

Technical documentation



Support & training

**[RES11A-Q1](https://www.ti.com/product/RES11A-Q1)** [SLPS755A](https://www.ti.com/lit/pdf/SLPS755) – OCTOBER 2023 – REVISED DECEMBER 2023

**RES11A-Q1 Automotive, Matched, Thin-Film Resistor Dividers With 1-kΩ Inputs**

# **1 Features**

<span id="page-0-0"></span>**TEXAS** 

**INSTRUMENTS** 

- AEC-Q200 Qualified for automotive applications: – Temperature: –40°C to +125°C
- High ratio matching precision: ±0.05 % (maximum)
- Low drift: ±2 ppm/°C TCR (maximum)

# **2 Applications**

- Precision voltage divider, precision level translation
- Gain and attenuating amplifiers
- Difference amplifiers with high CMRR
- Discrete instrumentation amps with high gain accuracy
- Fully differential amplifiers with high gain accuracy
- Pinpoint comparator threshold setting

# **3 Description**

The RES11A-Q1 is a matched pair of resistive dividers, implemented in thin-film SiCr with Texas Instruments' modern, high-performance, analog CMOS process. The device has a nominal input resistance of 1 kΩ, for low thermal and current noise, and is available in several nominal ratios to meet a wide array of system needs. Use the RES11A-Q1 in an inverse gain configuration by simply rotating the device placement by 180°. This feature supports layout reuse and increases flexibility for applications such as discrete instrumentation or difference amplifier implementations.

The RES11A-Q1 series features high ratio-matching precision, with the measured ratio of each divider within ±120 ppm (typical) of the nominal. This precision is maintained over the temperature range, with a maximum ratio drift of only ±2 ppm/°C. Additionally, the biased long-term stability of the device has been proven through thorough characterization.

The RES11A-Q1 is automotive qualified under AEC-Q200 temperature grade 1. The temperature range is specified from –40°C to +125°C. The device is offered in an 8‑pin, SOT‑23-THIN package, with a body size of 2.9 mm  $\times$  1.6 mm (body size is a nominal value and does not include pins).

#### **Package Information**



(1) For more information, see [Section 11](#page-30-0).

(2) The package size (length × width) is a nominal value and includes pins, where applicable.



**Device Information**

(1) Preview information (not Advanced Information).





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# **4 Pin Configuration and Functions**



# **Figure 4-1. DDF Package, 8-Pin SOT-23-THN (Top View)**

#### **Table 4-1. Pin Functions**



# <span id="page-3-0"></span>**5 Specifications**

## **5.1 Absolute Maximum Ratings**

over operating free-air temperature range (unless otherwise noted) $(1)$ 



(1) Operation outside the *Absolute Maximum Ratings* may cause permanent device damage. *Absolute Maximum Ratings* do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If used outside the *Recommended Operating Conditions* but within the *Absolute Maximum Ratings*, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

(2) Maximum instantaneous voltage permitted under transient conditions. Avoid sustained operation at these voltage levels because the resulting self-heating causes  $T_J$  to exceed 150°C.

# **5.2 ESD Ratings**



(1) AEC Q100-002 indicates that HBM stressing must be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

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## **5.3 Recommended Operating Conditions**

over operating free-air temperature range (unless otherwise noted)



(1) Assumes RθJA = 156.2 °C/W. Applies whether the specified current is applied across a *single* divider, or *both* dividers simultaneously. For long-term use under static dc biases, keep the current less than or equal to the nominal value. For long-term use under dynamic conditions, keep the RMS current less than or equal to the maximum value. Adhere to the limitations in *Absolute Maximum Ratings*.

#### **5.4 Thermal Information**



(1) For more information about traditional and new thermal metrics, see the *[Semiconductor and IC Package Thermal Metrics](https://www.ti.com/lit/pdf/SPRA953)* application report.

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## **5.5 Electrical Characteristics**





# **5.5 Electrical Characteristics (continued)**

at  $T_A$  = 25°C (unless otherwise noted)



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# <span id="page-7-0"></span>**5.5 Electrical Characteristics (continued)**





(1) Relation of  $R_{G1}$  /  $R_{IN1}$  or  $R_{G2}$  /  $R_{IN2}$  to nominal ratio.<br>(2) Relation of  $R_{G1}$ ,  $R_{IN1}$ ,  $R_{G2}$ , or  $R_{IN2}$  to nominal resistation

(2) Relation of  $R_{G1}$ ,  $R_{IN1}$ ,  $R_{G2}$ , or  $R_{IN2}$  to nominal resistance.

(3) The specification is the result of this expression, given as a percentage (multiplied by 100%).

(4) Specified by characterization.

(5) The specification is the calculated CMRR when implemented in a difference amplifier configuration with an ideal op-amp, such that the only source of common-mode error is the resistor network. See the *[Optimizing CMRR in Differential Amplifier Circuits With](https://www.ti.com/lit/pdf/sboa582) [Precision Matched Resistor Divider Pairs](https://www.ti.com/lit/pdf/sboa582)* application note for more information. Effects over frequency are not included. If the circuit is configured in an attenuating gain, this result changes accordingly.

# **5.6 AEC-Q200 Qualification Testing**

at  $T_A$  = 25°C (unless otherwise noted). Compliance is specified by design and/or characterization.



<span id="page-8-0"></span>

# **5.7 Typical Characteristics**





# **5.7 Typical Characteristics (continued)**





# **5.7 Typical Characteristics (continued)**



# **5.7 Typical Characteristics (continued)**



# <span id="page-12-0"></span>**6 Parameter Measurement Information**

## **6.1 DC Measurement Configurations**

An example of the circuit configuration used for dc measurements is shown in Figure 6-1. Voltage  $V_{Dx}$  refers to the voltage across a given divider, such as  $V_{D1}$  for divider 1. Voltage V<sub>Rx</sub> refers to the voltage across a given resistor, such as  $V_{\text{RIN1}}$  for  $R_{\text{IN1}}$  or  $V_{\text{RG1}}$  for  $R_{\text{G1}}$ .



**Figure 6-1. DC Measurement Terminology for Divider 1** 

When the RES11A-Q1 is used to set the gain of an op amp (shown in Figure 6-2), the ratio of the resistors in a divider sets the amplifier gain according to  $G = R_G / R_{IN}$ . Discrete-difference-amplifier and instrumentationamplifier circuits are variations on this ratiometric use case. Typical and maximum parameter values for ratio tolerance (t<sub>D1</sub>, t<sub>D2</sub>) are expressed in terms of R<sub>Gx</sub> / R<sub>INx</sub> to simplify calculations for these circuits.

However, another valid use case of the RES11A-Q1 is a simple voltage divider, where the midpoint voltage  $V_{\text{MID}}$ is equal to the input voltage V<sub>D</sub> multiplied by R<sub>G</sub> / (R<sub>IN</sub> + R<sub>G</sub>), or by R<sub>IN</sub> / (R<sub>IN</sub> + R<sub>G</sub>) as shown in Figure 6-3. Typical and maximum parameter values for ratio tolerance of these voltage-divider circuits, expressed in terms of  $R_{INX}$  / ( $R_{INX}$  +  $R_{GX}$ ), are provided.







**Figure 6-3. Voltage-divider circuit** 

Figure 6-4 shows the circuit configuration used for CMRR calculations. For an ideal amplifier with no offset and infinite CMRR, the effective circuit CMRR is entirely a function of the matching of the resistors. See [Section](#page-18-0) [8.1.1.1](#page-18-0) and the *[Optimizing CMRR in Differential Amplifier Circuits With Precision Matched Resistor Divider Pairs](https://www.ti.com/lit/pdf/SBOA582)*  [application note](https://www.ti.com/lit/pdf/SBOA582) for more information.



**Figure 6-4. CMRR Calculation Reference Schematic** 



## <span id="page-13-0"></span>**6.2 AC Measurement Configurations**

Figure 6-5 shows the circuit configuration used for capacitance measurements. For the RES11A-Q1, a 1-M $\Omega$ R<sub>KNOWN</sub> resistance and 10-pF C<sub>KNOWN</sub> capacitance are used. The circuit creates an impedance divider; the resulting gain-vs-frequency relationship is used to calculate the parasitic capacitance in parallel with the resistor under test (in this case, R<sub>IN1</sub>). Calibration with an empty socket is performed to account for board parasitics. The ac source is swept from 100 Hz to 50 MHz.



**Figure 6-5. Capacitance Measurement Reference Schematic** 

Figure 6-6 shows the circuit configuration that is used for bandwidth measurements. The ac source is swept from 100 kHz to 500 MHz.



**Figure 6-6. Bandwidth Measurement Reference Schematic** 

Figure 6-7 shows the circuit configuration used for crosstalk measurements. The ac source is swept from 100 Hz to 100 MHz.



**Figure 6-7. Crosstalk Measurement Reference Schematic** 

# <span id="page-14-0"></span>**7 Detailed Description**

# **7.1 Overview**

The RES11A-Q1 consists of four precision thin-film SiCr resistors, arranged to form two matched dividers. The device has two *input* resistors, R<sub>IN1</sub> and R<sub>IN2</sub>, both nominally 1 kΩ. The device also has two *gain* resistors, R<sub>G1</sub> and R<sub>G2</sub>, with values that depend on the nominal ratio (R<sub>Gx</sub> / R<sub>INx</sub>) of the RES11A-Q1 device in question. The resistors are arranged with R<sub>IN1</sub> and R<sub>G1</sub> in series to form the first divider, and R<sub>IN2</sub> and R<sub>G2</sub> in series to form the second divider. Two GND pins are also provided to bias the device substrate.

# **7.2 Functional Block Diagram**



# **7.3 Feature Description**

## **7.3.1 Ratiometric Matching**

The resistors of the RES11A-Q1 are described by the following equations:

$$
R_{IN1} = R_{INnom} \times (1 + t_{abs}) = R_{INnom} \times (1 + t_{RIN1}) \times (1 + t_{SiCr})
$$
\n
$$
(1)
$$

$$
R_{IN2} = R_{INnom} \times (1 + t_{RIN2}) \times (1 + t_{SiCr})
$$
\n(2)

$$
R_{G1} = R_{Gnom} \times (1 + t_{RG1}) \times (1 + t_{SiCr})
$$
\n
$$
(3)
$$

$$
R_{G2} = R_{Gnom} \times (1 + t_{RG2}) \times (1 + t_{SiCr})
$$
\n<sup>(4)</sup>

R<sub>INnom</sub> and R<sub>Gnom</sub> are the nominal values of each resistor. The parameter  $t_{abs}$  is an error term that describes the absolute tolerance of the RES11A-Q1 device in question, such that |*tabs*| ≤ 12%. The absolute tolerance is dominated by the variation in the SiCr resistivity, *tSiCr*. The four resistors of a given RES11A-Q1 are interdigitated and come from the same area of the wafer; therefore, *tSiCr* is effectively the same for each of the four resistors, although *tSiCr* varies on a part-to-part basis. The following examples show that when each divider is considered in ratiometric terms, these error terms drop out. Parameter *tRx* is an error term that describes the remaining effective tolerance of each resistor of the given RES11A-Q1 device after accounting for the universal *tSiCr*.

$$
\frac{R_{Gx}}{R_{INx}} = \frac{R_{Gnom} \times (1 + t_{RGx}) \times (1 + t_{SiCr})}{R_{INnom} \times (1 + t_{RINx}) \times (1 + t_{SiCr})} = \frac{R_{Gnom} \times (1 + t_{RGx})}{R_{INnom} \times (1 + t_{RINx})} = G_{nom} \times \frac{(1 + t_{RGx})}{(1 + t_{RINx})} = G_{x}
$$
(5)  

$$
\frac{R_{INx}}{R_{INx} + R_{Gx}} = \frac{R_{INnom} \times (1 + t_{RINx}) \times (1 + t_{SiCr})}{R_{INnom} \times (1 + t_{RINx}) \times (1 + t_{SiCr}) + R_{Gnom} \times (1 + t_{RGx}) \times (1 + t_{SiCr})} = \frac{R_{INnom} \times (1 + t_{RINx})}{R_{INnom} \times (1 + t_{RINx}) + R_{Gnom} \times (1 + t_{RGx}) \times (1 + t_{SiCr})}
$$

The RES11A-Q1 is specified with a maximum divider ratio tolerance of 0.05%, meaning that the relationship between the actual divider ratio G<sub>x</sub> and nominal ratio G<sub>nom</sub> of a given divider *x* is described by the following:

$$
G_{\rm X} = G_{\rm nom} \times (1 + t_{\rm Dx}) \tag{7}
$$

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(6)



such that  $t_{Dx} \le 0.05\%$ . Because any devices that do not meet these criteria are screened out at final test, these equations can be used with [Equation 5](#page-14-0) to prove the effective bounds of *tRx*. Therefore, despite the device absolute end-to-end tolerance bounds of ±12%, the effective error tolerances of each resistor (for ratiometric applications) are within approximately ±0.025%, for the worst-case *tRx*.

The RES11A-Q1 is specified with a maximum divider matching tolerance of 0.1%, meaning that the relationship between the ratio of divider 1 (G<sub>1</sub>) and ratio of divider 2 (G<sub>2</sub>) is described by the following:

$$
t_{M} = t_{D2} - t_{D1} = \frac{G_2 - G_1}{G_{nom}}
$$
 (8)

By definition,  $|t_M| \le 0.1\%$ . Again, the previous equations relate  $t_M$  to the parameters  $t_{DX}$  and  $t_{RX}$ . As a result of the interdigitation of the two dividers, the actual typical magnitude of *tM* is significantly lower than this maximum value, depending on the specific RES11A-Q1 device. This value is used to calculate the common-mode rejection ratio (CMRR) when implementing a difference amplifier circuit. For example, typical *tM* for the RES11A40-Q1 is approximately 85 ppm, and the typical CMRR is 95.4 dB.

#### **7.3.2 Ratiometric Drift**

The ratiometric matching of the RES11A-Q1 provides a benefit not just for initial conditions, but also when considering parametric drift. The resistors must be considered individually, in absolute terms, and ratiometrically to each other, in matched terms. The absolute temperature coefficients of each resistor show strong correlation, with the coefficient of R<sub>IN1</sub> comparable to that of R<sub>IN2</sub> and the coefficient of R<sub>G1</sub> comparable to that of R<sub>G2</sub>. The absolute temperature coefficient (in Ω/°C) of each R<sub>G</sub> is approximately G<sub>nom</sub> times greater than that of the comparable R<sub>IN</sub>; hence, the normalized absolute temperature coefficient (in  $ppm$ /°C) of every resistor is about the same.

Because the resistors of the RES11A-Q1 are interdigitated, and occupy a small footprint, the die temperature of the device is effectively common to each of the four resistors. As the temperature changes, each resistor experiences a similar temperature rise. Because the resistors have very similar temperature coefficients, the ratio of R<sub>G</sub> to R<sub>IN</sub> is well preserved. For example, the RES11A40-Q1 has a typical absolute temperature coefficient of approximately 18 ppm/°C for  $R_{\text{IN}}$  or  $R_{\text{G}}$ . When considered in ratiometric terms, the typical temperature coefficient of t<sub>D1</sub> or t<sub>D2</sub> is –0.2 ppm/°C, and the temperature coefficient of t<sub>M</sub> is 0.05 ppm/°C.

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#### **7.3.3 Predictable Voltage Coefficient**

The voltage coefficients of the RES11A-Q1 are almost entirely related to self-heating, where the power dissipated in the device raises the die temperature. As previously mentioned, the commonality of this temperature rise leads to a comparable shift in each resistor, such that the divider ratio is well preserved.

Applying voltage *V* across resistor or divider *R* results in the loss of a corresponding power dissipation of *P =*   $V^2$  / R, in the form of heat in the device die. This heat leads to a localized increase in the junction temperature, which in turn causes the same parametric shifts previously discussed in the context of temperature coefficients. TCR is specified as a function of ambient temperature; therefore, use the effective junction-to-ambient thermal resistance to determine the effective temperature rise and calculate the nominal or expected shift.



The difference of the expected value of *R* from the actual value of *R* describes the actual-to-expected mismatch error of *R*, due to non-temperature-related effects on the voltage coefficient. Similar to the logarithmic conformity error of a logarithmic amplifier or the integrated nonlinearity error of an ADC, this error describes the deviations of the actual device behavior from the predictable behavior. While the absolute magnitude of the shift varies, the slope or trend is predictable.



**Figure 7-3. Resistor Actual-to-expected Mismatch vs Voltage**

The measured value of *R* for low bias (measured by sourcing a very small current) is used with the actual value of *R* to calculate the effective voltage coefficient of resistance.



(10)

Voltage coefficient (Ω/V) =  $\frac{\text{Rbiased} - \text{Riniital}}{\text{Vhis}}$ Vbias

This exercise is repeated for each R<sub>x</sub>, t<sub>D1</sub>, t<sub>D2</sub>, and t<sub>M</sub>, to calculate the voltage coefficients associated with each parameter. For example, the RES11A40-Q1 has a typical absolute voltage coefficient of approximately 0.02 Ω/V for R<sub>IN</sub> or R<sub>G</sub>. When considered in ratiometric terms, the typical voltage coefficient of t<sub>D1</sub> or t<sub>D2</sub> is 2 ppm/V, and the voltage coefficient of  $t_M$  is 0.5 ppm/V.

# **7.3.4 Ultra-Low Noise**

Noise in resistors can be evaluated in two separate regions: low-frequency flicker noise and wideband thermal noise. Flicker, or 1/f noise, is extremely important for systems that require signal gain at frequencies less than 100 Hz. Thermal noise typically dominates in the region greater than 1 kHz, and increases as resistor magnitude increases. Noise is modeled as a voltage source in series with the resistor.

For a resistive divider such as the RES11A-Q1, the thermal noise as measured at the center tap of two resistors,  $R_{IN}$  and  $R_G$ , is equivalent to the thermal noise of a resistor with value  $R_{IN} \parallel R_G$ :

$$
e_N = \sqrt{(4k_BTR)}\tag{11}
$$

where:

- $e_N$  is the thermal noise density in nV/ $\sqrt{Hz}$
- $T$  is the absolute temperature in kelvins  $(K)$
- $k_B$  is the Boltzmann constant, 1.381  $\times$  10-23 J/K

 $R = R_{IN} || R_G$ 

As an example, for the RES11A40-Q1 at 25°C:

$$
e_N = \sqrt{(4k_BTR)} = \sqrt{4 \times 1.38E^{-23} \frac{J}{K} \times 278 K \times (1 k\Omega \parallel 4 k\Omega)} = 3.5 \text{ nV} / \sqrt{Hz}
$$
(12)

# **7.4 Device Functional Modes**

The RES11A-Q1 is typically used with the two independently biased resistor dividers.  $R_{\text{IN1}}$  and  $R_{\text{G1}}$  in series form a resistive divider, with R<sub>IN2</sub> and R<sub>G2</sub> in series forming another divider. However, the two dividers do not have to be used independently. The resistors can be connected in series or in parallel like any other resistor.

Use one of the two GND pins to bias the part substrate. Connect the substrate to signal ground or a similar low-impedance bias point or plane for best noise rejection. While two GND/SUB connection pins are available on the device, connect only *one* of these to the ground plane. The two GND pins are internally connected through the substrate, which is not intended to conduct significant currents. Connect only *one* GND pin at a time and leave the other pin floating to prevent current return paths from developing through the substrate.

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# **8 Application and Implementation**

#### **Note**

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

#### **8.1 Application Information**

#### **8.1.1 Discrete Difference Amplifier**

The RES11A-Q1 is commonly used to implement a simple difference amplifier. The ratiometric matching between the two resistor dividers improves CMRR performance and gain drift for the circuit, when compared to a similar implementation using unmatched discrete resistors. The basic circuit is shown in Figure 8-1.



**Figure 8-1. Discrete Difference Amplifier Using RES11A-Q1** 

#### *8.1.1.1 Difference-Amplifier Common-Mode Rejection Analysis*

In this simple difference amplifier configuration, the nominal CMRR is calculated as:

$$
CMRR = 20 \times \log_{10} \left( \left| \frac{A_D}{A_{CM}} \right| \right) \tag{14}
$$

The term  $A_D$  is the differential gain of the circuit, and the term  $A_{CM}$  is the common-mode gain of the circuit. These are defined as the following:

$$
A_{D} \times = \frac{v_{OUT}}{v_{D}} = 0.5 \times \frac{\left(\frac{R_{G1}}{R_{G1} + R_{INI}}\right) + \left(\frac{R_{G2}}{R_{G2} + R_{IN2}}\right)}{\left(\frac{R_{IN2}}{R_{G2} + R_{IN2}}\right)}
$$
(15)

$$
A_{CM} = \frac{V_{OUT}}{V_{CM}} = \frac{\left(\frac{R_{G1}}{R_{G1} + R_{IN1}}\right) - \left(\frac{R_{G2}}{R_{G2} + R_{IN2}}\right)}{\left(\frac{R_{IN2}}{R_{G2} + R_{IN2}}\right)}
$$
(16)

Therefore,



$$
CMRR = 20 \times \log_{10} \left( \left| 2 \times \frac{R_{G1} \times (R_{IN2} + R_{G2}) - R_{G2} \times (R_{IN1} + R_{G1})}{R_{G1} \times (R_{IN2} + R_{G2}) + R_{G2} \times (R_{IN1} + R_{G1})} \right| \right)
$$
(17)

When this expression is evaluated with the definitions given in [Section 7.3.1,](#page-14-0) assuming the worst-case scenario of the most unbalanced divider matching possible,

$$
CMRR = 20 \times \log_{10} \left( \left| \frac{G_{\text{nom}} + 1 + \text{ }t_{\text{Rx}}^2 (1 - G_{\text{nom}})}{4 \times \text{ }t_{\text{Rx}}} \right| \right) \tag{18}
$$

Because *tRx<sup>2</sup>* << 1, the worst-case CMRR is approximated as

$$
CMRR = 20 \times \log_{10} \left( \left| \frac{G_{\text{nom}} + 1}{4 \times t_{\text{Rx}}} \right| \right) \tag{19}
$$

By definition, the parameter  $t_M$  describes the effective error that is otherwise equivalent to 4  $\times$   $t_\chi$  for an unmatched divider network, and so the maximum value of *tM* can be used to calculate the same worst-case result. Likewise, the typical value of *tM* can be used to approximate the typical CMRR.

$$
CMRR = 20 \times \log_{10}\left(\left|\frac{G_{\text{nom}} + 1}{t_M}\right|\right) \tag{20}
$$

For example, the worst-case CMRR for a RES11A40-Q1 device with G = 4 is approximately 74.0 dB, with a typical CMRR of approximately 95.4 dB. In comparison, implementation of a comparable G = 4 difference amplifier with unmatched 0.1%-tolerance resistors results in a worst-case CMRR of approximately 62 dB.

In a difference amplifier configuration, the CMRR of the op amp contributes error as well. The op-amp CMRR is considered in parallel with the CMRR of the resistor network, as per the following equation:

$$
\frac{1}{\text{CMRR}_{\text{TOTAL}}} = \frac{1}{\text{CMRR}_{\text{AMP}}} + \frac{1}{\text{CMRR}_{\text{RESISTORS}}} \tag{21}
$$

Additional mismatches in the divider end-to-end resistances reduce the effective CMRR of a difference amplifier. While the low absolute tolerance span of the RES11A-Q1 (235 ppm typical) helps reduce these concerns, parasitic trace resistances can lead to additional mismatches that impact the CMRR specs. Bench results from a difference amplifier implementation of the RES11A40-Q1 and the OPA210 are presented for various deliberate input-impedance mismatches.



**Figure 8-2. Effect of Input Impedance Mismatch on Common-mode Rejection Ratio**

#### **8.1.2 Discrete Instrumentation Amplifiers**

The RES11A-Q1 can be used to in conjunction with a dual-channel operational amplifier to implement a discrete instrumentation amplifier (INA). The ratiometric matching between the two resistor dividers improves CMRR performance for the circuit when compared to a similar implementation using unmatched discrete resistors,

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and results in better overtemperature and overaging gain drift characteristics. INAs are often used instead of difference amplifiers when high input impedance and low bias currents are needed, such as when measuring bridge sensors.

Discrete INAs are often configured as a differential-input differential-output circuit as shown in Figure 8-3. While not shown, if needed, use an additional discrete difference amplifier stage (requiring a second RES11A-Q1 and another op-amp channel) to convert the differential output voltage to a single-ended voltage (for example, when driving a single-ended ADC). This extra stage can also add an additional offset and provide additional gain, effectively mimicking the common three-amplifier INA architecture.



#### **Figure 8-3. Differential-Input, Differential-Output Instrumentation Amplifier Using the RES11A-Q1**

Less commonly, a discrete INA can be implemented as a differential-input, single-ended output circuit as shown in Figure 8-4. This topology maintains high input impedances, allows an offset to be applied, and gives a single-ended output without requiring a third amplifier channel. The offset must be driven by a low-impedance source, such as a reference buffer. When designing a discrete INA, carefully consider the output swing and input common-mode range limitations of the amplifiers used in the circuit design process.







#### *8.1.2.1 Instrumentation Amplifier Common-Mode Rejection Analysis*

The differential-input, differential-output instrumentation amplifier shown in [Figure 8-3](#page-20-0) has a common-mode gain of  $A_{CM}$  = 1 V/V. The differential gain is described by the following (assuming an ideal amplifier):

$$
A_{D} = \frac{R_{G1} + R_{G2}}{R_{IN1} + R_{IN2}} + 1 = G_{nom} \times \frac{(1 \pm t_{RG1}) + (1 \pm t_{RG2})}{(1 \pm t_{RIN1}) + (1 \pm t_{RIN2})} + 1
$$
\n(24)

Because the worst-case-stage CMRR occurs when the differential gain is lowest, and the common-mode gain is unity, the minimum CMRR is evaluated as:

$$
\frac{A_D}{A_{CM}} = G_{\text{nom}} \times \frac{(1 - t_{RG1}) + (1 - t_{RG2})}{(1 + t_{RIN1}) + (1 + t_{RIN2})} + 1 = G_{\text{nom}} \times \frac{1.9995}{2.0005} + 1
$$
\n(25)

For example, for an instrumentation amplifier with RES11A90-Q1, the worst-case CMRR is:

$$
\frac{A_D}{A_{CM}} = G_{\text{nom}} \times \frac{(1 - t_{\text{RG1}}) + (1 - t_{\text{RG2}})}{(1 + t_{\text{RIN1}}) + (1 + t_{\text{RIN2}})} + 1 = 9 \text{ V/V} \times \frac{1.9995}{2.0005} + 1 = 9.9955 \text{ V/V}
$$
\n(26)

#### **8.1.3 Fully Differential Amplifier**

The RES11A-Q1 can be used to set the gain of a fully differential amplifier, such as the THP210. The ratiometric matching between the two resistor dividers leads to improved gain matching and CMRR performance for the circuit, when compared to a similar implementation using unmatched discrete resistors.

Figure 8-5 shows a generic schematic representation of a fully differential amplifier driving a differential ADC, with a RES11A-Q1 used to set the amplifier gain.



**Figure 8-5. Fully-differential Amplifier Gain Setting Using RES11A-Q1** 

<span id="page-22-0"></span>

#### **8.2 Typical Application**

#### **8.2.1 Common-Mode Shifting Input Stage**

The RES11A-Q1 can be used to implement a common-mode attenuator at the high-impedance inputs of an instrumentation amplifier (INA). This configuration extends the usable signal range, so long as the maximum differential voltage limitation of each resistor divider is respected.

Figure 8-6 shows an example of a high-side current-sense circuit where a differential voltage,  $V_{SHUNT}$ , develops across a sense resistor with an undesirably high common-mode voltage  $V_{CM}$ .  $V_{REF}$  is used to shift input common-mode voltages  $V_{MID1}$  and  $V_{MID2}$  to levels within the specified input common-mode range of the INA. The amplifier output,  $V_{\text{OUT}}$ , is a scaled function of  $V_{\text{SHUNT}}$ , such that nominally:

$$
V_{OUT} = V_{SHUNT} \times \left(\frac{R_{IN}}{R_G + R_{IN} + R_{EQUIV}}\right)
$$
\n(28)

 $V<sub>OUT</sub>$  can be gained up further by the INA stage, to make maximal use of the effective resolution of a downstream ADC. In practice  $R_{EQUIV}$  is optional; however, if  $R_{EQUIV}$  =  $R_{SHUNT}$ , this resistance equalizes the nominal impedance between  $V_{CM}$  and each of the INA high-impedance inputs, thus improving CMRR performance. Select an INA with input bias currents  $I_{B1}$  and  $I_{B2}$  <<  $I_{STATIC1}$  and  $I_{STATIC2}$ , such as the [INA333](https://www.ti.com/product/INA333) or [INA823](https://www.ti.com/product/INA823). Select a RES11A-Q1 device with a sufficiently high divider series resistance so that I<sub>STATIC1</sub> and I<sub>STATIC2</sub>  $<<$   $I_{I \Omega AD}$ .



**Figure 8-6. RES11A-Q1 Common-Mode Shifting Circuit**

To achieve a desired nominal input common-mode voltage,  $V_{MID1TARGE}$ , set  $V_{REF}$  as follows:

$$
V_{REF} = V_{MID1TARGE} \times \left(\frac{R_G + R_{IN} + R_{EQUIV}}{R_G + R_{EQUIV}}\right) - V_{CM} \times \left(\frac{R_G + R_{IN} + R_{EQUIV}}{R_G + R_{EQUIV}} - 1\right)
$$
(29)



#### *8.2.1.1 Design Requirements*

Consider a level-shifting application where a high-side current shunt measurement from an 18-V supply rail must be measured by a 3.3-V amplifier and ADC.



#### *8.2.1.2 Detailed Design Procedure*

The design parameters are used with the aforementioned equations to select a nominal target G. When the possible V<sub>REF</sub> voltages available in the system are considered, V<sub>REF</sub> = 0 V with G = 9 is found to result in a V<sub>MID1</sub> value of 1.8 V, well within the input common-mode range of a 3.3‑V rail-to-rail amplifier such as the [OPA392.](https://www.ti.com/product/OPA392) When the corresponding RES11A90-Q1 is employed, the loss terms  $I<sub>STATIC1</sub>$  and  $I<sub>STATIC2</sub>$  are nominally 1.80 mA and 1.77 mA for I<sub>LOAD</sub> = 300 mA, resulting in an effective floor of 1.77 mA for I<sub>LOAD</sub>. For simplicity, the error contributions of the INA stage  $V_{OS}$  and I<sub>B</sub> are ignored.

For the INA stage, an integrated TI instrumentation amplifier (IA) can be used. Alternatively, a discrete approach can be implemented using another RES11A-Q1 device or devices, and one or more op amps. For this example, an IA stage is constructed with two channels of a [OPA4392](https://www.ti.com/product/OPA4392) and a second RES11A90-Q1 (R<sub>IN3</sub>, R<sub>G3</sub>, R<sub>IN4</sub>, and  $R_{G4}$ ). This stage is in turn cascaded with a difference amplifier stage, constructed with the third amplifier channel and a RES11A00-Q1 (R<sub>IN5</sub>, R<sub>G5</sub>, R<sub>IN6</sub>, and R<sub>G6</sub>). The level-shifting stage gain of 10<sup>-1</sup>, multiplied by the instrumentation amplifier stage gain of 10, results in an effective unity-gain transfer function for V<sub>SHUNT</sub>. Therefore, the differential output voltage for this stage is approximately 0.3 V, with amplifier outputs of 1.936 V and 1.634 V. After the final difference amplifier stage gain of G = 10, the common-mode voltage drops out and the maximum value of the resulting  $V_{\text{OUT}}$  is nominally 3.0 V, compatible with a single-ended 3.3-V ADC such as the [ADS7046.](https://www.ti.com/product/ADS7046) If desired, the fourth channel of the OPA4392 can be used to buffer this output signal and serve as a dedicated ADC driver.



**Figure 8-7. High-Side Current Shunt Common-Mode Shifting Circuit**



#### *8.2.1.3 Application Curves*





## <span id="page-25-0"></span>**8.3 Power Supply Recommendations**

The ratio of a given RES11A-Q1 device dictates the maximum differential voltage rating for the resistor dividers of the device. See the *Absolute Maximum Ratings* and *Recommended Operating Conditions* for device-specific values under transient and sustained bias conditions, respectively. See Figure 8-12 for approximate values, assuming  $R_{\theta,IA}$  = 156.2°C/W and that both dividers are biased to the same dc voltage at the same time. Keep  $T_{\theta}$ less than the absolute maximum rating of 150°C.



**Figure 8-12. Maximum Recommended Divider Voltage vs Ambient Temperature**

# **8.4 Layout**

## **8.4.1 Layout Guidelines**

For best operational performance of the device, use good printed-circuit board (PCB) layout practices, including:

- Reduce parasitic coupling by running input traces as far away from supply or output traces as possible. If these traces cannot be kept separate, crossing the sensitive trace perpendicular is much better as opposed to in parallel with the noisy trace.
- Place the external components as close to the device as possible.
- Keep the length of input traces as short as possible. Always remember that the input traces are the most sensitive part of the circuit. For differential circuits, match the length of the input traces as best possible.
- Keep high impedance input signals away from noisy traces.
- Make sure system supply voltages are adequately filtered.
- Clean the PCB following board assembly for best performance.
- Any precision integrated circuit can experience performance shifts resulting from moisture ingress into the plastic package. Following any aqueous PCB cleaning process, bake the PCB assembly to remove moisture introduced into the device packaging during the cleaning process. A low temperature, post-cleaning bake at 85°C for 30 minutes is sufficient for most circumstances.
- Only connect one of the two GND/SUB pins to the ground plane, to prevent the formation of current return paths through the device substrate. Float the other GND/SUB pin.



#### **8.4.2 Layout Examples**

In the following examples, the RES11A-Q1 is shown with a VSSOP amplifier and 0402-size decoupling capacitors.



**Figure 8-13. Single-Layer Difference Amplifier Implementation**



**Figure 8-14. Single-Layer Instrumentation Amplifier Implementation**



**Figure 8-15. Front-and-Back Instrumentation Amplifier Implementation**







For Figure 8-17, two RES11A-Q1 devices (bottom side) and one dual-channel op-amp (top side) are used.



**Figure 8-17. Front-and-Back Dual Difference Amplifiers Implementation**

<span id="page-28-0"></span>

# **9 Device and Documentation Support**

#### **9.1 Device Support**

#### **9.1.1 Development Support**

#### *9.1.1.1 PSpice® for TI*

[PSpice](https://www.ti.com/tool/PSPICE-FOR-TI)® for TI is a design and simulation environment that helps evaluate performance of analog circuits. Create subsystem designs and prototype solutions before committing to layout and fabrication, reducing development cost and time to market.

#### *9.1.1.2 TINA-TI™ Simulation Software (Free Download)*

TINA-TI™ simulation software is a simple, powerful, and easy-to-use circuit simulation program based on a SPICE engine. TINA-TI simulation software is a free, fully-functional version of the TINA™ software, preloaded with a library of macromodels, in addition to a range of both passive and active models. TINA-TI simulation software provides all the conventional dc, transient, and frequency domain analysis of SPICE, as well as additional design capabilities.

Available as a [free download](http://www.ti.com/tool/tina-ti) from the [Design tools and simulation](https://www.ti.com/design-resources/design-tools-simulation.html) web page, TINA-TI simulation software offers extensive post-processing capability that allows users to format results in a variety of ways. Virtual instruments offer the ability to select input waveforms and probe circuit nodes, voltages, and waveforms, creating a dynamic quick-start tool.

#### **Note**

These files require that either the TINA software or TINA-TI software be installed. Download the free TINA-TI simulation software from the [TINA-TI™ software folder.](http://www.ti.com/tool/tina-ti)

#### *9.1.1.3 TI Reference Designs*

TI reference designs are analog solutions created by TI's precision analog applications experts. TI reference designs offer the theory of operation, component selection, simulation, complete PCB schematic and layout, bill of materials, and measured performance of many useful circuits. TI reference designs are available online at [https://www.ti.com/reference-designs](https://www.ti.com/reference-designs/).

#### *9.1.1.4 Filter Design Tool*

The [filter design tool](http://www.ti.com/lsds/ti/analog/webench/webench-filters.page) is a simple, powerful, and easy-to-use active filter design program. The filter design tool allows the user to create optimized filter designs using a selection of TI operational amplifiers and passive components from TI's vendor partners.

Available as a web-based tool from the [Design tools and simulation](https://www.ti.com/design-resources/design-tools-simulation.html) web page, the [filter design tool](http://www.ti.com/lsds/ti/analog/webench/webench-filters.page) allows the user to design, optimize, and simulate complete multistage active filter solutions within minutes.



# <span id="page-29-0"></span>**9.2 Documentation Support**

### **9.2.1 Related Documentation**

For related documentation see the following:

- Texas Instruments, *[Optimizing CMRR in Differential Amplifier Circuits With Precision Matched Resistor](https://www.ti.com/lit/pdf/SBOA582)  Divider Pairs* [application note](https://www.ti.com/lit/pdf/SBOA582)
- Texas Instruments, *[THP210 Ultra-Low Offset, High-Voltage, Low-Noise, Precision, Fully-Differential Amplifier](https://www.ti.com/lit/pdf/SBOS932)*  [data sheet](https://www.ti.com/lit/pdf/SBOS932)
- Texas Instruments, *[OPAx392 Precision, Low-Offset-Voltage, Low-Noise, Low-Input-Bias-Current, Rail-to-Rail](https://www.ti.com/lit/pdf/SBOS926) [I/O, e-trim™ Operational Amplifiers](https://www.ti.com/lit/pdf/SBOS926)* data sheet

# **9.3 Receiving Notification of Documentation Updates**

To receive notification of documentation updates, navigate to the device product folder on [ti.com.](https://www.ti.com) Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

## **9.4 Support Resources**

TI E2E™ [support forums](https://e2e.ti.com) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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## **9.5 Trademarks**

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#### **9.6 Electrostatic Discharge Caution**



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage. ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may

be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

# **9.7 Glossary**

[TI Glossary](https://www.ti.com/lit/pdf/SLYZ022) This glossary lists and explains terms, acronyms, and definitions.

# **10 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.



<span id="page-30-0"></span>

# **11 Mechanical, Packaging, and Orderable Information**

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

#### **11.1 Tape and Reel Information**



#### **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**











<span id="page-32-0"></span>

#### **11.2 Mechanical Data**



# **PACKAGE OUTLINE**

# **DDF0008A SOT-23 - 1.1 mm max height**

PLASTIC SMALL OUTLINE



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing
- per ASME Y14.5M. 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.





# **EXAMPLE BOARD LAYOUT**

# **DDF0008A SOT-23 - 1.1 mm max height**

PLASTIC SMALL OUTLINE



NOTES: (continued)

4. Publication IPC-7351 may have alternate designs.

5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.





# **EXAMPLE STENCIL DESIGN**

# **DDF0008A SOT-23 - 1.1 mm max height**

PLASTIC SMALL OUTLINE



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations. 7. Board assembly site may have different recommendations for stencil design.





# **PACKAGING INFORMATION**



**(1)** The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

**(3)** MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

**(4)** There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.



# **PACKAGE OPTION ADDENDUM**

**(5)** Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

**(6)** Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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#### **OTHER QUALIFIED VERSIONS OF RES11A-Q1 :**

• Catalog : [RES11A](http://focus.ti.com/docs/prod/folders/print/res11a.html)

NOTE: Qualified Version Definitions:

• Catalog - TI's standard catalog product



# **PACKAGE OUTLINE**

# **DDF0008A SOT-23-THIN - 1.1 mm max height**

PLASTIC SMALL OUTLINE



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.



# **EXAMPLE BOARD LAYOUT**

# **DDF0008A SOT-23-THIN - 1.1 mm max height**

PLASTIC SMALL OUTLINE



4. Publication IPC-7351 may have alternate designs.

5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



# **EXAMPLE STENCIL DESIGN**

# **DDF0008A SOT-23-THIN - 1.1 mm max height**

PLASTIC SMALL OUTLINE



<sup>6.</sup> Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



<sup>7.</sup> Board assembly site may have different recommendations for stencil design.

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