

Hall Effect Current Sensor from LEM

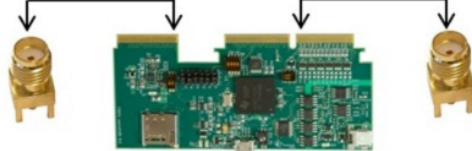
BURDEN

Level shifting

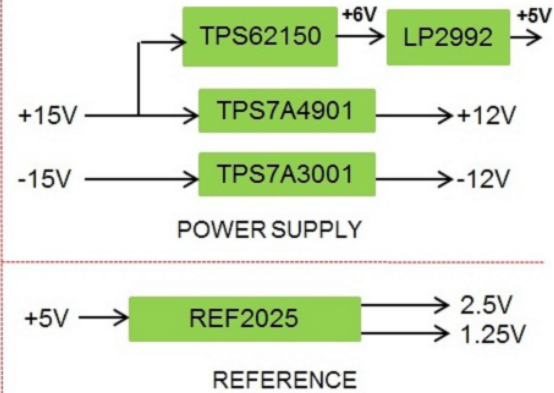
OPA322

Gain + Filtering

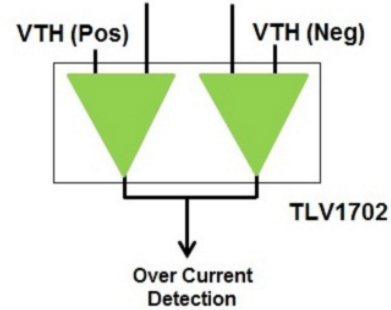
THS4531A



Note: The SMA Connectors are used to connect to external ADC EVMs



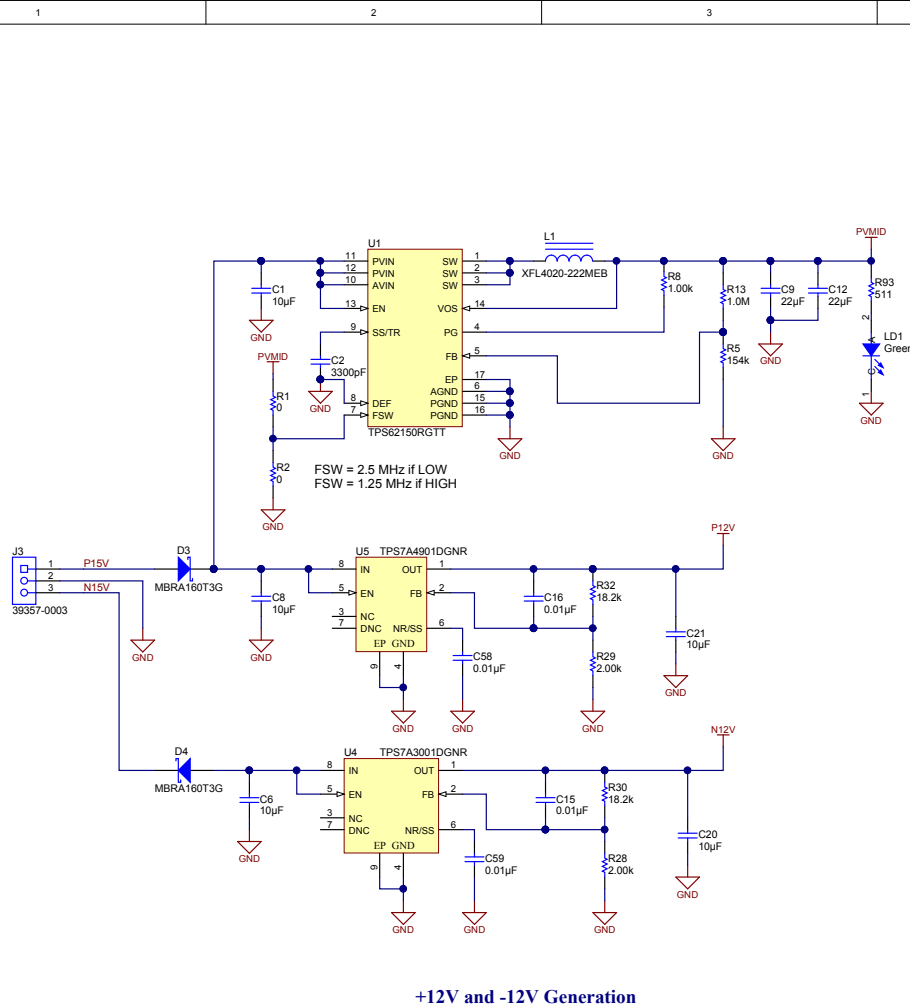
The voltage across Burden is also given as input to the comparators for OC detection.



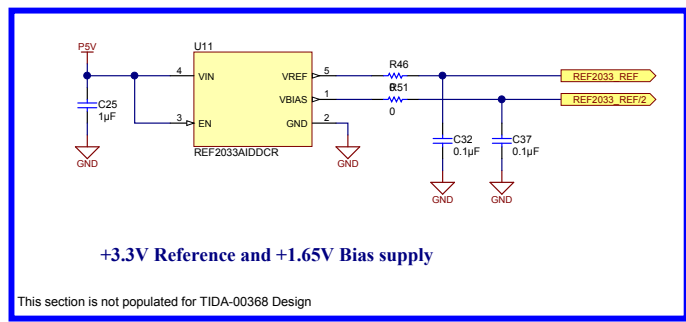
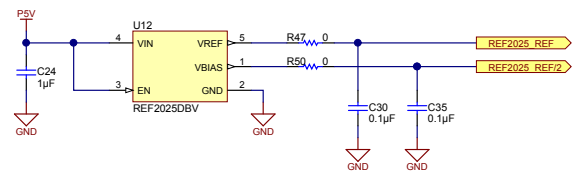
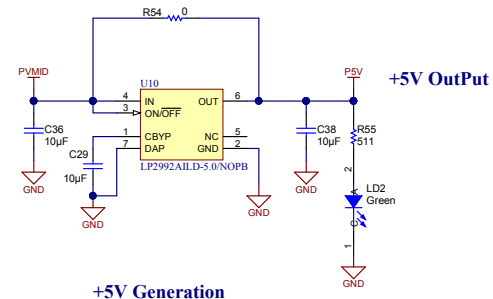
Revision History	
Revision	Notes

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Orderable: N/A	Designed for: Public Release	Mod. Date: 6/18/2015	 http://www.ti.com © Texas Instruments 2015
TID #: TIDA-00368	Project Title: Motor Current Measurement using Hall Sensors		
Number: TIDA-00368 Rev: E2	Sheet Title: Block Diagram		
SVN Rev: Not in version control	Assembly Variant: Variant name not interpreted	Sheet: 1 of 6	
Drawn By: Sanjay Pithadia	File: SH07_CoverSheet_SchDoc	Size: B	
Engineer: Sanjay Pithadia	Contact: http://www.ti.com/support		

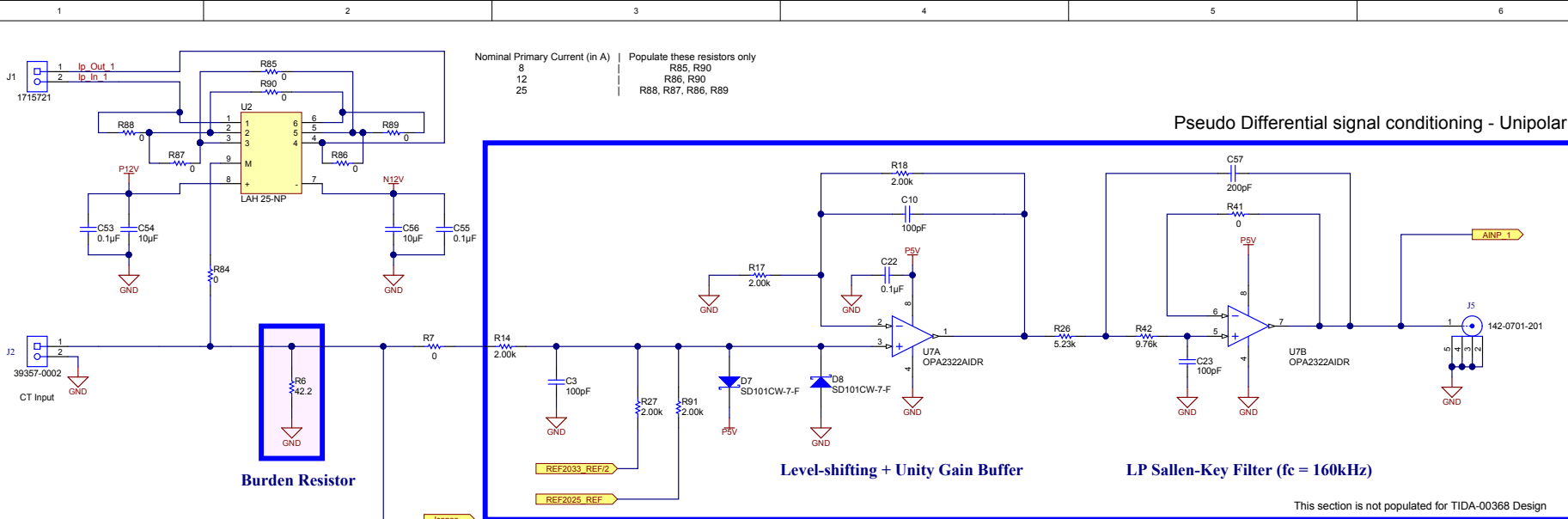


Currently PVMID is set to 6V and R54 is DNP.
When LP2992 is not used, Mount R54 and Set PVMID = 5V



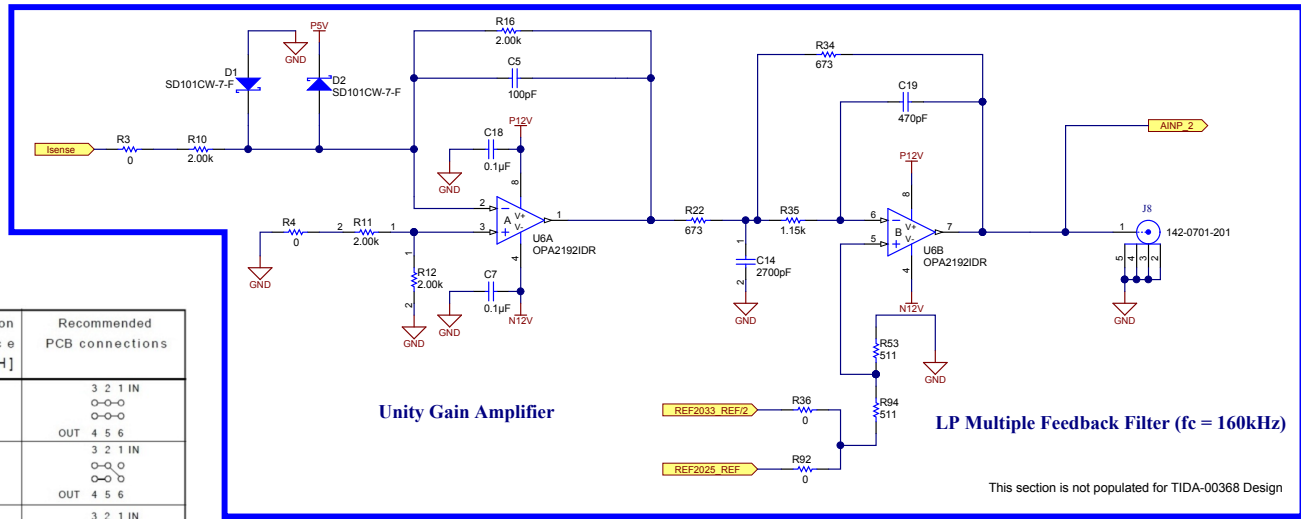
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TID #: TIDA-00368	Project Title: Motor Current Measurement using Hall Sensors		
Number: TIDA-00368	Rev: E2	Sheet Title: Power Supply	
SVN Rev: Not in version control	Assembly Variant: Variant name not interpreted	Sheet 2 of 6	
Drawn By: Sanjay Pithadia	File: SH02_Power_supply_SchDoc	Size: B	
Engineer: Sanjay Pithadia	Contact: http://www.ti.com/support		http://www.ti.com © Texas Instruments 2015



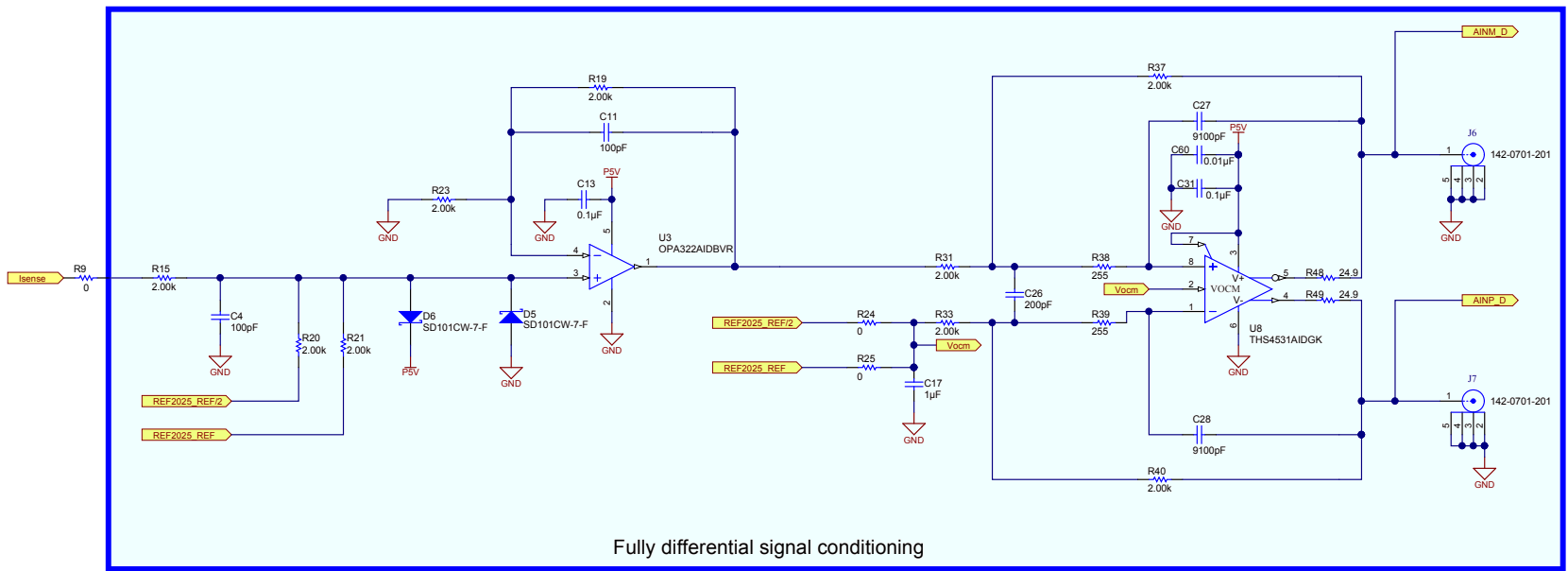
Burden Resistor = 42.2 ohms (when external +5V operated ADC is used)
 Burden Resistor = 18.2 ohms (when internal ADC of MCU is used)

Number of primary turns	Primary current		Nominal output current I_{SN} [mA]	Turns ratio K_N	Primary resistance R_p [mΩ]	Primary insertion inductance L_p [μH]	Recommended PCB connections
	nominal I_{PN} [A]	maximum I_p [A]					
1	25	55	25	1 : 1000	0.18	0.012	3 2 1 IN O-O-O O-O-O OUT 4 5 6
2	12	27	24	2 : 1000	0.81	0.054	3 2 1 IN O-O-O O-O-O OUT 4 5 6
3	8	18	24	3 : 1000	1.62	0.110	3 2 1 IN O-O-O O-O-O OUT 4 5 6

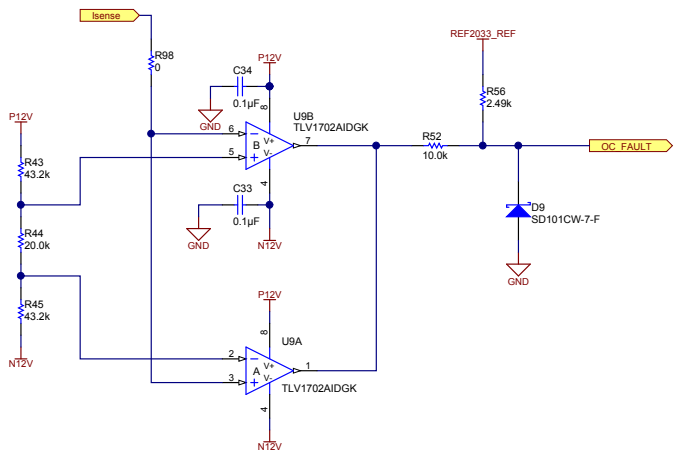


Pseudo Differential signal conditioning - Bipolar

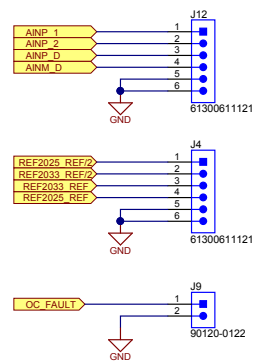
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Fully differential signal conditioning

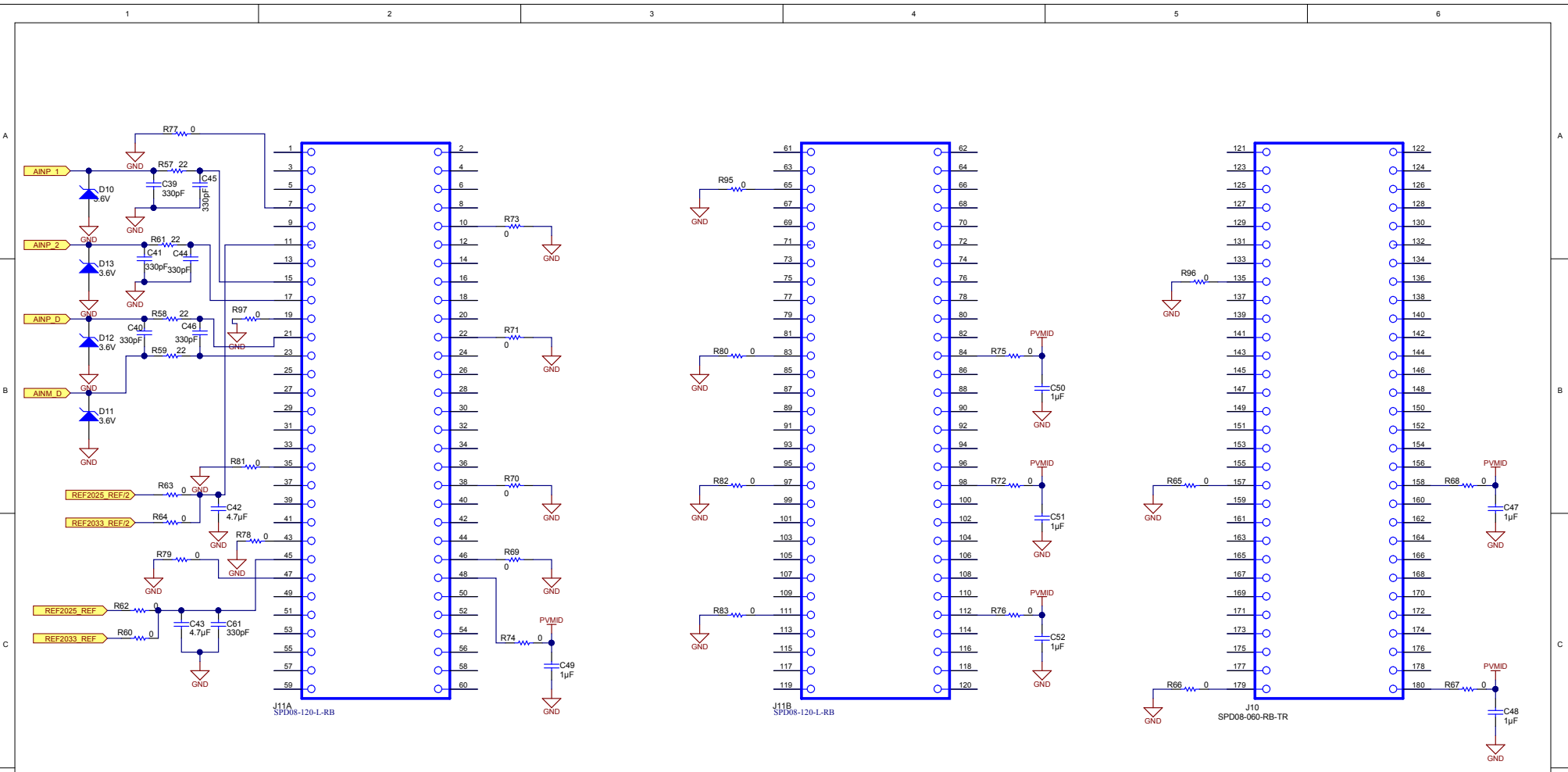


Overcurrent Protection



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TID #: TIDA-00368	Project Title: Motor Current Measurement using Hall Sensors		
Number: TIDA-00368	Rev: E2	Sheet Title: Signal Chain - Fully Differential + AD57854	
SVN Rev: Not in version control	Assembly Variant: Variant name not interpreted	Sheet: 4 of 6	
Drawn By: Sanjay Pillhadia	File: SH04_Fully_differential_ended_SC_to_ADC_Sch_Size_B	http://www.ti.com	
Engineer: Sanjay Pillhadia	Contact: http://www.ti.com/support	© Texas Instruments 2015	



Connection to Delfino Control Card

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Designed for Public Release		Mod. Date: 6/18/2015		
Project Title: Motor Current Measurement using Hall Sensors				
Number: TIDA-00368	Rev: E2	Sheet Title: Delfino Controller Interface		
SVN Rev: Not in version control		Assembly Variant: Variant name not interpreted		
Drawn By: Sanjay Pillhadia		File: SH05_160_pin_connector_interface.SchDoc		Sheet 5 of 6
Engineer: Sanjay Pillhadia		Contact: http://www.ti.com/support		Size: B
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H2 NY PMS 440 0025 PH H1 NY PMS 440 0025 PH H3 NY PMS 440 0025 PH H4 NY PMS 440 0025 PH

H12 1902C H11 1902C H9 1902C H10 1902C

FID2 FID1 FID3 FID6 FID5 FID4

PCB Number: TIDA-00368
PCB Rev: E2

PCB
LOGO
Texas Instruments

PCB
LOGO
Pb-Free Symbol

Label Table	
Variant	Label Text
001	ChangeMe!
002	ChangeMe!

ZZ1
Assembly Note
These assemblies are ESD sensitive, ESD precautions shall be observed.

ZZ2
Assembly Note
These assemblies must be clean and free from flux and all contaminants. Use of no clean flux is not acceptable.

ZZ3
Assembly Note
These assemblies must comply with workmanship standards IPC-A-610 Class 2, unless otherwise specified.

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TID #: TIDA-00368	Project Title: Motor Current Measurement using Hall Sensors	
Number: TIDA-00368	Rev: E2	Sheet Title:
SVN Rev: Not in version control	Assembly Variant: Variant name not interpreted	Sheet 6 of 6
Drawn By:	File: SH06_Hardware_SchDoc	Size: B
Engineer: Sanjay Pithadia	Contact: http://www.ti.com/support	



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