

# THVD24xxV-EP Enhanced 3V to 5.5V RS-485 Transceivers With 1.8V VIO Capability

#### 1 Features

- Meets or exceeds the requirements of the TIA/ EIA-485A and TIA/EIA-422B standards
- **Enhanced Product** 
  - Military temperature range (-55°C to 125°C)
  - One wafer fabrication site and one assembly and test site
  - Gold bond wire, NiPdAu lead finish
  - Wafer lot traceability
  - Extended product life cycle
- 3V to 5.5V supply voltage
- Differential output exceeds 2.1V for PROFIBUS compatibility with 5V supply
- 1.65V to 5.5V Supply for data and enable signals
- SLR Pin Selectable Data Rates:
  - THVD2410V-EP: 250kbps and 1Mbps
  - THVD2450V-EP, THVD2452V-EP: 20Mbps and 50Mbps
- Bus I/O protection
  - ±70V DC bus fault
  - ±16kV HBM ESD
  - THVD2410V-EP, THVD2450V-EP
    - ±15kV IEC 61000-4-2 contact and air-gap discharge
  - THVD2452V-EP
    - ±8kV IEC 61000-4-2 contact and air-gap discharge
  - ±4kV IEC 61000-4-4 fast transient burst
- Half-duplex and full-duplex devices available in two speed grades
- Symmetric common mode voltage range: ±12V
- Enhanced receiver hysteresis for noise immunity
- Low power consumption
  - Low shutdown supply current: < 1μA</li>
  - Current during operation: < 5.3mA</li>
- Glitch-free power-up/down for hot plug-in capability
- Open, short, and idle bus failsafe
- Thermal shutdown
- 1/8 unit load (up to 256 bus nodes)
- Small mm x 3mm VSON package (half-duplex) to save board space, or 14-D (full-duplex) for drop-in compatibility

### 2 Applications

- **Avionics**
- **Smart munitions**
- Sensors, imaging and radar
- Ruggedized communication

### 3 Description

THVD24xxV-EP are ±70V fault-protected, half and full-duplex RS-422/RS-485 transceivers using a 1.65V to 5.5V logic supply for data and enable logic signals. and a 3V to 5.5V bus side supply. These devices have slew rate select feature that enables them to be used at two maximum speeds based on the SLR pin setting

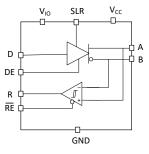
These devices feature integrated IEC ESD protection, eliminating the need for external system-level protection components. The ±12V input commonmode range makes reliable data communication over longer cable run lengths and/or in the presence of large ground loop voltages. Enhanced 250mV receiver hysteresis provides high noise rejection. In addition, the receiver fail-safe feature makes sure of a logic high when the inputs are open or shorted together.

THVD24xxV-EP half-duplex devices are available in small VSON package for space-constrained applications. The devices are available in standard 14-SOIC package.

#### **Package Information**

PART NUMBER	BER PACKAGE <sup>(1)</sup> PACKAGE			
THVD2410V-EP THVD2450V-EP	VSON (10)	3mm × 3mm		
THVD2452V-EP	SOIC (14)	8.65mm × 6mm		

- For more information, see Section 11.
- The package size (length × width) is a nominal value and includes pins, where applicable.



THVD2410V-EP and THVD2450V-EP Simplified **Schematic** 



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# **4 Pin Configuration and Functions**

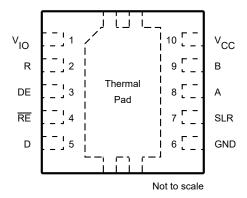


Figure 4-1. THVD2410V-EP, THVD2450V-EP 10-Pin DRC Package (VSON) (Top View)

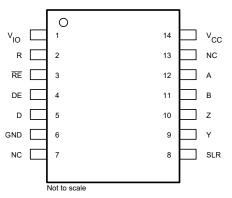


Figure 4-2. THVD2452V-EP 14-Pin D Package (SOIC) (Top View)

**Table 4-1. Pin Functions** 

NAME	PIN NO. DRC D		TYPE	DESCRIPTION	
NAME			ITPE	DESCRIPTION	
V <sub>IO</sub>	1	1	Logic Supply	1.65V to 5.5V supply for logic I/O signals R, $\overline{\text{RE}}$ , D, DE, and SLR)	
R	2	2	Digital Output	eceive data output	
DE	3	4	Digital Input	river enable input; integrated pull-down	
RE	4	3	Digital Input	Receiver enable input; integrated pull-up	
D	5	5	Digital Input	Transmission data input; integrated pull-up	
GND	6	6	Reference Potential	Local device ground	
SLR	7	8	Digital Input	Slew rate select; integrated pull-down. For THVD2410V-EP: Low = 1Mbps, High = 250kbps. Defaults to 1Mbps if SLR is left floating. For THVD2450V-EP and THVD2452V-EP: Low = 50Mbps, High = 20Mbps. Defaults to 50Mbps if left floating.	
A	8	12	Bus Input	Bus I/O (half-duplex), bus input (full-duplex)	
В	9	11	Bus Input	Bus I/O (half-duplex), bus input (full-duplex)	
V <sub>CC</sub>	10	14	Bus Supply	3V to 5.5V supply for the transceiver	
Υ	-	9	Bus Output	Bus output, Y	
Z	-	10	Bus Output	Bus output, Z	
NC	-	7, 13		No connect pin. Internally not connected	



### **5 Specifications**

### 5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) (1) (2)

		MIN	MAX	UNIT
Logic supply voltage	V <sub>IO</sub>	-0.5	V <sub>CC</sub> + 0.2	V
Bus supply voltage	V <sub>CC</sub>	-0.5	6.5	V
Bus voltage	Range at any bus pin as differential or common-mode with respect to GND	-70	70	V
Input voltage	Range at any logic pin (D, DE, SLR or RE)	-0.3	V <sub>IO</sub> + 0.2	V
Receiver output current	Io	-24	24	mA
Storage temperature	$T_{stg}$	-65	170	°C

- (1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.
- (2) All voltage values, except differential I/O bus voltages, are with respect to ground terminal.

### 5.2 ESD Ratings

				VALUE	UNIT
	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/	Bus terminals and GND	±16,000	V
V <sub>(ESD)</sub>		JEDEC JS-001 <sup>(1)</sup>	All pins except bus terminals and GND	±4,000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>		±1,500	V

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

# 5.3 ESD Ratings [IEC]

				VALUE	UNIT
	Electrostatic discharge, Half	Contact discharge, per IEC 61000-4-2	Bus terminals and GND	±15,000	.,
V <sub>(ESD)</sub>	duplex devices THVD2410V/ 2450V-EP (1) Air-gap discharge, per IEC 61000-4-2 Bus ter		Bus terminals and GND	±15,000	V
.,	Electrostatic discharge, Full	Contact discharge, per IEC 61000-4-2	Bus terminals and GND	±8,000	.,
V <sub>(ESD)</sub>	duplex devices THVD2452V- EP (1)	Air-gap discharge, per IEC 61000-4-2	Bus terminals and GND	±8,000	V
V <sub>(EFT)</sub>	Electrical fast transient	Per IEC 61000-4-4	Bus terminals	±4,000	V

(1) For optimized IEC ESD performance, it is recommended to have series resistor (≥ 50 Ω) on all logic inputs to minimize transient currents going into or out of the logic pins.

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# **5.4 Recommended Operating Conditions**

over operating free-air temperature range (unless otherwise noted)

			MIN	NOM	MAX	UNIT
V <sub>CC</sub>	Supply voltage		3		5.5	V
V <sub>IO</sub>	I/O supply voltage	supply voltage  ut voltage at any bus terminal (separately or common mode) <sup>(1)</sup> uh-level input voltage (driver, driver enable, receiver enable and slew rate selectuts)  v-level input voltage (driver, driver enable, receiver enable and slew rate selectuts)  ferential input voltage bus pins  tput current, driver  tput current, receiver  V <sub>IO</sub> = 1.8 V or 2.5 V  tput current, receiver  V <sub>IO</sub> = 3.3 V or 5 V  ferential load resistance  THVD2410V, THVD2412V with SLR = V <sub>IO</sub> THVD2410V, THVD2412V with SLR = GN or floating			V <sub>CC</sub>	V
VI	Input voltage at any bus termin	supply voltage  It voltage at any bus terminal (separately or common mode) <sup>(1)</sup> In-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver enable, receiver enable and slew rate select ats)  Ir-level input voltage (driver, driver)  Ir-level input voltage (driver, dri			12	V
V <sub>IH</sub>	High-level input voltage (driver inputs)	High-level input voltage (driver, driver enable, receiver enable and slew rate select nputs)			V <sub>IO</sub>	V
V <sub>IL</sub>	Low-level input voltage (driver, inputs)	driver enable, receiver enable and slew rate select	0		0.3*V <sub>IO</sub>	V
V <sub>ID</sub>	Differential input voltage bus p	ins	-25		25	V
Io	Output current, driver		-60		60	mA
I <sub>OR</sub>	Output current, receiver	V <sub>IO</sub> = 1.8 V or 2.5 V	-4		4	mA
I <sub>OR</sub>	Output current, receiver	V <sub>IO</sub> = 3.3 V or 5 V	-8		8	mA
R <sub>L</sub>	Differential load resistance		54	60		Ω
		THVD2410V, THVD2412V with SLR = V <sub>IO</sub>			250	kbps
4 /4	Simpling rate	· · · · · · · · · · · · · · · · · · ·			1	Mbps
1/t <sub>UI</sub>	Signaling rate	THVD2450V, THVD2452V with SLR = V <sub>IO</sub>			20	Mbps
		THVD2450V, THVD2452V with SLR = GND or floating			50	Mbps
T <sub>A</sub>	Operating ambient temperature	9	-55		125	°C
T <sub>J</sub>	Junction temperature		-55		150	°C

<sup>(1)</sup> The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet.

### 5.5 Thermal Information

		THVD2410V-EP THVD2450V-EP	THVD2452V-EP	
THERMAL METRIC <sup>(1)</sup>		DRC (VSON)	D (SOIC)	UNIT
		10 PINS	14 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	46.7	87.5	°C/W
R <sub>0</sub> JC(top)	Junction-to-case (top) thermal resistance	47.7	41.8	°C/W
R <sub>0JB</sub>	Junction-to-board thermal resistance	19.1	43.7	°C/W
ΨЈТ	Junction-to-top characterization parameter	0.7	8.1	°C/W
ΨЈВ	Junction-to-board characterization parameter	19.1	43.3	°C/W
R <sub>0JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	4.6	N/A	°C/W

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.



### 5.6 Power Dissipation

	PARAMETER	TEST CO	NDITIONS		VALUE	UNIT
			THVD2410V-EP	250 kbps	160	
		Unterminated	THVD2410V-EP	1Mbps	250	mW
		$R_L = 300 \Omega$ , $C_L = 50 pF (driver)$	THVD2450V-EP	20Mbps	310	IIIVV
	Y R connected to Z)		THVD2452V-EP	50 Mbps	630	
		RS-422 load R <sub>L</sub> = 100 $\Omega$ , C <sub>L</sub> = 50 pF (driver)	THVD2410V-EP	250 kbps	170	mW
D D				1Mbps	250	
P <sub>D</sub>			THVD2450V-EP THVD2452V-EP	20Mbps	290	
	square wave at 50% duty cycle			50 Mbps	570	
			THVD2410V-EP	250 kbps	220	
		RS-485 load	THVD2410V-EP	1Mbps	280	mW
		$R_L = 54 \Omega$ , $C_L = 50 pF (driver)$	THVD2450V-EP	20Mbps	325	IIIVV
			THVD2452V-EP	50 Mbps	560	



### **5.7 Electrical Characteristics**

over operating free-air temperature range (unless otherwise noted). All typical values are at  $25^{\circ}$ C and supply voltage of  $V_{CC}$  = 5 V,  $V_{IO}$  = 3.3 V , unless otherwise noted. (1)

	PARAMETER	TEST CONDITIONS		MIN	TYP	MAX	UNIT
Driver							
		$R_L = 60 \Omega$ , $-25 V \le V_{test} \le 25 V$ (See Figure 6-1)		1.5	3.3		V
IV I	Driver differential output	$R_L$ = 60 Ω, -25 V ≤ $V_{test}$ ≤ 25 V, 4.5 V ≤ $V_{CC}$ ≤ 5.5	V (See Figure 6-1)	2.1	3.3		V
V <sub>OD</sub>	voltage magnitude	$R_L$ = 100 $\Omega$ (See Figure 6-2 )		2	4		V
		$R_L = 54 \Omega \text{ (See Figure 6-2)}$		1.5	3.5		V
$\Delta  V_{OD} $	Change in differential output voltage	$R_L$ = 54 Ω or 100 Ω (See Figure 6-2 )		-50		50	mV
V <sub>oc</sub>	Common-mode output voltage	$R_L$ = 54 Ω or 100 Ω (See Figure 6-2 )		1	V <sub>CC</sub> /2	3	V
$\Delta V_{OC(SS)}$	Change in steady-state common-mode output voltage	$R_L$ = 54 Ω or 100 Ω (See Figure 6-2 )		-50		50	mV
I <sub>os</sub>	Short-circuit output current	DE = $V_{IO}$ , -70 V ≤ ( $V_A$ or $V_B$ ) ≤ 70 V, or A shorted terminals for half duplex, Y/Z are for full duplex)	o B (A,B are driver	-250		250	mA
Receiver						1	
			V <sub>I</sub> = 12 V		90	125	μA
	Due issue ourset	DE - 0 V V - 5 T V - 5 T V	V <sub>I</sub> = 25 V		200	250	μA
I <sub>I</sub>	Bus input current	DE = 0 V, $V_{CC}$ and $V_{IO}$ = 0 V or 5.5 V	V <sub>I</sub> = -7 V	-100	-80		μA
			V <sub>I</sub> = -25 V	-350	-220	50 3 50 250 250 200 -40 40 0.4 1 5	μA
V <sub>TH+</sub>	Positive-going input threshold voltage (2)			40	125	200	mV
V <sub>TH-</sub>	Negative-going input threshold voltage (2)	Over common-mode range of ± 12 V	ver common-mode range of ± 12 V		-125	-40	mV
V <sub>HYS</sub>	Input hysteresis				250		mV
V <sub>TH_FSH</sub>	Input fail-safe threshold					40	mV
C <sub>A,B</sub>	Input differential capacitance	Measured between A and B, f = 1 MHz			50		pF
V <sub>OH</sub>	Output high voltage	I <sub>OH</sub> = -8 mA, V <sub>IO</sub> = 3 to 3.6 V or 4.5 V to 5.5 V		V <sub>IO</sub> - 0.4	V <sub>IO</sub> – 0.2		V
V <sub>OL</sub>	Output low voltage	I <sub>OL</sub> = 8 mA, V <sub>IO</sub> = 3 to 3.6 V or 4.5 V to 5.5 V			0.2	0.4	V
V <sub>OH</sub>	Output high voltage	I <sub>OH</sub> = -4 mA, V <sub>IO</sub> = 1.65 to 1.95 V or 2.25 V to 2.7	5 V	V <sub>IO</sub> - 0.4	V <sub>IO</sub> – 0.2		V
V <sub>OL</sub>	Output low voltage	I <sub>OL</sub> = 4 mA, V <sub>IO</sub> = 1.65 to 1.95 V or 2.25 V to 2.75	V		0.2	0.4	V
l <sub>oz</sub>	Output high-impedance current, R pin	$V_O = 0 \text{ V or } V_{IO}, \overline{RE} = V_{IO}$		-1		1	μA
Logic							
I <sub>IN</sub>	Input current (DE , SLR)	1.65 V ≤ V <sub>IO</sub> ≤ 5.5 V, 0 V ≤ V <sub>IN</sub> ≤ V <sub>IO</sub>				5	μΑ
I <sub>IN</sub>	Input current (D, RE)	$1.65 \text{ V} \le \text{V}_{\text{IO}} \le 5.5 \text{ V}, 0 \text{ V} \le \text{V}_{\text{IN}} \le \text{V}_{\text{IO}}$		-5			μA
Thermal P	rotection						
T <sub>SHDN</sub>	Thermal shutdown threshold	Temperature rising		150	180		°C
T <sub>HYS</sub>	Thermal shutdown hysteresis				10		°C
Supply						'	
UV <sub>VCC</sub>	Rising under-voltage threshold on V <sub>CC</sub>				2.3	2.6	V
UV <sub>VCC</sub> (falling)	Falling under-voltage threshold on V <sub>CC</sub>			1.95	2.2		V
UV <sub>VCC(hys)</sub>	Hysteresis on under-voltage of $V_{\text{CC}}$				150		mV
UV <sub>VIO</sub> (rising)	Rising under-voltage threshold on V <sub>IO</sub>				1.4	1.6	V
UV <sub>VIO</sub>	Falling under-voltage threshold on V <sub>IO</sub>			1.2	1.3		V



### **5.7 Electrical Characteristics (continued)**

over operating free-air temperature range (unless otherwise noted). All typical values are at 25°C and supply voltage of  $V_{CC}$  = 5 V,  $V_{IO}$  = 3.3 V , unless otherwise noted. (1)

	PARAMETER	TEST CONDITIONS		MIN	TYP	MAX	UNIT
UV <sub>VIO(hys)</sub>	Hysteresis on under-voltage of V <sub>IO</sub>				30		mV
l <sub>cc</sub>		Driver and receiver enabled	RE = 0 V, DE = V <sub>IO</sub> , No load		3.5	5.3	mA
	Supply current (quiescent),	Driver enabled, receiver disabled	$\overline{RE}$ = V <sub>IO</sub> , DE = V <sub>IO</sub> , No load		2.5	4.2	mA
ICC	V <sub>CC</sub> = 4.5 V to 5.5 V	Driver disabled, receiver enabled	RE = 0 V, DE = 0 V, No load		1.8	2.4	mA
		Driver and receiver disabled	RE = V <sub>IO</sub> , DE = 0 V, D = open, No load		0.1	1.2	μА
		Driver and receiver enabled	RE = 0 V, DE = V <sub>IO</sub> , No load		3	4.1	mA
	Supply current (quiescent),	Driver enabled, receiver disabled	RE = V <sub>IO</sub> , DE = V <sub>IO</sub> , No load		2	3	mA
'cc	V <sub>CC</sub> = 3 V to 3.6 V	Driver disabled, receiver enabled	RE = 0 V, DE = 0 V, No load		1.6	30	mA
		Driver and receiver disabled	RE = V <sub>IO</sub> , DE = 0 V, D = open, No load		0.1		μA
		Driver disabled, Receiver enabled, SLR = GND	DE = 0 V, RE = 0 V, No load		4.5	8.4	μА
UV <sub>VIO(hys)</sub> $I_{CC}$ $I_{IO}$	Logic supply current (quiescent), V <sub>IO</sub> = 3 to 3.6 V	Driver disabled, Receiver enabled, SLR = V <sub>IO</sub>	DE = 0 V, RE = 0 V, No load		3.3	8.4	μA
IIO		Driver disabled, Receiver disabled, SLR = GND	DE = 0 V, RE = V <sub>IO</sub> , No load		0.1	1	μА
		Driver disabled, Receiver disabled, SLR = V <sub>IO</sub>	DE = 0 V, RE = V <sub>IO</sub> , No load		1.8	30	μА

<sup>(1)</sup> A, B are driver output and receiver input terminals for Half duplex devices; A/B are Receiver input, Y/Z are driver output terminals for Full duplex devices

<sup>(2)</sup> Under any specific conditions,  $V_{TH+}$  is assured to be at least  $V_{HYS}$  higher than  $V_{TH-}$ .



### 5.8 Switching Characteristics - 250 kbps

250-kbps (THVD2410V-EP with SLR =  $V_{IO}$ ) over recommended operating conditions. All typical values are at 25°C and supply voltage of  $V_{CC}$  = 5 V ,  $V_{IO}$  = 3.3 V, unless otherwise noted. (1)

-	PARAMETER	TEST COND	TIONS	MIN	TYP	MAX	UNIT
Driver			,			<u>'</u>	
t <sub>r</sub> , t <sub>f</sub>	Differential output rise/fall time	V <sub>CC</sub> = 3 to 3.6 V, Typical at 3.3V		450	560	1200	ns
		V <sub>CC</sub> = 4.5 to 5.5 V, Typical at 5 V		500	625	1200	ns
	Dropogation dolay	V <sub>CC</sub> = 3 to 3.6 V, Typical at 3.3V	$R_L = 54 \Omega, C_L = 50 pF$		500	720	ns
lPHL, lPLH	Propagation delay	V <sub>CC</sub> = 4.5 to 5.5 V, Typical at 5 V	See Figure 6-3		540	770	ns
	Dulas alsour la la la	V <sub>CC</sub> = 3 to 3.6 V, Typical at 3.3V			10	70	ns
<sup>L</sup> SK(P)	Pulse skew,  t <sub>PHL</sub> - t <sub>PLH</sub>	V <sub>CC</sub> = 4.5 to 5.5 V, Typical at 5 V		Figure 6-6  Figure 6-7  Figure 6-8  Figure 6-9   450  500  500  500  500  500  540  10  40  40  70  7  7  7  800  900  900  7  11  540  800  7  11  540  800	70	ns	
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Disable time	RE = X			40	75	ns
	Enchle time	RE = 0 V	3V 5 V 3V See Figure 6-3  See Figure 6-4 and Figure 6-5  See Figure 6-6		70	280	ns
<sup>L</sup> PZH, <sup>L</sup> PZL	Enable time	RE = V <sub>IO</sub>			2.5	4.5	μs
t <sub>SHDN</sub>	Time to shutdown	RE = V <sub>IO</sub>		50		500	ns
Receiver							
t <sub>r</sub> , t <sub>f</sub>	Output rise/fall time				7	20	ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Propagation delay	C <sub>L</sub> = 15 pF	See Figure 6-6		800	1270	ns
t <sub>SK(P)</sub>	Pulse skew,  t <sub>PHL</sub> - t <sub>PLH</sub>		V V R <sub>L</sub> = 54 Ω, C <sub>L</sub> = 50 pF See Figure 6-3 V V See Figure 6-4 and Figure 6-5  See Figure 6-6 See Figure 6-7 O See Figure 6-8 See Figure 6-9		5	45	ns
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Disable time	DE = X			30	40	ns
+		$V_{IO}$ = 3 V to 3.6 V; DE = $V_{IO}$			90	120	ns
PZH(1)	Enable time	$V_{IO}$ = 1.65 V to 1.95 V, DE = $V_{IO}$	Soo Figure 6.7		100	1200 1200 720 770 70 75 280 4.5 500 20 1270 45	ns
t <sub>r</sub> , t <sub>f</sub> t <sub>PHL</sub> , t <sub>PLH</sub> tsk(P)  t <sub>PHZ</sub> , t <sub>PLZ</sub> t <sub>SHDN</sub> Receiver  t <sub>r</sub> , t <sub>f</sub> t <sub>PHL</sub> , t <sub>PLH</sub> tsk(P)  t <sub>PHL</sub> , t <sub>PLH</sub> tsk(P)  t <sub>PHL</sub> , t <sub>PLH</sub> t <sub>PL</sub> t <sub>P</sub>	Enable time	$V_{IO}$ = 3 V to 3.6 V; DE = $V_{IO}$	See Figure 0-7		900	1320	ns
<sup>L</sup> PZL(1)		$V_{IO}$ = 1.65 V to 1.95 V; DE = $V_{IO}$			900	1320	ns
t <sub>PZH(2)</sub> , t <sub>PZL(2)</sub>	Enable time	DE = 0 V	See Figure 6-8		3.3	5.4	μs
t <sub>D(OFS)</sub>	Delay to enter fail-safe operation	5	Soo Figure 6.0	7	11	18	μs
t <sub>D(FSO)</sub>	Delay to exit fail-safe operation	OL = 10 bc	See Figure 6-3  See Figure 6-4 and Figure 6-5  See Figure 6-6  See Figure 6-7  See Figure 6-8  See Figure 6-9	540	800	1260	ns
t <sub>SHDN</sub>	Time to shutdown	DE = 0 V	See Figure 6-8	50		500	ns

<sup>(1)</sup> A, B are driver output and receiver input terminals for Half duplex devices; A/B are Receiver input, Y/Z are driver output terminals for Full duplex device



### 5.9 Switching Characteristics - 1 Mbps

1Mbps (THVD2410V-EP with SLR = 0 or floating) over recommended operating conditions. All typical values are at 25°C and supply voltage of  $V_{CC}$  = 5 V ,  $V_{IO}$  = 3.3 V, unless otherwise noted. (1)

	PARAMETER	TEST COND	TIONS	MIN	TYP	MAX	UNIT
Driver							
	Differential automotoria (fell time)	V <sub>CC</sub> = 3 to 3.6 V, Typical at 3.3 V		125	150	300	ns
t <sub>r</sub> , t <sub>f</sub>	Differential output rise/fall time	V <sub>CC</sub> = 4.5 to 5.5 V, Typical at 5 V		130	160	300	ns
	B	V <sub>CC</sub> = 3 to 3.6 V, Typical at 3.3 V	$R_1 = 54 \Omega, C_1 = 50 pF$		160	240	ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Propagation delay	V <sub>CC</sub> = 4.5 to 5.5 V, Typical at 5 V	See Figure 6-3		185	280	ns
i	D. I. II. II. I	V <sub>CC</sub> = 3 to 3.6 V, Typical at 3.3 V			2	20	ns
t <sub>SK(P)</sub>	Pulse skew,  t <sub>PHL</sub> - t <sub>PLH</sub>	V <sub>CC</sub> = 4.5 to 5.5 V, Typical at 5 V			2	15	ns
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Disable time	RE = X			40	95	ns
	E 11 C	RE = 0 V	See Figure 6-4		90	275	ns
t <sub>PZH</sub> , t <sub>PZL</sub>	Enable time	RE = V <sub>IO</sub>	and Figure 6-5		3	4.6	μs
t <sub>SHDN</sub>	Time to shutdown	RE = V <sub>IO</sub>	RE = V <sub>IO</sub>			500	ns
Receiver							
t <sub>r</sub> , t <sub>f</sub>	Output rise/fall time				7	15	ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Propagation delay	C <sub>L</sub> = 15 pF	See Figure 6-6		50	85	ns
t <sub>SK(P)</sub>	Pulse skew,  t <sub>PHL</sub> - t <sub>PLH</sub>				4	12.5	ns
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Disable time	DE = X			30	40	ns
t <sub>PZH(1)</sub> ,	E 11 C	V <sub>IO</sub> = 3 V to 3.6 V; DE = V <sub>IO</sub>	0 5 07		90	120	ns
t <sub>PZL(1)</sub>	Enable time	$V_{IO}$ = 1.65 V to 1.95 V; DE = $V_{IO}$	See Figure 6-7		90	130	ns
t <sub>PZH(2)</sub> , t <sub>PZL(2)</sub>	Enable time	DE = 0 V	See Figure 6-8		3	4.5	μs
t <sub>D(OFS)</sub>	Delay to enter fail-safe operation	C = 15 pE	Soo Figure 6.0	7	10	18	μs
t <sub>D(FSO)</sub>	Delay to exit fail-safe operation	C <sub>L</sub> = 15 pF	See Figure 6-9	27	40	60	ns
t <sub>SHDN</sub>	Time to shutdown	DE = 0 V	See Figure 6-8	50		500	ns

<sup>(1)</sup> A, B are driver output and receiver input terminals for Half duplex devices; A/B are Receiver input, Y/Z are driver output terminals for Full duplex device

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### 5.10 Switching Characteristics - 20 Mbps

20-Mbps (THVD2450V-EP, THVD2452V-EP with SLR =  $V_{IO}$ ) over recommended operating conditions. All typical values are at 25°C and supply voltage of  $V_{CC}$  = 5 V,  $V_{IO}$  = 3.3 V, unless otherwise noted. (1)

	PARAMETER	TEST COND	ITIONS	MIN	TYP	MAX	UNIT
Driver							
	Differential output rice (fall time	V <sub>CC</sub> = 3 to 3.6 V, Typical at 3.3 V		4	8	15	ns
t <sub>r</sub> , t <sub>f</sub>	Differential output rise/fall time	V <sub>CC</sub> = 4.5 to 5.5 V, Typical at 5 V		4	7	15	ns
	Decree attended to	V <sub>CC</sub> = 3 to 3.6 V, Typical at 3.3 V	$R_1 = 54 \Omega, C_1 = 50 pF$	6	12	30	ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Propagation delay	V <sub>CC</sub> = 4.5 to 5.5 V, Typical at 5 V	See Figure 6-3	4	9	26	ns
	Dulas alsour la de la	V <sub>CC</sub> = 3 to 3.6 V, Typical at 3.3 V			1	3	ns
t <sub>SK(P)</sub>	Pulse skew,  t <sub>PHL</sub> - t <sub>PLH</sub>	V <sub>CC</sub> = 4.5 to 5.5 V, Typical at 5 V			1	3	ns
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Disable time	RE = X			17	35	ns
	Facility time	RE = 0 V	See Figure 6-4		14	39	ns
t <sub>PZH</sub> , t <sub>PZL</sub>	Enable time	RE = V <sub>IO</sub>	and Figure 6-5		3	4.5	μs
t <sub>SHDN</sub>	Time to shutdown	RE = V <sub>IO</sub>		50		500	ns
Receiver						'	
t <sub>r</sub> , t <sub>f</sub>	Output rise/fall time	C <sub>L</sub> = 15 pF			1.5	6	ns
	Decree attended to	V <sub>IO</sub> = 3 V to 3.6 V	0 Firmer 6 6	25	33	58	ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Propagation delay	V <sub>IO</sub> = 1.65 V to 1.95 V	See Figure 6-6	25	35	60	ns
t <sub>SK(P)</sub>	Pulse skew,  t <sub>PHL</sub> - t <sub>PLH</sub>	C <sub>L</sub> = 15 pF			0.5	5	ns
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Disable time	DE = X			12	25	ns
t <sub>PZH(1)</sub> , t <sub>PZL(1)</sub>	Enable time	DE = V <sub>IO</sub>	See Figure 6-7		50	82	ns
t <sub>PZH(2)</sub> , t <sub>PZL(2)</sub>	Enable time	DE = 0 V	See Figure 6-8		2.8	5	μs
t <sub>D(OFS)</sub>	Delay to enter fail-safe operation	- C <sub>1</sub> = 15 pF	See Figure 6-9	7	10	18	μs
t <sub>D(FSO)</sub>	Delay to exit fail-safe operation	OL - 19 bL	See rigule 0-9	19	32	50	ns
t <sub>SHDN</sub>	Time to shutdown	DE = 0 V	See Figure 6-8	50		500	ns

<sup>(1)</sup> A, B are driver output and receiver input terminals for Half duplex devices; A/B are Receiver input, Y/Z are driver output terminals for Full duplex device



### **5.11 Switching Characteristics - 50 Mbps**

50-Mbps (THVD2450V-EP, THVD2452V-EP with SLR = 0 or floating) over recommended operating conditions. All typical values are at 25°C and supply voltage of  $V_{CC}$  = 5 V,  $V_{IO}$  = 3.3 V, unless otherwise noted. (1)

PARAMETER		TEST CONDIT	MIN	TYP	MAX	UNIT	
Driver			<u>'</u>				
t <sub>r</sub> , t <sub>f</sub>	Differential output rise/fall time	V <sub>IO</sub> = 3 V to 3.6 V, V <sub>CC</sub> = 3 to 3.6 V, Typical at 3.3 V		1	5	7	ns
	·	V <sub>CC</sub> = 4.5 to 5.5 V, Typical at 5 V		1	5	6	ns
		V <sub>IO</sub> = 3 V to 3.6 V, V <sub>CC</sub> = 3 to 3.6 V, Typical at 3.3 V		5	11	19	ns
	t <sub>PLH</sub> Propagation delay	V <sub>IO</sub> = 1.65 V to 1.95 V, V <sub>CC</sub> = 3 to 3.6 V, Typical at 3.3 V	$R_L = 54 \Omega, C_L = 50 pF$	7	12	22	ns
t <sub>PHL</sub> , t <sub>PLH</sub>		V <sub>IO</sub> = 3 V to 3.6 V, V <sub>CC</sub> = 4.5 to 5.5 V, Typical at 5 V	See Figure 6-3	4	8	15	ns
		V <sub>IO</sub> = 1.65 V to 1.95 V, V <sub>CC</sub> = 4.5 to 5.5 V, Typical at 5 V		6	10	19	ns
	Dulas alson la la la	V <sub>CC</sub> = 3 to 3.6 V, Typical at 3.3 V			1	3	ns
t <sub>SK(P)</sub>	Pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub>	V <sub>CC</sub> = 4.5 to 5.5 V, Typical at 5 V			1	3	ns
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Disable time	RE = X			14	30	ns
		RE = 0 V; V <sub>IO</sub> = 1.65 V to 1.95 V, 2.25 V to 2.75 V	See Figure 6-4		20	35	ns
$t_{PZH}$ , $t_{PZL}$	Enable time	$\overline{RE} = 0 \text{ V}$ ; $V_{IO} = 3 \text{ V}$ to $V_{CC} \text{ V}$	and Figure 6-5		15	32	ns
		RE = V <sub>IO</sub>			2.5	4.5	μs
t <sub>SHDN</sub>	Time to shutdown	RE = V <sub>IO</sub>		50		500	ns
Receiver							
t <sub>r</sub> , t <sub>f</sub>	Output rise/fall time	C <sub>L</sub> = 15 pF	See Figure 6-6		1.5	6	ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Propagation delay	C <sub>L</sub> = 15 pF, V <sub>IO</sub> = 3 V to 3.6 V	See Figure 6-6	25	33	58	ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Propagation delay	C <sub>L</sub> = 15 pF, V <sub>IO</sub> = 1.65 V to 1.95 V	See Figure 6-6	25	35	60	ns
t <sub>SK(P)</sub>	Pulse skew,  t <sub>PHL</sub> - t <sub>PLH</sub>	C <sub>L</sub> = 15 pF	See Figure 6-6		0.5	5	ns
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Disable time	DE = X			12	25	ns
t <sub>PZH(1)</sub> ,	Fachle time	DE - V	V <sub>IO</sub> = 1.65 V to 1.95 V, See Figure 6-7		50	82	ns
t <sub>PZL(1)</sub> Enable time	DE = V <sub>IO</sub>	V <sub>IO</sub> = 3 V to 3.6 V, See Figure 6-7		50	75	ns	
t <sub>PZH(2)</sub> , t <sub>PZL(2)</sub>	Enable time	DE = 0 V	See Figure 6-8		2.8	5	μs
t <sub>D(OFS)</sub>	Delay to enter fail-safe operation	C = 15 pE	Soo Figure 6.0	7	10	18	μs
t <sub>D(FSO)</sub>	Delay to exit fail-safe operation	- C <sub>L</sub> = 15 pF	See Figure 6-9	19	32	50	ns
t <sub>SHDN</sub>	Time to shutdown	DE = 0 V	See Figure 6-8	50		500	ns

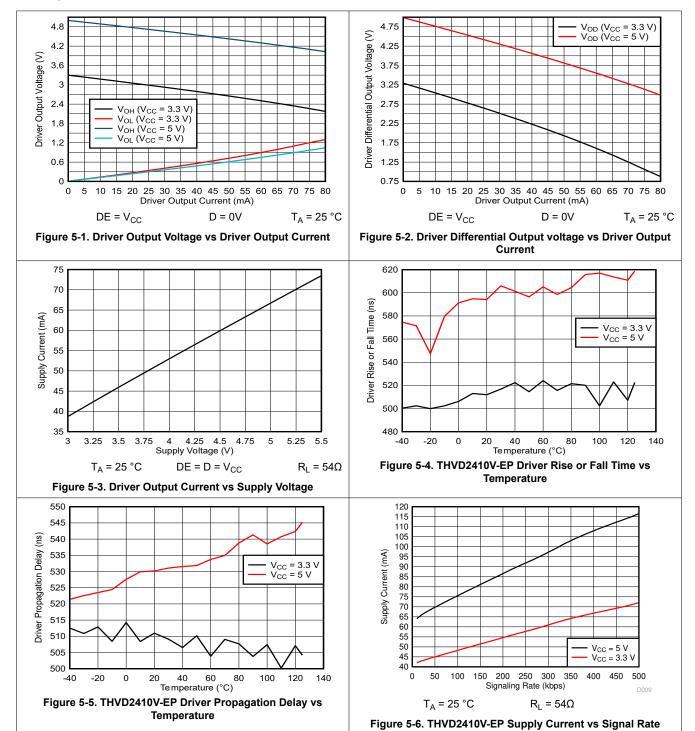
<sup>(1)</sup> A, B are driver output and receiver input terminals for Half duplex devices; A/B are Receiver input, Y/Z are driver output terminals for Full duplex device

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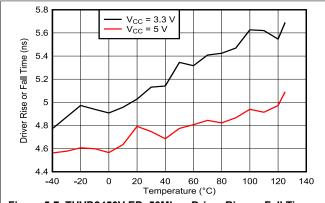


### 5.12 Typical Characteristics





### **5.12 Typical Characteristics (continued)**





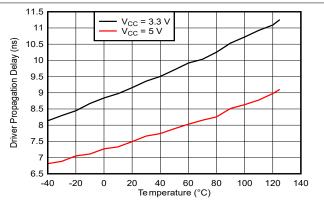


Figure 5-8. THVD2450V-EP: 50Mbps Driver Propagation Delay vs Temperature



### **6 Parameter Measurement Information**

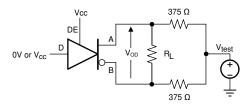


Figure 6-1. Measurement of Driver Differential Output Voltage With Common-Mode Load

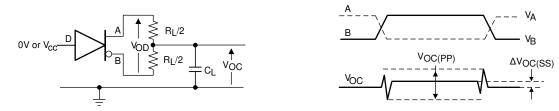


Figure 6-2. Measurement of Driver Differential and Common-Mode Output With RS-485 Load

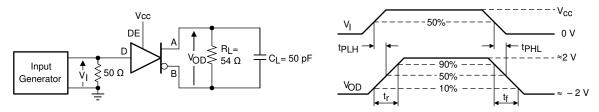
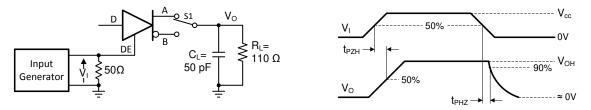
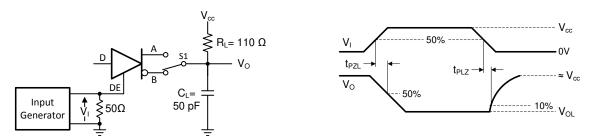


Figure 6-3. Measurement of Driver Differential Output Rise and Fall Times and Propagation Delays



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Figure 6-4. Measurement of Driver Enable and Disable Times With Active High Output and Pull-Down Load



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Figure 6-5. Measurement of Driver Enable and Disable Times With Active Low Output and Pull-up Load



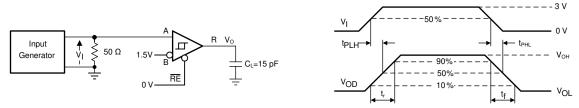


Figure 6-6. Measurement of Receiver Output Rise and Fall Times and Propagation Delays

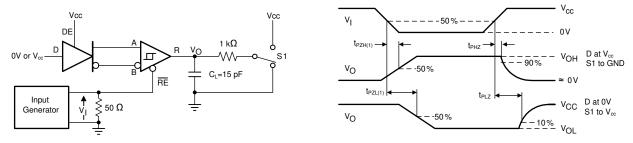
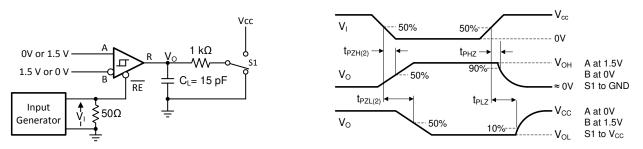
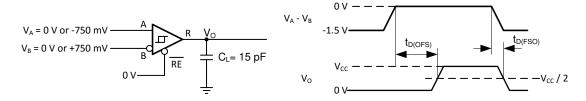


Figure 6-7. Measurement of Receiver Enable/Disable Times With Driver Enabled



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Figure 6-8. Measurement of Receiver Enable Times With Driver Disabled



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Figure 6-9. Measurement of Fail-Safe Delay



### 7 Detailed Description

#### 7.1 Overview

THVD2410V-EP and THVD2450V-EP are fault-protected, half duplex RS-485 transceivers available in two speed grades suitable for data transmission up to 1Mbps and 50Mbps respectively. THVD2452V-EP is a full-duplex transceiver that can be configured for two speeds using the SLR pin: 20Mbps and 50Mbps. The devices have active-high driver enables and active-low receiver enables. A shutdown current of less than  $1\mu$ A can be achieved by disabling both driver and receiver.

### 7.2 Functional Block Diagrams

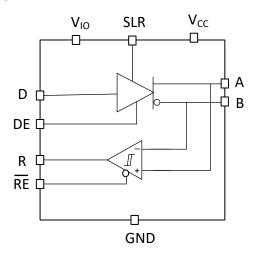


Figure 7-1. THVD2410V-EP and THVD2450V-EP Block Diagram

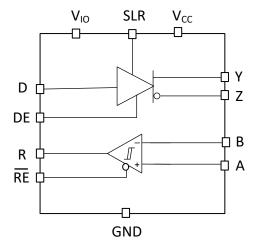


Figure 7-2. THVD2452V-EP Block Diagram

### 7.3 Feature Description

### 7.3.1 ±70-V Fault Protection

THVD24xxV-EP transceivers have extended bus fault protection compared to standard RS-485 devices. Transceivers that operate in rugged industrial environments are often exposed to voltage transients greater than the -7V to +12V defined by the TIA/EIA-485A standard. To protect against such conditions, the generic RS-485 devices with lower absolute maximum ratings requires expensive external protection components. To simplify system design and reduce overall system cost, THVD24xxV-EP devices are protected up to ±70V without the need for any external components.

### 7.3.2 Integrated IEC ESD and EFT Protection

Internal ESD protection circuits protect the transceivers against electrostatic discharges (ESD) according to IEC 61000-4-2 of up to ±12kV and against electrical fast transients (EFT) according to IEC 61000-4-4 of up to ±4kV. THVD24xxV-EP ESD structures help to limit voltage excursions and recover from them quickly that they allow EFT Criterion A at the system level (no data loss when transient noise is present).

#### 7.3.3 Driver Overvoltage and Overcurrent Protection

The THVD24xxV-EP drivers are protected against any DC supply shorts in the range of -70V to +70V. The devices internally limit the short circuit current to ±250mA to comply with the TIA/EIA-485A standard. In addition, a fold-back current limiting circuit further reduces the driver short circuit current to less than ±5mA if the output fault voltage exceeds |±25V|.

All devices feature thermal shutdown protection that disables the driver and the receiver if the junction temperature exceeds the  $T_{SHDN}$  threshold due to excessive power dissipation.

### 7.3.4 Enhanced Receiver Noise Immunity

The differential receivers of THVD24xxV-EP feature fully symmetric thresholds to maintain duty cycle of the signal even with small input amplitudes. In addition, 250mV (typical) hysteresis provides noise immunity.

### 7.3.5 Receiver Fail-Safe Operation

The receivers are fail-safe to invalid bus states caused by the following:

- · Open bus conditions, such as a disconnected connector
- · Shorted bus conditions, such as cable damage shorting the twisted-pair together
- · Idle bus conditions that occur when no driver on the bus is actively driving

In any of these cases, the receiver outputs a fail-safe logic high state if the input amplitude stays for longer than  $t_{D(OFS)}$  at less than  $|V_{TH\ FSH}|$ .

#### 7.3.6 Low-Power Shutdown Mode

Driving DE low and  $\overline{RE}$  high for longer than 500ns puts the devices into the shutdown mode. If either DE goes high or  $\overline{RE}$  goes low, the counters reset. The devices does not enter the shutdown mode if the enable pins are in disable state for less than 50ns. This feature prevents the devices from accidentally going into shutdown mode due to skew between DE and  $\overline{RE}$ .

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#### 7.4 Device Functional Modes

When the driver enable pin, DE, is logic high, the differential outputs A and B follow the logic states at data input D. A logic high at D causes A to turn high and B to turn low. In this case the differential output voltage defined as  $V_{OD} = V_A - V_B$  is positive. When D is low, the output states reverse: B turns high, A becomes low, and  $V_{OD}$  is negative.

When DE is low, both outputs turn high-impedance. In this condition the logic state at D is irrelevant. The DE pin has an internal pull-down resistor to ground, thus when left open the driver is disabled (high-impedance) by default. The D pin has an internal pull-up resistor to  $V_{CC}$ , thus, when left open while the driver is enabled, output A turns high and B turns low.

		Table 1-1.	Diivei i aiic	CHOTT TUDIC
INPUT	ENABLE	OUTI	PUTS	FUNCTION
D	DE	A/Y	B/Z	FUNCTION
Н	Н	Н	L	Actively drive bus high
L	Н	L	Н	Actively drive bus low
Х	L	Z	Z	Driver disabled
Х	OPEN	Z	Z	Driver disabled by default
OPEN	Н	Н	L	Actively drive bus high by default

**Table 7-1. Driver Function Table** 

When the receiver enable pin,  $\overline{RE}$ , is logic low, the receiver is enabled. When the differential input voltage defined as  $V_{ID} = V_A - V_B$  is higher than the positive input threshold,  $V_{TH+}$ , the receiver output, R, turns high. When  $V_{ID}$  is lower than the negative input threshold,  $V_{TH-}$ , the receiver output, R, turns low. If  $V_{ID}$  is between  $V_{TH+}$  and  $V_{TH-}$  the output is indeterminate.

When  $\overline{RE}$  is logic high or left open, the receiver output is high-impedance and the magnitude and polarity of  $V_{ID}$  are irrelevant. Internal biasing of the receiver inputs causes the output to go failsafe-high when the transceiver is disconnected from the bus (open-circuit), the bus lines are shorted to one another (short-circuit), or the bus is not actively driven (idle bus).

DIFFERENTIAL INPUT	ENABLE	OUTPUT	FUNCTION
$V_{ID} = V_A - V_B$	RE	R	FUNCTION
$V_{TH+} < V_{ID}$	L	Н	Receive valid bus high
$V_{TH-} < V_{ID} < V_{TH+}$	L	?	Indeterminate bus state
V <sub>ID</sub> < V <sub>TH-</sub>	L	L	Receive valid bus low
X	Н	Z	Receiver disabled
X	OPEN	Z	Receiver disabled by default
Open-circuit bus	L	Н	Fail-safe high output
Short-circuit bus	L	Н	Fail-safe high output
Idle (terminated) bus	L	Н	Fail-safe high output

Table 7-2. Receiver Function Table



Table 7-3 shows SLR (slew rate select) pin functionality. SLR has integrated pull-down, so the device remains in higher speed mode until SLR is pulled high which limits the slew rate and puts the device in slower speed mode.

### Table 7-3. SLR pin control

Device	Functionality w.r.t SLR pin
THVD2410V-EP	SLR = Low or floating: Both transmitter (TX) and receiver (RX) maximum speed is 1Mbps SLR = High: Both TX and RX maximum speed is limited to 250kbps
THVD2450V-EP, THVD2452V-EP	SLR = Low or floating: Both transmitter (TX) and receiver (RX) maximum speed is 50Mbps SLR = High: Both TX and RX maximum speed is limited to 20Mbps

Table 7-4 shows the device behavior in undervoltage scenarios:

### Table 7-4. Supply Function Table

Supply Function Table V <sub>IO</sub>		Driver Output	Receiver Output		
> UV <sub>VCC(rising)</sub>	> UV <sub>VIO(rising)</sub>	Determined by DE and D inputs	Determined by RE and A-B		
< UV <sub>VCC(falling)</sub>	> UV <sub>VIO(rising)</sub>	High impedance	High impedance		
> UV <sub>VCC(rising)</sub>	< UV <sub>VIO(falling)</sub>	High impedance	High impedance		
< UV <sub>VCC(falling)</sub>	< UV <sub>VIO(falling)</sub>	High impedance	High impedance		

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### 8 Application and Implementation

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 8.1 Application Information

THVD2410 and THVD2450 are fault-protected, half-duplex RS-485 transceivers commonly used for asynchronous data transmissions. For these devices, the driver and receiver enable pins allow for the configuration of different operating modes.

### 8.2 Typical Application

An RS-485 bus consists of multiple transceivers connecting in parallel to a bus cable. To eliminate line reflections, each cable end is terminated with a termination resistor,  $R_T$ , whose value matches the characteristic impedance,  $Z_0$ , of the cable. This method, known as parallel termination, generally allows for higher data rates over longer cable length.

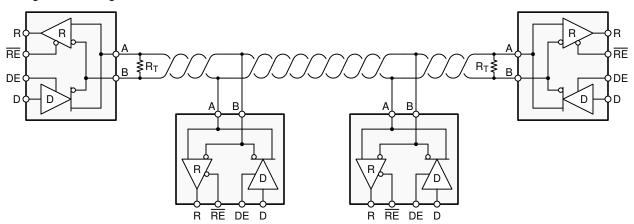


Figure 8-1. Typical RS-485 Network With Half-Duplex Transceivers

#### 8.2.1 Design Requirements

RS-485 is a robust electrical standard suitable for long-distance networking that may be used in a wide range of applications with varying requirements, such as distance, data rate, and number of nodes.

#### 8.2.1.1 Data Rate and Bus Length

There is an inverse relationship between data rate and cable length, which means the higher the data rate, the short the cable length; and conversely, the lower the data rate, the longer the cable length. While most RS-485 systems use data rates between 10kbps and 100kbps, some applications require data rates up to 250kbps at distances of 4000 feet and longer. Longer distances are possible by allowing for small signal jitter of up to 5 or 10%.



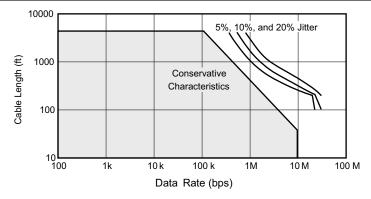


Figure 8-2. Cable Length vs Data Rate Characteristic

Even higher data rates are achievable (that is, 50Mbps for the THVD2450) in cases where the interconnect is short enough (or has suitably low attenuation at signal frequencies) to not degrade the data.

#### 8.2.1.2 Stub Length

When connecting a node to the bus, the distance between the transceiver inputs and the cable trunk, known as the stub, should be as short as possible. Stubs present a non-terminated piece of bus line which can introduce reflections of varying phase as the length of the stub increases. As a general guideline, the electrical length, or round-trip delay, of a stub should be less than one-tenth of the rise time of the driver, thus giving a maximum physical stub length as shown in Equation 1.

$$L_{(STUB)} \le 0.1 \times t_r \times v \times c \tag{1}$$

#### where

- t<sub>r</sub> is the 10/90 rise time of the driver
- c is the speed of light (3 × 10<sup>8</sup> m/s)
- v is the signal velocity of the cable or trace as a factor of c

### 8.2.1.3 Bus Loading

The RS-485 standard specifies that a compliant driver must be able to drive 32 unit loads (UL), where 1 unit load represents a load impedance of approximately  $12k\Omega$ . Because the THVD24xxV-EP devices consist of 1/8 UL transceivers, connecting up to 256 receivers to the bus is possible.



#### 8.2.1.4 Transient Protection

The bus pins of the THVD24xxV-EP transceivers include on-chip ESD protection against  $\pm 30$ kV HBM and  $\pm 12$ kV IEC 61000-4-2 contact discharge. The International Electrotechnical Commission (IEC) ESD test is far more severe than the HBM ESD test. The 50% higher charge capacitance,  $C_{(S)}$ , and 78% lower discharge resistance,  $R_{(D)}$ , of the IEC model produce significantly higher discharge currents than the HBM model. As stated in the IEC 61000-4-2 standard, contact discharge is the preferred transient protection test method.

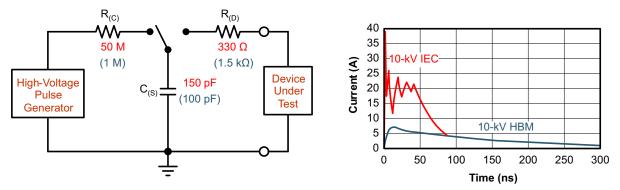


Figure 8-3. HBM and IEC ESD Models and Currents in Comparison (HBM Values in Parenthesis)

The on-chip implementation of IEC ESD protection significantly increases the robustness of equipment. Common discharge events occur because of human contact with connectors and cables. Designers may choose to implement protection against longer duration transients, typically referred to as surge transients.

EFTs are generally caused by relay-contact bounce or the interruption of inductive loads. Surge transients often result from lightning strikes (direct strike or an indirect strike which induce voltages and currents), or the switching of power systems, including load changes and short circuit switching. These transients are often encountered in industrial environments, such as factory automation and power-grid systems.

Figure 8-4 compares the pulse-power of the EFT and surge transients with the power caused by an IEC ESD transient. The left side diagram shows the relative pulse-power for a 0.5kV surge transient and 4kV EFT transient, both of which dwarf the 10kV ESD transient visible in the lower-left corner. 500V surge transients are representative of events that may occur in factory environments in industrial and process automation.

The right side diagram shows the pulse power of a 6kV surge transient, relative to the same 0.5kV surge transient. 6kV surge transients are most likely to occur in power generation and power-grid systems.

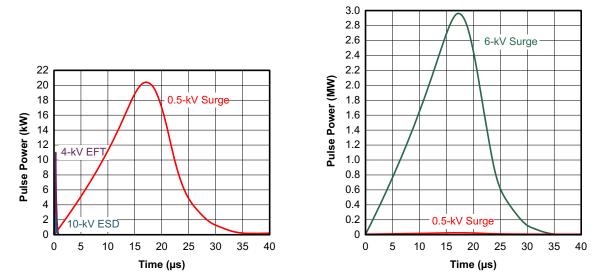


Figure 8-4. Power Comparison of ESD, EFT, and Surge Transients



For surge transients, high-energy content is characterized by long pulse duration and slow decaying pulse power. The electrical energy of a transient that is dumped into the internal protection cells of a transceiver is converted into thermal energy, which heats and destroys the protection cells, thus destroying the transceiver. Figure 8-5 shows the large differences in transient energies for single ESD, EFT, surge transients, and an EFT pulse train that is commonly applied during compliance testing.

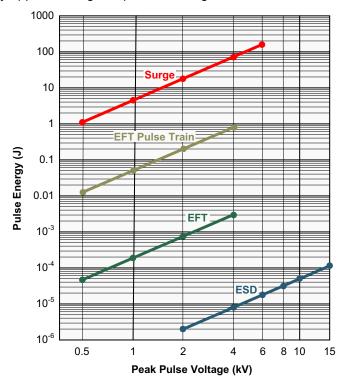


Figure 8-5. Comparison of Transient Energies



### 8.2.2 Detailed Design Procedure

Figure 8-6 suggests a protection circuit against 1kV surge (IEC 61000-4-5) transients. Table 8-1 shows the associated bill of materials. SMAJ30CA TVS diodes are rated to operate up to 30V. This makes sure the protection diodes do not conduct if a direct RS-485 bus shorts to 24V DC industrial power rail.

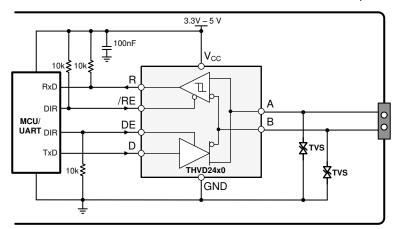


Figure 8-6. Transient Protection Against Surge Transients for Half-Duplex Devices

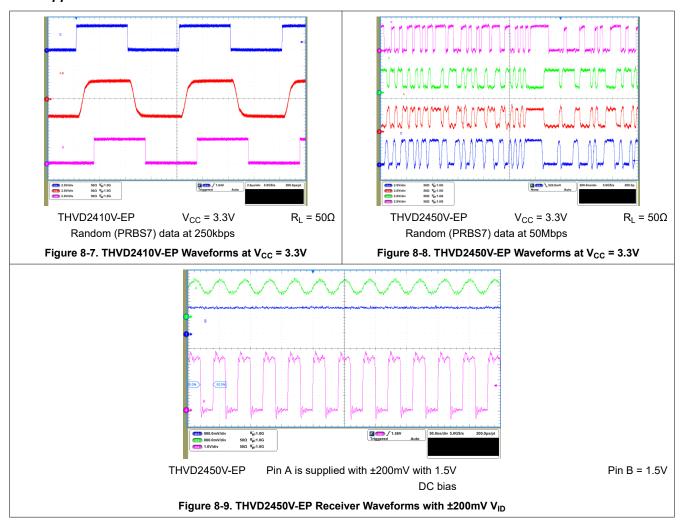
**Table 8-1. Components List** 

DEVICE	FUNCTION	ORDER NUMBER	MANUFACTURER <sup>(1)</sup>		
XCVR	RS-485 transceiver	THVD2410V-EP Or THVD2450V-EP	ті		
TVS	Bidirectional 400-W transient suppressor	SMAJ30CA	Littelfuse		

(1) See Third-Party Products Disclaimer



### 8.2.3 Application Curves



### 8.3 Power Supply Recommendations

For reliable operation at all data rates and supply voltages, each supply should be decoupled with a 100nF ceramic capacitor located as close to the supply pins as possible. This helps to reduce supply voltage ripple present on the outputs of switched-mode power supplies and also helps to compensate for the resistance and inductance of the PCB power planes.



### 8.4 Layout

#### 8.4.1 Layout Guidelines

Robust and reliable bus node design often requires the use of external transient protection devices to protect against surge transients that may occur in industrial environments. Since these transients have a wide frequency bandwidth (from approximately 3MHz to 300MHz), high-frequency layout techniques should be applied during PCB design.

- 1. Place the protection circuitry close to the bus connector to prevent noise transients from propagating across the board.
- 2. Use V<sub>CC</sub> and ground planes to provide low inductance. Note that high-frequency currents tend to follow the path of least impedance and not the path of least resistance.
- 3. Design the protection components into the direction of the signal path. Do not force the transient currents to divert from the signal path to reach the protection device.
- 4. Apply 100nF to 220nF decoupling capacitors as close as possible to the  $V_{CC}$  and  $V_{IO}$  pins of transceiver, UART and/or controller ICs on the board.
- 5. Use at least two vias for the ground connections of the decoupling capacitors at the power pins and the protection devices to minimize the effective via inductance.
- 6. Use  $1k\Omega$  to  $10k\Omega$  pull-up and pull-down resistors for enable lines to limit noise currents in these lines during transient events.
- 7. Insert pulse-proof resistors into the A and B bus lines if the TVS clamping voltage is higher than the specified maximum voltage of the transceiver bus pins. These resistors limit the residual clamping current into the transceiver and prevent it from latching up.

#### 8.4.2 Layout Example

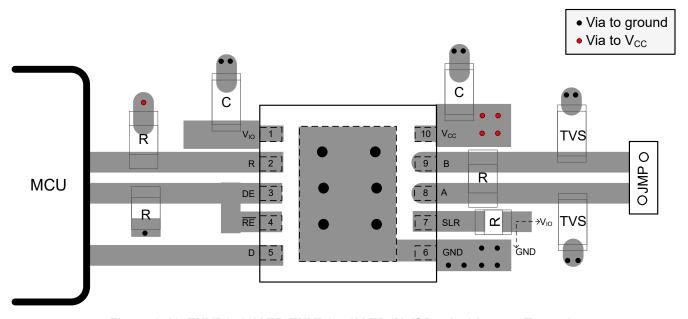


Figure 8-10. THVD2410V-EP, THVD2450V-EP (Half-Duplex) Layout Example

### 9 Device and Documentation Support

### 9.1 Device Support

### 9.1.1 Third-Party Products Disclaimer

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### 9.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 9.3 Support Resources

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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#### 9.4 Trademarks

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### 9.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 9.6 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.

### 10 Revision History

# 

### 11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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#### PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
THVD2410VDRCREP	ACTIVE	VSON	DRC	10	5000	RoHS & Green	(6) NIPDAU	Level-2-260C-1 YEAR	-55 to 125	V2410	Samples
THVD2450VDRCREP	ACTIVE	VSON	DRC	10	5000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-55 to 125	V2450	Samples
THVD2452VDREP	ACTIVE	SOIC	D	14	2500	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-55 to 125	T2452V	Samples
V62/22613-01XE	ACTIVE	VSON	DRC	10	5000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR		V2410	Samples
V62/22613-02XE	ACTIVE	VSON	DRC	10	5000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR		V2450	Samples
V62/22613-03XE	ACTIVE	SOIC	D	14	2500	RoHS & Green	NIPDAU	Level-1-260C-UNLIM		T2452V	Samples
V62/22613-03YE	ACTIVE	SOIC	D	14	2500	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-55 to 125	T2452V	Samples

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

# **PACKAGE OPTION ADDENDUM**

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(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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#### OTHER QUALIFIED VERSIONS OF THVD2410V-EP, THVD2450V-EP, THVD2452V-EP:

Catalog: THVD2410V, THVD2450V, THVD2452V

NOTE: Qualified Version Definitions:

Catalog - TI's standard catalog product

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### TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
THVD2410VDRCREP	VSON	DRC	10	5000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
THVD2450VDRCREP	VSON	DRC	10	5000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
THVD2452VDREP	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1



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### \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
THVD2410VDRCREP	VSON	DRC	10	5000	346.0	346.0	33.0
THVD2450VDRCREP	VSON	DRC	10	5000	346.0	346.0	33.0
THVD2452VDREP	SOIC	D	14	2500	353.0	353.0	32.0



SMALL OUTLINE INTEGRATED CIRCUIT



#### NOTES:

- 1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm, per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.43 mm, per side.
- 5. Reference JEDEC registration MS-012, variation AB.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



3 x 3, 0.5 mm pitch

PLASTIC SMALL OUTLINE - NO LEAD

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



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PLASTIC SMALL OUTLINE - NO LEAD



#### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
  2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.



PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- 5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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