

Power Supply Design Seminar

(Demo Hall Presentation)

Designing Low-EMI Power Converters for Industrial & Automotive Systems

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Designing Low-EMI Power Converters for Industrial & Automotive Systems

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- Key features of Wide Input Voltage (Wide VIN) Automotive and Industrial DC/DC Converters
- Techniques for reducing emissions in Switching Power Supplies
- EMI Mitigation by proper PCB Layout
- Spread Spectrum
- Slew Rate Control
- Input EMI filter design
- WEBENCH EMI tool

Wide Vin DC-DC Leadership



Synchronous Switchers

- Synchronous regulators up to 40V operation
- 2.2MHz switching frequency options
- Very Low (μA) no-load quiescent current
- LM536xx 0.65A to 3.5A 2.1MHz
- Coming Soon: LMR23610/25/30 1A, 2.5A, 3A

Specialty Buck Regulators

- Synchronous regulators, up to 100V operation
- Fly-Buck support: smallest multi-output bias supplies
- \bullet LM5160A and LM5161 65V and 100V Sync Buck / Fly-Buck
- Coming soon: LM5165/6 Ultra-low Sync Buck
- 65V, 150mA/500mA versions w/ 10uA standby Iq



uck



Wide Vin Buck Regulator Power Modules

- Integrated inductor modules with input range to 60V
- Proven EMI performance
- LMZ34202 and LMZ36002 4.5V to 42V or 60V at 2A



Wide Vin DC-DC Leadership



Buck-Boost, Boost Controllers

- Synch & non-synch buck-boost controllers up to 75Vin & 200W
- Stackable, multi-phase synchronous boost controllers
- LM5175-Q1 USB PD (Type C) reference designs in progress
- Coming soon: LM5170 the first 48<->12 bidirectional controller



- The only 100V buck controller in the TI portfolio
- Emulated Current Mode simplifies high step-down & high current
- LM5140/1 Dual/single 2.2MHz buck controllers 3.8-65Vin, 2.2MHz, 30µA Iq, phase interleaved, EMI reduction



Smart Diode Controllers

- Replaces reverse voltage protection diode with NFET to reduce losses
- Ideal diode for wired OR' applications with multiple power sources
- No ground connection required zero quiescent current
- LM74610 / LM74670







VBAT







EMI in Switch Mode Power Supplies



Engineering Approach To Mitigate EMI





Steps To Mitigate EMI In PCB Design



What Can We Do In PCB Layout?



Critical Path Area Comparison



Critical Path Area Comparison

Critical Path Area Reduction

Grounding

• Buck Regulator Comparison with Cin location (single Cin, smaller loop area)



PINOUT Designed With Performance In Mind

Compact, Low EMI, Good Thermal Performance for Industrial applications



Parallel input cap placement for Automotive Applications





PCB Layout Tips...for High Current Buck Controller Applications



EMI Mitigation by PCB Layout

Critical Path Loop Reduction

Grounding

- Ground Plane
 - Return Current Takes The Least IMPEDANCE Path
 - o Unbroken Ground Plane Provides Shortest Return Path Image current return path





Buck Switch Node Voltage Ringing Due to Circuit Parasitics



FET Package and PBC Parasitics

- MOSFET package inductance, and capacitance
- PCB inductance and capacitance



Buck Switch Node Waveform with Slew Rate Control No Snubber



 R_{HOH} =10 ohms R_{HOL} =0 ohms L_{LOH} =10 ohms R_{LOL} =10 ohms

Benefits of LM5140 Gate Driver Slew Rate Control

- High and Low Side FET Drivers have separate source and sink pins allowing the turn-on and turn-off times to be independently controlled via series resistors
- Optimizing gate drive slew rate reduces EMI with ~1% reduction in efficiency (as measured on LM5140 EVM)







Measured on LM5140 Standard EVM: 2.2MHz, 3.3V/5.0Vout

Spread spectrum/Dithering – What is it?

Spread spectrum is a means of reducing EMI interference by dithering the switching regulator frequency, in the case of LM53600/53601, by +/-4%. This has the effect of widebanding the noise spectrum and reducing the fundamental energy, as shown



Combining Slew Rate Control and Spread Spectrum

- Wide Input voltage range: 3.8V to 65V (Abs Max 70V)
- Fixed output 3.3V, 5V, or adjustable from 1.5V-15V
- Fixed 2.2MHz, or 440 kHz oscillator; frequency can be shifted from the fundamental via RT pin resistor setting
 - RT adjustment range 300kHz-500kHz, or 1.8MHz-2.53MHz
- EMC features:
 - Spread Spectrum selectable
 - Gate drive slew rate control
 - Synchronizable to external clock
 - FPWM mode disables skip mode at light load assuring operation at fixed frequency



Simplified Schematic

Differential Mode Conducted EMI



- Differential Mode Conducted EMI
 - o In DC-DC converter topology differential mode noise usually dominates common mode
 - o Involves the Normal Operation of the Circuit
 - o Only Related to CURRENT, not voltage
 - For example, with the same power level Buck converter, lower input voltage means higher input current, thus worse conducted EMI
- Why we care?

o Excessive Input and/or Output Voltage Ripple can compromise operation of Supply and/or Load

Input Filter Design for Conducted EMI

There are two basic requirements for the conducted EMI filter:

- Meet noise attenuation requirement (i.e. CISPR 25)
- Not interfere with the normal operation of the SMPS converter

Example of a Buck regulator

- No input filter
- Fails CISPR 25 regulation limits

But how do we estimate how much filter attenuation to add?



Conducted EMI plot LM53603 without Input Filter

Necessary Input Filter Attenuation

Methods of estimating the filter attenuation prior to making a certified measurement with a LISN (Line Impedance Stabilization Network) and Spectrum Analyzer

- <u>Method 1 estimation using oscilloscope measurement</u>
 - Measure the input ripple voltage using a wide bandwidth scope and calculate the attenuation. $|Att|_{dB} = 20 \times \log(\frac{VinRipple_{pk-pk}}{1\mu V}) - V_{MAX}$
 - VMAX is the allowed $dB\mu V$ noise level for the particular EMI standard.
- Method 2 Estimation using the first harmonic of input current
 - Assume the input current is a square wave (small ripple approximation)

$$|\text{Att}|_{\text{dB}} = 20 \log \left(\frac{\frac{1}{\pi^2 f_{\text{s}} C_{\text{IN}}} \sin(\pi D)}{1 \, \mu \text{V}}\right) - \text{V}_{\text{max}}$$

- VMAX is the allowed $dB\mu V$ noise level for the particular EMI standard.
- CIN is the existing input capacitor of the Buck converter.
- D is the duty cycle , I is the output current, Fs is the switching frequency



Typical Conducted EMI Filter



Follow the design steps described in AN-2162.

- Calculate the required attenuation using Method 1 or Method 2.
- Capacitor **CIN** represents the existing capacitor at the input of the switching converter.
- Inductor Lf is usually between 1μ H and 10μ H, but can be smaller to reduce losses if this is a high current design.
- Calculate capacitor Cf. Use the larger of the two values (Cfa and Cfb) below:

$$C_{fa} = \frac{C_{IN}}{C_{IN}L_{f}(2\pi f_{s}/10)^{2} - 1} \qquad \qquad C_{fb} = \frac{1}{L_{f}} \left(\frac{10^{|Att|_{dB}/40}}{2\pi f_{s}}\right)^{2}$$

• Capacitor Cd and its ESR provides damping so that the Lf Cf filter does not affect the stability of the switching converter.

$$C_d \ge 4 \times C_{IN} \quad ESR_d \approx \sqrt{L_f/C_{IN}}$$

Conducted EMI Before and After Filter – LM53603 – 150kHz to 30MHz

Input 13V, Output 5V@3A, resistor load, CISPR 25 CE setup Red Line: Class 5 Limits (Peak/Average Detection) Yellow: Peak detection result, Blue: Average detection result Using guidelines on the previous slides the filter was implemented and Conducted EMI retaken





COT Converter with EMI Input Filter



Conducted EMI Plots: CISPR 22 Class B (150kHz \rightarrow 30MHz)

Input 13.5V, Output 5V @ 100mA, COT mode, Resistive load, CISPR 22 CE setup

230kHz



Input filter: $L_{IN} = 22 \ \mu H$, $C_{\chi_2} = 10 \mu F$



Conducted EMI Filter Design Tool- Webench



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