

**TI *Live!* BATTERY MANAGEMENT
SYSTEMS SEMINAR**

MIKE EMANUEL

**AUTONOMOUS SOLAR PANEL MAXIMUM
POWER POINT TRACKING WITH FULLY
INTEGRATED BUCK-BOOST CHARGERS**



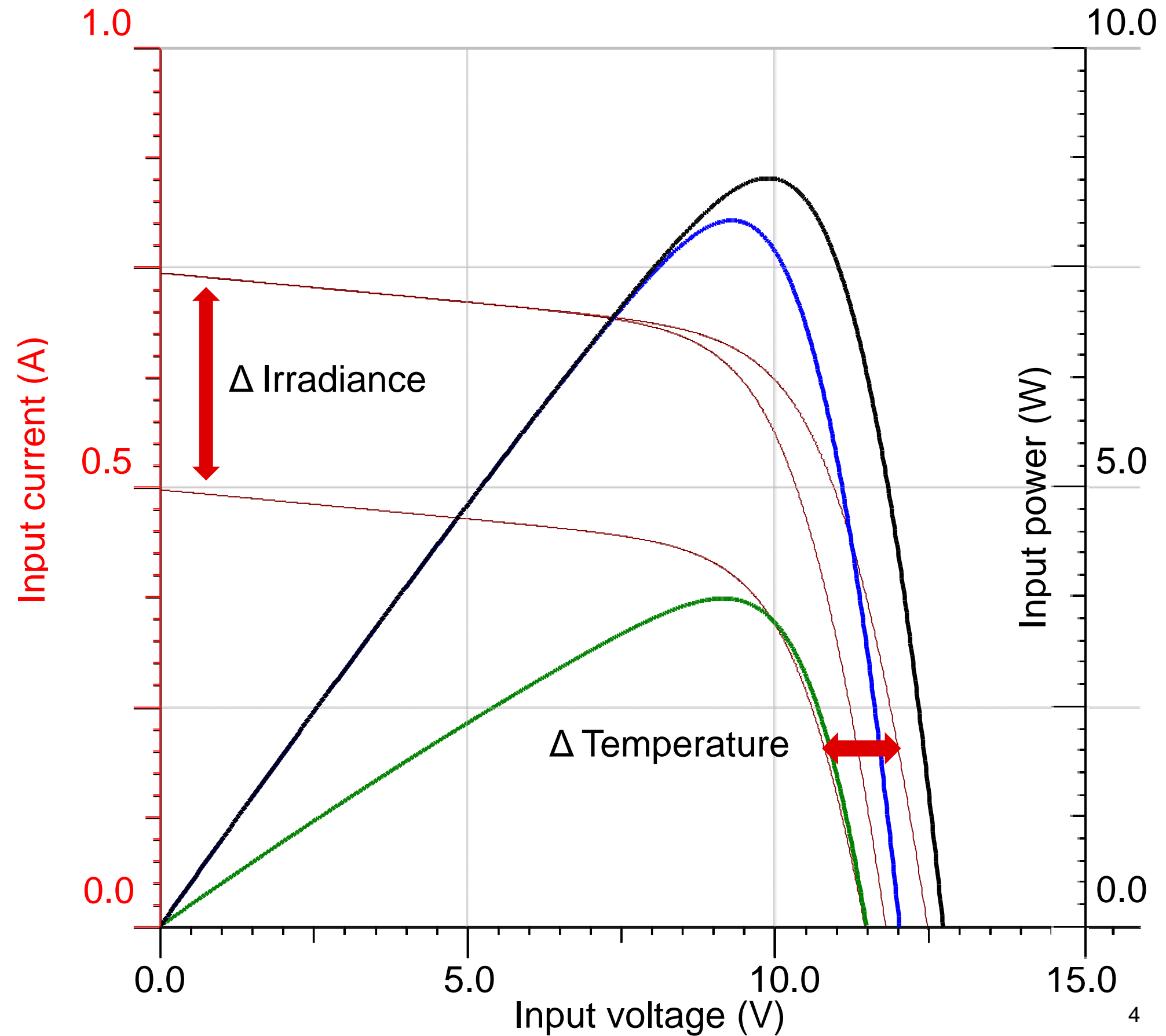
Agenda

- Solar panel application solutions
- Key charger features for solar panel maximum power point tracking (MPPT)
- MPPT algorithm implementation and results

SOLAR PANEL APPLICATION SOLUTIONS

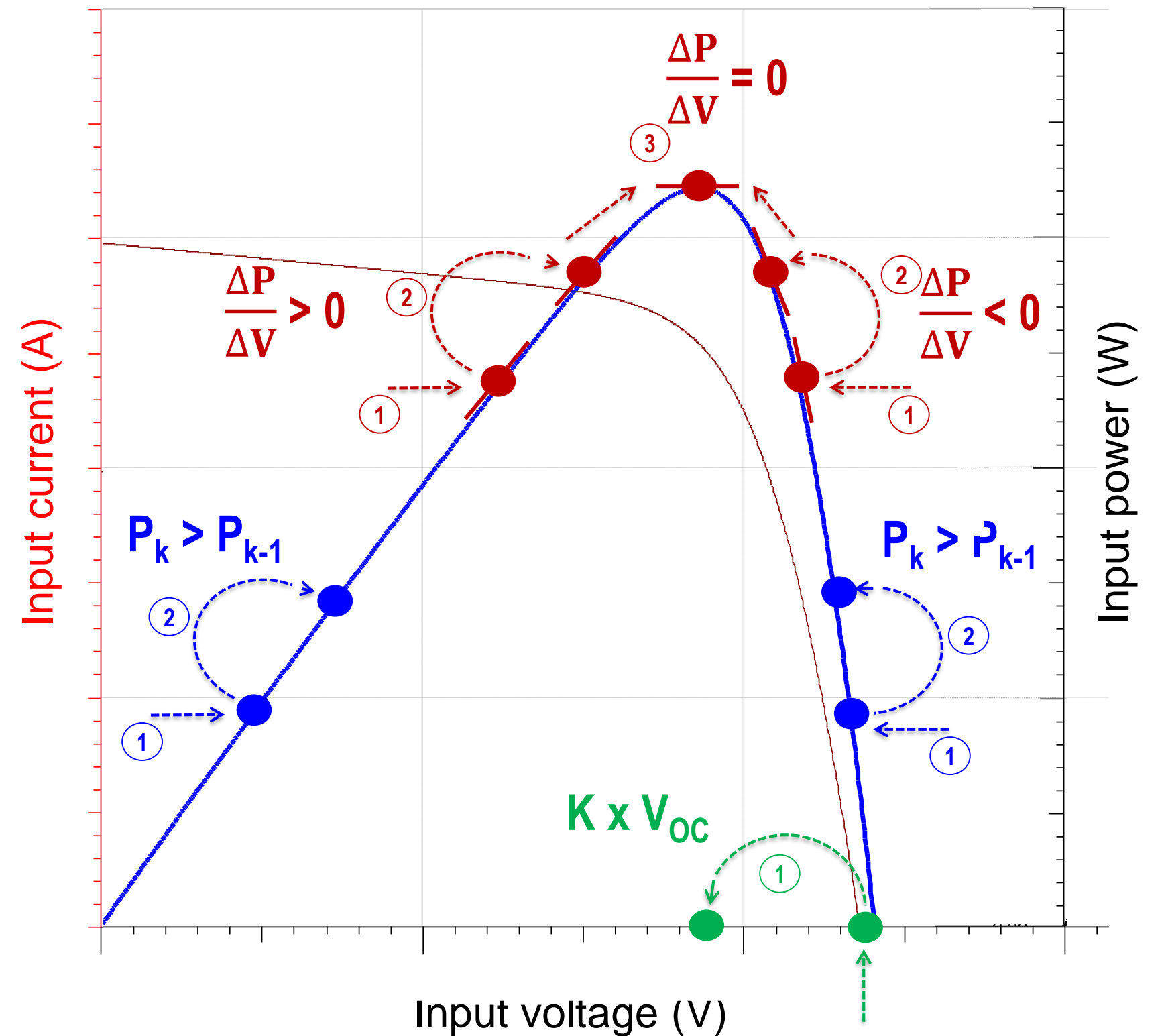
Solar characteristics

- I-V characteristic:
 - High impedance source
 - Non-ideal parameters affect curve:
 - Resistive losses
 - Diode leakage
 - Material properties
- Maximum power point (MPP):
 - Irradiance:
 - Affects short circuit current
 - Temperature:
 - Affects open circuit voltage
 - Causes MPP to move



Solar panel MPPT solutions

- Maximum power point tracking algorithm:
 - Fractional open circuit voltage (F.OCV)
 - Fixed ratio of the instantaneous open-circuit voltage
 - Perturb & observe (P&O)
 - Manipulates load and monitors the input power
 - Incremental conductance (IC)
 - Manipulates load and monitors the derivative of the input power with respect to voltage



Solution comparison

- Algorithm/controller considerations:

- Software:

- Calculation, measurement and storage
- Processing, power and speed

- Hardware:

- Sensing, memory and control
- Cost, size, speed and efficiency

- Implementation:

- Timing and power consumption

MPPT	Software	Hardware	Implementation
F.OCV	<ul style="list-style-type: none"> • Calculate $K \cdot V_{OC}$ 	<ul style="list-style-type: none"> • (V) sensor • Requires disabling input current draw 	<ul style="list-style-type: none"> • Algorithm doesn't directly account for different irradiances
P&O	<ul style="list-style-type: none"> • Calculate (P) • Store previous states 	<ul style="list-style-type: none"> • (V) and (I) sensors • Multiplier and memory 	<ul style="list-style-type: none"> • Requires fine stepping of input voltage
IC	<ul style="list-style-type: none"> • Calculate (P) and (dP/dV) • Store previous states 	<ul style="list-style-type: none"> • (V) and (I) sensors • Multiplier and memory 	<ul style="list-style-type: none"> • Requires instantaneous conductance to be calculated • Requires fine stepping of input voltage
Proposed MPPT	<ul style="list-style-type: none"> • Calculate $K \cdot V_{OC}$ • Store minimal previous states 	<ul style="list-style-type: none"> • (V) and (I) sensors • Requires disabling input current draw • Memory 	<ul style="list-style-type: none"> • Requires only infrequent open circuit voltage and battery current measurements

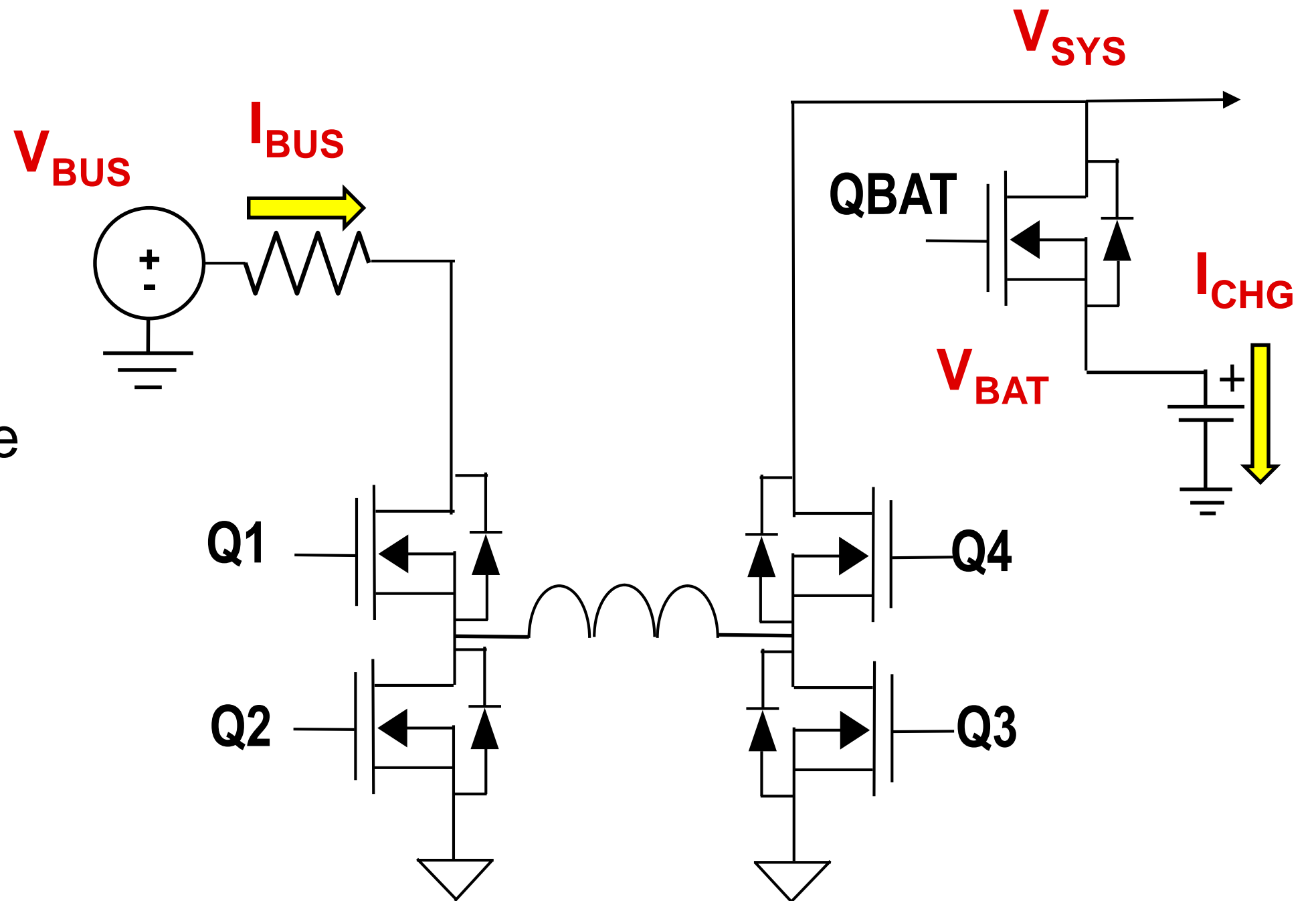
The solar charging solution: 3M approach

- Basic solar charger functions:
 - **Manipulate:**
 - Operating point and load conditions
 - Requires temporarily stopping converter
 - High-impedance (Hi-Z) mode
 - **Monitor:**
 - Key charging and input parameters
 - Requires measurement capability
 - Analog-to-digital converter (ADC)
 - **Maximize:**
 - Input power and charging current
 - Requires control of operating point:
 - V_{IN} DPM selection
 - Requires wide input range for converter
- Charging MPPT algorithm needs:
 - Accuracy:
 - Measurement and tracking
 - Simplicity:
 - Communication
 - Implementation
 - Integration
 - Low power consumption

KEY CHARGER FEATURES FOR SOLAR PANEL MPPT

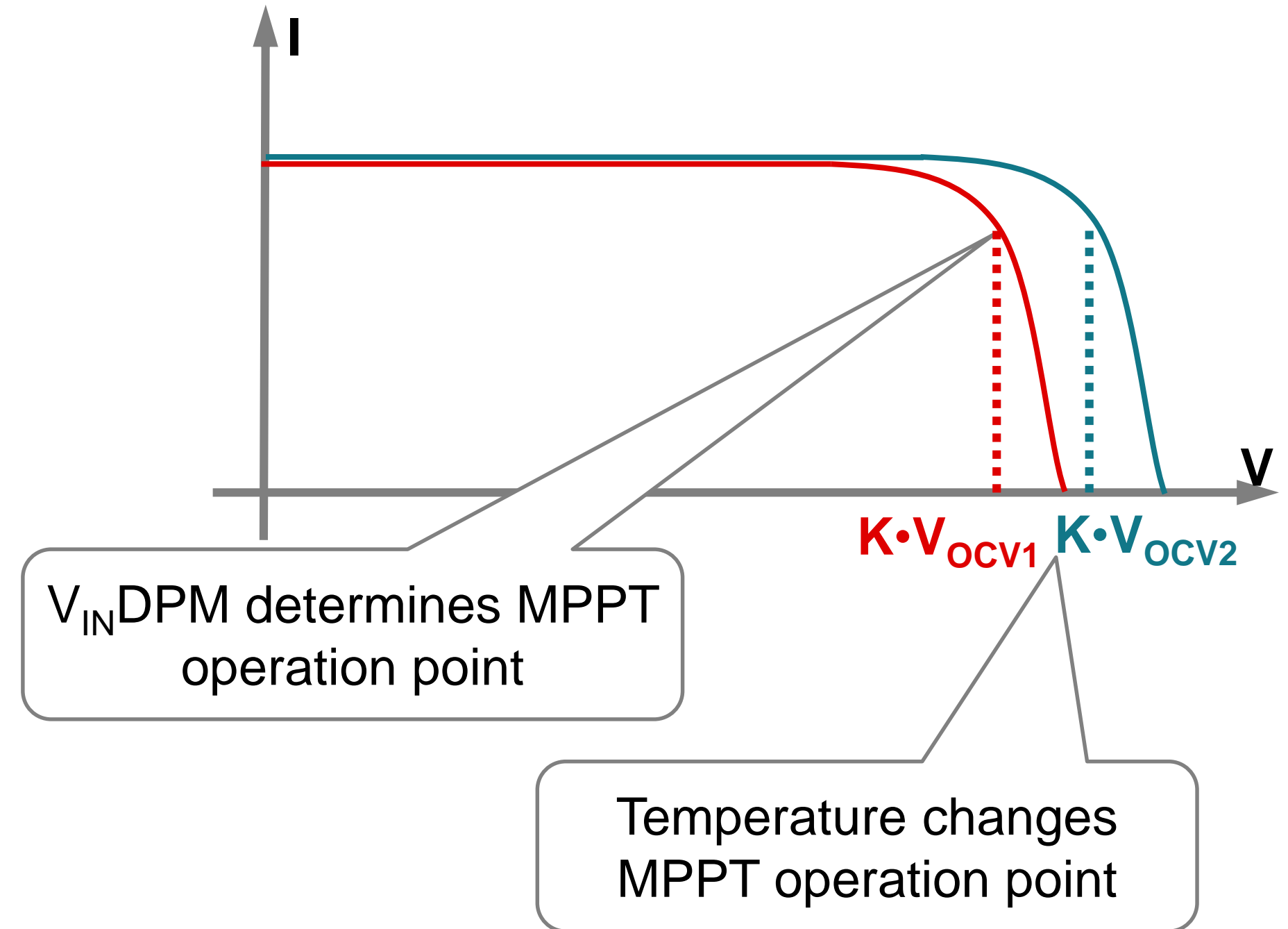
MPPT solar charger features

- **Manipulate** and **Monitor**:
 - Open circuit voltage (OCV) measurement:
 - Input Hi-Z mode
 - ADC
 - “Multiplier” to calculate $K \cdot V_{OCV}$
 - $V_{IN}DPM$ to set the MPPT input voltage
- **Maximize**:
 - Charge current measurement for optimization
- **Buck and boost topology**:
 - Wide input voltage range of input and battery



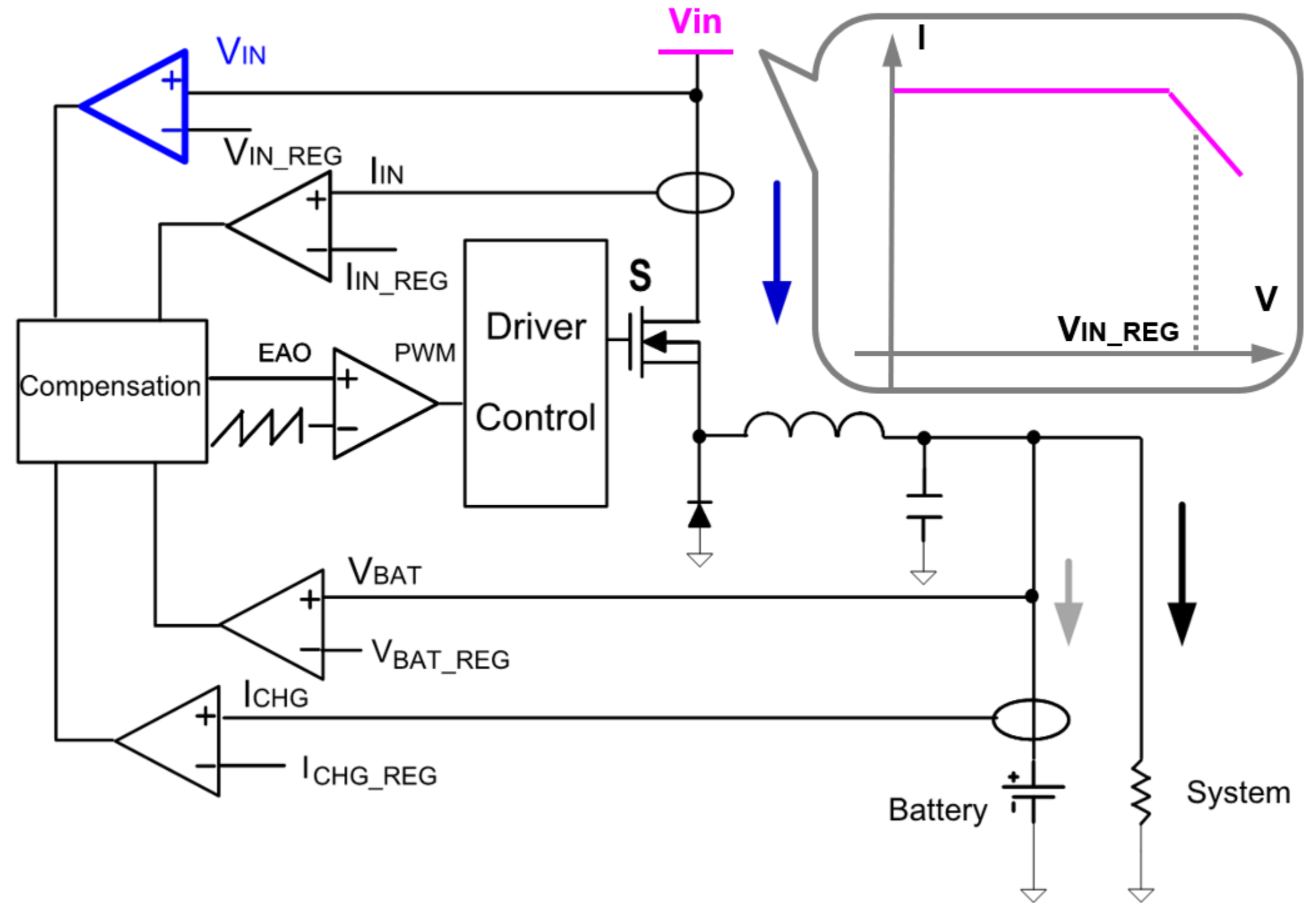
Manipulate: Regulating voltage to achieve MPPT

- In a solar application:
 - Need to **manipulate** operating point
 - Panel voltage may collapse when overloaded
 - Need to prevent “brown-out” condition
- Autonomous MPPT implementation:
 - Periodic measurement of OCV
 - K factor determined
 - $K \cdot V_{OCV}$ ($V_{IN}DPM$) determines the MPPT



Autonomous charging: $V_{IN}DPM$

- Input voltage dynamic power management ($V_{IN}DPM$):
 - Set minimum input voltage to prevent input voltage drop below this threshold
- Autonomous MPPT implementation:
 - Set $K \cdot V_{OCV}$ as $V_{IN}DPM$



K factor selection

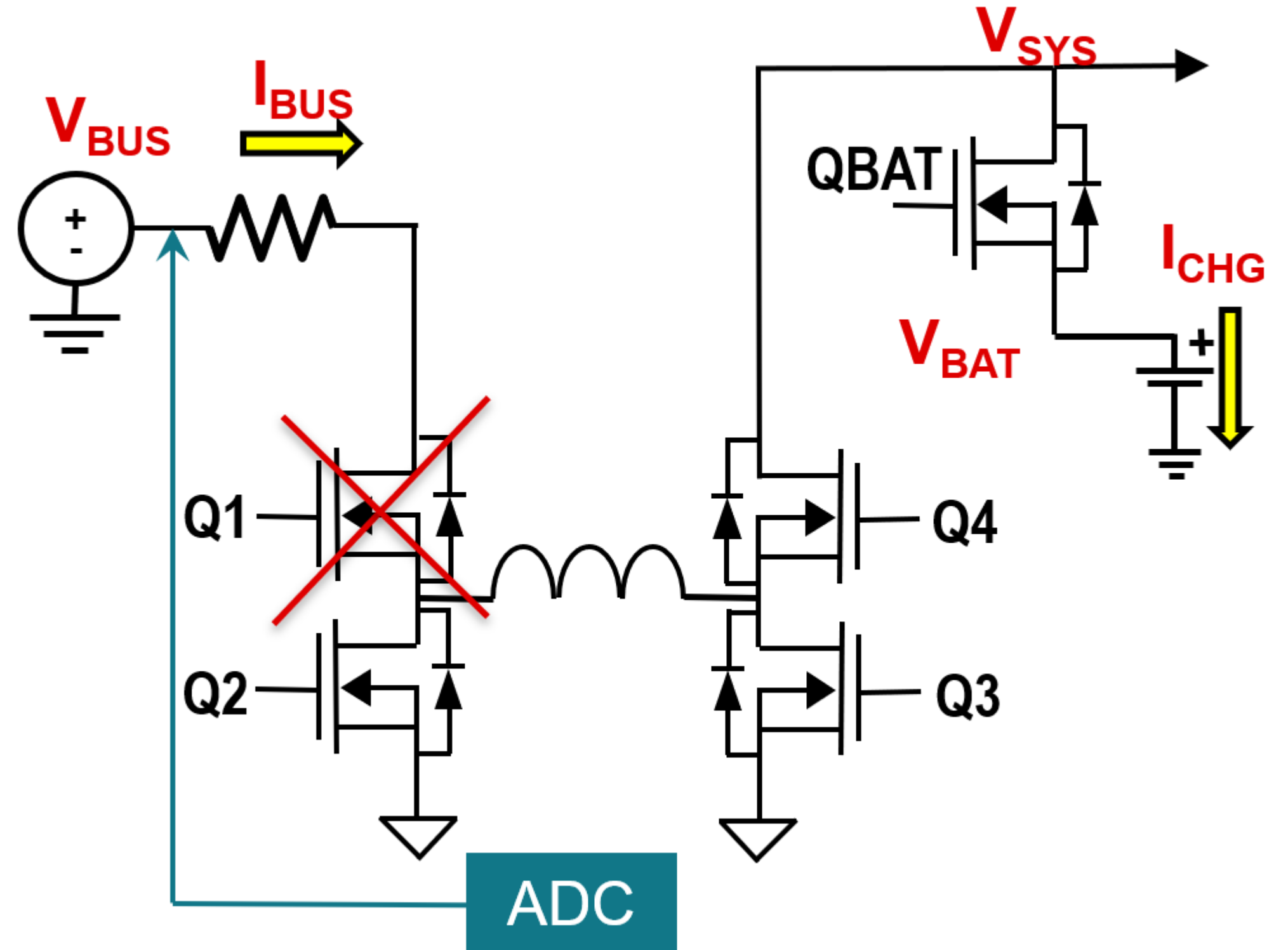
Table 8-31. REG15_MPPT_Control Register Field Descriptions

Bit	Field	Type	Reset	Notes	Description
7-5	VOC_PCT_2:0	R/W	5h	Reset by: REG_RST	To set the VINDPM as a percentage of the VBUS open circuit voltage when the VOC measurement is done. Type : RW POR: 101b 0h = 0.5625 1h = 0.625 2h = 0.6875 3h = 0.75 4h = 0.8125 5h = 0.875 (default) 6h = 0.9375 7h = 1

- Determined by the solar panel, temperatures, sunlight, etc.
- BQ25798 offers different options from 56.3% to 93.8% – configurable via I²C
- Implement the “multiplier” automatically

Manipulate and monitor: OCV measurement

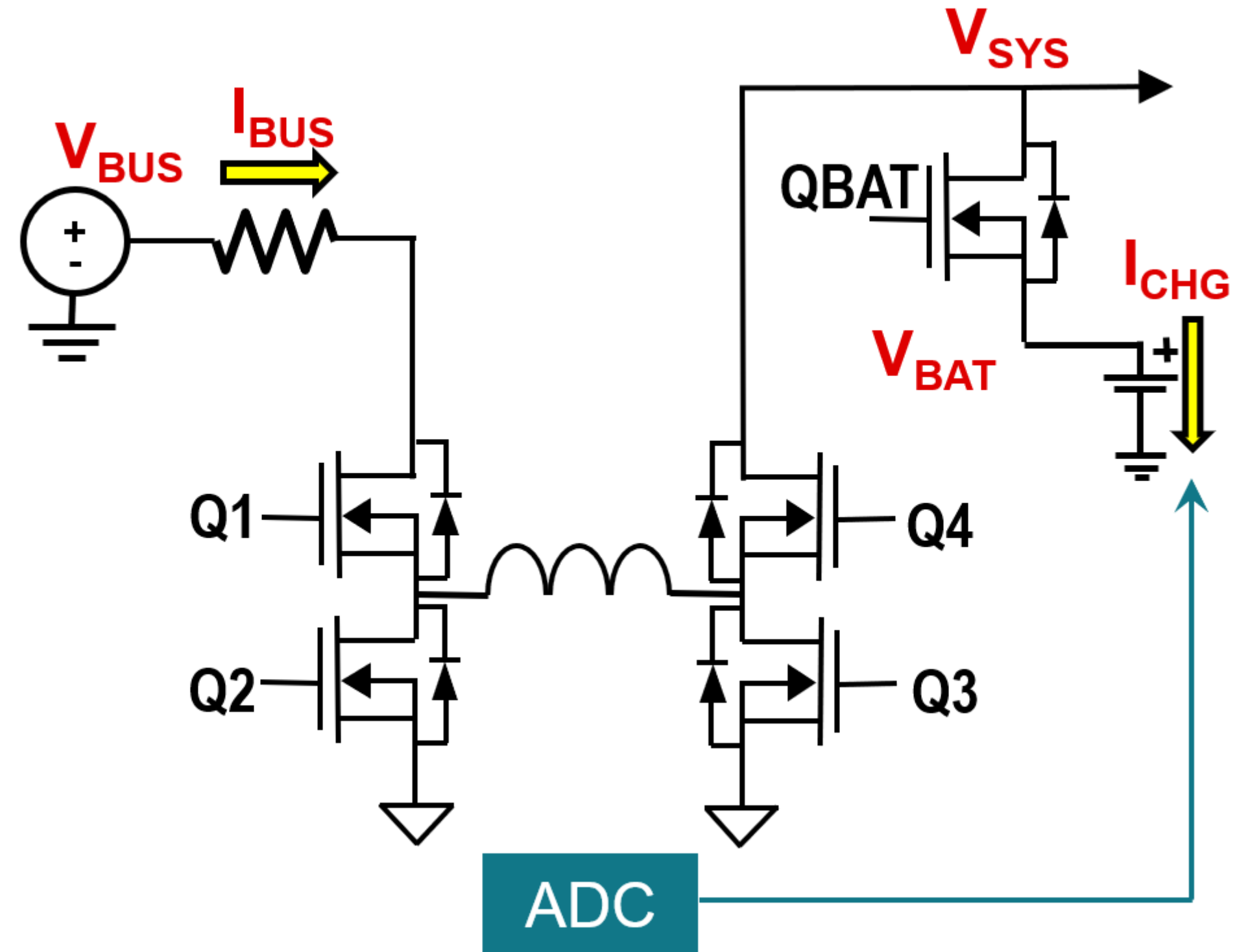
- Input Hi-Z mode:
 - Disables converter and internal biasing
 - VBUS sees unloaded input source voltage
- In a solar application:
 - **Manipulate** the input voltage of the panel
 - **Monitor** the input voltage of the panel
 - Good option for F. OCV MPPT



Maximize: Monitoring the charging current (I_{CHG})

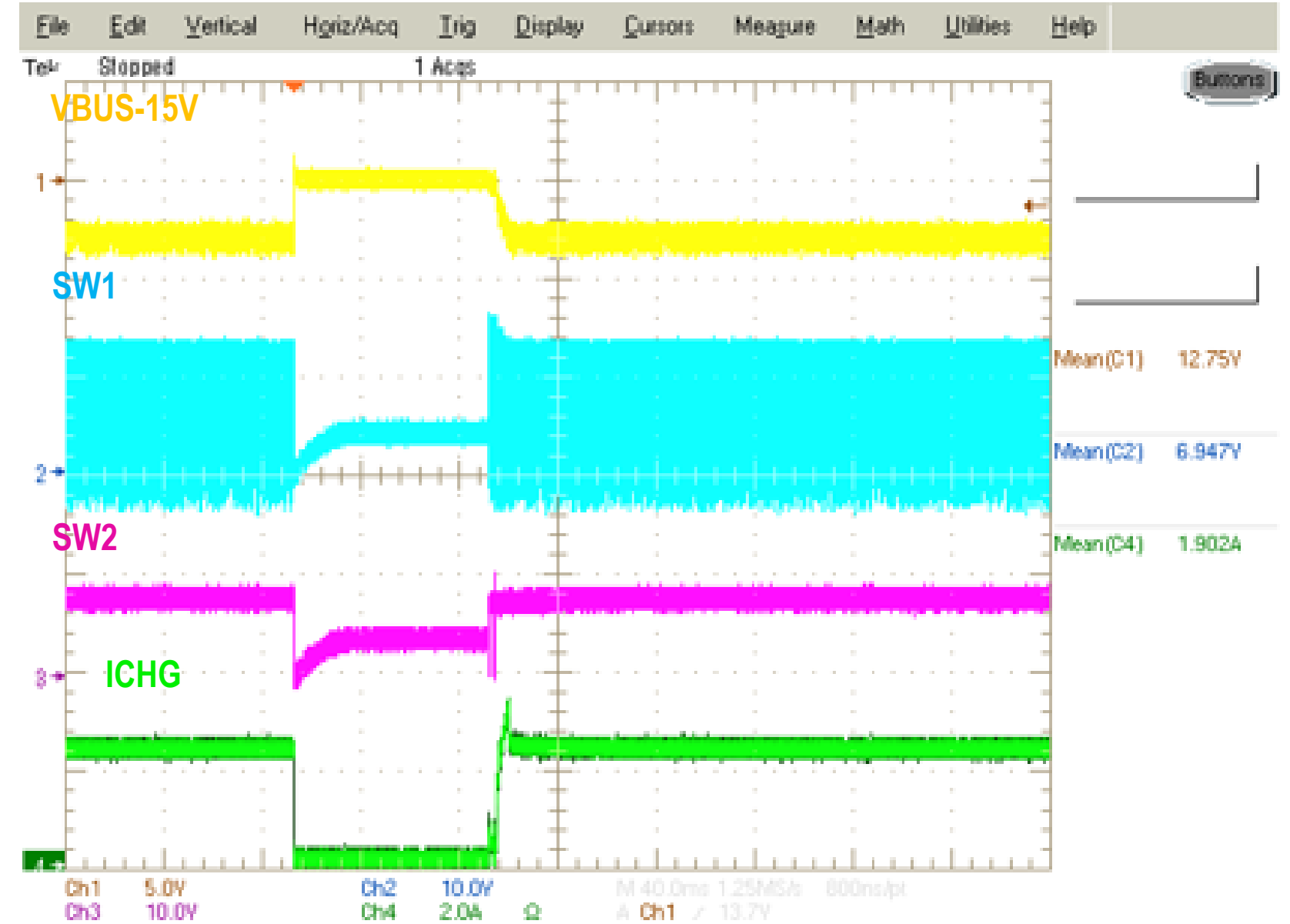
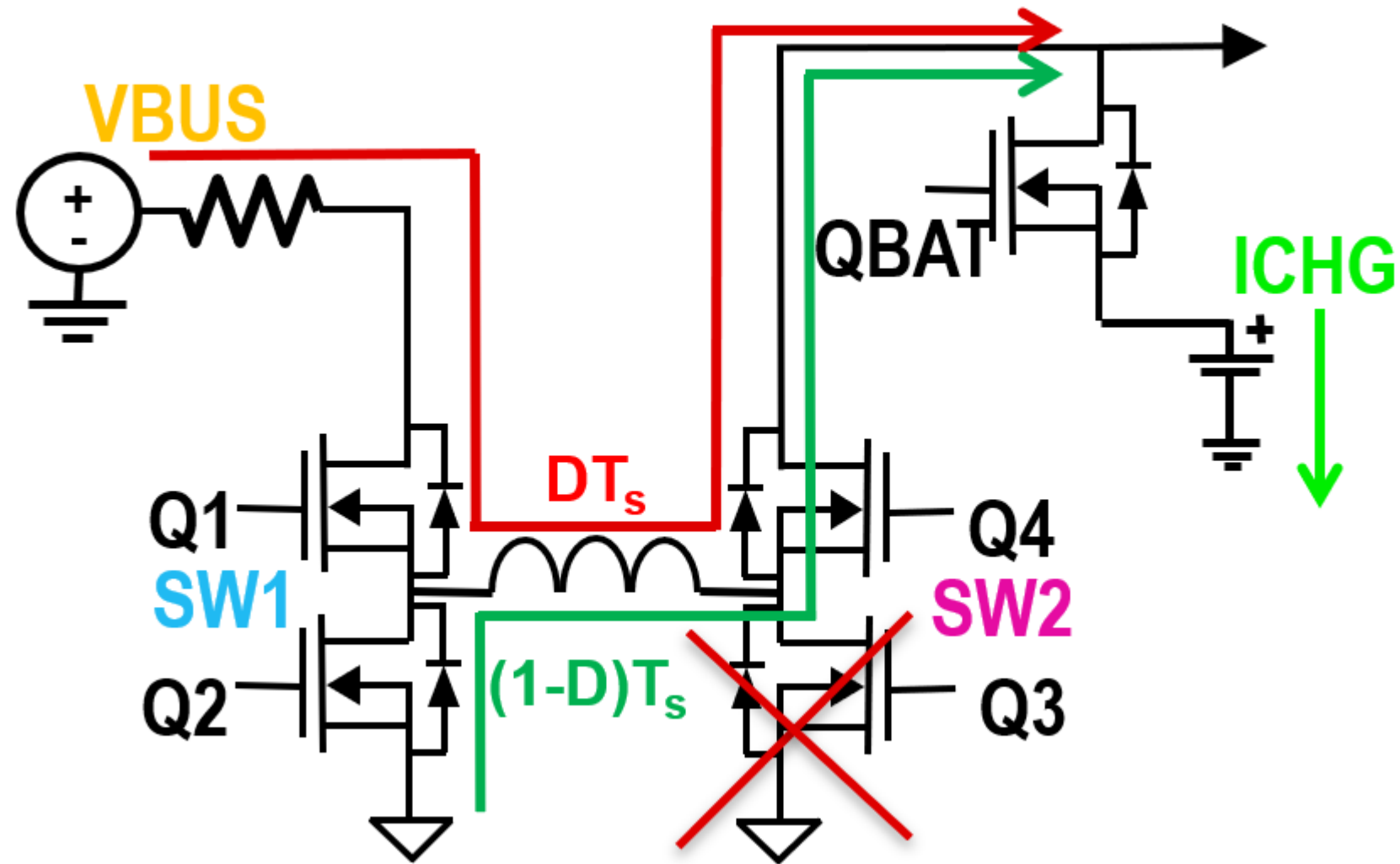
- Host control of the ADC:
 - Measure I_{CHG} to measure output power
 - Checking I_{CHG} **maximizes** the input power
 - $P = V_{BAT} \times I_{CHG}$

Remains constant in a short time period



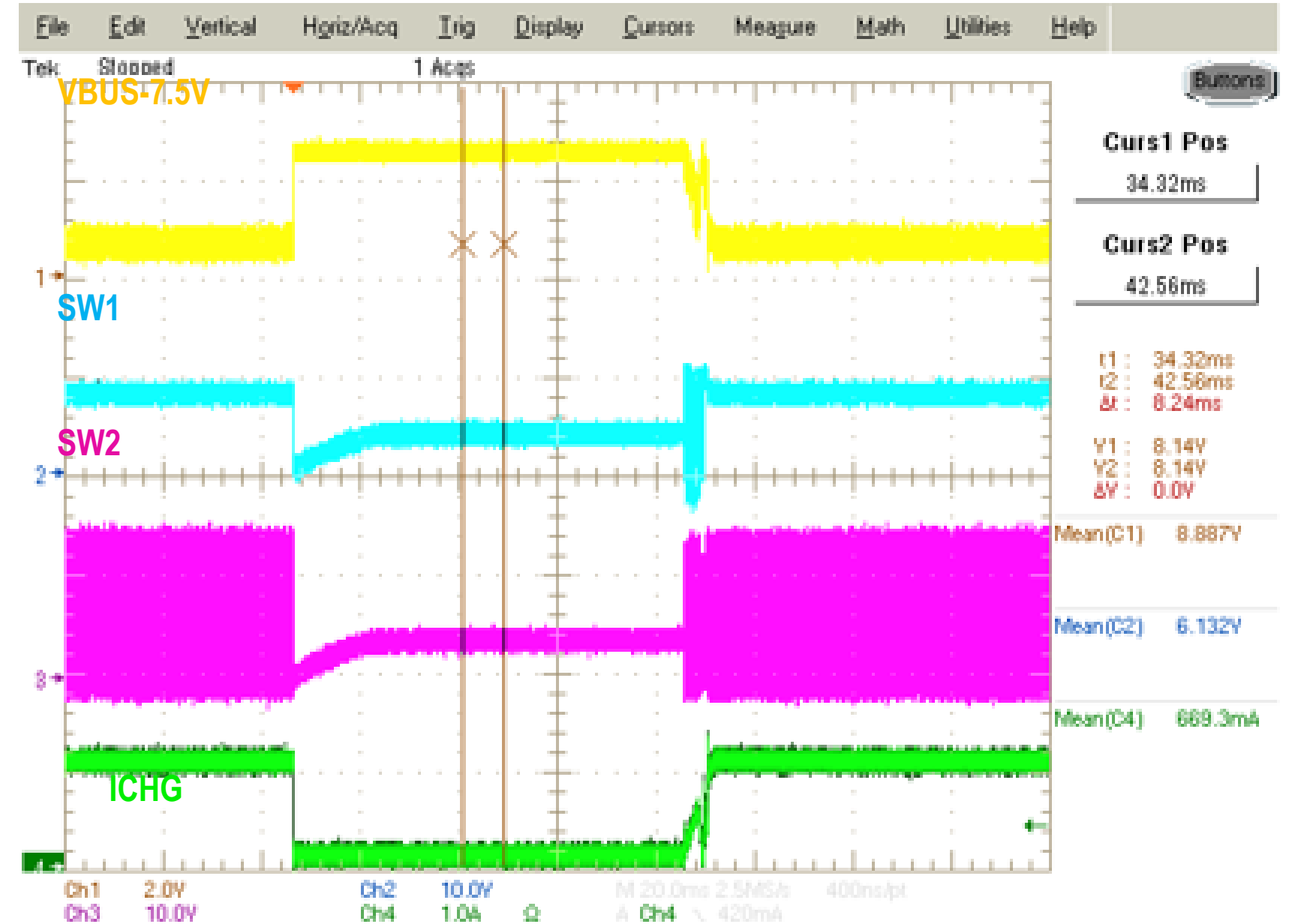
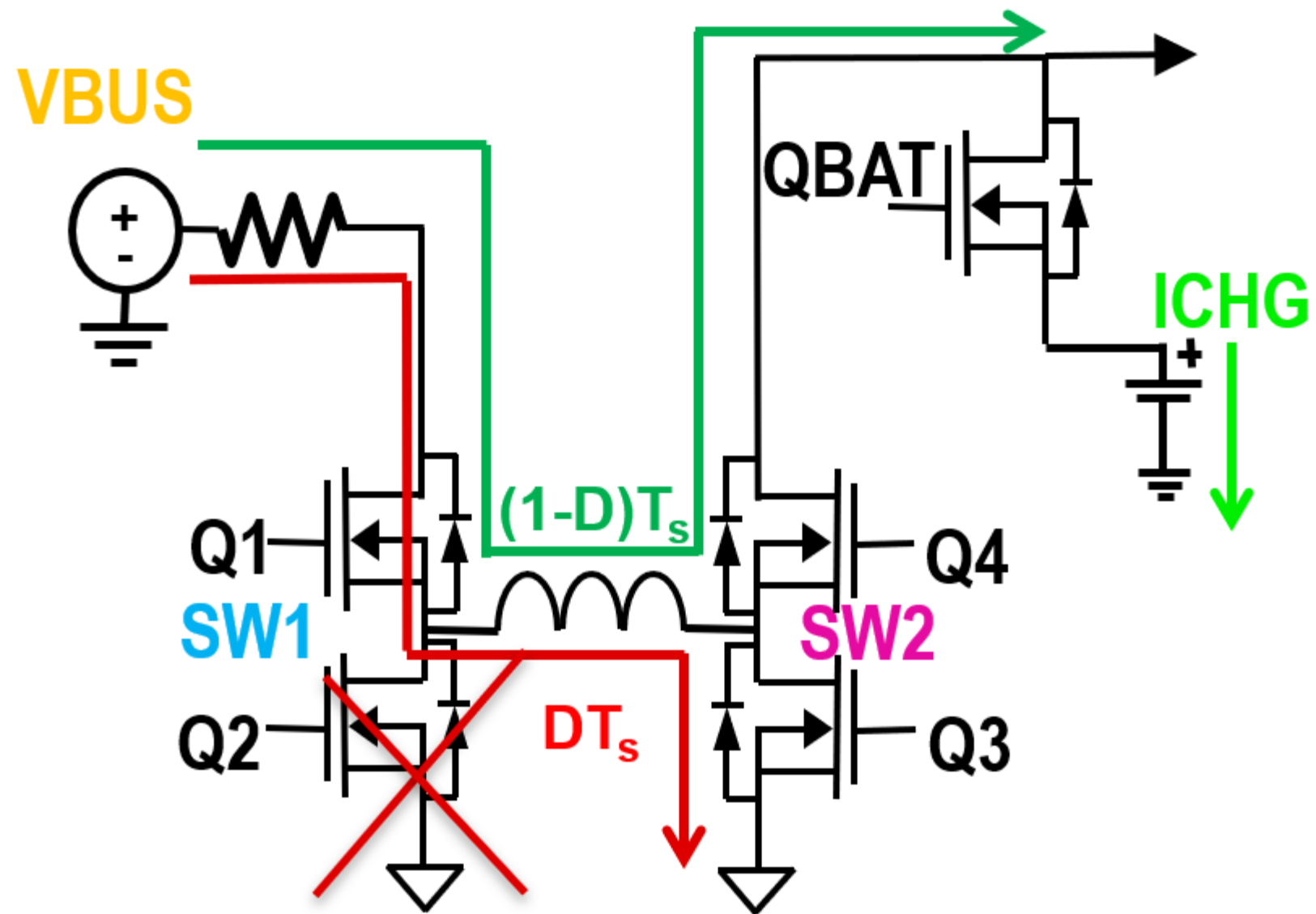
MPPT ALGORITHM IMPLEMENTATION AND RESULTS

Autonomous MPPT: Buck operation ($7.3 V_{BAT}$)



- Converter turns off to measure open-circuit voltage and update $V_{IN}DPM$
- Charging resumes for 30 seconds
- $15 V_{IN}$, 1.5-A supply current limit and 7.3-V battery

Autonomous MPPT: Boost operation ($11.5 V_{BAT}$)

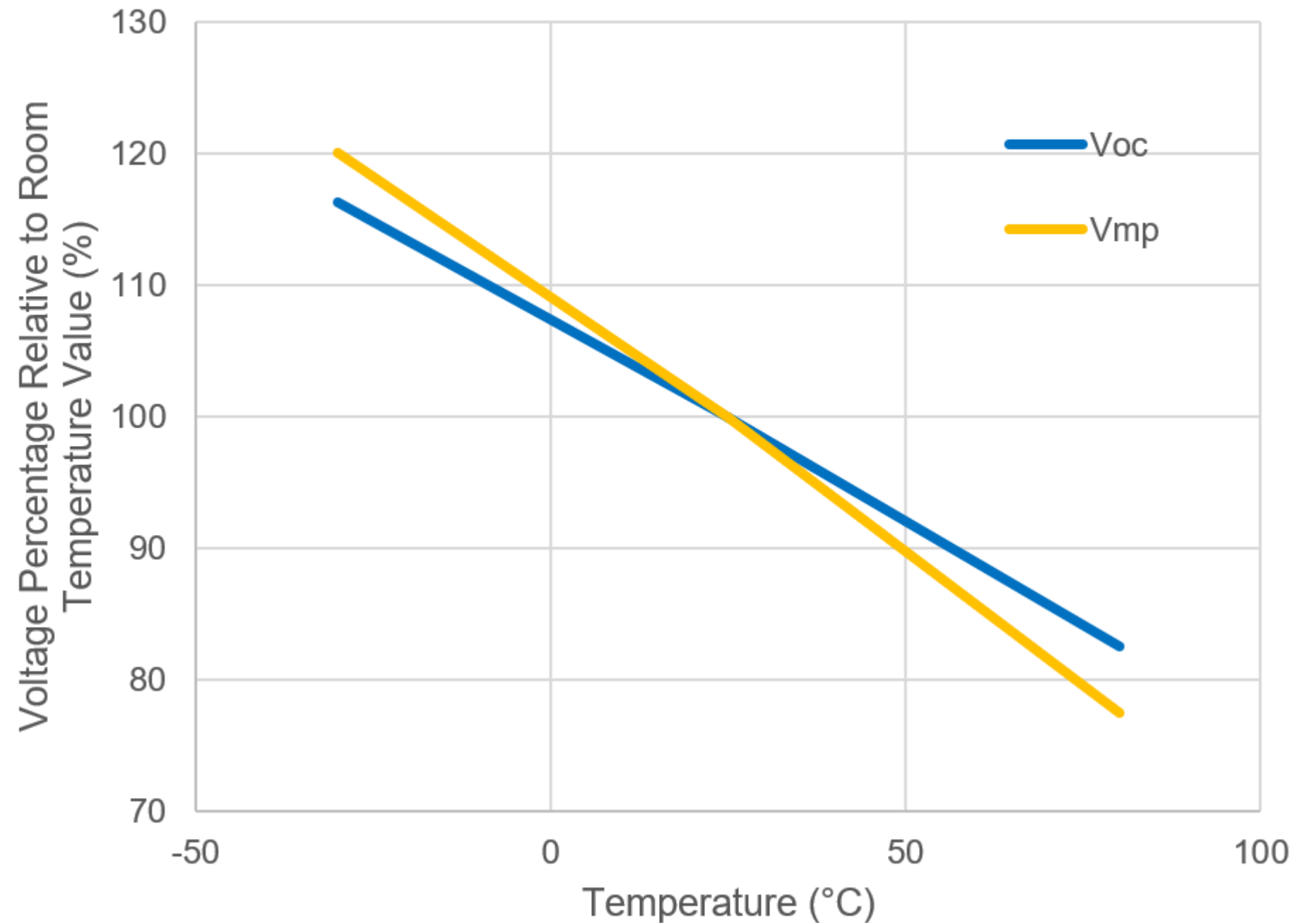


- Converter turns off to measure open-circuit voltage and update $V_{IN}DPM$
- Charging resumes for 30 seconds
- $10 V_{IN}$, 1.5-A supply current limit, 11.5-V battery

MPPT across temperature

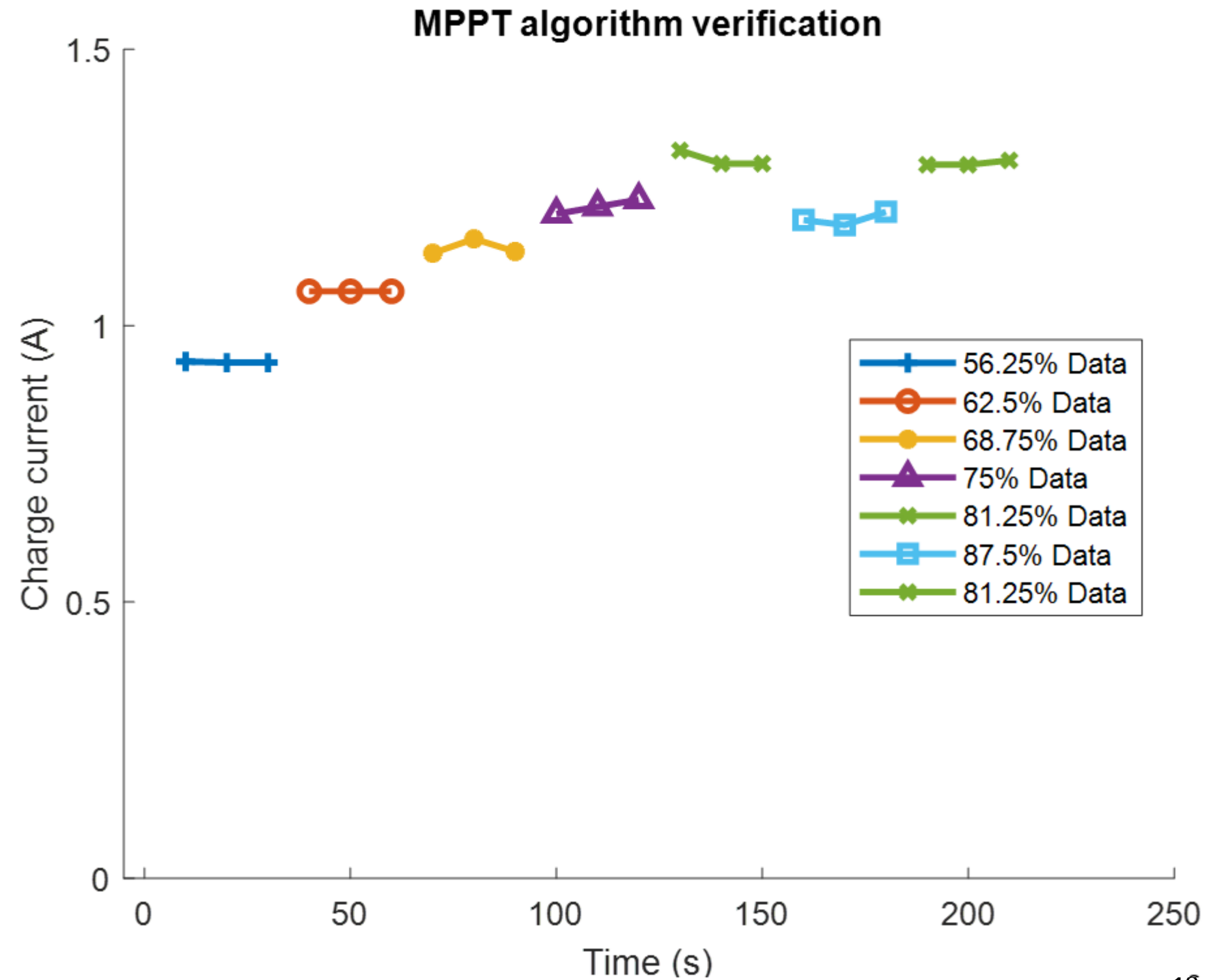
- As temperature changes, the MPPT voltage and the open circuit voltage change by roughly the same percentage
- For a fully sunny day, a fixed percentage of the open circuit voltage will **maximize** the power throughout the day as the temperature changes

Solar Panel Characteristics vs Temperature



Algorithm flow example

- **Monitor:**
 - Input voltage and charge current using an ADC
- **Manipulate:**
 - Test different operating points using Hi-Z and $V_{IN}DPM$
- **Maximize:**
 - Update $V_{IN}DPM$ percentage based upon which setting yielded the most charge current
 - Repeat as conditions change



Algorithm flow diagram

- **Monitor:**

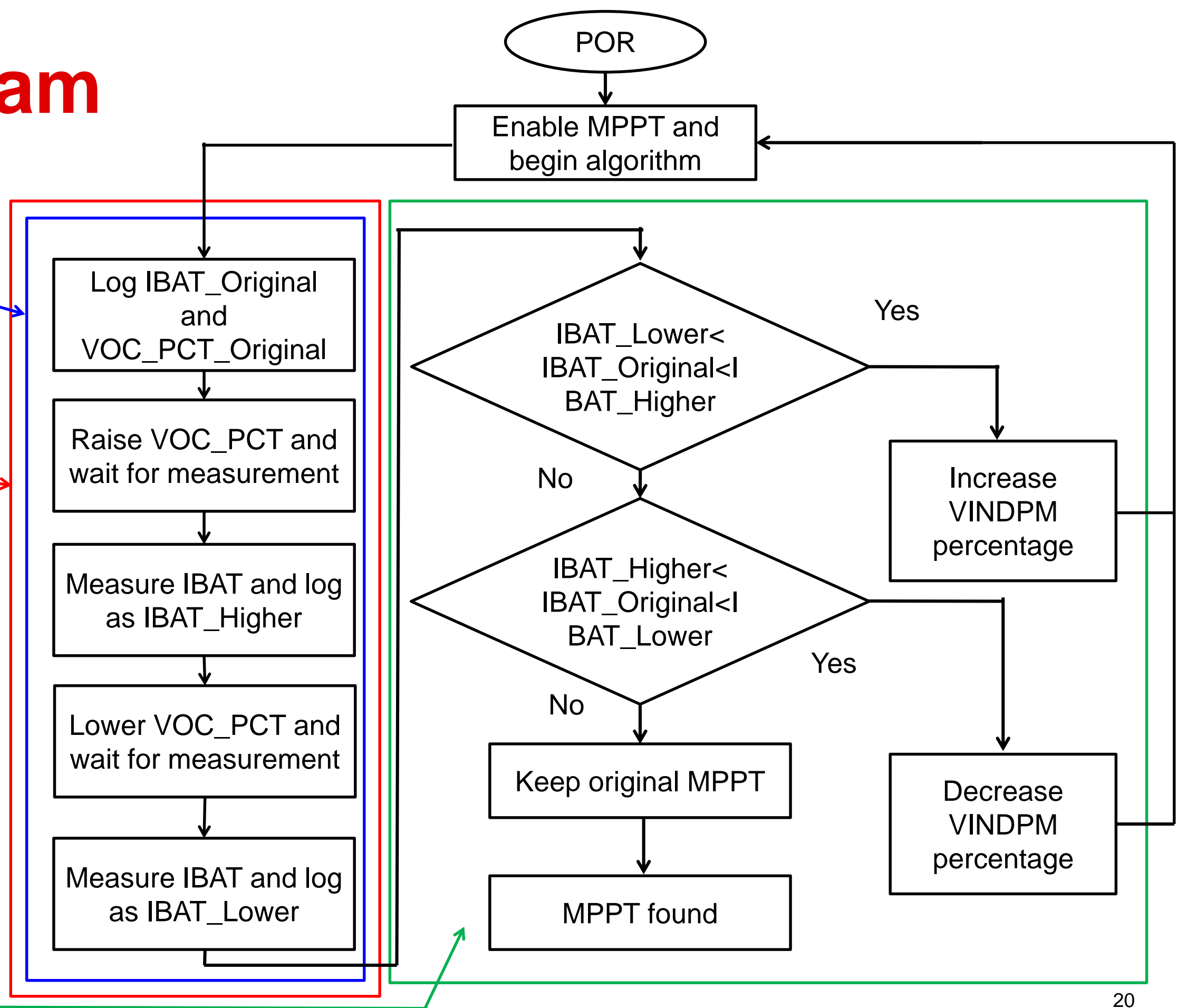
- Input voltage and charge current using an ADC

- **Manipulate:**

- Test three different operating points using Hi-Z and $V_{IN}DPM$

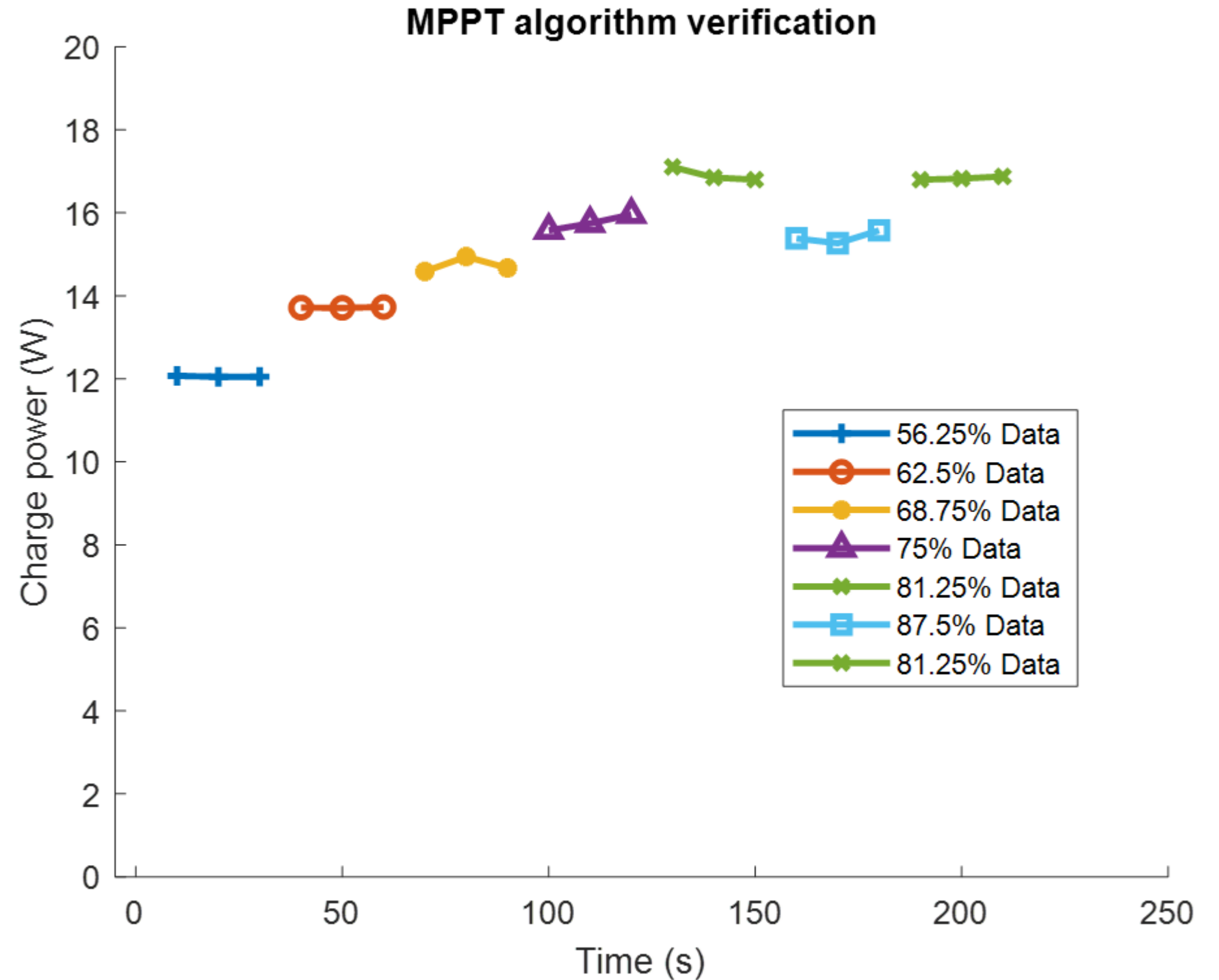
- **Maximize:**

- Update $V_{IN}DPM$ percentage based upon which setting yielded the most charge current
- Repeat as conditions change



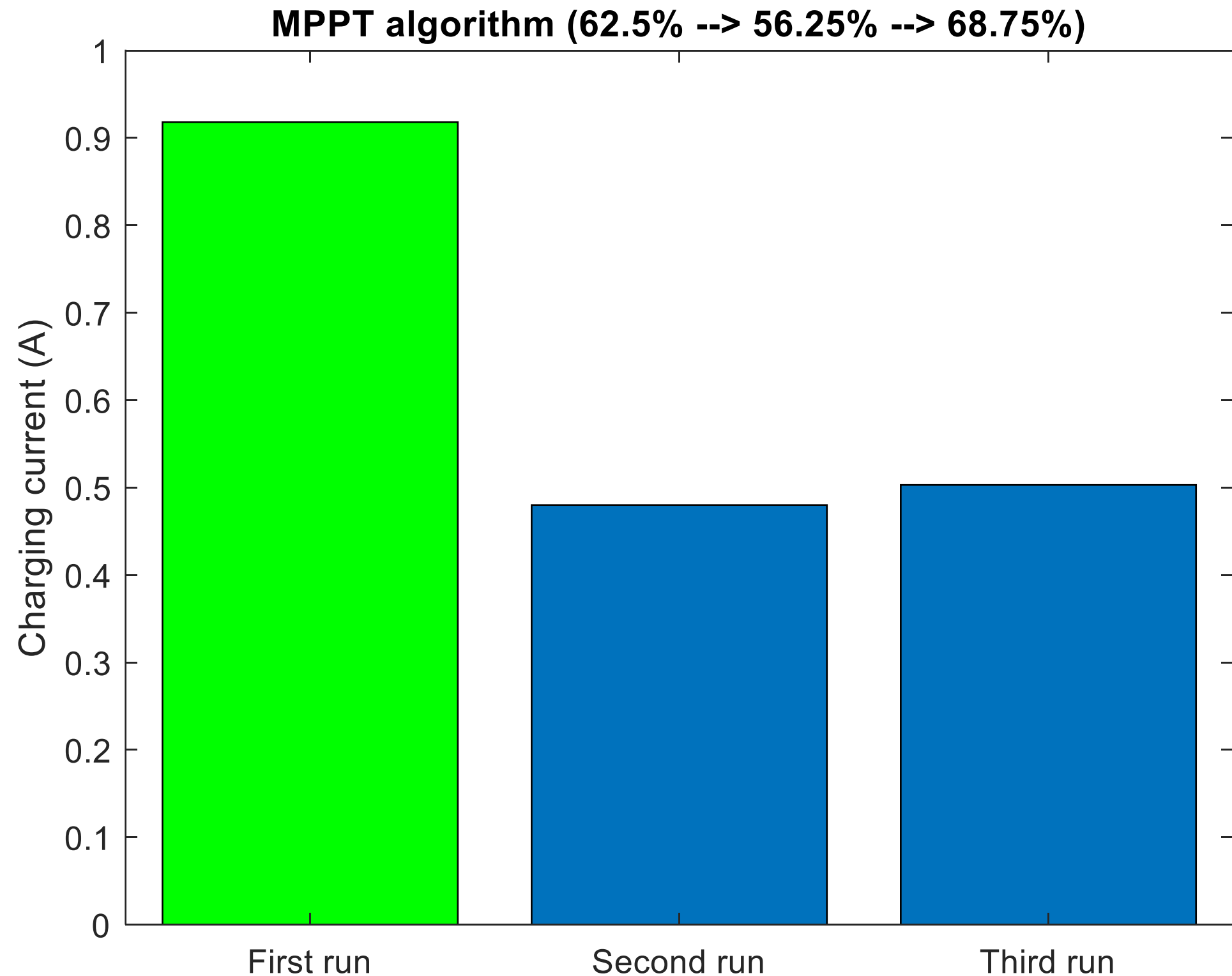
Maximize: Sunny day charge power

- Very sunny
- Approximately 13-V battery with solar input voltage of ...
 - 10.1-V (boost)
 - 11.3-V (boost)
 - 12.4-V (boost)
 - 13.5-V (buck-boost)
 - 14.6-V (buck)
 - 15.8-V (buck)
- 81.25% V_{IN} DPM **maximizes** charging current



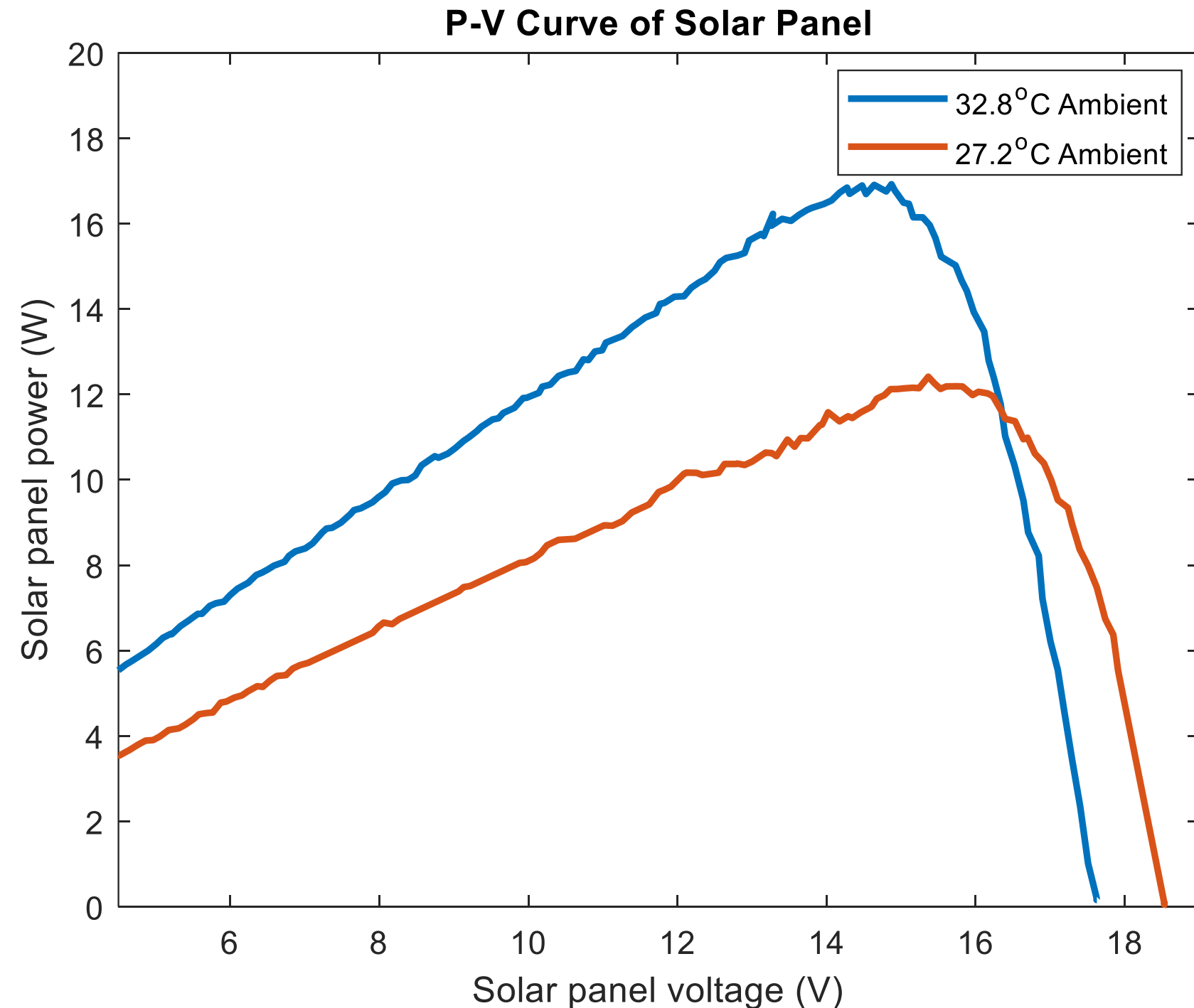
Maximize: Partly cloudy run charge current

- Intermittent cloud activity
- 13-V battery with solar input voltage of ...
 - 11.3-V (boost)
 - 10.1-V (boost)
 - 12.0-V (boost)
- 62.5% V_{IN} DPM maximizes charging current



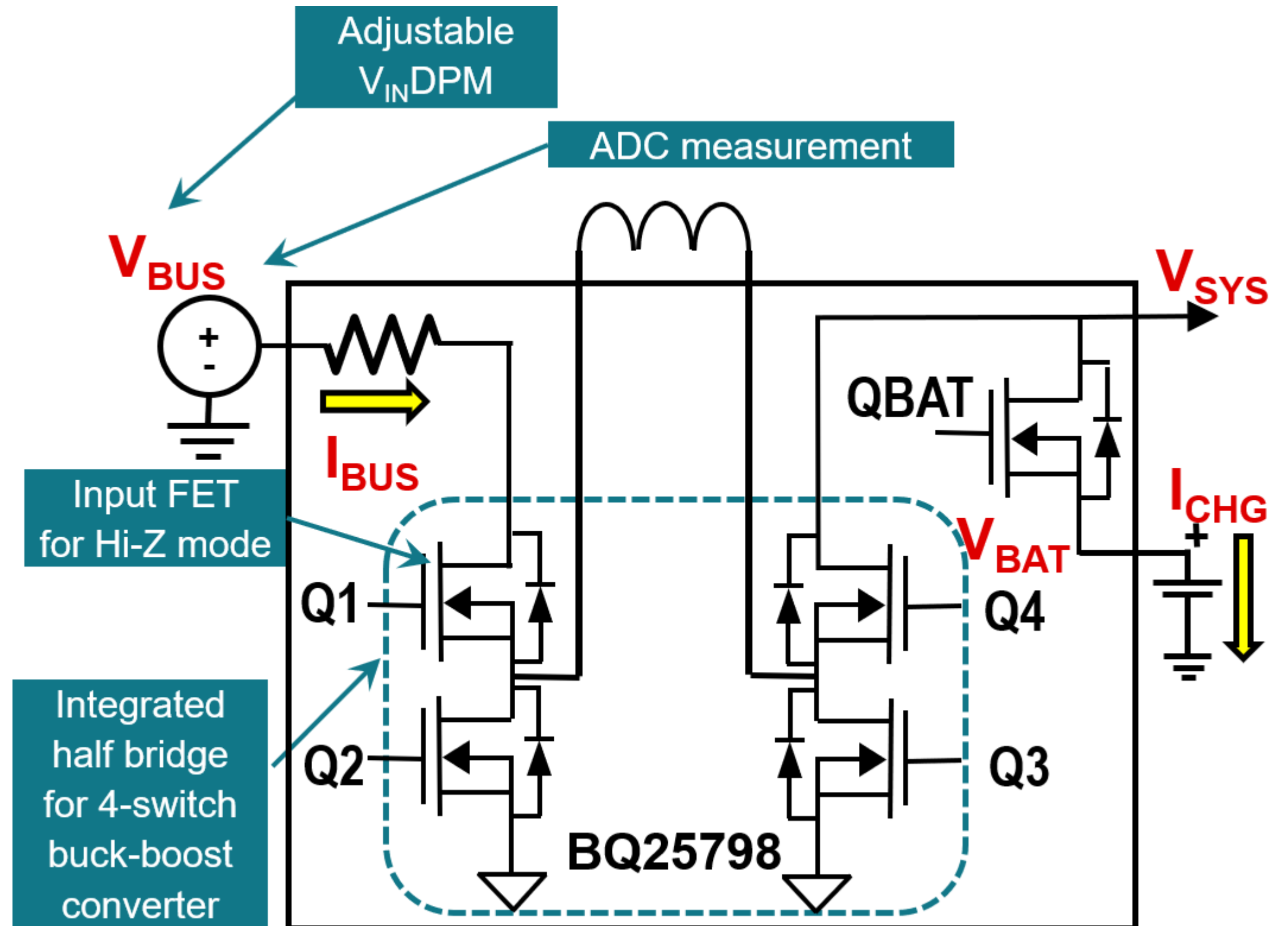
Maximize: Solar panel characterization

- Different irradiance and temperature test environment
- Approximately 12.8-V battery
 - Converter operating in buck and boost mode
- MPPT occurs around ...
 - 14.6-V for brighter test
 - 15.5-V for less bright test
- 81.25% setting **maximizes** input power



Solar charger: BQ25798

- Autonomous MPPT for solar input
 - Input Hi-Z mode
 - 16-bit integrated ADC for further system optimization
 - Only need to set K factor for $K \cdot V_{OCV}$ ($V_{IN\ DPM}$)
- Buck-boost topology with wide input voltage range
 - 3.6-V ~ 24-V



Summary

- Solar power tracking:
 - Max power dependent on sunlight and temperature
 - Three algorithms compared
 - **Manipulate**, **monitor**, and **maximize** input and output conditions for faster charging
- BQ25798: **Manipulate** and **Monitor**
 - Autonomous MPPT with K factor setting: integrated features for easy design and small solution size
- Simple MPPT implementation: **Maximize**
 - Max I_{CHG} indicates maximum power point due to steady battery voltage
 - Proposed algorithm combines fractional open circuit voltage and perturb and observe approaches
- MPPT operation achieved under varying weather conditions and with various solar panels



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