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# **LMV831 Single / LMV832 Dual / LMV834 Quad 3.3-MHz Low-Power CMOS, EMI-Hardened Operational Amplifiers**

## <span id="page-0-1"></span>**1 Features**

Texas

**INSTRUMENTS** 

- Unless Otherwise Noted, Typical Values at  $T_A = 25$ °C, V<sup>+</sup> = 3.3 V
- Supply Voltage 2.7 V to 5.5 V
- Supply Current (per Channel) 240 µA
- Input Offset Voltage 1-mV Maximum
- Input Bias Current 0.1 pA
- GBW 3.3 MHz
- EMIRR at 1.8 GHz 120 dB
- Input Noise Voltage at 1 kHz 12 nV/√Hz
- Slew Rate 2 V/µs
- Output Voltage Swing Rail-to-Rail
- Output Current Drive 30 mA
- Operating Ambient Temperature Range −40°C to 125°C

## <span id="page-0-2"></span>**2 Applications**

- Photodiode Preamps
- Piezoelectric Sensors
- Portable/Battery-Powered Electronic Equipment
- <span id="page-0-3"></span>• Filters and Buffers
- <span id="page-0-0"></span>• PDAs and Phone Accessories

# **3 Description**

TI's LMV83x devices are CMOS input, low-power operation amplifier ICs, providing a low input bias current, a wide temperature range of −40°C to 125°C, and exceptional performance, making them robust general-purpose parts. Additionally, the LMV83x are EMI-hardened to minimize any interference, making them ideal for EMI-sensitive applications.

The unity gain stable LMV83x feature 3.3-MHz of bandwidth while consuming only 0.24 mA of current per channel. These parts also maintain stability for capacitive loads as large as 200 pF. The LMV83x provide superior performance and economy in terms of power and space usage.

This family of parts has a maximum input offset voltage of 1 mV, a rail-to-rail output stage and an input common-mode voltage range that includes ground. Over an operating range from 2.7 V to 5.5 V, the LMV83x provide a PSRR of 93 dB, and a CMRR of 91 dB. The LMV831 is offered in the space-saving 5-pin SC70 package, the LMV832 in the 8-pin VSSOP and the LMV834 is offered in the 14--in TSSOP package.

### **Device Information[\(1\)](#page-0-0)**

<b>PART NUMBER</b>	<b>PACKAGE</b>	<b>BODY SIZE (NOM)</b>
LMV831	SC70 (5)	1.25 mm $\times$ 2.00 mm
LMV832	VSSOP (8)	$3.00$ mm $\times$ 3.00 mm
LMV834	<b>TSSOP (14)</b>	4.40 mm $\times$ 5.00 mm

<sup>(1)</sup> For all available packages, see the orderable addendum at the end of the data sheet.

# **Typical Application**



# **Table of Contents**





## <span id="page-1-0"></span>**4 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

#### **Changes from Revision B (March 2013) to Revision C Page**

#### • Added *ESD Ratings* table, *Feature Description* section, *Device Functional Modes*, *Application and Implementation* section, *Power Supply Recommendations* section, *Layout* section, *Device and Documentation Support* section, and *Mechanical, Packaging, and Orderable Information* section. ... [1](#page-0-3)

#### **Changes from Revision A (March 2013) to Revision B Page**

• Changed layout of National Semiconductor Data Sheet to TI format .. [24](#page-23-0)

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# <span id="page-2-0"></span>**5 Pin Configuration and Functions**





**PW Package 14-Pin TSSOP Top View** 14 OUT D OUT A  $13$  $IND^2$ IN A  $IND^+$  $\vee$ v  $10<sup>1</sup>$  $IN C^+$  $INB$  $N C$ 

 $\overline{\mathsf{N}}$ 

 $\overline{N}$  $0<sup>U</sup>$ 

**Pin Functions**

OUT C



## <span id="page-3-0"></span>**6 Specifications**

## <span id="page-3-1"></span>**6.1 Absolute Maximum Ratings**

See (1)(2)



(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.

(3) The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $R_{\theta JA}$ , and  $T_A$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A) / R_{\theta,IA}$ . All numbers apply for packages soldered directly onto a PCB.

### <span id="page-3-2"></span>**6.2 ESD Ratings**



(1) Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of JEDEC) Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC).

### <span id="page-3-3"></span>**6.3 Recommended Operating Conditions**



(1) The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$ , and  $T_A$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A)/\theta_{JA}$ . All numbers apply for packages soldered directly onto a PCB.

### <span id="page-3-4"></span>**6.4 Thermal Information**



(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953.](http://www.ti.com/lit/pdf/spra953)

(2) The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $R_{\theta JA}$ , and  $T_A$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A) / R_{\theta JA}$ . All numbers apply for packages soldered directly onto a PCB.

4



#### <span id="page-4-0"></span>**6.5 Electrical Characteristics, 3.3 V**

Unless otherwise specified, all limits are specified for at T<sub>A</sub> = 25°C, V<sup>+</sup> = 3.3 V, V<sup>-</sup> = 0 V, V<sub>CM</sub> = V<sup>+</sup>/2, and R<sub>L</sub> = 10 kΩ to  $V^{\texttt{+}}$ /2. $^{(1)}$ 



- (1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . No specification of parametric performance is indicated in the electrical tables under conditions of internal self-heating where  $T_J$  >  $T_A$ .
- (2) Limits are 100% production tested at 25°C. Limits over the operating temperature range are specified through correlations using statistical quality control (SQC) method.
- (3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.
- (4) The typical value is calculated by applying absolute value transform to the distribution, then taking the statistical average of the resulting distribution.
- (5) This parameter is specified by design and/or characterization and is not tested in production.<br>(6) The EMI Rejection Ratio is defined as EMIRR = 20log ( $V_{RF}$   $_{PEAK}/\Delta V_{OS}$ ).
- (6) The EMI Rejection Ratio is defined as EMIRR = 20log ( $V_{RF}$   $_{PEAR}/\Delta V_{OS}$ ).<br>(7) The specified limits represent the lower of the measured values for each
- The specified limits represent the lower of the measured values for each output range condition.

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## **Electrical Characteristics, 3.3 V (continued)**

Unless otherwise specified, all limits are specified for at T<sub>A</sub> = 25°C, V<sup>+</sup> = 3.3 V, V<sup>-</sup> = 0 V, V<sub>CM</sub> = V<sup>+</sup>/2, and R<sub>L</sub> = 10 kΩ to  $V^{+}/2$ . $^{(1)}$  $^{(1)}$  $^{(1)}$ 



(8) Number specified is the slower of positive and negative slew rates.



## **Electrical Characteristics, 3.3 V (continued)**

Unless otherwise specified, all limits are specified for at T<sub>A</sub> = 25°C, V<sup>+</sup> = 3.3 V, V<sup>-</sup> = 0 V, V<sub>CM</sub> = V<sup>+</sup>/2, and R<sub>L</sub> = 10 kΩ to  $V^{+}/2$ . $^{(1)}$  $^{(1)}$  $^{(1)}$ 



### <span id="page-6-1"></span><span id="page-6-0"></span>**6.6 Electrical Characteristics, 5 V**

Unless otherwise specified, all limits are specified for at T<sub>A</sub> = 25°C, V<sup>+</sup> = 5 V, V<sup>-</sup> = 0 V, V<sub>CM</sub> = V<sup>+</sup>/2, and R<sub>L</sub> = 10 kΩ to V<sup>+</sup>/2. <sup>(1)</sup>



- (1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . No specification of parametric performance is indicated in the electrical tables under conditions of internal self-heating where  $T_J$  >  $T_A$ .
- (2) Limits are 100% production tested at 25°C. Limits over the operating temperature range are specified through correlations using statistical quality control (SQC) method.
- (3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.
- (4) The typical value is calculated by applying absolute value transform to the distribution, then taking the statistical average of the resulting distribution.
- (5) This parameter is specified by design and/or characterization and is not tested in production.
- (6) The EMI Rejection Ratio is defined as EMIRR = 20log ( $V_{RF\_PEAK}/\Delta V_{OS}$ ).

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### **Electrical Characteristics, 5 V (continued)**



Unless otherwise specified, all limits are specified for at  $T$ <sup>+</sup> = 5 V, V<sup>-</sup> = 0 V, V<sub>CM</sub> = V<sup>+</sup>/2, and R<sub>L</sub> = 10 kΩ to V<sup>+</sup>/2.<sup>[\(1\)](#page-8-0)</sup>

(7) The specified limits represent the lower of the measured values for each output range condition.



### **Electrical Characteristics, 5 V (continued)**



Unless otherwise specified, all limits are specified for at T<sub>A</sub> = 25°C, V<sup>+</sup> = 5 V, V<sup>-</sup> = 0 V, V<sub>CM</sub> = V<sup>+</sup>/2, and R<sub>L</sub> = 10 kΩ to V<sup>+</sup>/2. <sup>[\(1\)](#page-8-0)</sup>

<span id="page-8-0"></span>(8) Number specified is the slower of positive and negative slew rates.



0.3

0.2

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## <span id="page-9-0"></span>**6.7 Typical Characteristics**

0.3

0.2

At T<sub>A</sub> = 25°C, R<sub>L</sub> = 10 kΩ, V<sup>+</sup> = 3.3 V, V<sup>-</sup> = 0 V, Unless otherwise specified.

125°C

85°C



 $85^{\circ}C$  125 $\frac{1}{1}$ 



#### **Typical Characteristics (continued)**



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### **Typical Characteristics (continued)**





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### **Typical Characteristics (continued)**



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### **Typical Characteristics (continued)**

At T<sub>A</sub> = 25°C, R<sub>L</sub> = 10 kΩ, V<sup>+</sup> = 3.3 V, V<sup>-</sup> = 0 V, Unless otherwise specified.



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#### **Typical Characteristics (continued)**



#### **[LMV831,](http://www.ti.com/product/lmv831?qgpn=lmv831) [LMV832,](http://www.ti.com/product/lmv832?qgpn=lmv832) [LMV834](http://www.ti.com/product/lmv834?qgpn=lmv834)**

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### **Typical Characteristics (continued)**





## <span id="page-16-0"></span>**7 Detailed Description**

## <span id="page-16-1"></span>**7.1 Overview**

The LMV831, LMV832, and LMV834 are operational amplifiers with excellent specifications, such as low offset, low noise and a rail-to-rail output. The EMI hardening makes the LMV831, LMV832 or LMV834 a must for almost all operational amplifier applications that are exposed to Radio Frequency (RF) signals such as the signals transmitted by mobile phones or wireless computer peripherals. The LMV831, LMV832, and LMV834 will effectively reduce disturbances caused by RF signals to a level that will be hardly noticeable. This again reduces the need for additional filtering and shielding. Using this EMI resistant series of operational amplifiers will thus reduce the number of components and space needed for applications that are affected by EMI, and will help applications, not yet identified as possible EMI sensitive, to be more robust for EMI.

## **7.2 Functional Block Diagram**

<span id="page-16-2"></span>



#### <span id="page-17-0"></span>**7.3 Feature Description**

#### **7.3.1 Input Characteristics**

The input common-mode voltage range of the LMV831, LMV832, and LMV834 includes ground, and can even sense well below ground. The CMRR level does not degrade for input levels up to 1.2 V below the supply voltage. For a supply voltage of 5 V, the maximum voltage that should be applied to the input for best CMRR performance is thus 3.8 V.

When not configured as unity gain, this input limitation will usually not degrade the effective signal range. The output is rail-to-rail and therefore will introduce no limitations to the signal range.

The typical offset is only 0.25 mV, and the TCV<sub>OS</sub> is 0.5  $\mu$ V/°C, specifications close to precision operational amplifiers.

#### **7.3.2 EMIRR**

With the increase of RF transmitting devices in the world, the electromagnetic interference (EMI) between those devices and other equipment becomes a bigger challenge. The LMV831, LMV832, and LMV834 are EMIhardened operational amplifiers which are specifically designed to overcome electromagnetic interference. Along with EMI-hardened operational amplifiers, the EMIRR parameter is introduced to unambiguously specify the EMI performance of an operational amplifier. This section presents an overview of EMIRR. A detailed description on this specification for EMI-hardened operational amplifiers can be found in AN-1698 ([SNOA497\)](http://www.ti.com/lit/pdf/SNOA497).

The dimensions of an operational amplifier IC are relatively small compared to the wavelength of the disturbing RF signals. As a result the operational amplifier itself will hardly receive any disturbances. The RF signals interfering with the operational amplifier are dominantly received by the PCB and wiring connected to the operational amplifier. As a result the RF signals on the pins of the operational amplifier can be represented by voltages and currents. This representation significantly simplifies the unambiguous measurement and specification of the EMI performance of an operational amplifier.

RF signals interfere with operational amplifiers through the non-linearity of the operational amplifier circuitry. This non-linearity results in the detection of the so called out-of-band signals. The obtained effect is that the amplitude modulation of the out-of-band signal is downconverted into the base band. This base band can easily overlap with the band of the operational amplifier circuit. As an example [Figure](#page-17-1) 43 depicts a typical output signal of a unity-gain connected operational amplifier in the presence of an interfering RF signal. Clearly the output voltage varies in the rhythm of the on-off keying of the RF carrier.



**Figure 43. Offset Voltage Variation Due to an Interfering RF Signal**

### <span id="page-17-1"></span>**7.3.3 EMIRR Definition**

To identify EMI-hardened operational amplifiers, a parameter is needed that quantitatively describes the EMI performance of operational amplifiers. A quantitative measure enables the comparison and the ranking of operational amplifiers on their EMI robustness. Therefore the EMI Rejection Ratio (EMIRR) is introduced. This parameter describes the resulting input-referred offset voltage shift of an operational amplifier as a result of an applied RF carrier (interference) with a certain frequency and level. The definition of EMIRR is given by [Equation](#page-17-2) 1:

<span id="page-17-2"></span>
$$
EMIRR_{V_{RF\_PEAK}} = 20 \log \left( \frac{V_{RF\_PEAK}}{\Delta V_{OS}} \right)
$$

In which

 $V_{RF\_PEAK}$  is the amplitude of the applied un-modulated RF signal (V)



#### **Feature Description (continued)**

•  $\Delta V_{\rm OS}$  is the resulting input-referred offset voltage shift (V) (1) (1)

The offset voltage depends quadratically on the applied RF level, and therefore, the RF level at which the EMIRR is determined should be specified. The standard level for the RF signal is 100 mV<sub>P</sub>. AN-1698 [\(SNOA497\)](http://www.ti.com/lit/pdf/SNOA497) addresses the conversion of an EMIRR measured for an other signal level than 100 mV<sub>P</sub>. The interpretation of the EMIRR parameter is straightforward. When two operational amplifiers have an EMIRR which differ by 20 dB, the resulting error signals when used in identical configurations, differ by 20 dB as well. So, the higher the EMIRR, the more robust the operational amplifier.

#### *7.3.3.1 Coupling an RF Signal to the IN+ Pin*

Each of the operational amplifier pins can be tested separately on EMIRR. In this section, the measurements on the IN+ pin (which, based on symmetry considerations, also apply to the IN– pin) are discussed. In AN-1698 [\(SNOA497](http://www.ti.com/lit/pdf/SNOA497)) the other pins of the operational amplifier are treated as well. For testing the IN+ pin the operational amplifier is connected in the unity gain configuration. Applying the RF signal is straightforward as it can be connected directly to the IN+ pin. As a result the RF signal path has a minimum of components that might affect the RF signal level at the pin. The circuit diagram is shown in [Figure](#page-18-0) 44. The PCB trace from  $RF_{\text{IN}}$  to the IN+ pin should be a 50-Ω stripline in order to match the RF impedance of the cabling and the RF generator. On the PCB a 50-Ω termination is used. This 50-Ω resistor is also used to set the bias level of the IN+ pin to ground level. For determining the EMIRR, two measurements are needed: one is measuring the DC output level when the RF signal is off; and the other is measuring the DC output level when the RF signal is switched on. The difference of the two DC levels is the output voltage shift as a result of the RF signal. As the operational amplifier is in the unity-gain configuration, the input referred offset voltage shift corresponds one-to-one to the measured output voltage shift.



**Figure 44. Circuit for Coupling the RF Signal to IN+**

### <span id="page-18-0"></span>*7.3.3.2 Cell Phone Call*

The effect of electromagnetic interference is demonstrated in a set-up where a cell phone interferes with a pressure sensor application. The application is shown in [Figure](#page-22-3) 49.

This application needs two operational amplifiers and therefore a dual operational amplifier is used. The operational amplifier configured as a buffer and connected at the negative output of the pressure sensor prevents the loading of the bridge by resistor R2. The buffer also prevents the resistors of the sensor from affecting the gain of the following gain stage. The operational amplifiers are placed in a single-supply configuration.

The experiment is performed on two different dual operational amplifiers: a typical standard operational amplifier and the LMV832, EMI-hardened dual operational amplifier. A cell phone is placed on a fixed position a couple of centimeters from the operational amplifiers in the sensor circuit.

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### **Feature Description (continued)**

When the cell phone is called, the PCB and wiring connected to the operational amplifiers receive the RF signal. Subsequently, the operational amplifiers detect the RF voltages and currents that end up at their pins. The resulting effect on the output of the second operational amplifier is shown in [Figure](#page-19-1) 45.



**Figure 45. Comparing EMI Robustness**

<span id="page-19-1"></span>The difference between the two types of dual operational amplifiers is clearly visible. The typical standard dual operational amplifier has an output shift (disturbed signal) larger than 1 V as a result of the RF signal transmitted by the cell phone. The LMV832, EMI-hardened operational amplifier does not show any significant disturbances. This means that the RF signal will not disturb the signal entering the ADC when using the LMV832.

### <span id="page-19-0"></span>**7.4 Device Functional Modes**

#### **7.4.1 Output Characteristics**

As already mentioned the output is rail-to-rail. When loading the output with a 10-kΩ resistor the maximum swing of the output is typically 6 mV from the positive and negative rail.

The output of the LMV83x can drive currents up to 30 mA at 3.3 V and even up to 65 mA at 5 V.

The LMV83x can be connected as noninverting unity-gain amplifiers. This configuration is the most sensitive to capacitive loading. The combination of a capacitive load placed at the output of an amplifier along with the output impedance of the amplifier creates a phase lag, which reduces the phase margin of the amplifier. If the phase margin is significantly reduced, the response will be under damped which causes peaking in the transfer and, when there is too much peaking, the operational amplifier might start oscillating. The LMV83x can directly drive capacitive loads up to 200 pF without any stability issues. In order to drive heavier capacitive loads, an isolation resistor,  $R_{\text{ISO}}$ , should be used, as shown in [Figure](#page-19-2) 46. By using this isolation resistor, the capacitive load is isolated from the output of the amplifier, and hence, the pole caused by  $C_\mathsf{L}$  is no longer in the feedback loop. The larger the value of  $R_{ISO}$ , the more stable the amplifier will be. If the value of  $R_{ISO}$  is sufficiently large, the feedback loop will be stable, independent of the value of C<sub>L</sub>. However, larger values of R<sub>ISO</sub> result in reduced output swing and reduced output current drive.



**Figure 46. Isolating Capacitive Load**

<span id="page-19-2"></span>A resistor value of around 150 Ω would be sufficient. As an example some values are given in [Table](#page-20-0) 1, for 5 V.

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#### **Device Functional Modes (continued)**

<span id="page-20-0"></span>

#### **Table 1. Resistor Values**

#### **7.4.2 CMRR Measurement**

The CMRR measurement results may need some clarification. This is because different set-ups are used to measure the AC CMRR and the DC CMRR.

The DC CMRR is derived from  $\Delta V_{OS}$  versus  $\Delta V_{CM}$ . This value is stated in the tables, and is tested during production testing. The AC CMRR is measured with the test circuit shown in [Figure](#page-20-1) 47.



**Figure 47. AC CMRR Measurement Set-Up**

<span id="page-20-1"></span>The configuration is largely the usually applied balanced configuration. With potentiometer P1, the balance can be tuned to compensate for the DC offset in the DUT. The main difference is the addition of the buffer. This buffer prevents the open-loop output impedance of the DUT from affecting the balance of the feedback network. Now the closed-loop output impedance of the buffer is a part of the balance. As the closed-loop output impedance is much lower, and by careful selection of the buffer also has a larger bandwidth, the total effect is that the CMRR of the DUT can be measured much more accurately. The differences are apparent in the larger measured bandwidth of the AC CMRR.

One artifact from this test circuit is that the low frequency CMRR results appear higher than expected. This is because in the AC CMRR test circuit the potentiometer is used to compensate for the DC mismatches. So, mainly AC mismatch is all that remains. Therefore, the obtained DC CMRR from this AC CMRR test circuit tends to be higher than the actual DC CMRR based on DC measurements.

The CMRR curve in [Figure](#page-21-0) 48 shows a combination of the AC CMRR and the DC CMRR.

**EXAS STRUMENTS** 



<span id="page-21-0"></span>



## <span id="page-22-0"></span>**8 Application and Implementation**

#### **NOTE**

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

#### <span id="page-22-1"></span>**8.1 Application Information**

The LMV83x family of amplifiers is specified for operation from 2.7 V to 5.5 V ( $\pm$ 1.35 V to  $\pm$ 2.25 V). Parameters that can exhibit significant variance with regard to operating voltage or temperature are presented in the *[Typical](#page-9-0) [Characteristics](#page-9-0)*.

#### <span id="page-22-2"></span>**8.2 Typical Application**



**Figure 49. Pressure Sensor Application**

#### <span id="page-22-3"></span>**8.2.1 Design Requirements**

The LMV83x can be used for pressure sensor applications. Because of their low power the LMV83x are ideal for portable applications, such as blood pressure measurement devices, or portable barometers. This example describes a universal pressure sensor that can be used as a starting point for different types of sensors and applications.

The pressure sensor used in this example functions as a Wheatstone bridge. The value of the resistors in the bridge change when pressure is applied to the sensor. This change of the resistor values will result in a differential output voltage, depending on the sensitivity of the sensor and the applied pressure.

#### **8.2.2 Detailed Design Procedure**

The difference between the output at full-scale pressure and the output at zero pressure is defined as the span of the pressure sensor. A typical value for the span is 100 mV. A typical value for the resistors in the bridge is 5 kΩ. Loading of the resistor bridge could result in incorrect output voltages of the sensor. Therefore the selection of the circuit configuration, which connects to the sensor, should take into account a minimum loading of the sensor.

The configuration shown in [Figure](#page-22-3) 49 is simple, and is very useful for the read out of pressure sensors. With two operational amplifiers in this application, the dual LMV832 fits very well. The operational amplifier configured as a buffer and connected at the negative output of the pressure sensor prevents the loading of the bridge by resistor R2. The buffer also prevents the resistors of the sensor from affecting the gain of the following gain stage. Given the differential output voltage  $V<sub>S</sub>$  of the pressure sensor, the output signal of this operational amplifier configuration,  $V_{\text{OUT}}$ , equals [Equation](#page-23-1) 2:

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**ISTRUMENTS** 

**EXAS** 

## <span id="page-23-1"></span>**Typical Application (continued)**

$$
V_{\text{OUT}} = \frac{V_{\text{DD}}}{2} - \frac{V_{\text{S}}}{2} \left( 1 + 2 \times \frac{R1}{R2} \right)
$$

To align the pressure range with the full range of an ADC, the power supply voltage and the span of the pressure sensor are needed. For this example a power supply of 5 V is used and the span of the sensor is 100 mV. When a 100-Ω resistor is used for R2, and a 2.4-kΩ resistor is used for R1, the maximum voltage at the output is 4.95 V and the minimum voltage is 0.05 V. This signal is covering almost the full input range of the ADC. Further processing can take place in the microprocessor following the ADC.

## <span id="page-23-0"></span>**8.2.3 Application Curve**

[Figure](#page-23-2) 50 shows the resulting output voltage as  $R_X$  is varied between 4.5 kΩ and 5.5 kΩ.



<span id="page-23-2"></span>**Figure 50. Output Voltage vs R<sup>X</sup>**



## <span id="page-24-0"></span>**9 Power Supply Recommendations**

For proper operation, the power supplies must be properly decoupled. For decoupling the supply lines, TI recommends that 10-nF capacitors be placed as close as possible to the operational amplifier power supply pins. For single-supply, place a capacitor between V+ and V− supply leads. For dual supplies, place one capacitor between V+ and ground, and one capacitor between V– and ground.

#### **CAUTION**

Supply voltages larger than 6 V can permanently damage the device.

The internal RFI filters shunt the received EMI energy to the supply pins. To maximize the effectiveness of the built-in EMI filters, the power supply pin bypassing should have a low impedance, low inductance path to RF ground.

The normally suggested 0.1-µF and larger capacitors tend to be inductive over the effective frequency range of the EMI filters and are not effective at filtering high frequencies (> 50 MHz). Capacitors with high self-resonance frequencies near the GHz range should be placed at the supply pins. This can be accomplished with small (0805 or less) 10 pF to 100 pF SMT ceramic capacitors placed directly at the supply pins to a solid RF ground. These capacitors will provide a direct AC path for the high-frequency EMI to ground. These capacitors are in addition to, and not a replacement for, the recommended low-frequency supply bypassing capacitors.

## <span id="page-25-0"></span>**10 Layout**

#### <span id="page-25-1"></span>**10.1 Layout Guidelines**

- Connect low-ESR, 0.1-μF ceramic bypass capacitors between each supply pin and ground, placed as close to the device as possible. A single bypass capacitor from V+ to ground is applicable for single-supply applications.
- For single-supply, place a capacitor between V<sup>+</sup> and V<sup>-</sup>.
- For dual supplies, place one capacitor between V<sup>+</sup> and the board ground, and a second capacitor between ground and V<sup>−</sup>.
- Noise can propagate into analog circuitry through the power pins of the circuit as a whole and operational amplifier itself. Bypass capacitors are used to reduce the coupled noise by providing low-impedance power sources local to the analog circuitry.
- Separate grounding for analog and digital portions of circuitry is one of the simplest and most-effective methods of noise suppression. One or more layers on multilayer PCBs are usually devoted to ground planes. A ground plane helps distribute heat and reduces EMI noise pick-up. Make sure to physically separate digital and analog grounds paying attention to the flow of the ground current. For more detailed information refer to *Circuit Board Layout Techniques*, [SLOA089.](http://www.ti.com/lit/pdf/SLOA089)
- In order to reduce parasitic coupling, run the input traces as far away from the supply or output traces as possible. If it is not possible to keep them separate, it is much better to cross the sensitive trace perpendicular as opposed to in parallel with the noisy trace.
- Place the external components as close to the device as possible, keeping RF and RG close to the inverting input minimizes parasitic capacitance.
- Keep the length of input traces as short as possible. Always remember that the input traces are the most sensitive part of the circuit.

Even with the LMV83x inherent hardening against EMI, TI still recommends to keep the input traces short and as far as possible from RF sources. Then the RF signals entering the chip are as low as possible, and the remaining EMI can be, almost, completely eliminated in the chip by the EMI reducing features of the LMV83x.

### <span id="page-25-2"></span>**10.2 Layout Example**



**Figure 51. SOT-23 Noninverting Layout Example**



## <span id="page-26-1"></span>**11 Device and Documentation Support**

#### <span id="page-26-2"></span>**11.1 Device Support**

#### **11.1.1 Development Support**

LMV831 PSPICE Model, [SNOM049](http://www.ti.com/lit/zip/snom049)

LMV832 PSPICE Model, [SNOM050](http://www.ti.com/lit/zip/snom050)

LMV834 PSPICE Model, [SNOM038](http://www.ti.com/lit/zip/snom038)

TINA-TI SPICE-Based Analog Simulation Program, <http://www.ti.com/tool/tina-ti>

TI Filterpro Software, <http://www.ti.com/tool/filterpro>

DIP Adapter Evaluation Module, <http://www.ti.com/tool/dip-adapter-evm>

TI Universal Operational Amplifier Evaluation Module, <http://www.ti.com/tool/opampevm>

### <span id="page-26-3"></span>**11.2 Documentation Support**

#### **11.2.1 Related Documentation**

For related documentation, see the following:

- *AN-028 Feedback Plots Define Op Amp AC Performance*, [SBOA015](http://www.ti.com/lit/pdf/SBOA015)
- *Circuit Board Layout Techniques*, [SLOA089](http://www.ti.com/lit/pdf/SLOA089)
- *Capacitive Load Drive Solution using an Isolation Resistor*, [TIPD128](http://www.ti.com/tool/TIPD128)
- *Handbook of Operational Amplifier Applications*, [SBOA092](http://www.ti.com/lit/pdf/SBOA092)
- *EMI-Hardened Operational Amplifiers for Robust Circuit Design*, [SNOA817](http://www.ti.com/lit/pdf/SNOA817)
- *AN-1698 A Specification for EMI Hardened Operational Amplifiers*, [SNOA497](http://www.ti.com/lit/pdf/SNOA497)
- *AN-1867 EMIRR Evaluation Boards for LMV831/LMV832/LMV834* (Boards are no longer available for reference only), [SNOA530](http://www.ti.com/lit/pdf/SNOA530)

### <span id="page-26-0"></span>**11.3 Related Links**

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.



#### **Table 2. Related Links**

#### <span id="page-26-4"></span>**11.4 Community Resources**

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms](http://www.ti.com/corp/docs/legal/termsofuse.shtml) of [Use.](http://www.ti.com/corp/docs/legal/termsofuse.shtml)

**TI E2E™ Online [Community](http://e2e.ti.com)** *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design [Support](http://support.ti.com/)** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

## <span id="page-26-5"></span>**11.5 Trademarks**

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#### **[LMV831,](http://www.ti.com/product/lmv831?qgpn=lmv831) [LMV832,](http://www.ti.com/product/lmv832?qgpn=lmv832) [LMV834](http://www.ti.com/product/lmv834?qgpn=lmv834)**

SNOSAZ6C –AUGUST 2008–REVISED NOVEMBER 2015 **[www.ti.com](http://www.ti.com)**



#### <span id="page-27-0"></span>**11.6 Electrostatic Discharge Caution**



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

## <span id="page-27-1"></span>**11.7 Glossary**

#### [SLYZ022](http://www.ti.com/lit/pdf/SLYZ022) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## <span id="page-27-2"></span>**12 Mechanical, Packaging, and Orderable Information**

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



## **PACKAGING INFORMATION**



**(1)** The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

**(3)** MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

**(4)** There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

**(5)** Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.



# **PACKAGE OPTION ADDENDUM**

www.ti.com 10-Dec-2020

<sup>(6)</sup> Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

# **PACKAGE MATERIALS INFORMATION**

**TEXAS NSTRUMENTS** 

www.ti.com 5-Jan-2022

## **TAPE AND REEL INFORMATION**





## **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**







www.ti.com 5-Jan-2022

# **PACKAGE MATERIALS INFORMATION**



\*All dimensions are nominal





www.ti.com 5-Jan-2022

# **TUBE**



#### \*All dimensions are nominal





# **PACKAGE OUTLINE**

# **DGK0008A VSSOP - 1.1 mm max height**

SMALL OUTLINE PACKAGE



NOTES:

PowerPAD is a trademark of Texas Instruments.

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-187.



# **EXAMPLE BOARD LAYOUT**

#### **DGK0008A VSSOP - 1.1 mm max height** TM

SMALL OUTLINE PACKAGE



NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- 8. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown
- on this view. It is recommended that vias under paste be filled, plugged or tented.
- 9. Size of metal pad may vary due to creepage requirement.



# **EXAMPLE STENCIL DESIGN**

# **DGK0008A VSSOP - 1.1 mm max height** TM

SMALL OUTLINE PACKAGE



NOTES: (continued)

11. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

12. Board assembly site may have different recommendations for stencil design.





# **PACKAGE OUTLINE**

# **DCK0005A SOT - 1.1 max height**

SMALL OUTLINE TRANSISTOR



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. Refernce JEDEC MO-203.
- 4. Support pin may differ or may not be present.
- 5. Lead width does not comply with JEDEC.
- 6. Body dimensions do not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.25mm per side



# **EXAMPLE BOARD LAYOUT**

# **DCK0005A SOT - 1.1 max height**

SMALL OUTLINE TRANSISTOR



NOTES: (continued)

7. Publication IPC-7351 may have alternate designs.

8. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



# **EXAMPLE STENCIL DESIGN**

# **DCK0005A SOT - 1.1 max height**

SMALL OUTLINE TRANSISTOR



NOTES: (continued)

9. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

10. Board assembly site may have different recommendations for stencil design.





# **PACKAGE OUTLINE**

# **PW0014A TSSOP - 1.2 mm max height**

SMALL OUTLINE PACKAGE



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-153.



# **EXAMPLE BOARD LAYOUT**

# **PW0014A TSSOP - 1.2 mm max height**

SMALL OUTLINE PACKAGE



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



# **EXAMPLE STENCIL DESIGN**

# **PW0014A TSSOP - 1.2 mm max height**

SMALL OUTLINE PACKAGE



NOTES: (continued)

9. Board assembly site may have different recommendations for stencil design.



<sup>8.</sup> Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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