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SLVSAD1B –JUNE 2010–REVISED JANUARY 2016

# **TPS80010 PMU for Alkaline Battery-Powered Applications**

# <span id="page-0-1"></span>**1 Features**

- 1.8-V Buck DC-DC Converter
- 3.1-V Boost DC-DC Converter with 3-V Post-Regulation LDO
- Over 91% Conversion Efficiency
- Current-Limited Start-Up for Both DC-DC **Converters**
- Load Switch With Current-Limited Turnon
- **Battery-Level Monitor Switch**
- 32-Pin, 4-mm × 4-mm × 1-mm VQFN Package
- ESD Performance Tested per JESD 22
	- 2000-V Human-Body Model (A114-B, Class II)
	- 500-V Charged-Device Model (C101)

# <span id="page-0-3"></span><span id="page-0-2"></span>**2 Applications**

- Wireless Mice
- Wireless Keyboards
- <span id="page-0-0"></span>Game Controllers

# **3 Description**

The TPS80010 device provides an integrated powermanagement solution for 2-cell alkaline battery applications such as wireless mice, keyboards, and video game controllers. The VBUCK 1.8-V output is powered by a buck converter with a load capacity of 100 mA. A Power Good (PG) signal is generated when VBUCK is greater than 90% of its target output voltage. Integrated in the TPS80010 is an 80-mΩ load switch that can be connected to the VBUCK output, allowing more system design flexibility when connecting to multiple loads. The 3.1-V VBOOST output is powered by a boost converter. The VBOOST output voltage is post-regulated by the integrated 3-V LDO. This post-regulation provides a low-noise supply level through the specified battery range.

#### **Device Information[\(1\)](#page-0-0)**



(1) For all available packages, see the orderable addendum at the end of the data sheet.



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# **Table of Contents**





# <span id="page-1-0"></span>**4 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

## **Changes from Revision A (June 2010) to Revision B Page**





# <span id="page-2-0"></span>**5 Pin Configuration and Functions**



#### **Pin Functions**



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# **Pin Functions (continued)**





# <span id="page-4-0"></span>**6 Specifications**

## <span id="page-4-1"></span>**6.1 Absolute Maximum Ratings**

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>



(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *[Recommended](#page-4-3) Operating [Conditions](#page-4-3)* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

# <span id="page-4-2"></span>**6.2 ESD Ratings**



(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

## <span id="page-4-3"></span>**6.3 Recommended Operating Conditions**

 $T_A = 0$ °C to 85°C; typical values are at  $T_A = 25$ °C



### <span id="page-4-4"></span>**6.4 Thermal Information**

<span id="page-4-5"></span>

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953.](http://www.ti.com/lit/pdf/spra953)



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### <span id="page-5-0"></span>**6.5 Electrical Characteristics**

 $T_A = 0$ °C to 85°C; typical values are at T<sub>A</sub> = 25°C (unless otherwise noted)





# **Electrical Characteristics (continued)**

 $T_A = 0$ °C to 85°C; typical values are at  $T_A = 25$ °C (unless otherwise noted)



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## **Electrical Characteristics (continued)**

 $T_A = 0^\circ \text{C}$  to 85°C; typical values are at  $T_A = 25^\circ \text{C}$  (unless otherwise noted)



# <span id="page-7-0"></span>**6.6 Timing Requirements**





### **6.7 Typical Characteristics**

<span id="page-8-0"></span>

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### **Typical Characteristics (continued)**





# <span id="page-10-0"></span>**7 Detailed Description**

## <span id="page-10-1"></span>**7.1 Overview**

The TPS80010 provides a system level solution for 2-cell alkaline battery applications. Popular applications include handheld devices including wireless mice, keyboards, and video game controllers. The TPS80010 provides two DC-DC converters, a load switch, post-regulation LDO, and battery monitoring switch—each with their own enable pins to allow for maximum flexibility.

The buck converter operates at a fixed voltage, 1.8 V, and can provide up to 150 mA load. Automatic switching is implemented to maximize power efficiency. In moderate to heavy loads the converter operates in PWM mode; as load current decreases it switches to PFM mode. PWM can be forced regardless of load size by disabling this power save mode (PFM mode). The buck allows for several loads to be connected to its output, due to the power distributing load switch connected externally to the output of the buck.

The boost converter regulates at a fixed voltage of 3.1 V, and can provide up to 50 mA load current. It contains a discontinuous current mode to maintain efficiency at low load currents. The boost provides a low noise supply at low input voltages due to a post regulation LDO.

The battery monitoring switch is used to check battery lifetime. Using a false load implementation and the battery voltage it can determine the battery impedance and therefore health.

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## <span id="page-11-0"></span>**7.2 Functional Block Diagram**





### <span id="page-12-0"></span>**7.3 Feature Description**

### **7.3.1 Enable**

The TPS80010 includes two DC-DC converters, a load switch, post-regulation LDO, and battery monitoring switch. Each of these circuits has a dedicated enable pin with an internal pulldown resistor,  $R_{\text{PULLDOWN}}$ , that can be driven by standard logic or by an open-drain driver. The EN\_BUCK pin not only enables the buck converter, but also serves as the master enable for the device. No other circuitry in the TPS80010 can operate without EN\_BUCK set high.

#### **7.3.2 Buck DC-DC Converter and Load Switch**

The synchronous step-down (buck) converter in the TPS80010 provides a fixed 1.8-V output with a load capacity of 150 mA. This converter operates with a fixed switching frequency of 2.25 MHz during pulse-width-modulation (PWM) operation at moderate to heavy loads. As the load current decreases, the converter automatically switches to a power-save mode and operates in pulse-frequency-modulation (PFM) mode to maximize power efficiency. During PFM operation, the converter positions the output at a voltage about 1% greater than the nominal output voltage. This feature minimizes the output voltage drops during sudden load transients. The power-save mode can be disabled by setting the MODE\_BUCK pin high.

The buck converter has internal soft-start circuitry that limits the inrush current during startup to 150 mA, allowing a slow and controlled output-voltage ramp. Once the output voltage reaches 1.7 V, the output monitoring circuitry generates a Power Good (PG) output signal.

The TPS80010 also includes a load switch that is to be connected externally to the buck output voltage. This switch provides flexibility in the design and power distribution of the end application by allowing several loads (such as memory, I/O, Bluetooth, and so forth) to be connected to the same supply while being able to power down or disconnect some of these loads selectively when the end application goes to a low-power mode of operation. This switch has a controlled turnon to limit the inrush current caused by the load, and hence the load transient to the buck converter.

#### **7.3.3 Boost DC-DC Converter and Post-Regulation LDO**

The TPS80010 includes a synchronous step-up (boost) converter that provides a 3.1-V fixed output at 50-mA load current. The boost converter is controlled by a hysteretic current-mode controller. This controller regulates the output voltage by keeping the inductor ripple current constant and adjusting the offset of this inductor current depending on the output load. If the required average input current is lower than the average inductor current defined by this constant ripple, the converter goes into discontinuous-current mode (DCM) to keep the efficiency high at low-load conditions. The boost also has a soft-start circuit that limits the inrush current to 150 mA.

To provide a clean, low-noise supply when  $V_{BAT} > 3.1$  V, the output of the boost is post-regulated by a 3-V LDO. This post-regulation allows the TPS80010 to provide a solid 3-V supply rail to the end application across the full input or battery-voltage range while minimizing the number of external components. To minimize power loss through the power path, the LDO allows for 100-mV input-voltage headroom at 50-mA load.

#### **7.3.4 Battery Monitoring Switch and False Load**

The TPS80010 implements a battery-voltage monitor switch to briefly check battery lifetime. The integrated falseload switch connects a specified load to the battery. When this *false* load is applied, the battery monitor switch is turned on, gating the sensed battery voltage to the ADC in the system. Based on this measurement, the system can determine the battery impedance and, therefore, battery health.



# <span id="page-13-0"></span>**7.4 Device Functional Modes**

The step-down converter has two modes of operations to maximize efficiency: Pulse frequency modulation (PFM) and pulse width modulation (PWM).

PFM mode is for:

- Light loads
- Automatic transition from this mode to PWM mode automatically when MODE\_BUCK pin is pulled low
- Increasing output voltage setting by 1%
- Better accuracy

PWM mode is for:

- Moderate to heavy loads
- Small output ripple
- Pulling MODE\_BUCK pin high to result in PWM mode over all load range



# <span id="page-14-0"></span>**8 Application and Implementation**

#### **NOTE**

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

#### <span id="page-14-1"></span>**8.1 Application Information**

The TPS80010 is ideal for dual-cell alkaline battery-powered and noise-sensitive applications. The application controller has the ability to enable resources on the power management IC to allow for maximum flexibility. The device resources are often used to power memory, IO, and optical sensors. These devices are common in wireless keyboards and video game controllers.

#### <span id="page-14-2"></span>**8.2 Typical Application**



**Figure 11. TPS80010 Typical Application Diagram**

#### **8.2.1 Design Requirements**

<span id="page-14-3"></span>The design requirements for TPS80010 are located in [Table](#page-14-3) 1.

#### **Table 1. TPS80010 Design Requirements**





(1)

#### **8.2.2 Detailed Design Procedure**

#### *8.2.2.1 Buck Output Filter Design*

The TPS80010 buck regulator is designed to operate with inductors in the range of 1.5 µH to 4.7 µH and with output capacitors in the range of 4.7  $\mu$ F to 22  $\mu$ F. The part is optimized for operation with a 2.2- $\mu$ H inductor and 10-µF output capacitor.

Larger or smaller inductor values can be used to optimize the performance of the device for specific operation conditions. For stable operation, the L and C values of the output filter must not be less than 1-µH effective inductance and 3.5-µF effective capacitance.

#### *8.2.2.2 Buck Inductor Selection*

The inductor value has a direct effect on the ripple current. The selected inductor must be rated for its DC resistance and saturation current. The inductor ripple current  $(\Delta I_L)$  decreases with higher inductance and increases with higher  $V_{IN}$  or  $V_{BUCK}$ .

The inductor selection also has an impact on the output-voltage ripple in PFM mode. Higher inductor values lead to lower output-voltage ripple and higher PFM frequency; lower inductor values lead to a higher output-voltage ripple but lower PFM frequency.

[Equation](#page-15-0) 1 calculates the maximum inductor current in PWM mode under static load conditions. The saturation current of the inductor must be rated higher than the maximum inductor current, as calculated with [Equation](#page-15-1) 2. This is recommended because during heavy load transients, the inductor current rises above the calculated value.

<span id="page-15-1"></span><span id="page-15-0"></span>
$$
\Delta I_{L} = V_{BUCK} \times \frac{1 - \frac{V_{BUCK}}{V_{IN}}}{L \times f}
$$

$$
I_{Lmax} = I_{Omax} + \frac{\Delta I_{L}}{2}
$$

where

- f = Switching frequency (2.25 MHz typical)
- $\bullet$  L = Inductor value
- $\Delta I_1$  = Peak-to-peak inductor ripple current
- $I_{Lmax}$  = Maximum inductor current (2)

A more conservative approach is to select the inductor current rating just for the switch current limit,  $I_{LIMF}$ , of the converter.

Accepting larger values of ripple current allows the use of lower inductance values, but results in higher output voltage ripple, greater core losses, and lower output current capability.

The total losses of the coil have a strong impact on the efficiency of the DC-DC conversion and consist of both the losses in the DC resistance  $(R_{(DC)})$  and the following frequency-dependent components:

- The losses in the core material (magnetic hysteresis loss, especially at high switching frequencies)
- Additional losses in the conductor from the skin effect (current displacement at high frequencies)
- Magnetic field losses of the neighboring windings (proximity effect)
- Radiation losses

### *8.2.2.3 Buck Output Capacitor Selection*

The advanced fast-response voltage mode control scheme of the TPS80010 buck regulator allows the use of tiny ceramic capacitors. Ceramic capacitors with low ESR values have the lowest output voltage ripple and are recommended. The output capacitor requires either an X7R or X5R dielectric. Y5V- and Z5U-dielectric capacitors, aside from their wide variation in capacitance over temperature, become resistive at high frequencies. At nominal load current, the device operates in PWM mode and the RMS ripple current is calculated with [Equation](#page-16-0) 3.



<span id="page-16-0"></span>

$$
I_{\text{RMSCout}} = V_{\text{BUCK}} \times \frac{1 - \frac{V_{\text{BUCK}}}{V_{\text{IN}}}}{L \times f} \times \frac{1}{2 \times \sqrt{3}}
$$
(3)

<span id="page-16-1"></span>At nominal load current, the device operates in PWM mode and the overall output voltage ripple is the sum of the voltage spike caused by the output capacitor ESR plus the voltage ripple caused by charging and discharging the output capacitor in [Equation](#page-16-1) 4.

$$
\Delta V_{\text{Buck}} = V_{\text{Buck}} \times \frac{1 - \frac{V_{\text{Buck}}}{V_{\text{IN}}}}{L \times f} \times \left(\frac{1}{8 \times C_{\text{OUT}} \times f} + \text{ESR}\right)
$$
\n(4)

At light-load currents, the converter operates in power-save mode, and the output-voltage ripple depends on the output-capacitor and inductor values. Larger output-capacitor and inductor values minimize the voltage ripple in PFM mode and tighten DC output accuracy in PFM mode.

#### *8.2.2.4 Buck Input Capacitor Selection*

An input capacitor is required for best input voltage filtering and for minimizing the interference with other circuits caused by high input-voltage spikes. For most applications, a 4.7-µF to 10-µF ceramic capacitor is recommended. Because a ceramic capacitor loses up to 80% of its initial capacitance at 5 V, TI recommends that 10-µF input capacitors be used for input voltages > 4.5 V. The input capacitor can be increased without any limit for better input-voltage filtering. Take care when using only small ceramic input capacitors. When a ceramic capacitor is used at the input and the power is being supplied through long wires, such as from a wall adapter, a load step at the output or  $V_{\text{IN}}$  step on the input can induce ringing at the VIN BUCK pin. This ringing can couple to the output and be mistaken as loop instability or could even damage the part by exceeding the maximum ratings.

<b>COMPONENT</b>	<b>VALUE</b>	<b>PART</b>	<b>SUPPLIER</b>	<b>SIZE</b>
Inductor	$2.2 \mu H$	LOM2HPN2R2MJ0L	Murata	2.5 mm $\times$ 2 mm $\times$ 1.2 mm (1008)
		LPS3015-222ML	Coilcraft	$3$ mm $\times$ 3 mm $\times$ 1.5 mm
Cacitor (IN)	10 uF	GRM188R60J106ME47D	Murata	0603
Capacitor (OUT)	$10 \mu F$	GRM188R60J106ME47D	Murata	0603

**Table 2. Recommended Component List for Buck Converter**

### *8.2.2.5 Boost Inductor Selection*

To ensure proper operation of the TPS80010 boost DC-DC converter, a suitable inductor must be connected between pins VIN\_BOOST and SW\_BOOST. Inductor values of 4.7 μH show good performance over the whole input and output voltage range.

<span id="page-16-2"></span>Choosing other inductance values affects the switching frequency f proportional to 1/L as shown in [Equation](#page-16-2) 5.

$$
L = \frac{1}{f \times 200 \text{ mA}} \times \frac{V_{\text{IN}} \times (V_{\text{BOOST}} - V_{\text{IN}})}{V_{\text{BOOST}}}
$$

(5)

Choosing inductor values higher than 4.7 μH can improve efficiency due to reduced switching frequency and correspondingly reduced switching losses. Using inductor values less than 2.2 μH is not recommended.

<span id="page-16-3"></span>Having selected an inductance value, the peak current for the inductor in steady-state operation can be calculated. [Equation](#page-16-3) 6 gives the peak current estimate.

$$
L = \frac{1}{f \times 200 \text{ mA}} \times \frac{v_{\text{IN}} \times (v_{\text{BOOST}} - v_{\text{IN}})}{v_{\text{BOOST}}}
$$
(5)  
using inductor values higher than 4.7 µH can improve efficiency due to reduced switching frequency and  
aspondingly reduced switching losses. Using inductor values less than 2.2 µH is not recommended.  
ng selected an inductance value, the peak current for the inductor in steady-state operation can be  
ulated. Equation 6 gives the peak current estimate.  

$$
I_{L,MAX} = \begin{cases} \frac{V_{\text{BOOST}} \times I_{\text{BOOST}}}{0.8 \times V_{\text{IN}}} + 100 \text{ mA} \end{cases}
$$
continuous current operation  

$$
I_{L,MAX} = 200 \text{ mA}
$$
(6)

 $I_{L_{MAX}}$  is the required minimum inductor-current rating. The load-transient or overcurrent conditions may require an even higher current rating.

<span id="page-17-0"></span>The condition in [Equation](#page-17-0) 7 provides an easy way to determine whether the device is in continuous or discontinuous operation. As long as the condition is true, the device operates in continuous-current mode. If the condition becomes false, discontinuous-current operation is established.

$$
\frac{V_{\text{BOOST}} \times I_0}{V_{\text{IN}}} > 0.8 \times 100 \text{ mA}
$$
 (7)

Due to the use of current hysteretic control in the TPS80010 boost, the series resistance of the inductor can impact the operation of the main switch. There is a simple calculation that can ensure proper operation of the TPS80010 boost converter. The relationship between the series resistance  $(R_{\rm IN})$ , the input voltage (V<sub>IN</sub>), and the switch current limit  $(I_{SW})$  is shown in [Equation](#page-17-1) 8.

$$
R_{IN} < \frac{V_{IN}}{I_{SW}} \tag{8}
$$

<span id="page-17-1"></span>Examples include [Equation](#page-17-2) 9 and [Equation](#page-17-3) 10.

(9) In [Equation](#page-17-2) 9, R<sub>IN</sub> < 2.5 V / 400 mA; therefore, R<sub>IN</sub> must be less than 6.25 Ω. (10)

<span id="page-17-3"></span>In [Equation](#page-17-3) 10, R<sub>IN</sub> < 1.8 V / 400 mA; therefore, R<sub>IN</sub> must be less than 4.5  $\Omega$ .

#### *8.2.2.6 Boost Input Capacitor*

The input capacitor must be at least 10 μF to improve transient behavior of the regulator and EMI behavior of the total power-supply circuit. The input capacitor must be a ceramic capacitor and be placed as close as possible to the VIN BOOST and GND pins of the IC. These capacitors must be X7R or X5R ceramic capacitors.

#### *8.2.2.7 Boost Output Capacitor*

<span id="page-17-2"></span> $I_{SW} = 400 \text{ mA}, V_{IN} = 2.5 \text{ V}$ <br>
uation 9, R<sub>IN</sub> < 2.5 V / 400<br>  $I_{SW} = 400 \text{ mA}, V_{IN} = 1.8 \text{ V}$ <br>
uation 10, R<sub>IN</sub> < 1.8 V / 40<br>
6 **Boost Input Capacito**<br>
nput capacitor must be at I<br>
power-supply circuit. The in<br>
IN\_BOOST a For the output capacitor  $C_{\text{OUT}}$ , TI recommends using small X7R or X5R ceramic capacitors placed as close as possible to the VO\_BOOST and GND pins of the IC. If, for any reason, the application requires the use of large capacitors which cannot be placed close to the IC, the use of a small ceramic capacitor with a capacitance value of around 4.7  $\mu$ F in parallel with the larger one is recommended. This small capacitor must be placed as close as possible to the VO\_BOOST and GND pins of the IC.

<span id="page-17-4"></span>A minimum *effective* capacitance value of 6 μF must be used; 10 μF is recommended. If the inductor value exceeds 4.7 μH, the value of the effective output capacitance value must be half the inductance value or higher for stability reasons; see [Equation](#page-17-4) 11.

$$
C_{OUT} \geq \frac{L}{2} \times \frac{\mu F}{\mu H}
$$

(11)

#### **NOTE**

When choosing the output capacitor, be aware of the effects of bias voltage, temperature, and tolerance on the effective capacitance of the component. A capacitor in a 0603 package size suffers more capacitance degradation than a 0805 package at a similar bias voltage. For example, either a 22-µF 0603-sized capacitor or a 10-µF 0805-sized capacitor is required to work with a nominal 10-µH inductor.

The TPS80010 boost is not sensitive to ESR in terms of stability. Using low-ESR capacitors, such as ceramic capacitors, is recommended to minimize output-voltage ripple. If heavy load changes are expected, the output capacitor value must be increased to avoid output voltage drops during fast load transients.











### **8.2.3 Application Curves**



# <span id="page-18-0"></span>**9 Power Supply Recommendations**

The TPS80010 was originally designed for dual-cell alkaline battery applications. Therefore, the device has working input voltage ranges from 1.95 V to 3.6 V. As long as the input voltage range is followed, the input supply can be from other regulated supplies.

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**STRUMENTS** 

**XAS** 

# <span id="page-19-0"></span>**10 Layout**

### <span id="page-19-1"></span>**10.1 Layout Guidelines**

The VIN\_BOOST and VIN\_BUCK pins must be bypassed to ground with a low-ESR ceramic bypass capacitor. Texas Instruments recommends the typical bypass capacitance is 10 μF.

- The optimum placement is closest to the VIN\_BUCK and VIN\_BOOST pins of the device. Minimize the loop area formed by the bypass capacitor connection, the VINDCDC and VINLDO pins, and the thermal pad of the device.
- The thermal pad must be tied to the PCB ground plane with multiple vias.
- The FB \_BOOST, FB\_BUCK, SW\_BOOST, SW\_BCUK, and OUT\_VM pins (feedback and output pins) traces must be routed away from any potential noise source to avoid coupling.
- Output capacitance must be placed immediately at the output pins. Excessive distance from the capacitance to output pins may cause poor converter performance.

## <span id="page-19-2"></span>**10.2 Layout Example**



**Figure 16. TPS80010 Layout**



# <span id="page-20-0"></span>**11 Device and Documentation Support**

### <span id="page-20-1"></span>**11.1 Device Support**

#### **11.1.1 Third-Party Products Disclaimer**

TI'S PUBLICATION OF INFORMATION REGARDING THIRD-PARTY PRODUCTS OR SERVICES DOES NOT CONSTITUTE AN ENDORSEMENT REGARDING THE SUITABILITY OF SUCH PRODUCTS OR SERVICES OR A WARRANTY, REPRESENTATION OR ENDORSEMENT OF SUCH PRODUCTS OR SERVICES, EITHER ALONE OR IN COMBINATION WITH ANY TI PRODUCT OR SERVICE.

### <span id="page-20-2"></span>**11.2 Community Resources**

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms](http://www.ti.com/corp/docs/legal/termsofuse.shtml) of [Use.](http://www.ti.com/corp/docs/legal/termsofuse.shtml)

**TI E2E™ Online [Community](http://e2e.ti.com)** *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design [Support](http://support.ti.com/)** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

#### <span id="page-20-3"></span>**11.3 Trademarks**

E2E is a trademark of Texas Instruments. All other trademarks are the property of their respective owners.

#### <span id="page-20-4"></span>**11.4 Electrostatic Discharge Caution**



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

# <span id="page-20-5"></span>**11.5 Glossary**

[SLYZ022](http://www.ti.com/lit/pdf/SLYZ022) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

# <span id="page-20-6"></span>**12 Mechanical, Packaging, and Orderable Information**

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



# **PACKAGING INFORMATION**



**(1)** The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

**(3)** MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

**(4)** There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

**(5)** Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

**(6)** Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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**TEXAS** 

## **TAPE AND REEL INFORMATION**

**ISTRUMENTS** 





#### **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**







# **PACKAGE MATERIALS INFORMATION**

www.ti.com 20-Apr-2023



\*All dimensions are nominal



# **GENERIC PACKAGE VIEW**

# **RSM 32 VQFN - 1 mm max height**

**4 x 4, 0.4 mm pitch** PLASTIC QUAD FLATPACK - NO LEAD

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.







# **PACKAGE OUTLINE**

# **RSM0032B VQFN - 1 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



# **EXAMPLE BOARD LAYOUT**

# **RSM0032B VQFN - 1 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



# **EXAMPLE STENCIL DESIGN**

# **RSM0032B VQFN - 1 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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