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# **INA28x High-Accuracy, Wide Common-Mode Range, Bidirectional Current Shunt Monitors, Zero-Drift Series**

**Technical** [Documents](#page-25-0)

- <span id="page-0-4"></span>Wide Common-Mode Range:  $-14$  V to +80 V
- 
- 
- -
	-
	-
- -
	- 100 V/V: INA286
	-
	- 500 V/V: INA284
	- 1000 V/V: INA285
- Quiescent Current: 900 μA (Max)

# <span id="page-0-2"></span>**2 Applications**

- <span id="page-0-0"></span>
- **Automotive**
- Power Management
- <span id="page-0-3"></span>Solar Inverters

# <span id="page-0-1"></span>**1 Features 3 Description**

Tools & **[Software](#page-25-0)** 

The INA28x family includes the INA282, INA283, INA284, INA285, and INA286 devices. These devices Offset Voltage: ±20 μV<br>CMRR: 140 dB<br>CMRR: 140 dB<br>CMRR: 140 dB sense drops across shunts at common-mode • Accuracy: voltages from –14 V to +80 V, independent of the supply voltage. The low offset of the zero-drift – ±1.4% Gain Error (Max)<br>
– 0.3 uV/°C Offset Drift<br>
architecture enables current sensing with maximum<br>
drops across the shunt as low as 10 mV full-scale drops across the shunt as low as 10 mV full-scale.

– 0.005%/°C Gain Drift (Max) These current sense amplifiers operate from <sup>a</sup> single  $+2.7-V$  to  $+18-V$  supply, drawing a maximum of 900 – 50 V/V: INA282 μA of supply current. These devices are specified over the extended operating temperature range of –40°C to +125°C, and offered in SOIC-8 and – 200 V/V: INA283 VSSOP-8 packages.

#### **Device Information[\(1\)](#page-0-0)**



• Telecom Equipment (1) For all available packages, see the package option addendum at the end of the datasheet.



# **Detailed Block Diagram**



# **Table of Contents**





# <span id="page-1-0"></span>**4 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

### **Changes from Revision B (September 2012) to Revision C Page**



# **Changes from Revision A (July 2010) to Revision B Page**

• Changed devices from product preview to production data. .. [1](#page-0-4)



# <span id="page-2-0"></span>**5 Pin Configuration and Functions**



(1) NC: This pin is not internally connected. Leave the NC pin floating or connect this pin to GND.



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# <span id="page-3-0"></span>**6 Specifications**

# <span id="page-3-1"></span>**6.1 Absolute Maximum Ratings**

Over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>



(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

 $V_{+IN}$  and  $V_{-IN}$  are the voltages at the +IN and –IN pins, respectively.

(3) Input voltages must not exceed common-mode rating.

# <span id="page-3-2"></span>**6.2 ESD Ratings**

<span id="page-3-6"></span><span id="page-3-5"></span>

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

# <span id="page-3-3"></span>**6.3 Recommended Operating Conditions**

over operating free-air temperature range (unless otherwise noted)



# <span id="page-3-4"></span>**6.4 Thermal Information**



(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953.](http://www.ti.com/lit/pdf/spra953)



## <span id="page-4-0"></span>**6.5 Electrical Characteristics**

At  $T_A = 25^{\circ}$ C, V+ = 5 V, V<sub>+IN</sub> = 12 V, V<sub>REF1</sub> = V<sub>REF2</sub> = 2.048 V referenced to GND, and V<sub>SENSE</sub> = V<sub>+IN</sub> – V<sub>-IN</sub> (unless otherwise noted)



<span id="page-4-1"></span>(1) RTI = referred-to-input.

(2) See typical characteristic graph [Figure](#page-6-1) 7.

(3) The average of the voltage on pins REF1 and REF2 must be between  $V_{GND}$  and the lesser of ( $V_{GND}$  + 9 V) and V+.

(4) Reference divider accuracy specifies the match between the reference divider resistors using the configuration in [Figure](#page-16-0) 36.

(5) See typical characteristic graph [Figure](#page-6-1) 12.

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### **Electrical Characteristics (continued)**

At  $T_A = 25^{\circ}$ C, V+ = 5 V, V<sub>+IN</sub> = 12 V, V<sub>REF1</sub> = V<sub>REF2</sub> = 2.048 V referenced to GND, and V<sub>SENSE</sub> = V<sub>+IN</sub> – V<sub>-IN</sub> (unless otherwise noted)



(6) See typical characteristic graphs [Figure](#page-7-0) 16 through Figure 18.

(7) See typical characteristic graph [Figure](#page-6-2) 1 and the *Effective [Bandwidth](#page-13-1)* section.



### <span id="page-6-0"></span>**6.6 Typical Characteristics**

<span id="page-6-2"></span><span id="page-6-1"></span>

#### **[INA282,](http://www.ti.com/product/ina282?qgpn=ina282) [INA283](http://www.ti.com/product/ina283?qgpn=ina283), [INA284](http://www.ti.com/product/ina284?qgpn=ina284), [INA285](http://www.ti.com/product/ina285?qgpn=ina285), [INA286](http://www.ti.com/product/ina286?qgpn=ina286)**

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## **Typical Characteristics (continued)**

At  $T_A = 25^{\circ}$ C, V+ = 5 V, V<sub>+IN</sub> = 12 V, V<sub>REF1</sub> = V<sub>REF2</sub> = 2.048 V referenced to GND, and V<sub>SENSE</sub> = V<sub>+IN</sub> – V<sub>-IN</sub> (unless otherwise noted)



<span id="page-7-0"></span>8 *Submit [Documentation](http://www.go-dsp.com/forms/techdoc/doc_feedback.htm?litnum=SBOS485C&partnum=INA282) Feedback* Copyright © 2009–2015, Texas Instruments Incorporated



### **Typical Characteristics (continued)**

<span id="page-8-0"></span>

#### **[INA282,](http://www.ti.com/product/ina282?qgpn=ina282) [INA283](http://www.ti.com/product/ina283?qgpn=ina283), [INA284](http://www.ti.com/product/ina284?qgpn=ina284), [INA285](http://www.ti.com/product/ina285?qgpn=ina285), [INA286](http://www.ti.com/product/ina286?qgpn=ina286)**

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# **Typical Characteristics (continued)**

<span id="page-9-0"></span>



# **Typical Characteristics (continued)**



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# **Typical Characteristics (continued)**





# <span id="page-12-0"></span>**7 Detailed Description**

# <span id="page-12-1"></span>**7.1 Overview**

The INA28x family of voltage output current-sensing amplifiers are specifically designed to accurately measure voltages developed across current-sensing resistors on common-mode voltages that far exceed the supply voltage powering the devices. This family features a common-mode range that extends 14 V below the negative supply rail, as well as up to 80 V, allowing for either low-side or high-side current sensing while the device is powered from supply voltages as low as 2.7 V.

The zero-drift topology enables high-precision measurements with maximum input offset voltages as low as 70  $\mu$ V with a maximum temperature contribution of 1.5  $\mu$ V/°C over the full temperature range of  $-40^{\circ}$ C to +125°C.

#### <span id="page-12-2"></span>**7.2 Functional Block Diagram**





# <span id="page-13-0"></span>**7.3 Feature Description**

# **7.3.1 Selecting R<sub>S</sub>**

The zero-drift offset performance of the INA28x family offers several benefits. Most often, the primary advantage of the low offset characteristic enables lower full-scale drops across the shunt. For example, nonzero-drift, current-shunt monitors typically require a full-scale range of 100 mV. The INA28x family gives equivalent accuracy at a full-scale range on the order of 10 mV. This accuracy reduces shunt dissipation by an order of magnitude, with many additional benefits. Alternatively, applications that must measure current over a wide dynamic range can take advantage of the low offset on the low end of the measurement. Most often, these applications can use the lower gains of the INA282, INA286, or INA283 to accommodate larger shunt drops on the upper end of the scale. For instance, an INA282 operating on a 3.3-V supply can easily handle a full-scale shunt drop of 55 mV, with only 70 μV of offset.

# <span id="page-13-1"></span>**7.3.2 Effective Bandwidth**

The extremely high dc CMRR of the INA28x family results from the switched-capacitor input structure. Because of this architecture, the INA28x exhibits discrete time-system behaviors, as illustrated in the *Gain vs Frequency* curve of [Figure](#page-6-2) 1 and the *Step Response* curves of [Figure](#page-8-0) 21 through [Figure](#page-9-0) 28. The response to a step input depends in part on the phase of the internal INA28x clock when the input step occurs. It is possible to overload the input amplifier with a rapid change in input common-mode voltage (see [Figure](#page-6-2) 4). Errors as a result of common-mode voltage steps or overload situations typically disappear within 15 μs after the disturbance is removed.

### **7.3.3 Transient Protection**

The –14-V to +80-V common-mode range of the INA28x family is ideal for withstanding automotive fault conditions that range from 12-V battery reversal up to 80-V transients; no additional protective components are needed up to those levels. In the event that the INA28x family is exposed to transients on the inputs in excess of its ratings, then external transient absorption with semiconductor transient absorbers (Zener diodes or transorbs) are required. Use of metal-oxide varistors (MOVs) or voltage-dependent resistors (VDRs) is not recommended except when they are used in addition to a semiconductor transient absorber. Select a transient absorber that does not allow the INA28x family to be exposed to transients greater than 80 V (that is, allow for transient absorber tolerance, as well as additional voltage as a result of transient absorber dynamic impedance). Despite the use of internal zener-type electrostatic discharge (ESD) protection, the INA28x family does not lend itself to using external resistors in series with the inputs without degrading gain accuracy.



#### <span id="page-14-0"></span>**7.4 Device Functional Modes**

# <span id="page-14-4"></span>**7.4.1 Reference Pin Connection Options**

<span id="page-14-3"></span>[Figure](#page-14-1) 32 illustrates a test circuit for reference-divider accuracy. The output of the INA28x family can be connected for unidirectional or bidirectional operation. Do not connect the REF1 pin or the REF2 pin to any voltage source lower than GND or higher than V+. The effective reference voltage (REF1 + REF2) / 2 must be 9 V or less. This parameter means that the V+ reference output connection shown in [Figure](#page-15-0) 34 is not allowed for a V+ value greater than 9 V. However, the split-supply reference connection shown in [Figure](#page-16-0) 36 is allowed for all values of V+ up to 18 V.



(1) Reference divider accuracy is determined by measuring the output with the reference voltage applied to alternate reference resistors, and calculating a result where the amplifier offset is cancelled in the final measurement.

#### **Figure 32. Test Circuit For Reference Divider Accuracy**

#### <span id="page-14-1"></span>*7.4.1.1 Unidirectional Operation*

Unidirectional operation allows the INA28x family to measure currents through a resistive shunt in one direction. In the case of unidirectional operation, set the output at the negative rail (near ground, and the most common connection) or at the positive rail (near V+) when the differential input is 0 V. The output moves to the opposite rail when a correct polarity differential input voltage is applied.

The required polarity of the differential input depends on the output voltage setting. If the output is set at the positive rail, the input polarity must be negative to move the output down. If the output is set at ground, the polarity is positive to move the output up.

The following sections describe how to configure the output for unidirectional operation.

#### **7.4.1.1.1 Ground Referenced Output**

<span id="page-14-2"></span>When using the INA28x family in ground referenced output mode, both reference inputs are connected to ground; this configuration takes the output to the negative rail when there is 0 V differential at the input (as [Figure](#page-14-2) 33 shows).



**Figure 33. Ground Referenced Output**

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## **Device Functional Modes (continued)**

#### **7.4.1.1.2 V+ Referenced Output**

<span id="page-15-2"></span>V+ referenced output mode is set when both reference pins are connected to the positive supply. This mode is typically used when a diagnostic scheme requires detection of the amplifier and the wiring before power is applied to the load (as shown in [Figure](#page-15-0) 34).



**Figure 34. V+ Referenced Output**

#### <span id="page-15-0"></span>*7.4.1.2 Bidirectional Operation*

Bidirectional operation allows the INA28x family to measure currents through a resistive shunt in two directions. In this case, the output can be set anywhere within the limits of what the reference inputs allow (that is, between 0 V to 9 V, but never to exceed the supply voltage). Typically, the reference inputs are set at half-scale for equal range in both directions. In some cases, however, the reference inputs are set at a voltage other than half-scale when the bidirectional current is nonsymmetrical.

The quiescent output voltage is set by applying voltage or voltages to the reference inputs. REF1 and REF2 are connected to internal resistors that connect to an internal offset node. There is no operational difference between the pins.

#### **7.4.1.2.1 External Reference Output**

<span id="page-15-1"></span>Connecting both pins together and to a reference produces an output at the reference voltage when there is no differential input; this configuration is illustrated in [Figure](#page-15-1) 35. The output moves down from the reference voltage when the input is negative relative to the –IN pin and up when the input is positive relative to the –IN pin. Note that this technique is the most accurate way to bias the output to a precise voltage.



**Figure 35. External Reference Output**



## **Device Functional Modes (continued)**

#### **7.4.1.2.2 Splitting The Supply**

<span id="page-16-2"></span>By connecting one reference pin to V+ and the other to the ground pin, the output is set at half of the supply when there is no differential input, as shown in [Figure](#page-16-0) 36. This method creates a midscale offset that is ratiometric to the supply voltage; thus, if the supply increases or decreases, the output remains at half the supply.



**Figure 36. Split-Supply Output**

#### <span id="page-16-0"></span>**7.4.1.2.3 Splitting an External Reference**

In this case, an external reference is divided by two with an accuracy of approximately 0.5% by connecting one REF pin to ground and the other REF pin to the reference (as [Figure](#page-16-1) 37 illustrates).



**Figure 37. Split Reference Output**

# <span id="page-16-1"></span>**7.4.2 Shutdown**

While the INA28x family does not provide a shutdown pin, the quiescent current of 600 μA enables the device to be powered from the output of a logic gate. Take the gate low to shut down the INA28x family devices.

# **7.4.3 Extended Negative Common-Mode Range**

Using a negative power supply can extend the common-mode range 14 V more negative than the supply used. For instance, a –10-V supply allows up to a –24-V negative common-mode. Remember to keep the total voltage between the GND pin and V+ pin to less than 18 V. The positive common-mode decreases by the same amount.

The reference input simplifies this type of operation because the output quiescent bias point is always based on the reference connections. [Figure](#page-17-0) 38 shows a circuit configuration for common-mode ranges from  $-24$  V to  $+70$ V.

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# <span id="page-17-1"></span>**Device Functional Modes (continued)**



(1) Connect the REF pins as desired; however, they cannot exceed 9 V above the GND pin voltage.

### **Figure 38. Circuit Configuration for Common-Mode Ranges from –24 V to +70 V**

#### <span id="page-17-2"></span><span id="page-17-0"></span>**7.4.4 Calculating Total Error**

The electrical specifications for the INA28x family of devices include the typical individual errors terms such as gain error, offset error, and nonlinearity error. Total error including all of these individual error components is not specified in the *Electrical [Characteristics](#page-4-0)* table. In order to accurately calculate the expected error of the device, the operating conditions of the device must first be known. Some current shunt monitors specify a total error in the product data sheet. However, this total error term is accurate under only one particular set of operating conditions. Specifying the total error at this one point has little practical value because any deviation from these specific operating conditions no longer yields the same total error value. This section discusses the individual error sources, with information on how to apply them in order to calculate the total error value for the device under any normal operating conditions.

The typical error sources that have the largest impact on the total error of the device are input offset voltage, common-mode rejection ratio, gain error, and nonlinearity error. For the INA28x, an additional error source referred to as *reference voltage rejection ratio* is also included in the total error value.

The nonlinearity error of the INA28x is relatively low compared to the gain error specification. This low error results in a gain error that can be expected to be relatively constant throughout the linear input range of the device. While the gain error remains constant across the linear input range of the device, the error associated with the input offset voltage does not. As the differential input voltage developed across a shunt resistor at the input of the INA28x decreases, the inherent input offset voltage of the device becomes a larger percentage of the measured input signal resulting in an increase in error in the measurement. This varying error is present among all current shunt monitors, given the input offset voltage ratio to the voltage being sensed by the device. The relatively low input offset voltages present in the INA28x devices limit the amount of contribution the offset voltage has on the total error term.

The term *reference voltage rejection ratio* refers to the amount of error induced by applying a reference voltage to the INA28x device that deviates from the inherent bias voltage present at the output of the first stage of the device. The output of the switched-capacitor network and first-stage amplifier has an inherent bias voltage of approximately 2.048 V. Applying a reference voltage of 2.048 V to the INA28x reference pins results in no additional error term contribution. Applying a voltage to the reference pins that differs from 2.048 V creates a voltage potential in the internal difference amplifier, resulting in additional current flowing through the resistor network. As a result of resistor tolerances, this additional current flow causes additional error at the output because of resistor mismatches. Additionally, as a result of resistor tolerances, this additional current flow causes additional error at the output based on the common-mode rejection ratio of the output stage amplifier. This error term is referred back to the input of the device as additional input offset voltage. Increasing the difference between the 2.048 V internal bias and the external reference voltage results in a higher input offset voltage. Also, as the error at the output is referred back to the input, there is a larger impact on the input-referred offset,  $V_{OS}$ , for the lower-gain versions of the device.



#### **Device Functional Modes (continued)**

Two examples are provided that detail how different operating conditions can affect the total error calculations. Typical and maximum calculations are shown as well, to provide the user more information on how much error variance is present from device to device.

#### *7.4.4.1 Example 1*

# INA282; V+ = 5 V; V<sub>CM</sub> = 12 V; V<sub>REF1</sub> = V<sub>REF2</sub> = 2.048 V; V<sub>SENSE</sub> = 10 mV

<span id="page-18-2"></span><span id="page-18-0"></span>

# **Table 1. Example 1**

# *7.4.4.2 Example 2*

<span id="page-18-1"></span>INA286; V+ = 5 V; V<sub>CM</sub> = 24 V; V<sub>REF1</sub> = V<sub>REF2</sub> = 0 V; V<sub>SENSE</sub> = 10 mV



#### **Table 2. Example 2**

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# <span id="page-19-0"></span>**8 Applications and Implementation**

### **NOTE**

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

# <span id="page-19-1"></span>**8.1 Application Information**

The INA28x family of devices measure the voltage developed across a current-sensing resistor when current passes through it. The ability to drive the reference pins to adjust the functionality of the output signal is shown in multiple configurations.

### **8.1.1 Basic Connections**

<span id="page-19-3"></span>[Figure](#page-19-2) 39 shows the basic connection of an INA28x family device. Connect the input pins, +IN and –IN, as closely as possible to the shunt resistor to minimize any resistance in series with the shunt resistance.



**Figure 39. Basic Connections**

<span id="page-19-2"></span>Power-supply bypass capacitors are required for stability. Applications with noisy or high-impedance power supplies may require additional decoupling capacitors to reject power-supply noise. Connect bypass capacitors close to the device pins.

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# <span id="page-20-0"></span>**8.2 Typical Applications**

# **8.2.1 Current Summing**

<span id="page-20-2"></span>The outputs of multiple INA28x family devices are easily summed by connecting the output of one INA28x family device to the reference input of a second INA28x family device. The circuit configuration shown in [Figure](#page-20-1) 40 is an easy way to achieve current summing.



<span id="page-20-1"></span>NOTE: The voltage applied to the reference inputs must not exceed 9 V.

#### **Figure 40. Summing the Outputs of Multiple INA28x Family Devices**

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## **Typical Applications (continued)**

#### *8.2.1.1 Design Requirements*

In order to sum multiple load currents, multiple INA28x devices must be connected. [Figure](#page-20-1) 40 shows summing for two devices. Summing beyond two devices is possible by repeating this connection. The reference input of the first INA28x family device sets the output quiescent level for all the devices in the string.

#### *8.2.1.2 Detailed Design Procedure*

Connect the output of one INA28x family device to the reference input of the next INA28x family device in the chain. Use the reference input of the first circuit to set the reference of the final summed output. The currents sensed at each circuit in the chain are summed at the output of the last device in the chain.

#### *8.2.1.3 Application Curves*

<span id="page-21-0"></span>An example output response of a summing configuration is shown in [Figure](#page-21-0) 41. The reference pins of the first circuit are connected to ground, and sine waves at different frequencies are applied to the two circuits to produce a summed output as shown. The sine wave voltage input for the first circuit is offset so that the whole wave is above GND.



 $V_{BEF} = 0 V$ 

**Figure 41. Current Summing Application Output Response**



# **Typical Applications (continued)**

### **8.2.2 Current Differencing**

<span id="page-22-1"></span>Occasionally, the need arises to confirm that the current into a load is identical to the current out of a load, usually as part of diagnostic testing or fault detection. This situation requires precision current differencing, which is the same as summing except that the two amplifiers have the inputs connected opposite of each other.



<span id="page-22-0"></span>NOTE: The voltage applied to the reference inputs must not exceed 9 V.

#### **Figure 42. Current Differencing Using an INA28x Family Device**

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## **Typical Applications (continued)**

#### *8.2.2.1 Design Requirements*

For current differencing, connect two INA28x devices, and have the inputs connected opposite to each other, as shown in [Figure](#page-22-0) 42. The reference input of the first INA28x family device sets the output quiescent level for all the devices in the string.

#### *8.2.2.2 Detailed Design Procedure*

Connect the output of one INA28x family device to the reference input of the second INA28x family device. The reference input of the first circuit sets the reference at the output. This circuit example is identical to the current summing example, except that the two shunt inputs are reversed in polarity. Under normal operating conditions, the final output is very close to the reference value and proportional to any current difference. This current differencing circuit is useful in detecting when current in to and out of a load do not match.

#### *8.2.2.3 Application Curves*

<span id="page-23-0"></span>An example output response of a difference configuration is shown in [Figure](#page-23-0) 43. The reference pins of the first circuit are connected to a reference voltage of 2.048 V. The inputs to each circuit is a 100-Hz sine wave, 180° out of phase with each other, resulting in a zero output as shown. The sine wave input to the first circuit is offset so that the input wave is completely above GND.



 $V_{RFF} = 2.048$  V

**Figure 43. Current Differencing Application Output Response**



# <span id="page-24-0"></span>**9 Power Supply Recommendations**

The INA28x family makes accurate measurements well outside of its own power-supply voltage (V+) because the inputs (+IN and –IN) operate anywhere between –14 V and +80 V independent of V+. For example, the V+ power supply can be 5 V while the common-mode voltage being monitored by the shunt may be as high as 80 V. Of course, the output voltage range of the INA28x family is constrained by the V+ supply voltage. Note that when the power to the INA28x family is off (that is, no voltage is supplied to the V+ pin), the input pins (+IN and –IN) are high impedance with respect to ground and typically leak less than  $\pm 1$   $\mu$ A over the full common-mode range of –14 V to +80 V

# <span id="page-24-1"></span>**10 Layout**

### <span id="page-24-2"></span>**10.1 Layout Guidelines**

Connect the input pins to the sensing resistor using a Kelvin or 4-wire connection. This connection technique makes sure that only the current-sensing resistor impedance is detected between the input pins. Poor routing of the current-sensing resistor commonly results in additional resistance present between the input pins. Given the very low ohmic value of the current resistor, any additional high-current carrying impedance causes significant measurement errors.

Place the power-supply bypass capacitor as close as possible to the supply and ground pins. The recommended value of this bypass capacitor is 0.1 μF. Add additional decoupling capacitance to compensate for noisy or highimpedance power supplies.

### <span id="page-24-3"></span>**10.2 Layout Example**





# <span id="page-25-1"></span>**11 Device and Documentation Support**

## <span id="page-25-0"></span>**11.1 Related Links**

[Table](#page-25-7) 3 lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

<span id="page-25-7"></span>

### **Table 3. Related Links**

# <span id="page-25-2"></span>**11.2 Community Resources**

The following links connect to TI community resources. Linked contents are provided *AS IS* by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms](http://www.ti.com/corp/docs/legal/termsofuse.shtml) of [Use.](http://www.ti.com/corp/docs/legal/termsofuse.shtml)

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## <span id="page-25-3"></span>**11.3 Trademarks**

E2E is a trademark of Texas Instruments. All other trademarks are the property of their respective owners.

#### <span id="page-25-4"></span>**11.4 Electrostatic Discharge Caution**



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

# <span id="page-25-5"></span>**11.5 Glossary**

### [SLYZ022](http://www.ti.com/lit/pdf/SLYZ022) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

# <span id="page-25-6"></span>**12 Mechanical, Packaging, and Orderable Information**

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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**FXAS** 



# **PACKAGING INFORMATION**



**(1)** The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the  $\leq$ =1000ppm threshold requirement.



# **PACKAGE OPTION ADDENDUM**

**(3)** MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

**(4)** There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

**(5)** Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

<sup>(6)</sup> Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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#### **OTHER QUALIFIED VERSIONS OF INA282, INA283, INA284, INA285, INA286 :**

• Automotive : [INA282-Q1](http://focus.ti.com/docs/prod/folders/print/ina282-q1.html), [INA283-Q1,](http://focus.ti.com/docs/prod/folders/print/ina283-q1.html) [INA284-Q1](http://focus.ti.com/docs/prod/folders/print/ina284-q1.html), [INA285-Q1,](http://focus.ti.com/docs/prod/folders/print/ina285-q1.html) [INA286-Q1](http://focus.ti.com/docs/prod/folders/print/ina286-q1.html)

NOTE: Qualified Version Definitions:

• Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

**TEXAS** 

## **TAPE AND REEL INFORMATION**

**ISTRUMENTS** 





#### **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**







# **PACKAGE MATERIALS INFORMATION**

www.ti.com 20-Feb-2024





# **TEXAS NSTRUMENTS**

www.ti.com 20-Feb-2024

# **TUBE**



# **B - Alignment groove width**

### \*All dimensions are nominal





# **PACKAGE OUTLINE**

# **DGK0008A VSSOP - 1.1 mm max height**

SMALL OUTLINE PACKAGE



NOTES:

PowerPAD is a trademark of Texas Instruments.

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-187.



# **EXAMPLE BOARD LAYOUT**

#### **DGK0008A VSSOP - 1.1 mm max height** TM

SMALL OUTLINE PACKAGE



NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- 8. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown
- on this view. It is recommended that vias under paste be filled, plugged or tented.
- 9. Size of metal pad may vary due to creepage requirement.



# **EXAMPLE STENCIL DESIGN**

# **DGK0008A VSSOP - 1.1 mm max height** TM

SMALL OUTLINE PACKAGE



NOTES: (continued)

11. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

12. Board assembly site may have different recommendations for stencil design.





# **PACKAGE OUTLINE**

# **D0008A SOIC - 1.75 mm max height**

SMALL OUTLINE INTEGRATED CIRCUIT



NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.

- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



# **EXAMPLE BOARD LAYOUT**

# **D0008A SOIC - 1.75 mm max height**

SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



# **EXAMPLE STENCIL DESIGN**

# **D0008A SOIC - 1.75 mm max height**

SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

9. Board assembly site may have different recommendations for stencil design.



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