

TMS470R1x System Module Reference Guide

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System Module

The system module provides an interface from the ARM CPU to the Texas Instruments (TI) TMS470R1x family of devices. The module defines the CPU bus and the expansion bus. The system module is responsible for memory interface and protection, interrupt prioritization, reset generation, and clock synthesis.

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1 System Module Overview

This section provides an overview of the system module. Table 1 contains a brief description of the system module and lists its significant pins.

Table 1. System Module Overview

Description	The system module sets the protocol for bus accesses, decodes addresses, provides memory protection, manages interrupt requests, handles exceptions, and controls the clock distribution. A real-time interrupt is also located within the system module.	
Pins	$\overline{\text{RST}}$	Bidirectional reset. The internal circuitry can assert a reset and an external system reset can assert a device reset.
	AWD	Analog watchdog reset. AWD provides a system reset if the WD KEY is not written in time by the system.
	$\overline{\text{PORRST}}$	Input master chip power-up reset. External V_{CC} monitor circuitry must assert a power-on reset.
	CLKOUT	Clock out bidirectional pin. CLKOUT can be programmed as a GIO pin or the output of SYSCLK, ICLK, or MCLK.

Table 2 lists the system registers in the order they are discussed in this chapter and provides an overview of their functionality.

Table 2. System Module Internal Registers

Address	Mnemonic	Register Name	Register Description	Page
Bus Structure Registers				
0xFFFF_FD00	SMCR0	Static Memory Control Register 0	Controls the wait states, memory width, and endianism for accesses to given expansion memory. Configurable on a memory by memory basis	72
0xFFFF_FD04	SMCR1	Static Memory Control Register 1		74
0xFFFF_FD08	SMCR2	Static Memory Control Register 2		74
0xFFFF_FD0C	SMCR3	Static Memory Control Register 3		74
0xFFFF_FD10	SMCR4	Static Memory Control Register 4		74
0xFFFF_FD14	SMCR5	Static Memory Control Register 5		74
0xFFFF_FD18	SMCR6	Static Memory Control Register 6		74
0xFFFF_FD1C	SMCR7	Static Memory Control Register 7		74
0xFFFF_FD20	SMCR8	Static Memory Control Register 8		74
0xFFFF_FD24	SMCR9	Static Memory Control Register 9		74
0xFFFF_FD2C	WCR0	Write Control Register	Controls global attributes of expansion memory accesses	75

Table 2. System Module Internal Registers (Continued)

Address	Mnemonic	Register Name	Register Description	Page
Bus Structure Registers (Continued)				
0xFFFF_FD34	PLR	Peripheral Location Register	Configures the peripheral as internal/external	78
0xFFFF_FD38	PPROT	Peripheral Protection Register	Controls whether peripherals may be addressed in privilege mode only or in user and privilege mode	79
Memory Registers				
0xFFFF_FE00	MFBAHR0	Memory Fine Base Address High Register 0	Memory Fine Base Address High and Memory Fine Base Address Low registers configure the memory-select signals. The base address, block size, and protection for the associated memory are set in these registers.	81
0xFFFF_FE04	MFBALR0	Memory Fine Base Address Low Register 0		81
0xFFFF_FE08	MFBAHR1	Memory Fine Base Address High Register 1	Memory Fine Base Address Low Register 0 contains the memory-select bit that enables the memory maps as configured through the memory fine base address and memory coarse base address registers.	84
0xFFFF_FE0C	MFBALR1	Memory Fine Base Address Low Register 1		84
0xFFFF_FE10	MFBAHR2	Memory Fine Base Address High Register 2		84
0xFFFF_FE14	MFBALR2	Memory Fine Base Address Low Register 2		84
0xFFFF_FE18	MFBAHR3	Memory Fine Base Address High Register 3		84
0xFFFF_FE1C	MFBALR3	Memory Fine Base Address Low Register 3		84
0xFFFF_FE20	MFBAHR4	Memory Fine Base Address High Register 4		84
0xFFFF_FE24	MFBALR4	Memory Fine Base Address Low Register 4		84
0xFFFF_FE28	MFBAHR5	Memory Fine Base Address High Register 5		84
0xFFFF_FE2C	MFBALR5	Memory Fine Base Address Low Register 5		84
0xFFFF_FE30	MCBAHR0	Memory Coarse Base Address High Register 0		86
0xFFFF_FE34	MCBALR0	Memory Coarse Base Address Low Register 0		86

Table 2. System Module Internal Registers (Continued)

Address	Mnemonic	Register Name	Register Description	Page
Memory Registers (Continued)				
0xFFFF_F38	MCBAHR1	Memory Coarse Base Address High Register 1	Memory Fine Base Address High and Memory Fine Base Address Low registers configure the memory-select signals. The base address, block size, and protection for the associated memory are set in these registers.	86
0xFFFF_FE3C	MCBALR1	Memory Coarse Base Address Low Register 1		86
0xFFFF_FE40	MCBAHR2	Memory Coarse Base Address High Register 2	Memory Fine Base Address Low Register 0 contains the memory-select bit that enables the memory maps as configured through the memory fine base address and memory coarse base address registers.	86
0xFFFF_FE44	MCBALR2	Memory Coarse Base Address Low Register 2		86
0xFFFF_FE48	MCBAHR3	Memory Coarse Base Address High Register 3		86
0xFFFF_FE4C	MCBALR3	Memory Coarse Base Address Low Register 3		86
0xFFFF_FE50	MCBAHR4	Memory Coarse Base Address High Register 4		86
0xFFFF_FE54	MCBALR4	Memory Coarse Base Address Low Register 4		86
0xFFFF_FE58	MCBAHR5	Memory Coarse Base Address High Register 5		86
0xFFFF_FE5C	MCBALR5	Memory Coarse Base Address Low Register 5		86
Memory Protection Unit (MPU) Address Registers (Offset Address)				
0x00	MPUAHR0	MPU Address High Register 0		66
0x04	MPUALR0	MPU Address Low Register 0		66
0x08	MPUAHR1	MPU Address High Register 1	MPU Address High and MPU Address Low Registers configure the address range to be protected by the MPU. The MPU channel is enabled (and the channel's protection set) within the MPU control register	66
0x0C	MPUALR1	MPU Address Low Register 1		66
0x10	MPUAHR2	MPU Address High Register 2		66
0x14	MPUALR2	MPU Address Low Register 2		66
0x18	MPUAHR3	MPU Address High Register 3		66
0x1C	MPUALR3	MPU Address Low Register 3		66
0x20	MPUCTRL	MPU Control Register	Controls the channel's protection and enable	67

Table 2. System Module Internal Registers (Continued)

Address	Mnemonic	Register Name	Register Description	Page
Interrupts				
0xFFFF_FF20	IRQIVEC	IRQ Index Offset Vector Register	Provides a numerical offset to the highest priority pending interrupt request (IRQ) interrupt	98
0xFFFF_FF24	FIQIVEC	FIQ Index Offset Vector Register	Provides a numerical offset to the highest priority pending fast interrupt request (FIQ) interrupt	99
0xFFFF_FF28	CIMIVEC	CIM Index Offset Vector Register	Provides a numerical offset to the highest priority pending interrupt	100
0xFFFF_FF2C	FIRQPR	FIQ/IRQ Program Control Register	Controls whether the request channel generates an IRQ or an FIQ request to the CPU	101
0xFFFF_FF30	INTREQ	Pending Interrupt Read Location Register	Shows the pending interrupts	101
0xFFFF_FF34	REQMASK	Interrupt Mask Register	Enables interrupt request channels	102
0xFFFF_FFF8	SSIF	System Software Interrupt Flag Register	Flag for software interrupt	120
0xFFFF_FFFC	SSIR	System Software Interrupt Request Register	Generates software interrupt	121
Real-Time Interrupt (RTI) Registers				
0xFFFF_FF00	RTICNTR	RTI Counter	Contains MOD and CNTR counters for the RTI	89
0xFFFF_FF04	RTI PCTL	RTI Preload Control Register	Controls the MOD preload value and tap interrupt selection	90
0xFFFF_FF08	RTI CNTL	RTI Control Register	Contains tap interrupt flag and enable	92
0xFFFF_FF0C	WKEY	Watchdog Key Register	Correct sequence written to this register discharges the watchdog capacitor.	93
0xFFFF_FF10	RTI CMP1	RTI Compare Register 1	Contains value to compare to CNTR.	94
0xFFFF_FF14	RTI CMP2	RTI Compare Register 2	Contains value to compare to CNTR.	94
0xFFFF_FF18	RTI CINT	RTI Compare Interrupt Control Register	Contains enables and flags for compare 1 and compare 2 interrupts	95
0xFFFF_FF1C	RTI CNTEN	RTI Counter Enable Register	Enables the RTI counter based upon the CPU operating mode	97

Table 2. System Module Internal Registers (Continued)

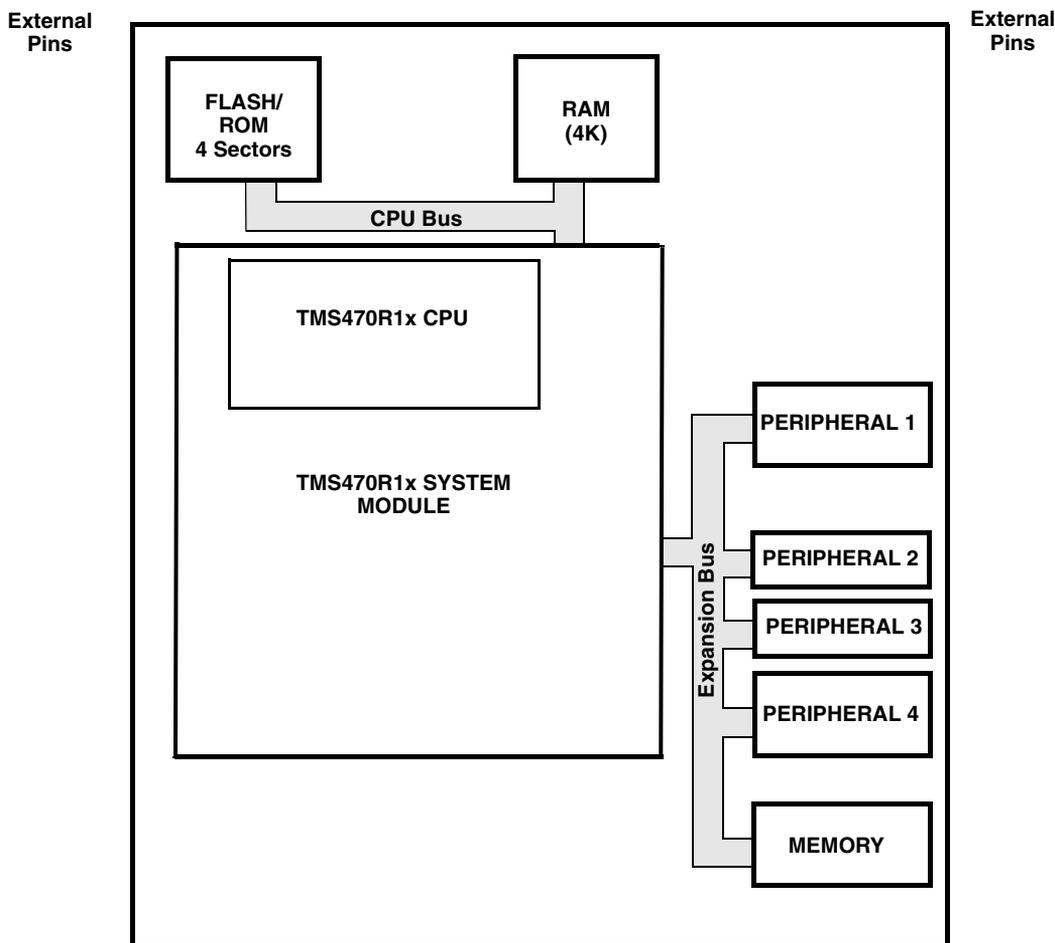
Address	Mnemonic	Register Name	Register Description	Page
Clock Registers				
0xFFFF_FD30	PCR	Peripheral Clock Register	Contains the ICLK divider and peripheral enable	76
0xFFFF_FF00	CLKCNTL	Clock Control Register	Controls CLKOUT pin, peripheral power down, and device low power modes	105
0xFFFF_FFDC	GLBCTRL	Global Control Register	Contains PLL-specific bits as well as the flash memory configuration bit	108
Reset Registers				
0xFFFF_FFE0	SYSECR	System Exception Control Register	Contains software reset	110
0xFFFF_FFE4	SYSESR	System Reset Exception Status Register	Contains reset flags	112
0xFFFF_FFE8	ABRTESR	Abort Exception Status Register	Contains abort flags	115
0xFFFF_FFEC	GLBSTAT	Global Status Register	Contains bits that determine the source of illegal address, illegal access and clock reset exceptions	116
Parallel Signature Analysis (PSA) Registers				
0xFFFF_FF40	CPU PSA	CPU Data Bus PSA Registers	Contains the signature value for the PSA	103
0xFFFF_FF50	PSA DISABLE	PSA Enable	Contains PSA enable bit	103
Miscellaneous Registers				
0xFFFF_FF00	DEV	Device Identification Register	Contains device-specific information hard-coded during device manufacture	119

2 Bus Structure

The system module defines two independent buses: a CPU bus and an expansion bus. The memory arrays (flash, ROM and RAM), CPU, DMA, and system module connect to the CPU bus. The system module, DMA, expansion peripherals, and expansion memories (for example, HET RAM) connect to the expansion bus. These buses are illustrated in Figure 1. This section (bus structure) discusses the protocol on the separate buses.

- CPU bus protocol
- Expansion bus protocol
 - Protocol for memory accesses on expansion bus
 - Protocol for peripheral accesses on expansion bus

Figure 1. System Block Diagram



2.1 CPU Bus

The CPU bus connects the central processor to its tightly coupled memories (that is, ROM, RAM, flash). In general, the CPU bus is a high-speed, internal bus. The system module acts as a bridge between the CPU and the expansion buses.

2.2 Expansion Bus

While the CPU bus protocol is fixed, the expansion bus protocol is configurable. The expansion bus supports protocol for interfacing to:

- Memory
- Peripherals

2.2.1 Protocol for Memory Accesses on the Expansion Bus

Memory Select:

Memory selects allow the user to place physical memory within the address space at user-defined addresses. The memory selects are configured by the MFBADDRx, MFBALRx, MCBADDRx, and MCBALRx registers (see section 9.8).

Memory accesses on the expansion bus are carried out at the SYSCLK frequency. The WCR0 register contains bits that control the global properties of the expansion bus protocol for memory; you can enable a write buffer that allows the CPU to write to the expansion bus and the CPU can perform other actions (not on the expansion bus) while the wait state is ongoing. You must configure the WCR0 register so that the expansion bus protocol is appropriate for the accessed memory.

Additionally, each memory select may be configured uniquely for the memory accessed through the expansion bus. Each SMCRx register configures the expansion bus separately for specific data widths and wait states. The mapping of SMCRx registers to different memory selects is device specific. (See the device-specific data sheet for additional details.)

Data Width

The expansion bus supports 8-bit, 16-bit, and 32-bit read/write operations to all memory modules. You configure the data width of the memory region with the DW bit field (SMCRx.1:0) as shown in Table 3. (The system module automatically configures the DW bit field for SMCR0 during reset.) No unaligned memory accesses are permitted.

Table 3. Aligned Address Boundary by Access Type

Read/Write Access	Aligned Address Boundary
8-bit	Any boundary (0x00, 0x01, 0x02, 0x03,...)
16-bit	Any even boundary (0x00, 0x02, 0x04, 0x06,...)
32-bit	Any multiple of 4 (0x00, 0x04, 0x08, 0x0C)

Memory Wait States

The expansion bus can support zero wait states, but it also supports wait states on the address setup, during the memory access, and on the trailing edge in order to meet the memory requirements of the expansion bus memory. These wait states are summed together. The memory access timing can be customized on a memory select by programming the ASC, WS, and TWS bits of the appropriate SMCRx register. Figure 2 and Figure 3 illustrate the timing of the zero wait state memory read and write transaction, respectively.

Note: The timings in Figure 2 through Figure 8 are presented for reference. The signal behavior should be verified in the device data sheet.

Figure 2. Zero Wait-State Memory Read Transaction

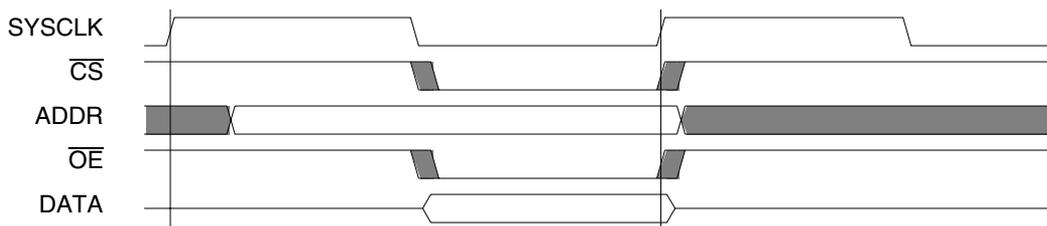
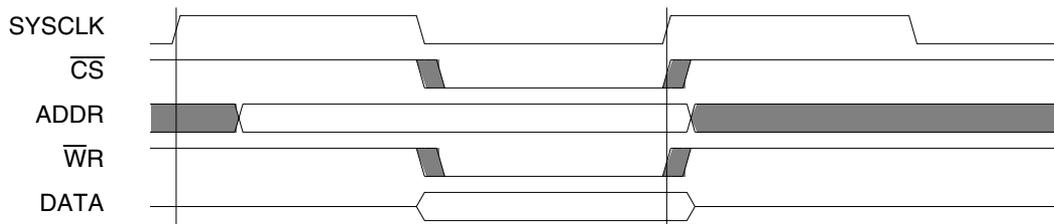
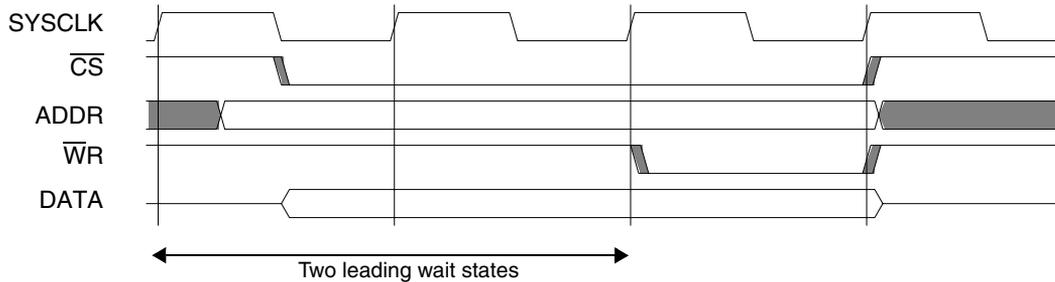


Figure 3. Zero Wait-State Memory Write Transaction



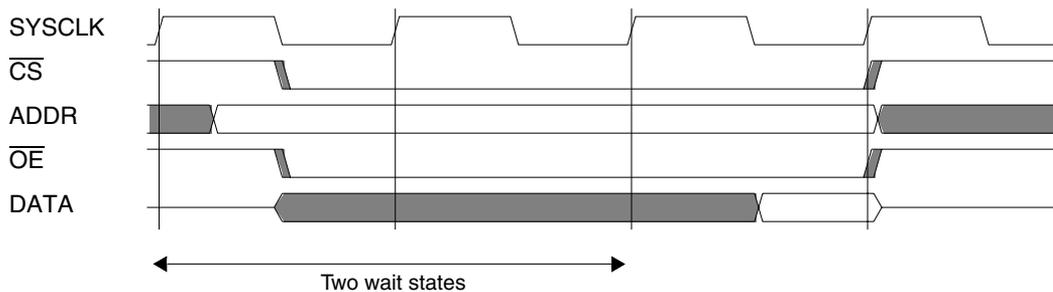
- Address setup wait states are programmed into the ASC bit field (SMCRx.13:12).
 - Read:
 - The ASC wait states do not affect read accesses.
 - Figure 4 illustrates the leading wait-state memory write transaction.

Figure 4. Leading Wait-State Memory Write Transaction



- The memory select (\overline{CS}) is active and the data is valid ASC SYSCLK cycles before the write strobe (\overline{WR}) is asserted.
 - The address setup wait states support flexible \overline{WR} setup time requirements for write operations.
- Wait states during the memory access are programmed into the WS.3:0 bit field (SMCRx.7:4). For devices with 470+ architecture, there is a minimum of one wait state.
 - Figure 5 illustrates the wait-state memory read transaction.

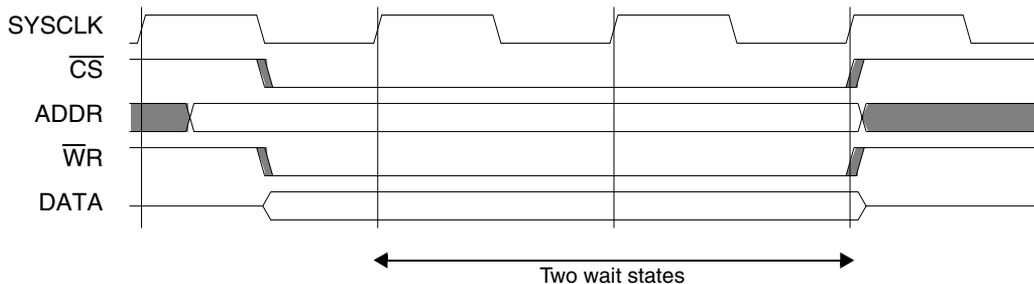
Figure 5. Wait-State Memory Read Transaction



- The memory select (\overline{CS}), output enable (\overline{OE}), and data are valid at the same time. These signals are stretched for WS SYSCLK cycles.

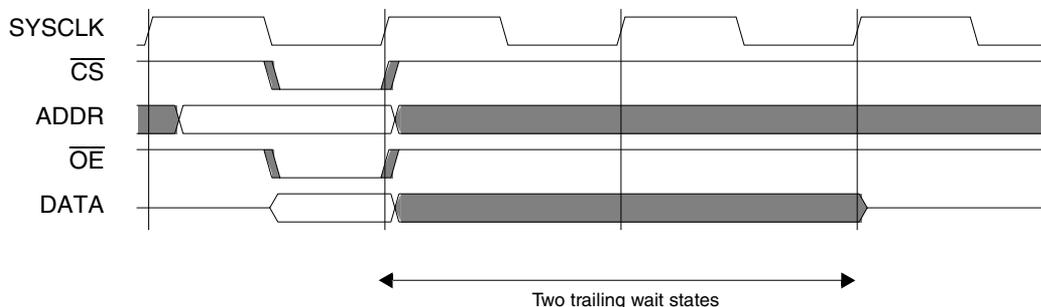
- The wait states support slow read/write accesses.
- Figure 6 illustrates the wait-state memory write transaction.

Figure 6. Wait-State Memory Write Transaction



- The memory select (\overline{CS}), write strobe (\overline{WR}), and data are valid at the same time. These signals are stretched for WS SYSCLK cycles.
- The wait states support slow read/write accesses.
- Trailing edge wait states are programmed into the TWS bit field (SMCRx.11:9). Write accesses on the expansion bus have at least one trailing wait state unless TWS is cleared to 0x00 and the WTWSOVR bit field (WCR0.1) is set to 1.
- Figure 7 illustrates the trailing wait-state memory read transaction.

Figure 7. Trailing Wait-State Memory Read Transaction

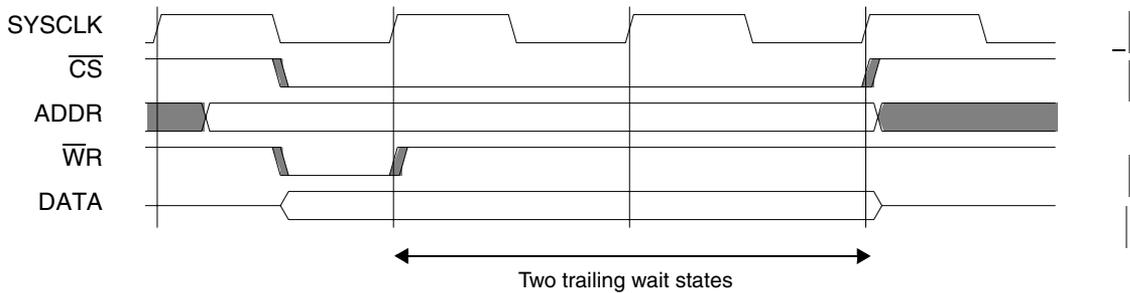


- The memory select (\overline{CS}), output enable (\overline{OE}), and data are valid at the same time. The expansion bus is held for TWS SYSCLK cycles, but there are no wait states at the CPU unless another expansion bus access is required prior to the completion of the trailing wait states.

- The trailing wait states prevent bus drive conflicts from memories with slow output disables. A slow output disable is not a concern for byte reads to the same memory. Byte reads do not have trailing wait states between the byte reads because the same memory does not require the output disable.

■ Figure 8 illustrates the trailing wait-state memory write transaction.

Figure 8. *Trailing Wait-State Memory Write Transaction*



- The memory select (\overline{CS}), write strobe (\overline{WR}), and data are valid at the same time. The memory select and data are stretched by TWS SYSCLK cycles. The write strobe goes inactive TWS SYSCLK cycles before the memory select and the data.
- The trailing wait state supports flexible hold times for write operations.

- The expansion bus can be used for off-chip memory accesses (if the bus is brought external). The location of the memory (on chip or external) is configured in the MLOC bit field (SMCRx.2 [in this case x cannot be 0].)
- The system allows for interfacing to different endian memories. The endianism of the expansion memory is programmed into the END bit field (SMCRx.3 [in this case x cannot be 0].)
- Expansion bus frequency is SYSCLK frequency for memory accesses.

2.2.2 Protocol for Peripheral Accesses on the Expansion Bus

Peripheral accesses on the expansion bus are carried out at the ICLK frequency (see Section 7, *Clocks*, on page 43). The expansion bus protocol for peripheral access is handled by the system module.

- The expansion bus supports 8-bit, 16-bit, and 32-bit read/write operations to all peripheral modules. (However, the peripheral itself may not support 8-bit, 16-bit, and 32-bit read/write operations.)

- ❑ The expansion bus can be used for off-chip peripheral accesses (if the bus is brought external). The location of the peripheral (on chip or external) is configured in the PLR register.
- ❑ The peripheral control registers may be protected on a peripheral-by-peripheral basis through the peripheral protection register, PPROT. The peripheral protection register allows the user to restrict access to the peripherals based upon whether the ARM CPU is in user mode.
- ❑ The peripheral modules (including HET) are held in reset until the PENABLE bit (PCR.0) is set.

ICLK is generated from SYSCLK. The ICLK frequency is determined by the CLKDIV bit field (PCR.4:1); the system divides the SYSCLK frequency to generate ICLK for reduced power.

- ❑ ICLK is not guaranteed to be a 50% duty cycle.
- ❑ Peripheral accesses are measured in terms of ICLK.
 - Peripheral reads take a minimum of 2 ICLK cycles.
 - Peripheral writes take a minimum of 2 ICLK + 1 SYSCLK cycles.
 - If ICLK is divided down from SYSCLK (that is, CLKDIV \neq 0x00), the system asserts wait states at the beginning of the peripheral access, if required, so that the access begins on an ICLK boundary.

3 Memory

Memory Map:

The memory map shows where the memory is located within the address space.

The memory arrays have a user-defined address. The memory section discusses:

- How the memory arrays are addressed within the overall memory map of the device
- Protection for these memory arrays

3.1 Memory Map

Address Space:

The address space is the set of all possible unique addresses. For the 470R1x family of devices, the memory map is 4G bytes because of the 32-bit architecture.

A generic device memory map is shown in Figure 9. The physical memory of the device (control registers, flash memory, ROM, and RAM) must be addressed within this memory map. The control registers are located at fixed addresses that are device specific. (See the device-specific data sheet for the mapping of peripherals to the peripheral selects.) 1K-byte sections of the memory map are reserved for each peripheral's control registers, and these 1-Kbyte sections of memory are accessed through a peripheral select.

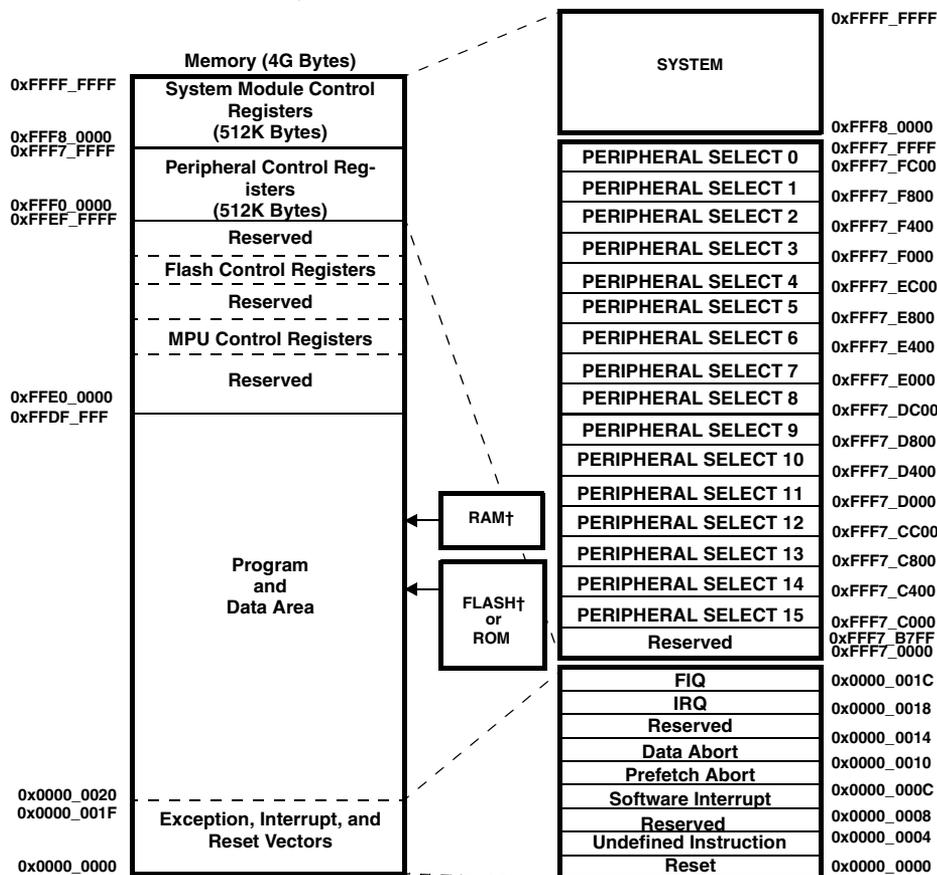
Peripheral Select:

The system module decodes the top 22 bits of the address bus. If the address lies between addresses 0xFFFF7_FFFF and 0xFFFF7_C000, then the system sends a peripheral-select signal plus the bottom 10 bits of the address bus to the selected peripheral.

The system control registers and flash control registers are located in the upper 2M bytes of the memory map. System control registers (except for the MPU) are located from 0xFFFF_FFFF to 0xFFFF_FD00. In addition to the control registers, the exception vectors have a fixed map from 0x1F to 0x00. These vectors are shown in Figure 9. These control registers and vector addresses are always valid. To access the peripheral control registers, the peripheral must be released from reset by setting PENABLE to 1 (PCR.0 = 1).

There are exceptions that consist of reset, undefined instruction, software interrupt, prefetch, abort, data abort, IRQ, and FIQ. Each of these exceptions has its own vector.

Figure 9. Generic Device Memory Map

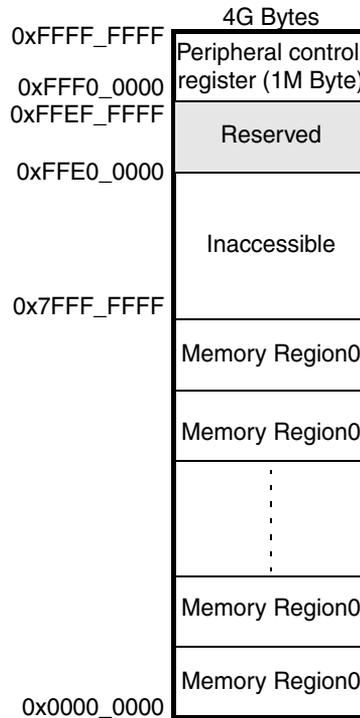


† The base address for the flash and RAM is programmable.

3.2 Memory Selects

After reset, the memory map control registers for flash, system, and peripherals are all valid. Valid too are the exception vectors located from 0x1F to 0x00. Additionally, the entire flash or ROM is available. This flash or ROM is mirrored throughout the bottom 2G bytes of the memory map. (See Figure 10.)

Figure 10. Memory Map After Reset



3.2.1 Configuring Memory Selects

The available memory arrays are configured within the memory map (the arrays should not be addressed within the top 2M bytes) through definition of memory selects. The memory selects are configured in the MFBAHRx, MFBALRx, MCBAHRx, and MCBALRx registers by defining:

- ❑ The first 22 bits (maximum) of the starting address (origin) of the array area
- ❑ The block size (length) of the array

The block size determines how many address bits must be used to address the memory array; these n bits are masked from the address bus for memory selection generation. When the remaining (top) bits on the address bus match the base address for a memory array, the associated memory select is activated. The memory array then receives the memory select plus the n remaining bits of the address.

Note: Base Address Must be a Multiple of the Block Size

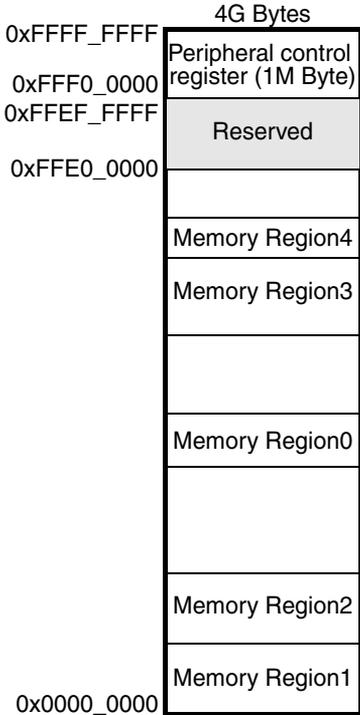
The details concerning how the system generates memory selects can be summarized with the rule that the base address must be a multiple of the block size.

3.2.2 Enabling the Memory Map

All memory selects except memory select 0 (attached to boot) are disabled at reset. The boot program should set up the memory base address control registers (configure all memory selects) and then set the memory map select bit in the memory base address register 0 (MFBALR0.8). Once the memory map select bit is set, the memory selects are generated based on the content of the memory base address registers.

The memory map is activated when the memory map select bit (MFBALR0.8) is set. Figure 11 shows an example of an enabled memory map.

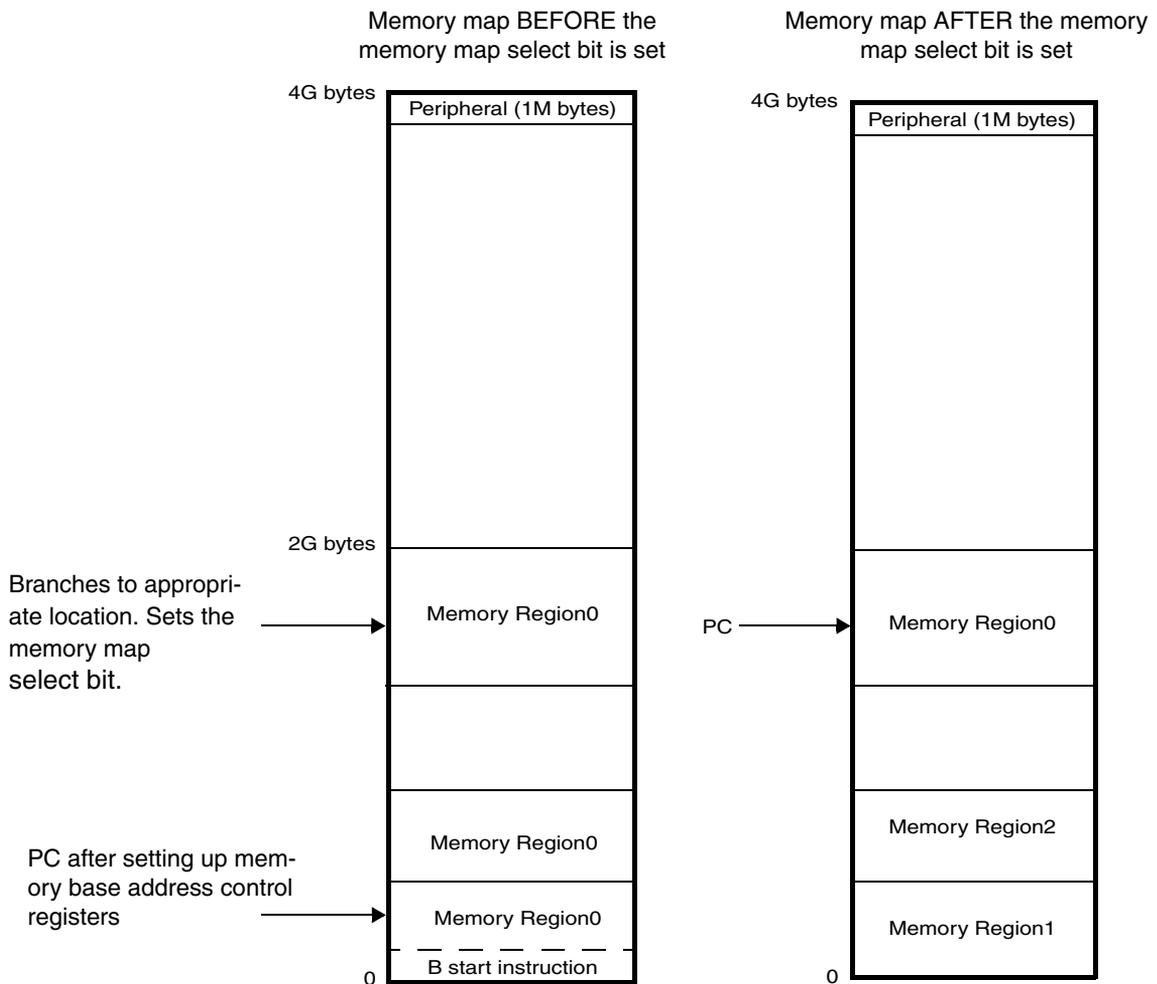
Figure 11. Sample Memory Map After Memory Map is Configured and Enabled



3.2.3 Relocating Boot Memory

If any application needs to map the boot memory to a location other than 0x0000_0000, the boot program should have a branch instruction that changes the program counter (PC) to the new boot program address region. (The memory attached to memory select 0 is mirrored throughout the lower 2G bytes—from 0x0000_0000 to 0x7FFF_FFFF; at every boundary of the memory size, the memory repeats.) Changing the PC to the new boot location ensures that the PC does not get lost when the memory map is reconfigured. Figure 12 shows the memory mapping scheme with the boot memory mapped to a location other than 0x0000_0000.

Figure 12. Memory Mapping Scheme for Relocating Boot Memory



3.3 Memory Protection

Memory protection is implemented through memory selects and an auxiliary memory protection unit (MPU).

The memory-select protection provides uniform protection for the entire memory block selected, and as such, the memory protection constitutes a block protection scheme.

The memory protection unit allows a more refined granularity on the protection of memory blocks, and this finer protection is typically used with RAM. (See Figure 14, on page 21.) Both auxiliary and block memory protection allow the user to:

- Declare the memory accessible in privilege mode only (or in user and privilege mode)
- Configure the memory as read only (or allow both reads and writes)

3.3.1 Memory Block Protection

The block memory protection relies on the memory selects, and the options for protection are configured within the MFBALRx and MCBALRx registers. An access which uses the memory select invokes the protection for the entire memory region. The privilege protection is set with the PRIV bit (MFBALRx.0 and MCBALRx.0). The read-only protection is set with the RONLY bit (MFBALRx.1 and MCBALRx.1).

Note: Memory-Select Protection and MPU Work Separately

On memories in which the block and auxiliary memory protection are both active, the protection schemes work separately. The block protection restricts access, whereas the auxiliary memory protection unit (MPU) allows access. Therefore, the block protection must be as minimal as the minimal MPU protection within the memories in which both MPU and memory-select protections are active.

3.3.2 Auxiliary Memory Protection—MPU for Internal RAM

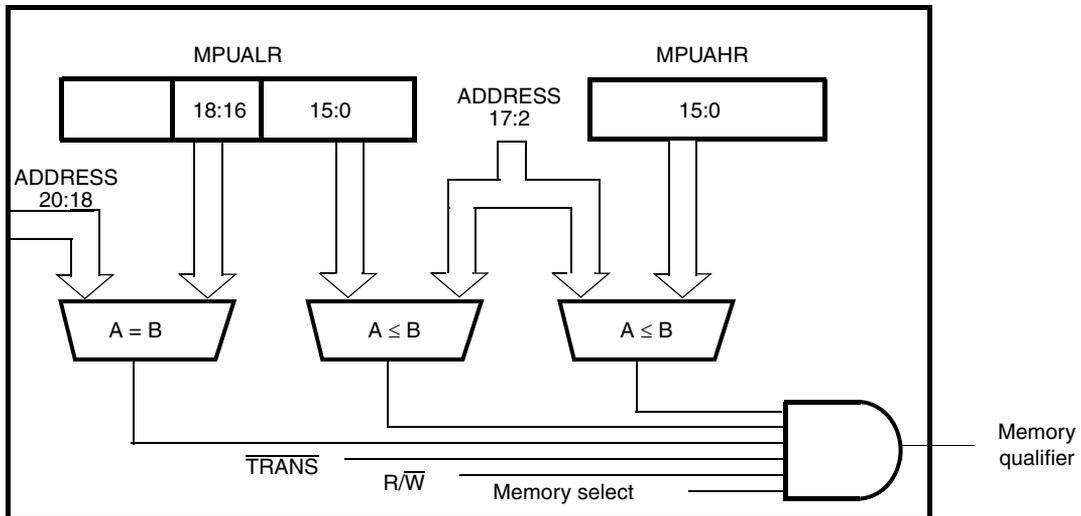
The MPU is activated by enabling any one of the four channels. Until one MPU channel is enabled, the entire MPU is disabled and the memory is protected only by the block protection. As soon as one channel is enabled, the MPU protects the entire RAM by making the entire array inaccessible except for the area in which access is **allowed** by an MPU channel.

The MPU allows access to memory addresses based upon whether the addresses fall within specified address windows. The MPU address windows

are specified by defining the upper and lower address of the accessible window (see Figure 14, on page 21). The window may be as great as 256K bytes or as small as 4 bytes. (Additionally, a window may not cross a 256K-byte boundary.) The MPU allows access to a memory location under the following conditions:

- ❑ Address bus bits 20:2 correspond to the bits programmed into MPUALRx and MPUAHRx.
- ❑ The associated memory select is active (see Figure 13). See the device-specific data sheet for additional information on which memory selects are associated with the MPU.
- ❑ The access type (privilege/user mode, write/read) is allowed.

Figure 13. MPU Address Decode



The MPU decodes the address (bits 31:21 and 1:0 of the address bus are masked off of the address) and generates illegal access or illegal address errors based upon the protection.

If the memory address is not within one of the four specified address windows, the MPU does not permit access. All memory that is not specified in an address window is inaccessible — that is, protected with the strongest possible protection.

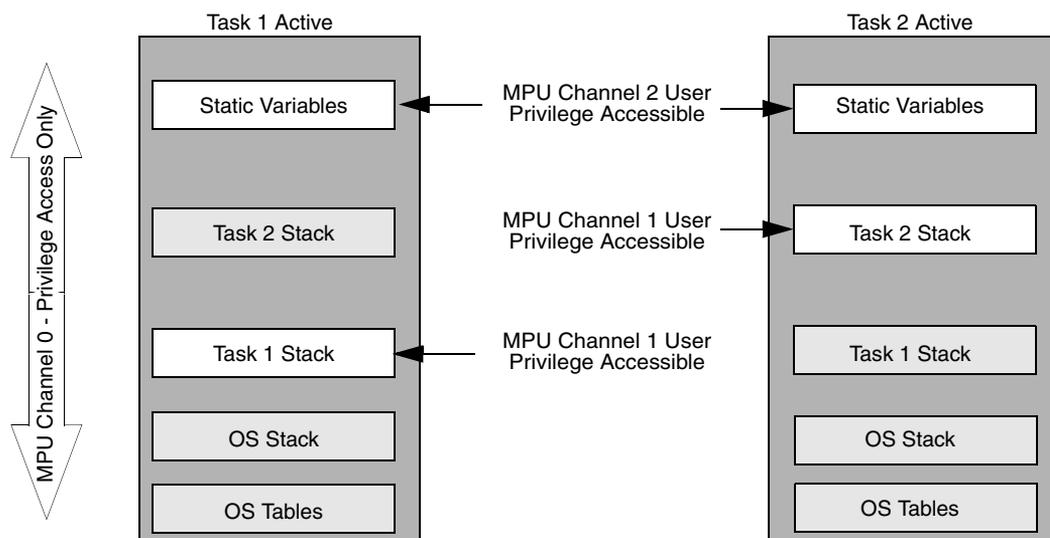
When two or more channel ranges overlap the same memory region, the channel with the lowest protection controls the memory. Table 4 shows the priority of the control register bits when two or more channels overlap. Note the changing role of the PRIV bit in privilege (non-user) mode.

Table 4. Priority of Control Register Bits for Overlapping Channels

Protection	User Mode	Privilege Mode
Highest	RONLY+ PRIV	RONLY, RONLY+PRIV
:	PRIV	
:	RONLY	
Lowest	None	PRIV, None

Figure 14 shows a typical configuration in which the MPU protects the RAM and allows access to only one task's stack at a time. In the left image, task 1 is active and the operating system has allowed access to the static variables and the task 1 stack. When the operating system switches to task 2, it opens the task 2 stack and makes the task 1 stack inaccessible.

Figure 14. Typical Operating System Use of the MPU



3.4 Memory Resets

Reset:

On a reset condition, the program counter jumps to address 0x0000_0000. The CPSR mode changes to reset mode, and the control registers are reset to their default values.

The different memory protection schemes generate resets and aborts when the protection is violated (for additional details, see Section 6, *Resets*, on page 41). The system generates four separate reset/abort conditions that relate to memory protection (see Table 5, on page 24):

- Illegal address

- Illegal access
- Illegal map
- Peripheral illegal access

3.4.1 **Illegal Address**

An illegal address reset/abort indicates an access to an unimplemented address in the memory map. The illegal address exception is generated by the memory selects or the MPU.

- An illegal address in user mode generates an abort.
- An illegal address in privilege mode generates a reset.
- The System Illegal Address exception indicates an access to an unimplemented address in the memory map. The SYS ADDR status bit in the global status register (GLBSTAT) is set to 1 to indicate that an illegal address signal has been detected from the system.
- MPU Illegal Address indicates an access to a memory location not specified by one of the four MPU channels (with the MPU enabled). Both MPUADDR and MPUACC status bits of the global status register (GLBSTAT) are set to 1 to indicate that illegal address and illegal access signals have been detected from the MPU.

Peripheral Register Frame:

The 1-Kbyte regions of the memory map that may be accessed by peripheral selects are referred to as peripheral register frames.

Note: Addresses Within the Peripheral Register Frame

Addresses within the peripheral register frame that are not used by the peripheral are not detected as illegal addresses because the peripheral select is valid.

3.4.2 **Illegal Access**

An illegal access reset/abort indicates an access to a protected memory region. The two types of illegal access protection are read-only protection and access-only protection in privilege mode.

- An illegal access in user mode generates an abort.
- An illegal access in privilege mode generates a reset.

❑ Memory-select illegal access:

All protection violations (such as writing to the read-only memory, a data fetch from memory in user mode while memory is programmed for privilege mode) are detected. When a protection violation is detected, the system manager asserts an illegal access signal, which prevents write operations for the illegal accesses.

❑ MPU illegal access:

While one of the memory-select inputs to the MPU is active, the MPU generates an illegal access signal to the system if the application program attempts to write to a subregion which is programmed read-only or attempts to access, in user mode, a subregion which is accessible only in privilege mode. Hence, the MPUACC status bit of the system module global status register (GLBSTAT) is set to 1 to indicate that an illegal access has been detected from the MPU.

Note: Privilege Access in Control Registers

Control register bits have access protection. Illegal accesses to the control registers do not generate an exception. Illegal accesses to control register bits are ignored.

3.4.3 *Illegal Map*

If the memory map is programmed so that two memory regions overlap, or if a memory array is programmed to access the top 1M byte (reserved for peripheral frame), a system reset occurs. The reset occurs when the overlapping memory regions is accessed by software.

Illegal map does not detect a memory overlap of control registers in the second megabyte (0xFFFF0_0000 to 0xFFE0_0000). The top 2M bytes are reserved for TI use, so you must not map memory to this region.

3.4.4 *Peripheral Illegal Access*

In user mode, a peripheral illegal access abort indicates an access to a protected peripheral. The peripheral protection register (PPROT) allows you to restrict access to peripherals in user mode. The system does not generate

a peripheral select when a peripheral illegal access is detected. A peripheral illegal access generates an abort in user mode (see Table 5).

Table 5. Memory Reset/Abort Causes and Their Associated Exception Flag

Exception Flags	Abort Cause					Reset Cause			
	Illegal Address		Illegal Access			Illegal Address		Illegal Access	
	MPU Illegal Address	System Illegal Address	MPU Illegal Access	System Illegal Access	Peripheral Illegal Access	MPU Illegal Address	System Illegal Address	MPU Illegal Access	System Illegal Access
System Exception Status Register (SYSESR)									
ILL ADDR						1	1		
ILL ACC						1		1	1
PILL ACC									
Abort Exception Status Register (ABRTESR)									
ADDR ABT	1	1							
MEM ABT	1		1	1					
PACC VIO					1				
Global Status Register (GLBSTAT)									
SYS ADDR		1					1		
SYS ACC				1					1
MPU ADDR	1					1			
MPU ACC	1		1			1		1	

4 Interrupts

The TMS470R1x interrupt architecture includes a central interrupt controller that provides hardware assistance for prioritizing and controlling the many interrupt sources present on a device. Interrupts are caused by events outside the normal flow of program execution. Normally these events require a timely response from the central processing unit (CPU); therefore, when an interrupt occurs, the CPU switches execution from the normal program flow to an interrupt service routine. The interrupt service routine is a small program designed to handle the event occurrence in a timely manner.

4.1 Interrupt Handling at the CPU

FIQ/IRQ:

Interrupt exception vectors in the CPU. FIQs are higher priority than IRQ, and FIQ interrupts may interrupt IRQ interrupts.

The ARM7™ CPU provides two vectors for interrupt requests—fast interrupt requests (FIQ) and normal interrupt requests (IRQ). The CPU may enable these interrupt request channels individually within the CPSR; CPSR bits 6 and 7 must be cleared to enable the FIQ and IRQ interrupt requests at the CPU. When both interrupt requests are enabled, the FIQ interrupt request has higher priority than the IRQ and is handled first.

When the CPU recognizes an interrupt request, the CPSR changes mode to either the FIQ or IRQ mode. When an IRQ interrupt is recognized, the CPU disables other IRQ interrupts by setting CPSR bit 7. When an FIQ interrupt is recognized, the CPU disables both IRQ and FIQ interrupts by setting CPSR bits 6 and 7. After the interrupt is recognized by the CPU, the program counter jumps to the appropriate interrupt vector—0x0018 for IRQ and 0x001C for FIQ.

4.2 Interrupt Generation at the Peripheral

Interrupts begin when an event occurs within a peripheral module. Some examples of interrupt-capable events are expiration of a counter within a timer module, receipt of a character in a communications module, and completion of a conversion in an analog-to-digital converter (ADC) module. Some TMS470R1x peripherals are capable of requesting interrupts on more than one central interrupt manager (CIM) channel.

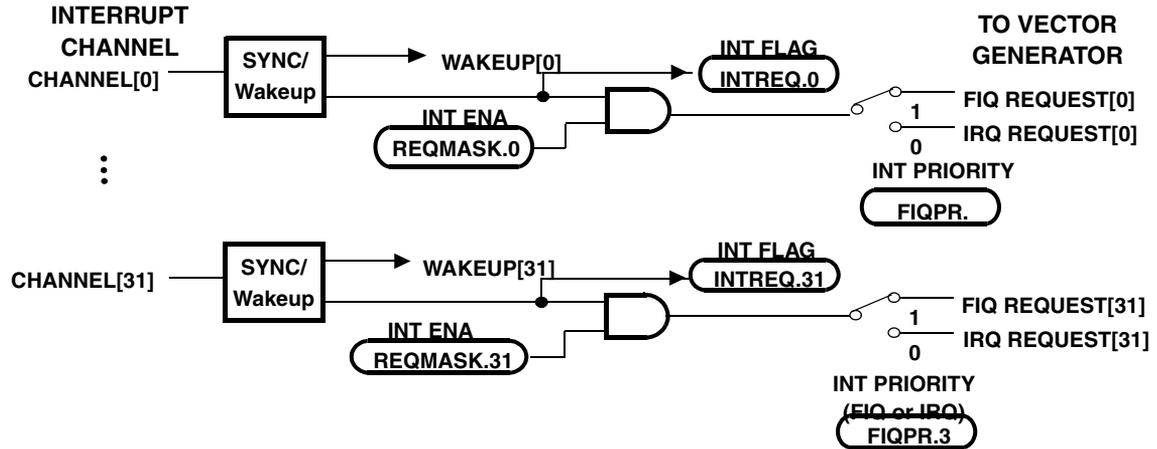
Interrupts are not always generated when an event occurs; the peripheral must make an interrupt request to the central interrupt manager (CIM) based upon the event occurrence. Typically, the peripheral contains:

- An interrupt flag bit for each event to signify the event occurrence
- An interrupt-enable bit to control whether the event occurrence causes an interrupt request to the CIM

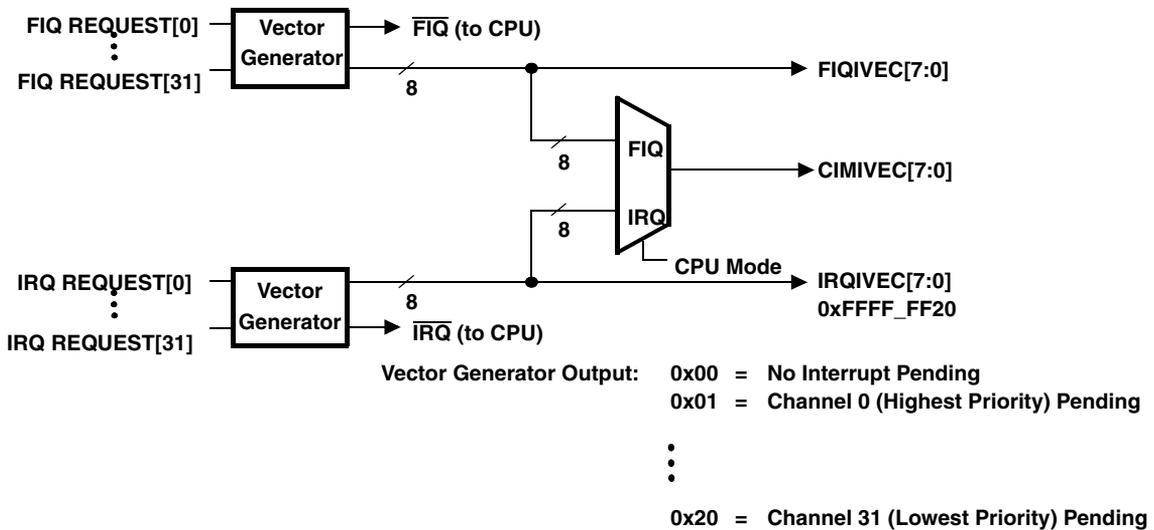
4.3 CIM Interrupt Management

A block diagram of the CIM is shown in Figure 15.

Figure 15. Central Interrupt Manager (CIM) Block Diagram



(a) CIM Interrupt Channel Control



(b) CIM Vector Generator



(c) CIM Wake up From Low-Power Mode on Interrupt

The CIM can support 32 interrupt request lines (channel [0] to channel [31]) from the peripherals. These peripheral interrupt requests are hardwired to each of the CIM 32 channels, and these connections are device specific. (See the device-specific data sheet for details on which module is tied to which interrupt request channel.) All requests pass through a synchronizer to prevent setup time violations; the CIM samples the interrupt requests from the synchronizer every system clock (SYSCLK) cycle. The CIM combines the 32 channels into two outputs – an FIQ request to the CPU and an IRQ request to the CPU. The CIM performs the following functions:

- ❑ Manages the input channels
- ❑ Prioritizes the interrupt requests to the CPU

4.3.1 **CIM Input Channel Management**

On the input side, the CIM enables channels on a channel-by-channel basis (in the REQMASK register); unused channels may be masked to prevent spurious interrupts. Each interrupt channel can be designated to send either an FIQ or IRQ request to the CPU (in the FIQPR register).

Note: LPM Wake-up Interrupts are not Masked at the CIM

Note that if an interrupt is to be used to wake the device up out of any low-power mode (LPM), the interrupts must be enabled/disabled at the individual module level. The REQMASK register has no effect on the enable/disable of an interrupt while the device is in low-power mode.

4.3.2 **CIM Prioritization**

The CIM prioritizes the received interrupts based upon a hardware and software prioritization scheme. The software prioritization scheme is user configurable. The CIM can send two interrupt requests to the CPU simultaneously—one IRQ and one FIQ. If both interrupt types are enabled at the CPU, then the FIQ has greater priority and is handled first. The hardware prioritization scheme sends the lowest numbered active channel (in each FIQ and IRQ interrupt request) to the CPU. Within the FIQ and IRQ classes of interrupts, the lowest channel has the highest priority interrupt. The CIM sends the highest priority interrupt (that is, the lowest active channel) of both the IRQ and FIQ classes of interrupt requests to the CPU.

4.3.3 **CIM Operation**

When the CPU recognizes an interrupt request and responds, the program counter jumps to the appropriate interrupt vector. The interrupt vector is typically a branch statement to an interrupt table. The interrupt table reads the pending interrupt from a vector offset register (FIQIVC.7:0 for FIQ interrupts

and IRQIVEC.7:0 for IRQ interrupts). The CIM has an overall offset register (CIMIVEC.7:0) that is read as IRQ offset or FIQ offset depending upon the mode of the CPU. (All pending interrupts can be viewed in the INTREQ register.)

Example 1 has the fastest response to the FIQ interrupt and is applicable to a system which has only one channel assigned as FIQ (remainder are all IRQ). The FIQ interrupt does not have to take additional branches before reaching the service routine.

Example 1. How to Respond to FIQ With Short Latency

Label	Address	Instructions	Comments
		.sect ".intvecs"	
	00000000h	b _RESET	;RESET interrupt
	00000004h	b _UNDEF_INST_INT	;UNDEFINED INSTRUCTION interrupt
	00000008h	b _SW_INT	;SOFTWARE interrupt
	0000000Ch	b _ABORT_PREF_INT	;ABORT (PREFETCH) interrupt
	00000010h	b _ABORT_DATA_INT	;ABORT (DATA) interrupt
	00000014h	b #-8	; reserved
	00000018h	b _IRQ_ENTRY_0	;IRQ interrupt

		; INTERRUPT PROCESSING AREA	

		=====	
	0000001Ch	_FIQ_INT	; FIQ INTERRUPT ENTRY
		=====	
	0000001Ch	mvn R8, #0xD7	;Load R8 with address of CIMIVEC ; R8 used as address pointer is ; the first FIQ banked register
	00000020h	ldrb R8, [R8]	;Get the FIQ index
	00000024h	ldr PC, [PC, R8, LSL#2]	;Branch to the indexed interrupt ; routine. The prefetch ; operation causes the PC to be 2 ; words (8 bytes) ahead of the ; current instruction, so ; pointing to _INT_TABLE.
	00000028h	nop	; Required due to pipeline.
		=====	
	00000030h	_INT_TABLE	; FIQ/IRQ INTERRUPT DISPATCH
		=====	
	00000030h	.word _FIQ_TABLE	;beginning of FIQ Dispatch
	00000034h	.word _ISR0	;dispatch to interrupt routine 0
	00000038h	.word _ISR1	;dispatch to interrupt routine 1
		.	
		.	
		.word _ISR31	;dispatch to interrupt routine 32

4.4 System Software Interrupts (SSI)

The TMS470 can initiate an IRQ/FIQ interrupt through software. The application software can initiate an IRQ/FIQ interrupt by writing a specific key to the system software interrupt request register (SSIR). The most significant eight bits of the SSIR register are the key register bits. When 0x75 is written to the key register bits, the system software interrupt flag register (SSIF) is set, and an IRQ/FIQ interrupt is generated. The IRQ/FIQ interrupt request is asserted until the software interrupt flag register (SSIF) is cleared by the software. The least significant eight bits of the SSIR register are user register bits that the application software may use to provide a different entry point for the system software interrupt routine.

5 Real-Time Interrupt (RTI)

The 470R1x family of microcontrollers provides a real-time interrupt (RTI) that can generate interrupts periodically or based on compare values. The RTI runs independently of the software loop or the CPU state (not in halt mode), and provides real time to the system.

5.1 RTI Overview

The primary function of the RTI is to provide a programmable clock period, separate from the system clock domain (RTICLK). (See Section 7, *Clocks*, on page 43.)

The RTI may be used for:

- Providing periodic interrupts for an operating system
- Measuring elapsed time within an application (not necessarily interrupt driven)
- Measuring time intervals based upon user/privilege mode for benchmarking code

The RTI can generate interrupts on three separate channels. There are two programmable compare values and one tap interrupt. The compare values trigger an interrupt when the value in the compare control register is equal to the value in the RTI counter. The tap interrupt, on the other hand, triggers an interrupt when the selected bit in the counter clears, that is, when the bit changes from 1 to 0.

5.2 RTI Operating Modes and Conditions

The RTI module is capable of waking up the clock module and bringing the system out of idle or low power mode in the same manner as any wake-up interrupt. Table 6 below lists the different RTI operating modes.

Table 6. RTI Operating Modes

Mode	Clocks	Analog Watchdog (AWD)	RTI
Run	ON - Global	RC	Digital
Idle	ON - Global	RC	Digital
Standby	Local to RTI	RC	Digital
Halt	OFF	RC	Analog
Test	ON	Reset disabled	Interrupt disabled

The DRTI operates in run, idle and standby modes. The AWD operates at all times except during test mode. In test mode, the AWD should not be allowed to reset the device. This can be handled by controlling the capacitance level on the external AWD pin.

5.2.1 RTI Module Clock Source

A dedicated clock, RTICK, is used by the RTI module to clock its internal counters. This RTICK comes from the clock control module (CCM). RTICK can have two different sources - the oscillator clock coming directly from the oscillator or the clock coming from the on chip phase lock loop (PLL). The register bit RTI OSC EN (GLBCTRL.14) of the System Module Global Control Registers is used to select the clock source. There is also the option of enabling or disabling the on-chip PLL. The register bit PLL STBY DIS (GLBCTRL.13) of the System Module Global Control Register handles this feature. This is an added feature to some devices and will be denoted as the Enhanced RTI Module (See the device-specific data sheet to see if this feature has been implemented).

Once RTI OSC EN is programmed, the source of RTICK is the oscillator for all operating modes. When PLL STBY DIS is programmed, the PLL is disabled upon entering STBY mode. This results in lower current consumption. When the device is awakened from STBY mode, the PLL will relock. An external interrupt to the CIM/IEM will trigger the PLL to start the relock process. While the PLL relocks, the system clocks are held off for 4096 cycles. See Table 7 for the clocks available to the RTI module and the corresponding PLL activities during standby mode.

Table 7. PLL State During Standby Mode

RTI OSC EN	PLL STBY DIS	RTI Clock Source	PLL ON/OFF
0	0	PLL CLOCK	ON
0	1	PLL CLOCK	ON
1	0	OSC CLOCK	ON
1	1	OSC CLOCK	OFF

5.3 RTI Operation

A block diagram of the RTI is shown in Figure 16.

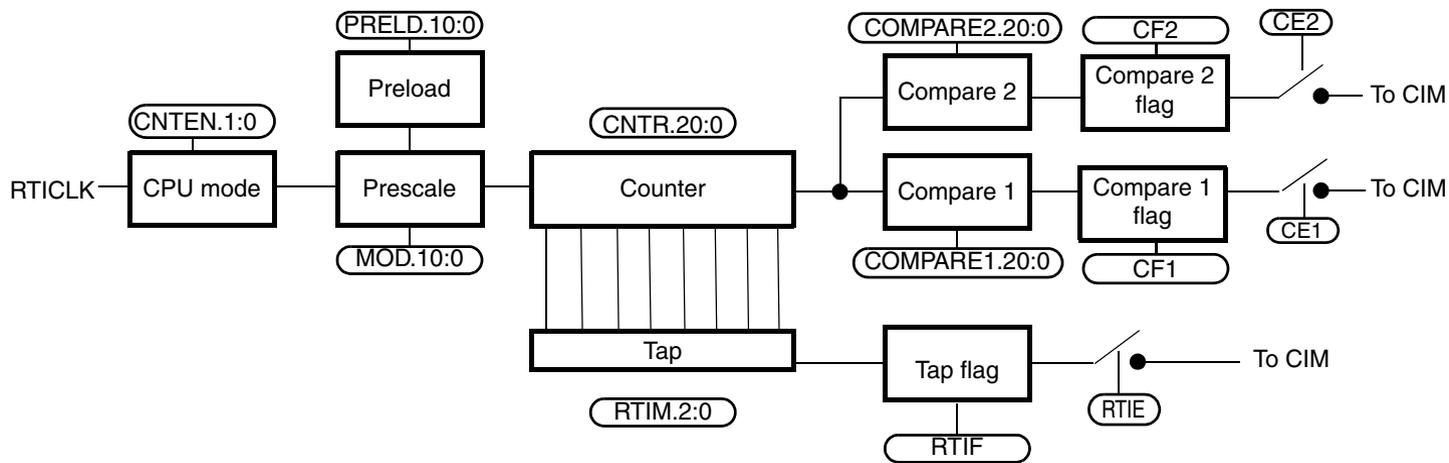


Figure 16. RTI Block Diagram

The RTI is clocked by the RTICK, which runs at SYSClk frequency (see Section 7, *Clocks*, on page 43). The RTI counts RTICK periods based upon the state of the CPU and the control bits CNTEN.1:0 (RTICNTEN.1:0). An 11-bit preload value, PRELD.10:0 (RTIPCTL.10:0), provides the prescale value. The prescale, MOD.10:0 (RTICNTR.10:0) counts down from the preload to 0.

When the prescale counts down to 0, a 21-bit counter is incremented. The counter, CNTR.20:0 (RTICNTR.31:11), is a count up counter. During a read access, both of the RTI counters (MOD.10:0 and CNTR.20:0) are read together in the same cycle as a single 32-bit value (RTICNTR.31:0). However, because the modulo M counter (MOD.10:0) is a down counter, a calculation needs to be performed to convert the 32-bit RTI counter value into system clock cycles which is given by Equation 1:

(EQ 1)

$$RTIClockCycles = (M + 1) \times N + (M - nm)$$

Where:

M = Preload value PRELD.10:0 (RTIPCL.10:0),
when PRELD.10:0 = 0, M = 2048

m = Current value of MOD.10:0 (RTICNTR.10:0)

N = Current value of CNTR.20:0 (RTICNTR.31:11)

The real-time counter can generate three distinct interrupts off of this up counter:

- Tap interrupt
- Two compare interrupts (Compare1 and Compare 2)

5.3.1 Tap Interrupt

The tap interrupt is configured so that when a specified bit of the counter is cleared, the tap interrupt is generated. The RTIM.2:0 bit field (RTIPCTL.13:11) designates which bit is tapped for the interrupt. (See Table 8 for relationship between RTIM.2:0 bits and tap value.) This tap interrupt flag, RTIF (RTICNTL.7), is set every time the specific bit transitions from 1 to 0. In order to generate an interrupt, the tap interrupt enable, RTIE (RTICNTL.6), must be set; the tap interrupt is periodic.

Note: Clear Tap Flag Before Enabling Interrupt

Prior to enabling the tap interrupt, the interrupt flag should be cleared to prevent spurious interrupts.

Table 8. Tap Interrupts

RTIM.2:0 (Binary)	Tap Bit	Tap Value
000	CNTR.20	2097152
001	CNTR.17	262144
010	CNTR.14	32768
011	CNTR.11	4096
100	CNTR.8	512
101	CNTR.5	64
110	CNTR.2	8
111	Underflow	1

The tap interrupt is calculated as shown in Equation 2:

(EQ 2)

$$T = (M + 1) \times (TapValue) \times (RTICLKPeriod)$$

Where:

M = Preload value PRELD.10:0 (RTIPCL.10:0),
when PRELD.10:0 = 0, M = 2048.

TapValue is the value shown in Table 8.

T = Tap Period

Tap period assumes that CNTEN.1:0 (RTICNTEN.1:0) = 0x00

5.3.2 Compare Interrupts

The compare interrupt flags, CF1 (RTICINT.7) or CF2 (RTICINT.6), are set when the 21-bit compare value, COMPARE1.20:0 (RTICMP1.20:0) or COMPARE2.20:0 (RTICMP2.20:0), is equal to the 21-bit counter value. In order to generate an interrupt, the compare interrupt enable, CE1 (RTICINT.5) or CE2 (RTICINT.4) must be set.

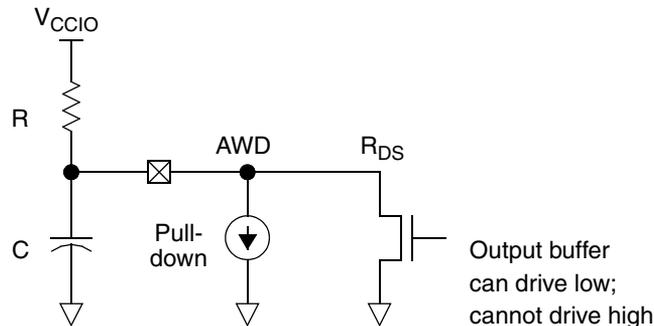
Note: Clear Compare Flag Before Enabling Interrupt

Before the compare interrupt is enabled, the interrupt flag should be cleared to prevent spurious interrupts.

5.4 Analog Watchdog

The 470R1x family of devices may have an external AWD pin. This pin has an internal pull-down so that when the pin is unconnected, the analog watchdog is disabled. When an RC combination is added to the AWD pin, the voltage level on the pin depends on the specific value of resistor and capacitor.

Figure 17. External Required Circuit for Watchdog



When the voltage passes V_{th} (see device specification for V_{th} on AWD), the analog watchdog generates a system reset. The watchdog reset is caused by a high voltage level on the AWD pin.

The watchdog may be cleared by writing 0x0E5 and then 0x0A3 to the WKEY register. When the correct values are written, the analog watchdog drains the external capacitor and resets the external RC delay. If an incorrect value is written to the WKEY register, a watchdog reset occurs immediately. Table 9 illustrates the WKEY register sequence.

Table 9. Example WKEY Register Sequence

Step	Value Written to WKEY	Result
1	0x0A3	No action
2	0x0A3	No action
3	0x0E5	WKEY is enabled for reset by the next 0x0A3.
4	0x0E5	WKEY is enabled for reset by the next 0x0A3.
5	0x0E5	WKEY is enabled for reset by the next 0x0A3.
6	0x0A3	Watchdog is reset.
7	0x0A3	No action
8	0x0E5	WKEY is enabled for reset by the next 0x0A3.
9	0x0A3	Watchdog is reset.
10	0x0E5	WKEY is enabled for reset by the next 0x0A3.
11	0x023	System reset due to an improper key value written to WKEY.

In applications using the analog watchdog (AWD) pin, the choice of external resistor (R), external capacitor (C), and watchdog discharge time ($T_{WATCHDOG}$) must be chosen *in order to include the interaction with the silicon*. The AWD pin must be tied to ground if not used. In most cases, the AWD pin has an on-silicon pull-down, implemented with a current source to ground, so that the pin is not required to be connected externally. (If there is no pull-down, the AWD must be tied to ground externally in order to prevent AWD resets.) When the AWD key is written, the output buffer sinks current for 256 SYSCLK cycles in order to discharge the external capacitor. The presence/absence of a pull-down, its current range, and the size of the output buffer are device-specific and must be verified against the device data sheet.

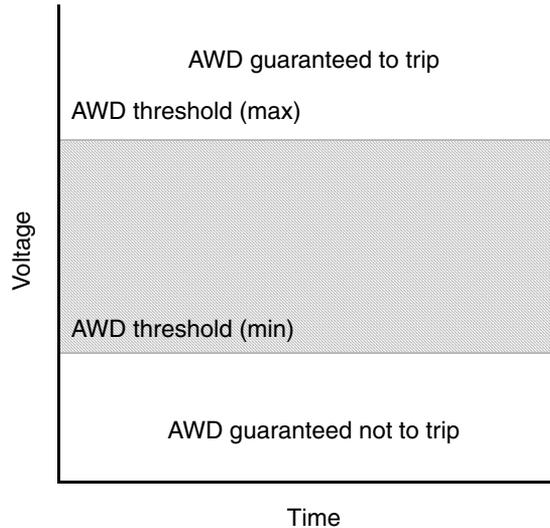
Figure 17 shows a system configuration with external resistor and capacitor. It shows that the AWD resistor, capacitor and discharge interval are:

- AWD threshold (min and max)
- V_{CCIO} (min and max)
- Pull-down current (min and max)
- Maximum drain-source resistance for the output buffer when enabled ($R_{DS_{ON}}$)

- SYSCLK frequency [discharge is active for 256 cycles]

5.4.1 AWD Threshold

Figure 18. AWD Threshold



The external resistor and capacitor values need to be chosen so that the AWD will trip and generate a reset if not discharged. (Note that the AWD when not used is configured so that it cannot trip and generate a reset.) Specifically, the hardware must allow the voltage on the AWD pin to exceed AWD threshold (max) in order to guarantee a reset on all parts over the specified voltage and temperature ranges.

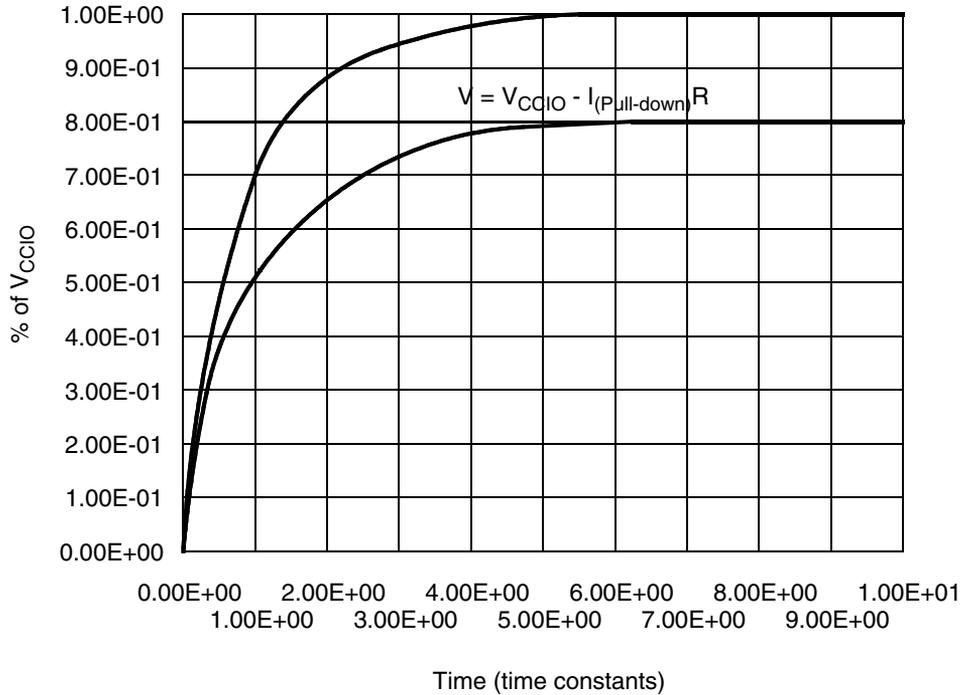
At the same time, the discharge interval must be chosen so that the voltage on the AWD pin never reaches the minimum AWD threshold. The software must discharge the capacitor while the AWD is guaranteed not to trip and generate a reset.

When the voltage is greater than the minimum AWD threshold and less than the maximum AWD threshold, the AWD will trip on some devices but not all. For the sake of figuring the discharge interval, this region must be completely avoided.

5.4.2 Effect of Pull-down

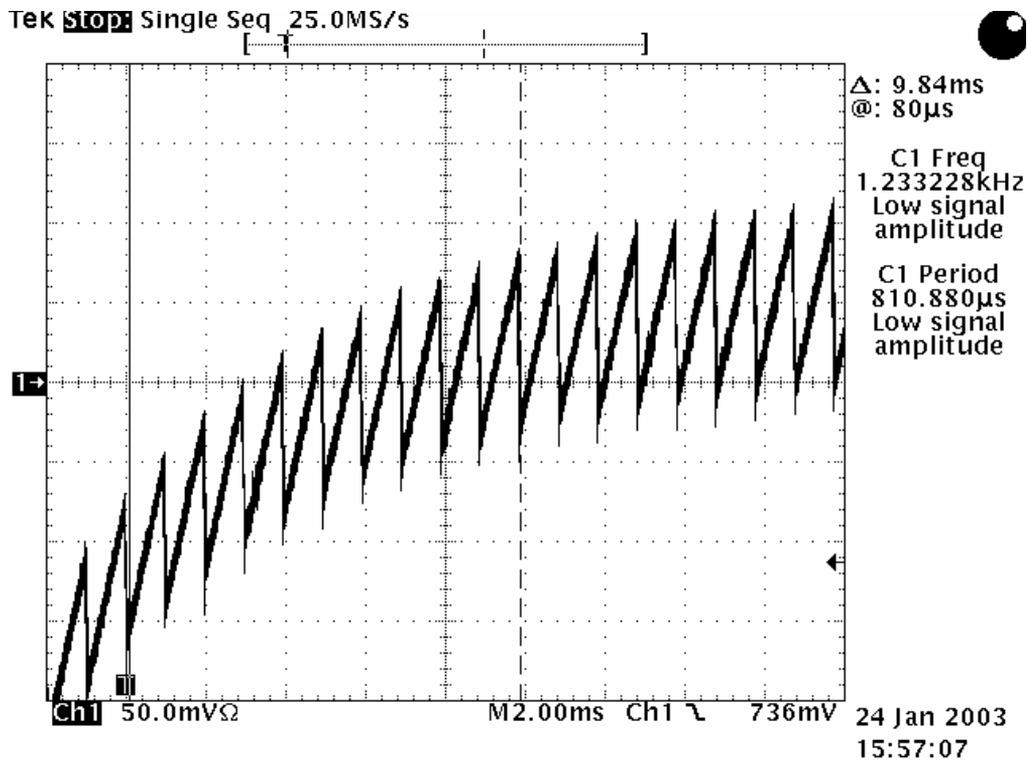
The pull-down has the effect of lowering the charging asymptote by $I_{(\text{Pull-down})}R$ as seen in Figure 19.

Figure 19. Effect of Pull-down



As the discharge time is fixed by SYSCLK, the capacitor may not discharge fully. If not fully discharged, each charge/discharge cycle will start from a new voltage level until the discharging voltage equals the charging voltage, as shown in Figure 20. At this point, the charging starts from some voltage V_0 , charges to V_F and is discharged back to V_0 .

Figure 20. Sequential AWD Charge/Discharge Cycles Reach Charge Asymptote



5.4.3 Effect of $R_{DS_{ON}}$

The output buffer has a resistance from drain to source. The maximum resistance is determined by the buffer strength, as shown in Table 10. Please see the device-specific data sheet.

Table 10. Maximum Resistance by Buffer Strength

Buffer	$R_{DS_{ON}}$ (max)
2 mA	150 Ω
4 mA	75 Ω
8 mA	38 Ω

The non-zero value of $R_{DS_{ON}}$ means that the capacitor discharge follows an RC discharge curve, as shown in Table 11.

Table 11. RC Discharge Curve

	Capacitance	Resistance	Time
Charging	C	R	$T_{\text{WATCHDOG}} - 256 \cdot T_{\text{SYSCLK}}$
Discharging	C	$R_{\text{DS}_{\text{ON}}}$	$256 \cdot T_{\text{SYSCLK}}$

The discharge time may not be sufficient to discharge the AWD pin all the way to ground. In this case, some residual charge remains on the capacitor and the next charging cycle begins from the voltage to which the capacitor was discharged.

The resistor, capacitor, discharge interval must be chosen so that the AWD never trips – *guaranteeing that the pin does not trip during the first charge/discharge cycle is **not** sufficient.*

6 Resets

The TMS470R1x device generates a reset in response to multiple causes. Table 12 shows the different resets and their cause.

Table 12. Causes of TMS470R1x Reset/Abort

Reset	Cause
Power-On Reset (PORRST)	<p>The voltage on the $\overline{\text{PORRST}}$ pin is low. A reset occurs when an external voltage monitor pulled $\overline{\text{PORRST}}$ pin low. A power on reset indicates an initial power up or a voltage supply dip.</p> <p>Flag: SYSESR.15</p>
Clock	<p>A clock reset indicates that the external oscillator's frequency is too low or that the PLL has detected a discrepancy between the reference and VCO phase. See the device specific data sheet for the frequency value that triggers the OSC FAIL flag ($f_{i(\text{OSCRST})}$).</p> <p>A reset occurs if:</p> <ol style="list-style-type: none"> 1. PLL slip (GLBSTAT.0) = 1 or 2. RST OSC FAIL (GLBCTRL.15) = 1 and OSC FAIL (GLBSTAT.1) = 1
Watchdog	<p>A watchdog reset indicates that the watchdog counter was not reset prior to the AWD pin reaching its threshold voltage.</p> <p>Flag: SYSESR.13</p> <p>See Section 5.1, <i>RTI Overview</i>, on page 30 for further details.</p>
Illegal Mode	<p>An illegal mode reset indicates that the ARM mode bits in the current program status register (CPSR) are not in one of the seven legal modes (user, FIQ, IRQ, supervisor, abort, undefined, or system).</p> <p>Flag: SYSESR.12</p>
Illegal Address	<p>(1) An illegal address reset/abort indicates an access to an unimplemented address in the memory. The illegal address reset/abort is generated by the system.</p> <p>(2) The memory protection unit (MPU) may generate an illegal address reset/abort if the memory access within the memory select is not within one of the MPU selects.</p> <ul style="list-style-type: none"> • An illegal address generates an abort in user mode. • An illegal address generates a reset in privilege mode. <p>See Section 3.4.1, <i>Illegal Address</i>, on page 22 for more information.</p>

Table 12. Causes of TMS470R1x Reset/Abort (Continued)

Reset	Cause
Illegal Access	<p>An illegal access reset/abort indicates:</p> <ul style="list-style-type: none"> (1) a write access to protected memory; or (2) an access to a memory location when in user mode. <p>The illegal access reset/abort is generated by the system or the memory protection unit (MPU).</p> <ul style="list-style-type: none"> • Illegal access generates an abort in user mode. • Illegal access generates a reset in privilege mode. <p>See Section 3, <i>Memory</i>, on page 14 for more information.</p>
Peripheral Illegal Access	<p>A peripheral illegal access abort indicates an access to a protected peripheral when in user mode. The peripheral protection register (PPROT) allows the user to restrict access to peripherals when in user mode.</p> <ul style="list-style-type: none"> □• A peripheral illegal access generates an abort in user mode. <p>See Section 3, <i>Memory</i>, on page 14 for more details.</p>
Illegal Map	<p>An illegal map reset indicates an access to overlapped memory regions. The address decoder (DEC) does not prevent the user from overlapping memory regions; when the overlapped region is accessed, the reset occurs.</p> <p>See Section 3, <i>Memory</i>, on page 14 for more details.</p>
Software Reset	<p>A software reset is triggered by a write to SYSECR.15:14. SYSECR.15 = 0 and SYSECR.14 = 1 does not generate a reset.</p>
External Reset ($\overline{\text{RST}}$)	<p>The external reset is generated when the $\overline{\text{RST}}$ pin is driven low.</p>

7 Clocks

The TMS470R1x has five separate clock domains. Table 13 describes the clock domains.

Table 13. Clock Domains

Clock	Description
ACLK	ACLK is the output clock from the oscillator/PLL prior to the prescale divider. The system synthesizes the other device clocks off the prescaled ACLK.
SYSCLK	The clock control module synthesizes SYSCLK from ACLK by dividing the frequency by the prescale divider (GLBCTRL). SYSCLK clocks: RAM HET Flash control registers Flash System control registers DMA
MCLK	MCLK operates at the same frequency as SYSCLK and is inverted (180° out of phase). MCLK clocks the CPU.
ICLK	ICLK is generated from the SYSCLK, and the frequency is controlled by a prescale (PCR.4:1). ICLK clocks peripherals.
RTICLK	RTICLK operates at the same frequency and is in phase with the SYSCLK. RTICLK clocks only the real-time interrupt counters.

The clock domains are active/inactive in different device modes. Table 14 summarizes the clock domain activity based on device conditions.

Table 14. Active Clock Domains and Device Condition

Device Condition	LPM Bits	Oscillator	ACLK	RTICKL	SYSCLK	ICLK	MCLK
RUN	LPM.1:0=0x00	Active	Active	Active	Active	Active	Active
$\overline{\text{RST}}$ low	n/a	Active	Active	Active	Active	Active	Active
IDLE	LPM.1:0=0x01	Active	Active	Active	Active	Active	Inactive
STAND-BY	LPM.1:0=0x02	Active	Active	Active	Inactive	Inactive	Inactive
$\overline{\text{PORRST}}$ low	n/a	Active	Inactive	Inactive	Inactive	Inactive	Inactive
HALT	LPM.1:0=0x03	Inactive	Inactive	Inactive	Inactive	Inactive	Inactive

7.1 Low-Power Modes

Members of the TMS470R1x family of devices have two low-power modes (halt and standby) and an idle mode. The low power modes reduce the operating power by reducing or stopping the activity of various modules. Bits 0 and 1 of the clock control register (CLKCNTL) select the halt, standby, or idle modes.

The standby mode stops the system clocks. The RTI clock is still active. A device can be awakened from standby mode by the following events:

- RTI interrupt
- External interrupt
- CAN message
- Class II message
- SCI message
- I2C message

The halt mode stops the internal clock. This stops processing in all of the modules, resulting in the lowest amount of power consumption. A device can be awakened from halt by any of the following events:

- External interrupt
- CAN message
- Class II message
- SCI message
- I2C message

The idle mode (which is not a low-power mode) is a state that waits for the next interrupt. A device can be awakened from idle by any interrupt.

When a device is initially powered or when it is coming out of a low-power mode, there is an associated delay that exists before code execution can begin. This delay permits the PLL to lock. The following formulas provide the length of the delay.

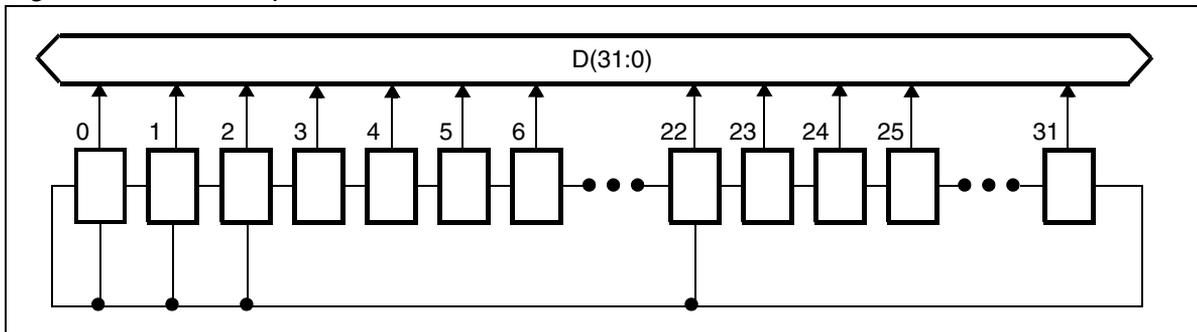
- a) From Power Down = regulator ramp/oscillator start time + 4096 OSCIN cycles + 8 SYSCLK cycles
(Regulator ramp/oscillator start time is application dependent.)
- b) From Halt = oscillator start time + 4096 OSCIN cycles + # of cycles required to service the interrupt
(Oscillator start time is the time it takes to start oscillations.)
- c) From Standby w/ PLL disabled = 4096 OSCIN cycles + # of cycles required to service the interrupt
(Oscillator is active during Standby mode.)
- d) From Standby w/ PLL enabled = "any analog delay" + # of cycles required to service the interrupt
(When PLL is active, system clocks are not held off for 4096 cycles.)

8 Parallel Signature Analyzer Overview

The PSA produces a signature for a given sequence of CPU data bus values. The signature is generated through a feedback path from data bus bits 0, 1, 2, 22, and 31. (See Figure 21.) The PSA signature is based on the primitive polynomial in Equation 3.

$$f(X) = 1 + X + X^2 + X^{22} + X^{31} \quad (\text{EQ 3})$$

Figure 21. PSA Operation



Identical bus sequences produce identical signatures when the PSA is initialized with the same seed value, whereas different sequences of bus activity generally produce different signatures.

The PSA is first initialized by writing a seed value to CPUPSA. The PSA then monitors the CPU data bus and generates a signature value.

One common application of the PSA is to verify the contents of the on-chip memories, either in test or functional modes. This is accomplished by initializing the PSA to a known seed value, using a quick instruction loop to read from the memory, and verifying the PSA signature at the end of the loop. Other applications include online testing.

8.1 PSA Updates

A PSA update is defined as compression of one data bus word. To achieve consistent signatures, the PSA updates during every CPU read data access from memory. The PSA does not update during instruction fetches. Since only CPU memory read accesses trigger PSA updates, differences in memory latencies from the memory subsystem are ignored. In addition, DMA memory accesses do not affect the PSA signature. Furthermore, for accesses of less than a word (32-bits), the PSA treats the non-valid bits of the CPU bus as zeros. After a device reset, the PSA reverts to its initial value and starts updating on the first CPU memory access.

8.2 Read/Write Operation

When the PSA register is read, the PSA returns the current signature to the data bus. The PSA then updates after the CPU data's next memory access. When the PSA register is written with the seed value, the register starts updating after the next CPU memory access. Depending on the size of the data access (word, half-word or byte), the PSA reads in the appropriate data size from the CPU data bus and treats the remaining bits on the data bus as zeros. The PSA does not update during a wait state or system reset.

8.3 Emulation Support

In emulation mode, the PSA does not perform any updates. This allows interrupted code to behave correctly when continued.

8.4 Enable/Disable

The PSA can be turned on or off to conserve power. To power down the PSA, a 1 must be loaded into the PSADIS. When powered down, the PSA stops functioning and the current status of the registers remains the same. The PSA is powered on by a 0 being written to the PSADIS bit.

Note:

There is a small probability that signature aliasing can occur for different sequences and result in identical signatures. In this case, any fault is undetected.

8.5 PSA Pseudo Code

The PSA pseudo code is shown in Example 2.

Example 2. PSA Pseudo Code

```
union ubits
{
    unsigned int uint;
    struct
    {
        unsigned char by0;
        unsigned char by1;
        unsigned char by2;
        unsigned char by3;
    }bytes;
    struct
    {
        int b0:1;
        int b1:1;
        int b2:1;
        int:18;
    }
}
```

```

                                int b21:1;
                                int b22:1;
                                int:8;
                                int b31:1;
                                }bits;
};

UNIT32 calc_psa (UNIT32 *data, Unit32 length, UNIT32 seed)
{
    union ubits a,b,c;
    UNIT32 i;
    c.uint=seed
    for (i=0;i<length>2;i++)
    {
        a.uint=data[i];
        b.bytes.by0=a.bytes.by3;
        b.bytes.by1=a.bytes.by2;
        b.bytes.by2=a.bytes.by1;
        b.bytes.by3=a.bytes.by0;
        a.uint=c.uint;

        c.uint=b.uint^(a.uint<<1);
        c.bits.b0=a.b31^b.bits.b0;
        c.bits.b1=b.bits.b1^a.bits.b0^a.bits.b31;
        c.bits.b2=b.bits.b2^a.bits.b1^a.bits.b31;
        c.bits.b22=b.bits.b22^a.bits.b21^a.bits.b31;
    }
    return c.uint;
}
```

9 Registers

This section details the system module registers memory map as listed in Table 16. A detailed description of each register and its bits is also provided.

Each register begins on a word boundary. The registers in Table 16 are listed in address order with the MPU registers listed first. For architectures with 470+, all system register accesses take two cycles; for architectures other than 470+, system register accesses take one cycle.

The registers within the system module have either 16-bit or 32-bit access sizes as shown in Table 15. No register is accessible for 8-bit writes.

Table 15. System Register Accessibility

32-BIT ACCESSES ONLY	16-BIT or 32-BIT ACCESSES
MPUA(H/L)Rx	SMCRx
MPUCTRL	WCRO
RTICNTR	PCR
RTIPCTL	PLR
RTICNTL	PPROT
WKEY	MFBA(H/L)Rx
RTICMP1	MCBA(H/L)Rx
RTICMP2	CLKCNTL
RTICINT	GLBCTRL
RTICNTEN	SYSECR
IRQIVEC	SYSESR
FIQIVEC	ABRTEsr
CIMIVEC	GLBSTAT
FIRQPR	DEV
INTREQ	SSIF
REQMASK	SSIR
CPUPSA	
PSAENABLE	

Table 16. Control Register Map

Offset Address Register	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	0	Page
Memory Protection Unit (Addresses are pointers)																		
0x00 MPUAHR0	Reserved																66	
	UPPERBOUND																	
0x04 MPUALR0	Reserved														EQUAL		66	
	LOWERBOUND																	
0x08 MPUAHR1	Reserved																66	
	UPPERBOUND																	
0x0C MPUALR1	Reserved														EQUAL		66	
	LOWERBOUND																	
0x10 MPUAHR2	Reserved																66	
	UPPERBOUND																	

Table 16. Control Register Map (Continued)

Offset Address Register	31	15	30	14	29	13	28	12	27	11	26	10	25	9	24	8	23	7	22	6	21	5	20	4	19	3	18	2	17	1	16	0	Page
0x14 MPUALR2	Reserved																								EQUAL		66						
	LOWERBOUND																																
0x18 MPUAHR3	Reserved																																66
	UPPERBOUND																																
0x1C MPUALR3	Reserved																								EQUAL		66						
	LOWERBOUND																																
0x20 MPUCTRL	Reserved																																67
	CHAN3R ONLY	CHAN3 PRIV	CHAN3 EN	CHAN3 Special	CHAN2 RONLY	CHAN2 PRIV	CHAN2 EN	CHAN2 Special	CHAN1 RONLY	CHAN1 PRIV	CHAN1 EN	CHAN1 Special	CHAN0 RONLY	CHAN0 PRIV	CHAN0 EN	CHAN0 Special																	
0xFFFF_FD00 SMCR0	Reserved																																71
	Reserved		ASC		TWS		Rsrv'd	WS		END	Rsrv'd	DW																					

Table 16. Control Register Map (Continued)

Offset Address Register	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	0	Page
0xFFFF_FD04 SMCR1	Reserved																74	
	Reserved	ASC	TWS	Rsrv'd	WS	END	MLOC	DW										
0xFFFF_FD08 SMCR2	Reserved																74	
	Reserved	ASC	TWS	Rsrv'd	WS	END	MLOC	DW										
0xFFFF_FD0C SMCR3	Reserved																74	
	Reserved	ASC	TWS	Rsrv'd	WS	END	MLOC	DW										
0xFFFF_FD10 SMCR4	Reserved																74	
	Reserved	ASC	TWS	Rsrv'd	WS	END	MLOC	DW										
0xFFFF_FD14 SMCR5	Reserved																74	
	Reserved	ASC	TWS	Rsrv'd	WS	END	MLOC	DW										

Table 16. Control Register Map (Continued)

Offset Address Register	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	0	Page
0xFFFF_FD18 SMCR6	Reserved																74	
	Reserved	ASC	TWS	Rsrv'd	WS	END	MLOC	DW										
0xFFFF_FD1C SMCR7	Reserved																74	
	Reserved	ASC	TWS	Rsrv'd	WS	END	MLOC	DW										
0xFFFF_FD20 SMCR8	Reserved																74	
	Reserved	ASC	TWS	Rsrv'd	WS	END	MLOC	DW										
0xFFFF_FD24 SMCR9	Reserved																74	
	Reserved	ASC	TWS	Rsrv'd	WS	END	MLOC	DW										
0xFFFF_FD2C WCR0	Reserved																75	
	Reserved														WT WS OVR	WB EN ABLE		

Table 16. Control Register Map (Continued)

Offset Address Register	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	0	Page
0xFFFF_FD30 PCR	Reserved																76	
	Reserved											CLKDIV		PEN ABLE				
0xFFFF_FD34 PLR	Reserved																78	
	PLOC.15:0																	
0xFFFF_FD38 PPROT	Reserved																79	
	PPROT.15:0																	
Memory Fine Base Address Registers																		
0xFFFF_FE00 MFBHR0	Reserved																81	
	Address.31:16																	
0xFFFF_FE04 MFBALR0	Reserved																81	
	Address.15:10					Rsrv'd	MS	Block Size				0	Rsrv'd	RONLY	PRIV			

Table 16. Control Register Map (Continued)

Offset Address Register	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	0	Page
0xFFFF_FE08 MFBAHR1	Reserved																84	
	Address.31:16																	
0xFFFF_FE0C MFBALR1	Reserved																84	
	Address.15:10				AW	Rsrv'd	Block Size				Reserved	RONLY	PRIV					
0xFFFF_FE10 MFBAHR2	Reserved																84	
	Address.31:16																	
0xFFFF_FE14 MFBALR2	Reserved																84	
	Address.15:10				AW	Rsrv'd	Block Size				Reserved	RONLY	PRIV					
0xFFFF_FE18 MFBAHR3	Reserved																84	
	Address.31:16																	

Table 16. Control Register Map (Continued)

Offset Address Register	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	Page
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
0xFFFF_FE1C MFBALR3	Reserved																84
	Address.15:10						AW	Rsrv'd	Block Size				Reserved	RONLY	PRIV		
0xFFFF_FE20 MFBHR4	Reserved																84
	Address.31:16																
0xFFFF_FE24 MFBALR4	Reserved																84
	Address.15:10						AW	Rsrv'd	Block Size				Reserved	RONLY	PRIV		
0xFFFF_FE28 MFBHR5	Reserved																84
	Address.31:16																
0xFFFF_FE2C MFBALR5	Reserved																84
	Address.15:10						AW	Rsrv'd	Block Size				Reserved	RONLY	PRIV		

Table 16. Control Register Map (Continued)

Offset Address Register	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	0	Page
0xFFFF_FE30 MCBAHR0	Reserved																86	
	Address.31:16																	
0xFFFF_FE34 MCBALR0	Reserved																86	
	Address.15	Reserved					AW	Rsrv'd	Block Size			0	Rsrv'd	RONLY	PRIV			
0xFFFF_FE38 MCBAHR1	Reserved																86	
	Address.31:16																	
0xFFFF_FE3C MCBALR1	Reserved																86	
	Address.15	Reserved					AW	Rsrv'd	Block Size			0	Rsrv'd	RONLY	PRIV			
0xFFFF_FE40 MCBAHR2	Reserved																86	
	Address.31:16																	

Table 16. Control Register Map (Continued)

Offset Address Register	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	0	Page
0xFFFF_FE44 MCBALR2	Reserved																86	
Address. 15	Reserved					AW	Rsrv'd	Block Size			0	Rsrv'd	RONLY	PRIV				
0xFFFF_FE48 MCBAHR3	Reserved																86	
Address.31:16																		
0xFFFF_FE4C MCBALR3	Reserved																86	
Address. 15	Reserved					AW	Rsrv'd	Block Size			0	Rsrv'd	RONLY	PRIV				
0xFFFF_FE50 MCBAHR4	Reserved																86	
Address.31:16																		
0xFFFF_FE54 MCBALR4	Reserved																86	
Address. 15	Reserved					AW	Rsrv'd	Block Size			0	Rsrv'd	RONLY	PRIV				

Table 16. Control Register Map (Continued)

Offset Address Register	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	0	Page
0xFFFF_FE58 MCBAHR5	Reserved																86	
	Address.31:16																	
0xFFFF_FE5C MCBALR5	Reserved																86	
	Address. 15	Reserved				AW	Rsrv'd	Block Size			0	Rsrv'd	RONLY	PRIV				
0xFFFF_FF00 RTICNTR	CNTR.20:5																89	
	CNTR.4:0					MOD.10:0												
0xFFFF_FF04 RTIPCTL	Reserved																90	
	Reserved	RTIM.2:0			PRELD.10:0													
0xFFFF_FF08 RTICNTL	Reserved																92	
	Reserved							TAP FLAG	TAP ENA	Reserved								

Table 16. Control Register Map (Continued)

Offset Address Register	31 15	30 14	29 13	28 12	27 11	26 10	25 9	24 8	23 7	22 6	21 5	20 4	19 3	18 2	17 1	16 0	Page
0xFFFF_FF0C WKEY	WKEY.31:16																93
	WKEY.15:0																
0xFFFF_FF10 RTICMP1	Reserved										COMPARE1.20:16						94
	COMPARE1.15:0																
0xFFFF_FF14 RTICMP2	Reserved										COMPARE2.20:16						94
	COMPARE2.15:0																
0xFFFF_FF18 RTICINT	Reserved																95
	Reserved								CMP1 FLAG	CMP2 FLAG	CMP1 ENA	CMP2 ENA	Reserved				
0xFFFF_FF1C RTICNTEN	Reserved																97
	Reserved														CNTEN.1:0		

Table 16. Control Register Map (Continued)

Offset Address Register	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	Page
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
0xFFFF_FF20 IRQIVEC	Reserved																98
	Reserved								IRQIVEC.7:0								
0xFFFF_FF24 FIQIVEC	Reserved																99
	Reserved								FIQIVED.7:0								
0xFFFF_FF28 CIMIVEC	Reserved																100
	Reserved								CIMVEC.7:0								
0xFFFF_FF2c FIRQPR	FIRQPR.31:16																101
	FIRQPR.15:0																
0xFFFF_FF30 INTREQ	INTREQ.31:16																101
	INTREQ.15:0																

Table 16. Control Register Map (Continued)

Offset Address Register	31	15	30	14	29	13	28	12	27	11	26	10	25	9	24	8	23	7	22	6	21	5	20	4	19	3	18	2	17	1	16	0	Page
0xFFFF_FF34 REQMASK	REQMASK.31:16																															102	
	REQMASK.15:0																																
0xFFFF_FF40 CPUPSA	CPUPSA.31:16																															103	
	CPUPSA.15:0																																
0xFFFF_FF50 PSAENABLE	Reserved																															103	
	Reserved																														PSA DIS		
0xFFFF_FFDC CLKCNTL	Reserved																															105	
	Reserved															PPW NOVR	CLKSR	CLK DIR	CLK DOUT	CLK DIN	LPM												
0xFFFF_FFDC GLBCTRL	Reserved																															108	
	PLL Specific	RTI OSC EN	PLL STBY DIS	PLL Specific																		FL CON-FIG	PLL Specific										

Table 16. Control Register Map (Continued)

Offset Address Register	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	Page
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
0xFFFF_FFE0 SYSECR	Reserved																110
	RESET	RESET	Reserved											PACC OVR	ACC OVR	ILL OVR	
0xFFFF_FFE4 SYSESR	Reserved																112
	POR RST	CLK RST	WD RST	ILL MODE	ILL ADR	ILL ACC	PLL ACC	ILL MAP	SW RST	Reserved							
0xFFFF_FFE8 ABRTESR	Reserved																115
	ADR ABT	MEM ABT	PACC VIO	Reserved													
0xFFFF_FFEC GLBSTAT	Reserved																116
	Reserved								SYS ADDR	SYS ACC	MPU ADDR	MPU ACC	Reserved		OSC FAIL	PLL SLIP	
0xFFFF_FFF0 DEV	Reserved																119
	DEV.15:0																

Table 16. Control Register Map (Continued)

Offset Address Register	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	0	Page
0xFFFF_FFF8	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0		120
SSIF	Reserved																	
	Reserved															SSI FLAG		
0xFFFF_FFFC	Reserved																121	
SSIR	Reserved																	
	SSKEY.7:0								SSDATA.7:0									

9.1 MPU Address Registers

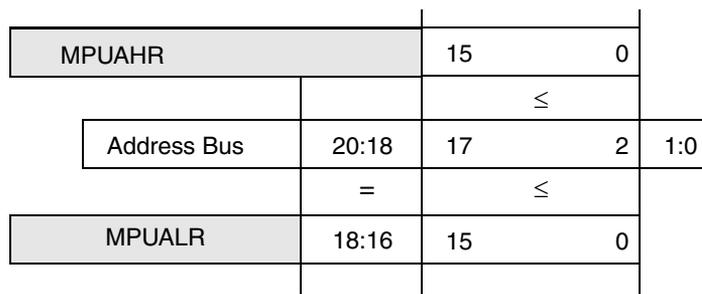
This section describes all MPU address registers used to define any memory sub-regions that require protection checks. The MPU contains eight address registers, two for each channel, as shown in Table 17. It should be noted that the MPU upper and lower bound address registers need to be written to by first right-rotating the value by two bits.

Table 17. MPU Registers

Register	Offset Address
MPUAHR0	0x00
MPUALR0	0x04
MPUAHR1	0x08
MPUALR1	0x0C
MPUAHR2	0x10
MPUALR2	0x14
MPUAHR3	0x18
MPUALR3	0x1C
MPUCTRL	0x20

Figure 22 illustrates the MPU register alignment with the address bus.

Figure 22. MPU Register Alignment with Address Bus

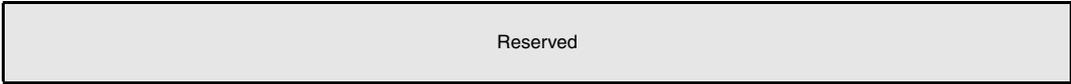


- 1) If the address on the address bus is less than LOWERBOUND, the MPU channel cannot allow access to the region.
- 2) If the address on the address bus is greater than LOWERBOUND and if the address on the address bus is bounded by UPPERBOUND and EQUAL, then the MPU channel allows access to the address based upon the protection specified in MPUCTRL.

9.1.1 MPU Address High Register (MPUAHRx)

Bits 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16

Offset
0x00



Bits 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0



RWP-0

R = Read in all modes, WP = Write in privilege mode only; -n = Value after reset

Bits [31:16] Reserved.

Reads are undefined and writes have no effect.

Bits [15:0] UPPERBOUND.

UPPERBOUND defines the upper bound of the memory region protected by the MPU channel. The address bus (shifted right by 2) is compared to UPPERBOUND.

9.1.2 MPU Address Low Register (MPUALRx)

Bits 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16

Offset_
0x04



R-0

RWP-0

Bits 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0



RWP-0

RWP = Read in all modes, write in privilege mode only; -n = Value after reset

Bits [31:1] Reserved.

Reads are undefined and writes have no effect.

Bits [18:16] EQUAL.

Address bus bits 20:18 are compared to EQUAL.

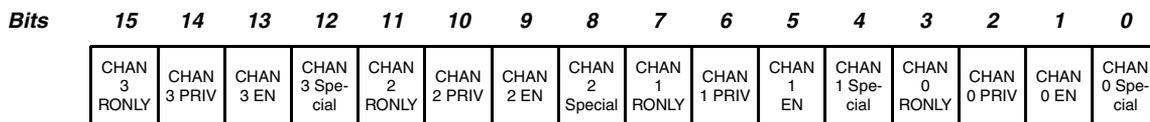
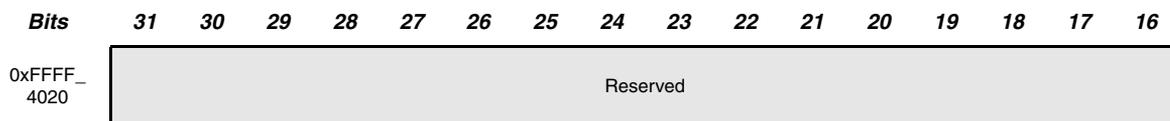
Bits [15:0] LOWERBOUND.

LOWERBOUND defines the lower bound of the memory region protected by the MPU channel. The address bus (shifted right by 2) is compared to LOWERBOUND.

9.2 MPU Control Register

This section describes the bits for the MPU control register, which provides configuration information for each of the four channels and is used by the comparator logic to determine access violations. The 4-bit control field corresponds to one channel. The same bit descriptions can be applied to the other three channels. Writes to this register take two system clock cycles.

9.2.1 MPU Control Register (MPUCTRL)



RWP-0 RWP-0

R = Read in all modes, WP = Write in privilege mode only; -n = Value after reset;

Bits [31:16] Reserved.

Reads are undefined and writes have no effect.

Bit 15 CHAN3 RONLY. Memory region 3 read/write activation.

Determines if a memory region is read-only or read/write.

User and privilege mode (read):

Privilege mode (write):

0 = Memory region is read/write.

1 = Memory region is read only.

Bit 14 CHAN3 PRIV. Memory region 3 access control.

Determines if a memory region can be accessed in all CPU modes or only a non-user (that is, a privileged) mode.

User and privilege mode (read):

Privilege mode (write):
0 = Memory region is accessible in user and privilege modes.
1 = Memory is accessible only in privilege modes.

Bit 13 **CHAN3 EN.** Memory region 3 enable.

Enables a memory region.

User and privilege mode (read):
Privilege mode (write):
0 = MPU channel 3 is disabled.
1 = MPU channel 3 is enabled.

Memory access is checked only when any of the four MPU channels is active.

Bit 12 **CHAN3 Special.** Special access to peripheral addresses for memory region 3.

Controls whether a peripheral may be accessed or not. If a channel is enabled and its *Special* access bit is set to 1, CPU address lines A[31:20] are compared against 0XFFF and FFE to determine if the channel is active.

However, if a channel is enabled and its *Special* access bit is set to 0, the channel is active when the MPU receives an incoming chip select from the Address Manager.

User and privilege mode (read):
Privilege mode (write):
0 = MPU channel active with associated memory select.
1 = MPU protection lies in the upper 2 MBytes of memory map.

Bit 11 **CHAN2 RONLY.** Memory region 2 read/write activation.

Determines if a memory region is read-only or read/write.

User and privilege mode (read):
Privilege mode (write):
0 = Memory region is read/write.
1 = Memory region is read only.

Bit 10 **CHAN2 PRIV.** Memory region 2 access control.

Determines if a memory region can be accessed in all CPU modes or only a non-user (that is, a privileged) mode.

User and privilege mode (read):
Privilege mode (write):
0 = Memory region is accessible in user and privilege modes.
1 = Memory is accessible only in privilege modes.

- Bit 9** **CHAN2 EN.** Memory region 2 enable.
- Enables a memory region.
- User and privilege mode (read):
Privilege mode (write):
0 = MPU channel 2 is disabled.
1 = MPU channel 2 is enabled.
- Memory access is checked only when any of the four MPU channels is active.
- Bit 8** **CHAN2 Special.** Special access to peripheral addresses for memory region 2.
- Controls whether a peripheral may be accessed or not. If a channel is enabled and its *Special* access bit is set to 1, CPU address lines A[31:20] are compared against 0XFFF and FFE to determine if the channel is active.
- However, if a channel is enabled and its *Special* access bit is set to 0, the channel is active when the MPU receives an incoming chip select from the Address Manager.
- User and privilege mode (read):
Privilege mode (write):
0 = MPU channel active with associated memory select.
1 = MPU protection lies in the upper 2M bytes of memory map.
- Bit 7** **CHAN1 RONLY.** Memory region 1 read/write activation.
- Determines if a memory region is read-only or read/write.
- User and privilege mode (read):
Privilege mode (write):
0 = Memory region is read/write.
1 = Memory region is read only.
- Bit 6** **CHAN1 PRIV.** Memory region 1 access control.
- Determines if a memory region can be accessed in all CPU modes or only a non-user (i.e, a privileged) mode.
- User and privilege mode (read):
Privilege mode (write):
0 = Memory region is accessible in user and privilege modes.
1 = Memory is accessible only in privilege modes.
- Bit 5** **CHAN1 EN.** Memory region 1 enable.
- Enables a memory region.

User and privilege mode (read):
Privilege mode (write):
0 = MPU channel 1 is disabled.
1 = MPU channel 1 is enabled.

Memory access is checked only when any of the four MPU channels is active.

Bit 4 **CHAN1 Special.** Special access to peripheral addresses for memory region 1.

Controls whether a peripheral may be accessed or not. If a channel is enabled and its *Special* access bit is set to 1, CPU address lines A[31:20] are compared against 0FFF and FFE to determine if the channel is active. However, if a channel is enabled and its *Special* access bit is set to 0, the channel is active when the MPU receives an incoming chip select from the Address Manager.

User and privilege mode (read):
Privilege mode (write):
0 = MPU channel active with associated memory select.
1 = MPU protection lies in the upper 2M bytes of memory map.

Bit 3 **CHAN0 RONLY.** Memory region 0 read/write activation.

Determines if a memory region is read-only or read/write.

User and privilege mode (read):
Privilege mode (write):
0 = Memory region is read/write.
1 = Memory region is read only.

Bit 2 **CHAN0 PRIV.** Memory region 0 access control.

Determines if a memory region can be accessed in all CPU modes or only a non-user (i.e, a privileged) mode.

User and privilege mode (read):
Privilege mode (write):
0 = Memory region is accessible in user and privilege modes.
1 = Memory is accessible only in privilege modes.

Bit 1 **CHAN0 EN.** Memory region 0 enable.

Enables a memory region.

User and privilege mode (read):
Privilege mode (write):
0 = MPU channel 0 is disabled.
1 = MPU channel 0 is enabled.

Memory access is checked only when any of the four MPU channels is active.

Bit 0 **CHAN0 Special.** Special access to peripheral addresses for memory region 0.

Controls whether a peripheral may be accessed or not. If a channel is enabled and its *Special* access bit is set to 1, CPU address lines A[31:20] are compared against 0XFFF and FFE to determine if the channel is active.

However, if a channel is enabled and its *Special* access bit is set to 0, the channel is active when the MPU receives an incoming chip select from the Address Manager.

User and privilege mode (read):

Privilege mode (write):

0 = MPU channel active with associated memory select.

1 = MPU protection lies in the upper 2M bytes of memory map.

Note: MPU Special Protection Mode

The MPU can be used to protect the upper 2M bytes of the memory map by setting the *Special* bit of the channel in the MPUCTRL register.

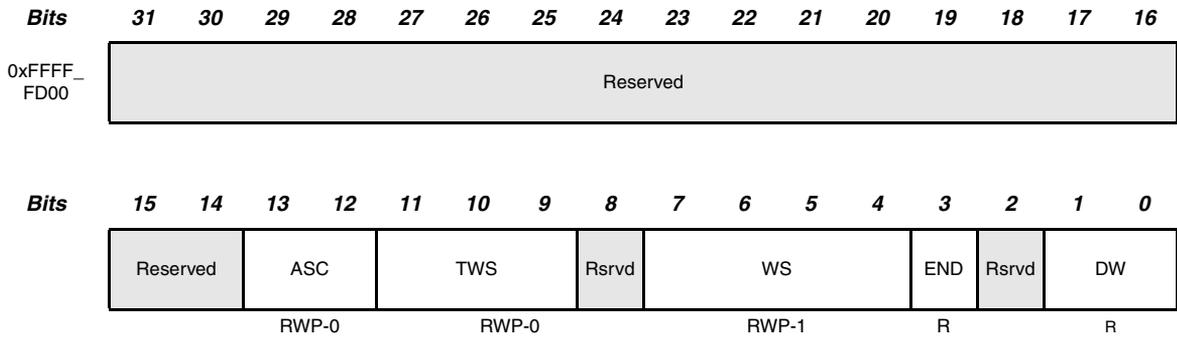
9.3 Static Memory Control Registers

This section describes the static memory control registers used by the system. See Table 18 for a list of register starting addresses. The static memory control registers determine the wait states and the memory widths to be decoded for multiple accesses.

Table 18. Static Memory Control Register Starting Addresses

Register	Address
SMCR0	0xFFFF_FD00
SMCR1	0xFFFF_FD04
SMCR2	0xFFFF_FD08
SMCR3	0xFFFF_FD0C
SMCR4	0xFFFF_FD10
SMCR5	0xFFFF_FD14
SMCR6	0xFFFF_FD18
SMCR7	0xFFFF_FD1C
SMCR8	0xFFFF_FD20
SMCR9	0xFFFF_FD24

9.3.1 Static Memory Control Register 0 (SMCR0)



R = Read only; RWP = Read in all modes, write in privilege mode only; -n = Value after reset

Bits [31:14] Reserved.

Reads are undefined and writes have no effect.

Bits [13:12] ASC. Address setup time cycles (write operations).

Determine the number of clock cycles required for the address setup time to the write strobe for the write operations. When this field is zero, the address is valid at the beginning of the system cycle and the write strobe is asserted from the middle of the cycle. When this field is programmed to a non-zero value, the address is valid at the beginning of the memory cycle and the write strobe assertion is delayed by the number of cycles that is equivalent to the programmed value.

User and privilege mode (read):

Privilege mode (write):

00 = No setup time required

01 = Write strobe is delayed one cycle

10 = Write strobe is delayed two cycles

11 = Write strobe is delayed three cycles

Bits [11:9] TWS. Trailing wait states.

Determine the trailing wait states after read and write operations to the memory associated with the chip select corresponding to the wait states. The trailing wait states after a read operation compensate the \overline{OE} or chip select to disable the data bus. The trailing wait states after a write operation fulfill the address and data hold times to the write strobe and chip selects. During the trailing wait state period (for both read and write operations), the CPU is not held unless the CPU requests another access to the memories or peripherals on the expansion bus. If the WTWSOVR bit in the write control register is 0, there will be one implicit trailing wait state after a write operation. This means

that programming 0 or 1 in the TWS field in this register results in one trailing wait state after a write operation. If the WTWSOVR bit in the write control register is set to 1, the programmed value in the TWS field determines the number of trailing wait states for the write operation.

Bits [7:4] **WS.** Wait states (both read/write operations).

Each memory region can be programmed for up to 15 wait states. Each wait state lasts one SYSCLK cycle period.

Table 19 lists the encoding for the wait-state bits.

Table 19. Wait State Definition for Memory Bank0

Encoding	Number of Wait States
0000	0 [†]
0001	1
:	:
1111	15

[†] For devices with 470+ architecture, all expansion bus memory accesses are performed with a minimum of 1 wait state. Hence, for devices with 470+ architecture, if WS.3:0 = 0x00, then there is still 1 wait state. There are no other changes to this table for devices with 470+ architecture.

Bit 3 **END.** Endian mode.

This is a read-only bit and represents the endian mode of the CPU and the boot memory.

User and privilege mode (read):
 0 = CPU is in big endian mode.
 1 = CPU is in little endian mode.

Bit 2 **Reserved.**

The read/write values are indeterminate.

Bits [1:0] **DW.** Data width.

This field determines the data width of the memory region. Table 20 lists the bit encoding of this field.

User and privilege mode (read):
 Privilege mode (write)

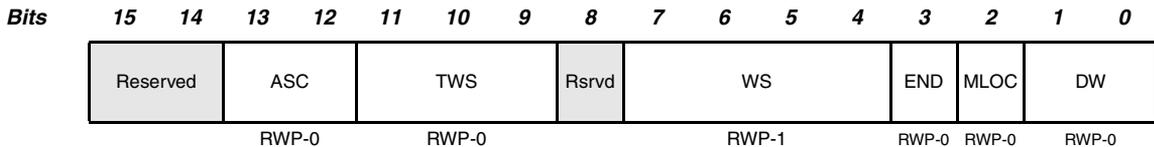
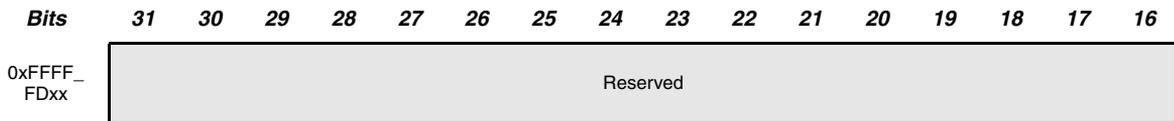
Table 20. Data Widths for Data Memory Bank0

Encoding	Mem Bank0 Data Width
00	8 bits
01	16 bits
10	32 bits
11	Reserved

9.3.2 Registers SMCR1-SMCR9

The register diagrams on the following pages describe the bits for registers SMCR1 through SMCR9. For descriptions of each bit or group of bits, refer to the above bit descriptions for register SMCR0 on page 72. Bits [2] and [3] for the registers in the following sections function differently to those in SMCR0. The register tables are listed below. The descriptions for these bits are shown below.

9.3.3 Static Memory Control Registers (SMCRx)



R = Read Only; RWP = Read in all modes, write in privilege mode only; -n = Value after reset

Bit 3 **END.** Endian mode.

Determines the endianism of the memory region associated with the corresponding chip select. When this bit is 0, the bytes are stored in big endian mode. When this bit is 1, the bytes are stored in little endian mode.

User and privilege mode (read):

Privilege mode (write):

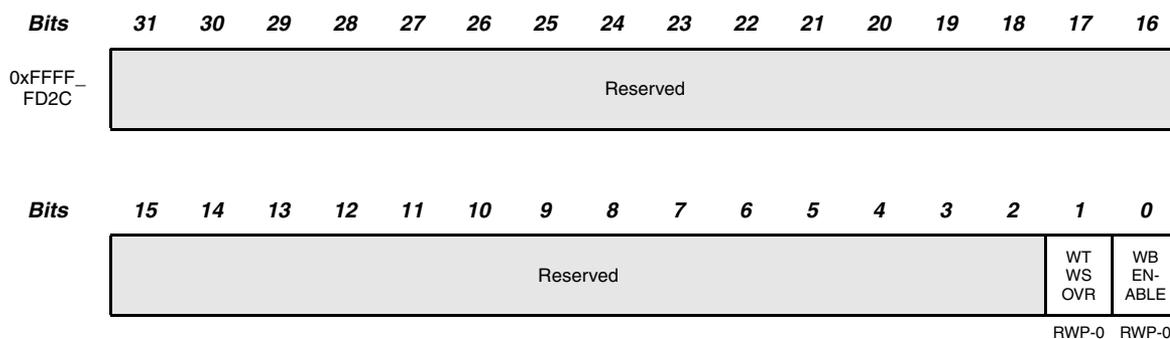
0 = Bytes are stored in big endian mode for this memory select only.

1 = Bytes are stored in little endian mode for this memory select only.

Bit 2 **MLOC.** Memory location.

Determines the location of the memory; that is, whether memory is connected to the internal expansion bus or an external expansion bus. This bit is used to sample the data from the associated data bus and to replace memory. When this bit is set for external memory the internal chip select is deasserted, and when set for internal memory, the external chip select is deasserted.

- 0 = The memory is on the internal expansion bus.
- 1 = The memory in on the external expansion bus.

9.4 Write Control Register (WCR0)

RWP = Read in all modes, write in privilege mode only; -n = Value after reset;

Bits [31:2] **Reserved.**

Reads are undefined and writes have no effect.

Bit 1 **WTWSOVR.** Write trailing wait state override.

When set to 1, there is no implicit trailing wait state after a write operation to the memories; the number of wait states is determined by the TWS bit field in the SMCRx register. When this bit is 0, there is always at least one trailing wait state on a write operation; if the TWS bit field in the SMCRx registers is non-zero, the trailing wait states are determined by the TWS bit field.

User and privilege mode (read):

Privilege mode (write):

- 0 = At least one trailing wait state
- 1 = TWS sets trailing wait states.

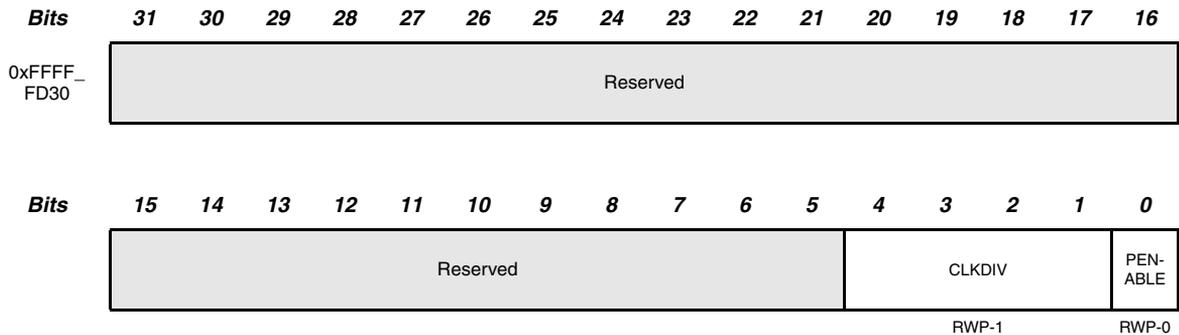
Bit 0 **WBENABLE.** Write buffer enable.

When this bit is set to 1, the memory controller latches the data and control signals in the first cycle for write operations to the memories and peripherals

on the expansion bus and lets the CPU perform other operations. However, the CPU starts a wait state if there is another request before the memory controller finishes.

User and privilege mode (read):
 Privilege mode (write):
 0 = Write buffer disabled
 1 = Write buffer enabled

9.5 Peripheral Clock Register (PCR)



RWP = Read in all modes, write in privilege mode only; -n = Value after reset;

Bits [31:5] Reserved.

Read/write values are indeterminate.

Bits [4:1] CLKDIV. Peripheral clock divided ratio.

Determine the division ratio for ICLK with respect to SYSCLK. Table 21 on page 77 describes the bit encoding for the ICLK/SYSCLK division ratios.

Table 21. Peripheral Clock Division Ratios

Bit Encoding	ICLK
0000	ICLK = SYSCLK
0001	ICLK = SYSCLK/2
0010	ICLK = SYSCLK/3
0011	ICLK = SYSCLK/4
0100	ICLK = SYSCLK/5
0101	ICLK = SYSCLK/6
0110	ICLK = SYSCLK/7
0111	ICLK = SYSCLK/8
1000	ICLK = SYSCLK/9
1001	ICLK = SYSCLK/10
1010	ICLK = SYSCLK/11
1011	ICLK = SYSCLK/12
1100	ICLK = SYSCLK/13
1101	ICLK = SYSCLK/14
1110	ICLK = SYSCLK/15
1111	ICLK = SYSCLK/16 (default at reset)

Bit 0**PENABLE.** Peripheral enable.

When this bit is set to 1, the peripheral reset is deasserted. After a reset the peripheral clock is SYSCLK /16.

The boot routine should set the CLKDIV field to the desired value before the PENABLE bit is set so that all the peripherals are in a reset state when the clock frequency is changed.

User and privilege mode (read):

Privilege mode (write):

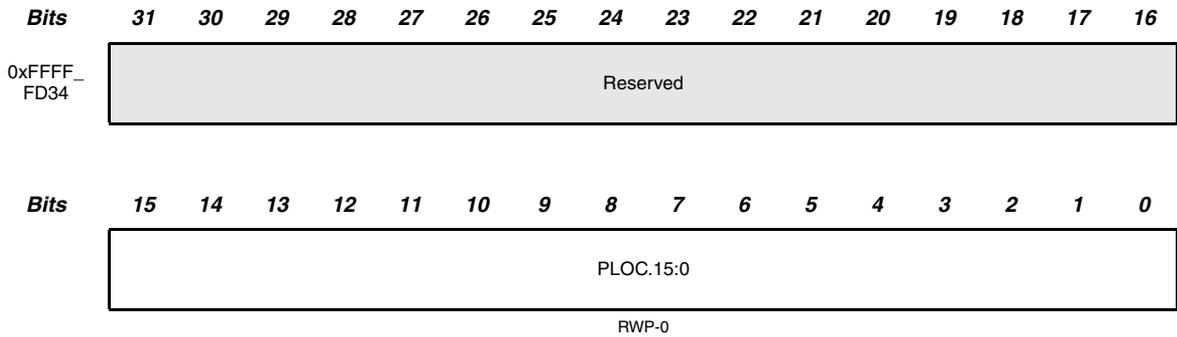
0 = Peripheral reset is asserted. (default at reset)

1 = Peripheral reset is deasserted.

Note: Peripherals not Accessible Until Enabled

User software must set the ICLK divider and then set PENABLE before peripherals can be accessed.

9.6 Peripheral Location Register (PLR)



RWP = Read in all modes, write in privilege mode only; -n = Value after reset;

Bits [31:16] Reserved.

Reads are undefined and writes have no effect.

Bits [15:0] PLOC.15:0. Peripheral location bits.

The 16 bits of this register correspond to the 16 peripheral selects. The mapping of peripherals to peripheral selects is device specific. (See the device-specific data sheet for details of which peripheral select is tied to which peripheral.)

Each bit corresponds to one peripheral select (bit 15 - PS[15]). The register configures peripherals as internal or external.

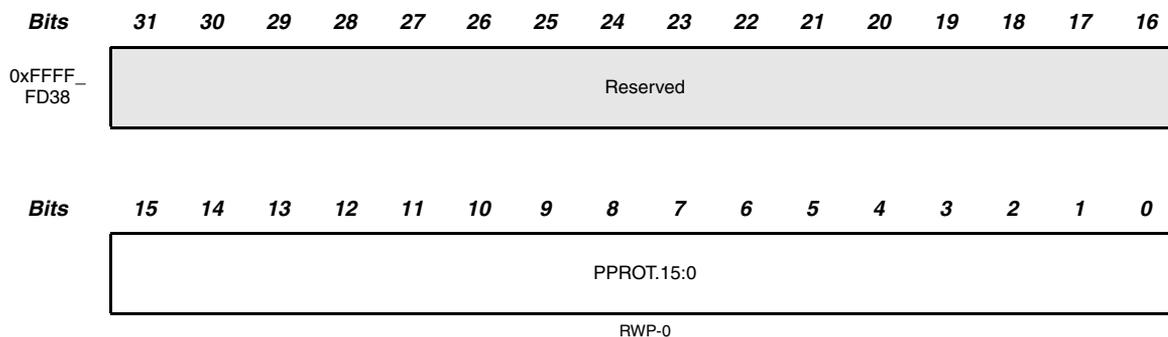
User and privilege mode (read):

Privilege mode (write):

0 = The peripheral is internal.

1 = The peripheral is external.

9.7 Peripheral Protection Register (PPROT)



RWP = Read in all modes, write in privilege mode only; -n = Value after reset;

Bits [31:16] Reserved.

Reads are undefined and writes have no effect.

Bits [15:0] PPROT.15:0. Peripheral protection bits.

The 16 bits of this register correspond to the 16 peripheral selects. The mapping of peripherals to peripheral selects is device specific. (See the device-specific data sheet for details of which peripheral select is tied to which peripheral.)

Each bit corresponds to one peripheral select (bit 15 - PS[15]). The register configures peripherals so that they may be accessed in user and privilege modes or in privilege mode only.

User and privilege mode (read):

Privilege mode (write):

0 = The peripheral is accessible in all modes.

1 = The peripheral is accessible in privilege mode.

9.8 Memory Fine Base Address Registers

This section describes all the control registers that need to be programmed for generating static memory selects and for providing memory protection. The structure of MFBAHR0 and MFBALR0 differs from the bit fields of the other MFBAHRx and MFBALRx registers.

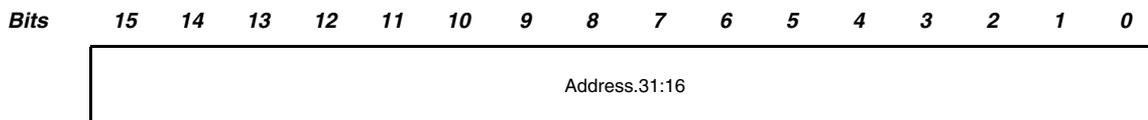
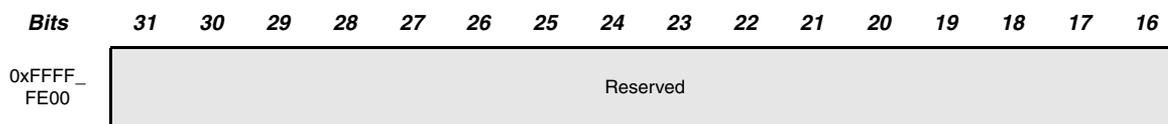
There are six sets of fine base address control registers. MFBALR0 has a slightly different structure from the other MFBALRx registers; for this reason, MFBAHR0 and MFBALR0 are discussed first. The control registers from

MFBAHR1 to MFBAHR5 and MFBALR1 to MFBALR5 have exactly the same structure. The register addresses are listed in Table 22.

Table 22. Fine Base Control Register Addresses

Register	Address
MFBAHR0	0xFFFF_FE00
MFBALR0	0xFFFF_FE04
MFBAHR1	0xFFFF_FE08
MFBALR1	0xFFFF_FE0C
MFBAHR2	0xFFFF_FE10
MFBALR2	0xFFFF_FE14
MFBAHR3	0xFFFF_FE18
MFBALR3	0xFFFF_FE1C
MFBAHR4	0xFFFF_FE20
MFBALR4	0xFFFF_FE24
MFBAHR5	0xFFFF_FE28
MFBALR5	0xFFFF_FE2C

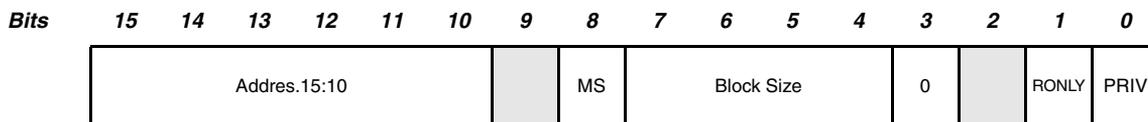
9.8.1 Memory Fine Base Address High Register 0 (MFBHR0)



RWP=0

R = Read in all modes, WP = Write in privilege mode only; -n = Value after reset

9.8.2 Memory Fine Base Address Low Register 0 (MFBALR0)



RWP=0

RWP=0

RWP=0

RWP=0

RWP=0

RWP=0

R = Read in all modes, WP = write in privilege mode only; -n = Value after reset

Bits [31:10] Address.31:10. Base address.

The base address sets the 22 most significant bits of a memory address. When the top bits of an addressed location match the bits programmed into the base address field, then this memory select is activated.

User and privilege mode (read):

Privilege mode (write):

Address.31:10 = Contains the top 22 bits of the memory base address for the memory select.

Bit 9 Reserved. Reads are undefined and writes have no effect.

Bit 8 MS. Memory-map select.

Memory-map select enables the fine and coarse bus address registers as memory selects and thereby activates the memory map.

User and privilege modes (read):

Privilege mode (write):

0 = Memory select 0 is active selecting the flash or ROM at 0x00 and mirrored throughout the bottom 2G bytes.

1 = All fine and coarse memory base address control registers are active.

Note: Memory-Map Select

All memory selects and associated wait states (SMCRx) should be configured before the memory map is enabled.

Bits [7:4] Block size.

The block size field determines the length of the memory selected by the memory-select bit. Table 23 lists the bit coding for the bit field.

Table 23. Block Size Bit Encoding (Fine Memory Selects)

Block Size Field	Block Size in Bytes	CPU Address Lines Compared
0000	Memory select is disabled.	
0001	1K	Address.[31:10]
0010	2K	Address.[31:11]
0011	4K	Address.[31:12]
0100	8K	Address.[31:13]
0101	16K	Address.[31:14]
0110	32K	Address.[31:15]
0111	64K	Address.[31:16]
1000	128K	Address.[31:17]
1001	256K	Address.[31:18]
1010	512K	Address.[31:19]
1011	1M	Address.[31:20]
1100	2M	Address.[31:21]
1101	4M	Address.[31:22]
1110	8M	Address.[31:23]
1111	16M	Address.[31:24]

-
- Bit 3** **Reserved.** Reserved for future use.
User must clear this bit to 0.
- Bit 2** **Reserved.**
Reads are undefined and writes have no effect.
- Bit 1** **RONLY.** Read-only protection.

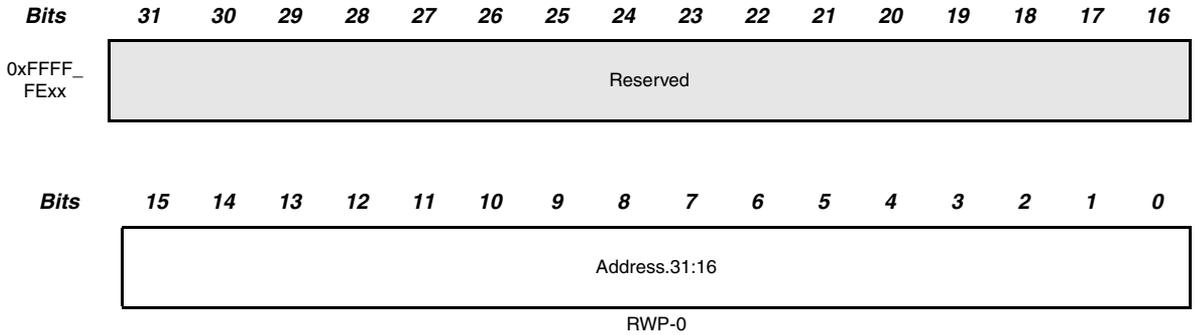
The RONLY bit sets read-only protection for the memory region selected by the memory select. An illegal access exception is generated when a write is attempted to the memory protected by read-only protection.

User and privilege modes (read):
Privilege mode (write):
0 = Read/write accesses to memory
1 = Read accesses to memory only
- Bit 0** **PRIV.** Privilege mode protection.

The PRIV bit sets privilege mode protection for the memory region selected by the memory select. An illegal access exception is generated on *any* access to memory protected by privilege mode protection if the CPU is in user mode.

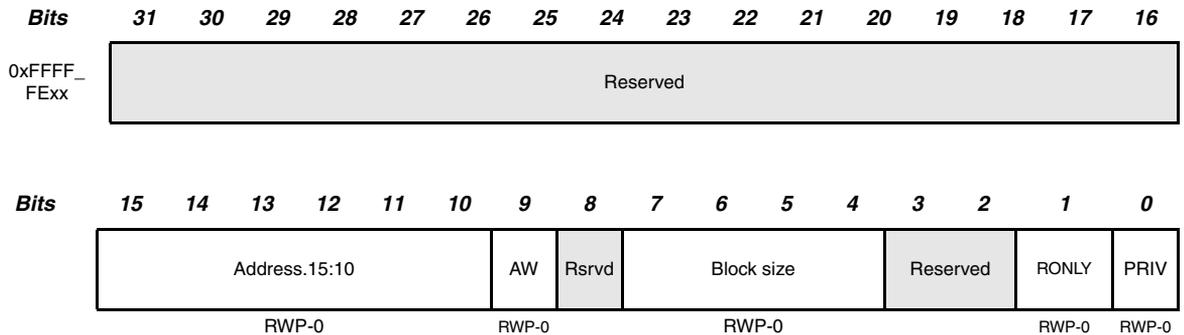
User and privilege modes (read):
Privilege mode (write):
0 = User/privilege mode accesses to memory
1 = Privilege mode accesses to memory only

9.8.3 Memory Fine Base Address High Register (MFBHRx)



R = Read in all modes, WP = Write in privilege mode only; -n = Value after reset

9.8.4 Memory Fine Base Address Low Register (MFBALRx)



R = Read in all modes, WP = Write in privilege mode only; -n = Value after reset

Bit 9 AW. Auto-wait-on-write.

When this bit is set, any write operation on this memory select takes two system cycles.

0 = The write operation is not supplemented with an additional cycle.

1 = The write operation takes an additional cycle.

The auto-wait-on-write bit AW (MFBALRx.8 and MCBALRx.8 [except MFBALR0]) holds the CPU for one cycle during a write operation. The auto-wait-on-write is intended to support memories that latch address, select, and read/write signals on the same clock edge. This bit should **not** be used for expansion bus memory accesses.

9.9 Memory Coarse Select Control Registers

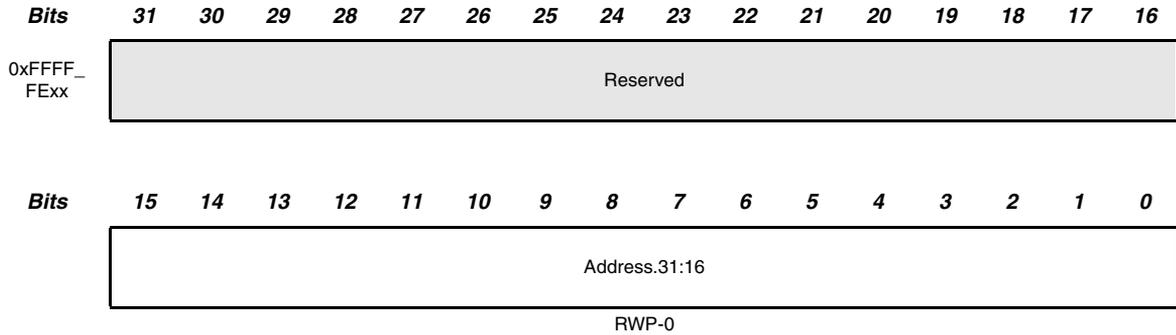
This section describes all the control registers which need to be programmed to generate chip-select signals and to provide protection for the memory associated with these coarse selects.

There are six sets of coarse base address control registers. The control registers from MCBADR0 to MCBADR5 and MCBALR0 to MCBALR5 have exactly the same structure. The starting address for each register is listed in Table 24.

Table 24. Coarse Base Control Register Addresses

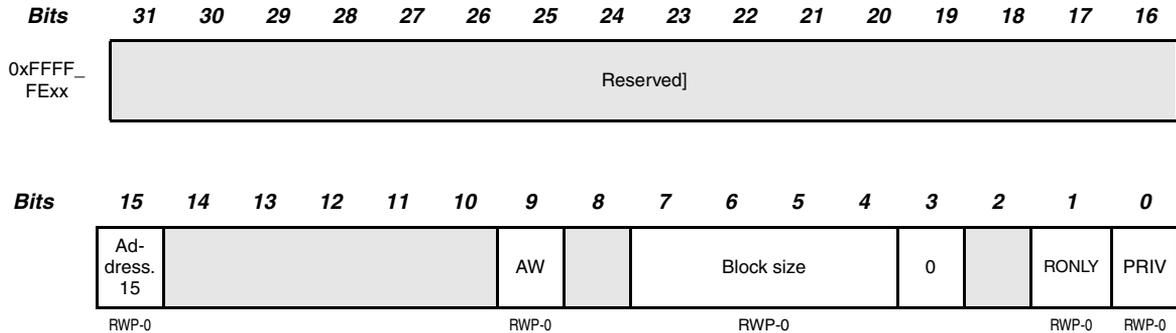
Register	Address
MCBAHR0	0xFFFF_FE30
MCBALR0	0xFFFF_FE34
MCBAHR1	0xFFFF_FE38
MCBALR1	0xFFFF_FE3C
MCBAHR2	0xFFFF_FE40
MCBALR2	0xFFFF_FE44
MCBAHR3	0xFFFF_FE48
MCBALR3	0xFFFF_FE4C
MCBAHR4	0xFFFF_FE50
MCBALR4	0xFFFF_FE54
MCBAHR5	0xFFFF_FE58
MCBALR5	0xFFFF_FE5C

9.9.1 Memory Coarse Base Address High Register (MCBAHRx)



R = Read in all modes, WP = Write in privilege mode only; -n = Value after reset

9.9.2 Memory Coarse Base Address Low Register (MCBALRx)



R = Read in all modes, WP = Write in privilege mode only; -n = Value after reset

Bits [31:15] Address.31:15. Base address.

This base address sets the 17 most significant bits of a memory address. When the top bits of an addressed location match the bits programmed into the base address field, then this memory select is activated.

User and privilege mode (read):
Privilege mode (write):

Address.31:15 = Contains the top 17 bits of the memory base address for the memory select.

Bits [14:10] Reserved.

Reads are undefined and writes have no effect.

-
- Bit 9** **AW.** Auto-wait-on-write.
- When set, any write operation on this memory select takes an additional system cycle.
- 0 = The write operation is completed in one cycle.
1 = The write operation takes one additional cycle.
- The auto-wait-on-write bit AW (MFBALRx.8 and MCBALRx.8 [except MFBALR0]) holds the CPU for one cycle during a write operation. The auto-wait-on-write is intended to support memories that latch address, select, and read/write signals on the same clock edge. This bit should **not** be used for expansion bus memory accesses.
- Bit 8** **Reserved.**
- Reads are undefined and writes have no effect.
- Bits [7:4]** **Block size.**
- The block size field determines the length of the memory selected by the memory select bit. Table 25 lists the bit coding for the bit field.

Table 25. Block Size Bit Encoding (for Coarse Selects)

Block Size Field	Block Size in Bytes	CPU Address Bus Lines Compared
0000	Disables memory select	
0001	32K	Address.32:15
0010	64K	Address.32:16
0011	128K	Address.32:17
0100	256K	Address.32:18
0101	512K	Address.32:19
0110	1M	Address.32:20
0111	2M	Address.32:21
1000	4M	Address.32:22
1001	8M	Address.32:23
1010	16M	Address.32:24
1011	32M	Address.32:25
1100	64M	Address.32:26
1101	128M	Address.32:27
1110	256M	Address.32:28
1111	512M	Address.32:29

Bit 3 **Reserved.** Reserved for future use.

You must clear this bit to 0.

Bit 2 **Reserved.**

Reads are undefined and writes have no effect.

Bit 1 **RONLY.** Read-only protection.

The RONLY bit sets read-only protection for the memory region selected by the memory select. An illegal access exception is generated when a write is attempted to the memory protected by read-only protection.

User and privilege modes (read):

Privilege mode (write):

0 = Read/write accesses to memory

1 = Read accesses to memory only

Bit 0 **PRIV.** Privilege mode protection.

The PRIV bit sets privilege mode protection for the memory region selected by the memory select. An illegal access exception is generated on any access to memory protected by privilege mode protection if the CPU is in user mode.

User and privilege modes (read):

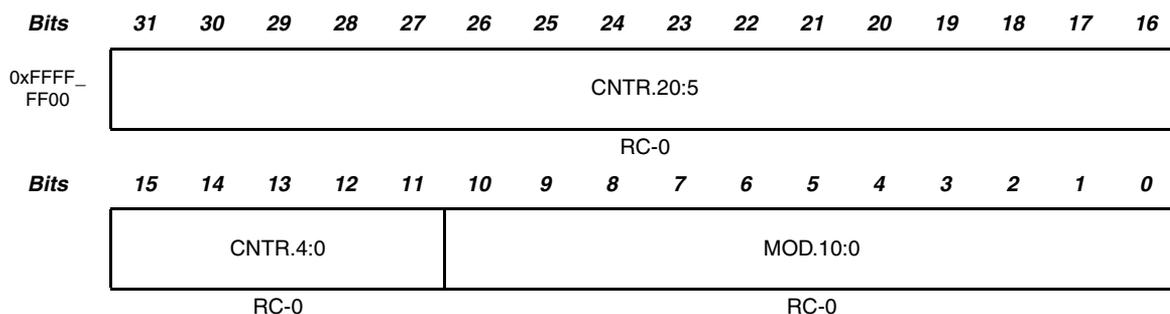
Privilege mode (write):

0 = User/privilege mode accesses to memory

1 = Privilege mode accesses to memory only

9.10 RTI Counter (RTICNTR)

The RTICNTR must be accessed with a word access. The RTI counter contains two separate counters. MOD counts down from the preload value (RTIPCTL) to 0. When MOD reaches 0, CNTR is incremented and PRELD is reloaded into MOD. MOD counts down and CNTR counts up.



R = Read in any mode, C = Clear in privileged mode only; -n = Value after reset

Bits [31:11] **CNTR.20:0.** RTI Counter (counts up).

User and privilege mode (read):

Tap and Compare interrupts are generated off this counter. Write access to the RTICNTR will clear the CNTR (21 bit counter) and will cause a Tap interrupt if the corresponding bit switches from a "1" to a "0". Therefore, disable the RTI prior to changing the RTICNTR value. See Section Table 6., *RTI Operating Modes*, on page 30 for details of how to compute clock cycles.

Privilege mode (write):

Any write resets the register.

Bits [10:0] **MOD.10:0.** RTI module down counter.

User and privilege mode (read):

Represents the current value of the modulo M counter within the RTI. See Section Table 6., *RTI Operating Modes*, on page 30 for details of how to compute clock cycles.

Privilege mode (write):

Any write resets the register and the preload value is loaded into MOD.

The values of both counters are read simultaneously as a 32-bit word. However, keep in mind that they are not a single 32-bit number but two numbers of 21 bits and 11 bits, respectively. Furthermore, the modulo M counter is a down counter. Both counters do not stop while the device is in normal operating modes. The counters are cleared by a system reset. The counters are also cleared by a write to RTINCTR; a write resets CNTR and resets MOD to the preload value.

9.11 RTI Preload Control Register (RTIPCTL)

The RTI preload control register contains the preload value loaded into MOD (RTICNTR) and the tap select.



R = Read in all modes, *WP* = write in privileged mode only; *-n* = Value after reset

Bits [31:14] **Reserved.**

Reads are undefined and writes have no effect.

Bits [13:11] **RTIM.2:0.** Tap select.

User and privilege mode (read):

Privilege mode (write):

Configures tap select for the count-up counter (CNTR), as shown in Table 26.

Table 26. Tap Interrupts

RTIM.2:0		Tap Bit	Tap Value
000	CNTR.20	RTICNTR.31	2097152
001	CNTR.17	RTICNTR.28	262144
010	CNTR.14	RTICNTR.25	32768
011	CNTR.11	RTICNTR.22	4096
100	CNTR.8	RTICNTR.19	512
101	CNTR.5	RTICNTR.16	64
110	CNTR.2	RTICNTR.13	8
111	Underflow	Underflow	1

Bits [10: 0] **PRELD.** Modulo M of preload value.

User and privilege mode (read):

Privilege mode (write):

Holds the preload value M for the Modulo M counter. When the modulo M counter counts to 0, PRELD[10:0] is automatically loaded into the MOD counter. If the preloaded value is changed, it is recommended that RTICNTR be written to so that it is cleared to ensure the module keeps the correct time.

9.12 RTI Control Register (RTICNTL)

The RTI control register contains the tap enable and tap flag.



R = read in all modes, W = Write in all modes; C = Clear; -n = Value after reset

Bits [31:8] **Reserved.**

Reads are undefined and writes have no effect/

Bit 7 **TAPFLAG.** Tap interrupt flag bit.

The tap flag indicates that the transition edge (high-to-low) has occurred on the selected tap bit of the CNTR. Once active, this bit remains set until cleared.

User and privilege mode (read):

0 = Transition has not occurred since last clear.

1 = Transition has occurred since last clear.

Privilege mode (write):

0 = Clears the bit

1 = Has no effect

Bit 6 **TAPENA.** Tap interrupt enable bit.

Enables Tap interrupt.

User and privilege mode (read):

Privilege mode (write):

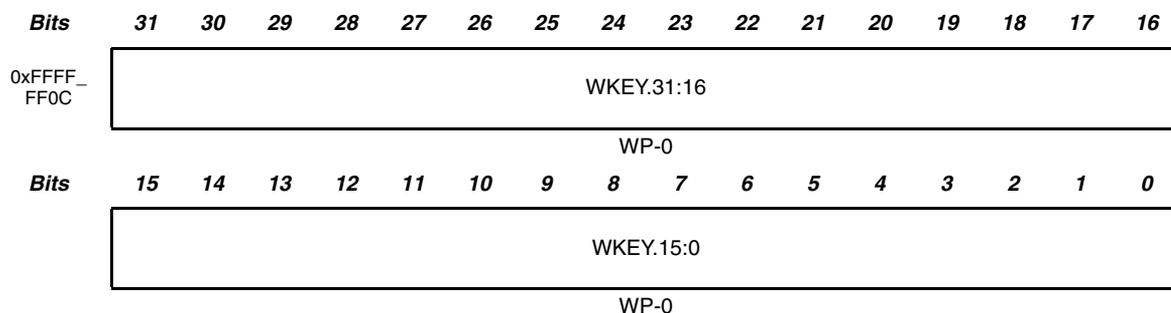
0 = Tap does not generate an interrupt request

1 = Tap does generate an interrupt request

Bits [5:0] **Reserved.**

Reads are undefined and writes have no effect.

9.13 Watchdog Key Register (WKEY)



WP = Writable in privilege mode only; -n = Value after reset

Bits [31:0] **WKEY.31:0.** Key Sequence location.

User and privilege mode (read):
Reads are indeterminate.

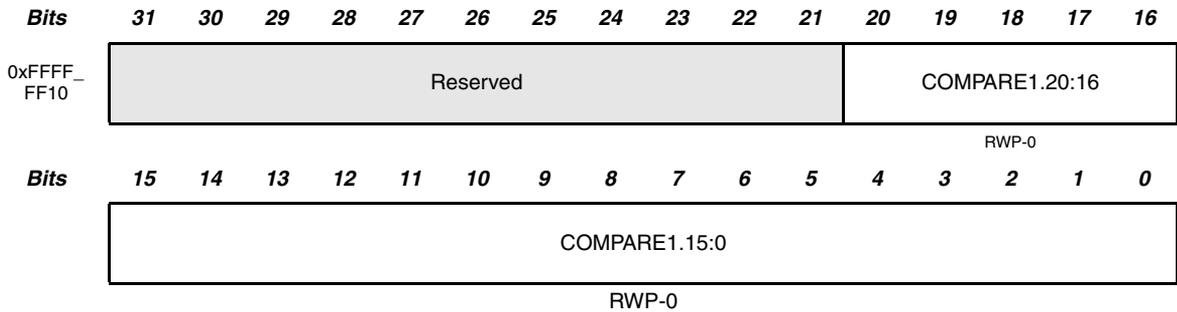
Privilege mode (write):

A write of 0xE5 followed by 0xA3 in two separate write operations defines the Key Sequence and discharges the watchdog capacitor. Writing any other value causes a digital watchdog reset, as shown in Table 27.

Table 27. Example of a WKEY Sequence

Step	Value Written to WKEY	Result
1	0x0A3	No action
2	0x0A3	No action
3	0x0E5	WKEY is enabled for reset by the next 0x0A3.
4	0x0E5	WKEY is enabled for reset by the next 0x0A3.
5	0x0E5	WKEY is enabled for reset by the next 0x0A3.
6	0x0A3	Watchdog is reset.
7	0x0A3	No action
8	0x0E5	WKEY is enabled for reset by the next 0x0A3.
9	0x0A3	Watchdog is reset.
10	0x0E5	WKEY is enabled for reset by the next 0x0A3.
11	0x023	System reset; incorrect value written to WKEY

9.14 RTI Compare Register 1(RTICMP1)



R = Read in all modes, WP = Write in privilege mode only; -n = Value after reset

Bits [31:21] Reserved.

Reads are undefined and writes have no effect.

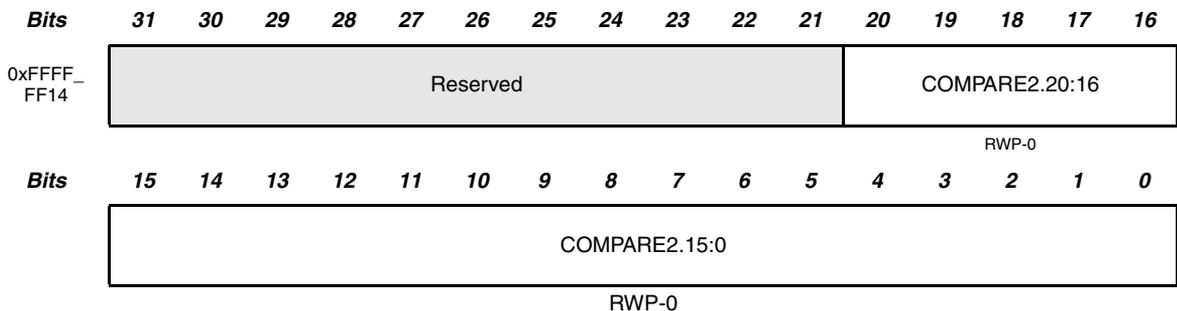
Bits [20:0] COMPARE1. Compare value 1.

Value to be compared with CNTR[31:11]. When the value in CNTR[31:11] matches the value in COMPARE1[20:0], CF1 is set. The flag remains set until cleared.

User and privilege (read):
Privilege mode (write):

Compare value

9.15 RTI Compare Register 2(RTICMP2)



R = Read in all modes, WP = Write in privilege mode only; -n = Value after reset

Bits [31:21] Reserved.

Reads are undefined and writes have no effect.

Bits [20:0] **COMPARE2.20:0.** Compare value 2.

Value to be compared with CNTR.31:11. Once the value in CNTR.31:11 matches the value in COMPARE2.20:0, CF2 is set. The flag remains set until cleared.

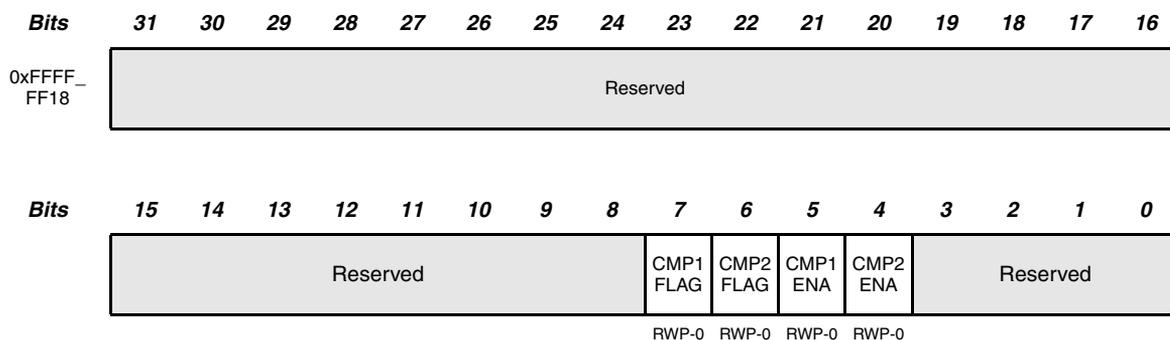
User and privilege (read):

Privilege mode (write):

Compare value

9.16 Compare Interrupt Control Register (RTICINT)

The RTI compare interrupt control register contains flags and enables for the compare interrupts.



R = Read in all modes, WP = Write in privilege mode only; -n = Value after reset

Bits [31:8] **Reserved.**

Reads are undefined and writes have no effect.

Bit 7 **CMP1 FLAG.** Compare 1 Interrupt flag.

The CMP1 flag indicates that the CNTR value equals the value set in RTICMP1. Once active, this bit remains set until cleared.

User and privilege mode (read):

0 = Equality compare has not occurred since last clear.

1 = Equality compare has occurred since last clear.

Privilege mode (write):

0 = Clears the bit.

1 = Has no effect.

Bit 6 **CMP2 FLAG.** Compare 2 Interrupt flag.

The CMP2 flag indicates that the CNTR value equals the value set in RTICMP2. Once active, this bit remains set until cleared.

User and privilege mode (read):

0 = Equality compare has not occurred since last clear.

1 = Equality compare has occurred since last clear.

Privilege mode (write):

0 = Clears the bit.

1 = Has no effect.

Bit 5 **CMP1 ENA.** Compare 1 enable.

Enables the compare 1 register.

User and privilege mode (read):

Privilege mode (write):

0 = CMP1 does not generate an interrupt request.

1 = CMP1 generates an interrupt request.

Bit 4 **CMP2 ENA.** Compare 2 Interrupt enable.

Enables the compare 2 interrupt register.

User and privilege mode (read):

Privilege mode (write):

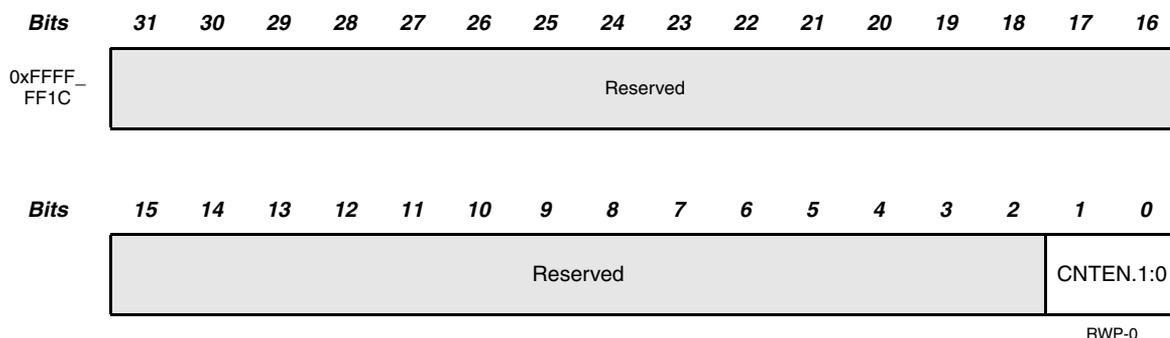
0 = CMP1 does not generate an interrupt request.

1 = CMP1 generates an interrupt request.

Bits [3:0] **Reserved.**

Reads are undefined and writes have no effect.

9.17 RTI Count Enable Register (RTICNTEN)



R = Read in all modes, WP = Write in privilege mode only; -n = Value after reset

Bits [31:2] Reserved.

Reads are undefined and writes have no effect.

Bits [1:0] CNTEN.1:0.

Based on the CPU operating mode, allows the MOD and CNTR counters (RTICNTR) within the RTI to count or not. Table 28 lists the CPU modes in which count activity is allowed to occur.

User and privilege mode (read):

Privilege mode (write):

Table 28. Real-Time Interrupt Counter Enable Modes

CNTEN1	CNTEN0	Count
0	0	User/privilege
0	1	Privilege only
1	0	User only
1	1	No count

9.18 CIM Offset Vector Registers

The CIM offset register provides the user with the numerical index value that represents the pending interrupt with the highest precedence. (IRQIVEC holds the index to the highest priority IRQ interrupt; FIQIVEC holds the index to the highest priority FIQ interrupt; and CIMIVEC holds the index to the highest priority interrupt based on the state of the CPU). The index can be

used to locate the interrupt routine in a dispatch table, as shown in Table 29. Reading any of these registers clears the interrupt flag as well as the offset.

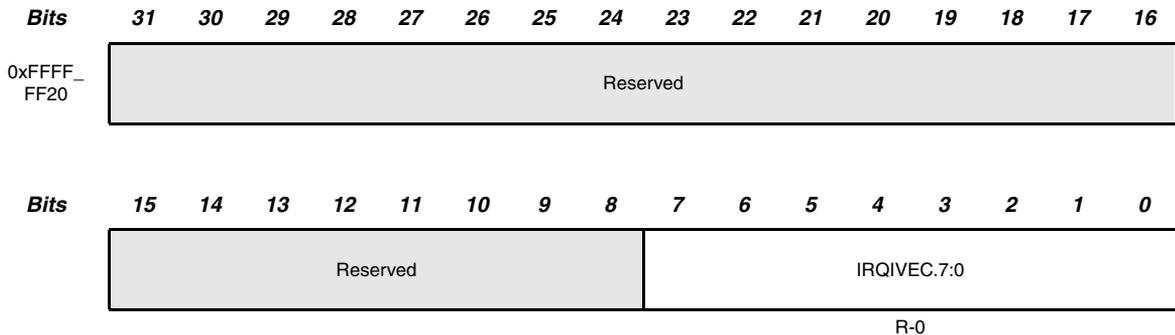
Table 29. Interrupt Dispatch Table

IVEC Index	Pending Interrupt
0x00	No interrupt
0x01	Channel 0
:	:
0x20	Channel 31

The CIM offset registers are read only. They are updated continuously by the CIM. Once the interrupt is serviced, the offset vectors show the index for the next highest pending interrupt or if no interrupt is pending, 0x00.

9.18.1 IRQ Index Offset Vector Register (IRQIVEC)

The IRQ offset register provides the user with the numerical index value that represents the highest priority, pending IRQ interrupt.



R = Read only; -n = Value after reset

Bits [31:8] Reserved.

Reads are undefined and writes have no effect.

Bits [7:0] IRQIVEC.7:0. Index vector.

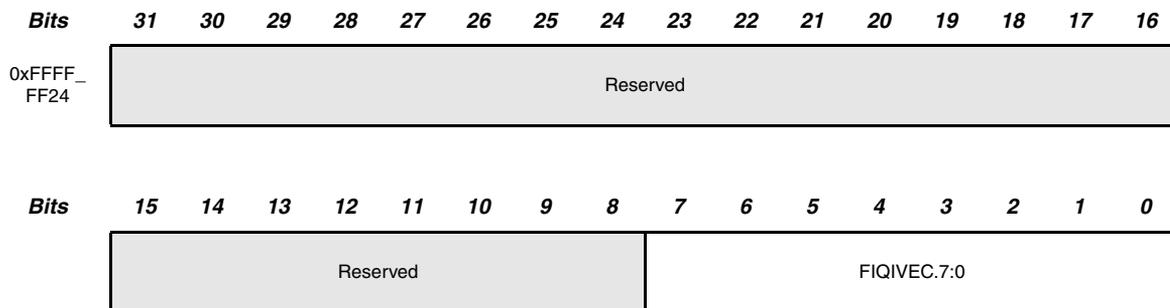
User and privilege mode (read):

The least significant bits represent the index of the IRQ pending interrupt with the highest precedence, as shown in Table 29. When no interrupts are pending, the least significant byte of IRQIVEC is 0x00. A read clears the offset and the pending interrupt flag.

User and privilege mode (write):
Writes have no effect.

9.18.2 FIQ Index Offset Vector Registers (FIQIVEC)

The FIQIVEC register provides the user with a numerical index value that represents the highest priority pending FIQ interrupt.



R-0

R = Read only; -n = Value after reset

Bits [31:8] **Reserved.**

Reads are undefined and writes have no effect.

Bits [7:0] **FIQIVEC.7:0.** Index vector.

User and privilege mode (read):

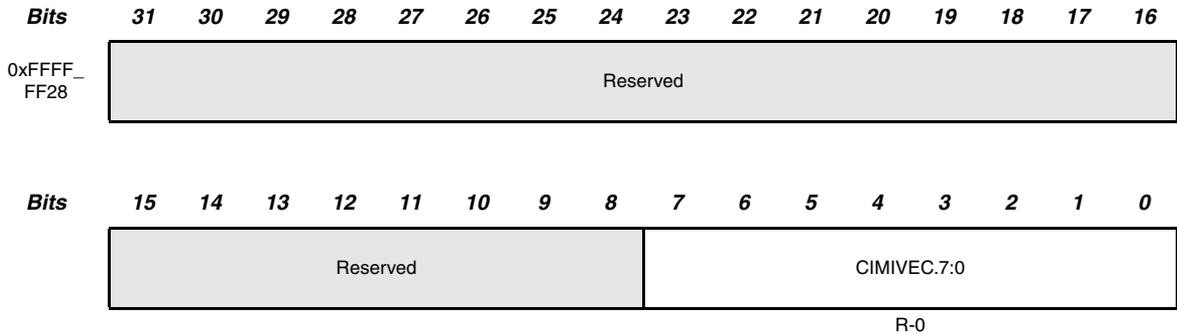
The least significant bits represent the index of the FIQ pending interrupt with the highest precedence, as shown in Table 29. When no interrupts are pending, the least significant byte of FIQIVEC is 0x00. A read clears the offset and the pending interrupt flag.

User and privilege mode (write):

Writes have no effect.

9.18.3 CIM Index Offset Vector Register (CIMIVEC)

The CIMIVEC offset register provides the user with the numerical index value that represents the highest priority pending interrupt. The CIMIVEC returns the highest priority IRQ interrupt when the CPU is in IRQ mode, and the CIMIVEC returns the highest priority FIQ interrupt when the CPU is in FIQ mode.



R = Read only; -n = Value after reset

Bits [31:8] **Reserved.**

Reads are undefined and writes have no effect.

Bits [7:0] **CIMIVEC.7:0.** Index vector.

User and privilege mode (read):

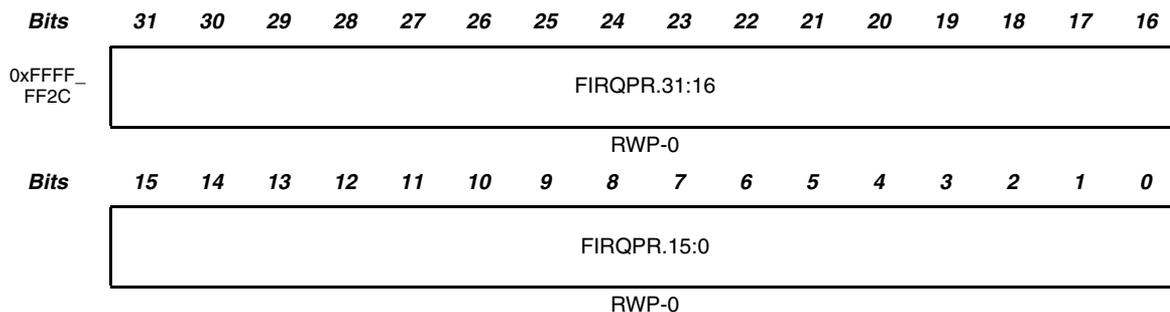
The least significant bits represent the index of the pending interrupt with the highest precedence, as shown in Table 29. When no interrupts are pending, the least significant byte of CIMIVEC is 0x00. A read clears the offset and the pending interrupt flag.

User and privilege mode (write):

Writes have no effect.

9.19 FIQ/IRQ Program Control Register (FIRQPR)

A 32-bit FIQ/IRQ program control register (FIRQPR) determines whether a given interrupt request will be FIQ or IRQ type.



R = Read in all modes, WP = Writable in privilege mode only; -n = Value after reset

Bits [31:0] FIRQPR.31:0. FIQ/IRQ program control bits.

These bits determine whether an interrupt request from a peripheral is of type FIQ or IRQ. Each bit corresponds to one request channel.

User and privilege mode (read):

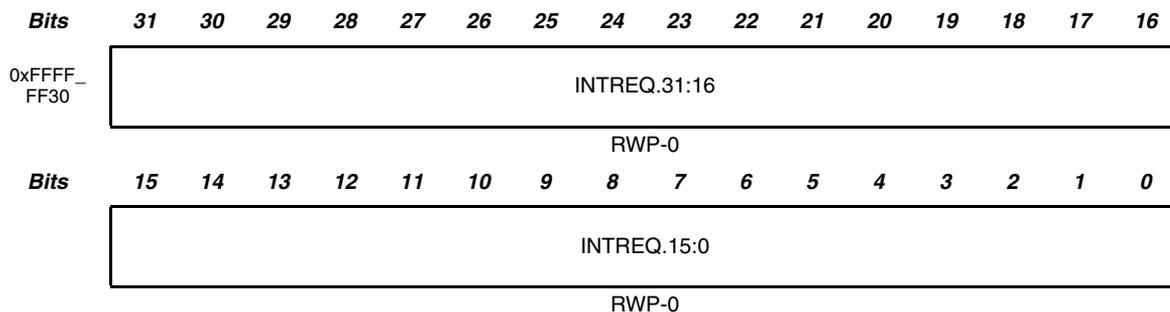
Privilege mode (write):

0 = Interrupt request is of IRQ type.

1 = Interrupt request is of FIQ type.

9.20 Pending Interrupt Read Location (INTREQ)

The pending interrupt register gives the pending interrupt requests. The register is updated every SYSCLK cycle.



R = Read in all modes, WP = Writable in privilege mode only; -n = Value after reset

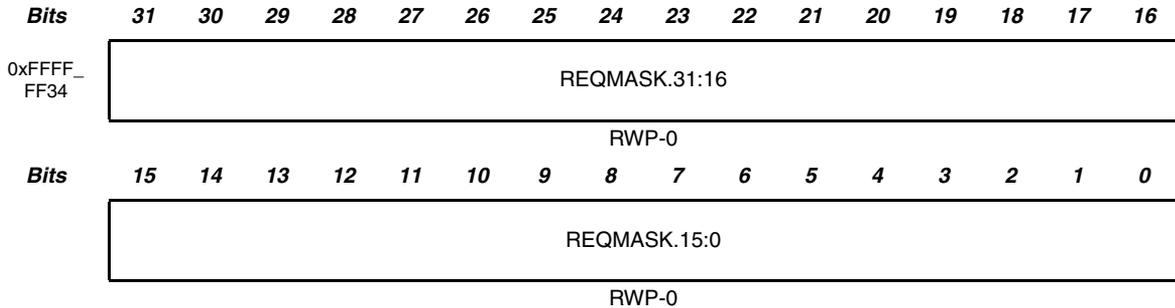
Bits [31:0] INTREQ.31:0. Pending interrupt bits.

Determines whether an interrupt request is pending.

User and privilege mode (read):
 Privilege mode (write):
 0 = No interrupt event has occurred.
 1 = Interrupt is pending.

9.21 Interrupt Mask Register (REQMASK)

The interrupt register mask selectively disables individual request channels.



R = Read in all modes, WP = Writable in privilege mode only; -n = Value after reset

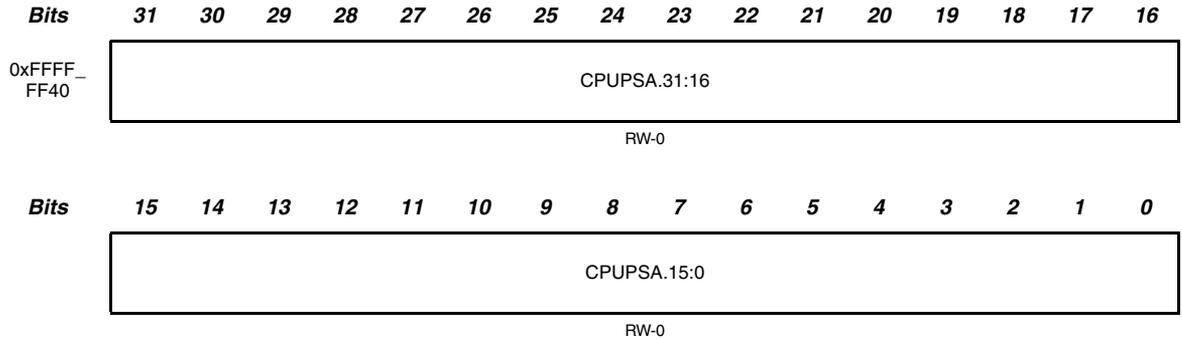
Bits [31:0] REQMASK.31:0. Request mask bits.

This vector determines whether the interrupt request channel is enabled.

User and privilege mode (read):
 Privilege mode (write):
 0 = Interrupt request channel is disabled.
 1 = Interrupt request channel is enabled.

9.22 CPU Data Bus Parallel Signature Analysis Register (CPUPSA)

The CPU data bus parallel signature analysis contains the original send value. During and after the PSA runs, CPUPSA contains the current signature.



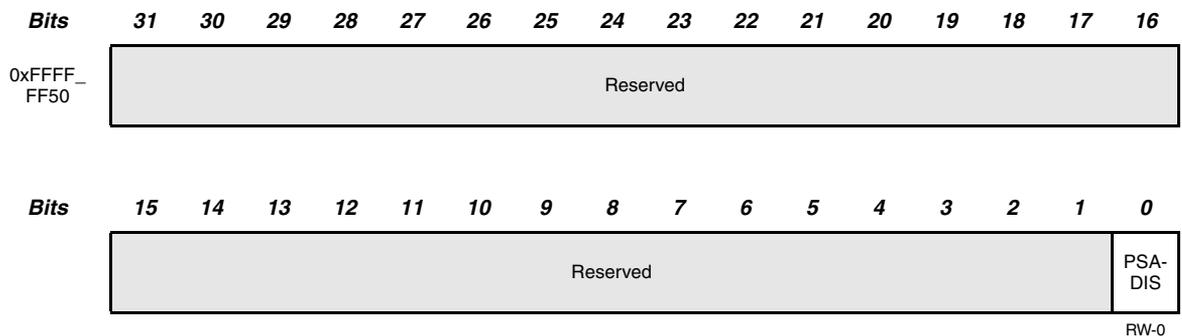
RW = Read/write; -n = Value after reset

Bits [31:0] **CPUPSA.31:0.** Contains the current signature result.

To initialize the PSA, a seed value must first be written. Based on the current data on the CPU bus, a signature value is generated. This value can then be compared to expected signature values (usually generated by an external tool).

9.23 PSA Enable (PSAENABLE)

The least significant bit (PSADIS) enables the PSA.



RW = Read/write; -n = Value after reset

Bits [31:1] **Reserved.**

Reads are undefined and writes have no effect.

Bit 0

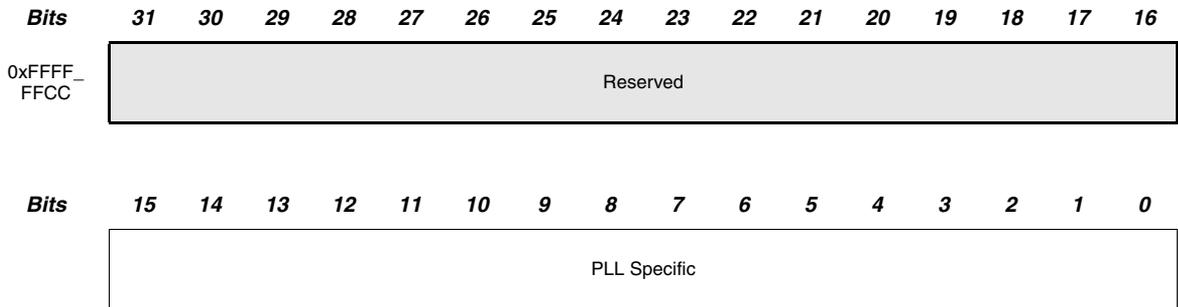
PSADIS.

Enables the corresponding PSA module

0 = PSA enabled

1 = PSA disabled

9.24 New Global Control Register (GCR_N)



RW = Read/write; -n = Value after reset

Bits[32:14] Reserved

Reads are undefined and writes have no effect.

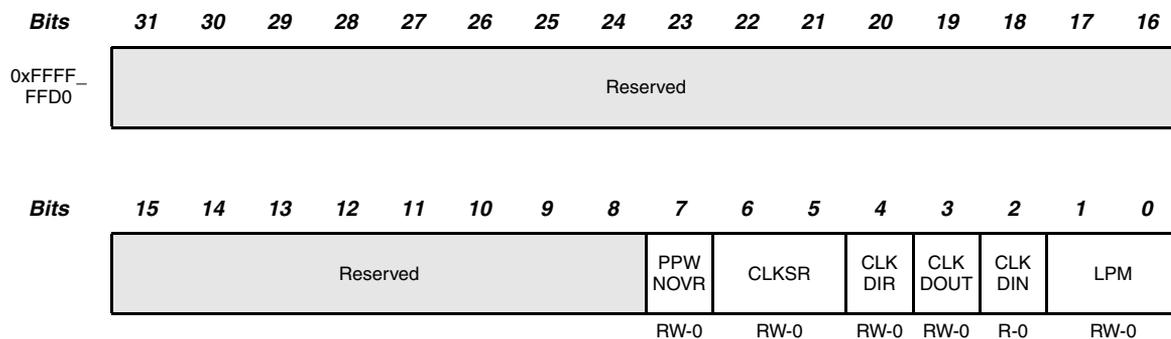
Bits [15:0] PLL Specific.

See the specific PLL user guide document for additional details on the PLL-specific bits.

9.25 Clock Control Register (CLKCNTL)

The clock control register configures the CLKOUT pin and a bit that controls the module low power mode.

CLKCNTL is accessible in user and privilege mode and supports byte, half-word, and word accesses. Any access to this register takes two SYSCLK cycles.



R = Read in all modes, W = Write in all modes.; -n = Value after reset

Bits [31:8] **Reserved.**

Reads are undefined and writes have no effect.

Bit 7 **PPWNOVR.** Peripheral power down enable.

The PPWNOVR enables the power down of clocks to the control registers of the module. The PPWNOVR bit works with the power-down bit in a given module. Typically, when the module is powered down via the module level bit, the clocks to the module's logic stop; when the module is powered down and PPWNOVR is set, the clocks to both the logic and the control registers are stopped. To manually wake a module, the PPWNOVR must be cleared and the power-down bit at the module must be serviced.

User and privilege mode (read/write):

0 = All peripheral control registers are clocked.

1 = Control registers of the peripherals that are powered down are not clocked.

Bits [6:5] CLKSR. Clock source bits.

Controls the source/function of the CLKOUT pin. (See Table 30.) The possible configurations for the CLKOUT pin are as follows:

User and privilege mode (read/write):

- 00 = Configured as a digital input/output pin
- 01 = Driven by the interface clock (ICLK)
- 10 = Driven by the CPU clock (MCLK)
- 11 = Driven by the system clock (SYSCLK)

Bit 4 CLKDIR. CLKOUT pin direction.

If the CLKOUT pin is selected as a digital I/O pin, this bit determines whether the CLKOUT pin is an input or output pin; otherwise this bit has no effect. (See Table 30.)

User and privilege mode (read/write):

- 0 = CLKOUT pin is configured as an input.
- 1 = CLKOUT pin is configured as an output.

Bit 3 CLKDOUT. CLKOUT output pin data.

If the CLKOUT pin is configured as a digital I/O and as an output pin (CLKSR=0x00 and CKDIR=1), This bit will place either a logic value 0 or 1 to the pin; otherwise this bit has no effect. (See Table 30.)

User and privilege mode (read/write):

- 0 = Logic low (output voltage on CLKOUT is V_{OL} or lower)
- 1 = Logic high (output voltage on CLKOUT is V_{OH} or higher)

Bit 2 CLKDIN. CLKOUT input pin data.

If the CLKOUT pin is configured as a digital I/O and as an input pin (CLKSR = 0x00 and CKDIR = 0), this bit represents the logic value on the pin; otherwise, this bit has no effect. (See Table 30.)

User and privilege mode (read):

- 0 = Logic low (input voltage on CLKOUT is V_{IL} or lower)
- 1 = Logic high (input voltage on CLKOUT is V_{IH} or higher)

User and privilege mode (write):

Writes have no effect.

Table 30. CLKOUT Values

	CLK SR.1	CLK SR.0	CLK DIR	CLKD OUT	CLKD IN [†]
CLKOUT (ICLK)	0	1	X	X	X
CLKOUT (MCLK)	1	0	X	X	X
CLKOUT (SYSCLK)	1	1	X	X	X
General-purpose input	0	0	0	X	X
General-purpose output, low	0	0	1	0	X
General-purpose output, high	0	0	1	1	X

† CLKDIN is a read-only bit. Its value always reflects the level on the CLKOUT pin.

Bits [1:0] LPM. Low-power mode bits.

Determines the different low-power operating modes (see Table 30). For more information on the clock domains and low-power mode, see Section 7, *Clocks*, on page 43.

User and privilege mode (read/write):

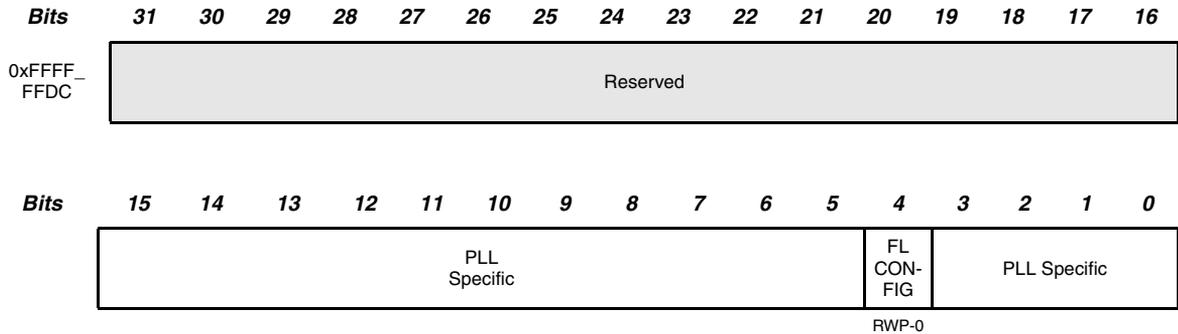
Table 31. Wake-up Interrupt Reset Modes

Mode	LPM.1:0	
	LPM.1	LPM.0
Run	0	0
Idle	0	1
Standby	1	0
Halt	1	1

9.26 Global Control Register (GLBCTRL)

The global control register controls the PLL and one bit that configures the flash. See the specific PLL user guide document for additional details on the PLL specific bits.

Further, any write to this register asserts three wait states.



R = Read in all modes, WP = write in privilege mode only; -n = Value after reset

Bits [31:16] Reserved.

Reads are undefined and writes have no effect.

Bits [15:5] PLL Specific.

See the specific PLL user guide document for additional details on the PLL-specific bits.

Bit 4 FLCONFIG. Flash configuration mode bit.

Controls write access to the flash wrapper's control registers. See the flash wrapper user specification for details on the flash wrapper's control registers.

User and privilege mode (read):

Privilege mode (write):

0 = No read or write access allowed; read or write access to the flash control registers generates an illegal address exception.

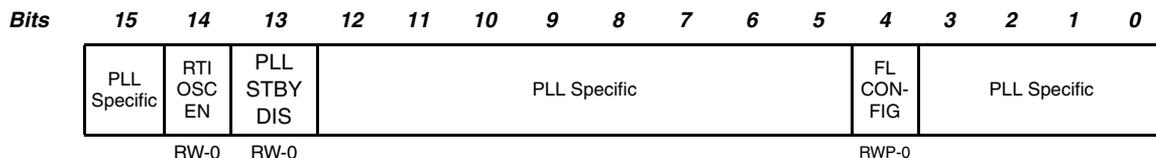
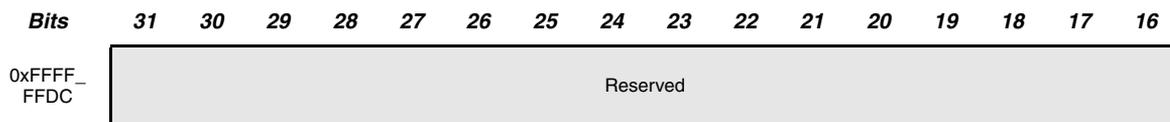
1 = Allows read or write access to flash wrapper's control register

Bit [3:0] PLL Specific.

See the specific PLL user guide document for additional details on the PLL-specific bits

Note: Device with Enhanced RTI

On a device with an enhanced RTI, the RTI may be clocked at OSCIN or SYSClk frequencies. Additionally, the PLL may be disabled during stand-by. (See the device-specific data sheet regarding enhanced RTI.)



R = Read in all modes, WP = write in privilege mode only; -n = Value after reset

Bits 15 **PLL Specific.**

See the specific PLL user guide document for additional details on the PLL-specific bits.

Bits 14 **RTI OSC EN.** RTI Oscillator Enable.

When this bit is set, the RTI will run using the clock generated by the oscillator. This bit is implemented only on the Enhanced RTI Module. (See the device-specific data sheet to see if this feature has been implemented).

User and privilege mode (read/write):

- 0 = This is the default state for the bit. The RTI is clocked directly from the clock control module at system clock speed.
- 1 = The RTI is clocked directly from the oscillator.

Bits 13 **PLL STBY DIS.** PLL Standby Disable.

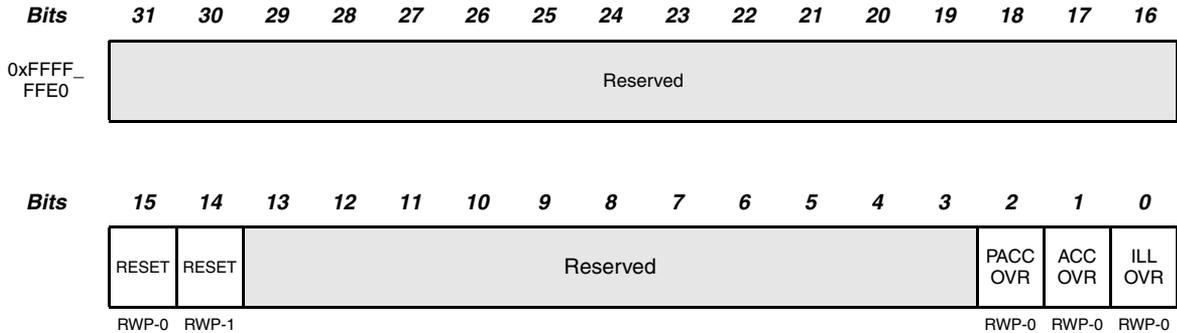
When this bit is set, the PLL will be disabled upon entering standby mode. This bit is only effective in standby mode.

User and privilege mode (read/write):

- 0 = PLL is enabled
- 1 = PLL is disabled

9.27 System Exception Control Register (SYSECR)

The system exception control register contains bits that allow the user to generate a software reset; the OVR bits disable some reset/abort conditions when $\overline{\text{TRST}}$ is high.



R = Read in all modes, WP = write in privilege mode only; -n = Value after reset

Bits [31:16] **Reserved.**

Reads are undefined and writes have no effect.

Bits [15:14] **RESET.** Software reset bits.

Setting RESET or clearing RESET causes a software reset. There are three possible reset cases:

User and privilege mode (read):
Always reads 01

Privilege mode (write):

01 = No reset

1X = Global system reset (X = don't care)

X0 = Global system reset (X = don't care)

Bits [13:3] Reserved.

Read are undefined and writes have no effect.

Note: SYSECR.2:0 Only Active in Test and Emulation Mode

The override bits (SYSECR.2:0) are active only in test and emulation mode. These bits are active only when $\overline{\text{TRST}}$ is high, and it is recommended that $\overline{\text{TRST}}$ be held low in normal applications.

Bit 2 PACCOVR. Peripheral access violation override bit.

Prevents a peripheral access violation error from causing a reset or abort exception.

User and privilege mode (read):

Privilege mode (write):

0 = Peripheral access violation error causes a reset or abort

1 = No action taken on a peripheral access violation

Bit 1 ACCOVR. Memory access reset override bit.

Prevents a a memory access rights violation from causing a reset or abort exception.

User and privilege mode (read):

Privilege mode (write):

0 = Memory access violation rights error causes a reset or abort

1 = No action taken on a memory access rights violation

Bit 0 ILLOVR. Illegal address reset override bit.

Prevents an illegal access from causing a reset or abort.

User and privilege mode (read):

Privilege mode (write):

0 = An illegal address causes a reset or abort.

1 = No action taken on an illegal address.

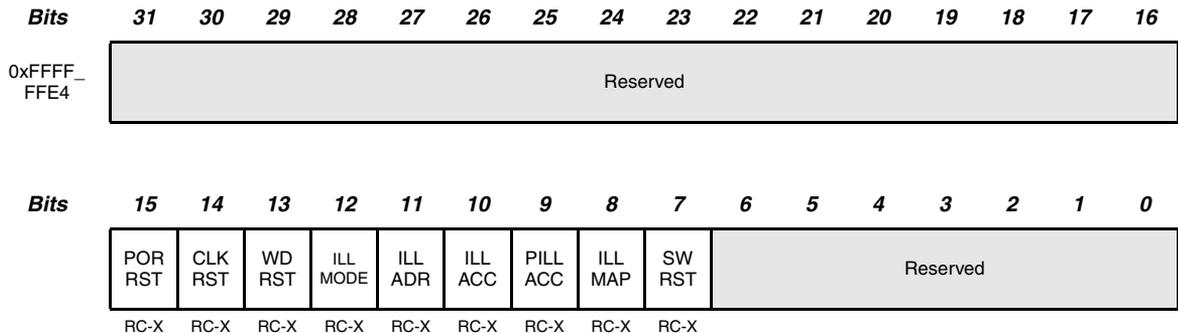
9.28 System Reset Exception Status Register (SYSESR)

The system reset exception status register contains flags for different reset/abort sources. On power-up, all bits are cleared to 0. When a reset condition is recognized, the appropriate bit in SYSESR is set and the value of the bit is maintained through the reset (as long as V_{CC} remains within specifications). See Section 6, *Resets*, on page 41 for further information about the causes of resets.

When a new reset condition occurs, the current contents of this register are not cleared. The contents of this register are cleared on a power-on reset or by software.

Note: The PORRST Bit

The PORRST bit is always set when the device is powered up. The bit is cleared to 0 on power up, but is active whenever the $\overline{\text{PORRST}}$ pin is low. The $\overline{\text{PORRST}}$ pin is low coming out of power up, so the bit is always set to 1.



R = Read in all modes, Clear = Clear in all modes by writing a 0; -X = Value unchanged after reset

Bits [31:16] Reserved.

Reads are undefined and writes have no effect.

Bit 15 PORRST. Power-up reset flag.

Set when **Power-On Reset** is asserted. Reset is asserted as long as **Power-On Reset** is active. Whenever a device is powered, this bit is set.

User and privilege modes (read):

- 0 = Power-up reset has not occurred since the last clear.
- 1 = Power-up reset has occurred since the last clear.

User and privilege modes (write):

- 0 = Clears the corresponding bit to 0
- 1 = Has no effect

- Bit 14** **CLKRST.** Clock fail flag.
- Indicates that a clock fault condition has occurred. When power-up reset occurs, the CLKRST is reset to 0. Value remains unchanged during other resets.
- User and privilege modes (read):
0 = A clock failure has not occurred since the last clear.
1 = A clock failure has occurred since the last clear.
- User and privilege modes (write):
0 = Clears the corresponding bit to 0.
1 = Has no effect.
- Bit 13** **WDRST.** Watchdog reset flag.
- Set when the last reset is caused by the watchdog.
- User and privilege modes (read):
0 = A watchdog reset has not occurred since the last clear.
1 = A watchdog reset has occurred since the last clear.
- User and privilege modes (write):
0 = Clears the corresponding bit to 0.
1 = Has no effect.
- Bit 12** **ILLMODE.** Illegal mode flag.
- Set when the mode bits in the program status register are set to an illegal value.
- User and privilege modes (read):
0 = An illegal mode has not occurred since the last clear.
1 = An illegal mode has occurred since the last clear.
- User and privilege modes (write):
0 = Clears the corresponding bit to 0.
1 = Has no effect.
- Bit 11** **ILLADR.** Illegal address access flag.
- Set when an access to an unimplemented location in the memory map is detected in non-user mode.
- User and privilege modes (read):
0 = An illegal address has not occurred since the last clear.
1 = An illegal address has occurred since the last clear.
- User and privilege modes (write):
0 = Clears the corresponding bit to 0
1 = Has no effect

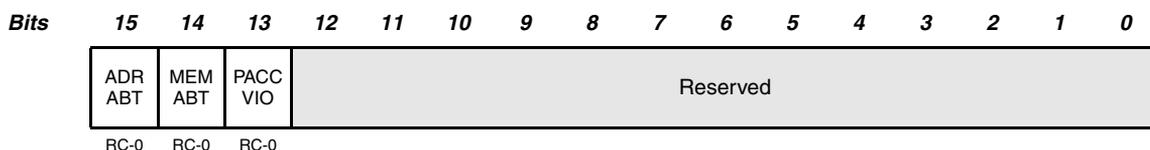
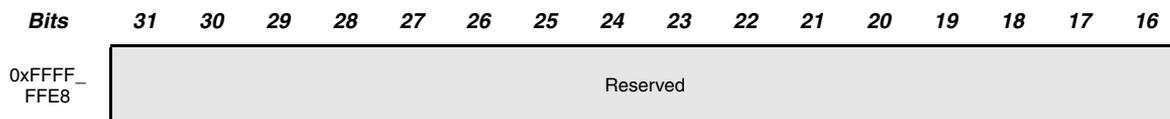
- Bit 10** **ILLACC.** Illegal memory access flag.
- Set when an access to a protected location without permission rights is detected in non-user mode.
- User and privilege modes (read):
0 = An illegal memory access has not occurred since the last clear.
1 = An illegal memory access has occurred since the last clear.
- User and privilege modes (write):
0 = Clears the corresponding bit to 0
1 = Has no effect
- Bit 9** **PILLACC.** Peripheral illegal access flag.
- Set when a peripheral access violation is detected in user mode.
- User and privilege modes (read):
0 = An illegal peripheral access has not occurred since the last clear.
1 = An illegal peripheral access has occurred since the last clear.
- User and privilege modes (write):
0 = Clears the corresponding bit to 0
1 = Has no effect
- Bit 8** **ILLMAP.** Illegal address map flag.
- Set when the base addresses of one or more memories overlap. Reset occurs when the overlapped region is accessed.
- User and privilege modes (read):
0 = An illegal address mapping has not occurred since the last clear.
1 = An illegal address mapping has occurred since the last clear.
- User and privilege modes (write):
0 = Clears the corresponding bit to 0
1 = Has no effect
- Bit 7** **SWRST.** Software reset flag.
- Set when the last reset is caused by software writing to the RESET bits.
- User and privilege modes (read):
0 = A software reset has not occurred since the last clear.
1 = A software reset has occurred since the last clear.
- User and privilege modes (write):
0 = Clears the corresponding bit to 0
1 = Has no effect

Bits [6:0] Reserved.

Reads are undefined and writes have no effect.

9.29 Abort Exception Status Register (ABRTESR)

The abort exception status register shows the abort cause. For more information on aborts, see Section 6, *Resets*, on page 41 and Section 3.4, *Memory Resets*, on page 21.



RC = Read in all modes, C = Clear in all modes by writing a 0; -n = Value after reset;

Bits [31:16] Reserved.

Reads are undefined and writes have no effect.

Bit 15 ADRABT. Illegal address abort.

An illegal address access was detected in user mode. An abort was generated due to an illegal address access from either the MPU or system.

User and privilege mode (read):

- 0 = No illegal address
- 1 = Abort caused by an illegal address

User and privilege mode (write):

- 0 = Clears bit to 0
- 1 = Has no effect

Bit 14 MEMABT. Memory access abort.

Indicates an illegal memory access was detected in user mode. An abort was generated due to the illegal memory access from either the MPU or system.

User and privilege mode (read):

- 0 = No illegal memory access
- 1 = Abort caused by an illegal memory access

User and privilege mode (write):
 0 = Clears bit to 0
 1 = Has no effect

Bit 13 **PACCVIO.** Peripheral access violation error.

Indicates a peripheral access violation error was detected during a peripheral register access in user mode. An abort was generated due to a peripheral access violation.

User and privilege mode (read):
 0 = No peripheral access violation
 1 = Abort caused by an peripheral access violation

User and privilege mode (write):
 0 = Clears bit to 0
 1 = Has no effect

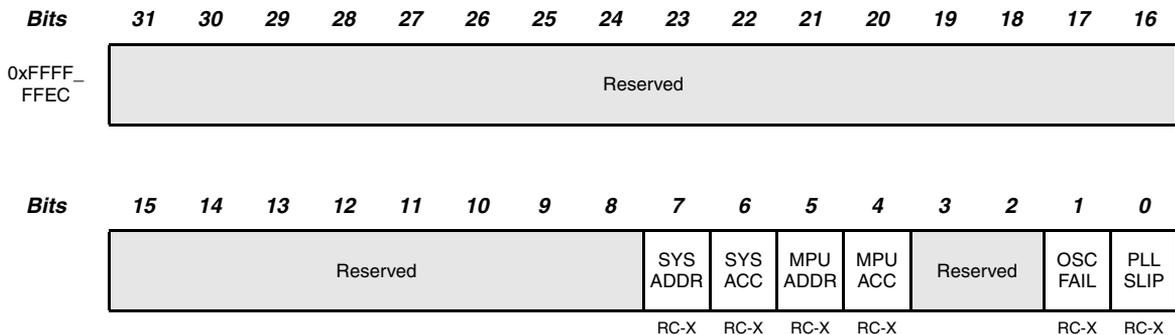
Bits [12:0] **Reserved.**

Reads are undefined and writes have no effect.

9.30 Global Status Register (GLBSTAT)

The global status register specifies the module that triggered the illegal address, illegal access, abort, or reset.

When a new reset condition occurs, the current contents of this register are not cleared. The contents of this register are cleared on a power-on reset or by software.



R = Read in all modes, C = Clear in all modes by writing a 0; -X = Value unchanged after reset

Bits [31:8] **Reserved.**

Reads are undefined and writes have no effect. To maintain future compatibility of software, initialize these bits to 0.

Bit 7**SYSADDR.** System illegal address flag.

Set when the system detects an illegal address.

User and privilege mode (read):

0 = No system illegal address

1 = Abort or reset caused by a system illegal address

User and privilege mode (write):

0 = Clears bit to 0

1 = Has no effect

Bit 6**SYSACC.** System illegal access flag.

Set when the system detects an illegal access.

User and privilege mode (read):

0 = No system illegal access

1 = Abort or reset caused by a system illegal access

User and privilege mode (write):

0 = Clears bit to 0

1 = Has no effect

Bit 5**MPUADDR.** MPU illegal address flag.

Set when the memory protection unit (MPU) detects an illegal address.

User and privilege mode (read):

0 = No MPU illegal address

1 = Abort or reset caused by a MPU illegal address

User and privilege mode (write):

0 = Clears bit to 0

1 = Has no effect

Bit 4**MPUACC.** MPU illegal access flag.

Set when the memory protection unit (MPU) detects an illegal access. (The MPUACC flag is set along with the MPUADDR flag when an MPU illegal address is detected. See Section 3.4.1, *Illegal Address*, on page 22.)

User and privilege mode (read):

0 = No MPU illegal access

1 = Abort or reset caused by a MPU illegal access

User and privilege mode (write):

0 = Clears bit to 0

1 = Has no effect

Bits [3:2] Reserved.

Reads are undefined and writes have no effect. To maintain future compatibility of software, initialize these bits to 0.

Bit 1 OSCFAIL. Oscillator Fail Flag Bit.

When set, this bit indicates that the external reference (oscillator or crystal) is operating at a frequency too slow to be functional when compared to an internal reference oscillator. For more information, see Section 6, *Resets*, on page 41.

User and privilege mode (read):

0 = No oscillator failure

1 = Abort caused by an oscillator failure

User and privilege mode (write):

0 = Clears bit to 0

1 = Has no effect

Bits 0 PLLSLIP. PLL Slip Flag Bit.

When set, this bit indicates that a discrepancy between the reference and VCO oscillator phases has been detected. This bit can be read and filtered in user software to determine if the slip is caused by noise or is deemed to be a true failure. For more information, see Section 6, *Resets*, on page 41.

User and privilege mode (read):

0 = No PLL slip

1 = Abort caused by a PLL slip

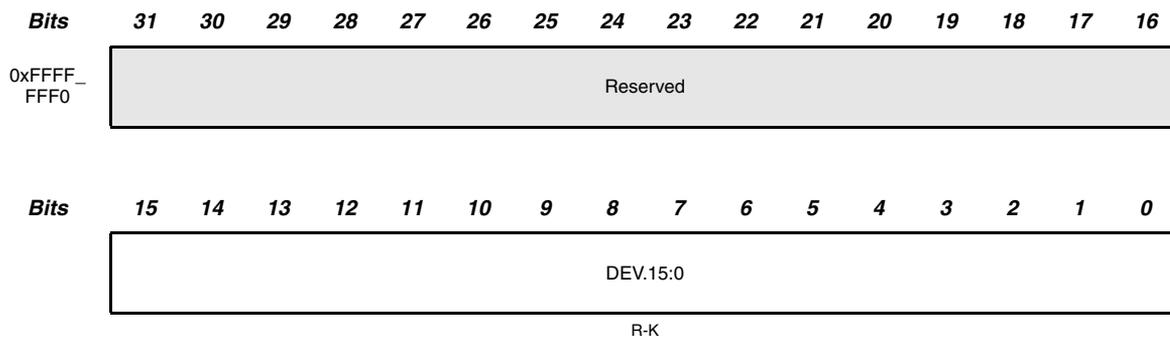
User and privilege mode (write):

0 = Clears bit to 0

1 = Has no effect

9.31 Device Identification Register (DEV)

The register contains device-specific information that is hard coded during device manufacture.



R = Read only; -K = Constant value

Bits [31:16] Reserved.

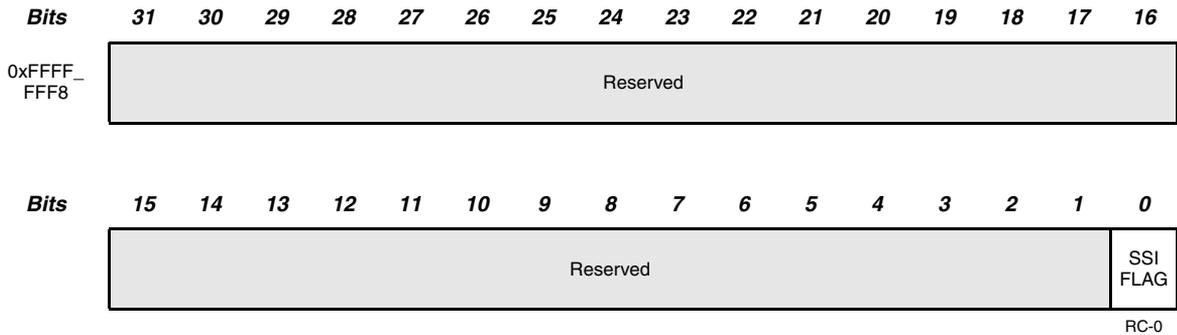
Reads are undefined and writes have no effect. To maintain future compatibility of software, initialize these bits to 0.

Bits [15:0] DEV.15:0. Device identification code.

This is a read-only register. See the device-specific data sheet for details on the device identification code.

9.32 System Software Interrupt Flag Register (SSIF)

The system software interrupt flag is set when a software interrupt is triggered. The flag allows the user to poll for a software interrupt.



R = Read, C = Clear; -n = Value after reset

Bits [31:1] **Reserved.**

Reads are undefined and writes have no effect.

Bit 0 **SSIF.** System software interrupt flag.

Set when a correct SSKEY is written to the SSIR register. Cleared only by software. Possible values are as follows:

User and privilege mode (read):

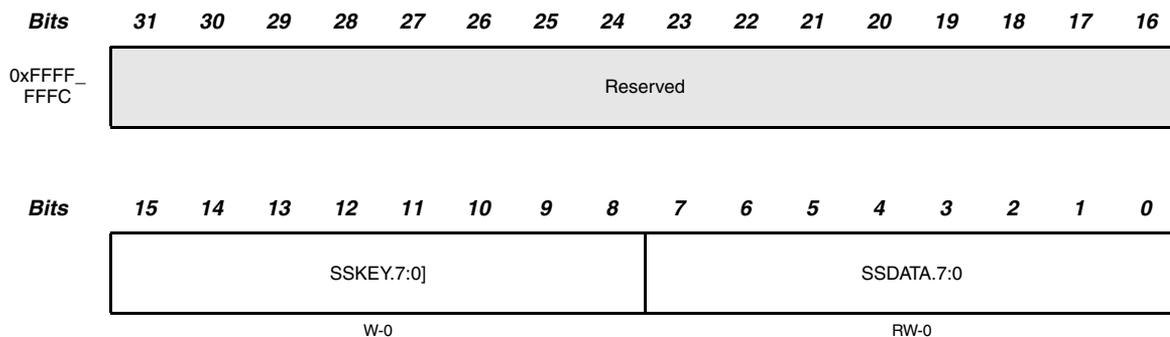
- 0 = No IRQ/FIQ interrupt request has been generated since the last clear.
- 1 = An IRQ/FIQ interrupt request has been generated since the last clear.

User and privilege mode (write):

- 0 = Clears the bit
- 1 = Has no effect

9.33 System Software Interrupt Request Register (SSIR)

The system software interrupt request register contains a key sequence that triggers a software interrupt request to the CIM. Also, the register contains an 8-bit data field.



R = Reads, W = Writes; -n = Value after reset

Bits [31:16] Reserved.

Reads are undefined and writes have no effect.

Bits [15:8] SSKEY.7:0. System software interrupt request key.

Write-only data bits executable in user and privilege modes. A 0x75 written to these bits initiates IRQ/FIQ interrupts. Data in this field is always read as zero (0).

Bits [7:0] SSDATA.7:0. System software interrupt data.

User and privilege mode (read/write):
SSDATA provides an 8-bit field that can be used for passing messages into the system software interrupt.

