# Industrial Functional Safety for C2000™ Real-Time Microcontrollers



Streamline and speed-up IEC 61508 (SIL) and ISO13849 (PL) certification process with our Functional Safety-Compliant products, documentation, software and support from our knowledgeable experts. Our C2000<sup>™</sup> real-time MCUs are independently assessed and certified by TUV SUD to meet a systematic capability up to SIL 3 and help you create industrial applications requiring functional safety. C2000 real-time MCUs also address **Automotive Functional Safety**.

Highlights of the C2000 functional safety offering are

- Device architecture for functional safety
- Documentation to support to ease customer's safety assessment at system level
- Software library to implement the safety mechanisms

# **C2000 Key Safety Mechanisms**

### Sensing

Redundant peripherals for sensing

ADC to DAC loopback check

Online monitoring of temperature

ADC PPB (Post-Processing Block)

**ADC Result HW comparison** 

Comparator Subsystem with configurable digital filter

#### Communications

200 Mbps Fast Serial Interface (FSI) with built in diagnostics Redundant communications peripherals

Embedded Pattern Generator (EPG) for peripheral self-test

## **Processing**

Dual-Core Lock Step for CPU subsystem

Reciprocal comparison with

Hardware built-in self-test for C28x CPU

Software test of C28x and CLA

Memory built-in self-test

ECC/Parity for all SRAM and Flash

Lock mechanism for critical control registers

Background CRC for CLA-ROM (CLAPROMCRC)

Embedded Real-time
Analysis and Diagnostics (ERAD)

ePIE double SRAM hardware

#### Actuation

ePWM Safe State Assertion Using trip mechanism

Redundant peripheral for control and actuation

Configurable Logic Block (CLB)

## Common Cause and Dependent Failures

Dual oscillators for missing clock detect

Windowed Watchdog (WWD)

Dedicated ERRORSTS pin

**Dual Code Security Module (DCSM)** 

Access protection mechanism for memories

Safety mechanisms play a key role in the overall safety of a system by detecting potentially dangerous failures and consequently helping place the system in a safe state. With over 300 safety mechanisms defined and independently assessed by TUV SUD for its effectiveness, C2000 MCUs provide the required diagnostic coverage to meet a random hardware capability of SIL 2 at a component level. Functional safety manuals provide detailed information on the safety mechanisms, techniques for achieving non-interference between elements and avoiding dependent failures, to aid customers in the development of compliant systems up to SIL 3. The tunable FMEDA provides increased flexibility to customize and calculate HW metrics with features such as package FIT estimation, product function tailoring, safety mechanism tailoring and custom diagnostics allowing customers to tune the FMEDA to their own application specific needs.

Learn More about C2000 real-time MCU Safety Mechanisms

Key safety features		F2838x	F28P65x	F2837x F2807x	F28P55x	F28003x	F28002x	F280015x
	SIL 3 Compliant Development Process	✓	✓	✓	✓	✓	✓	✓
	Random Hardware Capability	SIL 2	SIL 2	SIL 2	SIL 2	SIL 2	QM	SIL 2
	Systematic Capability	SIL 3	SIL 3	SIL 3	SIL 3	SIL 3	SIL 3	SIL 3
	Single Point Fault Coverage of CPU (SPFM)	Reciprocal comparison	Reciprocal comparison (CPU1 + CLA) Lockstep C28x (CPU2)	Reciprocal comparison	Reciprocal comparison	Reciprocal comparison	N/A	Lockstep C28x
	Memory parity	✓	✓	✓	✓	Χ	Х	✓
l e	Memory ECC	<b>√</b>	Flash only	✓	✓	<b>√</b>	✓	✓
] wa	Memory BIST (MPOST)	<b>√</b>	<b>√</b>	Х	✓	<b>√</b>	✓	✓
Hardware	Dual Core Security Module (DCSM) to achieve non-interference between software elements	<b>√</b>	<b>√</b>	√	<b>√</b>	<b>√</b>	√	<b>√</b>
	Windowed watch-dog timer with independent clock	✓	✓	✓	✓	✓	✓	✓
	Hardware CRC acceleration	<b>√</b>	<b>√</b>	<b>√</b>	<	<b>√</b>	<b>√</b>	<b>√</b>
	Hardware BIST (HWBIST): Permanent fault coverage of 90%+ for C28x CPU	<b>√</b>	<b>√</b>	<b>√</b>	Х	<b>√</b>	<b>√</b>	Х
	Redundant and independent ADC / PWM Modules	✓	✓	✓	✓	✓	✓	✓
	Automatic comparison of ADC conversion results in HW	X	✓	X	✓	X	Х	Х
	Redundant Configurable Logic Block (CLB) option	✓	✓	✓	✓	✓	√	N/A
<u>ə</u>	STL (Software Test Library): Permanent fault coverage of 60%+ for C28x CPU	N/A	√	N/A	Coming soon	N/A	N/A	✓
Software	STL (Software Test Library): Permanent fault coverage of 60% for CLA	✓	<b>√</b>	✓	Coming soon	✓	N/A	N/A
Ŏ	Functional Safety Quality (FSQ) Flash APIs	Х	<b>√</b>	X	<b>√</b>	<b>√</b>	N/A	✓
Doc	Safety Manual: detailed product overview, capabilities and constraints, TI development process, safety elements, and safety diagnostics.	SFFS022	<u>SFFS700</u>	SPRUI78	Beta	<u>SFFS277</u>	SPRUIT5	SFFS222
	Device Certification	SSZQQM2	SFFS901	SWAQ009	Coming soon	<u>SFFS610</u>	N/A	<u>SFFS748</u>

Safety collateral					
Development Process Certificate  Hardware   Software	TUV-SUD certificate for QRAS-AP00210. Functional safety development process for IEC 61508-2 and ISO 26262-5 Compliant Components				
C2000 Safety package*	By request and NDA required. Packages include below elements:				
*Not publicly available collateral.  Contact your local TI representative to request.	C2000 Safety Package for Automotive and Industrial MCUs Technical Report on Random HW Capability Technical Report on Systematic Capability FMEDA: A failure mode, effects and diagnostic analysis (FMEDA) is used in the development stage to provide a detailed analysis of different failure modes, the associated effects of failure modes, diagnostics and the impact of any implemented diagnostics/ safety mechanisms in terms of diagnostic coverage. 5-part FMEDA training video series. Device Concept Assessment SAR (Safety Analysis Report): Contains results of safety analysis according to the targeted functional safety standards.				
	Device-specific self-test library package  • C28x_STL (C28x Self-Test Library): Library for software test of C28x CPU  • CLA_STL (CLA Self-Test Library): Library for software test of CLA				
Software diagnostic library	A library of modules and examples demonstrating safety features and mechanisms. CPU, memory, clocks/ watchdogs, HWBIST, etc.				
	F2837x/07x supported through this library. All other F28x series supported by libraries released in C2000Ware.				
Functional safety flash APIs	Library is available in <a href="C2000Ware">C2000Ware</a> . Contact local TI representative for further compliance support package offerings.				
Compiler qualification kit	Compare compiler coverage for customer use cases against coverage of TI compiler release validations				
Safety certified RTOS (SafeRTOS)	Pre-certified safety Real Time Operating System (RTOS)				
MathWorks simulation & code generation	IEC certification kit helps you qualify MathWorks code generation and verification tools to streamline certification of your embedded systems				

Industrial Safety Architectures common in machinery applications typically require a dual channel safety approach (hardware fault tolerance = 1). C2000 devices offer unique capability and scalability to implement two different architectures for SIL-2 (or cat 3 PL d) and SIL-3 (or cat 3 or cat 4 PL e) systems; a C2000 MCU for each of two safety channels (Figure 1) or a C2000 MCU for one safety channel and a C2000 MCU for the second safety channel and the controller combined in single device (Figure 2).

However, for several industrial applications such as mobile robots, **single** channel architectures can be used to fulfill the safety requirements (hardware fault tolerance = 0). A C2000 device together with external test equipment result in an optimal architecture to achieve the required SIL-2 (or cat 2 PL d); a C2000 MCU can be used as the motor controller as well as for diagnostics and as test equipment an external power supply with diagnostics is used to diagnose and ensure the proper functionality of the C2000 MCU (Figure 3). Read more about <u>simplifying robotics motor drive safety assessments.</u>

Further, compared to general purpose MCUs being used for safety functions C2000 devices offer superior compute performance and device features for implementing complex safe motion functions beyond just Safe Torque Off (STO) that requires real-time monitoring of parameters such as SLS (Safe Limiting Speed), Safe Brake Control (SBC), Safe Direction (SDI), Safe Speed Monitor (SSM) and fast actuation of the safe state.

Further details – including a TUV report on these concepts and architectures - are available under NDA in the C2000 Safety package.

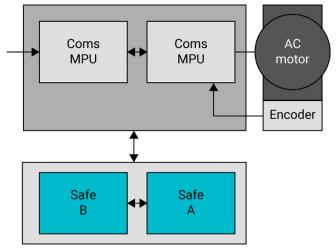


Figure 1. Architecture 1 with dual safety MCUs (HFT=1, SIL 2 or SIL 3).

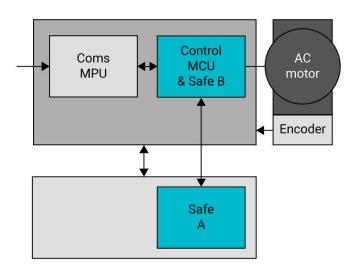


Figure 2. Architecture 2 with single safety MCU and safety integrated functions into the Drive MCU (HFT=1, SIL 2 or SIL 3).

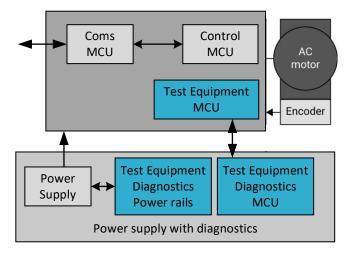


Figure 3. Architecture 3 with single safety MCU and PMIC (HFT=0, SIL 2)



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