

[TPS62914,](https://www.ti.com/product/TPS62914) [TPS62916](https://www.ti.com/product/TPS62916), [TPS62918](https://www.ti.com/product/TPS62918) [SLVSG94C](https://www.ti.com/lit/pdf/SLVSG94) – NOVEMBER 2023 – REVISED JUNE 2024

TPS6291x 3V to 17V, 4.5A/6A/8A, Low Noise and Low Ripple Buck Converter With Integrated Ferrite Bead Filter Compensation

1 Features

TEXAS

INSTRUMENTS

- Low output 1/f noise $<$ 20 μ V_{RMS}(100Hz to 100kHz)
- Low output voltage ripple $\leq 10 \mu V_{RMS}$ after ferrite bead
- High PSRR of > 65dB (up to 100kHz)
- 2.2MHz, 1.4MHz, or 1.0MHz fixed frequency peak current mode control
- Synchronizable with external clock (optional)
- Integrated loop compensation supports ferrite bead for second stage L-C filter with 30dB attenuation (optional)
- Spread spectrum modulation (optional)
- 3.0V to 17V input voltage range
- 0.8V to 5.5V output voltage range
- 25mΩ/7mΩ R_{DSon}
- Output voltage accuracy of ±1% over temperature
- Precise enable input allows
	- User-defined undervoltage lockout
	- Exact sequencing
- Adjustable soft start
- Power-good output
- Output discharge (optional)
- –40°C to 150°C junction temperature range
- 2. mm × 3.0mm QFN with 0.5mm pitch
- Create a custom design using the TPS6291x with the WEBENCH® [Power Designer](https://webench.ti.com/wb5/TISearch/panel.html?p=TPS62913&origin=ODS__TPS62913)

2 Applications

- **[Telecom infrastructure](http://www.ti.com/applications/communications-equipment/wireless-infrastructure/overview.html)**
- [Test and measurement](http://www.ti.com/applications/industrial/test-measurement/overview.html)
- [Aerospace and defense \(radar, avionics\)](http://www.ti.com/applications/industrial/aerospace-defense/overview.html)
- **[Medical](http://www.ti.com/applications/industrial/medical/overview.html)**

Output Noise Versus Frequency

3 Description

The TPS6291x devices are a family of high-efficiency, low noise, and low ripple current mode synchronous buck converters. The devices are designed for noise sensitive applications that normally use an LDO for post regulation such as high-speed ADCs, clock and jitter cleaner, serializer, de-serializer, and radar applications.

To reduce the output voltage ripple, the device loop compensation is designed to operate with an optional second-stage ferrite bead L-C filter. Lowfrequency noise levels, similar to a low-noise LDO, are further achieved by filtering the internal voltage reference with a capacitor connected to the NR/SS pin. Combined, these features allow for an output voltage ripple below $10\mu V_{RMS}$.

The device operates at a fixed switching frequency of 2.2MHz, 1.4MHz, or 1MHz, and can be synchronized to an external clock. An optional spread spectrum modulation scheme spreads the DC/DC switching frequency over a wider span, which lowers the mixing spurs.

Device Information

(1) For more information, see [Section 10.](#page-29-0)

(2) The package size (length × width) is a nominal value and includes pins, where applicable.

Typical Application

Table of Contents

4 Pin Configuration and Functions

Figure 4-1. 14-Pin VQFN-HR, RPY Package (Top View)

Table 4-1. Pin Functions

(1) $I = input, O = output$

5 Specifications

5.1 Absolute Maximum Ratings

over operating junction temperature range (unless otherwise noted) (1)

(1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

(2) All voltage values are with respect to the network ground terminal.

(3) While switching.

5.2 ESD Ratings

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

5.3 Recommended Operating Conditions

over operating junction temperature range (unless otherwise noted)

5.3 Recommended Operating Conditions (continued)

over operating junction temperature range (unless otherwise noted)

(1) Operating lifetime is derated at junction temperatures above 125°C.

5.4 Thermal Information

(1) For more information about traditional and new thermal metrics, see the *[Semiconductor and IC Package Thermal Metrics](https://www.ti.com/lit/an/spra953c/spra953c.pdf?ts=1593713041028)* application note.

(2) Not applicable to an EVM.

5.5 Electrical Characteristics

Over recommended input voltage range, Tյ= –40℃ to 150℃. Typical values are at Vin = 12 V and Tյ = 25℃ (unless otherwise noted)

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5.5 Electrical Characteristics (continued)

Over recommended input voltage range, Tյ= –40℃ to 150℃. Typical values are at Vin = 12 V and Tյ = 25℃ (unless otherwise noted)

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5.6 Typical Characteristics

 $_{IN}$ = 12 V, V_{OUT} = 1.2 V, T_A = 25°C, BOM = [Table 7-1](#page-16-0), (unless otherwise noted)

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5.6 Typical Characteristics (continued)

 $_{IN}$ = 12 V, V_{OUT} = 1.2 V, T_A = 25°C, BOM = [Table 7-1](#page-16-0), (unless otherwise noted)

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5.6 Typical Characteristics (continued)

 $_{IN}$ = 12 V, V_{OUT} = 1.2 V, T_A = 25°C, BOM = [Table 7-1](#page-16-0), (unless otherwise noted)

6 Detailed Description

6.1 Overview

The TPS6291x low-noise, low-ripple synchronous buck converter is a fixed frequency current mode converter. The converter has a filtered internal reference to achieve a low-noise output similar to low noise LDOs. The converter achieves lower output voltage ripple by using a switching frequency of either 2.2 MHz, 1.4 MHz, or 1 MHz and a larger inductance. The output voltage ripple can be further reduced by adding a small second stage L-C filter to the output. This can be a ferrite bead or a small inductor, followed by an output capacitor. Internal compensation maintains stability with an external filter inductor up to 50 nH. To avoid voltage drops across this second stage filter, the device regulates the output voltage after the filter. The TPS6291x family supports an optional spread spectrum modulation. When powering ADCs, for example, spread spectrum modulation reduces the mixing spurs. Switching frequency, spread spectrum modulation, and output discharge are set using the S-CONF pin.

6.2 Functional Block Diagram

6.3 Feature Description

6.3.1 Smart Config (S-CONF)

This S-CONF pin configures the device based on the resistor value. This pin is read after EN/SYNC goes high. The device configuration cannot be changed during operation. The S-CONF value is re-read if EN is pulled below 200 mV or if VIN falls below UVLO. Table 6-1 shows the configuration options of switching frequency, spread spectrum modulation, output discharge, and synchronization.

To make sure the internal circuit detects the resistor value correctly, minimize the distance between the resistor and the S-CONF pin and do not place any capacitors on the S-CONF pin.

6.3.2 Device Enable (EN/SYNC)

The device is enabled by pulling the EN/SYNC pin high, and has an accurate rising threshold voltage of typically 1.01 V. After the device is enabled, the operation mode is set by the configuration of the S-CONF pin. This action occurs during the device start-up delay time t_{delay}. After t_{delay} expires, the internal soft-start circuitry ramps up the output voltage over the soft-start time set by the C_{NR/SS} capacitor. The start-up delay time t_{delay} varies depending on the selected S-CONF value. The start-up delay time is shortest with smaller S-CONF resistors.

The EN/SYNC pin has an active pulldown resistor R_{PD} . This resistor prevents an uncontrolled start-up of the device, in case the EN/SYNC pin cannot be driven to a low level. The pulldown resistor is disconnected after start-up. With EN set to a low level, the device enters shutdown and the pulldown resistor is activated again.

6.3.3 Device Synchronization (EN/SYNC)

The EN/SYNC pin is also used for device synchronization. After a clock signal is applied to this pin, the device is enabled and reads the configuration of the S-CONF pin. The external clock frequency must be within the clock synchronization frequency range set by the S-CONF pin. When the clock signal changes from a clock to a static high, then the device switches from external clock to internal clock. To shutdown the device when using an external clock, EN/SYNC must go low for at least 10 µs.

The clock signal can be a logic signal with a logic level as specified in the electrical table, and can be applied directly to the EN/SYNC pin. External logic, such as an AND gate, can be used to combine separate enable and clock inputs, as shown in Figure 6-1.

Figure 6-1. Synchronization with Separate Enable Signal (Optional)

6.3.4 Spread Spectrum Modulation

Using the S-CONF pin enables or disables spread spectrum modulation. DC/DC converter generate an output voltage ripple at the switching frequency. When powering ADCs or an analog front-end (AFE), the switching frequency generates high frequency mixing spurs as well as a low frequency spur in the output frequency spectrum. Using the optional second stage L-C filter reduces the ripple of the converter and spurs by up to 30 dB.

The device has an integrated random spread spectrum modulation (SSM) scheme, selected by the resistor connected to the S-CONF pin according to [Table 6-1.](#page-11-0) Selecting random modulation to spread the switching frequency over a larger frequency range is possible. The modulation spread is +/– 10% of the device switching frequency. This SSM provides high attenuation when the receiver bandwidth is ≤ the modulation frequency, typically the case for systems using Fast Fourier Transforms (FFT) post processing as in high speed ADC applications. For applications sensitive to noise at the modulation frequency, random SSM is used. Using a random spread spectrum modulation also reduces the spurs in the output spectrum as shown in [Figure 5-2](#page-6-0). The randomized modulation uses a Fibonacci Linear-Feedback Shift Register (LFSR) so that every tone is generated once during the pseudo-random generation period. The frequency spreading is shown in [Figure 6-2.](#page-13-0).

Figure 6-2. Spread Spectrum Modulation

6.3.5 Output Discharge

Output discharge is enabled or disabled, depending on the S-CONF setting. With output discharge enabled, the output voltage is pulled low by a discharge resistor R_{DIS} of typically 7 Ω . The output discharge function is enabled during thermal shutdown, UVLO, or when EN/SYNC is pulled low.

6.3.6 Undervoltage Lockout (UVLO)

To avoid mis-operation of the device at low input voltages, the device is enabled after the input voltage is above the undervoltage lockout threshold. The device is disabled after the input voltage falls below the undervoltage threshold.

6.3.7 Power-Good Output

The device has a power-good output. The PG pin goes high impedance after the FB pin voltage is above 95% of the nominal voltage, and is driven low after the voltage falls below typically 90% of the nominal voltage. Table 6-2 shows the typical PG pin logic. The PG pin is an open-drain output and is specified to sink up to 10 mA. The power-good output requires a pullup resistor connecting to any voltage rail less than 18 V. The PG signal can be used for sequencing of multiple rails by connecting to the EN pin of other converters. If not used, the PG pin can be left floating or connected to GND. PG has a deglitch time of typically 8 μs before going low.

6.3.8 Noise Reduction and Soft-Start Capacitor (NR/SS)

A capacitor connected to this pin reduces the low frequency noise of the converter and sets the soft-start time. The larger the capacitor, the lower the noise and the longer the start-up time of the converter. A 470 nF capacitor is typically connected to this pin for a start-up time of 5 ms, although longer and shorter start-up times can be used. During soft start with a light load, the device skips switching pulses as needed to not discharge the output voltage. The device can start into a prebiased output voltage.

The device achieves low noise by adding an R-C filter to the reference voltage, as shown in *[Section 6.2](#page-10-0)*. During start-up, the NR/SS capacitor is charged with a constant current of 75 µA (typical) to 0.8 V. Larger NR/SS capacitors provide for lower low frequency noise. The maximum NR/SS cap is 3.3 µF for a start-up time of 35 ms. The minimum start-up time is set internally to 0.7 ms, which occurs when there is a small NR/SS capacitor or no NR/SS capacitor.

6.3.9 Current Limit and Short-Circuit Protection

The device is protected against short circuits and overcurrent. The switch current limit prevents the device from high inductor current and from drawing excessive current from the input voltage rail. Excessive current can occur with a shorted, saturated inductor or a heavy load, shorted output circuit condition. If the inductor current reaches the threshold I_{SWpeak}, the high-side MOSFET is turned off and the low-side MOSFET is turned on to ramp down the inductor current. The high-side MOSFET is turned on again only when the low-side current is below the low-side sourcing current limit I_{SWvallev}.

Due to internal propagation delay, the actual current can exceed the static current limit, especially if the input voltage is high and very small inductances are used. The dynamic current limit is calculated as follows in Equation 1:

$$
I_{PEAK(typ)} = I_{SWpeak} + \left(\frac{V_L}{L}\right) \times t_{PD}
$$
\n(1)

where

- ISWpeak is the static current limit, specified in *[Electrical Characteristics](#page-4-0)*
- L is the inductance
- V_1 is the voltage across the inductor (VIN VOUT)
- \cdot t_{PD} is the internal propagation delay, typically 50 ns

The low-side MOSFET also contains a negative current limit to prevent excessive current from flowing back through the inductor to the input. If the low-side sinking current limit is exceeded, the low-side MOSFET is turned off. In this scenario, both MOSFETs are off until the start of the next cycle.

6.3.10 Thermal Shutdown

The device goes into thermal shutdown after the junction temperature exceeds typically 170°C with a 20°C hysteresis.

6.4 Device Functional Modes

6.4.1 Fixed Frequency Pulse Width Modulation

To minimize output voltage ripple, the device operates in fixed frequency PWM operation down to no load. The switching frequency of 1 MHz, 1.4 MHz, or 2.2 MHz is selected using the S-CONF pin.

6.4.2 Low Duty Cycle Operation

For high input voltages or low output voltages, the 70 ns minimum on-time limits the maximum input to output voltage difference and the switching frequency selected. When the minimum on-time is reached, the output voltage rises above the regulation point. Refer to [Table 7-2](#page-17-0) for detailed design recommendations.

6.4.3 High Duty Cycle Operation (100% Duty Cycle)

The device offers a low input-to-output voltage differential by entering 100% duty cycle mode. In this mode, the high-side MOSFET switch is constantly turned on. The minimum input voltage to maintain output voltage regulation, depending on the load current and the output voltage level, is calculated as:

$$
V_{IN\ (min)} = V_{OUT(min)} + I_{OUT} \times \left(R_{DS(ON)} + R_L\right) \tag{2}
$$

where

 $V_{\text{OUT(min)}}$ is the minimum output voltage the load can accept

- I_{OUT} is the output current
- $R_{DS(ON)}$ is the $R_{DS(ON)}$ of the high-side MOSFET
- R_l is the DC resistance of the inductor used

To maintain fixed frequency switching, the device requires a minimum off-time of 50 ns (typical), 60 ns (maximum). If this limit is reached during a switching pulse, the device skips switching pulses to maintain output voltage regulation. If the input voltage decreases further, the device enters 100% mode.

6.4.4 Second Stage L-C Filter Compensation (Optional)

Most low-noise and low-ripple applications use a ferrite bead and bypass capacitor before the load. Using a second L-C filter is especially useful for low-noise and low-ripple applications with constant load current such as ADCs, DACs, and Jitter Cleaner. The second stage L-C filter is optional, and the device can be used without this filter. Without the filter, the device has a low output voltage noise of typically 16.9 μV_{RMS} with an output voltage ripple of 280 μV_{RMS} shown in [Figure 5-10.](#page-7-0) The second stage L-C filter attenuates the output voltage ripple by another approximately 30 dB shown in [Figure 5-12.](#page-7-0) To improve load regulation, the device can remote sense the output voltage after the second stage L-C filter and is internally compensated for the additional double pole generated by the L-C filter.

To keep the second stage L-C filter as small as possible, the internal compensation is optimized for a 10 nH to 50 nH inductance. A small ferrite bead or even a PCB trace provides sufficient inductance for output voltage ripple filtering. See *[Section 7.2.2.2.4](#page-19-0)* for details.

7 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

7.1 Application Information

The TPS6291x family of devices are designed for low noise and low output voltage ripple.

7.2 Typical Applications

Figure 7-1. Typical Schematic

Table 7-1 shows the list of recommended components for most applications.

Table 7-1. List of Components

7.2.1 Design Requirements

The external components have to fulfill the needs of the application, but also meet the stability criteria of the control loop of the device. The device is designed to work within a range of external components, and can be optimized for efficiency, output ripple, component count, or lowest 1/f noise.

Typical applications that have input voltages of ≤ 6 V use a 1 µH inductor with a 2.2 MHz switching frequency. Applications that have input voltages > 6 V can be optimized for efficiency using a 1 µH inductor with a 1 MHz or 1.4 MHz switching frequency depending on the output voltage. Optimization for powering clock and PLL circuits that need a 3.3 V output use a 1 µH inductor with 2.2 MHz switching frequency, minimizing output voltage ripple and low frequency noise.

For the application cases that are not found in Table 7-2, there are two methods to design the TPS6291x circuit. *Section 7.2.2.1* uses WEBENCH to design the circuit automatically or the calculations in *[Section 7.2.2.2](#page-18-0)* can be used instead.

Table 7-2. Typical Single L-C Filter Design Recommendations

(1) The maximum input to output voltage difference is limited by the device maximum minimum on-time of 70 ns. This limit is especially important for input voltages above 12 V or output voltages below 1 V. See [Section 7.2.2.2.1.](#page-18-0)

(2) For inductor part numbers, see [Table 7-4](#page-19-0).

(3) For output capacitor part numbers, see [Table 7-5.](#page-19-0)

The second stage L-C filter is optional, as the device can be used without this filter to achieve below 20 μV_{RMS} noise typically. A second stage filter is added to provide additional attenuation of the output ripple voltage. The output voltage is sensed after the second L-C filter by connecting the FB resistors to the second stage L-C filter capacitor. This action provides remote sense, minimizing output voltage drop due to the ferrite bead. Refer to Table 7-3 for second stage L-C filter recommendations based on the output voltage.

Table 7-3. Second Stage L-C (Ferrite Bead) Filter Design Recommendations

(1) For output capacitor part numbers, see [Table 7-5.](#page-19-0)

(2) For second stage L-C filter part numbers, see [Table 7-6](#page-20-0).

7.2.2 Detailed Design Procedure

If the specific design is not found in Table 7-2, TI recommends WEBENCH to generate the design. Alternatively, follow the manual design procedure in *[External Component Selection](#page-18-0)*.

7.2.2.1 Custom Design With WEBENCH® Tools

[Click here](https://webench.ti.com/wb5/TISearch/panel.html?p=TPS62913&origin=ODS__TPS62913) to create a custom design using the TPS6291x device with the WEBENCH Power Designer.

- 1. Start by entering the input voltage (V_{IN}), output voltage (V_{OUT}), and output current (I_{OUT}) requirements.
- 2. Optimize the design for key parameters such as efficiency, footprint, and cost.
- 3. Open the advanced tab to optimize for output voltage ripple.
- 4. After in a TPS6291x design, you can enable the second stage L-C filter and change other settings from the drop-down on the left.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at [www.ti.com/WEBENCH.](http://www.ti.com/WEBENCH)

7.2.2.2 External Component Selection

7.2.2.2.1 Switching Frequency Selection

The switching frequency can be chosen to optimize efficiency (lower) or ripple noise (higher). Using the higher 1.4 MHz or 2.2 MHz setting increases the gain of the feedback loop and can result in lower output noise. However, additional considerations for minimum on-time and duty cycle must also be considered. First, calculate the duty cycle using Equation 3. Higher efficiency results in a shorter on-time, so a conservative approach is to use a higher efficiency than expected in the application.

$$
D = \frac{V_{OUT}}{V_{IN} \times \eta} \tag{3}
$$

where:

• η = estimated efficiency (use the value from the efficiency curves or 0.9 as an conservative assumption)

Then, calculate the on-time with 1 MHz, 1.4 Mhz, and 2.2 MHz using Equation 4. The on-time must always remain above the minimum on-time of 70 ns. Use the maximum input voltage and maximum efficiency to determine the minimum duty cycle, D_{min} . Use the maximum switching frequency for f_{SW} .

$$
T_{ON} = \frac{D_{min}}{f_{SW_min}}\tag{4}
$$

then

- If $t_{ON,min}$ minimum < 70 ns with 2.2 MHz, use 1.4 MHz.
- If t_{ON} _{min} minimum < 70 ns with 1.4 MHz, use 1 MHz
- If t_{ON} _{min} minimum < 70 ns with 1 MHz, reduce the maximum input voltage.
- If t_{ON_min} minimum ≥ 70 ns, use a lower frequency for highest efficiency, or the highest frequency for the lowest noise and ripple.

7.2.2.2.2 Inductor Selection for the First L-C Filter

The inductor must be rated for the appropriate saturation current. Equation 5 and Equation 6 calculate the maximum inductor current under static load conditions. The formula takes the converter efficiency into account. The calculation must be done for the maximum input voltage where the peak switch current is highest.

$$
\Delta I_L = \frac{\frac{V_{OUT}}{\eta} \times \left(1 - \frac{V_{OUT}}{V_{IN} \times \eta}\right)}{f_{SW} \times L}
$$
 (5)

$$
I_{PEAK} = I_{OUT} + \frac{\Delta I_L}{2} \tag{6}
$$

where:

- f_{SW} is the switching frequency (1 MHz, 1.4 MHz, or 2.2 MHz)
- $L =$ inductance
- η = estimated efficiency (use the value from the efficiency curves or 0.9 as an conservative assumption)

Note The calculation must be done for the maximum input voltage of the application.

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Calculating the maximum inductor current using the actual operating conditions gives the minimum saturation current. TI recommends a margin of 20% be added to cover for load transients during operation.

See Table 7-4 for typical inductors.

Table 7-4. Inductor Selection

7.2.2.2.3 Output Capacitor Selection

The effective output capacitance can range from 80 μ F (minimum) up to 400 μ F (maximum) for a single L-C system design. When using a second L-C filter, the first L-C filter must have output capacitance between 80 μF and 160 μF, the second stage L-C filter (if used) must have at least 20 μF of capacitance, and the total capacitance for both L-C filters must be less than 400 μF. Load transient testing and measuring the bode plot are good ways to verify stability.

Note For designs requiring cold temperature $(< -10^{\circ}C$) operation, TI recommends to use a minimum effective output capacitance of 120 μF for a single L-C system design or within the first L-C filter when using a second L-C filter design.

TI recommends ceramic capacitors (X5R or X7R). Ceramic capacitors have a DC-Bias effect, which has a strong influence on the final effective capacitance. Choose the right capacitor carefully in combination with considering the package size and voltage rating. The ESR and ESL of the output capacitor are also important considerations in selecting the output capacitors for low noise applications. Smaller package sizes typically have lower ESL and ESR. TI recommends 0805 or smaller packages, as long as the packages provide the required capacitance and voltage rating for stable operation. Table 7-5 lists recommended output capacitors.

Table 7-5. Recommended Output Capacitors

7.2.2.2.4 Ferrite Bead Selection for Second L-C Filter

Using a ferrite bead for the second stage L-C filter minimizes the external component count because most of the noise sensitive circuits use a RF bead for high frequency attenuation as a default component at their inputs.

Make sure to select a ferrite bead with sufficiently high inductance at full load, and with low DC resistance (below 10 mΩ) to keep the converter efficiency as high as possible. The ferrite bead inductance decreases with increased load current. Therefore, the ferrite bead must have a current rating much higher than the desired load current.

The recommendation is to choose a ferrite bead with an impedance of 8 Ω to 20 Ω at 100 MHz. Ferrite beads can be used in parallel if higher current is needed, however this can halve the inductance and filtering. Refer to [Table 7-6](#page-20-0) for possible ferrite beads.

Table 7-6. Recommended Ferrite Beads

The internal compensation has been designed to be stable with up to 50 nH of inductance in the second stage filter. To achieve low ripple, the second L-C filter requires only 5-nH to 10-nH inductance. The inductance can be estimated from the ferrite bead impedance specification at 100 MHz, with the assumption that the inductance is similar at the selected converter switching frequency of 1 MHz, 1.4 MHz, or 2.2 MHz, and can be verified through tools available on some manufacturer websites. Use Equation 7 to calculate the inductance of a ferrite bead:

$$
L = \frac{Z}{2\pi \times f} \tag{7}
$$

where

- Z is the impedance of the ferrite bead in ohms at the specified frequency (usually 100 MHz)
- f is the specified frequency (usually 100 MHz)

7.2.2.2.5 Input Capacitor Selection

For the best output and input voltage filtering, TI recommends X5R or X7R ceramic capacitors. The input bulk capacitor minimizes input voltage ripple, suppresses input voltage spikes, and provides a stable system rail for the device. TI recommends a 10-μF or larger input capacitor. Having two in parallel further improves the input voltage ripple filtering, minimizing noise coupling into adjacent circuits. The voltage rating of the cap must also be taken into consideration, and must provide the required 5-μF minimum effective capacitance after DC bias derating.

In addition to the bulk input cap, a smaller cap must be placed directly from the VIN pin to the PGND pin to minimize input loop parasitic inductance, thereby minimizing the high frequency noise of the device. The input cap placement affects the output noise, so care needs to be taken in placing both the bulk cap and bypass caps as shown in *[Section 7.4.2](#page-26-0)*. Table 7-7 lists recommended input capacitors.

7.2.2.2.6 Setting the Output Voltage

Choose resistors R1 and R2 to set the output voltage within a range of 0.8 V to 5.5 V, according to Equation 8. To keep the feedback network robust from noise, and to reduce the self-generated noise of resistors, set R2 equal to or lower than 5 kΩ. Lower values of FB resistors achieve better noise immunity, and lower light load efficiency, as explained in the *[Design Considerations for a Resistive Feedback Divider in a DC/DC Converter](https://www.ti.com/lit/pdf/SLYT469)* [analog design journal.](https://www.ti.com/lit/pdf/SLYT469)

$$
R_1 = R_2 \times \left(\frac{V_{OUT}}{V_{FB}} - 1\right) = R_2 \times \left(\frac{V_{OUT}}{0.8V} - 1\right)
$$
\n(8)

A feedforward capacitor (C_{FF}) is not required for proper operation, but can further improve output noise. However, care must be taken in choosing the C_{FF} because the power-good (PG) function can not be valid with a large C_{FF} during start-up, and can cause spurious triggering of the PG pin during a large load transient. Refer to the *[Pros and Cons Using a Feedforward Capacitor with a Low Dropout Regulator](https://www.ti.com/lit/pdf/SBVA042) application report for* a discussion of the pros and cons of using a feedforward capacitor.

7.2.2.2.7 Bootstrap Capacitor Selection

A 0.1-µF ceramic capacitor must be connected between the BOOT and SW pins for proper operation. The capacitor must be rated for at least 10 V to minimize DC bias derating.

A resistor must be added in series with the BOOT capacitor to slow down the turn-on of the high-side MOSFET and rising edge overshoot on the SW pin for applications with input voltage greater than 13.5 V, which comes with the trade off of more power loss and lower efficiency. As a best practice, include a 0-Ω placeholder in all prototype designs in case parasitic inductance in the PCB layout results in more voltage overshoot at the SW pin than is normal, which helps keep the voltage within the ratings of the device and reduces the high frequency noise on the SW node. The recommended BOOT resistor value to decrease the SW pin overshoot is 2.2 $Ω$.

7.2.2.2.8 NR/SS Capacitor Selection

As described in *[Section 6.3.8](#page-13-0)*, the NR/SS cap affects both the total noise and the soft-start time. The recommended value for a 5-ms soft-start time and good noise performance is 470 nF. The maximum NR/SS cap is 3.3 μF for a start-up time of 35 ms. Values greater than 1 μF have minimal improvement in noise performance. Use Equation 9 and Equation 10 to calculate the soft-start time based on desired soft-start time or the chosen capacitor value.

$$
C_{NRSS}\left(F\right) = \frac{I_{NRSS} \times t_{SS}}{0.8 \, V} \tag{10}
$$

7.2.3 Application Curves

 V_{IN} = 12 V, V_{OUT} = 1.2 V, T_A = 25°C, BOM = [Table 7-1](#page-16-0)

1.8 3.352 $V_{IN} = 5V$ 3.348 1.797 $V_{IN} = 12V$ 3.344 V_{IN} = 17V 1.794 3.34 1.791 3.336 $\sum_{ }^{1.788}$ 3.332 $V_{\text{OUT}}(V)$ V_{out} (V) 3.328 1.785 3.324 1.782 3.32 3.316 1.779 3.312 1.776 $V_{IN} = 5V$ 3.308 $V_{IN} = 12V$ 1.773 3.304 $V_{IN} = 17V$ 1.77 L
0 $3.3 \frac{L}{0}$ 0 1 2 3 4 5 6 7 8
ILOAD (A) 0 1 2 3 4 5 6 7 8 ILOAD (A) 1.8 Vout 1 μH, 1.4 MHz 1st L-C Only 3.3 Vout 1 μH, 2.2 MHz 1st L-C Only **Figure 7-8. Output Voltage vs Load Current Figure 7-9. Output Voltage vs Load Current** $10.0 \text{V} \approx 2$ $\sqrt{1.00}$ ms $\frac{1.00MS}{10k}$ $\overline{2}$ \overline{J} 10.0 V % (2) $4.00ms$ $\left[\frac{250kS}{10k}$ points $\overline{2}$ 500 NR/SS = 470 nF NR/SS = 470 nF 12 V to 1.2 V 1 μH, 1 MHz 1 A Load 12 V to 1.2 V 1 μH, 1 MHz 0 A Load, Discharge On **Figure 7-10. Start-up Figure 7-11. Shutdown** $6.40mV$ $\sqrt{100 \mu s}$ $\begin{array}{|l|l|}\hline 10.0 \text{MS/s} \\ \hline 10 \text{k points} \end{array}$ $\sqrt{100 \mu s}$ 10.0MS/s
10k point Assia Save Save Save Save Screen Image Waveform $\begin{array}{c|c} \text{Save} & \text{Recall} \\ \text{Setup} & \text{Waveform} \end{array}$ Recall
Setup File
Utilities 300 mA to 4.5 A to 300 mA assign

Save[to

Image $\left[\begin{smallmatrix} 24 & \text{Apr} & 2024 \\ 02 & 39 & 17 \end{smallmatrix}\right]$ 12 V to 1.2 V 1 μH, 1 MHz 1st L-C Only 300 mA to 4.5 A to 300 mA 12 V to 1.2 V 1 μH, 1 MHz After 2nd L-C **Figure 7-12. Load Transient Figure 7-13. Load Transient**

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7.3 Power Supply Recommendations

The power supply to the TPS6291x must have a current rating according to the supply voltage, output voltage, and output current of the TPS6291x.

7.4 Layout

7.4.1 Layout Guidelines

A proper layout is critical for the operation of any switched mode power supply, especially at high switching frequencies. Therefore, the PCB layout of the TPS6291x demands careful attention to make sure of best performance. A poor layout can lead to issues like bad line and load regulation, instability, increased EMI radiation, and noise sensitivity. Refer to the *[Five Steps to a Great PCB Layout for a Step-Down Converter](https://www.ti.com/lit/pdf/SLYT614)* analog [design journal](https://www.ti.com/lit/pdf/SLYT614) for a detailed discussion of general best practices. Specific recommendations for the device are listed below.

- Place the input capacitor or capacitors as close as possible to the VIN and PGND pins of the device. This placement is the most critical component placement. Route the input capacitors directly to the VIN and PGND pins avoiding vias.
- Place the inductor close to the SW pin. Minimize the copper area at the switch node.
- Place the output capacitor ground close to the PGND pin and route directly avoiding vias. Minimize the length of the connection from the inductor to the output capacitor.
- Connect the VO pin directly to the first output capacitor, C_{OUT} .
- Connect sensitive traces, such as the connections to the NR/SS, VO, and FB pins with short traces and be routed away from any noise source, such as the SW pin.
- Connect the PSNS pin directly to the system GND plane with a via.
- Place the second L-C filter, L_f and C_f , near the load to reduce any radiated coupling around the second L-C filter
- Avoid placing the ferrite bead in the keep out region as shown in [Figure 7-23](#page-26-0)
- Place the FB resistors, R1 and R2, close to the FB pin and route the VOUT connection from R1 to the load as a remote sense trace. If a second L-C filter is used, this connection must be made after L_{f} .
- See the recommended layout implemented on the EVM and shown in the EVM user's guide, *[TPS62916EVM](https://www.ti.com/lit/pdf/SLVUCO4) [Evaluation Module](https://www.ti.com/lit/pdf/SLVUCO4)*, as well as in [Figure 7-23](#page-26-0).

7.4.2 Layout Example

Figure 7-22. Recommended Layout for Single L-C Filter

Note

The start winding of the inductor, as shown in the figures as a black dot, must be connected to the DC/DC converter switch pin, SW, to minimize capacitive coupling to the surrounding area.

Note

The red dot indicates where the feedback sense must be placed for the best DC regulation. For a single L-C configuration, the feedback sense is placed near the VOUT capacitors. For a second L-C filter design, the feedback sense is placed near the load after the VOUT_FILT capacitors.

Figure 7-23. Recommended Layout for Design with Second L-C Filter

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Note

The ferrite bead can be placed closer to the device as long as it is *not* placed between the inductor and output capacitors. Placing the ferrite bead further away avoids capacitive and electromagnetic coupling to the output of the ferrite bead. If the ferrite bead is placed in the keep out area, the filtering effect of the ferrite bead is greatly reduced. If the ferrite bead is routed through a via to the back side of the board, make sure adequate ground plane between the layers if the ferrite bead are in this area.

8 Device and Documentation Support

8.1 Device Support

8.1.1 Third-Party Products Disclaimer

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8.1.2 Development Support

8.1.2.1 Custom Design With WEBENCH® Tools

[Click here](https://webench.ti.com/wb5/TISearch/panel.html?access=N&p=TPS62913&origin=ODS__TPS62913) to create a custom design using the TPS6291x device with the WEBENCH Power Designer.

- 1. Start by entering the input voltage (V_{IN}), output voltage (V_{OUT}), and output current (I_{OUT}) requirements.
- 2. Optimize the design for key parameters such as efficiency, footprint, and cost.
- 3. Open the advanced tab to optimize for output voltage ripple.
- 4. After in a TPS6291x design, you can enable the second stage L-C filter and change other settings from the drop-down on the left.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at [www.ti.com/WEBENCH.](http://www.ti.com/WEBENCH)

8.2 Documentation Support

8.2.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, *Pros and Cons Using a Feedforward Capacitor with a Low Dropout Regulator* application [report](https://www.ti.com/lit/pdf/SBVA042)
- Texas Instruments, *[TPS62916EVM Evaluation Module](https://www.ti.com/lit/pdf/SLVUCO4)* EVM user's guide
- Texas Instruments, *[Five Steps to a Great PCB Layout for a Step-Down Converter](https://www.ti.com/lit/pdf/SLYT614)* analog design journal
- Texas Instruments, *[Design Considerations for a Resistive Feedback Divider in a DC/DC Converter](https://www.ti.com/lit/pdf/SLYT469)* analog [design journal](https://www.ti.com/lit/pdf/SLYT469)

8.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com.](https://www.ti.com) Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

8.4 Support Resources

TI E2E™ [support forums](https://e2e.ti.com) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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8.6 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

8.7 Glossary

[TI Glossary](https://www.ti.com/lit/pdf/SLYZ022) This glossary lists and explains terms, acronyms, and definitions.

9 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

• Deleted the preview note from TPS62918 and TPS62914...[1](#page-0-0)

10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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