6.6 Typical Characteristics

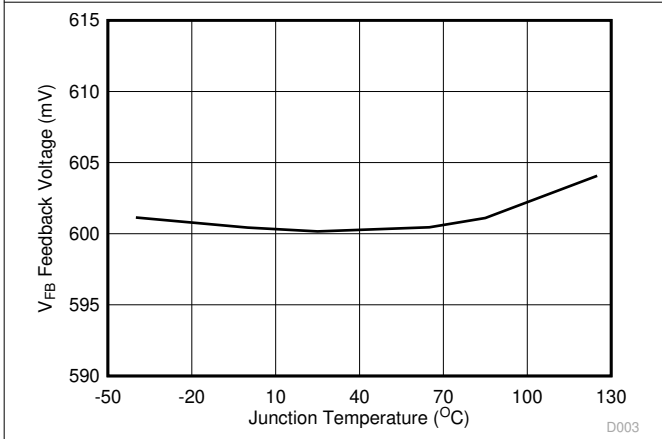
$T_J = -40^{\circ}\text{C}$ to 125°C , $V_{VIN} = 12\text{V}$ (unless otherwise noted)



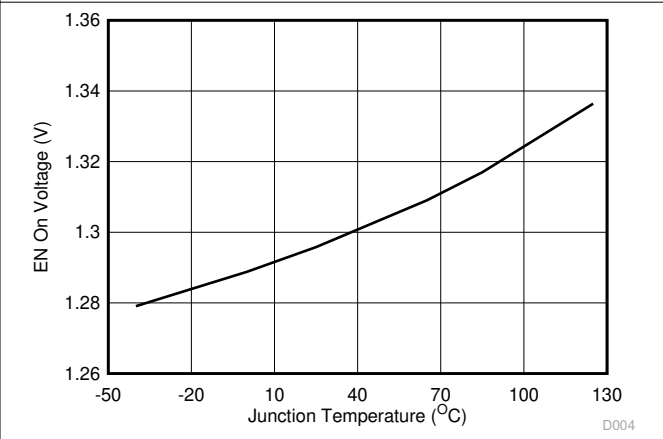
6-1. Supply Current vs Junction Temperature



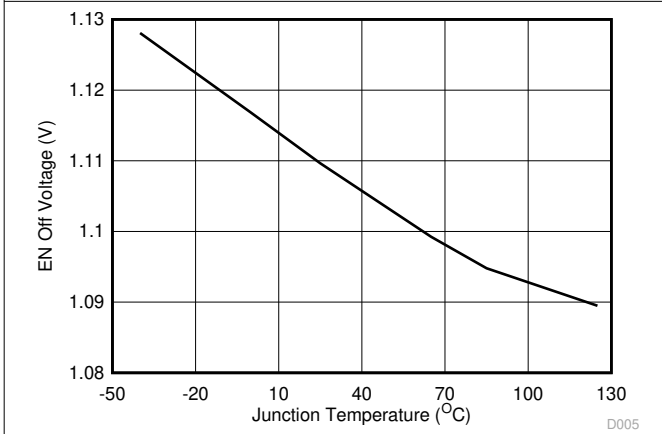
6-2. Shutdown Current vs Temperature



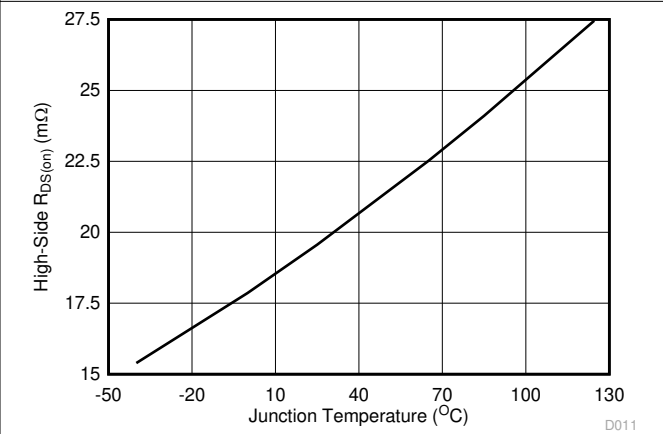
6-3. Feedback Voltage vs Junction Temperature



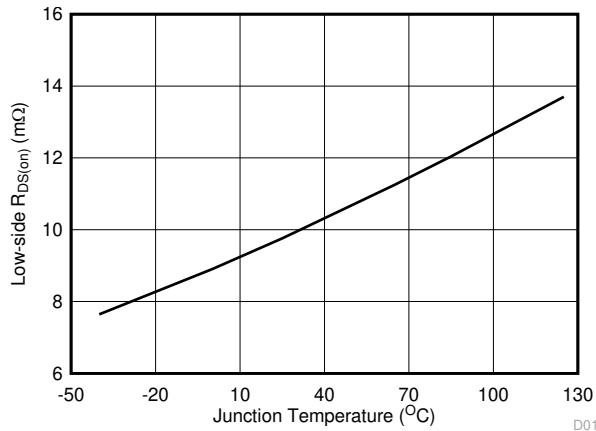
6-4. Enable On Voltage vs Junction Temperature



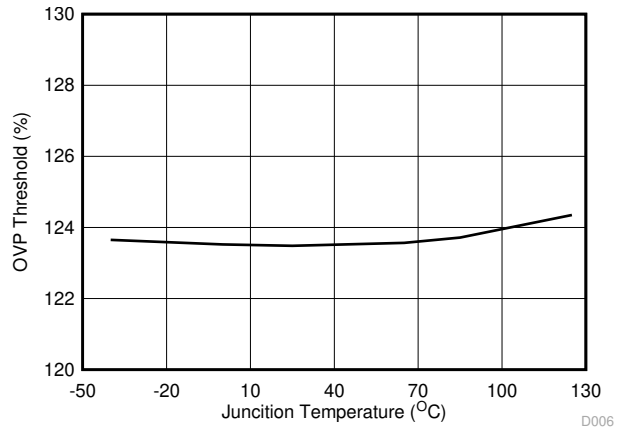
6-5. Enable Off Voltage vs Junction Temperature



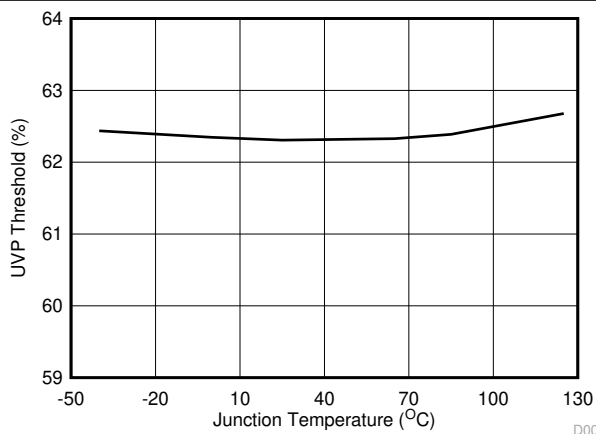
6-6. High-Side $R_{DS(on)}$ vs Junction Temperature



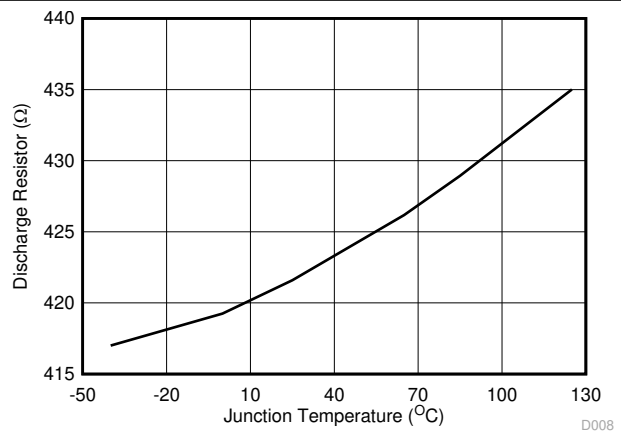
6-7. Low-Side $R_{DS(on)}$ vs Junction Temperature



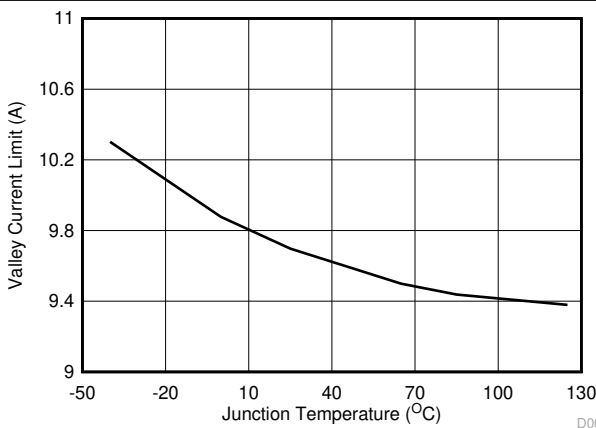
6-8. OVP Threshold vs Junction Temperature



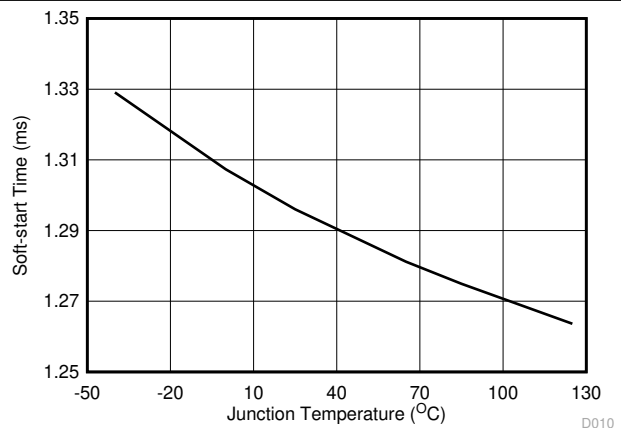
6-9. UVP Threshold vs Junction Temperature



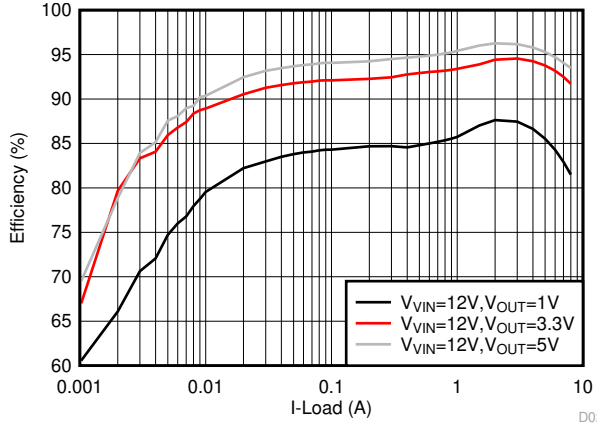
6-10. Discharge Resistor vs Junction Temperature



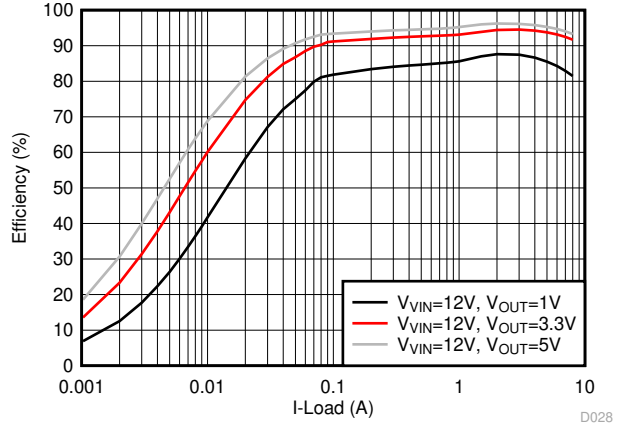
6-11. Valley Current Limit vs Junction Temperature



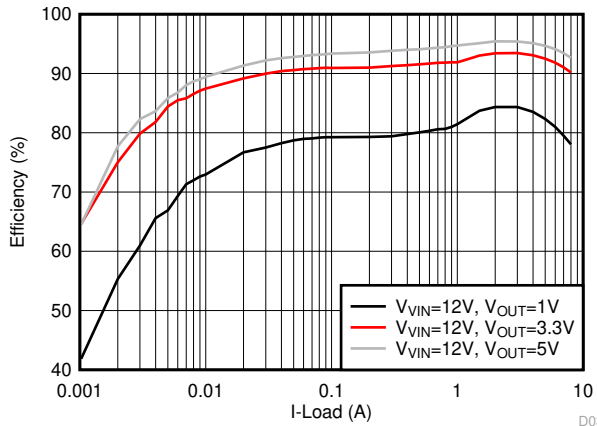
6-12. Soft-Start Time vs Junction Temperature



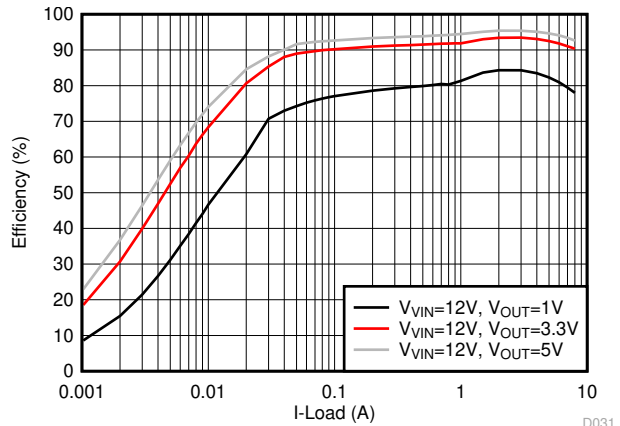
6-13. Efficiency, Eco-mode, $F_{SW} = 600$ kHz



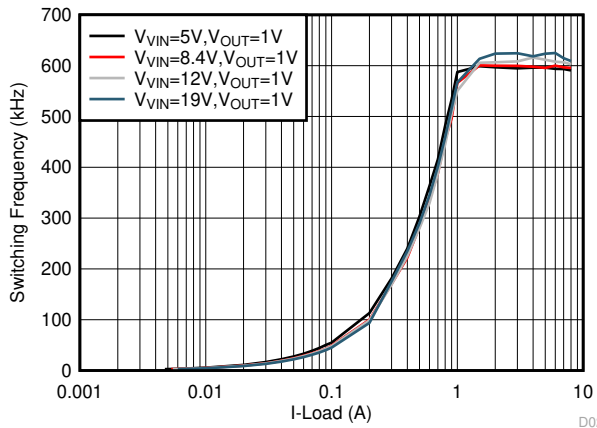
6-14. Efficiency, OOA-mode, $F_{SW} = 600$ kHz



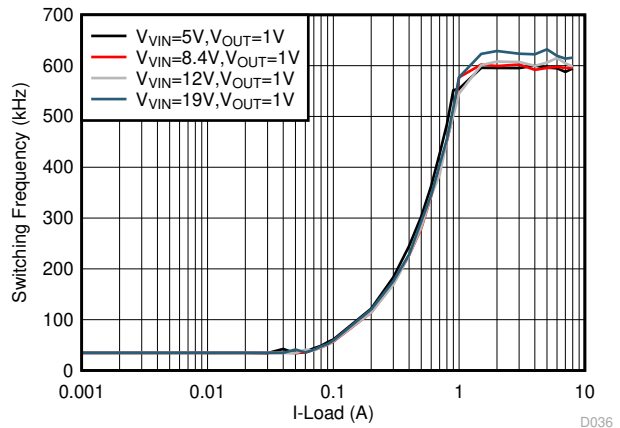
6-15. Efficiency, Eco-mode, $F_{SW} = 1$ MHz



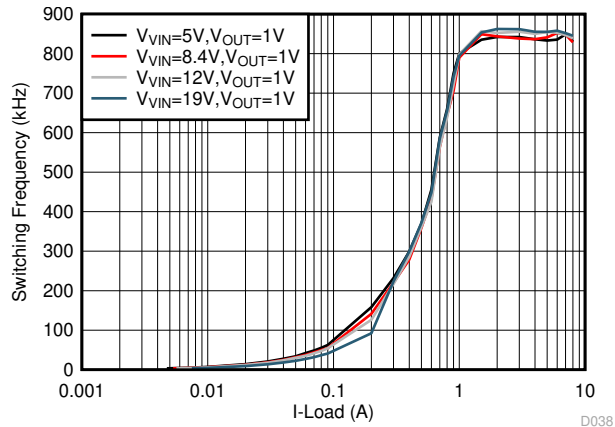
6-16. Efficiency, OOA-mode, $F_{SW} = 1$ MHz



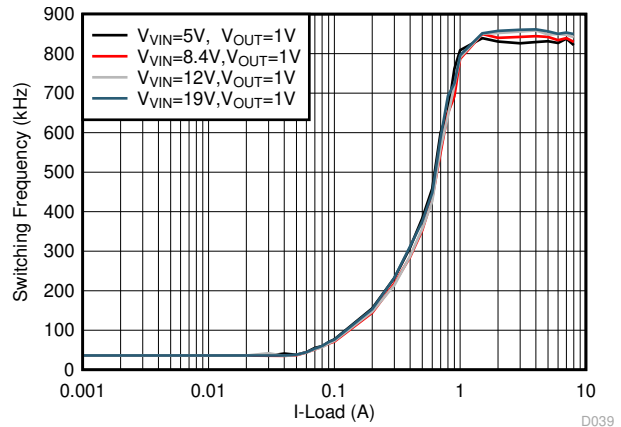
6-17. F_{SW} Load Regulation, Eco-mode, $F_{SW} = 600$ kHz



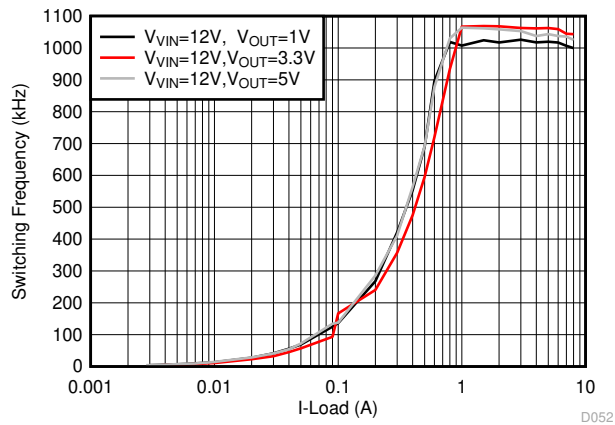
6-18. F_{SW} Load Regulation, OOA-mode, $F_{SW} = 600$ kHz



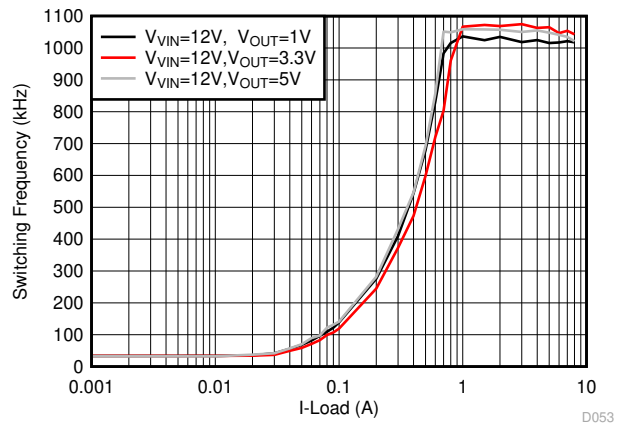
6-19. F_{sw} Load Regulation, Eco-mode, $F_{sw} = 800$ kHz



6-20. F_{sw} Load Regulation, OOA-mode, $F_{sw} = 800$ kHz



6-21. F_{sw} Load Regulation, Eco-mode, $F_{sw} = 1$ MHz



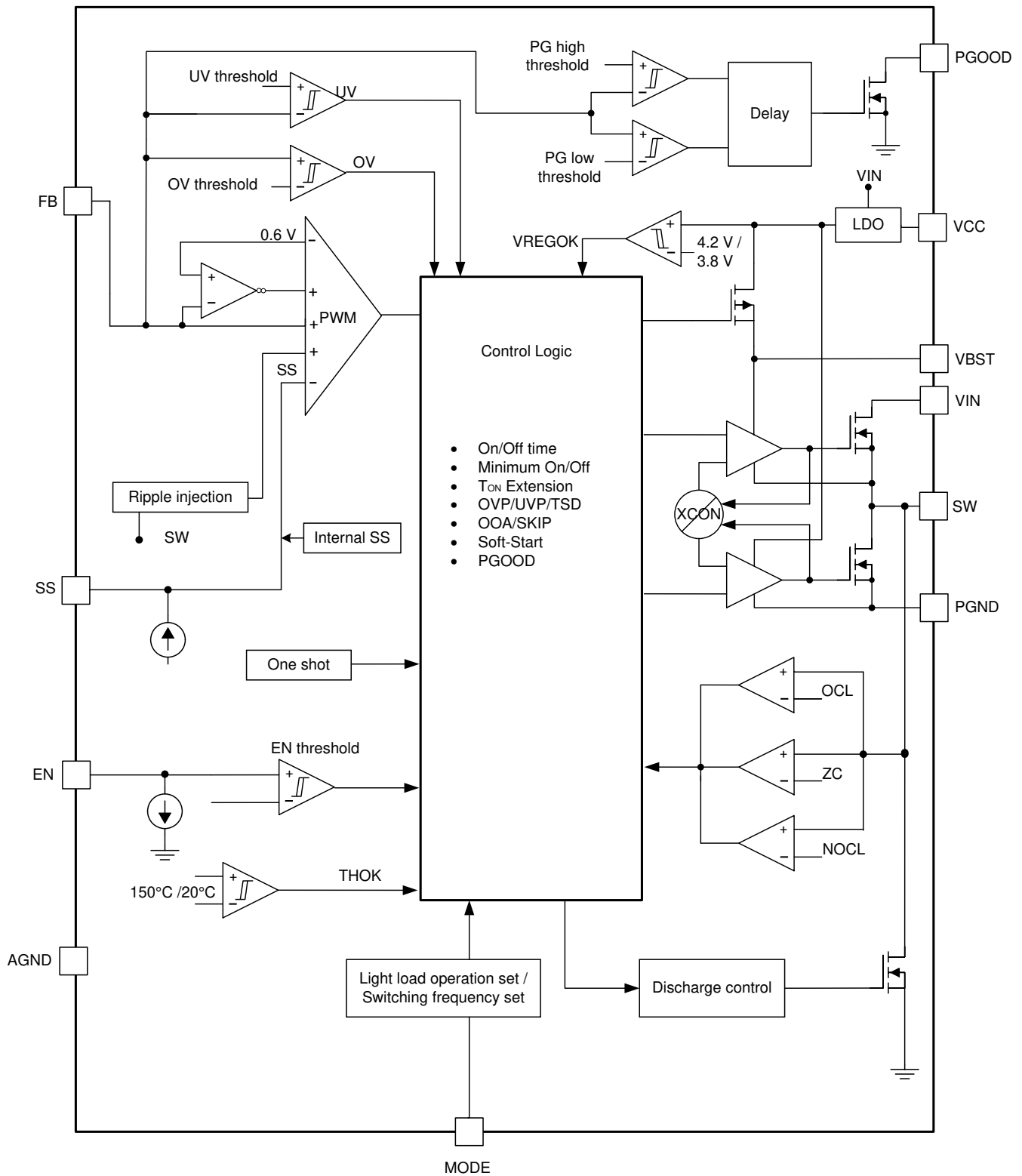
6-22. F_{sw} Load Regulation, OOA-mode, $F_{sw} = 1$ MHz

7 Detailed Description

7.1 Overview

The TPS51396A is 8-A integrated FET synchronous buck converter which operates from 4.5-V to 24-V input voltage (V_{IN}), and the output is from 0.6 V to 7 V. The proprietary D-CAP3 mode enables low external component count, ease of design, optimization of the power design for cost, size, and efficiency. The key feature of the TPS51396A is ultra-low quiescent current (ULQ) mode. This feature is beneficial for long battery life in system standby mode. The device employs D-CAP3 mode control that provides fast transient response with no external compensation components and an accurate feedback voltage. The control topology provides seamless transition between CCM operating mode at higher load condition and DCM operation at lighter load condition. Eco-mode allows the TPS51396A to maintain high efficiency at light load. OOA (out of audio) mode makes switching frequency above audible frequency larger than 25 kHz, even there is no loading at output side. The TPS51396A is able to adapt to both low equivalent series resistance (ESR) output capacitors such as POSCAP or SP-CAP, and ultra-low ESR ceramic capacitors.

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 PWM Operation and D-CAP3 Control

The main control loop of the buck is adaptive on-time pulse width modulation (PWM) controller that supports a proprietary DCAP3 mode control. The DCAP3 mode control combines adaptive on-time control with an internal compensation circuit for pseudo-fixed frequency and low external component count configuration with both low-ESR and ceramic output capacitors. It is stable even with virtually no ripple at the output. The TPS51396A also includes an error amplifier that makes the output voltage very accurate.

At the beginning of each cycle, the high-side MOSFET is turned on. This MOSFET is turned off after internal one-shot timer expires. This one-shot duration is set proportional to the output voltage, V_{OUT} , and is inversely proportional to the converter input voltage, V_{IN} , to maintain a pseudo-fixed frequency over the input voltage range, hence it is called adaptive on-time control. The one-shot timer is reset and the high-side MOSFET is turned on again when the feedback voltage falls below the reference voltage. An internal ripple generation circuit is added to reference voltage for emulating the output ripple, this enables the use of very low-ESR output capacitors such as multi-layered ceramic caps (MLCC). No external current sense network or loop compensation is required for DCAP3 control topology.

For any control topology that is compensated internally, there is a range of the output filter it can support. The output filter used with the TPS51396A is a low-pass L-C circuit. This L-C filter has a double-pole frequency described in 式 1.

$$f_p = \frac{1}{2 \times \pi \times \sqrt{L_{OUT} \times C_{OUT}}} \quad (1)$$

At low frequency, the overall loop gain is set by the output set-point resistor divider network and the internal gain of the TPS51396A. The low-frequency L-C double pole has a 180 degree drop in phase. At the output filter frequency, the gain rolls off at a –40 dB per decade rate and the phase drops rapidly. The internal ripple generation network introduces a high-frequency zero that reduces the gain roll off from –40 dB to –20 dB per decade and leads the 90 degree phase boost. The internal ripple injection high-frequency zero is related to the switching frequency. The crossover frequency of the overall system should usually be targeted to be less than one-third of the switching frequency (F_{SW}).

7.3.2 Soft Start

The TPS51396A has an internal 1.3-ms soft start, and also an external SS pin is provided for setting higher soft-start time if needed. When the EN pin becomes high, the soft-start function begins ramping up the reference voltage to the PWM comparator.

If the application needs a larger soft start time, it can be set by connecting a capacitor on SS pin. When the EN pin becomes high, the soft-start charge current (I_{SS}) begins charging the external capacitor (C_{SS}) connected between SS and AGND. The device tracks the lower of the internal soft-start voltage or the external soft-start voltage as the reference. The equation for the soft-start time (T_{SS}) is shown in 式 2:

$$T_{SS} = \frac{C_{SS}(\text{nF}) \times V_{REF}(\text{V})}{I_{SS}(\mu\text{A})} \quad (2)$$

where

- V_{REF} is 0.6 V and I_{SS} is 5 μA

7.3.3 Large Duty Operation

The TPS51396A can support large duty operations by its internal T_{ON} extension function. When the $V_{IN}/V_{OUT} < 1.6$, and the V_{FB} is lower than internal V_{REF} , the T_{ON} will be extended to implement the large duty operation and also improve the performance of the load transient performance.

7.3.4 Power Good

The Power Good (PGOOD) pin is an open-drain output. Once the V_{FB} is between 90% and 110% of the target output voltage, the PGOOD is de-asserted and floats after a 1-ms de-glitch time. A 100 k Ω pullup resistor is recommended to pull the voltage up to VCC. The PGOOD pin is pulled low when:

- the FB pin voltage is lower than 85% or greater than 115% of the target output voltage
- in an OVP, UVP, or thermal shutdown event
- during the soft-start period.

7.3.5 Over Current Protection and Undervoltage Protection

The TPS51396A has the over current protection and undervoltage protection. The output over current limit (OCL) is implemented using a cycle-by-cycle valley detect circuit. The switch current is monitored during the OFF state by measuring the low-side FET drain to source voltage. This voltage is proportional to the switch current. To improve accuracy, the voltage sensing is temperature compensated.

During the on-time of the high-side FET switch, the switch current increases at a linear rate determined by V_{IN} , V_{OUT} , the on-time and the output inductor value. During the on-time of the low-side FET switch, this current decreases linearly. The average value of the switch current is the load current I_{OUT} . If the monitored current is above the OCL level, the converter maintains low-side FET on and delays the creation of a new set pulse, even the voltage feedback loop requires one, until the current level becomes OCL level or lower. In subsequent switching cycles, the on-time is set to a fixed value and the current is monitored in the same manner.

There are some important considerations for this type of over current protection. When the load current is higher than the over current threshold by one half of the peak-to-peak inductor ripple current, the OCL is triggered and the current is being limited, the output voltage tends to drop because the load demand is higher than what the converter can support. When the output voltage falls below 60% of the target voltage, the UVP comparator detects it, the output will be latched after a wait time of 256 μ s. When the over current condition is removed, the output voltage is latched till the EN is toggled or re-power the power input.

7.3.6 Over Voltage Protection

The TPS51396A has the over voltage protection feature. When the output voltage becomes higher than 125% of the target voltage, the OVP comparator output goes high, the output will be discharged after a wait time of 20 μ s. When the over voltage condition is removed, the output voltage is latched till the EN is toggled or re-power the power input.

7.3.7 UVLO Protection

Undervoltage Lockout protection (UVLO) monitors the V_{IN} power input. When the voltage is lower than UVLO threshold voltage, the device is shut off and output is discharged. This is a non-latch protection.

7.3.8 Output Voltage Discharge

The TPS51396A has the discharge function by using internal MOSFET about 420 Ω $R_{DS(on)}$, which is connected to the output terminal SW. The discharge is slow due to the lower current capability of the MOSFET.

7.3.9 Thermal Shutdown

The TPS51396A monitors the internal die temperature. If the temperature exceeds the threshold value (typically 150 $^{\circ}$ C), the device is shut off and the output will be discharged. This is a non-latched protection, the device restarts switching when the temperature goes below the thermal shutdown threshold.

7.4 Device Functional Modes

7.4.1 Light Load Operation

TPS51396A has a MODE pin which can setup three different modes of operation for light load running and 600 kHz/800 kHz/1 MHz switching frequency at heavy load .The light load running includes out-of-audio mode ,advanced Eco-mode and force CCM mode.

7.4.2 Advanced Eco-mode™ Control

The advanced Eco-mode™ control scheme to maintain high light load efficiency. As the output current decreases from heavy load conditions, the inductor current is also reduced and eventually comes to a point where the rippled valley touches zero level, which is the boundary between continuous conduction and discontinuous conduction modes. The rectifying MOSFET is turned off when the zero inductor current is detected. As the load current further decreases, the converter runs into discontinuous conduction mode. The on-time is kept almost the same as it was in the continuous conduction mode so that it takes longer time to discharge the output capacitor with smaller load current to the level of the reference voltage. This makes the switching frequency lower, proportional to the load current, and keeps the light load efficiency high. The light load current where the transition to Eco-mode™ operation happens ($I_{OUT(LL)}$) can be calculated from 式 3.

$$I_{OUT(LL)} = \frac{1}{2 \times L_{OUT} \times F_{SW}} \times \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{V_{IN}} \quad (3)$$

After identifying the application requirements, design the output inductance (L_{OUT}) so that the inductor peak-to-peak ripple current is approximately between 20% and 30% of the $I_{OUT(max)}$ (peak current in the application). It is also important to size the inductor properly so that the valley current does not hit the negative low-side current limit.

7.4.3 Out of Audio Mode

Out-of-Audio (OOA) light-load mode is a unique control feature that keeps the switching frequency above audible frequency towards a virtual no-load condition. During Out-of-Audio operation, the OOA control circuit monitors the states of both high-side and low-side MOSFETs and forces them switching if both MOSFETs are off for more than 28 μ s. When both high-side and low-side MOSFETs are off for more than 28 μ s during a light-load condition, the lowside FET will be on for discharge till reverse OC happens or output voltage drops to trigger the high-side FET on. This mode initiates one cycle of the low-side MOSFET and the high-side MOSFET turning on. Then, both MOSFETs stay turned off waiting for another 28 μ s.

If the MODE pin is selected to operate in OOA mode, when the device works at light load, the minimum switching frequency is above 25 kHz which avoids the audible noise in the system.

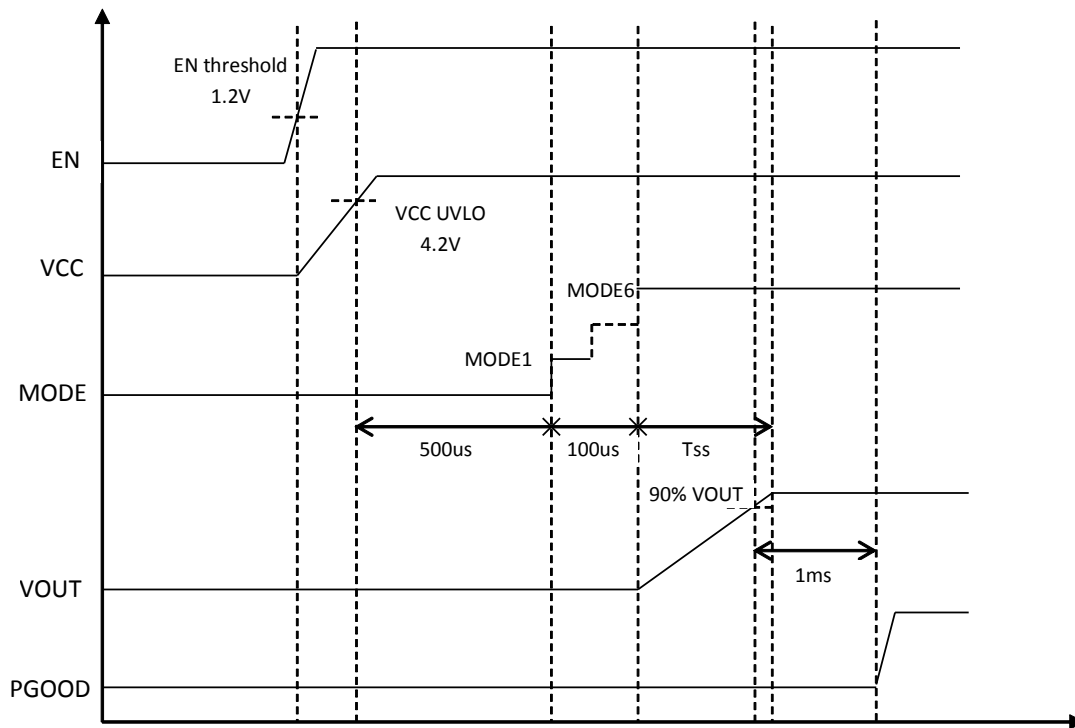
7.4.4 Mode Selection

The device reads the voltage on the MODE pin during start-up and latches onto one of the MODE options listed below in 表 7-1 . The voltage on the MODE pin can be set by connecting this pin to the center tap of a resistor divider connected between VCC and AGND. A guideline for the top resistor (R_{M_H}) and the bottom resistor (R_{M_L}) is shown in 表 7-1, and 1% resistors are recommended. It is important that the voltage for the MODE pin is derived from the VCC rail only since internally this voltage is referenced to detect the MODE option. The MODE pin setting can be reset only by a VIN power cycling or EN toggle.

表 7-1. MODE Pin Resistor Settings

| $R_{M_H}(k\Omega)$ | $R_{M_L}(k\Omega)$ | Light Load Operation | Switching Frequency (kHz) |
|---------------------|---------------------|----------------------|---------------------------|
| 330 | 5.1 | Eco-mode | 600 |
| 330 | 15 | Eco-mode | 800 |
| 330 | 27 | Eco-mode | 1000 |
| 300 | 43 | OOA mode | 600 |
| 150 | 33 | OOA mode | 800 |
| 160 | 51 | OOA mode | 1000 |

☒ 7-1 below shows the typical start-up sequence of the device once the enable signal crosses the EN turn on threshold. After the voltage on VCC crosses the rising UVLO threshold it takes about 500us to read the first mode setting and approximately 100us from there to finish the last mode setting. The output voltage starts ramping after the mode reading is done.



7-1. Power-Up Sequence

7.4.5 Standby Operation

The TPS51396A can be placed in standby mode by pulling the EN pin low. The device operates with a shutdown current of 2 μA when in standby condition. EN pin is pulled low internally, when float, the part is disabled by default.

8 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

8.1 Application Information

The schematic of [Figure 8-1](#) shows a typical application for TPS51396A with 1-V output. This design converts an input voltage range of 4.5 V to 24 V down to 1 V with a maximum output current of 8 A.

8.2 1V Output Typical Application

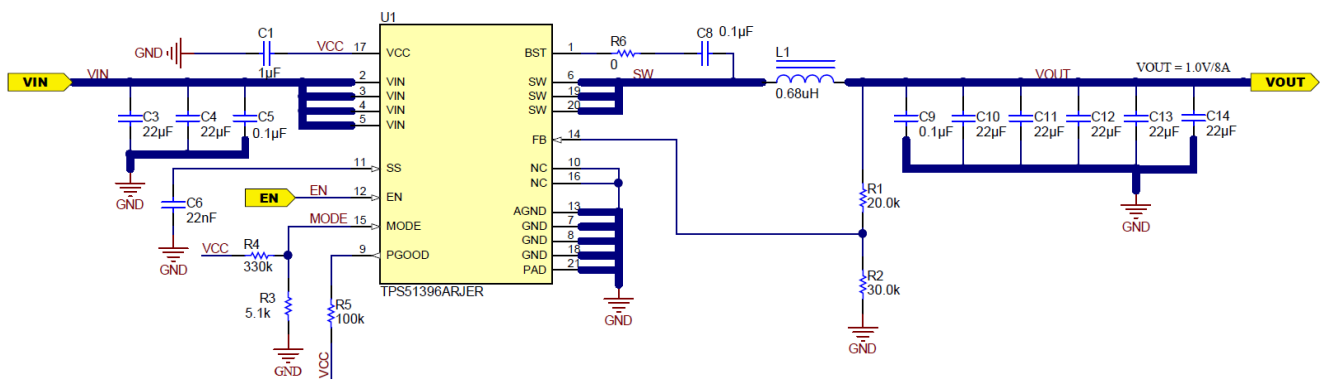


Figure 8-1. 1V/8A Reference Design with Eco-mode, $F_{sw} = 600$ kHz

8.2.1 Design Requirements

[Table 8-1](#) lists the design parameters for this example.

Table 8-1. Design Parameters

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNIT |
|-------------------|-----------------------------|------------------------------|----------|-----|---------------------|
| OUTPUT | | | | | |
| V_{OUT} | Output voltage | | 1 | | V |
| I_{OUT} | Output current | | 8 | | A |
| ΔV_{OUT} | Transient response | 0 A - 8 A load step, 2.5A/us | | ±40 | mV |
| V_{IN} | Input voltage | 4.5 | 12 | 24 | V |
| $V_{OUT(ripple)}$ | Output voltage ripple (CCM) | | 18 | | mV _(p-p) |
| F_{SW} | Switching frequency | | 600 | | kHz |
| | Light load operating mode | | Eco-mode | | |
| T_A | Ambient temperature | | 25 | | °C |

8.2.2 Detailed Design Procedure

8.2.2.1 External Component Selection

8.2.2.1.1 Output Voltage Set Point

To change the output voltage of the application, it is necessary to change the value of the upper feedback resistor. By changing this resistor the user can change the output voltage above 0.6 V. See [Equation 4](#)

$$V_{OUT} = 0.6 \times \left(1 + \frac{R_{UPPER}}{R_{LOWER}}\right) \quad (4)$$

8.2.2.1.2 Inductor Selection

The inductor ripple current is filtered by the output capacitor. A higher inductor ripple current means the output capacitor should have a ripple current rating higher than the inductor ripple current. See [表 8-2](#) for recommended inductor values.

The RMS and peak currents through the inductor can be calculated using [式 5](#) and [式 6](#). It is important that the inductor is rated to handle these currents.

$$I_{L(RMS)} = \sqrt{\left[I_{OUT}^2 + \frac{1}{12} \times \left(\frac{V_{OUT} \times (V_{IN(max)} - V_{OUT})}{V_{IN(max)} \times L_{OUT} \times F_{SW}} \right)^2 \right]} \quad (5)$$

$$I_{L(peak)} = I_{OUT} + \frac{I_{L(ripple)}}{2} \quad (6)$$

During transient and short-circuit conditions, the inductor current can increase up to the current limit of the device so it is safe to choose an inductor with a saturation current higher than the peak current under current limit condition.

8.2.2.1.3 Output Capacitor Selection

After selecting the inductor the output capacitor needs to be optimized. In DCAP3™, the regulator reacts within one cycle to the change in the duty cycle so the good transient performance can be achieved without needing large amounts of output capacitance. The recommended output capacitance range is given in [表 8-2](#).

Ceramic capacitors have very low ESR, otherwise the maximum ESR of the capacitor should be less than $V_{OUT(ripple)}/I_{OUT(ripple)}$.

表 8-2. Recommended Component Values

| V _{OUT} (V) | R _{LOWER} (kΩ) | R _{UPPER} (kΩ) | F _{sw} (kHz) | L _{OUT} (μH) | C _{OUT(min)} (μF) | C _{OUT(max)} (μF) | C _{FF} (PF) |
|----------------------|-------------------------|-------------------------|-----------------------|-----------------------|----------------------------|----------------------------|----------------------|
| 0.6 | 10 | 0 | 600 | 0.47 | 66 | 500 | - |
| | | | 800 | 0.33 | 66 | 500 | - |
| | | | 1000 | 0.27 | 66 | 500 | - |
| 1 | 30 | 20 | 600 | 0.68 | 66 | 500 | - |
| | | | 800 | 0.47 | 66 | 500 | - |
| | | | 1000 | 0.33 | 66 | 500 | - |
| 3.3 | 20 | 90 | 600 | 1.5 | 66 | 500 | 47-330 |
| | | | 800 | 1.2 | 66 | 500 | 47-330 |
| | | | 1000 | 1 | 66 | 500 | 47-330 |
| 5.0 | 30 | 220 | 600 | 2.2 | 66 | 500 | 47-330 |
| | | | 800 | 1.5 | 66 | 500 | 47-330 |
| | | | 1000 | 1.2 | 66 | 500 | 47-330 |

8.2.2.1.4 Input Capacitor Selection

The TPS51396A requires input decoupling capacitors on power supply input VIN, and the bulk capacitors are needed depending on the application. The minimum input capacitance required is given in 式 7.

$$C_{IN(min)} = \frac{I_{OUT} \times V_{OUT}}{V_{IN(ripple)} \times V_{IN} \times F_{SW}} \quad (7)$$

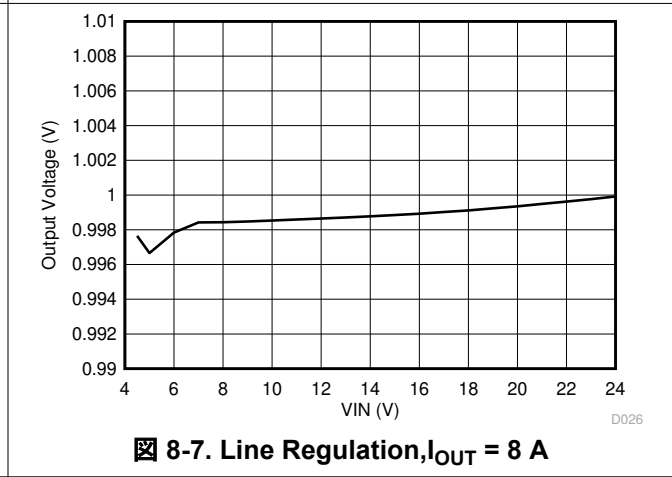
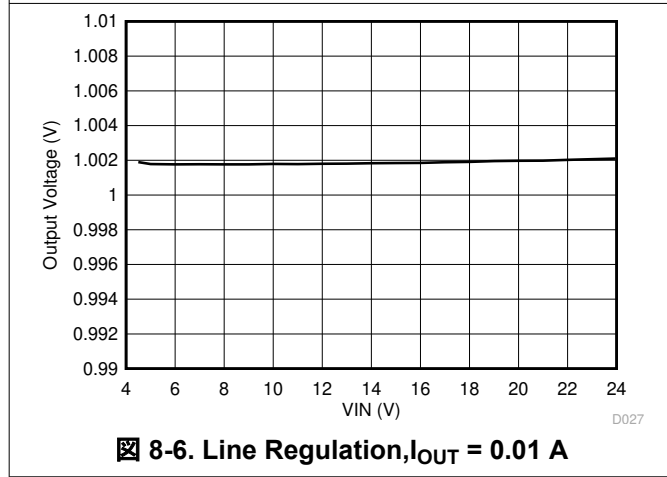
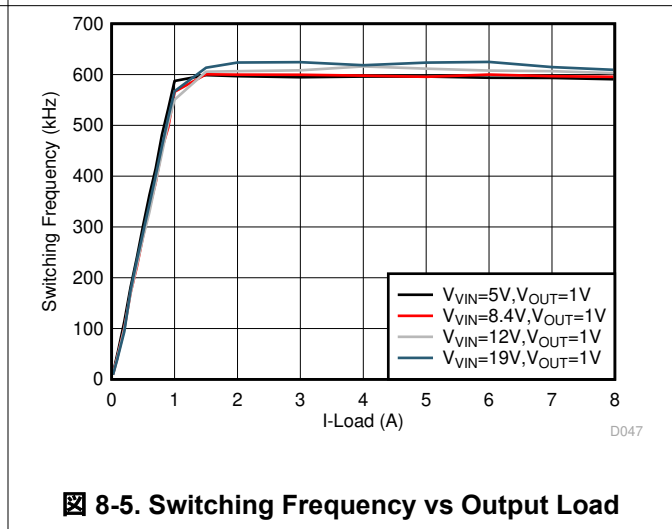
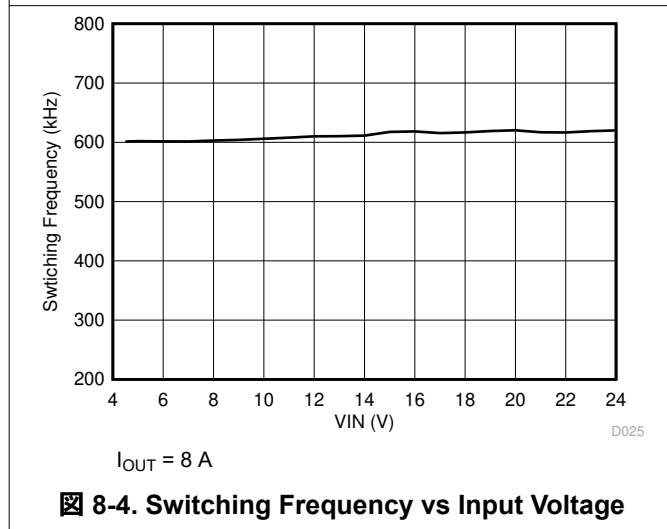
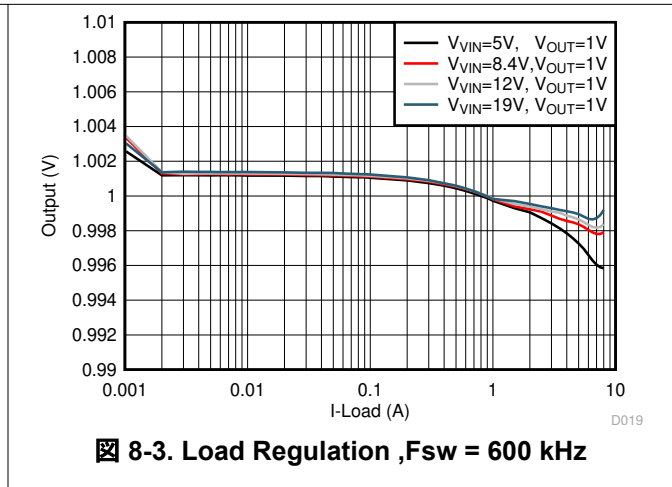
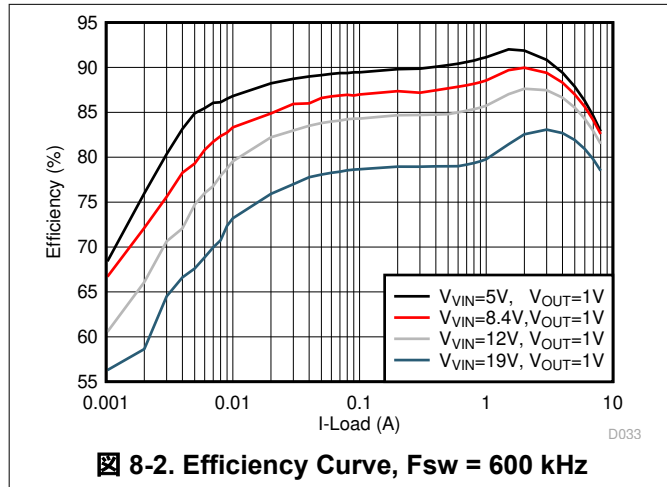
TI recommends using a high-quality X5R or X7R input decoupling capacitors of 40 μF on the input voltage pin VIN. The voltage rating on the input capacitor must be greater than the maximum input voltage. The capacitor must also have a ripple current rating greater than the maximum input current ripple of the application. The input ripple current is calculated by 式 8:

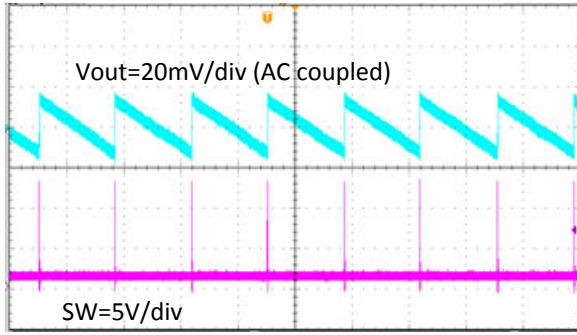
$$I_{CIN(rms)} = I_{OUT} \times \sqrt{\frac{V_{OUT}}{V_{IN(min)}} \times \frac{(V_{IN(min)} - V_{OUT})}{V_{IN(min)}}} \quad (8)$$

A 1-μF ceramic capacitor is needed for the decoupling capacitor on VCC pin.

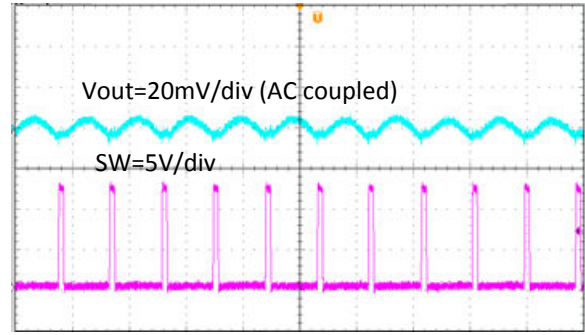
8.2.3 Application Curves

☒ 8-2 through ☒ 8-15 apply to the circuit of ☒ 8-1. $V_{IN} = 12\text{ V}$. $T_J = 25^\circ\text{C}$ unless otherwise specified.

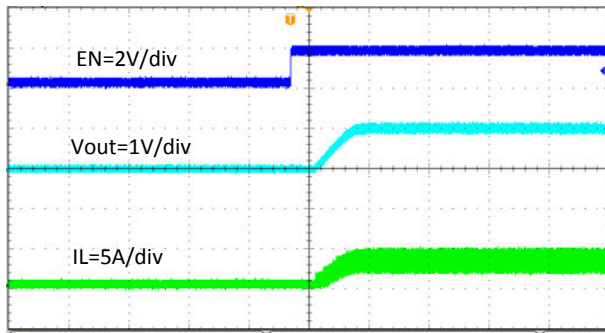




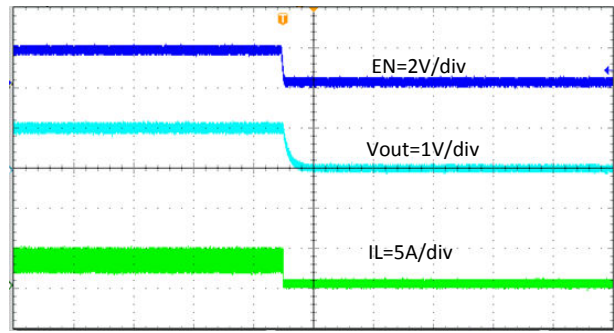
8-8. Output Voltage Ripple, $I_{OUT} = 0.01\text{ A}$



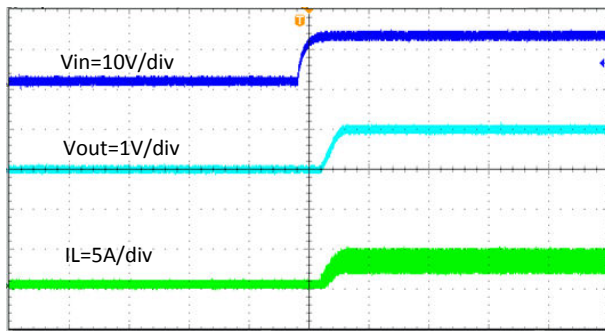
8-9. Output Voltage Ripple, $I_{OUT} = 8\text{ A}$



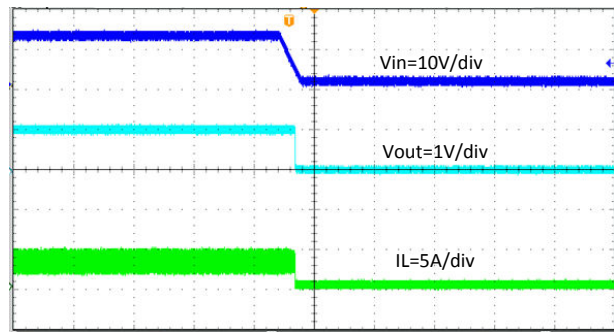
8-10. Start-Up Through EN, $I_{OUT} = 4\text{ A}$



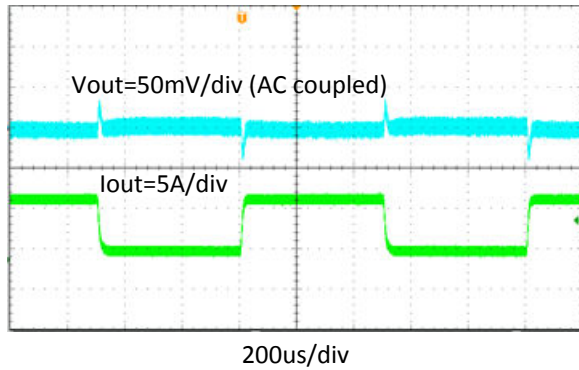
8-11. Shut-down Through EN, $I_{OUT} = 4\text{ A}$



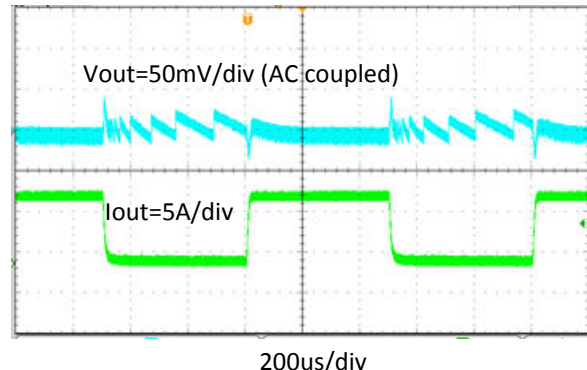
8-12. Start Up Relative to V_{IN} Rising, $I_{OUT} = 4\text{ A}$



8-13. Start Up Relative to V_{IN} Falling, $I_{OUT} = 4\text{ A}$



ASlew Rate=2.5A/us

 **8-14. Transient Response, 0.8 A to 7.2 A**


ASlew Rate=2.5A/us

 **8-15. Transient Response, 0 A to 8 A**

9 Power Supply Recommendations




The TPS51396A is intended to be powered by a well regulated dc voltage. The input voltage range is 4.5 to 24 V. TPS51396A is a buck converter. The input supply voltage must be greater than the desired output voltage for proper operation. Input supply current must be appropriate for the desired output current. If the input voltage supply is located far from the TPS51396A circuit, additional input bulk capacitance is recommended, typical values are 100 μ F to 470 μ F.

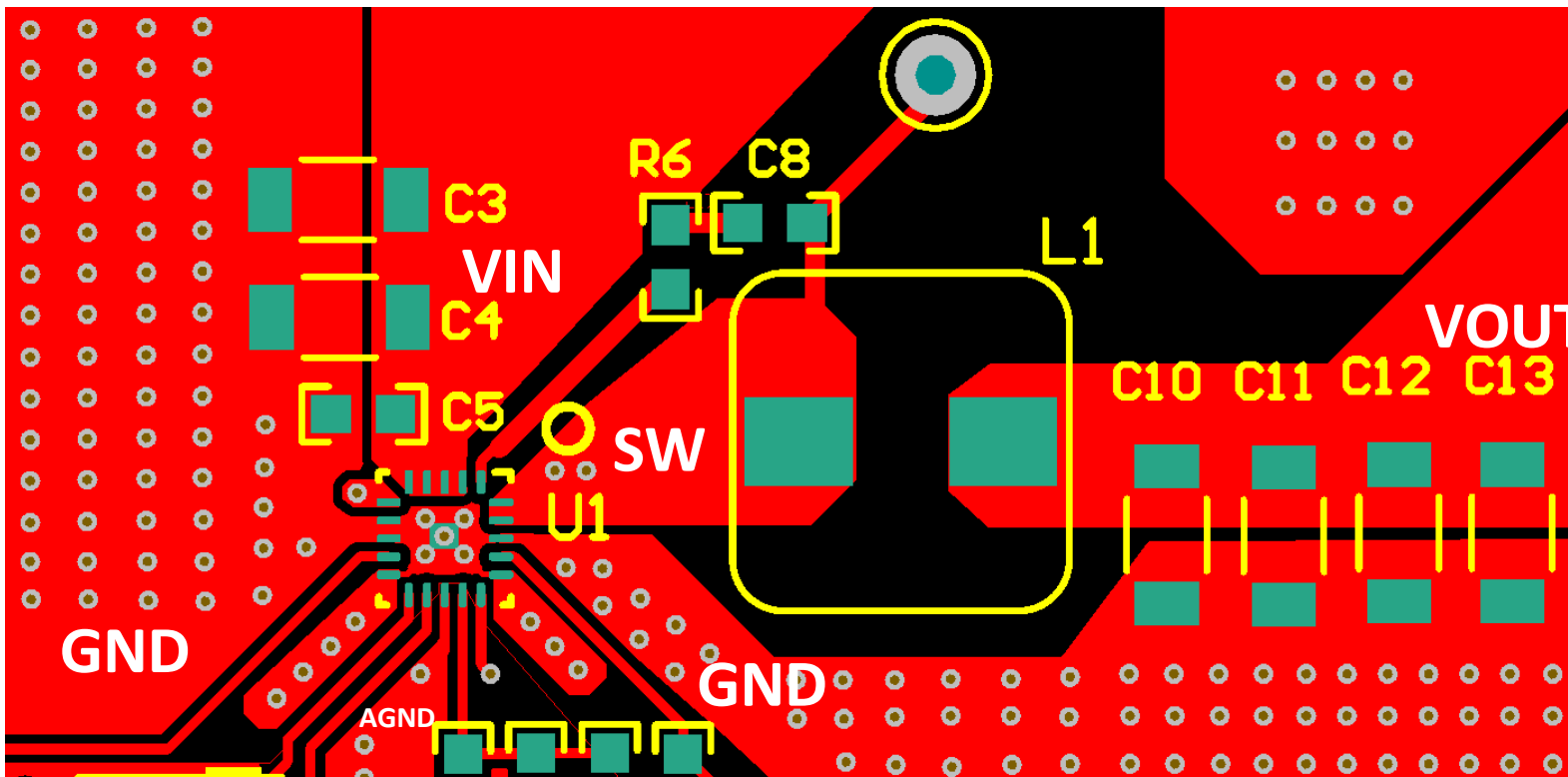
10 Layout

10.1 Layout Guidelines

- TI recommends a four-layer PCB for good thermal performance and with maximum ground plane. 3-inch × 3-inch, four-layer PCB with 2-oz copper is used as example.
- Place the decoupling capacitors right across VIN and VCC as close as possible.
- Place output inductor and capacitors with IC at the same layer, SW routing should be as short as possible to minimize EMI, and should be a width plane to carry big current, enough vias should be added to the GND connection of output capacitor and also as close to the output pin as possible.
- Place BST resistor and capacitor with IC at the same layer, close to BST and SW plane, >15 mil width trace is recommended to reduce line parasitic inductance.
- Feedback could be 20 mil and must be routed away from the switching node, BST node or other high efficiency signal.
- VIN trace must be wide to reduce the trace impedance and provide enough current capability.
- Place multiple vias under the device near VIN and GND and near input capacitors to reduce parasitic inductance and improve thermal performance

10.2 Layout Example

 10-1 shows the recommended top-side layout. Component reference designators are the same as the circuit shown in  8-1. Resistor divider for EN is not used in the circuit of  8-1, but are shown in the layout for reference.



 10-1. Top-Layer Layout

11 Device and Documentation Support

11.1 Device Support

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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

11.6 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

| Orderable Device | Status (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan (2) | Lead finish/ Ball material (6) | MSL Peak Temp (3) | Op Temp (°C) | Device Marking (4/5) | Samples |
|------------------|---------------|--------------|-----------------|------|-------------|-----------------|--------------------------------------|----------------------|--------------|-------------------------|-------------------------|
| TPS51396ARJER | ACTIVE | VQFN-HR | RJE | 20 | 3000 | RoHS & Green | Call TI SN | Level-2-260C-1 YEAR | -40 to 125 | 51396A | Samples |
| TPS51396ARJET | ACTIVE | VQFN-HR | RJE | 20 | 250 | RoHS & Green | Call TI SN | Level-2-260C-1 YEAR | -40 to 125 | 51396A | Samples |

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSELETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

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Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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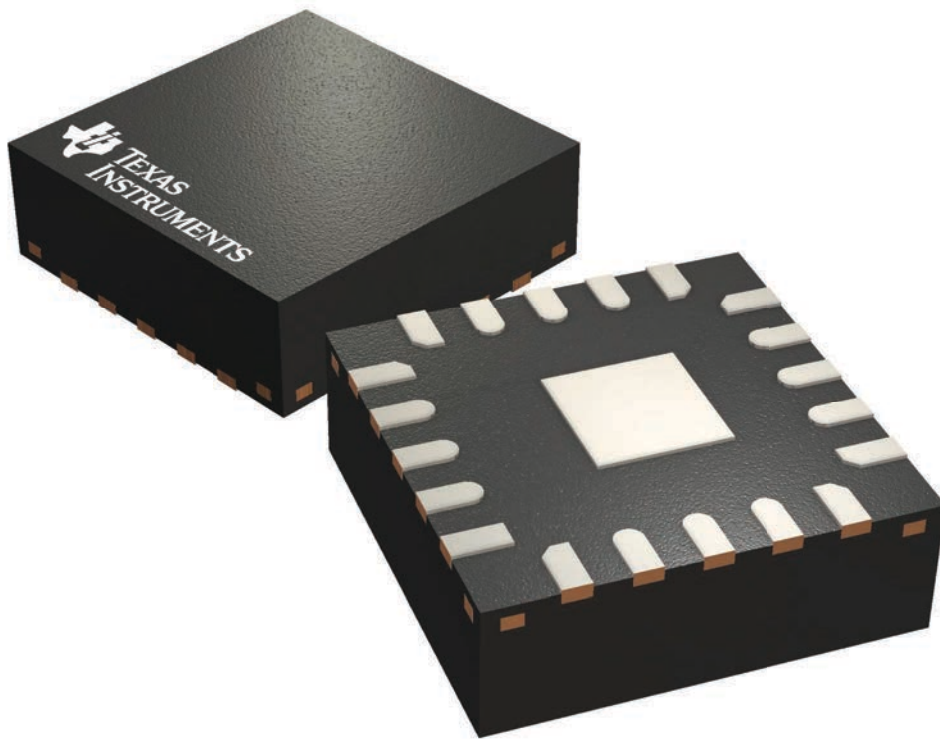
GENERIC PACKAGE VIEW

RJE 20

VQFN-HR - 1 mm max height

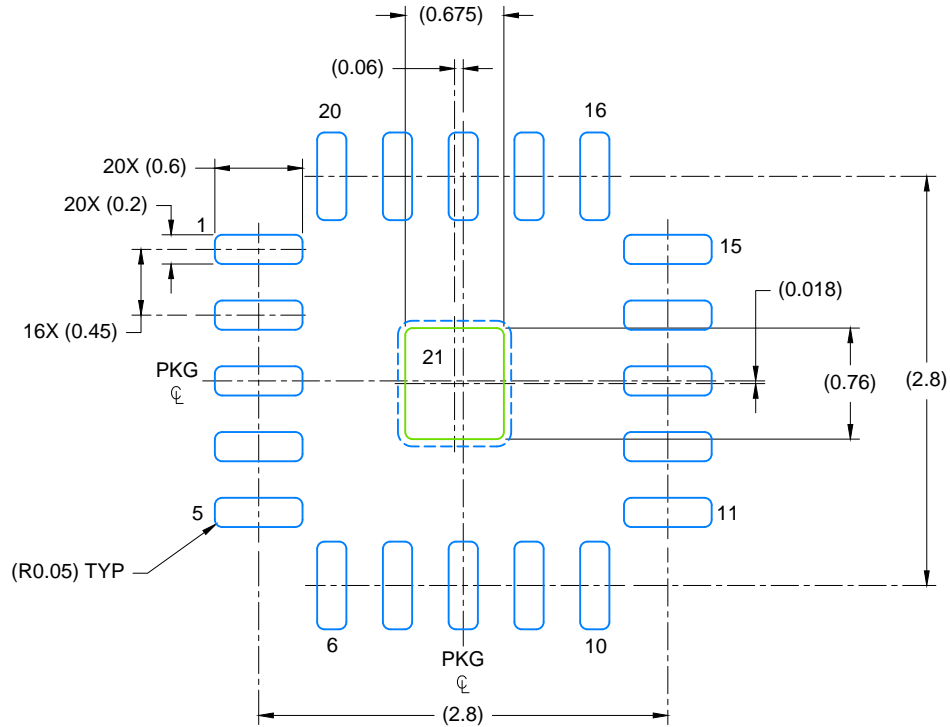
3 x 3, 0.45 mm pitch

QUAD FLATPACK- NO LEAD

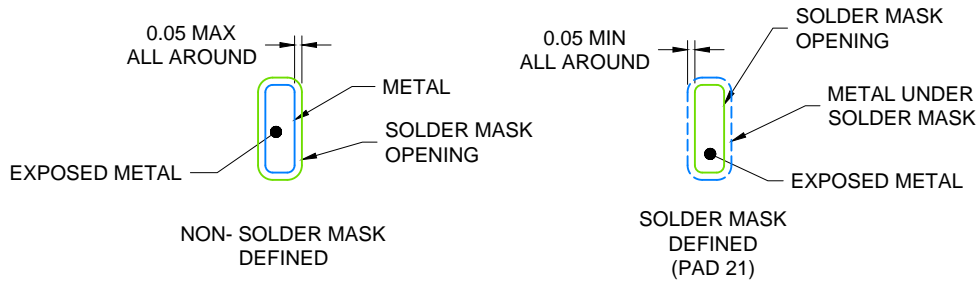


Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

4224683/A



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE: 20X

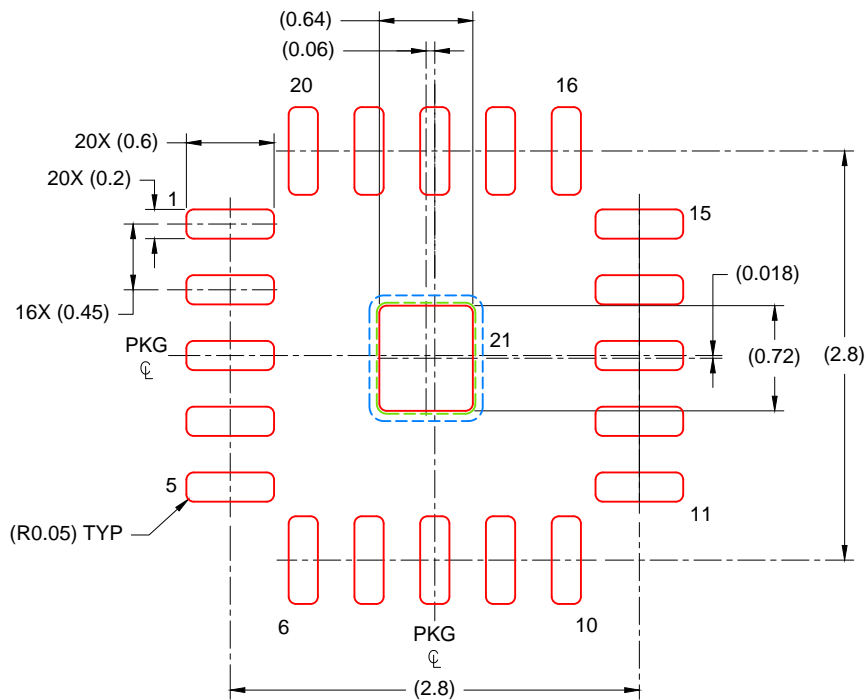


SOLDER MASK DETAILS

4223546 / B 08/2017

NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SOLDER PASTE EXAMPLE
 BASED ON 0.1 mm THICK STENCIL
 PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE
 PAD 21: 90%
 SCALE: 20X

4223546 / B 08/2017

NOTES: (continued)

- 6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations..

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