# 16-Bit, 8-Channel Serial Output Sampling ANALOG-TO-DIGITAL CONVERTER 

## FEATURES

- BIPOLAR INPUT RANGE
- PIN-FOR-PIN COMPATIBLE WITH THE ADS7844 AND ADS8344
- SINGLE SUPPLY: 2.7V to 5V
- 8-CHANNEL SINGLE-ENDED OR 4-CHANNEL DIFFERENTIAL INPUT
- UP TO 100kHz CONVERSION RATE
- 85dB SINAD
- SERIAL INTERFACE
- QSOP-20 AND SSOP-20 PACKAGES


## APPLICATIONS

- DATA ACQUISITION
- TEST AND MEASUREMENT EQUIPMENT
- INDUSTRIAL PROCESS CONTROL
- PERSONAL DIGITAL ASSISTANTS
- BATTERY-POWERED SYSTEMS


## DESCRIPTION

The ADS8345 is an 8-channel, 16 -bit, sampling Analog-to-Digital (A/D) converter with a synchronous serial interface. Typical power dissipation is 8 mW at a 100 kHz throughput rate and a +5 V supply. The reference voltage $\left(\mathrm{V}_{\mathrm{REF}}\right)$ can be varied between 500 mV and $\mathrm{V}_{\mathrm{CC}} / 2$, providing a corresponding input voltage range of $\pm \mathrm{V}_{\text {REF }}$. The device includes a shutdown mode which reduces power dissipation to under $15 \mu \mathrm{~W}$. The ADS8345 is ensured down to 2.7 V operation.

Low-power, high-speed, and an onboard multiplexer make the ADS8345 ideal for battery-operated systems such as personal digital assistants, portable multi-channel data loggers, and measurement equipment. The serial interface also provides low-cost isolation for remote data acquisition. The ADS8345 is available in a QSOP-20 or SSOP-20 package and is ensured over the $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ temperature range.


Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

ABSOLUTE MAXIMUM RATINGS ${ }^{(1)}$


NOTE: (1) Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. Exposure to absolute maximum conditions for extended periods may affect device reliability.

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.
ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

PACKAGE/ORDERING INFORMATION

| PRODUCT | MAXIMUM INTEGRAL LINEARITY ERROR (LSB) | $\begin{aligned} & \text { MAXIMUM } \\ & \text { GAIN } \\ & \text { ERROR (\%) } \end{aligned}$ | PACKAGE-LEAD | PACKAGE DESIGNATOR ${ }^{(1)}$ | SPECIFIED TEMPERATURE RANGE | ORDERING NUMBER | TRANSPORT MEDIA, QUANTITY |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ADS8345E | 8 | $\pm 0.05$ | QSOP-20 | DBQ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | ADS8345E | Rails, 100 |
| " | " | " | " | " | " | ADS8345E/2K5 | Tape and Reel, 2500 |
| ADS8345N | 8 | $\pm 0.05$ | SSOP-20 | DB | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | ADS8345N | Rails, 100 |
| " | " | " | " | " | " | ADS8345N/1K | Tape and Reel, 1000 |
| ADS8345EB | 6 | $\pm 0.024$ | QSOP-20 | DBQ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | ADS8345EB | Rails, 100 |
| " | " | " | " | " | " | ADS8345EB/2K5 | Tape and Reel, 2500 |
| ADS8345NB | 6 | $\pm 0.024$ | SSOP-20 | DB | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | ADS8345NB | Rails, 100 |
| " | " | " | " | " | " | ADS8345NB/1K | Tape and Reel, 1000 |

NOTE: (1) For the most current specifications and package information, refer to our web site at www.ti.com.

## PIN CONFIGURATION



## PIN DESCRIPTIONS

| PIN | NAME | DESCRIPTION |
| :---: | :---: | :---: |
| 1 | CH0 | Analog Input Channel 0 |
| 2 | CH1 | Analog Input Channel 1 |
| 3 | CH2 | Analog Input Channel 2 |
| 4 | CH3 | Analog Input Channel 3 |
| 5 | CH 4 | Analog Input Channel 4 |
| 6 | CH5 | Analog Input Channel 5 |
| 7 | CH6 | Analog Input Channel 6 |
| 8 | CH7 | Analog Input Channel 7 |
| 9 | COM | Common reference for analog inputs. This pin is typically connected to $\mathrm{V}_{\text {REF }}$. |
| 10 | $\overline{\text { SHDN }}$ | Shutdown. When LOW, the device enters a very low-power shutdown mode. |
| 11 | $\mathrm{V}_{\text {REF }}$ | Voltage Reference Input. See the Electrical Characteristics Table for ranges. |
| 12 | $+\mathrm{V}_{\mathrm{Cc}}$ | Power Supply, 2.7V to 5.25 V |
| 13 | GND | Ground |
| 14 | GND | Ground |
| 15 | $\mathrm{D}_{\text {OUT }}$ | Serial Data Output. Data is shifted on the falling edge of DCLK. This output is high impedance when $\overline{\mathrm{CS}}$ is HIGH . |
| 16 | BUSY | Busy Output. Busy goes LOW when the $\mathrm{D}_{\text {IN }}$ control bits are being read and also when the device is converting. The Output is high impedance when $\overline{\mathrm{CS}}$ is HIGH. |
| 17 | $\mathrm{D}_{\text {IN }}$ | Serial Data Input. If $\overline{\mathrm{CS}}$ is LOW, data is latched on rising edge of $D_{\text {CLK }}$. |
| 18 | $\overline{\mathrm{CS}}$ | Chip Select Input; Active LOW. Data will not be clocked into $D_{\text {IN }}$ unless $\overline{C S}$ is LOW. When $\overline{C S}$ is HIGH, $D_{\text {OUt }}$ is high impedance. |
| 19 | DCLK | External Clock Input. The clock speed determines the conversion rate by the equation $f_{\text {DCLK }}=24 \cdot f_{\text {SAMPLE }}$. |
| 20 | $+\mathrm{V}_{\mathrm{CC}}$ | Power Supply |

## ELECTRICAL CHARACTERISTICS: +5V

At $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C},+\mathrm{V}_{\mathrm{CC}}=+5 \mathrm{~V}$, $\mathrm{V}_{\text {REF }}=+2.5 \mathrm{~V}$, $\mathrm{f}_{\text {SAMPLE }}=100 \mathrm{kHz}$, and $\mathrm{f}_{\mathrm{CLK}}=24 \cdot \mathrm{f}_{\text {SAMPLE }}=2.4 \mathrm{MHz}$, unless otherwise noted.

| PARAMETER | CONDITIONS | ADS8345E, N |  |  | ADS8345EB, NB |  |  | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | MIN | TYP | MAX | MIN | TYP | MAX |  |
| RESOLUTION |  |  | 16 |  |  | * |  | Bits |
| ANALOG INPUT <br> Full-Scale Input Span Absolute Input Range <br> Capacitance <br> Leakage Current | Positive Input-Negative Input $\begin{aligned} & +\mathrm{IN} \\ & -\mathrm{IN} \end{aligned}$ | $\begin{gathered} -\mathrm{V}_{\text {REF }} \\ -0.2 \\ -0.2 \end{gathered}$ | $\begin{aligned} & 25 \\ & \pm 1 \end{aligned}$ | $\begin{gathered} +\mathrm{V}_{\mathrm{REF}} \\ +\mathrm{V}_{\mathrm{CC}}+0.2 \\ +\mathrm{V}_{\mathrm{CC}}+0.2 \end{gathered}$ | * | * | $\begin{aligned} & * \\ & * \\ & * \end{aligned}$ | V <br> V V pF $\mu \mathrm{A}$ |
| SYSTEM PERFORMANCE <br> No Missing Codes Integral Linearity Error <br> Bipolar Error <br> Bipolar Error Match <br> Gain Error <br> Gain Error Match <br> Noise <br> Power-Supply Rejection | $+4.75 \mathrm{~V}<\mathrm{V}_{\mathrm{CC}}<5.25 \mathrm{~V}$ | 14 | $\begin{gathered} 4 \\ 1.0 \\ 20 \\ 3 \end{gathered}$ | $\begin{gathered} \pm 8 \\ \pm 2 \\ 8 \\ \pm 0.05 \\ 4 \end{gathered}$ | 15 | * <br> * <br> * <br> * | $\begin{gathered} \pm 6 \\ \pm 1 \\ * \\ \pm 0.024 \\ * \end{gathered}$ | $\begin{gathered} \text { Bits } \\ \mathrm{LSB} \\ \mathrm{mV} \\ \mathrm{LSB} \\ (1) \\ \% \\ \mathrm{LSB} \\ \mu \mathrm{Vrms} \\ \mathrm{LSB} \\ \end{gathered}$ |
| SAMPLING DYNAMICS <br> Conversion Time <br> Acquisition Time <br> Throughput Rate <br> Multiplexer Settling Time <br> Aperture Delay <br> Aperture Jitter <br> Internal Clock Frequency <br> External Clock Frequency | $\overline{\mathrm{SHDN}}=\mathrm{V}_{\mathrm{DD}}$ <br> Data Transfer Only | $4.5$ $\begin{gathered} 0.024 \\ 0 \end{gathered}$ | $\begin{gathered} 500 \\ 30 \\ 100 \\ 2.4 \end{gathered}$ | $\begin{gathered} 16 \\ 100 \\ \\ 2.4 \\ 2.4 \end{gathered}$ | * <br> * <br> * | $\begin{aligned} & * \\ & * \\ & * \\ & * \end{aligned}$ | * <br> * <br> * <br> * | CLK Cycles CLK Cycles kHz ns ns ps MHz MHz MHz |
| DYNAMIC CHARACTERISTICS <br> Total Harmonic Distortion(2) Signal-to-(Noise + Distortion) Spurious-Free Dynamic Range Channel-to-Channel Isolation | $\begin{aligned} & \mathrm{V}_{\mathbb{I N}}=5 \mathrm{Vp}-\mathrm{p} \text { at } 10 \mathrm{kHz} \\ & \mathrm{~V}_{\mathbb{I N}}=5 \mathrm{Vp}-\mathrm{p} \text { at } 10 \mathrm{kHz} \\ & \mathrm{~V}_{\mathbb{I N}}=5 \mathrm{Vp}-\mathrm{p} \text { at } 10 \mathrm{kHz} \\ & \mathrm{~V}_{\mathrm{IN}}=5 \mathrm{Vp}-\mathrm{p} \text { at } 10 \mathrm{kHz} \end{aligned}$ |  | $\begin{gathered} -96 \\ 85 \\ 98 \\ 105 \\ \hline \end{gathered}$ |  |  | $\begin{aligned} & * \\ & * \\ & * \\ & * \end{aligned}$ |  | $\begin{aligned} & \mathrm{dB} \\ & \mathrm{~dB} \\ & \mathrm{~dB} \\ & \mathrm{~dB} \end{aligned}$ |
| REFERENCE INPUT <br> Range <br> Resistance Input Current | DCLK Static DCLK Static | 0.5 | $\begin{gathered} 5 \\ 40 \\ 0.001 \end{gathered}$ | $\begin{gathered} +\mathrm{V}_{\mathrm{CC}} / 2 \\ 100 \\ 3 \end{gathered}$ | * | $\begin{aligned} & * \\ & * \\ & * \end{aligned}$ | * <br> * <br> * | $\begin{gathered} \mathrm{V} \\ \mathrm{G} \Omega \\ \mu \mathrm{~A} \\ \mu \mathrm{~A} \end{gathered}$ |
| DIGITAL INPUT/OUTPUT <br> Logic Family <br> Logic Levels <br> $\mathrm{V}_{\mathrm{IH}}$ <br> $\mathrm{V}_{\text {IL }}$ <br> $\mathrm{V}_{\mathrm{OH}}$ <br> $\mathrm{V}_{\mathrm{OL}}$ <br> Data Format | $\begin{aligned} & \left\|\mathrm{I}_{\mathrm{IH}}\right\| \leq+5 \mu \mathrm{~A} \\ & \left\|\mathrm{I}_{\mathrm{IL}}\right\| \leq+5 \mu \mathrm{~A} \\ & \mathrm{I}_{\mathrm{OH}}=-250 \mu \mathrm{~A} \\ & \mathrm{I}_{\mathrm{OL}}=250 \mu \mathrm{~A} \end{aligned}$ | $\begin{gathered} 3.0 \\ -0.3 \\ 3.5 \\ \text { Bina } \end{gathered}$ | CMOS <br> wo's | $\begin{gathered} 5.5 \\ +0.8 \\ \\ 0.4 \\ \text { iplement } \end{gathered}$ | $\begin{aligned} & * \\ & * \\ & * \end{aligned}$ | * <br> * | * <br> * <br> * | $\begin{aligned} & \mathrm{V} \\ & \mathrm{~V} \\ & \mathrm{~V} \\ & \mathrm{~V} \end{aligned}$ |
| POWER-SUPPLY REQUIREMENTS $+V_{\text {cc }}$ <br> Quiescent Current <br> Power Dissipation | Specified Performance $\begin{gathered} \mathrm{f}_{\mathrm{SAMPLE}}=10 \mathrm{kHz} \\ \text { Power-Down Mode }{ }^{(3)}, \overline{\mathrm{CS}}=+\mathrm{V}_{\mathrm{CC}} \end{gathered}$ | 4.75 | $\begin{array}{r} 1.5 \\ 1.2 \\ 7.5 \end{array}$ | $\begin{gathered} 5.25 \\ 2.0 \\ \\ 3 \\ 10 \end{gathered}$ | * | $*$ $*$ <br> * | $\begin{aligned} & * \\ & * \\ & * \\ & * \end{aligned}$ | $\begin{gathered} \mathrm{V} \\ \mathrm{~mA} \\ \mathrm{~mA} \\ \mu \mathrm{~A} \\ \mathrm{~mW} \end{gathered}$ |
| TEMPERATURE RANGE Specified Performance |  | -40 |  | +85 | * |  | * | ${ }^{\circ} \mathrm{C}$ |

* Same specifications as ADS8345E, N.

NOTES: (1) LSB means Least Significant Bit. With $\mathrm{V}_{\text {REF }}$ equal to +2.5 V , one LSB is $76 \mu \mathrm{~V}$. (2) First nine harmonics of the test frequency. (3) Auto power-down mode $(P D 1=P D 0=0)$ active or $\overline{\text { SHDN }}=$ GND.

## ELECTRICAL CHARACTERISTICS: +2.7V

At $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C},+\mathrm{V}_{\mathrm{CC}}=+2.7 \mathrm{~V}, \mathrm{~V}_{\text {REF }}=+1.25 \mathrm{~V}, \mathrm{f}_{\text {SAMPLE }}=100 \mathrm{kHz}$, and $\mathrm{f}_{\mathrm{CLK}}=24 \cdot \mathrm{f}_{\text {SAMPLE }}=2.4 \mathrm{MHz}$, unless otherwise noted.

| PARAMETER | CONDITIONS | ADS8345E, N |  |  | ADS8345EB, NB |  |  | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | MIN | TYP | MAX | MIN | TYP | MAX |  |
| RESOLUTION |  |  | 16 |  |  | * |  | Bits |
| ANALOG INPUT <br> Full-Scale Input Span Absolute Input Range <br> Capacitance <br> Leakage Current | Positive Input-Negative Input $\begin{aligned} & +\mathrm{IN} \\ & -\mathrm{IN} \end{aligned}$ | $\begin{gathered} -\mathrm{V}_{\mathrm{REF}} \\ -0.2 \\ -0.2 \end{gathered}$ | $\begin{aligned} & 25 \\ & \pm 1 \end{aligned}$ | $\begin{aligned} & +V_{\text {REF }} \\ & +V_{\mathrm{CC}}+0.2 \\ & +\mathrm{V}_{\mathrm{CC}}+0.2 \end{aligned}$ | * | $\begin{aligned} & * \\ & * \end{aligned}$ | * | $\begin{gathered} \mathrm{V} \\ \mathrm{~V} \\ \mathrm{~V} \\ \mathrm{pF} \\ \mu \mathrm{~A} \end{gathered}$ |
| SYSTEM PERFORMANCE <br> No Missing Codes <br> Integral Linearity Error <br> Bipolar Error <br> Bipolar Error Match <br> Gain Error <br> Gain Error Match <br> Noise <br> Power-Supply Rejection | $+2.7<\mathrm{V}_{\mathrm{CC}}<+3.3 \mathrm{~V}$ | 14 | $\begin{gathered} 2 \\ 1 \\ 20 \\ 3 \end{gathered}$ | $\begin{gathered} \pm 8 \\ \pm 1.0 \\ 4 \\ \pm 0.05 \\ 4 \end{gathered}$ | 15 | * <br> * <br> * <br> * | $\begin{gathered} \pm 6 \\ \pm 0.5 \\ * \\ \pm 0.024 \\ * \end{gathered}$ | Bits LSB mV LSB \% of FSR LSB $\mu \mathrm{Vrms}$ LSB(1) |
| SAMPLING DYNAMICS <br> Conversion Time <br> Acquisition Time <br> Throughput Rate <br> Multiplexer Settling Time <br> Aperture Delay <br> Aperture Jitter <br> Internal Clock Frequency <br> External Clock Frequency | $\overline{\mathrm{SHDN}}=\mathrm{V}_{\mathrm{DD}}$ <br> When used with Internal Clock Data Transfer Only | $\begin{gathered} 4.5 \\ \\ \\ \\ 0.024 \\ 0.024 \\ 0 \end{gathered}$ | $\begin{gathered} 500 \\ 30 \\ 100 \\ 2.4 \end{gathered}$ | $\begin{gathered} 16 \\ 100 \\ \\ \\ 2.4 \\ 2.0 \\ 2.4 \end{gathered}$ | * <br> * <br> * <br> * | $\begin{aligned} & * \\ & * \\ & * \\ & * \end{aligned}$ | * <br> * <br> * <br> * <br> * | $\begin{gathered} \text { CLK Cycles } \\ \text { CLK Cycles } \\ \mathrm{kHz} \\ \mathrm{~ns} \\ \mathrm{~ns} \\ \mathrm{ps} \\ \mathrm{MHz} \\ \mathrm{MHz} \\ \mathrm{MHz} \\ \mathrm{MHz} \end{gathered}$ |
| DYNAMIC CHARACTERISTICS <br> Total Harmonic Distortion(2) <br> Signal-to-(Noise + Distortion) Spurious-Free Dynamic Range Channel-to-Channel Isolation | $\begin{aligned} & \mathrm{V}_{\mathrm{IN}}=2.5 \mathrm{Vp}-\mathrm{p} \text { at } 1 \mathrm{kHz} \\ & \mathrm{~V}_{\mathrm{IN}}=2.5 \mathrm{Vp}-\mathrm{p} \text { at } 1 \mathrm{kHz} \\ & \mathrm{~V}_{\mathrm{IN}}=2.5 \mathrm{Vp}-\mathrm{p} \text { at } 1 \mathrm{kHz} \\ & \mathrm{~V}_{\mathrm{IN}}=2.5 \mathrm{Vp}-\mathrm{p} \text { at } 10 \mathrm{kHz} \end{aligned}$ |  | $\begin{gathered} -95 \\ 81 \\ 95 \\ 108 \\ \hline \end{gathered}$ |  |  | $\begin{aligned} & * \\ & * \\ & * \\ & * \end{aligned}$ |  | $\begin{aligned} & \mathrm{dB} \\ & \mathrm{~dB} \\ & \mathrm{~dB} \\ & \mathrm{~dB} \end{aligned}$ |
| REFERENCE INPUT <br> Range <br> Resistance Input Current | DCLK Static DCLK Static | 0.5 | $\begin{gathered} 5 \\ 13 \\ 0.001 \end{gathered}$ | $\begin{gathered} +\mathrm{V}_{\mathrm{CC}} / 2 \\ 40 \\ 3 \end{gathered}$ | * | $\begin{aligned} & * \\ & * \\ & * \end{aligned}$ | * <br> * <br> * | $\begin{gathered} \mathrm{V} \\ \mathrm{G} \Omega \\ \mu \mathrm{~A} \\ \mu \mathrm{~A} \end{gathered}$ |
| DIGITAL INPUT/OUTPUT <br> Logic Family Logic Levels <br> $\mathrm{V}_{\mathrm{IH}}$ <br> $\mathrm{V}_{\text {IL }}$ <br> $\mathrm{V}_{\mathrm{OH}}$ <br> $\mathrm{V}_{\mathrm{OL}}$ <br> Data Format | $\begin{aligned} & \left\|\mathrm{I}_{\mathrm{IH}}\right\| \leq+5 \mu \mathrm{~A} \\ & \left\|\mathrm{I}_{\mathrm{IL}}\right\| \leq+5 \mu \mathrm{~A} \\ & \mathrm{I}_{\mathrm{OH}}=-250 \mu \mathrm{~A} \\ & \mathrm{I}_{\mathrm{OL}}=250 \mu \mathrm{~A} \end{aligned}$ | $\begin{array}{r} +\mathrm{V}_{\mathrm{cc}} \cdot 0.7 \\ -0.3 \\ +\mathrm{V}_{\mathrm{Cc}} \cdot 0.8 \\ \quad \text { Binary } \end{array}$ | CMOS <br> wo's Co | $\begin{gathered} 5.5 \\ +0.8 \\ \\ 0.4 \\ \text { plement } \end{gathered}$ | $\begin{aligned} & * \\ & * \\ & * \end{aligned}$ | * <br> * | * <br> * <br> * | $\begin{aligned} & \mathrm{V} \\ & \mathrm{~V} \\ & \mathrm{~V} \\ & \mathrm{~V} \end{aligned}$ |
| POWER-SUPPLY REQUIREMENTS $+\mathrm{V}_{\mathrm{CC}}$ <br> Quiescent Current <br> Power Dissipation | Specified Performance $\begin{gathered} \mathrm{f}_{\mathrm{SAMPLE}}=10 \mathrm{kHz} \\ \text { Power-Down Mode }{ }^{(3)}, \overline{\mathrm{CS}}=+\mathrm{V}_{\mathrm{CC}} \end{gathered}$ | 2.7 | $\begin{array}{r} 1.2 \\ 950 \\ \\ 3.2 \end{array}$ | $\begin{gathered} 3.6 \\ 1.85 \\ 3 \\ 5 \end{gathered}$ | * | * <br> * | $\begin{aligned} & * \\ & * \\ & * \\ & * \end{aligned}$ | $\begin{gathered} \mathrm{V} \\ \mathrm{~mA} \\ \mu \mathrm{~A} \\ \mu \mathrm{~A} \\ \mathrm{~mW} \end{gathered}$ |
| TEMPERATURE RANGE Specified Performance |  | -40 |  | +85 | * |  | * | ${ }^{\circ} \mathrm{C}$ |

* Same specifications as ADS8345E, N.

NOTES: (1) LSB means Least Significant Bit. With $\mathrm{V}_{\text {REF }}$ equal to +1.25 V , one LSB is $38 \mu \mathrm{~V}$. (2) First nine harmonics of the test frequency. (3) Auto power-down mode $($ PD1 $=$ PD0 $=0)$ active or $\overline{\text { SHDN }}=$ GND.

## TYPICAL CHARACTERISTICS: +5V

At $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C},+\mathrm{V}_{\mathrm{CC}}=+5 \mathrm{~V}, \mathrm{~V}_{\text {REF }}=+2.5 \mathrm{~V}, \mathrm{f}_{\text {SAMPLE }}=100 \mathrm{kHz}$, and $\mathrm{f}_{\mathrm{DCLK}}=24 \cdot \mathrm{f}_{\text {SAMPLE }}=2.4 \mathrm{MHz}$, unless otherwise noted.


## TYPICAL CHARACTERISTICS: +5V (Cont.)

At $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C},+\mathrm{V}_{\mathrm{CC}}=+5 \mathrm{~V}, \mathrm{~V}_{\text {REF }}=+2.5 \mathrm{~V}, \mathrm{f}_{\text {SAMPLE }}=100 \mathrm{kHz}$, and $\mathrm{f}_{\text {DCLK }}=24 \cdot \mathrm{f}_{\text {SAMPLE }}=2.4 \mathrm{MHz}$, unless otherwise noted.






## TYPICAL CHARACTERISTICS: +5V (Cont.)

At $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C},+\mathrm{V}_{\mathrm{CC}}=+2.5 \mathrm{~V}, \mathrm{~V}_{\text {REF }}=+2.5 \mathrm{~V}$, $\mathrm{f}_{\text {SAMPLE }}=100 \mathrm{kHz}$, and $\mathrm{f}_{\mathrm{DCLK}}=24 \cdot \mathrm{f}_{\text {SAMPLE }}=2.4 \mathrm{MHz}$, unless otherwise noted.


TYPICAL CHARACTERISTICS: +2.7V
At $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C},+\mathrm{V}_{\mathrm{CC}}=+2.7 \mathrm{~V}, \mathrm{~V}_{\mathrm{REF}}=+1.25 \mathrm{~V}, \mathrm{f}_{\mathrm{SAMPLE}}=100 \mathrm{kHz}$, and $\mathrm{f}_{\mathrm{DCLK}}=24 \cdot \mathrm{f}_{\mathrm{SAMPLE}}=2.4 \mathrm{MHz}$, unless otherwise noted.


SIGNAL-TO-NOISE RATIO AND SIGNAL-TO-(NOISE + DISTORTION) vs INPUT FREQUENCY


SPURIOUS-FREE DYNAMIC RANGE AND TOTAL HARMONIC DISTORTION vs INPUT FREQUENCY


## TYPICAL CHARACTERISTICS: +2.7V (Cont.)

At $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C},+\mathrm{V}_{\mathrm{CC}}=+2.7 \mathrm{~V}, \mathrm{~V}_{\text {REF }}=+1.25 \mathrm{~V}, \mathrm{f}_{\text {SAMPLE }}=100 \mathrm{kHz}$, and $\mathrm{f}_{\text {DCLK }}=24 \cdot \mathrm{f}_{\text {SAMPLE }}=2.4 \mathrm{MHz}$, unless otherwise noted.







## TYPICAL CHARACTERISTICS: +2.7V (Cont.)

At $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C},+\mathrm{V}_{\mathrm{CC}}=+2.7 \mathrm{~V}, \mathrm{~V}_{\text {REF }}=+1.25 \mathrm{~V}, \mathrm{f}_{\mathrm{SAMPLE}}=100 \mathrm{kHz}$, and $\mathrm{f}_{\mathrm{DCLK}}=24 \cdot \mathrm{f}_{\mathrm{SAMPLE}}=2.4 \mathrm{MHz}$, unless otherwise noted.







## THEORY OF OPERATION

The ADS8345 is a classic Successive Approximation Register (SAR) A/D converter. The architecture is based on capacitive redistribution which inherently includes a sample-and-hold function. The converter is fabricated on a $0.6 \mu \mathrm{~m}$ CMOS process.
The basic operation of the ADS8345 is shown in Figure 1. The device requires an external reference and an external clock. It operates from a single supply of 2.7 V to 5.25 V . The external reference can be any voltage between 500 mV and $+\mathrm{V}_{\mathrm{CC}} / 2$. The value of the reference voltage directly sets the input range of the converter. The average reference input current depends on the conversion rate of the ADS8345.
The analog input to the converter is differential and is provided via an eight-channel multiplexer. The input can be provided in reference to a voltage on the COM pin (which is generally $+\mathrm{V}_{\mathrm{CC}} / 2$ ) or differentially by using four of the eight input channels ( $\mathrm{CH}-\mathrm{CH} 7$ ). The particular configuration is selectable via the digital interface.

## ANALOG INPUT

The analog input is bipolar and fully differential. There are two general methods of driving the analog input of the ADS8345: single-ended or differential (see Figure 2). When the input is single-ended, the COM input is held at a fixed voltage. The CHX input swings around the same voltage and the peak-to-peak amplitude is $2 \cdot \mathrm{~V}_{\text {REF }}$. The value of $\mathrm{V}_{\text {REF }}$
determines the range over which the common voltage may vary (see Figure 3).
When the input is differential, the amplitude of the input is the difference between the CHX and COM input (see Figure 4). A voltage or signal is common to both of these inputs. The peak-to-peak amplitude of each input is $\mathrm{V}_{\text {REF }}$ about this common voltage. However, since the input are $180^{\circ} \mathrm{C}$ out-ofphase, the peak-to-peak amplitude of the difference voltage is $2 \cdot \mathrm{~V}_{\text {REF }}$. The value of $\mathrm{V}_{\text {REF }}$ also determines the range of the voltage that may be common to both inputs (see Figure 5). In each case, care should be taken to ensure that the output impedance of the sources driving the CHX and COM inputs are matched. If this is not observed, the two inputs could have different settling times. This may result in offset error, gain error, and linearity error which changes with both temperature and input voltage. If the impedance cannot be matched, the errors can be lessened by giving the ADS8345 additional acquisition time.

The input current on the analog inputs depends on a number of factors: sample rate, input voltage, and source impedance. Essentially, the current into the ADS8345 charges the internal capacitor array during the sample period. After this capacitance has been fully charged, there is no further input current.

Care must be taken regarding the absolute analog input voltage. Outside of these ranges, the converter's linearity may not meet specifications. Please refer to the Electrical Characteristics table for min/max ratings.


FIGURE 1. Basic Operation of the ADS8345.

## REFERENCE INPUT

The external reference sets the analog input range. The ADS8345 will operate with a reference in the range of 500 mV to $+\mathrm{V}_{\mathrm{CC}} / 2$. Keep in mind that the analog input is the differ-


FIGURE 2. Methods of Driving the ADS8345—Single-Ended or Differential.


FIGURE 3. Single-Ended Input-Common Voltage Range vs $\mathrm{V}_{\mathrm{REF}}$.
ence between the CHX input and the COM input, as shown in Figure 4. For example, in the single-ended mode, a 1.25 V reference with the COM pin at $\mathrm{V}_{\mathrm{CC}} / 2$, the selected input channel ( $\mathrm{CH} 0-\mathrm{CH} 7$ ) will properly digitize a signal in the range of $\left(\mathrm{V}_{\mathrm{CC}} / 2-1.25 \mathrm{~V}\right)$ to $\left(\mathrm{V}_{\mathrm{CC}} / 2+1.25 \mathrm{~V}\right)$.


FIGURE 4. Simplified Diagram of the Analog Input.


FIGURE 5. Differential Input-Common Voltage Range vs $\mathrm{V}_{\text {REF }}$.

There are several critical items concerning the reference input and its wide-voltage range. As the reference voltage is reduced, the analog voltage weight of each digital output code is also reduced. This is often referred to as the LSB (Least Significant Bit) size and is equal to the reference voltage divided by 65536. Any offset or gain error inherent in the A/D converter will appear to increase, in terms of LSB size, as the reference voltage is reduced. For example, if the offset of a given converter is 2 LSB with a 2.5 V reference, then it will typically be 10 LSB with a 0.5 V reference. In each case, the actual offset of the device is the same, $152.8 \mu \mathrm{~V}$.
The noise or uncertainty of the digitized output will increase with lower LSB size. With a reference voltage of 500 mV , the LSB size is $15.3 \mu \mathrm{~V}$. This level is below the internal noise of the device. As a result, the digital output code will not be stable and will vary around a mean value by a number of LSBs. The distribution of output codes will be gaussian and the noise can be reduced by simply averaging consecutive conversion results or applying a digital filter.
With a lower reference voltage, care should be taken to provide a clean layout including adequate bypassing, a clean (low-noise, low-ripple) power supply, a low-noise reference, and a low-noise input signal. Because the LSB size is lower, the converter will also be more sensitive to nearby digital signals and electromagnetic interference.
The voltage into the $\mathrm{V}_{\text {REF }}$ input is not buffered and directly drives the Capacitor Digital-to-Analog Converter (CDAC) portion of the ADS8345. Typically, the input current is $13 \mu \mathrm{~A}$ with a 2.5 V reference. This value will vary by microamps depending on the result of the conversion. The reference current diminishes directly with both conversion rate and reference voltage. As the current from the reference is drawn on each bit decision, clocking the converter more quickly during a given conversion period will not reduce overall current drain from the reference.

## DIGITAL INTERFACE

The ADS8345 has a 4-wire serial interface compatible with several microprocessor families (note that the digital inputs are over-voltage tolerant up to +5.5 V , regardless of $+\mathrm{V}_{\mathrm{CC}}$ ). Figure 6 shows the typical operation of the ADS8345 digital interface.

Most microprocessors communicate using 8-bit transfers; the ADS8345 can complete a conversion with three such transfers, for a total of 24 clock cycles on the DCLK input, provided the timing is as shown in Figure 6.
The first eight clock cycles are used to provide the control byte via the $\mathrm{D}_{\text {IN }}$ pin. When the converter has enough information about the following conversion to set the input multiplexer appropriately, it enters the acquisition (sample) mode. After four more clock cycles, the control byte is complete and the converter enters the conversion mode. At this point, the input sample-and-hold goes into the Hold mode. The next sixteen clock cycles accomplish the actual A/D conversion.

## Control Byte

Figure 6 shows placement and order of the control bits within the control byte. Tables I and II give detailed information about these bits. The first bit, the " S " bit, must always be HIGH and indicates the start of the control byte. The ADS8345 will ignore inputs on the $D_{\text {IN }}$ pin until the START bit is detected. The next three bits (A2-A0) select the active input channel or channels of the input multiplexer (see Tables III and IV and Figure 4).

| BIT 7 <br> (MSB) | BIT 6 | BIT 5 | BIT 4 | BIT 3 | BIT 2 | BIT 1 | BIT 0 <br> (LSB) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| S | A2 | A1 | A0 | - | SGL/ $\overline{\mathrm{IIF}}$ | PD1 | PD0 |

TABLE I. Order of the Control Bits in the Control Byte.

| BIT | NAME | DESCRIPTION |
| :--- | :---: | :--- |
| 7 | S | Start Bit. Control byte starts with first HIGH bit on <br> (IN. |
| 6-4 | A2-A0 | Channel Select Bits. Along with the SGL/DIF bit, <br> these bits control the setting of the multiplexer input. |
| 1-0 | SGL/DIF | SD1-PDO <br> Single-Ended/Differential Select Bit. Along with bits <br> A2-A0, this bit controls the setting of the multiplexer <br> input. <br> Power-Down Mode Select Bits. See Table V for <br> details. |

TABLE II. Descriptions of the Control Bits within the Control Byte.


FIGURE 6. Conversion Timing, 24-Clocks per Conversion, 8-Bit Bus Interface. No DCLK delay required with dedicated serial port.

The SGL/DIF-bit controls the multiplexer input mode: either in single-ended mode, where the selected input channel is referenced to the COM pin, or in differential mode, where the two selected inputs provide a differential input. See Tables III and IV and Figure 4 for more information. The last two bits (PD1-PD0) select the Power-Down mode and Clock mode, as shown in Table V. If both PD1 and PD0 are HIGH, the device is always powered up. If both PD1 and PD0 are LOW, the device enters a power-down mode between conversions. When a new conversion is initiated, the device will resume normal operation instantly-no delay is needed to allow the device to power up and the very first conversion will be valid.

| A2 | A1 | A0 | CH0 | CH1 | CH2 | CH3 | CH4 | CH5 | CH6 | CH7 | COM |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | +IN |  |  |  |  |  |  |  | -IN |
| 1 | 0 | 0 |  | +IN |  |  |  |  |  |  | -IN |
| 0 | 0 | 1 |  |  | +IN |  |  |  |  |  | -IN |
| 1 | 0 | 1 |  |  |  | +IN |  |  |  |  | -IN |
| 0 | 1 | 0 |  |  |  |  | +IN |  |  |  | -IN |
| 1 | 1 | 0 |  |  |  |  |  | +IN |  |  | -IN |
| 0 | 1 | 1 |  |  |  |  |  |  | +IN |  | -IN |
| 1 | 1 | 1 |  |  |  |  |  |  |  | +IN | -IN |

TABLE III. Single-Ended Channel Selection (SGL/(̄IF HIGH).

| A2 | A1 | A0 | CHO | CH1 | CH2 | CH3 | CH4 | CH5 | CH6 | CH7 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | +IN | -IN |  |  |  |  |  |  |
| 0 | 0 | 1 |  |  | +IN | -IN |  |  |  |  |
| 0 | 1 | 0 |  |  |  |  | +IN | -IN |  |  |
| 0 | 1 | 1 |  |  |  |  |  |  | $+\mathrm{IN}$ | -IN |
| 1 | 0 | 0 | -IN | $+\mathrm{IN}$ |  |  |  |  |  |  |
| 1 | 0 | 1 |  |  | -IN | +IN |  |  |  |  |
| 1 | 1 | 0 |  |  |  |  | -IN | $+\mathrm{IN}$ |  |  |
| 1 | 1 | 1 |  |  |  |  |  |  | -IN | $+\mathrm{IN}$ |

TABLE IV. Differential Channel Control (SGL/DIF LOW).

| PD1 | PD0 | DESCRIPTION |
| :---: | :---: | :--- |
| 0 | 0 | Power-down between conversions. When each <br> conversion is finished, the converter enters a <br> low-power mode. At the start of the next conver- <br> sion, the device instantly powers up to full power. <br> There is no need for additional delays to assure full <br> operation and the very first conversion is valid. <br> 1 |
| 0 | 1 | Selects internal clock mode. <br> Reserved for future use. <br> No power-down between conversions, device al- <br> ways powered. Selects external clock mode. |

TABLE V. Power-Down Selection.

## Clock Modes

The ADS8345 can be used with an external serial clock or an internal clock to perform the successive-approximation conversion. In both clock modes, the external clock shifts data in and out of the device. Internal clock mode is selected when PD1 is HIGH and PD0 is LOW.
If the user decides to switch from one clock mode to the other, an extra conversion cycle will be required before the ADS8345 can switch to the new mode. The extra cycle is required because the PD0 and PD1 control bits need to be written to the ADS8345 prior to the change in clock modes.
When power is first applied to the ADS8345, the user must set the desired clock mode. It can be set by writing PD1 = 1 and PD0 $=0$ for internal clock mode or PD1 $=1$ and PD0 $=1$ for external clock mode. After enabling the required clock mode, only then should the ADS8345 be set to power-down between conversions (i.e., PD1 = PD0 = 0). The ADS8345 maintains the clock mode it was in prior to entering the power-down modes.

## External Clock Mode

In external clock mode, the external clock not only shifts data in and out of the ADS8345, it also controls the A/D conversion steps. BUSY will go HIGH for one clock period after the last bit of the control byte is shifted in. Successive-approximation bit decisions are made and appear at $D_{\text {OUt }}$ on each of the next 16 DCLK falling edges (see Figure 6). Figure 7 shows the BUSY timing in external clock mode.


FIGURE 7. Detailed Timing Diagram.

Since one clock cycle of the serial clock is consumed with BUSY going HIGH (while the MSB decision is being made), 16 additional clocks must be given to clock out all 16 bits of data; thus, one conversion takes a minimum of 25 clock cycles to fully read the data. Since most microprocessors communicate in 8-bit transfers, this means that an additional transfer must be made to capture the LSB.

There are two ways of handling this requirement. One is where the beginning of the next control byte appears at the same time the LSB is being clocked out of the ADS8345 (see Figure 6). This method allows for maximum throughput and 24 clock cycles per conversion.

The other method is shown in Figure 8, which uses 32 clock cycles per conversion; the last seven clock cycles simply shift out zeros on the $\mathrm{D}_{\text {OUt }}$ line. BUSY and $\mathrm{D}_{\text {OUt }}$ go into a high-impedance state when $\overline{\mathrm{CS}}$ goes HIGH; after the next $\overline{\mathrm{CS}}$ falling edge, BUSY will go LOW.

## Internal Clock Mode

In internal clock mode, the ADS8345 generates its own conversion clock internally. This relieves the microprocessor from having to generate the SAR conversion clock and allows the conversion result to be read back at the processor's convenience, at any clock rate from 0 MHz to 2.0 MHz . BUSY goes LOW at the start of a conversion and then returns HIGH when the conversion is complete. During the conversion, BUSY will remain LOW for a maximum of $8 \mu \mathrm{~s}$. Also, during the conversion, DCLK should remain LOW to achieve the best noise performance. The conversion result is stored in an internal register; the data may be clocked out of this register any time after the conversion is complete.

If $\overline{\mathrm{CS}}$ is LOW when BUSY goes LOW following a conversion, the next falling edge of the external serial clock will write out the MSB on the $\mathrm{D}_{\text {Out }}$ line. The remaining bits (D14-D0) will be clocked out on each successive clock cycle following the MSB. If $\overline{C S}$ is HIGH when BUSY goes LOW then the Dout line will remain in tri-state until $\overline{\mathrm{CS}}$ goes LOW, as shown in Figure 9. $\overline{\mathrm{CS}}$ does not need to remain LOW once a conversion has started. Note that BUSY is not tri-stated when $\overline{\mathrm{CS}}$ goes HIGH in internal clock mode.
Data can be shifted in and out of the ADS8345 at clock rates exceeding 2.4 MHz , provided that the minimum acquisition time $t_{\mathrm{ACQ}}$, is kept above $1.7 \mu \mathrm{~s}$.

## Digital Timing

Figure 7 and Tables VI and VII provide detailed timing for the digital interface of the ADS8345.

| SYMBOL | DESCRIPTION | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\mathrm{ACQ}}$ | Acquisition Time | 1.5 |  |  | $\mu \mathrm{~s}$ |
| $\mathrm{t}_{\mathrm{DS}}$ | $\mathrm{D}_{\text {IN }}$ Valid Prior to DCLK Rising | 100 |  |  | ns |
| $\mathrm{t}_{\mathrm{DH}}$ | $\mathrm{D}_{\text {IN }}$ Hold After DCLK HIGH | 10 |  |  | ns |
| $\mathrm{t}_{\mathrm{DO}}$ | DCLK Falling to D DOT Valid |  |  | 200 | ns |
| $\mathrm{t}_{\mathrm{DV}}$ | $\overline{\mathrm{CS}}$ Falling to D DUT Enabled |  |  | 200 | ns |
| $\mathrm{t}_{\mathrm{TR}}$ | $\overline{\mathrm{CS}}$ Rising to DouT Disabled |  |  | 200 | ns |
| $\mathrm{t}_{\mathrm{CSS}}$ | $\overline{\mathrm{CS}}$ Falling to First DCLK Rising | 100 |  |  | ns |
| $\mathrm{t}_{\mathrm{CSH}}$ | $\overline{\mathrm{CS}}$ Rising to DCLK Ignored | 0 |  |  | ns |
| $\mathrm{t}_{\mathrm{CH}}$ | DCLK HIGH | 200 |  |  | ns |
| $\mathrm{t}_{\mathrm{CL}}$ | DCLK LOW | 200 |  |  | ns |
| $\mathrm{t}_{\mathrm{BD}}$ | DCLK Falling to BUSY Rising |  |  | 200 | ns |
| $\mathrm{t}_{\mathrm{BDV}}$ | $\overline{\mathrm{CS}}$ Falling to BUSY Enabled |  |  | 200 | ns |
| $\mathrm{t}_{\mathrm{BTR}}$ | $\overline{\mathrm{CS}}$ Rising to BUSY Disabled |  |  | 200 | ns |

TABLE VI. Timing Specifications $\left(+\mathrm{V}_{\mathrm{CC}}=+2.7 \mathrm{~V}\right.$ to 3.6 V , $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $\left.+85^{\circ} \mathrm{C}, \mathrm{C}_{\mathrm{LOAD}}=50 \mathrm{pF}\right)$.


FIGURE 8. External Clock Mode, 32 Clocks Per Conversion.


FIGURE 9. Internal Clock Mode Timing.

| SYMBOL | DESCRIPTION | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\text {ACO }}$ | Acquisition Time | 1.7 |  |  | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {DS }}$ | $\mathrm{D}_{\text {IN }}$ Valid Prior to DCLK Rising | 50 |  |  | ns |
| $\mathrm{t}_{\mathrm{DH}}$ | $\mathrm{D}_{\text {IN }}$ Hold After DCLK HIGH | 10 |  |  | ns |
| $t_{\text {D }}$ | DCLK Falling to Dout Valid |  |  | 100 | ns |
| $\mathrm{t}_{\mathrm{DV}}$ | $\overline{\text { CS Falling to Dout Enabled }}$ |  |  | 70 | ns |
| $\mathrm{t}_{\text {TR }}$ | $\overline{\text { CS }}$ Rising to Dout Disabled |  |  | 70 | ns |
| $\mathrm{t}_{\text {css }}$ | CS Falling to First DCLK Rising | 50 |  |  | ns |
| $\mathrm{t}_{\text {cSH }}$ | CS Rising to DCLK Ignored | 0 |  |  | ns |
| ${ }_{\text {t }}^{\text {ch }}$ | DCLK HIGH | 150 |  |  | ns |
| $\mathrm{tc}_{\text {cl }}$ | DCLK LOW | 150 |  |  | ns |
| $t_{\text {B }}$ | DCLK Falling to BUSY Rising |  |  | 100 | ns |
| $\mathrm{t}_{\text {BDV }}$ | $\overline{\text { CS }}$ Falling to BUSY Enabled |  |  | 70 | ns |
| $\mathrm{t}_{\text {tir }}$ | $\overline{\text { CS }}$ Rising to BUSY Disabled |  |  | 70 | ns |

TABLE VII. Timing Specifications $\left(+\mathrm{V}_{\mathrm{CC}}=+4.75 \mathrm{~V}\right.$ to +5.25 V , $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, and $\mathrm{C}_{\text {LOAD }}=50 \mathrm{pF}$ ).

## Data Format

The output data from the ADS8345 is in Binary Two's Complement format, as shown in Table VIII. This table represents the ideal output code for the given input voltage and does not include the effects of offset, gain error, or noise.

| DESCRIPTION | analog value | DIGITAL OUTPUT BINARY TWO'S COMPLEMENT |  |
| :---: | :---: | :---: | :---: |
| Full-Scale Range <br> Least Significant Bit (LSB) | $\begin{gathered} 2 \cdot V_{\text {REF }} \\ 2 \cdot V_{\text {REF } / 65536} \end{gathered}$ |  |  |
|  |  | BINARY CODE | HEX CODE |
| +Full-Scale | $+\mathrm{V}_{\text {REF }}-1$ 1SB | 0111111111111111 | 7FFF |
| Midscale | OV | 0000000000000000 | 0000 |
| Midscale - 1LSB | OV - 1LSB | 1111111111111111 | FFFF |
| -Full-Scale | $-V_{\text {REF }}$ | 1000000000000000 | 8000 |

TABLE VIII. Ideal Input Voltages and Output Codes.

## POWER DISSIPATION

There are three power modes for the ADS8345: full-power (PD1-PD0 = 11B), auto power-down (PD1-PD0 = 00B), and shutdown ( $\overline{\mathrm{SHDN}}$ LOW). The effects of these modes varies depending on how the ADS8345 is being operated. For example, at full conversion rate and 24 -clocks per conversion, there is very little difference between full-power mode and auto power-down; a shutdown will not lower power dissipation.

When operating at full-speed and 24-clocks per conversion (see Figure 6), the ADS8345 spends most of its time acquiring or converting. There is little time for auto power-down, assuming that this mode is active. Thus, the difference between full-power mode and auto power-down is negligible. If the conversion rate is decreased by simply slowing the frequency of the DCLK input, the two modes remain approximately equal. However, if the DCLK frequency is kept at the maximum rate during a conversion, but conversions are simply done less often, then the difference between the two modes is dramatic. In the latter case, the converter spends an increasing percentage of its time in power-down mode (assuming the auto power-down mode is active).

If DCLK is active and $\overline{\mathrm{CS}}$ is LOW while the ADS8345 is in auto power-down mode, the device will continue to dissipate some power in the digital logic. The power can be reduced to a minimum by keeping $\overline{\mathrm{CS}} \mathrm{HIGH}$.
Operating the ADS8345 in auto power-down mode will result in the lowest power dissipation, and there is no conversion time "penalty" on power-up. The very first conversion will be valid. $\overline{\text { SHDN }}$ can be used to force an immediate power-down.

## NOISE

The noise floor of the ADS8345 itself is rather low (see Figures 10 and 11). The ADS8345 was tested at both 5V and 2.7 V , and in both the internal and external clock modes. A low-level DC input was applied to the analog-input pins and the converter was put through 5000 conversions. The digital output of the A/D converter will vary in output code due to the internal noise of the ADS8345. This is true for all 16-bit, SARtype, A/D converters. Using a histogram to plot the output codes, the distribution should appear bell-shaped with the peak of the bell curve representing the nominal code for the input value. The $\pm 1 \sigma, \pm 2 \sigma$, and $\pm 3 \sigma$ distributions will represent the $68.3 \%, 95.5 \%$, and $99.7 \%$, respectively, of all codes. The transition noise can be calculated by dividing the number of codes measured by 6 and this will yield the $\pm 3 \sigma$ distribution, or $99.7 \%$, of all codes. Statistically, up to 3 codes could fall outside the distribution when executing 1000 conversions. The ADS8345, with 5 output codes for the $\pm 3 \sigma$ distribution, will yield $\mathrm{a}< \pm 0.83 \mathrm{LSB}$ transition noise at 5 V operation. Remember, to achieve this low-noise performance, the peak-to-peak noise of the input signal and reference must be $<50 \mu \mathrm{~V}$.


FIGURE 10. Histogram of 5000 Conversions of a DC Input at the Code Transition, 5V operation external clock mode. $\mathrm{V}_{\text {REF }}=\mathrm{V}_{\text {COM }}=2.5 \mathrm{~V}$.


FIGURE 11. Histogram of 5000 Conversions of a DC Input at the Code Center, 2.7 V operation external clock mode. $\mathrm{V}_{\text {REF }}=\mathrm{V}_{\text {COM }}=1.25 \mathrm{~V}$.

## AVERAGING

The noise of the A/D converter can be compensated by averaging the digital codes. By averaging conversion results, transition noise will be reduced by a factor of $1 / \sqrt{n}$, where $n$ is the number of averages. For example, averaging 4 conversion results will reduce the transition noise by $1 / 2$ to $\pm 0.25$ LSBs. Averaging should only be used for input signals with frequencies near DC.
For AC signals, a digital filter can be used to low-pass filter and decimate the output codes. This works in a similar manner to averaging: for every decimation by 2, the signal-to-noise ratio will improve 3dB.

## LAYOUT

For optimum performance, care should be taken with the physical layout of the ADS8345 circuitry. This is particularly true if the reference voltage is LOW and/or the conversion rate is HIGH.
The basic SAR architecture is sensitive to glitches or sudden changes on the power supply, reference, ground connections, and digital inputs that occur just prior to latching the
output of the analog comparator. Thus, during any single conversion for an n -bit SAR converter, there are n "windows" in which large external transient voltages can easily affect the conversion result. Such glitches might originate from switching power supplies, nearby digital logic, and highpower devices. The degree of error in the digital output depends on the reference voltage, layout, and the exact timing of the external event. The error can change if the external event changes in time with respect to the DCLK input.
With this in mind, power to the ADS8345 should be clean and well bypassed. A $0.1 \mu \mathrm{~F}$ ceramic bypass capacitor should be placed as close to the device as possible. In addition, a $1 \mu \mathrm{~F}$ to $10 \mu \mathrm{~F}$ capacitor and a $5 \Omega$ or $10 \Omega$ series resistor may be used to low-pass filter a noisy supply.
The reference should be similarly bypassed with a $0.1 \mu \mathrm{~F}$ capacitor. Again, a series resistor and large capacitor can be used to low-pass filter the reference voltage. If the reference voltage originates from an op amp, make sure that it can drive the bypass capacitor without oscillation (the series resistor can help in this case). The ADS8345 draws very little current from the reference on average, but it does place larger demands on the reference circuitry over short periods of time (on each rising edge of DCLK during a conversion).
The ADS8345 architecture offers no inherent rejection of noise or voltage variation in regards to the reference input. This is of particular concern when the reference input is tied to the power supply. Any noise and ripple from the supply will appear directly in the digital results. While high-frequency noise can be filtered out as discussed in the previous paragraph, voltage variation due to line frequency $(50 \mathrm{~Hz}$ or 60 Hz ) can be difficult to remove.
The GND pin should be connected to a clean ground point. In many cases, this will be the "analog" ground. Avoid connections which are too near the grounding point of a microcontroller or digital signal processor. If needed, run a ground trace directly from the converter to the power-supply entry point. The ideal layout will include an analog ground plane dedicated to the converter and associated analog circuitry.

Texas

## PACKAGING INFORMATION

| Orderable Device | Status <br> (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan <br> (2) | Lead finish/ Ball material <br> (6) | MSL Peak Temp <br> (3) | Op Temp ( ${ }^{\circ} \mathrm{C}$ ) | Device Marking (4/5) | Samples |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ADS8345E | ACTIVE | SSOP | DBQ | 20 | 50 | RoHS \& Green | Call TI | Level-2-260C-1 YEAR | -40 to 85 | ADS8345E | Samples |
| ADS8345E/2K5 | ACTIVE | SSOP | DBQ | 20 | 2500 | RoHS \& Green | Call TI | Level-2-260C-1 YEAR | -40 to 85 | ADS8345E | Samples |
| ADS8345EB | ACTIVE | SSOP | DBQ | 20 | 50 | RoHS \& Green | Call TI | Level-2-260C-1 YEAR | -40 to 85 | ADS8345E | Samples |
| ADS8345N | ACTIVE | SSOP | DB | 20 | 70 | RoHS \& Green | Call TI | Level-2-260C-1 YEAR | -40 to 85 | $\begin{aligned} & \text { ADS8345N } \\ & \text { B } \end{aligned}$ | Samples |
| ADS8345N/1K | ACTIVE | SSOP | DB | 20 | 1000 | RoHS \& Green | Call TI | Level-2-260C-1 YEAR | -40 to 85 | $\begin{aligned} & \text { ADS8345N } \\ & \text { B } \end{aligned}$ | Samples |
| ADS8345NB | ACTIVE | SSOP | DB | 20 | 70 | RoHS \& Green | Call TI | Level-2-260C-1 YEAR | -40 to 85 | $\begin{aligned} & \text { ADS8345N } \\ & \text { B } \end{aligned}$ | Samples |

${ }^{(1)}$ The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but Tl does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.
${ }^{(2)}$ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed $0.1 \%$ by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free"
RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption
Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the $<=1000 \mathrm{ppm}$ threshold requirement
${ }^{(3)}$ MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature
${ }^{(4)}$ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
${ }^{(5)}$ Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
${ }^{(6)}$ Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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TAPE AND REEL INFORMATION


TAPE DIMENSIONS


| A0 | Dimension designed to accommodate the component width |
| :---: | :--- |
| B0 | Dimension designed to accommodate the component length |
| K0 | Dimension designed to accommodate the component thickness |
| W | Overall width of the carrier tape |
| P1 | Pitch between successive cavity centers |

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | $\begin{gathered} \mathrm{AO} \\ (\mathrm{~mm}) \end{gathered}$ | $\begin{gathered} \text { B0 } \\ (\mathrm{mm}) \end{gathered}$ | $\begin{gathered} \mathrm{KO} \\ (\mathrm{~mm}) \end{gathered}$ | $\begin{gathered} \mathrm{P} 1 \\ (\mathrm{~mm}) \end{gathered}$ | $\begin{gathered} \mathrm{W} \\ (\mathrm{~mm}) \end{gathered}$ | Pin1 <br> Quadrant |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ADS8345E/2K5 | SSOP | DBQ | 20 | 2500 | 330.0 | 16.4 | 6.5 | 9.0 | 2.1 | 8.0 | 16.0 | Q1 |
| ADS8345N/1K | SSOP | DB | 20 | 1000 | 330.0 | 16.4 | 8.2 | 7.5 | 2.5 | 12.0 | 16.0 | Q1 |


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ADS8345E/2K5 | SSOP | DBQ | 20 | 2500 | 356.0 | 356.0 | 35.0 |
| ADS8345N/1K | SSOP | DB | 20 | 1000 | 356.0 | 356.0 | 35.0 |

## TUBE



- B - Alignment groove width
*All dimensions are nominal

| Device | Package Name | Package Type | Pins | SPQ | L(mm) | W (mm) | T $(\boldsymbol{\mu m})$ | B (mm) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ADS8345E | DBQ | SSOP | 20 | 50 | 506.6 | 8 | 3940 | 4.32 |
| ADS8345EB | DBQ | SSOP | 20 | 50 | 506.6 | 8 | 3940 | 4.32 |
| ADS8345N | DB | SSOP | 20 | 70 | 530 | 10.5 | 4000 | 4.1 |
| ADS8345NB | DB | SSOP | 20 | 70 | 530 | 10.5 | 4000 | 4.1 |

DBQ (R-PDSO-G20) PLASTIC SMALL-OUTLINE PACKAGE


NOTES: A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion not to exceed $0.006(0,15)$ per side.
D. Falls within JEDEC MO-137 variation AD.


NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
5. Reference JEDEC registration MO-150.


NOTES: (continued)
6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.


SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL SCALE: 10X

NOTES: (continued)
8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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