

TPS631012 および TPS631013 ウェハ・チップ・スケール・パッケージに I²C 搭載、1.6V~5.5V 入力電圧 1.5A 昇降圧コンバータ

1 特長

- 入力電圧範囲: 1.6V~5.5V
 - スタートアップ時のデバイス入力電圧 > 1.65V
- 1.0V~5.5V の出力電圧範囲 (調整可能)
- 高い出力電流能力、3A ピーク・スイッチ電流
 - $V_{IN} \geq 3V$, $V_{OUT} = 3.3V$ 時の I_{OUT} は 2A
 - $V_{IN} \geq 2.7V$, $V_{OUT} = 3.3V$ 時の I_{OUT} は 1.5A
- 全負荷範囲にわたって高効率を実現
 - 静止電流 8 μ A (標準値)
 - 自動パワー・セーブ・モードおよび強制 PWM モードを構成可能
- ピーク電流昇降圧モード・アーキテクチャ
 - シームレスなモード遷移
 - 順方向および逆方向電流動作
 - あらかじめ出力にバイアスを印加した状態で起動
 - 2MHz スwitchングの固定周波数動作
- 安全で堅牢な動作を実現する機能
 - 過電流保護および短絡保護
 - アクティブ・ランプを採用したソフト・スタート機能内蔵
 - 過熱保護および過電圧保護
 - 負荷切断による真のシャットダウン機能
 - 順方向および逆方向の電流制限
- 内部 EN のデフォルト設定
 - TPS631012 および TPS631012X(X=1,2,3):
CONVERTER_EN = 0
 - TPS631013: CONVERTER_EN = 1
- 小型ソリューション・サイズ
 - 小型 1 μ H インダクタ
 - 1.803mm × 0.905 mm (WCSP)

2 アプリケーション

- TWS
- システム・プリレギュレータ (スマートフォン、タブレット、端末、テレマティクス)
- ポイント・オブ・ロード・レギュレーション (有線センサ、ポート / ケーブル・アダプタ、ドングル)
- 指紋、カメラ・センサ (電子スマート・ロック、IP ネットワーク・カメラ)
- 電圧スタビライザ (データコム、光モジュール、冷却 / 加熱)

3 概要

TPS631012 および TPS631013 は、超小型ウェハ・チップ・スケール・パッケージに封止された定周波数ピーク電流モード制御昇降圧コンバータです。3A のピーク電流制限 (標準値) と 1.6V~5.5V の入力電圧範囲を備え、システム・プリレギュレータと電圧スタビライザの電源ソリューションを提供します。

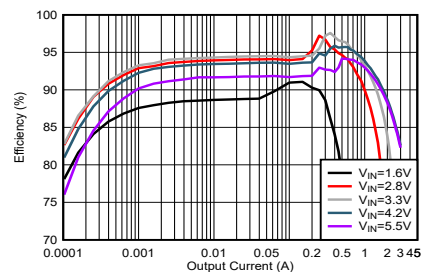
入力電圧に応じて自動的に昇圧モード、降圧モード、3 サイクル昇降圧モード (入力電圧が出力電圧とほぼ等しい場合) で動作します。モード間の遷移は定義されたデューティ・サイクルで発生し、モード間の不要な切り替えが避けられるので出力電圧リップルを減らすことができます。8 μ A の静止電流とパワー・セーブ・モードにより、軽負荷から無負荷までの状況で最高の効率を実現します。

これらのデバイスは、WCSP で非常に小型のソリューション・サイズを実現しています。

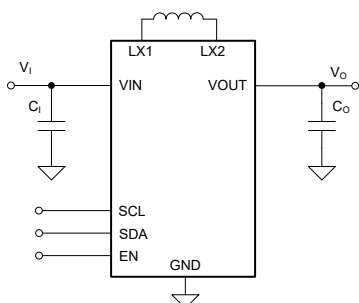
パッケージ情報

部品番号	パッケージ (1)	本体サイズ (公称)
TPS631012	WCSP	1.803mm × 0.905mm
TPS631013(2)		

- 利用可能なパッケージについては、このデータシートの末尾にある注文情報を参照してください。
- プレビュー情報 (製品データではありません)。



効率と出力電流との関係 ($V_{OUT} = 3.3V$)



代表的なアプリケーション



Table of Contents

1 特長	1	8.4 Device Functional Modes.....	11
2 アプリケーション	1	8.5 Programming	12
3 概要	1	8.6 Register Map.....	14
4 Revision History	2	9 Application and Implementation	17
5 Device Comparison Table	3	9.1 Application Information.....	17
6 Pin Configuration and Functions	4	9.2 Typical Application.....	17
7 Specifications	5	9.3 Power Supply Recommendations.....	23
7.1 Absolute Maximum Ratings.....	5	9.4 Layout.....	23
7.2 ESD Rating.....	5	10 Device and Documentation Support	25
7.3 Recommended Operating Conditions.....	5	10.1 Device Support	25
7.4 Thermal Information.....	5	10.2 ドキュメントの更新通知を受け取る方法.....	25
7.5 Electrical Characteristics	6	10.3 サポート・リソース.....	25
7.6 Timing Requirements.....	7	10.4 Trademarks.....	25
8 Detailed Description	8	10.5 静電気放電に関する注意事項.....	25
8.1 Overview.....	8	10.6 用語集.....	25
8.2 Functional Block Diagram.....	8	11 Mechanical, Packaging, and Orderable Information	26
8.3 Feature Description	8		

4 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

DATE	REVISION	NOTES
July 2023	*	Advance Information

5 Device Comparison Table

PART NUMBER	Default Setting of Internal EN ⁽³⁾	I ² C Target Address
TPS631012	CONVERTER_EN = 0	0x2A
TPS6310121 ⁽¹⁾ ⁽²⁾	CONVERTER_EN = 0	0x28
TPS6310122 ⁽¹⁾ ⁽²⁾	CONVERTER_EN = 0	0x29
TPS6310123 ⁽¹⁾ ⁽²⁾	CONVERTER_EN = 0	0x2B
TPS631013 ⁽¹⁾ ⁽²⁾	CONVERTER_EN = 1	0x2A

- (1) Product Preview. Contact TI factory for more information.
 (2) TPS631012 and TPS631012X(X = 1, 2, 3) differ only in the I2C target address.
 (3) Refer to the [Register CONTROL1](#).

6 Pin Configuration and Functions

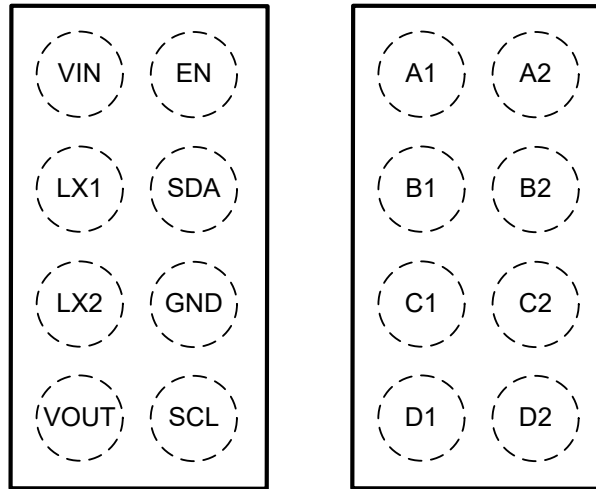


图 6-1. 8-Pin YBG WCSP Package (Top View)

表 6-1. Pin Functions

PIN		I/O ⁽¹⁾	DESCRIPTION
NAME	NO.		
VIN	A1	PWR	Supply input voltage
EN	A2	I	Device enable. Set high to enable and low to disable. It must not be left floating.
LX1	B1	PWR	Inductor switching node of the buck stage
SDA	B2	I	I ² C serial interface data. Pull this pin up to the I ² C bus voltage with a resistor.
LX2	C1	PWR	Inductor switching node of the boost stage
GND	C2	PWR	Power ground
VOUT	D1	PWR	Power stage output
SCL	D2	I	I ² C serial interface clock. Pull this pin up to the I ² C bus voltage with a resistor.

(1) PWR = power, I = input

7 Specifications

7.1 Absolute Maximum Ratings

over operating junction temperature range (unless otherwise noted)⁽¹⁾

		MIN	MAX	UNIT
V _I	Input voltage (VIN, LX1, LX2, VOUT, EN, SCL, SDA) ⁽²⁾	-0.3	6.0	V
	Input voltage for less than 10 ns (LX1, LX2) ⁽²⁾	-2.0	7.0	V
T _J	Operating junction temperature	-40	150	°C
T _{stg}	Storage temperature	-65	150	°C

- Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.
- All voltage values are with respect to network ground terminal, unless otherwise noted.

7.2 ESD Rating

			VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±1000	V
		Charged-device model (CDM), per JEDEC specification JS-002 ⁽²⁾	± 500	

- JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating junction temperature (unless otherwise noted)

			MIN	NOM	MAX	UNIT
V _I	Supply voltage		1.6		5.5	V
V _O	Output voltage		1.0		5.5	V
C _I	Effective Input capacitance	V _I = 1.6 V to 5.5 V	4.2			μF
C _O	Effective Output capacitance	1.2 V ≤ V _O ≤ 3.6 V, nominal value at V _O = 3.3 V	10.4	16.9	330	μF
		3.6 V < V _O ≤ 5.5 V, nominal value at V _O = 5 V	7.95	10.6	330	μF
L	Effective Inductance		0.7	1	1.3	μH
T _J	Operating junction temperature range		-40		125	°C

7.4 Thermal Information

over operating free-air temperature range (unless otherwise noted)

THERMAL METRIC		TPS631012 TPS631013	UNIT
		YBG(WCSP)	
		8 pins	
R _{θJA}	Junction-to-ambient thermal resistance	84	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	0.7	°C/W
R _{θJB}	Junction-to-board thermal resistance	43.9	°C/W
Ψ _{JT}	Junction-to-top characterization parameter	2.9	°C/W
Ψ _{JB}	Junction-to-board characterization parameter	43.7	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	N/A	°C/W

7.5 Electrical Characteristics

Over operating junction temperature range and recommended supply voltage range (unless otherwise noted). Typical values are at $V_I = 3.8\text{ V}$, $V_O = 3.3\text{ V}$ and $T_J = 25^\circ\text{C}$ (unless otherwise noted).

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT	
SUPPLY								
I_{SD}	Shutdown current into VIN	$V_I = 3.8\text{ V}$, $V_{(EN)} = 0\text{ V}$	$T_J = 25^\circ\text{C}$		0.5	0.9	μA	
I_Q	Quiescent current into VIN	$V_I = 2.2\text{ V}$, $V_O = 3.3\text{ V}$, $V_{(EN)} = 2.2\text{ V}$, no switching			0.15	6.1	μA	
I_Q	Quiescent current into VOUT	$V_I = 2.2\text{ V}$, $V_O = 3.3\text{ V}$, $V_{(EN)} = 2.2\text{ V}$, no switching			8		μA	
V_{IT+}	Positive-going UVLO threshold voltage	V_I rising		1.5	1.55	1.599	V	
V_{IT-}	Negative-going UVLO threshold voltage	V_I falling		1.4	1.45	1.499	V	
V_{hys}	UVLO threshold voltage hysteresis			99			mV	
$V_{I(POR)T+}$	Positive-going POR threshold voltage ⁽¹⁾	maximum of V_I or V_O		1.25	1.45	1.65	V	
$V_{I(POR)T-}$	Negative-going POR threshold voltage ⁽¹⁾			1.22	1.43	1.6	V	
I/O SIGNALS								
V_{T+}	Positive-going threshold voltage	EN, SDA, SCL		0.77	0.98	1.2	V	
V_{T-}	Negative-going threshold voltage	EN, SDA, SCL		0.5	0.66	0.76	V	
V_{hys}	Hysteresis voltage	EN, SDA, SCL			300		mV	
I_{IH}	High-level input current	EN, SDA, SCL	$V_{(EN)} = V_{(SDA)} = V_{(SCL)} = 1.5\text{ V}$, no pullup resistor		± 0.01	± 0.25	μA	
I_{IL}	Low-level input current	EN, SDA, SCL	$V_{(EN)} = V_{(SDA)} = V_{(SCL)} = 0\text{ V}$		± 0.01	± 0.1	μA	
I_{IB}	Input bias current	EN, SDA, SCL	$V_{(EN)} = 5.5\text{ V}$		± 0.01	± 0.3	μA	
POWER SWITCH								
$r_{DS(on)}$	On-state resistance	Q1	$V_I = 3.8\text{ V}$, $V_O = 3.3\text{ V}$, test current = 0.2 A		45		m Ω	
		Q2			50		m Ω	
		Q3			50		m Ω	
		Q4			85		m Ω	
CURRENT LIMIT								
$I_{L(PEAK)}$	Switch peak current limit ⁽²⁾	Q1	$V_O = 3.3\text{ V}$	Output sourcing current	2.6	3	3.35	A
				Output sinking current, $V_I = 3.3\text{ V}$	-0.7	-0.55	-0.45	A
I_{PFM_entry}	PFM mode entry threshold (peak) current ⁽²⁾		I_O falling		145		mA	
PROTECTION FEATURES								
$V_{T+(OVP)}$	Positive-going OVP threshold voltage			5.55	5.75	5.95	V	
$V_{T+(IVP)}$	Positive-going IVP threshold voltage			5.55	5.75	5.95	V	
T_{SD_R}	Thermal shutdown threshold temperature		T_J rising		160		$^\circ\text{C}$	
T_{SD_HYS}	Thermal shutdown hysteresis				25		$^\circ\text{C}$	
TIMING PARAMETERS								
$t_{d(EN)}$	Delay between a rising edge on the EN pin and the start of the output voltage ramp				0.87	1.5	ms	
$t_{d(ramp)}$	Soft-start ramp time				6.42	7.55	8.68	ms
f_{sw}	Switching frequency				1.8	2	2.2	MHz

- (1) The POR (Power On Reset) threshold is the minimum supply of the internal VMAX block that allows the device to operate
- (2) Current limit production test are performed under DC conditions. The current limit in operation is somewhat higher and depending on propagation delay and the applied external components

7.6 Timing Requirements

Over operating junction temperature range and recommended supply voltage range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	NOM	MAX	UNIT
I²C INTERFACE						
f _{SCL}	SCL clock frequency	Standard mode	0		100	kHz
		Fast mode	0		400	
		Fast mode plus ⁽¹⁾	0		1000	
t _{LOW}	LOW period of the SCL clock	Standard mode	4.7			μs
		Fast mode	1.3			
		Fast mode plus ⁽¹⁾	0.5			
t _{HIGH}	HIGH period of the SCL clock	Standard mode	4.0			μs
		Fast mode	0.6			
		Fast mode plus ⁽¹⁾	0.26			
t _{BUF}	Bus free time between a STOP and a START condition	Standard mode	4.7			μs
		Fast mode	1.3			
		Fast mode plus ⁽¹⁾	0.5			
t _{SU:STA}	Set-up time for a repeated START condition	Standard mode	4.7			μs
		Fast mode	0.6			
		Fast mode plus ⁽¹⁾	0.26			
t _{HD:STA}	Hold time (repeated) START condition	Standard mode	4.0			μs
		Fast mode	0.6			
		Fast mode plus ⁽¹⁾	0.26			
t _{HD:DAT}	Data hold time	Standard mode	0			μs
		Fast mode	0			
		Fast mode plus ⁽¹⁾	0			
t _r	Rise time of both SDA and SCL signals	Standard mode			1000	ns
		Fast mode	20		300	
		Fast mode plus ⁽¹⁾			20	
t _f	Fall time of both SDA and SCL signals	Standard mode			300	ns
		Fast mode	20×V _{DD} /5.5		300	
		Fast mode plus ⁽¹⁾	20×V _{DD} /5.5		120	
t _{SU:STO}	Set-up time for STOP condition	Standard mode	4.0			μs
		Fast mode	0.6			
		Fast mode plus ⁽¹⁾	0.26			
t _{VD:DAT}	Data valid time	Standard mode			3.45	μs
		Fast mode			0.9	
		Fast mode plus ⁽¹⁾			0.45	
t _{VD:ACK}	Data valid acknowledge time	Standard mode			3.45	μs
		Fast mode			0.9	
		Fast mode plus ⁽¹⁾			0.45	
C _b	Capacitive load for each bus line	Standard mode			400	pF
		Fast mode			400	

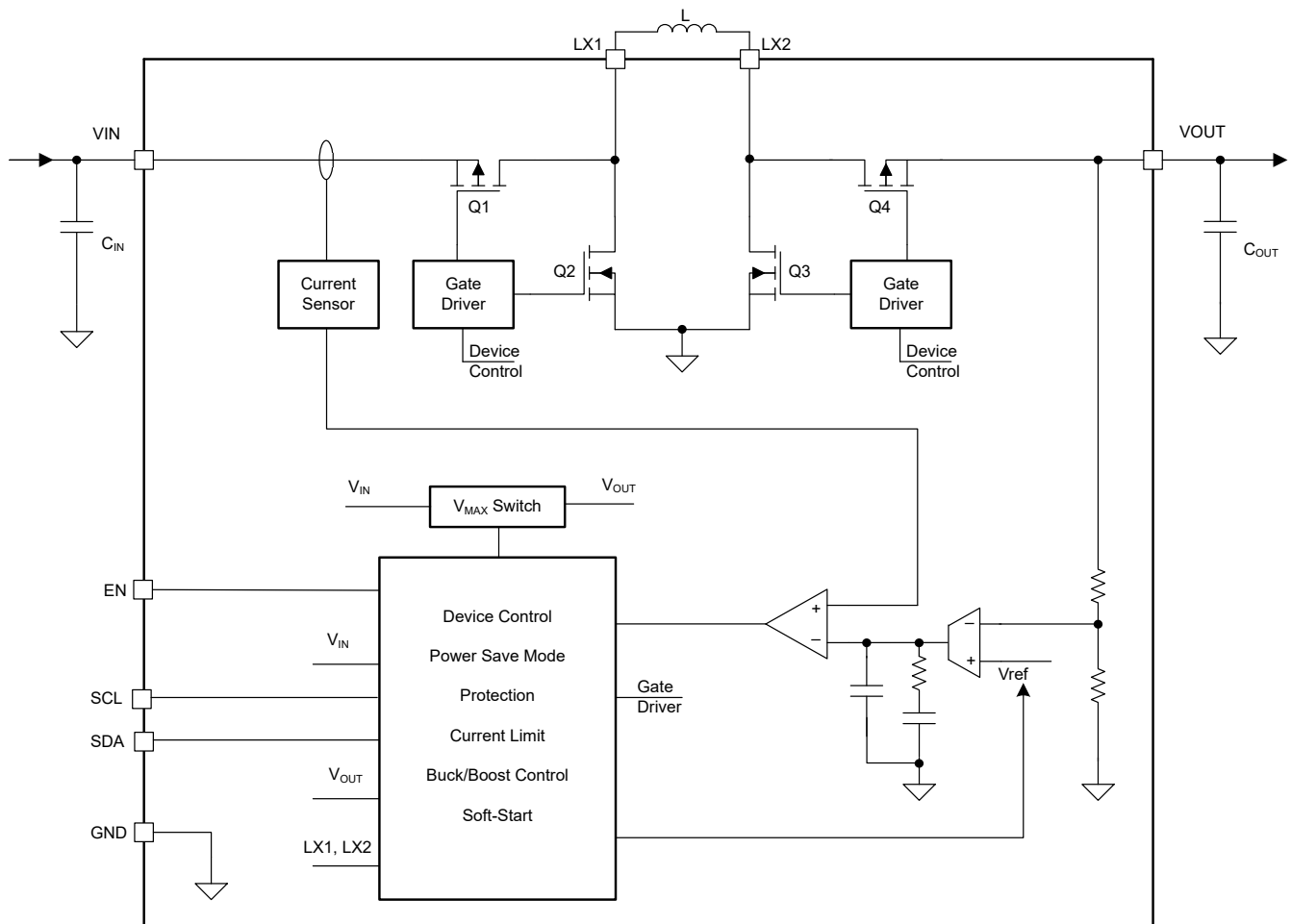
(1) Fast mode plus is compatible but not compliant with I²C standard

8 Detailed Description

8.1 Overview

The TPS631012 and TPS631013 are constant frequency peak current mode control buck-boost converters. The converters use a fixed-frequency with approximately 2-MHz switching frequency. The modulation scheme has three clearly defined operation modes where the converters enter with defined thresholds over the full operation range of V_{IN} and V_{OUT} . The maximum output current is determined by the Q1 peak current limit, which is typically 3 A.

8.2 Functional Block Diagram



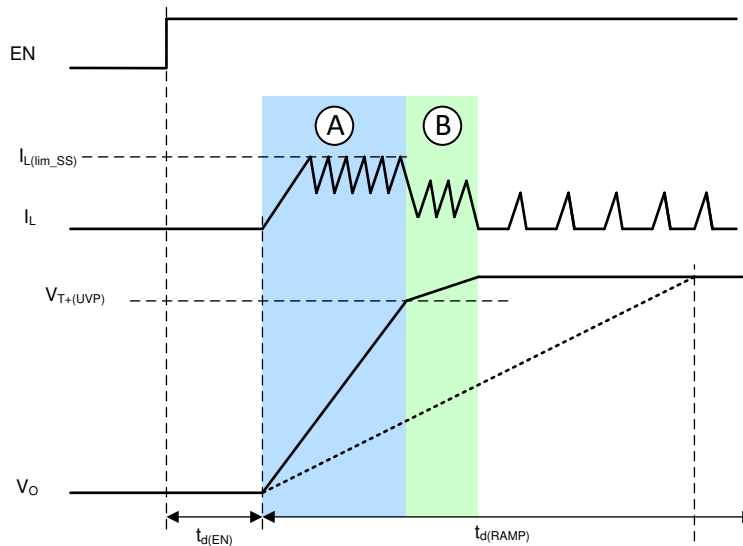
8.3 Feature Description

8.3.1 Undervoltage Lockout (UVLO)

The input voltage of the VIN pin is continuously monitored if the device is not in shutdown mode. UVLO only stops or starts the converter operation. The UVLO does not impact the core logic of the device. UVLO avoids a brownout of the device during device operation. In case the supply voltage on the VIN pin is lower than the negative-going threshold of UVLO, the converter stops its operation. To avoid a false disturbance of the power conversion, the UVLO falling threshold logic signal is digitally de-glitched.

If the supply voltage on the VIN pin recovers to be higher than the UVLO rising threshold, the converter returns to operation. In this case, the soft-start procedure restarts faster than under start-up without a pre-biased output.

8.3.2 Enable and Soft Start



8-1. Typical Soft-Start Behavior

When the input voltage is above the UVLO rising threshold and the EN pin is pulled to a voltage above 1.2 V, the TPS631012 and TPS631013 are enabled and start up after a short delay time, $t_{d(EN)}$.

The TPS631012 and TPS631013 have two start-up mechanisms that are controlled by the FAST_RAMP_EN bit in [Register CONTROL2](#). [8-1](#) shows a typical start-up case (low output load, typical output capacitance).

- When FAST_RAMP_EN = 1, the fast ramp mode is enabled. The output ramp behavior is shown as the solid line V_o in [8-1](#)
- When FAST_RAMP_EN = 0, the fast ramp mode is disabled. The output ramp behavior is shown as the dash line V_o in [8-1](#)

When fast ramp mode is enabled, the devices control the inductor peak current to limit the inrush current and ensure the fastest possible soft start if the capacitance is chosen lower than that for which the ramp time $t_{d(RAMP)}$ was selected. The output voltage then rises faster than the reference voltage ramp (see phase A in [8-1](#)). To avoid an output overshoot, the current clamp is deactivated when the output is close to the target voltage and follows the reference voltage ramp slew value given by the voltage ramp, which is finishing the start up (see phase B in [8-1](#)). Transition from the current clamp operation is detected using the $V_{T+(UVP)}$ threshold, which is typically 90% of the target output voltage. After phase B, the output voltage is well regulated to the nominal target voltage. The current waveform depends on the output load and operation mode. The current limit during start-up has two options and is controlled by the CL_RAMP_MIN bit in [Register CONTROL2](#).

- When CL_RAMP_MIN = 0, the typical current limit during start-up (phase A in [8-1](#)) is 500mA
- When CL_RAMP_MIN = 1, the typical current limit during start-up (phase A in [8-1](#)) is 1000mA

When fast ramp mode is disabled, the output voltage is totally controlled by the internal reference voltage ramp slew rate. There are three bits of TD_RAMP in [Register CONTROL2](#) to define the output voltage ramp time.

Note that if, during start-up, the current limit ($I_{L(lim_SS)}$) is lower than the current required to follow the voltage ramp controlled by TD_RAMP, the current automatically increases to follow the voltage ramp.

8.3.3 Device Enable (EN)

The EN pin enables and disables the device.

- When the EN pin is high, the device is enabled.
- When the EN pin is low, the device is disabled.

The CONVERTER_EN bit in the [Register CONTROL1](#) can also be used to enable and disable the output of the converter.

- For TPS631012, the default bit of CONVERTER_EN = 0.
- For TPS631013, the default bit of CONVERTER_EN = 1.

表 8-1. Device Enable Truth Table

EXTERNAL EN PIN	INTERNAL EN (CONVERTER_EN)	DEVICE STATE	OUTPUT STATE
0	X	Device in Shutdown	No Output
1	0	Programming Interface Active	No Output
1	1	Device Active	Output Enabled

Note that when the EN pin is connected to logic low, all the I²C registers are cleaned and reset to the default values. While setting CONVERTER_EN to 0 has no influences on the I²C registers

8.3.4 Output Voltage Control

The TPS631012 and TPS631013 can generate output voltages from 1.0 V to 5.5 V with a 25 mV step. The [Register VOUT](#) is used to set the output voltage:

- $V_{OUT} = 1.000 + (V_{OUT}[7:0] \times 0.025)$ V, when $0x00 \leq V_{OUT}[7:0] \leq 0xB4$;
- $V_{OUT} = 5.5$ V, when $0xB5 \leq V_{OUT}[7:0] \leq 0xFF$

VOUT[7 :0] is the 8-bit value in the [Register VOUT](#).

The dynamic voltage scaling control bit of EN_FAST_DVS in [Register CONTROL1](#) controls the VOUT settling time when VOUT is set between different voltages.

- When EN_FAST_DVS = 1, the typical VOUT slew rate is 7.2 V/ms;
- When EN_FAST_DVS = 0, the typical VOUT slew rate is 0.4 V/ms

8.3.5 Mode Selection (PFM/FPWM)

The TPS631012 and TPS631013 have two modes of PFM and FPWM. During PFM mode operation, the devices feature a power save mode to maintain the highest efficiency over the full operating output current range. In PFM mode the devices automatically change the converter operation from CCM to pulse frequency modulation. During FPWM mode, the devices use PWM for all operating conditions regardless of the output current to achieve minimum output ripple.

The PFM/FPWM mode selection is controlled by the FPWM bit in [Register CONTROL2](#):

- When FPWM = 0b0, the devices work in PFM mode
- When FPWM = 0b1, the devices work in FPWM mode

8.3.6 Output Discharge

The TPS631012 and TPS631013 provide an active pull down current to quickly discharge output when the EN pin is logic low or the CONVERTER_EN bit is set to 0. With this function, the VOUT is connected to ground through internal circuitry, preventing the output from “floating” or entering into an undetermined state. The output discharge function makes the power on and off sequencing smooth. Pay attention to the output discharge function if use this device in applications such as power multiplexing, because the output discharge circuitry creates a constant current path between the multiplexer output and the ground.

The output discharge is controlled by the two bits named with EN_DISCH_VOUT. The output discharge can be disabled or set to three different options. Please refer to the EN_DISCH_VOUT bits in [Register CONTROL2](#) for detailed I²C settings.

8.3.7 Reverse Current Operation

The device can support reverse current operation (the current flows from VOUT pin to VIN pin) in FPWM mode. If the internal output feedback voltage is higher than the reference voltage, the converter regulation forces a current into the input capacitor. The reverse current operation is independent of the V_{IN} voltage or V_{OUT} voltage ratio, hence it is possible on all device operation modes boost, buck, or buck-boost.

8.3.8 Protection Features

The following sections describe the protection features of the device.

8.3.8.1 Input Overvoltage Protection


The TPS631012 and TPS631013 have input overvoltage protection which avoids any damage to the device in case the current flows from the output to the input and the input source cannot sink current (for example, a diode in the supply path).

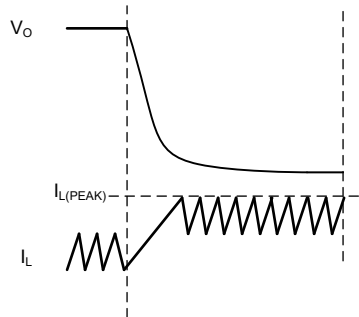
If forced PWM mode is active, the current can go negative until it reaches the sink current limit. Once the input voltage threshold, $V_{T+(IVP)}$, is reached on the VIN pin, the protection disables forced PWM mode and only allows current to flow from VIN to VOUT. After the input voltage drops under the input voltage protection threshold, forced PWM mode can be activated again.

8.3.8.2 Output Overvoltage Protection

The devices have the output overvoltage protection which avoids any damage to the device. When the output voltage threshold $V_{T+(OVP)}$ is reached on the VOUT pin, the protection disables the converter power stage and makes the switching nodes high impedance.

8.3.8.3 Short Circuit Protection/Hiccup

The device features peak current limit performance at short circuit protection.  8-2 shows a typical device behavior of an short/overload event of the short circuit protection.



 **8-2. Typical Device Behavior During Short Circuit Protection**

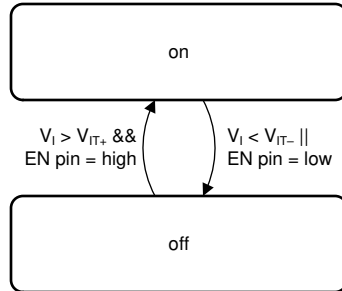
When the EN_SCP bit in [Register CONTROL1](#) is set to 1 to enable the short circuit hiccup protection, the hiccup timer works, limiting the switching on time to a typical 9 ms followed by a typical off time of 22 ms, then the device restarts. If the short condition disappears, the device automatically enters the normal working mode.

8.3.8.4 Thermal Shutdown

To avoid thermal damage of the device, the temperature of the die is monitored. The device stops operation once the sensed temperature rises over the typical thermal threshold 160 °C. After the temperature drops below the typical thermal shutdown hysteresis 25 °C, the converter returns to normal operation.

8.4 Device Functional Modes

The device has two functional modes: off and on. The device enters the on mode when the voltage on the VIN pin is higher than the UVLO threshold and a high logic level is applied to the EN pin. The device enters the off mode when the voltage on the VIN pin is lower than the UVLO threshold or a low logic level is applied to the EN pin.



8-3. Device Functional Modes

8.5 Programming

8.5.1 Serial Interface Description

I²C is a 2-wire serial interface developed by Philips Semiconductor, now NXP Semiconductors (see [NXP Semiconductors, UM10204 – I²C-Bus Specification and User Manual](#)). The bus consists of a data line (SDA) and a clock line (SCL) with pullup structures. When the bus is idle, both SDA and SCL lines are pulled high. All the I²C-compatible devices connect to the I²C bus through open-drain I/O pins, SDA, and SCL. A controller device, usually a microcontroller or a digital signal processor, controls the bus. The controller is responsible for generating the SCL signal and device addresses. The controller also generates specific conditions that indicate the START and STOP of data transfer. A target device receives and transmits data on the bus under control of the controller device.

The device works as a target and supports the following data transfer modes, as defined in the I²C-Bus Specification:

- Standard-mode (100 kbps)
- Fast-mode (400 kbps)
- Fast-mode Plus (1 Mbps)

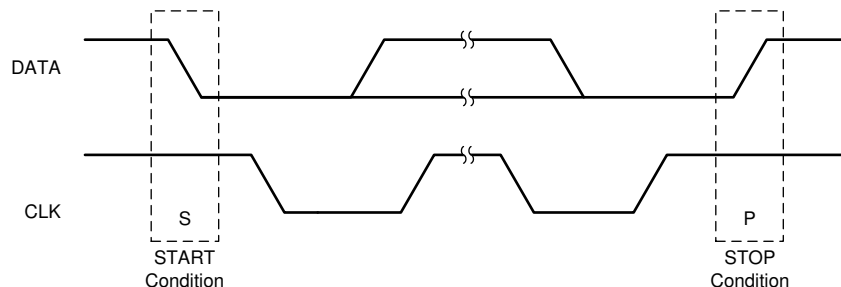
The interface adds flexibility to the power supply solution, enabling most functions to be programmed to new values, depending on the instantaneous application requirements. Register contents remain intact as long as supply voltage remains above $V_{IT+(POR)}$.

The data transfer protocol for standard and fast modes is exactly the same, therefore, it is referred to as F/S-mode in this document. The device supports 7-bit addressing; 10-bit addressing and general call address are not supported. The device 7-bit address is 2Ah (00101010b).

To make sure that the I²C function in the device is correctly reset, it is recommended that the I²C controller initiates a STOP condition on the I²C bus after the initial power up of SDA and SCL pullup voltages.

8.5.2 Standard-, Fast-, and Fast-Mode Plus Protocol

The controller initiates a data transfer by generating a start condition. The start condition is when a high-to-low transition occurs on the SDA line while SCL is high, as shown in 8-4. All I²C-compatible devices recognize a start condition.



8-4. START and STOP Conditions

The controller then generates the SCL pulses and transmits the 7-bit address and the read/write direction bit, R/W, on the SDA line. During all transmissions, the controller ensures that data is valid. A valid data condition requires the SDA line to be stable during the entire high period of the clock pulse (see [Figure 8-5](#)). All devices recognize the address sent by the controller and compare it to their internal fixed addresses. Only the target device with a matching address generates an acknowledge (see [Figure 8-6](#)) by pulling the SDA line low during the entire high period of the ninth SCL cycle. Upon detecting this acknowledge, the controller knows that communication link with a target has been established.

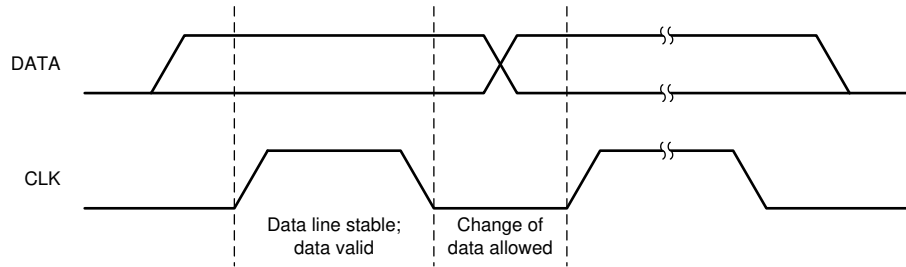


Figure 8-5. Bit Transfer on the Serial Interface

The controller generates further SCL cycles to either transmit data to the target (R/W bit 1) or receive data from the target (R/W bit 0). In either case, the receiver needs to acknowledge the data sent by the transmitter. An acknowledge signal can either be generated by the controller or by the target, depending on which one is the receiver. 9-bit valid data sequences consisting of 8-bit data and 1-bit acknowledge can continue as long as necessary.

To signal the end of the data transfer, the controller generates a stop condition by pulling the SDA line from low to high while the SCL line is high (see [Figure 8-4](#)). This low level to high level transition on the SDA line when the SCL is at high releases the bus and stops the communication link with the addressed target. All I²C-compatible devices must recognize the stop condition. Upon the receipt of a stop condition, all devices know that the bus is released and they wait for a start condition followed by a matching address.

Attempting to read data from register addresses not listed in this section results in 00h being read out.

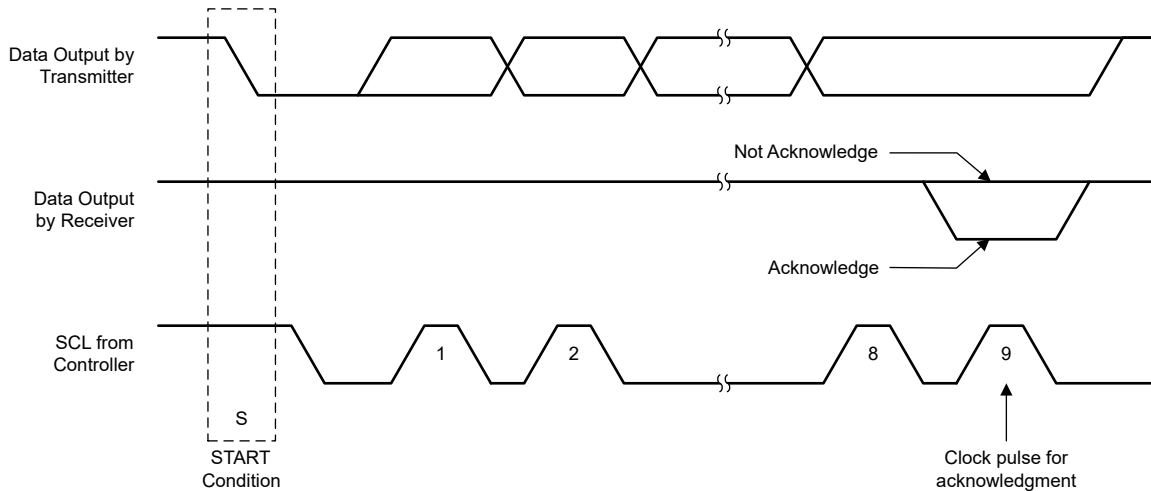
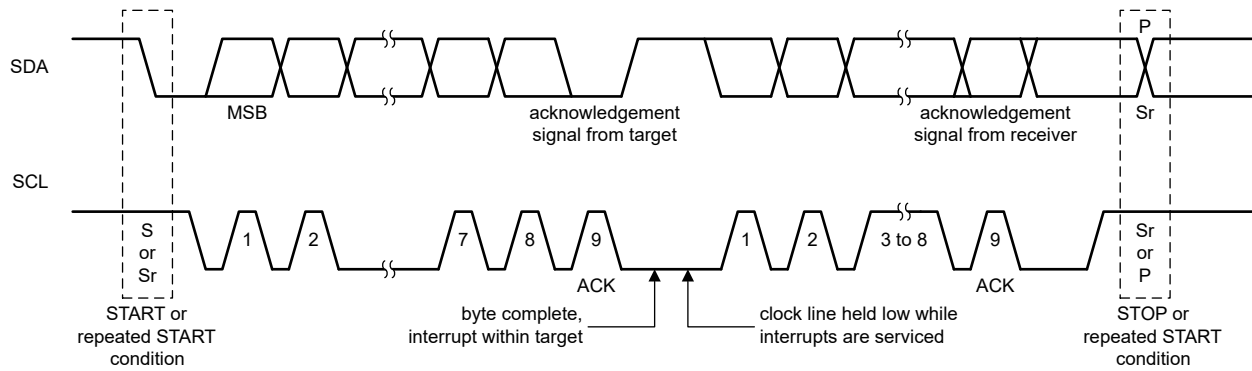


Figure 8-6. Acknowledge on the I²C Bus



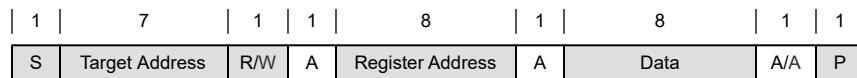
8-7. Bus Protocol

8.5.3 I²C Update Sequence

A single update requires the following:

- A start condition
- A valid I²C target address
- A register address
- A data byte

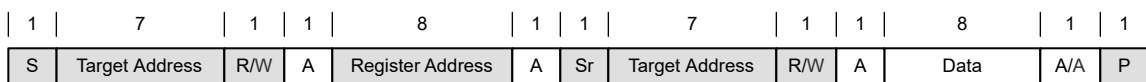
To acknowledge the receipt of each byte, the device pulls the SDA line low during the high period of a single clock pulse. The device performs an update on the falling edge of the acknowledge signal that follows the last byte.



- From controller to target
- From target to controller

A = Acknowledge (SDA low)
 A = Not acknowledge (SDA high)
 S = START condition
 Sr = REPEATED START condition
 P = STOP condition

8-8. “Write” Data Transfer Format in Standard, Fast, and Fast-Plus Modes



“0” Write

“1” Write

- From controller to target
- From target to controller

A = Acknowledge (SDA low)
 A = Not acknowledge (SDA high)
 S = START condition
 Sr = REPEATED START condition
 P = STOP condition

8-9. “Read” Data Transfer Format in Standard, Fast, and Fast-Plus Modes

8.6 Register Map

8.6.1 Register Description

8.6.1.1 Register Map

表 8-2. Register Map

ADDRESS	ACRONYM	REGISTER NAME	SECTION
0x02	CONTROL1	Control 1 Register	Go
0x03	VOUT	VOUT Register	Go
0x05	CONTROL2	Control 2 Register	Go

8.6.1.2 Register CONTROL1 (Register address: 0x02; Default: 0x08)

Return to [Register Map](#)

表 8-3. Register CONTROL1 Format

7	6	5	4	3	2	1	0
NIL[3:0]				EN_FAST_DVS	EN_SCP	NIL	CONVERTER_EN
R				R/W	R/W	R	R/W

LEGEND: R/W = Read/Write; R = Read only

SCP: Short Circuit Protection

表 8-4. Register CONTROL1 Field Descriptions

Bit	Field	Type	Reset	Description
7:4	NIL[3:0]	R	0b0000	Not used. During write operations data for these bits are ignored. During read operations 0 is returned
3	EN_FAST_DVS	R/W	0b1	Sets DVS to fast mode 0 : DISABLE, 1 : ENABLE
2	EN_SCP	R/W	0b0	Enable short circuit hiccup protection 0 : DISABLE, 1 : ENABLE
1	NIL	R	0b0	Not used.
0	CONVERTER_EN	R/W	0b0	Enable Converter ('AND'ed with EN-pin) 0 : DISABLE, 1 : ENABLE

8.6.1.3 Register VOUT (Register address: 0x03; Default: 0x5C)

Return to [Register Map](#)

表 8-5. Register VOUT Format

7	6	5	4	3	2	1	0
VOUT[7 :0]							
R/W							

LEGEND: R/W = Read/Write

表 8-6. Register VOUT Field Descriptions

Bit	Field	Type	Reset	Description
7:0	VOUT[7:0]	R/W	0x5C	These bits set the output voltage Output voltage = 1.000 + (VOUT[7 :0] × 0.025) V when 0x00 ≤ VOUT[7 :0] ≤ 0xB4; Output voltage = 5.5 V when 0xB5 ≤ VOUT[7 :0] ≤ 0xFF

8.6.1.4 Register CONTROL2 (Register address: 0x05; Default: 0x45)

Return to [Register Map](#)

表 8-7. Register CONTROL2 Format

7	6	5	4	3	2	1	0
FPWM	FAST_RAMP_EN	EN_DISCH_VOUT[1:0]		CL_RAMP_MIN	TD_RAMP[2:0]		
R/W	R/W	R/W		R/W	R/W		

LEGEND: R/W = Read/Write

表 8-8. Register CONTROL2 Field Descriptions

Bit	Field	Type	Reset	Description
7	FPWM	R/W	0b0	Force PWM operation 0 : DISABLE, 1 : ENABLE
6	FAST_RAMP_EN	R/W	0b1	Device can start-up faster than VOUT ramp 0 : DISABLE, 1 : ENABLE
5:4	EN_DISCH_VOUT[1:0]	R/W	0b00	Enable of BUBO Vout Discharge 00 : DISABLE 01 : SLOW (34mA) 10 : MEDIUM (67mA) 11 : FAST (100mA)
3	CL_RAMP_MIN	R/W	0b0	Define the minimum current limit during the soft start ramp 0 : Low (500mA) 1 : High (2x Low)
2:0	TD_RAMP[2:0]	R/W	0b101	Defines the ramp time for the Vo soft start ramp 000: 0.256ms 001: 0.512ms 010: 1.024ms 011: 1.920ms 100: 3.584ms 101: 7.552ms 110: 9.600ms 111: 24.320ms

9 Application and Implementation

注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

9.1 Application Information

The TPS631012 and TPS631013 are high-efficiency, low-quiescent current, buck-boost converters. The devices are suitable for applications needing a regulated output voltage from an input supply that can be higher or lower than the output voltage.

9.2 Typical Application

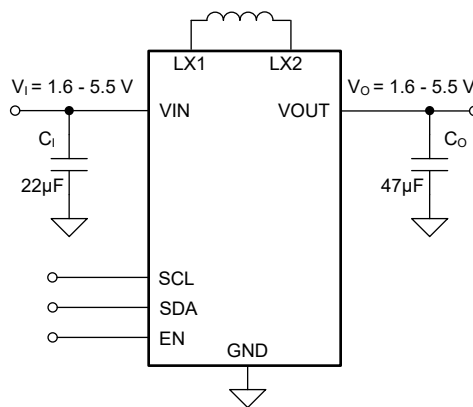


图 9-1. 3.3-V_{OUT} Typical Application

9.2.1 Design Requirements

The design parameters are listed in 表 9-1.

表 9-1. Design Parameters

PARAMETERS	VALUES
Input voltage	2.7 V to 4.3 V
Output voltage	3.3 V
Output current	1.5 A

9.2.2 Detailed Design Procedure

The first step is the selection of the output filter components. To simplify this process, セクション 7.3 outlines minimum and maximum values for inductance and capacitance. Pay attention to the tolerance and derating when selecting nominal inductance and capacitance.

9.2.2.1 Inductor Selection

The inductor selection is affected by several parameters such as the following:

- Inductor ripple current
- Output voltage ripple
- Transition point into power save mode
- Efficiency

See 表 9-2 for typical inductors.

For high efficiencies, the inductor with a low DC resistance is needed to minimize conduction losses. Especially at high-switching frequencies, the core material has a high impact on efficiency. When using small chip inductors, the efficiency is reduced mainly due to higher inductor core losses. Core losses need to be considered when selecting the appropriate inductor. The inductor value determines the inductor ripple current. The larger the inductor value, the smaller the inductor ripple current and the lower the conduction losses of the converter. Conversely, larger inductor values cause a slower load transient response. To avoid saturation of the inductor, the peak current for the inductor in steady state operation is calculated using 式 2. Only the equation that defines the switch current in boost mode is shown because this provides the highest value of current and represents the critical current value for selecting the right inductor.

$$\text{Duty Cycle Boost} \quad D = \frac{V_{\text{OUT}} - V_{\text{IN}}}{V_{\text{OUT}}} \quad (1)$$

$$I_{\text{PEAK}} = \frac{I_{\text{out}}}{\eta \times (1 - D)} + \frac{V_{\text{in}} \times D}{2 \times f \times L} \quad (2)$$

where:

- D = duty cycle in boost mode
- f = converter switching frequency (typical 2 MHz)
- L = inductor value
- η = estimated converter efficiency (use the number from the efficiency curves or 0.9 as an assumption)

注

The calculation must be done for the minimum input voltage in boost mode.

Calculating the maximum inductor current using the actual operating conditions gives the minimum saturation current of the inductor needed. It is recommended to choose an inductor with a saturation current 20% higher than the value calculated using 式 2. Possible inductors are listed in 表 9-2.

表 9-2. List of Recommended Inductors

INDUCTOR VALUE [μ H]	SATURATION CURRENT [A]	DCR [$m\Omega$]	PART NUMBER	MANUFACTURER ⁽¹⁾	SIZE (L × W × H mm)
1	4.3	42	DFE252012P-1R0M=P2	MuRata	2.5 × 2.0 × 1.2
1	4.2	43	HTEK20161T-1R0MSR	Cyntec	2.0 × 1.6 × 1.0
1	2.2	75	MAKK2016T1R0M ⁽²⁾	Taiyo Yuden	2.0 × 1.6 × 1.0
1	2.0	144	DFE18SAN1R0ME0 ⁽²⁾	Murata	1.6 × 0.8 × 0.8

- (1) See the [Third-Party Products Disclaimer](#).
 (2) This inductor does not support full output current range.

9.2.2.2 Output Capacitor Selection

For the output capacitor, use small ceramic capacitors placed as close as possible to the VOUT and PGND pins of the IC. The recommended total nominal output capacitor value is 47 μ F. If, for any reason, the application requires the use of large capacitors that cannot be placed close to the IC, use a smaller ceramic capacitor in parallel to the large capacitor, and place the small capacitor as close as possible to the VOUT and PGND pins of the IC.

It is important that the effective capacitance is given according to the recommended value in [セクション 7.3](#). In general, consider DC bias effects resulting in less effective capacitance. The choice of the output capacitance is mainly a tradeoff between size and transient behavior as higher capacitance reduces transient response over/undershoot and increases transient response time. Possible output capacitors are listed in [表 9-3](#).

表 9-3. List of Recommended Capacitors

CAPACITOR VALUE [μ F]	VOLTAGE RATING [V]	ESR [$m\Omega$]	PART NUMBER	MANUFACTURER ⁽¹⁾	SIZE (METRIC)
47	6.3	10	GRM219R60J476ME44	Murata	0805 (2012)
47	10	40	CL10A476MQ8QRN	Semco	0603 (1608)

- (1) See the [Third-Party Products Disclaimer](#).

9.2.2.3 Input Capacitor Selection

A 22- μ F input capacitor is recommended to improve line transient behavior of the regulator and EMI behavior of the total power supply circuit. An X5R or X7R ceramic capacitor placed as close as possible to the VIN and PGND pins of the IC is recommended. This capacitance can be increased without limit. If the input supply is located more than a few inches from the converter, additional bulk capacitance can be required in addition to the ceramic bypass capacitors. An electrolytic or tantalum capacitor with a value of 47 μ F is a typical choice.

表 9-4. List of Recommended Capacitors

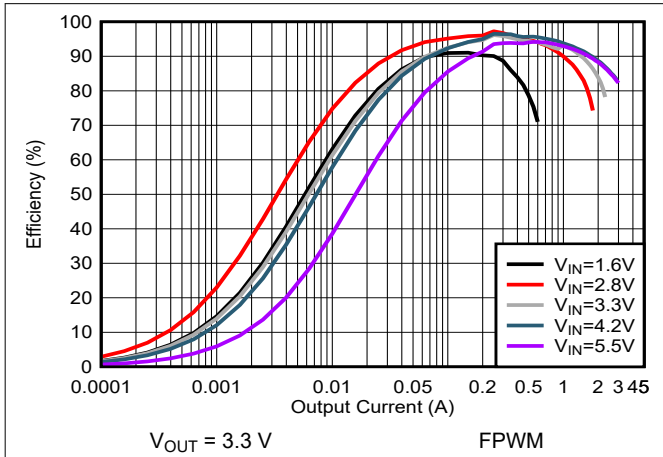
CAPACITOR VALUE [μ F]	VOLTAGE RATING [V]	ESR [$m\Omega$]	PART NUMBER	MANUFACTURER ⁽¹⁾	SIZE (METRIC)
22	6.3	43	GRM187R61A226ME15	Murata	0603 (1608)
10	10	40	GRM188R61A106ME69	Murata	0603 (1608)

- (1) See the [Third-Party Products Disclaimer](#).

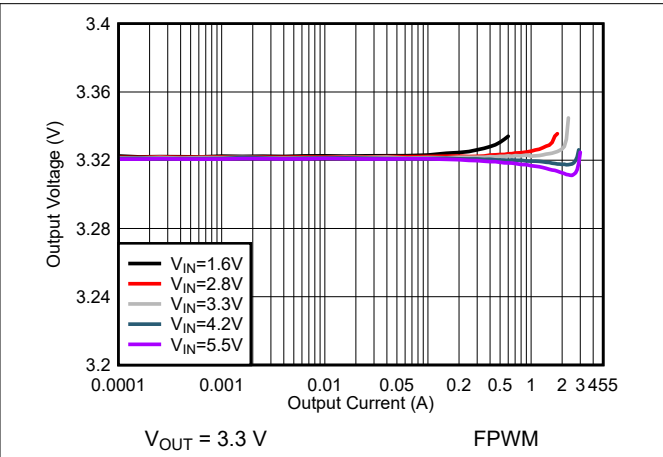
9.2.2.4 Setting the Output Voltage

The output voltage is set by I²C. Please refer to the part of [Output Voltage Control](#) for the detailed output voltage settings.

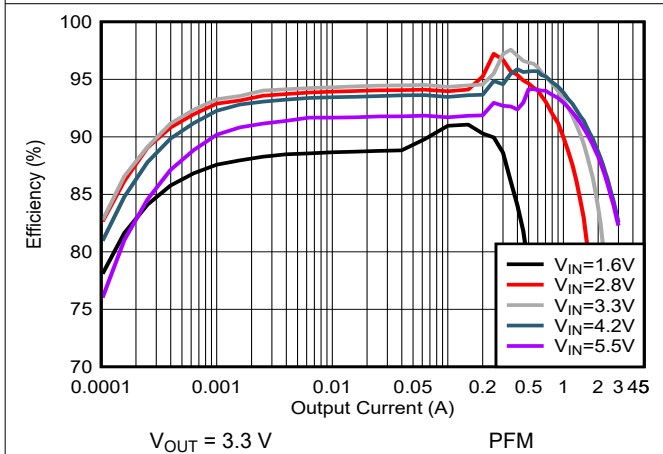
9.2.3 Application Curves



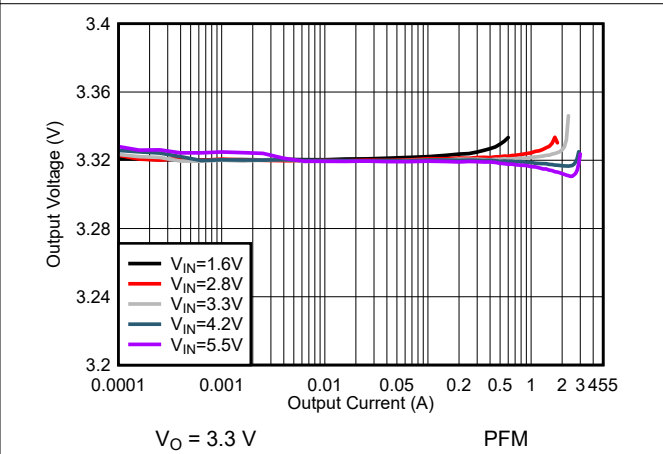
9-2. Efficiency vs Output Current (FPWM)



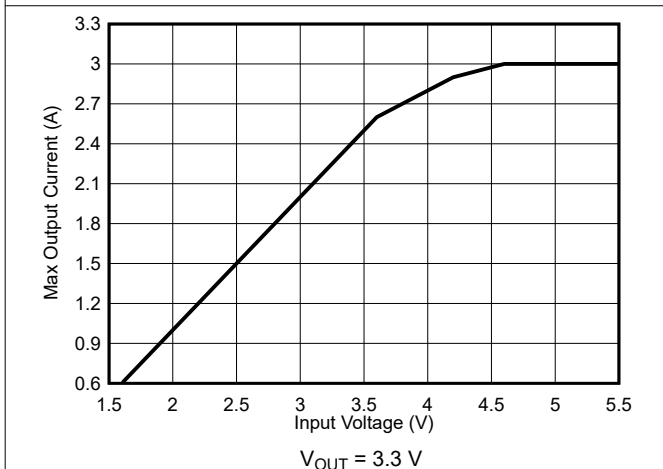
9-3. Load Regulation (FPWM)



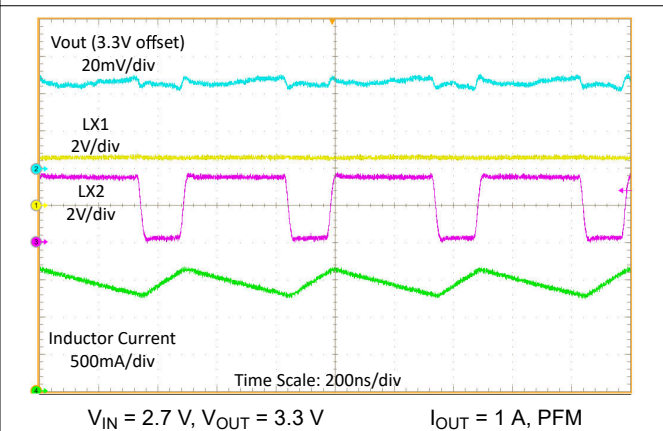
9-4. Efficiency vs Input Voltage (PFM)



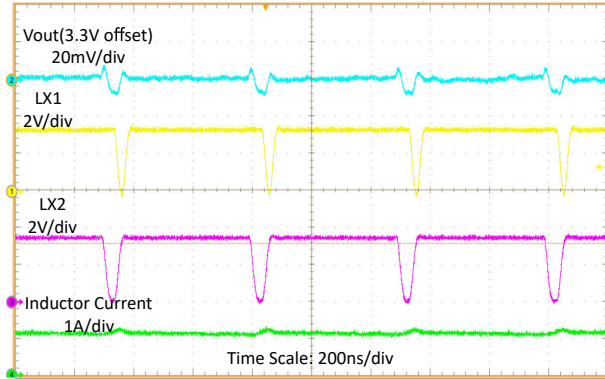
9-5. Load Regulation (PFM)



9-6. Typical Output Current Capability vs Input Voltage

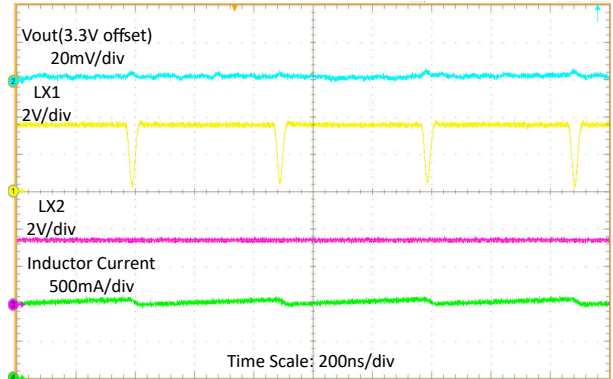


9-7. Switching Waveforms, Boost Operation with 1-A Load



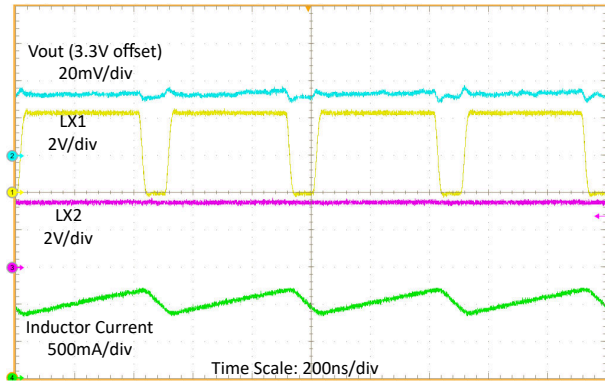
$V_{IN} = 3.4\text{ V}$, $V_{OUT} = 3.3\text{ V}$ $I_{OUT} = 1\text{ A}$, FPWM

9-8. Switching Waveforms, Buck-Boost Operation with 1-A Load



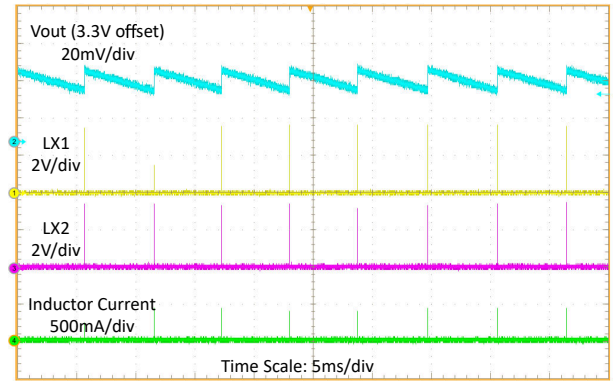
$V_{IN} = 3.6\text{ V}$, $V_{OUT} = 3.3\text{ V}$ $I_{OUT} = 1\text{ A}$, PFM

9-9. Switching Waveforms, Buck Operation with 1-A Load



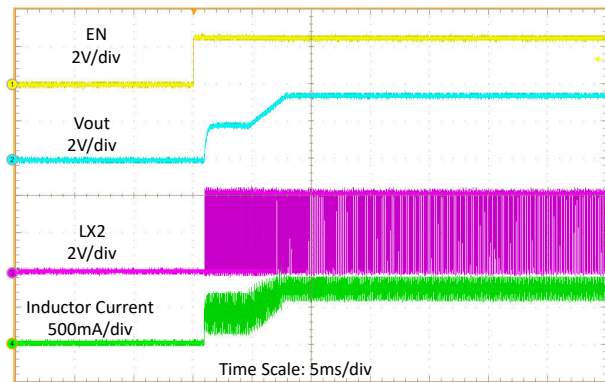
$V_{IN} = 4.3\text{ V}$, $V_{OUT} = 3.3\text{ V}$ $I_{OUT} = 1\text{ A}$, PFM

9-10. Switching Waveforms, Buck Operation with 1-A Load



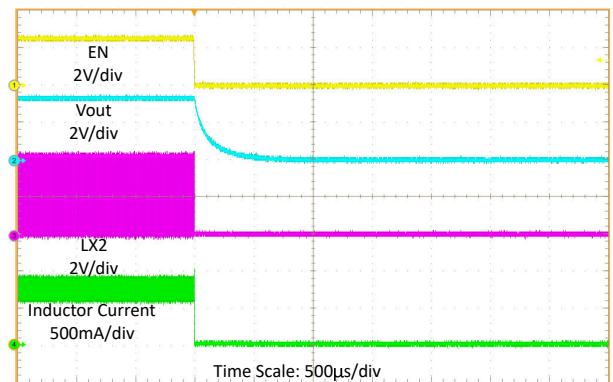
$V_{IN} = 3.6\text{ V}$, $V_{OUT} = 3.3\text{ V}$ $I_{OUT} = 1\text{ mA}$, PFM

9-11. Switching Waveforms at 1-mA Load



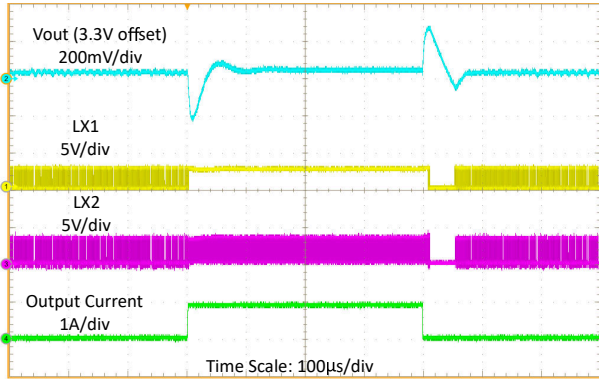
$V_{IN} = 3.3\text{ V}$, $V_{OUT} = 3.3\text{ V}$ $R_{load} = 4\ \Omega$, PFM

9-12. Start-Up by EN (Measured on TPS631013)



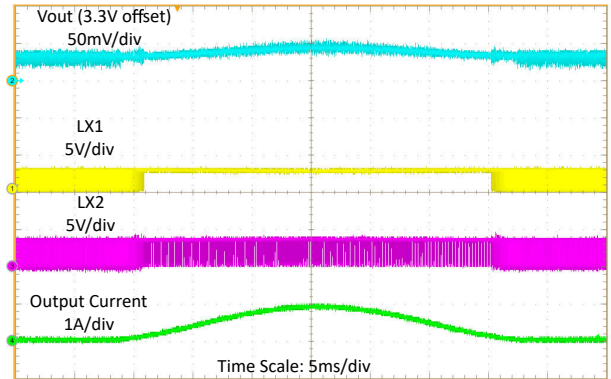
$V_{IN} = 3.3\text{ V}$, $V_{OUT} = 3.3\text{ V}$ $R_{load} = 4\ \Omega$, PFM

9-13. Shutdown by EN



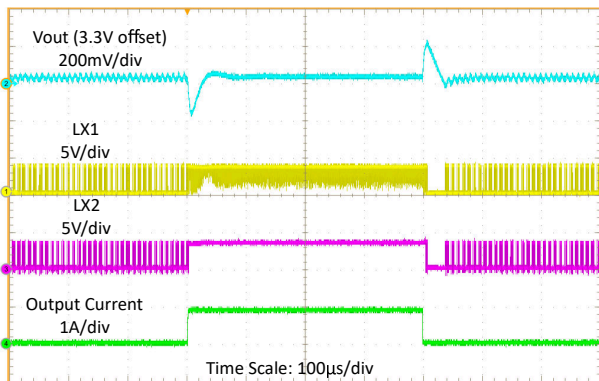
$V_{IN} = 2.7\text{ V}$, $V_{OUT} = 3.3\text{ V}$ $I_{OUT} = 100\text{ mA to }1\text{ A}$ with $20\text{-}\mu\text{s}$ slew rate

9-14. Load Transient at 2.7-V Input Voltage



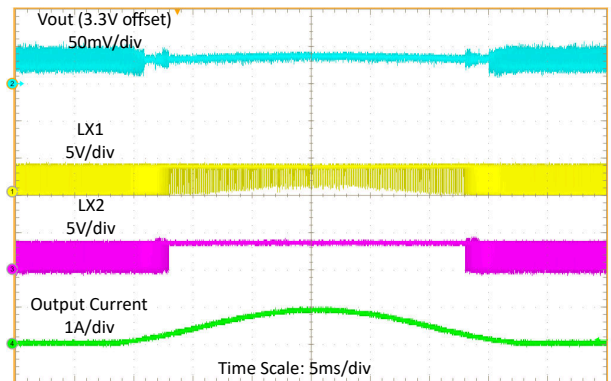
$V_{IN} = 2.7\text{ V}$, $V_{OUT} = 3.3\text{ V}$ $I_{OUT} = 100\text{ mA to }1\text{-A sweep}$

9-15. Load Sweep at 2.7-V Input Voltage



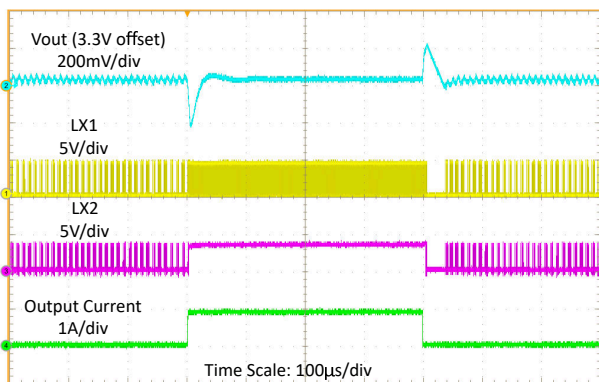
$V_{IN} = 3.6\text{ V}$, $V_{OUT} = 3.3\text{ V}$ $I_{OUT} = 100\text{ mA to }1\text{ A}$ with $20\text{-}\mu\text{s}$ slew rate

9-16. Load Transient at 3.6-V Input Voltage



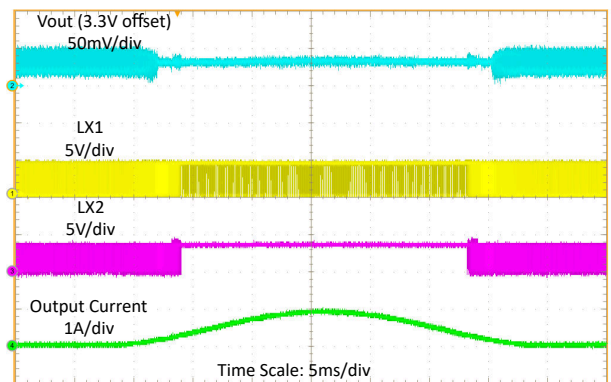
$V_{IN} = 3.6\text{ V}$, $V_{OUT} = 3.3\text{ V}$ $I_{OUT} = 100\text{ mA to }1\text{-A sweep}$

9-17. Load Sweep at 3.6-V Input Voltage



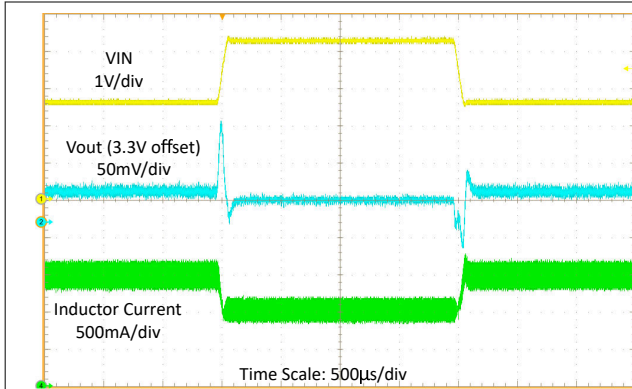
$V_{IN} = 4.3\text{ V}$, $V_{OUT} = 3.3\text{ V}$ $I_{OUT} = 100\text{ mA to }1\text{ A}$ with $20\text{-}\mu\text{s}$ slew rate

9-18. Load Transient at 4.3-V Input Voltage



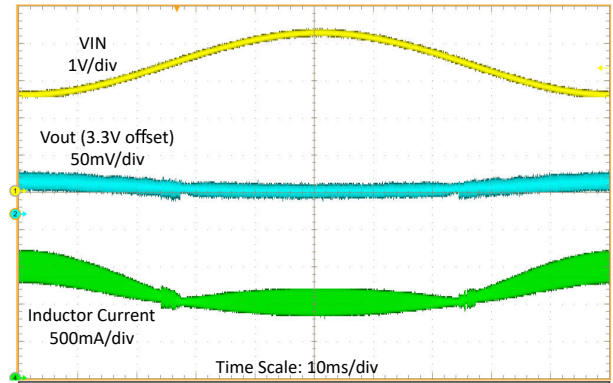
$V_{IN} = 4.3\text{ V}$, $V_{OUT} = 3.3\text{ V}$ $I_{OUT} = 100\text{ mA to }1\text{-A sweep}$

9-19. Load Sweep at 4.3-V Input Voltage



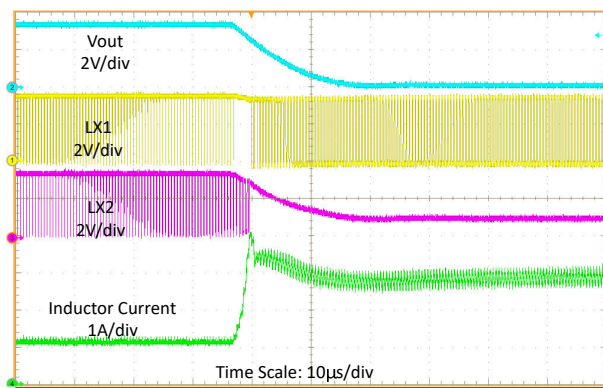
$V_{IN} = 2.7\text{ V to }4.3\text{ V with }20\text{-}\mu\text{s}$ $I_{OUT} = 1\text{ A}$
slew rate, $V_{OUT} = 3.3\text{ V}$

图 9-20. Line Transient at 1-A Load Current



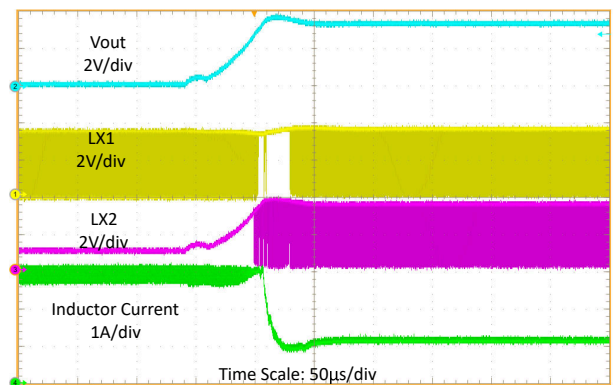
$V_{IN} = 2.7\text{-V to }4.3\text{-V sweep,}$ $I_{OUT} = 1\text{ A}$
 $V_{OUT} = 3.3\text{ V}$

图 9-21. Line Sweep at 1-A Load Current



$V_{IN} = 3.6\text{ V, }V_{OUT} = 3.3\text{ V}$ $I_{OUT} = 1\text{ A, FPWM}$

图 9-22. Output Short Protection (Entry)



$V_{IN} = 3.6\text{ V, }V_{OUT} = 3.3\text{ V}$ $I_{OUT} = 1\text{ A, FPWM}$

图 9-23. Output Short Protection (Recover)

表 9-5. Components for Application Characteristic Curves for $V_{OUT} = 3.3\text{ V}$

REFERENCE	DESCRIPTION ⁽²⁾	PART NUMBER	MANUFACTURER ⁽¹⁾
U1	High Power Density 1.5 A Buck-Boost Converter	TPS631012 or TPS631013	Texas Instruments
L1	1.0 μH , 2.5 mm x 2.0 mm, 4.3 A, 42 m Ω	DfE252012P-1R0M=P2	MuRata
C1	22 μF , 0603, Ceramic Capacitor, $\pm 20\%$, 6.3 V	GRM187R61A226ME15	Murata
C2	47 μF , 0805, Ceramic Capacitor, $\pm 20\%$, 6.3 V	GRM219R60J476ME44	Murata

(1) See the [Third-Party Products Disclaimer](#).

(2) For other output voltages, refer to for resistor values.

9.3 Power Supply Recommendations

The TPS631012 and TPS631013 have no special requirements for its input power supply. The input power supply output current needs to be rated according to the supply voltage, output voltage, and output current.

9.4 Layout

9.4.1 Layout Guidelines

The PCB layout is an important step to maintain the high performance of the device.

- Place input and output capacitors as close as possible to the IC. Traces need to be kept short. Route wide and direct traces to the input and output capacitors results in low trace resistance and low parasitic inductance.
- The sense trace connected to FB is signal trace. Keep these traces away from LX1 and LX2 nodes.

10 Device and Documentation Support

10.1 Device Support

10.1.1 サード・パーティ製品に関する免責事項

サード・パーティ製品またはサービスに関するテキサス・インスツルメンツの出版物は、単独またはテキサス・インスツルメンツの製品、サービスと一緒に提供される場合に関係なく、サード・パーティ製品またはサービスの適合性に関する是認、サード・パーティ製品またはサービスの是認の表明を意味するものではありません。

10.2 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、ti.com のデバイス製品フォルダを開いてください。「更新の通知を受け取る」をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取れます。変更の詳細については、修正されたドキュメントに含まれている改訂履歴をご覧ください。

10.3 サポート・リソース

[TI E2E™ サポート・フォーラム](#)は、エンジニアが検証済みの回答と設計に関するヒントをエキスパートから迅速かつ直接得ることができる場所です。既存の回答を検索したり、独自の質問をしたりすることで、設計に必要な支援を迅速に得ることができます。

リンクされているコンテンツは、該当する貢献者により、現状のまま提供されるものです。これらは TI の仕様を構成するものではなく、必ずしも TI の見解を反映したものではありません。TI の[使用条件](#)を参照してください。

10.4 Trademarks

TI E2E™ is a trademark of Texas Instruments.

すべての商標は、それぞれの所有者に帰属します。

10.5 静電気放電に関する注意事項



この IC は、ESD によって破損する可能性があります。テキサス・インスツルメンツは、IC を取り扱う際には常に適切な注意を払うことを推奨します。正しい取り扱いおよび設置手順に従わない場合、デバイスを破損するおそれがあります。

ESD による破損は、わずかな性能低下からデバイスの完全な故障まで多岐にわたります。精密な IC の場合、パラメータがわずかに変化するだけで公表されている仕様から外れる可能性があるため、破損が発生しやすくなっています。

10.6 用語集

[テキサス・インスツルメンツ用語集](#)

この用語集には、用語や略語の一覧および定義が記載されています。

11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
TPS631012YBGR	ACTIVE	DSBGA	YBG	8	3000	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-40 to 125	1OL	Samples
TPS631013YBGR	ACTIVE	DSBGA	YBG	8	3000	RoHS & Green	SNAGCU	Level-1-260C-UNLIM	-40 to 125	1P7	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

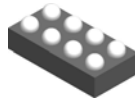
(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer:The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

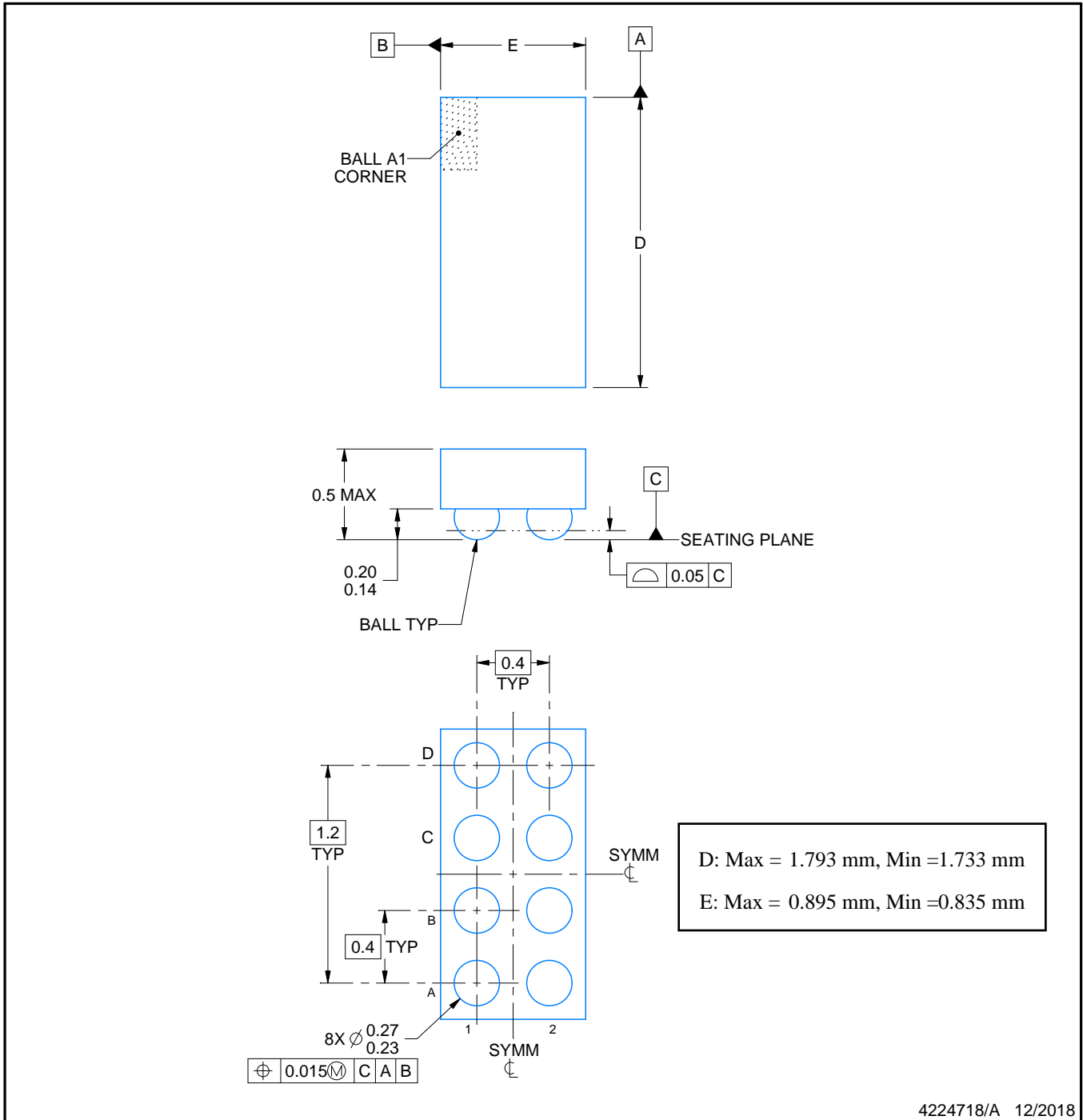
YBG0008



PACKAGE OUTLINE

DSBGA - 0.5 mm max height

DIE SIZE BALL GRID ARRAY



4224718/A 12/2018

NOTES:

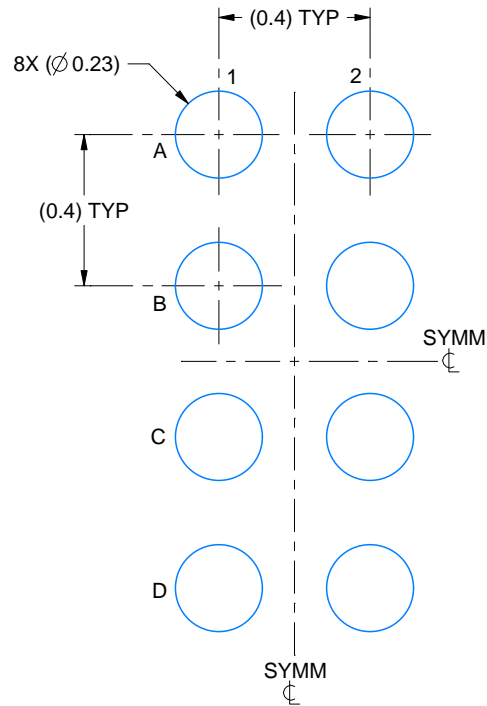
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

EXAMPLE BOARD LAYOUT

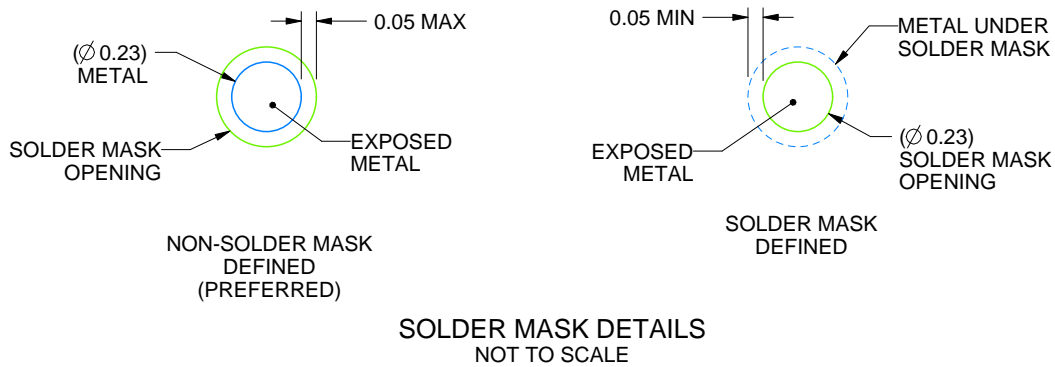
YBG0008

DSBGA - 0.5 mm max height

DIE SIZE BALL GRID ARRAY



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE: 50X



4224718/A 12/2018

NOTES: (continued)

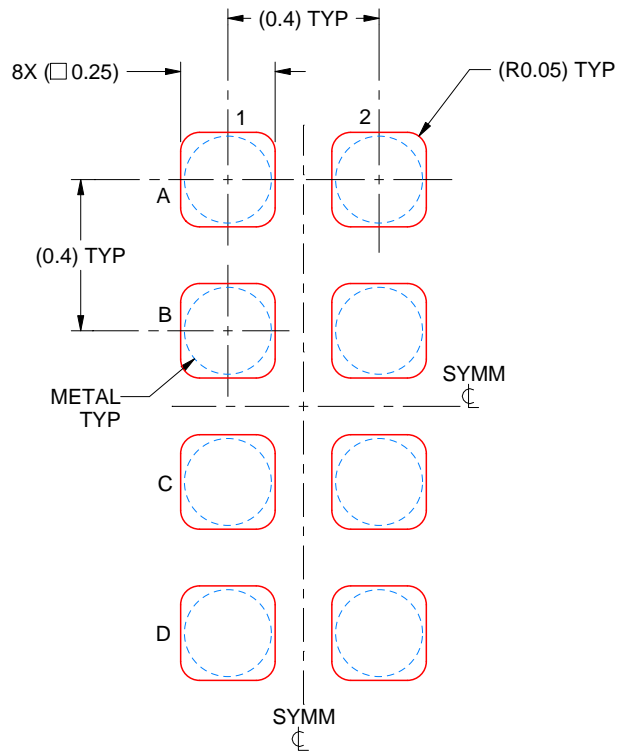
- Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. See Texas Instruments Literature No. SNVA009 (www.ti.com/lit/snva009).

EXAMPLE STENCIL DESIGN

YBG0008

DSBGA - 0.5 mm max height

DIE SIZE BALL GRID ARRAY



SOLDER PASTE EXAMPLE
BASED ON 0.1 mm THICK STENCIL
SCALE: 50X

4224718/A 12/2018

NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.

重要なお知らせと免責事項

TI は、技術データと信頼性データ (データシートを含みます)、設計リソース (リファレンス・デザインを含みます)、アプリケーションや設計に関する各種アドバイス、Web ツール、安全性情報、その他のリソースを、欠陥が存在する可能性のある「現状のまま」提供しており、商品性および特定目的に対する適合性の黙示保証、第三者の知的財産権の非侵害保証を含むいかなる保証も、明示的または黙示的にかかわらず拒否します。

これらのリソースは、TI 製品を使用する設計の経験を積んだ開発者への提供を意図したものです。(1) お客様のアプリケーションに適した TI 製品の選定、(2) お客様のアプリケーションの設計、検証、試験、(3) お客様のアプリケーションに該当する各種規格や、その他のあらゆる安全性、セキュリティ、規制、または他の要件への確実な適合に関する責任を、お客様のみが単独で負うものとし、

上記の各種リソースは、予告なく変更される可能性があります。これらのリソースは、リソースで説明されている TI 製品を使用するアプリケーションの開発の目的でのみ、TI はその使用をお客様に許諾します。これらのリソースに関して、他の目的で複製することや掲載することは禁止されています。TI や第三者の知的財産権のライセンスが付与されている訳ではありません。お客様は、これらのリソースを自身で使用した結果発生するあらゆる申し立て、損害、費用、損失、責任について、TI およびその代理人を完全に補償するものとし、TI は一切の責任を拒否します。

TI の製品は、[TI の販売条件](#)、または [ti.com](https://www.ti.com) やかかる TI 製品の関連資料などのいずれかを通じて提供する適用可能な条項の下で提供されています。TI がこれらのリソースを提供することは、適用される TI の保証または他の保証の放棄の拡大や変更を意味するものではありません。

お客様がいかなる追加条項または代替条項を提案した場合でも、TI はそれらに異議を唱え、拒否します。

郵送先住所 : Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2023, Texas Instruments Incorporated