

# TAS6424M-Q1 45-W, 2-MHz digital input 4-channel automotive class-D audio amplifier with load dump protection and I<sup>2</sup>C diagnostics

## 1 Features

- AEC-Q100 Qualified for Automotive Applications
  - Device Temperature Grade 1: –40°C to +125°C T<sub>A</sub>
- Advanced Load Diagnostics
  - DC Diagnostics run without Input Clocks
  - AC Diagnostic for Tweeter Detection with Impedance and Phase Response
- Easily meet CISPR25-L5 EMC Specification
- Audio Inputs
  - 4 Channel I<sup>2</sup>S or 4/8-Channel TDM Input
  - Input Sample Rates: 44.1 kHz, 48 kHz, 96 kHz
  - Input Formats: 16-bit to 32-bit I<sup>2</sup>S, and TDM
- Audio Outputs
  - Four-Channel Bridge-Tied Load (BTL)
  - Two-Channel Parallel BTL (PBTL)
  - Up to 2.1 MHz Output Switching Frequency
  - 27 W, 10% THD Into 4 Ω at 14.4 V BTL
  - 45 W, 10% THD Into 2 Ω at 14.4 V BTL
  - 80 W, 10% THD Into 2 Ω at 18 V PBTL
- Audio Performance Into 4 Ω at 14.4 V BTL
  - THD+N < 0.02% at 1 W
  - 42 μV<sub>RMS</sub> Output Noise
  - –90 dB Crosstalk
- Load Diagnostics
  - Output Open and Shorted Load
  - Output-to-Battery or Ground Shorts
  - Line Output Detection Up to 6 kΩ
  - Host-Independent Operation
- Protection
  - Output Current Limiting
  - Output Short Protection
  - 40 V Load Dump
  - Open Ground and Power Tolerant
  - DC Offset
  - Overtemperature
  - Undervoltage and Overvoltage
- General Operation
  - 4.5 V to 18 V Supply voltage
  - I<sup>2</sup>C Control With 4 Address Options
  - Clip Detection and Thermal Warning

## 2 Applications

- Automotive Head Unit
- Automotive External Amplifier

## 3 Description

The TAS6424M-Q1 device is a four-channel digital-input Class-D audio amplifier that implements a 2.1 MHz PWM switching frequency enabling a cost-optimized solution in a very small PCB size, full operation down to 4.5 V for start/stop events, and exceptional sound quality with up to 40 kHz audio bandwidth.

The output switching frequency can be set either above the AM band, which eliminates AM-band interferences and reduces output filtering and cost, or below the AM band to optimize efficiency.

The device has a built-in load diagnostic function for detecting and diagnosing misconnected outputs as well as detection of AC-coupled tweeters to help to reduce test time during the manufacturing process.

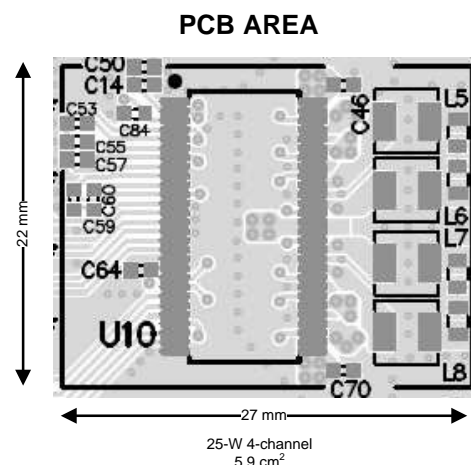
The TAS6424M-Q1 Class-D audio amplifier is designed for use in automotive head units and external amplifier modules. The device provides four channels at 27 W into 4 Ω at 10% THD+N and 45 W into 2 Ω at 10% THD+N from a 14.4 V supply.

For pin compatible one, two and four-channel devices see the TAS6421-Q1, TAS6422-Q1, TAS6424L-Q1 and TAS6424-Q1.

### Device Information<sup>(1)</sup>

| PART NUMBER | PACKAGE    | BODY SIZE (NOM)    |
|-------------|------------|--------------------|
| TAS6424M-Q1 | HSSOP (56) | 18.41 mm x 7.49 mm |

(1) For all available packages, see the orderable addendum at the end of the datasheet.



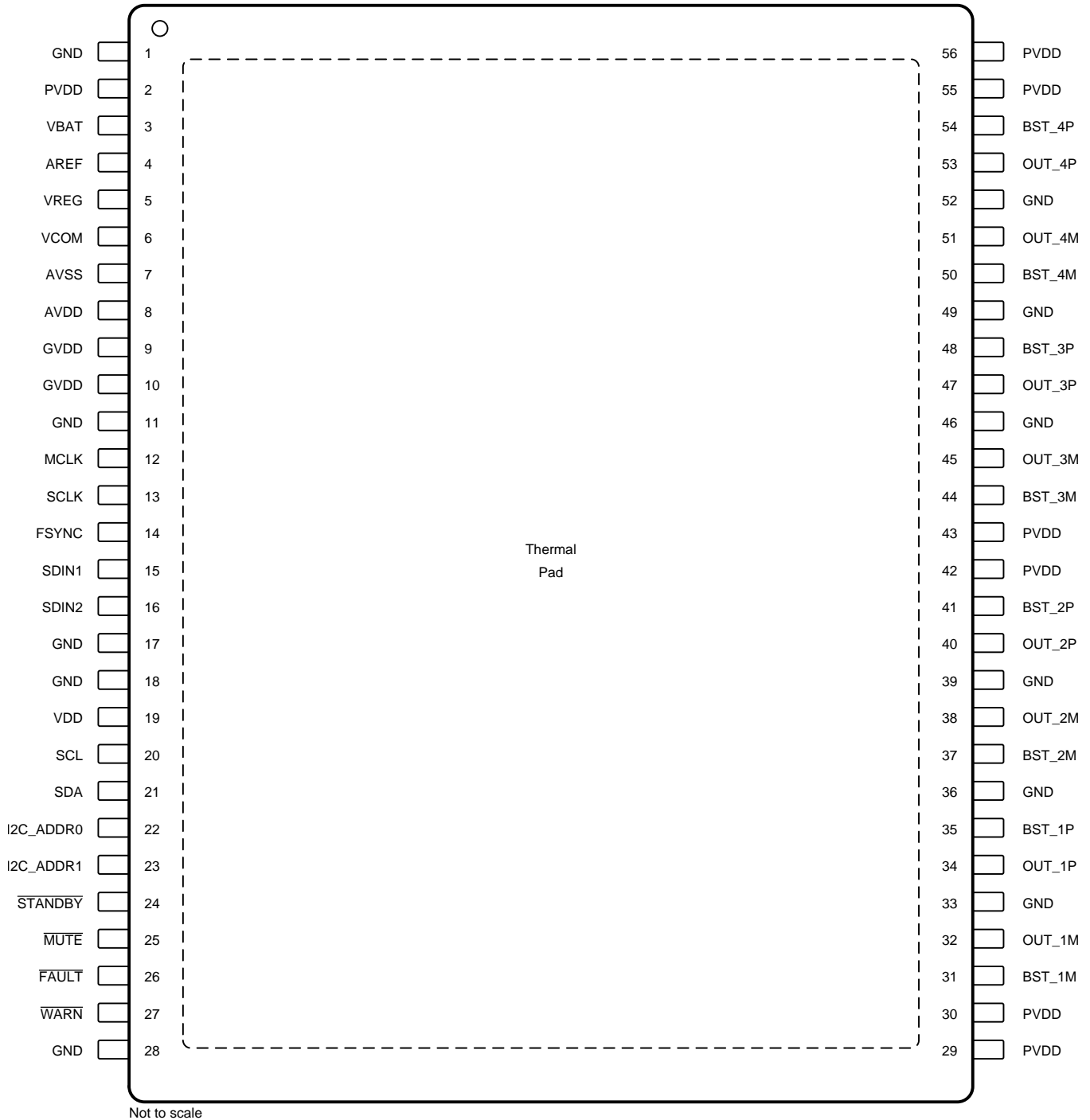


## 5 Device Options

| Part Number | Channel Count | Power-Supply Voltage Range | Current Limit (Typ) | Output Power / 10% THD     |                                 |                            |                                  |
|-------------|---------------|----------------------------|---------------------|----------------------------|---------------------------------|----------------------------|----------------------------------|
|             |               |                            |                     | 4 $\Omega$ / BTL<br>14.4 V | 4 $\Omega$ / BTL<br>Max Voltage | 2 $\Omega$ / BTL<br>14.4 V | 2 $\Omega$ / PBTL<br>Max Voltage |
| TAS6424-Q1  | 4             | 4.5 V to 26.4 V            | 6.5 A               | 27 W                       | 75 W at 25 V                    | 45 W                       | 150 W at 25 V                    |
| TAS6424M-Q1 | 4             | 4.5 V to 18 V              | 6.5 A               | 27 W                       | 45 W at 18 V                    | 45 W                       | 80 W at 18 V                     |
| TAS6424L-Q1 | 4             | 4.5 V to 18 V              | 4.8 A               | 27 W                       | 45 W at 18 V                    | 27 W                       | 80 W at 18 V                     |
| TAS6422-Q1  | 2             | 4.5 V to 26.4 V            | 6.5 A               | 27 W                       | 75 W at 25 V                    | 45 W                       | 150 W at 25 V                    |
| TAS6421-Q1  | 1             | 4.5 V to 26.4 V            | 6.5 A               | 27 W                       | 75 W at 25 V                    | 45 W                       | N/A                              |

## 6 Pin Configuration and Functions

**DKQ Package**  
**56-Pin HSSOP With Exposed Thermal Pad**  
**Top View**



### Pin Functions

| PIN                         |   | TYPE <sup>(1)</sup> | DESCRIPTION  |
|-----------------------------|---|---------------------|--|
| NAME                        | NO.   |                     |  |
| AREF                        | 4   | PWR                 | VREG and VCOM bypass capacitor return  |
| AVDD                        | 8   | PWR                 | Voltage regulator bypass. Connect 1 $\mu$ F capacitor from AVDD to AVSS  |
| AVSS                        | 7   | PWR                 | AVDD bypass capacitor return   |
| BST_1M                      | 31  | PWR                 | Bootstrap capacitor connection pins for high-side gate driver  |
| BST_1P                      | 35  | PWR                 | Bootstrap capacitor connection pins for high-side gate driver  |
| BST_2M                      | 37  | PWR                 | Bootstrap capacitor connection pins for high-side gate driver  |
| BST_2P                      | 41  | PWR                 | Bootstrap capacitor connection pins for high-side gate driver  |
| BST_3M                      | 44  | PWR                 | Bootstrap capacitor connection pins for high-side gate driver  |
| BST_3P                      | 48  | PWR                 | Bootstrap capacitor connection pins for high-side gate driver  |
| BST_4M                      | 50  | PWR                 | Bootstrap capacitor connection pins for high-side gate driver  |
| BST_4P                      | 54  | PWR                 | Bootstrap capacitor connection pins for high-side gate driver  |
| $\overline{\text{FAULT}}$   | 26  | DO                  | Reports a fault (active low, open drain), 100-k $\Omega$ internal pull-up resistor   |
| FSYNC                       | 14  | DI                  | Audio frame clock input  |
| GND                         | 1, 11, 17, 18,<br>28, 33, 36, 39,<br>46, 49, 52 | GND                 | Ground   |
| GVDD                        | 9   | PWR                 | Gate drive voltage regulator derived from VBAT input pin. Connect 2.2 $\mu$ F capacitor to GND                               |
|                             | 10  |                     | Gate drive voltage regulator derived from VBAT input pin. Connect 2.2 $\mu$ F capacitor to GND                               |
| I2C_ADDR0                   | 22  | DI                  | I <sup>2</sup> C address pins. Refer to <a href="#">Table 8</a>  |
| I2C_ADDR1                   | 23  |                     |  |
| MCLK                        | 12  | DI                  | Audio master clock input   |
| $\overline{\text{MUTE}}$    | 25  | DI                  | Mutes the device outputs (active low) while keeping output FETs switching at 50%, 100-k $\Omega$ internal pull-down resistor |
| OUT_1M                      | 32  | NO                  | Negative output for the channel  |
| OUT_1P                      | 34  | PO                  | Positive output for the channel  |
| OUT_2M                      | 38  | NO                  | Negative output for the channel  |
| OUT_2P                      | 40  | PO                  | Positive output for the channel  |
| OUT_3M                      | 45  | NO                  | Negative output for the channel  |
| OUT_3P                      | 47  | PO                  | Positive output for the channel  |
| OUT_4M                      | 51  | NO                  | Negative output for the channel  |
| OUT_4P                      | 53  | PO                  | Positive output for the channel  |
| PVDD                        | 2, 29, 30, 42,<br>43, 55, 56                    | PWR                 | PVDD voltage input (can be connected to battery). Bulk capacitor and bypass capacitor required                               |
| SCL                         | 20  | DI                  | I <sup>2</sup> C clock input   |
| SCLK                        | 13  | DI                  | Audio bit and serial clock input   |
| SDA                         | 21  | DI/O                | I <sup>2</sup> C data input and output   |
| SDIN1                       | 15  | DI                  | TDM data input and audio I <sup>2</sup> S data input for channels 1 and 2  |
| SDIN2                       | 16  | DI                  | Audio I <sup>2</sup> S data input for channels 3 and 4   |
| $\overline{\text{STANDBY}}$ | 24  | DI                  | Enables low power standby state (active Low), 100-k $\Omega$ internal pull-down resistor                                     |
| VBAT                        | 3   | PWR                 | Battery voltage input  |
| VCOM                        | 6   | PWR                 | Bias voltage   |
| VDD                         | 19  | PWR                 | 3.3-V external supply voltage  |
| VREG                        | 5   | PWR                 | Voltage regulator bypass   |
| $\overline{\text{WARN}}$    | 27  | DO                  | Clip and overtemperature warning (active low, open drain), 100-k $\Omega$ internal pull-up resistor                          |
| Thermal Pad                 | —   | GND                 | Provides both electrical and thermal connection for the device. Heatsink must be connected to GND.                           |

(1) GND = ground, PWR = power, PO = positive output, NO = negative output, DI = digital input, DO = digital output, DI/O = digital input and output, NC = no connection

## 7 Specifications

### 7.1 Absolute Maximum Ratings<sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

|                         |  | MIN  | MAX       | UNIT |
|-------------------------|--|------|-----------|------|
| PVDD, VBAT              | DC supply voltage relative to GND  | -0.3 | 30        | V    |
| V <sub>MAX</sub>        | Transient supply voltage: PVDD, VBAT   | -1   | 40        | V    |
| V <sub>RAMP</sub>       | Supply-voltage ramp rate: PVDD, VBAT   |      | 75        | V/ms |
| VDD                     | DC supply voltage relative to GND  | -0.3 | 3.5       | V    |
| I <sub>MAX</sub>        | Maximum current per pin (PVDD, VBAT, OUT_xP, OUT_xM, GND)  |      | 8         | A    |
| I <sub>MAX_PULSED</sub> | Pulsed supply current per PVDD pin (one shot)  |      | 12        | A    |
| V <sub>LOGIC</sub>      | Input voltage for logic pins (SCL, SDA, SDIN1, SDIN2, MCLK, BCLK, LRCLK, MUTE, STANDBY, I2C_ADDRx) | -0.3 | VDD + 0.5 | V    |
| V <sub>GND</sub>        | Maximum voltage between GND pins   | -0.3 | 0.3       | V    |
| T <sub>J</sub>          | Maximum operating junction temperature   | -55  | 150       | °C   |
| T <sub>stg</sub>        | Storage temperature  | -55  | 150       | °C   |

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 7.2 ESD Ratings

|                    |                         | VALUE   | UNIT                           |       |
|--------------------|-------------------------|---|--------------------------------|-------|
| V <sub>(ESD)</sub> | Electrostatic discharge | Human-body model (HBM), per AEC Q100-002 <sup>(1)</sup><br>HBM ESD Classification Level 2 | ±3000                          |       |
|                    |                         | Charged-device model (CDM), per AEC Q100-011<br>CDM ESD Classification Level C4           | All pins                       | ±500  |
|                    |                         |   | Corner pins (1, 28, 29 and 56) | ±1000 |

(1) AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

### 7.3 Recommended Operating Conditions

|                     |  |  | MIN | NOM  | MAX | UNIT |
|---------------------|--|--|-----|------|-----|------|
| PVDD                | Output FET supply voltage                              | Relative to GND                                      | 4.5 |      | 18  | V    |
| VBAT                | Battery supply voltage input                           | Relative to GND                                      | 4.5 | 14.4 | 18  | V    |
| VDD                 | DC logic supply  | Relative to GND                                      | 3.0 | 3.3  | 3.5 | V    |
| T <sub>A</sub>      | Ambient temperature                                    |  | –40 |      | 125 | °C   |
| T <sub>J</sub>      | Junction temperature                                   | An adequate thermal design is required               | –40 |      | 150 | °C   |
| R <sub>L</sub>      | Nominal speaker load impedance                         | BTL Mode   | 2   | 4    |     | Ω    |
|                     |  | PBTL Mode  | 1   | 2    |     |      |
| R <sub>PU_I2C</sub> | I <sup>2</sup> C pullup resistance on SDA and SCL pins |  | 1   | 4.7  | 10  | kΩ   |
| C <sub>Bypass</sub> | External capacitance on bypass pins                    | Pin 2, 3, 5, 6, 8, 19                                |     | 1    |     | μF   |
| C <sub>GVDD</sub>   | External capacitance on GVDD pins                      | Pin 9, 10  |     | 2.2  |     | μF   |
| C <sub>OUT</sub>    | External capacitance to GND on OUT pins                | Limit set by DC-diagnostic timing                    |     | 1    | 3.3 | μF   |
| L <sub>O</sub>      | Output filter inductance                               | Minimum inductance at I <sub>SD</sub> current levels | 1   |      |     | μH   |

### 7.4 Thermal Information

| THERMAL METRIC <sup>(1)</sup> |  | TAS6424M-Q1 <sup>(2)</sup> | TAS6424M-Q1 <sup>(3)</sup> | UNIT |
|-------------------------------|--|----------------------------|----------------------------|------|
|                               |  | DKQ (HSSOP)                | DKQ (HSSOP)                |      |
|                               |  | 56 PINS                    | 56 PINS                    |      |
| R <sub>θJA</sub>              | Junction-to-ambient thermal resistance       | 38.8                       | —                          | °C/W |
| R <sub>θJC(top)</sub>         | Junction-to-case (top) thermal resistance    | 0.3                        | 1.1                        | °C/W |
| R <sub>θJB</sub>              | Junction-to-board thermal resistance         | 16.0                       | —                          | °C/W |
| ψ <sub>JT</sub>               | Junction-to-top characterization parameter   | 0.1                        | —                          | °C/W |
| ψ <sub>JB</sub>               | Junction-to-board characterization parameter | 14.6                       | 10                         | °C/W |
| R <sub>θJC(bot)</sub>         | Junction-to-case (bottom) thermal resistance | n/a                        | —                          | °C/W |

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report (SPRA953).

(2) JEDEC Standard 4 Layer PCB.

(3) Measured using the TAS6424M-Q1 EVM layout and heat sink. The device is not intended to be used without a heat sink.

## 7.5 Electrical Characteristics

Test conditions (unless otherwise noted):  $T_C = 25^\circ\text{C}$ ,  $PVDD = VBAT = 14.4\text{ V}$ ,  $VDD = 3.3\text{ V}$ ,  $R_L = 4\ \Omega$ ,  $P_{out} = 1\text{ W/ch}$ ,  $f = 1\text{ kHz}$ ,  $f_{SW} = 2.11\text{ MHz}$ , AES17 Filter, default  $I^2C$  settings, see [Figure 79](#)

| PARAMETER                          |   | TEST CONDITIONS  | MIN  | TYP   | MAX | UNIT          |
|------------------------------------|---|--|------|-------|-----|---------------|
| <b>OPERATING CURRENT</b>           |   |  |      |       |     |               |
| $I_{PVDD\_IDLE}$                   | PVDD idle current                               | All channels playing, no audio input   |      | 75    | 90  | mA            |
| $I_{VBAT\_IDLE}$                   | VBAT idle current                               | All channels playing, no audio input   |      | 90    | 100 | mA            |
| $I_{PVDD\_STBY}$                   | PVDD standby current                            | STANDBY Active, $VDD = 0\text{ V}$   |      | 0.5   | 1   | $\mu\text{A}$ |
| $I_{VBAT\_STBY}$                   | VBAT standby current                            | STANDBY Active, $VDD = 0\text{ V}$   |      | 4     | 6   | $\mu\text{A}$ |
| $I_{VDD}$                          | VDD supply current                              | All channels playing, $-60\text{-dB}$ signal   |      | 15    | 18  | mA            |
| <b>OUTPUT POWER</b>                |   |  |      |       |     |               |
| $P_{O\_BTL}$                       | Output power per channel, BTL                   | $4\ \Omega$ , $PVDD = 14.4\text{ V}$ , $THD+N = 1\%$ , $T_C = 75^\circ\text{C}$  | 20   | 22    |     | W             |
|                                    |   | $4\ \Omega$ , $PVDD = 14.4\text{ V}$ , $THD+N = 10\%$ , $T_C = 75^\circ\text{C}$   | 25   | 27    |     |               |
|                                    |   | $2\ \Omega$ , $PVDD = 14.4\text{ V}$ , $THD+N = 1\%$ , $T_C = 75^\circ\text{C}$  | 38   | 40    |     |               |
|                                    |   | $2\ \Omega$ , $PVDD = 14.4\text{ V}$ , $THD+N = 10\%$ , $T_C = 75^\circ\text{C}$   | 42   | 45    |     |               |
|                                    |   | $4\ \Omega$ , $PVDD = 18\text{ V}$ , $THD+N = 1\%$ , $T_C = 75^\circ\text{C}$  | 30   | 33    |     |               |
|                                    |   | $4\ \Omega$ , $PVDD = 18\text{ V}$ , $THD+N = 10\%$ , $T_C = 75^\circ\text{C}$   | 40   | 45    |     |               |
| $P_{O\_PBTl}$                      | Output power per channel in parallel mode, PBTl | $2\ \Omega$ , $PVDD = 14.4\text{ V}$ , $THD+N = 1\%$ , $T_C = 75^\circ\text{C}$  | 35   | 40    |     | W             |
|                                    |   | $2\ \Omega$ , $PVDD = 14.4\text{ V}$ , $THD+N = 10\%$ , $T_C = 75^\circ\text{C}$   | 45   | 50    |     |               |
|                                    |   | $1\ \Omega$ , $PVDD = 14.4\text{ V}$ , $THD+N = 1\%$ , $T_C = 75^\circ\text{C}$  | 72   | 80    |     |               |
|                                    |   | $1\ \Omega$ , $PVDD = 14.4\text{ V}$ , $THD+N = 10\%$ , $T_C = 75^\circ\text{C}$   | 80   | 90    |     |               |
|                                    |   | $2\ \Omega$ , $PVDD = 18\text{ V}$ , $THD+N = 1\%$ , $T_C = 75^\circ\text{C}$  | 60   | 65    |     |               |
|                                    |   | $2\ \Omega$ , $PVDD = 18\text{ V}$ , $THD+N = 10\%$ , $T_C = 75^\circ\text{C}$   | 75   | 80    |     |               |
| $EFF_P$                            | Power efficiency                                | 4 channels operating, 25 W output power/ch, $4\ \Omega$ load, $PVDD = 14.4\text{ V}$ , $T_C = 25^\circ\text{C}$ , including inductor losses(1) |      | 86%   |     |               |
| <b>AUDIO PERFORMANCE</b>           |   |  |      |       |     |               |
| $V_n$                              | Output noise voltage                            | Zero input, A-weighting, gain level 1, $PVDD = 14.4\text{ V}$  |      | 42    |     | $\mu\text{V}$ |
|                                    |   | Zero input, A-weighting, gain level 2, $PVDD = 14.4\text{ V}$  |      | 55    |     |               |
|                                    |   | Zero input, A-weighting, gain level 3, $PVDD = 18\text{ V}$  |      | 67    |     |               |
|                                    |   | Zero input, A-weighting, gain level 4, $PVDD = 18\text{ V}$  |      | 85    |     |               |
| GAIN                               | Peak output voltage/dBFS                        | Gain level 1, Register 0x01, bit 1-0 = 00  |      | 7.5   |     | V/FS          |
|                                    |   | Gain level 2, Register 0x01, bit 1-0 = 01  |      | 15    |     |               |
|                                    |   | Gain level 3, Register 0x01, bit 1-0 = 10  |      | 21    |     |               |
|                                    |   | Gain level 4, Register 0x01, bit 1-0 = 11  |      | 29    |     |               |
| Crosstalk                          | Channel crosstalk                               | $PVDD = 14.4\text{ Vdc} + 1\text{ V}_{RMS}$ , $f = 1\text{ kHz}$   |      | -90   |     | dB            |
| PSRR                               | Power-supply rejection ratio                    | $PVDD = 14.4\text{ Vdc} + 1\text{ V}_{RMS}$ , $f = 1\text{ kHz}$   |      | 75    |     | dB            |
| THD+N                              | Total harmonic distortion + noise               |  |      | 0.02% |     |               |
| $G_{CH}$                           | Channel-to-channel gain variation               |  | -0.5 | 0     | 0.5 | dB            |
| <b>LINE OUTPUT PERFORMANCE</b>     |   |  |      |       |     |               |
| $V_{n\_LINEOUT}$                   | Line output noise voltage                       | Zero input, A-weighting, channel set to LINE MODE  |      | 42    |     | $\mu\text{V}$ |
| $V_{O\_LINEOUT}$                   | Line output voltage                             | 0-dB input, channel set to LINE MODE   |      | 5.5   |     | $V_{RMS}$     |
| THD+N                              | Line output total harmonic distortion + noise   | $V_O = 2\text{ V}_{RMS}$ , channel set to LINE MODE  |      | 0.01% |     |               |
| <b>DIGITAL INPUT PINS</b>          |   |  |      |       |     |               |
| $V_{IH}$                           | Input logic level high                          |  | 70   |       |     | %VDD          |
| $V_{IL}$                           | Input logic level low                           |  |      | 30    |     | %VDD          |
| $I_{IH}$                           | Input logic current, high                       | $V_I = VDD$  |      | 15    |     | $\mu\text{A}$ |
| $I_{IL}$                           | Input logic current, low                        | $V_I = 0$  |      | -15   |     | $\mu\text{A}$ |
| <b>PWM OUTPUT STAGE</b>            |   |  |      |       |     |               |
| $R_{DS(on)}$                       | FET drain-to-source resistance                  | Not including bond wire and package resistance   |      | 90    |     | m $\Omega$    |
| <b>OVERVOLTAGE (OV) PROTECTION</b> |   |  |      |       |     |               |
| $V_{PVDD\_OV}$                     | PVDD overvoltage shutdown                       |  | 19.3 | 20    | 22  | V             |
| $V_{PVDD\_OV\_HYS}$                | PVDD overvoltage shutdown hysteresis            |  |      | 0.8   |     | V             |
| $V_{VBAT\_OV}$                     | VBAT overvoltage shutdown                       |  | 20   | 21.5  | 23  | V             |



## Electrical Characteristics (continued)

Test conditions (unless otherwise noted):  $T_C = 25^\circ\text{C}$ ,  $PVDD = VBAT = 14.4\text{ V}$ ,  $VDD = 3.3\text{ V}$ ,  $R_L = 4\ \Omega$ ,  $P_{out} = 1\text{ W/ch}$ ,  $f = 1\text{ kHz}$ ,  $f_{SW} = 2.11\text{ MHz}$ , AES17 Filter, default I<sup>2</sup>C settings, see [Figure 79](#)

| PARAMETER                              |  | TEST CONDITIONS   | MIN | TYP | MAX  | UNIT |
|--|--|---|-----|-----|------|------|
| $V_{VBAT\_OV\_HYS}$                    | VBAT overvoltage shutdown hysteresis                         |   |     | 0.6 |      | V    |
| <b>UNDERVOLTAGE (UV) PROTECTION</b>    |  |   |     |     |      |      |
| $VBAT_{UV}$                            | VBAT undervoltage shutdown                                   |   |     | 4   | 4.5  | V    |
| $VBAT_{UV\_HYS}$                       | VBAT undervoltage shutdown hysteresis                        |   |     | 0.2 |      | V    |
| $PVDD_{UV}$                            | PVDD undervoltage shutdown                                   |   |     | 4   | 4.5  | V    |
| $PVDD_{UV\_HYS}$                       | PVDD undervoltage shutdown hysteresis                        |   |     | 0.2 |      | V    |
| <b>BYPASS VOLTAGES</b>                 |  |   |     |     |      |      |
| $V_{GVDD}$                             | Gate drive bypass pin voltage                                |   |     | 7   |      | V    |
| $V_{AVDD}$                             | Analog bypass pin voltage                                    |   |     | 6   |      | V    |
| $V_{VCOM}$                             | Common bypass pin voltage                                    |   |     | 2.5 |      | V    |
| $V_{VREG}$                             | Regulator bypass pin voltage                                 |   |     | 5.5 |      | V    |
| <b>POWER-ON RESET (POR)</b>            |  |   |     |     |      |      |
| $V_{POR}$                              | VDD voltage for POR  |   |     | 2.1 | 2.7  | V    |
| $V_{POR\_HY}$                          | VDD POR recovery hysteresis voltage                          |   |     | 0.5 |      | V    |
| <b>OVERTEMPERATURE (OT) PROTECTION</b> |  |   |     |     |      |      |
| OTW(i)                                 | Channel overtemperature warning                              |   |     | 150 |      | °C   |
| OTSD(i)                                | Channel overtemperature shutdown                             |   |     | 175 |      | °C   |
| OTW                                    | Global junction overtemperature warning                      | Set by register 0x01 bit 5-6, default value                               |     | 130 |      | °C   |
| OTSD                                   | Global junction overtemperature shutdown                     |   |     | 160 |      | °C   |
| OT <sub>HYS</sub>                      | Overtemperature hysteresis                                   |   |     | 15  |      | °C   |
| <b>LOAD OVER CURRENT PROTECTION</b>    |  |   |     |     |      |      |
| $I_{LIM}$                              | Overcurrent cycle-by-cycle limit                             | OC Level 1  | 4   | 4.8 |      | A    |
|  |  | OC Level 2  | 6   | 6.5 |      |      |
| $I_{SD}$                               | Overcurrent shutdown   | OC Level 1, Any short to supply, ground, or other channels                |     | 7   |      | A    |
|  |  | OC Level 2, Any short to supply, ground, or other channels                |     | 9   |      |      |
| <b>MUTE MODE</b>                       |  |   |     |     |      |      |
| $G_{MUTE}$                             | Output attenuation   |   |     | 100 |      | dB   |
| <b>CLICK AND POP</b>                   |  |   |     |     |      |      |
| $V_{CP}$                               | Output click and pop voltage                                 | ITU-R 2k filter, High-Z/MUTE to Play, Play to Mute/High-Z                 |     | 7   |      | mV   |
| <b>DC OFFSET</b>                       |  |   |     |     |      |      |
| $V_{OFFSET}$                           | Output offset voltage  |   |     | 2   | 5    | mV   |
| <b>DC DETECT</b>                       |  |   |     |     |      |      |
| $DC_{FAULT}$                           | Output DC fault protection                                   |   |     | 2   | 2.5  | V    |
| <b>DIGITAL OUTPUT PINS</b>             |  |   |     |     |      |      |
| $V_{OH}$                               | Output voltage for logic level high                          | $I = \pm 2\text{ mA}$   |     | 90  |      | %VDD |
| $V_{OL}$                               | Output voltage for logic level low                           | $I = \pm 2\text{ mA}$   |     |     | 10   | %VDD |
| $t_{DELAY\_CLIPDET}$                   | Signal delay when output clipping detected                   |   |     |     | 20   | μs   |
| <b>LOAD DIAGNOSTICS</b>                |  |   |     |     |      |      |
| S2P                                    | Maximum resistance to detect a short from OUT pins to PVDD   |   |     |     | 500  | Ω    |
| S2G                                    | Maximum resistance to detect a short from OUT pins to ground |   |     |     | 200  | Ω    |
| SL                                     | Shorted load detection tolerance                             | Other channels in Hi-Z  |     |     | ±0.5 | Ω    |
| OL                                     | Open load  | Other channels in Hi-Z  | 40  | 70  |      | Ω    |
| $T_{DC\_DIAG}$                         | DC diagnostic time   | All 4 Channels  |     | 230 |      | ms   |
| LO                                     | Line output  |   |     |     | 6    | kΩ   |
| $T_{LINE\_DIAG}$                       | Line output diagnostic time                                  |   |     | 40  |      | ms   |
| $AC_{IMP}$                             | AC impedance accuracy  | Gain linearity, $f = 19\text{ kHz}$ , $R_L = 2\ \Omega$ to $16\ \Omega$ , |     |     | 25%  |      |
|  |  | Offset  |     |     | ±0.5 | Ω    |
| $T_{AC\_DIAG}$                         | AC diagnostic time   | All 4 Channels  |     | 520 |      | ms   |

## Electrical Characteristics (continued)

Test conditions (unless otherwise noted):  $T_C = 25^\circ\text{C}$ ,  $PVDD = VBAT = 14.4\text{ V}$ ,  $VDD = 3.3\text{ V}$ ,  $R_L = 4\ \Omega$ ,  $P_{out} = 1\text{ W/ch}$ ,  $f = 1\text{ kHz}$ ,  $f_{SW} = 2.11\text{ MHz}$ , AES17 Filter, default I<sup>2</sup>C settings, see [Figure 79](#)

| PARAMETER                       | TEST CONDITIONS                                       | MIN | TYP | MAX | UNIT          |
|---------------------------------|---|-----|-----|-----|---------------|
| <b>I<sup>2</sup>C_ADDR PINS</b> |   |     |     |     |               |
| $t_{I2C\_ADDR}$                 | Time delay needed for I <sup>2</sup> C address set-up |     | 300 |     | $\mu\text{s}$ |

(1) Tested with Output Inductor DFEG7030D-3R3M.

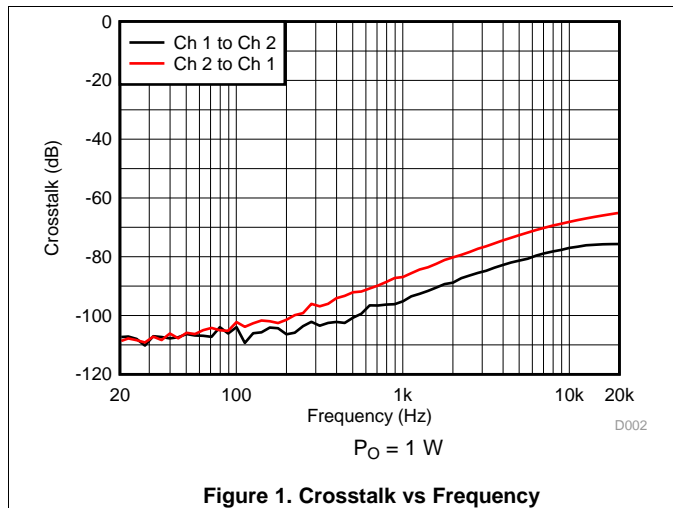
## 7.6 Timing Requirements

Test conditions (unless otherwise noted):  $T_C = 25^\circ\text{C}$ ,  $PVDD = VBAT = 14.4\text{ V}$ ,  $VDD = 3.3\text{ V}$ ,  $R_L = 4\ \Omega$ ,  $P_O = 1\text{ W/ch}$ ,  $f = 1\text{ kHz}$ ,  $f_{SW} = 2.11\text{ MHz}$ , AES17 Filter, default I<sup>2</sup>C settings, see [Figure 79](#)

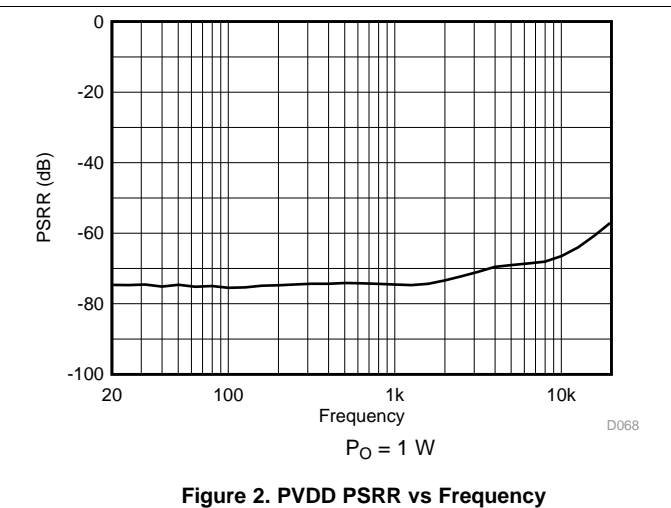
|  |   | MIN                        | TYP | MAX | UNIT          |
|--|---|----------------------------|-----|-----|---------------|
| <b>I<sup>2</sup>C CONTROL PORT (See <a href="#">Figure 42</a>)</b> |   |                            |     |     |               |
| $t_{BUS}$  | Bus free time between a STOP and START condition            | 1.3                        |     |     | $\mu\text{s}$ |
| $t_{HOLD1}$  | Hold time, SCL to SDA                                       | 0                          |     |     | ns            |
| $t_{HOLD2}$  | Hold time, start condition to SCL                           | 0.6                        |     |     | $\mu\text{s}$ |
| $t_{START}$  | I <sup>2</sup> C startup time after VDD power on reset      |                            |     | 12  | ms            |
| $t_{RISE}$   | Rise time, SCL and SDA                                      |                            |     | 300 | ns            |
| $t_{FALL}$   | Fall time, SCL and SDA                                      |                            |     | 300 | ns            |
| $t_{SU1}$  | Setup, SDA to SCL   | 100                        |     |     | ns            |
| $t_{SU2}$  | Setup, SCL to start condition                               | 0.6                        |     |     | $\mu\text{s}$ |
| $t_{SU3}$  | Setup, SCL to stop condition                                | 0.6                        |     |     | $\mu\text{s}$ |
| $t_{W(H)}$   | Required pulse duration SCL <i>High</i>                     | 0.6                        |     |     | $\mu\text{s}$ |
| $t_{W(L)}$   | Required pulse duration SCL <i>Low</i>                      | 1.3                        |     |     | $\mu\text{s}$ |
| <b>SERIAL AUDIO PORT (See <a href="#">Figure 32</a>)</b>           |   |                            |     |     |               |
| $D_{MCLK}$ ,<br>$D_{SCLK}$   | Allowable input clock duty cycle                            | 45%                        | 50% | 55% |               |
| $f_{MCLK}$   | Supported MCLK frequencies: 128, 256, or 512                | 128                        |     | 512 | xFS           |
| $f_{MCLK\_Max}$  | Maximum frequency   |                            |     | 25  | MHz           |
| $t_{SCY}$  | SCLK pulse cycle time                                       | 40                         |     |     | ns            |
| $t_{SCL}$  | SCLK pulse-with LOW   | 16                         |     |     | ns            |
| $t_{SCH}$  | SCLK pulse-with HIGH  | 16                         |     |     | ns            |
| $t_{rise/fall}$  | Rise and fall time  |                            | <5  |     | ns            |
| $t_{SF}$   | SCLK rising edge to FSYNC edge                              | 8                          |     |     | ns            |
| $t_{FS}$   | FSYNC rising edge to SCLK edge                              | 8                          |     |     | ns            |
| $t_{DS}$   | DATA set-up time  | 8                          |     |     | ns            |
| $t_{DH}$   | DATA hold time  | 8                          |     |     | ns            |
| $C_i$  | Input capacitance, pins MCLK, SCLK, FSYNC, SDIN1, SDIN2     |                            |     | 10  | pF            |
| $T_{LA}$   | Latency from input to output measured in FSYNC sample count | FSYNC = 44.1 kHz or 48 kHz |     | 30  |               |
|  |   | FSYNC = 96 kHz             |     | 12  |               |

### 7.7 Typical Characteristics

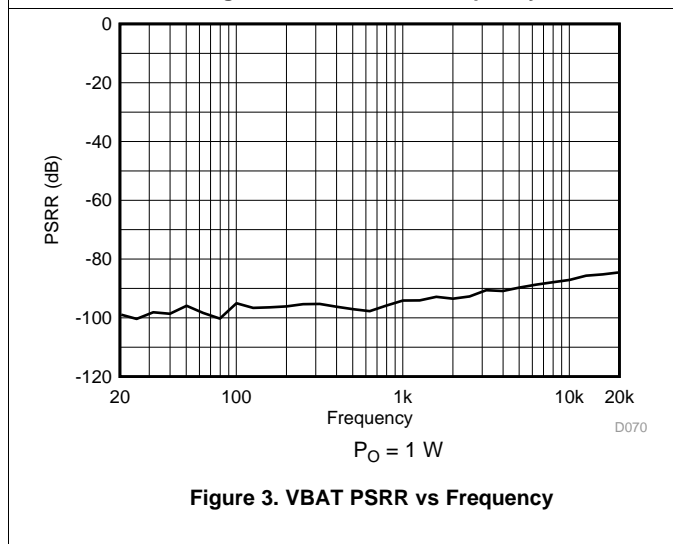
$T_A = 25\text{ }^\circ\text{C}$ ,  $V_{VDD} = 3.3\text{ V}$ ,  $V_{BAT} = PVDD = 14.4\text{ V}$ ,  $R_L = 4\text{ }\Omega$ ,  $f_{IN} = 1\text{ kHz}$ ,  $f_s = 48\text{ kHz}$ ,  $f_{SW} = 2.1\text{ MHz}$ , AES17 filter, default I<sup>2</sup>C settings, see Figure 79 and Figure 82 (unless otherwise noted)



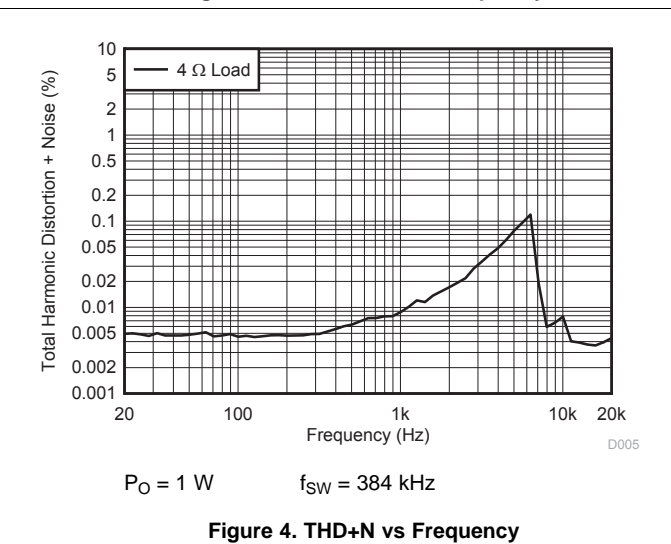
**Figure 1. Crosstalk vs Frequency**



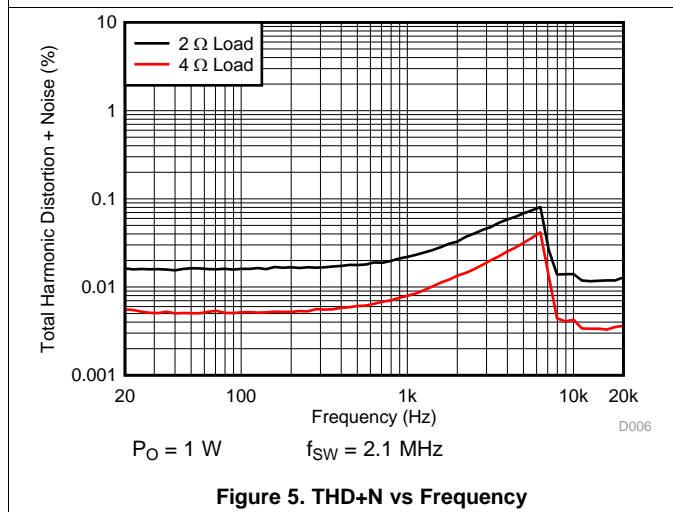
**Figure 2. PVDD PSRR vs Frequency**



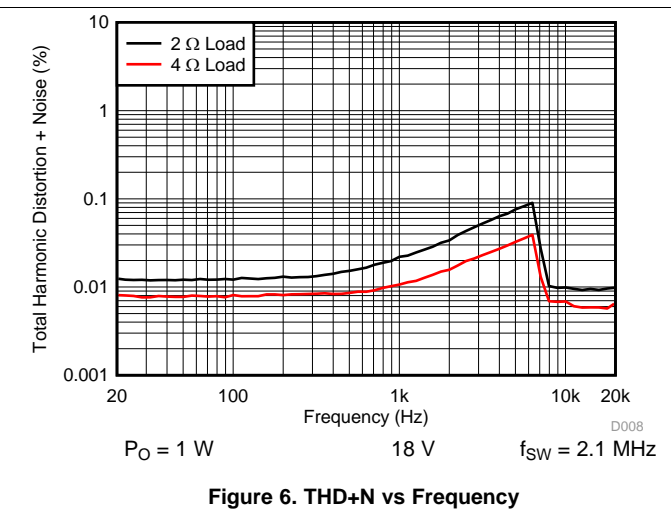
**Figure 3. VBAT PSRR vs Frequency**



**Figure 4. THD+N vs Frequency**



**Figure 5. THD+N vs Frequency**



**Figure 6. THD+N vs Frequency**

Typical Characteristics (continued)

$T_A = 25\text{ }^\circ\text{C}$ ,  $V_{DD} = 3.3\text{ V}$ ,  $V_{BAT} = PV_{DD} = 14.4\text{ V}$ ,  $R_L = 4\ \Omega$ ,  $f_{IN} = 1\text{ kHz}$ ,  $f_s = 48\text{ kHz}$ ,  $f_{SW} = 2.1\text{ MHz}$ , AES17 filter, default I<sup>2</sup>C settings, see Figure 79 and Figure 82 (unless otherwise noted)

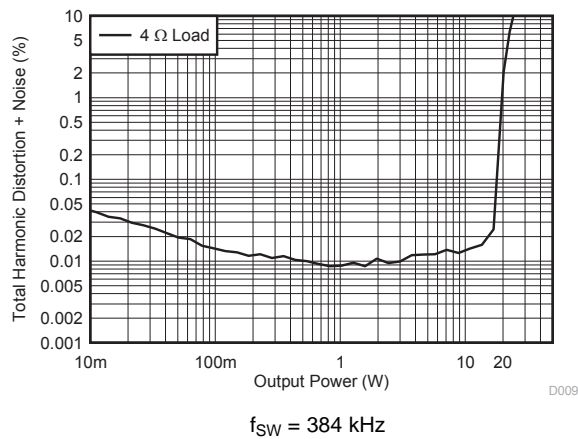


Figure 7. THD+N vs Power

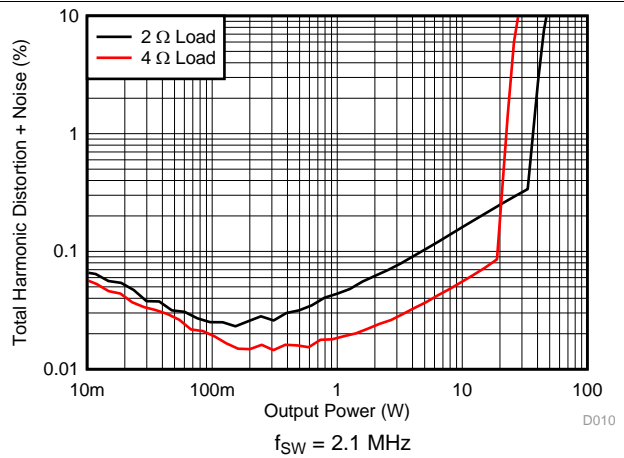


Figure 8. THD+N vs Power

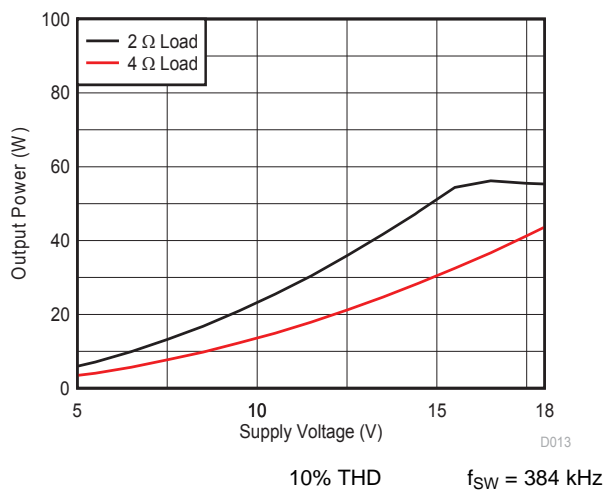


Figure 9. Output Power vs Supply Voltage

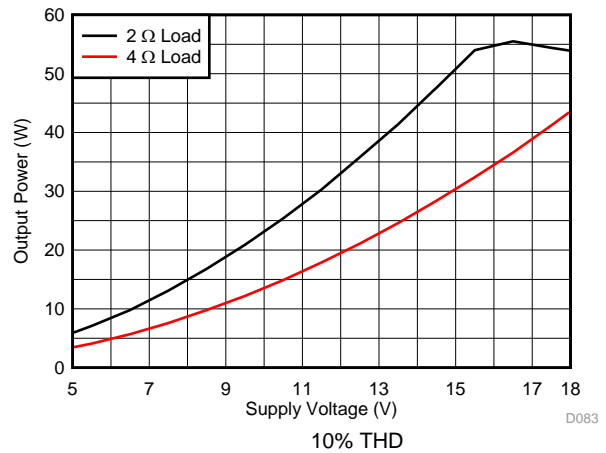


Figure 10. Output Power vs Supply Voltage

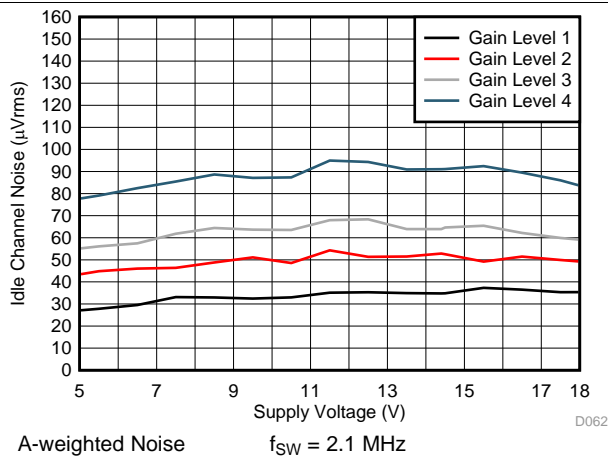


Figure 11. Noise vs Supply voltage

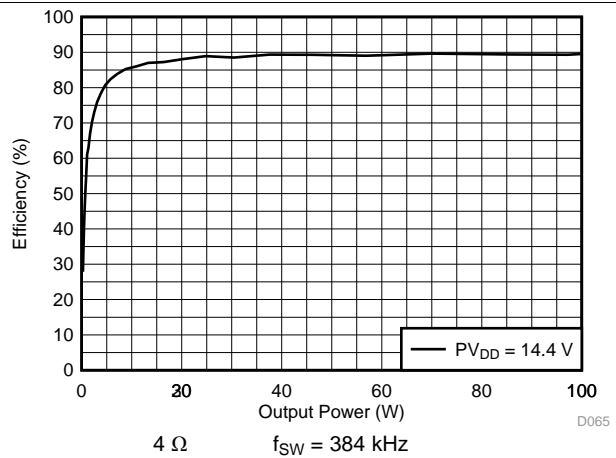


Figure 12. PVDD Power Efficiency vs Total Output Power

Typical Characteristics (continued)

$T_A = 25\text{ }^\circ\text{C}$ ,  $V_{VDD} = 3.3\text{ V}$ ,  $V_{BAT} = PVDD = 14.4\text{ V}$ ,  $R_L = 4\ \Omega$ ,  $f_{IN} = 1\text{ kHz}$ ,  $f_s = 48\text{ kHz}$ ,  $f_{SW} = 2.1\text{ MHz}$ , AES17 filter, default I<sup>2</sup>C settings, see Figure 79 and Figure 82 (unless otherwise noted)

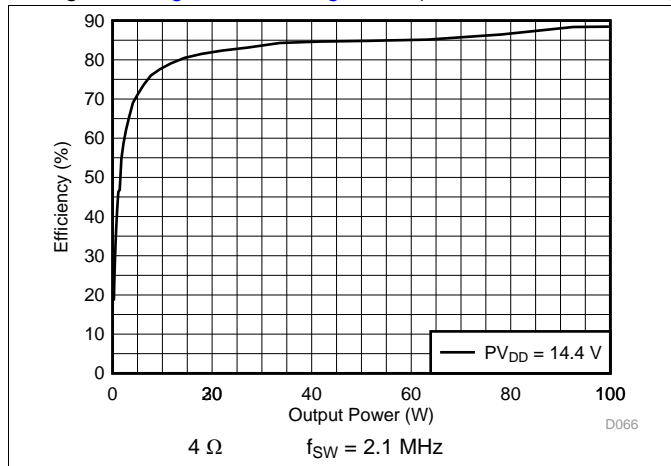


Figure 13. PVDD Power Efficiency vs Total Output Power

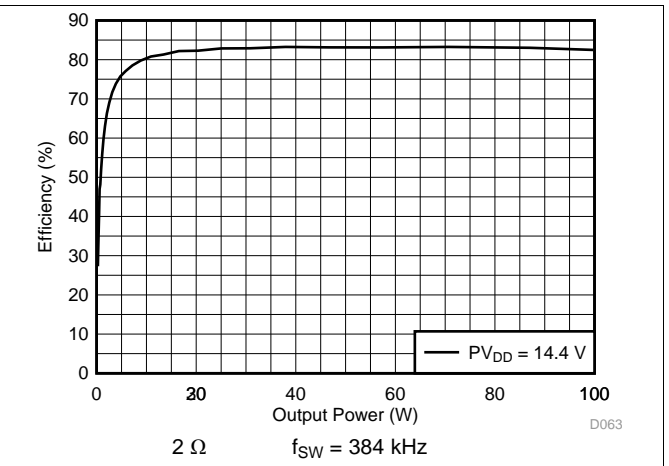


Figure 14. PVDD Power Efficiency vs Total Output Power

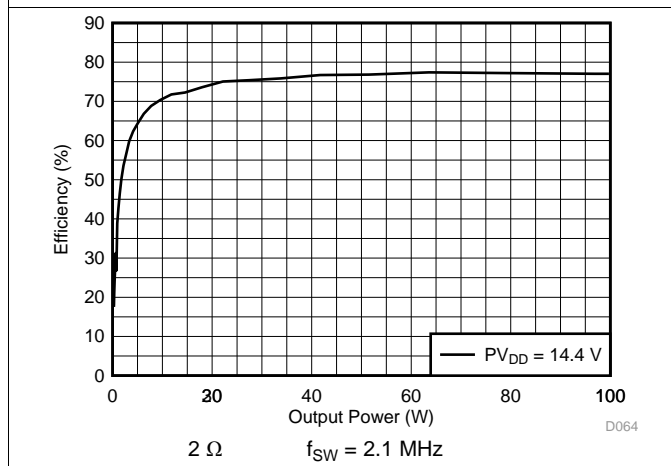


Figure 15. PVDD Power Efficiency vs Total Output Power

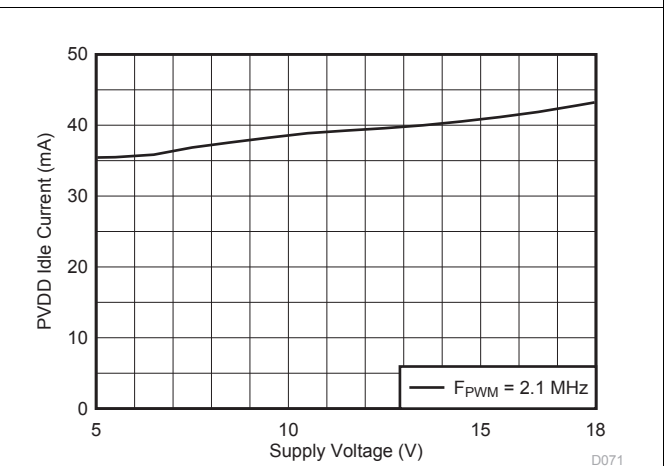


Figure 16. PVDD Idle Current vs Voltage

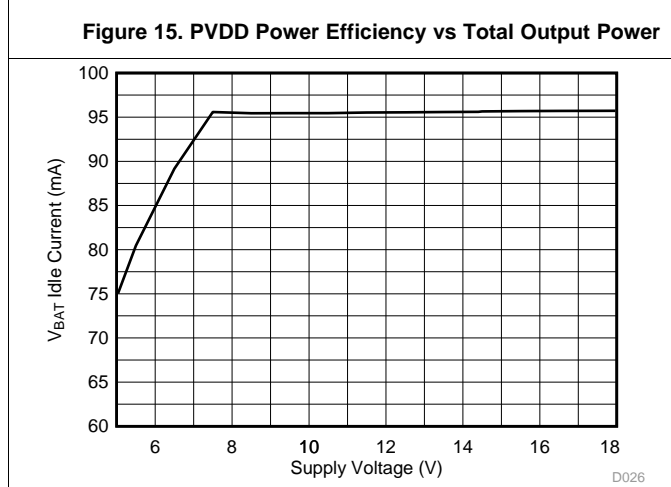


Figure 17. VBAT Idle Current vs Voltage

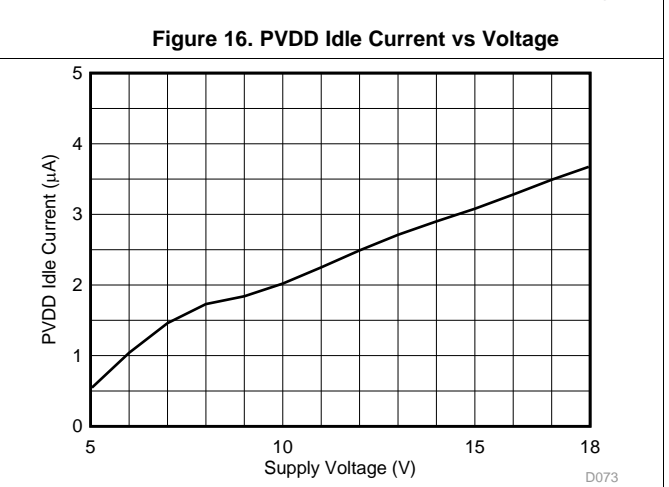


Figure 18. PVDD Standby Current vs Voltage

Typical Characteristics (continued)

$T_A = 25\text{ }^\circ\text{C}$ ,  $V_{DD} = 3.3\text{ V}$ ,  $V_{BAT} = PV_{DD} = 14.4\text{ V}$ ,  $R_L = 4\ \Omega$ ,  $f_{IN} = 1\text{ kHz}$ ,  $f_s = 48\text{ kHz}$ ,  $f_{SW} = 2.1\text{ MHz}$ , AES17 filter, default I<sup>2</sup>C settings, see Figure 79 and Figure 82 (unless otherwise noted)

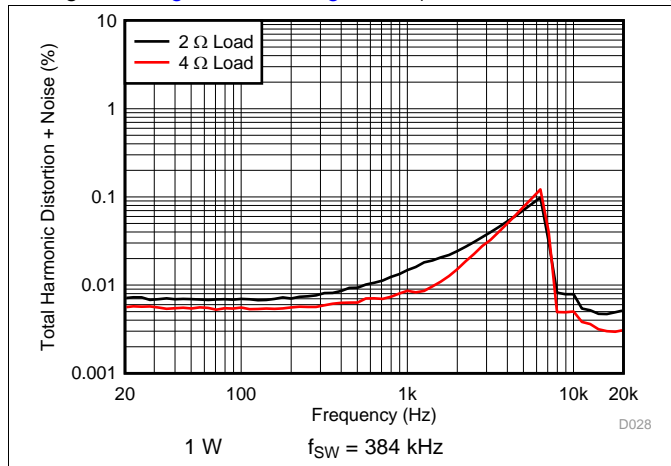


Figure 19. PBTL THD+N vs Frequency

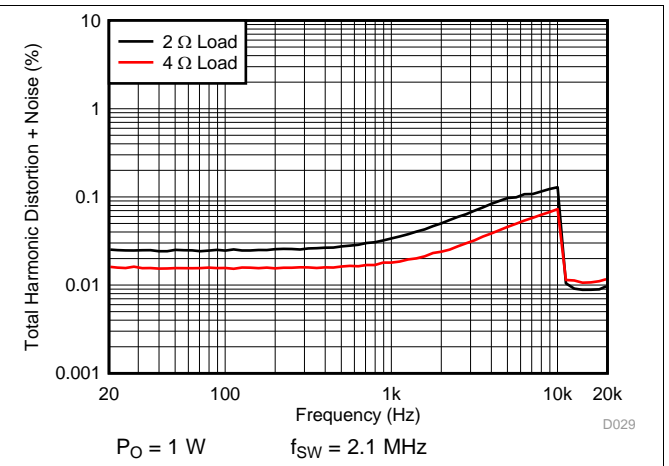


Figure 20. PBTL THD+N vs Frequency

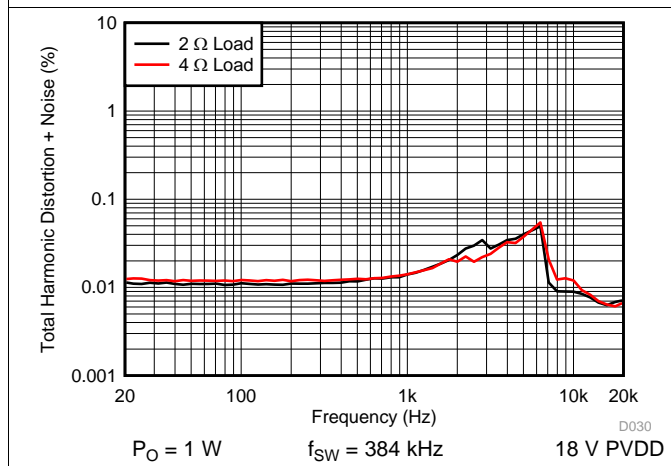


Figure 21. PBTL THD+N vs Frequency

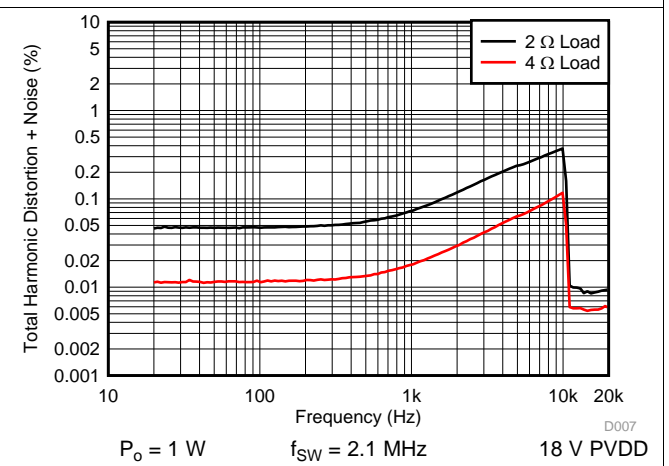


Figure 22. PBTL THD+N vs Frequency

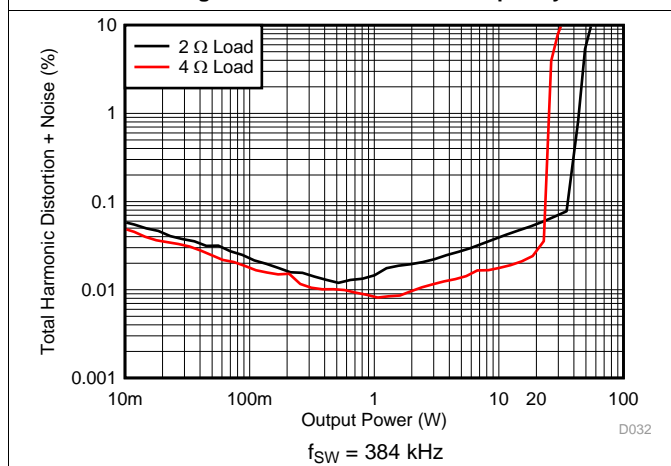


Figure 23. PBTL THD+N vs Power

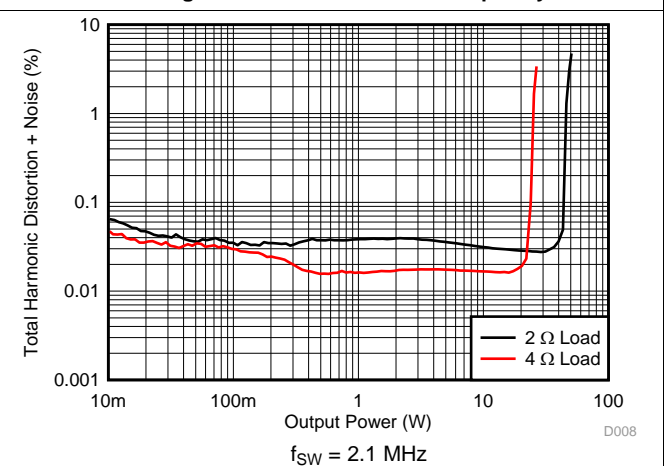


Figure 24. PBTL THD+N vs Power

Typical Characteristics (continued)

$T_A = 25\text{ }^\circ\text{C}$ ,  $V_{DD} = 3.3\text{ V}$ ,  $V_{BAT} = PVDD = 14.4\text{ V}$ ,  $R_L = 4\ \Omega$ ,  $f_{IN} = 1\text{ kHz}$ ,  $f_s = 48\text{ kHz}$ ,  $f_{SW} = 2.1\text{ MHz}$ , AES17 filter, default I<sup>2</sup>C settings, see Figure 79 and Figure 82 (unless otherwise noted)

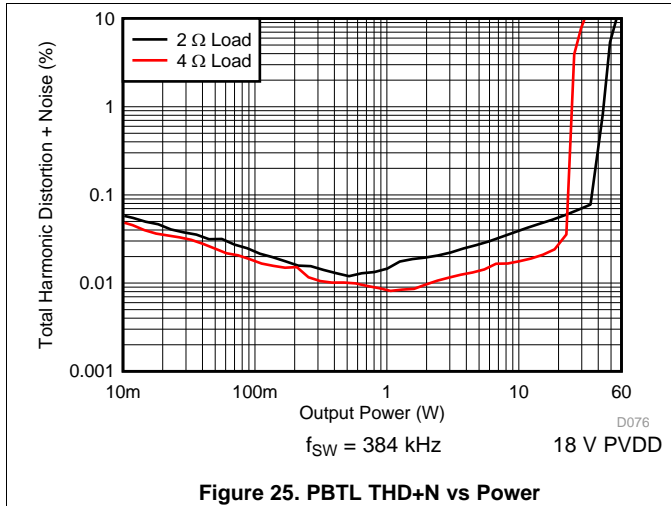


Figure 25. PBTL THD+N vs Power

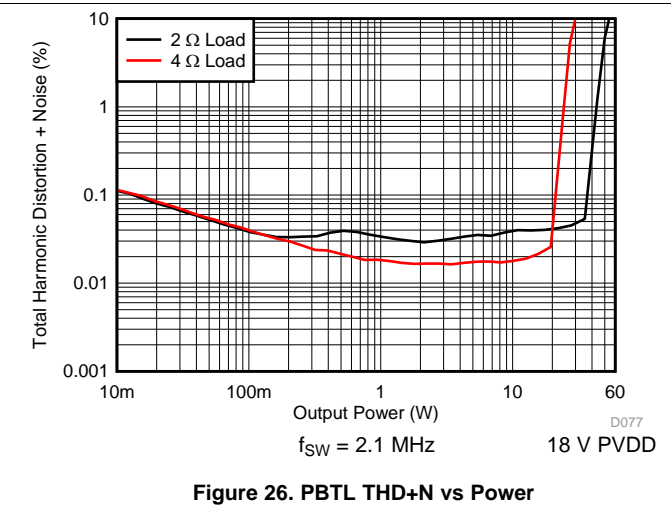


Figure 26. PBTL THD+N vs Power

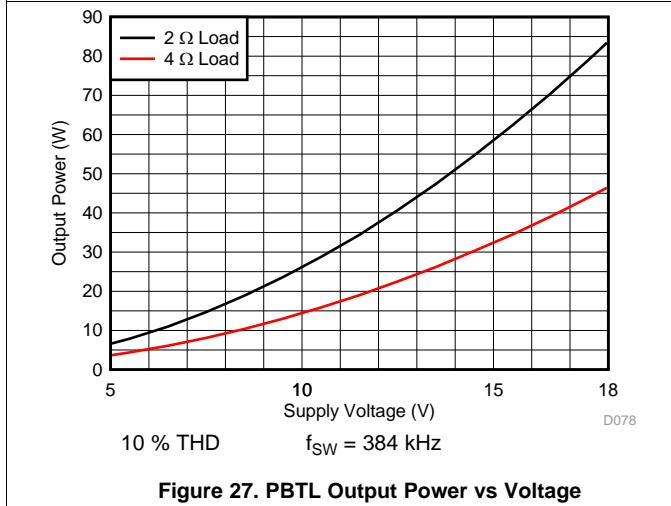


Figure 27. PBTL Output Power vs Voltage

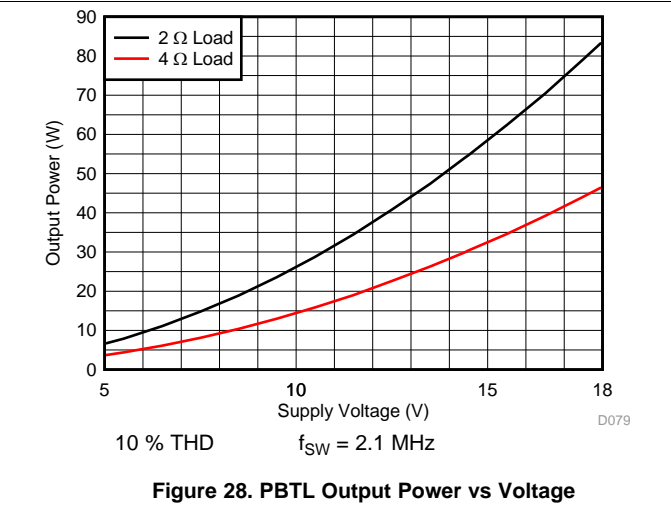


Figure 28. PBTL Output Power vs Voltage

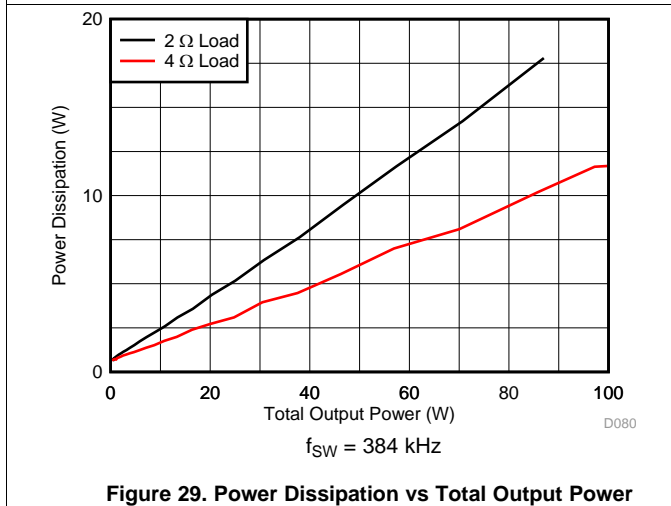


Figure 29. Power Dissipation vs Total Output Power

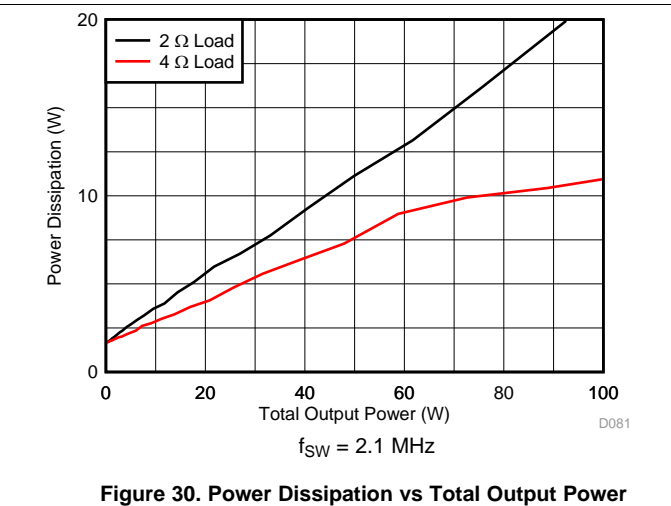


Figure 30. Power Dissipation vs Total Output Power

## 8 Parameter Measurement Information

The parameters for the TAS6424M-Q1 device were measured using the circuit in [Figure 79](#).

For measurements with 2.1 MHz switching frequency the 3.3  $\mu\text{H}$  inductor from the TAS6424M-Q1 EVM is used.

For measurements with 384 kHz switching frequency a 10  $\mu\text{H}$  inductor was used.



## 9 Detailed Description

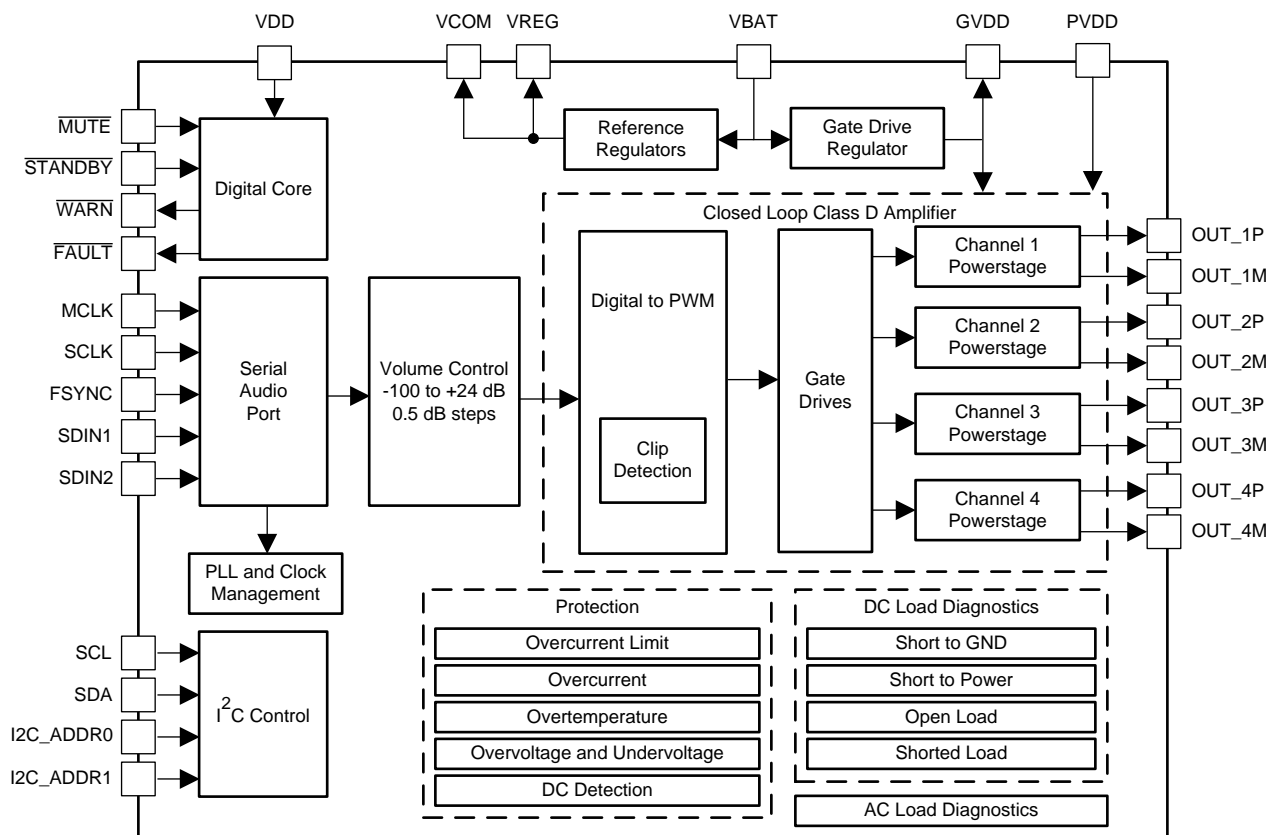
### 9.1 Overview

The TAS6424M-Q1 device is a four-channel digital-input Class-D audio amplifier specifically tailored for use in the automotive industry. The device is designed for vehicle battery operation. This ultra-efficient Class-D technology allows for reduced power consumption, reduced PCB area and reduced heat. The device realizes an audio sound-system design with smaller size and lower weight than traditional Class-AB solutions.

The core design blocks are as follows:

- Serial audio port
- Clock management
- High-pass filter and volume control
- Pulse width modulator (PWM) with output stage feedback
- Gate drive
- Power FETs
- Diagnostics
- Protection
- Power supply
- I<sup>2</sup>C serial communication bus

### 9.2 Functional Block Diagram



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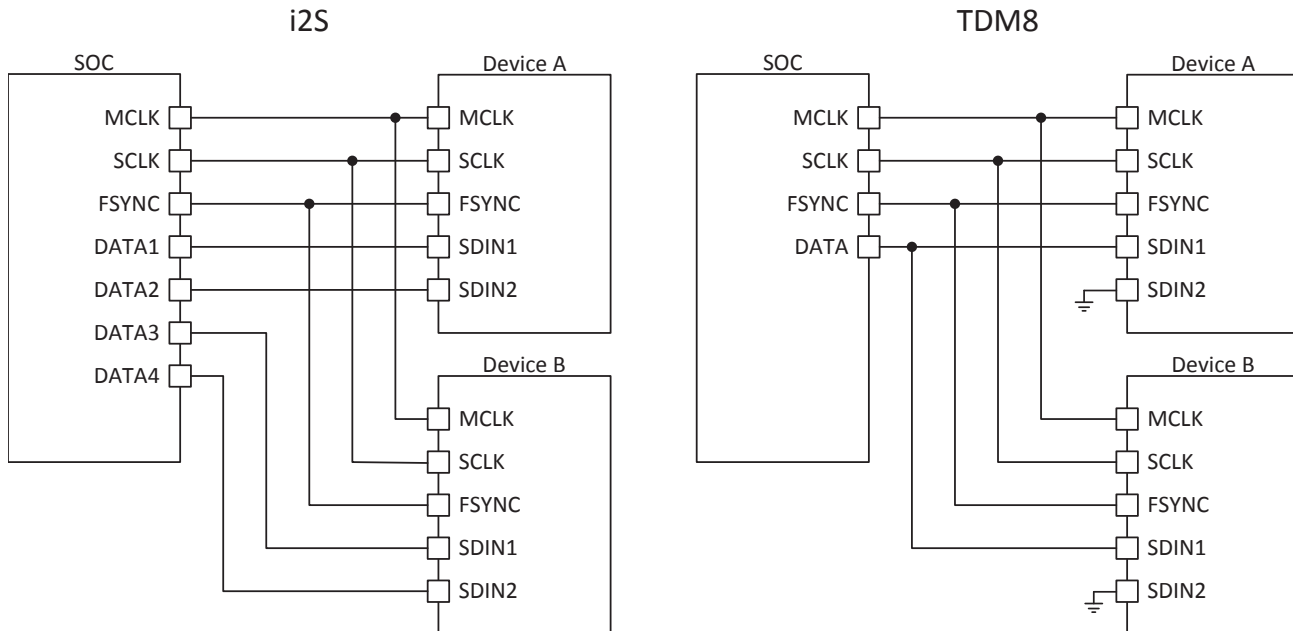
## 9.3 Feature Description

### 9.3.1 Serial Audio Port

The serial audio port (SAP) receives audio in either I<sup>2</sup>S, left justified, right justified, or TDM formats.

Settings for the serial audio port are programmed in the SAP control register (address 0x03), see the [SAP Control \(Serial Audio-Port Control\) Register \(address = 0x03\) \[default = 0x04\]](#) section.

Figure 31 shows the digital audio data connections for I<sup>2</sup>S and TDM8 mode for an eight channel system.



**Figure 31. Digital-Audio Data Connection**

#### 9.3.1.1 I<sup>2</sup>S Mode

I<sup>2</sup>S timing uses the FSYNC pin to define when the data being transmitted is for the left channel and when the data is for the right channel. The FSYNC pin is low for the left channel and high for the right channel. The bit clock, SCLK, runs at  $32 \times f_s$  or  $64 \times f_s$  and is used to clock in the data. A delay of one bit clock occurs from the time the FSYNC signal changes state to the first bit of data on the data lines. The data is presented in 2s-complement form (MSB-first). The data is valid on the rising edge of the bit clock and is used to clock in the data.

#### 9.3.1.2 Left-Justified Timing

Left-justified (LJ) timing also uses the FSYNC pin to define when the data being transmitted is for the left channel and when the data is for the right channel. The FSYNC pin is high for the left channel and low for the right channel. A bit clock running at  $32 \times f_s$  or  $64 \times f_s$  is used to clock in the data. The first bit of data appears on the data lines at the same time FSYNC toggles. The data is written MSB-first and is valid on the rising edge of the bit clock. Digital words can be 16-bits or 24-bits wide and pad any unused trailing data-bit positions in the left-right (L/R) frame with zeros.

#### 9.3.1.3 Right-Justified Timing

Right-justified (RJ) timing also uses the FSYNC pin to define when the data being transmitted is for the left channel and when the data is for the right channel. The FSYNC pin is high for the left channel and low for the right channel. A bit clock running at  $32 \times f_s$  or  $64 \times f_s$  is used to clock in the data. The first bit of data appears on the data 8-bit clock periods (for 24-bit data) after the FSYNC pin toggles. In RJ mode the LSB of data is always clocked by the last bit clock before the FSYNC pin transitions. The data is written MSB-first and is valid on the rising edge of bit clock. The device pads the unused leading data-bit positions in the L/R frame with zeros.

## Feature Description (continued)

### 9.3.1.4 TDM Mode

TDM mode supports 4 or 8 channels of audio data. The TDM mode is automatically selected when the TDM clocks are present. The device can be configured through I<sup>2</sup>C to use different stereo pairs in the TDM data stream. The TDM mode supports 16-bit, 24-bit, and 32-bit input data lengths.

In TDM mode, SCLK must be  $128 \times f_s$  or  $256 \times f_s$ , depending on the TDM slot size. In TDM mode SCLK and MCLK can be connected together. If SCLK and MCLK are connected together then FSYNC should be minimum 2 MCLK pulses long.

In TDM mode, the SDIN1 pin (pin 15) is used for digital audio data. TI recommends to connect the unused SDIN2 pin (pin 16) to ground. [Table 1](#) lists register settings for the TDM channel selection.

**Table 1. TDM Channel Selection**

| REGISTER SETTING |               | TDM8 CHANNEL SLOT |     |     |     |     |     |     |     |
|------------------|---------------|-------------------|-----|-----|-----|-----|-----|-----|-----|
| 0x03<br>BIT 5    | 0x03<br>BIT 3 | 1                 | 2   | 3   | 4   | 5   | 6   | 7   | 8   |
| 0                | 0             | CH1               | CH2 | CH3 | CH4 | —   | —   | —   | —   |
| 1                | 0             | —                 | —   | —   | —   | CH1 | CH2 | CH3 | CH4 |
| 0                | 1             | CH3               | CH4 | CH1 | CH2 | —   | —   | —   | —   |
| 1                | 1             | —                 | —   | —   | —   | CH3 | CH4 | CH1 | CH2 |

If PBTL mode is programmed for channel 1/2 or channel 3/4 the datasource can be set according to [Table 2](#).

**Table 2. TDM Channel Selection in PBTL Mode**

| REGISTER SETTING |               |               | TDM8 CHANNEL SLOT |               |               |               |               |               |               |               |
|------------------|---------------|---------------|-------------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| 0x03<br>BIT 5    | 0x03<br>BIT 3 | 0x21<br>BIT 6 | 1                 | 2             | 3             | 4             | 5             | 6             | 7             | 8             |
| 0                | 0             | 0             | PBTL<br>CH1/2     | —             | PBTL<br>CH3/4 | —             | —             | —             | —             | —             |
| 1                | 0             | 0             | —                 | —             | —             | —             | PBTL<br>CH1/2 | —             | PBTL<br>CH3/4 | —             |
| 0                | 0             | 1             | —                 | PBTL<br>CH1/2 | —             | PBTL<br>CH3/4 | —             | —             | —             | —             |
| 1                | 0             | 1             | —                 | —             | —             | —             | —             | PBTL<br>CH1/2 | —             | PBTL<br>CH3/4 |
| 0                | 1             | 0             | PBTL<br>CH3/4     | —             | PBTL<br>CH1/2 | —             | —             | —             | —             | —             |
| 1                | 1             | 0             | —                 | —             | —             | —             | PBTL<br>CH3/4 | —             | PBTL<br>CH1/2 | —             |
| 0                | 1             | 1             | —                 | PBTL<br>CH3/4 | —             | PBTL<br>CH1/2 | —             | —             | —             | —             |
| 1                | 1             | 1             | —                 | —             | —             | —             | —             | PBTL<br>CH3/4 | —             | PBTL<br>CH1/2 |

### 9.3.1.5 Supported Clock Rates

The device supports MCLK rates of  $128 \times f_s$ ,  $256 \times f_s$ , or  $512 \times f_s$ .

The device supports SCLK rates of  $32 \times f_s$  or  $64 \times f_s$  in I<sup>2</sup>S, LJ or RJ modes or  $128 \times f_s$ , or  $256 \times f_s$  in TDM mode.

The device supports FSYNC rates of 44.1 kHz, 48 kHz, or 96 kHz.

The maximum clock frequency is 25 MHz. Therefore, for a 96 kHz FSYNC rate, the maximum MCLK rate is  $256 \times f_s$ .

The MCLK clock must not be in phase to sync to SCLK. Duty cycle of 50% is required for 128x FSYNC, for 256x and 512x 50% duty is not required.

### 9.3.1.6 Audio-Clock Error Handling

When any kind of clock error, MCLK-FSYNC or SCLK-FSYNC ratio, or clock halt is detected, the device puts all channels into the Hi-Z state. When all audio clocks are within the expected range, the device automatically returns to the state it was in. See the [Timing Requirements](#) table for timing requirements.

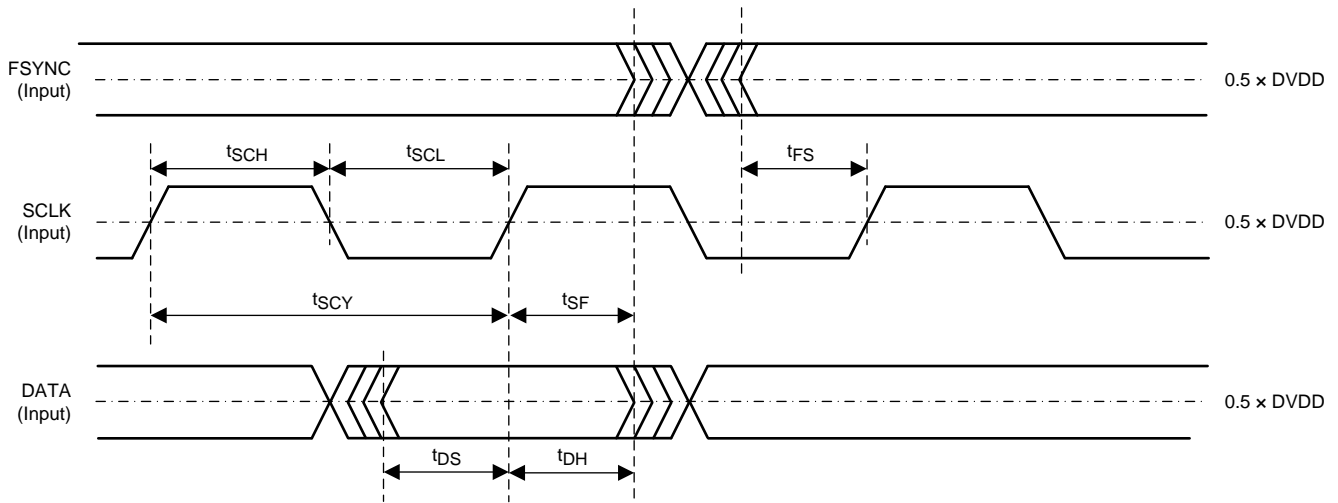


Figure 32. Serial Audio Timing

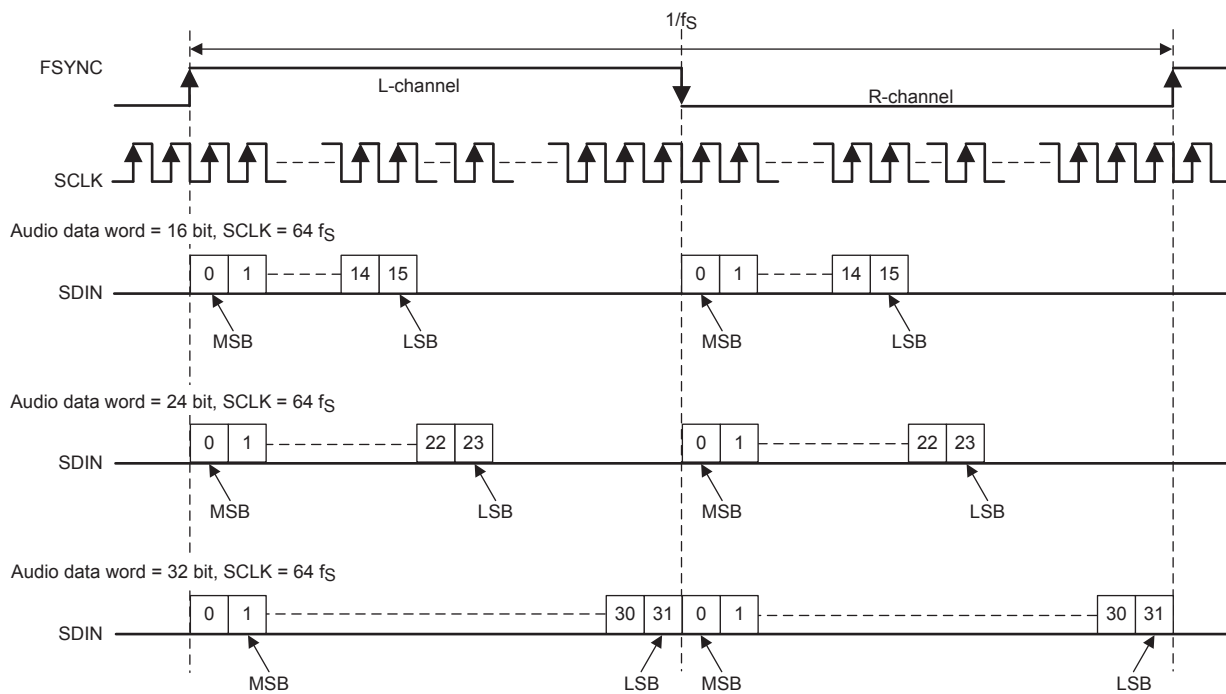


Figure 33. Left-Justified Audio Data Format

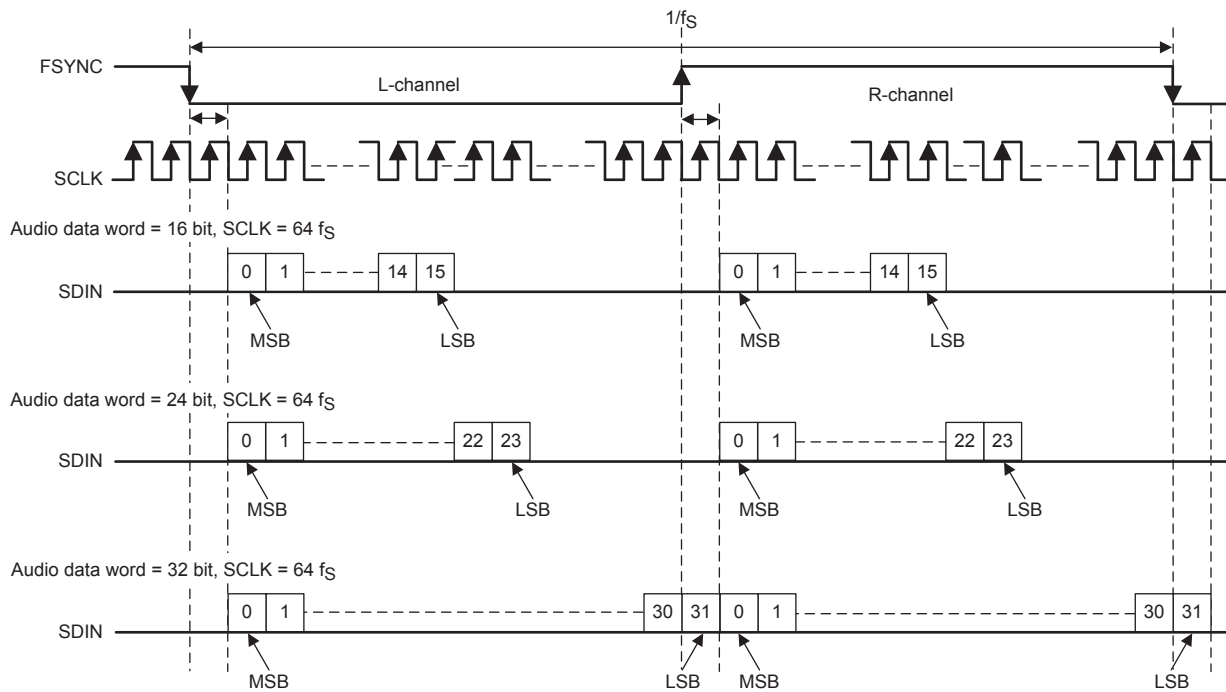
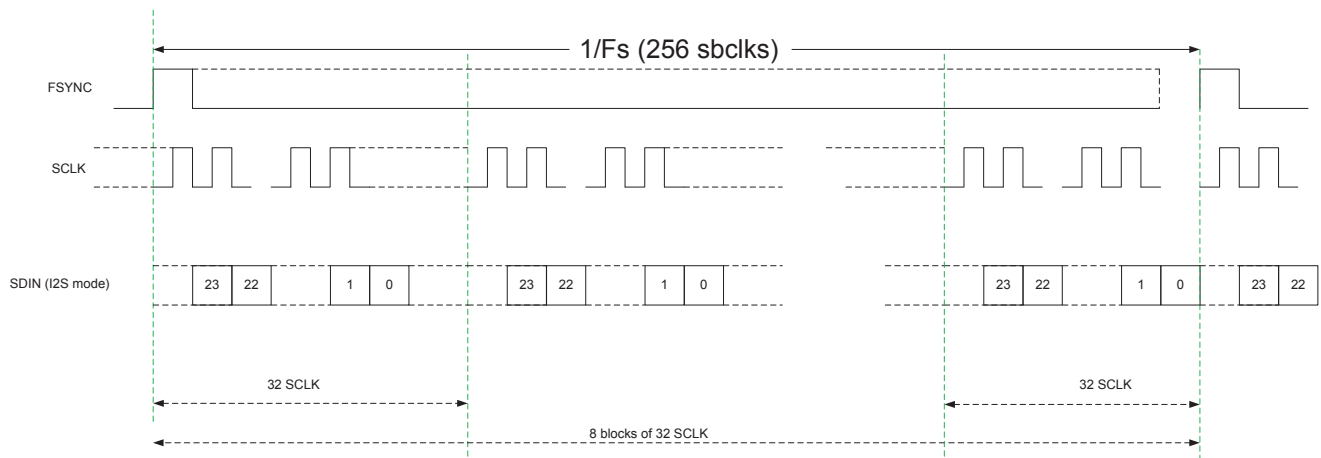


Figure 34. I²S Audio Data Format



Audio Data Format: TDM8 mode

Figure 35. TDM8 Audio Data Format

### 9.3.2 High-Pass Filter

Direct-current (DC) content in the audio signal can damage speakers. The data path has a high-pass filter to remove any DC from the input signal. The corner frequency is selectable from 4 Hz, 8 Hz, or 15 Hz to 30 Hz with bits 0 through 3 in register 0x26. The default value of -3 dB is approximately 4 Hz for 44.1 kHz or 48 kHz and approximately 8 Hz for 96 kHz sampling rates.

### 9.3.3 Volume Control and Gain

Each channel has an independent digital-volume control with a range from –100 dB to +24 dB with 0.5-dB steps. The volume control is set through I<sup>2</sup>C. The gain-ramp rate is programmable through I<sup>2</sup>C to take one step every 1, 2, 4, or 8 FSYNC cycles.

The peak output-voltage swing is also configurable in the gain control register through I<sup>2</sup>C. The four gain settings are 7.5 V, 15 V, 21 V, and 29 V. TI recommends selecting the lowest possible for the expected PVDD operation to optimize output noise and dynamic range performance.

### 9.3.4 High-Frequency Pulse-Width Modulator (PWM)

The PWM converts the PCM input data into a switched signal of varying duty cycle. The PWM modulator is an advanced design with high bandwidth, low noise, low distortion, and excellent stability. The output switching rate is synchronous to the serial audio-clock input and is programmed through I<sup>2</sup>C to be between 8× and 48× the input-sample rate. The option to switch at high frequency allows the use of smaller and lower cost external filtering components. [Table 3](#) lists the switch frequency options for bits 4 through 6 in the [Miscellaneous Control 2 Register \(address 0x02\)](#).

**Table 3. Output Switch Frequency Option**

| INPUT SAMPLE RATE | BIT 6:4 SETTINGS |         |            |          |          |               |
|-------------------|------------------|---------|------------|----------|----------|---------------|
|                   | 000              | 001     | 010 to 100 | 101      | 110      | 111           |
| 44.1 kHz          | 352.8 kHz        | 441 kHz | RESERVED   | 1.68 MHz | 1.94 MHz | 2.12 MHz      |
| 48 kHz            | 384 kHz          | 480 kHz | RESERVED   | 1.82 MHz | 2.11 MHz | Not supported |
| 96 kHz            | 384 kHz          | 480 kHz | RESERVED   | 1.82 MHz | 2.11 MHz | Not supported |

### 9.3.5 Gate Drive

The gate driver accepts the low-voltage PWM signal and level shifts it to drive a high-current, full-bridge, power-FET stage. The device uses proprietary techniques to optimize EMI and audio performance.

The gate-driver power-supply voltage, GVDD, is internally generated and a decoupling capacitor is connected at pin 9 and pin 10.

The full H-bridge output stages use only NMOS transistors. Therefore, bootstrap capacitors are required for the proper operation of the high side NMOS transistors. A 1-μF ceramic capacitor of quality X7R or better, rated for at least 16 V, must be connected from each output to the corresponding bootstrap input (see the application circuit diagram in [Figure 79](#)). The bootstrap capacitors connected between the BST pins and corresponding output function as a floating power supply for the high-side N-channel power MOSFET gate drive circuitry. During each high-side switching cycle, the bootstrap capacitors hold the gate-to-source voltage high keeping the high-side MOSFETs turned on.

### 9.3.6 Power FETs

The BTL output for each channel comprises four N-channel 90-mΩ FETs for high efficiency and maximum power transfer to the load. These FETs are designed to handle the fast switching frequency and large voltage transients during load dump.

### 9.3.7 Load Diagnostics

The device incorporates both DC-load and AC-load diagnostics, which are used to determine the status of the load. The DC diagnostics are turned on by default, but if a fast startup without diagnostics is required, the DC diagnostics can be bypassed through I<sup>2</sup>C. The DC diagnostics runs when any channel is directed to leave the Hi-Z state and enter the MUTE or PLAY state. The DC diagnostics can also be enabled manually to run on any or all channels. DC Diagnostics can be started from any operating condition, but if the channel is in PLAY state, then the time to complete the diagnostic is longer because the device must ramp down the audio signal of that channel before transitioning to the Hi-Z state. The DC diagnostics are available as soon as the device supplies are within the recommended operating range. The DC diagnostics do not rely on the audio input clocks to be available to function. DC Diagnostic results are reported for each channel separately through the I<sup>2</sup>C registers.

### 9.3.7.1 DC Load Diagnostics

The DC load diagnostics are used to verify the load connected. The DC diagnostics consists of four tests: short-to-power (S2P), short-to-ground (S2G), open-load (OL), and shorted-load (SL). The S2P and S2G tests trigger if the impedance to GND or a power rail is below that specified in the [Specifications](#) section. The diagnostic detects a short to vehicle battery, even when the supply is boosted. The SL test has an I<sup>2</sup>C-configurable threshold depending on the expected load to be connected. Because the speakers connected to each channel might be different, each channel can be assigned a unique threshold value. The OL test reports if the select channel has a load impedance greater than the limits in the [Specifications](#) section.

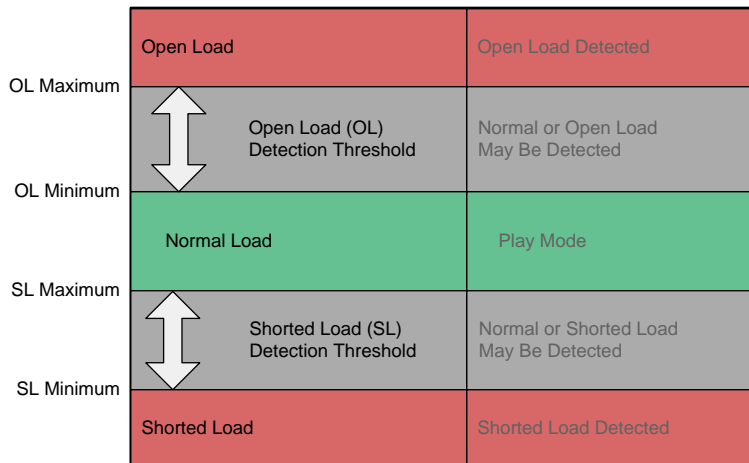


Figure 36. DC Load Diagnostic Reporting Thresholds

### 9.3.7.2 Line Output Diagnostics

The device also includes an optional test to detect a line-output load. A line-output load is a high-impedance load that is above the open-load (OL) threshold such that the DC-load diagnostics report an OL condition. After an OL condition is detected on a channel, if the line output detection bit is also set, the channel checks if a line-output load is present as well. This test is not pop free, so if an external amplifier is connected it should be muted.

### 9.3.7.3 AC Load Diagnostics

The AC load diagnostic is used to determine the proper connection of a capacitively-coupled speaker or tweeter when used with a passive crossover. The AC load diagnostic is controlled through I<sup>2</sup>C. The AC diagnostics requires an external input signal and reports the approximate load impedance and phase. The selected signal frequency should create current flow through the desired speaker for proper detection. If multiple channels must be tested, the diagnostics should be run in series. The AC load-diagnostic test procedure is as follows.

#### 9.3.7.3.1 Impedance Magnitude Measurement

For load-impedance detection, use the following test procedure:

1. Set the channels to be tested into the Hi-Z state.
2. Set the AC\_DIAGS\_LOOPBACK bit (bit 7 in register 0x16) to 0.
3. Apply a full-scale input signal from the DSP for the tested channels with the desired frequency (recommended 10 kHz to 20 kHz).

#### NOTE

The device ramps the signal up and down automatically to prevent pops and clicks.

4. Set the device into the AC diagnostic mode (set bit 3 through bit 0 as needed in register 0x15 to 1 for CH1 to CH4. (For PBTl mode, test channel 1 for PBTl12 and channel 3 for PBTl34))
5. Read back the AC impedance (register 0x17 through register 0x1A).

When the test is complete the channel reporting register indicates the status change from the AC diagnostic mode to the Hi-Z state. The detected impedance is stored in the appropriate I<sup>2</sup>C register.

The hexadecimal register value must be converted to decimal and used to calculate the impedance magnitude using the following equation:

$$\text{Channel } x \text{ Impedance} = \frac{\text{Impedance}_{CHx} \times 2.371 \text{ mV}}{(\text{Gain})(I \text{ mA})} \text{ (Ohms)}$$

**Figure 37. AC Magnitude Calculation**

### 9.3.7.3.2 Impedance Phase Reference Measurement

The first stage to determine the AC phase is to utilize the built-in loopback mode to determine the reference value for the phase measurement. This reference will nullify any phase offset in the device and measure only the phase of the load. This is measured for channels 1 and 3 only. Channel 2 will use the results of channel 1 for the calculations. Channel 4 will use the results of channel 3 for the calculations. Measure channel 1 and channel 3 sequentially, they cannot be measured at the same time.

For loopback delay detection, use the following test procedure for either BTL mode or PBTL mode:

- BTL mode
  1. Set the AC\_DIAGS\_LOOPBACK bit (bit 7 in register 0x16) to 1 to enable AC loopback mode.
  2. Apply a 0-dBFS 19 kHz signal and enable AC load diagnostics. CH1 and CH2 reuse the AC sensing loop of CH1 (set bit 3 in register 0x15 to 1). CH3, CH4 reuse the AC sensing loop of CH3 (set bit 1 in register 0x15 to 1).
  3. Read back the 16bit hexadecimal, AC\_LDG\_PHASE1 value. Register 0x1B holds the MSB and register 0x1C holds the LSB.
  4. For channel 1/2 set bit 3 in register 0x15 to 0. For channel 3/4 set bit 1 in register 0x15 to 0.
- PBTL mode
  1. Set the AC\_DIAGS\_LOOPBACK bit (bit 7 in register 0x16) to 1 to enable AC loopback mode.
  2. Set the PBTL\_CH12 and PBTL\_CH34 bits (see register 0x00) to 0 without toggling SDz pin to enter BTL mode only for load diagnostics.
  3. Apply a 0 dBFS 19 kHz signal and enable AC load diagnostics. For PBTL\_12, enable the AC sensing loop of CH1 (set bit 3 in register 0x15 to 1). For PBTL\_34, enable the AC sensing loop of CH3 (set bit 1 in register 0x15 to 1).
  4. Read back the AC\_LDG\_PHASE1 value. Register 0x1B holds the MSB and register 0x1C holds the LSB.
  5. Set the PBTL\_CH12 and PBTL\_CH34 bits (see register 0x00) to 1 to go back to PBTL mode for load diagnostics.
  6. For PBTL\_12 set bit 3 in register 0x15 to 0. For PBTL\_34 set bit 1 in register 0x15 to 0.

When the test is complete, the channel reporting register indicates the status change from the AC diagnostic mode to the Hi-Z state. The detected impedance is stored in the appropriate I<sup>2</sup>C register.

### 9.3.7.3.3 Impedance Phase Measurement

After performing the phase reference measurements, measure the phase of the speaker load. This is performed in the same manner as the reference measurements, except the loopback is disabled in bit 7 register 0x16. Previously, the phase reference is measured on channel 1 and channel 3. In this test stage all four channels will be measured. Measure the channels sequentially as they cannot be measured at the same time.

For loopback delay detection, use the following test procedure for either BTL mode or PBTL mode:

- BTL mode
  1. Set the AC\_DIAGS\_LOOPBACK bit (bit 7 in register 0x16) to 0 to disable AC loopback mode.
  2. Apply a 0-dBFS 19 kHz signal and enable AC load diagnostics. CH1 and CH2 reuse the AC sensing loop of CH1 (set bit 3 in register 0x15 to 1). CH3, CH4 reuse the AC sensing loop of CH3 (set bit 1 in register 0x15 to 1).
  3. Read back the 16bit hexadecimal, AC\_LDG\_PHASE1 value. Register 0x1B holds the MSB and register 0x1C holds the LSB.
  4. Read back the hexadecimal stimulus value, STI. Register 0x1D holds the MSB and register 0x1E holds



the LSB.

- For channel 1/2 set bit 3 in register 0x15 to 0. For channel 3/4 set bit 1 in register 0x15 to 0.

When the test is complete, the channel reporting register indicates the status change from the AC diagnostic mode to the Hi-Z state. The detected impedance is stored in the appropriate I<sup>2</sup>C register.

- PBTL mode
  - Set the AC\_DIAGS\_LOOPBACK bit (bit 7 in register 0x16) to 0 to disable AC loopback mode.
  - Set the PBTL CH12 and PBTL CH34 bits (see register 0x00) to 0 without toggling SDz pin to enter BTL mode only for load diagnostics.
  - Apply a 0 dBFS 19 kHz signal and enable AC load diagnostics. For PBTL\_12, enable the AC sensing loop of CH1 (set bit 3 in register 0x15 to 1). For PBTL\_34, enable the AC sensing loop of CH3 (set bit 1 in register 0x15 to 1).
  - Read back the AC\_LDG\_PHASE1 value. Register 0x1B holds the MSB and register 0x1C holds the LSB.
  - Read back the hexadecimal stimulus value, STI. Register 0x1D holds the MSB and register 0x1E holds the LSB
  - Set the PBTL CH12 and PBTL CH34 bits (see register 0x00) to 1 to go back to PBTL mode for load diagnostics.
  - For PBTL\_12 set bit 3 in register 0x15 to 0. For PBTL\_34 set bit 1 in register 0x15 to 0.

The AC phase in degrees is calculated with the following equation:

$$Phase\_CHx = 360 \left( \frac{Phase\_CHx(LBK) - Phase\_CHx(LDM)}{STI\_CHx(LDM)} \right)$$

**Figure 38. AC Phase Calculation**

Where:

- Phase\_CHx(LBK) is the reference phase measurement. LBK stands for loopback mode
- Phase\_CHx(LDM) is the phase measure of the load. LDM stands for load mode
- STI\_CHx(LDM) is the stimulus value

**Table 4. AC Impedance Code to Magnitude**

| SETTING                           | GAIN AT 19 kHz | I(A)  | MEASUREMENT RANGE (Ω) | MAPPING FROM CODE TO MAGNITUDE (Ω/Code) |
|-----------------------------------|----------------|-------|-----------------------|---|
| Gain = 4, I = 10 mA (recommended) | 4.28           | 0.01  | 12                    | 0.05832                                 |
| Gain = 4, I = 19 mA               | 4.28           | 0.019 | 6                     | 0.0307                                  |
| Gain = 1, I = 10 mA (recommended) | 1              | 0.01  | 48                    | 0.2496                                  |
| Gain = 1, I = 19 mA               | 1              | 0.019 | 24                    | 0.1314                                  |

### 9.3.8 Protection and Monitoring

#### 9.3.8.1 Overcurrent Limit ( $I_{LIMIT}$ )

The overcurrent limit terminates each PWM pulse to limit the output current flow when the current limit ( $I_{LIMIT}$ ) is exceeded. Power is limited, but operation continues without disruption and prevents undesired shutdown for transient music events.  $I_{LIMIT}$  is not reported as a fault condition to either registers or the FAULT pin. Each channel is independently monitored and limited. The two programmable levels can be set by bit 4 in the [Miscellaneous Control 1 register \(address 0x01\)](#).

### 9.3.8.2 Overcurrent Shutdown ( $I_{SD}$ )

If the output load current reaches  $I_{SD}$ , such as an output short to GND, then a peak current limit occurs, which shuts down the channel. The time to shutdown the channel varies depending on the severity of the short condition. The affected channel is placed into the Hi-Z state, the fault is reported to the register, and the  $\overline{\text{FAULT}}$  pin is asserted. The device will remain in this state until the CLEAR FAULT bit is set in Miscellaneous Control 3 Register, 0x21 bit 7. After clearing this bit and if the diagnostics are enabled, the device will automatically start diagnostics on the channel and, if no load failure is found, the device will restart. If a load fault is found the device continues to rerun the diagnostics once per second. Because this hiccup mode uses the diagnostics, no high current is created. If the diagnostics are disabled, the device sets the state for that channel to Hi-Z and requires the MCU to take the appropriate action, setting the CLEAR FAULT bit after the fault got removed, in order to return to Play state.

Two programable levels can be set by bit 4 in the [Miscellaneous Control 1 register \(address 0x01\)](#).

### 9.3.8.3 DC Detect

This circuit detects a DC offset continuously during normal operation at the output of the amplifier. If the DC offset exceeds the threshold, that channel is placed in the Hi-Z state, the fault is reported to the I<sup>2</sup>C register, and the  $\overline{\text{FAULT}}$  pin is asserted. A register bit can be used to mask reporting to the  $\overline{\text{FAULT}}$  pin if required.

### 9.3.8.4 Clip Detect

The clip detect is reported on the  $\overline{\text{WARN}}$  pin if 100% duty-cycle PWM is reached for a minimum number of PWM cycles set by the Clip Window Register (address 0x23). The default is 20 PWM cycles. If any channel is clipping, the clipping is reported to the pin. The clip detect is latched and can be cleared by I<sup>2</sup>C. Masking the clip reporting to the pin is possible through I<sup>2</sup>C.

### 9.3.8.5 Global Overtemperature Warning (OTW), Overtemperature Shutdown (OTSD)

Four overtemperature warning levels are available in the device (see the [Register Maps](#) section for thresholds). When the junction temperature exceeds the warning level, the  $\overline{\text{WARN}}$  pin is asserted, unless the mask bit has been set to disable reporting. The device functions until the OTSD value is reached at which point all channels are placed in the Hi-Z state, and the  $\overline{\text{FAULT}}$  pin is asserted. When the junction temperature returns to normal levels, the device automatically recovers and places all channels into the state indicated by the register settings.

### 9.3.8.6 Channel Overtemperature Warning [OTW(i)] and Shutdown [OTSD(i)]

In addition to the global OTW, each channel also has an individual overtemperature warning and shutdown. If a channel exceeds the OTW(i) threshold, the warning register bit is set as the  $\overline{\text{WARN}}$  pin is asserted, unless the mask bit has been set to disable reporting. If the channel temperature exceeds the OTSD(i) threshold then that channel goes to the Hi-Z state until the temperature drops below the OTW(i) threshold. At this point, the channel goes to the state indicated by the state control register.

### 9.3.8.7 Undervoltage (UV) and Power-On-Reset (POR)

The undervoltage (UV) protection detects low voltages on the PVDD and VBAT pins. In the event of an UV condition, the  $\overline{\text{FAULT}}$  pin is asserted, and the I<sup>2</sup>C register is updated. A power-on reset (POR) on the VDD pin causes the I<sup>2</sup>C to go to the high-impedance (Hi-Z) state, and all registers are reset to default values. At power-on or after a POR event, the POR warning bit and  $\overline{\text{WARN}}$  pin are asserted.

### 9.3.8.8 Overvoltage (OV) and Load Dump

The overvoltage (OV) protection detects high voltages on the PVDD pin. If the PVDD pin reaches the OV threshold, the  $\overline{\text{FAULT}}$  pin is asserted and the I<sup>2</sup>C register is updated. The device can withstand 40 V load-dump voltage spikes.

## 9.3.9 Power Supply

The device has three power supply inputs, VDD, PVDD, and VBAT, which are described as follows:

**VDD** This pin is a 3.3V supply pin that provides power to the low voltage circuitry.

**VBAT** This pin is a higher voltage supply that can be connected to the vehicle battery or the regulated voltage rail in a boosted system within the recommended limits. For best performance, this rail

should be 10 V or higher. See the [Recommended Operating Conditions](#) table for the maximum supply voltage. This supply rail is used for higher voltage analog circuits but not the output FETs.

**PVDD** This pin is a high-voltage supply that can either be connected to the vehicle battery or to another voltage rail in a boosted system. The PVDD pin supplies the power to the output FETs and can be within the recommended operating limits, even if that is below the VBAT supply, to allow for dynamic voltage systems.

Several on-chip regulators are included for generating the voltages necessary for the internal circuitry. The external pins are provided only for bypass capacitors to filter the supply and should not be used to power other circuits.

The device can withstand fortuitous open ground and power conditions within the absolute maximum ratings for the device. Fortuitous open ground usually occurs when a speaker wire is shorted to ground, allowing for a second ground path through the body diode in the output FETs.

### 9.3.9.1 Vehicle-Battery Power-Supply Sequence

#### Power-Up Sequence

In a typical system, the VBAT and PVDD supplies are both connected to the vehicle battery and power up at the same time. The VDD supply is recommended to be applied 200µs before the VBAT and PVDD supplies start ramping to their recommended operating range. As reference, please see [Figure 39](#). If this is unfeasible and VBAT / PVDD will be supplied before VDD, it is recommended wait 200µs after VDD is supplied before pulling the STANDBY pin high. As reference, please see [Figure 40](#).

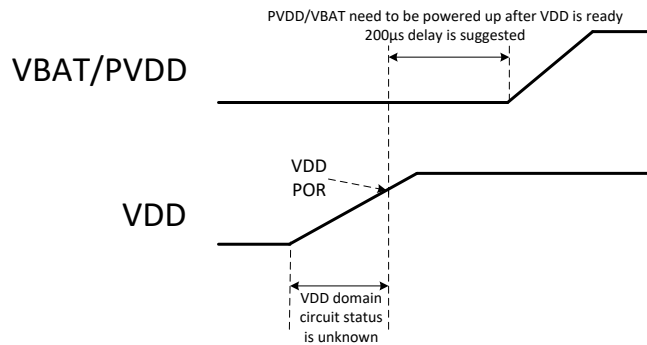


Figure 39. Power-Up Sequence Option 1

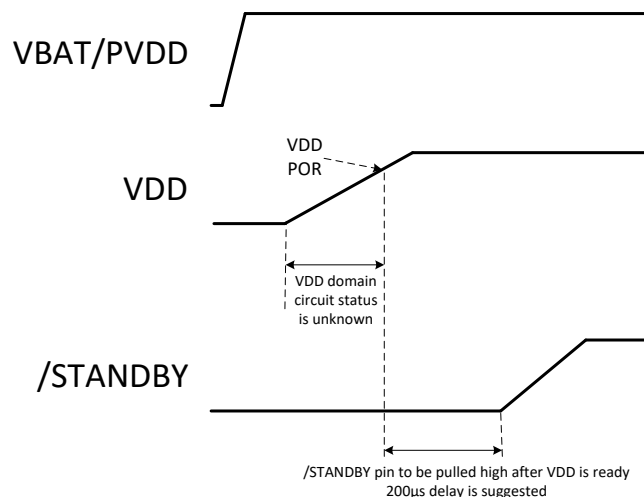


Figure 40. Power-Up Sequence Option 2

## Power-Down Sequence

When removing power from the device, TI recommends to deassert the VBAT and PVDD supplies together first, which provides the lowest click and pop performance, and VDD last. During powering down, VDD must remain available for at least 1.01s after all output stages got set to Hi-Z. To shorten this required delay to 46ms, a 20kOhm parallel resistor between AVDD and AVSS can be added.

### 9.3.9.2 Boosted Power-Supply Sequence

In this scenario, the VBAT and PVDD inputs are not connected to the same supply. During power-up, PVDD should be supplied last while during power-down PVDD should be removed first. All other recommendation apply as described in [Vehicle-Battery Power-Supply Sequence](#).

### 9.3.10 Hardware Control Pins

The device has four pins for control and device status:  $\overline{\text{FAULT}}$ ,  $\overline{\text{MUTE}}$ ,  $\overline{\text{WARN}}$ , and  $\overline{\text{STANDBY}}$ .

#### 9.3.10.1 $\overline{\text{FAULT}}$

The  $\overline{\text{FAULT}}$  pin reports faults and is active low under any of the following conditions:

- Any channel faults (overcurrent or DC detection)
- Overtemperature shutdown
- Overvoltage or undervoltage conditions on the VBAT or PVDD pins
- Clock errors

The  $\overline{\text{FAULT}}$  pin is deactivated when none of the previously listed conditions exist.

Register bits are available to mask fault categories from reporting to the  $\overline{\text{FAULT}}$  pin. These bits only mask the setting of the pin and do not affect the register reporting or protection of the device. By default all faults are reported to the pin. See the [Register Maps](#) section for a description of the mask settings.

This pin is an open-drain output with an internal 100 k $\Omega$  pullup resistor to VDD.

#### 9.3.10.2 $\overline{\text{WARN}}$

This active-low output pin reports audio clipping, overtemperature warnings, and POR events.

Clipping is reported if any channel is at the maximum modulation for 20 consecutive PWM clocks which results in a 10- $\mu$ s delay to report the onset of clipping. The warning bit is sticky and can be cleared by the CLEAR FAULT bit (bit 7) in register 0x21.

An overtemperature warning (OTW) is reported if the general temperature or any of the channel temperature warnings are set. The warning temperature can be set through bits 5 and 6 in register 0x01.

Register bits are available to mask either clipping or OTW reporting to the pin. These bits only mask the setting of the pin and do not affect the register reporting. By default both clipping and OTW are reported.

The  $\overline{\text{WARN}}$  pin is latched and can be cleared by writing the CLEAR FAULT bit (bit 7) in register 0x21.

This pin is an open-drain output with an internal 100 k $\Omega$  pullup resistor to VDD.

#### 9.3.10.3 $\overline{\text{MUTE}}$

This active-low input pin is used for hardware control of the mute and unmute function for all channels.

This pin has a 100 k $\Omega$  internal pulldown resistor.

#### 9.3.10.4 $\overline{\text{STANDBY}}$

When this active-low input pin is asserted, the device goes into shutdown and current draw is limited. This pin can be used to shut down the device rapidly. The outputs are ramped down in less than 5 ms if the device is not already in the Hi-Z state.

This pin has a 100 k $\Omega$  internal pulldown resistor.

## 9.4 Device Functional Modes

### 9.4.1 Operating Modes and Faults

The operating modes and faults are listed in the following tables.

**Table 5. Operating Modes**

| STATE NAME | OUTPUT FETS          | OSCILLATOR | I <sup>2</sup> C |
|------------|----------------------|------------|------------------|
| STANDBY    | Hi-Z                 | Stopped    | Active           |
| Hi-Z       | Hi-Z                 | Active     | Active           |
| MUTE       | Switching at 50%     | Active     | Active           |
| PLAY       | Switching with audio | Active     | Active           |

**Table 6. Global Faults and Actions**

| FAULT/<br>EVENT | FAULT/EVENT<br>CATEGORY | MONITORING<br>MODES | REPORTING<br>METHOD                              | ACTION<br>RESULT |
|-----------------|-------------------------|---------------------|--|------------------|
| POR             | Voltage fault           | All                 | I <sup>2</sup> C + $\overline{\text{WARN}}$ pin  | Standby          |
| VBAT UV         |                         | Hi-Z, mute, normal  | I <sup>2</sup> C + $\overline{\text{FAULT}}$ pin | Hi-Z             |
| PVDD UV         |                         |                     |  |                  |
| VBAT or PVDD OV |                         |                     |  |                  |
| OTW             | Thermal warning         | Hi-Z, mute, normal  | I <sup>2</sup> C + $\overline{\text{WARN}}$ pin  | None             |
| OTSD            | Thermal shutdown        | Hi-Z, mute, normal  | I <sup>2</sup> C + $\overline{\text{FAULT}}$ pin | Hi-Z             |

**Table 7. Channel Faults and Actions**

| FAULT/<br>EVENT      | FAULT/EVENT<br>CATEGORY | MONITORING<br>MODES | REPORTING<br>METHOD                              | ACTION<br>TYPE |
|----------------------|-------------------------|---------------------|--|----------------|
| Clipping             | Warning                 | Mute and play       | $\overline{\text{WARN}}$ pin                     | None           |
| Overcurrent limiting | Protection              |                     |  | Current limit  |
| Overcurrent fault    | Output channel fault    |                     | I <sup>2</sup> C + $\overline{\text{FAULT}}$ pin | Hi-Z           |
| DC detect            |                         |                     |  |                |

## 9.5 Programming

### 9.5.1 I<sup>2</sup>C Serial Communication Bus

The device communicates with the system processor through the I<sup>2</sup>C serial communication bus as an I<sup>2</sup>C slave-only device. The processor can poll the device through I<sup>2</sup>C to determine the operating status, configure settings, or run diagnostics. For a complete list and description of all I<sup>2</sup>C controls, see the [Register Maps](#) section.

The device includes two I<sup>2</sup>C address pins, so up to four devices can be used together in a system with no additional bus switching hardware. The I<sup>2</sup>C ADDR<sub>x</sub> pins set the slave address of the device as listed in [Table 8](#).

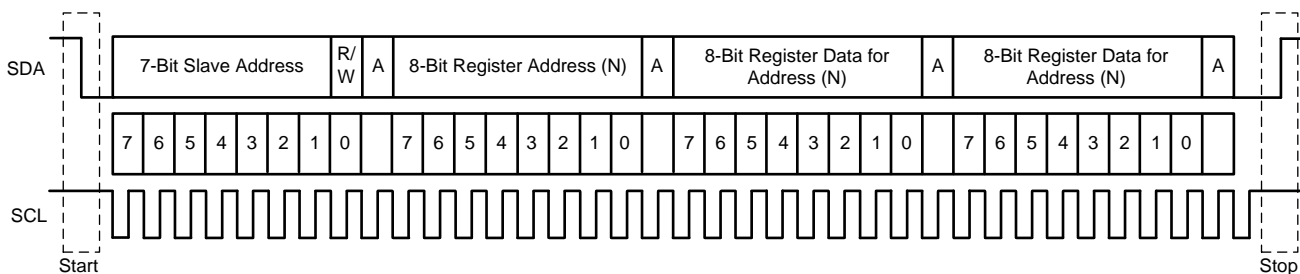
**Table 8. I<sup>2</sup>C Addresses**

| DESCRIPTION | I <sup>2</sup> C ADDR1 | I <sup>2</sup> C ADDR0 | I <sup>2</sup> C Write | I <sup>2</sup> C Read |
|-------------|------------------------|------------------------|------------------------|-----------------------|
| Device 0    | 0                      | 0                      | 0xD4                   | 0xD5                  |
| Device 1    | 0                      | 1                      | 0xD6                   | 0xD7                  |
| Device 2    | 1                      | 0                      | 0xD8                   | 0xD9                  |
| Device 3    | 1                      | 1                      | 0xDA                   | 0xDB                  |

### 9.5.2 I<sup>2</sup>C Bus Protocol

The device has a bidirectional serial-control interface that is compatible with the Inter IC (I<sup>2</sup>C) bus protocol and supports 100 kbps and 400 kbps data transfer rates for random and sequential write and read operations. The TAS6424M-Q1 device is a slave-only device that does not support a multimaster bus environment or wait-state insertion. The control interface is used to program the registers of the device and to read device status.

The I<sup>2</sup>C bus uses two signals, SDA (data) and SCL (clock), to communicate between integrated circuits in a system. Data is transferred on the bus serially, one bit at a time. The address and data are transferred in byte (8-bit) format with the most-significant bit (MSB) transferred first. In addition, each byte transferred on the bus is acknowledged by the receiving device with an acknowledge bit. Each transfer operation begins with the master device driving a start condition on the bus and ends with the master device driving a stop condition on the bus. The bus uses transitions on the data terminal (SDA) while the clock is HIGH to indicate a start and stop conditions. A HIGH-to-LOW transition on SDA indicates a start, and a LOW-to-HIGH transition indicates a stop. Normal data bit transitions must occur within the low time of the clock period. The master generates the 7-bit slave address and the read/write (R/W) bit to open communication with another device and then wait for an acknowledge condition. The device holds SDA LOW during the acknowledge-clock period to indicate an acknowledgment. When this occurs, the master transmits the next byte of the sequence. Each device is addressed by a unique 7-bit slave address plus a R/W bit (1 byte). All compatible devices share the same signals via a bidirectional bus using a wired-AND connection. An external pullup resistor must be used for the SDA and SCL signals to set the HIGH level for the bus. The number of bytes that can be transmitted between start and stop conditions is unlimited. When the last word transfers, the master generates a stop condition to release the bus.



**Figure 41. Typical I<sup>2</sup>C Sequence**

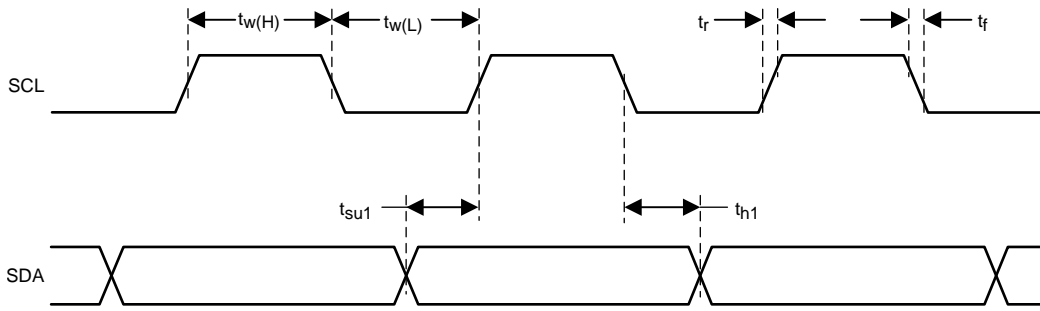


Figure 42. SCL and SDA Timing

Use the I<sup>2</sup>C ADDR<sub>x</sub> pins to program the device slave address. Read and write data can be transmitted using single-byte or multiple-byte data transfers.

### 9.5.3 Random Write

As shown in Figure 43, a single-byte data-write transfer begins with the master device transmitting a start condition followed by the I<sup>2</sup>C device address and the R/W bit. The R/W bit determines the direction of the data transfer. For a write data transfer, the R/W bit is a 0. After receiving the correct I<sup>2</sup>C device address and the R/W bit, the device responds with an acknowledge bit. Next, the master transmits the address byte or bytes corresponding to the internal memory address being accessed. After receiving the address byte, the device again responds with an acknowledge bit. Next, the master device transmits the data byte to be written to the memory address being accessed. After receiving the data byte, the device again responds with an acknowledge bit. Finally, the master device transmits a stop condition to complete the single-byte data-write transfer.

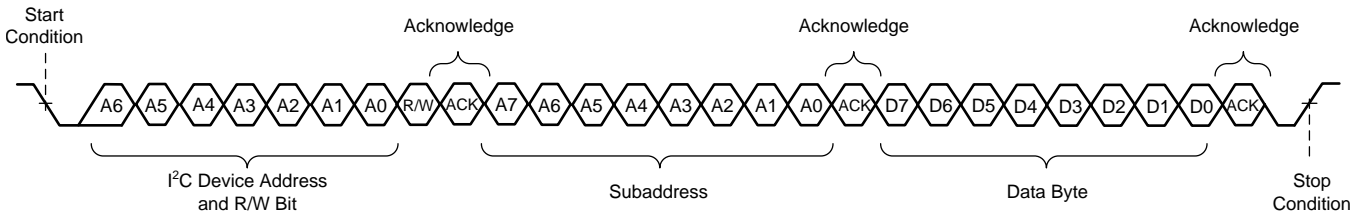


Figure 43. Random Write Transfer

### 9.5.4 Sequential Write

A sequential data-write transfer is identical to a single-byte data-write transfer except that multiple data bytes are transmitted by the master to the device as shown in Figure 44. After receiving each data byte, the device responds with an acknowledge bit and the I<sup>2</sup>C subaddress is automatically incremented by one.

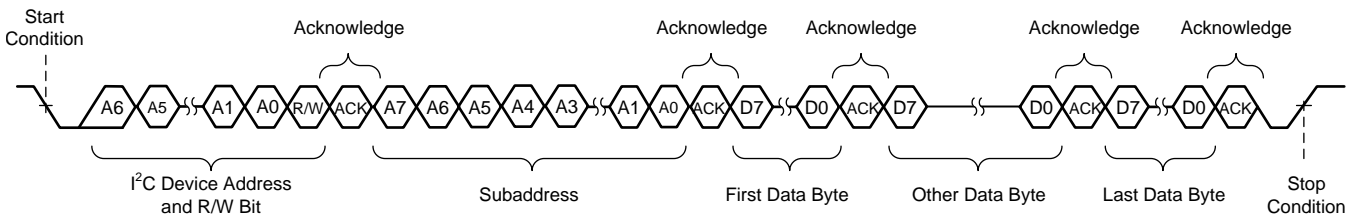


Figure 44. Sequential Write Transfer

### 9.5.5 Random Read

As shown in Figure 45, a single-byte data-read transfer begins with the master device transmitting a start condition followed by the I<sup>2</sup>C device address and the R/W bit. For the data-read transfer, both a write followed by a read occur. Initially, a write occurs to transfer the address byte or bytes of the internal memory address to be read. As a result, the R/W bit is a 0. After receiving the address and the R/W bit, the device responds with an acknowledge bit. In addition, after sending the internal memory address byte or bytes, the master device



transmits another start condition followed by the address and the R/W bit again. This time the R/W bit is a 1, indicating a read transfer. After receiving the address and the R/W bit, the device again responds with an acknowledge bit. Next, the device transmits the data byte from the memory address being read. After receiving the data byte, the master device transmits a not-acknowledge followed by a stop condition to complete the single-byte data-read transfer.

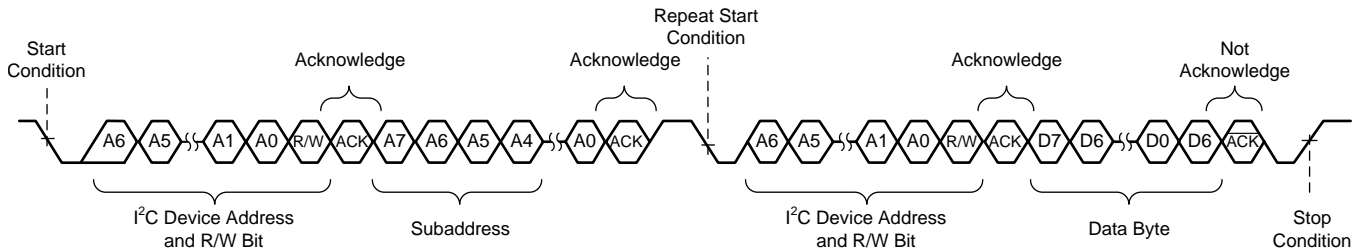


Figure 45. Random Read Transfer

### 9.5.6 Sequential Read

A sequential data-read transfer is identical to a single-byte data-read transfer except that multiple data bytes are transmitted by the device to the master device as shown in Figure 46. Except for the last data byte, the master device responds with an acknowledge bit after receiving each data byte and automatically increments the I<sup>2</sup>C subaddress by one. After receiving the last data byte, the master device transmits a not-acknowledge bit followed by a stop condition to complete the transfer.

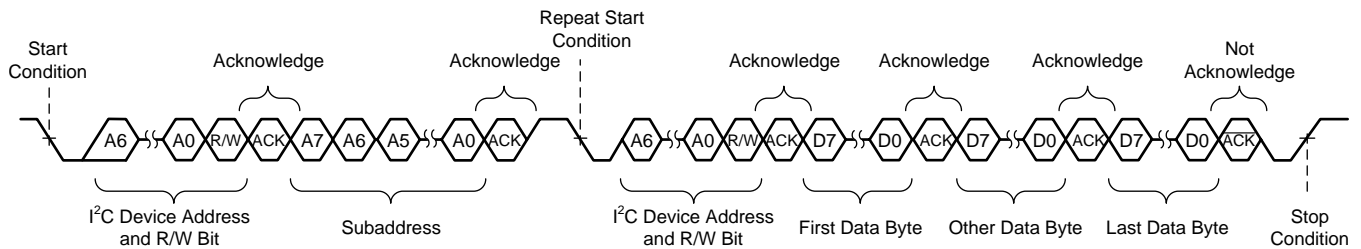


Figure 46. Sequential Read Transfer



## 9.6 Register Maps

**Table 9. I<sup>2</sup>C Address Register Definitions**

| Address | Type | Register Description                           | Section            |
|---------|------|--|--------------------|
| 0x00    | R/W  | Mode Control                                   | <a href="#">Go</a> |
| 0x01    | R/W  | Miscellaneous Control 1                        | <a href="#">Go</a> |
| 0x02    | R/W  | Miscellaneous Control 2                        | <a href="#">Go</a> |
| 0x03    | R/W  | SAP Control (Serial Audio-Port Control)        | <a href="#">Go</a> |
| 0x04    | R/W  | Channel State Control                          | <a href="#">Go</a> |
| 0x05    | R/W  | Channel 1 Volume Control                       | <a href="#">Go</a> |
| 0x06    | R/W  | Channel 2 Volume Control                       | <a href="#">Go</a> |
| 0x07    | R/W  | Channel 3 Volume Control                       | <a href="#">Go</a> |
| 0x08    | R/W  | Channel 4 Volume Control                       | <a href="#">Go</a> |
| 0x09    | R/W  | DC Diagnostic Control 1                        | <a href="#">Go</a> |
| 0x0A    | R/W  | DC Diagnostic Control 2                        | <a href="#">Go</a> |
| 0x0B    | R/W  | DC Diagnostic Control 3                        | <a href="#">Go</a> |
| 0x0C    | R    | DC Load Diagnostic Report 1 (Channels 1 and 2) | <a href="#">Go</a> |
| 0x0D    | R    | DC Load Diagnostic Report 2 (Channels 3 and 4) | <a href="#">Go</a> |
| 0x0E    | R    | DC Load Diagnostic Report 3-Line Output        | <a href="#">Go</a> |
| 0x0F    | R    | Channel State Reporting                        | <a href="#">Go</a> |
| 0x10    | R    | Channel Faults (Overcurrent, DC Detection)     | <a href="#">Go</a> |
| 0x11    | R    | Global Faults 1                                | <a href="#">Go</a> |
| 0x12    | R    | Global Faults 2                                | <a href="#">Go</a> |
| 0x13    | R    | Warnings                                       | <a href="#">Go</a> |
| 0x14    | R/W  | Pin Control                                    | <a href="#">Go</a> |
| 0x15    | R/W  | AC Load Diagnostic Control 1                   | <a href="#">Go</a> |
| 0x16    | R/W  | AC Load Diagnostic Control 2                   | <a href="#">Go</a> |
| 0x17    | R    | AC Load Diagnostic Report Channel 1            | <a href="#">Go</a> |
| 0x18    | R    | AC Load Diagnostic Report Channel 2            | <a href="#">Go</a> |
| 0x19    | R    | AC Load Diagnostic Report Channels 3           | <a href="#">Go</a> |
| 0x1A    | R    | AC Load Diagnostic Report Channels 4           | <a href="#">Go</a> |
| 0x1B    | R    | AC Load Diagnostic Phase Report High           | <a href="#">Go</a> |
| 0x1C    | R    | AC Load Diagnostic Phase Report Low            | <a href="#">Go</a> |
| 0x1D    | R    | AC Load Diagnostic STI Report High             | <a href="#">Go</a> |
| 0x1E    | R    | AC Load Diagnostic STI Report Low              | <a href="#">Go</a> |
| 0x1F    | R    | RESERVED                                       |                    |
| 0x20    | R    | RESERVED                                       |                    |
| 0x21    | R/W  | Miscellaneous Control 3                        | <a href="#">Go</a> |
| 0x22    | R/W  | Clip Control                                   | <a href="#">Go</a> |
| 0x23    | R/W  | Clip Window                                    | <a href="#">Go</a> |
| 0x24    | R/W  | Clip Warning                                   | <a href="#">Go</a> |
| 0x25    | R/W  | ILIMIT Status                                  | <a href="#">Go</a> |
| 0x26    | R/W  | Miscellaneous Control 4                        | <a href="#">Go</a> |
| 0x27    | R    | RESERVED                                       |                    |
| 0x28    | R    | RESERVED                                       |                    |

### 9.6.1 Mode Control Register (address = 0x00) [default = 0x00]

The Mode Control register is shown in [Figure 47](#) and described in [Table 10](#).

**Figure 47. Mode Control Register**

| 7     | 6        | 5         | 4         | 3           | 2           | 1           | 0           |
|-------|----------|-----------|-----------|-------------|-------------|-------------|-------------|
| RESET | RESERVED | PBTL CH34 | PBTL CH12 | CH1 LO MODE | CH2 LO MODE | CH3 LO MODE | CH4 LO MODE |
| R/W-0 | R/W-0    | R/W-0     | R/W-0     | R/W-0       | R/W-0       | R/W-0       | R/W-0       |

**Table 10. Mode Control Field Descriptions**

| Bit | Field       | Type | Reset | Description  |
|-----|-------------|------|-------|--|
| 7   | RESET       | R/W  | 0     | <b>0: Normal operation</b><br>1: Resets the device. Self-clearing, will read back 0.       |
| 6   | RESERVED    | R/W  | 0     | RESERVED   |
| 5   | PBTL CH34   | R/W  | 0     | <b>0: Channels 3 and 4 are in BTL mode</b><br>1: Channels 3 and 4 are in parallel BTL mode |
| 4   | PBTL CH12   | R/W  | 0     | <b>0: Channels 1 and 2 are in BTL mode</b><br>1: Channels 1 and 2 are in parallel BTL mode |
| 3   | CH1 LO MODE | R/W  | 0     | <b>0: Channel 1 is in normal/speaker mode</b><br>1: Channel 1 is in line output mode       |
| 2   | CH2 LO MODE | R/W  | 0     | <b>0: Channel 2 is in normal/speaker mode</b><br>1: Channel 2 is in line output mode       |
| 1   | CH3 LO MODE | R/W  | 0     | <b>0: Channel 3 is in normal/speaker mode</b><br>1: Channel 3 is in line output mode       |
| 0   | CH4 LO MODE | R/W  | 0     | <b>0: Channel 4 is in normal/speaker mode</b><br>1: Channel 4 is in line output mode       |

### 9.6.2 Miscellaneous Control 1 Register (address = 0x01) [default = 0x32]

The Miscellaneous Control 1 register is shown in [Figure 48](#) and described in [Table 11](#).

**Figure 48. Miscellaneous Control 1 Register**

| 7          | 6           | 5 | 4          | 3           | 2 | 1      | 0 |
|------------|-------------|---|------------|-------------|---|--------|---|
| HPF BYPASS | OTW CONTROL |   | OC CONTROL | VOLUME RATE |   | GAIN   |   |
| R/W-0      | R/W-01      |   | R/W-1      | R/W-00      |   | R/W-10 |   |

**Table 11. Misc Control 1 Field Descriptions**

| Bit | Field       | Type | Reset | Description  |
|-----|-------------|------|-------|--|
| 7   | HPF BYPASS  | R/W  | 0     | <b>0: High pass filter enabled</b><br>1: High pass filter disabled   |
| 6–5 | OTW CONTROL | R/W  | 01    | 00: Global overtemperature warning set to 140°C<br><b>01: Global overtemperature warning set to 130C</b><br>10: Global overtemperature warning set to 120°C<br>11: Global overtemperature warning set to 110°C |
| 4   | OC CONTROL  | R/W  | 1     | 0: Overcurrent is level 1<br><b>1: Overcurrent is level 2</b>  |
| 3–2 | VOLUME RATE | R/W  | 00    | <b>00: Volume update rate is 1 step / FSYNC</b><br>01: Volume update rate is 1 step / 2 FSYNCs<br>10: Volume update rate is 1 step / 4 FSYNCs<br>11: Volume update rate is 1 step / 8 FSYNCs                   |

**Table 11. Misc Control 1 Field Descriptions (continued)**

| Bit | Field | Type | Reset | Description  |
|-----|-------|------|-------|--|
| 1–0 | GAIN  | R/W  | 10    | 00: Gain level 1 = 7.5 V peak output voltage<br>01: Gain Level 2 = 15 V peak output voltage<br><b>10: Gain Level 3 = 21 V peak output voltage</b><br>11: Gain Level 4 = 29 V peak output voltage |

### 9.6.3 Miscellaneous Control 2 Register (address = 0x02) [default = 0x62]

The Miscellaneous Control 2 register is shown in [Figure 49](#) and described in [Table 12](#).

**Figure 49. Miscellaneous Control 2 Register**

| 7        | 6             | 5 | 4 | 3        | 2       | 1            | 0 |
|----------|---------------|---|---|----------|---------|--------------|---|
| RESERVED | PWM FREQUENCY |   |   | RESERVED | SDM_OSR | OUTPUT PHASE |   |
| R/W-110  |               |   |   | R/W-0    |         | R/W-10       |   |

**Table 12. Misc Control 2 Field Descriptions**

| Bit | Field         | Type | Reset | Description   |
|-----|---------------|------|-------|---|
| 7   | RESERVED      |      |       | <b>0</b>  |
| 6–4 | PWM FREQUENCY | R/W  | 110   | 000: $8 \times f_S$ (352.8 kHz / 384 kHz)<br>001: $10 \times f_S$ (441 kHz / 480 kHz)<br>010: RESERVED<br>011: RESERVED<br>100: RESERVED<br>101: $38 \times f_S$ (1.68 MHz / 1.82 MHz)<br><b>110: <math>44 \times f_S</math> (1.94 MHz / 2.11 MHz)</b><br>111: $48 \times f_S$ (2.12 MHz / not supported) |
| 3   | RESERVED      |      | 0     | <b>0</b>  |
| 2   | SDM_OSR       | R/W  | 0     | <b>0: 64x OSR</b><br>1: 128x OSR  |
| 1–0 | OUTPUT PHASE  | R/W  | 10    | 00: 0 degrees output-phase switching offset<br>01: 30 degrees output-phase switching offset<br><b>10: 45 degrees output-phase switching offset</b><br>11: 60 degrees output-phase switching offset  |

### 9.6.4 SAP Control (Serial Audio-Port Control) Register (address = 0x03) [default = 0x04]

The SAP Control (serial audio-port control) register is shown in [Figure 50](#) and described in [Table 13](#).

**Figure 50. SAP Control Register**

| 7                   | 6                    | 5             | 4                 | 3            | 2 | 1 | 0 |
|---------------------|----------------------|---------------|-------------------|--------------|---|---|---|
| INPUT SAMPLING RATE | 8 Ch TDM SLOT SELECT | TDM SLOT SIZE | TDM SLOT SELECT 2 | INPUT FORMAT |   |   |   |
| R/W-00              | R/W-0                | R/W-0         | R/W-0             | R/W-100      |   |   |   |

**Table 13. SAP Control Field Descriptions**

| Bit | Field               | Type | Reset | Description   |
|-----|---------------------|------|-------|---|
| 7–6 | INPUT SAMPLING RATE | R/W  | 00    | <b>00: 44.1 kHz</b><br>01: 48 kHz<br>10: 96 kHz<br>11: RESERVED |

**Table 13. SAP Control Field Descriptions (continued)**

| Bit | Field                | Type | Reset | Description  |
|-----|----------------------|------|-------|--|
| 5   | 8 Ch TDM SLOT SELECT | R/W  | 0     | <b>0:</b> First four TDM slots<br>1: Last four TDM slots   |
| 4   | TDM SLOT SIZE        | R/W  | 0     | <b>0:</b> TDM slot size is 24-bit or 32-bit<br>1: TDM slot size is 16-bit  |
| 3   | TDM SLOT SELECT 2    | R/W  | 0     | <b>0:</b> Normal<br>1: swap channel 1/2 with channel 3/4   |
| 2–0 | INPUT FORMAT         | R/W  | 100   | 000: 24-bit right justified<br>001: 20-bit right justified<br>010: 18-bit right justified<br>011: 16-bit right justified<br><b>100: I<sup>2</sup>S (16-bit or 24-bit)</b><br>101: Left justified (16-bit or 24-bit)<br>110: DSP mode (16-bit or 24-bit)<br>111: RESERVED |

### 9.6.5 Channel State Control Register (address = 0x04) [default = 0x55]

The Channel State Control register is shown in [Figure 51](#) and described in [Table 14](#).

**Figure 51. Channel State Control Register**

| 7                 | 6 | 5                 | 4 | 3        | 2 | 1        | 0 |
|-------------------|---|-------------------|---|----------|---|----------|---|
| CH1 STATE CONTROL |   | CH2 STATE CONTROL |   | RESERVED |   | RESERVED |   |
| R/W-01            |   | R/W-01            |   | R/W-01   |   | R/W-01   |   |

**Table 14. Channel State Control Field Descriptions**

| Bit | Field             | Type | Reset | Description  |
|-----|-------------------|------|-------|--|
| 7–6 | CH1 STATE CONTROL | R/W  | 01    | 00: PLAY<br><b>01: Hi-Z</b><br>10: MUTE<br>11: DC load diagnostics |
| 5–4 | CH2 STATE CONTROL | R/W  | 01    | 00: PLAY<br><b>01: Hi-Z</b><br>10: MUTE<br>11: DC load diagnostics |
| 3–2 | CH3 STATE CONTROL | R/W  | 01    | 00: PLAY<br><b>01: Hi-Z</b><br>10: MUTE<br>11: DC load diagnostics |
| 1–0 | CH4 STATE CONTROL | R/W  | 01    | 00: PLAY<br><b>01: Hi-Z</b><br>10: MUTE<br>11: DC load diagnostics |

### 9.6.6 Channel 1 Through 4 Volume Control Registers (address = 0x05–0x08) [default = 0xCF]

The Channel 1 Through 4 Volume Control registers are shown in [Figure 52](#) and described in [Table 15](#).

**Figure 52. Channel x Volume Control Register**

|             |   |   |   |   |   |   |   |
|-------------|---|---|---|---|---|---|---|
| 7           | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| CH x VOLUME |   |   |   |   |   |   |   |
| R/W-CF      |   |   |   |   |   |   |   |

**Table 15. Ch x Volume Control Field Descriptions**

| Bit | Field       | Type | Reset | Description  |
|-----|-------------|------|-------|--|
| 7–0 | CH x VOLUME | R/W  | CF    | 8-Bit Volume Control for each channel, register address for Ch1 is 0x05, Ch2 is 0x06, Ch3 is 0x07 and Ch4 is 0x08, 0.5 dB/step:<br>0xFF: 24 dB<br><b>0xCF: 0 dB</b><br>0x07: –100 dB<br>< 0x07: MUTE |

### 9.6.7 DC Load Diagnostic Control 1 Register (address = 0x09) [default = 0x00]

The DC Diagnostic Control 1 register is shown in [Figure 53](#) and described in [Table 16](#).

**Figure 53. DC Load Diagnostic Control 1 Register**

|              |         |           |          |   |   |               |            |
|--------------|---------|-----------|----------|---|---|---------------|------------|
| 7            | 6       | 5         | 4        | 3 | 2 | 1             | 0          |
| DC LDG ABORT | 2x_RAMP | 2x_SETTLE | RESERVED |   |   | LDG LO ENABLE | LDG BYPASS |
| R/W-0        | R/W-0   | R/W-0     |          |   |   | R/W-0         | R/W-0      |

**Table 16. DC Load Diagnostics Control 1 Field Descriptions**

| Bit | Field         | Type | Reset | Description   |
|-----|---------------|------|-------|---|
| 7   | DC LDG ABORT  | R/W  | 0     | <b>0: Default state, clear after abort</b><br>1: Aborts the load diagnostics in progress                              |
| 6   | 2x_RAMP       | R/W  | 0     | <b>0: Normal ramp time</b><br>1: Double ramp time   |
| 5   | 2x_SETTLE     | R/W  | 0     | <b>0: Normal Settle time</b><br>1: Double settling time   |
| 4–2 | RESERVED      |      | 0     | <b>0</b>  |
| 1   | LDG LO ENABLE | R/W  | 0     | <b>0: Line output diagnostics are disabled</b><br>1: Line output diagnostics are enabled                              |
| 0   | LDG BYPASS    | R/W  | 0     | <b>0: Automatic diagnostics when leaving Hi-Z and after channel fault</b><br>1: Diagnostics are not run automatically |

### 9.6.8 DC Load Diagnostic Control 2 Register (address = 0x0A) [default = 0x11]

The DC Diagnostic Control 2 register is shown in [Figure 54](#) and described in [Table 17](#).

**Figure 54. DC Load Diagnostic Control 2 Register**

|               |   |   |   |               |   |   |   |
|---------------|---|---|---|---------------|---|---|---|
| 7             | 6 | 5 | 4 | 3             | 2 | 1 | 0 |
| CH1 DC LDG SL |   |   |   | CH2 DC LDG SL |   |   |   |
| R/W-0001      |   |   |   | R/W-0001      |   |   |   |

**Table 17. DC Load Diagnostics Control 2 Field Descriptions**

| Bit | Field         | Type | Reset | Description   |
|-----|---------------|------|-------|---|
| 7–4 | CH1 DC LDG SL | R/W  | 0001  | DC load diagnostics shorted-load threshold<br>0000: 0.5 $\Omega$<br><b>0001: 1 <math>\Omega</math></b><br>0010: 1.5 $\Omega$<br>...<br>1001: 5 $\Omega$ |
| 3–0 | CH2 DC LDG SL | R/W  | 0001  | DC load diagnostics shorted-load threshold<br>0000: 0.5 $\Omega$<br><b>0001: 1 <math>\Omega</math></b><br>0010: 1.5 $\Omega$<br>...<br>1001: 5 $\Omega$ |

**9.6.9 DC Load Diagnostic Control 3 Register (address = 0x0B) [default = 0x11]**

 The DC Diagnostic Control 3 register is shown in [Figure 55](#) and described in [Table 18](#).

**Figure 55. DC Load Diagnostic Control 3 Register**

| 7             | 6 | 5 | 4 | 3             | 2 | 1 | 0 |
|---------------|---|---|---|---------------|---|---|---|
| CH3 DC LDG SL |   |   |   | CH4 DC LDG SL |   |   |   |
| R/W-0001      |   |   |   | R/W-0001      |   |   |   |

**Table 18. DC Load Diagnostics Control 3 Field Descriptions**

| Bit | Field         | Type | Reset | Description   |
|-----|---------------|------|-------|---|
| 7–4 | CH3 DC LDG SL | R/W  | 0001  | DC load diagnostics shorted-load threshold<br>0000: 0.5 $\Omega$<br><b>0001: 1 <math>\Omega</math></b><br>0010: 1.5 $\Omega$<br>...<br>1001: 5 $\Omega$ |
| 3–0 | CH4 DC LDG SL | R/W  | 0001  | DC load diagnostics shorted-load threshold<br>0000: 0.5 $\Omega$<br><b>0001: 1 <math>\Omega</math></b><br>0010: 1.5 $\Omega$<br>...<br>1001: 5 $\Omega$ |

**9.6.10 DC Load Diagnostic Report 1 Register (address = 0x0C) [default = 0x00]**

 DC Load Diagnostic Report 1 register is shown in [Figure 56](#) and described in [Table 19](#).

**Figure 56. DC Load Diagnostic Report 1 Register**

| 7       | 6       | 5      | 4      | 3       | 2       | 1      | 0      |
|---------|---------|--------|--------|---------|---------|--------|--------|
| CH1 S2G | CH1 S2P | CH1 OL | CH1 SL | CH2 S2G | CH2 S2P | CH2 OL | CH2 SL |
| R-0     | R-0     | R-0    | R-0    | R-0     | R-0     | R-0    | R-0    |

**Table 19. DC Load Diagnostics Report 1 Field Descriptions**

| Bit | Field   | Type | Reset | Description  |
|-----|---------|------|-------|--|
| 7   | CH1 S2G | R    | 0     | <b>0: No short-to-GND detected</b><br>1: Short-To-GND Detected |

**Table 19. DC Load Diagnostics Report 1 Field Descriptions (continued)**

| Bit | Field   | Type | Reset | Description  |
|-----|---------|------|-------|--|
| 6   | CH1 S2P | R    | 0     | <b>0: No short-to-power detected</b><br>1: Short-to-power detected |
| 5   | CH1 OL  | R    | 0     | <b>0: No open load detected</b><br>1: Open load detected           |
| 4   | CH1 SL  | R    | 0     | <b>0: No shorted load detected</b><br>1: Shorted load detected     |
| 3   | CH2 S2G | R    | 0     | <b>0: No short-to-GND detected</b><br>1: Short-to-GND detected     |
| 2   | CH2 S2P | R    | 0     | <b>0: No short-to-power detected</b><br>1: Short-to-power detected |
| 1   | CH2 OL  | R    | 0     | <b>0: No open load detected</b><br>1: Open load detected           |
| 0   | CH2 SL  | R    | 0     | <b>0: No shorted load detected</b><br>1: Shorted load detected     |

**9.6.11 DC Load Diagnostic Report 2 Register (address = 0x0D) [default = 0x00]**

 The DC Load Diagnostic Report 2 register is shown in [Figure 57](#) and described in [Table 20](#).

**Figure 57. DC Load Diagnostic Report 2 Register**

| 7       | 6       | 5      | 4      | 3       | 2       | 1      | 0      |
|---------|---------|--------|--------|---------|---------|--------|--------|
| CH3 S2G | CH3 S2P | CH3 OL | CH3 SL | CH4 S2G | CH4 S2P | CH4 OL | CH4 SL |
| R-0     | R-0     | R-0    | R-0    | R-0     | R-0     | R-0    | R-0    |

**Table 20. DC Load Diagnostics Report 2 Field Descriptions**

| Bit | Field   | Type | Reset | Description  |
|-----|---------|------|-------|--|
| 7   | CH3 S2G | R    | 0     | <b>0: No short-to-GND detected</b><br>1: Short-to-GND detected     |
| 6   | CH3 S2P | R    | 0     | <b>0: No short-to-power detected</b><br>1: Short-to-power detected |
| 5   | CH3 OL  | R    | 0     | <b>0: No open load detected</b><br>1: Open load detected           |
| 4   | CH3 SL  | R    | 0     | <b>0: No shorted load detected</b><br>1: Shorted load detected     |
| 3   | CH4 S2G | R    | 0     | <b>0: No short-to-GND detected</b><br>1: Short-to-GND detected     |
| 2   | CH4 S2P | R    | 0     | <b>0: No short-to-power detected</b><br>1: Short-to-power detected |
| 1   | CH4 OL  | R    | 0     | <b>0: No open load detected</b><br>1: Open load detected           |
| 0   | CH4 SL  | R    | 0     | <b>0: No shorted load detected</b><br>1: Shorted load detected     |

### 9.6.12 DC Load Diagnostics Report 3 Line Output Register (address = 0x0E) [default = 0x00]

The DC Load Diagnostic Report, Line Output, register is shown in [Figure 58](#) and described in [Table 21](#).

**Figure 58. DC Load Diagnostics Report 3 Line Output Register**

| 7        | 6 | 5 | 4 | 3          | 2          | 1        | 0        |
|----------|---|---|---|------------|------------|----------|----------|
| RESERVED |   |   |   | CH1 LO LDG | CH2 LO LDG | RESERVED | RESERVED |
|          |   |   |   | R-0        | R-0        | R-0      | R-0      |

**Table 21. DC Load Diagnostics Report 3 Line Output Field Descriptions**

| Bit | Field      | Type | Reset | Description  |
|-----|------------|------|-------|--|
| 7–4 | RESERVED   |      |       | <b>0</b>   |
| 3   | CH1 LO LDG | R    | 0     | <b>0: No line output detected on channel 1</b><br>1: Line output detected on channel 1 |
| 2   | CH2 LO LDG | R    | 0     | <b>0: No line output detected on channel 2</b><br>1: Line output detected on channel 2 |
| 1   | CH3 LO LDG | R    | 0     | <b>0: No line output detected on channel 3</b><br>1: Line output detected on channel 3 |
| 0   | CH4 LO LDG | R    | 0     | <b>0: No line output detected on channel 4</b><br>1: Line output detected on channel 4 |

### 9.6.13 Channel State Reporting Register (address = 0x0F) [default = 0x55]

The Channel State Reporting register is shown in [Figure 59](#) and described in [Table 22](#).

**Figure 59. Channel State-Reporting Register**

| 7                | 6 | 5                | 4 | 3                | 2 | 1                | 0 |
|------------------|---|------------------|---|------------------|---|------------------|---|
| CH1 STATE REPORT |   | CH2 STATE REPORT |   | CH3 STATE REPORT |   | CH4 STATE REPORT |   |
| R-01             |   | R-01             |   | R-01             |   | R-01             |   |

**Table 22. State-Reporting Field Descriptions**

| Bit | Field            | Type | Reset | Description  |
|-----|------------------|------|-------|--|
| 7–6 | CH1 STATE REPORT | R    | 01    | 00: PLAY<br><b>01: Hi-Z</b><br>10: MUTE<br>11: DC load diagnostics |
| 5–4 | CH2 STATE REPORT | R    | 01    | 00: PLAY<br><b>01: Hi-Z</b><br>10: MUTE<br>11: DC load diagnostics |
| 3–2 | CH3 STATE REPORT | R    | 01    | 00: PLAY<br><b>01: Hi-Z</b><br>10: MUTE<br>11: DC load diagnostics |
| 1–0 | CH4 STATE REPORT | R    | 01    | 00: PLAY<br><b>01: Hi-Z</b><br>10: MUTE<br>11: DC load diagnostics |



### 9.6.14 Channel Faults (Overcurrent, DC Detection) Register (address = 0x10) [default = 0x00]

The Channel Faults (overcurrent, DC detection) register is shown in [Figure 60](#) and described in [Table 23](#).

**Figure 60. Channel Faults Register**

| 7      | 6      | 5      | 4      | 3      | 2      | 1      | 0      |
|--------|--------|--------|--------|--------|--------|--------|--------|
| CH1 OC | CH2 OC | CH3 OC | CH4 OC | CH1 DC | CH2 DC | CH3 DC | CH4 DC |
| R-0    | R-0    | R-0    | R-0    | R-0    | R-0    | R-0    | R-0    |

**Table 23. Channel Faults Field Descriptions**

| Bit | Field  | Type | Reset | Description  |
|-----|--------|------|-------|--|
| 7   | CH1 OC | R    | 0     | <b>0: No overcurrent fault detected</b><br>1: Overcurrent fault detected |
| 6   | CH2 OC | R    | 0     | <b>0: No overcurrent fault detected</b><br>1: Overcurrent fault detected |
| 5   | CH3 OC | R    | 0     | <b>0: No overcurrent fault detected</b><br>1: Overcurrent fault detected |
| 4   | CH4 OC | R    | 0     | <b>0: No overcurrent fault detected</b><br>1: Overcurrent fault detected |
| 3   | CH1 DC | R    | 0     | <b>0: No DC fault detected</b><br>1: DC fault detected                   |
| 2   | CH2 DC | R    | 0     | <b>0: No DC fault detected</b><br>1: DC fault detected                   |
| 1   | CH3 DC | R    | 0     | <b>0: No DC fault detected</b><br>1: DC fault detected                   |
| 0   | CH4 DC | R    | 0     | <b>0: No DC fault detected</b><br>1: DC fault detected                   |

### 9.6.15 Global Faults 1 Register (address = 0x11) [default = 0x00]

The Global Faults 1 register is shown in [Figure 61](#) and described in [Table 24](#).

**Figure 61. Global Faults 1 Register**

| 7        | 6 | 5 | 4                | 3       | 2       | 1       | 0       |
|----------|---|---|------------------|---------|---------|---------|---------|
| RESERVED |   |   | INVALID<br>CLOCK | PVDD OV | VBAT OV | PVDD UV | VBAT UV |
|          |   |   | R-0              | R-0     | R-0     | R-0     | R-0     |

**Table 24. Global Faults 1 Field Descriptions**

| Bit | Field         | Type | Reset | Description  |
|-----|---------------|------|-------|--|
| 7–5 | RESERVED      |      | 0     | <b>0</b>   |
| 4   | INVALID CLOCK | R    | 0     | <b>0: No clock fault detected</b><br>1: Clock fault detected                         |
| 3   | PVDD OV       | R    | 0     | <b>0: No PVDD overvoltage fault detected</b><br>1: PVDD overvoltage fault detected   |
| 2   | VBAT OV       | R    | 0     | <b>0: No VBAT overvoltage fault detected</b><br>1: VBAT overvoltage fault detected   |
| 1   | PVDD UV       | R    | 0     | <b>0: No PVDD undervoltage fault detected</b><br>1: PVDD undervoltage fault detected |

**Table 24. Global Faults 1 Field Descriptions (continued)**

| Bit | Field   | Type | Reset | Description  |
|-----|---------|------|-------|--|
| 0   | VBAT UV | R    | 0     | <b>0: No VBAT undervoltage fault detected</b><br>1: VBAT undervoltage fault detected |

**9.6.16 Global Faults 2 Register (address = 0x12) [default = 0x00]**

The Global Faults 2 register is shown in [Figure 62](#) and described in [Table 25](#).

**Figure 62. Global Faults 2 Register**

| 7        | 6 | 5 | 4    | 3        | 2        | 1        | 0        |
|----------|---|---|------|----------|----------|----------|----------|
| RESERVED |   |   | OTSD | CH1 OTSD | CH2 OTSD | CH3 OTSD | CH4 OTSD |
|          |   |   | R-0  | R-0      | R-0      | R-0      | R-0      |

**Table 25. Global Faults 2 Field Descriptions**

| Bit | Field    | Type | Reset | Description  |
|-----|----------|------|-------|--|
| 7–5 | RESERVED |      |       | <b>0</b>   |
| 4   | OTSD     | R    | 0     | <b>0: No global overtemperature shutdown</b><br>1: Global overtemperature shutdown |
| 3   | CH1 OTSD | R    | 0     | <b>0: No overtemperature shutdown on Ch1</b><br>1: Overtemperature shutdown on Ch1 |
| 2   | CH2 OTSD | R    | 0     | <b>0: No overtemperature shutdown on Ch2</b><br>1: Overtemperature shutdown on Ch2 |
| 1   | CH3 OTSD | R    | 0     | <b>0: No overtemperature shutdown on Ch3</b><br>1: Overtemperature shutdown on Ch3 |
| 0   | CH4 OTSD | R    | 0     | <b>0: No overtemperature shutdown on Ch4</b><br>1: Overtemperature shutdown on Ch4 |

**9.6.17 Warnings Register (address = 0x13) [default = 0x20]**

The Warnings register is shown in [Figure 63](#) and described in [Table 26](#).

**Figure 63. Warnings Register**

| 7        | 6 | 5       | 4   | 3       | 2       | 1       | 0       |
|----------|---|---------|-----|---------|---------|---------|---------|
| RESERVED |   | VDD POR | OTW | OTW CH1 | OTW CH2 | OTW CH3 | OTW CH4 |
|          |   | R-0     | R-0 | R-0     | R-0     | R-0     | R-0     |

**Table 26. Warnings Field Descriptions**

| Bit  | Field    | Type | Reset | Description  |
|------|----------|------|-------|--|
| 7 -6 | RESERVED |      | 00    | <b>0</b>   |
| 5    | VDD POR  | R    | 0     | <b>0: No VDD POR has occurred</b><br><b>1 VDD POR occurred</b>                               |
| 4    | OTW      | R    | 0     | <b>0: No global overtemperature warning</b><br>1: Global overtemperature warning             |
| 3    | OTW CH1  | R    | 0     | <b>0: No overtemperature warning on channel 1</b><br>1: Overtemperature warning on channel 1 |
| 2    | OTW CH2  | R    | 0     | <b>0: No overtemperature warning on channel 2</b><br>1: Overtemperature warning on channel 2 |

**Table 26. Warnings Field Descriptions (continued)**

| Bit | Field   | Type | Reset | Description  |
|-----|---------|------|-------|--|
| 1   | OTW CH3 | R    | 0     | <b>0: No overtemperature warning on channel 3</b><br>1: Overtemperature warning on channel 3 |
| 0   | OTW CH4 | R    | 0     | <b>0: No overtemperature warning on channel 4</b><br>1: Overtemperature warning on channel 4 |

### 9.6.18 Pin Control Register (address = 0x14) [default = 0x00]

The Pin Control register is shown in [Figure 64](#) and described in [Table 27](#).

**Figure 64. Pin Control Register**

| 7       | 6         | 5       | 4       | 3       | 2           | 1         | 0        |
|---------|-----------|---------|---------|---------|-------------|-----------|----------|
| MASK OC | MASK OTSD | MASK UV | MASK OV | MASK DC | MASK ILIMIT | MASK CLIP | MASK OTW |
| R/W-0   | R/W-0     | R/W-0   | R/W-0   | R/W-0   | R/W-0       | R/W-0     | R/W-0    |

**Table 27. Pin Control Field Descriptions**

| Bit | Field       | Type | Reset | Description   |
|-----|-------------|------|-------|---|
| 7   | MASK OC     | R/W  | 0     | <b>0: Report overcurrent faults on the <math>\overline{\text{FAULT}}</math> pin</b><br>1: Do not report overcurrent faults on the $\overline{\text{FAULT}}$ Pin           |
| 6   | MASK OTSD   | R/W  | 0     | <b>0: Report overtemperature faults on the <math>\overline{\text{FAULT}}</math> pin</b><br>1: Do not report overtemperature faults on the $\overline{\text{FAULT}}$ pin   |
| 5   | MASK UV     | R/W  | 0     | <b>0: Report undervoltage faults on the <math>\overline{\text{FAULT}}</math> pin</b><br>1: Do not report undervoltage faults on the $\overline{\text{FAULT}}$ pin         |
| 4   | MASK OV     | R/W  | 0     | <b>0: Report overvoltage faults on the <math>\overline{\text{FAULT}}</math> pin</b><br>1: Do not report overvoltage faults on the $\overline{\text{FAULT}}$ pin           |
| 3   | MASK DC     | R/W  | 0     | <b>0: Report DC faults on the <math>\overline{\text{FAULT}}</math> pin</b><br>1: Do not report DC faults on the $\overline{\text{FAULT}}$ pin                             |
| 2   | MASK ILIMIT | R/W  | 0     | <b>0: Report Ilimit on the <math>\overline{\text{FAULT}}</math> pin</b><br>1: Do not report Ilimit on the $\overline{\text{FAULT}}$ pin                                   |
| 1   | MASK CLIP   | R/W  | 0     | <b>0: Report clipping on the <math>\overline{\text{WARN}}</math> pin</b><br>1: Do not report clipping on the $\overline{\text{WARN}}$ pin                                 |
| 0   | MASK OTW    | R/W  | 0     | <b>0: Report overtemperature warnings on the <math>\overline{\text{WARN}}</math> pin</b><br>1: Do not report overtemperature warnings on the $\overline{\text{WARN}}$ pin |

### 9.6.19 AC Load Diagnostic Control 1 Register (address = 0x15) [default = 0x00]

The AC Load Diagnostic Control 1 register is shown in [Figure 65](#) and described in [Table 28](#).

**Figure 65. AC Load Diagnostic Control 1 Register**

| 7          | 6        | 5          | 4        | 3          | 2          | 1          | 0          |
|------------|----------|------------|----------|------------|------------|------------|------------|
| CH1/2 GAIN | RESERVED | CH3/4 GAIN | RESERVED | CH1 ENABLE | CH2 ENABLE | CH3 ENABLE | CH4 ENABLE |
| R/W-0      | R/W-0    | R/W-0      | R/W-0    | R/W-0      | R/W-0      | R/W-0      | R/W-0      |

**Table 28. AC Load Diagnostic Control 1 Field Descriptions**

| Bit | Field                  | Type | Reset | Description                   |
|-----|------------------------|------|-------|-------------------------------|
| 7   | CH1, CH2, PBTL12: GAIN | R/W  | 0     | <b>0: Gain 1</b><br>1: Gain 4 |
| 6   | RESERVED               | R/W  | 0     | 0                             |

**Table 28. AC Load Diagnostic Control 1 Field Descriptions (continued)**

| Bit | Field                  | Type | Reset | Description   |
|-----|------------------------|------|-------|---|
| 5   | CH3, CH4, PBTL34: GAIN | R/W  | 0     | <b>0: Gain 1</b><br>1: Gain 4                                 |
| 4   | RESERVED               | R/W  | 0     | 0   |
| 3   | CH1 ENABLE             | R/W  | 0     | <b>0: AC diagnostics disabled</b><br>1: Enable AC diagnostics |
| 2   | CH2 ENABLE             | R/W  | 0     | <b>0: AC diagnostics disabled</b><br>1: Enable AC diagnostics |
| 1   | CH3 ENABLE             | R/W  | 0     | <b>0: AC diagnostics disabled</b><br>1: Enable AC diagnostics |
| 0   | CH4 ENABLE             | R/W  | 0     | <b>0: AC diagnostics disabled</b><br>1: Enable AC diagnostics |

**9.6.20 AC Load Diagnostic Control 2 Register (address = 0x16) [default = 0x00]**

The AC Load Diagnostic Control 2 register is shown in [Figure 66](#) and described in [Table 29](#).

**Figure 66. AC Load Diagnostic Control 2 Register**

| 7                     | 6        | 5     | 4         | 3          | 2     | 1        | 0     |
|-----------------------|----------|-------|-----------|------------|-------|----------|-------|
| AC_DIAGS_LO<br>OPBACK | RESERVED |       | AC TIMING | AC CURRENT |       | RESERVED |       |
| R/W-0                 | R/W-0    | R/W-0 | R/W-0     | R/W-0      | R/W-0 | R/W-0    | R/W-0 |

**Table 29. AC Load Diagnostic Control 2 Field Descriptions**

| Bit | Field             | Type | Reset | Description  |
|-----|-------------------|------|-------|--|
| 7   | AC_DIAGS_LOOPBACK | R/W  | 0     | <b>0: Disable AC Diag loopback</b><br>1: Enable AC Diag loopback |
| 6-5 | RESERVED          | R/W  | 00    | <b>00</b>  |
| 4   | AC TIMING         | R/W  | 0     | <b>0: 32 Cycles</b><br>1: 64 Cycles                              |
| 3-2 | AC CURRENT        | R/W  | 00    | <b>00: 10mA</b><br>01: 19 mA<br>10: RESERVED<br>11: RESERVED     |
| 1-0 | RESERVED          | R/W  | 00    | <b>00</b>  |

**9.6.21 AC Load Diagnostic Impedance Report Ch1 through CH4 Registers (address = 0x17–0x1A) [default = 0x00]**

The AC Load Diagnostic Report Ch1 through CH4 registers are shown in [Figure 67](#) and described in [Table 30](#).

**Figure 67. AC Load Diagnostic Impedance Report Chx Register**

| 7             | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------|---|---|---|---|---|---|---|
| CHx IMPEDANCE |   |   |   |   |   |   |   |
| R-00          |   |   |   |   |   |   |   |

**Table 30. Chx AC LDG Impedance Report Field Descriptions**

| Bit | Field          | Type | Reset | Description  |
|-----|----------------|------|-------|--|
| 7–0 | CH x IMPEDANCE | R    | 00    | 8-bit AC-load diagnostic report for each channel with a step size of 0.2496 $\Omega$ /bit (control by register 0x15 and register 0x16)<br><b>0x00: 0 <math>\Omega</math></b><br>0x01: 0.2496 $\Omega$<br>...<br>0xFF: 63.65 $\Omega$ |

**9.6.22 AC Load Diagnostic Phase Report High Register (address = 0x1B) [default = 0x00]**

The AC Load Diagnostic Phase High value registers are shown in [Figure 68](#) and described in [Table 31](#).

**Figure 68. AC Load Diagnostic (LDG) Phase High Report Register**

| 7             | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------|---|---|---|---|---|---|---|
| AC Phase High |   |   |   |   |   |   |   |
| R-00          |   |   |   |   |   |   |   |

**Table 31. AC LDG Phase High Report Field Descriptions**

| Bit | Field         | Type | Reset | Description |
|-----|---------------|------|-------|-------------|
| 7–0 | AC Phase High | R    | 00    | Bit 15:8    |

**9.6.23 AC Load Diagnostic Phase Report Low Register (address = 0x1C) [default = 0x00]**

The AC Load Diagnostic Phase Low value registers are shown in [Figure 69](#) and described in [Table 32](#).

**Figure 69. AC Load Diagnostic (LDG) Phase Low Report Register**

| 7            | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------------|---|---|---|---|---|---|---|
| AC Phase Low |   |   |   |   |   |   |   |
| R-00         |   |   |   |   |   |   |   |

**Table 32. AC LDG Phase Low Report Field Descriptions**

| Bit | Field        | Type | Reset | Description |
|-----|--------------|------|-------|-------------|
| 7–0 | AC Phase Low | R    | 00    | Bit 7:0     |

**9.6.24 AC Load Diagnostic STI Report High Register (address = 0x1D) [default = 0x00]**

The AC Load Diagnostic STI High value registers are shown in [Figure 70](#) and described in [Table 33](#).

**Figure 70. AC Load Diagnostic (LDG) STI High Report Register**

| 7           | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------|---|---|---|---|---|---|---|
| AC STI High |   |   |   |   |   |   |   |
| R-00        |   |   |   |   |   |   |   |

**Table 33. AC LDG STI High Report Field Descriptions**

| Bit | Field       | Type | Reset | Description |
|-----|-------------|------|-------|-------------|
| 7–0 | AC STI High | R    | 00    | Bit 15:8    |

**9.6.25 AC Load Diagnostic STI Report Low Register (address = 0x1E) [default = 0x00]**

The AC Load Diagnostic STI Low value registers are shown in [Figure 71](#) and described in [Table 34](#).

**Figure 71. AC Load Diagnostic (LDG) STI Low Report Register**

|            |   |   |   |   |   |   |   |
|------------|---|---|---|---|---|---|---|
| 7          | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| AC STI Low |   |   |   |   |   |   |   |
| R-00       |   |   |   |   |   |   |   |

**Table 34. Chx AC LDG STI Low Report Field Descriptions**

| Bit | Field      | Type | Reset | Description |
|-----|------------|------|-------|-------------|
| 7–0 | AC STI Low | R    | 00    | Bit 7:0     |

**9.6.26 Miscellaneous Control 3 Register (address = 0x21) [default = 0x00]**

The Miscellaneous Control 3 register is shown in [Figure 72](#) and described in [Table 35](#).

**Figure 72. Miscellaneous Control 3 Register**

|             |             |                     |          |                    |          |   |   |
|-------------|-------------|---------------------|----------|--------------------|----------|---|---|
| 7           | 6           | 5                   | 4        | 3                  | 2        | 1 | 0 |
| CLEAR FAULT | PBTL_CH_SEL | MASK ILIMIT WARNING | RESERVED | OTSD AUTO RECOVERY | RESERVED |   |   |
| R/W-0       | R/W-0       | R/W-0               | R/W-0    | R/W-0              |          |   |   |

**Table 35. Misc Control 3 Field Descriptions**

| Bit | Field               | Type | Reset | Description   |
|-----|---------------------|------|-------|---|
| 7   | CLEAR FAULT         | R/W  | 0     | <b>0: Normal operation</b><br>1: Clear fault  |
| 6   | PBTL_CH_SEL         | R/W  | 0     | <b>0: PBTL normal signal source</b><br>1: PBTL flip signal source   |
| 5   | MASK ILIMIT WARNING | R/W  | 0     | <b>0: Report ILIMIT on the <math>\overline{\text{WARN}}</math> pin</b><br>1: Do not report ILIMIT on the $\overline{\text{WARN}}$ pin |
| 4   | RESERVED            | R/W  | 0     |   |
| 3   | OTSD AUTO RECOVERY  | R/W  | 0     | <b>0: OTSD is latched</b><br>1: OTSD is autorecovery  |
| 2–0 | RESERVED            |      | 0     | <b>0</b>  |

**9.6.27 Clip Control Register (address = 0x22) [default = 0x01]**

The Clip Detect register is shown in and described in [Table 36](#). To ensure the Clip Detect Warning is operating according to the expectation, the related bit values in the [Clip Window Register \(address = 0x23\) \[default = 0x14\]](#) and [Clip Warning Register \(address = 0x24\) \[default = 0x00\]](#) must be set accordingly.

**Figure 73. Clip Control Register**

|          |   |   |   |   |   |   |            |
|----------|---|---|---|---|---|---|------------|
| 7        | 6 | 5 | 4 | 3 | 2 | 1 | 0          |
| RESERVED |   |   |   |   |   |   | CLIPDET_EN |
|          |   |   |   |   |   |   | R/W-1      |

**Table 36. Clip Control Field Descriptions**

| Bit | Field      | Type | Reset | Description   |
|-----|------------|------|-------|---|
| 0   | CLIPDET_EN | R/W  | 1     | <b>0: Clip detect disable</b><br><b>1: Clip Detect Enable</b> |

### 9.6.28 Clip Window Register (address = 0x23) [default = 0x14]

The Clip Window register is shown in [Figure 74](#) and described in [Table 37](#). The register value represents the minimum number of 100% duty-cycle PWM cycles in hexadecimal notation before Clip Detect is reported.

**Figure 74. Clip Window Register**

|                      |   |   |   |   |   |   |   |
|----------------------|---|---|---|---|---|---|---|
| 7                    | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| CLIP_WINDOW_SEL[7:1] |   |   |   |   |   |   |   |
| R/W-00010100         |   |   |   |   |   |   |   |

**Table 37. Clip Window Field Descriptions**

| Bit | Field                | Type | Reset    | Description  |
|-----|----------------------|------|----------|--|
| 7-0 | CLIP_WINDOW_SEL[7:1] | R/W  | 00010100 | <b>00010100: 20 100% duty-cycle PWM cycles before Clip Detect is triggered</b> |

### 9.6.29 Clip Warning Register (address = 0x24) [default = 0x00]

The Clip Warning register is shown in [Figure 75](#) and described in [Table 38](#).

**Figure 75. Clip Warning Register**

|          |   |   |   |          |          |          |          |
|----------|---|---|---|----------|----------|----------|----------|
| 7        | 6 | 5 | 4 | 3        | 2        | 1        | 0        |
| RESERVED |   |   |   | CH4_CLIP | CH3_CLIP | CH2_CLIP | CH1_CLIP |
|          |   |   |   | R-0      | R-0      | R-0      | R-0      |

**Table 38. Clip Warning Field Descriptions**

| Bit | Field    | Type | Reset | Description                                |
|-----|----------|------|-------|--|
| 7-4 | RESERVED |      | 0     | RESERVED                                   |
| 3   | CH4_CLIP | R    | 0     | <b>0: No Clip Detect</b><br>1: Clip Detect |
| 2   | CH3_CLIP | R    | 0     | <b>0: No Clip Detect</b><br>1: Clip Detect |
| 1   | CH2_CLIP | R    | 0     | <b>0: No Clip Detect</b><br>1: Clip Detect |
| 0   | CH1_CLIP | R    | 0     | <b>0: No Clip Detect</b><br>1: Clip Detect |

### 9.6.30 ILIMIT Status Register (address = 0x25) [default = 0x00]

The ILIMIT Status register is shown in [Figure 76](#) and described in [Table 39](#).

**Figure 76. ILIMIT Status Register**

|          |   |   |   |          |          |                     |                     |
|----------|---|---|---|----------|----------|---------------------|---------------------|
| 7        | 6 | 5 | 4 | 3        | 2        | 1                   | 0                   |
| RESERVED |   |   |   | RESERVED | RESERVED | CH2_ILIMIT_W<br>ARN | CH1_ILIMIT_W<br>ARN |
|          |   |   |   | R-0      | R-0      | R-0                 | R-0                 |

**Table 39. ILIMIT Status Field Descriptions**

| Bit | Field           | Type | Reset | Description                              |
|-----|-----------------|------|-------|--|
| 7-4 | RESERVED        |      | 0     | RESERVED                                 |
| 3   | CH4_ILIMIT_WARN | R    | 0     | <b>0: No ILIMIT</b><br>1: ILIMIT Warning |
| 2   | CH3_ILIMIT_WARN | R    | 0     | <b>0: No ILIMIT</b><br>1: ILIMIT Warning |

**Table 39. ILIMIT Status Field Descriptions (continued)**

| Bit | Field           | Type | Reset | Description                              |
|-----|-----------------|------|-------|--|
| 1   | CH2_ILIMIT_WARN | R    | 0     | <b>0: No ILIMIT</b><br>1: ILIMIT Warning |
| 0   | CH1_ILIMIT_WARN | R    | 0     | <b>0: No ILIMIT</b><br>1: ILIMIT Warning |

**9.6.31 Miscellaneous Control 4 Register (address = 0x26) [default = 0x40]**

 The Miscellaneous Control 4 register is shown in and described in [Table 40](#).

**Figure 77. Miscellaneous Control 4 Register**

| 7         | 6 | 5 | 4 | 3               | 2 | 1 | 0 |
|-----------|---|---|---|-----------------|---|---|---|
| RESERVED  |   |   |   | HPF_CORNER[2:0] |   |   |   |
| R/W-01000 |   |   |   | R/W-000         |   |   |   |

**Table 40. Misc Control 4 Field Descriptions**

| Bit | Field           | Type | Reset | Description  |
|-----|-----------------|------|-------|--|
| 7-3 | RESERVED        | R/W  | 01000 | <b>01000: DEFAULT</b>  |
| 2-0 | HPF_CORNER[2:0] | R/W  | 000   | <b>000: 3.7 Hz</b><br>001: 7.4 Hz<br>010: 15 Hz<br>011: 30 Hz<br>100: 59 Hz<br>101: 118 Hz<br>110: 235 Hz<br>111: 463 Hz |



## 10 Application and Implementation

### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 10.1 Application Information

The TAS6424M-Q1 is a four-channel class-D digital-input audio-amplifier design for use in automotive head units and external amplifier modules. The TAS6424M-Q1 incorporates the necessary functionality to perform in demanding OEM applications.

#### 10.1.1 AM-Radio Band Avoidance

AM-radio frequency interference can be avoided by setting the switching frequency of the device above the AM band. The switching frequency options available are  $38 f_s$ ,  $44 f_s$ , and  $48 f_s$ . If the switch frequency cannot be set above the AM band, then use the two options of  $8 f_s$  and  $10 f_s$ . These options should be changed to avoid AM active channels.

#### 10.1.2 Parallel BTL Operation (PBTL)

The device can drive more current-parallel BTL channels on the load side of the LC output filter. For parallel operation, the parallel BTL mode, PBTL, must be used and the paralleled channels must have the same state in the state control register. If the two states are not aligned the device reports a fault condition.

To set the requested channels to PBTL mode the device must be in standby mode for the commands to take effect.

A load diagnostic is supported for PBTL channels. Paralleling on the device side of the LC output filter is not supported.

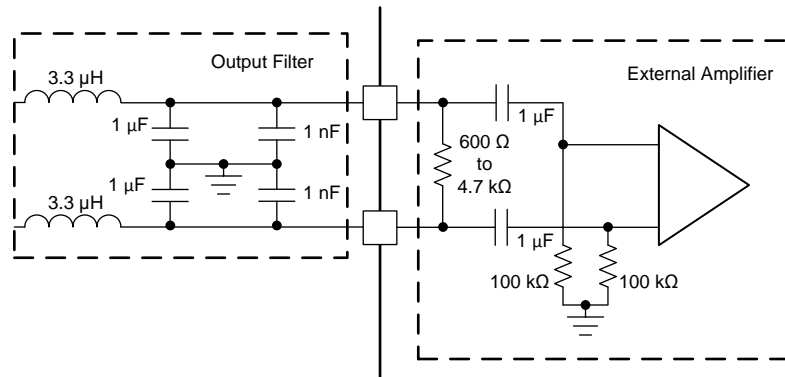
#### 10.1.3 Demodulation Filter Design

The amplifier outputs are driven by high-current LDMOS transistors in an H-bridge configuration. These transistors are either fully off or fully on. The result is a square-wave output signal with a duty cycle that is proportional to the amplitude of the audio signal. An LC demodulation filter is used to recover the audio signal. The filter attenuates the high-frequency components of the output signals that are out of the audio band. The design of the demodulation filter significantly affects the audio performance of the power amplifier. Therefore, to meet the system THD+N requirements, the selection of the inductors used in the output filter should be carefully considered.

#### 10.1.4 Line Driver Applications

In many automotive audio applications, the same head unit must drive either a speaker (with several ohms of impedance) or an external amplifier input (with several kilohms of impedance). The design is capable of supporting both applications and has special line-drive gain and diagnostics. Coupled with the high switching frequency, the device is well suited for this type of application. Set the desired channel in line driver mode through I<sup>2</sup>C register 0x00, the externally connected amplifier must have a differential impedance from 600  $\Omega$  to 4.7 k $\Omega$  for the DC line diagnostic to detect the connected external amplifier. [Figure 78](#) shows the recommended external amplifier input configuration.

**Application Information (continued)**



**Figure 78. External Amplifier Input Configuration for Line Driver**

## 10.2 Typical Applications

### 10.2.1 BTL Application

Figure 79 shows the schematic of a typical 4-channel solution for a head-unit application.

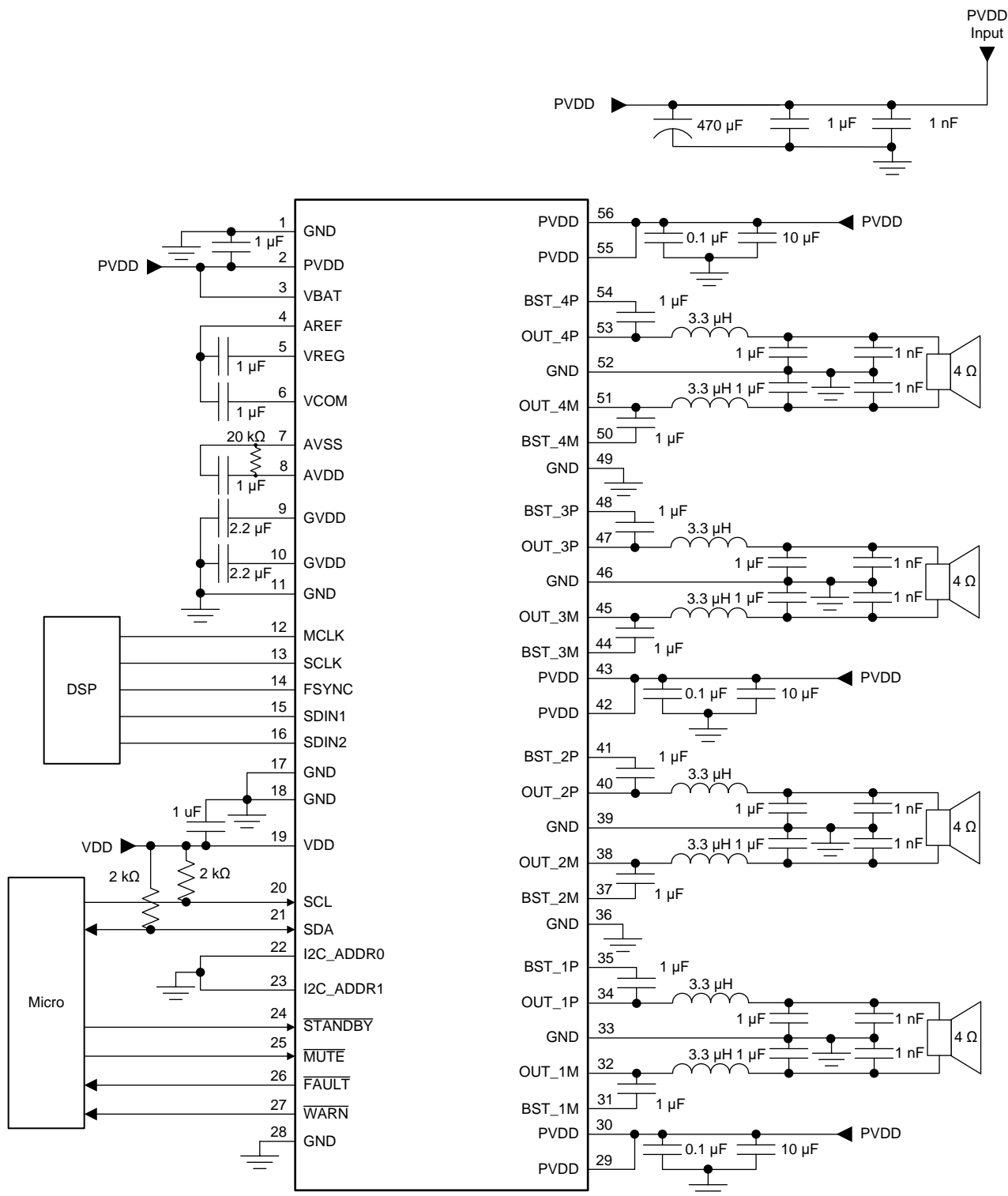


Figure 79. TAS6424M-Q1 Typical 4-Channel BTL Application Schematic

## Typical Applications (continued)

### 10.2.1.1 Design Requirements

Use the following requirements for this design:

- This head-unit example is focused on the smallest solution size for 4 × 50 W output power into 2 Ω with a battery supply of 14.4 V.
- The switching frequency is set above the AM-band with 44 times the input sample rate of 48 kHz which results in a frequency of 2.11 MHz.
- The selection of a 2.11 MHz switch frequency enables the use of a small output inductor value of 3.3 μH which leads to a very small solution size.

### 10.2.1.2 Communication

All communications to the TAS6424M-Q1 are through the I<sup>2</sup>C protocol. A system controller can communicate with the device through the SDA pins and SCL pins. The TAS6424M-Q1 is an I<sup>2</sup>C slave device and requires a master. The device cannot generate an I<sup>2</sup>C clock or initiate a transaction. The maximum clock speed accepted by the device is 400 kHz. If multiple TAS6424M-Q1 devices are on the same I<sup>2</sup>C bus, the I<sup>2</sup>C address must be different for each device. Up to four TAS6424M-Q1 devices can be on the same I<sup>2</sup>C bus.

The I<sup>2</sup>C bus is shared internally.

---

#### NOTE

Complete any internal operations, such as load diagnostics, before reading the registers for the results.

---

### 10.2.1.3 Detailed Design Procedure

#### 10.2.1.3.1 Hardware Design

Use the following procedure for the hardware design:

- Determine the input format. The input format can be either I<sup>2</sup>S or TDM mode. The mode determines the correct pin connections and the I<sup>2</sup>C register settings.
- Determine the power output that is required into the load. The power requirement determines the required power-supply voltage and current. The output reconstruction-filter components that are required are also driven by the output power.
- With the requirements, adjust the typical application schematic in [Figure 79](#) for the input connections.

#### 10.2.1.3.2 Digital Input and the Serial Audio Port

The TAS6424M-Q1 device supports four different digital input formats which are: I<sup>2</sup>S, Right Justified, Left Justified, and TDM mode. Depending on the format, the device can support 16, 18, 20, 24, and 32 bit data. The supported frequencies are 96 kHz, 48 kHz, and 44.1 kHz. Please see [Table 13](#) for the I<sup>2</sup>C register, SAP Control, for the complete matrix to set up the serial audio port.

---

#### NOTE

Bits 3, 4, and 5 in this register are ignored in all input formats except for TDM. Setting up all the control registers to the system requirements should be done before the device is placed in Mute mode or Play mode. After the registers are setup, use bit 7 in register 0x21 to clear any faults. Then read the fault registers to make sure no faults are present. When no faults are present, use register 0x04 to place the device properly into play mode.

---

#### 10.2.1.3.3 Bootstrap Capacitors

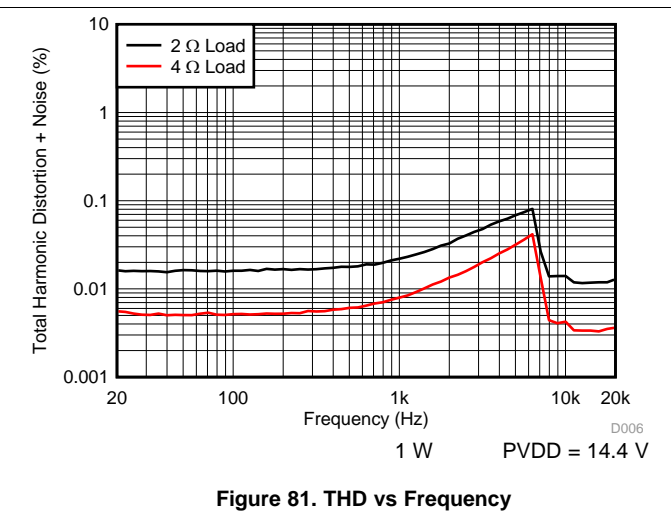
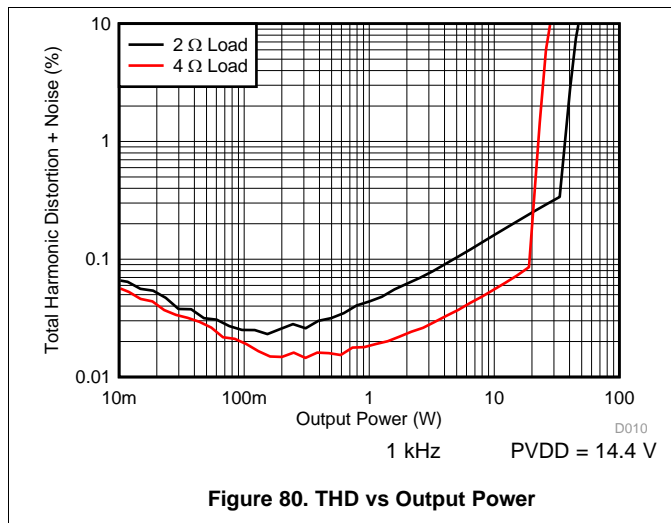
The bootstrap capacitors provide the gate-drive voltage of the upper N-channel FET. These capacitors must be sized appropriately for the system specification. A special condition can occur where the bootstrap may sag if the capacitor is not sized accordingly. The special condition is just below clipping where the PWM is slightly less than 100% duty cycle with sustained low-frequency signals. Changing the bootstrap capacitor value to 2.2 μF for driving subwoofers that require frequencies below 30 Hz may be necessary.

## Typical Applications (continued)

### 10.2.1.3.4 Output Reconstruction Filter

The output FETs drive the amplifier outputs in an H-Bridge configuration. These transistors are either fully off or fully on. The result is a square-wave output signal with a duty cycle that is proportional to the amplitude of the audio signal. The amplifier outputs require a reconstruction filter that comprises a series inductor and a capacitor to ground on each output, generally called an LC filter. The LC filter attenuates the PWM frequency and reduces electromagnetic emissions, allowing the reconstructed audio signal to pass to the speakers. refer to the [Class-D LC Filter Design](#), (SLOA119) for a detailed description of proper component description and design of the LC filter based upon the specified load and frequency response. The recommended low-pass cutoff frequency of the LC filter is dependent on the selected switching frequency. The low-pass cutoff frequency can be as high as 100 kHz for a PWM frequency of 2.1 MHz. At a PWM frequency of 384 kHz the low-pass cutoff frequency should be less than 40 kHz. Certain specifications must be understood for a proper inductor. The inductance value is given at zero current, but the TAS6424M-Q1 device will have current. Use the inductance versus current curve for the inductor to make sure the inductance does not drop below 1  $\mu\text{H}$  (for  $f_{\text{SW}} = 2.1 \text{ MHz}$ ) at the maximum current provided by the system design. The DCR of the inductor directly affects the output power of the system design. The lower the DCR, the more power is provided to the speakers. The typical inductor DCR for a 4  $\Omega$  system is 40 to 50 m $\Omega$  and for a 2  $\Omega$  system is 20 to 25 m $\Omega$ .

### 10.2.1.4 Application Curves



## Typical Applications (continued)

### 10.2.2 PBTL Application

Figure 82 shows a schematic of a typical 2-channel solution for a head unit or external amplifier application where high power into  $2\ \Omega$  is required.

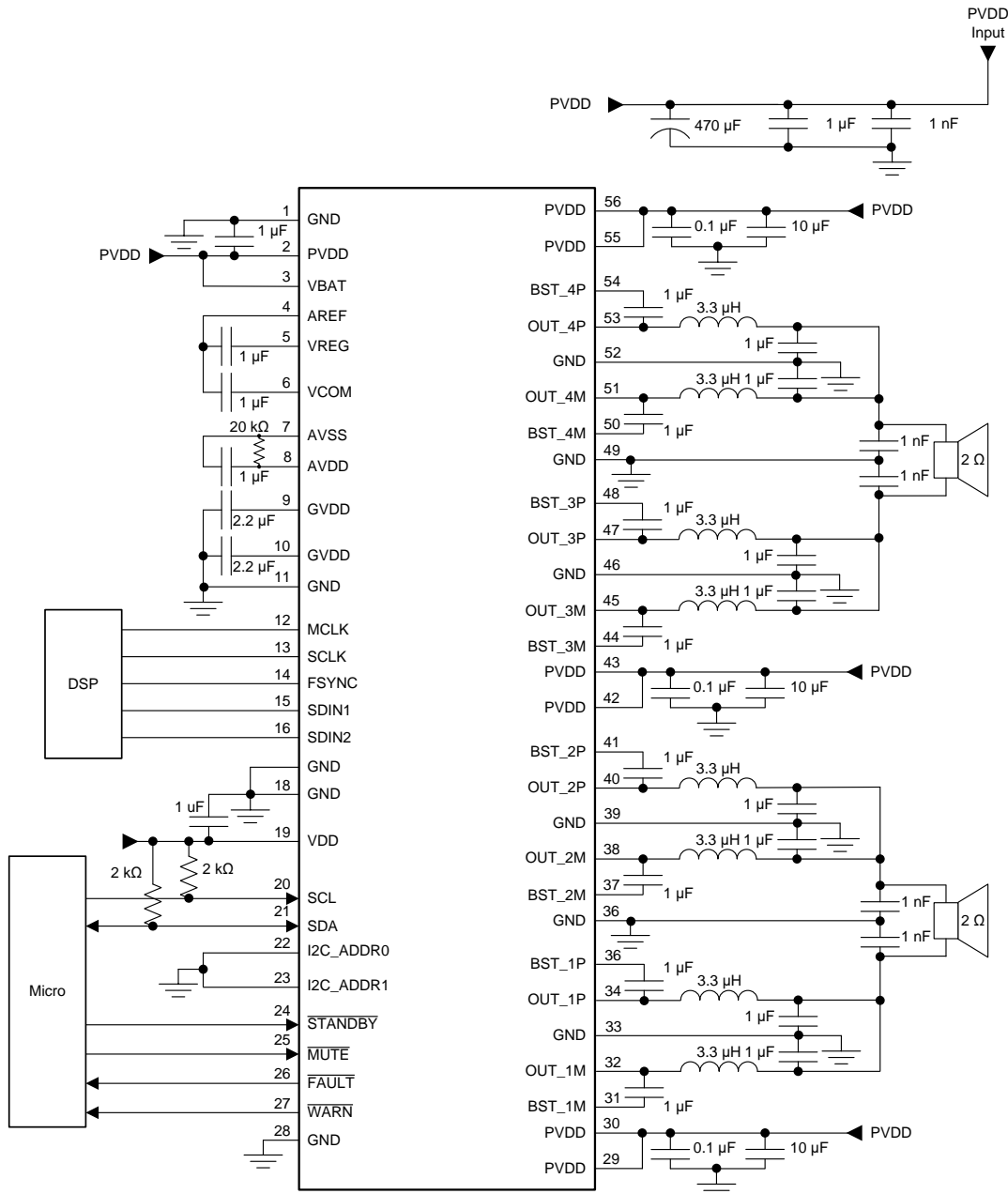


Figure 82. TAS6424M-Q1 Typical 2-Channel PBTL Application Schematic

To operate in PBTL mode the output stage must be paralleled according to the schematic in Figure 82. The device can operate in a mix of PBTL and BTL mode. This application can be set up for 3-channels, with one channel in PBTL mode and two channels in BTL mode. The device does not support a parallel configuration of all four channels for a one channel amplifier.

## Typical Applications (continued)

### 10.2.2.1 Design Requirements

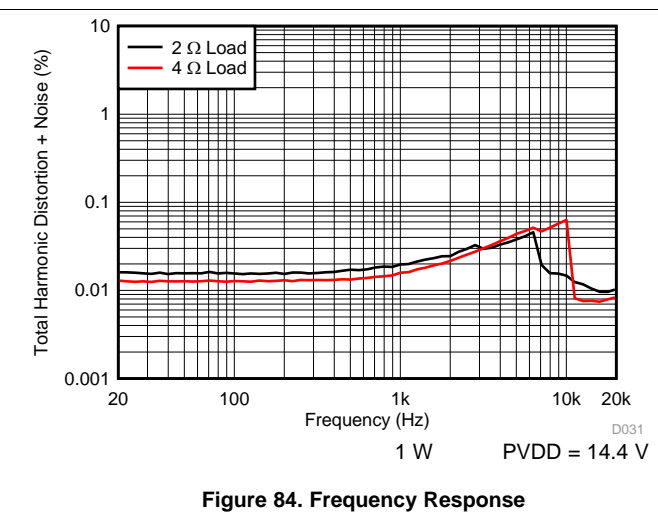
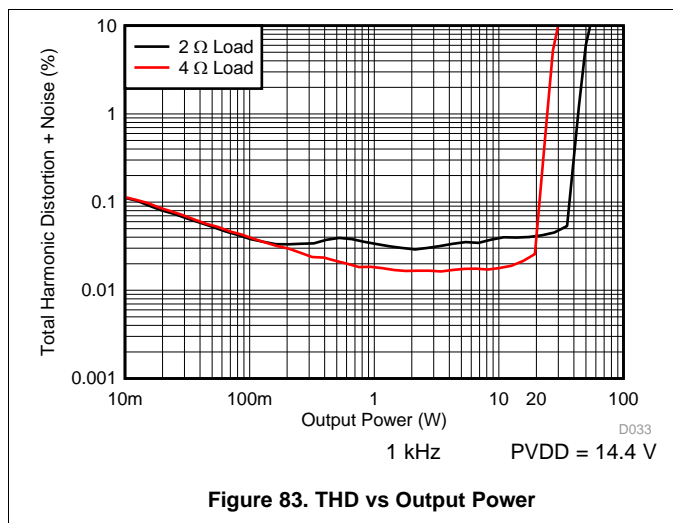
Use the following requirements for this design:

- This head-unit example is focused on the smallest solution size for 2 x 50 W output power into 2 Ω with a battery supply of 14.4 V.
- The switching frequency is set above the AM-band with 44 times the input sample rate of 48 kHz which results in a frequency of 2.11 MHz.
- The selection of a 2.11 MHz switch frequency enables the use of a small output inductor value of 3.3 μH which leads to a very small solution size.

#### 10.2.2.1.1 Detailed Design Procedure

As a starting point, refer to the [Detailed Design Procedure](#) section for the BTL application. PBTL mode requires schematic changes in the output stage as shown in [Figure 82](#). The other required changes include setting up the I<sup>2</sup>C registers correctly (see [Table 13](#)) and selecting which frame or channel to use on each output. Bit 6 in register 0x21 controls the frame selection.

### 10.2.2.2 Application Curves



## 11 Power Supply Recommendations

The TAS6424M-Q1 requires three power supplies. The PVDD supply is the high-current supply in the recommended supply range. The VBAT supply is lower current supply that must be in the recommended supply range. The PVDD and VBAT pins can be connected to the same supply if the recommended supply range for VBAT is maintained. The VDD supply is the 3.3 Vdc logic supply and must be maintained in the tolerance as shown in the [Recommended Operating Conditions](#) table.

## 12 Layout

### 12.1 Layout Guidelines

The pinout of the TAS6424M-Q1 was selected to provide flowthrough layout with all high-power connections on the right side, and all low-power signals and supply decoupling on the left side.

[Figure 85](#) shows the area for the components in the application example (see the [Typical Applications](#) section).

The TAS6424M-Q1 EVM uses a four-layer PCB. The copper thickness was selected as 70  $\mu\text{m}$  to optimize power loss.

The small value of the output filter provides a small size and, in this case, the low height of the inductor enables double-sided mounting.

The EVM PCB shown in [Figure 85](#) is the basis for the layout guidelines.

#### 12.1.1 Electrical Connection of Thermal pad and Heat Sink

For the DKQ package, the heat sink connected to the thermal pad of the device should be connected to GND. The heat slug must not be connected to any other electrical node.

#### 12.1.2 EMI Considerations

Automotive-level EMI performance depends on both careful integrated circuit design and good system-level design. Controlling sources of electromagnetic interference (EMI) was a major consideration in all aspects of the design. The design has minimal parasitic inductances because of the short leads on the package which reduces the EMI that results from current passing from the die to the system PCB. Each channel also operates at a different phase. The design also incorporates circuitry that optimizes output transitions that cause EMI.

For optimizing the EMI a solid ground layer plane is recommended, for a PCB design the fulfills the CISPR25 level 5 requirements, see the TAS6424M-Q1 EVM layout.

#### 12.1.3 General Guidelines

The EVM layout is optimized for low noise and EMC performance.

The TAS6424M-Q1 has an exposed thermal pad that is up, away from the PCB. The layout must consider an external heat sink.

Refer to [Figure 85](#) for the following guidelines:

- A ground plane, *A*, on the same side as the device pins helps reduce EMI by providing a very-low loop impedance for the high-frequency switching current.
- The decoupling capacitors on PVDD, *B*, are very close to the device with the ground return close to the ground pins.
- The ground connections for the capacitors in the LC filter, *C*, have a direct path back to the device and also the ground return for each channel is the shared. This direct path allows for improved common mode EMI rejection.
- The traces from the output pins to the inductors, *D*, should have the shortest trace possible to allow for the smallest loop of large switching currents.
- Heat-sink mounting screws, *E*, should be close to the device to keep the loop short from the package to ground.
- Many vias, *F*, stitching together the ground planes can create a shield to isolate the amplifier and power supply.



## 12.2 Layout Example

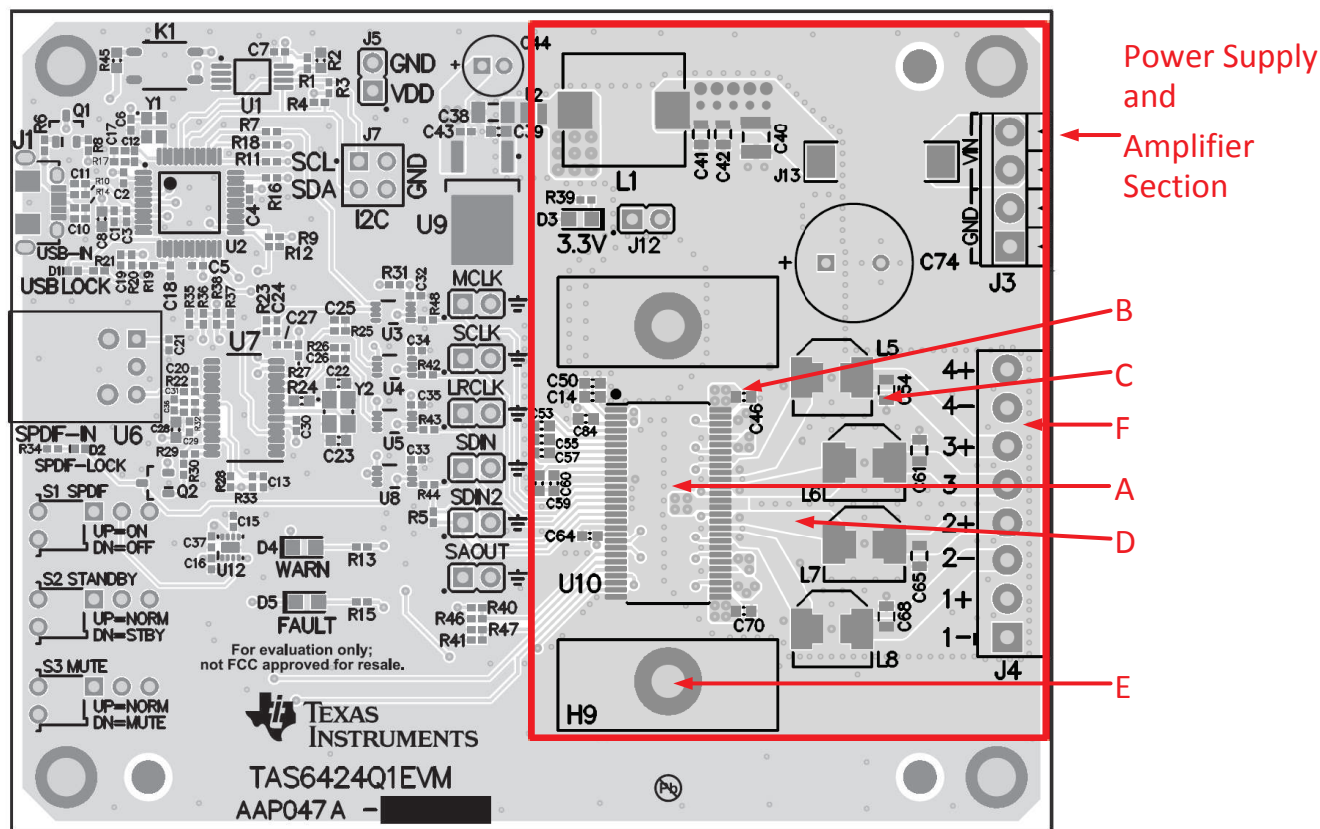


Figure 85. EVM Layout

## 12.3 Thermal Considerations

The thermally enhanced PowerPAD package has an exposed pad up for connection to a heat sink. The output power of any amplifier is determined by the thermal performance of the amplifier as well as limitations placed on it by the system, such as the ambient operating temperature. The heat sink absorbs heat from the TAS6424M-Q1 and transfers it to the air. With proper thermal management this process can reach equilibrium and heat can be continually transferred from the device. Heat sinks can be smaller than that of classic linear amplifier design because of the excellent efficiency of class-D amplifiers. This device is intended for use with a heat sink, therefore,  $R_{\theta JC}$  will be used as the thermal resistance from junction to the exposed metal package. This resistance will dominate the thermal management, so other thermal transfers will not be considered. The thermal resistance of  $R_{\theta JA}$  (junction to ambient) is required to determine the full thermal solution. The thermal resistance is comprised of the following components:

- $R_{\theta JC}$  of the TAS6424M-Q1
- Thermal resistance of the thermal interface material
- Thermal resistance of the heat sink

The thermal resistance of the thermal interface material can be determined from the manufacturer's value for the area thermal resistance (expressed in  $^{\circ}\text{Cmm}^2/\text{W}$ ) and the area of the exposed metal package. For example, a typical, white, thermal grease with a 0.0254 mm (0.001 inch) thick layer is approximately  $4.52^{\circ}\text{C mm}^2/\text{W}$ . The TAS6424M-Q1 in the DKQ package has an exposed area of  $47.6 \text{ mm}^2$ . By dividing the area thermal resistance by the exposed metal area determines the thermal resistance for the thermal grease. The thermal resistance of the thermal grease is  $0.094^{\circ}\text{C}/\text{W}$

Table 41 lists the modeling parameters for one device on a heat sink. The junction temperature is assumed to be  $115^{\circ}\text{C}$  while delivering an average power of 10 watts per channel into a  $4 \Omega$  load. The thermal-grease example previously described is used for the thermal interface material. Use Equation 1 to design the thermal system.

## Thermal Considerations (continued)

$$R_{\theta JA} = R_{\theta JC} + \text{thermal interface resistance} + \text{heat sink resistance} \tag{1}$$

**Table 41. Thermal Modeling**

| Description  | Value  |
|--|--|
| Ambient Temperature                                  | 25°C   |
| Average Power to load                                | 40W (4 x 10W)                                    |
| Power dissipation                                    | 8W (4 x 2W)                                      |
| Junction Temperature                                 | 115°C  |
| ΔT inside package                                    | 5.6°C (0.7°C/W x 8W)                             |
| ΔT through thermal interface material                | 0.75°C (0.094°C/W x 8W)                          |
| Required heat sink thermal resistance                | 10.45°C/W ((115°C – 25°C – 5.6°C – 0.75°C) / 8W) |
| System thermal resistance to ambient $R_{\theta JA}$ | 11.24°C/W  |

## 13 Device and Documentation Support

### 13.1 Documentation Support

#### 13.1.1 Related Documentation

For related documentation see the following:

- [PurePath™ Console 3](#) Graphical Development Suite
- [TAS6424-Q1 EVM User's Guide](#) (SLOU453)

### 13.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 13.3 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

**TI E2E™ Online Community** *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**E2E Audio Amplifier Forum** *TI's Engineer-to-Engineer (E2E) Community for Audio Amplifiers*. Created to foster collaboration among engineers. Ask questions and receive answers in real-time.

### 13.4 Trademarks

PurePath, E2E are trademarks of Texas Instruments. All other trademarks are the property of their respective owners.

### 13.5 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### 13.6 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

**PACKAGING INFORMATION**

| Orderable Device | Status<br>(1) | Package Type | Package<br>Drawing | Pins | Package<br>Qty | Eco Plan<br>(2) | Lead finish/<br>Ball material<br>(6) | MSL Peak Temp<br>(3) | Op Temp (°C) | Device Marking<br>(4/5) | Samples        |
|------------------|---------------|--------------|--------------------|------|----------------|-----------------|--------------------------------------|----------------------|--------------|-------------------------|----------------|
| TAS6424MQDKQRQ1  | ACTIVE        | HSSOP        | DKQ                | 56   | 1000           | RoHS & Green    | NIPDAU                               | Level-3-260C-168 HR  | -40 to 125   | TAS<br>6424M            | <b>Samples</b> |

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBsolete:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=100ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

**Important Information and Disclaimer:**The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**

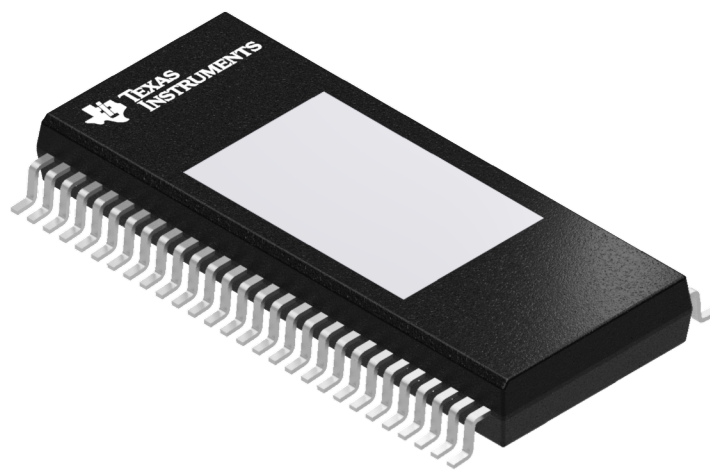

\*All dimensions are nominal

| Device          | Package Type | Package Drawing | Pins | SPQ  | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|-----------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| TAS6424MQDKQRQ1 | HSSOP        | DKQ             | 56   | 1000 | 330.0              | 32.4               | 11.35   | 18.67   | 3.1     | 16.0    | 32.0   | Q1            |
| TAS6424MQDKQRQ1 | HSSOP        | DKQ             | 56   | 1000 | 330.0              | 32.4               | 11.35   | 18.67   | 3.1     | 16.0    | 32.0   | Q1            |

**TAPE AND REEL BOX DIMENSIONS**

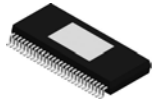

\*All dimensions are nominal

| Device          | Package Type | Package Drawing | Pins | SPQ  | Length (mm) | Width (mm) | Height (mm) |
|-----------------|--------------|-----------------|------|------|-------------|------------|-------------|
| TAS6424MQDKQRQ1 | HSSOP        | DKQ             | 56   | 1000 | 356.0       | 356.0      | 53.0        |
| TAS6424MQDKQRQ1 | HSSOP        | DKQ             | 56   | 1000 | 367.0       | 367.0      | 55.0        |



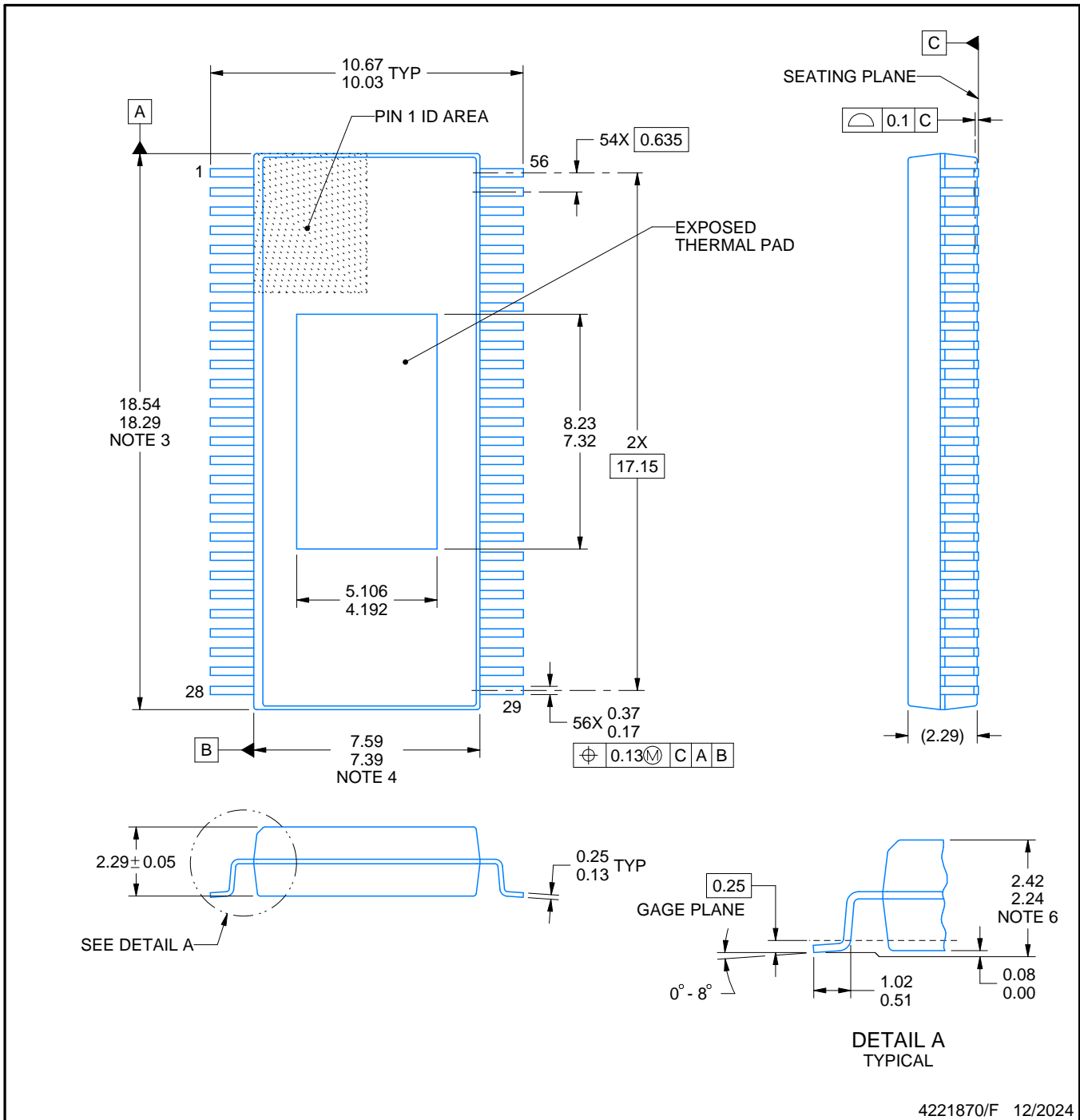
Images above are just a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

DKQ0056A



**PACKAGE OUTLINE**  
**PowerPAD™ HSSOP - 2.475 mm max height**

PLASTIC SMALL OUTLINE



4221870/F 12/2024

NOTES:

PowerPAD is a trademark of Texas Instruments.

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
5. The exposed thermal pad is designed to be attached to an external heatsink.
6. For clamped heatsink design, refer to overall package height above the seating plane as 2.33 +/- 0.09 and molded body thickness dimension.

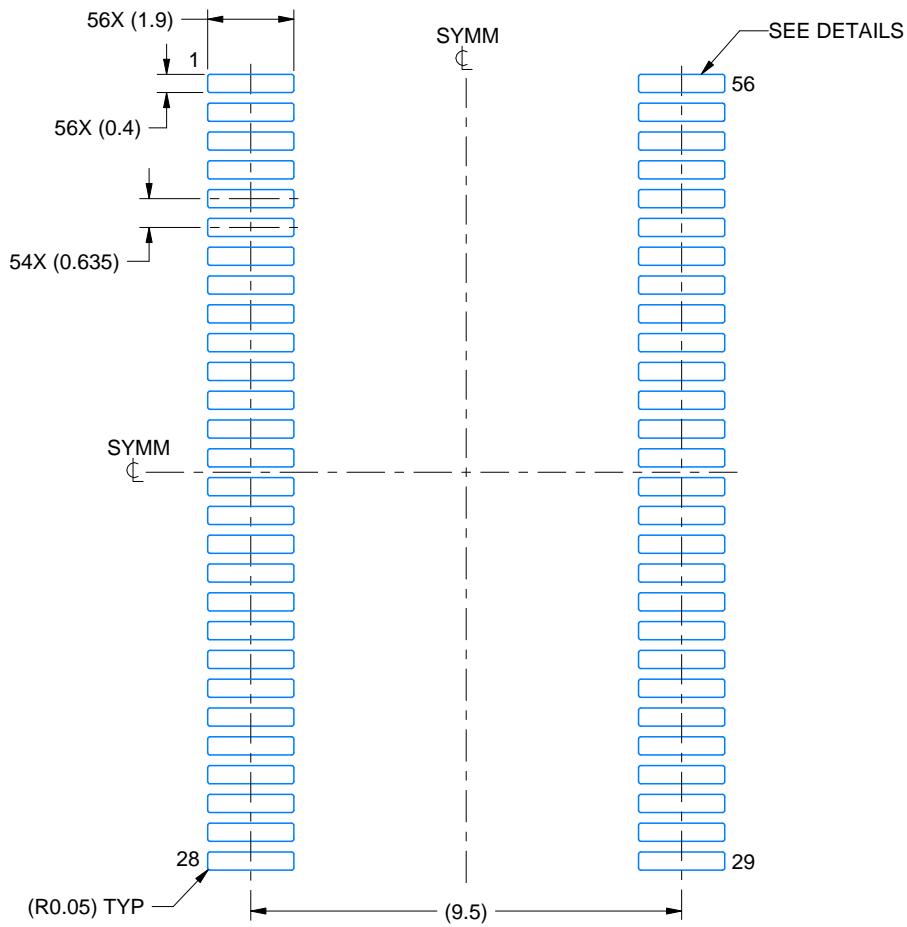


# EXAMPLE BOARD LAYOUT

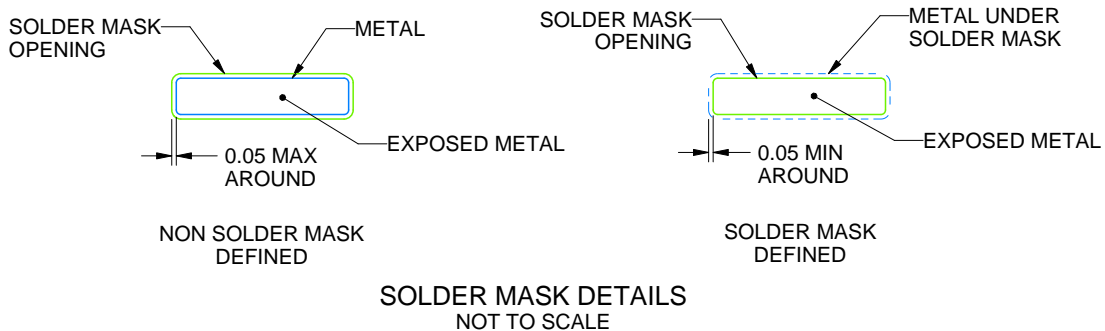
DKQ0056A

PowerPAD™ HSSOP - 2.475 mm max height

PLASTIC SMALL OUTLINE



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:6X



SOLDER MASK DETAILS  
NOT TO SCALE

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NOTES: (continued)

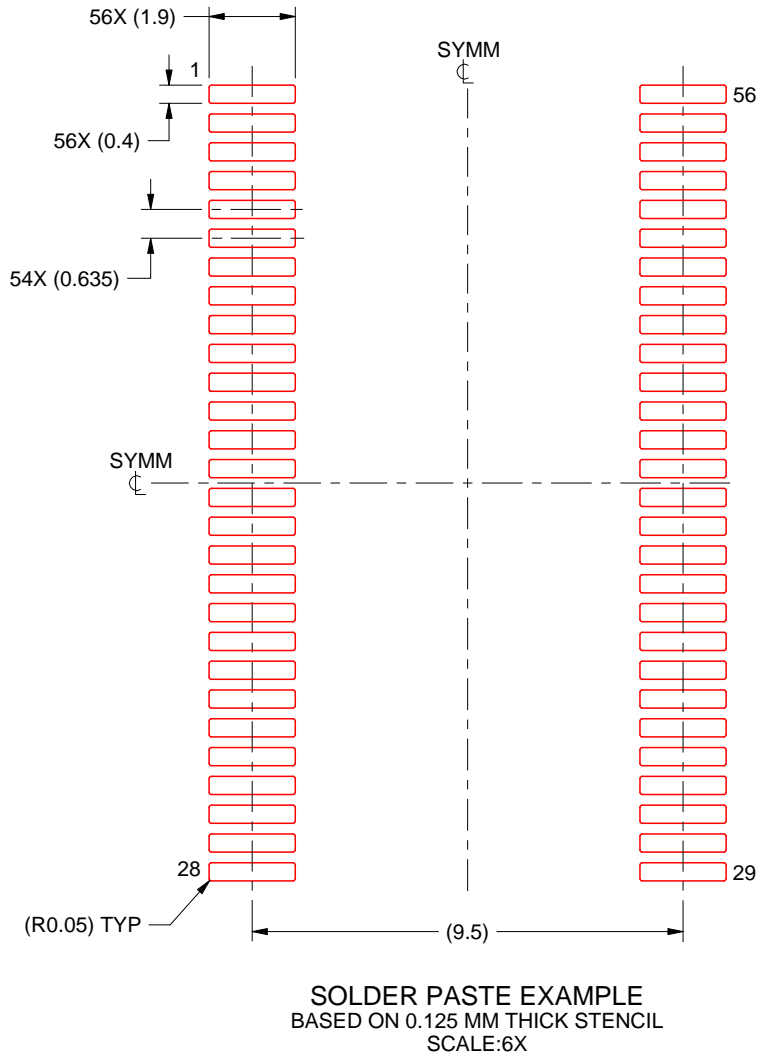
- 7. Publication IPC-7351 may have alternate designs.
- 8. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- 9. Size of metal pad may vary due to creepage requirement.

# EXAMPLE STENCIL DESIGN

DKQ0056A

PowerPAD™ HSSOP - 2.475 mm max height

PLASTIC SMALL OUTLINE



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NOTES: (continued)

10. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
11. Board assembly site may have different recommendations for stencil design.

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