

CDx4AC164, CDx4ACT164 8-Bit Serial-In/Parallel-Out Shift Register

1 Features

- **Buffered** inputs
- Typical propagation delay
 - 6ns at $V_{CC} = 5V$, $T_A = 25$ °C, $C_L = 50$ pF
- SCR-latchup-resistant CMOS process and circuit
- Speed of bipolar FAST™/AS/S with significantly reduced power consumption
- Balanced propagation delays
- AC types feature 1.5V to 5.5V operation and balanced noise immunity at 30% of the supply
- ±24mA output drive current
 - Fanout to 15 FAST™ ICs
 - Drives 50Ω transmission lines

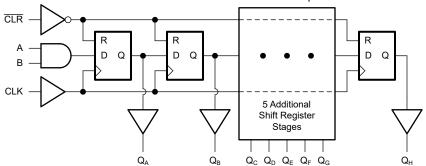
2 Description

The 'AC164 and 'ACT164 are 8-bit serial-in/parallelout shift registers with asynchronous reset that utilize Advanced CMOS Logic technology.

Device Information

PART NUMBER	PACKAGE ⁽¹⁾	PACKAGE SIZE(2)	BODY SIZE(3)
CDx4AC(T)164	BQA (WQFN, 14)	3mm × 2.5mm	3mm × 2.5mm
	D (SOIC, 14)	8.65mm × 6mm	8.65mm × 3.9mm
	N (PDIP, 14)	19.3mm x 9.4mm	19.3mm x 6.35mm
	PW (TSSOP, 14)	5mm x 6.4mm	5mm x 4.4mm

- For more information, see Section 10.
- The package size (length × width) is a nominal value and includes pins, where applicable.
- The body size (length × width) is a nominal value and does not include pins.



Functional Diagram

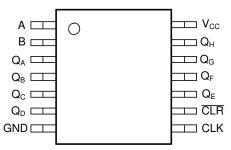


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3 Pin Configuration and Functions



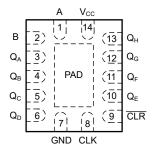


Figure 3-1. CD54AC(T)164 J Package; 14-Pin CDIP; CD74AC(T)164 D, N, or PW Package; 14-Pin SOIC, PDIP, or TSSOP (Top View)

Figure 3-2. CD74AC(T)164 BQA Package; 14-Pin WQFN (Top View)

Table 3-1. Pin Functions

	PIN	TVDE4	DESCRIPTION
NAME	NO.	TYPE1	DESCRIPTION
Α	1	I	Gated serial input A
В	2	I	Gated serial input B
Q _A	3	0	Parallel output A
Q _B	4	0	Parallel output B
Q _C	5	0	Parallel output C
Q_D	6	0	Parallel output D
GND	7	G	Ground
CLK	8	I	Clock input, rising edge triggered
CLR	9	I	Asynchronous register clear input, active low
Q _E	10	0	Parallel output E
Q _F	11	0	Parallel output F
Q_G	12	0	Parallel output G
Q _H	13	0	Parallel output H
V _{CC}	14	Р	Positive supply
Thermal pa	ad <mark>2</mark>	_	The thermal pad can be connect to GND or left floating. Do not connect to any other signal or supply.

- 1. Signal Types: I = Input, O = Output, P = Power, G = Ground.
- 2. BQA package only.



4 Specifications

4.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)(1)

			MIN	MAX	UNIT
V _{CC}	DC Supply Voltage		-0.5	6	V
I _{IK}	DC Input Diode Current	$(V_1 < -0.5V \text{ or } V_1 > V_{CC} + 0.5V)$		± 20	mA
I _{OK}	DC Output Diode Current	(V _O < -0.5V or V _O > V _{CC} + 0.5V)		±50	mA
Io	DC Output Source or Sink Current per Output Pin	(V _O > -0.5V or V _O < V _{CC} + 0.5V)		±50	mA
I _{CC} or I _{GND} ⁽²⁾	DC V _{CC} or Ground Current			±100	mA

⁽¹⁾ Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

4.2 ESD Ratings

			VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±2000	V

⁽¹⁾ JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

4.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

			MIN	MAX	UNIT
T _A	Temperature Range		-55	125	°C
	Supply Voltage Range			·	
V _{CC} (1)	AC Types	AC Types			
	ACT Types	4.5	5.5	V	
V _I , V _O	DC Input or Output Voltage	DC Input or Output Voltage			
	Input Rise and Fall Slew Rate			·	
dt/dv	AC Types	1.5V to 3V		50	ns
at/av	AC Types	3.6V to 5.5V		20	ns
	ACT Types	4.5V to 5.5V		10	ns

⁽¹⁾ Unless otherwise specified, all voltages are referenced to ground.

4.4 Thermal Information

			CD74AC(T)164					
THERMAL METRIC ⁽¹⁾		BQA (WQFN)	D (SOIC)	N (PDIP)	PW (TSSOP)	UNIT		
		14 PINS	14 PINS	14 PINS	14 PINS			
R _{θJA}	Junction-to-ambient thermal resistance	105.3	106.6	90	148.0	°C/W		

⁽¹⁾ θ_{JA} is measured with the component mounted on an evaluation PC board in free air.

⁽²⁾ For up to 4 outputs per device, add ±25mA for each additional output.



4.5 DC Electrical Specifications

	DADAMETED	TEST CO	NDITIONS	V 00	25°C	;	-40°C TO	85 °C	-55°C TO 125°C		UNITS
	PARAMETER	V _I (V)	I _O (mA)	V _{CC} (V)	MIN	MAX	MIN	MAX	MIN	MAX	UNIIS
AC TYPE	ES .					'					
				1.5	1.2	-	1.2	-	1.2	-	V
V_{IH}	High Level Input Voltage	-	-	3	2.1	-	2.1	-	2.1	-	V
	voltage			5.5	3.85	-	3.85	-	3.85	-	V
				1.5	-	0.3	-	0.3	-	0.3	V
V_{IL}	Low Level Input Voltage	-	-	3	-	0.9	-	0.9	-	0.9	V
	voltage			5.5	-	1.65	-	1.65	-	1.65	V
			-0.05	1.5	1.4	-	1.4	-	1.4	-	V
			-0.05	3	2.9	-	2.9	-	2.9	-	V
			-0.05	4.5	4.4	-	4.4	-	4.4	-	V
V _{OH}	High Level Output	V _{IH} or V _{IL}	-4	3	2.58	-	2.48	-	2.4	-	V
	Voltage		-24	4.5	3.94	-	3.8	-	3.7	-	V
			-75 ⁽¹⁾ ⁽²⁾	5.5	-	-	3.85	-	_	-	V
			-50 (1) (2)	5.5	-	-	-	-	3.85	-	V
			0.05	1.5	-	0.1	-	0.1	-	0.1	V
			0.05	3	-	0.1	-	0.1	-	0.1	V
	V _{OL} Low Level Output V _{IH} or		0.05	4.5	-	0.1	-	0.1	-	0.1	V
V _{OL}		V _{IH} or V _{IL}	12	3	-	0.36	-	0.44	_	0.5	V
			24	4.5	-	0.36	-	0.44	_	0.5	V
			75 (1) (2)	5.5	-	-	-	1.65	-	-	V
			50 ⁽¹⁾ (2)	5.5	-	-	_	-	-	1.65	V
I	Input Leakage Current	V _{CC} or GND	-	5.5	-	±0.1	-	±1	-	±1	μΑ
I _{CC}	Quiescent Supply Current MSI	V _{CC} or GND	0	5.5	-	8	-	80	-	160	μA
ACT TYP	PES					'					
V _{IH}	High Level Input Voltage	-	-	4.5 to 5.5	2	-	2	-	2	-	V
V _{IL}	Low Level Input Voltage	-	-	4.5 to 5.5	-	0.8	-	0.8	-	0.8	V
			-0.05	4.5	4.4	-	4.4	-	4.4	-	V
,,	High Level Output	\/\/	-24	4.5	3.94	-	3.8	-	3.7	-	V
V _{OH}	Voltage	V _{IH} or V _{IL}	-75 ⁽¹⁾ (2)	5.5	-	-	3.85	-	-	-	V
			-50 ⁽¹⁾ ⁽²⁾	5.5	-	-	-	-	3.85	-	V
			0.05	4.5	-	0.1	-	0.1	-	0.1	V
.,	Low Level Output	\/\/	24	4.5	-	0.36	-	0.44	-	0.5	V
V _{OL}	Voltage	V _{IH} or V _{IL}	75 ⁽¹⁾ ⁽²⁾	5.5	-	-	-	1.65	-	-	V
			50 (1) (2)	5.5	-	-	-	-	-	1.65	V
I _I	Input Leakage Current	V _{CC} or GND	-	5.5	-	±0.1	-	±1	-	±1	μA
I _{CC}	Quiescent Supply Current MSI	V _{CC} or GND	0	5.5	-	8	-	80	-	160	μΑ



PARAMETER		TEST CONDITIONS		V 00	25°C		-40°C TO 85 °C		-55°C TO 125°C		UNITS
		V _I (V)	I _O (mA)	V _{cc} (V)	MIN	MAX	MIN	MAX	MIN	MAX	ONITS
ΔI _{CC}	Additional Supply Current per Input Pin TTL Inputs High 1 Unit Load	V _{CC} -2.1	-	4.5 to 5.5	-	2.4	-	2.8	-	3	mA

- (1) Test one output at a time for a 1-second maximum duration. Measurement is made by forcing current and measuring voltage to minimize power dissipation.
- (2) Test verifies a minimum 50Ω transmission-line-drive capability at 85°C, 75Ω at 125°C.

Table 4-1. ACT Input Load Table

INPUT	UNIT LOAD
A, B	0.5
CLR	0.74
CLK	0.71

Unit load is ΔI_{CC} limit specified in DC Electrical Specifications Table, e.g., 2.4mA max at 25°C.

4.6 Prerequisite for Switching Function

	DADAMETED	V 00	-40°C TO	85°C	-55°C TO 125°C		UNITS
	PARAMETER	V _{CC} (V)	MIN	MAX	MIN	MAX	UNITS
	AC TYPES						
f _{MAX}		1.5	7	-	6	-	MHz
	Max. Clock Frequency	3.3 ⁽¹⁾	62	-	54	-	MHz
		5 ⁽²⁾	86	-	75	-	MHz
t _W		1.5	49	-	56	-	ns
	MR Pulse Width	3.3	5.5	-	6.3	-	ns
		5	3.9	-	4.5	-	ns
t _W		1.5	73	-	84	-	ns
	CP Pulse Width	3.3	8.2	-	9.4	-	ns
		5	5.9	-	6.7	-	ns
t _{SU}		1.5	27	-	31	-	ns
	Set-up Time	3.3	3.1	-	3.5	-	ns
		5	2.2	-	2.5	-	ns
t _H		1.5	27	-	31	-	ns
	Hold Time	3.3	3.1	-	3.5	-	ns
		5	2.2	-	2.5	-	ns
t _{REM}		1.5	1	-	1	-	ns
	MR to CP Removal Time	3.3	1	-	1	-	ns
		5	1	-	1	-	ns
	ACT TYPES	-					
f _{MAX}	Max. Clock Frequency	5 ⁽²⁾	80	-	70	-	MHz
t _W	MR Pulse Width	5	3.9	-	4.5	-	ns
t _W	CP Pulse Width	5	6.2	-	7.1	-	ns
t _{SU}	Set-up Time	5	2.2	-	2.5	-	ns
t _H	Hold Time	5	2.6	-	3	-	ns
t _{REM}	MR to CP Removal Time	5	0	-	0	-	ns

^{(1) 9. 3.3}V Min at 3.6V, Max at 3V.

^{(2) 10. 5}V Min at 5.5V, Max at 4.5V.



4.7 Switching Specifications

Input t_r , $t_f = 3$ ns, $C_L = 50$ pF (Worst Case)

	PARAMETER	V 00	-40°	C TO 85°C	;	-55°C TO 125°C			UNIT
	PARAMETER	V _{CC} (V)	MIN	TYP	MAX	MIN	TYP	MAX	UNII
AC TYPES									
t _{PLH} , t _{PHL}		1.5	-	-	143	-	-	157	ns
	Propagation Delay, CP to Qn	3.3 (1)	4.5	-	15.9	4.4	-	17.5	ns
	5 ⁽²⁾	3.2	-	11.4	3.1	-	12.5	ns	
t _{PLH} , t _{PHL}		1.5	-	-	158	-	-	174	ns
Propagation Delay, $\overline{\rm MR}$ to Qn	3.3	5	-	17.7	4.9	-	19.5	ns	
		5	3.6	-	12.6	3.5	-	13.9	ns
Cı	Input Capacitance	-	-	-	10	-	-	10	pF
C _{PD} (3)	Power Dissipation Capacitance	-	-	150	-	-	150	-	pF
ACT TYPES			•						
t _{PLH} , t _{PHL}	Propagation Delay, CP to Qn	5 (2)	3.8	-	13.5	3.7	-	14.9	ns
t _{PLH} , t _{PHL}	Propagation Delay, MR to Qn	5	4.1	-	14.4	4	-	15.8	ns
Cı	Input Capacitance	-	-	-	10	-	-	10	pF
C _{PD} (3)	Power Dissipation Capacitance	-	-	150	-	-	150	-	pF

^{(1) 3.3}V Min at 3.6V, Max at 3V.

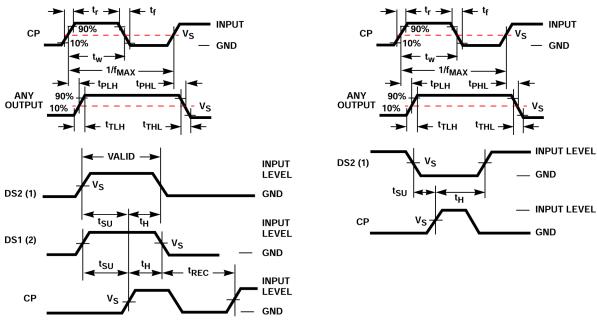
^{(2) 5}V Min at 5.5V, Max at 4.5V.

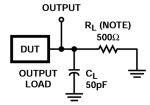
⁽³⁾ C_{PD} is used to determine the dynamic power consumption per device.



5 Parameter Measurement Information

Load Circuit And Voltage Waveforms





For AC Series Only: When VCC = 1.5V, RL = $1k\Omega$.For AC Series Only: When VCC = 1.5V, RL = $1k\Omega$.For AC Series Only: When VCC = 1.5V, RL = $1k\Omega$.

Figure 5-1. Propagation Delay Times

Table 5-1. Propagation Delay Times

	AC	ACT
Input Level	V _{CC}	3V
Input Switching Voltage, V _S	0.5 V _{CC}	1.5V
Output Switching Voltage, V _S	0.5 V _{CC}	0.5 V _{CC}



6 Detailed Description

6.1 Overview

The CDx4AC(T)164 is an 8-bit shift register with 2 serial inputs (A and B) connected through an AND gate, as well as an asynchronous clear (CLR). The device requires a high signal on both A and B to set the input data line high; a low signal on either input will set the input data line low. Data at A and B can be changed while CLK is high or low, provided that the minimum set-up time requirements are met.

The CLK pin of the CDx4AC(T)164 is rising-edge triggered, activating on the transition from LOW to HIGH. Upon a positive-edge trigger, the device will store the result of the (A \bullet B) input data line in the first register and propagate each register's data to the next register. The data of the last register, Q_H, will be discarded at each clock trigger. If a low signal is applied to the $\overline{\text{CLR}}$ pin, then the CDx4AC(T)164 will set all registers to a logical low value immediately.

6.2 Functional Block Diagram

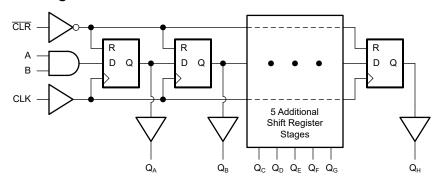


Figure 6-1. Logic Diagram (Positive Logic) for CDx4AC(T)164

6.3 Feature Description

6.3.1 Standard CMOS Inputs

This device includes standard CMOS inputs. Standard CMOS inputs are high impedance and are typically modeled as a resistor in parallel with the input capacitance given in the *Electrical Characteristics*. The worst case resistance is calculated with the maximum input voltage, given in the *Absolute Maximum Ratings*, and the maximum input leakage current, given in the *Electrical Characteristics*, using Ohm's law (R = V ÷ I).

Standard CMOS inputs require that input signals transition between valid logic states quickly, as defined by the input transition time or rate in the *Recommended Operating Conditions* table. Failing to meet this specification will result in excessive power consumption and could cause oscillations. More details can be found in *Implications of Slow or Floating CMOS Inputs*.

Do not leave standard CMOS inputs floating at any time during operation. Unused inputs must be terminated at V_{CC} or GND. If a system will not be actively driving an input at all times, then a pull-up or pull-down resistor can be added to provide a valid input voltage during these times. The resistor value will depend on multiple factors; a $10k\Omega$ resistor, however, is recommended and will typically meet all requirements.

6.3.2 TTL-Compatible CMOS Inputs

This device includes TTL-compatible CMOS inputs. These inputs are specifically designed to interface with TTL logic devices by having a reduced input voltage threshold.

TTL-compatible CMOS inputs are high impedance and are typically modeled as a resistor in parallel with the input capacitance given in the *Electrical Characteristics*. The worst case resistance is calculated with the maximum input voltage, given in the *Absolute Maximum Ratings*, and the maximum input leakage current, given in the *Electrical Characteristics*, using Ohm's law $(R = V \div I)$.

TTL-compatible CMOS inputs require that input signals transition between valid logic states quickly, as defined by the input transition time or rate in the *Recommended Operating Conditions* table. Failing to meet this



specification will result in excessive power consumption and could cause oscillations. More details can be found in the *Implications of Slow or Floating CMOS Inputs* application report.

Do not leave TTL-compatible CMOS inputs floating at any time during operation. Unused inputs must be terminated at V_{CC} or GND. If a system will not be actively driving an input at all times, a pull-up or pull-down resistor can be added to provide a valid input voltage during these times. The resistor value will depend on multiple factors; however, a $10k\Omega$ resistor is recommended and typically will meet all requirements.

6.4 Device Functional Modes

Table 6-1 lists the functional modes of the CDx4AC(T)164.

Table 6-1. Function Table

INPUTS ⁽¹⁾				FUNCTION	
Α	В	CLR	CLK	FUNCTION	
Х	Х	L	Х	Shift register is cleared.	
L	Х	Н	1	First stage of the shift register goes low. Other stages store the data of previous stage, respectively.	
Х	L	Н	1	First stage of the shift register goes low. Other stages store the data of previous stage, respectively.	
Н	Н	Н	1	First stage of the shift register goes high. Other stages store the data of previous stage, respectively.	

(1) H = High Voltage Level, L = Low Voltage Level, X = Do Not Care



7 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

7.1 Application Information

In this application, the CDx4AC(T)164 is used to control seven-segment displays. Unlike other I/O expanders, the CDx4AC(T)164 does not need a communication interface for control. It can easily operate with simple GPIO pins. Additional control is provided with two serial inputs that feed into an AND gate.

At power-up, the initial state of the shift registers is unknown. To give them a defined state, the shift register needs to be cleared. An RC can be connected to the $\overline{\text{CLR}}$ pin as shown in Figure 7-1 to initialize the shift register to all zeros.

7.2 Typical Application

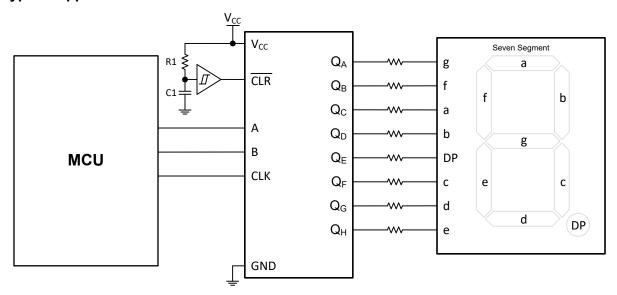


Figure 7-1. Typical Application Block Diagram

7.2.1 Design Requirements

7.2.1.1 Power Considerations

Ensure the desired supply voltage is within the range specified in the *Recommended Operating Conditions*. The supply voltage sets the device's electrical characteristics of the device as described in the *Electrical Characteristics* section.

The positive voltage supply must be capable of sourcing current equal to the maximum static supply current, I_{CC}, listed in the *Electrical Characteristics*, and any transient current required for switching.

The ground must be capable of sinking current equal to the total current to be sunk by all outputs of the CDx4AC(T)164 plus the maximum supply current, I_{CC}, listed in the *Electrical Characteristics*, and any transient current required for switching. The logic device can only sink as much current that can be sunk into its ground connection. Ensure the maximum total current through GND listed in the *Absolute Maximum Ratings* is not exceeded.

The CDx4AC(T)164 can drive a load with a total capacitance less than or equal to 50pF while still meeting all of the data sheet specifications. Larger capacitive loads can be applied; however, it is not recommended to exceed 50pF.

The CDx4AC(T)164 can drive a load with total resistance described by $R_L \ge V_O / I_O$, with the output voltage and current defined in the *Electrical Characteristics* table with V_{OL} . When outputting in the HIGH state, the output voltage in the equation is defined as the difference between the measured output voltage and the supply voltage at the V_{CC} pin.

Total power consumption can be calculated using the information provided in *CMOS Power Consumption and Cpd Calculation*.

Thermal increase can be calculated using the information provided in *Thermal Characteristics of Standard Linear* and Logic (SLL) Packages and Devices.

CAUTION

The maximum junction temperature, $T_{J(max)}$ listed in the *Absolute Maximum Ratings*, is an additional limitation to prevent damage to the device. Do not violate any values listed in the *Absolute Maximum Ratings*. These limits are provided to prevent damage to the device.

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7.2.1.2 Input Considerations

Input signals must cross $V_{IL(max)}$ to be considered a logic LOW, and $V_{IH(min)}$ to be considered a logic HIGH. Do not exceed the maximum input voltage range found in the *Absolute Maximum Ratings*.

Unused inputs must be terminated to either V_{CC} or ground. The unused inputs can be directly terminated if the input is completely unused, or they can be connected with a pull-up or pull-down resistor if the input will be used sometimes, but not always. A pull-up resistor is used for a default state of HIGH, and a pull-down resistor is used for a default state of LOW. The drive current of the controller, leakage current into the CDx4AC(T)164 (as specified in the *Electrical Characteristics*), and the desired input transition rate limits the resistor size. A $10k\Omega$ resistor value is often used due to these factors.

The CDx4AC(T)164 has CMOS inputs and thus requires fast input transitions to operate correctly, as defined in the *Recommended Operating Conditions* table. Slow input transitions can cause oscillations, additional power consumption, and reduction in device reliability.

Refer to the Feature Description section for additional information regarding the inputs for this device.

7.2.1.3 Output Considerations

The ground voltage is used to produce the output LOW voltage. Sinking current into the output will increase the output voltage as specified by the V_{OL} specification in the *Electrical Characteristics*.

Unused outputs can be left floating. Do not connect outputs directly to V_{CC} or ground.

Refer to the Feature Description section for additional information regarding the outputs for this device.

7.2.1.4 Application Curve

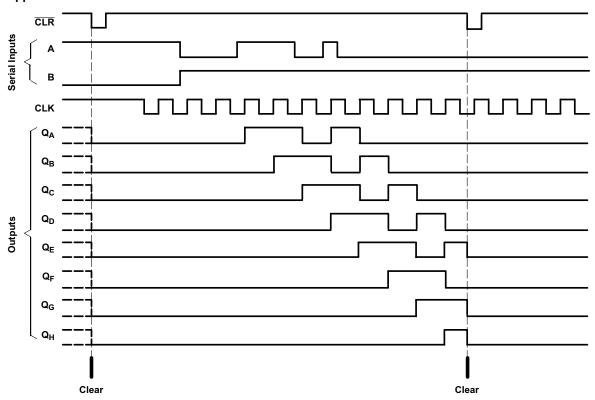


Figure 7-2. Application Timing Diagram

7.3 Power Supply Recommendations

The power supply can be any voltage between the minimum and maximum supply voltage rating located in the $Recommended\ Operating\ Conditions$. Each V_{CC} terminal should have a good bypass capacitor to prevent



power disturbance. A $0.1\mu\text{F}$ capacitor is recommended for this device. It is acceptable to parallel multiple bypass capacitors to reject different frequencies of noise. The $0.1\mu\text{F}$ and $1\mu\text{F}$ capacitors are commonly used in parallel. The bypass capacitor should be installed as close to the power terminal as possible for best results.

7.4 Layout

7.4.1 Layout Guidelines

- · Bypass capacitor placement
 - Place near the positive supply terminal of the device
 - Provide an electrically short ground return path
 - Use wide traces to minimize impedance
 - Keep the device, capacitors, and traces on the same side of the board whenever possible
- Signal trace geometry
 - 8mil to 12mil trace width
 - Lengths less than 12cm to minimize transmission line effects
 - Avoid 90° corners for signal traces
 - Use an unbroken ground plane below signal traces
 - Flood fill areas around signal traces
 - For traces longer than 12cm
 - · Use impedance controlled traces
 - · Source-terminate using a series damping resistor near the output
 - Avoid branches; buffer signals that must branch separately

7.4.2 Layout Example

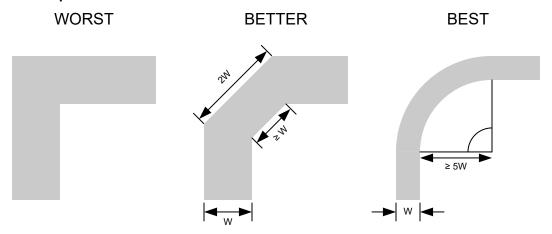


Figure 7-3. Example Trace Corners for Improved Signal Integrity



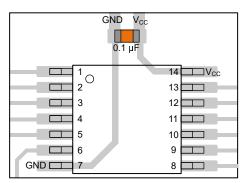


Figure 7-4. Example Bypass Capacitor Placement for TSSOP and Similar Packages

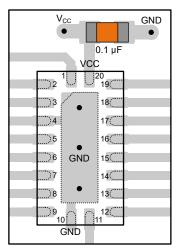


Figure 7-5. Example Bypass Capacitor Placement for WQFN and Similar Packages

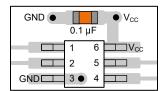


Figure 7-6. Example Bypass Capacitor Placement for SOT, SC70 and Similar Packages

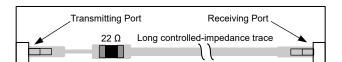


Figure 7-7. Example Damping Resistor Placement for Improved Signal Integrity



8 Device and Documentation Support

TI offers an extensive line of development tools. Tools and software to evaluate the performance of the device, generate code, and develop solutions are listed below.

8.1 Documentation Support

8.1.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, CMOS Power Consumption and Cpd Calculation application report
- Texas Instruments, *Designing With Logic* application report
- Texas Instruments, Thermal Characteristics of Standard Linear and Logic (SLL) Packages and Devices application report

8.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

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8.6 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.



9 Device and Documentation Support

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9.1 Documentation Support (Analog)

9.1.1 Related Documentation

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 9-1. Related Links

PARTS	PRODUCT FOLDER	SAMPLE & BUY	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY
CD54AC164	Click here	Click here	Click here	Click here	Click here
CD74AC164	Click here	Click here	Click here	Click here	Click here
CD54ACT164	Click here	Click here	Click here	Click here	Click here
CD74ACT164	Click here	Click here	Click here	Click here	Click here

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10 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision C (April 2024) to Revision D (October 2024)

Page

- Added Feature Descriptions section, Typical Application section, and Layout Example diagram......



•	Changed pin names throughout data sheet: DS1 \rightarrow A, DS2 \rightarrow B, Q0 \rightarrow Q _A , Q1 \rightarrow Q _B , Q2 \rightarrow Q _C , Q3 \rightarrow Q _D ,
	$CP \to CLK, !MR \to \overline{CLR}, Q4 \to Q_E, Q5 \to Q_F, Q7 \to Q_G, \to Q_H, \to V_{CC} \dots \dots$

Changes from Revision B (November 2023) to Revision C (April 2024)	
Herbert 100 Marshar 100 Marshar 100 Marshar 100 MM	

Page

11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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