



## ABSTRACT

This document describes the known exceptions to the functional specifications (advisories).

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## 1 Functional Advisories

Advisories that affect the device's operation, function, or parametrics.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev AE	Rev AD	Rev AB	Rev AA	Rev S	Rev Q	Rev O	Rev N	Rev M	Rev L
ADC1	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
ADC5	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
ADC7	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
ADC8	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
ADC9	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
ADC10	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
ADC11										✓
ADC18	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
ADC25	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
BCL5	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
MPY2	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
PORT3	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
RES3	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
RES4	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
TA12	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
TA16	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
TA21	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
TAB22	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
TB1	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
TB2	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
TB3	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
TB4	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
TB14	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
TB16	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
TB24	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
US13	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
US14	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
US15	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
WDG2	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓

## 2 Preprogrammed Software Advisories

Advisories that affect factory-programmed software.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev AE	Rev AD	Rev AB	Rev AA	Rev S	Rev Q	Rev O	Rev N	Rev M	Rev L
BSL3	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
BSL4	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
BSL5	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓

### 3 Debug Only Advisories

Advisories that affect only debug operation.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev AE	Rev AD	Rev AB	Rev AA	Rev S	Rev Q	Rev O	Rev N	Rev M	Rev L
<a href="#">EEM20</a>	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓

### 4 Fixed by Compiler Advisories

Advisories that are resolved by compiler workaround. Refer to each advisory for the IDE and compiler versions with a workaround.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev AE	Rev AD	Rev AB	Rev AA	Rev S	Rev Q	Rev O	Rev N	Rev M	Rev L
<a href="#">CPU4</a>	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓

Refer to the following MSP430 compiler documentation for more details about the CPU bugs workarounds.

#### TI MSP430 Compiler Tools (Code Composer Studio IDE)

- [MSP430 Optimizing C/C++ Compiler](#): Check the --silicon\_errata option
- [MSP430 Assembly Language Tools](#)

#### MSP430 GNU Compiler (MSP430-GCC)

- [MSP430 GCC Options](#): Check -msilicon-errata= and -msilicon-errata-warn= options
- [MSP430 GCC User's Guide](#)

#### IAR Embedded Workbench

- [IAR workarounds for msp430 hardware issues](#)

## 5 Nomenclature, Package Symbolization, and Revision Identification

The revision of the device can be identified by the revision letter on the [Package Markings](#) or by the [HW\\_ID](#) located inside the TLV structure of the device.

### 5.1 Device Nomenclature

To designate the stages in the product development cycle, TI assigns prefixes to the part numbers of all MSP MCU devices. Each MSP MCU commercial family member has one of two prefixes: MSP or XMS. These prefixes represent evolutionary stages of product development from engineering prototypes (XMS) through fully qualified production devices (MSP).

**XMS** – Experimental device that is not necessarily representative of the final device's electrical specifications

**MSP** – Fully qualified production device

Support tool naming prefixes:

**X**: Development-support product that has not yet completed Texas Instruments internal qualification testing.

**null**: Fully-qualified development-support product.

XMS devices and X development-support tools are shipped against the following disclaimer:

"Developmental product is intended for internal evaluation purposes."

MSP devices have been characterized fully, and the quality and reliability of the device have been demonstrated fully. TI's standard warranty applies.

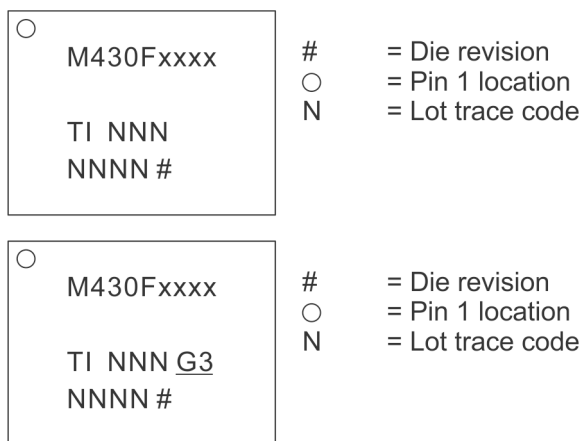
Predictions show that prototype devices (XMS) have a greater failure rate than the standard production devices. TI recommends that these devices not be used in any production system because their expected end-use failure rate still is undefined. Only qualified production devices are to be used.

TI device nomenclature also includes a suffix with the device family name. This suffix indicates the temperature range, package type, and distribution format.

### 5.2 Package Markings

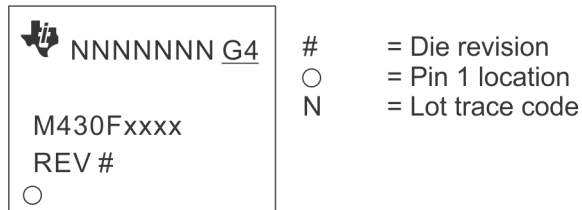
**RTD64**

**QFN (RTD), 64 Pin**



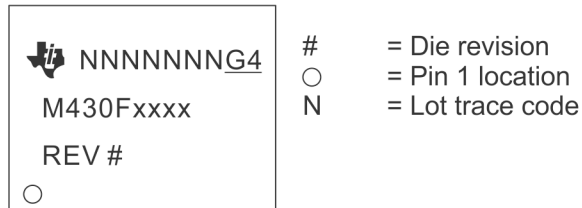
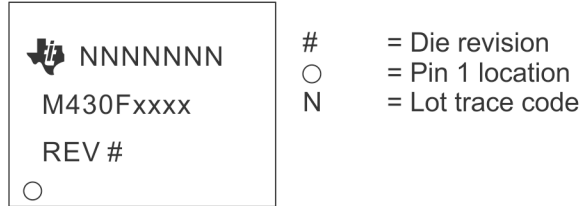
**PM64**

**LQFP (PM), 64 Pin**



**PAG64**

**TQFP (PAG), 64 Pin**



**5.3 Memory-Mapped Hardware Revision (TLV Structure)**

This device does not support reading the hardware revision from memory.

Further guidance on how to locate the TLV structure and read out the HW\_ID can be found in the device User's Guide.

## 6 Advisory Descriptions

<b>ADC1</b>	<b>ADC Module</b>
<b>Category</b>	Functional
<b>Function</b>	Start of conversion
<b>Description</b>	In single conversion/sequence mode (CONSEQ=0/1), the next conversion can be started with ADC12SC. It is not necessary to clear ENC before setting ADC12SC. This is contrary to the specification.
<b>Workaround</b>	None
<b>ADC5</b>	<b>ADC Module</b>
<b>Category</b>	Functional
<b>Function</b>	Interrupt flag register
<b>Description</b>	ADC12 interrupt flag may not be set when the CPU simultaneously accesses the ADC12IFG register.
<b>Workaround</b>	There is no need to access the interrupt flag register to process interrupt situations. Please use the ADC12IV register to identify the interrupt event. The corresponding flag bits will be reset automatically. Additional details are discussed in the device family user's guide.
<b>ADC7</b>	<b>ADC Module</b>
<b>Category</b>	Functional
<b>Function</b>	Conversion time overflow
<b>Description</b>	The timing overflow flag is set when the device is in sequence mode (CONSEQ = 1 or 3) and MSC = 0, even if no overflow has occurred.
<b>Workaround</b>	Verify correct timing and do not enable Conversion-Time Overflow interrupt.
<b>ADC8</b>	<b>ADC Module</b>
<b>Category</b>	Functional
<b>Function</b>	Interrupt flag register
<b>Description</b>	Clearing flags in the interrupt flag register with a CPU instruction will not clear the latest interrupt flag.
<b>Workaround</b>	Clear interrupt flags by accessing the conversion-memory registers.
<b>ADC9</b>	<b>ADC Module</b>
<b>Category</b>	Functional
<b>Function</b>	Interrupt vector register
<b>Description</b>	If the ADC12 uses a different clock than the CPU (MCLK) and more than one ADC interrupt is enabled, the ADC12IV register content may be unpredictable for one clock

cycle. This happens if, during the execution of an ADC interrupt, another ADC interrupt with higher priority occurs.

- Workaround**
- Read out ADC12IV twice and use only when values are equal.
  - or
  - Use ADC12IFG to determine which interrupt has occurred.

**ADC10** *ADC Module*

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**Category** Functional

**Function** Unintended start of conversion

**Description** Accessing ADC12OVIE or ADC12TOVIE at the end of an ADC12 conversion with BIS/BIC commands can cause the ADC12SC bit to be set again immediately after it was cleared. This might start another conversion, if ADC12SC is configured to trigger the ADC (SHS = 0).

- Workaround**
- If ADC12SC is configured to trigger the ADC, the control bits ADC12OVIE and ADC12TOVIE should be modified only when the ADC is not busy (ADC12BUSY = 0).

**ADC11** *ADC Module*

---

**Category** Functional

**Function** Temporary leakage current after conversion

**Description** The ADC12 causes temporary leakage current after a completed conversion. Duration and magnitude of the leakage current depends on parasitic effects.

**Workaround** None

**ADC18** *ADC Module*

---

**Category** Functional

**Function** Incorrect conversion result in extended sample mode

**Description** The ADC12 conversion result can be incorrect if the extended sample mode is selected (SHP = 0), the conversion clock is not the internal ADC12 oscillator (ADC12SSEL > 0), and one of the following two conditions is true:

- The extended sample input signal SHI is asynchronous to the clock source used for ADC12CLK and the undivided ADC12 input clock frequency exceeds 3.15 MHz.
- or
- The extended sample input signal SHI is synchronous to the clock source used for ADC12CLK and the undivided ADC12 input clock frequency exceeds 6.3 MHz.

- Workaround**
- Use the pulse sample mode (SHP = 1).
  - or
  - Use the ADC12 internal oscillator as the ADC12 clock source.
  - or
  - Limit the undivided ADC12 input clock frequency to 3.15 MHz.
  - or
  - Use the same clock source (such as ACLK or SMCLK) to derive both SHI and ADC12CLK, to achieve synchronous operation, and also limit the undivided ADC12 input clock frequency to 6.3 MHz.

<b>ADC25</b>	<b>ADC Module</b>
<b>Category</b>	Functional
<b>Function</b>	Write to ADC12CTL0 triggers ADC12 when CONSEQ = 00
<b>Description</b>	If ADC conversions are triggered by the Timer_B module and the ADC12 is in single-channel single-conversion mode (CONSEQ = 00), ADC sampling is enabled by write access to any bit(s) in the ADC12CTL0 register. This is contrary to the expected behavior that only the ADC12 enable conversion bit (ADC12ENC) triggers a new ADC12 sample.
<b>Workaround</b>	When operating the ADC12 in CONSEQ=00 and a Timer_B output is selected as the sample and hold source, temporarily clear the ADC12ENC bit before writing to other bits in the ADC12CTL0 register. The following capture trigger can then be re-enabled by setting ADC12ENC = 1.
<b>BCL5</b>	<b>BCL Module</b>
<b>Category</b>	Functional
<b>Function</b>	RSELx bit modifications can generate high frequency spikes on MCLK
<b>Description</b>	When DIVMx = 00 or 01 the RSELx bits of the Basic Clock Module are incremented or decremented in steps of 2 or greater, the DCO output may momentarily generate high frequency spikes on MCLK, which may corrupt CPU operation. This is not an issue when DIVMx = 10 or 11.
<b>Workaround</b>	Set DIVMx = 10 or 11 to divide the MCLK input prior to modifying RSELx. After the RSELx bits are configured as desired, the DIVMx setting can be changed back to the original selection.
<b>BSL3</b>	<b>BSL Module</b>
<b>Category</b>	Software in ROM
<b>Function</b>	Receiving framesBug
<b>Description</b>	Receiving frames with a checksum value equal to a legal address can change the content of this address or the bootstrap loader may stop operation.
<b>Workaround</b>	Software workaround is available as part of BSLDEMO.exe, found as part of the BSL-SCRIPTER download on the page for <a href="#">MSPBSL</a> .
<b>BSL4</b>	<b>BSL Module</b>
<b>Category</b>	Software in ROM
<b>Function</b>	Flash memory can not be programmed
<b>Description</b>	The bootstrap loader software cannot program the flash memory.
<b>Workaround</b>	Software workaround is available as part of BSLDEMO.exe, found as part of the BSL-SCRIPTER download on the page for <a href="#">MSPBSL</a>
<b>BSL5</b>	<b>BSL Module</b>
<b>Category</b>	Software in ROM



<b>Function</b>	BSL might not start if RST/NMI pin is configured as NMI input
<b>Description</b>	If the RST/NMI pin is configured to NMI, the bootstrap loader may not be started. Unpredictable operations will result.
<b>Workaround</b>	None

## CPU4 *CPU Module*

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<b>Category</b>	Compiler-Fixed
<b>Function</b>	PUSH #4, PUSH #8
<b>Description</b>	The single operand instruction PUSH cannot use the internal constants (CG) 4 and 8. The other internal constants (0, 1, 2, -1) can be used. The number of clock cycles is different:  PUSH #CG uses address mode 00, requiring 3 cycles, 1 word instruction PUSH #4/#8 uses address mode 11, requiring 5 cycles, 2 word instruction
<b>Workaround</b>	Refer to the table below for compiler-specific fix implementation information.

IDE/Compiler	Version Number	Notes
IAR Embedded Workbench	IAR EW430 v2.x until v6.20	User is required to add the compiler flag option below. --hw_workaround=CPU4
IAR Embedded Workbench	IAR EW430 v6.20 or later	Workaround is automatically enabled
TI MSP430 Compiler Tools (Code Composer Studio)	v1.1 or later	
MSP430 GNU Compiler (MSP430-GCC)	MSP430-GCC 4.9 build 167 or later	

## EEM20 *EEM Module*

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<b>Category</b>	Debug
<b>Function</b>	Debugger might clear interrupt flags
<b>Description</b>	During debugging read-sensitive interrupt flags might be cleared as soon as the debugger stops. This is valid in both single-stepping and free run modes.
<b>Workaround</b>	None.

## MPY2 *MPY Module*

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<b>Category</b>	Functional
<b>Function</b>	Multiplier Result register corruption
<b>Description</b>	Depending on the address of the write instruction, writing to the multiplier result registers (RESHI, RESLO, or SUMEXT) may corrupt the result registers. The address dependency varies between a 2-word and a 3-word instructions.
<b>Workaround</b>	Ensure that a write instruction to an MPY result register (for example, mov.w #200, &RESHI) is not located at an address with the four least significant bits shown in Table 1:

Table 1. Sensitive Addresses for Write Access to MPY Result Registers MAB[3:0]

RESLOW 013Ah		RESHI 013Ch		SUMEXT 013Eh	
3 Word	2 Word	3 Word	2 Word	3 Word	2 Word
2	4	2	4	2	4
6	8	4	6	6	8
A	C	A	C	A	C
E	0	C	E	–	–

**PORT3*****PORT Module*****Category**

Functional

**Function**

Port interrupts can get lost

**Description**

Port interrupts can get lost if they occur during CPU access of the P1IFG and P2IFG registers.

**Workaround**

None

**RES3*****RES Module*****Category**

Functional

**Function**

Reset

**Description**

When RST/NMI is held low during power up of VCC, some internal drivers are not reset correctly. This may result in a high Icc current until the internal power-on signal has generated one clock cycle to reset the internal drivers. This limits the time when the excess current can occur to the time the power-up circuit is active.

**Workaround**

None

**RES4*****RES Module*****Category**

Functional

**Function**

No reset if external resistor exceeds certain value

**Description**

No reset of the device is performed if the external pull down resistor on RST/NMI pin is above a certain limit. The limits are:

Vcc = 1.8V: maximum pull down resistor = 12 kohm

Vcc = 3.0V: maximum pull down resistor = 5 kohm

Vcc = 3.6V: maximum pull down resistor = 2.5 kohm

In addition, a higher current consumption occurs during high/low RST/NMI signal transition when using improper resistors.

**Workaround**

Use external pulldown resistors below the listed values or directly drive RST/NMI low to generate a reset.

**TA12*****TA Module*****Category**

Functional

**Function**

Interrupt is lost (slow ACLK)

**Description**

Timer\_A counter is running with slow clock (external TACLK or ACLK) compared to MCLK. The compare mode is selected for the capture/compare channel and the CCRx register

is incremented by one with the occurring compare interrupt (if TAR = CCRx). Due to the fast MCLK the CCRx register increment (CCRx = CCRx+1) happens before the Timer\_A counter has incremented again. Therefore the next compare interrupt should happen at once with the next Timer\_A counter increment (if TAR = CCRx + 1). This interrupt gets lost.

**Workaround** Switch capture/compare mode to capture mode before the CCRx register increment. Switch back to compare mode afterwards.

**TA16** *TA Module*

**Category** Functional

**Function** First increment of TAR erroneous when IDx > 00

**Description** The first increment of TAR after any timer clear event (POR/TACLRL) happens immediately following the first positive edge of the selected clock source (INCLK, SMCLK, ACLK or TACLK). This is independent of the clock input divider settings (ID0, ID1). All following TAR increments are performed correctly with the selected IDx settings.

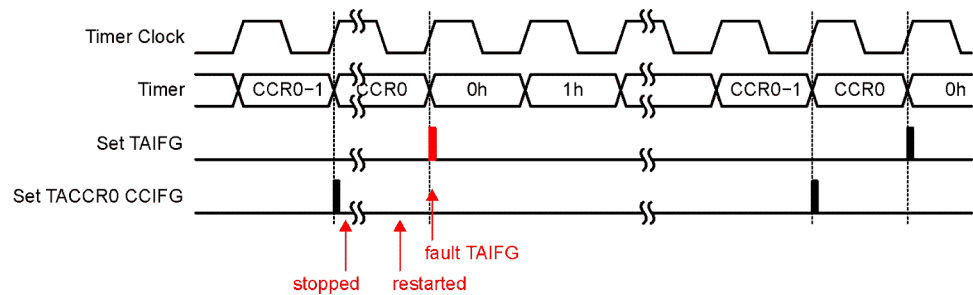
**Workaround** None

**TA21** *TA Module*

**Category** Functional

**Function** TAIFG Flag is erroneously set after Timer A restarts in Up Mode

**Description** In Up Mode, the TAIFG flag should only be set when the timer counts from TACCR0 to zero. However, if the Timer A is stopped at TAR = TACCR0, then cleared (TAR=0) by setting the TACLRL bit, and finally restarted in Up Mode, the next rising edge of the TACLK will erroneously set the TAIFG flag.



**Workaround** None.

**TAB22** *TAB Module*

**Category** Functional

**Function** Timer\_A/Timer\_B register modification after Watchdog Timer PUC

**Description** Unwanted modification of the Timer\_A/Timer\_B registers TACTL/TBCTL and TAIV/TBIV can occur when a PUC is generated by the Watchdog Timer(WDT) in Watchdog mode and any Timer\_A/Timer\_B counter register TACCRx/TBCCRx is incremented/decremented (Timer\_A/Timer\_B does not need to be running).

**Workaround** Initialize TACTL/TBCTL register after the reset occurs using a MOV instruction (BIS/BIC may not fully initialize the register). TAIV/TBIV is automatically cleared following this

initialization.

Example code:

```
MOV.W #VAL, &TACTL
or
MOV.W #VAL, &TBCTL
```

Where, VAL=0, if Timer is not used in application otherwise, user defined per desired function.

## TB1

### ***TB Module***

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#### **Category**

Functional

#### **Function**

"Equal mode" when grouping compare latches

#### **Description**

The "equal mode" for loading the compare latches (CLLD = 3) cannot be used when compare latches are grouped (TBCLGRP > 0).

#### **Workaround**

None

## TB2

### ***TB Module***

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#### **Category**

Functional

#### **Function**

Interrupt is lost (slow ACLK)

#### **Description**

Timer\_B counter is running with slow clock (external TBCLK or ACLK) compared to MCLK. The compare mode is selected for the capture/compare channel and the CCRx register is incremented by 1 with the occurring compare interrupt (if TBR = CCRx). Due to the fast MCLK, the CCRx register increment (CCRx = CCRx + 1) happens before the Timer\_B counter has incremented again. Therefore, the next compare interrupt should happen at once with the next Timer\_B counter increment (if TBR = CCRx + 1). This interrupt is lost.

#### **Workaround**

Switch capture/compare mode to capture mode before the CCRx register increment. Switch back to compare mode afterward.

## TB3

### ***TB Module***

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#### **Category**

Functional

#### **Function**

Timer\_B Port is switched to 3-state independent of selected function

#### **Description**

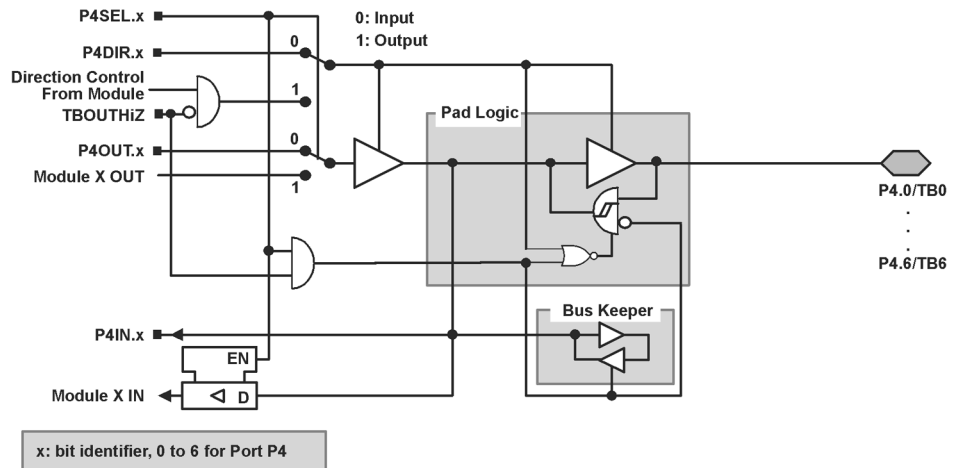
Incorrect 3-state function of Ports P4.0/TB0 through P4.6/TB6 (TBoutHiZ control). If TBoutHiZ is set to high, all ports P4.0/TB0 through P4.6/TB6 are set to 3-state, independent of the P4SEL.x control signals. This means a port P4.x is switched to 3-state with TBoutHiZ, even if it is not selected for Timer\_B function. In addition, the ports P4.0/TB0 through P4.6/TB6 are switched to 3-state with TBoutHiZ, even if the port direction (direction control from module) is set to input. This is in accordance with the specification description but, nevertheless, is an unexpected behavior.

#### **Workaround**

No workaround.

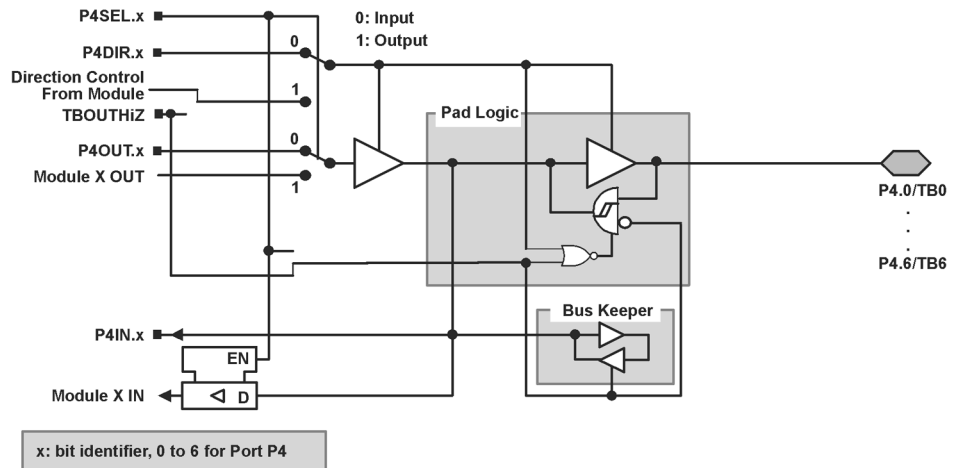
Port function as specified

port P4, P4.0 to P4.6, input/output with Schmitt-trigger



Port Realization With TB3 Bug

port P4, P4.0 to P4.6, input/output with Schmitt-trigger



**TB4**

**TB Module**

**Category**

Functional

**Function**

Group function

**Description**

If the shadow registers are organized in groups (SHR = 1, 2, or 3), one shadow register is not loaded correctly. This happens when the last CCRx register within a group is loaded at exactly the same time that the timer counter reaches the event for loading the shadow registers (TBR = 0 or TBR = CCR0).

**Workaround**

Ensure that all CCRx registers within a group are loaded before the shadow register load event occurs.

**TB14**

**TB Module**

**Category**

Functional

**Function**

PWM output

<b>Description</b>	<p>The PWM output unit may behave erroneously if the condition for changing the PWM output (EQUx or EQU0) and the condition for loading the shadow register TBCLx happen at the same time. Depending on the load condition for the shadow registers (CLLD bits in TBCCTLx), there are four possible error conditions:</p> <ol style="list-style-type: none"> <li>1. Change CCRx register from any value to CCRx = 0 (for example, sequence for CCRx = 4 3 2 0 0 0)</li> <li>2. Change CCRx register from CCRx = 0 to any value (for example, sequence for CCRx = 0 0 0 2 3 4)</li> <li>3. Change CCRx register from any value to current SHD0 (CCR0) value (for example, sequence for CCRx = 4 2 5 SHD0 3 8)</li> <li>4. Change CCRx register from current SHD0 (CCR0) value to any value (for example, sequence for CCRx = 4 2 SHD0 5 3 8)</li> </ol>
<b>Workaround</b>	No general workaround available.

## TB16 *TB Module*

---

**Category** Functional

**Function** First increment of TBR erroneous when IDx > 00

**Description** The first increment of TBR after any timer clear event (POR/TBCLR) happens immediately following the first positive edge of the selected clock source (INCLK, SMCLK, ACLK, or TBCLK). This is independent of the clock input divider settings (ID0, ID1). All following TBR increments are performed correctly with the selected IDx settings.

**Workaround** None

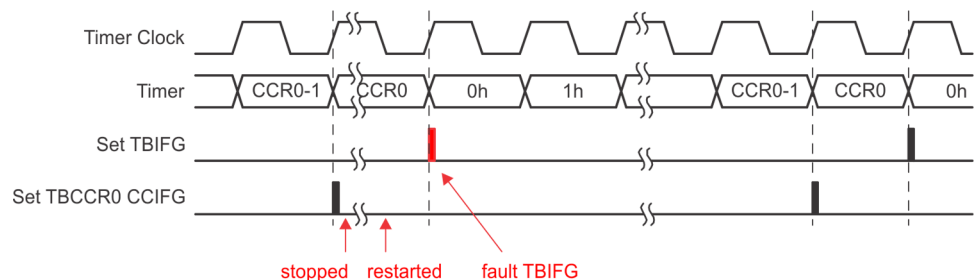
## TB24 *TB Module*

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**Category** Functional

**Function** TBIFG Flag is erroneously set after Timer B restarts in Up Mode

**Description** In Up Mode, the TBIFG flag should only be set when the timer resets from TBCCR0 to zero. However, if the Timer B is stopped at TBR = TBCCR0, then cleared (TBR=0) by setting the TBCLR bit, and finally restarted in Up Mode, the next rising edge of the TBCLK will erroneously set the TBIFG flag.



**Workaround** None.

## US13 *USART Module*

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**Category** Functional

**Function** Unpredictable program execution

**Description** USART interrupts requested by URXS can result in unpredictable program execution if this request is not served within two bit times of the received data.

**Workaround** Ensure that the interrupt service routine is entered within two bit times of the received data.

**US14** ***USART Module***

---

**Category** Functional

**Function** Start edge of received characters may be ignored

**Description** When using the USART in UART mode with UxBR0 = 0x03 and UxBR1 = 0x00, the start edge of received characters may be ignored due to internal timing conflicts within the UART state machine. This condition does not apply when UxBR0 is > 0x03.

**Workaround** None

**US15** ***USART Module***

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**Category** Functional

**Function** UART receive with two stop bits

**Description** USART hardware does not detect a missing second stop bit when SPB = 1. The Framing Error Flag (FE) will not be set under this condition and erroneous data reception may occur.

**Workaround** None (Configure USART for a single stop bit, SPB = 0)

**WDG2** ***WDG Module***

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**Category** Functional

**Function** Incorrectly accessing a flash control register

**Description** If a key violation is caused by incorrectly accessing a flash control register, the watchdog interrupt flag is set in addition to the expected PUC.

**Workaround** None

## 7 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

### Changes from October 9, 2019 to May 11, 2021

**Page**

- Changed the document format and structure; updated the numbering format for tables, figures, and cross references throughout the document.....6
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