

# HIGH VOLTAGE SEMINAR

## BEN LOUGH

### HIGH VOLTAGE CONTROLLERS

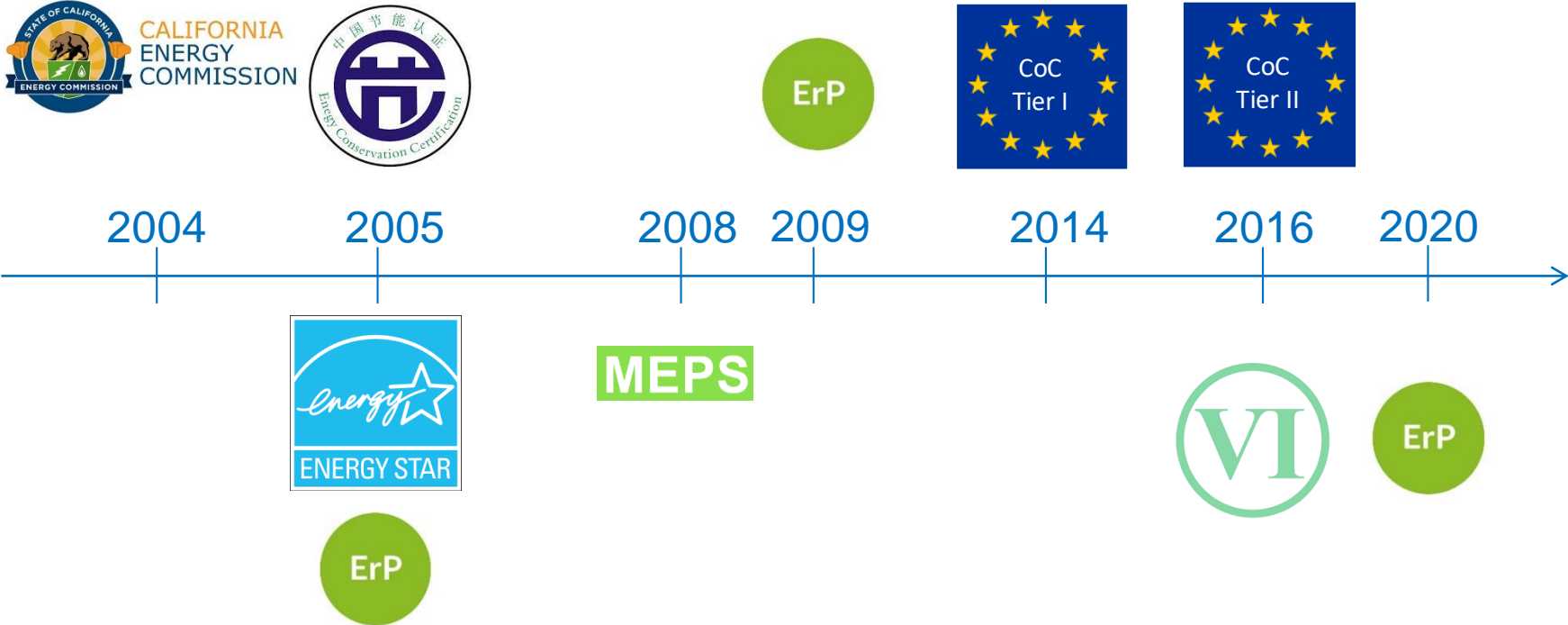
IMPLEMENTATION OF WIDE OUTPUT  
LLC IN POWER TOOL CHARGING AND  
LED LIGHTING APPLICATIONS



# Agenda

- Efficiency targets and standards
- Battery charging and LED lighting application overview
- The LLC topology
- Practical implementation considerations

# Efficiency standards: timeline



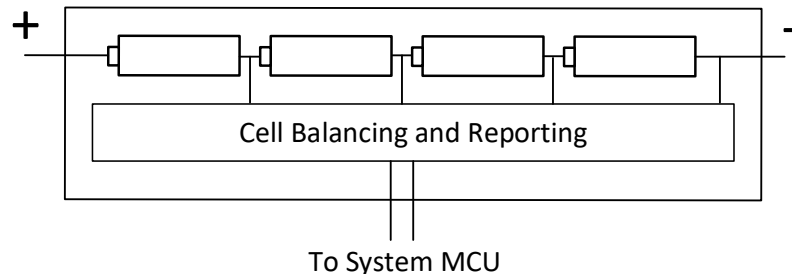
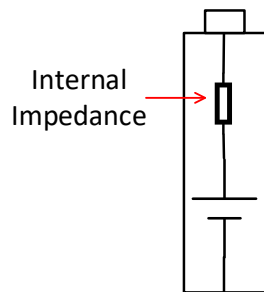
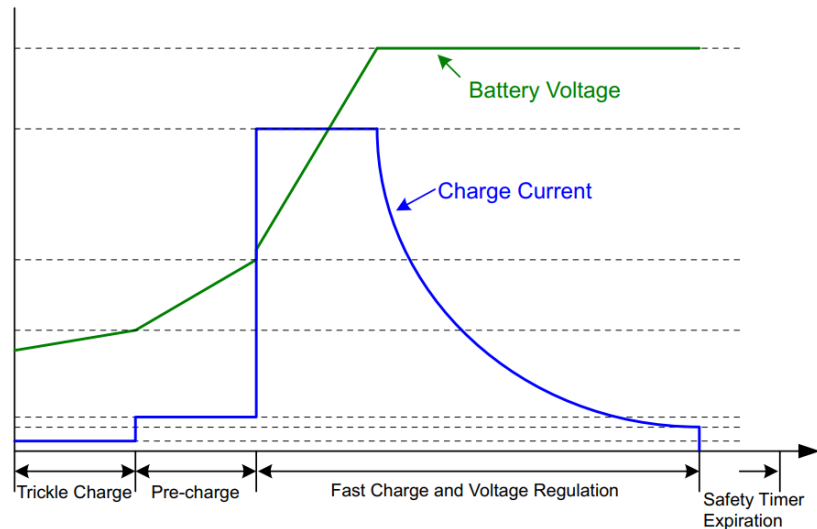
# DOE Level VI and Ecodesign 2019/1782

AC/DC low voltage external power supplies (excludes multi-output)		
Nameplate output power (P <sub>out</sub> )	Maximum input power at no load (in decimal)	Minimum average efficiency (active mode)
<1 W	$\leq 100 \text{ mW}$	$\geq 0.517 \times P_{out} + 0.087$
1 W to 49 W	$\leq 100 \text{ mW}$	$\geq 0.0834 \times \ln(P_{out}) - 0.0014 \times P_{out} + 0.609$
49 W to 250 W	$\leq 210 \text{ mW}$	$\geq 0.870$
>250 W	$\leq 500 \text{ mW}$	$\geq 0.875$

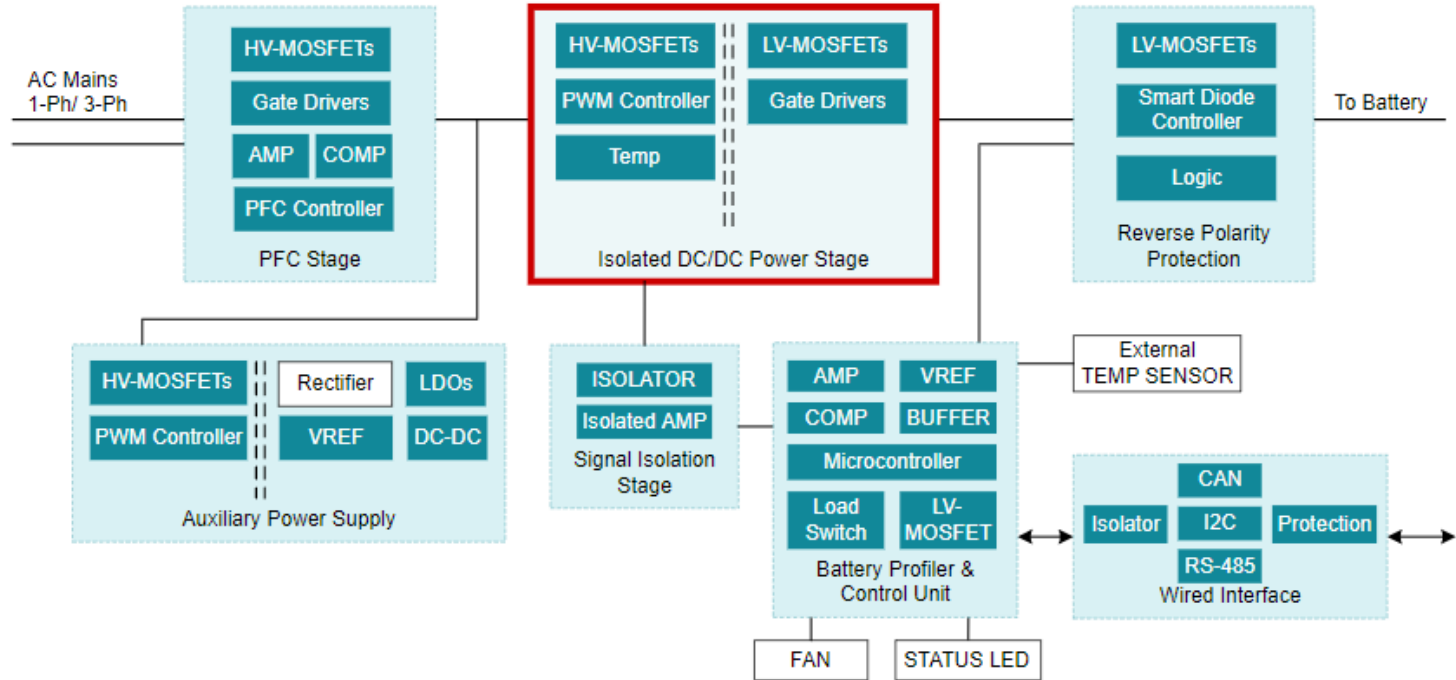
Key Differences			
	DOE Level VI	Ecodesign 2019/1782	CoC Tier II
Mandatory?	Yes	Yes	Voluntary
10% Load Requirement?	No	Reported but no requirement	Yes
Includes >250W Supplies?	Yes	No	No

# Battery charging: overview

- Typical Output Voltage Range
  - 2.7 V to 4.4 V per cell for Li-ion chemistries
  - Cells stacked in series
  - Some chargers will support trickle charging for severely depleted batteries
- Battery charged at fixed current, then regulated at fixed voltage

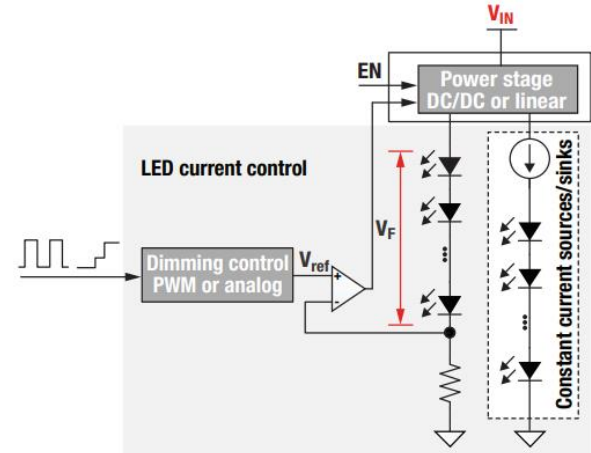
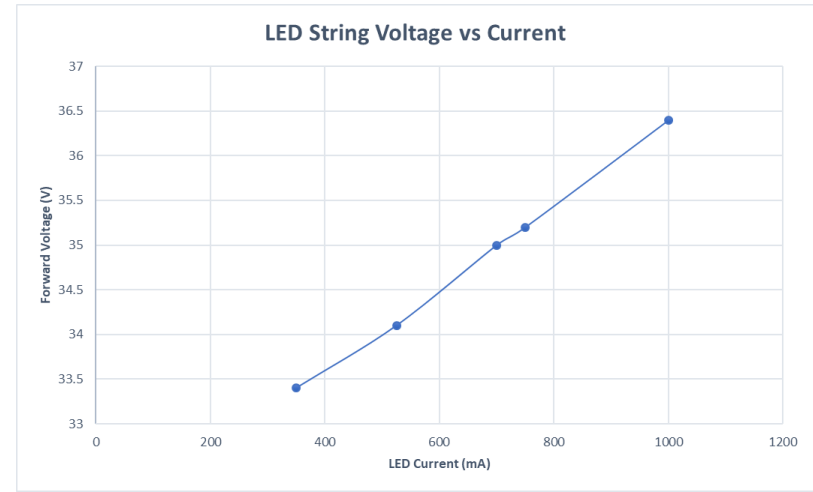


# Battery charging: typical AC/DC charger

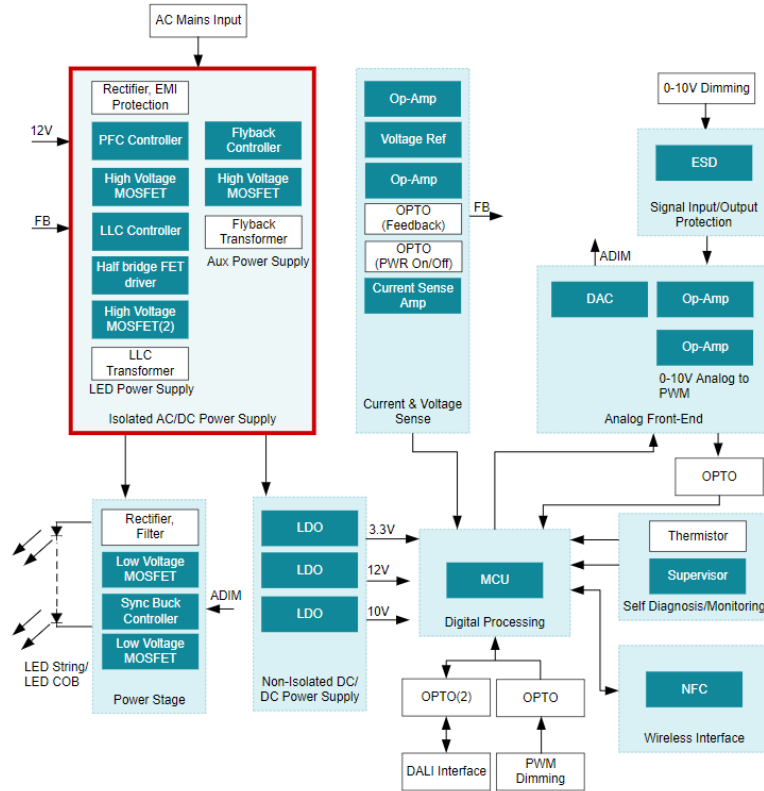


# LED lighting

- Typical input of 120 Vac to 277 Vac, PFC bus voltage of ~450 V
- Brightness proportional to current
- Forward voltage increases as forward current increases
- Constant Current (CC)
  - Easy to achieve more consistent brightness by regulating LED current
- Constant Voltage (CV)
  - Required for some light engines with built in dimming



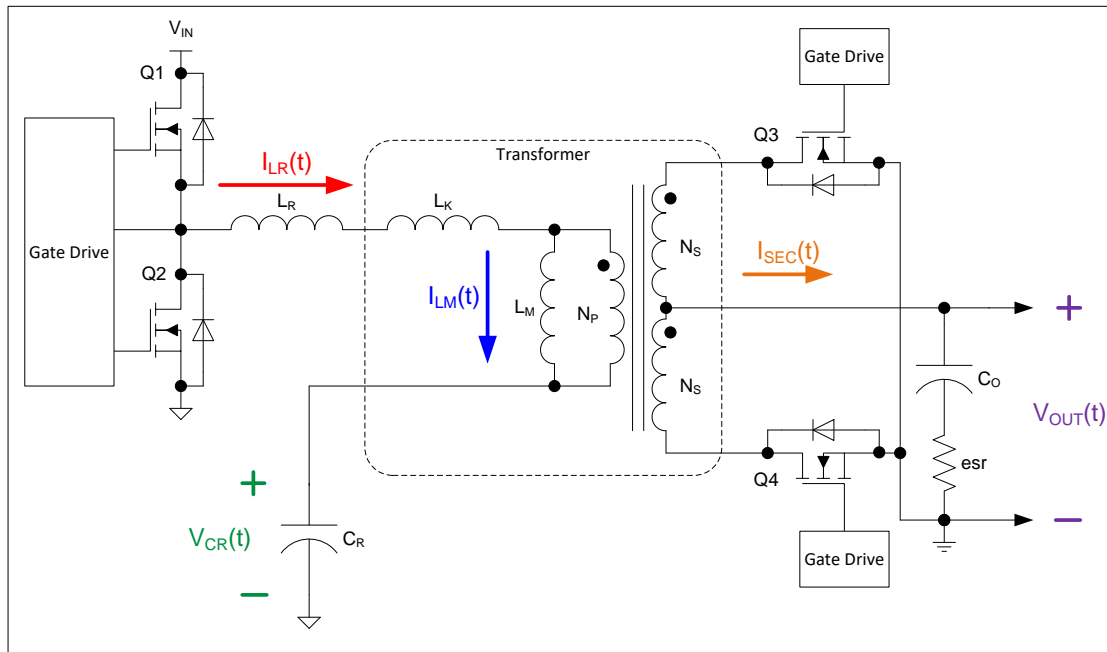
# LED lighting: typical AC/DC LED driver





# LLC converter: overview

- Why LLC?
  - Full zero voltage switching for primary switches (lower switching loss)
  - Zero current switching for secondary switches when at or below resonance
  - Sinusoidal power stage currents (lower DM currents from input)
  - Transformer leakage can be high (lower CM currents)



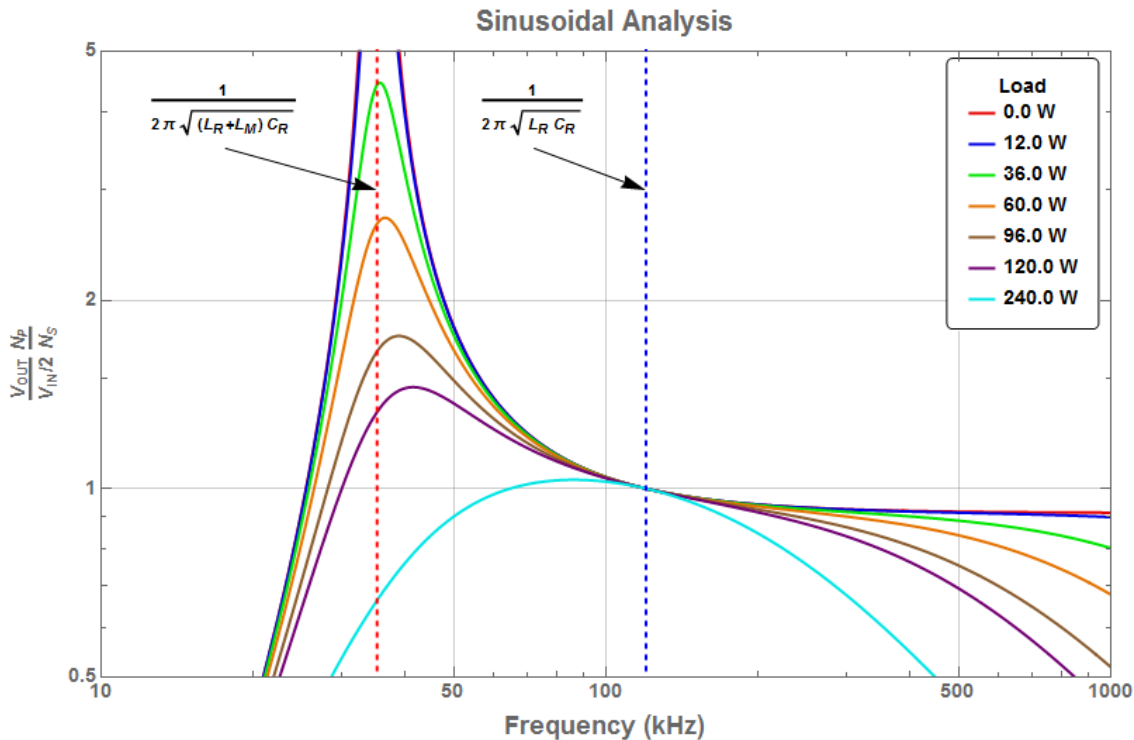
# LLC converter: overview

- Fixed, 50% duty cycle
- Regulation achieved via modulating frequency

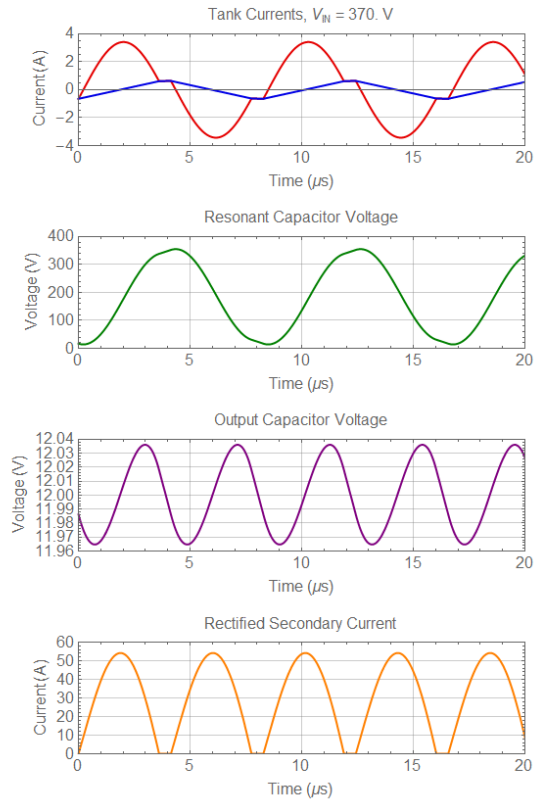
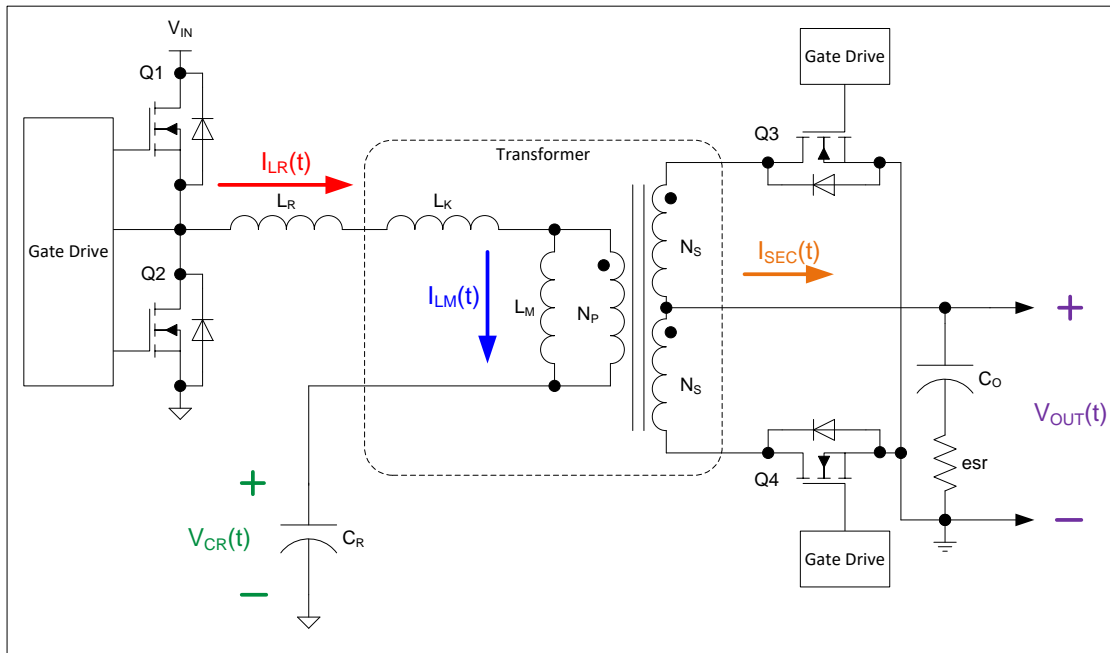
$$V_o = M_g \times \frac{1}{n} \times \frac{V_{in}}{2}$$

$$M_g = \frac{V_{oe}}{V_{ge}} = \left| \frac{jX_{L_m} \parallel R_e}{(jX_{L_m} \parallel R_e) + j(X_{L_r} - X_{C_r})} \right|$$

$$= \left| \frac{(j\omega L_m) \parallel R_e}{(j\omega L_m) \parallel R_e + j\omega L_r + \frac{1}{j\omega C_r}} \right|,$$

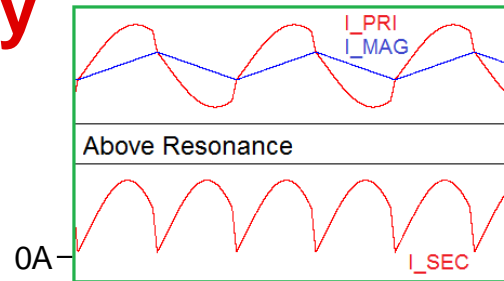


# LLC converter: power stage waveforms

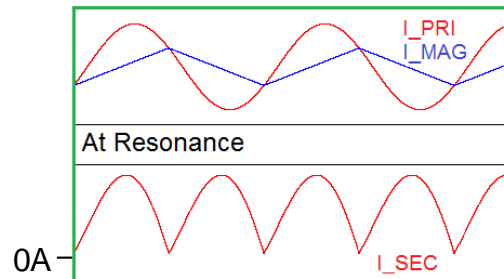


# LLC Converter: Operating Frequency

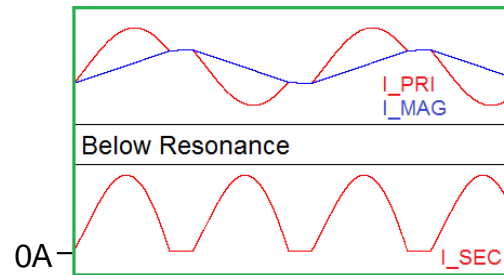
- Above resonance, ZVS achieved, CCM\* on sec, rectifiers not soft switched. Lower RMS currents for given power



- At resonance, ZVS achieved, CCM on sec, rectifiers are soft switched (ZCS), optimum efficiency

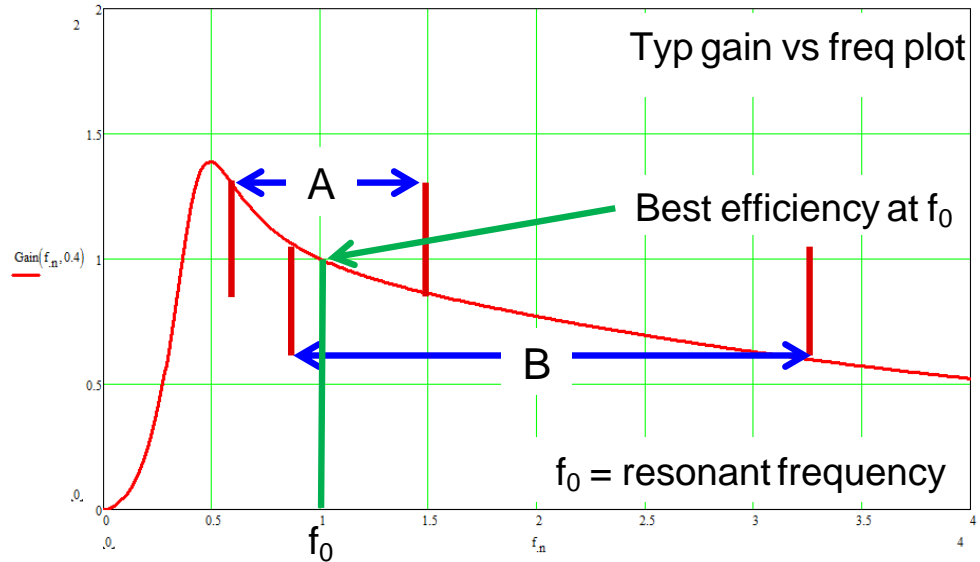


- Below resonance, ZVS achieved, DCM on sec, rectifiers are soft switched (ZCS), RMS currents higher for given power



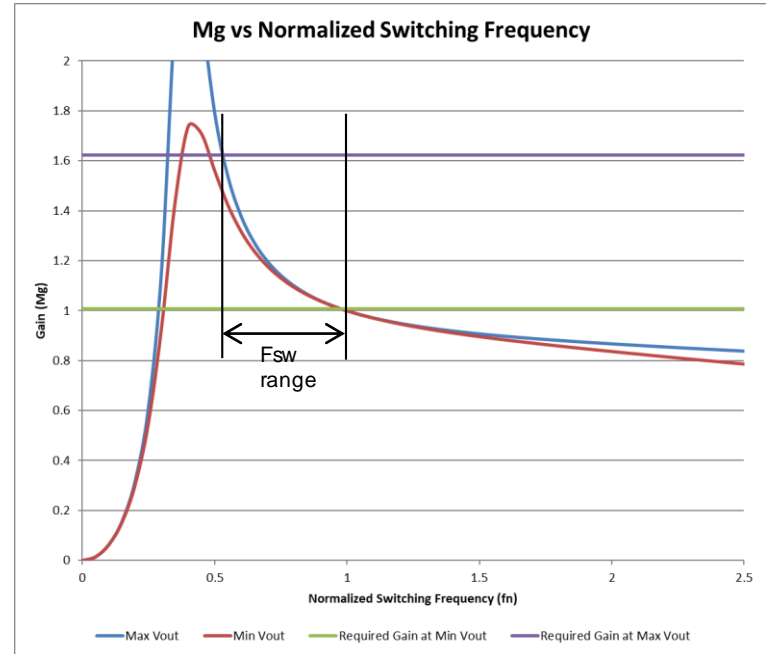
# LLC converter: gain curve considerations

- Both A and B achieve the same gain range (vertical bars). Which is better?
- Noteworthy Characteristics of A
  - Narrow range of frequency operation: easier to optimize core losses
  - Requires smaller  $L_m$ : increased magnetizing currents
- Noteworthy Characteristics of B
  - Best efficiency at lowest frequency: less heat at highest output power
  - Reverse recovery in rectifiers
  - Need to make sure enough magnetizing current to maintain ZVS at highest frequency



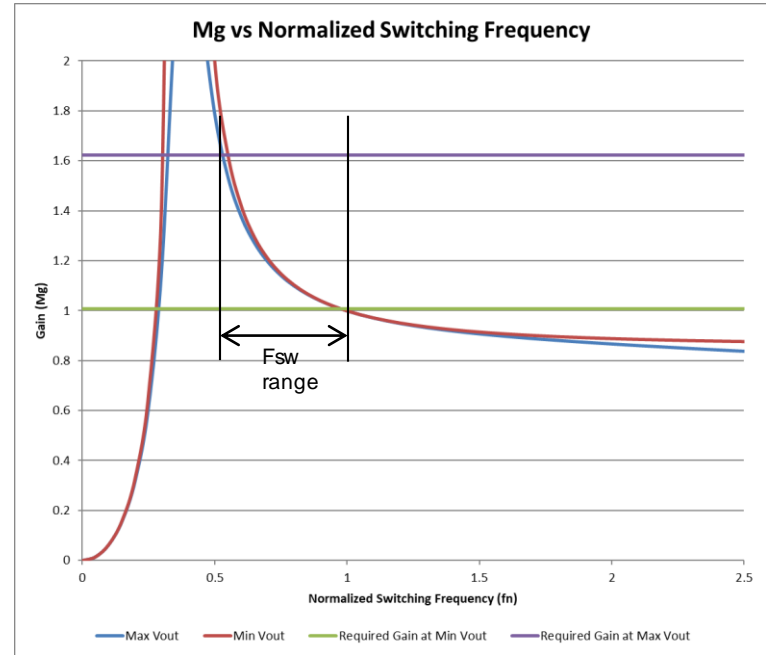
# LLC converter: gain curve considerations

- Shown at right
  - Vout range of 13V to 21V
  - Charging current of 12A
  - Lm: 510uH
  - Lr: 85uH
  - Cr: 30nF
  - Turns ratio of 15:1
- For a battery charger where output current is fixed, Re increases with output voltage
  - $R_e = \frac{8 \times n^2}{\pi^2} \times \frac{V_{out}}{I_{out}}$
  - Re at 21V: 319  $\Omega$
  - Re at 13V: 198  $\Omega$



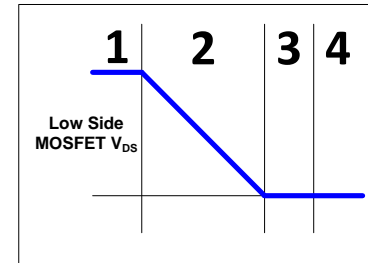
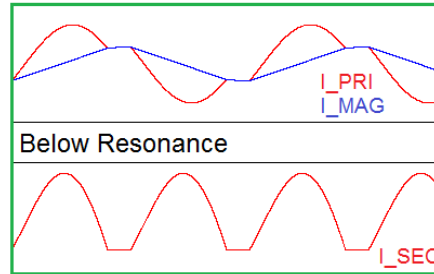
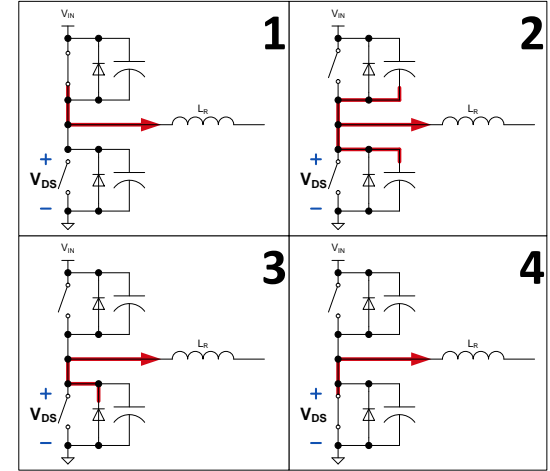
# LLC converter: gain curve considerations

- Shown at right
  - Vout range of 13V to 21V
    - LED string current of 12A at 21V output
    - LED string current of 1A at 13V output
  - Lm: 510uH
  - Lr: 85uH
  - Cr: 30nF
  - Turns ratio of 15:1
- For a LED driver, light load expected at lower output voltage
  - $R_e = \frac{8 \times n^2}{\pi^2} \times \frac{V_{out}}{I_{out}}$
  - Re at 21V: 319  $\Omega$
  - Re at 13V: 2370  $\Omega$



# LLC converter: switching loss and dead time

- $t_{deadtime} = t_{d(off)} + t_{res}$ 
  - $t_{d(off)}$ : delay time from falling edge of gate drive to MOSFET fully off
  - $t_{res}$ : time needed for switch node to charge up to  $V_{in}$  or discharge down to  $gnd$ 
    - $t_{res} = 2 \times C_{oss(tr)} \times \frac{V_{in}}{I_m}$
- Optimal  $t_{deadtime}$  changes with operating frequency
  - Excessive dead time gives longer body diode conduction
  - Insufficient dead time results in loss of ZVS and incurs turn on losses
  - Adaptive dead time convenient for wide  $V_{out}$  applications
- $P_{sw} \approx 0.5 \times I_m \times V_{in} \times t_{d(off)} \times f_{sw}$
- $P_{drive} \approx Q_g \times V_{gate} \times f_{sw}$





# LLC converter: conduction loss

- Conduction loss

- $I_{OE} = \frac{\pi}{2\sqrt{2}} \times \frac{I_{out}}{n}$

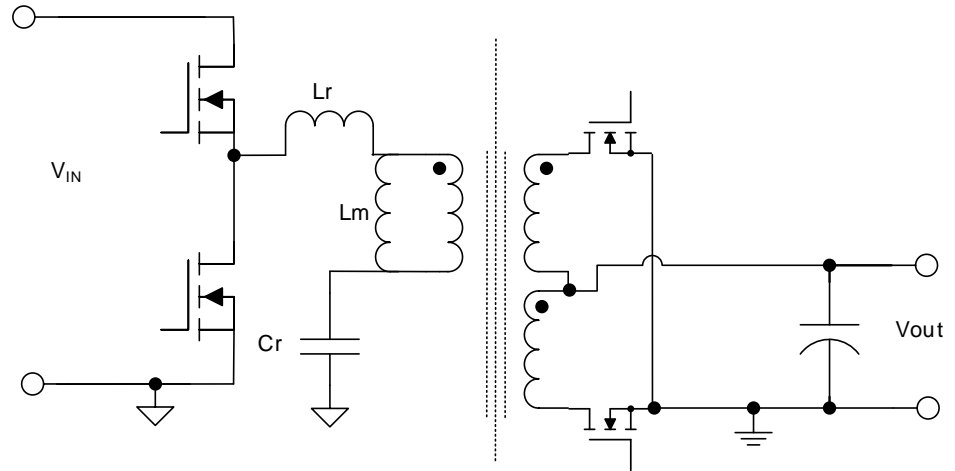
- $I_m = \frac{2\sqrt{2}}{\pi} \times n \times \frac{V_{out}}{2\pi \times f_{sw} \times L_m}$

- $I_r = \sqrt{I_m^2 + I_{OE}^2}$

- $P_{cond} = 0.5 \times I_r^2 \times R_{dson}$

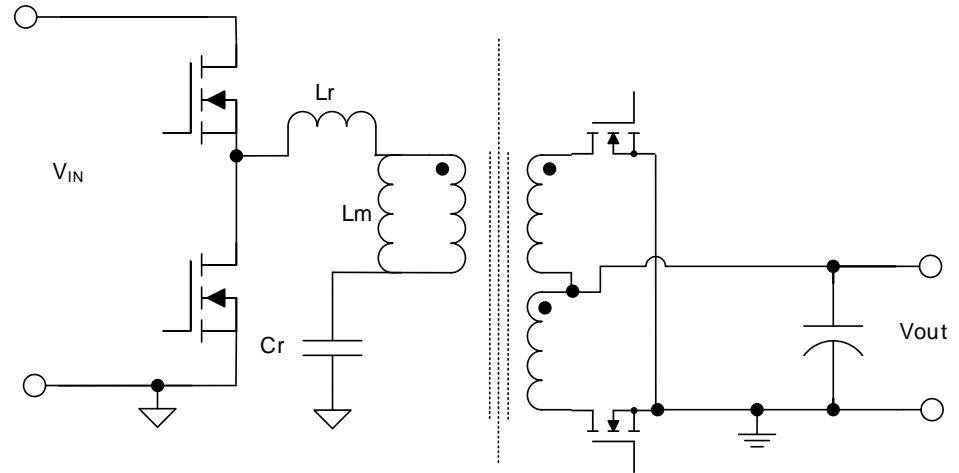
- Total Loss

- $P_{total} = P_{sw} + P_{drive} + P_{cond}$



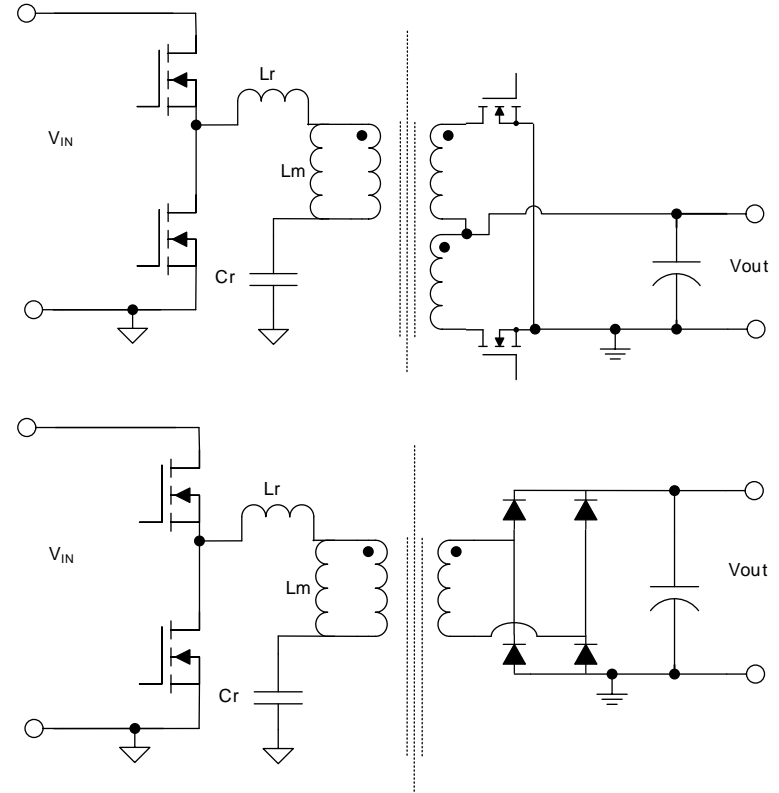
# LLC converter: rectifier losses

- Reverse Recovery Loss (above resonance only)
  - $P_{rr} \approx Q_{rr} \times f_{sw} \times V_{ds}$
- Conduction Loss
  - $I_{OES} = n \times I_{OE}$
  - $P_{cond} \approx I_{OES}^2 \times R_{dson}$
- Switching Loss
  - $P_{sw} = 0.5 \times C_{oss(eq)} \times V_{DS}^2 \times f_{sw}$
- Driver Loss
  - $P_{drive} \approx Q_g \times V_{gate} \times f_{sw}$
- Total loss
  - $P_{total} = P_{rr} + P_{cond} + P_{sw} + P_{drive}$



# LLC converter: center tap or full bridge?

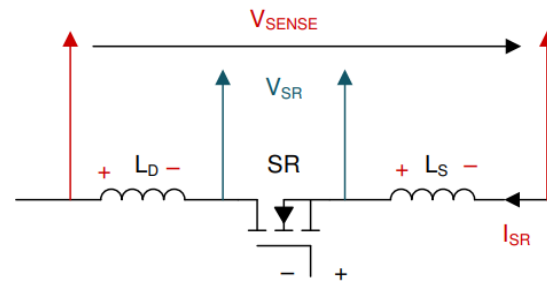
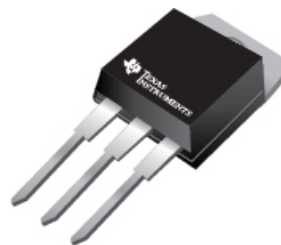
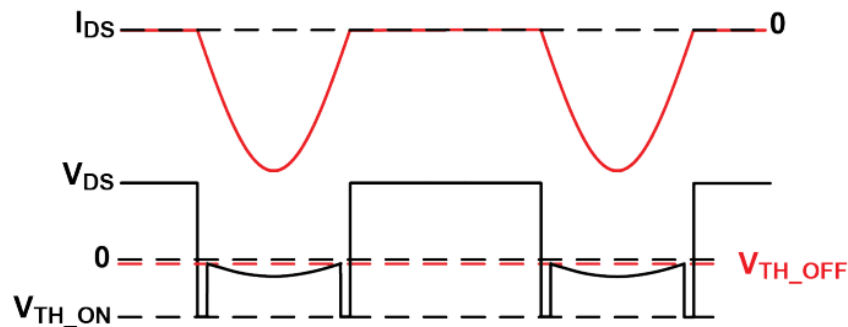
	Center Tap	Full Bridge
Rectifier Reverse Voltage Rating	$>2x V_{out}$	$>V_{out}$
Number of Rectifiers	2	4
Number of Secondary Windings	2 (needs tight matching)	1
Rectifier Conduction Losses		2x compared to center tap
$R_{sec}$ for same winding area	2x compared to full bridge	
$I_{rms}$ per winding	$\sqrt{0.5x}$ compared to full bridge	
Transformer secondary copper loss	2x compared to full bridge	



# Synchronous rectifier considerations

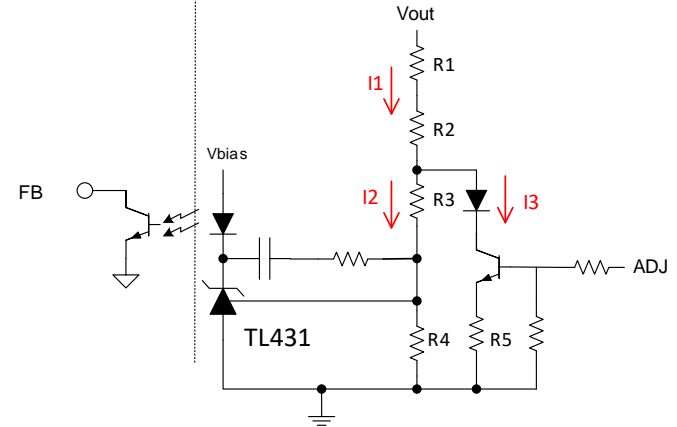
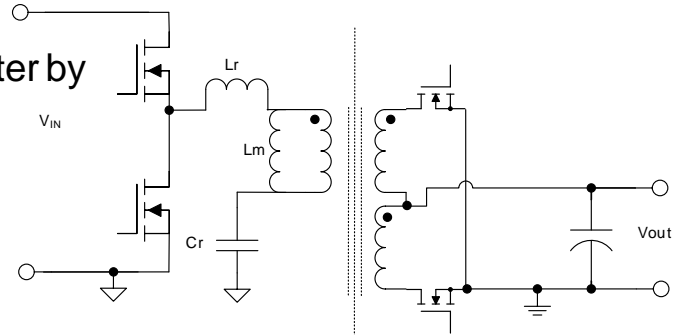
- Majority of analog SR controllers for LLC are based on  $V_{ds}$  sensing scheme
- Smaller  $R_{ds(on)}$  reduces conduction loss when the MOSFET is on but can lead to earlier turn-off and longer body diode conduction time
- Some designs will include circuitry to shut off the SR at no load or use SR controllers that shut down at light load

## SR Voltage and Current



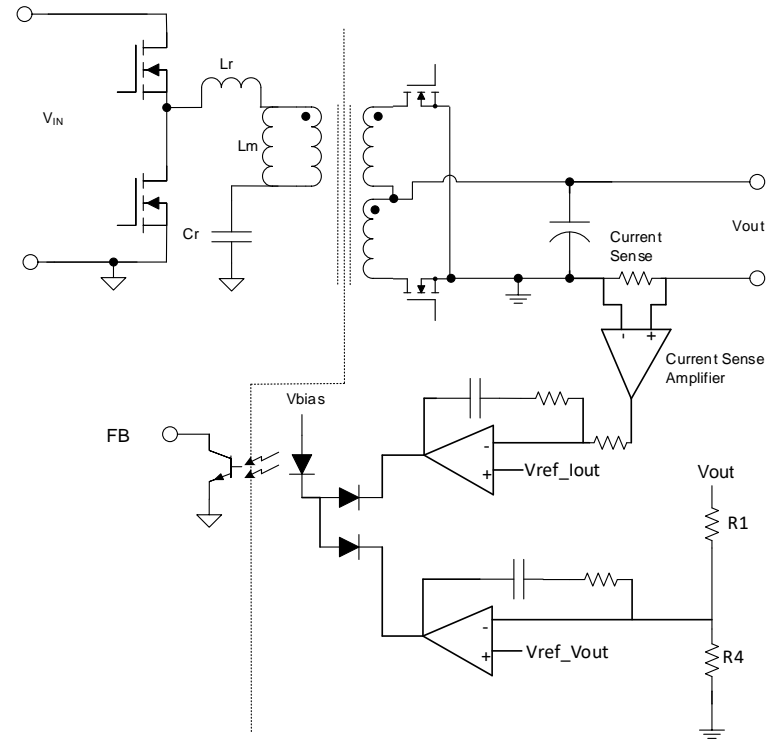
# Practical implementation: CV LED driver

- Motivation: optimize efficiency of downstream converter by adjusting LLC output voltage
- BJT circuit sets current  $I_3$
- $I_1 = I_2 + I_3$
- $$V_{out} = 2.5V \left( \frac{(R1+R2)(R3+R4)}{R3R4} + \frac{R3+R4}{R4} - \frac{R1+R2}{R3} \right) + I_3(R1 + R2)$$
- As ADJ voltage increases,  $V_{out}$  increases



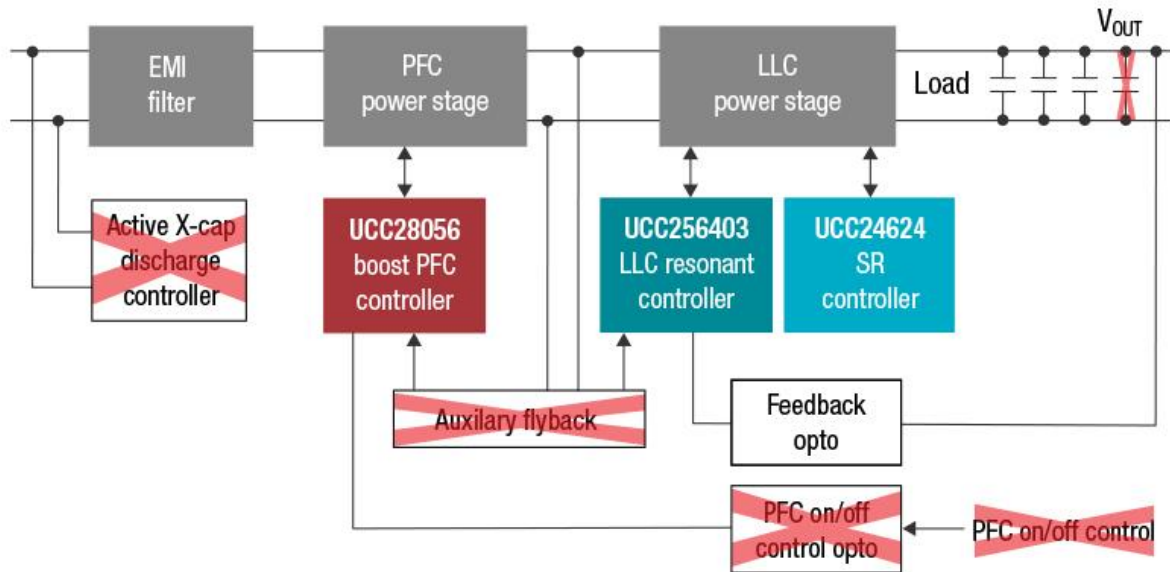
# Practical implementation: CC LED driver & battery charger

- Two control loops
  - One sets output current regulation
  - The other sets output voltage regulation
  - Diode OR'd together to opto-coupler
  - Loop with lowest error “wins” and controls the state of the LLC converter
- References for the error amplifiers can be fixed (i.e. TL103W) or adjustable
  - Analog dimming or trickle charge accomplished by adjusting reference voltage of current control loop



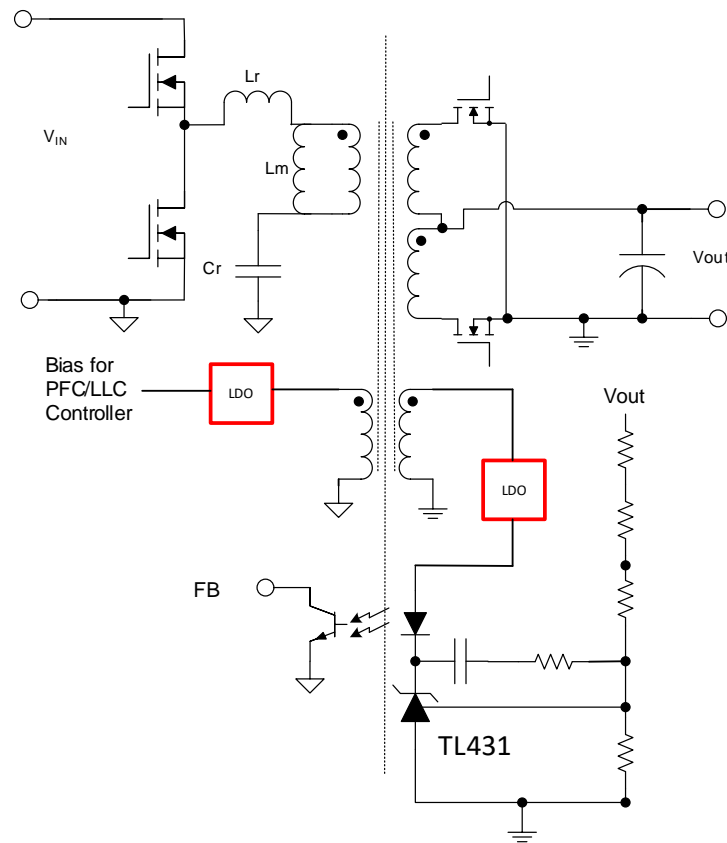
# Practical considerations: AUX or no AUX?

- Traditionally an AUX flyback is used to supply system power, PFC and LLC are shut down at standby to meet no load input power standards
- Newer PFC+LLC+SR controllers contain advanced light load features that can enable removing AUX supply and on/off circuitry while still meeting regulation requirements



# Practical considerations: AUX or no AUX?

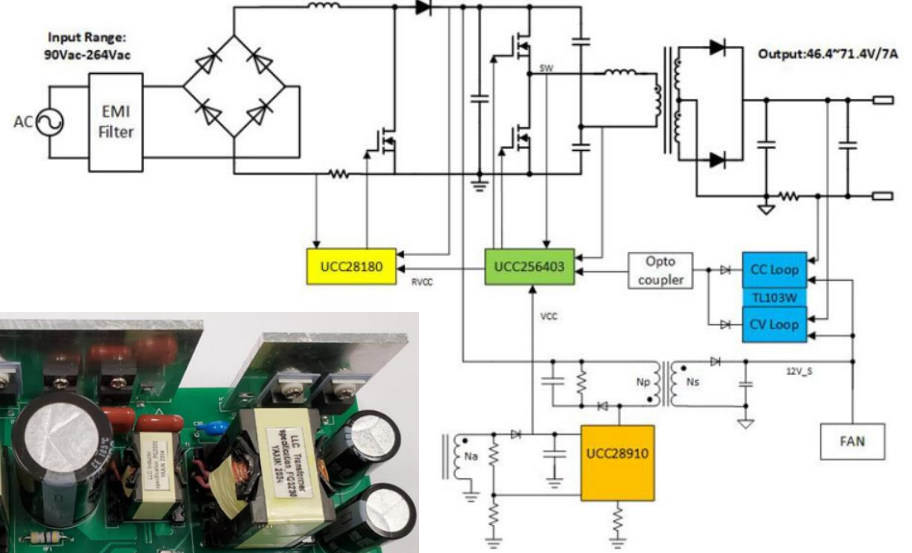
- If No AUX is pursued, bias for the primary/secondary side circuitry is typically done by adding AUX windings onto the LLC transformer
- Bias voltage will vary with the output voltage
  - AUX voltage may require post regulation to maintain safe voltage stresses depending on output voltage range





# Reference design: 500W e-bike charger

- Universal AC input
- 46V to 71V output at 7A charging current
- Precharge mode for <46V output
- 94% peak efficiency
- Status indication and fan control



<https://www.ti.com/tool/PMP40766>

# Additional resources

1. Design and Optimization of a High-Performance LLC Converter; B McDonald, J Freeman: [slup306](#)
2. Designing an LLC Resonant Half-Bridge Power Converter; H. Huang: [slup263](#)
3. LLC Design for UCC29950: J Leisten: (note: despite the title this covers LLC design in general) [slua733](#)
4. A current sharing, paralleled, synchronised HB-LLC, using a C2000 processor: [tiduct9](#)
5. LCC Converter Small Signal Modeling: McDonald.: Texas Instruments Power Supply Design Seminar, SEM2100, 2014. Note\_1
6. Zero Voltage Switching Resonant Power Conversion: Andreycaak.: Unitrode Power Supply Design Seminar 700, 1990.
7. Understanding Noise-Spreading Techniques and their Effects in Switch-Mode Power Applications, Rice et al. [slup269](#)
8. Survey of resonant converter topologies: [slup376](#)
9. Control and design challenges for synchronous rectifiers: [slup378](#)

Note\_1: TI power supply design seminar archive at <http://www.ti.com/ww/en/power-training/login.shtml?DCMP=pwr-psds-archive>

Note\_2: TI reference design library: <https://www.ti.com/reference-designs/index.html>



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